The Coupling Cloud: A community database of megathrust kinematic coupling models

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Abstract

Kinematic coupling models inverted from geodetic data are widely used to evaluate how slip deficit is distributed along subduction megathrusts during the interseismic period, and are central to earthquake and tsunami hazard assessment. Yet, existing coupling models differ widely in methodology and inputs, lack common community standards, and are scattered across publications and repositories. Here, we introduce the "Coupling Cloud" (https://couplingcloud.ucsd.edu), an open, extensible, community-driven platform that curates, standardizes, documents, and disseminates more than 95 kinematic coupling models from 56 publications across 21 subduction margins. The platform provides interactive 2D and 3D plate-interface viewers to inspect coupling models together with associated information such as slab geometry, uncertainty estimates and metadata. All datasets can be downloaded directly in standardized formats: surface-projected coupling values as NetCDF, plate-interface dislocation geometries as VTU, and model metadata as YAML files. We demonstrate the advantages of centralized and standardized coupling data through a Cascadia subduction zone example, where synthesizing eight full-margin models reveals along-strike patterns that are not apparent when models are examined individually. Consolidating coupling models within a coherent, version-controlled framework enables systematic cross-margin comparison and FAIR-compliant data sharing, opening the door to more comprehensive assessment of megathrust mechanics.

Introduction

Community databases can accelerate Earth science research by standardizing how data products are archived and shared, enabling synthesis across models and systematic evaluation of methodological choices. Several initiatives illustrate the scientific value of open, standardized data infrastructures. For example, SubMachine compiles global seismic tomography models (Hosseini et al., 2018), the SubMap initiative assembles long-term subduction zone observations (https://submap.gm.umontpellier.fr/), and the Nevada Geodetic Laboratory provides processed GNSS time series and velocity fields (Blewitt et al., 2018). Similarly, the SRCMOD database unified finite-fault source inversion formats and metadata to aggregate hundreds of finite slip models (Mai & Thingbaijam, 2014), directly motivating community benchmarks such as the Source Inversion Validation exercises (SIV, Mai et al., 2016). The USGS finite-fault model archive provides another example of how openly accessible, consistently formatted datasets accelerate scientific discovery (Goldberg et al., 2022; Hayes, 2017; https://earthquake.usgs.gov/data/finitefault/). In contrast, despite the central role of coupling models in subduction zone science and hazard assessment, the geodetic megathrust coupling community has lacked a centralized, standardized infrastructure for archiving, comparing, and reusing published models in consistent, interoperable data formats.

Kinematic coupling models identify regions along subduction interfaces that accommodate little interseismic slip, commonly inferred as frictionally locked, amid regions that creep steadily or slip transiently during the interseismic period**.** These models are constructed from inversions of interseismic or inter-slow slip events (inter-SSE) surface displacements most commonly derived from GNSS (Dixon, 1991; Feigl et al., 1993) and InSAR (Bürgmann et al., 2000), but also incorporating leveling (Burgette et al., 2009; Jackson & Bilham, 1994), coral-based reconstructions (Chlieh et al., 2008; Tsang et al., 2015) and offshore geodetic measurements such

as GNSS-Acoustic techniques (DeSanto et al., 2025; Gagnon et al., 2005; Yokota et al., 2016). Such inversions commonly use Green's functions from forward models based on elastic dislocation theory in a half-space (Meade, 2007; Okada, 1985, 1992), or viscoelastic earthquake-cycle formulations (Itoh et al., 2021; Li et al., 2015, 2018; Pollitz, 1997) and the backslip formulation to infer slip deficit (Savage, 1983). The inverse problem is then solved with linear schemes (Tarantola, 2005; Tarantola & Valette, 1982) or Bayesian approaches that integrate priors with data to quantify posterior uncertainty (e.g., Fukuda & Johnson, 2008; Minson et al., 2013; Tomita et al., 2021; Yabuki & Matsu'ura, 1992). Expressing the inferred slip deficit rate relative to the long-term plate convergence rate yields a kinematic coupling model (Wang & Dixon, 2004) that describes a continuous spectrum of fault behavior, ranging from areas creeping at the long-term slip rate (coupling ≈ 0) to effectively fixed regions with no creep (coupling ≈ 1).

Because kinematic coupling models delineate regions where elastic strain accumulates and may be released in future megathrust earthquakes, they are an important tool for assessing seismic and tsunami hazard in subduction zones (e.g., Giardini et al., 1999; Glehman et al., 2025; Ramos et al., 2021; Small & Melgar, 2021;Wang et al., 2015; Wang, 2011; Widiyantoro et al., 2020). However, despite their scientific value, these models face methodological challenges. Differences in assumed slab geometry and viscoelastic earth structure (Laske et al., 2013; Lovery et al., 2025; Luo et al., 2025; Wang et al., 2021), the period studied, density and quality of geodetic observations, velocity plate model, and the imposed regularization applied during coupling inversion affect the resulting coupling distributions (Fukuda & Johnson, 2008; Ide, 2007; Minson et al., 2013). Moreover, kinematic coupling models have traditionally lacked a unified, FAIR-compliant (Findable, Accessible, Interoperable, Reusable; Wilkinson et al., 2016) data format and are often scattered across publications in forms that are difficult to extract, evaluate, or systematically compare, limiting reproducibility and efforts to assess how modeling assumptions affect coupling estimates.

Here, we present the Coupling Cloud (https://couplingcloud.ucsd.edu, hereafter abbreviated to CC), an open online platform that aggregates a growing collection of published kinematic coupling models from subduction zones worldwide. The CC provides an intuitive interface to explore, visualize, and download these version controlled models, featuring a 2D map viewer for surface-projected coupling values and a 3D viewer that displays coupling on the underlying slab geometry. By centralizing and unifying these datasets and providing both 2D and 3D visualization tools within a single platform, the CC facilitates comparative analysis, strengthens reproducibility, and broadens community access to essential megathrust earthquake science resources. We demonstrate the value of this unified framework with a Cascadia case study, where along-strike patterns emerging from averaged models are not apparent when models are examined individually.

Data selection

As of January 12, 2026 the CC database comprises 96 kinematic coupling datasets compiled from 55 publications covering 21 subduction zones worldwide, for a total of 219 spatial data products. These include (in alphabetical order) two models in Alaska and the Aleutians (Drooff & Freymueller, 2021; Shanshan Li & Freymueller, 2018), two in the Caribbean (van Rijsingen et al., 2021), eleven in Cascadia (Li et al., 2018; Lindsey et al., 2021; Materna et al., 2023; Michel et al., 2019; Pollitz & Evans, 2017; Pollitz, 2025; Schmalzle et al., 2014; Sherrill et al., 2024), eight in

Chile (Jara et al., 2024; Jolivet et al., 2020; Klein et al., 2018; Li et al., 2015; Métois et al., 2012, 2013, 2016), four in Costa Rica (Feng et al., 2012; Perry et al., 2025; Xue et al., 2015), two in Ecuador-Colombia (Chlieh et al., 2021; Gombert et al., 2018), one in Guatemala (Ellis et al., 2019), six in Hikurangi (Maubant et al., 2023; Michel et al., 2025; Wallace et al., 2012, three in Himalayas (Dal Zilio et al., 2020; Panda & Lindsey, 2024; Stevens & Avouac, 2015), one in Indo-Burma (Lindsey et al., 2023), nineteen in the Japan Trench (Abe & Yoshioka, 2022; Itoh et al., 2021; Lindsey et al., 2021; Loveless & Meade, 2016), two in Java (Hanifa et al., 2014; Widiyantoro et al., 2020), four in Kamchatka (Bürgmann et al., 2005), two in Manila (Hsu et al., 2016), two in Makran (Cheng et al., 2024), six in Mexico (Cosenza-Muralles et al., 2022; Cruz-Atienza et al., 2025; Louise Maubant et al., 2022; Radiguet et al., 2016; Rousset et al., 2016), nine in Nankai (Liu et al., 2010; Loveless & Meade, 2016; Nishimura et al., 2018; Noda et al., 2018; Plata-Martinez et al., 2024; Sherrill et al., 2024; Yokota et al., 2016), ten in Peru (Jara et al., 2024; Lovery et al., 2024; Villegas-Lanza et al., 2016), one in Ryukyu (Kano et al., 2021), three in the Sagami trough (Loveless & Meade, 2016; Nishimura et al., 2018), and one in Sumatra (Chlieh et al., 2008). While the Coupling Cloud provides standardized access to these datasets, users are expected to cite the original publications associated with each model when using the data.

Data standardization and unified representation

Published coupling models vary widely in format and metadata, reflecting the diversity of data coverage, methods, and conventions used across studies and time. To standardize access and promote FAIR use (Wilkinson et al., 2016), we map each model onto a uniform latitude–longitude grid and store it as a NetCDF file. (Rew & Davis, 1990). When gridded outputs are not provided, interpolation is applied using a scheme chosen to match the representations in the original publications. Every file contains latitude, longitude, the coupling values, and additional optional parameters, such as standard deviation, interface depth, and slip deficit. The NetCDF format is machine-readable and supports direct analyses and visualization using open-source packages such as Matplotlib (Hunter, 2007), GMT (Wessel et al., 2019), and Xarray (Hoyer & Hamman, 2017). Because NetCDF files do not inherently preserve the original fault-dislocation geometry used to invert the geodetic observations, we reformat all available model dislocation geometries as VTU PolyData files (Schroeder et al., 1998). VTU is a widely adopted, self-describing format for unstructured meshes that natively supports complex 3D slab geometries and mixed element types, making it well suited for downstream use in numerical modeling workflows. This standardized format allows for direct visualization and processing using open-source tools such as ParaView (Ahrens et al., 2005), PyVista (Sullivan & Kaszynski, 2019), and Meshio (Schlömer, 2022) and preserves node coordinates, mesh connectivity, and associated attributes such as coupling values on both node and element levels. Together, these machine-readable formats remove the need to parse ASCII text files and allow users to work directly with the models using the tools listed above. They allow for quantitative operations, e.g., clipping by depth, computing isosurfaces, resampling to regular grids, decimation, and provide efficient binary input/output (I/O) with compression for large models. Both the regular-grid NetCDF products and the unstructured VTU meshes integrate with standard parallel analysis and visualization tools used in high-performance computing (HPC) workflows, enabling future scalable processing of large coupling model ensembles.

Beyond the spatial formats, we collect metadata on each study's modeling choices and assumptions to provide context for every hosted coupling model. Each dataset includes metadata

detailing the source publication DOI, allowing users to readily identify and cite the original studies, as well as a short description, region, and model type. The latter distinguishes between interseismic coupling models that represent time-averaged strain accumulation between earthquakes, inter-SSE models estimated during periods between slow-slip events, and kinematic block-model formulations that infer coupling from relative motions between tectonic blocks. Additional optional metadata includes the quantity and type of geodetic observations, the forward model formulation, and the inversion framework, including parameters such as the regularization type and associated weights (see Table 1 for a list of recommended metadata). These metadata are stored both within the NetCDF file and in an accompanying YAML file (Ben-Kiki et al., 2009), whose hierarchical structure separates observational, forward-model, and inversion information into human- and machine-readable records of model parameters. Lastly, when available, we include the original velocity fields and associated uncertainties in ASCII format as part of the model dataset. All CC data products, including NetCDF coupling values, VTU geometries, YAML metadata, and geodetic observations freely accessible through the CC interface as well as an example Jupyter notebook that demonstrates data access, metadata parsing, and visualization.

Platform architecture

The CC platform operates on a virtual machine within an eight-node Proxmox virtualization cluster hosted at the Scripps Institution of Oceanography, University of California San Diego. The system is configured with two virtual CPUs and 8 GB of RAM, running AlmaLinux 9.6, with Apache serving the web application and a FastAPI backend that handles all dynamic data requests (Fig. 1). The CC features two viewers: a 2D map viewer and a 3D geometry viewer. The 2D viewer displays surface-projected coupling values in a map interface and uses real-time server-side tiling via TiTiler, which converts NetCDF datasets into ``tiles'', small image segments, at multiple zoom levels that form the full map. These tiles are added as data layers in Leaflet, an open-source JavaScript library that renders the interactive basemap and enables users to explore and compare coupling fields in geographic context.

The 3D viewer provides an interactive environment for exploring coupling fields on the original plate-interface geometry. For models where the slab depth is available, we construct 3D representations of the interface by converting geographic coordinates (latitude, longitude, and depth) to Earth-Centered Earth-Fixed coordinates and exporting the resulting surfaces as VTK PolyData (.vtp) files (Schroeder et al., 1998). The Coupling Cloud 3D viewer loads these files directly in a browser using vtk.js (Fig. 1), an open-source JavaScript library for scientific visualization. For each subduction zone, the 3D viewer includes an Earth surface layer derived from GEBCO (Becker et al., 2009), providing geographic context as users rotate, zoom, and explore coupling models, the megathrust interface and the overlying topography.

The Coupling Cloud platform

The CC is a browser-based workspace for finding, visualizing in 2D and 3D, comparing, and downloading published kinematic coupling models across subduction zones. Using the 2D viewer, users can select a margin from the dataset panel, display one or several models for that region, and compare their spatial distributions by toggling through layers, and adjusting the colorbar, allowing

for examination of differences in the extent of coupling (Fig. 2A). In addition to the coupling fields, the CC documents supplementary fields such as uncertainty, which can become substantial where geodetic constraints are sparse, particularly in offshore regions (e.g., DeSanto et al., 2025; Lindsey et al., 2021; Nishimura et al., 2018). If provided, users can visualize these uncertainty data sets alongside the coupling maps (Fig. 2B) or download them, allowing assessment of the reliability of specific features and propagation of uncertainty into their own analyses.

Kinematic coupling models assume plate-interface geometries that range from planar surfaces to detailed 3D geometries, often based on the Slab2 model (Hayes et al., 2018), which may lead to variations in the inferred slip deficit distributions (Baba et al., 2002; Elston et al., 2025; Moreno et al., 2009). Within the CC 2D viewer, users can visualize and compare these geometric choices (Fig. 3C). In addition to the 2D viewer, the CC includes a 3D viewer for visualizing coupling on the 3D plate-interface geometry. Users can activate the 3D viewer by selecting a subduction zone and entering its 3D view, where all models with available geometry can be explored (Fig. 3). This tool provides an intuitive way to examine how geometric assumptions influence inferred coupling, complementing the 2D surface view and enhancing comparison across models that use different representations of the plate interface. Users can download dislocation geometries as VTU files for offline visualization and analyses.

Variability among kinematic coupling models arises from differences in inversion setup and observational constraints (Avouac, 2015; Kaneko et al., 2010). These differences include the geodetic measurement tools used, ranging from GNSS to InSAR, leveling, paleogeodetic, and offshore measurements, as well as the time periods over which interseismic velocities are estimated and how aseismic processes such as postseismic deformation and interseismic transients are treated (Bürgmann et al., 2000; Chlieh et al., 2008; Dixon, 1991; Gagnon et al., 2005; Jackson & Bilham, 1994). The inversion strategies themselves span regularized least-squares formulations to fully Bayesian frameworks that explicitly probe the posterior distribution. Differences in regularization schemes and associated weights, fault parameterization, a priori constraints (e.g., imposed creep at depth or fixed rake), the adopted kinematic block models and plate reference frame further influence the inferred coupling distribution (Lovery et al., 2024; Métois et al., 2016; Villegas-Lanza et al., 2016). To document these differences, we compiled detailed metadata for each model, which can be viewed directly on the platform (Fig. 4) or downloaded as YAML files.

Performance

To assess how well the server handles real-time tiling and how many users it can support simultaneously, we benchmark the number of concurrent tile requests the backend can sustain. We issue 3,000 requests for the same tile at progressively increasing concurrency levels and measure the time required for TiTiler to serve all requests. Under our current configuration, which includes two virtual CPUs and 8 GB of RAM, the total processing time decreases with increasing concurrency as CPU resources are utilized more fully, until it reaches a plateau where the server is operating at maximum capacity with sustaining a throughput of approximately 45 tile requests per second (Fig. 5). A typical 2D map viewer user interaction such as panning or zooming triggers approximately 15 new tile requests. In practice, tile caching means that retrieved tiles are stored locally in the user's browser. Thus, interactions within already viewed areas impose no additional load on the backend, and the CC 2D viewer can support many more users than implied by the baseline throughput for uncached tiles.

Even in cases where the dynamic server becomes slow to respond due to high user load, our benchmark demonstrates that the architecture is scalable at least for small numbers of CPUs. A single-CPU configuration delivers roughly half the throughput of the two-CPU setup (Fig. 5), indicating near-linear performance scaling in this test. This suggests that adding additional CPU resources can increase system capacity, with the caveat that allocating more virtual CPUs incur higher purchasing and maintenance costs. We highlight that the 3D viewer requires no backend computation, as all visualization is handled directly in the user's browser. The only server-side operation is transferring the VTK PolyData geometry files to the client, which are typically a few megabytes in size and load within seconds, depending on the user's internet connection.

A simple demonstration: along-strike segmentation of the Cascadia megathrust in kinematic coupling models

To illustrate the advantages of assembling many published coupling models within a single standardized framework, we present a case study for the Cascadia subduction zone. The CC currently aggregates eight full-margin Cascadia interseismic coupling models that include plate-interface depth information (Fig. 6A). These models span more than a decade of geodetic inversion studies and employ a range of elastic, viscoelastic, and boundary-based forward and inverse modeling approaches, including regularized, parameterized slip-rate deficit inversions (Schmalzle et al., 2014), regularized linear inversions (Michel et al., 2019), regularized inversions with physical constraints (Lindsey et al., 2021), Bayesian boundary inversions (Sherrill et al., 2024), and viscoelastic earthquake-cycle modeling (Pollitz & Evans, 2017; Pollitz, 2025). As a brief example of the utility of the CC platform, we view these models together (Fig. 6A1-8) to assess how their inferred coupling distributions relate to proposed along-strike segmentation of the Cascadia margin.

Whether a megathrust is segmented along strike controls rupture behavior and whether slip deficit is released in single margin-wide earthquakes or in a sequence of smaller events (e.g., Arnulf et al., 2022; Bassett et al., 2025; Melnick et al., 2009; Philibosian & Meltzner, 2020). Cascadia is a classic example where this question remains central (e.g., Melgar, 2021). Slow-slip and tremor catalogs reveal along-strike sections whose recurrence patterns and spatial distributions change abruptly along strike, implying structural or frictional contrasts (Bartlow, 2020; Brudzinski & Allen, 2007). High-resolution seismic imaging reveals sharp changes in megathrust morphology that align with these inferred segment boundaries (Carbotte et al., 2024). Together with along-strike patterns in turbidite records, these observations have been interpreted as evidence for Cascadia's along-strike segmentation, a pattern also suggested by early geodetic coupling estimates, with higher coupling in the northern and southern segments and lower coupling in the central portion (Goldfinger et al., 2012; Schmalzle et al., 2014).

We define three commonly used along-strike subsections of the Cascadia margin (e.g., Ramos et al., 2021): a northern segment (Vancouver Island to ~46°N), a central segment (~46–43.5°N), and a southern segment (~43.5°N to Mendocino Triple Junction). For each model, we extract Coupling Cloud–stored gridded coupling values shallower than 20 km, where along-strike variations in coupling are most commonly inferred (Fig. 6A1–2). These values correspond to spatially distinct fault patches within each along-strike segment. We describe how coupling values are distributed

across these spatial units by computing a probability density function (PDF) for each model and segment (e.g., Oryan & Gabriel, 2025) using a Gaussian kernel density estimator with bandwidth selected according to Scott's rule (Scott, 2015). We note that the PDF is used as a normalized representation of the density and relative weighting of coupling values across the coupling spectrum and not as a result of repeated measurements of a stochastic process). Finally, we express each segment's PDF as a deviation from the margin-wide PDF for the same model, so that positive deviations highlight coupling values that are overrepresented within a given segment relative to the margin as a whole.

Our analysis shows little sensitivity to kernel bandwidth and grid resolution, and reveals that the northern-segment PDF curve rises by up to ~1 in probability density above the margin-wide PDF at coupling values larger than 0.7. This indicates that high-coupling values are more concentrated in the northern segment than across the Cascadia subduction zone as a whole. Similarly, the central segment PDF remains below the margin-wide PDF for coupling values larger than ~0.8, indicating a lower density of high-coupling values relative to the margin-wide distribution (Fig. 6B2). In contrast, the southern segment does not show a higher concentration of high coupling values, and its PDF remains below the margin-wide distribution, reaching negative deviations of up to ~1 in probability density, similar in magnitude to the positive deviations observed in the northern segment (Fig. 6B3).

This example averages distributions across multiple coupling models spanning a range of inversion strategies and forward-modeling approaches. These models are not strictly independent,however, as they share geodetic datasets and related regularization strategies, and the ensemble spread should not be interpreted as a quantitative measure of uncertainty. Rather, the ensemble is intended to illustrate first-order behavior rather than provide a formal statistical treatment of inter-model variability and uncertainty. Even so, it shows that the concentration of coupling values in the northern and central segments aligns with previous interpretations of Cascadia's along-strike segmentation (Brudzinski & Allen, 2007; Carbotte et al., 2024; Goldfinger et al., 2012), whereas the southern segment does not exhibit a similarly coherent high-coupling pattern. This example also demonstrates how synthesizing ensemble models within the Coupling Cloud framework could help distinguish features that persist across modeling approaches from those that may depend on individual methodological choices. We therefore urge users to use the associated metadata and uncertainty information when comparing models and, most importantly, to consult the original publications describing each model, where the underlying assumptions and methodological choices are fully documented**.**

Current and future roles of the Coupling Cloud platform

The CC is designed with long-term sustainability in mind, hosted at Scripps / UC San Diego's institutional infrastructure with redundant backups and grounded in stable, widely supported data formats and libraries, ensuring continued accessibility and minimal maintenance. Our goal is for the CC to serve as a long-term community-driven global repository for kinematic coupling models, an up-to-date archive that the community can rely on for synthesis, comparison, and reproducibility. We also envision the CC to form a valuable teaching resource, offering standardized datasets for training the next generation of geodesists and subduction zone scientists, as well as providing an easy entry point for researchers new to the field. In addition, the platform

is extensible and supports user-driven uploads, allowing researchers to easily contribute new coupling models, metadata, and geometries directly. We invite all authors preparing new or forthcoming coupling models to upload their datasets to the CC so that the community can benefit from timely, open, and standardized access to the latest coupling models.

In addition, we hope that the unified file formats adopted here, NetCDF for surface-projected coupling fields, VTU (VTK PolyData) for plate-interface dislocation geometries, and YAML for FAIR-compliant metadata, will help providing a working standard for the community. By encouraging authors to express new coupling models directly in these formats, we aim to streamline data exchange and improve reproducibility across tools and research groups. At the same time, if the community converges on alternative standards, the CC framework can readily adopt them through simple import workflows, ensuring continued support for whichever formats best serve the megathrust research community.

Looking ahead, we see the Coupling Cloud not only as a repository of coupling models but as an evolving platform designed to reduce methodological variability and to bridge our understanding of how slip is accumulated and released in subduction zones (e.g., Wang et al., 2012). One promising direction is to host community validated Green's functions for subduction margins (e.g., Hori et al., 2021), providing a consistent set of forward-modeling kernels that removes a major source of variability among existing coupling models (Li et al., 2015; Lovery et al., 2025; Wang et al., 2021). A near-term direction for future developments is to link coupling models more directly to the geodetic observations used in the underlying inversions. Although users can already download the coupling-model associated observational datasets, if available, future versions of the CC may place greater emphasis on graphical representation, e.g., allowing GNSS velocities and time series, InSAR displacement fields, and offshore GNSS-Acoustic measurements to be viewed alongside coupling fields.

Finally, seamless integration of the CC interseismic coupling archive with the SRCMOD coseismic slip repository (Mai & Thingbaijam, 2014) and the Slow Earthquake Database (Kano et al., 2018) would unify complementary perspectives on megathrust behavior. Realizing this vision would require transforming the text-based FSP (Mai, Shearer, et al., 2016) and CSV formats used by SRCMOD and Slow Earthquake Databases into the VTU and NetCDF formats adopted by the Coupling Cloud, harmonizing metadata structures across both archives, and establishing an interface that links ruptures and slow slip events to corresponding interseismic coupling models. With such integration, users could examine coseismic and slow earthquake slip distributions alongside interseismic coupling fields, offering a unified perspective on strain accumulation and release across the earthquake cycle.

Conclusions

We have developed the Coupling Cloud, a unified and FAIR-compliant platform for standardizing, distributing, visualizing, and comparing kinematic geodetic coupling models across global subduction zones. The CC currently hosts 97 coupling models from 56 publications covering 21 subduction margins, each standardized into common file formats with preserved plate-interface geometries and complete metadata. By providing interactive 2D and 3D visualization tools and unified formats, the platform aims to remove long-standing barriers to reproducibility and to

enable more transparent comparison among models constructed with differing data sets and methodologies, while associated metadata enables users to consult the original publications for methodological details. As the Coupling Cloud grows through community contributions and future integration of observational datasets and models, it is well positioned to serve as a long-lived resource for advancing understanding of megathrust deformation and seismic hazard.

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Parameter	Description
Model type	Interseismic/Inter-SSE/Block model or a combination of these.
Inversion type	Method of inversion used (e.g. Tikhonov regularization, Bayesian, stochastic Bayesian, least-squares).
Forward model formulation	Earth model used to compute surface displacement, such as a uniform elastic half-space, layered elastic structure, or a viscoelastic rheology.
Type of dislocation	Geometry of the dislocation elements (triangular, rectangular, or piecewise-linear triangular).
Number of dislocations	Total number of dislocation elements used in the forward model.
Degrees of freedom	Total number of parameters solved for in the inversion.
Type of Observations	Type(s) of geodetic observations used (e.g., Campaign GNSS, permanent GNSS, InSAR, leveling, coral etc.).
Observation Components	East/North/Up (or E/N/U)
Number of sites	Number of sites (or pixels in case of InSAR) used in the inversion.
Number of observations	Total number of individual observation components (e.g., if one site uses North/East components and another uses Up/Down, the total is 3).
Reference frame	Global geodetic reference frame (e.g., ITRF2014, ITRF2008).
Plate-fixed frame	Tectonic or plate-relative reference frame used to interpret interseismic deformation (e.g., Australian plate) including when possible.
Earliest data used	Start date of the geodetic observations incorporated in the inversion (format: YYYY or YYYY-MM or YYYY-MM-DD).
Latest data used	End date of the geodetic observations incorporated in the inversion (format: YYYY or YYYY-MM or YYYY-MM-DD).
Regularization type	Form of regularization applied during the inversion (e.g., Laplacian smoothing, Tikhonov regularization. etc.).
Smoothing weight	Value of the regularization weights used in the inversion.
Couple values computed	Indicates whether coupling was computed at dislocation nodes or over full dislocation patches.

Poisson ratio	Value of the Poisson's ratio assumed if a single layer model is used.
Number of layers	Number of layers used in the model, if applicable.
Convergence model	Relative plate velocity model (required for normalization of slip deficit to obtain coupling)
Other kinematic constraints	A priori assumptions about slip deficit rate (e.g., rake direction etc).

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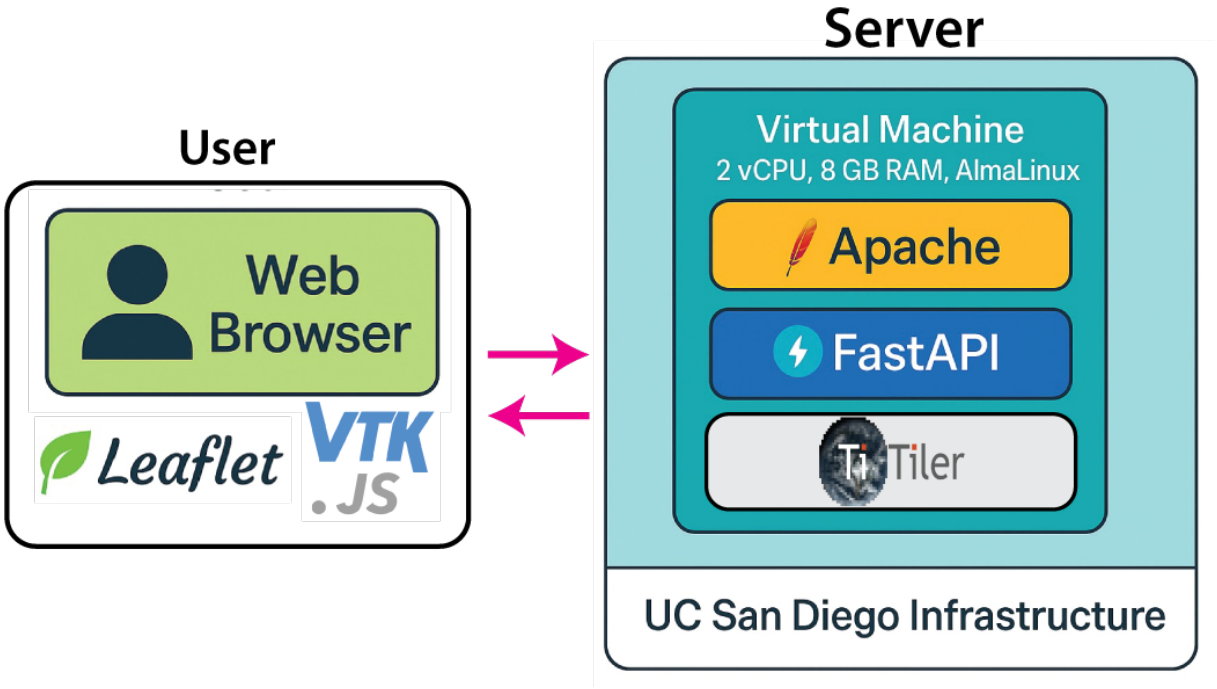
580 Table 1. Recommended metadata fields for coupling models.

581 ## Figure captions

582 **Figure 1 - CC platform architecture describing the server and user sides.**



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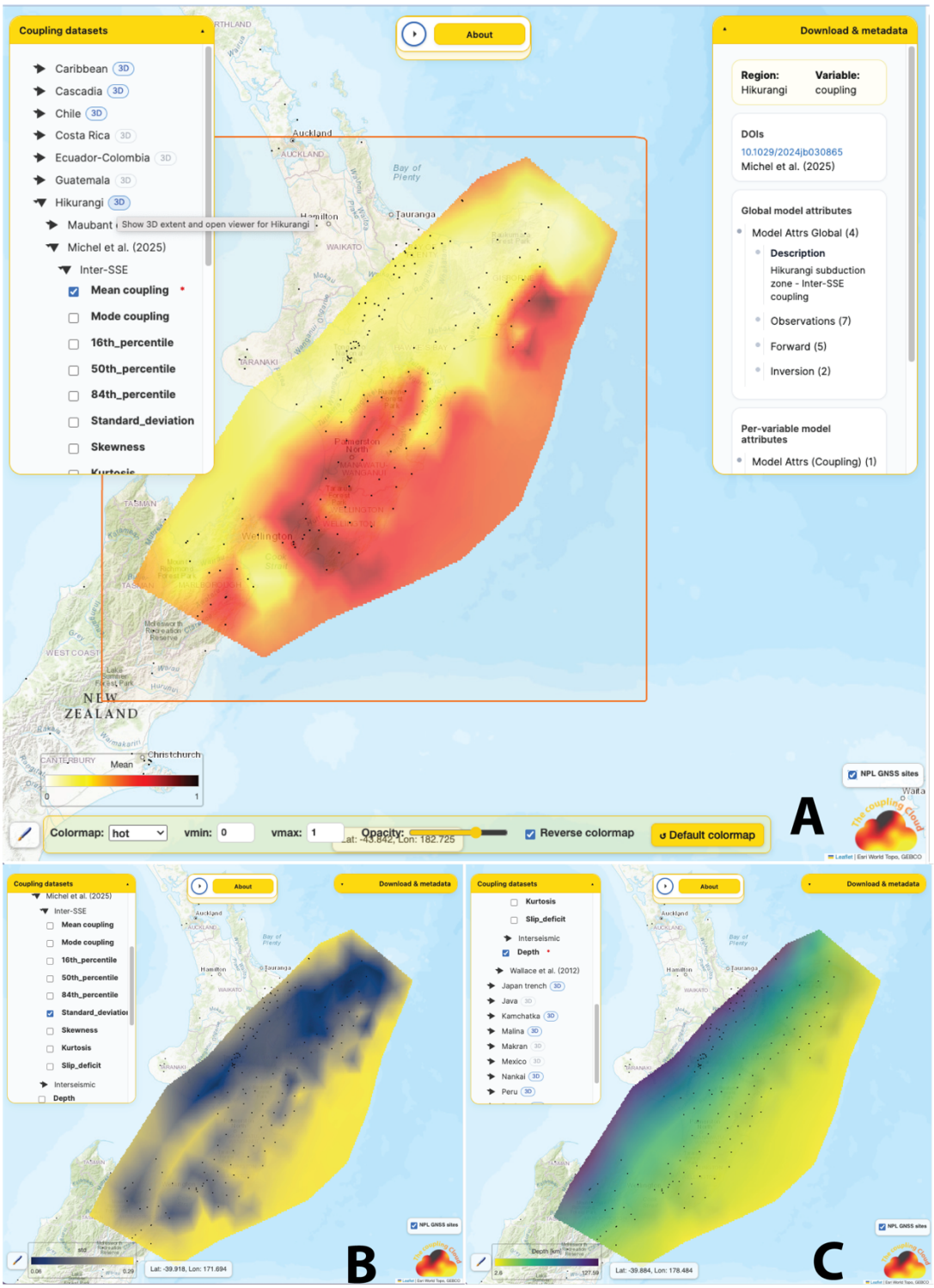

Figure 2. Coupling Cloud 2D viewer overview. The 2D viewer provides an interactive map-based interface for exploring kinematic coupling models and their associated metadata. Users can select models, adjust visualization settings, and switch seamlessly between the 2D and 3D viewers. A. The upper-left panel shows the dataset selector, which allows users to choose coupling models to display in the 2D map viewer. The 3D button switches to the 3D viewer, with the red polygon

indicating the region covered by the 3D viewer. The lower-left panel contains the brush controls used to configure colormap settings. The upper-right panel displays the metadata associated with the selected coupling model, and a link to download the dataset. The “About” panel contains the full reference list and additional platform information. Black dots indicate the position of GNSS stations associated with time series in the Nevada Geodetic Laboratory (NGL). Examples showing the selection of supplementary fields, including standard deviation and interface depth, for the same coupling model in Hikurangi (Michel et al., 2025).

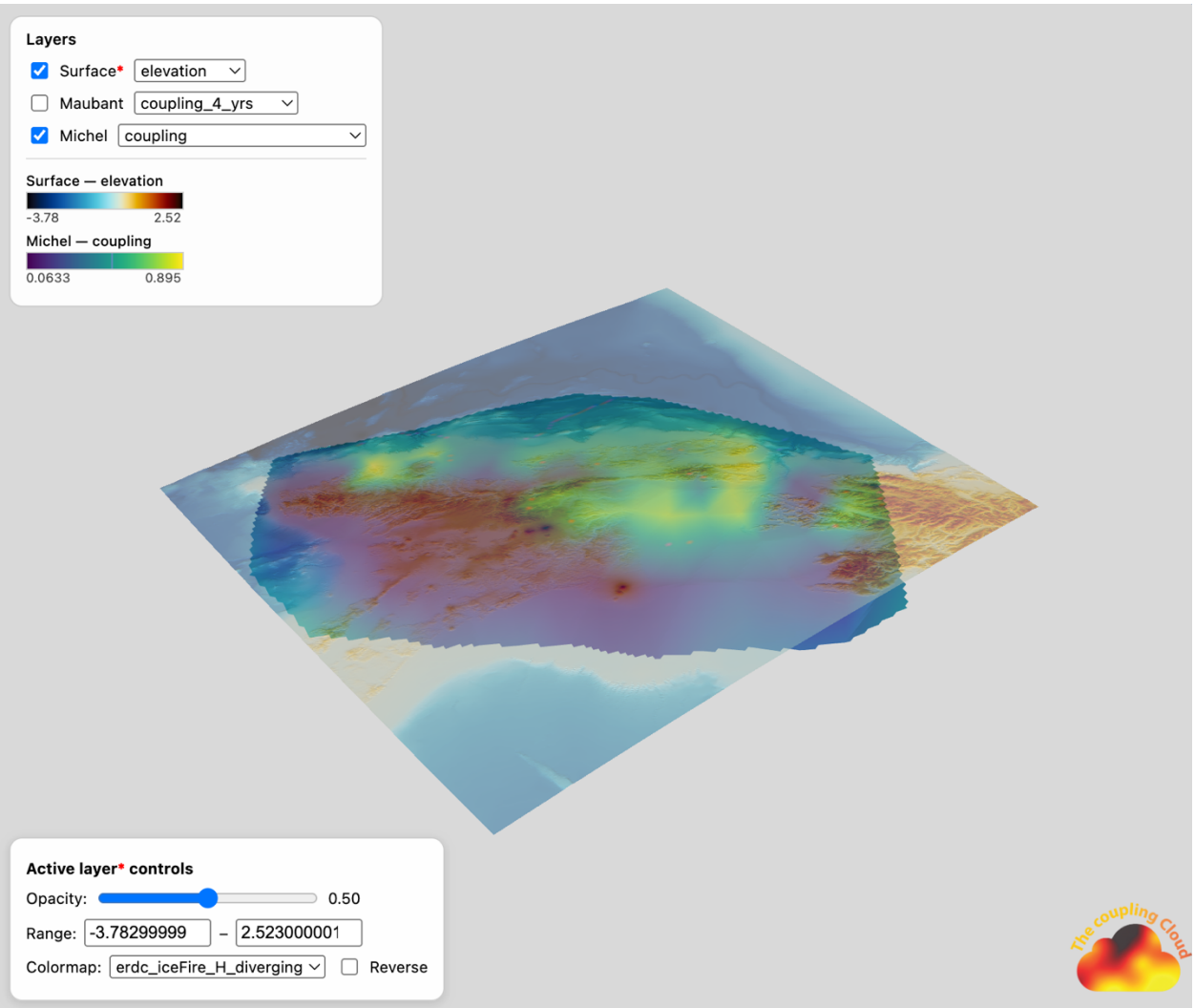

Figure 3 - Coupling Cloud 3D viewer overview. The 3D viewer enables interactive exploration of coupling models on the actual plate-interface geometry used in each inversion. It displays the megathrust surface in Earth-centered coordinates and overlays Earth-surface layer that provides geographic context. Users can select which geometric or coupling layers to display and customize their colormaps and opacity settings through the *Layers* and *Active Layers* control panels. The example shown here is from the Hikurangi subduction zone, illustrating the coupling field for the same model displayed in Fig 2 with the horizontal extent of the surface layer matching the red polygon shown in Fig. 2A.

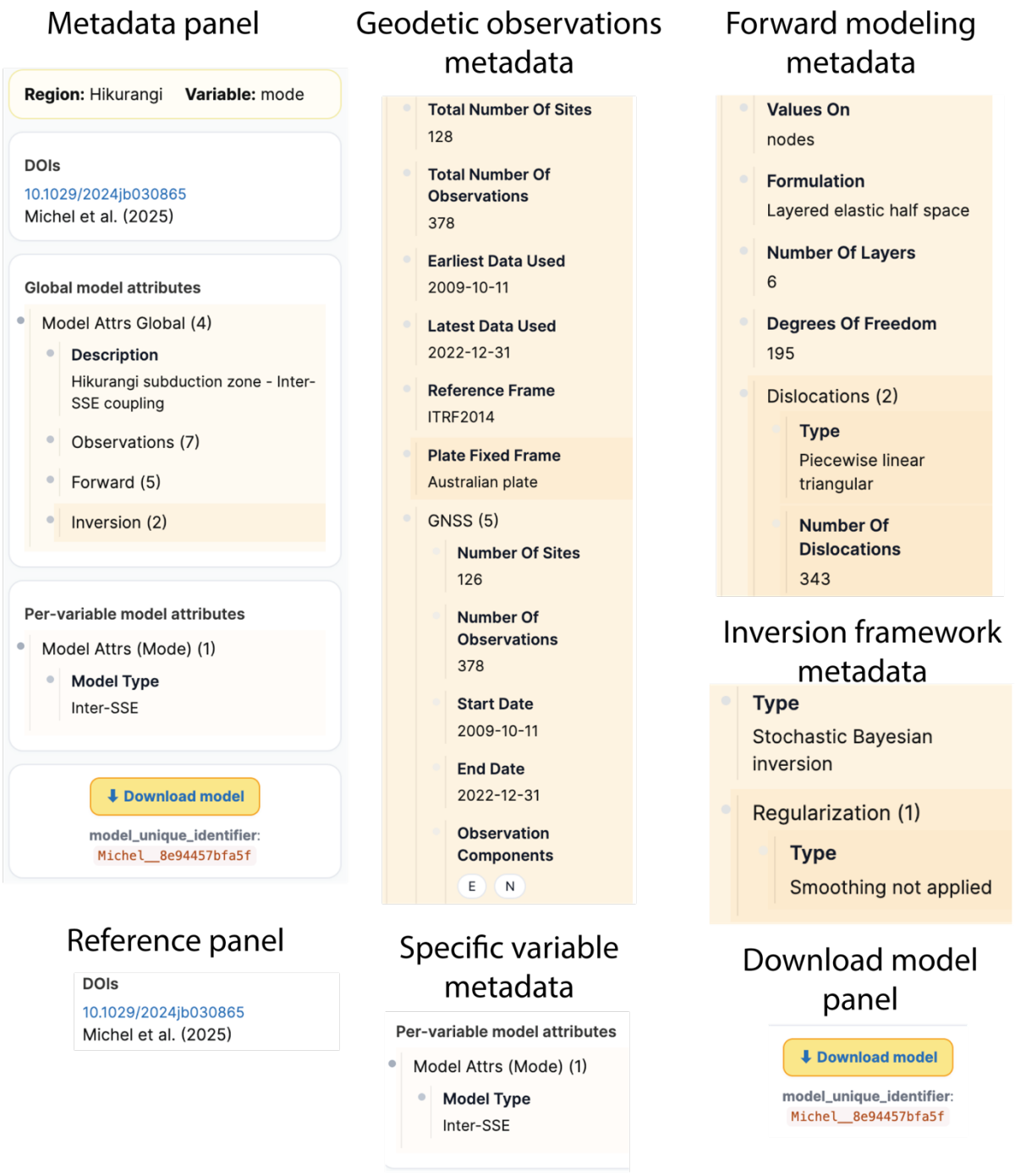

Figure 4. Example of the metadata interface in the Coupling Cloud platform. The metadata panel provides a detailed hierarchical summary of each coupling model, including DOIs, global attributes, per-variable attributes, observational constraints, forward-model settings, and inversion parameters. Shown here is the complete metadata for the Hikurangi coupling model of Michel et al. (2025), organized into its main components: the reference, observations, forward model, inversion, per-variable metadata, and download.

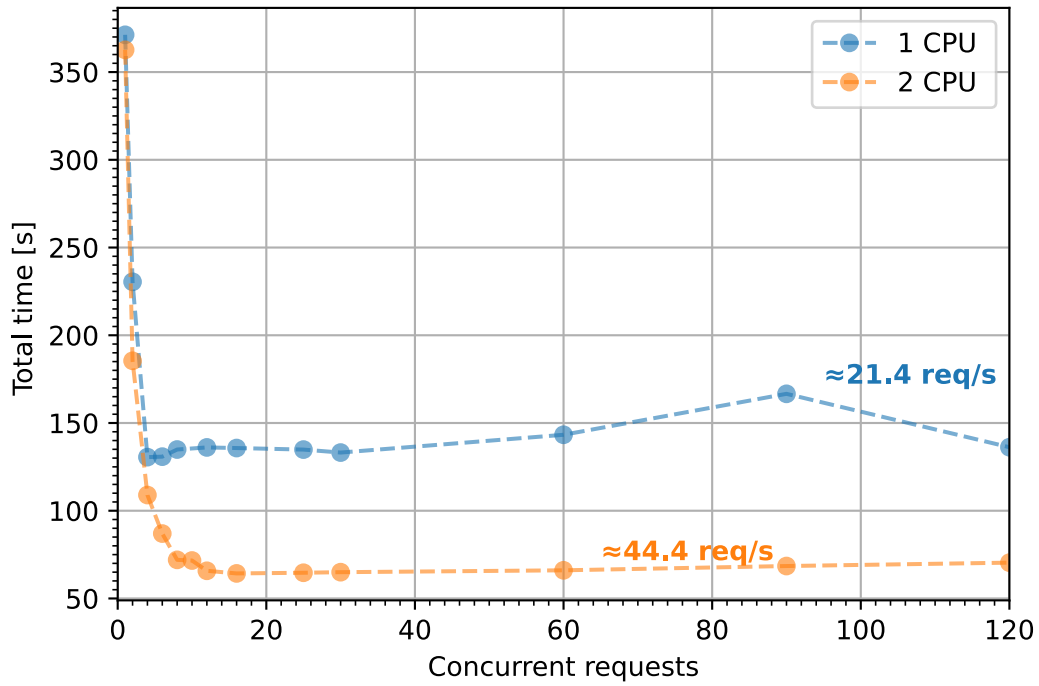

Figure 5. Coupling Cloud backend performance benchmark showing response times for increasing levels of concurrent tile requests. Points show the total time required to process 3,000 HTTP tile requests under different CPU configurations and concurrency levels.

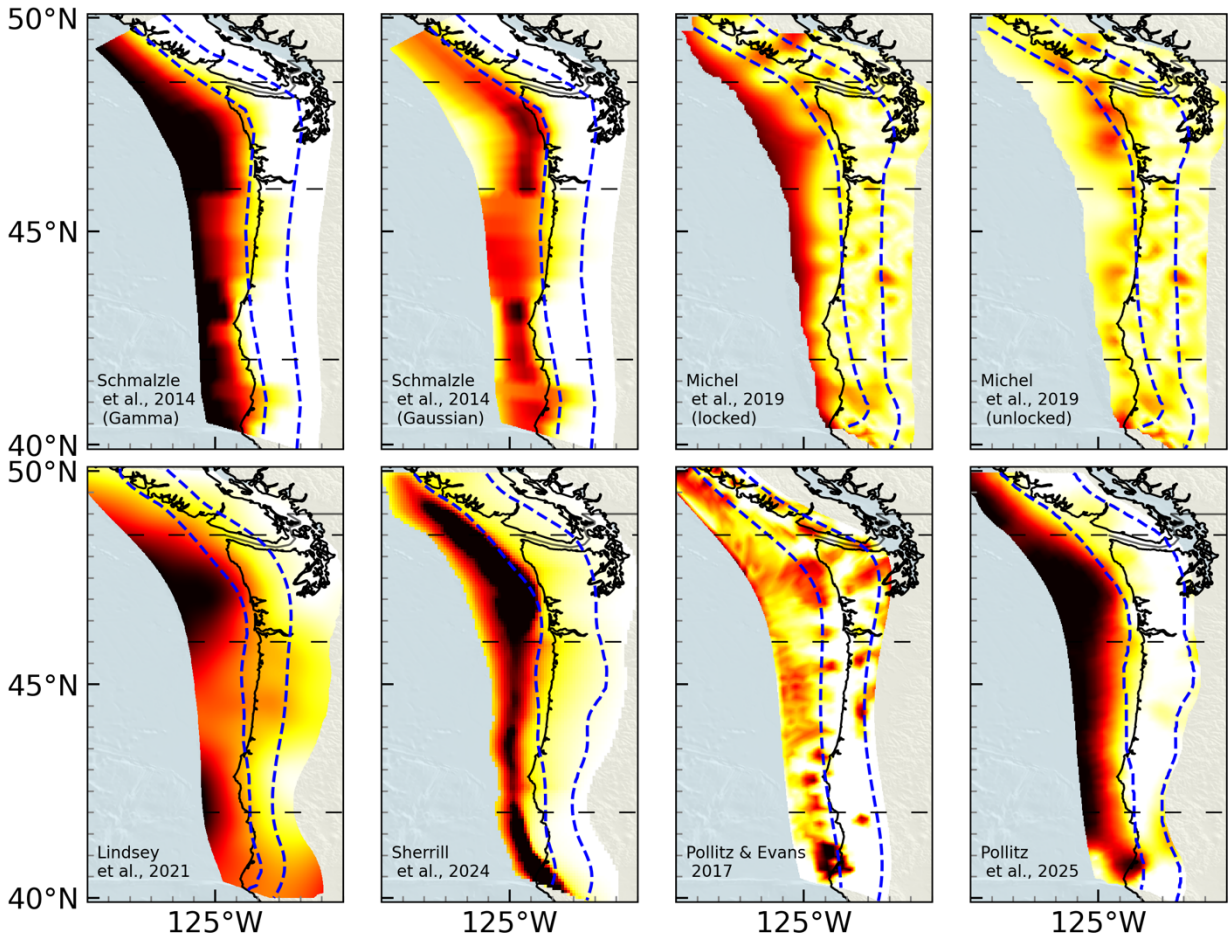

Figure 6. Cascadia case study. A - Eight Cascadia wide interseismic coupling models with slab depth available on the CC platform (Lindsey et al., 2021; Michel et al., 2019; Pollitz & Evans, 2017; Pollitz, 2025; Schmalzle et al., 2014; Sherrill et al., 2024), shown for interface depths shallower than 60 km. Contours indicate the megathrust interface depth used in each model. Horizontal dashed lines mark segments. B - Thin curves show the deviation of each model's segment-specific coupling probability density from that model's margin-wide probability density (ΔPDF). Positive ΔPDF values indicate coupling values that are more frequent within a given segment than across the margin. The shaded band denotes the 25th–75th percentile range of ΔPDF across the eight models.

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Data and code availability

All coupling datasets are freely available to download from couplingcloud.ucsd.edu. The code to run the coupling cloud can be found in Oryan, 2025 (https://zenodo.org/records/17821569).

Competing interests

All authors declare no competing interests.

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