Connectivity between primary and secondary subglacial drainage systems beneath a land-terminating outlet glacier of the Greenland Ice Sheet

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28 **Key Points:**

29 ● Hydraulic connectivity between primary and secondary subglacial drainage switches on
30   hourly timescales over spatial scales of 100s of meters

31 ● Large subglacial drainage axes, fed by upstream sources, dictate regional ice dynamics

32 ● Wireless 'Cryoegg' sensors measure moulin electrical conductivity and hydraulic head and
33   reveal long-term changes in drainage behavior

34 **Abstract**

35 The evolution and connectivity of subglacial drainage systems controls basal sliding and therefore
36 modulates ice flow, yet direct observations of these systems remain limited. Here, we investigate
37 hydraulic connectivity and its influence on ice motion at Isunnguata Sermia - a large land-
38 terminating outlet glacier of the Greenland Ice Sheet. We use 'Cryoegg' wireless sensors to obtain
39 moulin water pressure and electrical conductivity, in conjunction with passive seismics to
40 measure glacio-hydraulic tremor and GNSS-derived measurements of ice motion. We identify
41 rapid switching (<24 hours) of subglacial hydraulic connectivity between a large, primary
42 subglacial drainage axis located in a deep trough, and subsidiary secondary subglacial channels.
43 When surface melt inputs are high, the secondary channels fed by the instrumented moulins
44 couple to the efficient primary subglacial drainage axis, exhibiting smoothed diurnal variability
45 and synchronization with regional ice motion and seismic tremor. When melt inputs decrease,
46 the secondary drainage system becomes isolated and responds sensitively to variations in local
47 melt inputs, causing a reduction in hydraulic connectivity and an increase in local meltwater
48 residence time. Regional ice motion appears completely controlled by the characteristics of the
49 primary subglacial drainage axis and is insensitive to local inputs to secondary channels.

50 **Plain Language Summary**

51 Subglacial drainage systems transport meltwater beneath glaciers to downstream environments.
52 Because the structure of the drainage system controls where water flows and hence how slippery
53 parts of the ice bed may be, it influences ice motion, yet directly observing these systems is
54 extremely difficult. We use sensors, including wireless "Cryoeggs", deployed into moulins, to
55 measure water pressure and electrical conductivity variations as daily surface ice melt inputs
56 fluctuate over the summer melt season. We combine these data with measurements of seismic
57 tremor caused by flowing water and ice motion from GPS stations to explore the interactions
58 between primary and secondary subglacial drainage systems. We find that variations in surface
59 meltwater input cause the drainage system to rapidly switch between: (1) 'connected' states
60 associated with flooding of the main drainage route during warm periods, which captures the
61 local flow; and (2) 'disconnected' states associated with cooler periods, when the main drainage
62 route becomes more restricted and the system fragments into smaller catchments that respond
63 to local melt inputs. Ice motion is largely controlled by the fluctuating regional drainage system
64 rather than the smaller local catchments.

65 **1 Introduction**

66 Surface meltwater in the ablation area of the Greenland Ice Sheet (GrIS) accesses the glacier bed
67 through crevasses and moulins, and is then routed through the subglacial drainage system.
68 Drainage configurations evolve between hydraulically inefficient, distributed components (e.g.,
69 linked cavities, thin films and Darcian flow through permeable sediments; Kamb, 1987; Clarke
70 1987) and efficient, channelized structures (Röthlisberger, 1972; Nye, 1976; Ng, 2000) in
71 response to variations in meltwater inputs (Schoof, 2010). The variance in evolving hydraulic
72 connectivity between these configurations determines the overall efficiency of the subglacial
73 drainage system (Lefeuvre et al., 2015, Rada & Schoof, 2018), and controls subglacial water
74 pressure and its transmission across the bed (Lefeuvre et al., 2018; Murray & Clarke, 1995;

75 Werder et al., 2013). Variations in subglacial water pressure modulate basal sliding and ice
76 motion over spatial scales defined by longitudinal stress coupling lengths (Kamb, 1987; Iken and
77 Bindschadler, 1986; Ryser at el., 2014). Measurements of meltwater hydraulic head in moulins
78 or boreholes can thus act as a manometer of these hydrological changes (Hubbard et al. 1995;
79 Andrews et al. 2014).

80 Direct measurements of subglacial pressure variations are therefore critical for improving our
81 understanding of the evolution of the subglacial drainage, its influence on ice sheet dynamics
82 (Andrews et al., 2014; Cowton et al., 2016), and for informing process-based models of subglacial
83 hydrology (e.g., Flowers et al., 2003; Schoof 2010; Hewitt et al., 2013; Hoffman et al., 2011;
84 Werder et al. 2013). Long-term measurements of water pressure from borehole arrays on
85 mountain glaciers have revealed that subglacial drainage systems can undergo shifts in
86 connectivity. As subglacial water flow declines and effective pressure in channels decreases,
87 shifts in local hydraulic gradients can lead to the hydrological isolation of parts of the subglacial
88 system, causing the drainage network to fragment into distinct, isolated subsystems (Rada and
89 Schoof 2018; 2023) that respond independently to local meltwater inputs. Simultaneous
90 measurement of electrical conductivity (EC) can enable proxy assessment of meltwater residence
91 time (Brown et al., 1994), sediment availability (Collins, 1979), and meltwater origin (Gordon et
92 al., 1998), providing further evidence of meltwater isolation.

93 On the GrIS, direct observations from boreholes have provided detailed records of basal water
94 pressure and assessment of drainage configurations (e.g., Lüthi et al., 2002; Meierbachtol et al.,
95 2013; Andrews et al. 2014; Wright et al., 2016; Doyle et al., 2018; 2022). These data are
96 particularly powerful when used in tandem with surface measurements of ice motion across
97 spatial scales sufficient that capture both regional and local subglacial processes (Andrews et al.,
98 2014; Doyle et al., 2013; Mejia et al., 2022). GNSS-derived ice motion is a well-established
99 method for inferring subglacial efficiency; increases in surface velocity typically relate to regional
100 basal water pressure variations, while surface uplift can indicate hydraulic jacking (Iken et al.,
101 1983; Iken and Bindschadler, 1986; van de Wal et al., 2008). Passive seismic observations provide
102 a complementary perspective, where glacio-hydraulic tremor serves as a proxy for temporal
103 variations in regional subglacial discharge, where increased turbulence in subglacial channels
104 correlate with higher seismic power at specific frequencies (Bartholomaus et al., 2015; Gimbert
105 et al., 2016; Mejia et al., 2022). However, our current understanding of GrIS subglacial drainage
106 remains limited by the sparse and spatially restricted nature of direct observations, making it
107 challenging to infer large-scale drainage connectivity and properties (Luthi, 2013), and the limited
108 intersection between surface and sub-surface measurements of active drainage routes.

109 While boreholes offer stochastic access to the subglacial drainage system, often intercepting
110 poorly connected cavities, moulins provide direct access to channelized drainage and the
111 hydraulic response of subglacial channels to surface melt variability. Combining these data with
112 surface dynamic observations (e.g., Andrews et al. 2014; Cowton et al., 2013; 2016; Mejia et al.,
113 2021; 2022; Covington et al., 2020) can reveal hydrological behaviours often analogous to those
114 observed in mountain glaciers, including seasonally evolving subglacial drainage that modulates
115 ice sliding speeds (Andrews et al., 2014; Hoffman et al., 2011). Previous studies have typically

116 targeted moulins with large supraglacial inputs ($\sim 10^{-1}$ to 10 m^3 s^{-1}; e.g., Andrews et al., 2014;
117 Cowton et al., 2016), but the dynamics of smaller, local, secondary channels and their
118 connectivity to larger, primary subglacial drainage axes remain less well constrained. These
119 smaller channels likely deliver significant meltwater inputs to the primary drainage system, with
120 a periodicity that could modulate hydraulic response. We aim to explore the evolving hydraulic
121 connectivity of primary and secondary subglacial drainage systems beneath a land-terminating
122 outlet glacier of the GrIS through the deployment of novel wireless "Cryoegg" sensors and a
123 cabled piezometer, to measure water pressure and electrical conductivity (EC) in small moulins.
124 These observations occurred in tandem with high resolution GNSS-derived ice motion, passive
125 surface measurements of seismic tremor as a proxy for subglacial water discharge and
126 meteorological measurements of surface melt, to develop a full picture of the response of an
127 active sector of the GrIS to changing surface melt inputs.

128 **2 Methods**

129 2.1 Study Site

130 Isunnguata Sermia is a large land-terminating outlet glacier on the western margin of the GrIS,
131 situated in an overdeepened subglacial trough $\sim$650 m deep (Lindbäck et al. 2014). Our field site
132 is $\sim$800 m south of the trough and approximately 8 km from the terminus, in an area hypothesized
133 to contain multiple active subglacial lakes (Fig. 1a; Livingstone et al., 2019). Bed topography
134 measurements and subglacial routing from hydraulic potential predict a major subglacial
135 drainage axis through this trough (Fig. 1a; Livingstone et al., 2019; Pitcher et al., 2020). This axis
136 drains one of the largest land-terminating catchments in Greenland, routinely ranking among the
137 top five annual modelled runoff outlets of the GrIS (Fig. S4; Mankoff et al., 2020). Peak summer
138 subglacial discharge in the Isunnguata Sermia trough is estimated to be on the order of 10^3 m^3 s^{-1}
139 (Mankoff et al., 2020), approximately four orders of magnitude higher than the secondary, local
140 subglacial channels (10^{-2} m^3 s^{-1}) fed by the instrumented moulins.
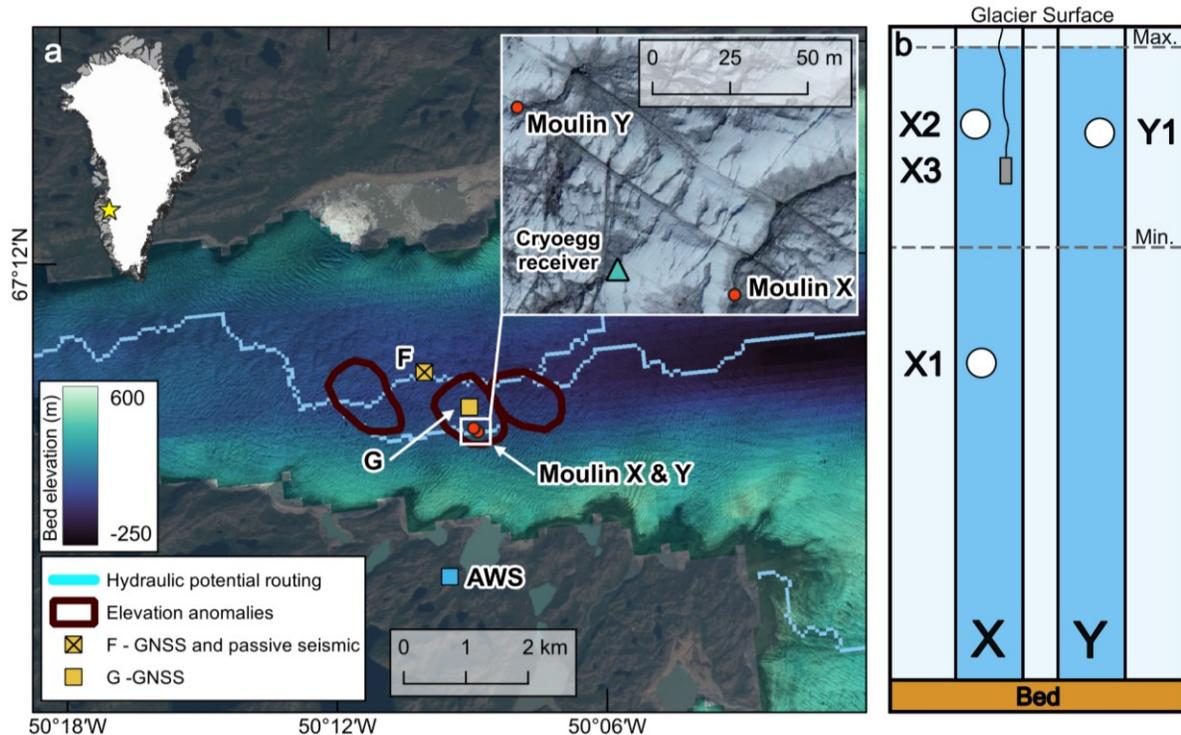
Figure 1. Study site on Isunnguata Sermia in southwest Greenland: (a) Overview of the study area, on a Sentinel-2 true-color image background. The shading represents the bed elevation from BedMachineV5 (Morlighem et al. 2022). Outlines of elevation anomalies (dark gray polygons) mark locations of suspected subglacial lakes (Livingstone et al. 2019) and the light blue line shows the dominant subglacial hydraulic potential routing. The inset on the top right shows a UAV true-color orthorectified image of instrumented Moulins X and Y. b) Schematic cross section of Moulins X and Y with estimated instrument locations (to scale in the vertical dimension), min/max moulin hydraulic head is denoted by the dashed lines.

2.2 Moulin instrumentation:

During July 2024, we instrumented two adjacent moulins (Moulins X and Y, Fig. 1a; 67° 10' N, 50° 10' W) above the margins of a suspected active subglacial lake (Livingstone et al. 2019) (Fig. 1a). Both moulins had an approximate radius at the surface of 2 m (Fig. S1) and small, poorly defined ice surface catchments of ~300 m^2. We estimated typical daily stream discharge into both moulins during the study period (July to August) to be about 0.03-0.06 m^{3}s^{-1} (Table S1).

Moulin X was instrumented on 12th July 2024 with a Geokon 4500SHSRX vibrating wire piezometer rated to 5 MPa attached to 400 m of cable with an integral high-tensile steel core. The Geokon piezometer was factory calibrated, and then zeroed in the field according to manufacturer's guidance to achieve accuracy of 0.1 bar. After calibration, the sensor was gradually lowered into the moulin until the pressure reading stopped increasing when additional cable was released; at which point the cable was anchored at the surface, with 300 m of cable

162 between the sensor and the ice surface. Water pressure and temperature were recorded at 15-
163 minute intervals by a Campbell CR1000 logger via a AVW200 vibrating wire interface (Fig. S2c).

164 We also installed two Cryoegg wireless sensor systems (Prior-Jones et al. 2021), X1 and X2, on
165 the 12th and 26th July 2024 respectively. Moulin Y, located ~90 m northwest from Moulin X, was
166 instrumented with a single Cryoegg (Y1) on the 18th July. The Cryoeggs were deployed by
167 dropping them into a moulin, where they descended via free-fall until becoming lodged or
168 entering the moulin water column (Movie S1). Cryoeggs recorded the water pressure, EC and
169 water temperature and transmitted their data wirelessly via VHF radio to a receiver on the ice
170 surface at hourly intervals (Figure S2a). The Cryoegg pressure and temperature sensor (Keller
171 7LD, 100 bar) was factory calibrated, whilst the EC sensor was bespoke and calibrated with a
172 dilution series of NaCl solution mixed with surface meltwater, cross-checked with a low-range
173 conductivity meter (Hanna), specifically targeting the most likely range for ice melt (2-50 μS cm^{-1}
174). Supraglacial meltwater inputs are typically solute-poor with low EC (~0.1 to 5 μS cm^{-1}; Collins,
175 1979; Gordon et al., 1998), whereas water with subglacial origin can have a significantly higher
176 EC (20 to 60 μS cm^{-1}; Tranter et al., 1997; Gordon et al., 1998) due to increased contact with
177 subglacial sediments, bedrock and debris-laden ice, and subsequent chemical weathering (Stone
178 and Clarke 1996), thus the sensor was calibrated to maximise sensitivity in these ranges. The
179 surface receiver included a barometric pressure sensor (TE Connectivity MS506702BA03) to
180 correct water pressure for atmospheric pressure variations, and an Iridium transceiver that
181 transmitted all received data to a UK-based server every hour. The Cryoeggs were modified with
182 a foam and mesh flotation device that increased their buoyancy asymmetrically, bringing them
183 closer to neutral buoyancy (Figure S2b) to aid their transit through the englacial drainage system.

184 To obtain an estimate of sensor depth relative to the bed, we recorded the free-fall duration of
185 Cryoegg Y1 before it impacted an ice ledge above the moulin's hydraulic head (confirmed by EC
186 readings). Combining this measurement with ice thickness estimates from nearby ice penetrating
187 radar surveys enabled calculation of Cryoegg Y1's height above the bed. By assuming hydraulic
188 equilibrium between Moulins X and Y at a selected reference date (Fig. S3), we converted water
189 depth to orthometric hydraulic head and water pressure to percentage of ice overburden (Text
190 S1). Cryoegg X2 and Y1, and Geokon X3, were only submerged in water when hydraulic head was
191 high, while Cryoegg X1 provided a full record of moulin hydraulic head. The EC time series from
192 Cryoegg Y1 was anomalous, suggesting the sensor was damaged during deployment. Therefore,
193 the measurements from this sensor are indicative, and only used to detect the transition
194 between submerged and dry conditions.

195 2.3 Meteorological data:

196 Hourly surface meltwater production over our field site was modeled using COSIPY – a COupled
197 Snowpack and Ice surface energy and mass-balance model in PYthon (see Sauter et al. 2020),
198 forced by extrapolated data from the PROMICE KAN_L automatic weather station (AWS) (Fausto
199 et al. 2021), which is situated approximately 12 km southeast of our field site at an elevation of
200 ~630 m a.s.l. Air temperature was extrapolated to the elevation of our field site using a lapse
201 rate of -5.3°C km^{-1} (Harper et al., 2011), and atmospheric pressure was corrected using a

202 barometric equation. Precipitation and snowfall data were extracted from the nearest ERA5-Land
203 reanalysis grid cell (native resolution of 9 km, Muñoz Sabater et al. 2021). While simple
204 extrapolation of variables limits the accuracy of absolute melt values over our field site, the
205 temporal variation in surface melt provided useful insight into the timing and magnitude of
206 surface water inputs into the subglacial hydrologic system. We also used air temperature data
207 from an AWS deployed 3 km south of our field site (elevation of 515 m a.s.l.; AWS in Fig. 1a). This
208 AWS does not measure all variables needed to force a surface energy balance model, hence the
209 use of KAN_L for calculating surface melt. For investigating rainfall, we also use precipitation data
210 measured by the land-based KAN_B weather station, located 6 km south of our field site.

211 2.4 Measurements of horizontal and vertical ice surface motion:

212 Time series of horizontal and vertical ice surface motion were determined from dual frequency
213 (L1 + L2) Global Navigation Satellite System (GNSS) data recorded by Leica GS10 and GM30
214 receivers at 0.1 Hz. GNSS stations F (67° 11' N, 50° 9' W) and G (67° 10' N, 50° 8' W) were located
215 1.2 km and 0.35 km from Moulin Y respectively (Fig. 1). GNSS antennas were mounted on 6-m-
216 long aluminium poles drilled 5 m into the ice surface. Rapid re-freezing of the hole secured the
217 antenna pole within the ice. Data were post-processed kinematically (King, 2004) relative to a
218 bedrock-mounted reference station using the differential carrier-phase positioning software
219 Track v1.53 (Chen, 1998). Baseline lengths were <4 km and precise ephemerides from the
220 International GNSS Service were used (Dow et al., 2009). Positioning uncertainties were
221 estimated at ~0.01 m in the horizontal and ~0.02 m in the vertical by calculating the standard
222 deviation of the residuals from linear regression applied to the position time series during a
223 month-long period of steady ice motion in November 2023. Small (<5 min) gaps in the position
224 record were linearly interpolated before a second-order 6 h low-pass Butterworth filter was
225 applied. The position record was then resampled to 10-minute medians and differentiated to
226 calculate velocity, which was further filtered using a 6 h moving average. To prevent phase shifts,
227 phase-preserving filters, differentiation, and resampling methods were used throughout. Vertical
228 displacement due to advection over varying bed topography was removed by calculating local
229 bed slope angles during stable winter periods (Hooke et al., 1989; Andrews et al., 2014). To
230 account for changing topography throughout the season, bed slope values were linearly
231 interpolated between calculations made before and after the 2024 melt season. These
232 calculations assume that basal sliding accounts for 96 % of the surface velocity measured by the
233 GNSS receivers (Maier et al., 2019) and that vertical displacement from cavity opening or
234 overburden pressure changes is negligible during non-melt season periods.

235 2.5 Measurements of glacio-hydraulic seismic tremor

236 To characterize water flow in the subglacial drainage system we installed a seismometer at site F
237 (Fig. 1) comprising a C100 Geobit borehole geophone with a corner frequency of 4.5 Hz drilled
238 to 5 m depth and logged by a Digos DATA-CUBE[3] at 100 Hz. Measurements of glacio-hydraulic
239 seismic tremor in alpine glaciers (Bartholomaus et al. 2015; Gimbert et al. 2016; Nanni et al. 2020)
240 and in Greenland (Mejia et al. 2022) have been used as a proxy for subglacial discharge and water
241 pressure. Seismic power was calculated by performing Welch's method over 3 s time windows

242   with 50% overlap (Welch, 1967) on the vertical component of ground motion. This time window
243   was chosen to minimise the influence of short-duration, but high energy, events such as
244   icequakes. To isolate the seismic tremor caused by subglacial discharge, the mean power
245   between 2 and 10 Hz (Bartholomaus et al. 2015; Gimbert et al. 2016) over 60 s time windows was
246   calculated and displayed in decibels (dB; decimal logarithmic).

247   **3 Results**

248   Between 18th July and 31st August 2024, the catchment exhibited five distinct periods of
249   hydrological behavior. These periods were grouped into two modes that had similarities in the
250   relationship between surface melt, ice velocity, glacio-hydraulic seismic tremor, moulin hydraulic
251   head and moulin EC. During Mode 1 moulin head and ice velocity co-vary (periods 1, 3 and 5;
252   pale red shading Fig. 2); while during Mode 2 moulin head exhibits large diurnal variations while
253   ice velocity and seismic tremor remain relatively stable or decrease towards background levels
254   (periods 2 and 4; blue shading Fig. 2).
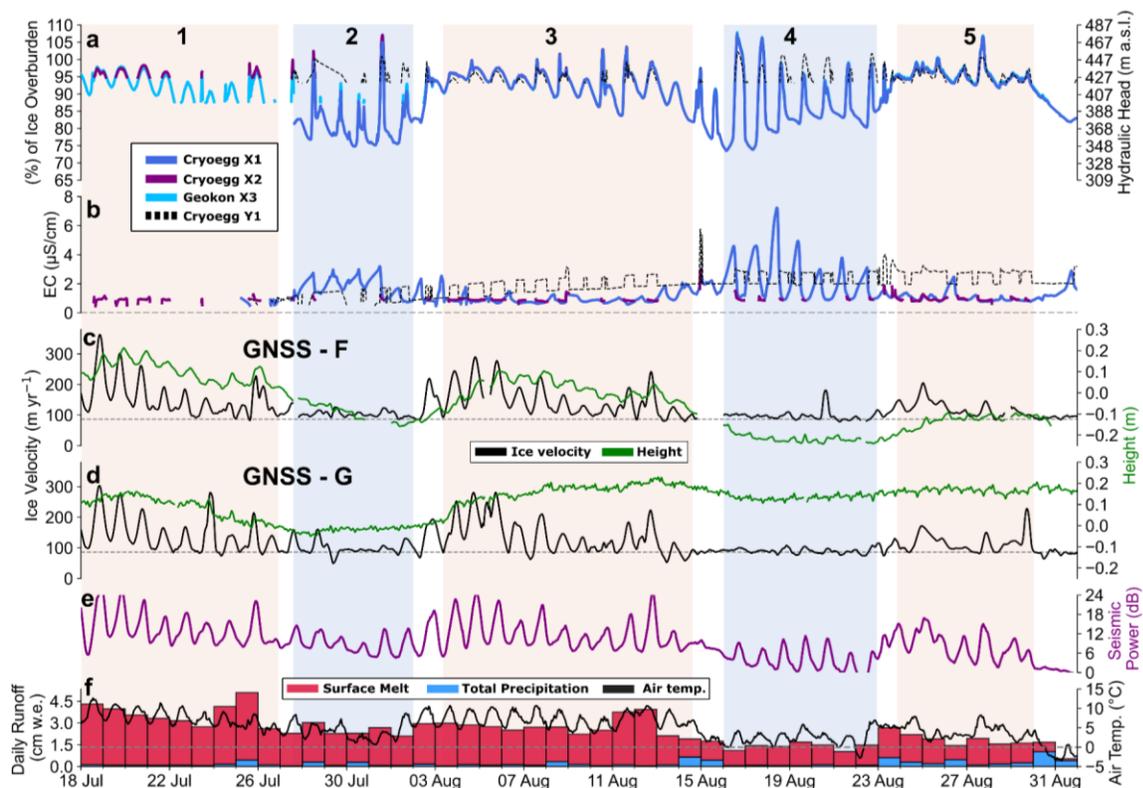
255
256   **Figure 2:** Supra- and englacial measurements from summer 2024. a) Hydraulic head in Moulin X
257   and Y. b) Electrical conductivity in Moulin X and Y. c) GNSS-derived ice velocity (black) and height
258   (green) for GNSS F. d) Same as c) for GNSS G. e) Mean seismic power at F for the frequency range
259   2 to 10 Hz. f) Modeled daily melt (red bars), daily rainfall from KAN_B weather station (blue bars)
260   and hourly air temperature at the AWS (black). Bold numbers on (a) denote identified periods
261   discussed in the text. Pale red shading highlights periods of Mode 1 behavior and pale blue

262 periods of Mode 2 behavior. The horizontal dashed gray line on (c) and (d) marks denotes the
263 median winter ice velocity for G. Time is West Greenland Summer Time (UTC -2).

264 *Period 1 (18th to 27th July 2024):*

265 Period 1 was characterized by strong diurnal fluctuations of surface melt, ice velocity, seismic
266 tremor and moulin hydraulic head (Fig. 2). Peak moulin hydraulic head, ice velocity, surface
267 height and seismic tremor all lagged peak daily surface melt. The mean lag time with respect to
268 melt varied from 6.7 ± 2.3 hours for hydraulic head, 5.6 ± 1.8 hours for ice velocity at G and F,
269 10.0 ± 1.6 hours for surface height at F and 8.5 ± 1.3 hours for seismic tremor (Fig. 3c-f). Moulin
270 X hydraulic head averaged ~94% of ice overburden pressure (~420 m a.s.l. hydraulic head) with
271 smooth diurnal variations of approximately 6 to 8% of ice overburden (~25 m hydraulic head)
272 (Fig. 2a), whilst ice velocity exhibited diurnal variations of up to ~200 m yr^{-1} at F and G (Fig. 2c-d).
273 Between the 21 and 24 July, the daily mean moulin hydraulic head decreased, with the water
274 level falling below the Geokon X3 sensor level (equivalent to ~ 86% of ice overburden) for ~10
275 hours overnight between 22nd and 27th July (Fig. 2a). This reduction in head coincided with
276 decreasing daily surface melt, a generally decreasing diurnal amplitude of ice velocity from ~200
277 m yr^{-1} to 50 m yr^{-1} (Fig. 2c), and declining seismic tremor at F (Fig. 2e). GNSS F, located over a
278 predicted major subglacial drainage route, exhibited diurnal variations in surface height of ~8 cm
279 day^{-1}, and had a background decrease in height of 20 cm (Fig. 2c), whilst GNSS G showed muted
280 diurnal variation but underwent a gradual 21 cm decrease in vertical position (Fig. 2d). EC showed
281 no resolvable variation during this period, with values of ~1 µS cm^{-1} (Fig. 2b).

282 *Period 2 (28th July to 3rd August 2024):*

283 Following two days of elevated surface melt on 24th and 25th July (~4 cm w.e. day^{-1}, Fig. 2f), daily
284 melt rates declined and the diurnal melt cycle became less distinct. This reduction in surface melt
285 marked the onset of a shift in dynamic and hydrological behavior, during which ice velocity
286 decoupled from the diurnal surface melt cycle. During period 2, the lag times for ice velocity and
287 surface height were highly variable or absent due to the muted diurnal variations (Fig. 3c-e). In
288 contrast, the lag time for the moulin hydraulic head decreased to 1.3 ± 0.9 hours, while EC
289 became inversely correlated, peaking 21.5 ± 1.3 hours after peak melt (Fig. 3a-b). Diurnal
290 variations in head at Moulin X became more pronounced, with an initial rapid increase from 75
291 % to 105 % of ice overburden pressure over 6 hours, followed by a decrease to 80% of ice
292 overburden pressure over 3 hours, and then a more gradual decrease overnight to 74% over 14
293 hours. The maximum diurnal range was ~30 % of ice overburden, with pressures reaching a
294 minimum of 75% and occasionally exceeding ice overburden pressure (Fig. 2a), notably different
295 to Period 1. This variation in head occurred with no associated increase in height or horizontal
296 ice displacement at G or F, and ice velocities decreased to the winter median or lower (Fig. 2c-d).
297 Tremor at F exhibited a gradual decline with a smaller diurnal amplitude (Fig. 2d) and a reduced
298 lag time, peaking 5.95 ± 2.5 hours after peak surface melt (Fig. 3f) . EC exhibited a strong, lagged
299 inverse correlation with hydraulic head and melt. For example, EC at Cryoegg X1 (~200 m above
300 the bed) displayed distinct diurnal variations superimposed on a gradual increase over ~17 hours
301 (up to ~2.5 µS cm^{-1}) as moulin hydraulic head decreased and stabilized. This was followed by a

302   rapid decline over ~5 hours as the hydraulic head rose again with the influx of surface meltwater
303   on 31st July (Fig. 2a). The daily minimum EC values remained elevated (> 1.5 µS cm^{-1}) from 28th to
304   31st   July,   with   later   minimum   daily   values   generally   <1   µS   cm^{-1}.
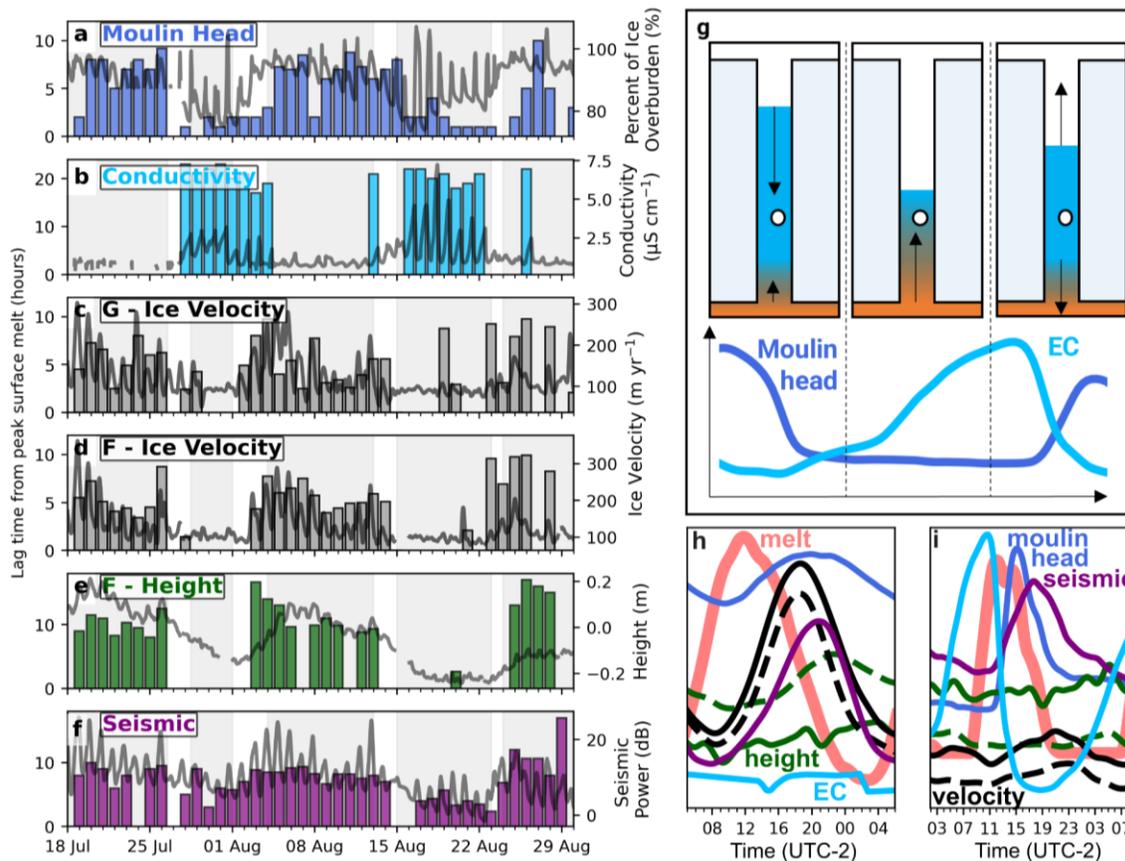
305
306   **Figure 3:** (a–f) Lag times (hours) between daily peaks in surface meltwater production and
307   subsequent peaks in measured variables (bars, left axis). Solid gray lines denote the variation of
308   each variable (right axis). (g) Conceptual model of the diurnal cycle of moulin head and electrical
309   conductivity during a disconnected period (plot shows 17th to 18th July 2024). (h and i) Normalized
310   time series comparing (h) connected (periods 1, 3 and 5) and (i) disconnected drainage periods 2
311   and 4. Line colors for each variable are consistent with plots (a to f). Height and velocity is shown
312   by a solid line for G and dotted line for F.

313   *Period 3 (3rd to 14th August 2024):*

314   With increased daily surface melt from the 1st to 2nd August (from 2.0 to 2.8 cm w.e. day^{-1}; Fig.
315   2f), the well-coupled behavior observed in Period 1 returned, characterized by large diurnal
316   variations in all variables apart from EC (Fig. 2). This re-coupling was also evident in the lag times
317   between peak surface melt and peaks in moulin hydraulic head at 6.3 ± 2.2 hours, ice velocity at
318   F and G at 5.3 ± 1.8 hours, surface uplift at F at 10.7 ± 1.9 hours, and seismic tremor at F at 8.2 ±
319   0.7 hours (Fig. 3a-f). Moulin X hydraulic head had a mean of ~93% of ice overburden. While the
320   initial diurnal range was ~5%, like Period 1, the variability increased in the latter half of the period
321   to ~15% as surface melt and ice velocity decreased. The almost identical diurnal variations in
322   hydraulic head at Moulin X and Y suggests they were hydraulically well connected (Fig. 2a). On

323 several days (e.g., 7th to 10th August), moulin hydraulic head showed a double-diurnal peak, with
324 an initial spike followed by a secondary sinusoidal curve. Over four days from 2 to 6 August, GNSS
325 F and G increased in height, by 26 cm and 16 cm respectively. Site F showed diurnal variations in
326 surface uplift of 6 to 8 cm (Fig. 2c), while no well-defined diurnal variation was present at G (Fig.
327 2d) and EC remained low (<1 μS cm^{-1};Fig. 2b).

Period 4 (15th to 23rd August 2024):

329 Daily surface melt decreased significantly from ~4 cm w.e. day^{-1} on 12th August to ~1.5 cm w.e.
330 day^{-1} by 14th August (period 4; Fig. 2f). This coincided with air temperatures dropping below
331 freezing on 16 August for the first time in the study period (Fig. 2f). Ice velocity and surface uplift
332 at G and F were characterized by muted diurnal variability, and their vertical positions decreased
333 by 13 and 23 cm respectively from 13th to 18th August (Fig. 2c-d). As melt decreased, moulin
334 hydraulic head initially exhibited increased diurnal variability, which decreased throughout the
335 period due to the convergence of maximum and minimum values (Fig. 2a). The hydraulic head
336 averaged ~85% of ice overburden during period 4, with a diurnal range of nearly 33%, and
337 exceeded ice overburden pressure on 17th and 18th August (Fig. 2a). The diurnal pattern of
338 hydraulic head resembled Period 2, with a rapid increase followed by a two-step decrease. When
339 submerged, Cryoegg Y1 recorded a similarly high hydraulic head in Moulin Y, with its daily
340 maximum exceeding that of Moulin X by up to 10% of ice overburden pressure (~40 m hydraulic
341 head) from 18th to 23rd August (Fig. 2a). EC exhibited a rapid shift in behavior with pronounced
342 diurnal variations of 3 μS cm^{-1} up to a maximum daily value of ~7 μS cm^{-1}, inversely correlated
343 with the hydraulic head (Fig. 2b). Moulin hydraulic head had a lag time of only 1.8 ± 1.0 hours, EC
344 of 20.4 ± 1.5 hours and seismic tremor of 3.9 ± 1.0 hours from peak surface melt (Fig. 3a-f).

Period 5 (24th to 30th August 2024):

346 On 24th August, rising air temperature led to increased and more variable overnight surface melt,
347 contrasting with the cessation of melt during the nights of the preceding period (Fig. 2f). This
348 shift triggered increased variability in seismic tremor at F (Fig. 2e), followed by greater variations
349 in ice velocity at both G and F, alongside a 20 cm rise in surface height at F (Fig. 2c). In contrast,
350 the height at G remained relatively stable (Fig. 2d). Less pronounced diurnal variability of surface
351 melt rendered the lag times highly variable and difficult to discern (Fig. 3a-f). Between 22nd and
352 26th August, sustained overnight surface melt resulted in a high and stable moulin hydraulic head
353 at both Moulin X and Y, maintaining ~95% of ice overburden pressure with variations of <5% (Fig.
354 2a). Diurnal variations in EC remained muted, stabilizing at around 1 μS cm^{-1} (Fig. 2b), except for
355 a 0.5 μS cm^{-1} increase on 26th August, coinciding with a day of low surface melt. After an increase
356 in daily surface melt on 27th August, moulin hydraulic head briefly exceeded ice overburden
357 pressure, followed by an increase in ice velocity at G and F (Fig. 2c-d). On 30th August, a decline
358 in daily surface melt (Fig. 2f) drove a linear decrease in moulin hydraulic head from 95% to 80%
359 of ice overburden pressure over a two-day period (Fig. 2a). This was coincident with a large
360 speed-up event at G (but not F), which was unrelated to surface melt forcing (Fig. 2d).

4 Discussion

The behavior exhibited during the five time periods was grouped into two characteristic hydrological modes that we classify as 'connected' (Mode 1), periods of regional-catchment dominated drainage where most variables co-vary (periods 1, 3 and to a certain extent, 5) and 'disconnected' (Mode 2), indicating more localized controls on drainage (periods 2 and 4). We attribute the rapid (<24 h) switching between these modes to interaction between the local secondary drainage system beneath the instrumented moulins and the larger, primary subglacial drainage axis located within the deep subglacial trough.

To differentiate between these different scales of drainage, we hereafter use the terms "primary" and "secondary" to refer to the subglacial drainage features, and "regional" and "local" to describe their respective catchments. The primary drainage axis is defined by the major subglacial drainage route that drains the main regional catchment up-glacier of our study site (~ 14,000 km^2; Mankoff et al., 2020), which is situated in the deep subglacial trough. The secondary (or subsidiary) channels are smaller conduits fed by a local catchment (typically ~ 300 m^2), represented by the instrumented moulins. This distinction allows us to differentiate between large-scale glacio-hydraulic response and local variations in subglacial water pressure.

Glaciological setting of the instruments

The passive seismic sensor and GNSS at F are located over the ~650-m-deep subglacial trough (Lindbäck et al. 2014), near a predicted major subglacial drainage route (Figs 1c, 4). We expect the seismic tremor at F (Fig. 2e) to represent the hydraulic characteristics of this drainage route, with high seismic power between 2 and 10 Hz indicating high subglacial discharges and/or turbulent flow driven by hydraulic gradients (Bartholomaus et al. 2015; Gimbert et al. 2016). In contrast, variations in ice velocity (Fig. 2c-d) are interpreted as a response to changes in basal sliding modulated by averaged regional basal water pressure (Iken and Bindschadler, 1986; Kamb et al., 1994). GNSS G was located ~400 m southeast of F above the centre of a purported active subglacial lake identified from elevation anomalies in satellite altimetry data (Livingstone et al., 2019; Figs. 1a, 4). Moulins X and Y were located approximately 800 m away from the main drainage route, on the edge of the elevation anomaly of the active subglacial lake (Fig. 4).

389
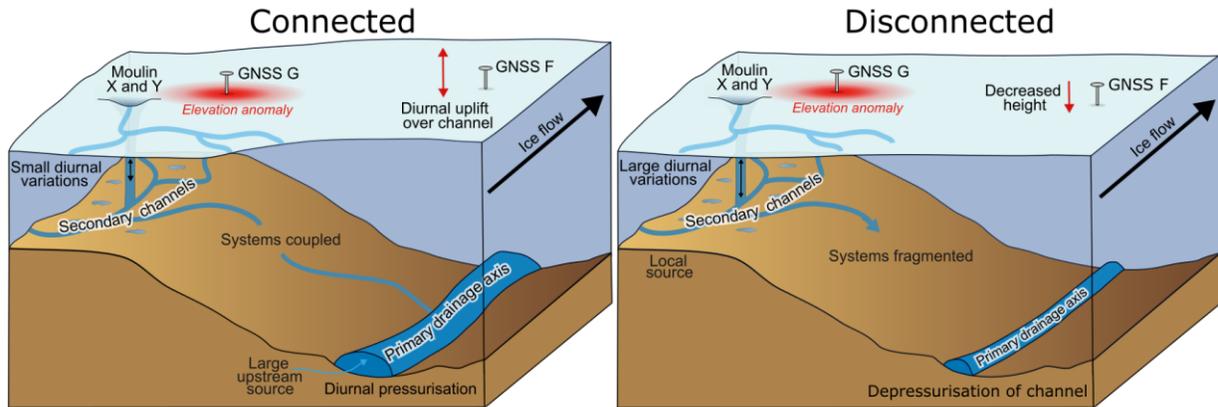
Figure 4. Schematic cross-section of study site for (a) connected periods and (b) disconnected periods. Ice flow is into the page. Figures are not to scale.

Proximity to the primary subglacial drainage axis, and the extent of the channelization, controls the response of the measured variables to changes in surface water inputs. During high melt periods, ice velocity, surface uplift and seismic tremor at F (Fig. 2c and 2e) exhibit strong diurnal cycles, related to increasing discharge and daily pressurization in the primary drainage axis as surface meltwater inputs from the wider catchment are routed through the trough. Further away at G (Fig. 2d), ice velocity shows a strong response but the diurnal cycle of surface uplift associated with pressurization of the primary drainage route is muted (Fig. 4). Moulin hydraulic head is episodically in phase with ice velocity (i.e. during 'connected' periods), but there are also 'disconnected' periods where water pressure exceeds ice overburden pressure with no associated increase in ice velocity or surface uplift at GNSS F or G (e.g., 31st July, 16th and 17th August; Fig. 2a). This illustrates the complex response of the ice surface to subglacial hydrological events in a small region: the ice velocity at G and F, along with the seismic tremor at F, reflect regional ice motion controlled by the primary subglacial drainage axis near F (Fig. 4). In contrast, while hydraulic head in Moulins X and Y (Fig. 2a) periodically co-varies with the diurnal ice motion and seismic tremor variations observed at F and G, at other times (e.g., periods 2 and 5) they respond to local surface water inputs. This, in tandem with similar observations where the relationship between hydraulic head and ice velocity varies according to connectivity with the drainage system in Greenland (Andrews, et al. 2014) and beyond (Rada and Schoof, 2018; Rada and Schoof 2023), suggests hydrological switching controlled by local (<1 km^2) or regional (> 1 km^2, and potentially glacier-scale) responses to melt.

Connected, efficient subglacial drainage responds to regional events:

The strong diurnal fluctuations in ice motion at F and G during 'connected' periods 1 and 3 (Fig. 2c-d) are indicative of an efficient, channelized subglacial drainage system, as observed by other studies in the ablation zone of the GrIS (Andrews et al. 2014; Cowton et al., 2016; Mejia et al., 2021; Chandler et al., 2021). Diurnal variability in surface melt causes pressurization of the primary subglacial drainage axis and surrounding hydraulically connected drainage system (Hubbard et al., 1995; Gordon et al., 1998), reducing basal friction and thus increasing velocity.

419   Transient pressurization of the primary drainage axis explains the strong diurnal surface uplift at
420   F (Fig. 2c), a behavior well-documented in other studies (Shepherd et al., 2009; Iken &
421   Bindschadler, 1986; Nienow et al., 2005; Sugiyama et al., 2008). In contrast, surface uplift at G
422   (Fig. 2d) does not have a strong diurnal cycle but rather displays a period-dependent cycle
423   comprising increased uplift during periods 1 and 3 and decreased uplift in periods 2 and 4 (Fig.
424   2d). Since G is further away from the primary subglacial drainage axis (Fig. 1 and 4), the effects
425   of pressurization are dampened. This is consistent with observations from Tedstone et al., (2014)
426   that show distributed drainage can readily interact with channelized features, smoothing out
427   spatial variations in velocity caused by pressure fluctuations within the channel.

428   The large lags between peak surface melt and ice velocity at F and G (~5 hours, Fig. 3) and seismic
429   tremor (~8 hours, Fig. 3) suggests that the system is driven by a large, upstream water source
430   (Chandler et al., 2021; Mejia et al. 2022). This behavior aligns with the large scale of the
431   Isunnguata Sermia catchment, which ranks among the top five largest runoff outlets of the entire
432   ice sheet (Fig. S4; Mankoff et al., 2020). In comparison, the nearby Leverett Glacier has a
433   substantially smaller catchment and typically exhibits a smaller lag between surface melt and ice
434   velocity of 2 to 3 hours (Shepherd et al. 2009; Bartholomew et al. 2011). The ~3 h difference in
435   lag time between ice velocity and seismic tremor may be because the velocity is associated with
436   the greatest rate of change of melt input (i.e. the rising limb), but tremor peaks at the subglacial
437   discharge maxima.

438   The moulin hydraulic head variations during periods 1 and 3 (Fig. 2a) align closely with the diurnal
439   behavior recorded by the instruments at F and G (Fig. 2c-d). Compared to inferred efficient,
440   channelized moulin head variations reported in Andrews et al., (2014), the diurnal variations
441   reported here show a smaller diurnal range and higher average. We attribute this difference to
442   the smaller size of our instrumented moulins and the associated channelized subglacial drainage
443   system, which exhibits less capacity to accommodate diurnal fluctuations in subglacial discharge.
444   The sinusoidal diurnal cycle in hydraulic head, with a large lag between peak surface melt and
445   hydraulic head (~6 hours, Fig. 3a), is interpreted to reflect the smoother regional discharge signal
446   (Chandler et al., 2021; Mejia et al. 2022). This implies that during the 'connected' periods, Moulin
447   X is hydraulically linked to the primary subglacial drainage axis , as locally derived meltwater
448   would typically produce a more immediate response in both water pressure and EC during the
449   efficient late-melt season, as seen in periods 2 and 4 (Fig. 4a). However, some days are
450   characterized by two peaks (e.g., 8th August, Fig. 2a), with an earlier rapid spike likely
451   representing locally-sourced surface meltwater inputs preceding the regional signal. There is an
452   anti-clockwise hystereses between surface melt and ice velocity, seismic tremor, and moulin
453   head (Fig. S5) demonstrating modulation of the system by upstream water (Chandler et al., 2021).
454   The low EC with limited variability suggests an efficient, channelized drainage system with low
455   residence times (Rada & Schoof, 2018). Consequently, we infer that the EC signal is dominated

456 by supraglacial inputs into the moulin rather than water that has had prolonged contact with the
457 bed (Gordon et al., 1998).

458 *Local, disconnected drainage:*

459 At the start of time periods 2 and 4, a 50% and 70% decrease in daily surface melt (Fig. 2f),
460 respectively, triggered a rapid shift in system behavior. The gradual decline in seismic tremor (Fig.
461 2e) with subdued diurnal variations indicates a reduction in discharge and / or water pressure
462 (Nanni et al. 2020), consistent with a subglacial drainage route that is now largely able to
463 accommodate the reduced melt inputs. The gradual drop in surface height at F and G (Fig. 2c-
464 d)indicates depressurization of the main drainage route and surrounding cavities hydraulically
465 connected to it, leading to increased basal traction and reduced sliding (Hoffman et al., 2011;
466 Mair et al., 2001; Iken and Truffer, 1997). This behavior is consistent with the decrease in ice
467 velocity to below the winter median (van de Wal et al. 2008; 2015; Sole et al. 2013; Fig. 2c-d).

468 The moulin hydraulic head during periods 2 and 4 exhibits large diurnal variations, frequently
469 reaching ice overburden pressure, without a corresponding increase in vertical or horizontal ice
470 motion response at G (Fig. 2a). Combined with the reduced lag time (~2 hours; Fig. 4a), which
471 points to a direct, local meltwater source, we interpret this behavior to indicate Moulins X and Y
472 becoming hydraulically disconnected from the primary subglacial drainage axis or other
473 upstream sources, and instead exhibit local variations in subglacial hydrology. This interpretation
474 is further supported by differences in maximum daily hydraulic head (e.g., 31st July–2nd August
475 and 18th–23rd August; Fig. 2a) occasionally observed between moulins X and Y, despite their
476 proximity (50 m apart). These differences suggest they are occasionally hydraulically
477 disconnected from each other and it is therefore unsurprising that they are also disconnected
478 from the main channel (Holmlund and Hooke 1983; Holmlund 1988). Fragmentation of
479 hydrological features is likely to occur both hydraulically and mechanically due to the increased
480 effective stress (bridging stresses) as the main drainage route depressurizes (Weertman, 1972).
481 These disconnected periods are similar to the 'switching behaviors' observed in previous studies,
482 where isolated cavities connect and disconnect from the main channelized system (Fudge et al.,
483 2008; Gordon et al., 1998; Murray & Clarke, 1995; Rada & Schoof, 2018; Andrews et al., 2014).

484 The larger diurnal fluctuations in EC during periods 2 and 4 show the influence of meltwater that
485 has had increased contact time with subglacial sediments (Gordon et al., 1998, 2001).
486 Asymmetric moulin hydraulic head (Fig. 3i) and longer residence times indicate the transient
487 storage and release of meltwater within the sediments and cavities surrounding the local
488 subglacial channel (Hubbard et al., 1995), a scenario simulated by gradual leakage of water from
489 weakly connected components of the subglacial drainage system (Hoffman et al., 2016). As
490 moulin hydraulic head increases during the day, the resulting high pressure forces water into an
491 inefficient distributed system adjacent to the local subglacial channel. When surface melt inputs
492 decrease, hydraulic head drops rapidly. This decline is characterized by two distinct phases: a
493 rapid initial drop in head reduces pressure in both the moulin and the connected subglacial
494 channel, during which the moulin EC remains static and low (Fig. 3g); followed by a slower
495 decrease overnight as the moulin begins to equilibrate with the pressure of the adjacent

496 distributed system. During this slower decline, the decrease in channel pressure reverses the
497 hydraulic gradient, releasing subglacial water that had been forced into the distributed system
498 earlier in the day (Hubbard et al., 1995) (Fig. 3g). This process, which can involve Darcian flow
499 through subglacial sediments, returns solute-rich water from the adjacent distributed system
500 into the channel. This water subsequently diffuses up the moulin water column, thereby
501 increasing the EC measured at the sensor location (Gordon et al., 1998).

502 *Implications for understanding ice sheet hydrology*

503 The surface topography of the lower ablation area of Isunnguata Sermia is notable for the large
504 number of small (<3 m diameter) moulins (Jones et al. 2018), which generally have small
505 catchments (<300 m²). The transient nature of these surface-to-bed connections, combined with
506 limited surface melt inputs, and the high density of moulins delivering meltwater to the bed,
507 hinders the development of larger hydrological catchments that could support a well-established,
508 local channelized subglacial drainage system in this region (Banwell et al. 2016). While large
509 diurnal variations in water pressure occur within these local moulins, they have little impact on
510 ice velocity. Instead, ice velocity is dominated by the influence of the primary subglacial drainage
511 axis and the regional background water pressure, which suggests the configuration of the local
512 secondary subglacial drainage system has a negligible impact on the spatial pattern of summer
513 ice motion (Tedstone et al., 2014). Consequently, the local secondary channels act independently
514 of the regional system when melt is low, but become connected into the broader network at
515 higher subglacial discharge.

516 We demonstrate that connectivity between primary and secondary drainage systems beneath
517 the margins of the GrIS changes rapidly and repeatedly in response to both varying daily melt
518 rates and the evolving capacity of the regional network. Despite the location of the monitored
519 moulins, ~800 m from the primary drainage axis along the subglacial trough (Fig. 4), their
520 hydraulic head was frequently influenced by the regional subglacial drainage response. This
521 behavior is consistent with the primary subglacial drainage axis becoming overwhelmed and
522 forming connections to the local secondary channels (Rada and Schoof, 2018; 2023),
523 demonstrating that subglacial channel(s) can have a broad lateral influence on hydrological
524 behavior. The much larger variations in surface melt and subglacial discharge at this site mean
525 that the lateral scale of connectivity (100s meters) is significantly greater than the <100 m scale
526 estimated from borehole arrays on smaller glaciers (Hubbard et al., 1995; Gordon et al., 1998;
527 Fudge et al., 2008; Rada and Schoof 2018; 2023). These lateral bounds are also consistent with
528 the width of meltwater corridors identified in palaeo-ice-sheet settings, supporting the
529 interpretation that these features are the geomorphic expression of hydraulic connectivity
530 (Lewington et al., 2020).

531 Conversely, during cooler periods, the influence of the primary subglacial drainage axis contracts
532 (Fig. 4b)) as the efficient drainage system that has evolved through the melt season is able to
533 accommodate the smaller, less variable melt inputs. This leads to fragmentation of the previously
534 channelized drainage system surrounding the primary drainage axis into hydraulically
535 disconnected and locally-influenced subsystems. While the moulins capture the sensitivity of the

536   local secondary system to changes in runoff, and frequently experience water pressures exceeding
537   ice-overburden pressure, this has minimal influence on ice motion. Regional ice motion is
538   predominantly controlled by the pressure and extent of the primary drainage axis, regardless of
539   local pressure highs in the secondary channels. Therefore, moulin records should not be
540   interpreted in isolation, but rather within the context of their connectivity to the regional
541   drainage system. Our data demonstrate how secondary channels can behave independently;
542   thus in these settings, moulin records are best viewed as a manometer of local connectivity,
543   providing context for interpreting coincident changes, or lack thereof, in ice velocity (Mejia et al.
544   2021). Further insights into these complex hydraulic interactions could also be gained through a
545   dedicated analysis of lag times across different hydrological variables (Mejia et al., 2022). Longer-
546   term records are particularly useful in this context (Rada and Schoof, 2018), especially if
547   supported by other indicators of meltwater residence time such as EC. The use of wireless
548   instruments such as Cryoegg (Prior-Jones et al. 2021) enables capture of these long-term data
549   with fewer logistical challenges than cabled sensors, and satellite telemetry of data provides the
550   functionality to monitor drainage system behaviors in near-real time.

551   **5 Conclusions**

552   Our observations of moulin water pressure, residence time (EC), ice motion (horizontal and
553   vertical velocity) and glacio-hydraulic tremor demonstrate the presence of a local secondary
554   channel(s) that periodically connect to the wider, primary subglacial drainage axis. Connectivity
555   between these two systems switches rapidly (hourly timescales) and frequently (twice during this
556   six-week dataset) in response to variations in melt input. The repeated disconnection of the
557   secondary channel(s) from the primary drainage axis provides evidence of fragmentation
558   between drainage systems on the GrIS. When disconnected (mode 2), local secondary channels
559   become hydraulically isolated (Fig. 4b) and experience large water pressure variations, frequently
560   exceeding ice overburden, that have minimal impact on regional ice velocity. Instead, regional
561   ice dynamics is controlled by the pressure and extent of the large primary subglacial drainage
562   axis adjacent to the catchment, whose lateral influence stretched at least 800 m (more than one
563   ice thickness) from the trough (Fig. 4). This disconnection challenges the assumption that
564   individual moulin and borehole pressure records can serve as direct proxies for regional
565   subglacial drainage conditions. These findings indicate that large primary drainage axes are the
566   fundamental drivers of regional ice dynamics in Greenland, and are capable of obscuring the
567   effects of local pressurisation in secondary channels. While these secondary channels play a
568   minimal role in driving regional ice flow, observing their behavior and connectivity to wider
569   systems provides useful context for process-based modelling of subglacial systems.

570   **Inclusion in Global Research Statement**

Acknowledgments

Open Research

The moulin hydraulic head, GNSS-derived ice motion, passive seismic, and meteorological data will be deposited at the UK Polar Data Centre upon acceptance of this manuscript . The PROMICE weather station data sets are available from How et al., (2022). The liquid ice discharge data are available at Mankoff et al., (2020). The BedMachine v5 dataset is available from Morlighem et al. (2022).

Conflict of Interest Disclosure

The authors declare there are no conflicts of interest for this manuscript.

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Supporting Information

Introduction. The supporting information includes photographs of the cryoegg field deployment, alongside detailed methods for sensor calibration and the calculation of hydraulic head as a percentage of ice overburden. Additionally, it presents supplementary figures for points discussed in the main text.
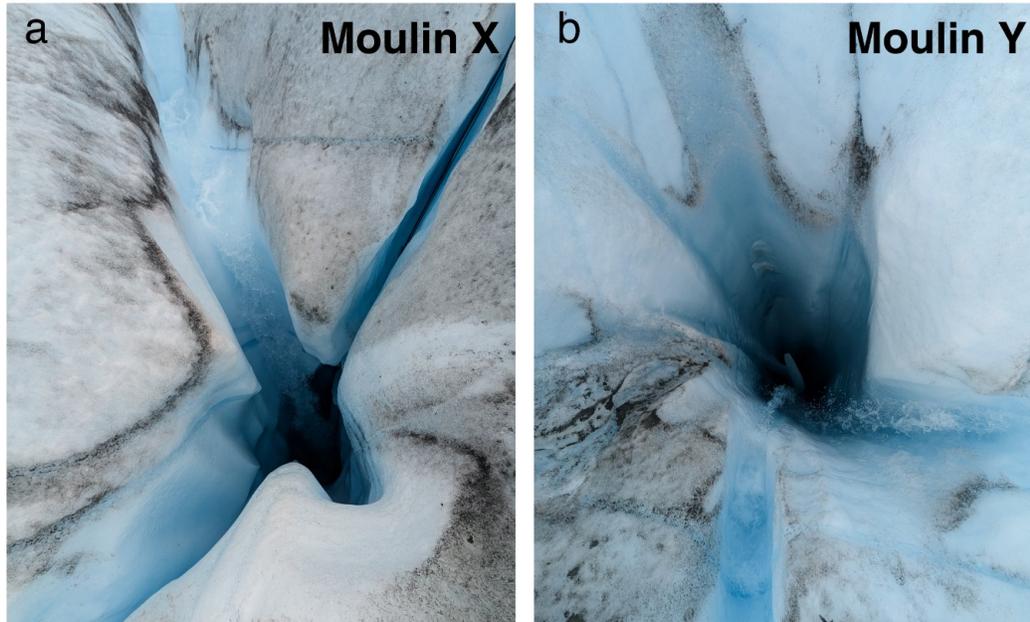

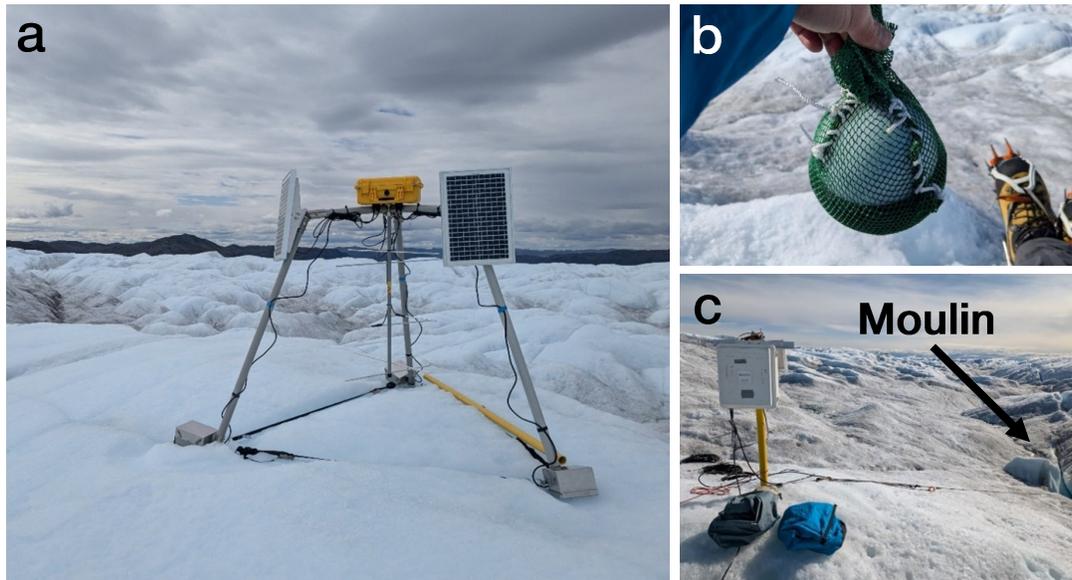Figure S1. a) Moulin X on 26th July 2024. b) Moulin Y on 26th July 2024.

Figure S2. a) Cryoegg receiver station with Iridium uplink. b) Deployed Cryoegg Y1 with foam and mesh floatation device. c) Moulin X site with Campbell logger for Geokon.

Text S1.

1. Calibration of Geokon piezometer

The pressure value measured by the Geokon 4500 vibrating wire piezometer was corrected for variations in atmospheric pressure using the PROMICE automated weather stations (Fausto et al., 2021, How et al, 2022). The time-varying component of atmospheric pressure observed at three nearby automated weather stations (KAN_B - 5.6 km, KAN_T - 5.6 km, KAN_L - 12 km) agrees well with the variations in atmospheric pressure observed at the Cryoegg receiver (R2=0.994 to 0.996, p<0.001). The upper boom atmospheric pressure at 2024-07-09 18:55:300 UTC for each of the PROMICE weather stations is subtracted from the hourly time series and the average time-varying change in atmospheric pressure is calculated. This change in pressure is then subtracted from the pressure recorded by the Geokon 4500 piezometer, which was calibrated to atmospheric pressure at the same timestamp, so that changes in atmospheric pressure are compensated prior to interpretation as hydraulic head in meters.

2. Cryoegg sensor deployment and calibration

Upon deployment, the time taken for Cryoegg Y1 to free-fall from the ice surface to a ledge inside the moulin (causing an audible thud) was measured (Movie S1). The measured fall time was 3.75 s. Using Equation (S1), the depth of Cryoegg Y1 was estimated to be approximately 69 m below the ice surface.

$$h = \frac{1}{2}gt^2 \text{ (Equation S1)}$$

Initial electrical conductivity and water pressure readings confirmed the sensor was positioned above the moulin's current water level. Due to the minimal deviation in hydraulic head between all the sensors in Moulin X and Y after calibration, we are also confident that Cryoegg Y1 did not move from this ice ledge.

Each Cryoegg was individually calibrated, to account for small variations in sensor geometry. The EC sensors were calibrated using NaCl solutions of varying conductivity, and the pressure sensor was zeroed using a unique initial offset between the TE pressure sensor in the surface receiver and the Keller sensor in each egg.

The ice thickness at each moulin was estimated from interpolated ground penetrating radar lines close to our site. For Moulin X the ice thickness was 446 m, and 450 m for Moulin Y. To provide an approximate estimate of orthometric ice surface elevation we use the ArcticDEM mosaic version 4.1 (Porter at al., 2023). From this, the bed elevation below each moulin was estimated to be approximately 50 m. This places Cryoegg Y1 at 381 m above the bed (ice thickness – sensor depth below surface) and at an orthometric height (Z_{sensor}) of 433 m a.s.l.

From the time series of uncalibrated water depth above each sensor, we select a time when diurnal oscillations suggest a well-connected system, with the variations of each

moulin in phase (e.g., 5th August 2024 at 21:00 UTC; Fig. S3) when all sensors are under water. During this time, we assume that the two moulins are well connected and in hydraulic equilibrium, with negligible friction loss between them (Röthlisberger 1972; Shreve 1972). This assumption is further justified by the moulins' close proximity (~100 m apart) and their similar estimated ice thicknesses.
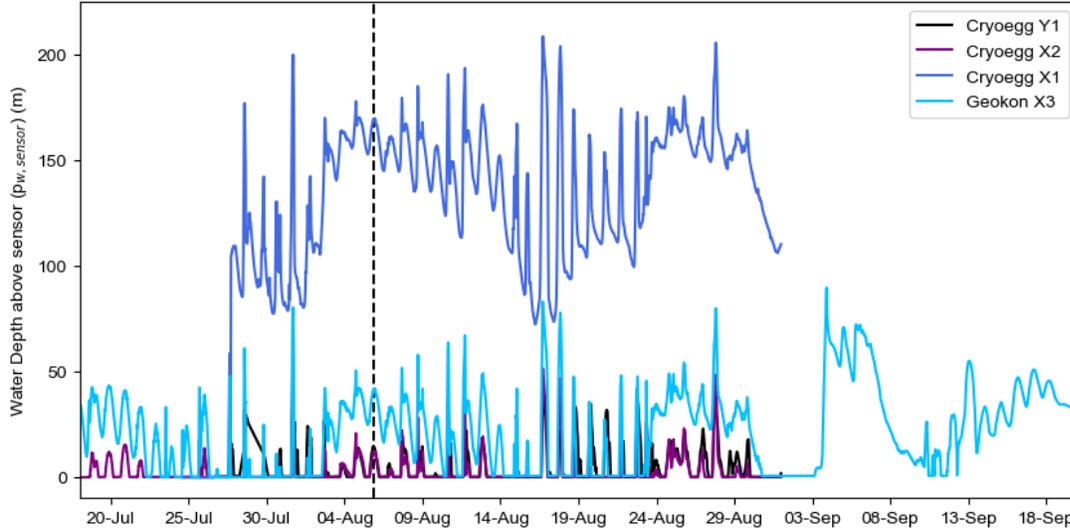

Figure S3. Time series of the water depth above each sensor in Moulin X and Moulin Y. Dashed black line shows the chosen calibration date of 5th August 2024 at 21:00 UTC.

Calibration to orthometric hydraulic head

For the 5th August 2024 at 21:00 UTC Cryoegg Y1 measured a water depth above the sensor ($p_{w,sensor}$) of 14 m. This equates to a water depth in the moulin ($p_{w,moulin}$) of 395 m and an orthometric height above sea level (Z_w) of 447 m a.s.l. (Equation S2).

$$Z_w = p_{w,sensor} + Z_{sensor} \text{ (Equation S2)}$$

Assuming hydraulic equilibrium between the two moulins, the orthometric height of the other sensors can be calculated using Equation S3.

$$Z_{sensor} = (p_{w,moulin} - p_{w,sensor}) + Z_b \text{ (Equation S3)}$$

Where Z_b is the orthometric bed elevation. This gives an orthometric height of the other sensors at 279 m a.s.l for Cryoegg X1, 437 m a.s.l. for Cryoegg X2 and 407 m a.s.l. for Geokon X3.

Calibration to percentage of ice overburden

To calculate water pressure in each moulin as a percentage of ice-overburden pressure we use Equation S4 and Equation S5.

$$p_i = \rho_i g H cos(\beta) \text{ (Equation S4)}$$

3

$$p_w = \rho_w g p_{w,moulin} \text{ (Equation S5)}$$

Where ρ_i is 910 kg m^{-3}, ρ_i is 999.8 kg m^{-3}, β is the bed slope and H is the ice thickness at each moulin.

Table S1: Discharge measurements for the supraglacial stream feeding Moulin X in July 2024 determined using salt tracing. Conductivity curves from the salt trace were recorded by a submerged Keller logger to calculate flow rates.

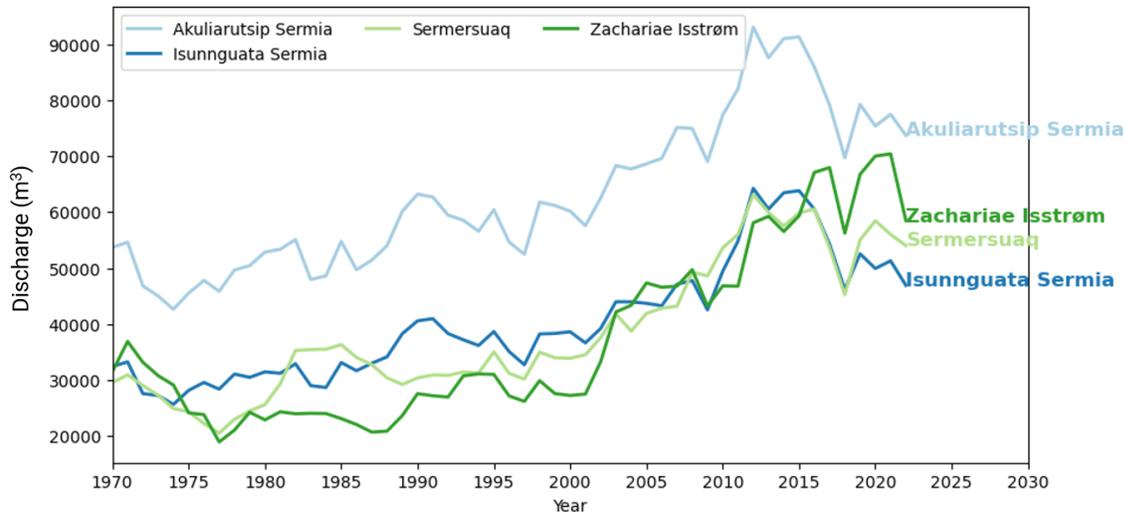| Date (UTC)	Stream Discharge (m^{3}s^{-1})
15/07/2024 17:00	0.050
18/07/2024 14:00	0.034
18/07/2024 15:00	0.057

Figure S4: The total annual runoff (6-year rolling mean) of the top four largest outlets. Data is from Mankoff et al., (2022), with the runoff derived from RACMO.
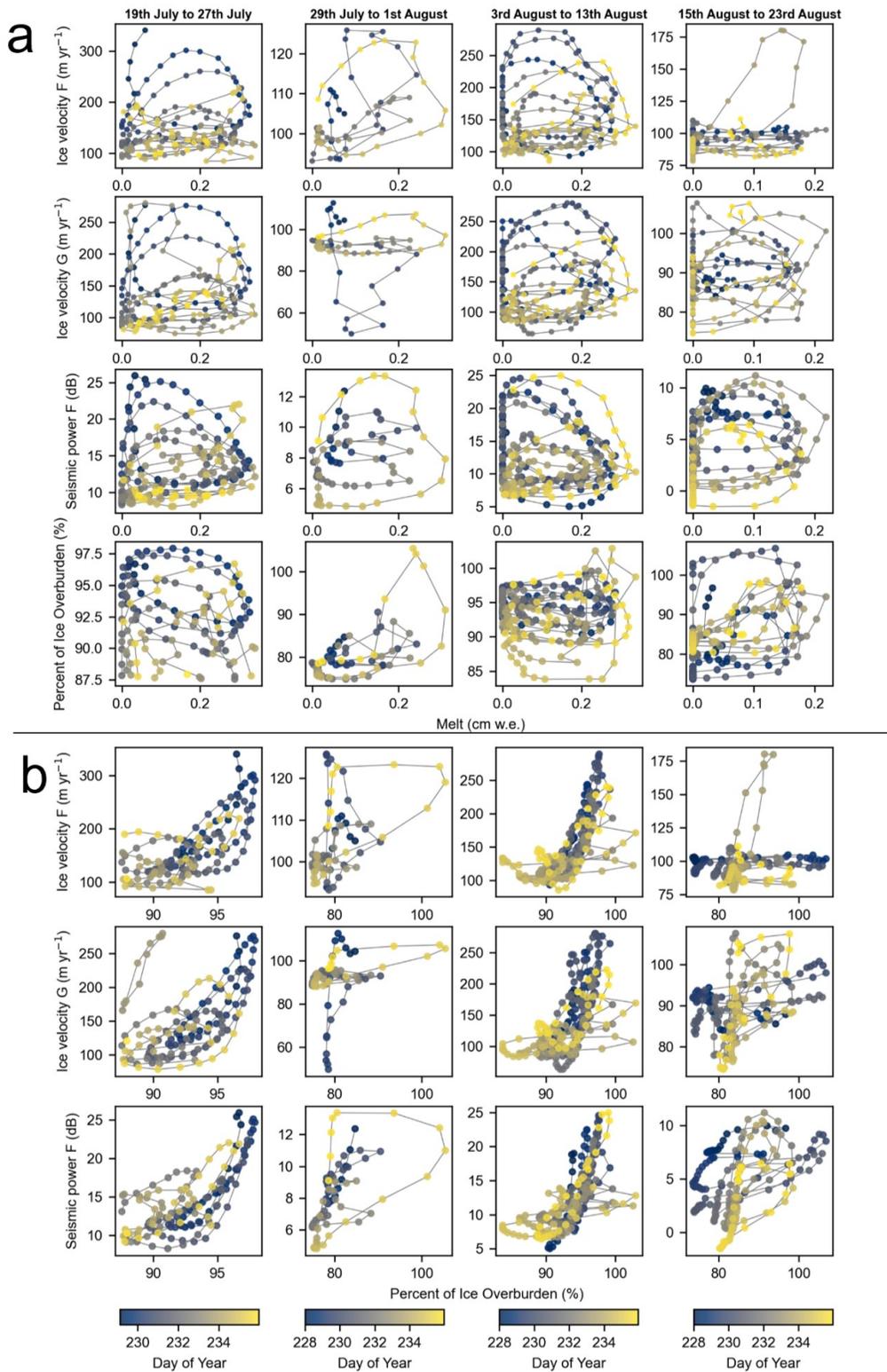
Figure S5: a) Hysteresis plots between hourly surface melt and all other variables (ice velocity at F and G, seismic tremor and median moulin hydraulic head of all sensors). b) Hysteresis plots between median moulin hydraulic head and ice velocity at F and G, and seismic tremor. Colours denote the day of year in 2024.

Movie S1. Video showing the deployment of Cryoegg Y1 down Moulin Y on the 18th July 2024.