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**A unifying basis for the interplay of stress and chemical processes
in the Earth: support from diverse experiments**

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Abstract

Interplay between stress and chemical processes is a fundamental aspect of how rocks evolve, relevant for understanding fracturing due to metamorphic volume change, deformation by pressure solution and diffusion creep, and the effects of stress on mineral reactions in crust and mantle. There is no agreed microscale theory for how stress and chemistry interact, so here I review support from eight different types of experiment for a relationship between stress and chemistry which is specific to individual interfaces: (chemical potential) = (Helmholtz free energy) + (normal stress at interface) \times (molar volume). The experiments encompass conditions 25 to 1300 degrees C and pressure from 1 bar to 1.8 GPa. The equation applies to boundaries with fluid and to incoherent solid-solid boundaries. It is broadly in accord with experiments that describe the behaviours of free and stressed crystal faces next to solutions, that document flow laws for pressure solution and diffusion creep, that address polymorphic transformations under stress, and that investigate volume changes in solid state reactions. The accord is not in all cases quantitative, but the equation is still used to assist explanation. An implication is that the chemical potential varies depending on interface, so there is no unique driving force for reaction in stressed systems. Instead, the overall evolution will be determined by combinations of reaction pathways and kinetic factors. The equation described here should be a foundation for grain scale models, which are a prerequisite for predicting larger scale Earth behaviour when stress and chemical processes interact.

Keywords

Stress Chemistry Thermodynamics Kinetics Metamorphism Mineral physics

Background

Pressure influences all chemical reactions, including those that occur in the Earth spanning simple transformations such as diamond to graphite to complex ones including many phases. This implies that stress, a more general state in which forces per unit area are different in different directions, must also influence reactions. Interactions of stress and chemical processes affect many aspects of Earth behaviour such as the rheology of the mantle when undergoing diffusion creep, reactive fluid flow in deforming media and fracturing of minerals due to reaction. One possible cause of intermediate depth earthquakes in subduction zones is the volume reduction during the transformation of basalt to eclogite possibly accommodated by huge stress buildups (Nakajima et al. 2013). These interactions are of practical importance in understanding for example how olivine fractures during serpentinisation, with implications

for CO₂ sequestration (Kelemen et al. 2011). Addition of water to anhydrite, forming gypsum, led to uplift and damage to an entire town, when the solid volume increase of the reaction overcame the weight of overlying rocks (Schweizer et al. 2019); yet elsewhere the same reaction occurred without apparent deformation (e.g. Fig. 2c of De Paola et al. (2008)). These examples show it is important to understand how stress and chemical processes influence each other.

Our understanding of the effect of pressure on reaction is underpinned by conventional (hydrostatic) thermodynamics, but there is no agreed theory on how stress affects reaction and since many parts of the Earth are under stress, this is a significant gap in our understanding. It might be expected that the effects of stress are the same on rocks as on other polycrystalline materials, so that Earth science could call upon such work, but to the writer's knowledge there is no text summarising those effects in any branch of science. There are several widely quoted works on mathematical foundations, but those works are not always tied directly to the experiments conducted in other studies. In Earth science opinions differ on the importance of stress, in terms of the magnitude of effects on chemical equilibrium and even whether equilibrium exists (Hobbs and Ord 2017; Powell et al. 2018; Tajcmanova et al. 2015; Wheeler 2014; Wheeler 2018). Those papers are all based on mathematical arguments and it would be useful to substantiate and test the contrasting predictions through experiments. Here I show that there are several different types of experiments already published over several decades which independently point to the same mathematical description of the effects of stress on chemical processes: namely, a single equation that applies at interfaces between crystals and relates local stresses to chemistry.

To proceed, definitions of pressure and stress are needed. Pressure strictly is used to imply an isotropic state of stress, in which the force per unit area is the same in all directions; commonly the phrase "hydrostatic pressure" is used to add clarity. "Stress", which is a second rank tensor σ from which the force per unit area on a notional surface of any orientation can be deduced. In this contribution compressive stresses are taken as positive. The word "pressure" has been used in different ways in different works both within and outside Earth science. Some works define pressure as the average of the three principal stresses: here, to avoid ambiguity, I call this the "mean stress" σ_m . It is a simple and unique function of the stress tensor. Other works sometimes use the word pressure for the force per unit area across a particular interface, the "normal stress" σ_n . This value depends on the interface orientation. It can have different values even for a single stress tensor because interfaces of different orientation are always present in a polycrystal. The symbol P might also be used to indicate hydrostatic pressure in a reference system (not the actual system), pressure in one part of a system and so forth; I point out its differing meanings in the works I review.

In this contribution I give a brief mathematical background and then show how descriptions of eight different types of experiment are in accord with a particular equation. Each work uses different language and notation, so it is necessary to explain some details to illustrate the extent to which the works overlap. Then I discuss the consequences of the equation, for a broader perspective on what the experiments tell us and to show how it should form a key part of grain scale mathematical models: such models are a prerequisite for predicting larger scale behaviour.

Brief mathematical framework

Some maths is required here to understand how the various experiments reviewed are linked back by the authors to basic thermodynamics. The physics of stress is well established; in terms of its chemical effects, although there is controversy, any mathematical description of the effects of stress must reduce to hydrostatic thermodynamics when the stress is isotropic and pressure has a single clearly defined value. In hydrostatic thermodynamics, the Gibbs free energy is a number which is minimised in a system at equilibrium. For each phase it has a functional dependence $G(P, T)$ on pressure and temperature. There is a common assumption that a generalised version of Gibbs free energy must exist in a stressed system, and once the generalised form of P is established, the equations, methods and databases of hydrostatic thermodynamics can be used to calculate equilibria: the choice is to use mean stress. In contrast others (Paterson 1973; Wheeler 2018) argue that there is no Gibbs free energy in a stressed system, and local chemical potentials vary from place to place, governed by different interface orientations and local normal stresses. Both approaches reduce to hydrostatic thermodynamics when stress is isotropic but their predictions are quite different, so clarification is required. Given the ambiguity over the existence of G , I express the mathematics in terms of local chemical potentials.

There is a single equation which applies at an interface and, I will argue, is supported by all the experiments I review:

$$\mu = F + \sigma_n V \quad \text{Eqn. 1}$$

Here μ is chemical potential (of a chemical component with the same composition as the solid), F is the Helmholtz free energy per mole (not itself strongly dependent on stress) and V is the molar volume of the crystalline solid (again not strongly dependent on stress since crystalline solids are not very compressible). Notation used here is summarised in Table 1. The equation indicates that chemical potential is a function of each particular interface and its orientation, and is roughly linear in σ_n , although there are circumstances in which the small non-linear dependence on F on stress also plays a role in explaining experimental results. There are also circumstances in which the curvature of the interface is large enough that surface energy makes a significant contribution. If the surface or interface energy is γ then a term is added as follows.

$$\mu = F + \sigma_n V + \gamma \kappa V \quad \text{Eqn. 2}$$

where κ is the curvature (positive for convex-out surfaces). Since differences in chemical potential drive transport and reaction, and chemical potential depends on interface orientation I argue that there is no chemical equilibrium in a stressed system (Wheeler 2014; Wheeler 2018). In hydrostatic thermodynamics, for a single component solid the chemical potential is equal to the Gibbs free energy per mole as follows:

$$\mu = G = F + PV \quad \text{Eqn. 3}$$

When stress is isotropic, the normal stress is equal to P regardless of interface orientation, and Eqn. 1 reduces to Eqn. 3. Equilibrium is possible since interface orientation no longer appears in the mathematical description. In contrast to Eqn. 1 other works e.g. (Tajmanova et al. 2015; Verhoogen 1951) assert that for a single component solid the chemical potential and Gibbs free energy are as follows:

$$\mu = G = F + \sigma_m V$$

Eqn. 4

where σ_m is the mean stress - not dependent on any particular interface. Again, this reduces to Eqn. 3 when stress is isotropic.

Eqn. 1 was proved by Gibbs for a stressed solid next to a fluid. Disputes arise when its use is extended to solid/solid boundaries, and confusion arises when there is an absorbed aqueous film along a solid/solid boundary. Such films are commonly described as “fluid films” and then may be incorrectly thought to be at fluid pressure P_f , but in general they carry stress (Gratier et al. 2013; Wheeler 2018). I assert that existing theoretical work in Earth and other branches of science justifies the use of Eqn. 1 at all interfaces (Wheeler 2018), but I realise that theoretical arguments on their own are not conclusive, in terms of whether the theory is accepted and how it is to be applied. So, in this contribution I summarise 8 different types of experiment (Table 2, Figure 1) that support Eqn. 1, and in some instances explain why the experiments contradict Eqn. 4. Because use of G is at best ambiguous in stressed systems, it is necessary to rephrase the mathematical development used in published works in terms of chemical potential, without changing the actual mathematical results. When the overall “driving force” for a reaction is written as ΔG , I suggest it is better to use affinity A . In a hydrostatic system, $A = -\Delta G$. In a stressed system A can be written as a difference between chemical potential of reactants and products - according to Eqn. 1 that will be dependent on the interfaces involved. In Wheeler (2014) I used the idea of a reaction pathway to describe which interfaces are involved in reaction. This is relevant for relating the various experiments I review to each other, and the pathways are shown by grey arrows in Figure 1. The experiments are directly related to Earth science but some involve soluble salts and overlap with other research fields.

Figure 1 Summary of systems discussed.

Chemical potential and local stresses cannot easily be measured directly, so there are inferences built into the justification of Eqn. 1 which will be discussed in each case. It can be used to formulate driving forces for various processes, using some mathematical details summarised in Appendix 1. In all the processes discussed, kinetics are important and are not always easy to quantify, and stress is generally heterogeneous. Despite these issues, I will show that Eqn. 1 provides explanatory power.

Experimental support for the equation

1. Stressed solid next to fluid

This first section discusses “free” surfaces of solids next to fluids. Mechanical equilibrium at the surface dictates that fluid pressure P_f equals normal stress σ_n in the solid. If σ_n is fixed, changes in tangential stresses σ_t might give rise to observable effects: changes in the chemical potential of the solid will give rise to changes in local equilibrium concentration in the fluid.

Ristic et al. (1997) grew alum from a supersaturated solution, comparing unstressed crystals with others under tension. The tensile stress led to a reduction in growth rate relative to the unstressed state. The alum deformed plastically to a small extent but the work shows that the dislocations involved could not have influenced growth kinetics. The growth rate will be a function of the affinity (driving force) $A = \mu^{solution} - \mu^{solid}$. A slower growth rate would be in accord with the chemical potential of the solid under stress (with tangential stress $\sigma_t \neq$

normal stress σ_n) being higher than its value under unstressed conditions, reducing the affinity. McLellan (using Eqn. 1) shows that, regardless of whether the tangential stress is relative tension or compression, the chemical potential always increases under stress; a version of that is shown in Appendix 1. Consequently, the driving force for growth is smaller in the stressed situation, in accord with the observed slower growth rate. In contrast Eqn. 4 predicts that “the potential is thus increased by a compression, decreased by a traction” (Verhoogen 1951). Thus, crystals under tension (from context, his “traction” means tension) would decrease their solubility, and the growth rate should be faster. Eqn. 4 is therefore not in accord with observations.

Morel and den Brok (2001) undertook experiments on crystals under compressive as well as tensile stress. They chose sodium chlorate (NaClO_3) because it has elastic–brittle mechanical behaviour at room temperature, thus avoiding any complications introduced by plastic deformation. In each experiment they drilled a hole in the crystal to create a heterogenous stress state, with varying states of tangential stress around the hole (including compressive and tensile). The fluid involved was “saturated sodium chlorate solution” (i.e. a solution that would be in equilibrium with an unstressed crystal at 1 atm), with a small additional dilution, so dissolution of the solid would be expected. They compared the dissolution behaviour of stressed and unstressed crystals. Regardless of whether the tangential stress was tension or compression, they found that stressed crystals dissolved faster than unstressed ones. They quantified the excess driving force due to stress in terms of the change in elastic strain energy given as their eqn 1.

I give a more general justification of their equation (based on Eqn. 1 here) in Appendix 1. Their discussion can therefore be rephrased in terms of changes in μ given by Eqn. 1. Morel and den Brok (2001) use this to show that the change in driving force ($\Delta\mu$) for dissolution due to stress (~ 0.1 J/mol) is minor in comparison to the driving force due to undersaturation (~ 60 J/mol), yet the actual change in dissolution rate is disproportionately large. Therefore, these experiments are in *qualitative* agreement with Eqn. 1 in terms of sign, but not quantitative agreement. One explanation may relate to instabilities and roughening of the stressed surface which might modify the average dissolution rate. Such instabilities are discussed in the next section.

Ostapenko et al. (1972) undertook experiments on stressed halite in solution, motivated by the need to understand, in their words, “two diametrically opposed theories” about the chemical potential of a solid under conditions of non-hydrostatic stress. They are referring to the difference between Eqn. 1 (they cite Gibbs) and Eqn. 4 (they cite Verhoogen (1951)). This is a reminder that the controversy I mention here is not new. One aspect of their interpretation requires modification (Appendix 3) but this does not affect their conclusion. In brief, they used an optical method to detect minute changes in concentration adjacent to a crystal of halite in solution. They applied compressive stresses and found no detectable changes in concentration adjacent to the crystal. They argued that Eqn. 4 predicts changes in concentration large enough that their method would have detected them, while Eqn. 1 predicts concentration changes below detectability limit. Consequently, this paper rejected Eqn. 4 in favour of Eqn. 1.

2. Stressed solid next to fluid - instabilities

Asaro and Tiller (1972) and Grinfeld (1986) show mathematically that a stressed planar interface is chemically unstable with respect to the development of periodic undulations above a certain wavelength, named after these works as Asaro-Tiller-Grinfeld (ATG) instabilities. In an undulation, the normal stress remains fixed but the normal direction varies spatially. The stress field near the surface is then non-uniform, though it becomes uniform over a distance of a few wavelengths inside the solid (Srolovitz 1989).

Figure 2

Figure 2 shows that in this non-uniform stress state the elastic strain energy (Helmholtz free energy) is more in a trough than in a peak. In accord with Eqn. 1 and setting $\sigma_n = 0$, there is a chemical potential difference between troughs and peaks. This is a driving force for dissolution in troughs and precipitation at peaks, so any perturbation will amplify regardless of wavelength. However, the surface energy provides an opposite effect. The troughs are concave outwards and peaks are convex outwards, so there is a driving force for peaks to dissolve and material to precipitate in troughs, and any perturbation will diminish: the minimum energy configuration is a flat surface. For short wavelengths the surface energy effect dominates but for long wavelengths λ the stress effect dominates and perturbations are predicted to amplify for

$$\lambda > \lambda_0 = \frac{\pi\gamma E}{\sigma_t^2}.$$

where γ is surface energy. There is a wavelength at which a maximum growth rate is predicted, a small multiple of λ_0 depending on the kinetics (e.g. surface diffusion, volume diffusion, evaporation-condensation).

den Brok and Morel (2001) put crystals of alum under compressive stress in a slightly undersaturated solution and discovered that instabilities develop. As in their experiments on sodium chlorate described above, they drilled a hole in the crystal to create a heterogeneous stress field. They found grooves and the groove spacing in some experiments was smaller at higher stress. To explain this, they used what Srolovitz called a crude initial estimate of critical wavelength

$$\lambda'_0 = \frac{8\gamma E}{\sigma_t^2}.$$

which is larger than λ_0 but a reasonable guide to the dominant wavelength that would develop (since that is a small multiple of λ_0).

Figure 3

They showed that for a local amplified stress of 15 MPa near the hole, wavelength is predicted to be 35 μm and observed as 20-40 μm (Figure 3). Such agreement indicates that ATG theory, based on Eqn. 1, has explanatory power, though more experiments are needed to consolidate the link to theory.

In subsequent sections I deal with situations in which the second order terms in stress do not have a significant effect, so equations 1 and 3 can both be considered linear in stress.

3. Pressure solution

Pressure solution is a deformation mechanism where strain is accommodated by diffusion of material through an aqueous grain boundary film from interfaces with high normal stress to those with low normal stress. The film “should only with the greatest care be treated as continuous with the fluid in the pore space and is perhaps better treated as a separate thermodynamic phase” (Gratier et al. 2013); it is itself stressed. As material moves away from high stress interfaces, shortening occurs parallel to σ_1 , and as the material precipitates at low stress interfaces, extension occurs parallel to σ_2 and/or σ_3 . Natural microstructures provide evidence for this, most clearly when the regions of precipitation have distinct features. Pore water may form part of the diffusion path in porous aggregates.

The form of the flow law in deformation experiments can be described by strain rate being proportional to (stress)ⁿ x (grain size)^{-p}. Other quantities such as temperature are involved but it is the exponents n and p which are relevant here as they give insight into the underlying processes. In experiments on pressure solution there are often two key features: first, strain rate is linear in differential stress (n = 1) and secondly it is inversely proportional to the cube of grain size (p = 3). Figure 4 shows an example for pressure solution of halite.

Figure 4

A flow law fitting such observations can be derived theoretically beginning with a local equilibrium relationship between chemical potential and stress at an interface (e.g. Rutter (1983) eqn 2)

$$\mu = U - TS + \sigma_n V \quad \text{Rutter eqn 2}$$

which is the same as Eqn. 1 above. The local equilibrium is between the stressed solid and its dissolved form in the adjacent grain boundary film or in an adjacent pore fluid

$$\mu = \mu^{gbf} \text{ or } \mu = \mu^{pf} \quad \text{Eqn. 5}$$

In pressure solution, we have long range diffusive transport from high stress interfaces to low stress interfaces, through the grain boundary film. The driving force is then, for a single chemical component and ignoring σ_2 for simplicity,

$$A = \mu_1^{gbf} - \mu_3^{gbf} = (F + \sigma_1 V) - (F - \sigma_3 V) = (\sigma_1 - \sigma_3) V \quad \text{Eqn. 6}$$

Note this quantity is not normally thought of as a chemical affinity, but it is consistent with other usage to call it that. The driving force is linear in the differential stress, so the strain rate is linear in differential stress, as observed (Newtonian viscosity), unless some kinetic factors are nonlinear. The full derivation of the flow law has been presented many times (Gratier et al. 2013; Rutter 1976; Rutter 1983). If local equilibrium is assumed between the stressed solid and the solid dissolved in the immediately adjacent grain boundary film, so diffusion is the main rate controlling step, then

$$\dot{\epsilon} = B \frac{DcV^2w}{RTa^3} (\sigma_1 - \sigma_3) \quad \text{Eqn. 7}$$

(e.g. (Rutter 1976)) where $\dot{\epsilon}$ is strain rate, B a dimensionless constant, D is grain boundary diffusion coefficient, c is concentration of solute in grain boundary (mol/m^3), w is grain boundary width, R the gas constant and a the grain size. The constant B depends on microstructural details such as porosity (Keszthelyi et al. 2016) and grain shape (Wheeler 2010), but what matters here is that the flow law predicts $n = 1$ and $p = 3$.

de Meer and Spiers (1995) show that for gypsum deforming by pressure solution, under certain circumstances the strain rate is proportional to the inverse grain size ($p = 1$). This is explained considering that dissolution and precipitation of the solid may be difficult; for example for precipitation, though to be rate controlling for gypsum, we require supersaturation in the pore fluid

$$\mu < \mu^{pf}.$$

This means that the chemical potential difference $\mu_1^{gbf} - \mu_3^{gbf}$ which drives diffusion in particular is no longer derived from Eqn. 6 and the flow law is modified by dissolution and precipitation rate terms e.g. Table 2.3, eqns 2.33 of Gratier et al. (2013). However, the key point is that Eqn. 1 still underpins the derivation of the flow law via their eqn 2.14 (Eqn. 6 here).

Eqn. 4 has never been used to explain pressure solution phenomena, and it is difficult to see how it could help. For example, suppose we stress a single phase polycrystal uniformly. Then Eqn. 4 predicts that G and chemical potential would have a single value everywhere, and there would be no driving force for deformation by chemical transport.

4. Diffusion creep

Diffusion creep is similar to pressure solution except the grain boundaries are essentially dry (there may be some water molecules which enhance diffusion rates but there is no aqueous film) and an additional diffusion pathway may act through grain interiors by volume diffusion. Elliott (1973) first highlighted the similarities between pressure solution and diffusion creep. Karato et al. (1986) found a deformation regime in fine grained olivine where the stress exponent was $n \sim 1.4$ and the grain size exponent $p \sim 2-3$. To explain this they called upon flow laws such as derived by Raj and Ashby (1971). To derive that flow law, that work states the following.

“Chemical equilibrium in the boundary plane means that the chemical potential μ , of vacancies at, and immediately adjacent to a point on the boundary is related to the normal stress σ_n , acting on the boundary at that point:

$$\mu = \mu_0 - \sigma_n \Omega \quad [\text{Raj and Ashby (1971) eqn B2}]$$

where Ω is the atomic volume, and μ_0 the chemical potential appropriate to a stress-free reference state”. Noting that the chemical potential of a vacancy is minus the chemical potential of the missing atom, this is the same as Eqn. 1 except that the relatively small second order stress terms in the Helmholtz free energy have been neglected. Larché and Cahn (1985) include the second order term but reiterate it is relatively small and can be neglected under many circumstances.

Raj and Ashby (1971) present flow laws (their eqns 22 and 23) with $n = 1$, and $p = 2$ (for volume diffusion) or $p = 3$ (for grain boundary diffusion). For the latter, using notation as in Eqn. 7,

$$\dot{\epsilon} = B \frac{DV_w}{RTa^3} (\sigma_1 - \sigma_3)$$

Eqn. 8

Note that the two equations have the same form except that the concentration c is missing in Eqn. 8; the two equations are reconciled by recognising that the concentration c of a material in a solid boundary is equal to $1/V$, and putting $cV = 1$ in Eqn. 7 gives Eqn. 8. The values of D are very different between pressure solution and diffusion creep but the *form* of the flow law is the same.

Using the flow laws for lattice and grain boundary diffusion creep Karato et al. (1986) appeal to volume diffusion (as they find p near 2) under dry conditions and grain boundary diffusion (as they find p near 3) in wet conditions. The stress exponent $n > 1$ due to the operation of other deformation mechanisms in parallel with diffusion creep. As for pressure solution, then, Eqn. 1 can be used to help explain the observed rheologies.

5. Force of crystallisation – single solid

Force of crystallisation is a phrase which covers several phenomena in which stress and chemical processes interact and is related to pressure solution. I suggest it is useful to distinguish two “end member” scenarios in which the phrase is used.

1. Experiments where dead weights are rested on crystals growing from supersaturated solutions (such as alum, Becker and Day (1916)). The crystal may be lifted, showing that the chemical process of crystallisation causes work to be done against an applied force. Here the force is applied externally, does not change, and the system is not confined.

2. Experiments where a solid reaction is mediated by fluid, and involves a solid volume increase, and occurs in a confined space may result in forces (Wolterbeek et al. 2016; Wolterbeek et al. 2017). The chemical processes give rise to stress, which can play a role in fracturing and lead to practical engineering problems. Because of the confinement, the volume change cannot be manifest, instead volume is conserved and elastic stresses increase. Force is developed internally, it builds up through time, and the system is confined.

These are “end member” scenarios and in reality confined experiments may allow some displacements, for example because the confining vessel is elastic (Wolterbeek et al. 2017) or deforms plastically (Ostapenko and Yaroshenko 1975). In both scenarios, some kind of chemical disequilibrium (e.g. CaO in the presence of water, water supersaturated with alum) causes new and existing phases to grow with some contribution from transport along aqueous grain boundary films *into* interfaces under high stress.

Correns (1949) undertook experiments in which a crystal of alum was placed in a supersaturated solution, with a force applied from above by a weighted lever and pushrod. The sideways stress on the crystal was 1 atm, since the system was not confined, and the vertical stress was > 1 atm in accord with the pushrod force and the area over which it was applied. Despite the “extra” vertical force, crystal growth displaced the pushrod upwards; the maximum stress that would still allow upwards displacement of the pushrod depended on the level of supersaturation in the solution. At low supersaturations the relationship was linear and at high supersaturations it was nonlinear and also depended on the crystal face being loaded (Figure 5).

Figure 5

The figure includes a theoretical curve and to understand this we need an expression for chemical potential in stressed interfaces. When these potentials are lower than those in the surroundings, inwards diffusion will occur along the interface, and upwards displacement can

occur. Correns provided a framework for explaining the observations, but Flatt et al. (2007) point out various ambiguities so here we will refer to their subsequent commentary. Considering growth of a crystal from supersaturated solution, Steiger (2005) states “the chemical potential μ_p of a crystal face under pressure p takes the form” (his eqn 4, verbatim)

$$\mu_p = \mu_0 + w + p V_m \quad \text{Eqn. 9}$$

Despite describing p as “pressure”, from context it is clear the system is not under hydrostatic (isotropic) pressure p , but p is actually the normal stress across a loaded interface - so I choose here to rename the chemical potential in a stressed interface as μ_σ . Steiger defines μ_0 is the chemical potential of the solid in the unstressed reference state, and w as molar [elastic] strain energy, so that $\mu_0 + w = F$. Noting that V_m is the molar volume of the solid in the stressed state, his eqn 4 is seen to be the same as Eqn. 1 here. Chemicals will diffuse into a stressed interface from a pore fluid if affinity $\mu^{pf} - \mu_\sigma = A > 0$ so the maximum stress that can be supported is when those two chemical potentials are equal. Because the alum solution has more than one ionic species in solution it is sensible to write the relationship in terms of activity; the link to concentration comes later.

$$\mu^{pf} = \mu_0^{pf} + RT \ln(a/a_0)$$

where μ_0^{pf} is a reference chemical potential at reference activity a . Choosing this reference as the chemical potential of the solid under hydrostatic pressure p , written here as μ_p then this equation can be expressed in terms of the activity a_s of dissolved material that would be in equilibrium with that solid *at hydrostatic pressure p* , i.e. the activity at which the solution is saturated.

$$\mu^{pf} = \mu_p + RT \ln(a/a_s).$$

Then the maximum stress that can be sustained is when $A = 0$ and

$$\mu_\sigma = \mu_p + RT \ln(a/a_s).$$

But μ_σ and μ_p are both given by Eqn. 1. Assuming uniform stress in the crystal, the Helmholtz free energy has the same value on stressed and free interfaces, as does the molar volume, so

$$F + \sigma V = F + pV + RT \ln(a/a_s).$$

which is rearranged to

$$\sigma - p = \frac{RT}{V} \ln(a/a_s). \quad \text{Eqn. 10}$$

Here the LHS is sometimes referred to as “crystallization pressure”, but it should be noted it is not a pressure: it is the numerical difference between the normal stress on a loaded interface and the pressure in a nearby fluid. When Figure 5 was first drawn, Correns and Steinborn (1939) implicitly assumed that activity was equal to concentration so

$$\sigma - p = \frac{RT}{V} \ln(c/c_e). \quad \text{Eqn. 11}$$

Flatt et al. (2007) and Appendix 2 explain that Correns had not considered the ionic nature of his alum solution, so his equation relating chemical potential to concentration was incorrect; instead

$$\sigma - p = n \frac{RT}{V} \ln(c/c_e). \quad \text{Eqn. 12}$$

where n is about 3.5. The calculated curve in Figure 5 when recalculated no longer fits the data. Rather than modify Eqn. 9, Flatt et al. (2007) suggest that for a number of reasons the measured “pressures” (stresses) were actually higher than those presented, but the original works do not provide enough experimental detail to be sure. Attempts to repeat the experiments have proved difficult (Caruso and Flatt 2014). There are many other experiments, focussed on building stone deterioration, which are interpreted using Eqn. 10 but they are generally complex and are not quite direct tests of the equation.

6. Force of crystallisation – two or more solids

So far we have considered a system with just one solid, and a supersaturated solution. Force of crystallisation is also manifest in systems where reactions involve one solid reacting to another, mediated by and involving fluid. The examples I cite are all hydration reactions, one with CO₂ also involved, where experiments and theory have been compared: lime to portlandite (Ostapenko and Yaroshenko 1975; Wolterbeek et al. 2017), bassanite to gypsum (Ostapenko and Yaroshenko 1975; Skarbek et al. 2018), periclase to brucite (Ostapenko 1976; Zheng et al. 2018) and olivine carbonation (Xing et al. 2018).

In these papers a particular equation appears repeatedly, relating force of crystallisation to the ΔG of reaction, i.e. the change in Gibbs free energy between reactants and products, or departure from chemical equilibrium. Some works assert that G is not defined in a stressed system (Kamb 1961; Paterson 1973; Wheeler 2018), therefore such expressions should be treated with care. However, in the equation below it is defined as the ΔG the reaction would have if all reactants and products were under hydrostatic fluid pressure P, which remains a well-defined number (from context, it means $G(\text{reactants}) - G(\text{products})$). Then

$$\sigma - p = \frac{\Delta G}{\Delta V_s}. \quad \text{Eqn. 13}$$

using my notation and where ΔV_s is the *solid* volume change per mole. Note the similarity with Eqn. 11 except instead of V we have ΔV_s in the denominator. There is some uncertainty over this equation, for example (Kelemen et al. 2011) write “the volume used in the denominator of [their] Equation 7 should *probably* be ΔV_s , as written” (my italics), so it is useful to trace the history of its derivation. Wolterbeek et al. (2017) derive an expression like Eqn. 13 (their eqn. 13) beginning with their eqn 6 which apart from notation is the same as Eqn. 1.

$$\mu_i^{\sigma T} \approx F_i^{\sigma T} + \sigma_n V_{m,i}^{\sigma T} \quad \text{Eqn. 14}$$

The approximation is indicated because the surface energy term (Eqn. 2) is omitted (Wolterbeek pers. comm.). The earliest use of Eqn. 13 known to me is in Ostapenko and Yaroshenko (1975) though that work does not refer to Eqn. 1. In Appendix 4 I show how their approach is equivalent to that of (Wolterbeek et al. 2017) and explained by Eqn. 1.

In some hydration experiments the stresses recorded during active reaction are much lower than those calculated using Eqn. 13. Ostapenko and Yaroshenko (1975), Wolterbeek et al. (2017) and Zheng et al. (2018) all suggest that the grain boundary film is squeezed out at high normal stress, shutting down the transport pathway before the maximum predicted stress is reached. Ostapenko (1976) modified the explanation, proposing that water molecules diffuse into the periclase-brucite interfaces and cause volume expansion (hence stress) “by enlargement of inter-grain spaces” *before* reaction. Then the reaction itself, considering the volumes of brucite, periclase *and water*, has a small (in fact negative) volume change in comparison to a large positive volume change of solids. Hence reaction would not affect the stress state. This explanation was not developed into a quantitative model, but it does draw attention to the possibility that the locations of volume changes in the microstructure (depending on kinetics) are likely to influence stresses produced. I address this in the Discussion. A further reason why measured stresses are below theoretical maxima is that pores are clogged by reaction products, inhibiting further reaction (Wolterbeek et al. 2017). Skarbek et al. (2018) present a numerical model involving compaction of the porous bassanite + gypsum aggregate as well as reaction, which successfully predicts initial expansion of the aggregate, i.e. work done against the applied stress, and then compaction. This includes an empirical reaction rate not explicitly coupled so cannot be regarded as a test of Eqn. 1, but it would be illuminating to include that equation in future models.

Xing et al. (2018) made porous cylindrical olivine “cups”, filled them with olivine sand, and added NaHCO₃ aqueous solution. This is out of equilibrium so carbonation and hydration reactions result, to form magnesite and other products. Evolution was observed in a synchrotron. In some experiments the cups cracked, with fracturing beginning on the outer surfaces whilst the interior was reacting. Grain positions were tracked using the synchrotron data and this gave a strain estimate of 0.03 which, in the elastic outer layer of the cup, gives a stress estimate of ~300 MPa which they note is in accord with estimates of “crystallisation pressure” (Kelemen et al. 2013). However, the cracks are not at the actual reaction site, and there many signs of dissolution in the interior, which would not be conducive to building up forces. It is not easy to link the experiments back to fundamental theory.

This section has shown that experiments more complex systems show evidence for “force of crystallisation” but in no case is it easy to link the observations back to theory.

7. Polymorphic transformations under stress

Here I will document experiments showing that the *direction* of some such reactions is in accord with Eqn. 1. Vaughan et al. (1984) studied the transformation of olivine to spinel under stress in a germanate analogue system, using a Griggs apparatus with confining pressure of 1-1.8 GPa and differential stress of 0.1 to 1.2 GPa. This reaction is analogous to that which defines the 410 km seismic discontinuity in the mantle.

Figure 6

Under stress, the microstructure showed anisotropic growth: the stress orientation had a direct effect on reaction (*Figure 6*). Spinel nucleated and grew preferentially on interfaces perpendicular to σ_1 . To explain the growth, they first noted that reaction kinetics under hydrostatic pressure can be described “fairly well”. For reactions under stress they state: “For the case of nonhydrostatic stress, however, the formulation is less straightforward because the

generalization of the Gibbs function to nonhydrostatic situations is somewhat controversial and often misunderstood”, citing reviews from Kamb (1961) and Paterson (1973). This is a reminder that the controversies motivating this contribution are not new. Vaughan et al. (1984) went from first principles to derive a condition for chemical equilibrium between olivine and spinel across an interface, in their notation

$$g^{ol} = g^{sp} \quad \text{Their eqn 2}$$

where

$$g = u - Ts + \sigma_n V \quad \text{Their eqn 2a}$$

Here u is internal energy and s is entropy. Since $F = u - Ts$ (Appendix 1), we see that their g is equal to μ here, as in Eqn 1. Consequently their eqn. 2 states that local equilibrium between olivine and spinel is described by

$$\mu^{ol} = \mu^{sp} \quad \text{Eqn. 15}$$

where μ is defined as in Eqn. 1, supporting that definition of chemical potential in a stressed system. Although they use the symbol g , and state it will reduce to the usual Gibbs free energy when the stress is hydrostatic, they do not call it Gibbs free energy, and make clear it is anisotropic as follows. “When the stress is nonhydrostatic, however, g varies with orientation of the interface because σ_n does. It is this property that provides an explanation of the anisotropic grain growth that we observe”. They elaborate upon this by defining a driving force for reaction, in my notation

$$A = \mu^{ol} - \mu^{sp} \quad \text{Eqn. 16}$$

If $A > 0$ there is a drive for olivine to convert to spinel *at the particular interface under consideration*. Expanding Eqn. 16 we find

$$A = (F^{ol} + \sigma_n V^{ol}) - (F^{sp} - \sigma_n V^{sp}) = \Delta F + \sigma_n \Delta V \quad \text{Eqn. 17}$$

where Δ indicates the difference in a quantity between olivine and spinel. Note that this is different to Eqn. 6 but both are derived from Eqn. 1. In the polymorphic reactions discussed here, long range transport of chemicals is not required: to turn one polymorph into another only requires transport across an interface, not along it. Hence, only a single local normal stress value appears in the mathematics. Since $\Delta V > 0$, A is a maximum where σ_n is a maximum, namely where $\sigma_n = \sigma_1$. On other interfaces A may be smaller (slower reaction) or even negative (no reaction). This explains why spinel nucleates first, or preferentially, on olivine boundaries perpendicular to σ_1 . When it grows, the spinel then forms “fingers” parallel to σ_1 . This is in accord with a greater driving force on interfaces perpendicular to σ_1 , hence faster growth parallel to σ_1 . Vaughan et al. (1984) use Eqn. 17 to explain finger growth morphology and aspect ratio in some detail.

At higher stresses the reaction is shear induced across coherent interfaces (Burnley and Green 1989). Under these circumstances a thermodynamic description different to Eqn. 1 may apply (Heidug and Lehner 1985; McLellan 1980). The olivine to spinel transition (via wadsleyite) is very important in the Earth but most solid state transformations proceed across incoherent interfaces; coherent interfaces are not discussed further here.

Kirby et al. (1991) used polymorphic transformations in water ice (ice I to denser ice II) as analogues for transformational faulting in the mantle. As the sample of ice I shortened under stress, there was very little radial strain: the volume reduction due to transformation was the main deformation mechanism. Direct microstructural observations were not made; instead, the indium metal jackets, peeled off the samples, were used to determine the surface topography of the samples. Lenses of ice II, elongate perpendicular to σ_1 , were diagnosed. The authors assert: “Samples that transformed in bulk did so at essentially the same σ_1 values as the pressures at which undeformed ice I transformed under hydrostatic conditions”. This is in accord with the olivine to spinel study in terms of driving force and microstructure, and in accord with Eqn. 1.

Hirth and Tullis (1994) caused quartz to transform to coesite in experiments investigating the brittle-plastic transition in quartz. The coesite formed, in part, along grain boundaries perpendicular to σ_1 . To clarify the thermodynamics of this reaction they plotted the conditions of coesite formation against σ_1 (*Figure 7*, inverted triangles) and separately against mean stress σ_m .

Figure 7

As *Figure 7* shows, using σ_m as a proxy for pressure does not easily explain the formation of coesite. This, together with the preferential formation of coesite along grain boundaries perpendicular to σ_1 , seems to be in accord with an equation similar to Eqn. 17 for the olivine to spinel transformation. The authors point out that the stress field in the experiment will be heterogeneous, and near the pistons (where most coesite formed) the stress might be roughly isotropic. In those regions locally $\sigma_m \approx \sigma_1$, implying ambiguity in how the coesite formation is to be interpreted. However, away from these “strain shadows” coesite is still found, and preferentially along grain boundaries perpendicular to σ_1 , implying “the importance of σ_1 in controlling the transition”. This illustrates that it is not straightforward to test fundamental thermodynamic ideas through experiments. Stress fields are commonly heterogeneous on the scale of a sample (Table 2), and even if they are initially uniform on that scale, there are likely to be grain-scale variations brought on in part by the volume changes associated with reaction.

Richter et al. (2016) revisited the quartz to coesite transformation, using two modified Griggs apparatus, and simple shear of a layer of quartz (initially powder) rather than pure shear of a cylinder. The layer was confined between two strong pistons cut at 45 degrees to the apparatus axis, so shortening was manifest as simple shear in the quartz layer. They found that “ σ_1 is the critical parameter for the quartz-to-coesite transformation—not P_c or σ_m ” (*Figure 7* circles). This is in agreement with Hirth and Tullis (1994) as discussed above, but with a different strain geometry hence extending the scope. Richter et al. (2016) also document the reverse transformation of coesite back to quartz when σ_1 fell below the local equilibrium value (numerically, the value of isotropic pressure for equilibrium between quartz and coesite). During pure shear the local strain shadows result from friction on the pistons, whereas in simple shear the friction drives an approximately uniform deformation across the width of the quartz layer, except at the ends of that layer where the pistons no longer overlap due to shear displacement. Microstructures figured in Richter et al. (2016) do show some clustering and patterns formed of coesite grains (e.g. their Fig. 9) but those patterns are themselves distributed uniformly across the slab.

8. Solid state reaction with volume change

In metamorphic reactions solid volume changes are ubiquitous, but it remains unclear how these are accommodated, and how the accommodation mechanisms affect reaction rate. As described in Section 6, it seems that volume changes give rise to stresses in reactions involving water. Fracturing can result from stresses caused by solid state volume change (e.g. coesite as inclusions in garnets transforming to quartz (Gillet et al. 1984)). It is hard to envisage how volume changes in general can occur without giving rise to local stresses in some fashion, and there may be feedbacks between stress and chemical processes. To understand such possibilities better, Milke et al. (2009) and Schmid et al. (2009) studied the reaction between olivine and quartz to grow orthopyroxene, involving a 6% volume reduction. If we imagine the reactants floating in fluid, which is not involved in the reaction except as a diffusion pathway in a system that changes volume easily so as to maintain pressure, then hydrostatic thermodynamics would describe the driving force for reaction. However, that is not the setting for solid state reactions through much of the Earth; instead solids are surrounded by other solids and porosity is negligible. Milke et al. (2009) hypothesised that, if one mineral were included in a matrix of the other, this volume change was too large to be accommodated by elastic strain; plastic strain would be required for the matrix to collapse inwards around the inclusion. They designed experiments in which olivine was embedded in quartz (so the quartz would have to deform) and quartz was embedded in olivine (so the olivine would have to deform). They argued that the intrinsic kinetics of orthopyroxene reaction rim growth would be the same in both configurations, so the effects of matrix deformation could be distinguished separately. This was shown to be the case, as reaction rims for quartz in an olivine matrix were for example 10.3 μm wide whilst those for olivine in a quartz matrix were 6.1 μm under identical imposed conditions. The quartz matrix was the stronger, and inhibited growth.

To quantify the effect Schmid et al. (2009) provided a combined mechanical and thermodynamic theory, based on an idealised spherically symmetric system. Their model is, in brief, as follows: in the next paragraph I will suggest how it may be rephrased and provide additional insights. Suppose the imposed large-scale pressure is P , then the overall driving force for reaction would be, under hydrostatic conditions

$$\Omega_0 = \Delta G(P) = G^{fo}(P) + G^q(P) - G^{en}(P)$$

where the enstatite formula is $\text{Mg}_2\text{Si}_2\text{O}_6$ and Ω_0 is the reaction affinity at pressure P . However, in a solid system, volume change must be accommodated, and stresses build up – in this case a state of relative radial tension in the matrix, as it must deform so as to collapse around the growing reaction rim. Stresses will modify affinity. They consider a radial stress σ_r (with tension as positive but I will rewrite using compression as positive as in the rest of this contribution). Far from the inclusion we will have $\sigma_r = P$, the far-field confining pressure. Near the inclusion σ_r decreases with $1/r^3$ where r is the distance from the centre. Assuming that σ_r on either side of the reaction rim is the same, their eqn (26) gives the effect of stress on what they call “generalized reaction affinity” as

$$\Omega = \Omega_0 + (\sigma_r - P)\Delta V$$

where P is the “far field” or imposed pressure. As $\sigma_r < P$ this reduces affinity and slows the reaction rim growth rate. They use this result to derive an overall reaction rate (their eqn (29)) which shows that reaction rate is slower for higher matrix viscosity and zero when the matrix cannot deform plastically (infinite viscosity).

I now re-express what they say, without changing the mathematics itself but showing some additional implications. G is undefined in the stressed system (though the definition of Ω_0 in hydrostatic reference system can be retained). Instead consider chemical potentials of the three phases, specifically *on interfaces perpendicular to σ_r* , assuming these are where the phases dissolve and precipitate (as in standard reaction rim models where growth proceeds by dissolution and precipitation on interfaces parallel to the rim). Then the affinity *for that particular reaction pathway* (i.e. involving those particular interfaces) is, using Eqn. 1,

$$\Omega = \mu^{fo} + \mu^q - \mu^{en} = F^{fo} + \sigma_r V^{fo} + F^q + \sigma_r V^q - F^{en} - \sigma_r V^{en} = \Omega_0 + (\sigma_r - P)\Delta V$$

Numerically we recover eqn (26) of Schmid et al. (2009), So, their approach is in accord with Eqn. 1 and is then shown to be in accord with observed rim growth and known rheologies of quartz and olivine. There is an additional implication of re-expressing their argument. The affinity as defined here depends on a particular reaction pathway: exchange of chemicals from one side of the reaction rim to the other). There is then the possibility of different reaction pathways with different affinities (c.f. Wheeler (2014)). For example, if the matrix deforms by diffusion creep, chemicals for the reaction might be supplied from radial interfaces (under high normal stress $\sigma_\theta > P$) and a different expression for affinity will result.

Discussion

All of the experiments I describe are qualitatively or quantitatively in accord with Eqn. 1 as summarised in the last column of Table 2. There are experiments argued to indicate that mean stress is the parameter to use as a proxy for pressure, as in Eqn. 4. Cionoiu et al. (2019) undertook experiments where an elliptical rigid alumina inclusion was embedded in calcite and then taken to high pressure conditions with a uniaxial load. Aragonite was produced in a non-uniform pattern, particularly above and below the inclusion. A mechanical model of the stress field is used to show that the pattern of σ_m mimics the pattern of aragonite abundance. The mix of calcite and aragonite shows that the system was nowhere in equilibrium (even if equilibrium in a stressed system exists), and the mechanical model does not include the effects of the volume change itself. There is scope for alternative explanations: for example, variation in σ_1 , which is not illustrated in that work. I cannot see how pressure solution (type 3) and diffusion creep (4) could be explained using thermodynamics based on mean stress, I cannot see how such an approach could explain oriented microstructures (6), and for olivine, ice, and quartz it is not in accord with conditions for polymorphic transformation (7). Surely at a fundamental level we need consistent mathematics to explain all the experiments I refer to so in the rest of the discussion I focus on implications of Eqn. 1.

Numerical models are always required to allow extrapolation of experimental results. All the experiments discussed here show that the *kinetics* of reaction will influence observations, so need to be included in future detailed numerical models. I suggest the “reaction pathway” idea (Wheeler 2014) is useful here. An example is provided by comparing the types of experiment labelled 1 and 5 here. In both, the reaction is alum precipitation, but by different pathways. *Figure 8* shows both pathways – surely in general they will both be active, but the papers I cite above have looked in detail at one or the other, not both. In an unstressed system all pathways will have the same affinity but in a stressed system the affinities may be different. The relative contribution of each pathway will be determined not just by the affinity but by the kinetics along that pathway. The kinetic factors are not intuitive. For example, one

might imagine that free face precipitation is easy, and given that pathway also has a bigger affinity, it would be the dominant precipitation mechanism: yet in Correns's experiment the weight moves up so the pathway with smaller affinity still functions. I suggest that more complex pathways as in Wheeler (2014) will similarly work in parallel, with the overall evolution being a result of affinity combined with kinetic factors along each pathway. I also suggest that the reaction pathway idea, being flexible, could help explain the discrepancies between experiments and theory in the force of crystallisation experiments (section 6). The works I refer to use Eqn. 13 to predict stresses, but that is based on a particular reaction pathway in which the hydration product grows at solid-solid boundaries. Suppose instead that reaction products grow in pores (same reaction, different pathway) – then there is no reason for the matrix to deform, and no extra stress is to be expected. Growth in pores is the reaction pathway documented for gypsum dehydration (Bedford et al. 2017; Llana-Funez et al. 2012). In Table 2 I give examples of alternative reaction pathways for each type of experiment; each will have a different affinity to the main pathway discussed.

Figure 8

Stress is almost certainly non-uniform on some scale in the experiments discussed (Table 2), whether they be designed thus (Cionoiu et al. 2019; den Brok and Morel 2001) or whether it be intrinsic to a process such as grain scale stress variations due to elastic (Burnley and Zhang 2008) or diffusion creep responses (Wheeler and Ford 2007). Such variations need to be included in numerical models to enable interpretation of experiments with complicated geometries (including any polycrystal).

The idea that reaction is a deformation mechanism is implicit in many of the experiments that I describe here. Pressure solution (experiment type 3) and diffusion creep (4) are obviously deformation mechanisms but can also be thought of as reactions in which reactants and products have the same chemistry. Correns's experiment (5) moves a weight and if such a system is confined (6) stress will build up with consequent elastic or inelastic deformation. Polymorphic transformation may involve a volume change in a particular direction – deformation again (7). More general solid-state reactions themselves may trigger surrounding deformation, but again are a deformation mechanism themselves (8). Even with a planar interface between olivine and quartz, one might expect the volume change to be manifest as shortening perpendicular to the reaction rim. What this implies is that, as numerical models are developed, it is to be expected that if stress terms appear in reaction rate, then reaction rate should appear in rheology.

As mentioned in the introduction there many topics of theoretical and practical importance in Earth science where stress interacts with chemical processes. Eqn. 1 has been used to make testable predictions about various physical and chemical processes. Several of the experiments I describe above involve a single soluble phase. What happens when different soluble phases exert forces on each other – as in most rocks? Wheeler (1987) makes a prediction about relative dissolution rates, yet to be tested but fundamental to understanding a rock's chemical response to stress. Development of that work leads to predictions of rheology of multiphase aggregates undergoing pressure solution and diffusion creep. They might be weaker than end member phases (Wheeler 1992) and that could help explain and extrapolate some observations of rheology, such as the weakness of harzburgite (Sundberg and Cooper

2008). This is important since regions in the Earth undergoing pressure solution or diffusion creep are significant in size (e.g. the lower mantle) or importance (slow creep in fault rocks between earthquakes). Wheeler (2014) predicts that stress may cause reactions to occur under quite different conditions to those predicted by hydrostatic thermodynamics, which could modify the way we interpret metamorphic assemblages.

I finish by returning to two situations, mentioned at the start, where stress effects are significant. First, we need to understand how chemical reactions induce stress sufficient to fracture rocks if we are to sequester CO₂ in peridotite (Kelemen et al. 2011). I suggest that different reaction pathways will have different effects: microstructures and in situ studies will help to determine which pathways operate. Secondly Nakajima et al. (2013) propose that in subducting plates, the volume changes involved in oceanic crust transforming to eclogite give rise to stresses which trigger earthquakes. The volume reduction in their model involves shortening in all directions and to accommodate this adjacent to mantle, which does not undergo densification, tensional stresses are generated in the crust. These are of the order of GPa (Kirby et al. 1996) so it would be useful to know how the stresses feedback on the eclogitisation reactions and the way in which the volume changes are manifest. In these and other large scale problems, it is essential to have grain scale models of how stress interacts with chemical processes: these would form the foundations for large scale predictions. New grain scale models should incorporate the key equation I describe here, building upon the models that have already been used to analyse published experiments.

Conclusions

- An equation relating chemical potential to normal stresses on particular interfaces is broadly in accord with published analyses of eight diverse types of experiment that involve interactions of stress and chemical effects.
- Where quantitative agreement is lacking, the equation is still used, directly or indirectly, to assist explanation.
- Because the equation relates to particular interfaces, there is the possibility of different reaction pathways with different affinities, depending on which interfaces are involved in reaction. The overall behaviour of an experiment or natural system will depend on kinetics as well as the affinities of various reaction pathways. This idea may help to resolve the lack of quantitative agreement between force of crystallisation experiments and theory – not all reaction pathways have been considered.
- Large-scale predictions of how stress interacts with chemical processes, including reaction rates and rheology, need to be based on grain-scale models for those interactions. The equation highlighted here should be used in building such grain-scale models.

Appendices

Appendix 1: some thermodynamic relationships

To understand how chemical potential varies according to Eqn. 1, I indicate here how the two terms in it vary. Properties with suffix 0 relate to zero stress. In what follows I will refer to standard results from mechanics and thermodynamics and assume mechanical isotropy for simplicity. The solid then has an isothermal bulk elastic modulus K and Poisson's ratio ν ; the Young's modulus E is dependent on these.

When a general stress is applied to a mechanically isotropic material the molar volume is

$$V = \left(1 - \frac{\sigma_m}{K}\right) V_0$$

where V_0 is the volume at zero pressure.

When a differential stress σ is applied in one direction to an isotropic material under zero pressure, for small linear elastic strains, the Helmholtz free energy is

$$F = F_0 + \frac{V_0}{2E} \sigma^2$$

The second term can be described as elastic strain energy, though there is more than one value for that depending on whether the strain is adiabatic, as in seismic waves, or isothermal, as in slow metamorphic processes (Aki and Richards 2002). The second term has been described incorrectly as internal energy but that quantity (U) is distinct from Helmholtz free energy:

$$F = U - TS$$

and is relevant when discussing energy changes during adiabatic not isothermal elasticity (the adiabatic elastic moduli differ from the isothermal versions). For a general strain, using the Einstein summation convention, the Helmholtz free energy is

$$F = F_0 + \frac{V_0}{6(1-2\nu)K} \left((1+\nu)\sigma_{ij}\sigma_{ij} - 9\nu\sigma_m^2 \right)$$

In Eqn. 1 and Eqn. 4, variations in the second “ σV ” term are generally more important than variations in F . This is because the F variation is of the order of $(\sigma/E) \times (\sigma V)$ and for representative stress values, the σ/E term is much less than 1; consequently Eqn. 1 and Eqn. 4 are both approximately linear in their relevant stress terms. This also implies that G for a solid at hydrostatic pressure P is approximately equal to the chemical potential of that solid at an interface under normal stress equal to P given by Eqn. 1, because the Helmholtz free energy and volume variations under stress give only second order effects.

There are circumstances in which the small quadratic term is significant – namely where the normal stress does not vary laterally, but tangential stress does. Consider an unstressed solid adjacent to a fluid at (perhaps high) pressure P . What happens to the chemical potential if the solid is put under tension or compression parallel to the surface? McLellan (1980) derives a completely general result but here I provide a simpler illustrative derivation. Suppose that one of the tangential stresses remains at P and the other is changed to be $P + \sigma$ where σ is differential stress. Then

$$\sigma_{ij}\sigma_{ij} = 3P^2 + 2P\sigma + \sigma^2$$

and

$$\sigma_m = P + \frac{\sigma}{3}$$

So, from the expression for F above,

$$F = F_0 + \frac{V_0}{K} \left(\frac{1}{2} P^2 + \frac{1}{3} P\sigma + \frac{1}{6(1-2\nu)} \sigma^2 \right)$$

So, when P is large, a relative tensional stress $\sigma < 0$ could reduce the Helmholtz free energy. This might be taken to indicate that, since it has reduced energy, the solid is more stable than in the unstressed state. This would be incorrect because the σV term in Eqn. 1 must be considered too. The molar volume is

$$V = \left(1 - \frac{\sigma_m}{K} \right) V_0$$

So under relative tension the molar volume increases and will counteract the Helmholtz energy decrease. Expanding the full expression for chemical potential, noting in this case $\sigma_n = P$,

$$\begin{aligned} \mu &= F + PV \\ &= F_0 + \frac{V_0}{K} \left(\frac{1}{2} P^2 + \frac{1}{3} P\sigma + \frac{1}{6(1-2\nu)} \sigma^2 + P \left(K - P - \frac{1}{3} \sigma \right) \right) \\ &= F_0 + \frac{V_0}{K} \left(-\frac{1}{2} P^2 + KP + \frac{1}{6(1-2\nu)} \sigma^2 \right) \\ &= \mu(P) + \frac{V_0}{2E} \sigma^2 \end{aligned}$$

where $\mu(P)$ is the chemical potential at hydrostatic pressure P. Now we see that the first order term in σ has cancelled out and, regardless of compression or tension, the stressed solid is less stable than the unstressed one.

Appendix 2: ionic solutions

A basic thermodynamic idea is relevant for understanding some of the experiments involving aqueous solutions (Flatt et al. 2007). When a substance is dissolved, the activity a is defined by

$$\mu^{pf} = \mu_0^{pf} + RT \ln(a/a_0)$$

relative to a reference state (suffix 0). This is always true, by definition. If this is a solution containing one molecular species (e.g. sucrose), and is ideal, then we can write this in terms of concentration c

$$\mu^{pf} = \mu_0^{pf} + RT \ln(c/c_0)$$

However ionic solutions, even if ideal, behave differently, since the solid dissociates into two or more ions. Suppose we assume halite (NaCl) forms an ideal solution (for simplicity), then $a = [\text{Na}^+][\text{Cl}^-]$ where the square brackets indicate concentration. Assuming we are dealing just with dissolved halite with concentration c , we then have $[\text{Na}^+] = c$ and $[\text{Cl}^-] = c$.

Consequently

$$\mu^{pf} = \mu_0^{pf} + 2RT \ln(c/c_0)$$

More generally

$$\mu^{pf} = \mu_0^{pf} + nRT \ln(c/c_0)$$

where n is the number of independent ions in solution. Flatt et al. point out that Correns implicitly assumed alum dissolved as molecules and corrected this (see main text). In appendix 3 I point out that Ostapenko et al. (1972) made a similar mistake for halite though it does not affect their conclusion. Flatt et al. further point out that non-ideality of ionic solutions, and the presence of water of crystallisation, will also affect n, and they deduce a value around 3.5 for alum.

Appendix 3: details of Ostapenko et al. 1972

In my description I will use values for concentrations N (given in mol/mol) as published; they have been revised slightly in subsequent work but not enough to make a difference to his conclusion. Temperature was precisely controlled, and at 41.7 °C, and at atmospheric pressure the equilibrium concentration of halite is $N_0 = 0.1006$ (more recent estimates are slightly higher but this makes no difference to the conclusion). Their method was able to detect dissolution just 0.2° C above the equilibrium temperature, or when 0.2 ml of pure water was added to 0.75 l of saturated solution (a concentration change of $0.1006 \times 0.2/750 = 2.7 \times 10^{-5}$). They applied a tangential stress of for example 150 kg/cm² (14.7 MPa) and found no detectable difference in concentration around the crystal, then used the two approaches to calculate the theoretical change in chemical potential. From Eqn. 4, ignoring the relatively small second order term,

$$\Delta\mu = \Delta\sigma_m V = \frac{1}{3}(\sigma_t - 1 \text{ bar})V$$

Then, assuming an ideal solution, if N_1 is the expected new concentration in equilibrium with the stressed solid

$$\Delta\mu = RT \ln(N_1/N_0) \cong RT\Delta N/N_0$$

which gives $\Delta N = 0.0053$. I suggest that because the solution is ionic the ideal solution equation they used is not correct (see Appendix Q) and ΔN should be halved so $\Delta N = 0.0027$. In contrast Eqn. 1 predicts, as in Appendix 1,

$$\Delta\mu = \frac{\sigma_t^2 V}{2E}$$

and $\Delta N = 9 \times 10^{-6}$. Again, I suggest because the solution is ionic this will be nearer 4.5×10^{-6} . My adjustments do not affect his qualitative conclusion: Eqn. 1 predicts ΔN is somewhat below the detectability limit of 2.7×10^{-5} whilst Eqn. 4 predicts it is 200 times greater. Consequently, since the actual concentration change was not detectable, Ostapenko et al. rejected Eqn. 4 in favour of Eqn. 1.

Appendix 4: derivation of Ostapenko and Yaroshenko 1975 equation

Wolterbeek et al. (2017) show how Eqn. 13 relates to local chemical potentials, mathematically in agreement with what I write here but their account still refers to overall Gibbs free energy. Here I will rephrase (Ostapenko and Yaroshenko 1975) in terms of chemical potential.

The paper considers two different hydration reactions at room temperature and 1 bar and I will illustrate their argument using hydration of lime (CaO) to portlandite (Ca(OH)₂). The solids are under stress (described further below) and in contact with water. Their eqn 4, verbatim, is

$$\Delta V_s(\tilde{P}_s^{max} - 1) + \Delta G_{298}^0 = 0$$

The “1” is the fluid pressure in bars, so I rewrite this as

$$\Delta V_s(\tilde{P}_s^{max} - P_f) + \Delta G_{298}^0 = 0$$

where P_f is fluid pressure, and ΔG_{298}^0 is, from context, the Gibbs free energy change at 298K and 1 atm. They define \tilde{P}_s^{max} “the maximum pressure on the solid phases”. To derive this equation they assert “... from the point of view of ‘abstract’ thermodynamics the system may be considered as one with unequal pressure on the solid phases and fluid”. There is a problem, as follows: if the word “pressure” implies isotropy of forces in every direction, it is not possible to have a material at one pressure in contact with and in mechanical equilibrium with a material at another pressure, let alone chemical equilibrium. However, it is clear from their Fig 7 that the authors mean the solids are under stress. There is then a second problem: in a stressed solid, a Gibbs free energy cannot be assigned, as (Ostapenko et al. 1972) point out, so the meaning of ΔG in Eqn. 13 must be examined critically. These problems are overcome by re-expressing the narrative, without changing the numbers.

The driving force for reaction under hydrostatic pressure P is

$$\Delta G(P) = G^{po}(P) - G^{li}(P) - G^w(P)$$

where $G(P)$ indicates functional dependence of G on pressure, and dependence on temperature is omitted for brevity. Now instead of a single pressure they use G for solids calculated at P_s and for water at P_f and assume for simplicity molar volumes for solids independent of pressure. I re-express this as follows: G for a solid at P_s is approximately equal to the chemical potential of that solid at an interface under normal stress equal to P_s given by Eqn. 1 (Appendix 1). Now suppose that the reaction involves movement of water into a stressed interface between lime and portlandite, where the water chemical potential is determined in the pores at pressure P_f . In that interface, reactant and product are both under normal stress P_s so the overall affinity for reaction by that mechanism is

$$\begin{aligned} A &= \mu^{li}(P_s) + \mu^w(P_f) - \mu^{po}(P_s) \\ &= \mu^{li}(P_f) + (P_s - P_f)V^{li} + \mu^w(P_f) - \mu^{po}(P_f) - (P_s - P_f)V^{po} \\ &= -\Delta G(P_f) + (P_s - P_f)(V^{li} - V^{po}) = -\Delta G(P_f) - (P_s - P_f)\Delta V_s \end{aligned} \quad \text{Eqn. 18}$$

where ΔV_s is the solid volume increase from reactants to products. As P_s increases, A decreases so the maximum normal stress that for which reaction can proceed is given when $A = 0$,

$$(P_s - P_f)\Delta V_s + \Delta G(P_f) = 0. \quad \text{Eqn. 19}$$

Which is in accord with their eqn. x, and can be rearranged to give

$$P_s - P_f = -\frac{\Delta G(P_f)}{\Delta V_s}$$

which apart from the sign of ΔG is the same as Eqn. 13. The significance of re-expressing the derivation is as follows.

1. It avoids reference to ΔG in a stressed system.
2. It is in accord with Eqn. 1, us of which focusses attention on the *specific* interfaces involved in reaction.
3. It has implicit within it a particular *reaction pathway*, in this case water moving into an interface where both lime and portlandite are stressed. Other pathways are in principle possible, form example lime dissolving in pore fluid and precipitating portlandite in pores. The affinity would then no longer be given by Eqn. 18.

Tables

Table 1. Notation

Notation: note other symbols are used when quoting from other works.

| Symbol | Meaning |
|--------------------|--|
| V | Molar volume |
| S | Entropy |
| F | Helmholtz free energy |
| U | Internal energy |
| G | Gibbs free energy |
| A | Affinity |
| P | Pressure (isotropic) |
| a | Activity |
| c | Concentration in a solution |
| P _f | Fluid pressure (isotropic) |
| P _c | Confining pressure |
| σ | Stress tensor |
| σ_n | Normal stress (defined at an interface) |
| σ_m | Mean stress (defined anywhere) |
| σ | Differential stress |
| μ^{med} | Chemical potential in or at the surface of medium “med” (e.g. solid, pore fluid) |
| μ_f | Chemical potential at an interface with solid under force per unit area f (e.g. fluid pressure, solid-solid normal stress) |
| γ | Surface energy |

Table 2. Summary of 8 types of experiment

| Type | Process | Main reaction pathway discussed | Alternative reaction pathway example | Reaction affinity in unstressed system | Stress heterogeneity | Support for equation |
|------|---|---|--|---|--|---|
| 1 | Free face growth of stressed solid next to fluid | Solute → free face | Solute → high stress face | $\mu^{\text{solution}} - \mu^{\text{solid}}$ | Stress might be homogenous in solid | Qualitative agreement for dissolution and growth, under tension and compression |
| 2 | Free face growth instability of stressed solid next to fluid | Troughs → peaks via solution | Solute → high stress face | $\mu^{\text{solution}} - \mu^{\text{solid}}$ | Instabilities amplify so local stresses near surface become heterogeneous | Qualitative and indications of quantitative agreement for development of periodic instabilities |
| 3 | Pressure solution in porous aggregate | High stress interface → pore wall | High stress interface → low stress interface | 0 | Grains support the imposed stress, whereas fluid is at a single uniform pressure (see figure in W18). | Quantitative agreement in terms of stress and grain size exponents |
| 4 | Diffusion creep | High stress interface → low stress interface | High stress interface → intermediate stress interface | 0 | Elastic anisotropy and the diffusion creep response leads to heterogeneity | Quantitative agreement in terms of stress and grain size exponents |
| 5 | Displacement of weight - force of crystallisation with a single solid | Solute → high stress face | Solute → free face | $\mu^{\text{solution}} - \mu^{\text{solid}}$ | Stress might be homogenous in solid | Qualitative link between stress and supersaturations |
| 6 | Hydration - force of crystallisation in multiphase system | Pore water → high stress boundary between phases | Solid at pore wall → hydrate in pore | $\mu^{\text{anhydrous}} + n\mu^{\text{water}} - \mu^{\text{hydrate}}$ | Very heterogeneous | Measured stresses lower than predicted for hydration reactions, but comparable for a carbonation reaction |
| 7 | Polymorphic transformation under stress | Light phase → dense phase <i>across</i> high stress interface | Light phase → dense phase <i>across</i> low stress interface | $\mu^{\text{light}} - \mu^{\text{dense}}$ | Stress might be homogenous in solid to begin with, but the geometry of transformation will lead to heterogeneity | Qualitative agreement with driving force (ol → sp, ice I → II); quantitative for qz → coe |
| 8 | Solid state reaction with volume change | Reaction rim edge → opposite edge | Matrix deforming by diffusion creep → Reaction rim edge | $\mu^a + \mu^b - \mu^{ab}$ | Stress evolves due to elastic and inelastic response to volume change. | Quantitative agreement based on a model of a reaction rim with volume change, including matrix rheology |

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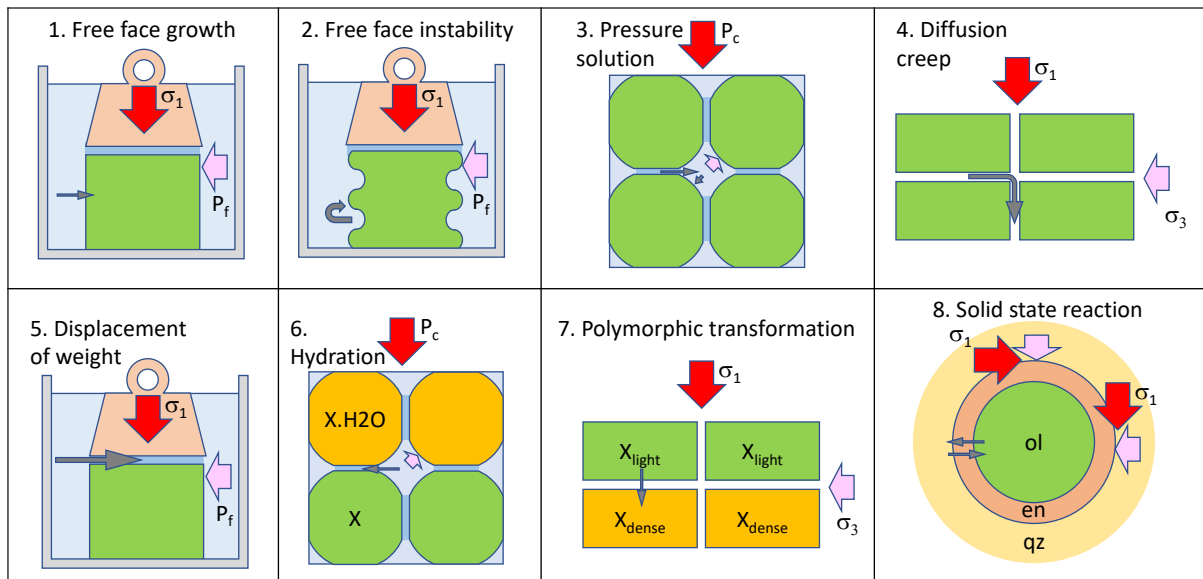
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1

Fig. 1 Schematic diagrams to illustrate the experiments described. In each diagram green indicates a particular solid, other solids are labelled, and pale blue indicates an aqueous solution held in a notional beaker (grey). Red arrow indicates maximum compressive stress, pink arrow indicates minimum compressive stress, and grey arrow indicates the transport pathway for one or more chemicals. In most experiments stress is heterogeneous on some scale as described in Table 2.

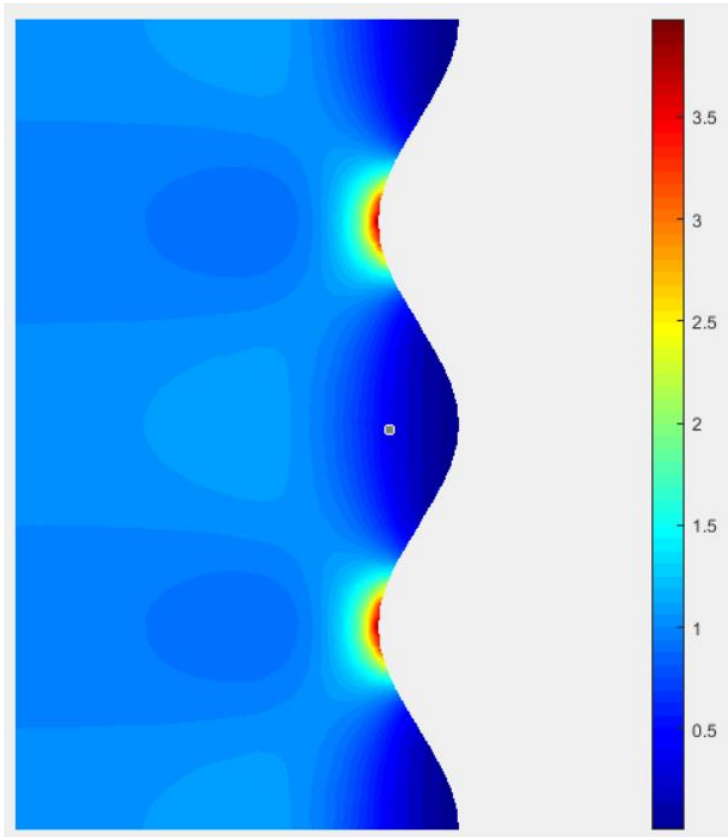


Fig. 2 The Helmholtz free energy near an undulating crystal surface when a N-S differential stress is applied, displayed in multiples of the uniform value in the crystal interior.

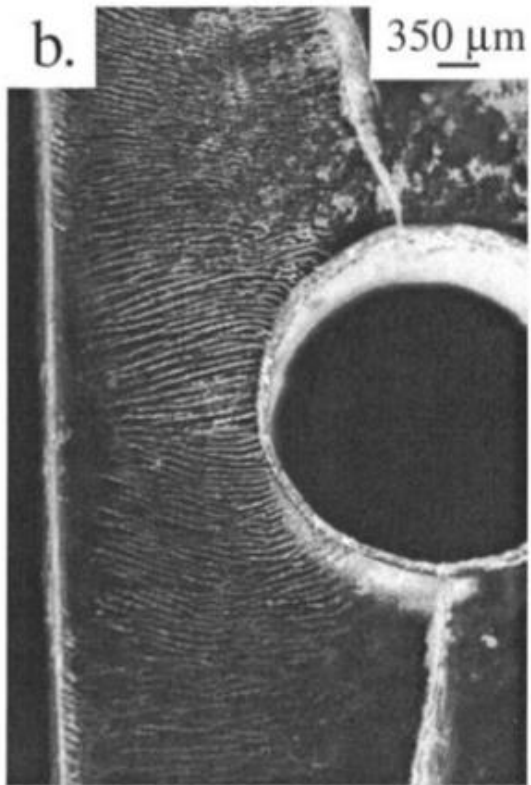


Fig. 3 Grooves showing surface instability in alum crystal under compressive stress (up-down) surrounded by solution. Bulk stress was 2.7 ± 0.2 MPa , amplified to 13-14 MPa around the hole (den Brok and Morel 2001).

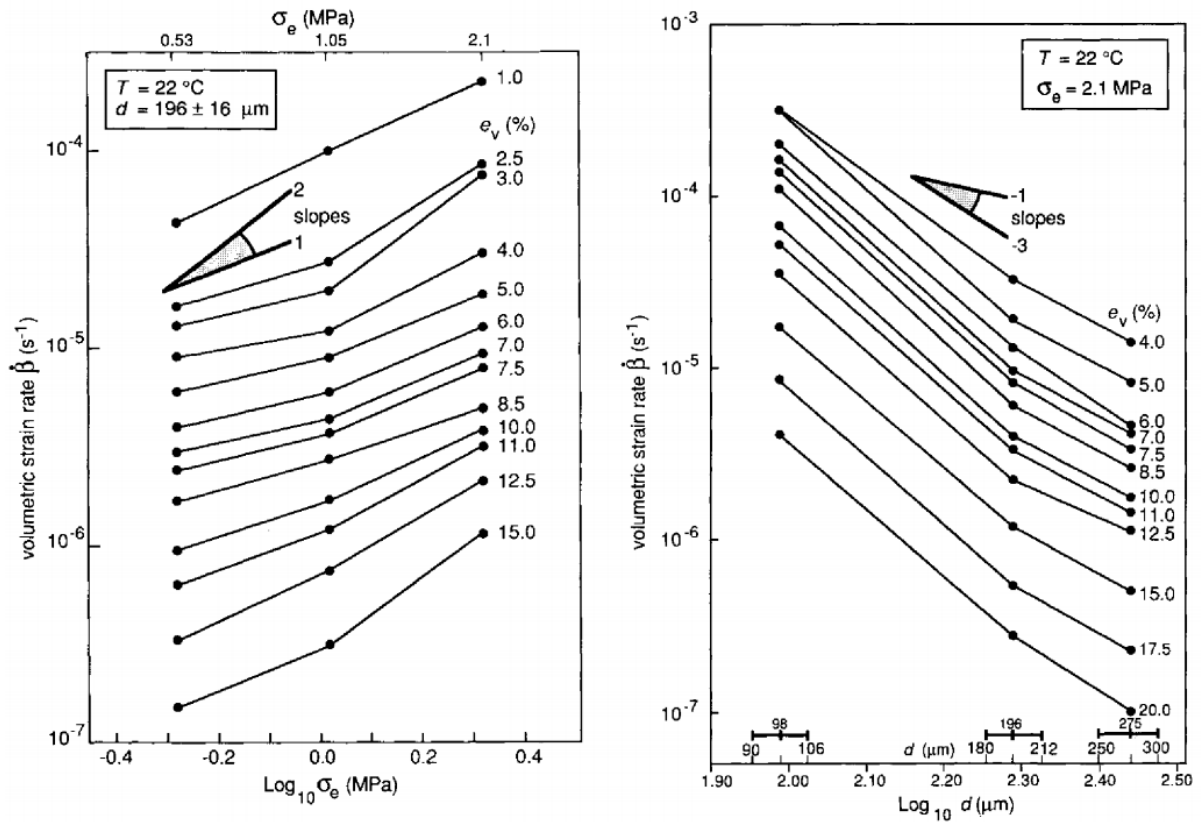


Fig. 4 (a) Log-log plot of strain rate (volumetric compaction rate) versus effective stress σ_e , for the values of volumetric strain (e_v) shown, for compaction of halite (Fig. 4 of Spiers et al. (1990)). Note slopes near 1. (b) Log-log plot of compaction rate versus grain size d (Fig. 5 of that work). Note slopes near -3.

Please see Fig. 8 of Flatt et al. (2007)

<https://link.springer.com/article/10.1007/s00254-006-0509-5>

for example here:

<https://link.springer.com/article/10.1007/s00254-006-0509-5/figures/8>

Fig. 5. Relationships between supersaturation in an alum solution and vertical stress that can be supported by a growing crystal: Fig. 8 of Flatt et al. (2007), itself redrawn from Correns and Steinborn (1939). a) calculated curve from Eqn 12. b) curve fitted to data for stressed (111) faces (open triangle no growth, filled triangle growth). c) curve fitted to data for stressed (110) faces (open circle no growth, filled circle growth).

Please see Figures 1 and 3 of Vaughan et al. (1984)

<https://www.sciencedirect.com/science/article/abs/pii/0040195184902415>

Fig. 6 Optical micrographs of spinel forming from germanate olivine, with maximum stress aligned top to bottom. Top: crossed polarizers, spinel in black: note residual lenses of olivine perpendicular to maximum stress (Fig. 1 of Vaughan et al. (1984)). Bottom: uncrossed and crossed polarizer images of spinel “fingers” (elongate parallel to maximum stress) separated by very thin spikes of olivine (Fig. 3 of that work).

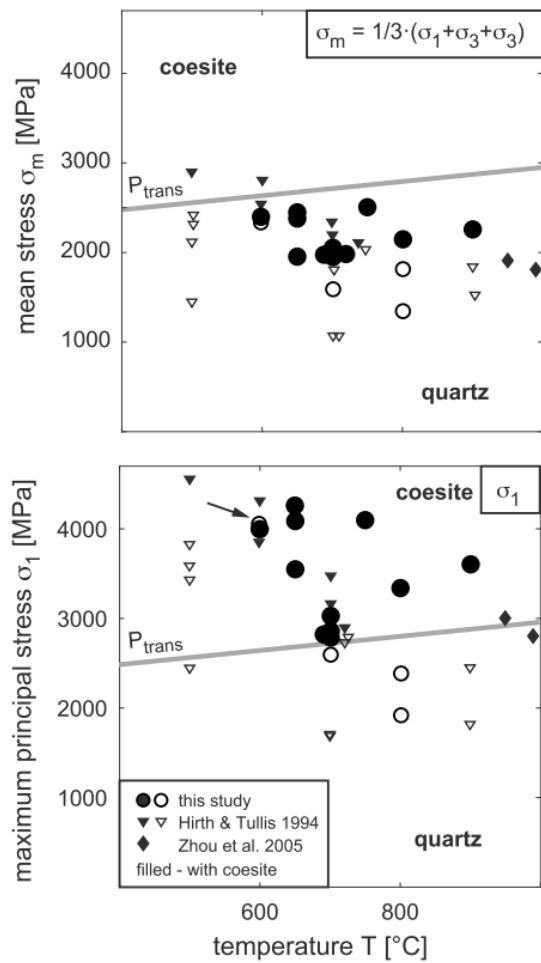


Fig. 7 The effects of differential stress on the quartz to coesite transformation from Fig. 5 of (Richter et al. 2016): round symbols are from that work; earlier results from Hirth and Tullis (1994) and (Zhou et al. 2005) are incorporated. Filled symbols show conditions where coesite was found, plotted using mean stress (above) and maximum principal stress (below).

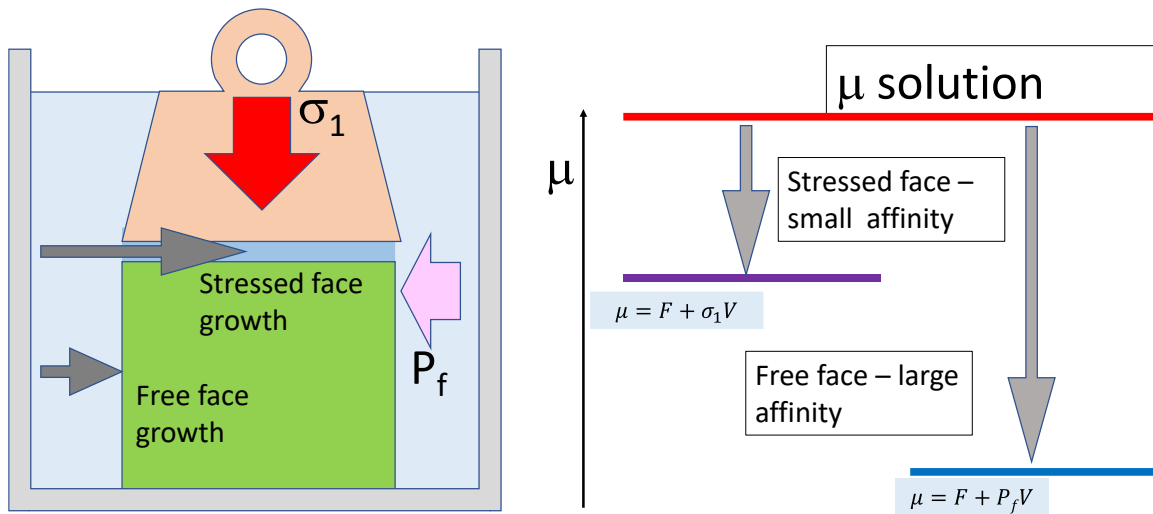


Fig. 8 Combining experiment types 1 and 5 to illustrate the possibility of different reaction pathways. On left, grey arrows illustrate two possible transport pathways for solute (arrow length is of no significance). On right, diagram shows that the two pathways have different affinities (chemical potential drops) indicated by arrow lengths.