

Atomistic simulations of Mg vacancy segregation to dislocation cores in forsterite

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10

11 **Abstract**

12 Interactions between dislocations in olivine and extrinsic cation vacancies created under hydrous or
13 oxidizing conditions may influence the rheology of the Earth's upper mantle. In this study, we use atomic-
14 scale simulations to calculate segregation energies for bare and protonated Mg vacancies to M1 and M2
15 sites in the core regions of [100](010) and [001](010) edge dislocations, and [100] and [001] screw
16 dislocations. Calculated segregation energies are different for the two symmetry distinct M sites. The
17 segregation energies calculated for the tightest binding M1 sites around [100] screw and [100](010) edge

18 dislocations are comparable to those calculated for the tightest binding M2 sites. Concentrations of M2
19 vacancy-related defects will thus be low in the core regions of these dislocations, given the comparatively
20 high energy of these defects in the bulk lattice. In contrast, segregation energies for M2 defects to
21 [001](010) edge dislocation cores are considerably lower than for equivalent M1 defects, and M2
22 vacancy concentrations around these dislocations will be similar to M1 vacancy concentrations. This
23 means that the effect of magnesium vacancies on the mobility of the [001](010) edge dislocation may be
24 significantly different to the effect on the mobility of the other dislocations considered.

25 **Keywords:** Forsterite, dislocation, point-defect segregation, atomistic simulation, cation vacancies

26 **1. Introduction**

27 Although nominally anhydrous, under the pressure and temperature conditions of the Earth's mantle,
28 olivine can incorporate modest quantities of water into its crystal structure, primarily as protonated cation
29 vacancies (e.g. Martin and Donnay, 1972; Bai and Kohlstedt, 1993; Kohlstedt et al., 1996). The water
30 solubility limit in olivine is sensitive to the water and oxygen fugacities, and also increases with silica
31 activity, consistent with incorporation via protonation of M site vacancies (Gaetani et al., 2014).
32 Protonated vacancies interact with dislocations in the olivine crystal lattice, and may preferentially
33 occupy atomic sites near such defects over sites in the bulk lattice, with the effect that vacancy-related
34 defect concentrations are potentially much greater in the core region of a dislocation than in the
35 unstrained bulk lattice. In extreme cases, impurity segregation can affect the bulk chemistry of minerals,
36 as for example in the formation of striped chemical zoning in olivine during low strain-rate deformation,
37 attributed to Fe^{2+} segregation to sub-grain boundaries formed by aligned arrays of edge dislocations
38 (Ando et al., 2001). High-resolution synchrotron images show that the concentration of protonated
39 defects in olivine is greatest around grain boundaries and cracks, demonstrating that these defects in

40 olivine will tend to segregate to locally strained regions of the crystal lattice (Sommer et al., 2008), while
41 hydrogen concentrations near [001] dislocations in water-saturated olivine can be sufficiently great to
42 induce climb dissociation of the dislocation core (Drury, 1991).

43 Interactions between point defects and dislocations can alter the mobility of the dislocation. Most
44 commonly, dislocations experience solute drag when immobile impurities segregate to dislocation cores,
45 pinning the dislocation in place and reducing strain rates accordingly (Cottrell and Bilby, 1949).
46 However, some defects can increase dislocation mobility in the glide creep regime by reducing the Peierls
47 barrier to glide, including vacancies in fcc Al (Lauzier et al., 1989; Lu and Kaxiras, 2002), hydrogen in
48 Fe (Taketomi et al., 2008), or interstitial O defects in UO₂ (Ashbee and Yust, 1982; Keller et al., 1988).
49 In olivine, interactions between water-related defects, occurring primarily as protonated vacancies may
50 facilitate deformation by increasing dislocation mobility in the dislocation climb-controlled creep regime
51 (e.g. Mackwell et al., 1985; Chen et al., 1998; Girard et al., 2013). Hydrous defects are thought to reduce
52 the Peierls stress, σ_p , required for dislocation glide, whose measured value for hydrated olivine is ~1.6-
53 2.9 GPa (Katayama and Karato, 2008), considerably lower than values measured for dry olivine
54 polycrystals, which range from at least 3.8 GPa (Idrissi et al., 2016) to as much as ~15 GPa (Demouchy
55 et al., 2013). Recent forced-oscillation measurements have suggested that Mg vacancies, produced to
56 charge balance the oxidation of Fe²⁺ to Fe³⁺ (Stocker and Smyth, 1978; Nakamura and Schmalzried,
57 1983) may enhance attenuation in Fo₉₀ olivine (Cline et al., 2018).. Natural dunites deforming in the
58 dislocation creep regime also show a moderate sensitivity to the oxygen fugacity (Keefner et al., 2011).
59 This suggests that bare cation vacancies may have a similar influence on the mechanical properties of
60 olivine as protonated cation vacancies.

61 The short length scales characteristic of impurity segregation to dislocation cores mean that it can be
62 difficult to study experimentally, although developments in the field of atom probe tomography mean
63 that it is now possible to visualize impurity clouds around dislocation lines (Miller et al., 2006; Peterman
64 et al., 2016). Theoretical modeling offers an alternative approach, allowing direct access to the atomic
65 scale and control over system chemistry. While interactions between dislocations and point defects far
66 from the dislocation line can be adequately modeled using linear elasticity theory, in the dislocation core
67 non-elastic, atomic-scale relaxation can be substantial. One way to model a dislocation is to insert two
68 or more dislocations into a 3D-periodic simulation cell, with their Burgers vectors \mathbf{b} summing to zero to
69 ensure continuity at the boundaries. Although this cell can be sufficiently small as to make the use of *ab*
70 *initio* methods practical, care must be taken to minimize dislocation-dislocation interactions. An
71 alternative is to embed a single dislocation in an isolated cluster of atoms with periodic boundary
72 conditions along the dislocation line (Walker et al., 2005a). Both the cluster-based (Walker et al., 2005b)
73 and supercell (Mahendran et al., 2017) approaches have been used to simulate [100] and [001] screw
74 dislocations in forsterite, producing comparable dislocation core structures, although the latter study did
75 not report core energies for either dislocation.

76 While atomistic modeling is a powerful tool for studying dislocations and their interactions with point
77 defects, there are several limitations that restrict its range of applicability. Firstly, obtaining a converged
78 dislocation core structure and energy may require the use of very large simulation cell, containing many
79 hundreds or thousands of atoms, for which the computational cost of using quantum chemical methods
80 such as DFT can be prohibitive. Instead, as in this study, interatomic potentials are more commonly used,
81 which are parameterized by fitting to experimental data or *ab initio* calculations. The second problem is
82 that the dislocation itself breaks the translational symmetry of the crystal, meaning that interactions
83 between point defects cannot be parametrized using any of the techniques available for solid solutions,

84 such as cluster expansion (Sanchez et al., 1984) or Special Quasirandom Structures (Zunger et al., 1990),
85 and the dislocation energy must be obtained from fully atomistic calculations. In practice, this limits
86 calculations to the dilute limit.

87 In this study, we use the cluster-based approach to determine segregation energies for bare and protonated
88 cation vacancies to dislocation cores in the forsterite (Mg_2SiO_4) end-member of the olivine solid solution.
89 Since the silica activity in mantle peridotites is high, Mg vacancies are expected to be more abundant
90 than Si vacancies. Consequently, we consider only Mg vacancies on the two symmetry distinct M sites,
91 labeled M1 and M2. At low pressure, the easiest slip system in olivine is $[100](010)$, but the $[001](010)$
92 slip system becomes more active at high pressure (Couvy et al., 2004; Hilairet et al., 2012). Here, we
93 use popular and well-tested empirical interatomic potential to calculate low energy core structures for
94 the $[100](010)$ and $[001](010)$ edge and $[100]$ and $[001]$ screw dislocation. Segregation energies are
95 calculated for bare and protonated M1 and M2 vacancies, written $\{V_{M1}\}''$, $\{2H_{M1}\}^X$, $\{V_{M2}\}''$ and
96 $\{2H_{M2}\}^X$ in the Kröger-Vink notation (Kröger and Vink, 1956), to sites within the core regions of these
97 dislocations. Energies for the different defects are compared to elucidate the effect of site occupation and
98 hydrogen fugacity on the interaction between Mg vacancies to dislocations. In the bulk, M1 vacancies
99 are energetically more favorable than M2 vacancies in the bulk lattice (Brodholt, 1997), but this may be
100 different near dislocation cores, which may have implications for olivine rheology in dislocation-
101 controlled creep regimes, as well as for Mg diffusion in crystals with high dislocation density.

102 **2. Computational methods**

103 Dislocation core structures and segregation energies were calculated using the cluster-based approach,
104 in which an isolated dislocation is inserted at the axis of a 1D-periodic cylinder of atoms (Sinclair, 1971;
105 Walker et al., 2005ab). The starting coordinates for the atoms are determined from the elastic

106 displacement field $\mathbf{u}(\mathbf{r})$ calculated using the sextic formulation for a dislocation in an anisotropic medium
 107 (Stroh, 1958). For edge dislocations, this is a non-conservative algorithm and atoms must be removed
 108 from the simulation cell to obtain a physically reasonable initial dislocation structure. To do this, a branch
 109 cut is created that is normal to both the Burgers and dislocation line vectors. Any atoms that are displaced
 110 across this branch cut by the displacement field $\mathbf{u}(\mathbf{r})$ are deleted. Atoms in close proximity to the branch
 111 cut are merged with any nearby atoms, if the distance between them falls below a specified threshold
 112 d_{\min} . The cluster of atoms is subsequently divided into two concentric regions, with radii R_I and R_{II} .
 113 During the geometry optimization step, atoms in the inner region (region I) are permitted to relax freely,
 114 while those in the outer region (region II) are held fixed at the coordinates predicted using the elastic
 115 displacement field.

116 The total excess energy per unit length, E_{dis} , contained within radius r of an isolated dislocation is

$$117 \quad E_{\text{dis}}(r) = E_{\text{core}} + \frac{Kb^2}{4\pi} \log(r/r_c), \quad (1)$$

118 where K is the elastic energy coefficient and depends on the dislocation geometry and elastic constants
 119 C_{ij} , E_{core} is the energy contained within the core region (termed the core energy), and r_c is the radius of
 120 the dislocation core, within which the displacement field diverges from the predictions of linear elasticity.
 121 The core radius r_c is an undetermined parameter, whose value cannot be determined from the radial excess
 122 energy of the dislocation. Its value must be chosen in order to set a gauge for the core energy. In this
 123 study, we use a core radius of $2b$, where b is the absolute magnitude of the Burgers vector.

124 The core energy is determined from atomistic cluster-based simulations by fitting equation (1) to the
 125 calculated radial dependence of the excess energy, which is the difference between the energy of a cluster
 126 containing the dislocation and a reference system containing an identical number of atoms. E_{core} is also

127 the excess energy of the dislocation at $r = r_c$. The excess energy is calculated from the energies of the
128 individual atoms as

$$129 \quad E_{excess}(r) = E_{dis}(r) - \sum_{species} n_{species}(r) E_{species}, \quad (2)$$

130 where $E_{dis}(r)$ is the total energy of the atoms within r of the dislocation line, the sum runs over the
131 different atomic species present, $n_{species}(r)$ gives the number of atoms of each species within r , and $E_{species}$
132 is the energy of the species in the bulk lattice. This is equal to

$$133 \quad E_{species} = 1/2 (E_{supercell} + E_{isolated} - E_{vac}), \quad (3)$$

134 where E_{vac} is the energy of a supercell from which one atom of the specified type has been removed,
135 without relaxing the coordinates of the remaining atoms, $E_{supercell}$ is the energy of the supercell without a
136 vacancy, and $E_{isolated}$ is the energy of an isolated atom of the specified type. In single-component crystals,
137 this is identical to the energy of the unit cell divided by the number of atoms it contains.

138 The core energy and core displacement field of a dislocation in a two-region cluster depends on the radius
139 of the relaxed region. A region I radius $R_I = 25 \text{ \AA}$ was sufficient to guarantee convergence of the
140 calculated core energies of the [100](010) edge and [100] and [001] screw dislocations to $<10 \text{ meV/\AA}$,
141 while a larger region I with radius $R_I = 35 \text{ \AA}$ was needed to achieve similar precision for the [001](010)
142 edge dislocation. The coulomb energy was calculated using the Wolf summation (Wolf et al., 1999),
143 which uses a charge neutralizing term to guarantee convergence of the energy at a finite distance. A
144 cutoff range of $r_{cut} = 15 \text{ \AA}$ and damping parameter $\xi = 0.2 \text{ \AA}^{-1}$ were used, giving lattice parameters and
145 elastic constants that differ from the values calculated using the Ewald method by $<1\%$. As electrostatic
146 interaction between ions is truncated at r_{cut} , the region II radius R_{II} of $R_I + r_{cut}$ is used for all cluster
147 calculations.

148 Due to the large size of the simulation cell, all calculations are performed using empirical interatomic
 149 potentials in the program GULP (Gale, 1997; Gale and Rohl, 2003). The interatomic potentials used are
 150 from the THB1 model, which was parameterized by fitting to experimental data (Sanders et al., 1984;
 151 Lewis and Catlow, 1985), and reproduces the physical properties of forsterite with reasonable accuracy
 152 (Price et al., 1987). Following Wright and Catlow (1994), we model protonated vacancies using the
 153 parameters developed by Schröder et al. (1992) to treat (OH)⁻ groups in zeolite, incorporating the
 154 subsequent modifications made to the Morse potential by Gatzemeier and Wright (2006). This potential,
 155 labeled THB1, has been widely used to model point and extended defects in forsterite, including Mg
 156 point defects (Walker et al., 2009), surface structures and energetics (de Leeuw et al., 2000), and screw
 157 dislocation core structures and energies (Walker et al., 2005b).

158 In cluster calculations, the segregation energy E_{seg} of a single point defect at an atomic site in a dislocation
 159 core is determined by calculating the excess energy ΔE_{dis} of a point defect of the specified type embedded
 160 it in a simulation cell whose length is a multiple of the unit cell edge parallel to the dislocation line vector,
 161 ξ , and comparing it with the excess energy ΔE_{perf} of an isolated defect in the bulk lattice, taken here to
 162 be the excess energy ΔE_{perf} of a point defect embedded in a 3D-periodic supercell of the material. This is
 163 equivalent to

$$164 \quad E_{seg} = (E_{dfct+dis} - E_{dis}) - (E_{dfct+supercell} - E_{supercell}), \quad (4)$$

165 where E_{dis} is the energy of a cluster containing a dislocation, $E_{dfct+dis}$ is the energy of that same cluster
 166 with a single point defect inserted, $E_{supercell}$ is the energy of a defect-free 3D-periodic supercell, and
 167 $E_{dfct+supercell}$ is the energy of a supercell containing a point defect. Negative segregation energies indicate
 168 that the point defect will tend to bind to the dislocation to lower the total energy of the system, while
 169 positive segregation energies indicate the reverse.

170 $\{V_{M1}\}''$ and $\{V_{M2}\}''$ defects are inserted into a simulation by removing atoms of the specified type. As
171 these defects are charged, a charge-neutralizing background was applied to the simulation cell, to
172 maintain over charge neutrality. In addition to calculating segregation energies for bare Mg vacancies,
173 segregation energies were also calculated for protonated Mg site vacancies. Constructing a $\{2H_{Mg}\}^X$
174 defect involves not only deletion of the Mg ion occupying the specified M site, and its replacement with
175 two H ions, but also the replacement of two of the O ions around the site with oxygen ions using the
176 hydroxyl potential. There are three symmetrically distinct O sites in olivine labeled O1, O2, and O3,
177 leading a large number of possible configurations of the $\{2H_{M1}\}^X$ and $\{2H_{M2}\}^X$ defects. For both
178 protonated defects, we use the configuration predicted by Walker et al. (2006) to have the lowest energy.
179 In a protonated M1 vacancy, the hydrogen atoms are bonded to oxygen in the O2 site, while the hydrogen
180 atoms in a protonated M2 vacancy are bonded to oxygen atoms on the O2 and O3 sites.

181 The segregation energies for the tightest binding site of the $\{V_{M1}\}''$, $\{V_{M2}\}''$, $\{2H_{M1}\}^X$, and $\{2H_{M2}\}^X$
182 defects for all four dislocations were converged to <0.05 eV by using supercells with length $n = 3$. The
183 distance between a point defect and its closest periodic image is thus 17.960 Å for dislocations with line
184 vector [001] and 14.346 Å for those with line vector [100]. Excess energies of isolated empty and
185 protonated M-site vacancies were calculated using a simulation cell with dimensions $4ax2bx4c$, where
186 a , b , and c are the forsterite cell parameters, sufficiently large to guarantee convergence to within the
187 tolerance specified for point defects in 1D-periodic clusters.

188 **3. Dislocation core properties**

189 The energy of a given dislocation depends on its coordinates within the crystallographic plane normal to
190 ξ . For each of the dislocations considered in this study, there are several possible symmetrically distinct
191 origins (labeled in Fig. 1). In the case of edge dislocations, which also break any rotational symmetry of

192 the crystal about the line vector ξ , the number of symmetrically distinct origins for a dislocation can be
193 even higher. Core energies for the most stable configuration found for each dislocation obtained by fitting
194 the computed radial variation of the excess energy (Fig. 3) to equation (1) are reported in Table 1. Also
195 shown are their associated elastic energy coefficients K , which are determined from the elastic constant
196 C_{ij} using the Stroh sextic theory (Stroh, 1958). The lowest energy core structures found are displayed in
197 Fig. 2.

198 [100] screw dislocations have higher core energies, E_{core} , than [001] screw dislocations. The calculated
199 core energies for the [100](010) and [001](010) edge dislocation slip systems are comparable. However,
200 the core radius r_c depends on the length of the Burgers vector, which is shorter for the [100](010) edge
201 dislocation, and E_{core} therefore corresponds to the energy of a smaller region. As can be seen in Table 1,
202 the [001] screw dislocation has the lowest core energy (1.50 eV/Å) and elastic energy coefficient (57.4
203 GPa) among the dislocations considered in this study. Consistent with these results, atomistic calculations
204 of generalized stacking fault energies have shown that both the relative volume change of SiO₄ tetrahedra
205 and the displacement of atoms away from the fault surface, which serve as measures of nonelastic strain,
206 are greater for [100](010) slip than [001](010) slip (Durinck et al., 2005). It follows that [100](010)
207 dislocations should be expected to have higher core energies than [001](010) dislocations.

208 Equilibrium core structures for the [100](010) and [001](010) edge dislocations are shown in Fig. 2ab.
209 As can be seen in Fig. 2a, the [100](010) edge dislocation has an asymmetric core structure, a
210 consequence of the absence of mirror planes parallel to [100]. The algorithm for creating an edge
211 dislocation creates something similar to a vacant M2 site near the [100](010) dislocation line. Inserting
212 an Mg atom at this site increases the core energy by 0.2 eV/Å. As a consequence, the [100](010) edge
213 dislocation has an empty channel parallel to ξ , causing the oxygen ions closest to the dislocation line to

214 be under-coordinated. In contrast to the [100](010) edge dislocation, the stable core structure of the
215 [001](010) edge dislocation is symmetric, due to the existence of mirror planes parallel to (001) located
216 at $z = 0.25$ and $z = 0.75$, passing through the row of Si atoms parallel to [010]. Both edge dislocations
217 lie on the median planes of the M_2O_6 polyhedra ($y = 0.25/0.75$). This is consistent with quantum
218 mechanical calculations of generalized stacking fault energies, which find that ideal shear stresses for
219 [100](010) and [001](010) slip are lowest when slip is localized at $y = 0.25$ (Durinck et al., 2005). The
220 Peierls stresses for dislocations gliding on (010) are similarly lowest when glide is on the plane at $y =$
221 0.25 (Durinck et al., 2007).

222 For the [100] screw dislocation, we find that the origin of the most stable core structure is $(0.5, 0.25)$,
223 halfway between adjacent M2 sites (labeled site C in Fig. 1a), which has a calculated core energy of E_{core}
224 $= 1.78 \text{ eV}/\text{\AA}$. This core structure was also reported by Mahendran et al. (2017), who used the alternative
225 supercell approach. Earlier work using the cluster-based approach, by contrast, found that the dislocation
226 centered on the M1 site has a lower energy (Walker et al., 2005b), for which we compute a relatively
227 high core energy of $1.97 \text{ eV}/\text{\AA}$. The discrepancy is likely due to the fact that Walker et al. (2005b)
228 searched for the minimum energy core structure using single point energy calculations at each possible
229 core position, whereas the core structures were relaxed in this study. Local atomic-scale structure thus
230 has a determining effect on the relative stability of the different core configurations for the [100] screw
231 dislocation in forsterite.

232 Whereas other dislocations gliding on (010) are located on the median plane of the sheet of M_2O_6
233 octahedra, the most stable core structure of the [001] screw dislocation is centered on the column of
234 M_1O_6 polyhedra running parallel to [001] (labeled site D in Fig. 1b), consistent with previous theoretical
235 calculations (Walker et al., 2005b; Mahendran et al., 2017). As found in previous studies (Carrez et al.,
236 2008), the [001] screw dislocation has a non-planar core. This is can be seen clearly in the sub-periodic

237 modulation of the displacement \mathbf{u} of M1 sites located in the lattice plane a distance $1/2b$ above and below
238 the glide plane. These atoms are displaced normal to the (010) glide plane, with the sense of this
239 displacement alternating along [001] (see Fig. 2d). The SiO_4 tetrahedra in this plane undergo significant
240 rotation, with the sign of this rotation alternating in the fashion as the sign of the displacement of
241 neighboring M1 sites. This modulation causes the two-fold rotation center at $z = 0.5$, where z is the
242 coordinate along the dislocation line, to disappear. In what follows, the region in which $0.0 \leq z < 0.5$ is
243 referred to as the "lower" region, and the region with z satisfying $0.5 \leq z < 1.0$ as the "upper" region. In
244 this labeling scheme, the lower region corresponds to those M1 sites that relax away from the (010) glide
245 plane, and the upper region to the sites that relax toward it.

246 **4. Segregation of Mg vacancies to dislocations**

247 *4.1 Excess energies of defects in the bulk lattice*

248 Segregation energies are calculated from equation (4), which requires the excess energy of a point defect
249 in the bulk lattice. This excess energy is defined as the difference between the energies of forsterite
250 supercells of the same size, with and without a point defect. The excess energy of an $\{\text{V}_{\text{M1}}\}$ defect,
251 corrected for the interactions between charged defects, is 24.0 eV, while a $\{\text{V}_{\text{M2}}\}$ defect has a modestly
252 higher excess energy of 25.9 eV, reflecting the lower energy of a magnesium ion in M2 site. Similarly,
253 the excess energy of a $\{2\text{H}_{\text{M2}}\}^{\text{X}}$ defect in the bulk lattice is 41.8 eV, significantly greater than the 39.4
254 eV excess energy calculated for the $\{2\text{H}_{\text{M1}}\}^{\text{X}}$ defect.

255 Creating an M1 vacancy, whether protonated or bare, is thus more energetically favorable than creating
256 an M2 vacancy. $\Delta H_{\text{M1} \rightarrow \text{M2}}$, the enthalpy required to exchange an Mg vacancy between the M1 and M2
257 sub-lattices is 1.9 eV, identical to previous values of $\Delta H_{\text{M1} \rightarrow \text{M2}}$ calculated using empirical potentials

258 (Jaoul et al., 1995; Walker et al., 2009), but higher than the 0.81 eV energy difference predicted by DFT
259 calculations (Brodholt, 1997). The energy difference $\Delta H_{M1 \rightarrow M2}$ between the $\{2H_{M1}\}^X$ and $\{2H_{M2}\}^X$
260 defects, at 2.4 eV, is even greater than that for bare vacancies. As the relative concentrations of vacancies
261 on the two sites depends exponentially on $\Delta H_{M1 \rightarrow M2}$, M1 vacancies, whether bare or protonated, will be
262 considerably more abundant than similar M2 vacancy-related defects in the bulk lattice.

263 4.2 Segregation of M1 vacancies

264 The segregation energy for the $\{V_{M1}\}''$ defect around a [100](010) edge dislocation is lowest for the three
265 sites located directly below the dislocation line (Fig. 4a). The $\{V_{M1}\}''$ defect binds particularly tightly to
266 the site directly below the glide plane, which has a segregation energy of -3.00 eV. Segregation energies
267 for the $\{2H_{M1}\}^X$ defect are similarly lowest for the three sites immediately below the glide plane, although
268 their segregation energies are more similar in value. $E_{seg} = -2.30$ eV for the site directly below the glide
269 plane. For both defects, segregation energies decrease rapidly with distance from the dislocation line.

270 Segregation energies for M1 defects around [001](010) edge dislocations are shown in Fig. 5. $\{V_{M1}\}''$
271 defects bind to the sites immediately above the glide plane of [001](010) edge dislocations, with
272 segregation energy -1.74 eV. As was found for $\{V_{M1}\}''$ around the [100](010) edge dislocation,
273 segregation energies increase markedly away from the most stable binding site; the next lowest energy
274 is -1.05 eV, corresponding to the M1 sites on either side of the tightest binding sites. As was found for
275 [100](010) dislocations, $\{2H_{M1}\}^X$ defects segregating to [001](010) edge dislocations preferentially bind
276 to sites directly below the glide plane and close to the dislocation line, albeit with considerably higher
277 segregation energies than found for [100](010) edge dislocations. For the tightest binding site, which is
278 located directly below the glide plane and on either side of the dislocation line, $E_{seg} = -1.08$ eV, and
279 segregation energies are only marginally higher for M1 sites above the glide plane.

280 The calculated minimum segregation energies for M1 vacancies binding to screw dislocation cores are
 281 higher than those for the edge dislocations, consistent with the lower stresses induced by a screw
 282 dislocation. For the [100] screw dislocation, the low energy sites are distributed radially around the
 283 dislocation core (Fig. 6), with the tightest binding sites being those closest to the (010) glide plane. The
 284 tightest binding sites for the $\{V_{M1}\}''$ defect, at $\mathbf{r} \approx \pm[(1/2)\mathbf{c}+(1/4)\mathbf{b}]$ (\mathbf{b} in this context referring to the unit
 285 cell length rather than the Burgers vector), have $E_{seg} = -0.87$ eV, while $E_{seg} = -0.81$ eV for the next most
 286 tightly bound sites, which are located at $\mathbf{r} \approx \pm[(1/2)\mathbf{c}-(1/4)\mathbf{b}]$. However, the sites closest to the dislocation
 287 line have comparatively high segregation energies (-0.20 eV). Comparing Fig. 6a and Fig. 6b, it can be
 288 readily seen that $\{2H_{M1}\}^X$ defects show greater site selectivity than $\{V_{M1}\}''$ defects, as the segregation
 289 energies for the sites at $\mathbf{r} \approx \pm[(1/2)\mathbf{c}-(1/4)\mathbf{b}]$, -0.99 eV, are considerably lower than those computed for
 290 any other site, while those at $\mathbf{r} \approx \pm[(1/2)\mathbf{c}+(1/4)\mathbf{b}]$ have considerably higher energies
 291 (-0.35 eV), comparable to the -0.40 eV of the M1 sites closest to the dislocation line. Segregation energies
 292 for $\{2H_{M1}\}^X$ defects decrease more rapidly with distance from dislocation line than do segregation
 293 energies calculated for bare M1 vacancies.

294 Segregation energies for defects around the [001] screw dislocation (Fig. 7) depend not only on their
 295 location in the plane normal to the line vector ξ , but also on their position along the ξ , due to the
 296 modulation of the crystal structure along the dislocation line. For the bare M1 vacancy the lowest
 297 segregation energy site is -0.77 eV within the lower region, compared with -0.61 eV in the upper region.
 298 Segregation energies for the $\{2H_{M1}\}^X$ defect are more sensitive to location along the dislocation line. E_{seg}
 299 = -0.89 eV for the tightest binding site in the lower region, while the lowest segregation energy found
 300 for any site in the upper region is only -0.62 eV. For both bare and protonated defects, E_{seg} is generally
 301 lower for sites in the lower region, and E_{seg} can be positive for sites in the upper region, particularly the
 302 site through which the dislocation line passes. Defect concentrations will be lower in this region than in

303 the bulk lattice. Segregation energies for M1 vacancy-related defects in the upper and lower regions of
304 the [001] screw dislocation are anti-correlated, which may inhibit pipe diffusion along this dislocation as
305 vacancy migration entails successive jumps between high and low segregation energy sites.

306 *4.3 Segregation of M2 vacancies*

307 The lowest segregation energy site for $\{V_{M2}\}''$ around the [100](010) edge dislocation is not at the glide
308 plane, but at $x = 0$ on the first sheet of $M2O_6$ octahedra below the dislocation (Fig. 4). The segregation
309 energy of the most stable binding site (-3.93 eV) is considerably lower than that calculated at any other
310 location in the dislocation core, matching the behavior found for $\{V_{M1}\}''$ defects segregating to this
311 dislocation. The energies of the next tightest binding sites, those immediately adjacent to the dislocation
312 on the glide plane, are considerably higher, with $E_{seg} = -1.4$ eV. As was found for the M1 defects
313 segregating to this dislocation, the segregation energy surface of the $\{2H_{M2}\}^X$ defect is profoundly
314 different to that of the $\{V_{M2}\}''$ defect. Unlike $\{V_{M2}\}''$, $\{2H_{M2}\}^X$ binds to sites near the glide plane, with
315 the lowest energies found for the four sites closest to the dislocation line. The two sites closest to the
316 dislocation line, which are above the glide plane, have $E_{seg} = -1.53$ eV, while $E_{seg} =$
317 -1.82 eV for the two sites below the glide plane. Above the glide plane, segregation energies rapidly
318 decay to zero.

319 The tightest binding sites for $\{V_{M2}\}''$ defects segregating to [001](010) edge dislocations are in the sheet
320 of $M2O_6$ octahedra above the glide plane (Fig. 5). For these sites, the segregation energy is -3.64 eV.
321 The M2 site closest to the dislocation line has the next lowest energy, with $E_{seg} = -3.40$ eV. The
322 segregation energy for $\{2H_{M2}\}^X$ defects is lowest for the site at $x = 0$ is the sheet of $M2O_6$ octahedra
323 below the glide plane, for which $E_{seg} = -3.07$ eV. Unlike $\{V_{M2}\}''$ defects, segregation of $\{2H_{M2}\}^X$ defects

324 to the M2 site closest to the dislocation line is comparatively unfavorable, with $E_{\text{seg}} = -0.70$ eV for this
325 site.

326 The low energy sites for $\{V_{M2}\}''$ and $\{2H_{M2}\}^X$ defects around the [100] screw dislocation are distributed
327 radially around the dislocation line (Fig. 6). However, for both defects the tightest binding sites are
328 located near the (010) glide plane. The energy for segregation of $\{V_{M2}\}''$ defects to the sites closest to
329 the dislocation line is -1.74 eV. The lowest segregation energies correspond to the next closest sites to
330 the dislocation line, for which $E_{\text{seg}} = -1.91$ eV. For protonated M2 vacancies, the sites immediately
331 adjacent to the dislocation line have the lowest energy, with $E_{\text{seg}} = -2.46$ eV. Segregation energies for
332 protonated vacancies increase more markedly with distance from the dislocation line than for bare M2
333 vacancies, and E_{seg} is only -1.39 eV for the next tightest binding site.

334 As was found for defects on the M1 sub-lattice around [001] screw dislocations, M2 segregation energies
335 vary along the dislocation line (Fig. 7). The sites for which the segregation energy of $\{V_{M2}\}''$ is a
336 minimum are found in the lower region. For these sites, $E_{\text{seg}} = -1.89$ eV, whereas the lowest segregation
337 energy for any site in the upper region is -1.06 eV. At upper mantle temperatures, the concentration of
338 $\{V_{M2}\}''$ defects will therefore be orders magnitude greater in the lower region than the upper region, due
339 to the exponential variation of relative concentrations on ΔH . For $\{2H_{M2}\}^X$ defects, the six sites closest
340 to the dislocation line have nearly identical segregation energies (approximately -1.73 eV).
341 In contrast to $\{V_{M2}\}''$ defects, the minimum energies in each region are comparable, and $\{2H_{M2}\}^X$ bind
342 as strongly to sites in the upper region as they do to sites in the lower region.

343 **5. Discussion**

344 *5.1 Comparing segregation energies for M1 and M2 defects*

345 For all dislocations considered in this study, $\{V_{M2}\}''$ defects bind more tightly to core sites than $\{V_{M1}\}''$
346 defects. The difference between the minimum segregation energies for the two defects around a
347 $[100](010)$ edge dislocation is 0.93 eV. Comparable values of 1.04 and 1.18 eV are found for the $[100]$
348 and $[001]$ screw dislocations, respectively. Except in the case of $[100](010)$ edge dislocations, for which
349 the minimum segregation energy for the $\{2H_{M2}\}^X$ defect is 0.48 eV higher than that for the $\{2H_{M1}\}^X$
350 defect, $\{2H_{M2}\}^X$ defects bind more strongly to dislocation cores, relative to the equivalent defect in the
351 unstrained lattice, than $\{2H_{M1}\}^X$ defects. M2 vacancy-related defects will be more strongly concentrated
352 near dislocation cores, relative to the bulk, than M1 defects. However, the lower absolute energies of M1
353 vacancies mean that these defects will remain more abundant near dislocation cores than M2 vacancies.
354 The ratio of defect concentrations on the two sites, $[\{V_{M1}\}'']/[\{V_{M2}\}'']$ will nevertheless still be lower
355 near a dislocation than in the bulk lattice, as will the ratio $[\{2H_{M1}\}^X]/[\{2H_{M2}\}^X]$, except around
356 $[100](010)$ edge dislocations.

357 However, while this means that the concentration of M2 vacancies, relative to M1 vacancies, is greater
358 in the vicinity of a dislocation core than in the bulk, this does not necessarily imply that they are lower
359 energy. Indeed, only in the case of $[001](010)$ edge dislocations are the differences between the lowest
360 segregation energies of the $\{V_{M1}\}''$ and $\{V_{M2}\}''$ defects comparable to $\Delta H_{M1 \rightarrow M2}$ for the bulk lattice. The
361 energy difference for protonated M1 and M2 vacancies is lower than the bulk $\Delta H_{M1 \rightarrow M2}$ for all four
362 dislocations, so that creation of a protonated M1 vacancy near the dislocation core is still more favorable
363 than creation of a protonated M2 vacancy. Assuming that vacancy-related defects can lubricate glide of
364 dislocations in olivine, it is probable that the effect will vary with the distance of the vacant site from the
365 glide plane. In forsterite, this implies that M2 vacancies will have a greater lubrication effect for
366 dislocations gliding on (010) than M1 vacancies, as glide occurs primarily on the (010)-parallel sheet of
367 M_2O_6 octahedra. However, as shown here, with the exception of the $[001](010)$ edge dislocation, M2

368 vacancies are much less abundant than M1 vacancies near dislocation cores, which could limit the
369 magnitude of the glide lubrication effect.

370 The [001](010) edge dislocation represents a partial exception, as $\{V_{M2}\}$ defects bind particularly
371 strongly to the core sites of this dislocations. The segregation energy (relative to an equivalent defect in
372 the bulk) of the tightest binding site for $\{V_{M2}\}$ defects in the core region of this dislocation is 1.9 eV
373 lower than that of the tightest binding M1 site, comparable to the value of $\Delta H_{M1 \rightarrow M2}$ in the bulk lattice
374 environment. This means that absolute energies for the $\{V_{M1}\}$ and $\{V_{M2}\}$ defects segregating to tightest
375 binding sites in [001](010) edge dislocation cores are identical, and their concentrations close the
376 dislocation line will be similar. The low energy of the tightest binding M2 vacancy for this defect is
377 readily explained by the fact that the dislocation runs through an M2 site, so that the region of highest
378 strain coincides with an M2 site. The difference between the minimum segregation energies for $\{2H_{M2}\}^x$
379 and $\{2H_{M1}\}^x$ defects around a [001](010) edge dislocation core is 2.0 eV. This is 0.4 eV lower than the
380 energy difference between the two defects in the absence of strain field. Consequently, although hydrated
381 M1 vacancies will be more abundant than M2 vacancies in the dislocation core, the relative abundance
382 of the latter will be far greater near the core of [001](010) edge dislocations than in the bulk lattice.

383 *5.2 Segregation energies of bare versus protonated defects*

384 Among dislocations in forsterite gliding on (010), segregation energies are lower for edge than screw
385 dislocations and, in general, lower for dislocations with Burgers vector $\mathbf{b} = [100]$ than those with $\mathbf{b} =$
386 [001]. Considering only the sites with the lowest segregation energies, bare and protonated M1 and M2
387 vacancies should be more abundant near [100](010) than [001](010) edge dislocations, and with
388 generally higher concentrations for [100] screw dislocations than [001] screw dislocations. The spatial
389 distribution of segregation energies for protonated and bare M site vacancies for a specific dislocation

390 are similar. However, as noted in the previous section, the fine details of the segregation energy surfaces
391 can vary considerably and non-trivially between $\{V_{M1}\}''$ and $\{2H_{M1}\}^X$, and $\{V_{M2}\}''$ and $\{2H_{M2}\}^X$. In this
392 section, we will attempt to quantify the degree to which protonation changes segregation energies.

393 The degree to which the segregation energies for two defects around a particular dislocation are similar
394 to one another can be quantified by computing a similarity measure for the segregation energy surfaces
395 around the dislocation core. One such measure is the cosine similarity measure, which is computed for
396 two vectors x_1 and x_2 as

$$397 \quad s_{12}(x_1, x_2) = x_1 \cdot x_2 / (\|x_1\| \|x_2\|), \quad (5)$$

398 The similarity $s_{12} = -1$ when the vectors are anti-correlated, while $s_{12} = 1$ for perfectly correlated vectors.

399 The cosine similarity measure is widely used in data mining to compare data sets, with applications
400 ranging from facial verification (e.g. Nguyen and Bai, 2010), to comparing linguistic data sets (e.g. Liao
401 and Xu, 2015), and automated text classification (e.g. Song et al., 2009). Here, we represent a segregation
402 energy surface for a single point defect around a dislocation as a vector of length equal to the number of
403 sites, whose entries correspond to the segregation energies of each site. Thus bare and protonated
404 vacancies around the same dislocation can be compared provided that segregation energies have been
405 computed for the same list of sites, as is the case in this study. However, the similarity measure cannot
406 be straightforwardly compared between slip systems, as the list of sites will be different. Computed
407 values of s_{12} for the M1 and M2 sites within 15 Å of the dislocation line are given in Table 3.

408 The similarity s_{12} of the M2 sub-lattice is strictly positive for all dislocations, meaning that the
409 segregation energies of $\{V_{M2}\}''$ and $\{2H_{M2}\}^X$ defects to dislocations in forsterite are invariably positively
410 correlated. For all four dislocations considered in this study, the cosine similarity measure is positive,
411 indicating a broad correlation between segregation energies of bare and protonated vacancies on the same

412 sub-lattice. Bare and protonated Mg vacancies around [100](010) edge dislocations have relatively
413 similar energies for both sub-lattices and, and $s_{12}(\text{M1})$ is only $\sim 3\%$ greater than the corresponding value
414 for the M2 sub-lattice. Around [001](010) edge dislocations, s_{12} differs considerably for defects on the
415 two sub-lattices around [001](010) edge dislocations, with $s_{12}(\text{M1})/s_{12}(\text{M2}) = 1.20$. In contrast, the
416 similarity measures computed using the calculated segregation energy surfaces for screw dislocations are
417 considerably greater on the M2 sub-lattice, with $s_{12}(\text{M2})/s_{12}(\text{M1}) = 1.14$ for [100] screw dislocations and
418 1.19 for [001] screw dislocation.

419 The [001] screw dislocation has a modulated core structure, and defects on M1 sites that are adjacent
420 along [001] have different segregation energies, as can be seen in Fig. 7. Considering the segregation
421 energies for the M1 sites at $y = 0.0$ (Fig. 7ab) and $y = 0.5$ (Fig. 7cd) separately, we find similarities $s_{12} =$
422 0.889 and $s_{12} = 0.44$. Thus, although $\{V_{\text{M1}}\}''$ and $\{2H_{\text{M1}}\}^{\text{X}}$ segregation energies are more strongly
423 correlated for the M1 sites which displace away from the (010) glide plane, they are only weakly
424 correlated for the M1 sites that are displaced towards the glide plane. As can be seen in Fig. 7, the pattern
425 of segregation energies for the M2 vacancies similarly varies between the upper and lower regions of the
426 [001] screw dislocation. However, the similarity measure varies much less between the two regions for
427 M2 vacancies than M1 vacancies, with $s_{12} = 0.87$ for sites in the lower region, and $s_{12} = 0.94$ in the upper
428 region.

429 *5.3 Defect segregation and olivine deformation*

430 Vacancy-lubrication of dislocation glide has been reported in a range of different materials. Generalized
431 stacking fault energy (GSFE) parametrized Peierls-Nabarro calculations have suggested that interstitial
432 H may facilitate dislocation glide in Al meta (Lu et al. 2001), while the presence of interstitial O in hyper-
433 stoichiometric UO_2 (i.e. UO_{2+x} , $x > 0$) is known to reduce the critical resolved shear stress (Keller et al.

434 1988), an effect attributed to interactions between the interstitial impurities and the dislocation core
435 (Ashbee and Yust, 1982). One possible explanation is that interactions between the dislocation core and
436 an adsorbed vacancy defect reduce the Peierls stress, although the precise mechanism remains unclear.
437 Deformation experiments in the glide-controlled creep regime show that the critical resolved shear stress
438 decreases from 3.8-15.0 GPa in dry olivine (Idrissi et al., 2016; Demouchy et al., 2013) to 1.6-2.9 GPa
439 for olivine under water-saturated conditions (Katayama and Karato, 2008). This CRSS represents the
440 stress required for deformation at 0 K, and is referred to by Katayama and Karato as the Peierls stress,
441 although it actually represents a weighted average of the Peierls stresses for several active slip systems.

442 The solubility limit of vacancy-related defects in the olivine crystal lattice is relatively high, and can
443 reach nearly 0.9 % for protonated vacancies at 12 GPa pressure (Smyth et al., 2006). However, these
444 concentrations are probably not sufficiently great to create Peierls stress reductions of the magnitude
445 reported by Katayama and Karato (2008). However, the strongly negative segregation energies calculated
446 for both edge and screw dislocations mean that the concentration of vacancy-related defects will be many
447 times greater in the dislocation core than in the bulk crystal lattice. It follows that the influence of
448 vacancy-related defects on the deformation of olivine in dislocation-controlled creep regimes can be
449 significant, even at low bulk concentrations. Moreover, $\{V_{M2}\}''$ and $\{2H_{M2}\}^X$ defects were found to have
450 considerably lower segregation energies than equivalent defects on the M1 sub-lattice, and the relative
451 abundance of M2 defects will be much higher in dislocation cores than in the bulk lattice. This is
452 significant, as M2 vacancies are expected to have the greatest influence on the Peierls stress for
453 dislocations gliding on (010), as these dislocations glide on the median plane of the sheet of M_2O_6
454 octahedra.

455 **6. Conclusions**

456 Vacancy related defects are important for understanding the material properties of olivine. The addition
457 of small quantities of water to Fo₉₀ olivine deforming in the glide creep regime increases strain rates,
458 indicating a reduction of the Peierls stress. This has been plausibly attributed to lubrication of dislocation
459 glide by protonated cation vacancies interacting with the dislocation, a process similar to the vacancy
460 lubrication phenomenon invoked to explain flow stress variations for a range of materials. Concentrations
461 of protonated vacancies or similar vacancy-related defects present at the dislocation core need to be high
462 for the lubrication effect to be substantial. However, H concentration in mantle olivine is typically low,
463 with <1000 ppm H/Si, although water contents may reach higher values in the deep upper mantle. Ferric
464 iron, an important source of bare vacancies in silicate minerals, has a similarly low abundance, except in
465 the most oxidized regions of the mantle (Kelley and Cottrell, 2009). Consequently, vacancy lubrication
466 is possible only if vacancy related defects bind strongly to sites around dislocation cores.

467 In this study, we have used cluster-based computational simulations to compute segregation energies for
468 both bare and protonated Mg vacancies around dislocations in forsterite. These segregation energies can
469 be < -1.0 eV, suggesting that vacancy-related defect concentrations near the dislocation core may be
470 orders of magnitude higher than in the bulk lattice, especially at low to moderate temperature. These are
471 precisely the temperature conditions at which dislocation glide is most important for the deformation of
472 olivine. However, not all vacancies are equal and, while the energy of an $\{V_{M2}\}''$ or $\{2H_{M2}\}^X$ defect is
473 considerably lower near an edge or screw dislocation line than an equivalent defect in the bulk lattice,
474 Mg vacancies still preferentially occupy M1 sites near dislocations, as they do in the bulk lattice. Thus,
475 even though concentrations of vacancy related defects at the dislocation core may be high, they may
476 occupy sites whose ability to directly influence dislocation glide is limited. The easy glide plane for
477 dislocations gliding on (010) is the median plane of the sheet of M₂O₆ octahedra, and M2 vacancies
478 located this glide plane may play a critical role in lubricating dislocation glide. Such strategically located

479 vacancies are expected to be most abundant around [001](010) edge dislocations, and any increase in the
480 glide mobility is likely to be most significant for the [001](010) slip system.

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489

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625

626 **Tables**

627 **Table 1** Calculated core energies and elastic energy coefficients and core energies for the most stable
 628 configurations of dislocations in forsterite

	E_{core} (eV/Å)	K (GPa)
[100](010) edge dislocation	2.42±0.04	135.0
[001](010) edge dislocation	2.46±0.07	92.3
[100] screw dislocation	1.78±0.02	79.1
[001] screw dislocation	1.50±0.03	57.4

629

630 **Table 2** Minimum segregation energies (in eV) for defects around dislocations in forsterite. In each of these cases,
 631 the minimum energy site is close to the dislocation core, where atomic-scale effects dominate over elastic terms
 632 such the size-effect and inhomogeneity interactions

	[100](010) edge dislocation	[100] screw dislocation	[001](010) edge dislocation	[001] screw dislocation
$\{V_{M1}\}''$	-3.00	-0.87	-1.74	-0.76
$\{2H_{M1}\}^X$	-2.30	-1.00	-1.08	-0.89
$\{V_{M2}\}''$	-3.93	-1.91	-3.64	-1.89
$\{2H_{M2}\}^X$	-1.82	-2.46	-3.07	-1.73

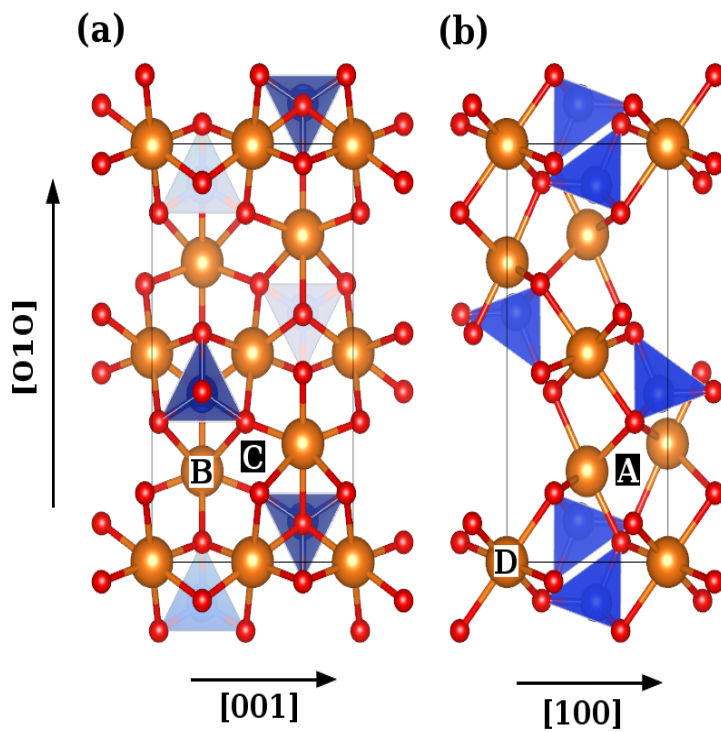
633

634 **Table 3** Values of the cosine similarity measure for bare and protonated M sites around the various dislocations
 635 in forsterite

	[100](010) edge dislocation	[100] screw dislocation	[001](010) edge dislocation	[001] screw dislocation
M1	0.89	0.78	0.81	0.73
M2	0.86	0.89	0.68	0.87

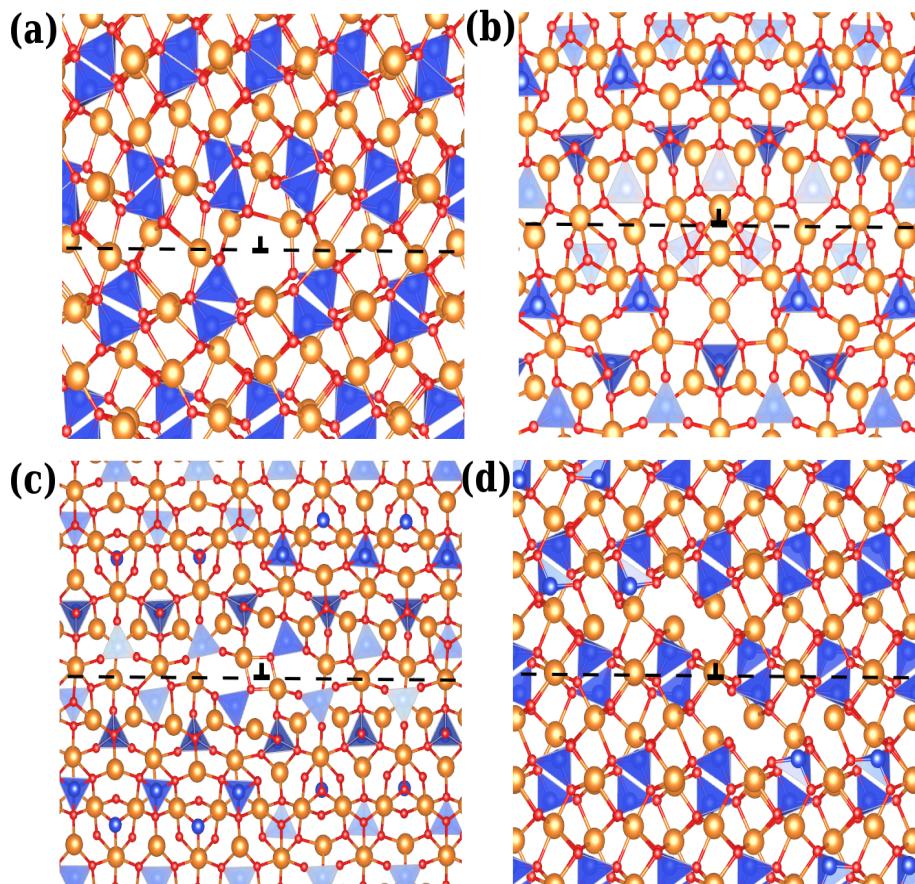
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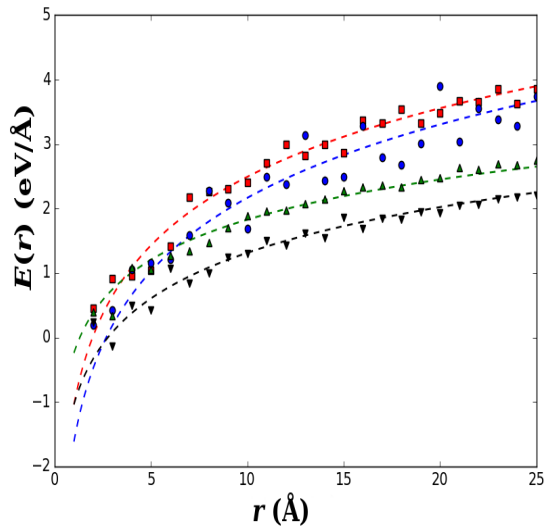
639

640 **Fig. 1** Olivine unit cell viewed down (a) the [100] cell direction, and (b) the [001] cell direction. Locations A, B,
 641 C, and D are, respectively, the points in the unit cell through which the most stable core structures for the
 642 [100](010) edge, [001](010) edge, [100] screw, and [001] screw dislocations pass. Visualization produced using
 643 VESTA 3 (Momma and Izumi 2011).



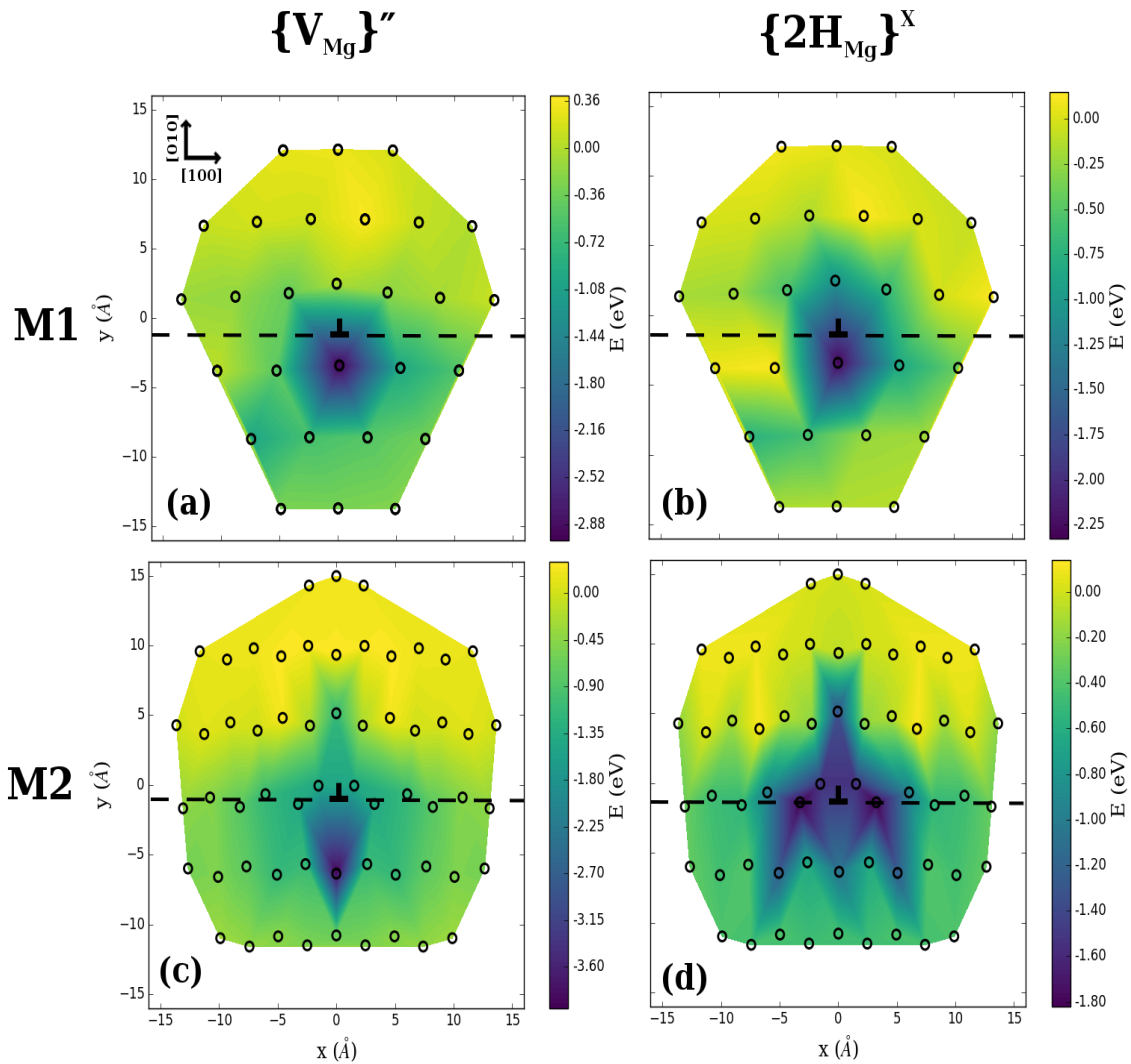
644

645 **Fig. 2** Atomic structures for the most stable core polymorphs of the (a) $[100](010)$ and (b) $[001](010)$ edge
 646 dislocations, and (c) $[100]$ and (d) $[001]$ screw dislocations in forsterite. The dislocation line and (010) glide plane
 647 have been marked. Visualization produced using VESTA 3 (Momma and Izumi 2011).



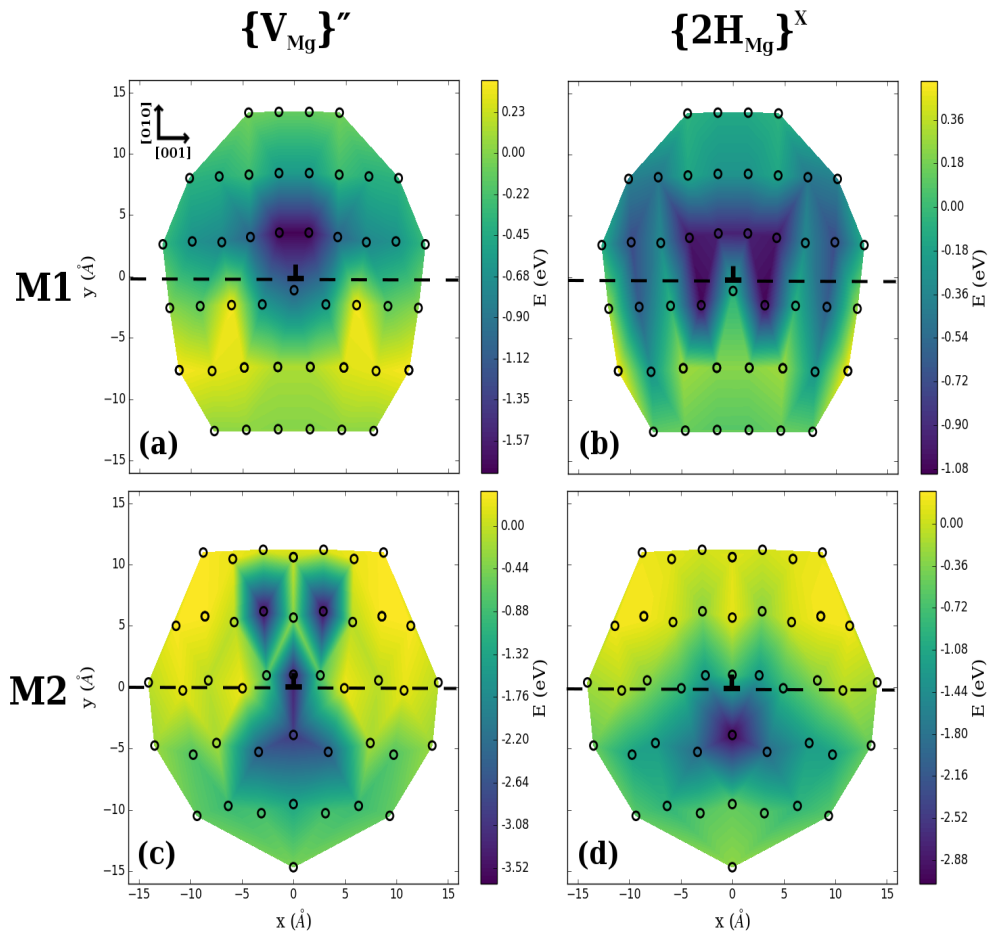
648

649 **Fig. 3** Dislocation line energies as a function of distance r from the dislocation line, together with the energy curve
 650 fitted using equation (1). $[100](010)$ edge, $[001](010)$ edge, $[100]$ screw, and $[001]$ screw dislocations energies
 651 are shown using squares, circles, triangles, and inverted triangles, respectively.



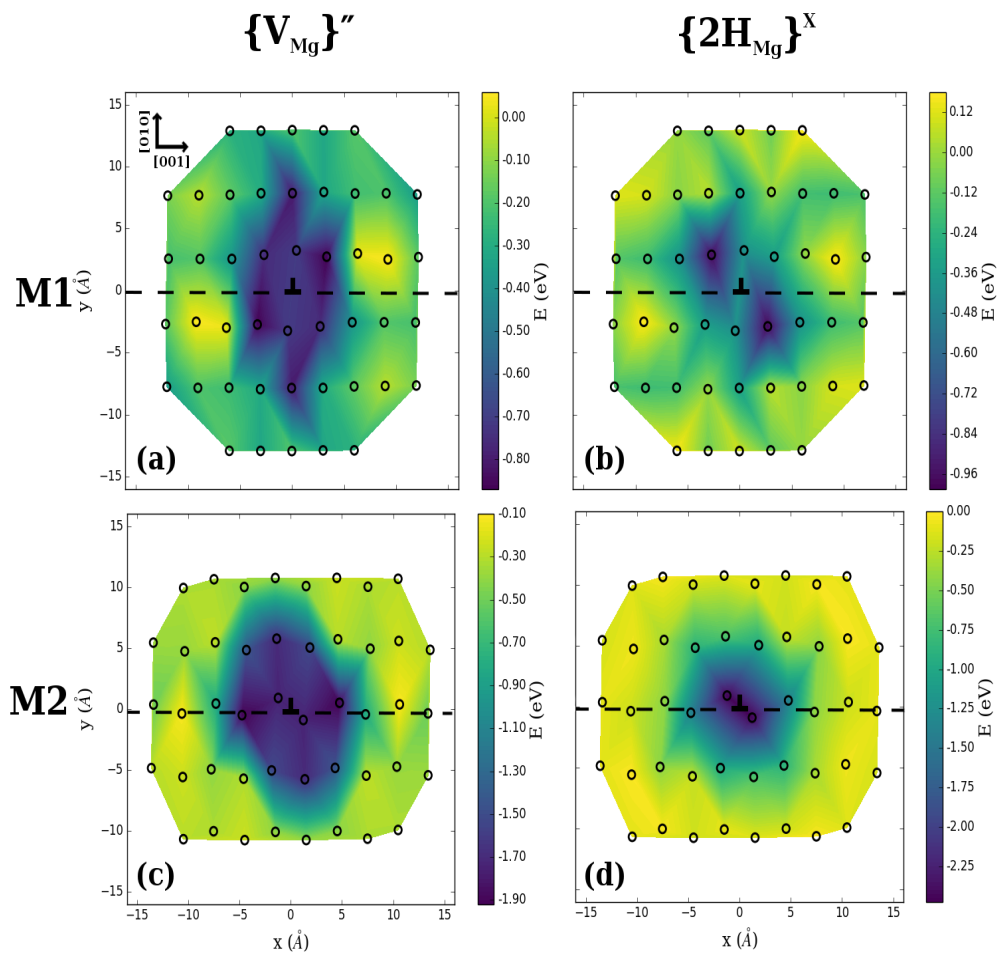
652

653 **Fig. 4** Segregation energies of bare and protonated Mg vacancies to the forsterite [100](010) edge dislocation. The
 654 [001] lattice vector is normal to the image plane. Note that segregation energies for M2 defects are computed
 655 relative to the corresponding defect in the bulk lattice, and are generally higher in energy than M1 defects. Both
 656 the dislocation line and (010) glide plane are displayed.



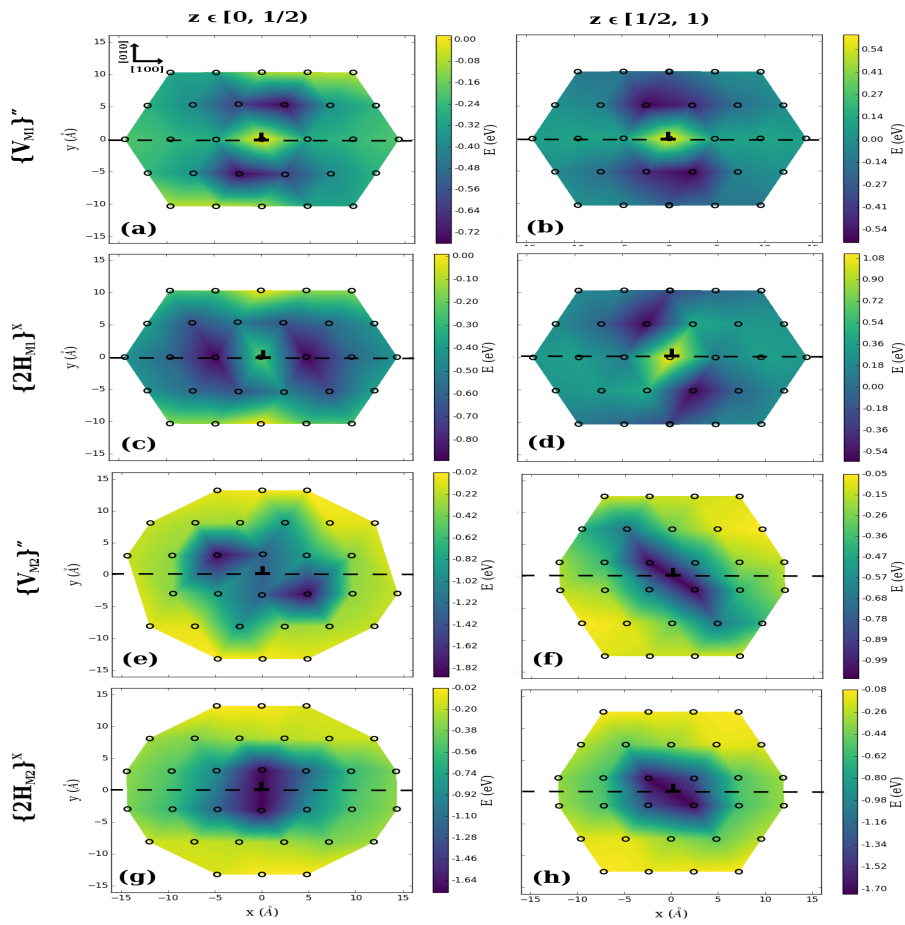
657

658 **Fig. 5** Segregation energies of bare and protonated Mg vacancies to the forsterite [001](010) edge dislocation. The
 659 [100] lattice vector is normal to the image plane.



660

661 **Fig. 6** Segregation energies of bare and protonated Mg vacancies to the forsterite [100] screw dislocation. The
 662 [100] lattice vector is normal to the image plane.



663

664 **Fig. 7** Segregation energies of Mg vacancies to atomic sites around [001] screw dislocations. To reflect the
 665 modulated crystal structure of this dislocation along x , segregation energies for the "lower" ($z \in [0, 0.5)$) and
 666 "upper" ($z \in [0.5, 1.0)$) regions are plotted separately.