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A detailed picture of Haiti's seismicity given by deep learning and template matching

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1 A detailed picture of Haiti's seismicity given 2 by deep learning and template matching

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ABSTRACT

Haiti regularly experiences destructive earthquakes, but seismic monitoring in the region has historically been limited. Recent deployments of citizen-hosted RaspberryShake seismometers and temporary seismic deployment following the 2021 M_w 7.2 earthquake provide new data to study the region's seismotectonics. However, high noise levels at many stations, in particular the RaspberryShake ones, limit detection, hence the fault imaging capability of these instruments. This study explores the use of a Deep Learning denoising algorithm, DeepDenoiser, to improve their seismic signal and earthquake detection capabilities. We find that DeepDenoiser raises the average signal-to-noise ratio of seismic signals by 4.7 dB and increases earthquake detections, but also raises false detections when using STA/LTA and a Deep Learning detection method. Template matching, however, when combined with DeepDenoiser, yields more true detections and fewer false detections than traditional band-pass filtered waveforms. This suggests that DeepDenoiser is better suited for retrospective studies than for real-time applications. Using DeepDenoiser and template matching, we compile a 2-year, high-resolution earthquake catalog for Haiti containing about 3 times the number of events of the original catalog. The improved catalog furthers our understanding of the 2021 M_w 7.2 earthquake sequence, highlighting particularly clearly the segmented nature of the aftershock distribution with a generally NE-dipping cluster in the east that coincides with the hypocenter and first reverse phase of the rupture, and a series of aftershocks farther west that coincide with the mostly strike-slip phase of the rupture. The improved catalog also reveals fluid-induced offshore seismic swarms in the Jérémie basin and active seismicity below Lake Enriquillo in the Dominican Republic. This catalog advances our knowledge of the region seismic activity and provides further opportunities to study the larger regional tectonic context.

7 INTRODUCTION

8 Our understanding of fault systems and earthquakes relies on regional efforts to monitor seismic activity and build com-
9 prehensive earthquake catalogs. Creating these catalogs involves multiple step workflows, including seismic data recording,
10 earthquake detection, phase picking, association, location, and magnitude estimation. Historically, these efforts have relied
11 on manual phase picking of seismic waveforms, but this becomes impractical with increasing data volumes. Energy-based
12 automatic detection methods, such as the short-term-average to long-term-average (STA/LTA) trigger (Allen, 1978), have
13 since been developed but provide coarser results, often generating false detections due to noise from non-tectonic impulsive
14 signals, requiring manual review. As a result, earthquake catalogs are known to be incomplete (Kagan, 2004; Peng et al.,
15 2006), particularly during time intervals of high background noise such as after a large earthquake.

16 Deep learning tools have emerged as a promising approach to monitor earthquake activity (Mousavi and Beroza, 2022)
17 and address noise levels that hinder detection (Zhu et al., 2019). Algorithms like ConvNet (Ross et al., 2018), PhaseNet (Zhu
18 and Beroza, 2019), or EQTransformer (Mousavi et al., 2020), can perform the critical step of phase picking – which is still rou-
19 tinely performed manually in most operational centers – with greater accuracy than traditional automatic algorithms (Allen,
20 1982). Recently proposed end-to-end algorithms can provide fast earthquake location and magnitude estimates directly from
21 the waveforms (van den Ende and Ampuero, 2020; Münchmeyer et al., 2021; Lara et al., 2023, 2025; Licciardi et al., 2022;
22 Hourcade et al., 2025), but still with lower accuracy than traditional methods (Kennett and Engdahl, 1991).

23 To improve earthquake catalog accuracy and completeness, several studies have developed denoising techniques that
24 remove overlapping noise, improving the signal-to-noise ratio (SNR) of recorded seismic signals (e.g. Zhu et al., 2019; Mousavi
25 and Langston, 2016, 2017). Unlike conventional spectral filtering, machine-learning denoisers adaptively separate target sig-
26 nals from noise, even in overlapping frequency bands (Zhu et al., 2019). While these techniques have the potential to improve
27 SNR and detection rates, few studies have quantitatively evaluated their performance on continuously recorded waveforms
28 (Yang et al., 2022; Dahmen et al., 2022).

29 In this study, we explore the potential gain in using recently developed deep learning tools for earthquake monitoring in
30 Haiti. The island of Hispaniola, including Haiti and the Dominican Republic, is situated along a transpressional section of the
31 Caribbean–north America plate boundary (Calais et al., 2016). This seismotectonic environment has resulted in numerous
32 severe earthquakes throughout history (e.g. Bakun et al., 2012). More recently, the 2010 M_W 7.0 Haiti earthquake, one of the

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most consequential events in history, caused over 200,000 fatalities and economic losses close to 100% of the country's gross domestic product (Calais et al., 2010). Despite considerable natural, economical, and political obstacles (Corbet et al., 2024), Haiti has maintained an operational earthquake monitoring system (Calais et al., 2020, 2022). This system relies on citizen-hosted low-cost RS4D RaspberryShake (RS) seismic sensors (Figure 1) forming the network with code name HY (<https://doi.org/10.7914/sn/hy>). The data is streamed in real-time to a monitoring platform, coined Ayiti-seismes, which has operated continuously since August 2019. The platform uses data from the HY network, publicly open data streams from all temporary and permanent stations in the region (Paul et al., 2023) and an STA/LTA automatic detection method, followed by manual verification, to monitor seismicity in the region. The Ayiti-seismes system has enabled a significantly improved monitoring of the region with an estimated magnitude of completeness (M_C) of 2.5. The improved monitoring provided critical data to understand the 2021 M_W 7.2 Nippes earthquake (Calais et al., 2022), revealing a multiple segment rupture. This earthquake affected a mostly rural area, resulting in lower impacts than the 2010 earthquake – about 2,500 dead and 13,000 injured (OCHA, 2021) – but stressed the necessity of improving the Haiti earthquake catalog and our understanding of regional seismicity.

As reported by Paul et al. (2023), RS stations have higher noise levels than broadband stations on the island, because they are mostly located in urban environments, inside the homes of the citizens who volunteer to host them, and without prior in-depth verification of the background noise levels. Here, we test a deep learning tool to reduce noise levels in Haiti's seismic recordings. Combining the insights from our tests with the wealth of data from the HY network and a temporary seismic network composed of 12 broadband stations deployed in response to the 2021 M_W 7.2 Nippes earthquake (Z2, Douilly et al., 2022), we compile a high-resolution 2-year catalog (January 2021 to December 2022) that reveals previously unidentified clusters of seismic activity.

53 DENOISING

To enhance the quality of seismic waveforms recorded in Haiti, we apply the DeepDenoiser deep learning algorithm (Zhu et al., 2019). DeepDenoiser is a convolutional neural network trained to separate earthquake signals from noise in the frequency domain. It takes spectrograms of noisy signals as input and outputs a signal and a noise mask, which are applied to the input signal to obtain the denoised signal. The original DeepDenoiser model was trained on an extensive dataset of earthquake and noise signals recorded in northern California (Zhu et al., 2019).

We test different DeepDenoiser models before applying them to continuous Haiti data: 1) the original DeepDenoiser model (Zhu et al., 2019), 2) UrbanDenoiser – a version retrained on the Long Beach (California, USA) focusing on urban environments – (Yang et al., 2022), and 3) models retrained on Haiti data. For retraining, we use 4,957 30-second-long earthquake waveforms with SNR above 10 dB from the Ayiti-seismes catalog, and 5,976 noise waveforms listed as “Not earthquakes” after applying the PhaseNet picker (Zhu and Beroza, 2019) to ensure no seismic phase is present. The dataset is split into train-

64 ing, validation and testing datasets in a 80%/10%/10% ratio. We retrain the model starting with the original DeepDenoiser
 65 weights, testing different retraining approaches (entire network, first layer, last layer), learning rates (10^{-2} to 10^{-6}), batch sizes
 66 (50, 100, 200, 500), and dropout rates (0, 0.01, 0.05, 0.1, 0.25). We used cross-entropy loss and stopped training once there
 67 was no validation loss improvement for 10 epochs, saving the epoch with best validation loss. For each epoch, each signal
 68 waveform is merged with all noise waveforms randomly scaling its amplitude to create multiple “noisy” signals (Zhu et al.,
 69 2019). To assess performance, we calculate the SNR and signal distortion ratio (SDR) of the test dataset waveforms (Zhu et al.,
 70 2019; Yang et al., 2022) using:

$$SNR = 10 \log_{10} \frac{\sigma_{signal}}{\sigma_{noise}}, \quad (1)$$

71 and

$$SDR = 10 \log_{10} \frac{||W_{GT}||}{||W - W_{GT}||}, \quad (2)$$

72 where W is the denoised waveform, W_{GT} the ground truth waveform, σ_{signal} the standard deviation of the signal, and σ_{noise}
 73 the standard deviation of the noise. High SDR indicates lower distortion, reflecting better separation of the signal of interest
 74 from noise.

75 Results from our tests of transfer learning and fine-tuning DeepDenoiser models on the Haiti test dataset are shown in
 76 Table 1. We present only the best results for each combination of dropout rates, batch sizes, and learning rates. Based on
 77 SNR metrics, retraining the entire network or just the last layer shows a slight improvement over the original DeepDenoiser
 78 model. However, when considering the average SDR estimates, the retrained models perform worse than the original model.
 79 This suggests that retrained models remove more noise before the first phase arrival but also misidentify more signal as noise,
 80 leading to higher waveform distortion. Notably, the UrbanDenoiser model, trained on urban data with large anthropogenic
 81 noise, performs worse than the original DeepDenoiser model and any of the retrained models.

82 Based on these results, we choose to use the original DeepDenoiser model for denoising in the rest of this study (Figure 2)
 83 as it presents the best balance of SNR and SDR (Table 1).

84 We apply the original DeepDenoiser model to all P-phase picks in the Ayiti-seismes catalog, including those with SNR
 85 < 10 dB, and compute SNRs for denoised and non-denoised waveforms (Figure 3). The average SNR increases by 4.7 dB
 86 across the full dataset and by 4.3 dB for the RS stations, indicating that DeepDenoiser improves signal quality similarly for
 87 the entire catalog and for the RS instruments, even though waveforms from RS instruments were absent from the training
 88 set.

89 **DETECTION**

90 To assess the impact of denoising on earthquake detection, we apply three detection methods: the STA/LTA ([Allen, 1978](#)),
91 PhaseNet deep learning picker ([Zhu and Beroza, 2019](#)), and template matching detection ([Gibbons and Ringdal, 2006](#)).

92 We perform detection on all the stations available in the island (Figure 1 and Table S1). To ensure a fair comparison, we
93 established consistent source-station distances and corresponding detection time windows for analysis. We determined a
94 distance threshold by examining the distribution of source-station distances for the earthquakes in our catalog (Figure S1a).
95 This distribution exhibited a clear bimodal pattern, with a noticeable decrease in number of phase picks around 120 km,
96 and a dominant first mode containing a higher number of phase picks. This bimodal shape reflects the island's geography,
97 as most stations are concentrated in its western side. Therefore, we selected 120 km as the distance threshold, focusing our
98 analysis on the dominant mode and local distances, similar to those used to train the DeepDenoiser and PhaseNet models
99 ([Zhu and Beroza, 2019](#); [Zhu et al., 2019](#)). This distance threshold corresponds to an approximate S-P time difference of 15 s
100 (Figure S1b).

101 We apply STA/LTA and PhaseNet to single-station waveforms separately, whereas we apply template matching to the entire
102 network waveforms. Therefore, we must perform association of the STA/LTA and PhaseNet phase picks, which we do using
103 the Rapid Earthquake Association and Location method (REAL) ([Zhang et al., 2019](#)).

104 To compare the different detection methods, we apply them to band-pass filtered, denoised and denoised-and-band-pass-
105 filtered waveforms. We then compare the number of detections and their quality by visual inspection. For PhaseNet, we also
106 compare raw waveform detections. We apply DeepDenoiser to continuous data, using the Seisbench package tools ([Woollam
107 et al., 2022](#)), processing 30 s windows of data with an overlap of 15 seconds (taking the average of overlapping segments).

108 **STA/LTA**

109 The STA/LTA method ([Allen, 1982](#)) is a detection technique widely used in real-time monitoring systems (e.g. [Helmholtz-
110 Centre Potsdam - GFZ German Research Centre for Geosciences and gempa GmbH, 2008](#)). It computes the ratio of a short-
111 term window's average (STA) amplitude to a long-term window's average (LTA) amplitude. Once this STA/LTA ratio exceeds
112 a predefined threshold, a detection is declared. We test STA/LTA using the parameters used in Ayiti-seismes ([Paul et al.,
113 2023](#)). We use ObsPy's recursive STA/LTA function ([Beyreuther et al., 2010](#)) with a 1 s short window, a 30 s long window
114 and a trigger threshold of 2.5. Detection of P-phases is performed on the vertical components, and S-phases on the average
115 envelope of the horizontal components.

116 **PhaseNet**

117 PhaseNet is a deep learning model that identifies seismic phase arrivals ([Zhu and Beroza, 2019](#)). PhaseNet is widely used
118 in deep learning earthquake detection workflows (e.g. [Liu et al., 2020](#); [Tan et al., 2021](#); [Wickham-Piotrowski et al., 2024](#)). It
119 analyzes three-component waveforms, evaluating the probability that a trace contains a P or S wave or noise. Similarly to

120 the original DeepDenoiser model, the original PhaseNet was trained on waveforms from the northern California earthquake
121 catalog. We use the Seisbench implemented PhaseNet model (Woollam et al., 2022), applying it to 30 s windows of 100 Hz
122 continuous data with 15 s steps. A P- or S-phase detection is declared if the respective probability exceeds 0.1.

123 **Association**

124 In the case of STA/LTA and PhaseNet, we associate detected picks using REAL (Zhang et al., 2019). REAL is an associator
125 that counts phase picks along theoretical travel-time windows, for which we use the velocity model inverted by Douilly
126 et al. (2022). The grid search parameters we use for the theoretical travel time calculations are 1.2° with 0.05° steps for the
127 horizontal distance and 40 km with 2 km steps for depth. We allow an earthquake detection every 10 seconds, limiting the
128 maximum source-station distance to 120 km and requiring at least 4 P-phase picks and 2 S-phase picks for a detection.

129 **Template Matching**

130 Template matching detects similar seismic events by cross-correlating waveforms of cataloged events with continuous wave-
131 forms (e.g. Gibbons and Ringdal, 2006; Neves et al., 2022). We use events from Ayiti-seismes' catalog as templates, selecting
132 events with at least 4 P-phase picks with source-station distances < 120 km and $\text{SNR} > 5$. For these events, we use a time
133 window from 1 s before the P-phase arrival to 16 s after, including also the S-phase arrival. We cross-correlate the templates
134 with continuous waveforms of the corresponding station using 1 hour segments with 1-sample steps. To improve the SNR of
135 the cross-correlation function (CCF), we shift and stack the CCFs of the entire network and declare a detection if the stacked
136 CCF is above 26 times the median absolute deviation.

137 **Impact of denoising on earthquake detection**

138 To assess the impact of denoising the waveforms recorded in Haiti considering the aforementioned detection methods, we
139 visually inspect the obtained catalogs during two time intervals: from August 1 to August 26, an interval that includes detec-
140 tions prior to the deployment of the temporary broadband network and the early aftershock period of the 2021 mainshock,
141 and November 6 and 7, the 2 days with the highest number of working stations in the dataset. Histograms summarizing the
142 classification of detected events as real and false detections are shown in Figure 4. The detection methods were tested on
143 band-passed filtered and denoised waveforms for all methods, and also on “raw” waveforms – *i.e.*, removing only the trend –
144 for PhaseNet detections, since PhaseNet was trained on unfiltered waveforms.

145 Considering only the detection numbers, PhaseNet applied to denoised waveforms returns the highest number of detec-
146 tions. However, when inspecting these detections, we find that more than 60% of them correspond to the detection and
147 association of impulsive artifacts resulting from the denoising process. A similar result is obtained using STA/LTA with
148 denoised waveforms: a higher number of events is detected but the majority corresponds to artifacts. For PhaseNet, the best
149 ratio of real detections is observed when applying the detector with raw waveforms, even though it misses detections found

150 only in denoised waveforms. In contrast, template matching performs best using denoised waveforms followed by a band-
151 pass filter. This strategy returns fewer false detections and more real detections than applying template matching on only
152 bandpass filtered waveforms or only denoised waveforms. It further returns a higher number of real detections than any
153 strategy using PhaseNet and STA/LTA, and almost 1.5 times more real detections than template matching with bandpass
154 filtered waveforms.

155 **COMBINING DENOISING AND TEMPLATE MATCHING TO COMPILE A NEW CATALOG**

156 Considering the performances of the methods tested here (Figure 4), we apply template matching detection to denoised and
157 bandpass filtered (2–16 Hz) waveforms in order to build an enhanced earthquake catalog in Haiti. To do so, we use 2,065
158 templates and search in all continuous waveforms available from January 2021 to December 2022. Magnitudes of the newly
159 detected events were estimated using relative magnitude estimation (see Supplemental File, Figure S3). The detection yields
160 a catalog of 13,877 events, four times the 3,471 events in the Ayiti-seismes catalog considering the same 120 km source-station
161 distance limit. We miss 1,824 Ayiti-seismes events due to our four recording stations within a 120 km radius requirement
162 (Figure S4).

163 We locate the new events using HypoDD ([Waldhauser and Ellsworth, 2000](#)), which determines relative earthquake loca-
164 tions by minimizing observed and theoretical travel-time difference residuals for pairs of earthquakes recorded at the same
165 station, reducing errors from velocity-model mismatches. We use cross-correlation-derived differential travel-times, comput-
166 ing the travel-time differences using denoised waveforms bandpass filtered between 2 and 16 Hz. We cross-correlate each
167 event with all events in a 5 km radius or the 10 closest events – whichever is larger – using -0.2 to 1.3 s windows around
168 P- and S-phase arrivals. We consider all measurements with a cross-correlation coefficient (CCC) > 0.6 , and only keep pairs
169 with at least 5 measurements and an average CCC > 0.7 , ensuring at least 3 stations in common. To avoid measurements
170 from spurious high CCC values, we recalculate CCCs using a 2 s window waveform and discard any travel-time measure-
171 ment whose maximum CCC differs by more than 1 sample. We use the [Douilly et al. \(2022\)](#) velocity model to locate the
172 events. The relocation results in a final catalog of 11,752 events (Figures 5–7 and S5). The majority of non-relocated events
173 corresponds to the largest magnitude events, a consequence of deteriorated CCC measurements between events with large-
174 magnitude differences ([Bachura and Fischer, 2019](#)). Additionally, poor waveform quality following the 2021 mainshock, with
175 fewer continuously working stations and increased data gaps at this time, results in a significant number of non-relocated
176 events (325) in the 10 days after the mainshock.

177 To confirm the positive impact of denoising on the final catalog, we apply the same template matching detection and
178 relocation procedure to only bandpass filtered waveforms (2–16 Hz) for August to November 2021. This test results in a catalog
179 of 6,774 events using the filtered waveforms compared to 7,393 events when using denoised waveforms. Furthermore, using
180 filtered waveforms, the relocated events pair on average with 59 events and have an average relative location uncertainty of

181 20 m, whereas using the denoised waveforms, each event pairs on average with 100 events and have an average uncertainty
182 of 14 m. Template matching is the biggest net contributor to the improved catalog, but denoising further reveals new events
183 and improves locations by providing more differential travel-time information data.

184 The final catalog presents 11,752 precisely located events, which is about 3 times the number of events in the Ayiti-seismes
185 catalog for the same time interval (3,992). Most of the newly detected events are located in the 2021 Nippes mainshock area,
186 but the new catalog also reveals clear clusters of seismicity in other regions like the Jérémie Basin and the Enriquillo lake
187 in Dominican Republic. We note that our catalog is biased towards sources similar to those already present in the Ayiti-
188 seismes catalog due to the characteristics of template matching and double-difference relocation, limiting improvements for
189 background or isolated seismicity.

190 DISCUSSION

191 On the use of denoising for earthquake monitoring in Haiti

192 Our findings indicate that DeepDenoiser is better suited for detailed seismicity analyses than for automatic detection work-
193 flows. Our comparative tests using STA/LTA (Figure 4a), the method used by Ayiti-seismes and commonly adopted by
194 earthquake monitoring agencies (e.g. [Duverger et al., 2021](#); [González, 2017](#)), reveal that denoising significantly increases
195 false alerts, increasing analysts' workload. Additionally, employing DeepDenoiser followed by a band-pass filter yields fewer
196 detections compared to traditional band-pass filtering. This discrepancy arises from variations in picking times that compli-
197 cate the association process. DeepDenoiser zeros the amplitude of segments deemed pure noise, leading to subtle fluctuations
198 being misinterpreted as phase onsets. Consequently, P-phases are often picked earlier than manual picks or from the standard
199 STA/LTA method. Combining DeepDenoiser with PhaseNet increases both false and real detections (Figure 4b). However,
200 PhaseNet was not retrained on local nor denoised waveforms; it is therefore possible that better results can be achieved
201 in any of these situations. Template matching shows a clear improvement applying DeepDenoiser and band-pass filtering
202 (Figure 4c), yielding more real detections and fewer false ones. However, despite the existence of near-real-time template
203 matching systems ([Chamberlain et al., 2020](#)), the method's computational cost and reliance on existing templates make it
204 better suited for detailed retrospective analyses.

205 We therefore advise caution when deploying DeepDenoiser directly in automated earthquake monitoring. In its current
206 form it is unsuitable for the Ayiti-seismes workflow, but improvements are possible: augment the training set with addi-
207 tional RS recordings which have different coupling and noise levels, incorporate intervals containing artifacts identified by
208 both STA/LTA and PhaseNet into the noise samples, and explore physics-based denoising methods that enforce real-world
209 constraints ([Banerjee et al., 2024](#)).

210 **A detailed picture of the 2021 mainshock area**

211 The majority of the events – about 67%, or 7,948 earthquakes – in our new high-resolution catalog lies in the area of the
212 2021 M_w 7.2 Nippes earthquake (Figs. 5 and 6). In this region we find 4.8 times more events than in the Ayiti-seismes system
213 catalog (7,948 vs 1,662 on the same time interval) and 2.7 more events than in the catalog of [Douilly et al. \(2022\)](#) (6,422 vs
214 2,417 from 20 August 2021 to 30 December 2021). The additional detections and improved locations provide a more detailed
215 picture of the 2021 sequence and the involved fault segments (Figure 8).

216 The 2021 M_w 7.2 Nippes earthquake ruptured near the Enriquillo-Plantain Garden Fault (EPGF) ([Calais et al., 2020](#)),
217 an east-west left-lateral strike-slip fault that spans Haiti's southern Peninsula and extends offshore toward Jamaica ([Mann](#)
218 [et al., 1995](#)). Inversions of seismic and geodetic data show that the mainshock rupture initiated on a mostly reverse-fault
219 segment and propagated westward to a mostly strike-slip segment ([Calais et al., 2022](#)). [Raimbault et al. \(2023\)](#) identified
220 two distinct segments: a first one dipping 66° N and mostly reverse, and a second one farther west dipping 86° north and
221 mostly strike-slip, associated with the Ravine du Sud fault (RSF). [Douilly et al. \(2022\)](#) also identified a multiple-segment
222 structure, with a western segment connected to the RSF and two eastern segments dipping 60° and 70° N. They noted a near-
223 vertical aftershock cluster near the expected EPGF extent at depth, interpreted as triggered seismicity on the EPGF, which
224 they suggested did not rupture coseismically. [Paul et al. \(2025\)](#) expanded the aftershock catalog of [Douilly et al. \(2022\)](#) and
225 applied the NLL-SSST-Coherence location method ([Lomax and Savvaidis, 2022](#)), identifying two clusters: a narrow western
226 cluster parallel to the EPGF, steeply dipping northward and interpreted as the EPGF at depth; and a broader ~N110°-trending
227 cluster dipping ~70° north, interpreted as a separate reverse fault, termed the “Nippes fault”.

228 As in those two catalogs, the aftershock distribution found here also delineates two clusters with different orientations. We
229 analyze the aftershock distribution by examining the dip variations of the seismic clusters shown in Figure 8. Events in the
230 western part (segments AA', BB' and CC' in Figure 8) generally show a near-vertical distribution, albeit discontinuous, with
231 a clearer lineament in segment CC'. Between 73.81° W and 73.63° W (segment DD', Figure 8e) the aftershock distribution
232 becomes more complex showing events still associated with the CC' near-vertical lineament, and additional events north
233 of it also showing near-vertical trends. Towards the center of segment DD', a north-dipping cluster appears below 10 km,
234 with a small gap to the west. West of 73.63° W, a large and complex cluster coincides with the mainshock hypocenter and
235 most aftershocks (segment EE'). We model this cluster by dividing it into several fault planes with equal longitudinal extent.
236 Testing partitions from 1 to 10 planes, we select the configuration with the lowest sum of squared differences between the
237 observed aftershock locations and the modeled planes. The cluster is best explained by 5 planes (shown in shades of green
238 in Figure 8a and respective cross-sections in Figs. 8g-k). Consistent with ([Douilly et al., 2022](#)) and [Paul et al. \(2025\)](#), this
239 structure strikes WSW-ENE in the west, gradually rotating to an almost NW-SE strike to the west, up until 73.48° W where
240 it returns to an almost E-W strike. This structure retains a northward dip of 55° to 78° throughout its length.

241 The aftershock distribution aligns well with the rupture geometry and coseismic slip distribution inferred from geodetic
242 data by [Raimbault et al. \(2023\)](#), shown with colored contours in Figure 8. The main cluster bends around the peak slip of
243 their 66°north-dipping structure (Figure 8a), in-line with our aftershock distribution dip estimates. To the west, aftershocks
244 in segments BB', CC', and DD' agree with the 86°north-dipping strike-slip segment of [Raimbault et al. \(2023\)](#), particularly in
245 segment CC', which shows a similar near-vertical dip. The observed gap in segment DD' coincides with the meeting point of
246 the strike-slip and reverse rupture segments found by [Raimbault et al. \(2023\)](#).

247 A significant difference between our catalog and that of [Douilly et al. \(2022\)](#) pertains to the distribution of aftershocks in
248 segment EE' closer to the surface trace of the EGPF. This previous catalog shows a near-vertical cluster at 5-10 km depths
249 close to the expected fault location. In our catalog, events at this location dip northward and align well with the previous
250 modeled planes. This suggests these events are part of the reverse fault where the mainshock initiated. We find no evidence
251 of aftershocks associated with a vertically-dipping EPGF in this area.

252 **Fluid-induced seismic swarms in the Jérémie basin?**

253 Our new catalog reveals several offshore earthquake clusters in the Jérémie basin, NW of the 2021 mainshock epicenter
254 (Figure 9), also present in the Ayiti-séismes catalog (Figure 5) but with a more spread-out distribution. Here, we identify six
255 clusters (C1 to C6) shown in Figure 9a. Cluster C1, the earliest and largest (2,136 events), and clusters C2 (216 events) and
256 C3 (358 events) are located near shallow reverse faults in the Jérémie–Malpasse fault system ([Calais et al., 2023](#)). Clusters
257 C1 and C3 delineate very low-angle SW-dipping structures consistent with identified thrust faults. Cluster C3 shows two
258 SW-dipping lineaments at depths of 11 km and 15 km (Figures S7). Cluster C2 shows a similar shallow and deeper group but
259 without clear lineaments (Figure S6). Cluster C4 (48 events) is a shallow group of events at less than 3 km depth that extends
260 in the E-W direction and shows a SSE dipping (Figure S8). Clusters C5 (123 events) and C6 (38 events) do not define clear
261 lineaments, with C5 located above 2 km depth and C6 concentrating around 11 km depth.

262 These clusters present swarm-like characteristics with no clear mainshock ([Mogi, 1963](#)). For example, the largest earth-
263 quake in cluster C1 is a M 4.8 event occurring 128 days after the onset. Cluster C1 also shows a clear NW migration pattern.
264 Earthquake swarms are usually explained as resulting from fluid pressure diffusion (e.g. [Shapiro et al., 1997](#)), aseismic slip
265 (e.g. [Roland and McGuire, 2009](#)), or an interplay of both (e.g. [Hainzl, 2004](#); [De Barros et al., 2020](#)). We test this hypothesis
266 by defining a propagation front adapting the methodology of previous studies ([Amezawa et al., 2021](#); [Danré et al., 2022](#)).
267 Considering the evolution of event distance to the initial event of each cluster, we define the front as the 90th percentile of
268 the distance in non-overlapping bins of 25 events for clusters with more than 100 events, and 10 events for smaller clusters.
269 We fit three models to the front ([Danré et al., 2024](#); [Adeboboye et al., 2025](#)): fluid pressure diffusion described by $R = \sqrt{4\pi Dt}$,
270 where R is the distance to the origin of the pressure source, D the diffusivity and t time ([Shapiro et al., 1997](#)); linear migra-
271 tion; and constant distance, to test the absence of migration. Clusters C1, C3, and C4 migration is best explained by the fluid

272 diffusion model (Figures 9d, S7d,e, and S8d); although in the case of C4 it is not significantly different than the constant
273 case. These results are consistent with the observed activity in the Jérémie basin being driven by fluids. Inferred diffusivities
274 (0.14 m²/s for C1, 0.004-0.04 m²/s for the others) fall into the range observed in other fluid-driven swarms (Talwani et al.,
275 2007). The estimated migration velocity and swarm duration, for example 38 m/day $\sim 4 \times 10^{-4}$ m/s and 160 days $\sim 1.4 \times 10^7$ s
276 for cluster C1, also fall in the middle of the scaling law empirically derived by Danré et al. (2024) for fluid-induced swarms,
277 comforting the hypothesis that the swarms are driven by fluid migration processes.

278 Evidence for seismic activity in Lake Enriquillo

279 The extension of the EPGF is well-documented in southern Haiti until about 72.27° W (Symithe and Calais, 2016). Further
280 east, its extension is still debated. Mann et al. (1995) proposed that the EPGF continues eastward through the Enriquillo-Cul-
281 de-Sac Valley into Lake Enriquillo, Dominican Republic, based on *en échelon* faults and folds (Figure 10). Lake Enriquillo is
282 bounded by active thrust faults (Mann et al., 1995) where moderate seismic activity has been recorded (Escuder-Viruete et al.,
283 2025; Rodriguez et al., 2018; Possee et al., 2019; Lee and Douilly, 2022). Mann et al. (1995) proposed that the EPGF extends
284 continuously to the east along the northern edge of Cabritos Island in Lake Enriquillo on the basis of subvertical zone of
285 incoherent reflections on a seismic profile, though reflectors at depth on this profile are continuous across and not affected
286 by faulting. Wang et al. (2018) analyzed high-resolution sonar data and proposed a continuous extension of the EPGF until at
287 least Cabritos Island with evidence for recent activity, though again the data do not document faulting at depth. In contrast
288 with this proposal of a continuous extent of the EPGF throughout Cul-de-Sac – Enriquillo basin, Symithe and Calais (2016)
289 posit that the EPGF stops around about 72.27° W and abuts against a series of reverse faults and fold-propagation folds that
290 extends along the southern edge of the basin. This interpretation is shared by other authors on the basis of field observations
291 (Saint Fleur et al., 2019; Wessels et al., 2019; Escuder-Viruete et al., 2025) and of earthquake distribution (Rodriguez et al.,
292 2018; Possee et al., 2019) in southern Haiti and Dominican Republic.

293 Our new catalog does not resolve the eastern extent of the EPGF, but documents seismic activity near Cabritos Island
294 (Figure 10). We identify 62 earthquakes along the island's northern edge, where Mann et al. (1995) proposed the EPGF
295 continuation. The events occur mostly in two distinct bursts, with a group of 47 events from July 21 to August 5, 2021, the
296 largest one of M 3.2, then a group of 14 events from July 16 to July 20, 2022, the largest one of M 2.0. The seismicity extends
297 from 4 to 11 km depth but does not align on a single, throughgoing, vertical structure. Part of the larger cluster (orange
298 on Figure 10a) appears near-vertical, but most of it actually follows a quasi-horizontal plane just above 5 km depth. The
299 magnitudes of the recorded earthquakes and the limited azimuthal station coverage preclude us from determining focal
300 mechanisms that would shed light on the fault kinematics associated with the observed seismicity.

301 **CONCLUSIONS**

302 We explored the applicability of a deep learning denoising tool, DeepDenoiser, for seismic monitoring in Haiti. We found it
303 is more suitable for retrospective detailed seismicity studies than for real-time application. When combined with template
304 matching, DeepDenoiser enhances detection rates while reducing false positives. Doing so, we enhanced the description of
305 Haiti's earthquake activity tripling the number of events compared to existing catalogs. The catalog we obtained provides a
306 detailed view of the 2021 M_w 7.2 Nippes earthquake, with aftershock distribution agreeing with recent coseismic slip models
307 (Raimbault et al., 2023) and no evidence of aftershocks associated with a vertical EPGF. It also reveals offshore swarms in the
308 Jérémie basin with fluid-driven migration patterns and a distinct group of events in Lake Enriquillo, Dominican Republic,
309 coinciding with a proposed EPGF continuation. These results show that denoising can enhance catalog completeness and
310 quality, revealing previously unidentified areas of active seismic activity in Hispaniola.

311 **DATA AND RESOURCES**

312 The detection and relocated catalogs are included as supplementary files (Supplemental Datasets S1 and S2). The Ayiti-
313 seismes earthquake catalog and data from the HY network are available at the Ayiti-seismes platform (<https://ayiti.unice.fr/ayiti-seismes>). Data from networks AY, CN (Natural Resources Canada, 1975), CU (Albuquerque
314 Seismological Laboratory (ASL)/USGS, 2006), DR (National Seismological Centre, 1998), LO (Instituto Politecnico Loyola,
315 2012) can be accessed through IRIS Web Services (<https://service.iris.edu/>). Z2 network data will be available
316 through IRIS Web Services in October 2026.

318 **DECLARATION OF COMPETING INTERESTS**

319 The authors declare no conflicts of interest.

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TABLE 1

Signal-to-noise ratio (SNR) and signal distortion ratio (SDR) for the different pretrained and retrained DeepDenoiser models. We show only the best result of the different hyperparameters.

	Pretrained			Retrained DeepDenoiser		
	Raw waveforms	DeepDenoiser	UrbanDenoiser	Entire Network	Last Layer	First Layer
SNR	15	34.42	17.66	35.44	32.51	34.86
SDR	-	6.74	6.48	5.36	4.59	5.83

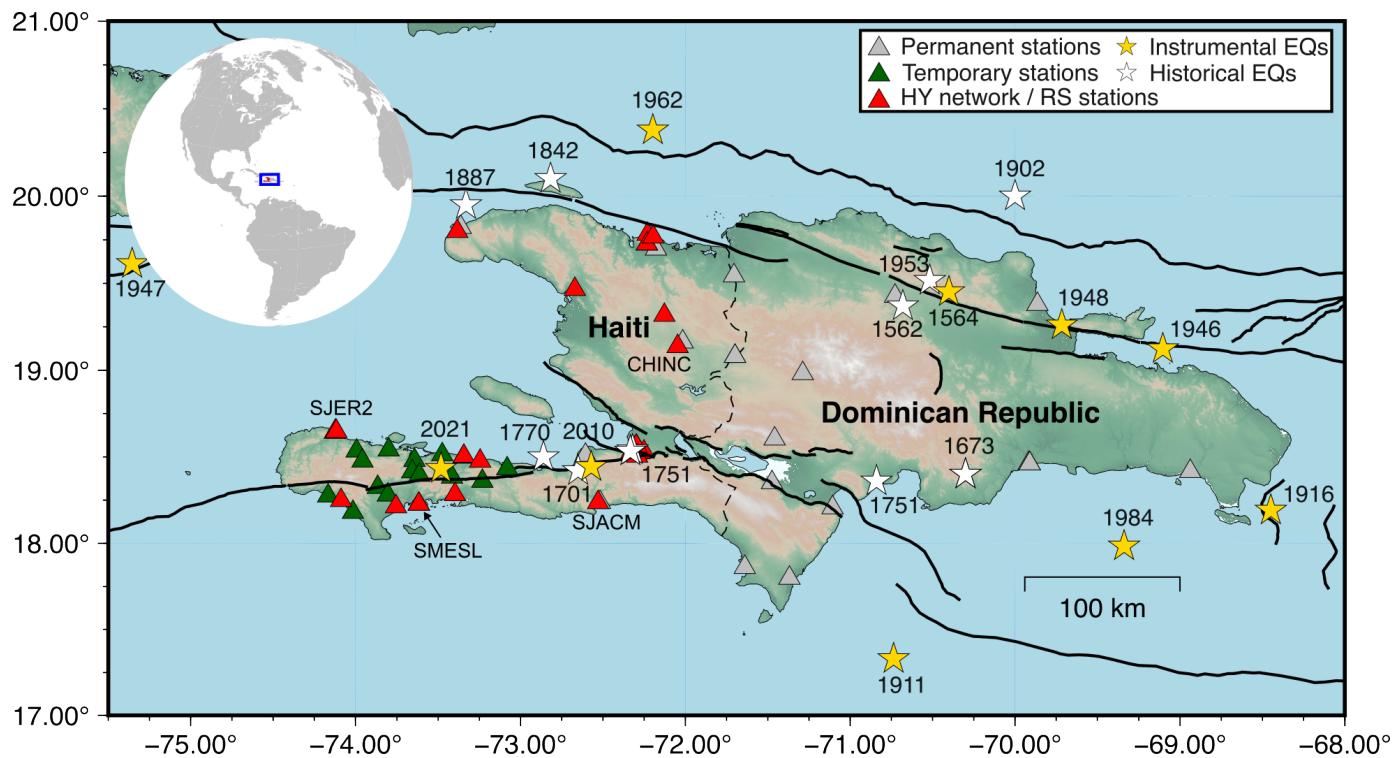


Figure 1. Map of Hispaniola showing seismic stations used in our study. Seismic stations are denoted by triangles: HY network in red, temporary deployment in green, permanent stations with publicly open data in gray. Stars mark major historical (white) and instrumentally recorded (yellow) events. Black lines indicate active fault traces [Styron et al. \(2020\)](#).

Alt-text: Map of Hispaniola displaying seismic stations used in our study together with major events and active fault lines in the island.

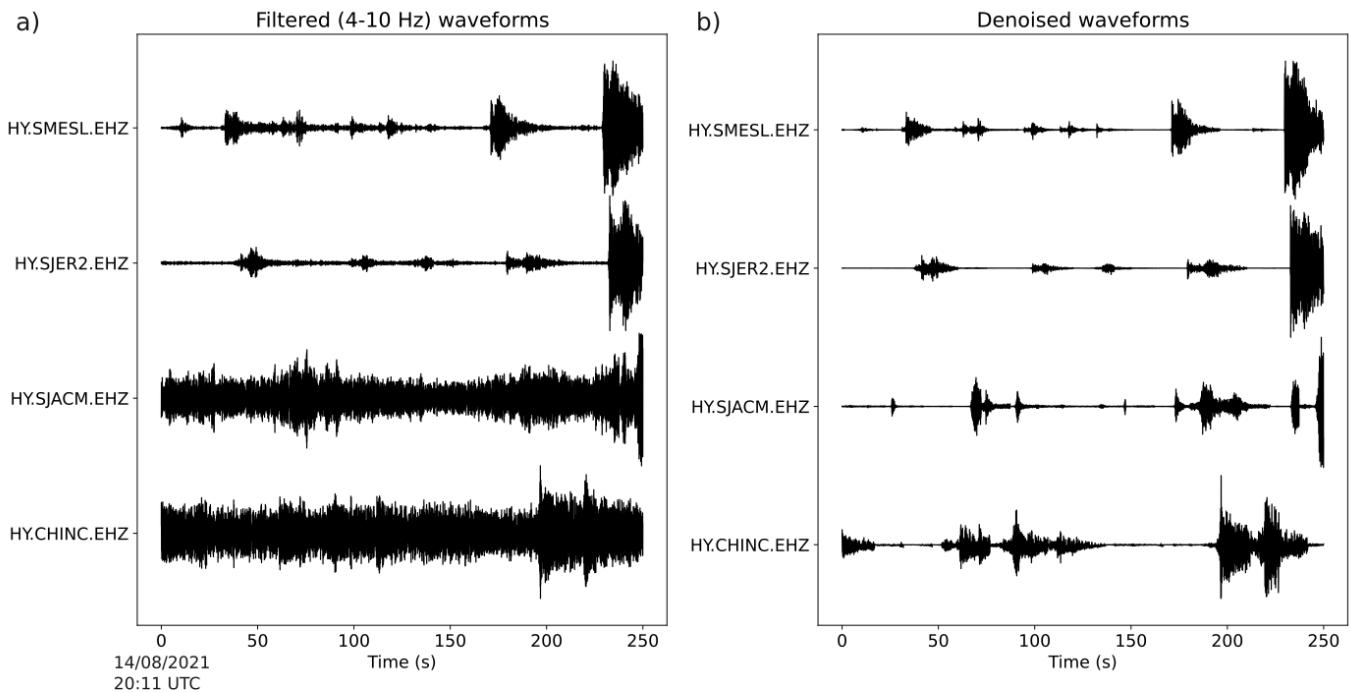


Figure 2. Examples of waveforms recorded on RS stations in Haiti. a) Bandpass filtered (4-10 Hz); b) Denoised using the original DeepDenoiser model. Station locations are shown in Figure 1.

Alt-text: Examples of denoised waveforms from RaspberryShake stations in Haiti compared to traditionally bandpass filtered waveforms.

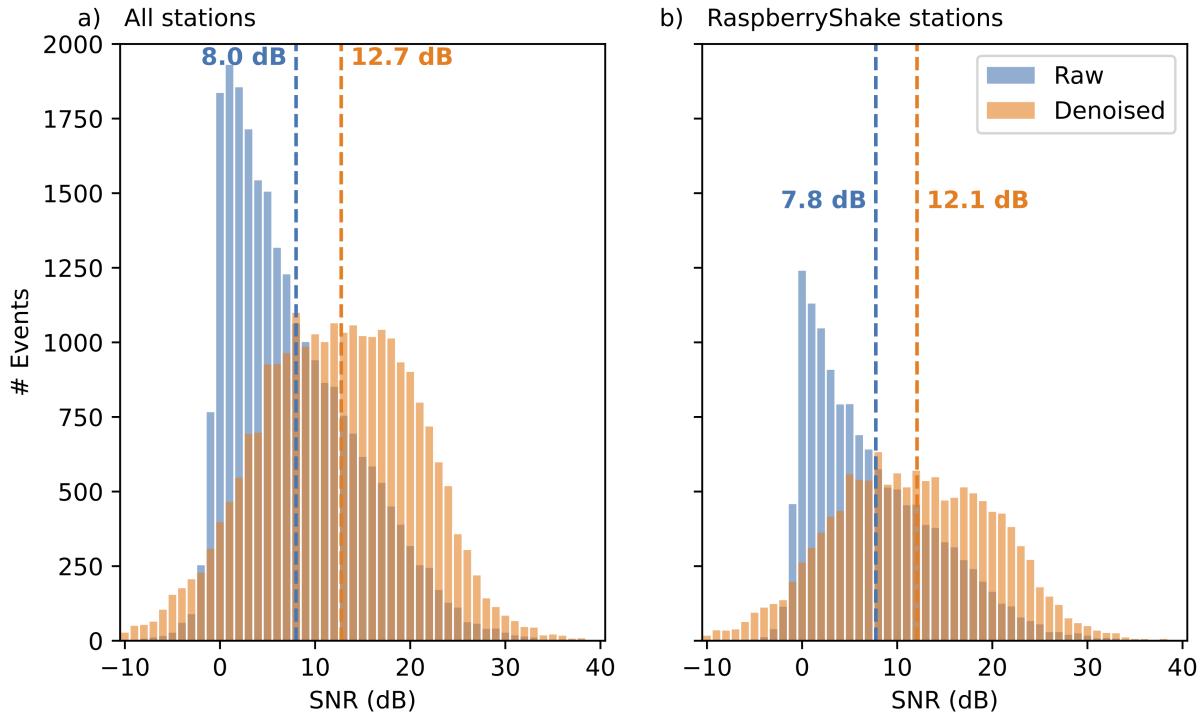


Figure 3. SNR distributions of cataloged phase picks using raw (blue) and denoised waveforms (orange). Panel (a) includes all stations on Hispaniola and panel (b) only the HY network. Negative SNRs reflect imprecise phase picks (see Figure S2).

Alt-text: SNR distributions comparing cataloged phase picks from raw (blue) and denoised (orange) waveforms. Panel a displays data from all stations, and panel b focuses on the HY network.

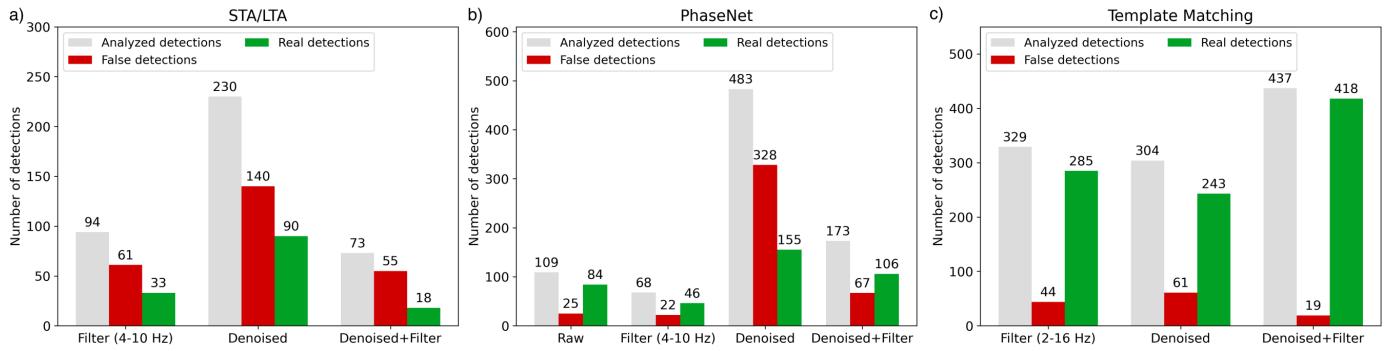


Figure 4. Comparison of detection tests using denoised and non-denoised waveforms. a) STA/LTA detection on filtered, denoised, and denoised-and-filtered waveforms. b) PhaseNet detection on raw, filtered, denoised, and denoised-and-filtered waveforms. c) Template matching detection on filtered, denoised, and denoised-and-filtered waveforms. Gray bars represent total detections, green real detections, and red bars detections.

Alt-text: Comparison of detection tests using denoised and non-denoised waveforms: panel a shows STA/LTA detections, panel b PhaseNet detections, and panel c template matching detections. Gray bars indicate total detections, green bars real detections, and red bars false detections.

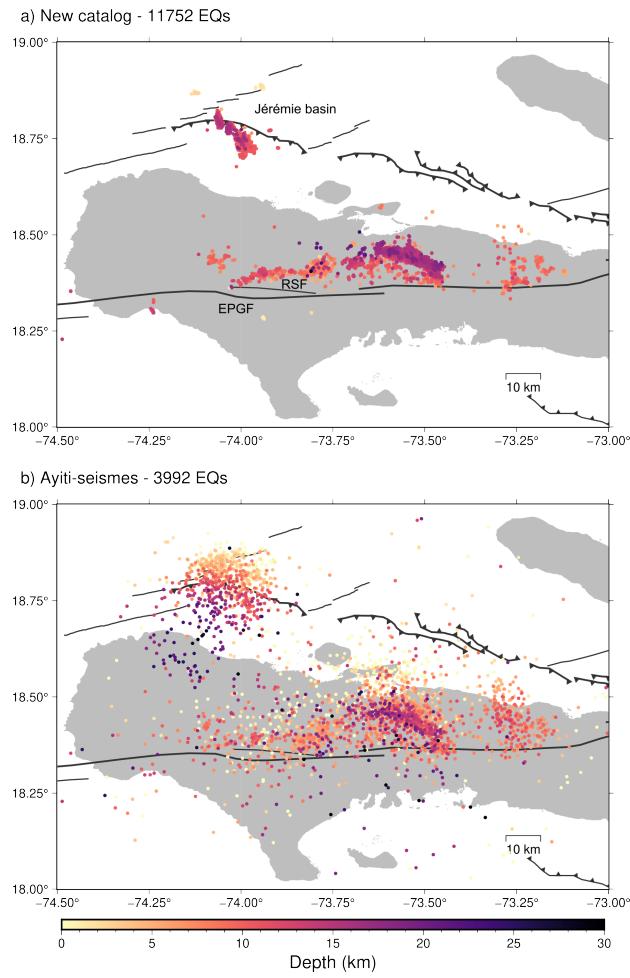


Figure 5. Catalog comparison with Ayiti-seismes earthquake catalog for 01/01/2021 to 31/12/2022. a) New catalog. b) Catalog from the Ayiti-seismes platform. Color denotes depth.

Alt-text: Comparison of our new catalog with Ayiti-seismes earthquake catalog.

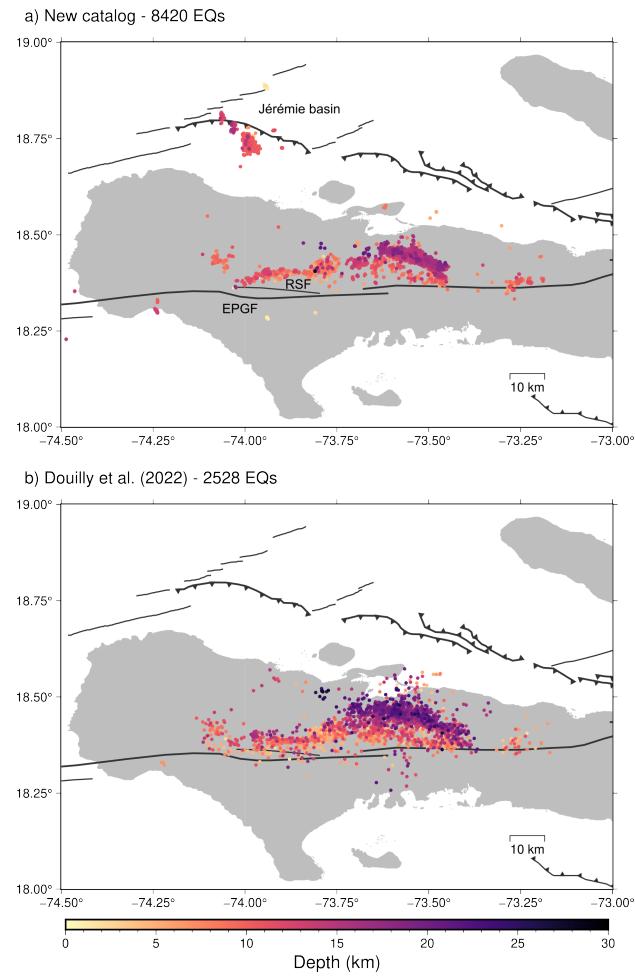


Figure 6. Catalog comparison with [Douilly et al. \(2022\)](#) earthquake catalog for 20/08/2021 to 30/12/2021. a) New catalog. b) [Douilly et al. \(2022\)](#) catalog. Color denotes depth.

Alt-text: Comparison of our new catalog with Douilly et al. (2022) earthquake catalog.

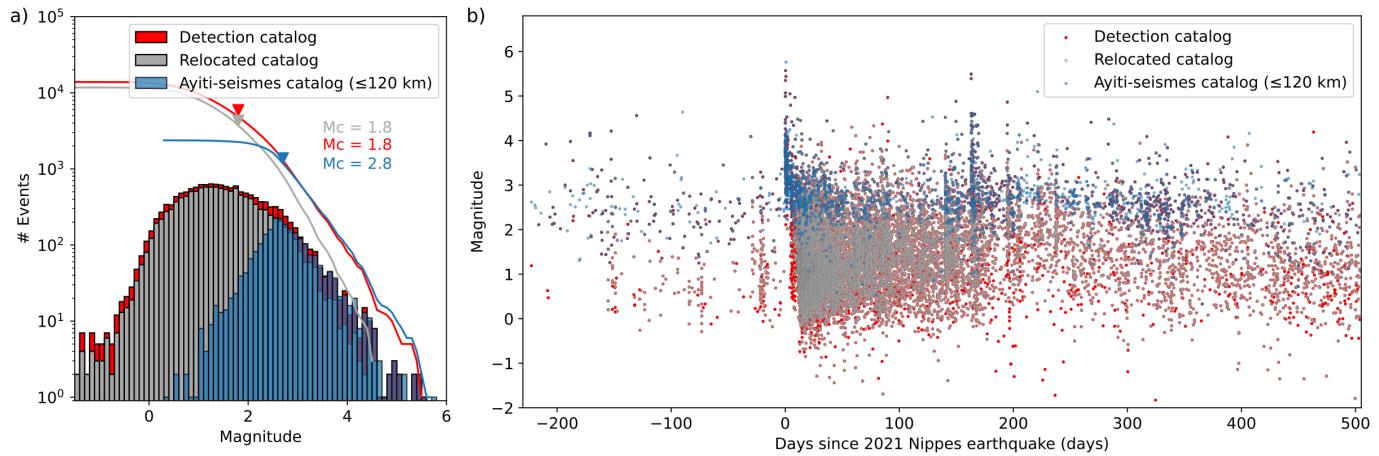


Figure 7. Magnitude distributions for the new relocated catalog (gray), detection catalog (red), and Ayiti-seismes catalog (blue). a) Magnitude-frequency distribution, with lines showing the cumulative distribution, and triangles indicate estimated magnitude of completeness using the maximum curvature method (Woessner and Wiemer, 2005). b) Magnitude distribution with time.
 Alt-text: Magnitude distributions for the relocated catalog (gray), detection catalog (red), and Ayiti-seismes catalog (blue). Panel a shows the magnitude-frequency distribution with cumulative lines and completeness estimates. Panel b presents the magnitude distribution over time.

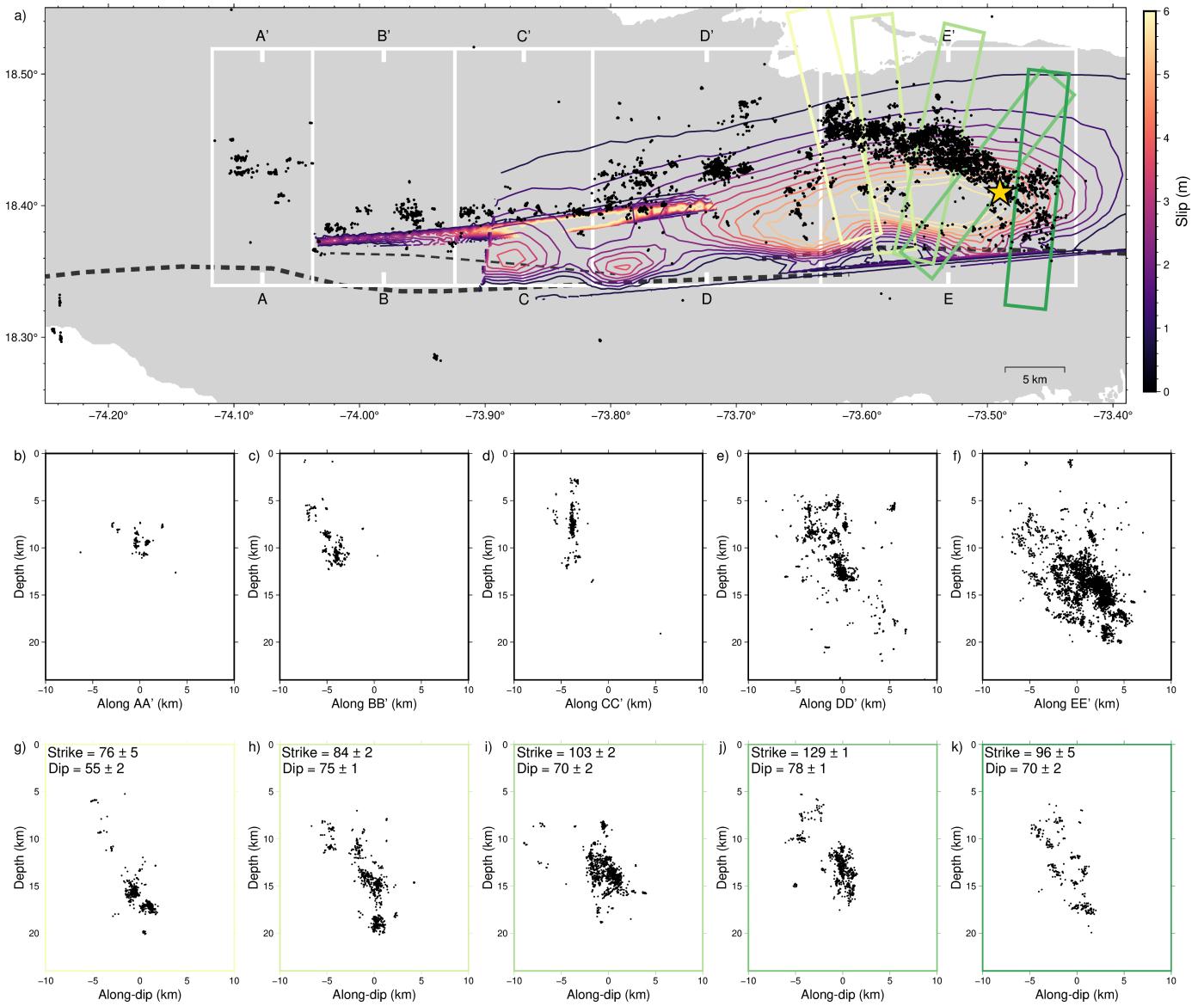


Figure 8. Spatial distribution of the seismicity in our new catalog for the 2021 M_W 7.2 Nippes earthquake region. a) Seismicity with co-seismic rupture slip contours from Raimbault et al. (2023) (color denotes slip amplitude in meters). Black dashed lines show faults with surface expression from Calais et al. (2023). b)-f) Cross-sections along A-A' to E-E' profiles. g)-k) Along-dip cross-sections of events within the corresponding colored rectangles in a).

Alt-text: Spatial distribution of seismicity in the 2021 Mw 7.2 Nippes earthquake region, with co-seismic rupture slip contours (panel a). Panels b-f present cross-sections along profiles A-A' to E-E', and panels g-k show along-dip cross-sections of events within the identified best planes described in the main text.

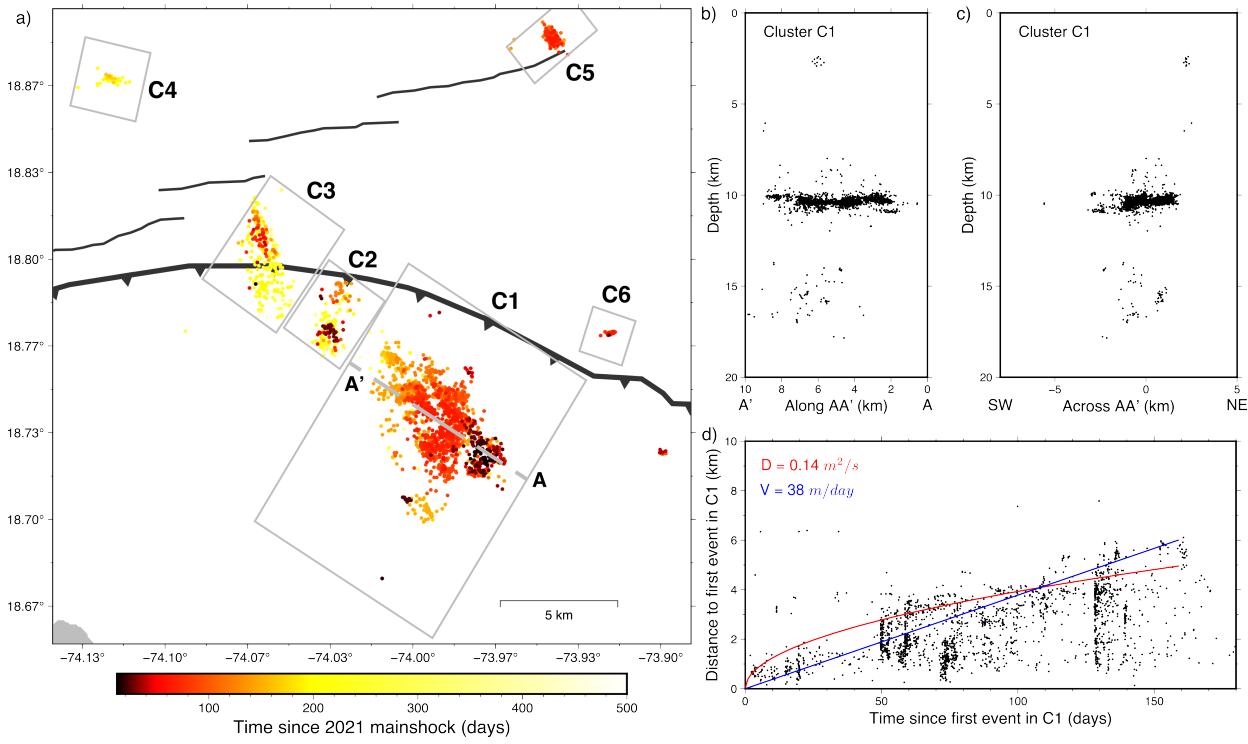


Figure 9. Jérémie basin clusters. a) Events in the new catalog colored by occurrence time and faults from Calais et al. (2023). b) Cross-section of cluster C1 along A-A'. c) Cross-section across A-A'. d) Distance of events to the first event in C1 versus time. Blue and red lines show the best fit using linear migration and fluid diffusion models, respectively.

Alt-text: Seismic clusters in the Jérémie basin, illustrating occurrence time and faults (panel a). Panels b and c present cross-sections of cluster C1. Panel d shows event distribution in C1 over time, with best fit models for linear migration and fluid diffusion.

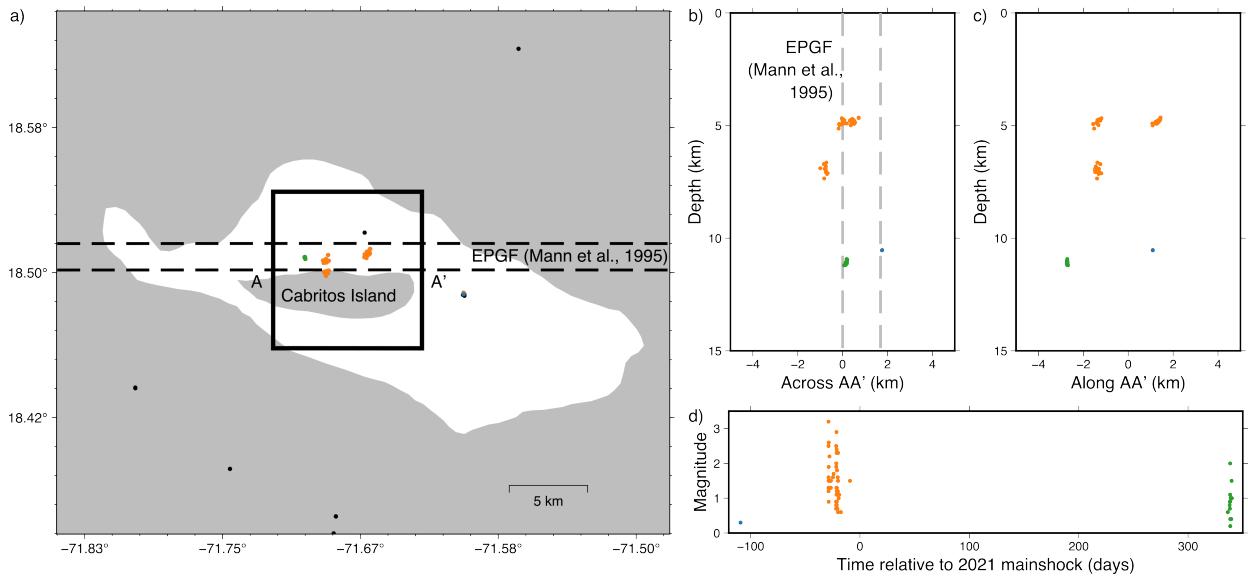


Figure 10. Seismicity in the Lake Enriquillo area. a) Events in the new catalog, colored by temporal groups; dashed black lines trace the EPGF continuation proposed by Mann et al. (1995). b) North–south cross-section of the seismicity with the proposed EPGF continuation shown in gray. c) West–east cross-section. d) Magnitude distribution with time.

Alt-text: Seismicity in the Lake Enriquillo area (panel a). Panel b presents a north-south cross-section of seismic events, with the proposed EPGF continuation by Mann (1995) highlighted in gray. Panel c features a west-east cross-section, and panel d illustrates the magnitude distribution over time.

1 Supplemental material to "Enhancing

2 earthquake monitoring with deep learning

3 in Haiti"

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6 Calais⁵ 

7 Used seismic stations and source-station distances considered

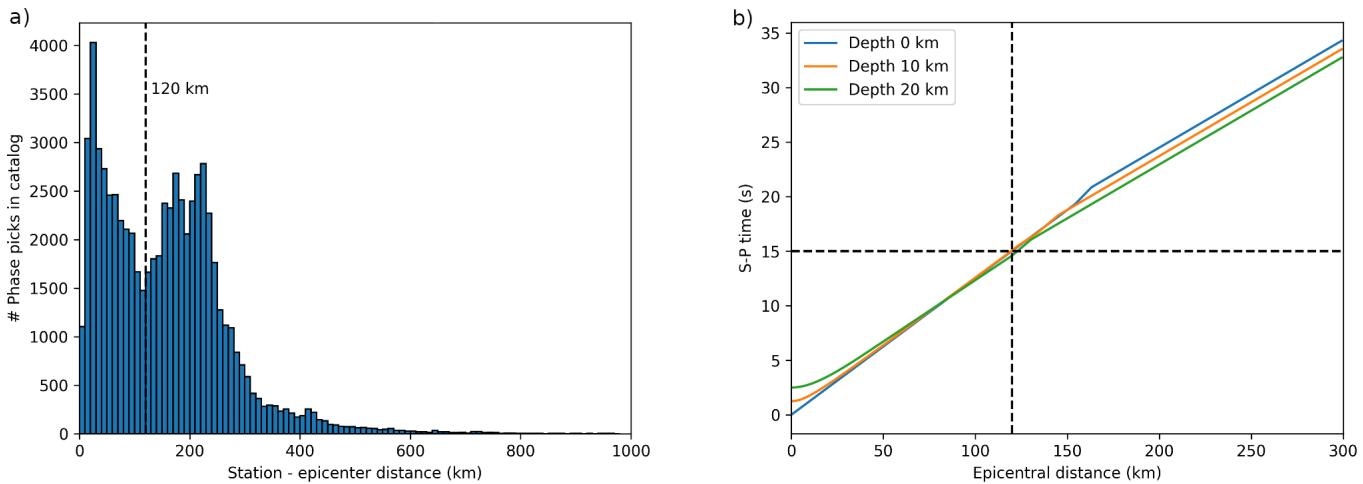


Figure S1. Phase picks used in our study and selection of a 16 s template matching window. a) Distribution of phase picks in the Ayiti-seismes catalog as a function of epicentral distance to the recording station. Dashed black line marks 120 km distance, the maximum epicentral distance considered in our study. b) Modeled S-P times as a function of epicentral distance for different depths considering the IASPEI91 velocity model (Kennett and Engdahl, 1991). Based on the model we choose to use a 16 s window for our template matching procedure.

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TABLE S1.
Seismic stations used in this study with first and last available dates during the study interval.

Network	Station	Channel code	First available date	Last available date	Number of available days
AY	PAPH1	HH	06.05.2022	31.12.2022	238
CN	LGNH	HH	01.01.2021	31.12.2022	652
CU	SDDR	BH	14.08.2021	31.12.2022	385
DR	SC01	BH	14.08.2021	31.12.2022	428
DR	SDD	BH	14.08.2021	31.12.2022	400
HY	CDELM	EH	09.02.2021	09.02.2021	1
HY	CGONA	EH	14.01.2021	31.12.2022	590
HY	CHINC	EH	23.07.2021	23.12.2022	173
HY	CMOCA	EH	10.10.2022	31.12.2022	81
HY	CPACO	EH	01.01.2021	31.12.2022	672
HY	CTORC	EH	10.02.2021	20.10.2021	98
HY	NCAP1	EH	24.07.2021	22.08.2022	376
HY	NCORM	EH	01.01.2021	31.12.2022	350
HY	NMSNI	EH	14.04.2021	07.10.2021	106
HY	NPIGN	EH	01.01.2021	08.12.2022	460
HY	NQBME	EH	16.04.2021	26.12.2022	258
HY	PPIM	EH	12.06.2022	30.12.2022	136
HY	SANSE	EH	25.03.2021	17.08.2021	57
HY	SAQUI	EH	19.08.2021	01.12.2022	398
HY	SCAYE	EH	01.01.2021	29.12.2022	152
HY	SJACM	EH	11.03.2021	20.08.2022	244
HY	SJER1	EH	09.02.2022	21.11.2022	254
HY	SJER2	EH	01.01.2021	31.12.2022	407
HY	SJER3	EH	16.06.2022	07.10.2022	7
HY	SMESL	EH	01.01.2021	31.12.2022	610
HY	SPRIV	EH	18.08.2021	04.07.2022	174
LO	LOBH	EH	14.08.2021	31.12.2022	410
LO	LODA2	EH	14.08.2021	31.12.2022	498
LO	LODU1	EH	14.08.2021	31.12.2022	505
LO	LONA2	EH	14.08.2021	31.12.2022	406
LO	LONE3	EH	14.08.2021	31.12.2022	497
LO	LOVI	EH	14.08.2021	31.12.2022	498
Z2	BFIN	HH	25.08.2021	31.12.2022	494
Z2	CAMPP	HH	02.10.2021	31.12.2022	400
Z2	CAVA	HH	26.08.2021	31.12.2022	379
Z2	CHARD	HH	27.08.2021	31.12.2022	492
Z2	HASL	HH	22.08.2021	31.12.2022	375
Z2	HBAR	HH	18.08.2021	01.02.2022	142
Z2	LBOR	HH	27.08.2021	02.09.2022	26
Z2	PBEAU	HH	26.08.2021	31.12.2022	493
Z2	PEST	HH	25.08.2021	31.12.2022	363
Z2	ROCH	HH	26.08.2021	31.12.2022	493
Z2	SALO	HH	02.10.2021	31.12.2022	380
Z2	STTHE	HH	26.08.2021	31.12.2022	491
Z2	TROU	HH	25.08.2021	31.12.2022	494
Z2	UR01	HH	21.01.2022	21.02.2022	32
Z2	UR02	HH	21.01.2022	22.02.2022	33
Z2	UR03	HH	21.01.2022	21.02.2022	30
Z2	UR04	HH	25.01.2022	21.02.2022	28

8 Signal-to-noise ratio analysis of cataloged phase picks

9 As part of our assessment of the impacts of the DeepDenoiser model in our dataset, we apply the denoiser to every P-phase
10 pick listed in the Ayiti-seismes catalog. We calculate the signal-to-noise ratio (SNR) of both the raw and denoised signals and
11 compare results in Figure 3. We calculate SNR using a 5 s window after the phase pick as signal, and a 5 s window prior as
12 noise. Our results show an average SNR improvement of 4.7 dB in the denoised signals. However our estimates also reveal a
13 group of signals with negative SNR when using the raw signals, which become even more negative after denoising. A visual
14 inspection of these events (Figure S2) reveals that they correspond to imprecisely picked phase arrivals in the catalog. These
15 incorrect picks exhibit a systematic delay to the actual P-phase arrival, likely due to the STA/LTA system, which becomes
16 more evident after denoising.

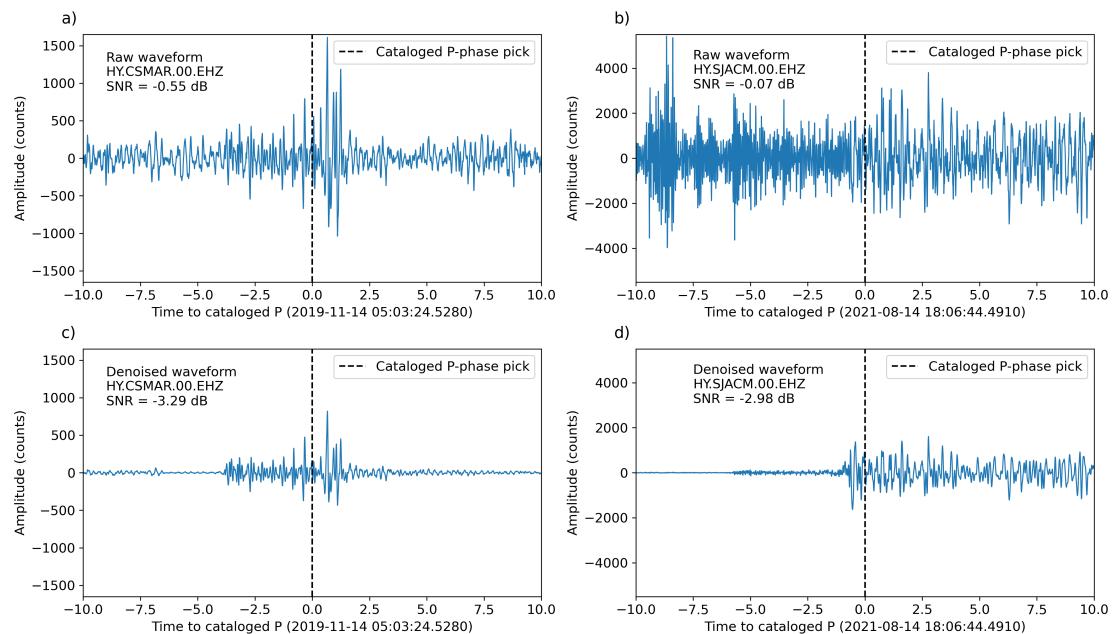


Figure S2. Example of catalog P-phase picks showing a negative estimated SNR. (a) and (b) show the raw waveforms (only with trend removed) for two different events at stations CSMAR and SJACM, respectively, and (c) and (d) the corresponding denoised waveform. The P-phase pick listed in the Ayiti-seismes catalog is marked at 0 s.

17 Magnitude Estimation

18 As noted in previous studies (Zhu et al., 2019; Yang et al., 2022), DeepDenoiser tends to distort waveforms and clip peak
 19 amplitudes. Thus, the estimated magnitudes are not comparable to those estimated from the original waveforms. Therefore,
 20 we follow a different approach and apply relative magnitude estimation, a method commonly used in template matching
 21 detection studies (e.g. Peng and Zhao, 2009; Neves et al., 2022, 2024).

22 Relative magnitudes can be estimated by comparing the waveforms of a new detection with those of a cataloged event
 23 using:

$$24 M_{New} = M_{Cat.Event} + c \times \log_{10} \alpha, \quad (S1)$$

25 where M_{New} is the estimated magnitude, $M_{Cat.Event}$ is the magnitude of the cataloged earthquake, c is a calibration constant,
 26 and α is the amplitude ratio between the new detection and the cataloged event. We calculate the amplitude ratio by com-
 27 paring the peak amplitudes of the new detection and the cataloged event following the method described in Neves et al.
 28 (2022) based on Shelly et al. (2016)'s method, but with amplitude ratios determined by the peak amplitude instead of using
 29 a principal component fit of the waveforms. c is determined by comparing each cataloged event's estimated magnitude and
 30 peak amplitude with those of all other cataloged events that correlate with a cross-correlation coefficient ≥ 0.6 , and then fit-
 31 ting the resulting pairs by least-squares. We determine c for bandpass-filtered, denoised, and bandpass-filtered-plus-denoised
 32 waveforms, finding a consistent value of 0.89 for all cases (Figure S3).

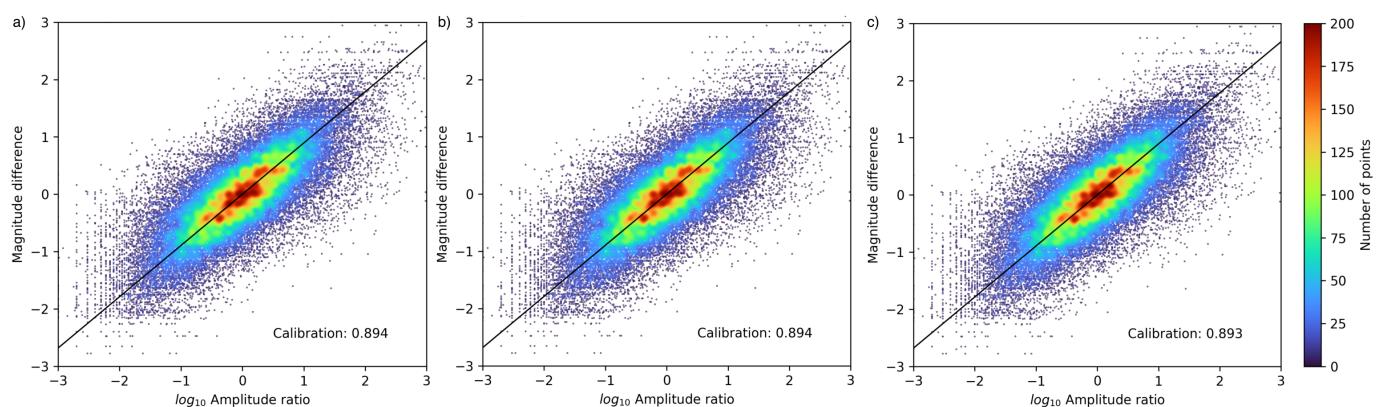


Figure S3. Magnitude calibration for relative magnitude measurements. Figures show the distribution of similar templates magnitude differences as a function of the corresponding templates logarithm of peak amplitude ratio for a) raw waveforms, b) band-pass filtered 2-16 Hz waveforms and c) denoised waveforms. Similar calibration factors are estimated for the three cases, suggesting that DeepDenoiser distorts the waveforms in similar ways, retaining the relative amplitude information.

33 **Relocated catalog and missed earthquake detections**

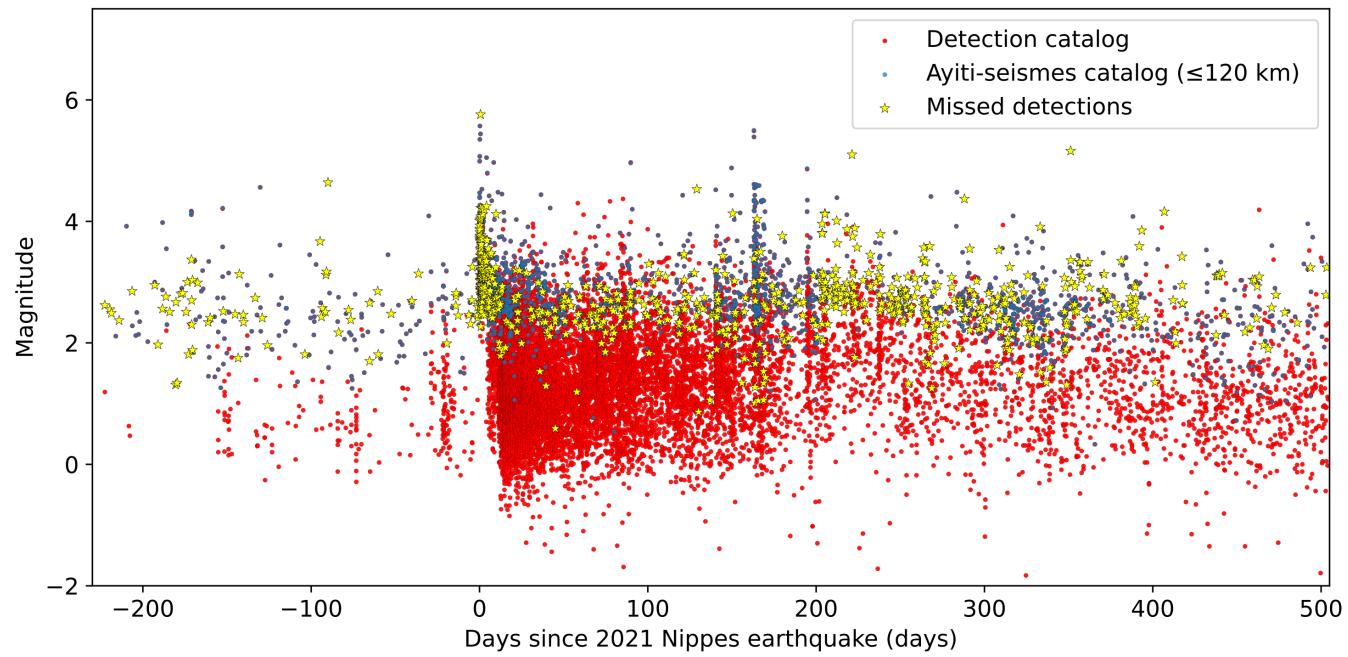


Figure S4. Detections missed by our denoising plus template matching workflow. Magnitude distribution with time of the detection catalog (red) and the Ayiti-seismes catalog (blue). Missed detections due to the requirement of at least 4 recording stations in a 120 km radius are marked by yellow stars.

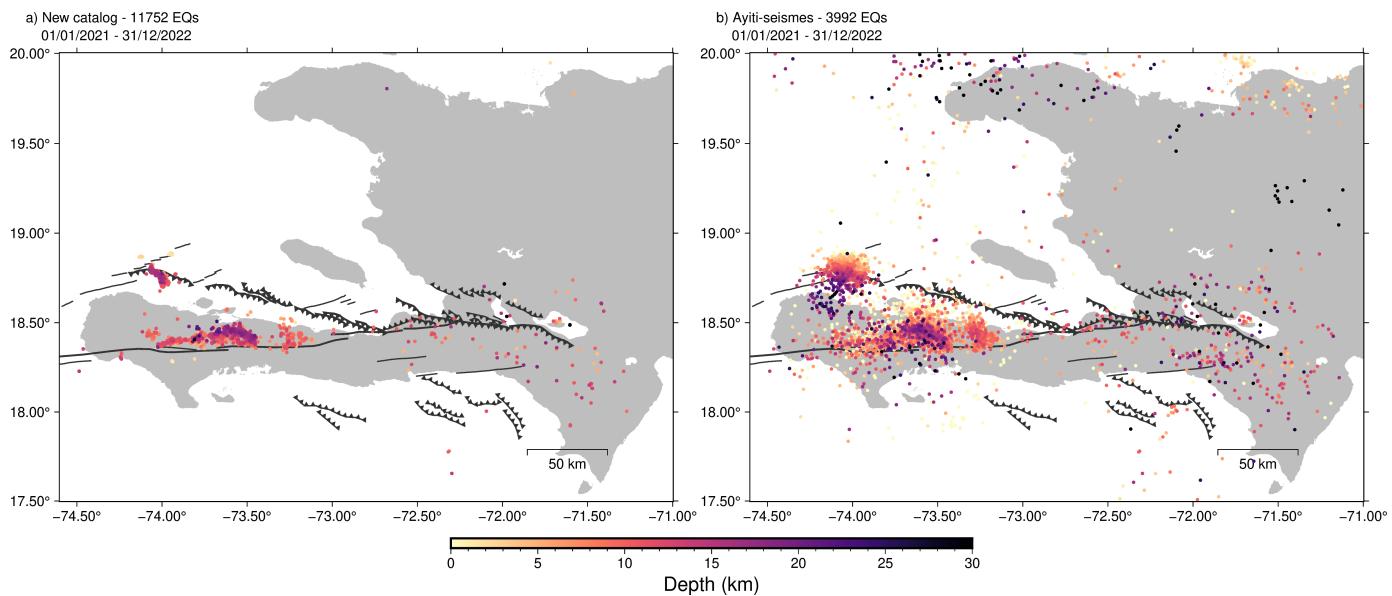


Figure S5. Catalog comparison of the entire area covered by our new relocated catalog with the Ayiti-seismes earthquake catalog. a) New catalog resulting from denoising, template matching detection, and cross-correlation relocation. b) Catalog from the Ayiti-seismes platform. Color denotes event depth.

Additional Jérémie basin clusters

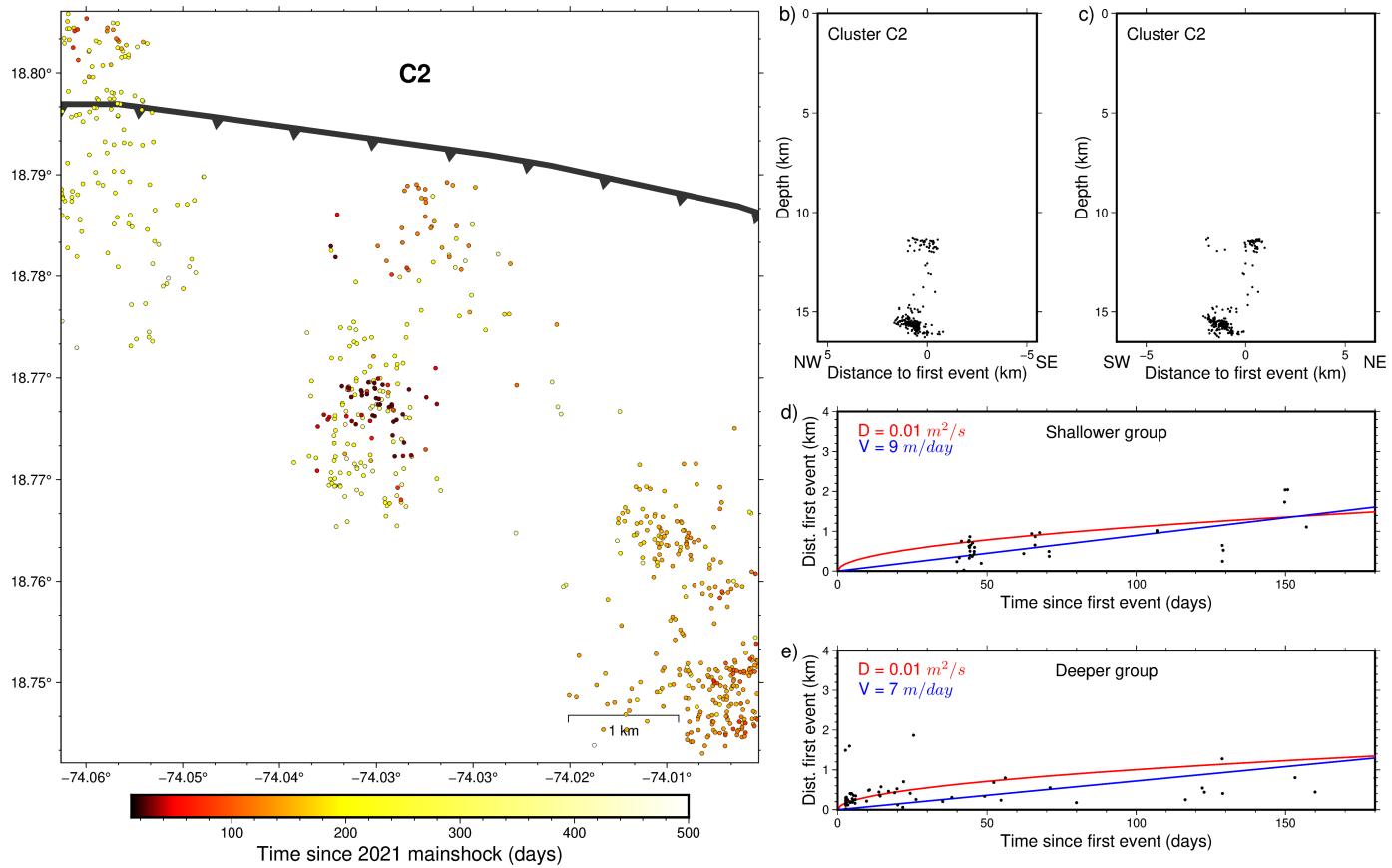


Figure S6. Jérémie basin C2 cluster (see Figure 9). a) Hypocenter distances to the first event in the cluster as a function of time and faults with surface expression identified in [Calais et al. \(2023\)](#). b) Cross-section of major cluster in the area along NW-SE direction. c) Cross-section along SW-NE direction. d) Distribution of the shallower events (above 14 km) in the cluster with time in relation to the first event. Red line denotes the best fit to a square root front and blue line the best fit to a linear front. e) Same as (d) for the deeper events (below 14 km depth).

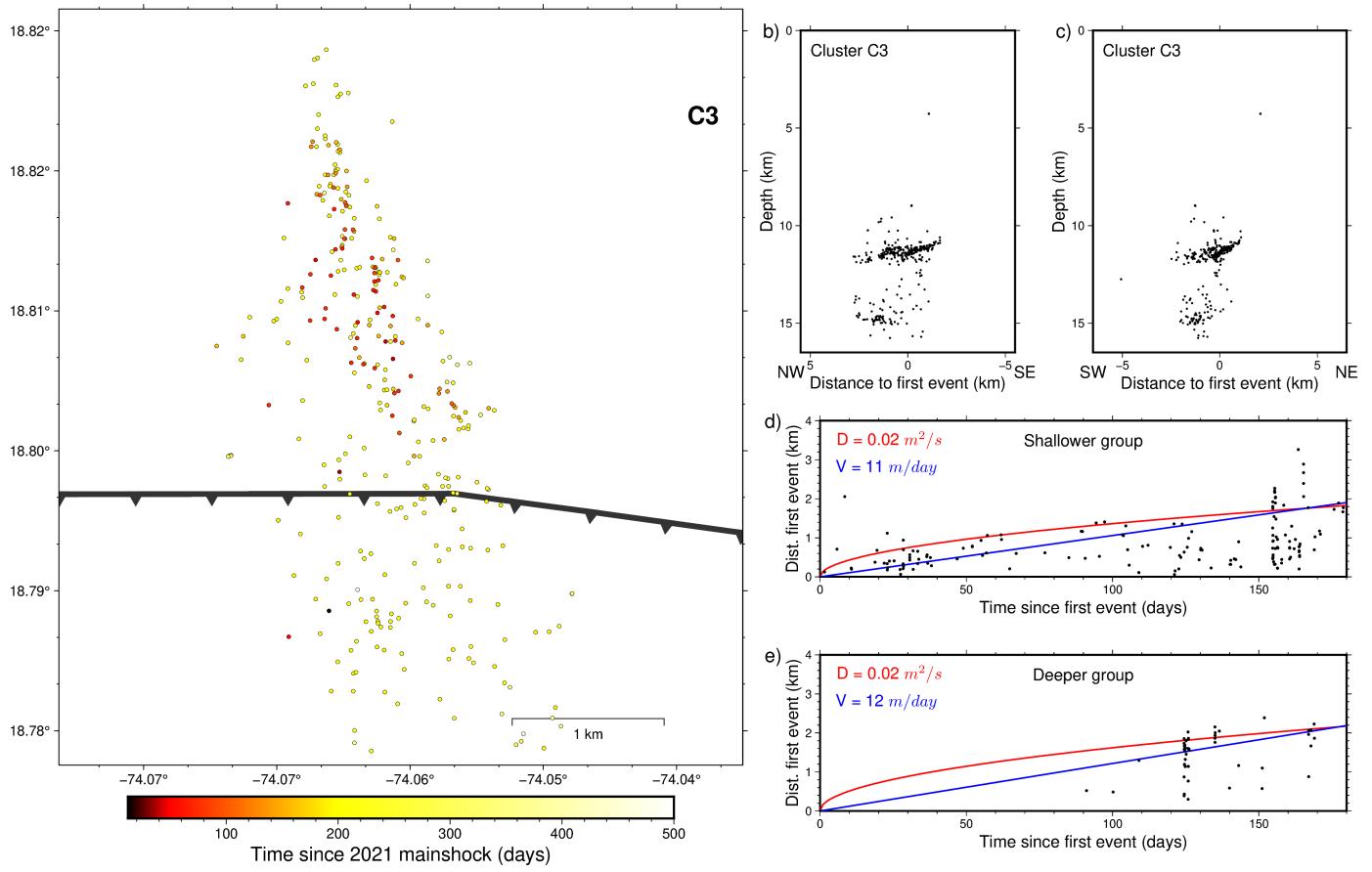


Figure S7. Jérémie basin C3 cluster (see Figure 9). a) Hypocenter distances to the first event in the cluster as a function of time and faults with surface expression identified in [Calais et al. \(2023\)](#). b) Cross-section of major cluster in the area along NW-SE direction. c) Cross-section along SW-NE direction. d) Distribution of the shallower events (above 14 km) in the cluster with time in relation to the first event. Red line denotes the best fit to a square root front and blue line the best fit to a linear front. e) Same as (d) for the deeper events (below 14 km depth).

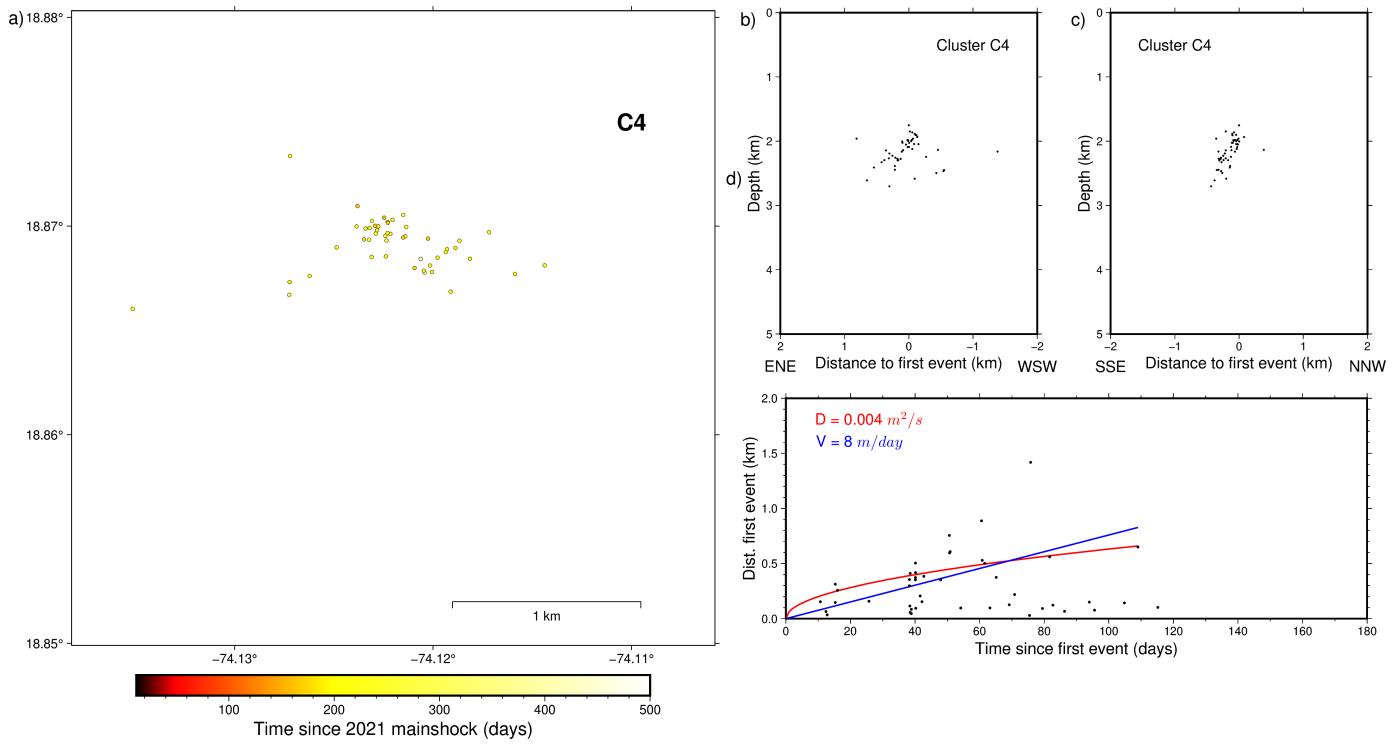


Figure S8. Jérémie basin C4 cluster (see Figure 9). a) Hypocenter distances to the first event in the cluster as a function of time. b) Cross-section of major cluster in the area along ENE-WSW direction. c) Cross-section along SSE-NNW direction. d) Distribution of events in the cluster with time in relation to the first event. Red line denotes the best fit to a square root front and blue line the best fit to a linear front.

35 **Description of supplemental datasets**

36 **Supplemental Dataset S1:** publication_detection_catalog.txt

37 Catalog containing detected events using the template matching detection on denoised waveforms followed by a bandpass
38 filter. It includes events only associated with local templates.

39 File format: DetID, YYYY, MM, dd, hh, mm, ss.sss, lat, lon, depth, mag

40 DetID: detection numeric identifier

41 YYYY: year of earthquake origin time

42 MM: month

43 dd: day

44 hh: hour

45 mm: minute

46 ss.sss: seconds

47 lat: latitude(degrees)

48 lon: longitude(degrees)

49 depth: depth in km

50 mag: earthquake magnitude

51 **Supplemental Dataset S2:** publication_relocation_catalog.txt

52 Catalog containing relocated events using cross-correlation-derived differential travel-time information.

53 File format: DetID, YYYY, MM, dd, hh, mm, ss.sss, lat, lon, depth, e_xx, e_yy, e_z, rms, mag

54 DetID: detection numeric identifier

55 YYYY: year of earthquake origin time

56 MM: month

57 dd: day

58 hh: hour

59 mm: minute

60 ss.sss: seconds

61 lat: latitude(degrees)

62 lon: longitude(degrees)

63 depth: depth in km

64 ex: North-South uncertainty (m)

65 ey: East-West uncertainty (m)

66 ez: depth uncertainty (m)

67 rms: root mean square of the differential times

68 mag: earthquake magnitude

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