

1 **How do variably striking faults reactivate during rifting? Insights from southern**
2 **Malawi**

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13
14 **Key points**

- 15 • Stress states at the southern end of the Malawi Rift are tested by assessing fault
16 reactivation potential.
- 17 • Variably oriented rift faults reactivate by all striking slightly obliquely to an E-W
18 trending minimum principal compressive stress.
- 19 • Faults may locally accommodate pure normal dip-slip due to the presence of a deep
20 seated crustal weakness.
- 21

22 **Abstract**

23 Active normal faults at the southern end of the Malawi Rift follow an arcuate bend in the
24 high grade metamorphic foliation, with strikes ranging from NW to NNE. However, previous
25 estimates of the stress state that allows such a wide range of normal fault strikes to reactivate
26 are enigmatic, as both a NW-SE and NE-SW trending minimum compressive stress (σ_3) have
27 been proposed. Furthermore, we present field observations of a consistently N-S striking sub-
28 vertical joint set in southern Malawi, which suggests an E-W trending σ_3 . We address this
29 problem by calculating the stress ratio (σ_3/σ_1 , where σ_1 is the maximum compressive stress)
30 and effective coefficient of friction (μ_s') required to reactivate the rift's variably striking
31 faults in stress states based on earthquake focal mechanisms (Stress State 1: $\sigma_3=06/242$) and
32 joint sets (Stress State 2: $\sigma_3=00/082$). Given the consistency of joint orientations, we infer a
33 uniform stress state and reject an alternative hypothesis that σ_3 rotates along the rift. In Stress
34 State 1, NW-striking faults are well oriented. However, misoriented NNE-striking faults
35 require $\mu_s' < 0.7$ to reactivate, which is inconsistent with the lack of frictionally weak
36 phyllosilicates detected in compositional analysis of these faults. In Stress State 2, all faults
37 are well oriented and can reactivate at $\mu_s' > 0.6$. This is also comparable to a previously
38 reported geodetically-derived extension direction. Stress State 2 is therefore favoured,
39 indicating that the southern Malawi Rift consists of a series of slightly-oblique basins, and
40 not alternating orthogonal and highly-oblique sections as predicted by typical models of
41 oblique rifting.

43 **Plain Language Summary**

44 Stretching of the upper brittle part of the Earth's crust should be accommodated by cracks
45 (faults) oriented at 90° to the stretching direction. However, this idealized scenario is rarely
46 observed because the crust is often mechanically heterogenous, or because the stretching
47 direction rotates over geological time. Thus, faults are often non-orthogonal (i.e. oblique) to
48 the stretching direction. Here, we use a mechanical analysis to test the obliquity of faults in
49 southern Malawi at the southern juvenile end of the East African Rift system where the crust
50 is actively extending at ~ 2 mm/yr. This section is of interest as fault orientation varies along
51 the rift, and a range of stretching directions have been proposed previously. Our mechanical
52 analysis indicates that extension is most likely accommodated in southern Malawi by faults
53 that are all slightly oblique to an E-W stretching direction. This is in contrast to previous
54 models of oblique rifting, which suggest that stretching is accommodated by some faults at
55 90° to the stretching direction, whilst others are at a very low ($< 40^\circ$) angle to stretching.

57 **Key words**

58 Continental rift, East African Rift, Fault reactivation, Tectonic stress, Normal faults, Stress
59 inversions

61 **1. Introduction**

62 The axis of a continental rift is expected to be orthogonal to the minimum principal
63 compressive stress (σ_3). This is, however, rarely the case [Brune *et al.*, 2018] due to factors
64 such as temporal stress rotations since the inception of the rifting [Bellahsen *et al.*, 2006;
65 Henstra *et al.*, 2015], or pre-existing crustal fabrics that present cohesionless [Etheridge,
66 1986; Morley *et al.*, 2004] or frictionally-weak planes [Massironi *et al.*, 2011]. These spatial

67 and temporal heterogeneities allow a much greater range of fault orientations, which strike
68 oblique to σ_3 and do not contain the intermediate principal compressive stress (σ_2).

69
70 Often, obliquely oriented rifts will contain faults with a wide range of strikes, whereby some
71 faults strike orthogonal to σ_3 and are linked oblique-slip or strike-slip transfer zones where
72 faults striking highly obliquely to σ_3 [Acocella *et al.*, 1999; Bellahsen & Daniel, 2005;
73 McClay & White, 1995; Withjack & Jamison, 1986], as has been proposed in the East African
74 Rift [Corti, 2012; Delvaux, 2001], Rio Grande Rift [Aldrich, 1986], Rhine Graben
75 [Chorowicz & Deffontaines, 1993; Lopes Cardozo & Behrmann, 2006], and the Gulf of Aden
76 [Bellahsen *et al.*, 2006]. The stress directions in these rifts are typically inferred from
77 measurements of incremental fault strain (i.e. fault slickensides, earthquake focal
78 mechanisms). This is justified by the Wallace-Bott criterion, which predicts that fault slip is
79 parallel to the direction of maximum resolved shear stress on a fault plane [Bott, 1959;
80 Wallace, 1951]. However, this criterion can break down [Pollard *et al.*, 1993; Twiss &
81 Unruh, 1998], including cases whereby rift faults that strike oblique to the regional σ_3 trend
82 accommodate pure normal dip-slip [Corti *et al.*, 2013; Morley, 2010; Petit *et al.*, 1996;
83 Philippon *et al.*, 2015]. Deriving stress states in rifts from fault-hosted slickensides is further
84 complicated because dip-slip faults can host oblique-slip and even strike-slip components due
85 to convergent patterns of co-seismic slip [Hampel *et al.*, 2013; Philippon *et al.*, 2015].

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87 In this study, we address the problem of resolving stress states in rifts with variably striking
88 faults by assuming *a priori* different stress states, and then interpreting their applicability in
89 terms of fault reactivation potential. We use the southern end of the Malawi Rift (Figure 1) as
90 a case example, as geological maps [Bloomfield & Garson, 1965; Habgood *et al.*, 1973;
91 Walshaw, 1965], fault scarps [Hodge *et al.*, 2019; Wedmore *et al.*, in prep.], and earthquake
92 focal mechanisms [Delvaux & Barth, 2010] demonstrate that active faults switch from
93 dominantly NW-SE striking in the Makanjira Graben to NNE-SSW in the Zomba Graben and
94 then back to NW-SE in the Lower Shire Graben as the rift follows an arcuate bend in the high
95 grade metamorphic foliation (Figure 2). Furthermore, there is an inconsistency in the regional
96 σ_3 trend when inferred from fault slickensides [Chorowicz & Sorlien, 1992], fault geometry
97 [Mortimer *et al.*, 2007], earthquake focal mechanisms [Delvaux & Barth, 2010], and geodetic
98 models [Stamps *et al.*, 2018]. Here, three possible stress states are considered:

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- 100 • Stress State 1: A uniform stress state where σ_3 trends SW (06/242, Figure 2d), as
101 proposed by an earthquake focal mechanism stress inversion for the Malawi Rift
102 [Delvaux & Barth, 2010]. In this way, the angle (α) between fault strike and σ_3 is
103 $\sim 90^\circ$ for NW-striking faults, whilst for NNE-striking faults α is $\sim 40^\circ$, and thus they
104 would act as oblique transfer zones.
 - 105 • Stress State 2: A uniform stress state with an \sim E-W trending σ_3 (00/082, Figure 2e),
106 which is consistent with the extension direction inferred from geodetic models
107 [Stamps *et al.*, 2018] and regional joint orientations (Figure 2c). Thus, both faults sets
108 form slightly oblique grabens σ_3 ($\alpha > 60^\circ$).
 - 109 • Stress State 3: The stress state is heterogenous in southern Malawi, with Proterozoic
110 fabrics actively rotating σ_3 along the rift so that α is consistently 90° (Figure 2f;
111 Morley, [2010]).

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113 We first compare these stress states to a new rift-wide stress inversion performed using an
114 updated compilation of earthquake focal mechanisms and fault slickenside orientations. Then
115 the reactivation potential of three differently oriented faults in these stress states is

116 determined in terms of their stress ratio, slip tendency, and effective coefficient of friction.
117 By comparing these results to the frictional properties of the faults inferred from new field
118 observations and compositional analysis, and deformation experiments performed by
119 *Hellebrekers et al.*, [in review], we can determine which stress state is most applicable in
120 southern Malawi. In doing so, new insights are gained into the applicability of using
121 incremental fault strain measurements in stress inversions, and on the controls on fault
122 geometry in an incipient rift.
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124 **2. Geological setting of the southern Malawi Rift**

125 The Malawi Rift is a 900 km long amagmatic section of the East African Rift System's
126 (EARS) Western Branch, and runs from the Rungwe Province in the north to the Urema
127 Graben in the south (Figure 1; *Ebinger et al.*, [1987]). It is typically further divided along its
128 axis into a series of 100-150 km long grabens and half grabens with alternating polarities
129 [*Ebinger*, 1989; *Ebinger et al.*, 1987; *Flannery & Rosendahl*, 1990; *Laõ-Dávila et al.*, 2015].
130 The focus of this study are the three southernmost grabens: the Lower Shire, Zomba, and
131 Makanjira Grabens (Figure 2a).
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133 Basement rock within these grabens constitute part of the Southern Irumide Belt (Figure 1), a
134 structurally complex Mesoproterozoic orogenic belt that underwent amphibolite-granulite
135 facies metamorphism during the Pan African orogeny (c. 800-450 Ma.; *Kröner et al.*, [2001];
136 *Johnson et al.*, [2006]; *Fritz et al.*, [2013]). Whether this belt experienced earlier Irumide age
137 deformation (c. 1020-950 Ma) is unclear [*Andreoli*, 1984; *Fritz et al.*, 2013; *Johnson et al.*,
138 2006; *Kröner et al.*, 2001] and the Lower Shire graben may strictly be part of the
139 Neoproterozoic Zambesi Belt [*Chorowicz & Sorlien*, 1992; *Hargrove et al.*, 2003; *Laõ-*
140 *Dávila et al.*, 2015]. The Lower Shire Graben also underwent NW-SE Karoo extension
141 (*Habgood*, 1963; *Castaing*, 1991), whereas this extension was comparatively minor further
142 north in the Zomba Graben [*Bloomfield*, 1965]. This was followed by a major period of
143 Upper Jurassic-Lower Cretaceous magmatism throughout southern Malawi, which formed
144 the Chilwa Alkaline Province [*Bloomfield*, 1965; *Castaing*, 1991; *Dulanya*, 2017; *Habgood*,
145 1963].
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147 EARS extension initiated at the northern end of the Malawi Rift c. 8.6 Ma [*Ebinger et al.*,
148 1993], although a c. 25 Ma has also been proposed [*Mortimer et al.*, 2016; *Roberts et al.*,
149 2012]. Given the gradual southward propagation of the EARS [*Ebinger et al.*, 1987], the
150 southern grabens analyzed here are likely younger (<5 Ma) than those further north; however,
151 there is little chronostratigraphic control on their evolution [*Dulanya*, 2017; *Wedmore et al.*,
152 in prep.]. As elsewhere in the EARS [*Versfelt & Rosendahl*, 1989], these grabens follow the
153 trend of regional foliation (Figure 2a). Thus, a range of NW-NNE striking faults have formed
154 in southern Malawi (Figure 2b). Topographic relationships demonstrate that both NW and
155 NNE striking faults can dip in either direction orthogonal to strike (Figure 2a). Therefore, the
156 range of fault orientations is polymodal [*Healy et al.*, 2015]; although given the lack of
157 accurate measurements of fault dip, we cannot be sure if the range is strictly quadrimodal
158 (four distinct clusters) or polymodal (continuous distribution of orientations).
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160 3. Strain and stress indicators within the Malawi Rift

161 3.1 Previous estimates of strain and stress within the Malawi Rift

162 At the scale of the EARS, kinematic models have been developed using a combination of
 163 earthquake slip vectors, and continuous and campaign GPS measurements [Saria *et al.*, 2014;
 164 Stamps *et al.*, 2008, 2018]. For southern Malawi, these models indicate an extension azimuth
 165 of $086^{\circ} \pm 5^{\circ}$ relative to a fixed Nubia Plate [Saria *et al.*, 2014; Stamps *et al.*, 2018]. The
 166 current azimuth of the one continuous GPS station in southern Malawi (ZOMB) is 072°
 167 (Figure 2a; Stamps *et al.*, [2018]).

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 169 *Delvaux and Barth*, [2010] used an earthquake focal mechanisms stress inversion to derive a
 170 near Andersonian normal fault stress state for the Malawi Rift, with a sub-vertical maximum
 171 compressive principal stress (σ_1 , 83/070) and sub-horizontal σ_3 (06/242). This σ_3 orientation
 172 implies NE-SW extension across the rift, in contrast to the E-W extension inferred from
 173 geodetic models [Stamps *et al.*, 2018]. Furthermore, this stress inversion predicts that NNE
 174 striking faults accommodate oblique extension (Figure 2d). However, slickensides on NNE
 175 striking faults indicate nearly pure dip-slip motion, and thus approximately NW-SE extension
 176 [Bloomfield and Garson, 1965; Chorowicz and Sorlien, 1992; Wedmore *et al.*, in prep.]. The
 177 geometry of faults from seismic reflection surveys within Lake Malawi have also been used
 178 to infer NW-SE rift extension [Mortimer *et al.*, 2007; Scott *et al.*, 1992].

179 180 3.2 An updated stress inversion for the Malawi Rift

181 The discrepancy in rift extension direction when inferred from earthquake focal mechanisms,
 182 geodetic models, and fault slickensides may reflect the high azimuthal error and limited
 183 dataset (13 focal mechanism across the 900 km long rift) used in the *Delvaux and Barth*,
 184 [2010] stress inversion. We therefore update this stress field with an expanded dataset of 23
 185 focal mechanisms (Table 1, Figure 1a), which incorporates: (1) subsequent seismicity such as
 186 the 2009 Karonga [Biggs *et al.*, 2010; Hamiel *et al.*, 2012] and 2018 Nsanje earthquake
 187 sequences [U.S. Department of the Interior U.S. Geological Survey, 2018], and (2) focal
 188 mechanisms from revised bodywave modelling [Craig *et al.*, 2011], which are considered
 189 more accurate than the Global Centroid Moment Tensor solutions used in the *Delvaux and*
 190 *Barth*, [2010] inversion (Table 1). As in *Delvaux and Barth*, [2010], we use Win-Tensor
 191 (version 5.8.8, *Delvaux and Sperner*, [2003]) to perform the inversion. Here, the data are first
 192 processed using the “Right Dihedron Method” to determine the possible range of σ_1 and σ_3
 193 orientations [Angelier & Mechler, 1977]. This range is then refined by using “Rotational
 194 Optimisation” [Delvaux & Sperner, 2003], which seeks to reduce the misfit angle (ω)
 195 between the earthquake slip vectors and the azimuth of maximum shear stress within the
 196 inversion. This inversion is first run for both nodal planes and then subsequently with just the
 197 plane that has the smallest misfit. Focal mechanisms were progressively filtered during the
 198 Right Dihedron Method analysis using the Counting Deviation method (*Delvaux and*
 199 *Sperner*, [2003], see supplementary information S1), and then by removing cases where
 200 $\omega > 45^{\circ}$ for both nodal planes during Rotational Optimisation.

201
 202 The revised stress field shows a slight clockwise rotation of σ_3 to 12/070 relative to the
 203 *Delvaux and Barth*, [2010] inversion (Figure 3). This σ_3 azimuth thus lies approximately
 204 halfway between those derived in Stress States 1 and 2 and is still inconsistent with NW
 205 trending slickensides. Notably, however, the azimuthal accuracy has been improved (from
 206 $\omega = \pm 22^{\circ}$ to $\pm 12^{\circ}$). This may reflect that *Delvaux and Barth*, [2010] included all focal
 207 mechanisms in their inversion regardless of whether they were compatible with each other,

208 whilst our expanded dataset allowed a more selective approach. Stress inversions combining
209 fault slickensides [*Chorowicz and Sorlien, 1992; Wedmore et al., in prep.*] and earthquake
210 focal mechanisms were also attempted. However, these could not produce a reliable reduced
211 stress tensor as either the data filtering was too severe, or the resulting stress shape ratio
212 ($\Phi = \sigma_2 - \sigma_3 / \sigma_1 - \sigma_3$) indicates an unrealistic prolate stress ellipsoid ($\Phi = 0.04$, *Lisle et al., [2006]*;
213 see Supplementary Information S1). In summary, the updated stress inversions for the
214 Malawi Rift cannot distinguish between the three stress states for southern Malawi postulated
215 in the introduction. Hence, there is a need to consider other indicators of stress and strain
216 within the rift, and to assess fault reactivation potential in different stress states.

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218 3.3 Joint orientations

219 Figures 2 and 4 show the orientations of two steeply-dipping joint sets in southern Malawi,
220 which strike N-S and E-W. N-S striking joints have bare surfaces and are mutually cross
221 cutting with the E-W striking set, though tend to cut across them more commonly than vice-
222 versa. The majority of measurements were taken within the Zomba Graben; however, the N-S
223 and E-W sets are also observed at two locations within the Makanjira Graben (Figure 2).
224 Joint orientations were all measured >50 m from faults and are inferred to be outside their
225 respective damage zones.

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227 By inferring that these joints are opening parallel to the trend of σ_3 , it is possible to derive
228 another estimate for its orientation within southern Malawi. To do this, we quantitatively
229 analyse joint orientations using Kamb Contours (Figure 4a), where contours represent
230 standard deviations away from the expected density of a random sample [*Kamb, 1959*]. This
231 analysis finds that the trend of the highest concentration of poles to the N-S striking joint set
232 trends $082^\circ \pm 7^\circ$, which is taken here as the joint-derived σ_3 trend. This trend indicates an
233 extension direction that is within error of the geodetically-derived extension direction for the
234 Malawi Rift [*Saria et al., 2014; Stamps et al., 2018*]. The E-W striking joints are interpreted
235 to reflect either: (1) an orthogonal joint set to the N-S set, and/or (2) the emplacement of E-W
236 striking Chilwa Akaline Province dykes [*Bloomfield, 1965*]. Many of the N-S striking joints
237 are foliation-parallel and thus may not necessarily reflect tectonic stresses [e.g. *Price, 1959*;
238 *Engelder, 1985; Williams et al., 2018*]. However, the N-S striking joint set is also observed
239 within isotropic rocks, and so the σ_3 trend is not significantly changed when foliation-parallel
240 joints are removed from the analysis ($079^\circ \pm 8^\circ$, Figure S4).

241

242 4. Fault strength in southern Malawi

243 To calculate fault reactivation potential at the southern end of the Malawi Rift, it is necessary
244 to consider the frictional properties of its faults. We therefore selected three faults
245 (Thyolo, Chingale Step, and Bilila-Mtakataka, Figure 2a), which: (1) encompass the range of
246 fault orientations observed in southern Malawi, (2) have late-Quaternary fault scarps, and are
247 therefore considered active [*Jackson and Blenkinsop, 1997; Hodge et al., 2018, 2019*;
248 *Wedmore et al., in prep.*], and (3) are well-exposed, so it is possible to sample them for
249 compositional analysis. The footwalls of the Chingale Step and Thyolo faults consist of
250 intensely fractured basement, which is in contact with the hanging wall post-Miocene
251 sediments (Figure 5; *Dulanya, [2017]*). The contact itself consists of a <1 m thick fault gouge
252 (Figure 5). Along most of its length, the Bilila-Mtakataka fault consists of a soil-mantled
253 scarp [*Hodge et al., 2018; Jackson & Blenkinsop, 1997*]. However, at Kasinje (Figure 2a), the
254 fault consists of a 3 m thick unit of intensely fractured gneiss that separates footwall and
255 hanging wall hornblende gneisses [*Hodge et al., 2018*].

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257 To assess the composition of the fault zones, X-ray diffraction (XRD) analyses were
 258 conducted on two samples from each of the faults: (1) a ‘country rock’ sample from the intact
 259 protolith closest to the fault, and (2) a ‘fault rock’ sample from the faulted contact itself, i.e.
 260 the fault gouge for the Thyolo and Chingale Step faults (Figure 5), and intensely fractured
 261 gneiss for the Bilila-Mtakataka fault. XRD patterns were collected on powdered samples with
 262 a Philips PW1710 Automated Powder Diffractometer using Cu-K α radiation at 35kV and
 263 40mA, between 2 and 70° 2 θ , at a scan speed of 0.04 °2 θ /s. From the scans, phases were
 264 identified using Philips PC Identify software. Using the peak areas, semi-quantitative analysis
 265 was then performed to estimate the weight percentage of each identified phase (Table 2,
 266 Figure S5).

267

268 For each fault, we find that the phyllosilicate content is <15% (Table 2). This is significant as
 269 faults that are frictionally weak (fault static coefficient of friction (μ_s)<0.4) typically contain
 270 interconnected phyllosilicates phases that constitute >30-40% of the fault rock [Massironi *et*
 271 *al.*, 2011; Moore & Lockner, 2004]. Thus, we infer that these faults exhibit ‘Byerlee’
 272 frictional strengths (μ_s ~0.6-0.8; Byerlee, [1978]), which is also consistent with the results of
 273 deformation experiments on a suite of basement lithologies from the Malawi Rift (μ_s =0.55-
 274 0.80; Hellebrekers *et al.*, [in review]). There are non-systematic differences in composition
 275 between some footwall country rock and fault rock samples (Table 2). For example, the
 276 Chingale Step fault gouge is near pure calcite, yet this phase is not detected in its country
 277 rock sample. These samples alone, however, are insufficient to determine if these differences
 278 reflect local protolith variations, near-surface weathering [Isaacs *et al.*, 2007], or fault zone
 279 alteration [*sensu* Sutherland *et al.*, 2012].

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281 5. Fault reactivation potential analysis in southern Malawi

282 Fault reactivation potential considers how susceptible a fault, of a given orientation and stress
 283 state, is to slip under the Mohr-Coulomb failure criterion. This criterion describes the shear
 284 stress (τ) required for a fault to exceed its frictional resistance:

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$$\tau = c + \mu_s(\sigma_n - P_f) \quad (1)$$

286

287 where σ_n is the normal stress, c is the cohesive strength, and P_f is pore fluid pressure. We
 288 consider fault reactivation in potential in southern Malawi in terms of Stress Ratio, Slip
 289 Tendency, and effective coefficient of friction (Figure 6).

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291 5.1. Stress ratio

292 The stress ratio is the ratio between σ_3 and σ_1 required for fault slip ($Q=\sigma_3/\sigma_1$, Figure 6;
 293 Sibson, [1985]). For the faults considered here, which strike obliquely to σ_3 and do not
 294 contain σ_2 , we use the 3D solution outlined by Leclère and Fabbri, [2013], where:

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$$Q = \frac{-(2AD\mu_s + 2C) \pm \sqrt{\Delta}}{A^2\mu_s^2 - C} \quad (2)$$

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297 Here, A , B , C , D and Δ are functions defined by the stress shape ratio (Φ), c , μ_s , magnitude of
 298 σ_1 , and the direction cosines between the normal to the fault plane and the three principal
 299 stress axes (see supplementary information S2). Q and μ_s must be real numbers with $Q \leq 1$
 300 and $\mu_s \geq 0$ [Leclère & Fabbri, 2013].

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We calculate Q for the three faults described in section 4, given Stress States 1 and 2. For Stress State 1 (α is $\sim 90^\circ$ for NW-striking faults and $\sim 40^\circ$ for NNE-striking faults) we use the principal stress orientations derived in the *Delvaux and Barth*, [2010] stress inversion ($\sigma_1=83/070$, $\sigma_2=02/333$, $\sigma_3=06/242$), whilst for Stress State 2 (α is $\sim 60^\circ$ for all faults) the principal stress orientations are based on joint orientations ($\sigma_1=90/000$, $\sigma_2=00/172$, $\sigma_3=00/082$). No reactivation analysis is conducted for the stress rotation hypothesis (Stress State 3), as it intrinsically assumes that all faults are optimally oriented for failure [*Morley*, 2010].

The strike of the Chingale Step and Thyolo faults is well constrained from their prominent scarps that are visible in a 12 m resolution TanDEM-X digital elevation model [*Hodge et al.*, 2019; *Wedmore et al.*, in prep.] . For the Chingale Step fault, the strike is the orientation of the line that connects the two ends of its scarp, whilst for the segmented Thyolo fault, strike is the orientation of its longer north-western section (Figure 2a). The Bilila-Mtakataka fault is best described by two sub-parallel segments, the longest of which is oriented 156/46 NE [*Hodge et al.*, 2018]. Dips of 57° and 60° for the Chingale and Thyolo faults were derived from field measurements (Figure 5). Although there is an uncertainty in how representative these surface measurements of fault dip are, these measurements are similar to those inferred at depth from geophysical surveys elsewhere in the Malawi Rift ($45\text{--}65^\circ$; *Wheeler and Rosendahl*, [1994]; *Mortimer et al.*, [2007]; *Kolawole et al.*, [2018]).

As justified in section 4, we infer that these faults exhibit Byerlee frictional strengths, and so a value of $\mu_s=0.7$ is used. A foliation-parallel pre-existing fault would generally be considered cohesionless [*Morley et al.*, 2004; *Sibson*, 1985]. However, the high-grade metamorphic fabrics within the Malawi Rift are qualitatively observed to be cohesive (Figure 4b). Furthermore, the low rift strain rates (~ 2 mm/yr; *Saria et al.*, [2014]) imply that there are long recurrence intervals between earthquakes, so it is possible that interseismic healing has led to a recovery of some fault cohesion [*Tenthorey & Cox*, 2006]. To account for this ambiguity, we calculate Q for end-member cases where $c=0$ and $c=40$ MPa, the latter of which is derived from crystalline rocks typically exhibiting tensile strengths (T_0) of 20 MPa, and that $c \approx 2T_0$ [*Lockner*, 1995; *Sibson*, 1985, 1998].

No knowledge of stress magnitudes is required for calculating Q for a cohesionless fault [*Leclère & Fabbri*, 2013]. However, the magnitude of σ_1 is needed to determine Q for a cohesive fault, which is calculated by assuming an Andersonian normal fault stress state where:

$$\sigma_1 = \sigma_v = \bar{\rho}(z)gz \quad (3)$$

where σ_v is the vertical stress, g is gravity (9.8 ms^{-2}), z is depth, and $\bar{\rho}(z)$ is the average density of the overlying crust for a given depth, which is a function of a Malawi Rift three-layer crustal model (Table S2; *Nyblade and Langston*, [1995]; *Fagereng*, [2013]). As Q will vary with depth for a cohesive fault, it is calculated here between 6-35 km, which encompasses the depth range for instrumentally-recorded earthquake nucleation in the Malawi Rift [*Biggs et al.*, 2010; *Craig et al.*, 2011; *Nyblade & Langston*, 1995].

We assume the pore fluid pressure, $P_f=0$; however, the influence of fluids on fault reactivation is assessed in section 5.3. The stress shape ratio (Φ) is 0.33, as derived from the

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349 updated stress inversion (Figure 3). For comparison, the orientation of the faults is shown in a
 350 stereoplot that is contoured by Q values for a given set of Φ , μ_s , principal stress orientations,
 351 and (for cohesive faults) depth. To allow for the uncertainty in Φ and μ_s , Q -contour plots are
 352 also constructed in Φ - μ_s space for a fixed set of fault and principal stress orientations
 353 [Boulton *et al.*, 2018].

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355 5.2 Slip tendency

356 Slip tendency (T_s) is a measure of the ratio of τ to σ_n acting on the fault surface [Lisle &
 357 Srivastava, 2004; Morris *et al.*, 1996]:

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$$T_s = \frac{\tau}{\sigma_n} \quad (4)$$

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360 For a given stress state, there is a maximum value of T_s , which is that acting on a
 361 cohesionless optimally-oriented fault (Figure 6; Lisle and Srivastava, [2004]). This leads to
 362 the definition of a normalized index of slip tendency (T'_s) that ranges between 0-1:

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$$T'_s = \frac{T_s}{\max(T_s)} = \frac{\tau}{\sigma_n \tan \phi} \quad (5)$$

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365 (corrected from eq. 3 in Lisle and Srivastava, [2004]; pers. comm. R. Lisle) where ϕ is the
 366 angle of internal fault friction ($\tan \phi = \mu_s$). A fault with low T'_s thus also reactivates at low Q
 367 (Figure 6). To calculate T_s and T'_s for the Chingale Step, Thyolo and Bilila-Mtakataka faults
 368 without knowledge of the magnitudes of τ and σ_n , we use the solutions outlined by Lisle and
 369 Srivastava, [2004] (see supplementary information S3). This analysis is performed for Stress
 370 States 1 and 2, assuming $\mu_s=0.7$, $P_f=0$, and $\Phi = 0.33$.

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372 5.3 Fault effective coefficient of friction

373 The concept of T_s can be extended to calculate the effective coefficient of friction (μ_s'),
 374 which describes the maximum value of μ_s or lowest value of P_f that allows faults to reactivate
 375 for a given stress state, without also inducing failure along optimally oriented planes in intact
 376 rock (Figure 6; Sibson, [1985]; Muluneh *et al.*, [2018]). Like T_s , μ_s' is a measure of the ratio
 377 of τ to σ_n acting on a fault, however, it is derived using inferred principal stress magnitudes,
 378 and fault cohesion can be incorporated. This is advantageous as μ_s' can then be compared to
 379 values of μ_s inferred from experimental and compositional analysis of faults to determine if
 380 they will reactivate in a given stress state, or if elevated fluid pressures are required for
 381 reactivation.

382

383 Principal stress magnitudes can be derived as μ_s' is being equated to the stresses acting on an
 384 optimally oriented fault (Figure 6). In this case, the relative principal stress magnitudes can
 385 be calculated using Mohr-Coulomb theory [Jaeger *et al.*, 2007]:

386

$$\sigma_1 = 2c \sqrt{\frac{1 + \sin \phi_{intact}}{1 - \sin \phi_{intact}}} + \sigma_3 \left(\frac{1 + \sin \phi_{intact}}{1 - \sin \phi_{intact}} \right) \quad (6)$$

387

388 where $\phi_{intact} = \tan^{-1} \mu_{s-intact}$, and $\mu_{s-intact}$ is the frictional strength of intact rock. Given the results
 389 of Hellebrekers *et al.*, [in review], we take $\mu_{s-intact}$ to equal 0.7, thus $\phi_{intact} = 35^\circ$ and is the same

390 as the fault frictional strength (μ_s). Since σ_1 can be derived from eq. 3, it is thus also possible
 391 to calculate σ_3 and σ_2 by rearranging eq. 6 and the equation for Φ (eq. S1) respectively. The
 392 principal stress magnitudes can then be used to calculate τ and σ_n as a function of depth
 393 [Jaeger *et al.*, 2007], and μ_s' can be derived by rearranging the Mohr Coulomb criterion (eq.
 394 1). Thus, for the parameters assumed here:
 395

$$\mu_s'(z) = \frac{\sqrt{C \left(\frac{2.7z\bar{\rho}(z) - 42}{9.8z\bar{\rho}(z)} \right)^2 - 2C \left(\frac{2.7z\bar{\rho}(z) - 42}{9.8z\bar{\rho}(z)} \right) + C - \frac{c}{\sigma_1}}}{A \left(\frac{2.7z\bar{\rho}(z) - 42}{9.8z\bar{\rho}(z)} \right) + B} \quad (7)$$

396 where the functions A , B , and C are defined by equations S2-S4 (see supplementary
 397 information S4). As previously, we calculate μ_s' for the Thyolo, Chingale Step, and Bilila-
 398 Mtakataka faults being reactivated in Stress States 1 and 2 over a depth range of 6-35 km and
 399 consider both cohesionless and cohesive faults. If μ_s' and $\mu_{s-intact}$ are set to be the same, then
 400 the minimum pore fluid pressure (P_f') required to reactivate a fault (Figure 6) can be
 401 calculated from μ_s' as a function of depth:
 402

$$P_f(z) = \sigma_n(z) - \left(\frac{\sigma_n(z)\mu_s'(z)}{\mu_s} \right) \quad (8)$$

403 (see supplementary information S4). This is calculated with $\mu_s=0.7$ and is plotted in terms of
 404 the effective pore-fluid factor ($\lambda_v'=P_f'/\sigma_v$). In addition, we show the results of this analysis at
 405 a depth of 20 km in 3D Mohr Space using MohrPlotter v. 2.8.3 [Allmendinger *et al.*, 2013].
 406
 407

408 6. Fault reactivation potential results

409 The Thyolo and Bilila-Mtakataka faults have a high reactivation potential under Stress State
 410 1, as their Q value is 'favourable' ($Q>0.5Q_{Optimal}$, Figures 6b and 7; Sibson,[1985]; Leclère
 411 and Fabbri, [2013]), and $T'_s \sim 1$ (Table 3, Figure S6). Thus, they will reactivate under Stress
 412 State 1 at relatively high μ_s' (>0.55), regardless of whether they are cohesive or not (Table 3,
 413 Figures 8 and 9a). Conversely, the Chingale Step fault is 'unfavourably' ($0.5Q_{Optimal}>Q>0$;
 414 Figures 6c and 7a) to 'severely misoriented' ($Q<0$ Figures 6d and 7c) in this stress state,
 415 depending on depth and whether it is cohesive or not. $T'_s=0.67$ (Table 3), and at depths >10
 416 km, will not reactivate in Stress State 1 unless $\mu_s'<0.7$ or $\lambda_v'>0.1$ (Table 3, Figures 8b, 9, and
 417 S7b).
 418

419 In Stress State 2, all faults are favourably oriented (Figure 6b) and exhibit $T'_s>0.8$, although
 420 the reactivation potentials of the Thyolo and Bilila-Mtakataka faults are slightly less than
 421 under Stress State 1 (Table 3). In Stress State 2, all faults will reactivate at $\mu_s>0.5$ at depths
 422 >10 km (Table 3, Figures 8 and 9b). All results for Q are broadly independent of the values
 423 of Φ and μ_s used in this analysis (Figures 10 and S8).
 424

425 7. How do faults in southern Malawi reactivate?

426 Although the Thyolo and Bilila-Mtakataka faults are well oriented in Stress State 1, the
 427 Chingale fault in the Zomba Graben is unfavourably to severely misoriented (Table 3). Late
 428 Quaternary activity on this fault has been demonstrated by Wedmore *et al.*, [in prep.], and so

429 its orientation is representative of a structure currently accommodating extension in this
430 region. To reactivate as a cohesionless fault under Stress State 1 at 10-35 km depth -the depth
431 range at which the majority of earthquakes nucleate in the Malawi Rift (Table 1)- μ_s' ranges
432 between 0.5-0.7 (Figure 8b). This is at the lower end of frictional strengths inferred from its
433 composition (Table 2) and deformation experiments on basement rocks in Malawi
434 [Hellebrekers *et al.*, in review]. In the cohesive fault case, $\mu_s' < 0.45$ (Figure 8b), and so below
435 its likely frictional strength.

436
437 Alternatively, the Chingale fault may reactivate under Stress State 1 at $\mu_s = 0.7$ through an
438 increase in fluid pressure ($\lambda_v' < 0.2$, Figure S8). These fluid pressures are sustainable in a
439 normal fault stress state [Sibson & Rowland, 2003]. However, the crust in the Malawi Rift
440 has been dehydrated during one or more episodes of high grade metamorphism, and is
441 therefore likely to be comparatively dry [Fagereng, 2013]. Furthermore, where faults do host
442 high fluid pressures, they often contain extensive vein networks [e.g. Bruhn *et al.*, 1994;
443 Caine *et al.*, 2010; Sutherland *et al.*, 2012], which are not observed in the fault zones we
444 considered (Figures 4b and 5).

445
446 We emphasise that this reactivation analysis cannot definitively discount any of the possible
447 stress states assessed here. Ideally, stress orientations would be measured using a range of
448 techniques (e.g. borehole breakouts). Nevertheless, if we assume frictionally strong faults and
449 cohesive high grade metamorphic fabrics, then it is difficult to account for why a structure
450 with the NNE-SSW strike of the Chingale Step fault (or indeed other similarly-oriented faults
451 in the Zomba Graben, Figure 2a) would have activated and continue reactivating in Stress
452 State 1, instead of a more optimally oriented fault forming. Conversely, all faults are
453 favourably oriented in Stress State 2, and so can reactivate at μ_s or P_f that require neither
454 frictionally weak minerals nor elevated fluid pressure (Figure 8). Furthermore, this stress
455 state is consistent with joint orientations and the geodetically-derived extension direction
456 [Stamps *et al.*, 2018].

457
458 Under the Wallace-Bott criterion, southern Malawi accommodates NE-SW extension in
459 Stress State 1 (Figure 2d) or E-W extension in Stress State 2. It is thus difficult to reconcile
460 these stress states to the range of NW-SE to NE-SW extension directions have been proposed
461 (see Section 3.1). Notably, however, fault slickensides and earthquake focal mechanisms in
462 the Zomba Graben (Table 1, Figure 5; Chorowicz and Sorlien, [1992]; Wedmore *et al.*, in
463 [prep.]) indicate NW-SE extension, in contrast to the highly oblique ($\alpha < 40^\circ$) NE-SW
464 extension predicted by applying the Wallace-Bott criterion to Stress State 1.

465
466 A range of extension directions can be accounted for by the model proposed in Morley,
467 [2010] where pre-existing Southern Irumide metamorphic fabrics rotate σ_3 along the southern
468 Malawi rift, so that all faults are pure dip-slip (i.e. Stress State 3, Figure 2f). In this way, all
469 faults will be optimally oriented for reactivation. Furthermore, although some oblique-slip
470 focal mechanisms (Table 1) and fault slickensides (Figure S2) are recorded in southern
471 Malawi, in the former case, these tend to be historical focal mechanisms that were not
472 instrumentally well-recorded, whilst with regards to the latter, this may relate to slickensides
473 that record the inherent oblique slip component of normal faulting earthquakes as the fault tip
474 is approached [Hampel *et al.*, 2013; Philippon *et al.*, 2015]. There is, however, a discrepancy
475 between this hypothesis and the homogenous orientation of joint sets in southern Malawi
476 Rift, which suggest a uniform stress state (Figure 2 and 4). The Bilila Mtakataka and
477 Chingale Step faults also locally cross-cut the foliation in a non-systematic manner at the

478 surface (Figure 2a; *Bloomfield*, [1965]; *Jackson and Blenkinsop*, [1997]; *Hodge et al.*,
 479 [2018]), further suggesting that the foliation is not actively rotating stresses.

480

481 We therefore propose a variation of the *Morley*, [2010] hypothesis based on analogue models
 482 [*Corti et al.*, 2013; *Philippon et al.*, 2015]. Here, the regional principal stress axes [*sensu*
 483 *Pollard et al.*, 1993] in southern Malawi are uniformly parallel to those in Stress State 2,
 484 however, at the local scale [*sensu Twiss and Unruh*, 1998] fault slip vectors are rotated to
 485 dip-slip along the rift by a deep-seated weak ductile shear zone that is oblique to σ_3 , but
 486 which conditions the geometry and distribution of the rift's faults (Figure 2e; *Hodge et al.*,
 487 [2018]; *Wedmore et al.*, [in prep.]; Figure 2e). The following constraints are therefore
 488 satisfied: (1) frictionally strong normal faults with a wide range of strikes are reactivated, (2)
 489 consistently oriented sets of N-S and E-W striking joints, (3) all faults have dip-slip
 490 kinematics. If true, this hypothesis has the following implications:

491

492 • A polymodal range of fault orientations at the southern end of the Malawi Rift (Figure
 493 2a) can be accounted for by a uniform stress state and the Mohr Coulomb criterion,
 494 given that Φ is low and variably oriented pre-existing crustal weaknesses [c.f. *Healy*
 495 *et al.*, 2015].

496 • Unlike in other rifts, variably striking faults in southern Malawi do not reactivate with
 497 faults striking orthogonally to σ_3 being linked by faults striking highly obliquely to
 498 σ_3 . Instead, all faults can reactivate while striking slightly oblique to a uniformly E-W
 499 trending σ_3 (Figure 2e).

500 • Using fault slickensides and earthquake focal mechanisms in stress inversions is
 501 problematic as regional stresses and fault displacement are not necessarily aligned
 502 [*Philippon et al.*, 2015; *Twiss & Unruh*, 1998]. Furthermore, accurate principal stress
 503 directions will not be derived from stress inversions in which only a subset of fault
 504 orientations from a polymodal distribution are included [*Healy et al.*, 2015; *Twiss &*
 505 *Unruh*, 1998].

506 • This justifies a reassessment of the stress states and extension directions that have
 507 been inferred elsewhere in the Malawi Rift [*Chorowicz & Sorlien*, 1992; *Delvaux &*
 508 *Barth*, 2010; *Mortimer et al.*, 2007; *Ring et al.*, 1992], and other rifts where highly-
 509 oblique transfer zones have been proposed [e.g. *Chorowicz and Deffontaines*, 1993;
 510 *Acocella et al.*, 1999].

511 • Normal faults with a wide range of strikes can all reactive within the same stress state,
 512 which should be considered during seismic hazard assessment of continental rifts.

513

514 8. Conclusions

515 Attempts to determine the stress state in the Malawi Rift using fault geometry and
 516 slickensides [*Chorowicz & Sorlien*, 1992; *Mortimer et al.*, 2007; *Scott et al.*, 1992],
 517 earthquake focal mechanisms (Figure 3, *Delvaux and Barth*, [2010]), and geodetic models
 518 [*Saria et al.*, 2014; *Stamps et al.*, 2018] have produced ambiguous results. Therefore, to test
 519 the applicability of two possible stress states, we determined the reactivation potential of
 520 three representative differently-oriented faults in southern Malawi, in terms of their slip
 521 tendency, stress ratio, and effective coefficient of friction. The NW-SE striking Thyolo and
 522 Bilila-Mtakataka faults are well-oriented with respect to a stress state where σ_3 is SW
 523 trending (Stress State 1, Figure 2d). However, it is difficult to account for the reactivation of
 524 the unfavourably to severely misoriented NNE-SSW striking Chingale Step fault under Stress
 525 State 1, given realistic frictional properties of the rift ($\mu_s \sim 0.7$, $P_f \sim 0$). If σ_3 has a consistent

526 ~E-W trend (Stress State 2, Figure 2e), all faults are favourably oriented to reactivate. An
 527 alternative hypothesis that fabrics actively rotate the stresses along the rift (Stress State 3,
 528 Figure 2f; *Morley*, [2010]), is inconsistent with spatially homogeneous joint orientations and
 529 local variations in the foliation orientation.

530
 531 From this reactivation analysis, we consider that Stress State 2 is most applicable to southern
 532 Malawi, which is also consistent with regional joint sets (Figures 2 and 4) and large scale
 533 geodetic models [*Stamps et al.*, 2018]. This would suggest that all faults in southern Malawi
 534 reactivate by being slightly oblique (angle between fault strike and regional σ_3 trend $<30^\circ$),
 535 and thus counter to typical models of oblique rifting in which one fault set strikes orthogonal
 536 to σ_3 and the other is highly oblique [*Acocella et al.*, 1999; *Bellahsen & Daniel*, 2005;
 537 *McClay & White*, 1995].

538
 539 It is unclear whether the slightly oblique E-W extension predicted by Stress State 2 in
 540 southern Malawi is reflected in the fault's kinematics, or if the faults are actually pure dip-
 541 slip as indicated by the few well-determined focal mechanisms (Table 1). In the latter case,
 542 this inconsistency can be explained by a deep-seated zone of crustal weakness, which is
 543 exploited by the rift's faults and re-orient slip [*Corti et al.*, 2013; *Hodge et al.*, 2018;
 544 *Philippon et al.*, 2015]. Nevertheless, in rifts where stress states derived from measurements
 545 of fault displacement are ambiguous, fault reactivation potential analysis provides a powerful
 546 way to test their applicability.

547

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554

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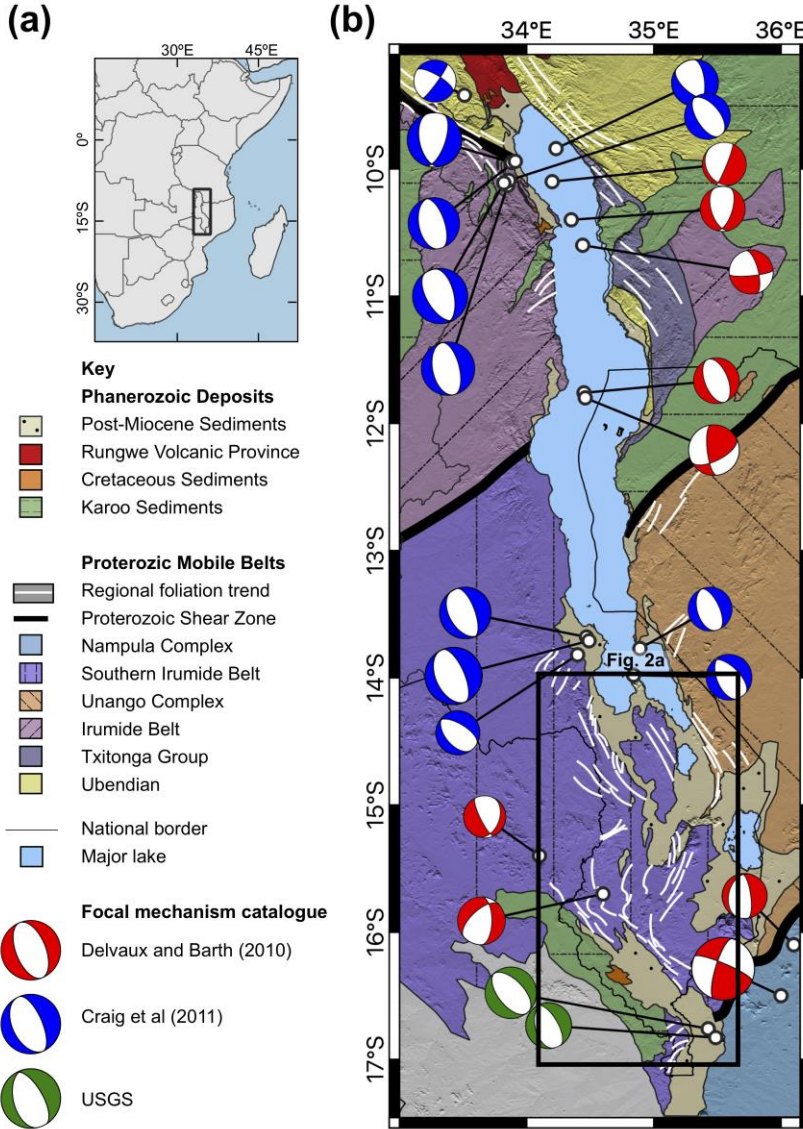
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839 **List of figures**

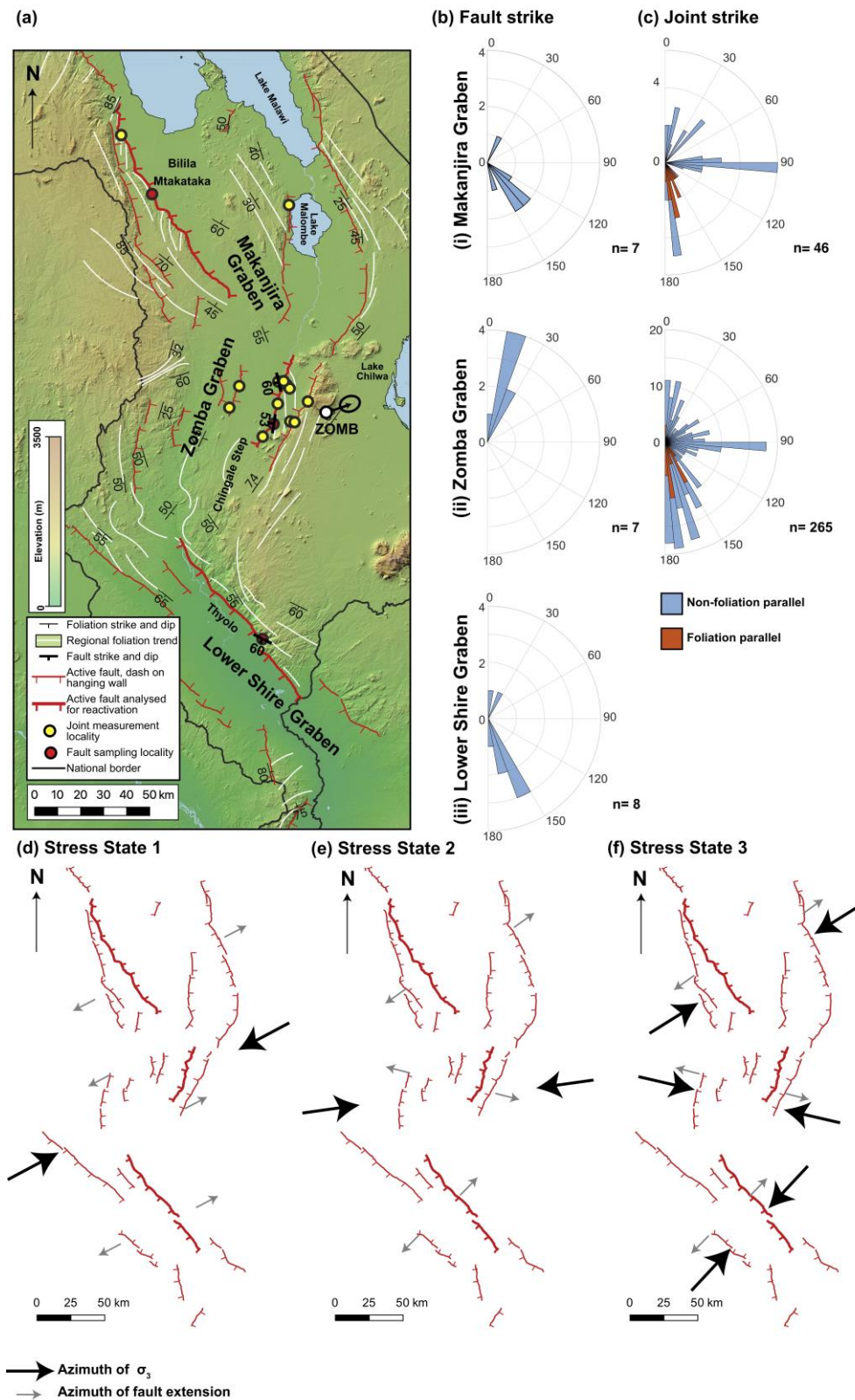
840 **Figure 1**



841

842 Figure 1: (a) Location of Malawi Rift within East Africa. (b) Simplified geological map of
 843 the rift with Proterozoic units taken from *Fritz et al.*, [2013], and underlain by Shuttle Radar
 844 Topography Mission (SRTM) 30 m digital elevation model (DEM; *Sandwell et al.*, [2011]).
 845 Location of focal mechanisms listed in Table 1 also given. Foliation orientations and trends
 846 collated from SRTM images, field measurements and previous studies [*Bloomfield*, 1958,
 847 1965; *Bloomfield & Garson*, 1965; *Habgood et al.*, 1973; *Hodge et al.*, 2018].

848 Figure 2



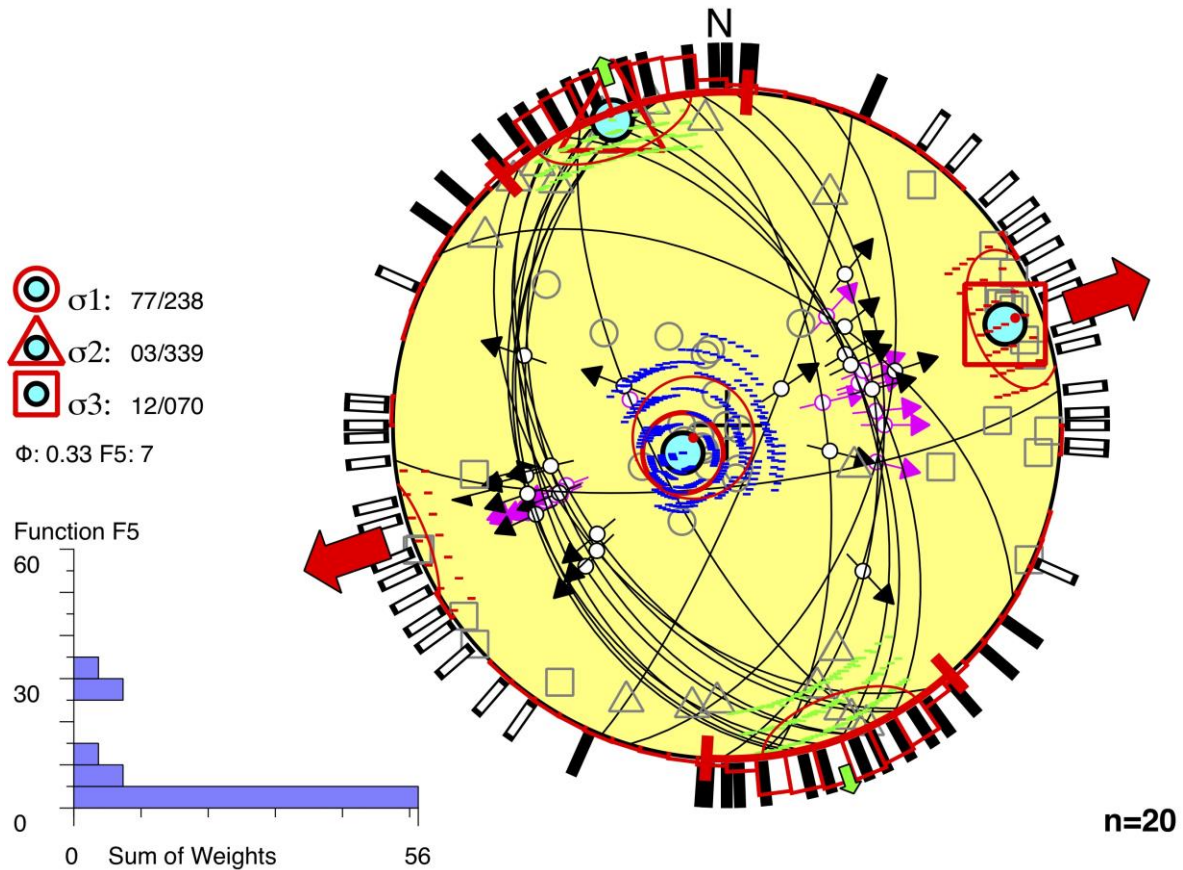
849

850 Figure 2: (a) Map of active faults in southern Malawi collated from TanDEM-X DEM and geological
 851 maps [Bloomfield, 1958, 1965; Bloomfield and Garson, 1965; Walshaw, 1965; Habgood et al., 1973;
 852 Hodge et al., 2018, 2019; Wedmore et al., in prep.]. Area shown is indicated in Figure 1b. The
 853 azimuth of the ZOMB permanent GPS station is also shown [Stamps et al., 2018]. Joint and fault

854 sampling and measurement localities also shown. Rose plots for measurements of (b) fault and (c)
855 joint strike for each of the grabens. Schematic representation of the σ_3 azimuth in Stress States (d) 1,
856 (e) 2, and (f) 3 with respect to faults in southern Malawi. In addition, we show extension direction as
857 inferred by the Wallace Bott criterion (for Stress States 1 and 3), or if a slip reorientation occurs (for
858 Stress State 2; *Philippon et al.*, [2015]). Area shown for each map is the same as in (a). Weighted
859 fault lines are those on which reactivation analysis was conducted.

860

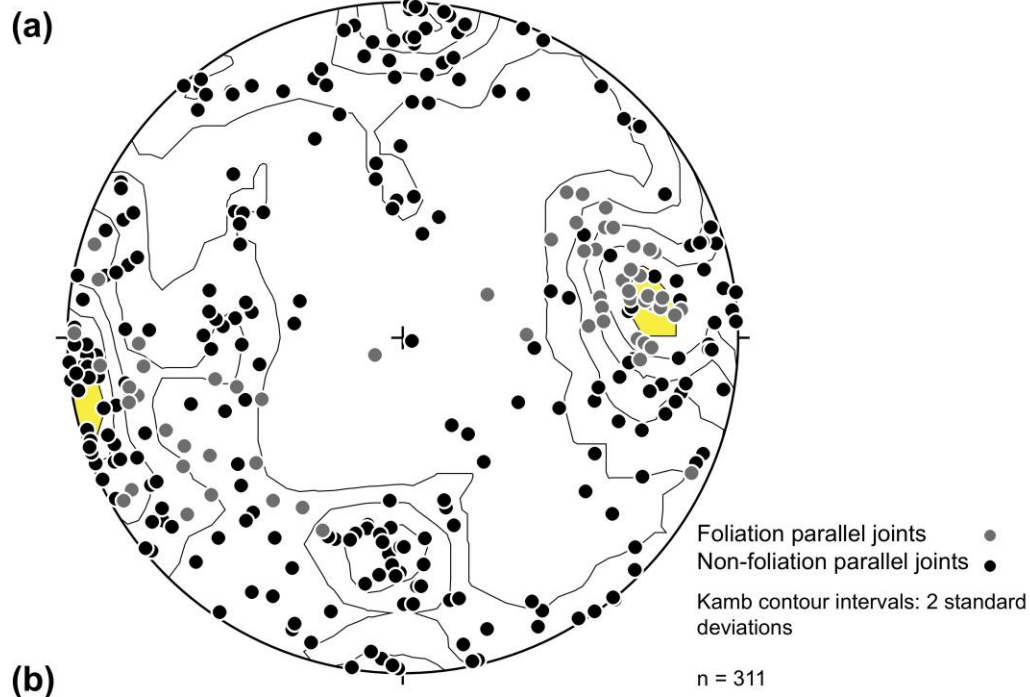
861 Figure 3



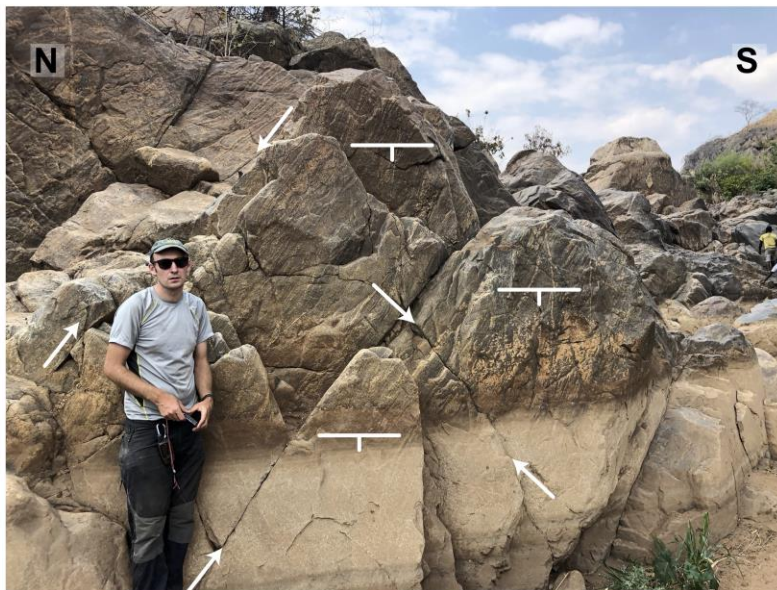
862
 863 Figure 3: Results of earthquake focal mechanism stress inversion for the Malawi Rift using
 864 Win-Tensor [Delvaux & Sperner, 2003] and the mechanisms listed in Table 1. Lower-
 865 hemisphere equal area stereoplot depicts selected nodal planes (black lines) with slip vectors
 866 (black arrows), the three principal stress axes (blue circles), maximum and minimum
 867 horizontal stress (S_{Hmax} and S_{Hmin}) trajectories (small green and large red arrows), S_{Hmax} and
 868 S_{Hmin} trajectories for individual focal mechanisms (black and white bars outside stereoplot),
 869 and kinematic axes for individual focal mechanisms (grey circle: p axis, triangle: b axis,
 870 square: t axis). Histogram represents distribution of misfit angles (ω), weighted arithmetically
 871 according to magnitude.

872

873 Figure 4



(b)



874

875 Figure 4: (a) Stereoplot showing poles to joint orientations that were also shown in Figure 2c.

876 Shaded contour interval indicates highest concentration of the N-S striking joints. The trend

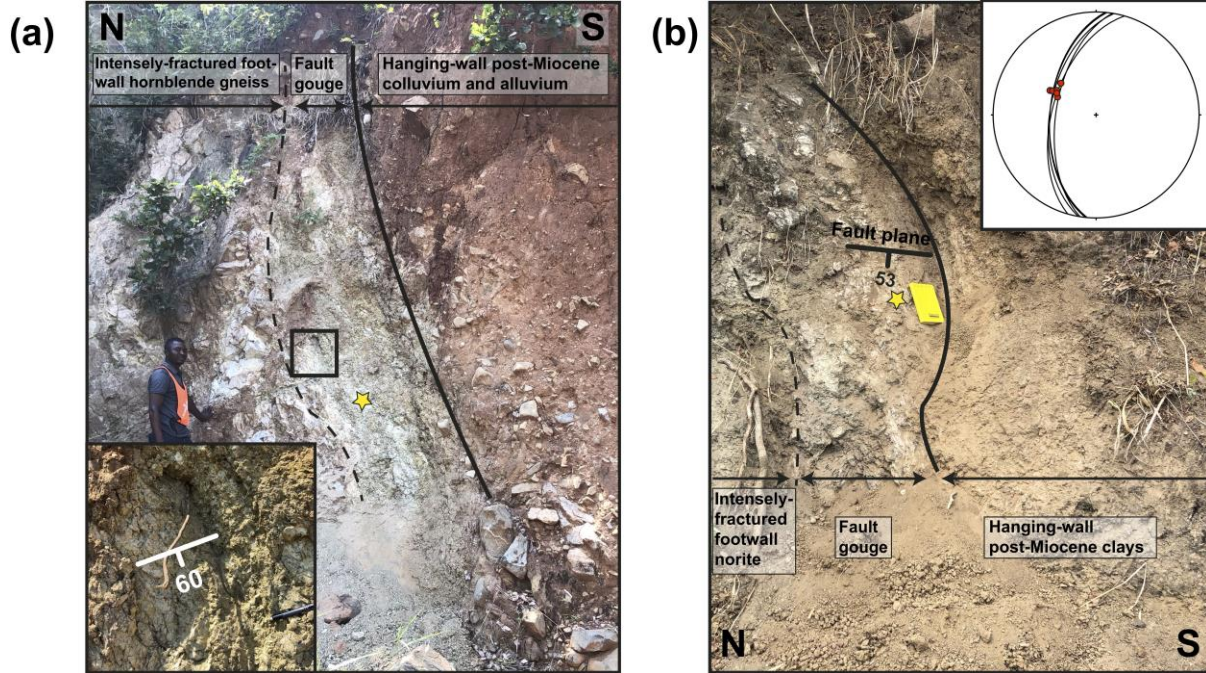
877 at the centre of this interval (082°) is used to infer the trend of the minimum principal stress

878 (σ_3) for Stress State 2. The range of this interval $\pm 7^\circ$. (b) Examples of joint sets in the Malawi

879 Rift. The joint set the facing the photo is a steeply dipping N-S set, which are mutually cross

880 cutting with an inclined E-W set.

881 Figure 5

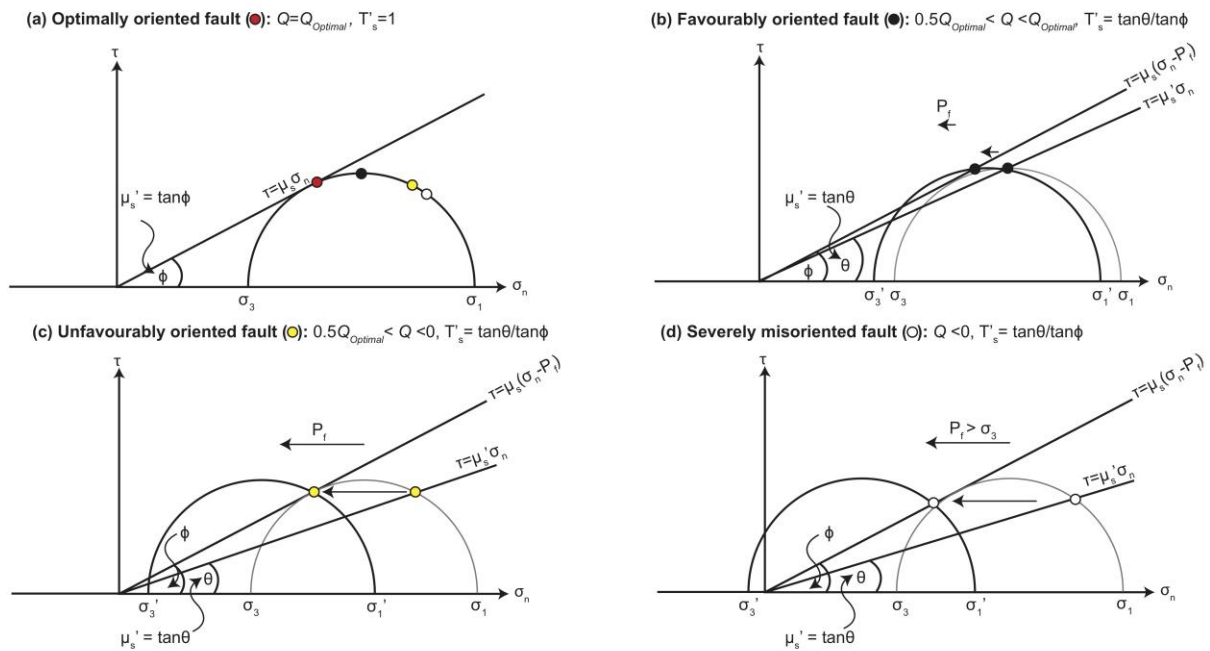


882

883 Figure 5: Examples of outcrops from (a) the Thyolo and (b) Chingale Step faults. Stars depict
 884 where ‘fault rock’ samples were taken from for these faults. Footwall and hanging-wall unit
 885 descriptions taken from *Habgood et al.*, [1973] and *Bloomfield*, [1965] respectively. Box in
 886 (a) highlights plane that was used to measure dip of Thyolo fault and is shown in the inset.
 887 Inset in (b) shows fault slickenside orientations [*Wedmore et al.*, in prep.]. Note, a dip of 57°
 888 was used for the Chingale Step fault reactivation analysis, based on the average dip measured
 889 over other sites (Figure 2a).

890

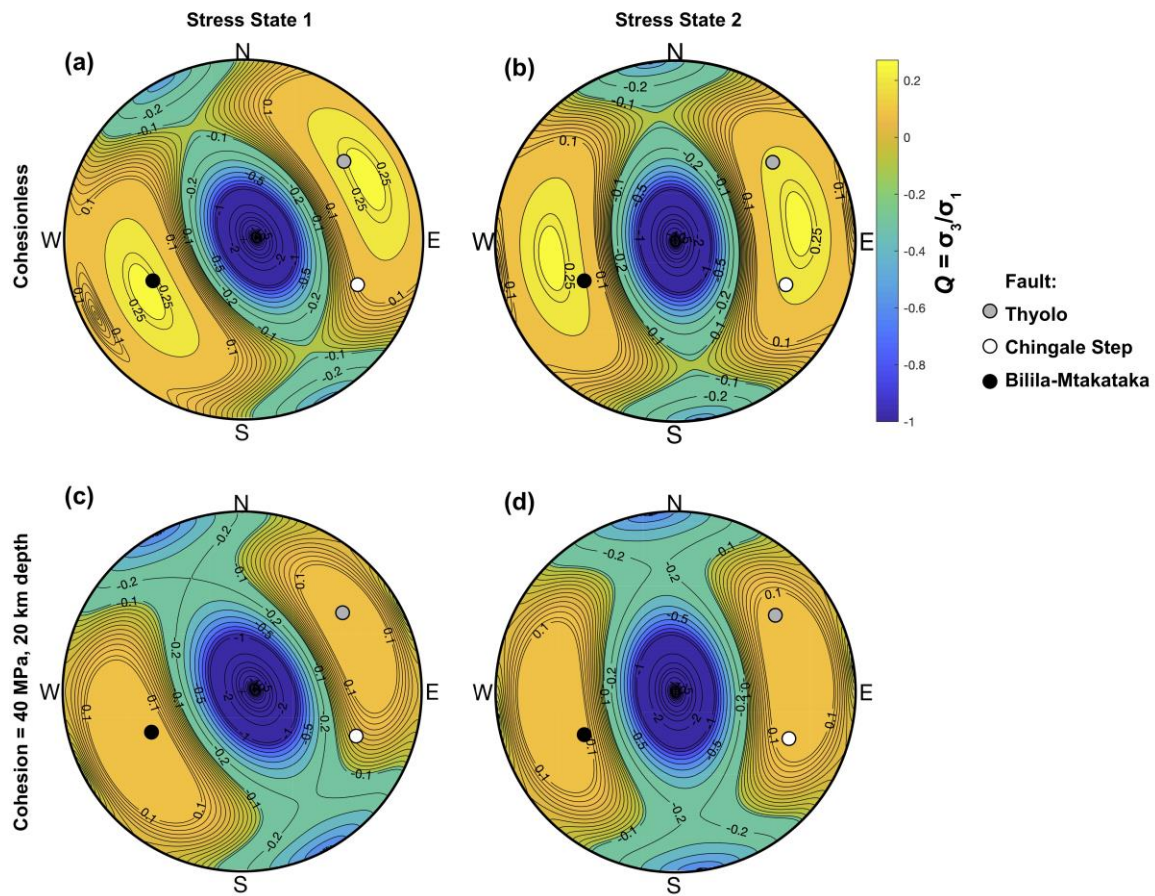
891 Figure 6



892
 893 Figure 6: Illustration in Mohr Space of different concepts for analysing fault reactivation. (a)
 894 The stress ratio ($Q = \sigma_3/\sigma_1$), normalized slip tendency (T'_s), and effective coefficient of friction
 895 (μ'_s) acting on an optimally-oriented cohesionless fault. In this case, $Q = Q_{Optimal}$, $T'_s = 1$, μ'_s
 896 is the same as the frictional strength of an optimally oriented fault ($\mu_s = \tan\phi$), and no fluid
 897 pressure (P_f) is required for reactivation. In addition, the orientation of three hypothetical
 898 faults is also depicted. The Q , T'_s , μ'_s , and P_f required for reactivation of these (b) favourably
 899 oriented, (c) unfavourably oriented, and (d) severely misoriented fault is then also shown. For
 900 clarity, this example is for a 2D reactivation analysis when the fault plane contains σ_2 .
 901 However, the principles are the same for a 3D analysis.

902

903 Figure 7

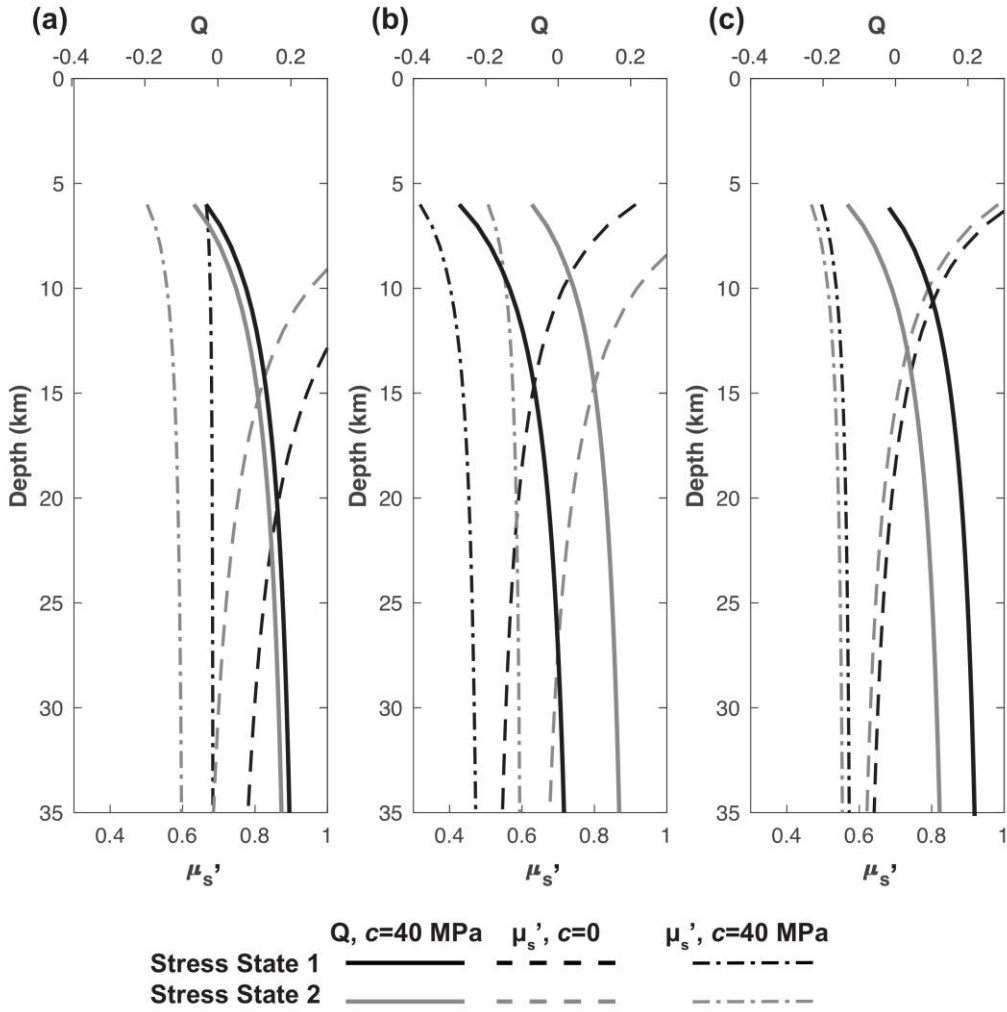


904

905 Figure 7: Stereoplots contoured by stress ratio ($Q=\sigma_3/\sigma_1$) required for fault reactivation in
 906 Stress States 1 and 2 [Leclère & Fabbri, 2013]. Both (a&b) cohesionless and (c&d) cohesive
 907 are considered. Results pertain to any depth for cohesionless faults and are calculated for a
 908 depth of 20 km for cohesive faults, assuming the density model for the rift outlined in Table
 909 S2. For all plots $\mu_s=0.7$ and $\Phi=0.33$. Poles to the fault orientations analyzed here are also
 910 shown.

911

912 Figure 8



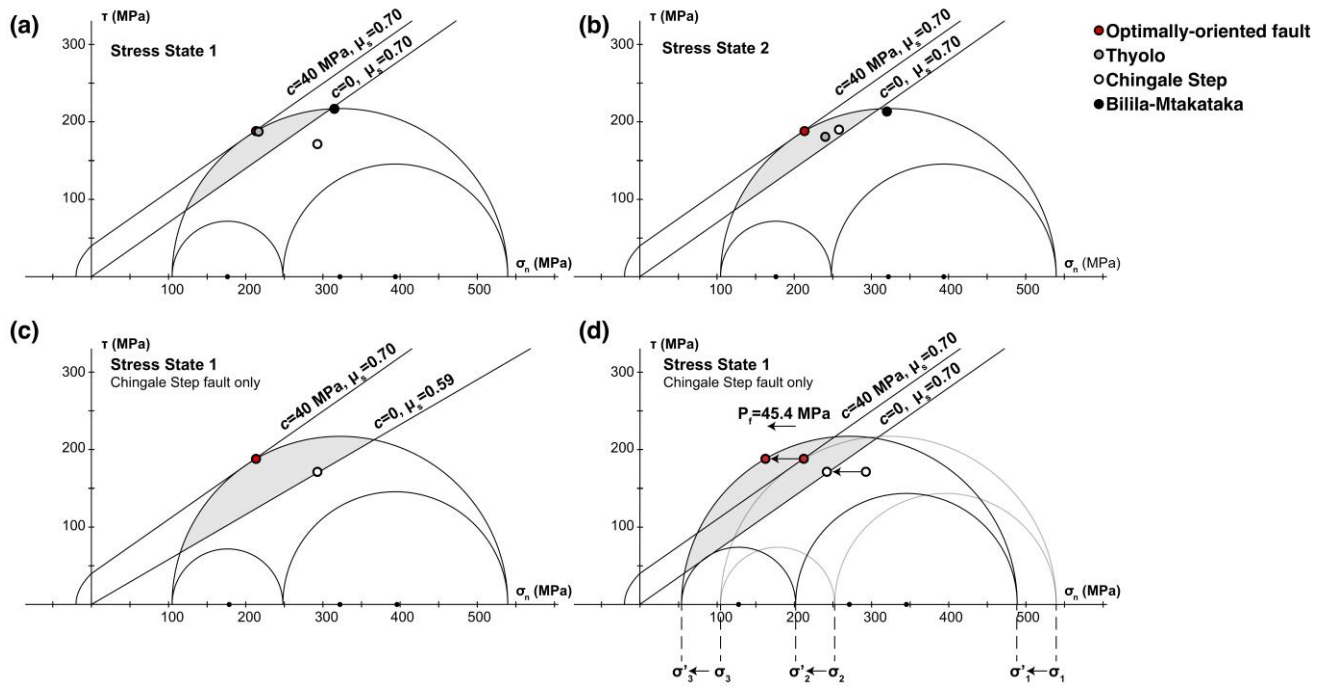
913

914 Figure 8: The stress ratio ($Q=\sigma_3/\sigma_1$) and effective coefficient of friction (μ_s') of (a) Thyolo,
 915 (b) Chingale Step, and (c) Bilila-Mtakataka fault for Stress States 1 and 2 between depths 6-
 916 35 km. For cohesionless faults, Q does not vary as a function of depth and so is not shown.

917 Only values where $\mu_s' < 1$ are plotted.

918

919 Figure 9

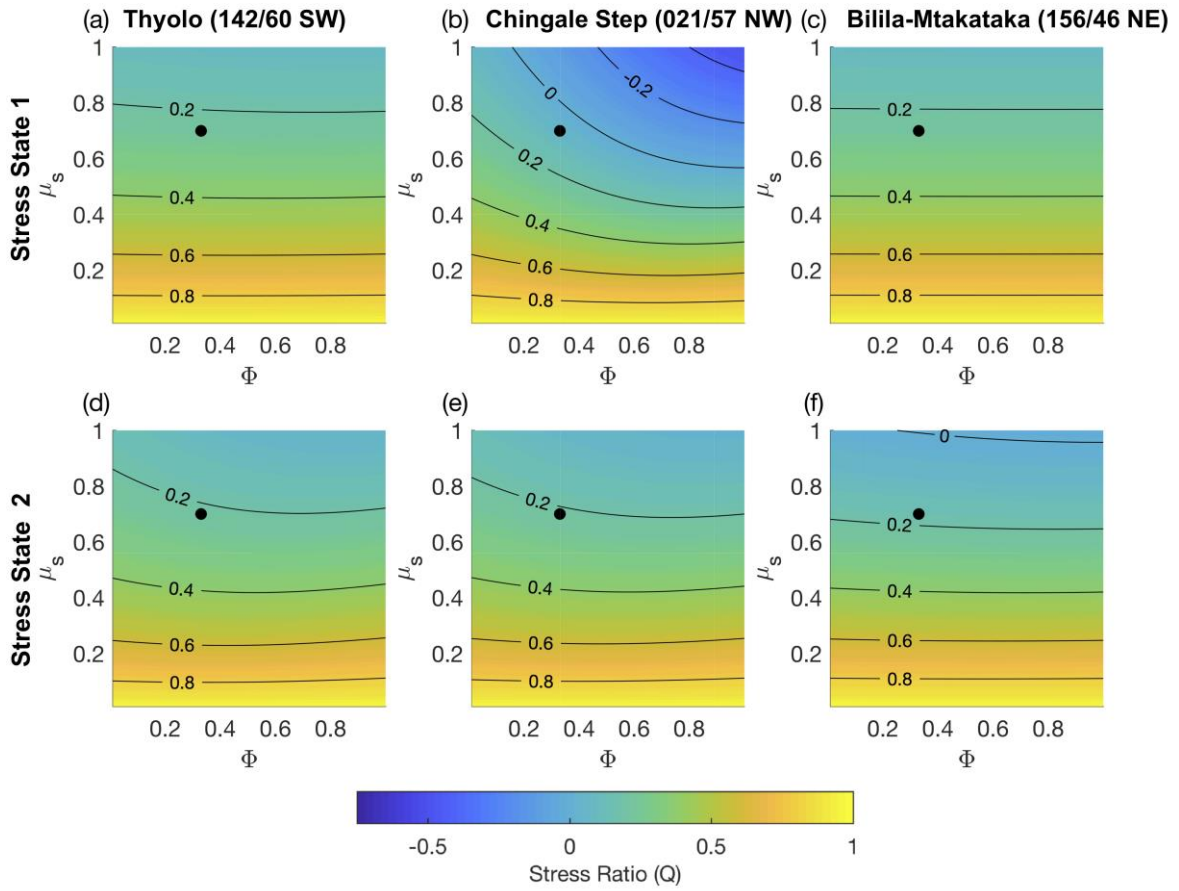


920

921 Figure 9: 3D Mohr Circle analysis for reactivation of faults in southern Malawi at 20 km
 922 depth. Shaded region in each plot depicts range of orientations where a cohesionless fault will
 923 reactivate. (a) Orientation of Thyolo, Chingale Step and Bilila-Mtakataka Fault in Stress
 924 States 1. Given the failure criteria assumed here, only the Thyolo and Bilila-Mtakataka
 925 fault will reactivate. (b) Same as (a) but for Stress State 2. The Thyolo and Chingale Step
 926 faults will reactivate in this stress state and reactivation of Bilila-Mtakataka requires a slight
 927 reduction in μ_s' to 0.67 (Table 3). Reactivation of cohesionless Chingale Step fault in Stress
 928 State 1 at 20 km depth requires that (c) $\mu_s'=0.59$ or that (d) $P_f'=45.4$ MPa (equivalent to
 929 $\lambda_v'=0.08$).

930

931 Figure 10



932

933 Figure 10: Contour plots for stress ratio ($Q=\sigma_3/\sigma_1$) needed for reactivation of a cohesionless
 934 fault in frictional strength-stress shape ratio ($\mu_s-\Phi$) space for the given fault orientations and
 935 Stress States 1 and 2. Black circle represents point where $\Phi=0.33$ and $\mu_s=0.70$, as is used in
 936 Figure 7. For similar analysis for cohesive fault, see Figure S8.

937

938

939 **List of tables**

940 Table 1

Date (yyyy/mm/dd)	M_w	Longitude	Latitude	Depth (km)	Catalogue	Strike	Dip	Rake	Rejected	Misfit (°)	Notes
1954/01/17	6.7	36.00	-16.5.0	20	DB2010	197	68	164	Y		
1966/05/06	5.1	34.60	-15.70	17	DB2010	001	51	-56		31	
1978/01/08	4.9	34.45	-11.76	15	DB2010	338	45	-90		0	
1989/03/09	5.5	34.47	-13.68	31	C2011	340	56	-99		2.6	Same as event 4 in DB2010
1989/03/10	6.1	34.49	-13.71	32	C2011	336	56	-92		1.2	Same as event 5 in DB2010
1989/09/05	5.4	34.46	-11.8	19.8	DB2010	063	52	149	Y		
1994/11/16	4.5	33.51	-9.42	7	C2011	301	64	-11	Y		Focal mechanism from gCMT
1995/07/22	4.9	34.84	-13.98	33	C2011	158	42	-105		7.3	
1995/09/30	4.7	34.40	-13.82	30	C2011	140	38	-75		2.4	
1996/08/30	4.5	34.10	-15.40	10	DB2010	071	27	-46		0.5	
1998/08/24	4.7	34.89	-13.77	44	C2011	163	37	-95		0.3	Same as event 7 in DB2010
1999/09/01	4.7	34.2	-10.10	10	DB2010	022	81	-144		3.7	
2000/01/04	4.8	36.10	-16.10	25	DB2010	352	66	-70		3.7	
2002/08/31	5.0	9.84	34.23	20	C2011	355	53	-126		28	Same as event 9 in DB2010
2004/03/14	4.8	34.35	-10.08	29	DB2010	017	52	-117		13.6	
2004/08/21	4.7	34.44	-10.60	12	DB2010	084	75	-17		4.1	
2009/12/06	5.7	-10.13	33.85	6	C2011	168	38	-91		1.2	
2009/12/09	5.8	-9.95	33.88	6	C2011	167	41	-70		27	
2009/12/11	4.9	-10.09	33.86	8	C2011	148	48	-96		4.4	Focal mechanism from gCMT

2009/12/12	5.5	-9.94	33.91	4	C2011	169	37	-95	0.4
2009/12/19	5.9	-10.11	33.82	5	C2011	149	46	-77	1
2018/03/08	5.5	35.427	-16.76	17	USGS	142	45	-94	6.4
2018/03/08	4.9	35.486	-16.83	10	USGS	330	54	-77	1.6

941 Table 1: Compilation of earthquake focal mechanisms for the Malawi Rift. Catalogue codes are: (1) DB2010, *Delvaux and Barth*, [2010] and
942 references therein, (2) C2011, *Craig et al.*, (2011) and references therein, (3) USGS, *U.S. Department of the Interior U.S. Geological Survey*,
943 [2018]. Focal mechanisms from C2011 are from waveform modelling unless otherwise stated. The reported nodal plane is the one favoured by
944 the stress inversion (i.e. the plane with the smallest misfit, the magnitude of which is also reported). We also indicate which mechanisms were
945 filtered during the stress inversion. Map of focal mechanisms is given in Figure 1.

946

947 Table 2

Fault	Sample	Quartz	Albite	Biotite	Muscovite	Actinolite	Kaolinite	Montmorillonite	Dolomite	Prehnite	Calcite
Thyolo	Country rock	43	40			14	3				
	Fault rock	81					8	5		6	
Chingale Step	Country rock	30	30	37			3				
	Fault rock	4						2	1		93
Bilila-Mtakataka	Country rock	11	52		8	26	3				
	Fault rock	74	16								10

948 Table 2: Quantitative XRD (as weight %) of samples collected from fault zones in the Malawi Rift. Results are normalized to 100% and so do
949 not include estimates of unidentified or amorphous material. XRD diffractograms are given in Figure S5.

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Fault	Fault orientation	Stress State	Stress Ratio (Q)		Slip tendency (T_s)	Normalized slip tendency (T'_s)	Effective coefficient of friction (μ_s')	
			$c=0$	$c=40$ MPa			$c=0$	$c=40$ MPa
Thyolo	142/60 SW	1	0.24	0.16	0.65	0.92	0.87	0.68
		2	0.22	0.14	0.61	0.87	0.75	0.59
Chingale Step	021/57 NW	1	0.07	-0.02	0.47	0.67	0.59	0.45
		2	0.21	0.13	0.60	0.86	0.74	0.58
Bilila-Mtakataka	156/46 NE	1	0.17	0.16	0.65	0.93	0.69	0.56
		2	0.24	0.08	0.57	0.81	0.67	0.54

952 Table 3: Results of fault reactivation analysis in terms of the stress ratio (Q) of each fault with respect to Stress States 1 and 2, slip tendency (T_s),
953 normalized slip tendency (T'_s), and effective frictional strength (μ_s') needed to reactivate them. T_s , T'_s , and Q where $c=0$ pertain to any depth. Q
954 where $c=40$ MPa and μ_s' are for a depth of 20 km, and assume a fault surrounded by intact rock where $\mu_{s-intact}=0.7$. See Figure 8 for how these
955 values vary with depth. All results to 2 decimal places.

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