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1 **A nationwide regional flood frequency analysis at ungauged sites** 2 **using ROI/GLS with copulas and super regions**

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7 **Abstract**

8 Region of influence is a common approach to estimate runoff information at ungauged locations. To
9 estimate flood quantiles from annual maximum discharges, the Generalized Least Squares (GLS)
10 framework has been recommended to account for unequal sampling variance and intersite correlation,
11 which requires a proper evaluation of the sampling covariance structure. Since some jurisdictions do not
12 have clear guidelines to perform this evaluation, a general procedure using copulas and a nonparametric
13 intersite correlation model is investigated to estimate sampling covariance structure in situations where no
14 common at-site distribution is imposed or when some paired sites do not have common periods of record.
15 The investigated methodology is applied on 771 sites in Canada. The Normal copula is verified to be an
16 adequate model that better fit paired observations than other types of extreme copulas. A sensitivity analysis
17 is carried out to evaluate the impact of either ignoring, or considering a simpler form of, intersite correlation.
18 Additionally, super regions are defined based on drainage area and mean annual precipitation to improve
19 the calibration of pooling groups across large territories and a wide range of climate conditions.
20 Performance criteria based on cross-validation revealed that using super regions and a combination of
21 geographic distance and similarity between catchment descriptors improves the calibration of the pooling
22 groups by providing more accurate estimates.

23 **keywords: Canada, Floods, Regional frequency analysis, Generalized least squares, Region of**
24 **influence, Ungauged.**

25 **1. Introduction**

26 To estimate flood quantiles at a site of interest where little or no streamflow information is available,
27 hydrologists and practitioners have relied on statistical models to predict runoff properties according to
28 available catchment descriptors. Countries such as the United States (IACWD, 1982), the United Kingdom
29 (Robson and Reed, 1999) and Australia (Ball et al. 2016) have adopted clear guidelines to standardize how
30 such analysis should be conducted. However, nationwide recommendations are not available in all
31 countries, including Canada. Recently, the project FloodNet (2015) was created as an initiative to
32 coordinate the efforts of experts in various fields, for improving the understanding of floods in Canada. In
33 this line, the present study investigates the problem of performing Regional Frequency Analysis (RFA) to
34 obtain flood quantiles at ungauged sites.

35 For Quebec and Ontario a previous study compared several combinations of delineation and prediction
36 methods (GREHYS, 1996a, 1996b). One general conclusion was that approaches based on the notion of
37 regions of influence (ROI), where each site is the center of its own pooling group, leads to better results
38 than the delineation of fixed regions. This finding is corroborated by other studies reported in Canada (Burn,
39 1990; Ribeiro-Corréa et al., 1995; Zrinji and Burn, 1994) and outside Canada (Eng et al., 2007; Merz and
40 Blöschl, 2005; Ouarda et al., 2008). Another conclusion was that the index-flood model (Dalrymple, 1960)
41 performed similarly to the direct estimation of the flood quantiles by regression (Thomas and Benson,
42 1975). Similar comparisons were repeated in a separate context with similar results (Durocher et al., 2016a;
43 Haddad and Rahman, 2012). Overall, the decision between these two approaches appears to be mostly
44 conceptual. One may argue that the index-flood model provides a more coherent framework by determining
45 the complete regional distribution, while the direct regression approach is more flexible and allows one to

46 easily mix sites with different types of distributions. The present study focuses on the direct regression
47 approach.

48 Flood frequency analysis is often performed over restricted geographic areas where boundaries are
49 determined by practical considerations. For instance, Canadian studies are generally performed at the
50 provincial level (El-Jabi et al., 2016; Gado and Nguyen, 2016; Sandrock et al., 1992), because water policies
51 fall within these jurisdictions. However, political boundaries are arbitrary from a hydrological perspective
52 and considering a larger database increases the amount of available information. On the other hand, a large
53 country such as Canada can have diverse climatic and flood regimes (Buttle et al., 2016). Therefore, a
54 nationwide analysis will also present additional challenges in the formation of the pooling groups and the
55 calibration of regression models. Many studies have reported a relation between the sample moments and
56 the drainage area or the mean annual precipitation (Basu and Srinivas, 2015; Blöschl and Sivapalan, 1997;
57 Meigh et al., 1997). In a study including sites in Italy, Austria and Slovakia, Salinas et al. (2014a) showed
58 that these two descriptors were proper surrogates for scale control and climate, which contribute to shape
59 the flood generating process. A classification of sites into super regions based on these surrogates could
60 provide a more meaningful solution for characterizing the outcomes of flood frequency analysis at a
61 national level than can be obtained using political regions.

62 An important decision when using ROI is the choice of a similarity measure that is necessary for creating
63 pooling groups centered around a target site. A distance between catchment descriptors is generally
64 preferred over geographical distance as the topography of nearby catchments can change quickly and lead
65 to distinct hydrological properties. Some studies have compared the usefulness of these two notions of
66 distance and showed that better predictions are generally obtained when considering both of them
67 simultaneously. In the United States, Eng et al.(2007) have successfully used a hierarchical approach where
68 the closest sites in terms of distance between descriptors are selected inside a bounded geographical area.
69 In contrast, Merz and Blöschl (2005) have found in an Austrian case study that superior predictive power

70 was found when using a spatial interpolation technique inside regions where a minimum of similarity
71 among the catchments was imposed. One possible explanation for these findings is that the set of available
72 catchment descriptors is not sufficient to fully characterize the flood generating process and hence,
73 geographical location represents a surrogate for missing descriptors that evolves smoothly in space. In
74 particular, for a study covering a large territory, such as Canada, the notion of geographical distance is
75 likely to be related to climate characteristics.

76 When using a regression model to estimate flood quantiles at ungauged sites the response variable is not
77 directly observed, but rather is estimated with different levels of uncertainty. Possible factors that contribute
78 in creating variations in the sampling variance include record lengths and observation scales (Tasker, 1980).
79 Additionally, large atmospheric systems that generate intense rainfall or build vast snowpacks can
80 simultaneously affect many sites. Omitting the impact of intersite correlation in RFA does not create bias
81 but does underestimate the model uncertainty (Bayazit and Önöz, 2004; Hosking and Wallis, 1988) and
82 reduces the power of homogeneity tests (Castellarin et al., 2008). Consequently, ignoring the spatial
83 component of the sampling can have important consequences on the decisions taken on the basis of a
84 selected model (Douglas et al., 2000; Madsen and Rosbjerg, 1997). Generalized Least Squares (GLS)
85 represents a natural approach to estimate parameters of a regression model that accounts for intersite
86 correlation and unequal variances. The model described in Tasker and Stedinger (1989) and considered in
87 several subsequent works (Haddad and Rahman, 2012; Kjeldsen and Jones, 2007; Madsen et al., 2002;
88 Robson and Reed, 1999), separates the total error into sampling and model components. In addition to a
89 better characterization of the source of variability, the approach was also shown to increase predictive
90 accuracies (Reis et al., 2005; Stedinger and Tasker, 1985; Vogel and Kroll, 1990).

91 Although GLS is considered as a good practice based on several studies, it has not been largely employed
92 in Canada. One reason to explain this low utilization may be the extra step required to evaluate the sampling
93 covariance structure. Across Canada, different regions of dominant nival, pluvial and mixed flood regimes

94 can be found (Burn et al., 2016). Therefore, it is reasonable to expect the existence of complex patterns of
95 spatial dependencies. However, Kroll and Stedinger (1998) indicated that using a smoothed version of the
96 intersite correlation structure has a relatively small impact on the predicted variability. Consequently,
97 several studies dealing with intersite correlations have preferred to accept some degree of approximation in
98 the sampling covariance matrix by using either Taylor approximation or by assuming simpler spatial
99 correlation models (Kjeldsen and Jones, 2004; Tasker and Stedinger, 1989). Moreover the evaluation of the
100 sampling may depend on the type of at-site distributions selected (Griffis and Stedinger, 2007), which
101 complicates the evaluation of the sampling covariance when no unique distribution is imposed.

102 The copula framework has gained popularity for describing non-traditional forms of spatial dependence
103 (Bárdossy, 2006; Gräler and Pebesma, 2011). Common assumptions in RFA are to consider the spatial
104 structure of a multivariate Normal distribution, which in terms of copula is equivalent to considering a
105 Normal copula (Durocher et al., 2016b; Renard, 2011). The Normal copula has also been considered in
106 RFA of extreme rainfall, but some studies have considered models based on the generalization of the
107 extreme value theory to spatial extremes, called max-stable processes, to provide more realistic
108 representation of the spatial dependence (Neves and Gomes, 2011; Shang et al., 2011; Westra and Sisson,
109 2011). In the copula framework, max-stable processes correspond to multivariate Husler-Reiss copula,
110 which has non-negligible probabilities that two extreme events occur jointly, which is not the case of the
111 Normal copula (Joe, 2015). Choosing a copula in RFA poses a similar dilemma to adopting, or not, the
112 GEV distribution in at-site frequency analysis as it is motivated by asymptotic arguments that assumes that
113 the maximums are taken over an infinite number of events. However, this assumption is not realistic in cold
114 regions, because the annual maximum discharge is generally the result of one event, the spring snowmelt.
115 The study of Wang et al. (2014) compared the performance of models based on max-stable processes and
116 regional L-moment algorithm (Hosking and Wallis, 1997) for extreme precipitation in Switzerland. When
117 correctly specified, the max-stable model improved the model fitting and the predicting capability, but when

118 misspecified it was shown to lead to non-negligible bias, which underlines the importance of correctly
119 choosing the copula when modeling spatial extremes.

120 The present study investigates the ROI/GLS framework when applied to a nationwide database that covers
121 vast territories and includes a large spectrum of climate conditions. Different models for estimating the
122 sampling covariance matrix are examined in light of the copula framework. Among them a nonparametric
123 model is proposed, which does not assume specific at-site distributions or estimation methods and remains
124 valid when few paired observations do not share common periods of record. In Canada, as far as the authors
125 know, there is no study that validates the choice of a proper copula for intersite correlation between floods.
126 One objective is to find such copula and to measure its impact on the estimation of flood quantiles. The
127 notion of super regions is also introduced in the context of ungauged analysis to help with calibrating and
128 understanding the outcomes of ROI/GLS regression models in terms of scale control and climate.
129 Additionally, the combination of geographical distance and distance between descriptors is explored to find
130 the right balance between them in the formation of pooling groups.

131 The present document is organized as follows. First, section 2 will describe the proposed ROI/GLS
132 methodology and its components. In section 3, the methods are applied on a large dataset of gauged sites
133 across Canada where different calibration of the regression models are examined in terms of quality of the
134 fitting and predictive performance. Finally, further discussions and conclusions are provided in section 4.

135 **2. Methodology**

136 The present methodology has three main components. First, an at-site frequency analysis of the gauged
137 sites is conducted to provide at-site estimates of flood quantiles. Second, an uncertainty analysis of the at-
138 site flood quantiles with return periods 10 and 100 years (denoted Q10 and Q100) is carried out including
139 the choice of a copula, the modeling of the intersite correlation and the estimation of a sampling covariance
140 matrix by Monte-Carlo simulation. Third, relationships between the flood quantiles and catchment

141 descriptors are characterized by the ROI/GLS approach and examined within super regions. The techniques
142 included in these three components are described in more detail below.

143 **2.1 At-site frequency analysis from annual maximums**

144 At-site frequency analysis based on annual maximums has a long tradition in hydrology and remains one
145 of the most common approaches for quantile estimation (Bezak et al., 2014). Theoretical arguments suggest
146 the utilization of Generalized Extreme Values (GEV) distribution, which arises as the limiting distribution
147 of blocks of maximums. However practical considerations often lead to the consideration of other types of
148 distributions. Identification of a best distribution remains an active debate (Salas et al., 2013). Guidelines
149 in the United States are to adopt the log-Pearson III (IACWD, 1982), while in the United Kingdom the
150 Generalized Logistic distribution is recommended (Robson and Reed, 1999). In Europe, Salinas et al.
151 (2014b) showed that even though the GEV often represents a good fit, it cannot accurately describe the
152 complete spectrum of hydrological diversities. Therefore, the present study will prioritize the GEV
153 distribution but will also consider alternative distributions when warranted; alternatives considered are the
154 Gumbel, Gamma, Pearson III, Normal, Generalized Normal and Generalized Logistic.

155 A classical approach for estimating the parameters of a statistical distribution is to maximize the data
156 likelihood (Coles, 2001). In the presence of a small sample size and heavy tails the maximum likelihood
157 estimator (ML) can sometimes have erratic behavior (Smith, 1985). Therefore, an estimator based on the
158 probability weighted moments, or equivalently the L-moments, is preferred (Hosking, 1990). In the present
159 study, the selection of the at-site distribution is established from a procedure that is guided by the Akaike
160 Information Criterion $AIC = 2k - 2l$, where k represents the number of parameters and l the log
161 likelihood (see, for instance, Di Baldassarre et al. (2009)). After identification of the best distribution in
162 terms of AIC, the AIC for the best distribution is compared to the AIC for the GEV distribution. If the
163 difference of AIC is less than one, the two distributions are assumed to fit the data equally well and the
164 GEV is selected. A comparison study of several statistical distributions was performed by Zhang et al.

165 (2018) and showed that the GEV is generally the best choice for Canadian Rivers. Therefore, the latter
166 criterion for judging the equivalence with the GEV is based on practical considerations and aims at selecting
167 alternative distributions only when this choice is not supported by the data. Note that a threshold of one in
168 this context is not very restrictive. In comparison, the addition of an extra parameter (for example passing
169 from Gumbel to GEV) increases the AIC by two and some authors even suggest a difference greater than
170 4 to be a meaningful difference (Burnham and Anderson, 2002).

171 The uncertainty analysis of the flood quantile estimates based on different types of at-site distributions is
172 not straightforward. In some analyses, the type of distribution is imposed, which allows the development
173 of simple approximate formulas (Bayazit and Önöz, 2004; Griffis and Stedinger, 2007; Kjeldsen and Jones,
174 2004). This is, however, not the case of the present study. Instead, Monte-Carlo simulations are considered
175 to approximate the sampling covariance matrix. The at-site frequency analysis is repeated 1000 times using
176 samples generated by parametric bootstraps. The covariance matrix is then computed empirically from
177 these samples. Although the method is computationally intensive, it is relatively simple to implement. The
178 simulations require the specification of a statistical model that accounts for the at-site distributions and the
179 intersite correlation.

180 **2.2 Intersite correlation in the copula framework**

181 A copula $C : [0,1]^d \rightarrow [0,1]$ is a multivariate distribution with uniform marginal distribution that respects
182 some basic properties (Nelsen, 2006). The fundamental advantage of the copula approach is the separation
183 of the dependence structure from marginal distributions. Commonly used multivariate distributions have
184 the following copula representation

$$185 \quad (0) \quad G(x_1, \dots, x_d) = C[F_1(x_1), \dots, F_d(x_d)],$$

186 where the F_i are the marginal distributions (Salvadori et al., 2007). For simulating a vector from G , one
 187 can obtain first a uniform vector from copula C and then transform the output to the desired marginal
 188 distribution using F_i^{-1} . This strategy is used to simulate one year of annual maximums where the marginal
 189 distribution are the at-site distributions and the intersite correlation is described by a multivariate copula.

190 The Normal copula and t-copula characterize respectively the dependence of a multivariate Normal and
 191 Student distribution. As in classical multivariate theory, the Normal copula is the limit case of a t-copula
 192 when the degree of freedom is converging to infinity (Demarta and McNeil, 2005). Formally, the t-copula
 193 is defined by

$$194 \quad (0) \quad C_{\Sigma, \nu}(u_1, \dots, u_d) = t_{\nu, d} \left[t_{\nu, 1}^{-1}(u_1), \dots, t_{\nu, 1}^{-1}(u_d); \Sigma \right],$$

195 where $t_{\nu, d}$ is the distribution function of a standard Student distribution of dimension d having degrees of
 196 freedom ν and correlation matrix Σ . An important difference between the two copulas is a property called
 197 upper tail dependence that is defined between two random variables $X_i \sim F_i$ with $i = 1, 2$ as

$$198 \quad (0) \quad \lambda_{up} = \lim_{q \rightarrow 0^+} P \left[X_2 > F_2^{-1}(q) \mid X_1 > F_1^{-1}(q) \right].$$

199 For a t-copula, this property is controlled by the degrees of freedom where low values imply higher
 200 probabilities that two extreme events occur jointly. At the opposite extreme, for the Normal copula $\lambda_{up} = 0$
 201 , which means that two extreme values never occur together.

202 The validity of the choice of a copula C can be assessed by a goodness-of-fit test. For bivariate copulas,
 203 extensive Monte-Carlo simulations showed that the test based on Cramer Von Mises statistics generally
 204 leads to superior or competitive power in comparison to other alternatives (Berg, 2009; Genest et al., 2009).
 205 However, such tests require many observations to discriminate between similar copulas. The idea of

206 assessing the quality of spatial models by examining paired observations inside a group of similar lag
 207 distances using copula was first suggested by Bárdossy (2006). Although this approach does not provide a
 208 formal test, rejection of the null hypothesis for some lag distance provides evidence of model
 209 misspecification. That strategy was later formalized by Durocher and Quessy (2017), who showed from
 210 simulation studies that reasonable power can be expected in realistic settings.

211 For t-copulas, the coefficients of correlation for Σ can be estimated by a moment-based estimator and once
 212 known, the degrees of freedom are estimated by maximum likelihood (Lindskog et al., 2003). Spearman
 213 rank correlation coefficient, or simply Spearman's rho ρ is defined as the correlation between the ranks of
 214 two variables. For the t-copula, there is a one-to-one relation between the Spearman's rho and one
 215 coefficient θ of Σ :

216 (0)
$$\theta = 2 \sin\left(\frac{\pi}{6} \rho\right).$$

217 In an ideal situation, all pairs of sites will have enough years of common record to ensure a reliable estimate
 218 of ρ and Σ . However, for different practical reasons, paired observations are recorded over different
 219 periods of time and so may prevent or lead to unreliable estimates of ρ . In that case, a spatial correlation
 220 model is necessary to have estimates at every pair of sites (Schabenberger and Gotway, 2004). A common
 221 choice of spatial correlation model is the power exponential model (POW) where the correlation function
 222 s in respect of distance h is

223 (0)
$$s(h) = \begin{cases} (1-\tau) \exp\left[-3\left(\frac{h}{\alpha}\right)^\gamma\right] & h \neq 0 \\ 1 & h = 0 \end{cases}$$

224 where $\alpha > 0$ controls the strength of the correlation, $0 \leq \tau \leq 1$ is a nugget effect and $0 < \gamma \leq 2$ is a
 225 smoothing parameter. This correlation model is attractive for its simplicity, but may not adequately fit all
 226 complex situations. For this reason, a nonparametric model that is more flexible is also considered. Let h_{ij}
 227 be the distance (km) between a pair of sites i and j and define the average drainage area A_{ij} (km²),
 228 longitude x_{ij} and latitude y_{ij} for the pair (i, j) . The nonparametric model characterizing the intersite
 229 correlation is

230 (0)
$$g(\rho_{ij}) = f_h(h_{ij}) + f_A(A_{ij}) + f_{xy}(x_{ij}, y_{ij}) + e_{ij}$$

231 where g is the Fisher z-transformation

232 (0)
$$g(\rho_{ij}) = \frac{1}{2} \log \left(\frac{1 + \rho_{ij}}{1 - \rho_{ij}} \right);$$

233 f_h , f_A and f_{xy} are smooth continuous functions and e_{ij} is an error term. A model of this form falls under the
 234 umbrella of generalized additive model where an in-depth description is provided for instance in Wood
 235 (2006). The Fisher transformation is used to transform the empirical Spearman's rho ρ_{ij} between -1 and 1
 236 to a near normal distribution. The smooth functions f_h , f_A and f_{xy} are thin plate regression splines, which
 237 are well suited for modeling spatial covariates (Wood, 2003). To avoid overfitting the estimation process
 238 is regularized by penalized least squares (Green and Silverman, 1993). The evolution of the Spearman's rho
 239 in respect of the distance is described by f_h , which plays a similar role to the POW model. The other
 240 components, f_A and f_{xy} , characterize other components of the intersite correlation. In particular,
 241 $f_{xy}(x_{ij}, y_{ij})$ adjusts the intersite correlation on the basis of the paired locations.

242 Estimation of Σ is deduced using equation (0) and fitted ρ_{ij} . However, the matrix Σ derived directly from
 243 the nonparametric model will not in general be positive definite, which leads to numerical problems and so
 244 the algorithm of Higham (2002) is used to find the nearest matrix that respects this condition.

245 **2.3 Regression models using GLS**

246 Flood quantiles are modeled by a multiple regression model at the logarithm scale for sites found inside a
 247 pooling group with regression equation

$$248 \quad (0) \quad \mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\omega}$$

249 where $\mathbf{X} \in \mathbb{R}^p$ is a design matrix of relevant catchment descriptors and $\boldsymbol{\omega}$ is an error term. Due to the
 250 uncertainty resulting from at-site estimation, it is assumed that the response variable $\mathbf{y} = (y_1, \dots, y_n)$ has
 251 a sampling error $\boldsymbol{\epsilon} = \epsilon_1, \dots, \epsilon_n$, with covariance matrix $E(\boldsymbol{\epsilon}\boldsymbol{\epsilon}') = \Sigma$ as described above. Stedinger and
 252 Tasker (1985) proposed considering a second term of error $\boldsymbol{\eta}$ of variance $\sigma_\eta^2 > 0$ that is independent and
 253 identically distributed. Overall, the total error $\boldsymbol{\omega} = \boldsymbol{\eta} + \boldsymbol{\epsilon}$ has covariance matrix

$$254 \quad (0) \quad \Lambda(\sigma_\eta^2) = \sigma_\eta^2 \mathbf{I} + \Sigma ,$$

255 which provides a better characterization of the multiple sources of variability. Notice that the total
 256 covariance matrix is dependent on an unknown parameter σ_η^2 that describes the model variance, *i.e.* the
 257 part of the total variance that is not due to sampling.

258 For a known model variance σ_η^2 , the total covariance matrix can be rewritten $\Lambda(\sigma_\eta^2) = \sigma_\eta^2 \mathbf{G}$. Computing
 259 $\mathbf{G} = \mathbf{U}^T \mathbf{U}$ by Cholesky decomposition allows reformulating the GLS problem as an ordinary least squares

260 (OLS) problem with transformed response variable $\mathbf{y}^* = \mathbf{U}^{-T} \mathbf{y}$ and design matrix $\mathbf{X}^* = \mathbf{U}^{-T} \mathbf{X}$. Therefore,
 261 the GLS estimator and its covariance matrix are derived directly from classical OLS theory:

262 (0)
$$\hat{\boldsymbol{\beta}} = [\mathbf{X}' \mathbf{G}^{-1} \mathbf{X}]^{-1} \mathbf{X} \mathbf{G}^{-1} \mathbf{y}$$

263 (0)
$$\Sigma_{\hat{\boldsymbol{\beta}}} = \sigma_{\eta}^2 [\mathbf{X}' \mathbf{G}^{-1} \mathbf{X}]^{-1} .$$

264 Moreover, the residuals can be linked to the GLS residuals

265 (0)
$$\tilde{\boldsymbol{\omega}} = \mathbf{y}^* - \mathbf{X}^* \hat{\boldsymbol{\beta}} = \mathbf{U}^{-T} \boldsymbol{\omega} ,$$

266 which has residual variance corresponding to the model variance σ_{η}^2 . In general, the model variance σ_{η}^2
 267 is unknown and a proper estimation can be obtained by iterative least squares (Kjeldsen and Jones, 2009).
 268 The procedure consists in estimating the model parameters $\boldsymbol{\beta}$ from an initial guess obtained by OLS and
 269 to update σ_{η}^2 using the empirical variance of GLS residuals in equation (0). These two steps are repeated
 270 until convergence.

271 **2.4 Pooling groups and super regions**

272 Pooling groups are formed of the M sites that are the closest to the target site. To that end, three types of
 273 distance are considered: The geographical distance (GEO), the Mahalanobis distance between catchment
 274 descriptors (PHY) and the canonical distance. The Mahalanobis distance is selected because it considers
 275 not only the scales of the catchment descriptors, but also their covariance structure, which accounts for
 276 information redundancy (Cunderlik and Burn, 2006). The study of Oudin et al. (2010) showed that regions
 277 based on the similarity among catchment descriptors do not always easily translate into similarity in terms
 278 of hydrological properties. Consequently, regions derived from these two notions may lead to very different

279 groups of sites. Canonical correlation analysis (CCA) can be used to create new canonical coordinates in
280 the hydrological space that are mutually independent and sequentially maximizes correlation with
281 catchment descriptors. The canonical distance defined as the distance between the canonical coordinates
282 was used in RFA to delineate homogenous regions (Ouarda et al., 2001; Spence et al., 2007) or to perform
283 spatial interpolation of the outcomes of hydrological models (Hundecha et al., 2008). For ungauged
284 analysis, the hydrological information is unknown, but a substitute target position is estimated using the
285 correlation with the catchment descriptors. Therefore the quality of the canonical distance for pooling
286 groups depends on the relevance of the canonical distance and the quality of the estimated target in the
287 canonical space (Durocher et al., 2016a).

288 The present study considers the formation of pooling groups directly using one of the three distances
289 mentioned, but also considering combinations of two distance measures using a hierarchical approach.
290 Specifically, the procedure involves identifying for each site a subset of M_1 sites located the closest to the
291 target based on the first distance and then forming a pooling group of size $M_2 \leq M_1$ based on the second
292 distance measure. For instance, a subset of the 100 nearest sites is extracted using the GEO distance and
293 then a pooling group of size 25 sites is selected among them based on the PHY distance. Such approach
294 will be denoted as GEO-PHY distance. This strategy is similar to the approach of Eng et al. (2007) that
295 used pooling groups based on the PHY distance, but where a fixed distance was used instead of a constant
296 number of sites.

297 If a pooling group contains too few sites, it will lead to a large predictive variance, but including many sites
298 that are not relevant to the site of interest may create bias. In addition to the size of the pooling group, the
299 choice of the catchment descriptors can also influence the quality of the fitting. To guide the calibration of
300 a pooling group, it is recommended to find settings that optimize the quality of the prediction (Reis et al.,
301 2005). Let y_0 be the flood quantiles at an ungauged location that has catchment descriptors \mathbf{x}_0 . Using the
302 GLS estimator in equation (0) the predictive variance is given by

303 (0)
$$\sigma_{\eta}^2 \left[1 + \mathbf{x}_0^T (\mathbf{X}^T \mathbf{G}^{-1} \mathbf{X})^{-1} \mathbf{x}_0 \right],$$

304 which can be optimized by comparing various combinations of pooling group size and catchment
 305 descriptors.

306 Another strategy for the calibration of the ROI/GLS model consists in selecting the same size and catchment
 307 descriptors for a group G of sites. Notice that these groups will only be used for calibration and do not
 308 affect the formation of the pooling groups. Although such groups could take different forms, the present
 309 study defines super regions according to site drainage area and mean annual precipitation. Similar super
 310 regions were considered by Salinas et al. (2014a), but instead of using 3 straightforward divisions (i.e.,
 311 small, medium and large), the present study uses a hierarchical agglomerative clustering method (Murtagh
 312 and Legendre, 2014; Ward, 1963) to provide more objective boundaries, while maintaining meaningful
 313 interpretation.

314 Inside a super region, the prediction performance associated with specific settings can be evaluated by
 315 cross-validation. Formally, let $y_{(i)}$ be predicted flood quantiles (log) obtained at the i -th site when it is
 316 considered ungauged. Optimal settings may be identified by minimizing a criterion based on the predicted
 317 residuals $y_i - y_{(i)}$. In this line, two common performance criteria are the Nash-Sutcliffe and the mean
 318 absolute deviation

319 (0)
$$\text{NSH} = 100 \times \left\{ 1 - \frac{\sum_{i \in G} w_i (y_i - y_{(i)})^2}{\sum_{i \in G} w_i (y_i - \bar{y})^2} \right\} \text{ and } \text{MAD} = \frac{\sum_{i \in G} w_i |y_i - y_{(i)}|}{\sum_{i \in G} w_i},$$

320 where w_i are weights such that $\sum_i w_i = 1$ and \bar{y} is the weighted average of the y_i . For the calibration of
 321 the ROI/GLS model, the weights are taken as the record length of a site, which gives more importance to
 322 sites with more data.

323 **3.Results**

324 **3.1 Data**

325 The annual maximums of river discharge are extracted from daily records provided by Water Survey of
326 Canada (2017) and catchment descriptors are provided by Environment and Climate Change Canada.
327 Figure 1 presents the locations of 771 selected sites where the desired catchment descriptors were available.
328 Every site is verified to possess at least 20 years of records and not exhibit significant trends according to
329 the Mann Kendall test (Önöz and Bayazit, 2012).

330 The concept of super regions is to improve the interpretability of the results by dividing sites with similar
331 scale control and climate. After some experimentation, the sites were divided into 8 super regions. Figure
332 2 presents the correspondence between position in the descriptor space and their locations. Super region 1
333 uniquely includes sites from the Pacific coast having small to medium drainage area and the largest mean
334 annual precipitation. Other wetter sites are found in super regions 2 to 4, which are located either in British
335 Columbia or in the southeastern part of Canada. The drier ones correspond to super regions 5 to 8, which
336 are mostly located in the prairie provinces (Alberta, Saskatchewan and Manitoba) and in the northern part
337 of Canada. In general, the largest watersheds are found in the more northerly locations and correspond to
338 super regions 7 and 8. In particular, super region 7 is wetter than super region 8 and is located mostly in the
339 north of Quebec, Ontario and British Columbia. One can see that British Columbia includes a large variety
340 of rivers as it includes sites from the eight super regions. Table 1 presents descriptive statistics for the
341 drainage area and mean annual precipitation as well as the other available catchment descriptors, which
342 include: basin compactness, average slope, streamflow density, percentage of waterbody area and site
343 elevation.

344 The fitting and the selection of the best distribution at each gauged site is performed as described in the
345 methodology section. The GEV distribution (including Gumbel) was preferred in 62.5 % of the gauged

346 sites, followed by the Pearson type III (including Gamma) with 29.7 %. The other distributions were
347 selected in lower proportions. The flood quantiles associated with return levels are then computed for each
348 site using the selected distribution.

349 **3.2 Estimation of the sample covariance matrix**

350 The correlation matrix of Spearman's rho coefficient is estimated using the nonparametric model in equation
351 (0), where an adjusted coefficient of determination (R^2) of 52% is obtained, indicating that the model fits
352 the data fairly well. The relative importance of each smooth term is assessed by examining the difference
353 of R^2 when that component is removed. As expected, the most important smooth term is f_h associated with
354 the distance and has a relative importance of 21%. It is followed respectively by f_{xy} and f_A with 13%
355 and 2 %. These values indicate that the intersite correlation is mostly influenced by the distance between
356 sites, but that a non-negligible effect is also depending mostly on the location. In other words, the
357 dependence among pairs of sites cannot be explained uniquely by the separating distance. The effect of f_{xy}
358 is illustrated in Figure 3 using a map of the smoothed terms, even though discharge can only be observed
359 at unique points on rivers. One can see different zones where the Spearman's rho is lower or higher than
360 what would be expected considering uniquely f_h , the effect of the distance between sites.

361 Figure 3 also shows the correlation coefficient in respect of the distance where the solid line represents the
362 POW model fitted by weighted least squares using record lengths as weights; with parameters $\alpha = 905$, τ
363 $= 0.14$ and $\gamma = 0.81$. Notice that the coefficient of correlation in respect of the distance becomes (in
364 average) stable after roughly 600 km, but never reaches zero. The POW model is biased after that point as
365 it can be assumed that for separations beyond 600 km, the correlation becomes more and more negligible.
366 From a practical point of view, after 600 km the correlation is relatively low (less than 0.2). It is then
367 reasonable to assume that it decreases to values that are not statistically different from zero.

368 The choice of a copula is investigated to determine the nature of the dependence among near sites. As the
369 power for rejecting the null hypothesis increases with the strength of the dependence, only paired
370 observations separated by less than 50 km and having at least 40 years of common record are selected. In
371 total, 109 paired observations are identified and are presented in Figure 1. Note that the minimum
372 Spearman's rho for these paired observations is 0.7. For each pair, goodness-of-fit tests are performed using
373 as null hypothesis one of the following copulas: Normal, t-copula, Husler-Reiss, Gumbel, Galambos and
374 Clayton (see, for instance, Salvadori et al. (2007) for a description of these copulas). The results show that
375 only the Clayton copula is rejected at a significance level 5% in a majority of the cases, while the other
376 copulas are not rejected for all pairs. In the present study, the size of the sample remains relatively small
377 and so the goodness-of-fit tests do not have high power of discrimination. Nevertheless, these results do
378 not indicate any evidence that would suggest rejecting these copulas.

379 Figure 4 presents a comparison of the log-likelihood between the bivariate Normal copula in respect of two
380 bivariate extreme copulas. One can see that for most paired observations, the Normal copula provides the
381 best fit as evidenced by there being more points below than above the 45° line. In particular, it suggests a
382 preference for a multivariate Normal copula over a max-stable process to characterize the spatial
383 dependence among all observations. The decision between the Normal copula or t-copula will affect the
384 behavior in terms of tail dependence. Fitting a multivariate t-copula on all paired observations led to
385 estimated degrees of freedom $\nu = 15$, which is associated with a relatively low tail dependence. For
386 instance, with correlation coefficient of 0.5 and 0.3 the tail dependence is respectively 0.03 and 0.01. This
387 agrees with the better fit of the bivariate Normal copula in comparison to extreme copulas for which tail
388 dependence is an important characteristic. Therefore, the Normal copula is adopted as a reasonable model
389 for the rest of the analysis.

390 The matrix of sampling covariances for the flood quantiles (log) is obtained for several return periods using
391 Monte-Carlo simulations as described in the methodology. Figure 5 (left panel) illustrates the correlation

392 between the paired Q100 in respect of the distance and the solid line represents the fitted POW model.
393 Similarly, the right part of Figure 5 shows fitted POW model for various return periods. One can see that
394 the strength of the correlation decreases with the return period. On average, the correlation between Q100
395 becomes less than 0.2 after roughly 100 km, while intersite correlation between annual maximum reach
396 that point more around 400 km. Note that the zero tail dependence property of the Normal copula implies
397 that for very large return periods the correlation between flood quantiles will continue to decrease towards
398 zero.

399 **3.3 Calibration of the pooling groups**

400 As described in the methodology, the calibration of the ROI/GLS models may be guided by the predictive
401 variance, equation (0), or by cross-validation, equation (0). In the following, each site is treated in turn as
402 ungauged and a regression model is fitted using several combinations of pooling group sizes and catchment
403 descriptors. More precisely, the pooling group sizes $M_2 = 20, 25, \dots, 80$ and all combinations of three or
404 more catchment descriptors are tried. The initial subset inside which the pooling groups are formed is
405 restricted to $M_1 = 100$ or 200 .

406 Table 2 presents the prediction performance obtained using different distances and comparing the
407 calibration obtained using the predictive variance (Individual) and the criterion MAD inside super regions.
408 Note that only the best hierarchical distances are reported. For GEO-PHY and GEO-CCA this corresponds
409 to $M_1 = 100$ sites, while for PHY-GEO, $M_1 = 200$ sites. When the predictive variance is used, the
410 geographical distance led to better predictive performance than the other distance in terms of MAD for both
411 Q10 and Q100. However, all the results are relatively similar in terms of NSH, except for the direct
412 canonical distance that has poorer performance. Nevertheless, better predictive performances are always
413 found when the models are calibrated using super regions. In these cases, the GEO-PHY and the PHY-GEO
414 distance perform similarly with a slight advantage to GEO-PHY. This illustrates the clear advantage of

415 combining these two distances. In particular, the hierarchical approach GEO-CCA performs substantially
416 better than the direct use of the canonical distance.

417 One objective of the present study is to examine the advantage of a nationwide analysis in comparison to
418 an analysis based on smaller geographical areas. To explore this impact, the calibration of the ROI/GLS
419 model is split in four distinct administrative regions. The first region regroups the four Atlantic provinces
420 (New Brunswick, Nova Scotia, Prince Edward Island and Newfoundland and Labrador) with 90 sites. The
421 second region combines Ontario and Quebec with 180 sites, while the third region regroups British
422 Columbia and Yukon Territory with 213 sites. The Prairies and the two remaining territories complete the
423 fourth region with 288 sites. For each region, 3 super regions were delineated inside. Note that these settings
424 do not represent all possibilities that involve administrative boundaries. Nevertheless, it should illustrate
425 the potential impact this has on the calibration of ROI/GLS. When using a nationwide analysis, the
426 performance criteria for Q100 using the GEO-PHY distance are NSH = 91.05 and MAD = 0.343. The same
427 criteria are slightly inferior when using administrative boundaries with NSH = 90.77 and MAD = 0.351.
428 Similar outcomes are observed with Q10 where performance criteria pass from NSH = 93.49 and MAD =
429 0.296 to NSH = 92.85 and MAD = 0.317, respectively.

430 The results obtained in the present study are coherent with previous studies for portions of Canada. In the
431 province of Quebec (Durocher et al., 2016a) and Ontario (Grover et al., 2002) relative root mean square
432 errors (RRMSE) of 0.435 and 0.347 were reported for Q100. When using similar metrics, the ROI/GLS
433 method used in the present study finds RRMSE of 0.438 and 0.346. However, such comparison must be
434 done with care as these studies don't consider exactly the same set of gauged sites and were conducted on
435 different periods.

436 3.4 Uncertainty analysis

437 Overall the best ROI/GLS models are obtained using super regions and the GEO-PHY distance, which is
438 now examined in more detail. Table 3 reports the sizes and catchment descriptors used in the pooling groups
439 of each super region and Table 4 separates the predictive performance by super regions. The wetter super
440 region 1 and the larger super region 8 are well fitted with NSH greater than 90 for both flood quantiles;
441 these super regions also have the lowest MAD. Good predictive performance is also observed for the wetter
442 super regions 2 to 4. The prediction of the drier sites mostly found in the Prairies and the north is, however,
443 relatively less accurate, especially for the smaller watersheds in super regions 5 and 6, with respective NSH
444 of 32.23 and 65.43. These lower predictive performances are largely due to the presence of problematic
445 sites. Figure 6 presents the predicted residuals standardized by the predictive variance. For Q10, one
446 potential outlier is found in super region 5 where the predictive residual is higher than 8 standard deviations.
447 For Q100, the same site remains problematic and other potential outliers arise in super region 6. This finding
448 suggests that smaller and drier sites are more likely to be problematic to estimate than those of the other
449 super regions. When predictive residuals higher than 3 standard deviations are removed for Q100, the NSH
450 of super regions 5 and 6 is much better and becomes 76.02 and 73.35, respectively. Note that the NSH
451 criterion evaluates the predictive performance in comparison to the weighted average, but does not represent
452 a measure of the absolute uncertainty. For instance, super region 3 includes medium sized catchments
453 strongly concentrated in southern Ontario. The NSH of Q100 for this super region is 69.72 which is less
454 than super region 7 with 84.85. However, the MAD of super region 3 is 0.29 in comparison to 0.38 for
455 super region 7, showing that estimations are overall less uncertain. Even after removing outliers, the
456 estimation of the flood quantiles Q10 and Q100 for the drier super regions 5 to 7 remain less accurate with
457 MAD greater than 0.33, while less than 0.29 for the other super regions.

458 A sensitivity analysis is conducted to measure the effect of the intersite correlation model used to obtain
459 the sampling covariance matrix on variability of the estimated flood quantile. Let σ_{IND}^2 , σ_{POW}^2 and σ_{NP}^2

460 denote the predictive variance obtained assuming intersite independence, the POW model and the
461 nonparametric model. The nonparametric model is more flexible and so its predictive variance should be
462 closer to the true value. Consequently σ_{NP}^2 is considered as a benchmark and Figure 7 shows the ratio of
463 variance $\sigma_{POW}^2 / \sigma_{NP}^2$ (left) and $\sigma_{IND}^2 / \sigma_{NP}^2$ (right). The ROI/GLS model was calibrated using the GEO
464 distance (top) and the GEO-PHY distance (bottom). The ratios $\sigma_{POW}^2 / \sigma_{NP}^2$ of both distances (left) show
465 that a smoother version of the intersite correlation has a limited impact on the evaluation of the model
466 uncertainties, while the assumption of independence tends to underestimate it. In particular, the
467 underestimation of the model uncertainties is affecting more the drier and larger basins found in super
468 regions 3, 6, 7 and 8. Figure 7 (bottom-right) indicates that even though the distance GEO-PHY mainly
469 formed the pooling group based on the distance between catchment descriptors, there is a substantial impact
470 on the estimation of predictive variance from the covariance model. However, this underestimation is as
471 expected less important than when using the GEO distance (top-right) that forces stronger intersite
472 correlations in the pooling groups.

473 **4. Conclusions**

474 The ROI/GLS method was investigated to estimate flood quantiles at ungauged locations using a large
475 database of 771 sites across Canada. The calibration procedure provides a general guideline to apply
476 ROI/GLS regression in situations where no direct formula is available for evaluating the sample covariance
477 matrix. A pairwise fitting of copulas was considered among close sites to show that the Normal copula is a
478 reasonable model for the intersite correlation structure. In particular, it reveals that extreme type of spatial
479 dependence is not generally the best option for characterizing the relationship among annual maximum
480 streamflow in Canada. Similar findings should be expected in other cold regions, because floods are
481 dominated by spring snowmelt. Such behavior goes in the opposite direction to the recent interest in the
482 max-stable processes in the characterization of spatial dependence between extreme rainfall events.

483 A nonparametric model was used to estimate the sampling covariance matrix of various pairs of flood
484 quantiles. This approach was selected to better estimate the associations between paired observations when
485 there are few or no years of common record. The main objective of using GLS in RFA is to obtain accurate
486 estimation of the uncertainties of flood quantiles. In this regard, it was found that a simpler intersite
487 correlation structure characterized by a power exponential model in respect of the geographical distance
488 does not largely affect the estimation of the predictive variance and led to similar evaluation of the
489 predictive variance. However, ignoring intersite correlation was shown to underestimate the predictive
490 variance substantially. This is especially true for the drier basins located mostly in the Prairies and in the
491 northern part of the country.

492 Cross-validation was used to evaluate and guide the calibration of the ROI/GLS models using three notions
493 of distance. It was shown that the best choice was a hierarchical approach where first the 100 nearest sites
494 to the target are identified according to the geographical distance and then a smaller pooling group is formed
495 using the Mahalanobis distance between catchment descriptors. Additionally, super regions were delineated
496 based on the drainage area and the mean annual precipitation to help the calibration of the ROI/GLS model.
497 For each super region the same catchment descriptors and pooling group sizes were chosen. This strategy
498 led to better predictive power than individually calibrating sites using the predictive variance. The effect of
499 administrative boundaries on the calibration of the regression models was also explored. The results showed
500 that performing a nationwide RFA analysis resulted in ROI/GLS models with better predictive power. The
501 concept of super regions was also found useful to calibrate the pooling groups and to better understand the
502 quality of the flood estimations in respect of scale control and climate. The results indicated that the flood
503 quantiles of the drier basins are estimated with greater uncertainty than the wetter ones. In particular,
504 ROI/GLS resulted in rather poor predictions for some problematic sites in some of the smaller and drier
505 basins.

506 Overall, the present study validates successful settings to carry out RFA using the ROI/GLS framework. In
507 particular, it provides guidelines for estimating the sampling covariance matrix in a general context and
508 using super regions to improve the calibration of the pooling groups. These outcomes are helpful to promote
509 the adoption of GLS in RFA.

510 **Acknowledgements**

511 This work was supported by the Natural Science and Engineering Research Council (NSERC) Canadian
512 FloodNet (# NETGP 451456 – 13). Computation were realized using the R environment (R Core Team,
513 2017).

514

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717 **Tables**

718 **Table 1: Summary statistics for runoff and catchment descriptors.**

Variables	Abrv.	Min	Q1	Med	Avg	Q3	Max
Record length (yr)		20	25	36	39	48	111
mean of annual maximum discharge (m ³ /s)		0.2	13.4	45.6	206.9	174.1	5068.3
Basin area (km ²)	area	1	146	460	2829	1992	48867
Basin compactness	comp	0.4	1.7	2.5	2.6	3.4	6.3
Basin mean slope (%)	slope	<0.1	1.2	3.6	10.5	17.1	59.0
Waterbody area (%)	wb	<0.1	0.4	1.3	3.7	4.5	38.3
Stream density (km ⁻¹)	dens	<0.1	0.6	1.0	1.2	1.6	3.4
Elevation at site (m)	elev	1	181	382	474	731	1699
Mean annual precipitation (mm)	map	213	498	761	836	1052	3216

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720

721 **Table 2 : Performance criteria for flood quantiles using the ROI/GLS model with different distance.**
 722 **Calibration using predictive variance (individual) and super region.**

723

Variable	Distance	Individual		Super Region	
		NSH	MAD	NSH	MAD
Q10	PHY	91.50	0.351	93.21	0.309
	GEO-PHY	92.05	0.337	93.49	0.296
	GEO	92.27	0.322	93.34	0.302
	PHY-GEO	91.53	0.343	93.48	0.299
	CCA	88.29	0.422	89.28	0.400
	GEO-CCA	91.93	0.346	93.31	0.308
Q100	PHY	88.74	0.411	90.72	0.362
	GEO-PHY	89.15	0.392	91.05	0.343
	GEO	89.57	0.378	90.80	0.351
	PHY-GEO	89.40	0.388	91.03	0.347
	CCA	84.42	0.488	85.96	0.457
	GEO-CCA	88.69	0.406	90.61	0.360

724 * Bold indicates best results in each column

725

726 **Table 3: Pooling group sizes and catchment descriptors for ROI/GLS model using GEO-PHY.**

	Super region	Size	Catchment descriptors
Q10	1	25	area + slope + wb + elev + map
	2	70	area + comp + elev + map
	3	25	area + slope + wb + elev + map
	4	60	area + slope + wb + map
	5	40	area + slope + elev + map
	6	40	area + dens + elev + map
	7	65	area + dens + slope + wb + elev + map
	8	40	area + dens + slope + wb + elev + map
Q100	1	25	area + slope + wb + elev + map
	2	25	area + comp + slope + wb
	3	25	area + slope + wb + elev
	4	60	area + slope + wb + map
	5	40	area + slope + elev + map
	6	25	area + wb + elev + map
	7	60	area + dens + wb + elev + map
	8	60	area + comp + dens + slope + wb + elev + map

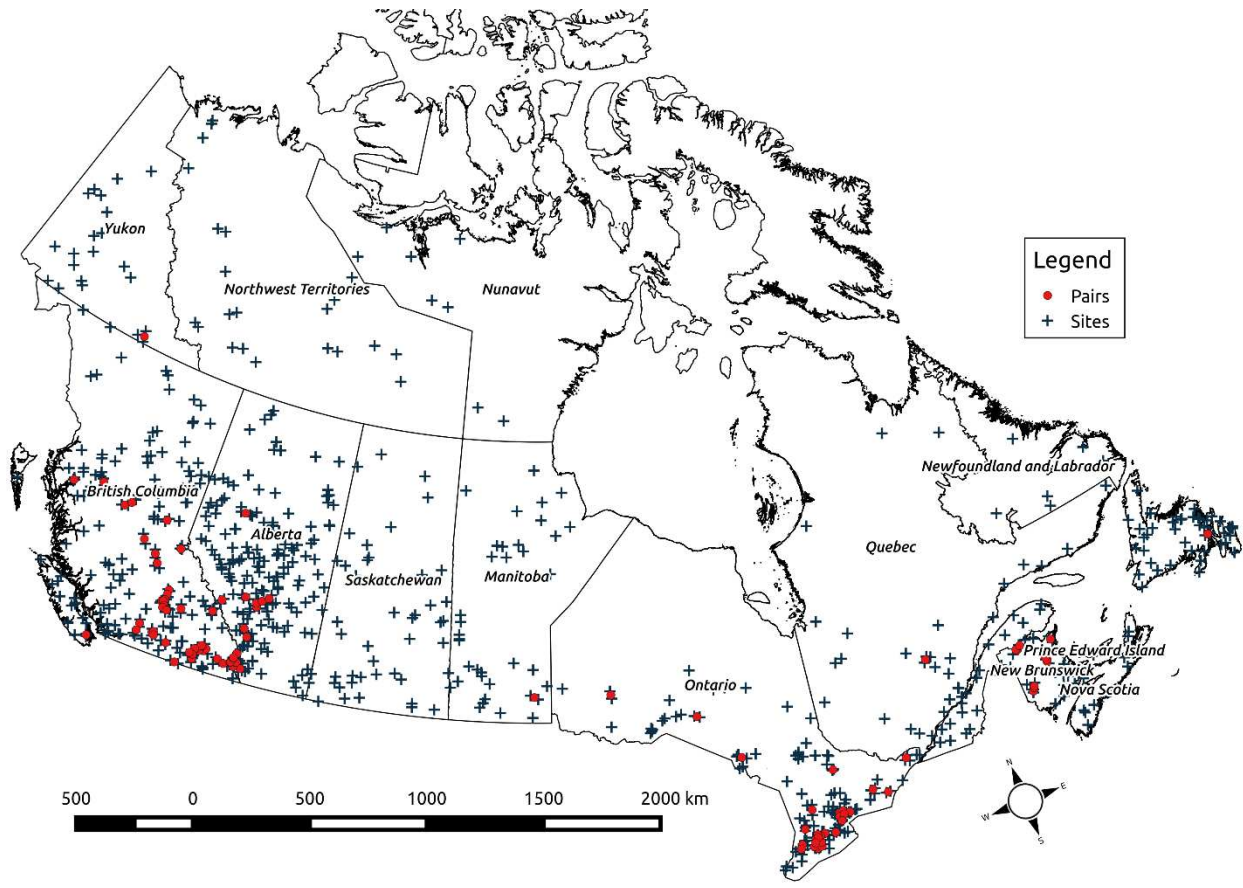
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728 **Table 4: Performance criteria for flood quantiles using the ROI/GLS model with a GEO-PHY**
 729 **distance detailed by super region.**

Super region	Q10		Q100	
	NSH	MAD	NSH	MAD
1	96.40	0.188	93.13	0.236
2	89.29	0.243	83.25	0.271
3	78.72	0.240	69.72	0.290
4	83.83	0.223	75.93	0.293
5	31.00	0.618	32.23	0.625
6	75.41	0.406	65.43	0.476
7	88.44	0.353	84.85	0.380
8	93.99	0.215	90.92	0.248
Total	93.56	0.296	91.17	0.343

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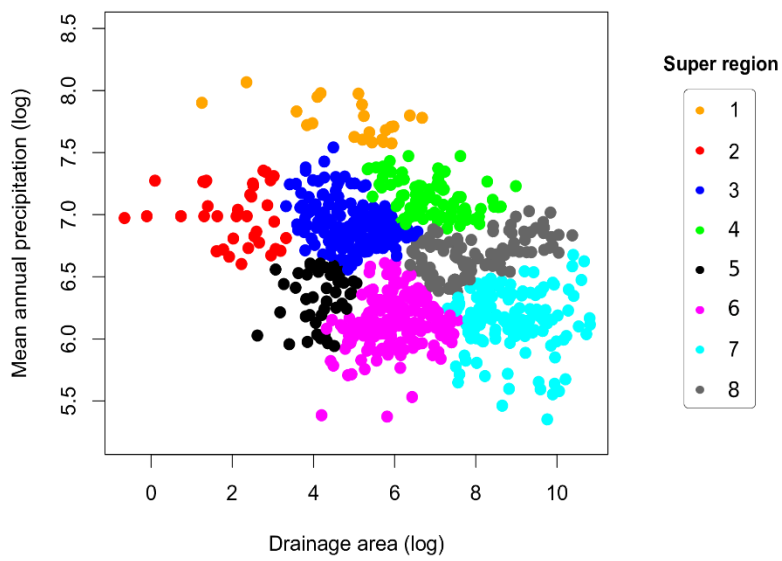
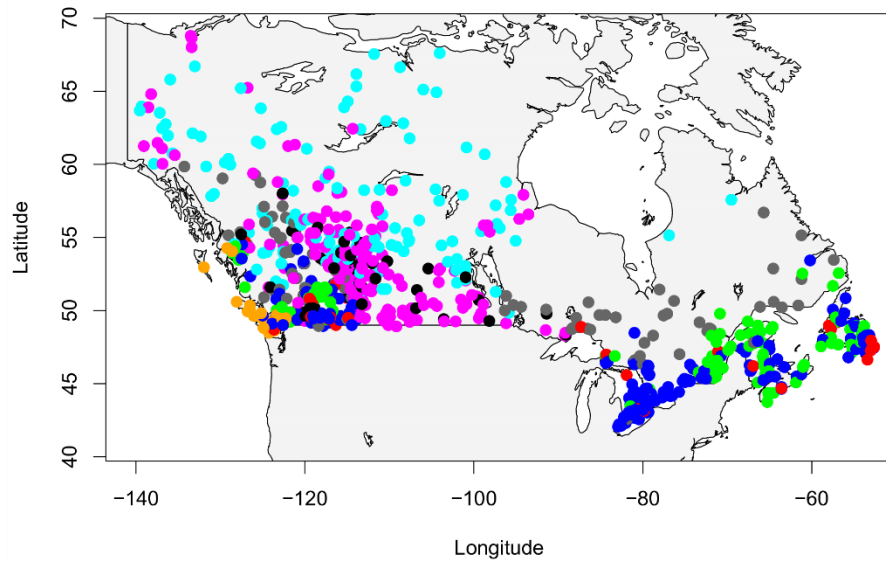


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734 **Figure 1: Locations of 771 gauged sites in Canada and average locations of 109 pairs of sites separated**
735 **by less than 50 km and having 40 years of common record.**

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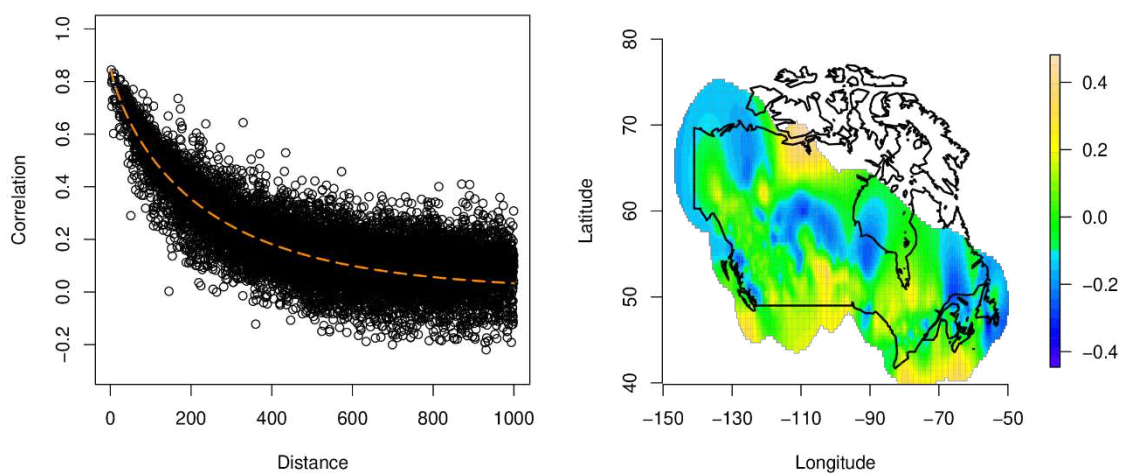
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739 **Figure 2: Super regions in geographical (top) and descriptor space (bottom).**

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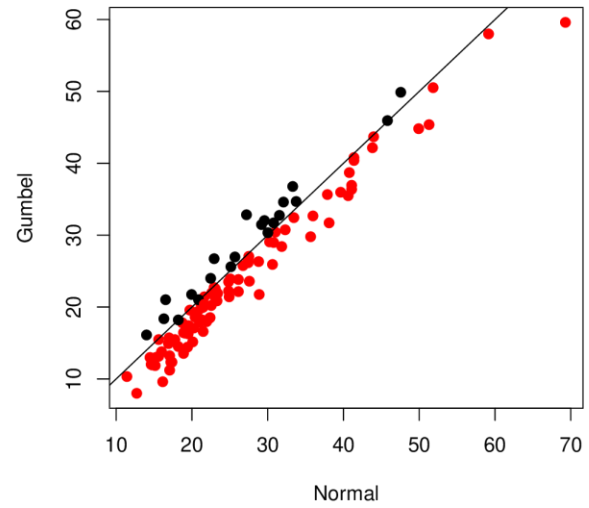
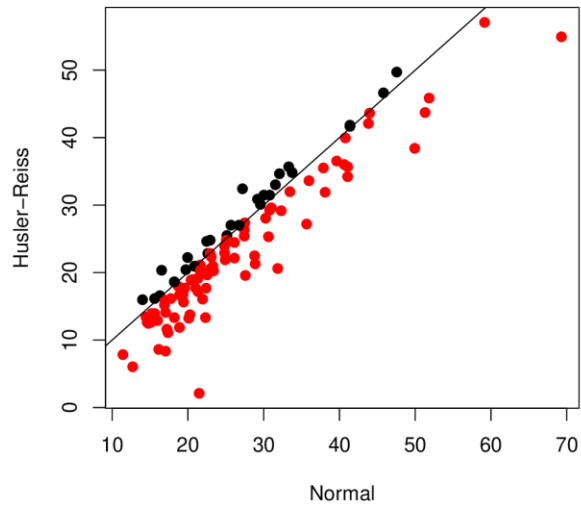
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744 **Figure 3:** At left, correlation coefficient estimated from the nonparametric model. The dashed line
745 represents the fitted POW model. At right, a representation of the component f_{xy} of the nonparametric
746 model on a grid of locations.

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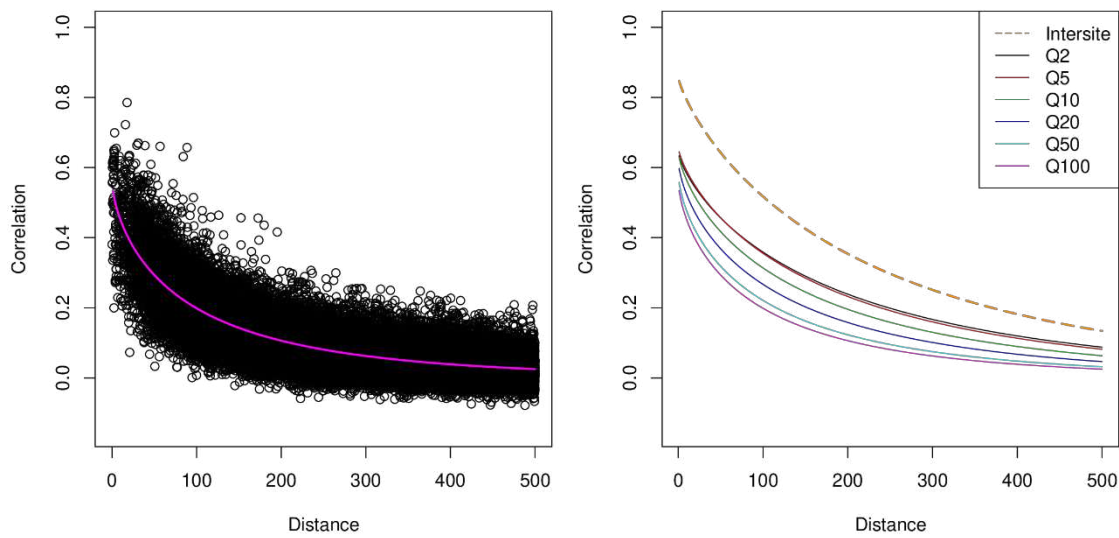


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749 **Figure 4: Log-likelihood of fitted copulas for the 109 paired sites in Figure 1.**

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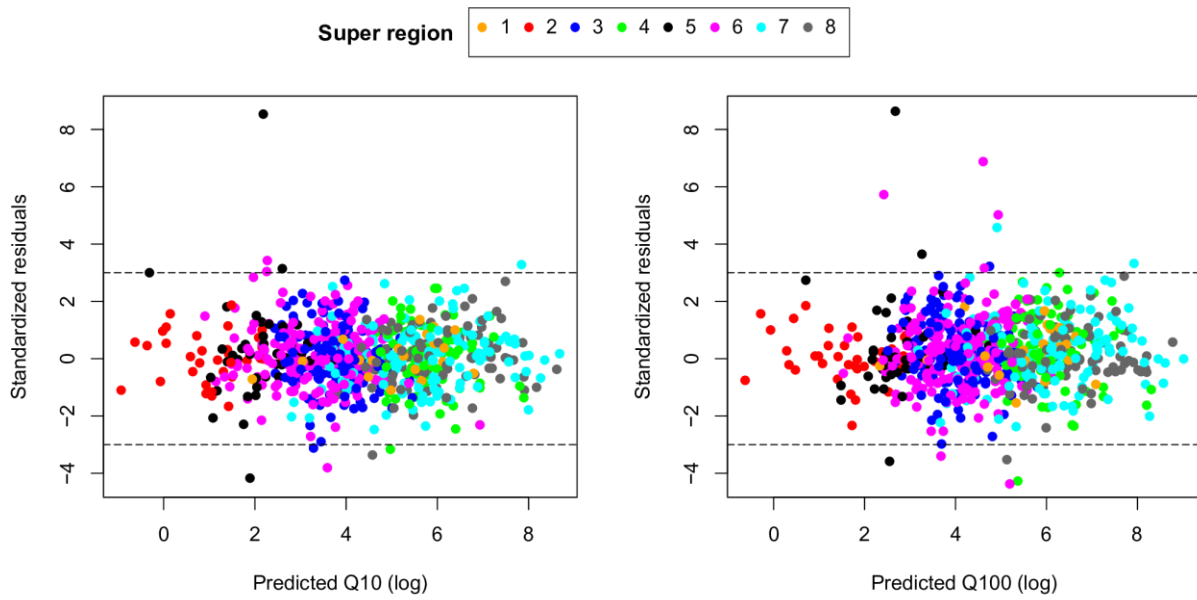
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753 **Figure 5: At left, correlation between paired Q100 (log) estimated by Monte-Carlo simulations using**
754 **the nonparametric model. The solid line represents the fitted POW models. At right, the POW models**
755 **are reported by return period. As a reference, the dashed line indicates the POW model for intersite**
756 **correlation found in Figure 3 .**

757

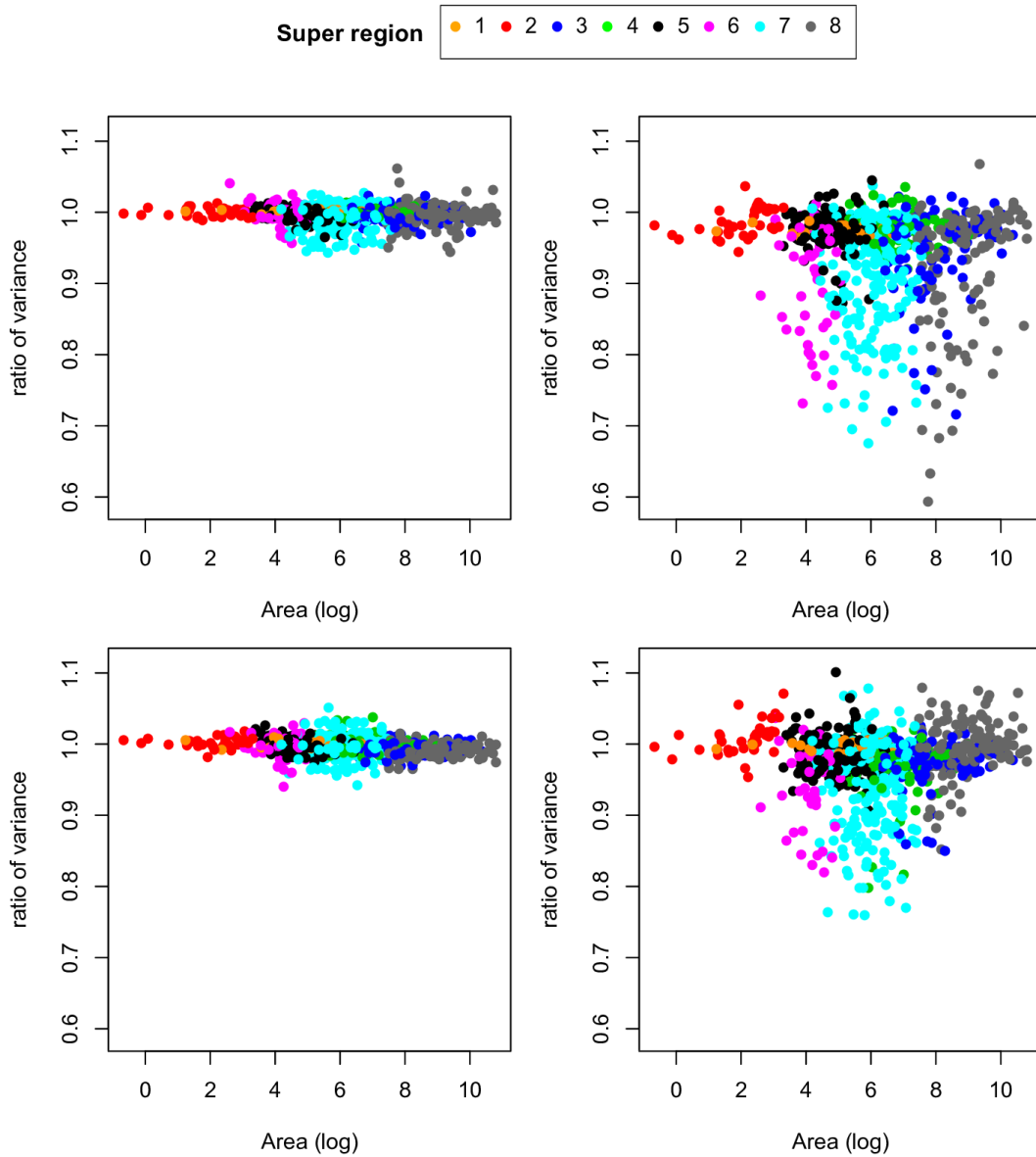
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761 **Figure 6 : Standardized predictive residuals using GEO-PHY and super regions.**



762

763 **Figure 7: Comparison of the ratio of predictive variance for Q10. The denominator is the predictive**
 764 **variance deduced from the nonparametric model, while the numerator is deduced from the POW**
 765 **model (left) and the assumption of independence (right). Pooling groups are formed using GEO**
 766 **distance (top) and GEO-PHY bottom.**