

# Upper Crustal Control on Nearshore Subduction Mechanics in Cascadia

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## Abstract

Along-strike upper plate heterogeneity is widely observed at subduction margins, but its direct influence on slab geometry and interseismic deformation remains debated. Here, we investigate the effect of upper-crustal geological segmentation on nearshore subduction mechanics at the Cascadia margin. Using a high-resolution, shore-crossing 3-D seismic tomography model from central to southern Oregon, we image sharp along-strike contrasts in upper-crustal velocity associated with distinct accreted terranes. We show that the subducting slab is systematically deeper beneath the coherent, high-velocity Siletz terrane and shallower beneath low-velocity faulted Siletz and Franciscan terranes. Numerical simulations constrained by the tomographic velocities demonstrate that upper-plate density and rigidity contrasts alone reproduce the observed variation in slab depth and, when combined with viscoelastic deformation, explain the magnitude and pattern of coastal uplift. These findings establish that the along-strike changes in upper-crustal backstop, despite being ignored in geodetic locking models, are a primary mechanical filter that organizes subduction zone architecture and regulates the accumulation of megathrust related strain.

## Teaser

Upper crustal geology shapes how the Cascadia slab bends and uplifts the coast, revealing structure-driven segmentation of subduction mechanics.

## INTRODUCTION

The last megathrust earthquake at the Cascadia Subduction Zone (CSZ) occurred in 1700 (1). Given an estimated average recurrence interval of approximately 300-500 years (2), the system is likely approaching the end of the current interseismic period. During this phase, both the upper and lower crust undergo significant deformation (3). Characterizing this ongoing accumulation of strain is critical for understanding future megathrust ruptures, as it provides essential constraints on the mechanics of the subduction system. This study investigates two distinct modes of nearshore crustal deformation at CSZ: flexural bending of the subducting slab and upper-plate uplift rates at the coast. We focus on the along-strike segmentation of these interseismic deformation modes to evaluate if upper crustal geological heterogeneity drives the observed along-strike variability in slab bending and coastal uplift rates (both interseismic and long-term), as suggested by several previous observations (4–6).

Contemporary interpretations of subduction mechanics frequently overlook the influence of upper-crustal geologic variability. For example, geodetic locking models of the CSZ (7–9), whether utilizing analytical elastic half-space solutions or numerical finite element models, have predominantly approximated the overriding or upper crust as a mechanically homogeneous elastic medium by neglecting variable earth structure (10) and delegating structural complexity to kinematic corrections rather than varying elastic moduli. Even viscoelastic formulations that incorporate mantle or glacial-isostatic relaxation generally assume a purely elastic, laterally invariant continental plate (8, 11). Yet along-strike

50 variations in upper-plate stiffness of tens of gigapascals are mechanically significant, as  
51 they alter the partitioning of interseismic strain and can bias geodetically inferred coupling  
52 patterns even when fault-slip conditions are identical (12). Numerical experiments further  
53 demonstrate that neglecting variable rigidity can introduce significant distortions (often up  
54 to 50%) in calculated surface deformation and subsurface shear-stress estimates,  
55 especially in thrust-faulting regimes (13). Thus, ignoring upper-crustal heterogeneity risks  
56 conflating mechanical contrasts in the overriding plate with true variations in megathrust  
57 frictional state.

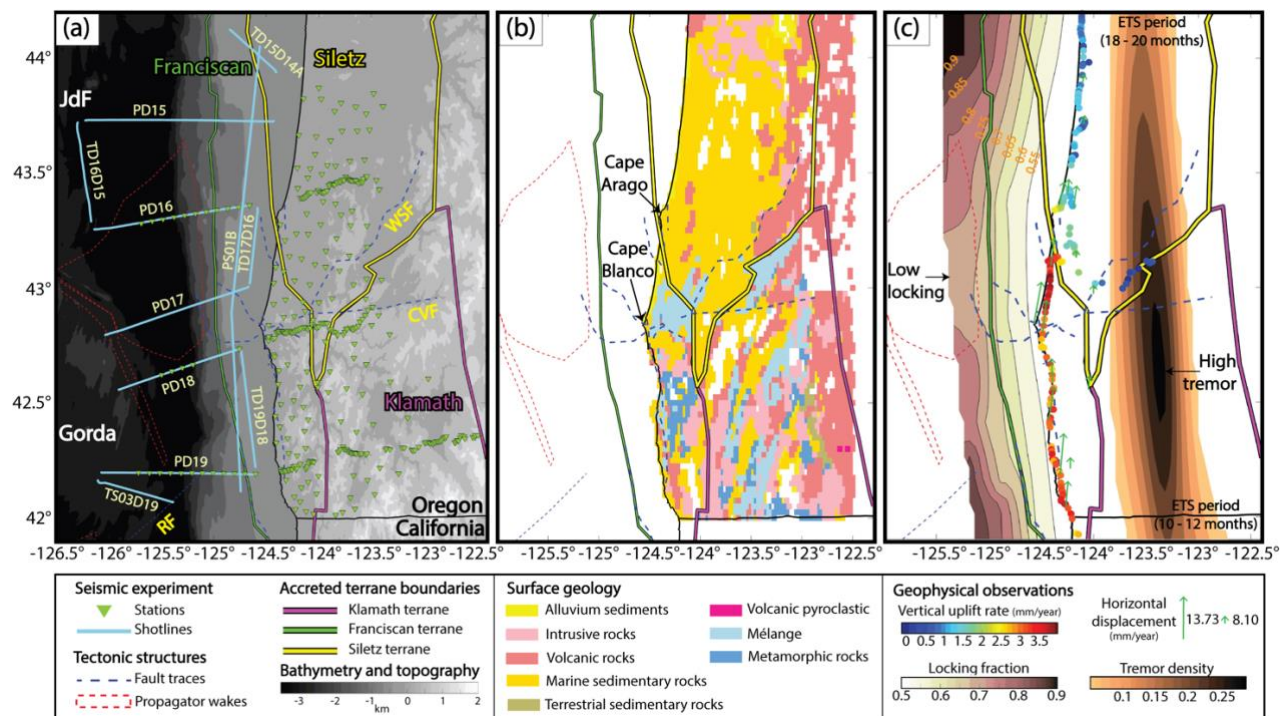
58 Beyond its influence on elastic strain partitioning, upper-crustal composition actively  
59 modulates megathrust mechanics through vertical loading, effective normal stress, and  
60 rheological segmentation. Density contrasts within the forearc directly affect lithostatic  
61 pressure on the plate interface, with dense mafic crust promoting stronger coupling and  
62 lower-density crust favoring aseismic slip (14). Observations from multiple subduction  
63 zones show that along-strike variations in interseismic coupling and slow-slip recurrence  
64 often coincide with forearc structural transitions rather than slab geometry alone (15–17).  
65 At smaller scales, gradients in fluid pressure, permeability, and the distribution of strong  
66 blocks within weak, hydrated matrices further localize deformation and regulate rupture  
67 propagation (16–18). Together, these lines of evidence indicate that upper-crustal strength  
68 is not merely a boundary condition imposed on subduction systems, but an active control  
69 on stress accumulation, slip behavior, and mechanical segmentation along the plate  
70 interface.

71 Forearc geology, such as contrasts in crustal density, composition, thickness, and fluids,  
72 imposes mechanical segmentation that may govern stress transfer across the plate  
73 interface. For instance, density-driven variations in vertical loading have been evidenced  
74 to modulate megathrust shear strength (14). Also, geodetic analyses show that  
75 mechanically weak segments may act as rupture barriers, which demonstrates that  
76 segmentation is imposed by upper plate structure rather than by transient seismic cycle  
77 effects (15). Over longer timescales, upper crustal strength contrasts may regulate forearc  
78 deformation and orogenic development by controlling where both elastic and permanent  
79 strain is stored versus distributed (19–21). These same strength contrasts also determine  
80 whether deformation remains localized on the megathrust or is partitioned into the upper  
81 plate, with strain partitioning emerging only where inherited crustal weaknesses permit  
82 stress transfer (22). Therefore, accounting for along-strike upper-crustal heterogeneity is  
83 essential for interpreting interseismic deformation at Cascadia and for improving physical  
84 models of megathrust behavior.

85 To evaluate the hypothesis that upper-crustal geology modulates interseismic deformation,  
86 we examine the central segment of the CSZ (42°–44.5° N) in central-to-southern Oregon  
87 (**Fig. 1**). This region represents the margin's most tectonically heterogeneous sector (5, 6),  
88 reflecting episodic accretion of distinct terranes during a complex history of long-lived  
89 subduction and continental lithospheric growth (23). At approximately 43.5° N, the  
90 forearc undergoes a major lithological shift where the overriding plate transitions abruptly  
91 along strike from the Franciscan and Klamath terranes in the south to the Siletz terrane in  
92 the north. This terrane-scale juxtaposition creates sudden lateral contrasts in lithology  
93 (**Fig. 1b**), crustal thickness (24, 25), vertical load (5), and inferred mechanical strength (6)  
94 that remain poorly resolved (5).

95 To the north, the upper plate is underpinned by the Siletz terrane (**Fig. 1a**), a Paleocene–  
96 Eocene large igneous province that accreted rapidly to North America (26). Composed of  
97 thick, plateau-derived basalts, it forms a robust, seaward-dipping backstop (24, 26). In  
98 contrast, the nearshore southern section is dominated by the Jurassic–Cretaceous Central

99 Belt of the Franciscan terrane (23, 27). Consisting predominantly of clastic sedimentary  
 100 rocks and mélanges with subordinate metamorphic and mafic components, it records  
 101 prolonged accretion and deformation within the subduction complex (27, 28). Inland, this  
 102 weaker, sediment-dominated assemblage gives way to the Klamath terrane, an  
 103 amalgamated collage of oceanic crust, arc volcanics, mélanges, and ophiolites stitched  
 104 together by plutonic intrusions (29). These sudden along-strike changes in upper-crustal  
 105 composition and rigidity, reinforced by fault-bounded terrane contacts, spatially correlate  
 106 with distinct variations in geophysical observations that act as proxies for subduction  
 107 mechanics (**Fig. 1c**). Specifically, the southern termination of the rigid Siletz block  
 108 demarcates a zone where interseismic uplift rates increase from negligible in the north to  
 109  $>2$  mm/year in the south (30), and tremor density intensifies (31) with shorter Episodic  
 110 Tremor and Slip (ETS) recurrence intervals (4). Furthermore, these upper-crustal terrane  
 111 boundaries coincide with a significant along-strike change in slab curvature, specifically a  
 112 distinct shallowing south of the Siletz terrane (5, 32).



**Figure 1: Geological framework and geophysical observations of the south-central Cascadia Subduction Zone.** (A) Map of seismic stations and shot locations from central to southern Oregon used to develop the shore-crossing 3-D seismic velocity model. Major tectonic features are shown, including fault traces and oceanic propagator wakes. The Canyonville Fault (CVF) and Wildlife Safari Fault (WSF) are drawn from (33); the Rogue Fault (RF) is from (34), and additional fault traces are from the U.S. National Seismic Hazard Model 2023 (35). Boundaries of the three accreted terranes from (28) are also shown. (B) Surface geology of the study area from the Oregon Department of Geology and Mineral Industries (36). (C) Geophysical observations across the study region highlighting differences between the northern and southern parts of the south-central CSZ, including uplift rates in circles (30), locking fraction (8), and episodic tremor and slip (ETS) periods (4).

124 The influence of upper crustal segmentation of strength on the subducting plate interface  
 125 and its mechanical behavior at subduction zones remains to be fully resolved by direct  
 126 observations (4). Therefore, our first goal is to characterize the detailed nearshore crustal  
 127 structures by developing a 3-D high-resolution shore-crossing P-wave seismic velocity  
 128 ( $V_p$ ) model through the joint inversion of active-source P and PmP arrivals (see **Figs. 1a**  
 129 **and S1** for experiment setup). This model resolves the shallow (0–20 km) architecture of  
 130 accreted terranes and major faults while also capturing the geometry of the subducting

131 oceanic slab. We spatially link these structural constraints on upper-crustal heterogeneity  
132 to the along-strike slab bending and interseismic coastal uplift rate. Second, we quantify  
133 the mechanical controls by converting tomographic velocities into density and elastic  
134 moduli to drive numerical simulations. Integrating 1-D finite-difference slab flexure  
135 modeling with a viscoelastic kinematic framework, we assess the extent to which  
136 seismically derived backstop rigidity influences subduction zone geometry and coastal  
137 uplift. The correspondence between these rigidity-driven simulations and observational  
138 data serves to validate the governing role of upper-crustal structure in subduction  
139 dynamics.

## 140 RESULTS

### 141 Vp tomographic inversion

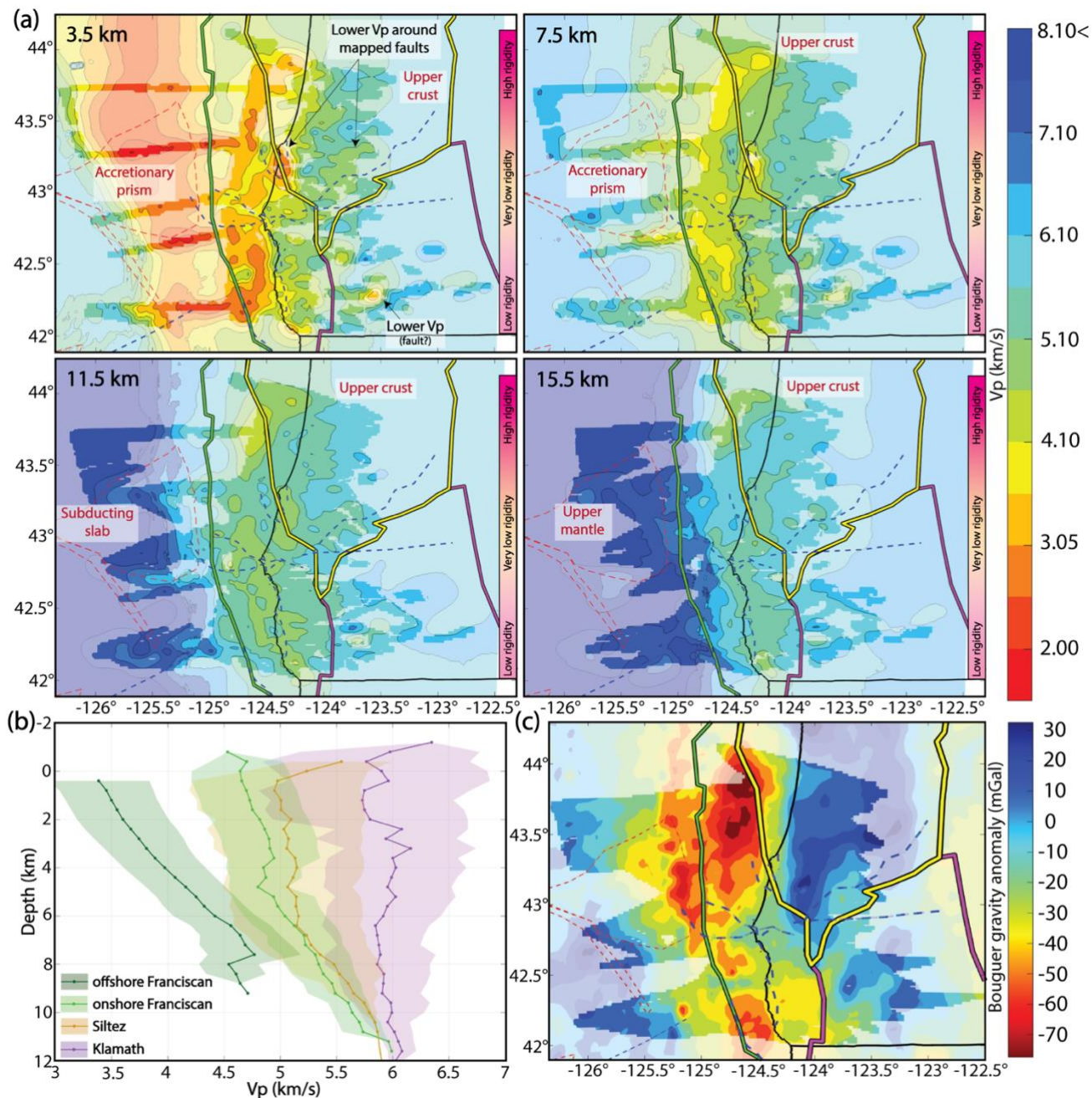
142 We modeled the shallow crustal structure (0 – 20 km) and slab Moho depth around  
143 offshore and onshore southern Oregon (42°N – 44°N) using a joint inversion of P and  
144 PmP arrivals (see **Materials and Methods** section for details). Supported by dense ray  
145 coverage and high derivative weight sum (DWS) values (**Fig. S2**), our modeling results in  
146 a robust (RMS misfit of 68.4 ms; **Fig. S3**), high-resolution model that effectively resolves  
147 5 – 10 km scale tectonic heterogeneities and sharp along-strike contrasts (see  
148 supplementary **Text S1** and **Fig. S4** for checkerboard test result).

149 Four primary components are readily identified in our tomographic model: the  
150 sedimentary accretionary prism, the accreted upper-crustal terranes, the subducting  
151 oceanic slab, and the underlying upper mantle (**Figs. 2** and **3**). The accretionary prism is  
152 characterized by the lowest velocities, with Vp values of ~3–5 km/s, reflecting its weak,  
153 sediment-dominated composition. Beneath the prism, the subducting slab exhibits Vp  
154 values of ~6.0–6.5 km/s west of the deformation front (trenchward), decreasing to ~5.0–  
155 6.5 km/s directly beneath the prism. At greater depths, the upper mantle is distinguished  
156 by significantly higher velocities, generally ranging from ~7.5 to 8.2 km/s. Together, these  
157 contrasts set the context and provide a framework for examining lateral variations within  
158 the upper crust and slab topography.

159 The tomographic model reveals pronounced along-strike velocity differences among the  
160 individual overlying terranes (**Figs. 2, 3, S5, and S6**). The Franciscan exhibits the lowest  
161 velocities and greatest variability. In this study, we divide the Franciscan terrane into its  
162 offshore and onshore parts because of their high Vp contrast (**Fig. 2a**). Vp ranges mostly  
163 from 3.0–5.5 km/s (mean: 3.4–4.75 km/s; **Fig 2b**) for offshore Franciscan and from 4.0–6.0  
164 km/s (mean: 4.5–5.7 km/s) for onshore Franciscan. In contrast, the Klamath unit displays  
165 the highest velocities and least variability, characterized by Vp values mostly between  
166 5.5–6.5 km/s (mean: 5.75–6.2 km/s). The Siletz terrane is intermediate, with Vp ranging  
167 between 4.5–6.5 km/s (mean: 5.0–5.9 km/s). The Vp structures of the accreted terranes  
168 align well with Bouguer gravity anomalies (**Fig. 2d**), lending confidence to the robustness  
169 of our results.

170 Our results also show intra-terrane Vp fluctuations that are driven by both inherent  
171 lithological diversity of each terrane (38, 39) and localized deformation structures such as  
172 faults (33). The presence of faults is notable in the southernmost extent of the Siletz  
173 terrane, where multiple crustal fault strands dissect through all terranes (**Fig. 1a**). These  
174 fault zones, concentrated between 42.75°N and 43.35°N latitude, exhibit localized velocity  
175 reductions (~1.0 km/s) relative to the surrounding crust. While these low-Vp anomalies  
176 are most pronounced at depths < 5 km, they persist even to depths of 15 km (**Fig. 2a**). Our  
177 tomographic results reflect a distinct three-way latitudinal division of the onshore terranes  
178 that may influence subduction mechanics. North of 43.5°N, the Siletz terrane exhibits a

179 relatively coherent Vp structure with velocities typically ranging from 5.0 to 6.5 km/s. In  
 180 contrast, the highly faulted region between 42.75°N and 43.35°N shows the lowest Vp,  
 181 ranging from 4.0 to 5.5 km/s. South of 42.75°N, the onshore Franciscan terrane is  
 182 characterized by a Vp range of 4.5–6.0 km/s, representing a velocity regime lower than the  
 183 coherent northern Siletz block but higher than the heavily faulted central zone.

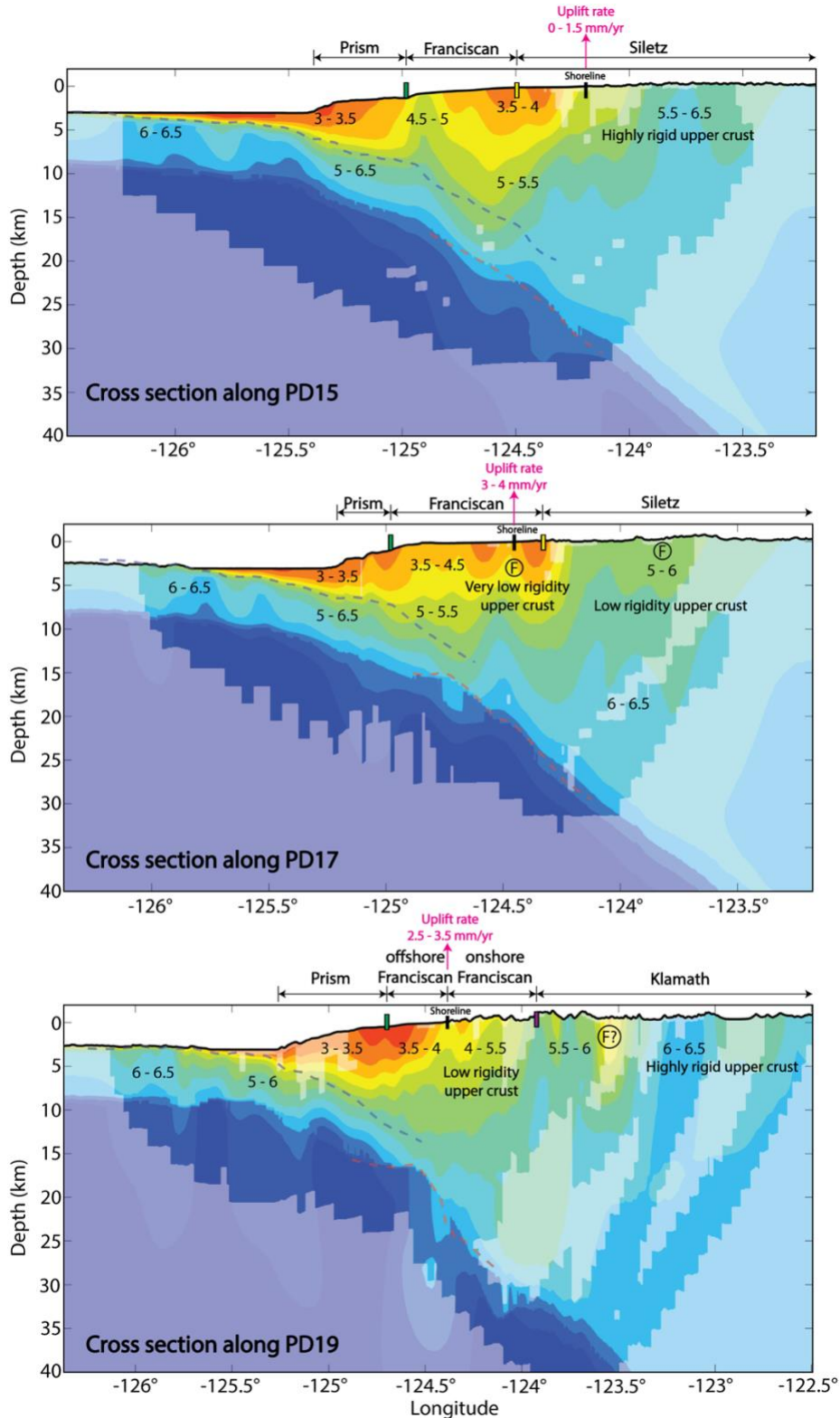


184  
 185 **Figure 2: 3-D velocity structure and gravity anomaly of the south-central CSZ.** (A) Map sections of the  
 186 high-resolution 3-D Vp tomographic model at selected depth intervals. Dark-toned regions indicate areas  
 187 with seismic ray coverage ( $DWS > 10$ ; **Fig. S2**), while light-toned regions represent unsampled volumes.  
 188 Tectonic features are shown with the same symbols as in **Figure 1**. See **Figure S2** in the supplementary  
 189 material for map sections every 2 km. (B) Average Vp-depth profiles for the accreted terranes in the study  
 190 area. Solid lines show mean Vp trends, small circles mark sampling depths from the 3-D model, and shaded  
 191 envelopes indicate standard deviation. (C) Bouguer gravity anomaly map from the USGS online repository  
 192 (37).

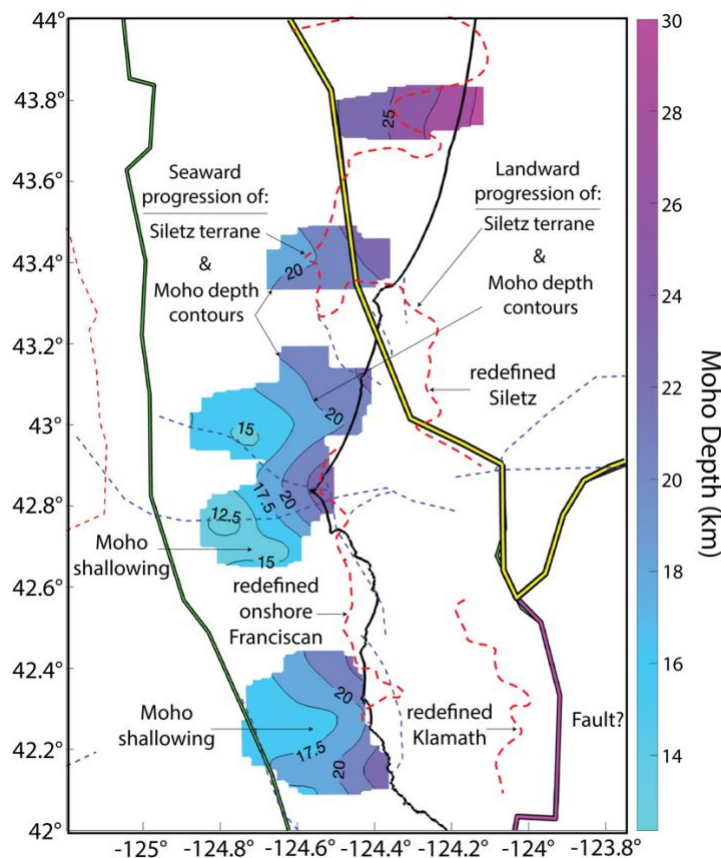
193 These findings highlight two primary modes of velocity distribution: terrane-specific  
194 averages reflecting bulk lithological properties, and along-strike fluctuations that  
195 transcend terrane boundaries due to localized deformation. We emphasize that these  
196 subsurface Vp distributions can be reliably estimated by integrating surface geology with  
197 established regional tectonic frameworks. For instance, while the northern and central  
198 Siletz regions are largely obscured by recent alluvial deposits (**Figs. 1b** and **S7**), regional  
199 geological constraints can predict a basaltic lithology (26, 39) with Vp between 5.5–6.5  
200 km/s for the unfractured northern block (40) and at least a 0.5–1.0 km/s velocity reduction  
201 within the highly faulted central regime (41). Farther south, Vp estimates based on surface  
202 geology for the onshore Franciscan and Klamath terranes closely align with our modeled  
203 Vp distributions (**Fig. S7b**), demonstrating that surface mapping can be a powerful proxy  
204 for characterizing upper-crustal structures.

205 While our overall Vp distribution is consistent with large-scale low-resolution terrane  
206 boundaries, which are mostly inferred from potential field data (24, 28), our high-  
207 resolution model can map the boundaries at a finer scale. To better constrain the  
208 boundaries, we generate terrane-specific similarity maps (**Fig. S8**) by comparing every 1-  
209 D Vp depth profile of the tomographic model against the terrane-averaged Vp depth  
210 profile (**Fig. 2b**). This analysis allows us to delineate the western boundary of the onshore  
211 terranes on a scale of 3-5 km resolution (**Fig. 4**). We also calculate the terrane-specific  
212 similarity index for the full 3-D tomographic volume, and using the 90% similarity  
213 contour (**Fig. S8**) for every depth interval, we extract the 3-D western or seaward  
214 boundary of the onshore accreted terranes. In **Figure 5**, we show this refined 3-D  
215 boundary of Siletz and onshore Franciscan as they form the shoreline-adjacent upper  
216 crustal terrane backstop in our study area. We identify a consistent seaward-dipping  
217 backstop that varies in geometry along strike. North of 43.3°N, the intact high-Vp Siletz  
218 block forms a gently dipping backstop (30°–40°). South of 43.3°N, however, the boundary  
219 steepens significantly (60°–80°) both adjacent to the lower-velocity faulted Siletz region,  
220 and along the onshore Franciscan terrane that dominates the nearshore regime south of  
221 42.9°N.

222 Inversion of PmP arrivals yields a high-resolution 3-D structure of the nearshore Moho  
223 interface (**Fig. 4**). The data provide a sampling density averaging 5–10 ray hits per km<sup>2</sup>. In  
224 the northern region (near 42.8°N), the modeled Moho beneath the Siletz terrane ranges in  
225 depth from ~22.5 to 30 km. To the south (near 42.2°N), the Moho beneath the Franciscan  
226 terrane ranges from ~17.5 to 20 km. Between 43°N and 43.6°N, the western boundary of  
227 the Siletz terrane extends seaward before retreating landward; Moho depth contours in this  
228 region deepen beneath the seaward extent and shallow under the landward retreat.  
229 Additionally, shallower Moho depths are observed to the southwest at latitudes  
230 corresponding to onshore upper-crustal faults.



**Figure 3: Across-strike cross sections of the 3-D shore-crossing  $V_p$  model of the CSZ.** Profiles follow offshore seismic shotlines and onshore dense nodal lines in the northern (PD15), central (PD17), and southern (PD19) study area. Colors and labeled contours indicate  $V_p$  values (km/s) using the same color scale as Fig. 2. Major tectonic boundaries, such as the accretionary prism, accreted terranes, shorelines, and known and inferred faults (F) are indicated along the top of each section. Observed coastal uplift rates from (30) are also shown on each profile. The blue dashed lines show the slab top from (32) and the red dashed lines show slab Moho from our PmP inversion results (Fig. 4). Inferred relative changes in upper crustal rigidity based on the along-strike seismic velocity changes are labelled.



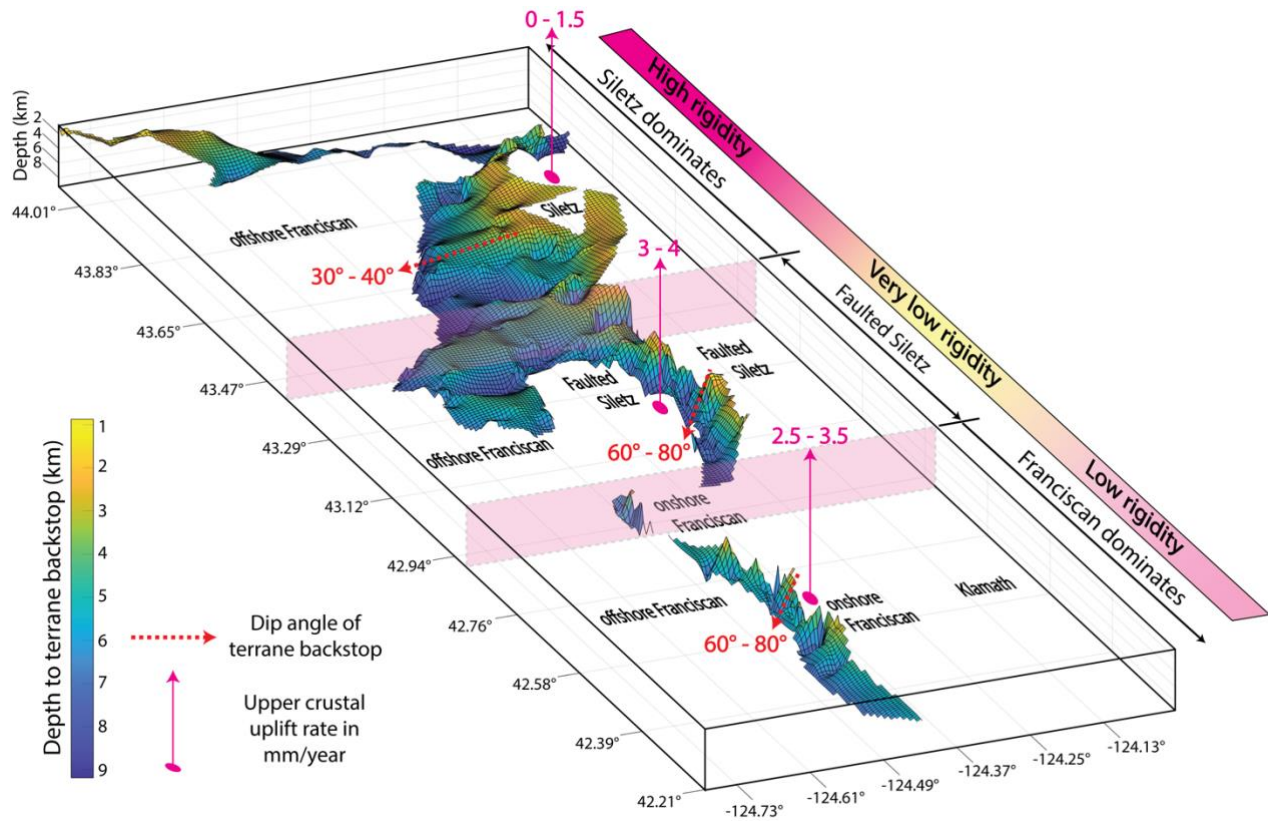
**Figure 4: Color-filled contours of Moho depth from the inversion, shown only where PmP reflections sample the interface.** Tectonic features (terrane boundary, faults, and propagator wakes) follow the symbology in Fig. 1. Red dashed lines mark the redefined western boundaries of the onshore terranes, inferred where our similarity analysis shows 90% similarity to the average Vp-depth profile of each terrane (Fig. 2b).

### Correlation of Vp structure with indicators of subduction mechanics

In the south-central CSZ, the forearc transitions from the Siletz terrane in north, composed of thick intrusive and volcanic rocks, to the Franciscan and Klamath terranes in south, dominated by clastic sediments, mélanges, and amalgamated oceanic and volcanic arc assemblages (Fig. 1b). These lithological contrasts manifest as distinct variations in crustal density and, consequently, the along-strike Vp structure of the overriding plate (Figs. 2 & 3). Here, we demonstrate how this heterogeneous upper-crustal Vp structure directly correlates with multiple independent indicators of mechanical segmentation, specifically subducted plate topography, coastal uplift rates, onshore relief, and upper-crustal backstop geometry.

First, we observe a correlation between along-strike variations in upper-crustal Vp and Moho depth. Broadly, the Moho is deeper beneath the high-velocity Siletz terrane and shallower beneath the lower-velocity faulted Siletz and onshore Franciscan terrane (Figs. 4, 5, 6, and 7). North of 43.25°N, the Moho deepens beneath the thickened Siletz block. South of this latitude, where the Siletz terrane retreats landward to be replaced by the Franciscan and Klamath terranes, crustal faults complicate the velocity structure; notably, low-Vp zones associated with the WSF and CVF coincide with localized Moho shallowing. This correlation persists at finer scales, where Moho depth contours closely track the seaward and landward extent of the high-Vp Siletz terrane (Fig. 4).

265 Furthermore, the modeled along-strike variation in upper-crustal Vp correlates strongly  
 266 with coastal uplift rates, exhibiting a distinct inverse relationship (Figs. 3, 5, and 6). North  
 267 of 43.25°N, high Vp within the Siletz terrane corresponds to relatively low uplift rates  
 268 (0.5–2 mm/yr). Conversely, south of 43.25°N, a sharp decrease in nearshore Vp,  
 269 associated with the faulted Siletz and Franciscan assemblages, coincides with an abrupt  
 270 increase in uplift to 2.5–3 mm/yr. This inverse pattern persists southward: a local increase  
 271 in Vp near 42.75°N aligns with a modest decline in uplift, while the return to low Vp  
 272 south of ~42.4°N is matched by higher uplift rates.



273  
 274 **Figure 5: 3-D geometry of the western boundary of the nearshore terranes** (Siletz in the north and  
 275 Onshore Franciscan in the south) from the similarity index calculation through the entire model volume (see  
 276 **Materials and Methods** and **Fig. S8** for more details).

277 Topography provides an additional, independent surface expression of this mechanical  
 278 segmentation. Across the along-strike transition from the high-Vp Siletz terrane to the  
 279 low-Vp onshore Franciscan terrane, the maximum onshore relief increases markedly: peak  
 280 elevations in the Siletz-dominated segment are ~0.6-0.8 km lower than in the Franciscan  
 281 segment (Figs. 1a and S9). This first-order topographic step is spatially coincident with  
 282 the shift to lower Vp and higher coastal uplift rates, consistent with stronger interseismic  
 283 shortening and long-term vertical growth in the lower-Vp forearc.

284 A correlation also exists between the backstop angle of nearshore terranes and the Vp of  
 285 the nearshore upper crust. 3D mapping of these boundaries (Fig. 5) reveals that the high  
 286 Vp Siletz terrane exhibits a gently dipping backstop (30°-40°). In contrast, the lower Vp  
 287 onshore Franciscan terrane is characterized by a significantly steeper backstop (60°-80°).

288 The observed correlations between Vp structure and various mechanical indicators suggest  
 289 that segmentation in upper crustal density and rigidity drives subduction dynamics. Based  
 290 on these observations, we subdivide the south-central CSZ upper crust into three  
 291 mechanical domains (Fig. 6). In the north, the intact, high-Vp Siletz terrane correlates

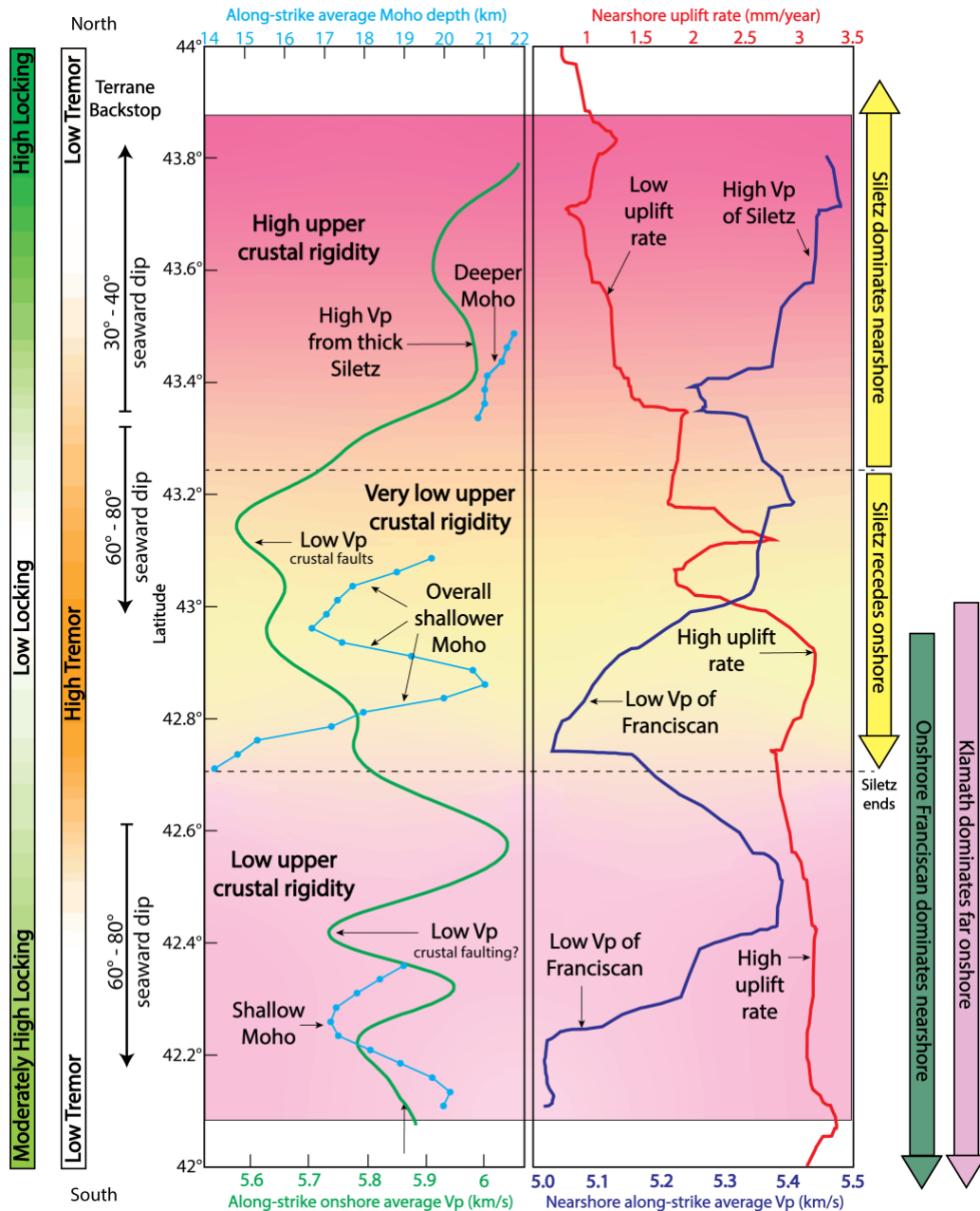
292 with a deeper Moho and minimal uplift, defining a high-rigidity domain. Central to the  
293 study area, the heavily faulted Siletz transitional zone exhibits the lowest Vp values, a  
294 shallow Moho, and peak uplift rates, forming a very low-rigidity domain. Further south,  
295 the nearshore Franciscan assemblage displays moderate Vp, a shallow Moho, and high  
296 uplift, representing a low-rigidity domain.

### 297 **Conceptual model for subduction mechanics**

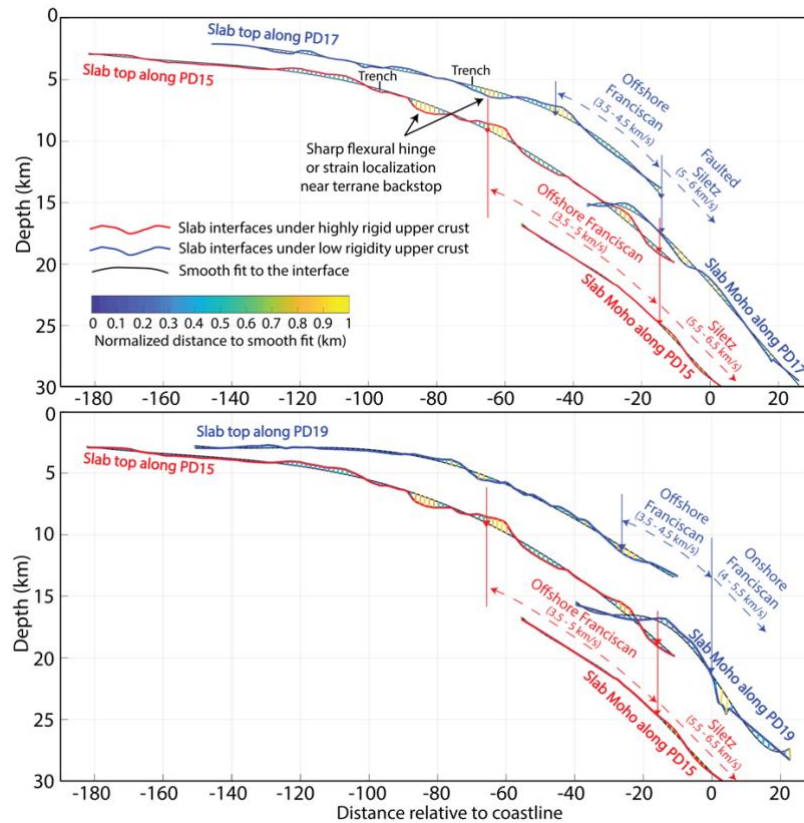
298 To test the hypothesis that upper-plate strength controls nearshore subduction mechanics,  
299 we conceptualize a numerical model varying only crustal properties reflecting density and  
300 rigidity to predict slab topography and onshore uplift (**Fig. 8**). First, we show that high-  
301 density blocks impose a greater vertical lithostatic load, effectively pushing the slab to  
302 greater depths compared to the lower-density blocks (42, 43). Secondly, our results  
303 indicate that upper-plate rigidity modulates the mechanical response to interseismic  
304 horizontal shortening, creating distinct coastal uplift patterns between high- and low-  
305 rigidity terranes.

306 Regarding the first mechanism, we observe that peak slab undulation spatially correlates  
307 with the seaward terminus of the onshore terranes (**Fig. 7**), indicating maximum flexural  
308 response at the primary across-strike Vp gradient. This flexure is likely a loading-  
309 dominated response, as downward deflection begins seaward of the terrane edge alongside  
310 localized Vp reductions (**Fig. 3**) indicative of bending-fault hydration (44, 45).

311 Secondly, the structural integrity of the overlying terrane controls the resulting strain  
312 distribution and uplift. Interseismic uplift reflects a superposition of recoverable elastic  
313 strain accumulation and permanent plastic deformation (6, 21, 46). At this late stage of the  
314 megathrust cycle in CSZ, elasto-plastic loading dominates over mantle relaxation as the  
315 primary driver of vertical motion (21). While seismically derived elastic moduli constrain  
316 the recoverable strain component, the magnitude of permanent deformation depends on  
317 the rheological competency (6) and geometry of the backstop (46). The high-rigidity Siletz  
318 backstop limits landward stress transfer, and its gently dipping geometry forces strain to  
319 localize offshore, resulting in minimal coastal uplift. In contrast, the low-rigidity  
320 Franciscan backstop has a lower yield strength, allowing efficient landward stress  
321 propagation. This facilitates permanent internal shortening and a steeper deformable  
322 backstop, manifesting as the significantly higher coastal uplift rates observed geodetically.  
323 Ultimately, the rheological contrast between the offshore wedge and the onshore backstop  
324 acts as the primary mechanical filter converting plate convergence into upper crustal  
325 vertical growth.



326  
 327 **Figure 6: Different trends showing correlation between geologic/tectonic features and geophysical**  
 328 **observations along-strike of the subducting slab, highlighting their north-south variations.** Left panel:  
 329 average onshore Vp at 9 km depth (green), calculated by averaging onshore values within each latitude  
 330 interval of the tomographic model and applying a Gaussian mean smoothing. Also shown is the along-strike  
 331 Moho depth averaged within latitudinal intervals. Right panel: uplift rate along shoreline from (30) (red),  
 332 averaged within each latitude interval, and then compared with nearshore average Vp (blue). The nearshore  
 333 Vp values were computed from 7 – 9 km depth at uplift rate measurement sites and smoothed using a  
 334 Gaussian mean across latitude intervals. See Fig. S10 in the supplementary material for the calculation of  
 335 the Gaussian smoothed mean.



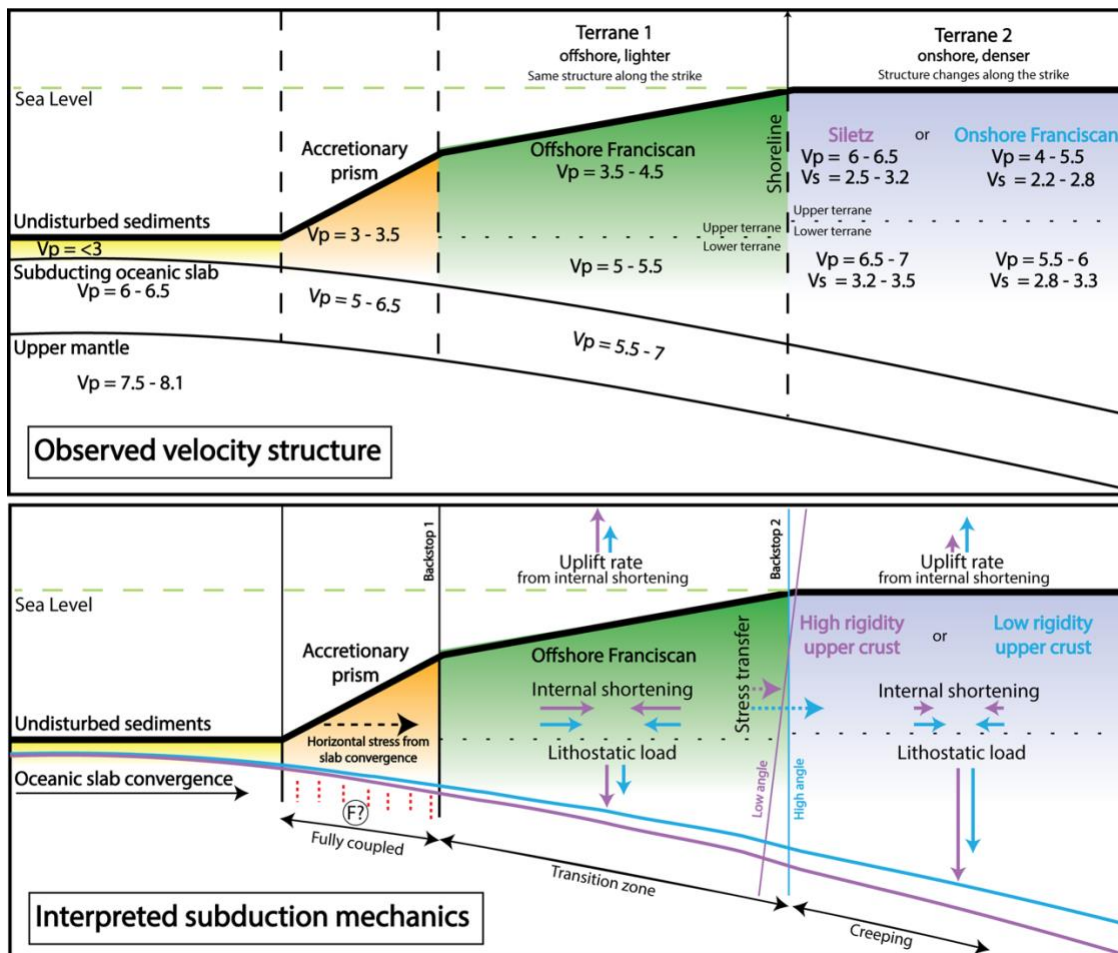
**Figure 7: Depth profiles of the top and bottom of the subducting slab along offshore seismic shotlines.** The profiles are shown for the northern high-rigidity segment (PD15; red) and southern low-rigidity segments (PD17 and PD19; blue). Profiles are plotted as depth versus distance relative to the coastline, with negative values offshore and positive values onshore. Solid colored curves mark the interpreted slab top and bottom (or Moho) along each profile, while black curves show a smooth reference fit to the interface used to quantify deviations in slab geometry. Color shading along the slab interfaces denotes the normalized distance to the smooth fit (0 - 1), highlighting zones of localized curvature and departures from long-wavelength bending. Boundaries of upper crustal features (trench and terranes) are indicated along the profiles.

### Numerical simulation of subduction mechanics

To test whether along-strike variations in upper-crustal rigidity are sufficient to explain the observed segmentation in slab geometry and coastal uplift, we conducted forward mechanical simulations constrained by our tomographic velocity structure (**Fig. 9**). We converted seismic velocities into density and elastic moduli, evaluating the high-rigidity Siletz and lower-rigidity Franciscan endmembers while holding all other subduction parameters (convergence rate, slab age, mantle density, and far-field boundary conditions such as slab pull) constant. To account for velocity uncertainties, we employed a stochastic Monte Carlo approach (see **Materials and Methods** for details).

First, we tested the effect of upper-plate density (which scales directly with  $V_p$ ) on nearshore slab geometry using a 1-D finite-difference flexural model. The simulations show that this difference in vertical loading alone deflects the slab approximately 2 km deeper (average of all Monte-Carlo realizations) beneath the high-density Siletz terrane compared to the lower-density Franciscan terrane (**Fig. 9**). This matches the magnitude and spatial pattern of our observed Moho depths (**Figs. 4, 5, and 6**), confirming that upper-plate density contrasts mechanically reproduce the along-strike segmentation in slab bending without invoking changes in slab buoyancy or plate kinematics.

Next, we evaluated interseismic coastal uplift using a kinematic viscoelastic formulation to capture both instantaneous elastic strain accumulation and time-dependent viscous deformation (6, 21, 46, 47). A purely elastic simulation produced only a modest uplift contrast between terranes ( $\sim 0.3$  mm/yr, or  $\sim 20\%$  of the observed difference) (Fig. 9). In contrast, incorporating viscoelastic strain partitioning fully reproduced the observed  $\sim 2$  mm/yr uplift contrast. Achieving this required a difference in Maxwell relaxation times:  $\sim 250$  years for the compliant Franciscan terrane versus  $\sim 50,000$  years for the rigid Siletz terrane.

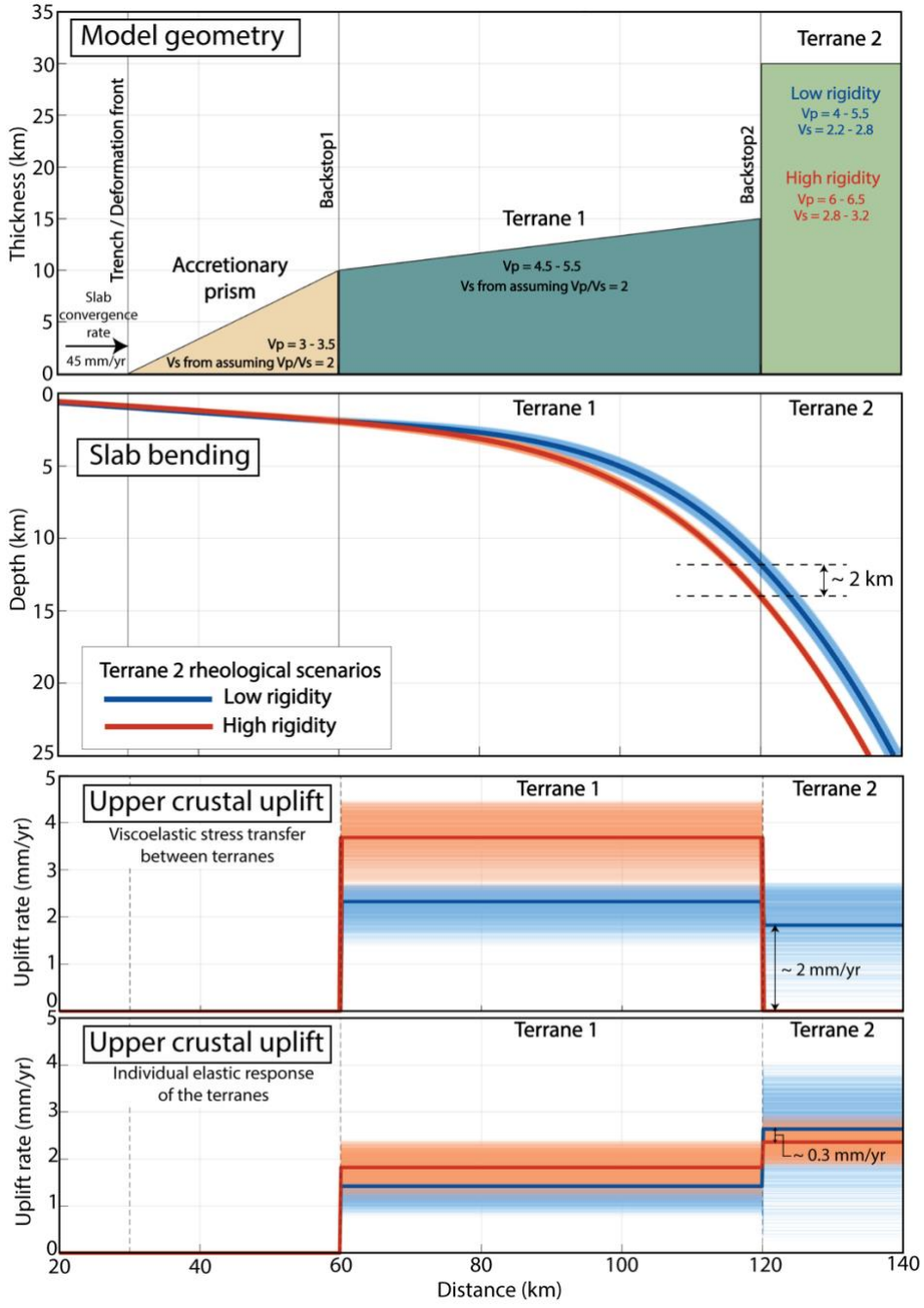


**Figure 8: Conceptual model linking observed seismic velocity structure to along-strike variations in subduction mechanics.** Top section shows an idealized across-strike cross-section illustrating the seismic velocity structure resolved by the shore-crossing tomography. Shaded regions indicate major tectonic units, including the accretionary prism, offshore Franciscan (Terrane 1), and onshore terranes (Terrane 2), with representative  $V_p$  and  $V_s$  ranges annotated for each unit. The onshore domain includes either high-velocity Siletz crust or lower-velocity onshore Franciscan crust, and upper–lower terrane subdivisions are indicated by dashed lines. Bottom section shows the corresponding schematic of the mechanical elements inferred from tomographic results and considered in the analysis. They include convergence direction, slab interface, lithostatic loading, internal shortening within forearc terranes, stress transfer across the backstop, backstop geometry, and uplift resulting from internal shortening. Arrows denote directions of either stress transfer between terranes or the rate of shortening and vertical motion.

This result shows that in the high-rigidity scenario, the backstop acts as a mechanically rigid buttress that resists internal deformation (0 mm/yr uplift), forcing strain to localize within the weaker offshore wedge. Conversely, in the low-rigidity scenario, the onshore backstop is compliant enough to absorb tectonic stress through distributed internal shortening, driving significant nearshore uplift ( $\sim 1.8$  mm/yr). Together, the numerical

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simulations (Fig. 9) confirm that upper-crustal rigidity controls subduction mechanics through two complementary pathways: density contrasts impose variable vertical loads that modulate slab bending, while rigidity-dependent rheology governs how interseismic shortening is partitioned, controlling the amplitude of coastal uplift.



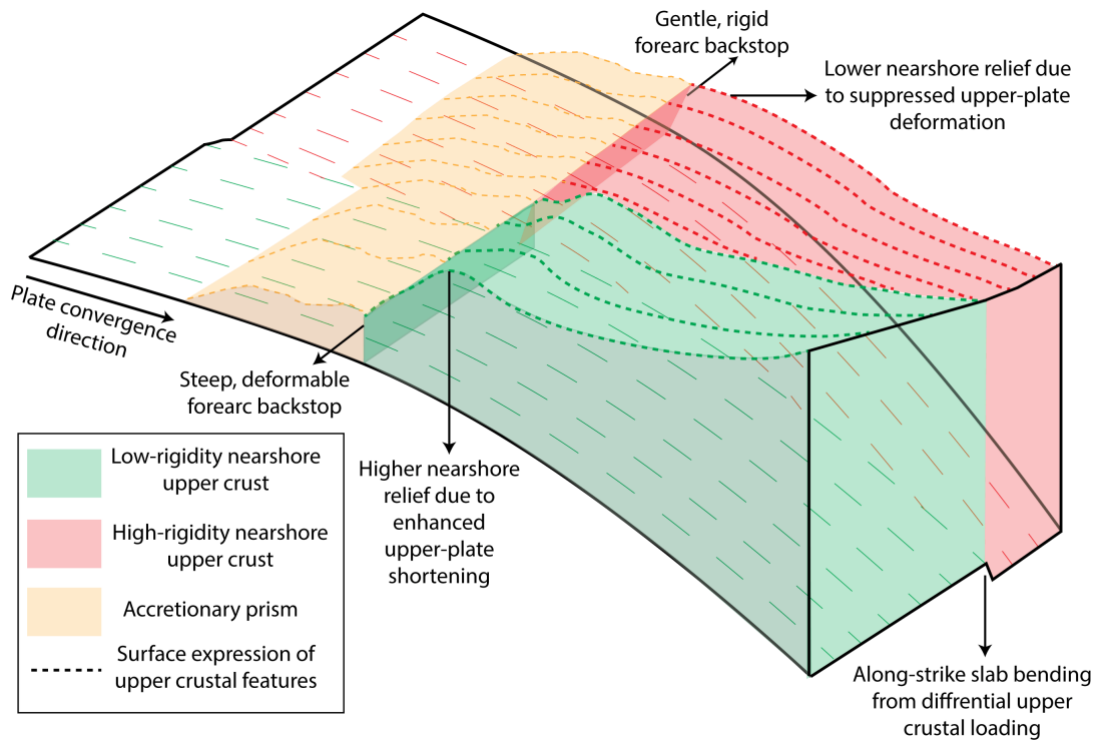
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**Figure 9: Numerical simulation setup and modeled responses for slab bending and upper-crustal uplift.** The top panel shows the model geometry used in the numerical experiments. The forearc is divided into an accretionary prism, Terrane 1 (offshore forearc), and Terrane 2 (onshore forearc), separated by idealized backstops. Representative  $V_p$  and  $V_s$  ranges assigned to each unit are shown, with  $V_s$  inferred assuming  $V_p/V_s = 2$  where noted. Slab convergence rate and trench/deformation front location are indicated. The second panel shows modeled slab bending beneath Terrane 1 and Terrane 2 for two rheological end-member scenarios assigned to Terrane 2: low rigidity (blue) and high rigidity (red). The third panel shows modeled upper-crustal uplift rates that include viscoelastic stress transfer between terranes. The bottom panel illustrates upper-crustal uplift rates predicted from the individual elastic response of each terrane, without viscoelastic stress transfer. Solid lines show the mean result, with shaded envelopes representing the spread of Monte Carlo realizations.

## DISCUSSION

### Impact of upper crustal heterogeneity on subduction mechanics

Our tomographic model (Figs. 2 and 3) resolves a forearc whose mechanical architecture is set by inherited lithology, fault damage, and fluid distribution rather than by depth alone, consistent with along-strike segmentation documented at other convergent margins (19, 20). The geologically heterogeneous south-central CSZ forearc exemplifies this process (4, 48). Three domains emerge: a coherent high-Vp Siletz block, a faulted low-Vp transitional zone, and a moderate-Vp onshore Franciscan segment (Figs. 2a and 6). Each domain exhibits a distinct backstop geometry (Figs. 4 and 5), ranging from a gently dipping rigid buttress (30°–40°) in the north to steep, deformable boundaries (60°–80°) in the south, mirroring the static-versus-dynamic backstop distinction documented in other accretionary systems (28, 50). The terrane-scale Vp hierarchy (Fig. 2b) is independently corroborated by surface geology (Fig. 1b) through empirical velocity–lithology relationships (40, 49) and supported by Bouguer gravity (Figs. 2c and S7), together providing the mechanical framework for interpreting along-strike variations in subduction dynamics.



**Figure 10: Conceptual 3-D model illustrating the mechanical effects of along-strike variations in nearshore upper-crustal rigidity.** Shaded volumes represent low-rigidity (green) and high-rigidity (red) nearshore upper crust, and the accretionary prism (yellow). In low-rigidity domains, a steep, deformable forearc backstop permits enhanced upper-plate shortening, producing higher nearshore relief and reduced slab loading. In high-rigidity domains, a gentle, rigid backstop suppresses upper-plate deformation, resulting in lower nearshore relief and increased loading of the subducting slab. Dashed lines denote the surface expression of upper-crustal structures, and the curved basal surface illustrates the subducting slab.

The modeled along-strike heterogeneity in upper-crustal terranes spatially correlates with multiple proxies of subduction mechanics, including coastal uplift and subsidence rates reflected by geodetic and geomorphic observations (6, 47), and slab geometry with its bending (32, 51). Also, along-strike segmentation in ETS recurrence intervals and tremor density relates to forearc terrane distribution, suggesting upper crustal rheology impacts stress accumulation and release along deeper plate interface (4, 31). In south-central CSZ,

434 this segmentation is also expressed in topography: peak elevations are  $\sim 0.6$ – $0.8$  km higher  
435 in the low- $V_p$  onshore Franciscan domain than in the high- $V_p$  Siletz domain (**Fig. 1a** and  
436 **S9**), indicating greater long-term vertical growth where the upper plate is more  
437 deformable.

438 Despite this evidence, geodetic inversions typically assume a laterally homogeneous upper  
439 plate with uniform elastic properties (e.g., shear and Young's moduli of  $\sim 40$  and  $\sim 100$   
440 GPa, respectively, with a constant Poisson's ratio of  $\sim 0.25$ ), ignoring crustal architectural  
441 and compositional variance (7–10). Our tomographic results, however, reveal a  $\sim 30$  GPa  
442 difference in Young's modulus and  $\sim 0.06$  in Poisson's ratio between the rigid Siletz and  
443 the compliant onshore Franciscan terranes (**Fig. S12**). Differences of this magnitude are  
444 mechanically significant for megathrust locking and will alter the partitioning of  
445 interseismic deformation and bias geodetically inferred coupling patterns even under  
446 identical fault slip conditions (12). The systematic mechanical segmentation our modeling  
447 suggests informs the nearshore subduction dynamics in two distinct pathways: the  
448 differential lithostatic loading driving the along-strike variability of nearshore slab depth  
449 (42, 43, 52), and the rigidity difference controlling the partition of stress and strain from  
450 plate convergence between elastic strain accumulation and permanent (plastic) vertical  
451 deformation along the coast (6, 21, 46, 47).

452 Our numerical modeling confirms that density contrasts alone reproduce the observed  $\sim 2$   
453 km along-strike variation in nearshore slab depth through differential lithostatic loading,  
454 without requiring changes in slab buoyancy or plate kinematics (**Fig. 9**). Capturing the full  
455 amplitude of coastal uplift, however, requires incorporating viscoelastic strain  
456 partitioning. While pure elastic models predict  $\sim 20$ – $25\%$  of the observed uplift contrast,  
457 viscoelastic simulations successfully reproduce the full  $\sim 2$  mm/yr difference (**Fig. 9**). In  
458 these simulations, horizontal shortening is distributed between recoverable elastic strain  
459 and time-dependent viscous deformation. Uplift rates are not prescribed but emerge from  
460 the time-dependent redistribution of tectonic force between mechanically coupled forearc  
461 blocks under constant convergence (**Fig. S11**). Rather than just resisting horizontal stress,  
462 the lower-rigidity backstops facilitate permanent internal shortening.

463 To reduce the dependency of uplift-rate simulation on specific numerical formulation, we  
464 additionally derived a closed-form elastic estimate using linear constitutive relations under  
465 plane-strain conditions (Supplementary **Text S3**). Despite neglecting viscous deformation  
466 and time-dependent relaxation, the elastic solution predicts a substantial uplift-rate  
467 contrast ( $\sim 0.5$  mm/year), corresponding to  $\sim 25\%$  of the observed along-strike difference.  
468 This indicates that upper-crustal elastic rigidity by itself can explain a partial but  
469 substantial portion of the uplift segmentation. However, when viscoelastic strain  
470 partitioning is incorporated, the model reproduces the full  $\sim 2$  mm/yr uplift contrast  
471 between high- and low-rigidity segments. Achieving this requires a large contrast in  
472 Maxwell relaxation time between terranes that is  $\sim 250$  years for the low-rigidity  
473 Franciscan domain and  $\sim 50,000$  years for the high-rigidity Siletz domain (a difference  
474 exceeding two orders of magnitude). Because Maxwell time scales with the ratio of  
475 effective viscosity to shear modulus, this contrast implies fundamentally different  
476 capacities for time-dependent strain accommodation within the forearc.

477 Such rheological contrasts are physically plausible for subduction settings (53). In  
478 exhumed subduction interface and *mélange* shear zones, which are appropriate analogs for  
479 weak sediment-dominated forearc materials, the compiled and field based estimates  
480 indicate effective viscosities in the range of  $10^{18}$ – $10^{20}$  Pa·s (54). For typical crustal shear  
481 moduli (20 – 40 GPa), these values naturally correspond to Maxwell times spanning a few  
482 hundred years ( $\sim 100$  – 300 years), consistent with our value of 250 years for low-rigidity

483 crust and supporting the interpretation that permanent (time-dependent) deformation can  
484 be efficient in the onshore Franciscan terrane. In contrast, compositionally strong crustal  
485 domains, such as the dry mafic crust, can sustain substantially higher effective viscosities,  
486 often exceeding  $\sim 10^{21}$  Pa·s (55, 56). For shear moduli of 40 – 70 GPa, appropriate for  
487 coherent mafic crust, viscosities of  $10^{22}$ - $10^{23}$  Pa·s correspond to Maxwell relaxation time  
488 of  $10^4$ - $10^5$  years. These values are consistent with our high-rigidity end member ( $\sim 50,000$   
489 yr), implying that a Siletz-like mafic backstop can behave effectively elastically over  
490 many earthquake cycles, while adjacent weak forearc domains relax on interseismic to  
491 century timescales.

### 492 **Implications for geodetic locking models**

493 Our results show that reliability of geodetically inferred megathrust locking depends  
494 systematically on overriding plate mechanics. In high-rigidity domains like the intact  
495 Siletz terrane, the forearc acts as a long-lived elastic buttress with negligible internal  
496 shortening. As a result, onshore surface velocities closely reflect elastic loading from the  
497 megathrust, providing a comparatively direct and robust constraint on the locking state.  
498 Conversely, beneath low-rigidity forearc domains, surface deformation is a complex  
499 superposition of elastic strain accumulation and permanent internal shortening.

500 Similar geodetic signals can be produced by markedly different combinations of  
501 megathrust locking and upper-plate rheology. More complications can arise when a  
502 significant part of interseismic vertical motion is retained over multiple earthquake cycles,  
503 rather than being fully recovered by coseismic and postseismic slip (47). Also, long-term  
504 coastal signal can depend on inelastic strain localization (e.g., occur within weak material  
505 adjacent to a rigid backstop, or via wedge faulting and plastic shortening), producing  
506 permanent uplift that pure elastic kinematic models fail to predict (6, 21). In addition to  
507 elasto-plastic loading of the sedimentary wedge (21, 46), other processes, such as  
508 sediment underplating, seamount subduction, tectonic erosion, and changing frictional  
509 coupling can also drive or modulate coastal uplift (57). Another limitation can be that slab  
510 dip variation leading to a change in downdip width (and thus surface area) of the locked  
511 interface can alter the integrated plate coupling force and the magnitude of horizontal  
512 compressive tractions transmitted into the upper plate (58). Furthermore, we did not  
513 explicitly vary the accretionary wedge geometry between segments. Yet wedge taper,  
514 basal dip, and the partitioning between outer- and inner-wedge deformation can vary  
515 substantially along strike (46). Nonetheless, even under these simplified conditions, our  
516 models demonstrate that upper-crustal rigidity contrasts alone provide a physically  
517 consistent explanation for the observed along-strike differences in slab depth and coastal  
518 uplift. Even when upper mantle relaxation is considered (8), the magnitude of relaxation-  
519 driven uplift is not independent of upper-plate structure, as its density contrasts modulate  
520 the buoyancy and stress transmitted to the mantle. Therefore, denser, more mafic terranes  
521 suppress relaxation-driven uplift relative to lower-density sedimentary forearc regions  
522 (Supplementary **Text S4**).

523 Reconciling near-trench deformation, coastal uplift, and along-strike locking segmentation  
524 requires integrating seafloor geodesy (59, 60). We show that onshore geodetic  
525 measurements on rigid forearc terranes remain spatially distant and minimally affected  
526 from updip portion of the megathrust, where locking gradients, slow slip, and stress  
527 heterogeneity are expected to be strongest. Also, since the mechanically weak forearc can  
528 absorb a substantial fraction of interseismic shortening, onshore geodesy alone cannot  
529 distinguish between reduced locking and enhanced upper plate compliance (**Fig. 10**).  
530 Integrating offshore geodesy with spatially variable upper-plate structure offers a path  
531 toward physically consistent locking models. Where high-resolution tomography is

532 unavailable, mapped lithologic assemblages and terrane boundaries offer a practical proxy  
533 for prescribing laterally variable elastic properties in geodetic models. This approach  
534 reduces bias by accounting for spatial differences in upper-plate mechanical response,  
535 rather than misattributing all surface deformation variability entirely to changes in  
536 megathrust friction.

### 537 **Implications for megathrust rupture**

538 Beyond shaping slab flexure and interseismic uplift, upper-plate rigidity contrasts can  
539 significantly influence coseismic rupture segmentation, slip magnitude, and tsunami  
540 potential. Variations in forearc composition and elastic strength impose persistent along-  
541 strike controls on megathrust coupling (61, 62). Denser, mechanically robust overriding  
542 plates accumulate elastic strain more efficiently, promoting stronger locking and larger,  
543 coherent coseismic slip patches—contrary to predictions from some uniform locking  
544 models (7). Conversely, weaker or heterogeneous domains can promote interseismic creep  
545 and distributed deformation, limiting stress accumulation. Applied to Cascadia, this  
546 implies that weaker forearc segments will likely favor partial rupture, yield reduced slip  
547 amplitudes, or act as persistent barriers to rupture propagation during a future great  
548 earthquake (32, 63).

549 Furthermore, lateral and depth-dependent variations in upper-plate rigidity directly  
550 modulate shallow rupture behavior and tsunami generation, even in the absence of  
551 changes in fault friction (64). Compliant upper plates favor larger shallow slip, slower  
552 rupture velocities, and enhanced slip-rate amplification (12). This translates directly into  
553 greater seafloor deformation and heightened tsunami potential. Consequently, models  
554 assuming an overly rigid, uniform forearc systematically underestimate shallow  
555 deformation and tsunami amplitudes. Ultimately, accurately representing spatially variable  
556 upper-plate elastic structure is essential for realistic earthquake rupture modeling and  
557 tsunami hazard assessment, as treating the overriding plate as mechanically uniform  
558 obscures critical controls on shallow megathrust behavior.

## 559 **MATERIALS AND METHODS**

### 560 **Seismic tomographic inversion**

561 We develop a 3-D high resolution shore crossing P-wave velocity ( $V_p$ ) model by jointly  
562 inverting active source travel times recorded offshore and onshore. The data combine  
563 CASIE21 marine air-gun shots (32) recorded by ocean bottom seismometers (OBS) (65)  
564 with wide-angle refractions recorded by Cascadia2021 onshore nodal array (5). For this  
565 study we use 11 CASIE21 shot lines recorded on 345 stations (6 permanent PNSN  
566 broadband stations, 28 OBS, and 311 temporary nodal stations), yielding 28,191 shot  
567 gathers (**Fig. 1a**). We manually pick 617,637 arrivals in total, including 598,082  
568 first-arriving P phases and 19,557 PmP reflections from the oceanic Moho, providing  
569 dense multi-azimuth ray coverage from the accretionary prism to ~100 km onshore (**Fig.**  
570 **S2**). Travel times are picked on reduced-time record sections using the Matlab-based  
571 tlPicker package and assigned phase-dependent uncertainties (5). We pick Pg/Pn first  
572 arrivals where separable on shore-crossing profiles and PmP reflections where coherent;  
573 along-strike gathers where Pg and Pn are difficult to distinguish are treated as generic P  
574 first arrivals. Average picking uncertainties are 41 ms (Pg), 35 ms (Pn), 62 ms (P), and 63  
575 ms (PmP). Data quality varies systematically with environment: near-shore stations are  
576 noisier due to ocean-wave microseisms, whereas inland nodal stations typically allow  
577 picks on ~40–60% of shots; offshore OBS record sections generally yield fewer reliable  
578 picks (<40% of shots) (5).

579 To improve phase identification and stabilize the nonlinear inversion, we use forward  
580 modeling to generate synthetic travel times from a suite of plausible starting models. The  
581 preferred initial  $V_p$  model is laterally and vertically smooth, with  $V_p$  increasing from  $\sim 2$ –  
582 5.5 km/s in the accretionary prism to  $>5.5$  km/s in the Siletz terrane. We embed a  
583 6-km-thick oceanic crust with  $V_p \sim 6.1$ – $6.8$  km/s and prescribe an upper-mantle  $V_p$  of 8.1  
584 km/s beneath the slab (**Fig. S12**). We apply a convolution with a moving average from the  
585 top depth to the bottom of the model to make the model vertically smooth. We use a  
586 smooth slab geometry combining high-resolution offshore CASIE21 basement data and  
587 low-resolution onshore Moho model (66). We also perform a “Pg-fit” preliminary  
588 inversion (Pg only, without slab/mantle) to refine upper-crustal velocities, then re-insert  
589 slab and mantle structure before the final joint inversion of all phases.

590 Tomographic inversion follows the travel-time tomography formulation of (67), which is  
591 well suited to strongly heterogeneous amphibious data sets (5, 68). We parameterize the  
592 model in slowness on a 3-D grid with 800-m node spacing in  $x$ ,  $y$ , and  $z$ . Bathymetry and  
593 topography are incorporated by vertically shearing grid columns to honor local relief.  
594 Predicted travel times are computed using a shortest-path (graph-theory) solution to the  
595 two-point ray-tracing problem, which efficiently approximates first-arrival ray paths in  
596 complex 3-D velocity fields. Travel times through the water column are computed on a  
597 finer  $50 \times 50$ -m horizontal grid using a constant water velocity of 1.49 km/s to reduce  
598 sensitivity to bathymetric roughness. The inverse problem is linearized to relate  
599 travel-time residuals (observed minus predicted) to perturbations in model slowness, and,  
600 when PmP is included, to perturbations of the oceanic Moho interface (69). We solve for  
601 slowness (and interface) updates using damped least squares, minimizing a functional that  
602 balances (i) data misfit weighted by pick uncertainties, (ii) a penalty term that limits  
603 deviation from the prior model, and (iii) separate horizontal and vertical smoothing  
604 constraints. The inversion is iterated to account for ray-path changes, using a creeping  
605 strategy so that regularization acts on the cumulative perturbation after each iteration.  
606 After each inversion, we examine phase-specific residuals, repick or remove inconsistent  
607 arrivals, and continue iterating until the RMS residual converges ( $\sim 50$  ms), comparable to  
608 the typical picking uncertainty.

609 Model coverage and resolution are evaluated using the derivative weight sum (DWS),  
610 which provides a quantitative measure of the cumulative sensitivity of the travel-time data  
611 to velocity perturbations at each model node (**Fig. S2**). DWS is defined as the sum of the  
612 absolute partial derivatives of all travel times with respect to slowness at a given node and  
613 therefore reflects both ray density and raypath geometry. High DWS values indicate  
614 regions that are strongly constrained by the data through multiple ray paths sampling the  
615 node from different directions, whereas low DWS values indicate weakly constrained  
616 regions regardless of inversion regularization. Based on the distribution of DWS values  
617 and consistency with previous active-source tomographic studies, we restrict geological  
618 interpretation to regions with  $DWS \geq 10$ , which correspond to areas of robust ray  
619 coverage.

620 The model's resolution was evaluated using a checkerboard test that involved inverting  
621 synthetic travel times through a perturbed  $V_p$  model containing 3-D sinusoidal patterns  
622 (see **Supplementary Text S1** and **Fig. S4** for details). Results demonstrate reliable pattern  
623 recovery in the nearshore region for 15 km spatial checkers, indicating that interpreted  
624 structures near the shoreline are not significantly biased by ray path geometry. While  
625 some east-west and vertical smearing occurs farther inshore or near model edges due to  
626 reduced crossing ray coverage, the north-south resolution remains robust throughout the  
627 study area. Ultimately, the nearly perfect recovery of larger checkers at depth confirms



668 evolving flexural response, the subducting slab is further partitioned into four along-  
 669 profile zones corresponding to the incoming plate and the segments underlying the prism,  
 670 Terrane 1, and Terrane 2, respectively. Within this framework, Terrane 2 is evaluated  
 671 under two rheological end-members, a low-velocity or weak case and a high-velocity or  
 672 strong case, representing the minimum complexity required to capture observed along-  
 673 strike variations in seismic velocity and geodetic uplift.

674 To rigorously account for uncertainties in seismic velocities and rheological parameters,  
 675 we execute the flexure and uplift simulations within a Monte Carlo framework. We  
 676 perform 10,000 realizations, where  $V_p$  and  $V_s$  values are randomly and uniformly  
 677 sampled from prescribed ranges for each tectonic component. This stochastic approach  
 678 ensures that our model results are robust against local velocity fluctuations and allows us  
 679 to quantify the sensitivity of slab curvature and surface deformation to the specific elastic  
 680 properties of the overriding terranes. We report ensemble means and probability  
 681 distributions of slab deflection and coastal uplift rate, and we visualize uncertainty using  
 682 cloud plots based on a random subset (2,000 realizations).

### 683 Numerical simulation of flexural slab bending

684 To investigate how along-strike variations in upper-plate density influence slab flexure,  
 685 we model the subducting plate as an elastic beam subjected to spatially variable vertical  
 686 loading and flexural rigidity. The model is formulated in two dimensions along a trench-  
 687 perpendicular profile and solved using a finite-difference approximation to the Euler-  
 688 Bernoulli beam equation, following classical thin-plate flexural theory. Although three-  
 689 dimensional flexural models are required where elastic thickness varies sharply along  
 690 strike, previous work has shown that 2-D variable-rigidity formulations adequately capture  
 691 slab bending where lateral variations are smooth or can be parameterized at the scale of  
 692 tectonic domains (43). Given our focus on first-order mechanical contrasts associated with  
 693 forearc terrane segmentation, a 2-D approach provides a computationally efficient  
 694 framework for isolating the influence of upper-plate rigidity on slab bending.

695 Mechanical properties within each element are parameterized using seismic velocities ( $V_p$   
 696 and  $V_s$ ), which are converted to density and elastic moduli and used to define spatially  
 697 variable flexural rigidity. Vertical loading arises from the combined effects of slab pull  
 698 and the excess mass of the overlying accretionary prism and forearc crust relative to a  
 699 reference water column. By prescribing geometry and material properties at the scale of  
 700 tectonic domains rather than individual faults, the model isolates the first-order  
 701 mechanical influence of upper-crustal segmentation on slab bending.

702 In the Euler-Bernoulli beam theory, the slab  $w(x)$  is controlled by the balance between the  
 703 internal stiffness of the lithosphere and the external buoyancy and tectonic loads. The  
 704 governing differential equation is below

$$705 \frac{d^2}{dx^2} \left( D(x) \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_w) g w = q(x) \quad (7)$$

706 Here,  $D(x)$  is the flexural rigidity,  $\rho_m$  is the mantle density (3300 kg/m<sup>3</sup>),  $\rho_w$  is the water  
 707 density (1030 kg/m<sup>3</sup>),  $g$  is the gravitational acceleration, and  $q(x)$  is the effective vertical  
 708 load. We then solve this fourth-order system (Eq. 7) using a finite difference method. We  
 709 approximate the curvature  $\frac{d^2 w}{dx^2}$  at the node  $i$  using the central difference stencil

$$710 \frac{d^2 w}{dx^2} \approx \frac{w_{i-1} - 2w_i + w_{i+1}}{\Delta x^2} \quad (8)$$

711 We construct the stiffness matrix  $A$  by applying the second derivative operator twice,  
 712 incorporating the spatially variable rigidity  $D(x)$  as a diagonal matrix  $M_D$  such that  $A \approx$

713  $D_2 M_D D_2 + K$ , where  $K$  represents the hydrostatic restoring force. The system was solved  
 714 via linear inversion  $w = A \backslash q$

715 For the inversion, we define the vertical load  $q(x)$  as the excess weight of the crustal  
 716 column relative to a reference water column

$$717 \quad q(x) = g \cdot (M_{\text{column}} - M_{\text{water}}) \quad (9)$$

718 For the rigid upper crustal blocks (e.g., Siletz), the load is simply  $q_{\text{block}} =$   
 719  $(\rho_{\text{crust}} - \rho_{\text{water}})gh$ . However, for the accretionary prism, we account for sediment  
 720 compaction, where porosity  $\phi$  decreases exponentially with depth  $z$  according to Athy's  
 721 Law,  $\phi(z) = \phi_0 e^{-z/\lambda}$ , where  $\phi_0$  is the surface porosity (assumed 0.30) and  $\lambda$  is the  
 722 compaction decay scale (assumed 3 km). Now, to derive the sediment mass, we assume  
 723 the bulk density  $\rho_{\text{bulk}}(z)$  at any depth is a mixture of grain density  $\rho_{\text{grain}}$  and fluid density  
 724  $\rho_{\text{fluid}}$

$$725 \quad \rho_{\text{bulk}}(z) = \phi(z)\rho_{\text{fluid}} + (1 - \phi(z))\rho_{\text{grain}} \quad (10)$$

726 Now, substituting the porosity function

$$727 \quad \rho_{\text{bulk}}(z) = \rho_{\text{grain}} - (\rho_{\text{grain}} - \rho_{\text{fluid}})\phi_0 e^{-z/\lambda} \quad (11)$$

728 To find the total mass  $M_{\text{sed}}$  of a sediment column of thickness  $h$ , we integrated the bulk  
 729 density from the surface ( $z = 0$ ) to the base ( $z = h$ )

$$730 \quad M_{\text{sed}} = \int_0^h \rho_{\text{bulk}}(z) dz \quad (12)$$

731 Now, substituting  $\rho_{\text{bulk}}$  from Equation 5,

$$732 \quad M_{\text{sed}} = \int_0^h \left[ \rho_{\text{grain}} - (\rho_{\text{grain}} - \rho_{\text{fluid}})\phi_0 e^{-z/\lambda} \right] dz \quad (13)$$

733 Solving this integral analytically yields the mas equation used in our simulation,

$$734 \quad M_{\text{sed}} = \rho_{\text{grain}}h - (\rho_{\text{grain}} - \rho_{\text{fluid}})\phi_0\lambda(1 - e^{-h/\lambda}) \quad (14)$$

735 The final effective load for the prism is,

$$736 \quad q_{\text{prism}} = [M_{\text{sed}} - (\rho_{\text{fluid}}h)]g \quad (15)$$

### 737 **Numerical simulation of interseismic uplift rate**

738 To quantify how upper-plate mechanical variability influences coastal uplift during the  
 739 interseismic period, we model forearc deformation using a time-dependent elastic–viscous  
 740 framework. Interseismic uplift along subduction margins reflects the combined effects of  
 741 elastic strain accumulation driven by ongoing plate convergence and time-dependent  
 742 stress relaxation within the upper plate and shallow mantle, rather than purely elastic  
 743 loading alone. Both theoretical and observational studies show that forearc deformation  
 744 during the earthquake cycle is governed by this competition between elastic locking on the  
 745 megathrust and viscous or inelastic accommodation within the overriding plate, producing  
 746 spatially variable uplift and subsidence patterns along the coast (21, 46).

747 We therefore represent interseismic deformation as the response of a mechanically  
 748 segmented forearc to imposed convergence, where elastic strain accumulates on short  
 749 timescales while viscous deformation progressively relaxes stress over longer timescales.  
 750 This formulation captures key aspects of subduction earthquake-cycle mechanics inferred  
 751 from analogue experiments and geodynamic models, including stress transfer from the  
 752 locked megathrust into the upper plate (21). Recent geodetic analyses further demonstrate

753 that regional and local patterns of uplift in Cascadia are sensitive to upper-plate rheology  
 754 and internal deformation, supporting the use of simplified viscoelastic representations to  
 755 interpret observed coastal uplift rates (6)

756 For calculating the interseismic uplift rate of the forearc terrane blocks, we modeled the  
 757 system as a Maxwell viscoelastic body (an elastic spring and viscous dashpot in a series)  
 758 under plane-strain compression. First, we discretize the subduction system into three  
 759 mechanical components arranged in series: the driving subducting slab, the offshore  
 760 terrane (Terrane 1), and the onshore/nearshore terrane (Terrane 2). We calculate the axial  
 761 stiffness  $k_i$  for each component as  $k_i = \frac{E_i A_i}{L_i}$ , where  $E_i$  is the Young's modulus,  $A_i$  is the  
 762 cross-sectional area perpendicular to compression, and  $L_i$  is the length of the block in the  
 763 direction of convergence. The total effective elastic stiffness  $K_{eq}$  of the system is derived  
 764 from the series combination of these components,

$$765 \frac{1}{k_{eq}} = \frac{1}{k_{slab}} + \frac{1}{k_{Terrane1}} + \frac{1}{k_{Terrane2}} \quad (16)$$

766 We assume the total convergence velocity of the slab ( $V_{conv}$ ) is conserved and partitioned  
 767 into elastic deformation velocity ( $V_{elastic}$ ) and viscous flow velocity ( $V_{viscous}$ ). From  
 768 Hooke's Law, stress relates to strain via stiffness  $k_{eq}$  as  $F = k_{eq}x$ . Differentiating with  
 769 respect to time gives the elastic velocity

$$770 V_{elastic} = \frac{dx}{dt} = \frac{1}{k_{eq}} \frac{dF}{dt} \quad (17)$$

771 For the viscous component, stress  $\sigma$  relates to strain rate  $\dot{\epsilon}$  via viscosity  $\eta$  such that  $\sigma =$   
 772  $\eta\dot{\epsilon}$ . Converting to force ( $F = \sigma A$ ) and velocity ( $V_{viscous} = \dot{\epsilon}L$ ),

$$773 V_{viscous} = \frac{F}{\eta} \frac{L}{A} \quad (18)$$

774 Where  $L$  is the block length, and  $A$  is the cross-sectional area. In this equation, we  
 775 parameterize the viscosity of the dashpot using a prescribed Maxwell relaxation time  
 776  $T_m = \frac{\eta}{\mu}$ , where  $\mu$  is the shear modulus.

777 Substituting the components from Equations 17 and 18 back into the velocity conservation  
 778 equation,

$$779 V_{conv} = \left( \frac{1}{k_{eq}} \frac{dF}{dt} \right) + \left( \frac{FL}{\eta A} \right) \quad (19)$$

780 Rearranging to solve for the rate of force change  $\frac{dF}{dt}$

$$781 \frac{dF}{dt} = k_{eq} \left( V_{conv} - \frac{FL}{\eta A} \right) \quad (20)$$

782 This ordinary differential equation (ODE) describes how tectonic force evolves over time,  
 783 transitioning from mostly elastic accumulation to mostly viscous deformation governed by  
 784 the prescribed Maxwell relaxation time. We solve this ODE numerically to find the force  
 785  $F(t)$  and its derivative  $dF/dt$  at the time of interest, which is the interseismic window.

786 Finally, the surface uplift rate is the vertical expansion resulting from horizontal  
 787 compression (Poisson effect). The total horizontal strain rate  $\dot{\epsilon}_{total}$  is the sum of elastic  
 788 and viscous strain rates

$$789 \dot{\epsilon}_{total} = \dot{\epsilon}_{elastic} + \dot{\epsilon}_{viscous} = \left( \frac{1}{EA} \frac{dF}{dt} \right) + \left( \frac{F}{\eta A} \right) \quad (21)$$

790 The vertical uplift rate is then

$$\text{Uplift rate} = \dot{\epsilon}_{\text{total}} \nu H_{\text{block}} \quad (22)$$

Where  $\eta$  is the Poisson's ratio and  $H_{\text{block}}$  is the block thickness.

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984

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989 Conceptualization: AA, EH

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992 Visualization: AA, EH, DT

993 Supervision: EH, DT

994 Writing—original draft: AA, EH

995 Writing—review & editing: AA, EH, DT

996 **Competing interests:** Authors declare that they have no competing interests.

997 **Data and materials availability:** All the data used in this study are publicly available.  
998 The seismic data acquired through stations of the Cascadia2021 experiment are available  
999 in PH5 format under network code Z4 2021 in the online repository of the Seismological  
1000 Facility for the Advancement of Geoscience (SAGE), which is operated by the Earthscope  
1001 Consortium. The OBS data can be accessed through network code YR 2021. The seismic  
1002 shot information for the CASIE21 experiment is available through the Marine Geoscience  
1003 Data System (MGDS) repository.

## Supplementary Text

### **Text S1: Checkerboard resolution test**

We use the checkerboard test to understand the model resolution and whether we can reliably resolve structures, especially in the nearshore region. First, we perturb the initial  $V_p$  model using 3-D sinusoids with alternating increases and decreases in amplitude of 20% in  $V_p$  values. This generates a checkerboard pattern with our assigned spatial scale. We then predict the travel time for ray paths, that correspond to the source-receiver geometry of the observed data, through this perturbed or checkerboard model. Using these synthetic travel times, we perform a tomographic inversion and evaluate the recovery of the checker pattern as an indicator of the model resolution.

We show the result of this test in **Fig. S4** using checkers with a spatial resolution of 15 km, both in along and across-strike direction of the subduction zone. The recovery of the checkers is reliable particularly in the nearshore regions both offshore and onshore. Resolution is remarkably good in the north-south direction with some east-west and vertical smearing especially farther inshore where crossing ray coverage is not as good. This result shows that the interpreted structures close to the shoreline (e.g., static backstop geometry) are not significantly biased by the ray path geometry. Farther from the shoreline, there is increased smearing in the east-west/across-strike direction due to fewer crossing rays near the model edge. Notably, there is minimal smearing in the north-south/along-strike direction, even near the edges of the model, showing that the model will resolve structural changes along the margin well. The east-west smearing decreases with larger checkers (~20 km). In the nearshore region, the recovery of larger checkers is nearly perfect. Even at around 10 km depth, we can reliably resolve along-strike changes in structures with our tomographic model (**Fig. S4**).

### **Text S2: Pseudo- $V_p$ Structure from Surface Geology**

In this study, we construct a pseudo- $V_p$  map from Oregon Department of Geology and Mineral Industries' (DOGAMI) surface geology (Franczyk et al., 2020) by grouping units into lithologic families and assigning each family a single shallow  $V_p$ -depth relation (valid for depths <4 km). These relations are developed by Brocher (2005, 2008), who compiled well logs, refraction data, and laboratory measurements to establish depth-dependent velocity functions and empirical regressions for different rock families. For our purposes, we directly adopted these published equations and applied them to the mapped lithologic families to generate the pseudo- $V_p$  map.

General Group 1: Marine sedimentary lithologies

Family A: They are mostly average marine basin clastics such as basin plain mudstone; slope mudstone; mudstone; siltstone; fine grained sediments; sandstone; deltaic sandstone; shelf sandstone, limestone; dolomite; marble; marine sedimentary rocks; sedimentary rocks. The following equation applied to these lithologies is based on Older Cenozoic sedimentary rocks / average basin" relation.

Equation:  $V_p = 2.24 + 0.60 z$

Family B: They are mostly high Vp marine rocks such as chert; tuffaceous sedimentary rocks; coarse-grained sediments; conglomerate; quartzite; basalt. The equation applied is based on rocks from Salinas and the East Bay Trough.

$$\text{Equation: } V_p = 4.354 + 0.74 (z - 3)$$

Family C: These are turbidite; mixed-grained sediments, mixed lithologies. The equation is based on rocks from the Great Valley Sequence.

$$\text{Equation: } V_p = 4.1675 + 0.4725 (z - 3)$$

#### General Group 2: Terrestrial sedimentary lithologies

Family A: They are mostly average continental basin clastics such as fine grained sediments, mudstone, sandstone, mixed-grained sediments (typical fluvial–lacustrine interbeds). The equation is based on typical onshore basins such as the Great Valley, West Delta, and Livermore.

$$\text{Equation: } V_p = 4.04 + 0.60 (z - 3)$$

Family B: These are coarse-grained sediments and conglomerate. The equation is based on rocks from Miocene transtensional basin.

$$\text{Equation: } V_p = 4.354 + 0.74 (z - 3)$$

Family C: They are mostly interbedded sand–mud successions.

$$\text{Equation: } V_p = 4.1675 + 0.4725 (z - 3)$$

#### General Group 2: Metamorphic lithologies

Family A: They mostly fall within felsic metamorphic bedrock such as gneiss, schist, hornfels, quartzite, mixed metamorphic rocks.

$$\text{Equation: } V_p = 6.18 + 0.159 (z - 3)$$

Family B: These are mafic metamorphic bedrock. We have subdivided this family into three subdivisions.

First one is Amphibolite/Metagabbro, with equation:  $V_p = 7.002 + 0.002 (z - 3)$

Second one is Greenstone, with the equation:  $V_p = 5.770 + 0.0584 (z - 3)$

Final one is Metabasalts, with equation:  $V_p = 5.361 + 0.475 (z - 3)$

Family C: This is ultramafic metamorphic bedrock, which is mostly serpentinite with a Vp of 5.29 km/s.

Family D: This family belongs to carbonate metamorphic rocks, which mostly include marble that has a Vp of 3.37.

#### General Group 3: Intrusive rocks

Family A: They are felsic intrusive felsic composition lithologies that include nepheline syenite, rhyolite, and ambiguous mixed lithologies that are dominantly felsic. Also, carbonate crystalline

such as marble falls into this family. The  $V_p$ -depth relationship for this family is derived based on rocks from onshore Bay area crystalline.

$$\text{Equation: } V_p = 6.18 + 0.159 (z - 3)$$

Family B: They are of intermediate composition, such as andesite, basaltic andesite, dacite, rhyodacite, trachydacite, and other intermediate composition lithologies.

$$\text{Equation: } V_p = 4.338 + 0.438 (z - 3)$$

Family C: They are Mafic rocks which include mafic composition lithologies, basalt, basanite, and breccia/brecciated rock.

$$\text{For Gabbro (intrusive), the equation: } V_p = 7 + 0.002 (z - 2)$$

$$\text{For Basalt (unaltered, extrusive), the equation: } V_p = 5.361 + 0.475 (z - 3)$$

Family D: They are of ultramafic composition lithologies, which are mostly serpentinite ( $V_p = 5.29$ ).

#### General Group 4: Mélange rocks

Family A: This family belongs to marine/forearc clastics such as mudstone, sandstone, conglomerate, mixed grained sediments, mixed lithologies, marine sedimentary rocks, sedimentary rocks, and turbidite. Equation for this family is based on the Franciscan metagraywacke matrix.

$$\text{Equation: } V_p = 4.1675 + 0.4725 (z - 3)$$

Family B: They are high- $V_p$  marine siliceous/carbonate such as chert.

$$\text{Equation: } V_p = 4.354 + 0.74 (z - 3)$$

Family C: The rocks of this group belong to the felsic metamorphic/crystalline group, such as gneiss, schist, and hornfels. The equation is based on the granite/felsic relation.

$$\text{Equation: } V_p = 6.18 + 0.159 (z - 3)$$

Family D: Rocks of this family are mafic metamorphic such as greenstone, blueschist, metabasalts, and other mafic composition lithologies.

$$\text{For greenstone, the equation is } V_p = 5.770 + 0.0584 (z - 3)$$

$$\text{For metabasalts, the equation is } V_p = 5.361 + 0.475 (z - 3)$$

Family E: These rocks are of Ultramafic composition which is mostly serpentine ( $V_p = 5.29$ ).

Family F: They are intermediate volcanic rocks such as dacite.

$$\text{Equation: } V_p = 4.338 + 0.438 (z - 3)$$

Family G: They are mafic volcanic rocks such as basalt, basanite.

$$\text{Equation: } V_p = 5.361 + 0.475 (z - 3)$$

Family H: They are carbonates such as limestone and marble. For limestone and marble, we use the same equation as Family A and Family C, respectively.

### General Group 5: Volcanic rocks

The subdivided families for this group are the same as the general group 4.

### General Group 6: Volcanic pyroclastic rocks

Family A: They are mafic volcanic (basaltic lavas).

$$\text{Equation: } V_p = 5.361 + 0.475 (z-3)$$

Family B: These are intermediate volcanic rocks such andesite, basaltic andesite and dacite lavas.

$$\text{Equation: } V_p = 4.338 + 0.438 (z-3)$$

Family C: Rocks of this family belong to felsic volcanic such as the massive rhyolite flows

$$\text{Equation: } V_p = 6.18 + 0.159 (z-3)$$

Family D: They are pyroclastic rocks such as tuff, ignimbrite, breccia, and tuffaceous.

$$\text{Equation: } V_p = 4.26 + 0.17 (z-1.5)$$

### **Text S3: Closed-form elastic estimate of coastal uplift**

Here we present an analytical, closed-form calculation of interseismic coastal uplift based purely on linear elasticity. The purpose of this exercise is not to replace the numerical elastic/viscoelastic model using force evolution in the main text, but to provide an independent and transparent benchmark. By deriving uplift rates directly from constitutive relations, the goal is to demonstrate that even in the elastic limit—without invoking viscous flow or time-dependent relaxation—contrasts in upper-crustal rigidity produce a significant fraction of the observed along-strike uplift-rate difference.

In this calculation, we consider a simplified forearc represented by two elastic blocks (Terrane 1 and Terrane 2) arranged in series along the convergence direction  $x$ . Each block has length  $L_i$ , thickness  $H_i$ , Young's modulus  $E_i$ , and Poisson's ratio  $\nu_i$ . Horizontal shortening is imposed by a constant far-field convergence rate  $V$  imposed across the combined length  $L = L_1 + L_2$ .

For an isotropic, linear elastic material under plane strain, the constitutive relation between stress and strain can be written in the form of generalized 3-D Hooke's law,

$$\epsilon_{xx} = \left(\frac{1}{E}\right) [\sigma_{xx} - \nu(\sigma_{yy} + \sigma_{zz})]$$

$$\epsilon_{yy} = \left(\frac{1}{E}\right) [\sigma_{yy} - \nu(\sigma_{xx} + \sigma_{zz})]$$

$$\epsilon_{zz} = \left(\frac{1}{E}\right) [\sigma_{zz} - \nu(\sigma_{xx} + \sigma_{yy})]$$

Now, we apply boundary conditions. First, we assume plane strain deformation, so  $\epsilon_{yy} = 0$ . Then the top surface is traction-free, so  $\sigma_{zz} = 0$ . This means

$$0 = \left(\frac{1}{E}\right) [\sigma_{yy} - \nu(\sigma_{xx} + 0)] \Rightarrow \sigma_{yy} = \nu\sigma_{xx}$$

After substituting  $\sigma_{yy} = \nu\sigma_{xx}$  and  $\sigma_{zz} = 0$ ,

$$\epsilon_{zz} = \left(\frac{1}{E}\right) [0 - \nu(\sigma_{xx} + \nu\sigma_{xx})] = -\frac{\sigma_{xx}}{E} \nu(1 + \nu)$$

To express vertical strain in terms of horizontal strain, we similarly simplify  $\epsilon_{xx}$ ,

$$\epsilon_{xx} = \frac{\sigma_{xx}}{E} [1 - \nu^2]$$

Taking the ratio gives the key elastic coupling under these boundary conditions,

$$\frac{\epsilon_{zz}}{\epsilon_{xx}} = -\frac{\nu}{1-\nu} \Rightarrow \epsilon_{zz} = -\frac{\nu}{1-\nu} \epsilon_{xx}$$

Also, vertical strain is related to the change in thickness of a block,  $\epsilon_{zz} = \frac{\Delta H}{H}$  and horizontal strain is  $\epsilon_{xx} = \frac{\Delta L}{L}$ .

Now, based on this horizontal strain rate  $\dot{\epsilon}_{xx} = \frac{d}{dt} \left(\frac{\Delta L}{L}\right) = \frac{1}{L} \frac{d(\Delta L)}{dt}$

However, for a block shortened at rate  $V_{conv}$  (positive toward shortening),  $\frac{d(\Delta L)}{dt} = -V_{conv}$

So, the horizontal strain rate becomes  $\dot{\epsilon}_{xx} = -\frac{V_{conv}}{L}$

Then, the vertical strain rate becomes  $\epsilon_{zz} = \frac{\nu}{1-\nu} \frac{V_{conv}}{L} = \frac{\Delta H}{H}$

Therefore, the change in uplift  $\Delta H = V_{conv} \left(\frac{\nu}{1-\nu}\right) \left(\frac{H}{L}\right)$

Using the plane-strain constitutive relation derived above, the horizontal stress–strain relation can be written as:

$$\sigma_{xx} = \left(\frac{E}{1-\nu^2}\right) \epsilon_{xx}$$

With  $\sigma_{xx} = \frac{F}{A}$  and  $\epsilon_{xx} = \frac{\Delta L}{L}$ , we obtain:

$$\frac{F}{A} = \left(\frac{E}{1-\nu^2}\right) \left(\frac{\Delta L}{L}\right) \Rightarrow F = \left[\frac{EA}{L(1-\nu^2)}\right] \Delta L$$

Now, when two elastic blocks are arranged in series, total convergence rate  $V_{conv}$  partitions into shortening rates  $V_1$  and  $V_2$  such that,  $V_{conv} = V_1 + V_2$ . Because the terranes are in series, they carry the same horizontal force  $F$  (force continuity):  $F_1 = F_2$ .

This motivates defining an effective elastic stiffness (per unit along-strike width) for terranes

$$K_i = \frac{E_i A_i}{[L_i (1-\nu_i^2)]}$$

Taking time derivatives yields  $\frac{dF}{dt} = K_i$ . And with  $F_1 = F_2$ , their rates are equal, so  $K_1 V_1 = K_2 V_2$ .

Then, combining with  $V_{conv} = V_1 + V_2$  gives,

$$V_1 = V_{conv} \left(\frac{K_2}{K_1 + K_2}\right), V_2 = V_{conv} \left(\frac{K_1}{K_1 + K_2}\right)$$

Substituting the partitioned convergence rate  $V_2$  into the single-block uplift relation gives the Terrane-2 uplift rate

$$\dot{u}_2 = V_2 \left(\frac{\nu_2}{1-\nu_2}\right) \left(\frac{H_2}{L_2}\right) = V_{conv} \left(\frac{K_1}{K_1 + K_2}\right) \left(\frac{\nu_2}{1-\nu_2}\right) \left(\frac{H_2}{L_2}\right)$$

Here,  $K_1$  and  $K_2$  are computed using  $K_i = \frac{E_i A_i}{[L_i(1-\nu_i^2)]}$ . Because  $A_i = H_i \cdot W$  (thickness times unit along-strike width  $W$ ),  $W$  cancels in the ratio  $\frac{K_1}{K_1+K_2}$ , so only  $H_i$ ,  $L_i$ ,  $E_i$ , and  $\nu_i$  are required.

We evaluate this closed-form expression using representative geometry of terranes from **Fig. 8**. Terrane2 thickness is approximately  $H_2 \approx 30$  km. Terrane1 thickness increases from  $\sim 10$  to  $\sim 15$  km across the forearc; we use a representative average  $H_1 \approx 12.5$  km. The along-dip extent of Terrane1 in the model spans roughly 60 km (from backstop1 at  $\sim 60$  km to backstop 2 at  $\sim 120$  km). Terrane 2 occupies the outer forearc; because shortening and uplift are distributed across a finite coastal belt rather than a single vertical interface, we use an effective shortening width  $L_2 \approx 40$  km for Terrane2 (this choice yields a conservative elastic contrast; using  $L_2 = 20$  km increases the predicted contrast modestly).

Elastic properties of the terranes used in our calculation:

Terrane 1:  $E_1 = 40$  GPa,  $\nu_1 = 0.27$ .

Terrane 2 (low-rigidity end member):  $E_2 = 42$  GPa,  $\nu_2 = 0.29$ .

Terrane 2 (high-rigidity end member):  $E_2 = 71$  GPa,  $\nu_2 = 0.35$ .

With these constraints, Terrane2 (nearshore-onshore terrane) uplift rate follows, for the low-rigidity case, 2.86 mm/year, and for the high-rigidity case, it is 5.81 mm/year. Thus, this closed-form elastic end member predicts an uplift-rate contrast for Terrane2 around 0.5 mm/year, which is around 25% of the observed  $\sim 2$  mm/year contrast. This shows that upper-crustal rigidity contrasts alone generate a substantial, physically inevitable component of uplift segmentation, providing an independent benchmark for the numerical simulations while motivating the additional time-dependent viscoelastic processes required to match the full amplitude of the observations.

#### **Text S4: Effect of upper crustal density contrast in mantle relaxation driven uplift**

The goal of this calculation is not to model the full interseismic uplift signal, which in the main text is treated using coupled elastic–viscoelastic simulations, but rather to isolate and quantify the contribution of upper-crustal density contrasts alone to mantle-relaxation-driven vertical motion. To estimate representative upper-crustal densities for the end-member terranes considered in this study, we convert  $V_p$  to density using empirical relationships compiled in the Materials and Methods. In low-rigidity forearc (Franciscan terrane), for  $V_p = 5.0$  km/s, we get the density  $\rho_{low} = 2.60$  g/cm<sup>3</sup>. And in high-rigidity forearc (Siletz terrane), for  $V_p = 6.25$  km/s, the density  $\rho_{high} = 2.91$  g/cm<sup>3</sup>.

Now the first order vertical velocity associated with mantle relaxation driven by a density contrast may be expressed as

$$V \propto \frac{(\rho_m - \rho_c)ghL}{\eta_m}$$

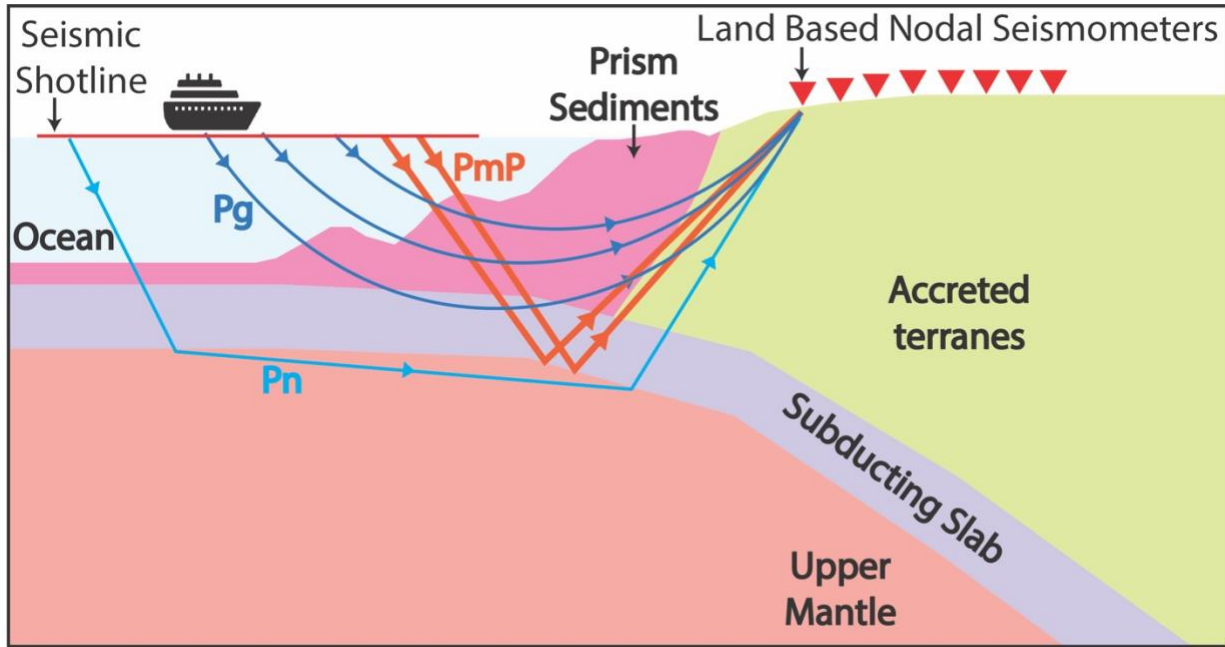
Where  $\rho_m$  is mantle density,  $\rho_c$  is crustal density,  $g$  is gravitational acceleration,  $h$  is the amplitude of the vertical load or deflection transmitted to the mantle,  $L$  is the characteristic lateral length scale of relaxation, and  $\eta_m$  is the mantle viscosity. Holding all parameters constant, except  $\rho_c$ , isolates the effect of upper-crustal density alone. Now, assuming a mantle density of

$\rho_m = 3.30 \text{ g/cm}^3$ , the effective density contrast for low rigidity crust  $\Delta\rho_{low} = 0.70 \text{ g/cm}^3$  and for high rigidity crust  $\Delta\rho_{high} = 0.39 \text{ g/cm}^3$

The ratio of relaxation-driven uplift rates between the two terranes is therefore

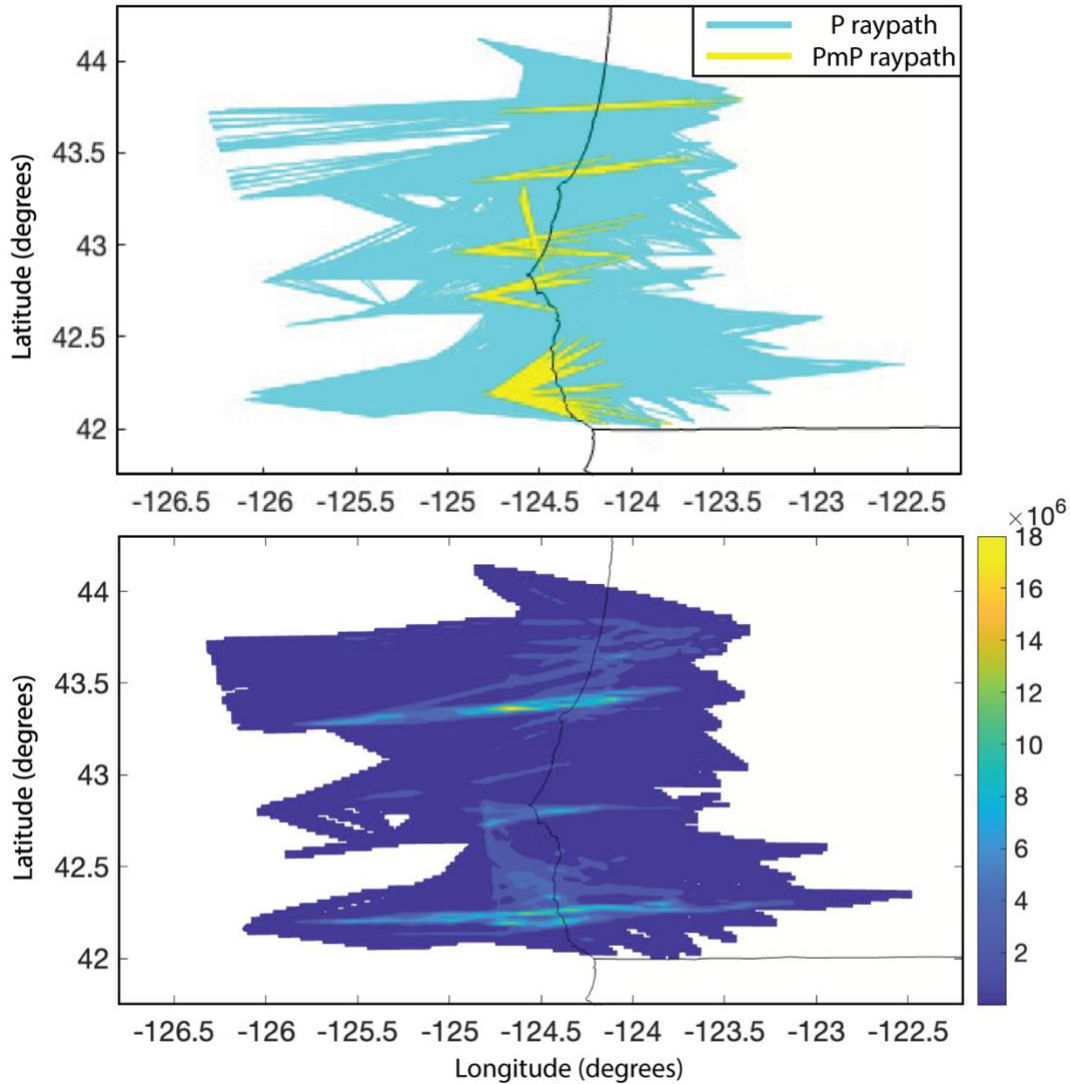
$$\frac{V_{high}}{V_{low}} = \frac{\Delta\rho_{high}}{\Delta\rho_{low}} = 0.56$$

This result implies that, purely due to density contrasts, mantle-relaxation-driven uplift beneath the Siletz terrane would be approximately 40–45% lower than beneath the Franciscan terrane, if mantle viscosity and tectonic forcing are identical.



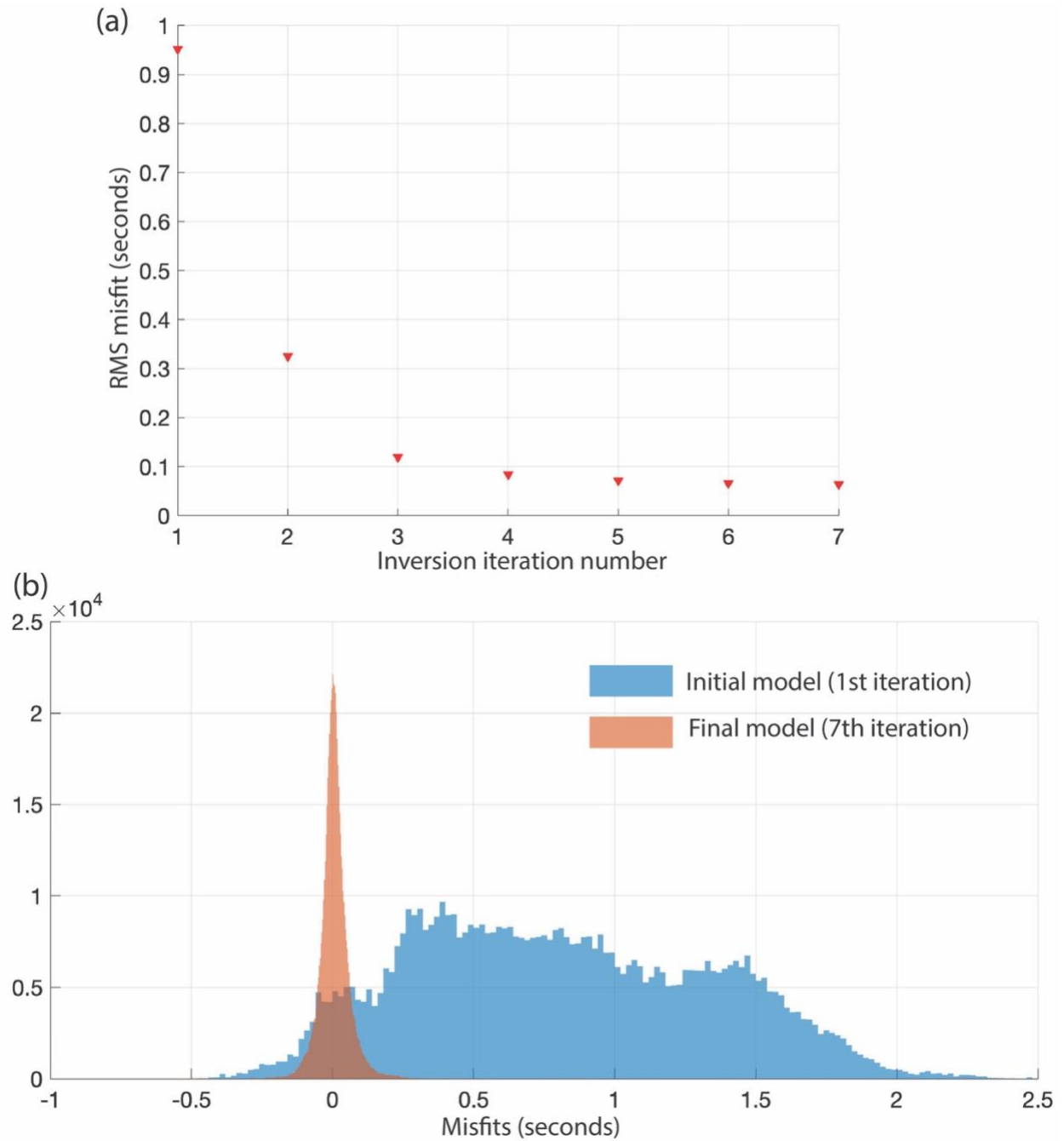
**Fig. S1.**

Schematic of the amphibious active-source seismic experiment used for the shore-crossing tomographic inversion. A marine seismic source (air-gun array) was fired along offshore shot lines and recorded by both offshore instruments and land-based nodal seismometers deployed across the coastline. Representative ray paths illustrate the phases used in the inversion: Pg refractions sampling the upper crust, Pn refractions traveling within the upper mantle, and PmP reflections from the oceanic Moho beneath the subducting slab. The experiment geometry enables continuous ray coverage from the offshore accretionary prism and prism sediments, across the shoreline, and into the onshore accreted terranes, providing joint constraints on shallow crustal velocity structure and slab geometry.

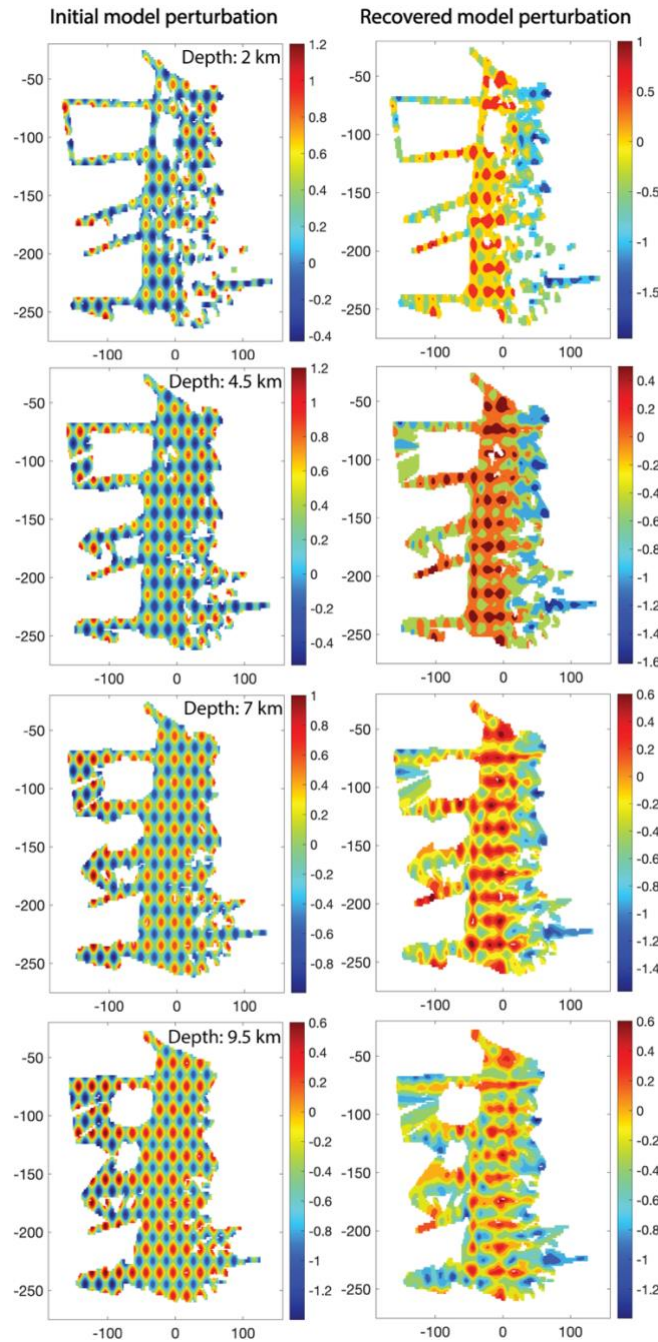


**Fig. S2.**

Raypath coverage and derivative weight sum (DWS) for the 3-D tomographic model. Top panel shows map views of representative seismic raypaths used in the tomographic inversion. Light-blue lines show Pg,Pn/P arrivals, with every 100th P arrival plotted for clarity, and yellow lines show PmP arrivals, with every 10th PmP arrival plotted. The distribution illustrates shore-crossing ray coverage from offshore sources to onshore receivers across the study area. The bottom panel shows DWS of the tomographic model, representing the cumulative sensitivity of travel-time observations to velocity perturbations within each model cell. Higher DWS values indicate stronger ray coverage and better-constrained regions of the model. We use  $DWS > 10$  to mask the contour plots of the tomographic model shown in this paper.

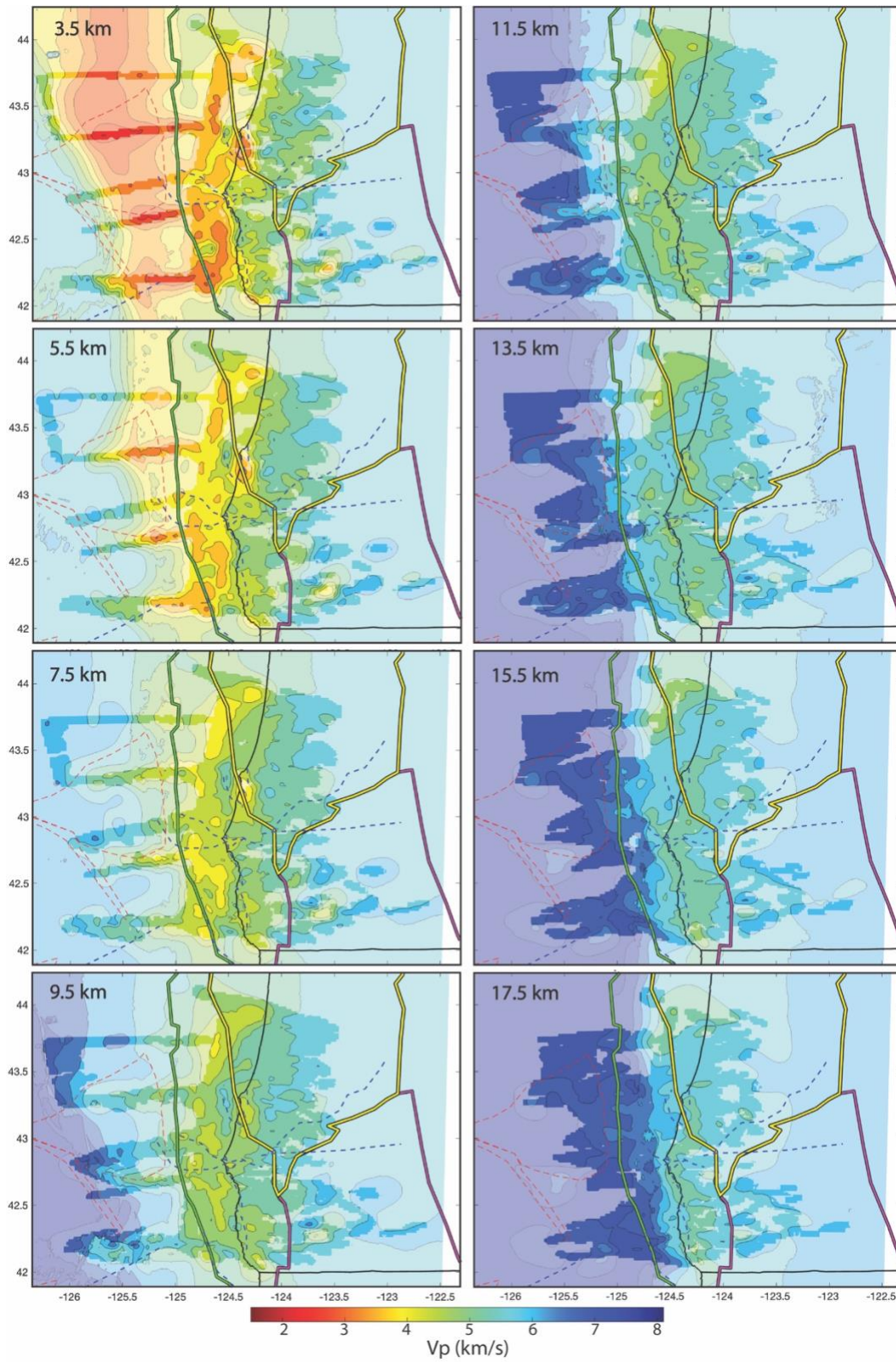
**Fig. S3.**

Graphs representing residual misfits (difference between observed and calculated seismic arrivals) of our tomographic inversion. (a) RMS misfit for each iteration of the inversion. (b) Histogram of misfits for the first and final iteration.

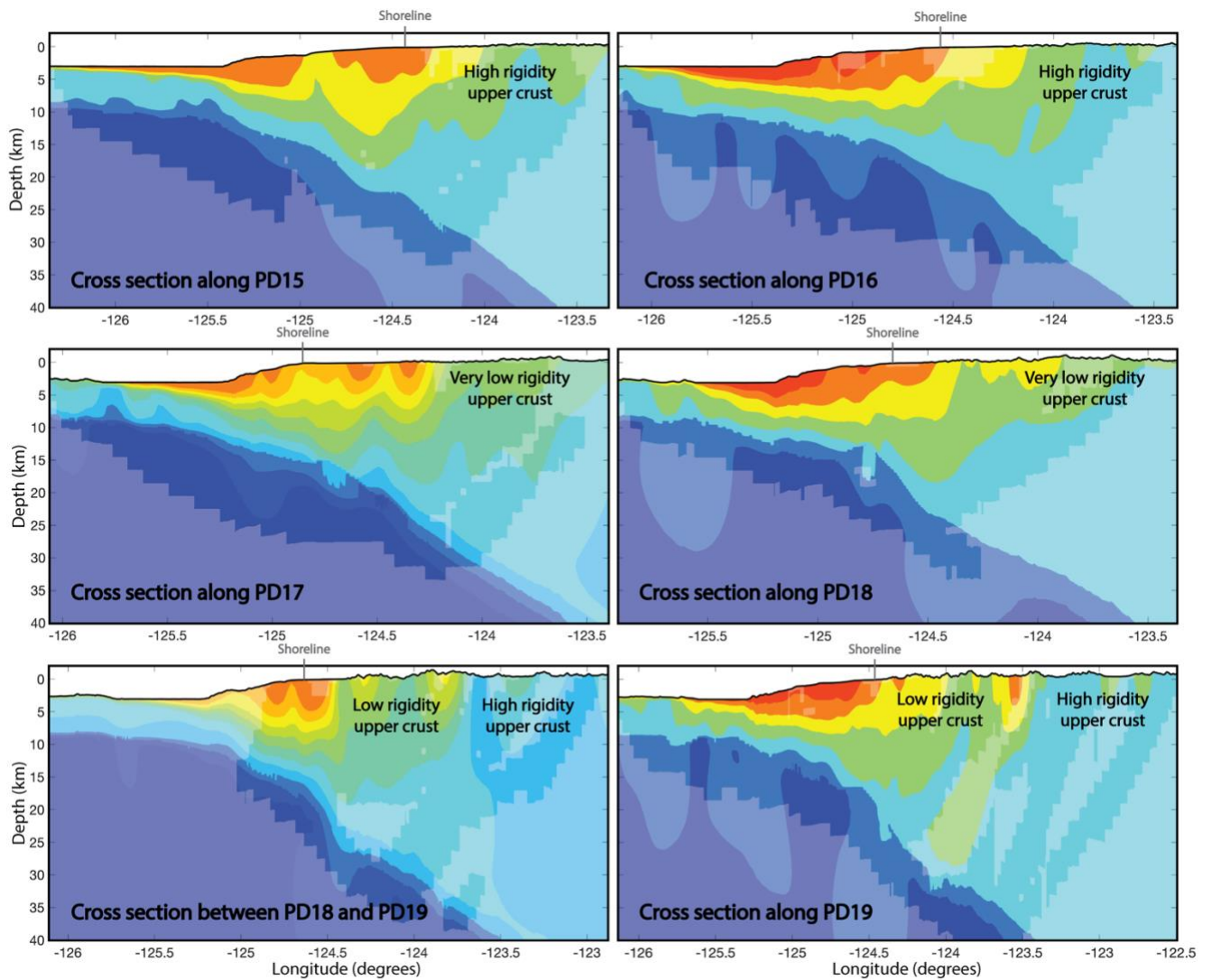


**Fig. S4.**

Checkerboard resolution test for the 3-D  $V_p$  tomographic inversion. Left panels show the imposed initial model perturbation, generated by applying 3-D sinusoidal checkerboard anomalies with  $\pm 20\%$   $V_p$  amplitude and a characteristic wavelength of  $\sim 15$  km in both along-strike and across-strike directions. Right panels show the recovered model perturbation obtained by inverting synthetic travel times calculated through the checkerboard model using the same source–receiver geometry, phase selection, and inversion parameters as the observed data. Maps are displayed in kilometers in the horizontal ( $x$ – $y$ ) directions; the central  $\pm 25$  km in the  $x$ -direction corresponds to the nearshore region.

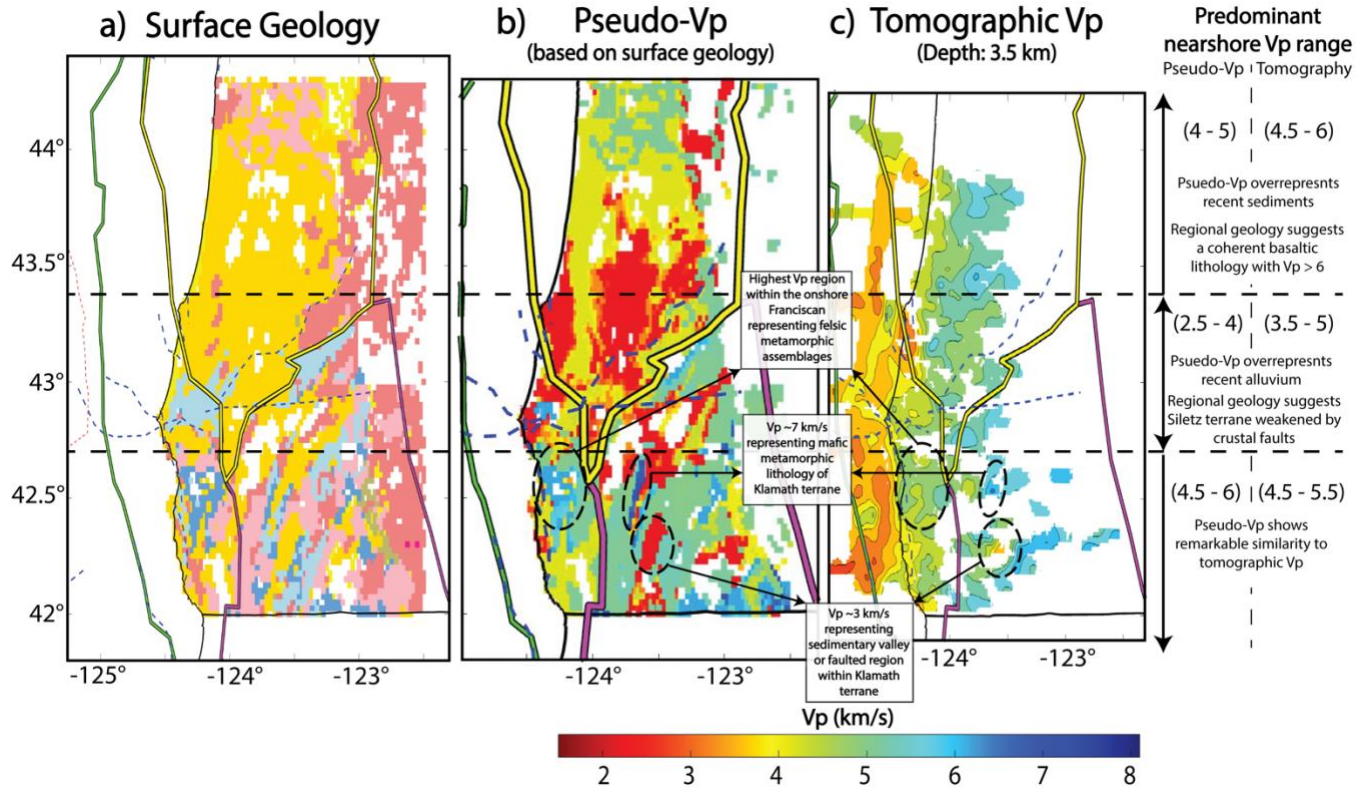


**Fig. S5.** Map sections at every 2 km intervals of the Vp tomographic model. Symbology is similar to **Figs. 1 and 2.**

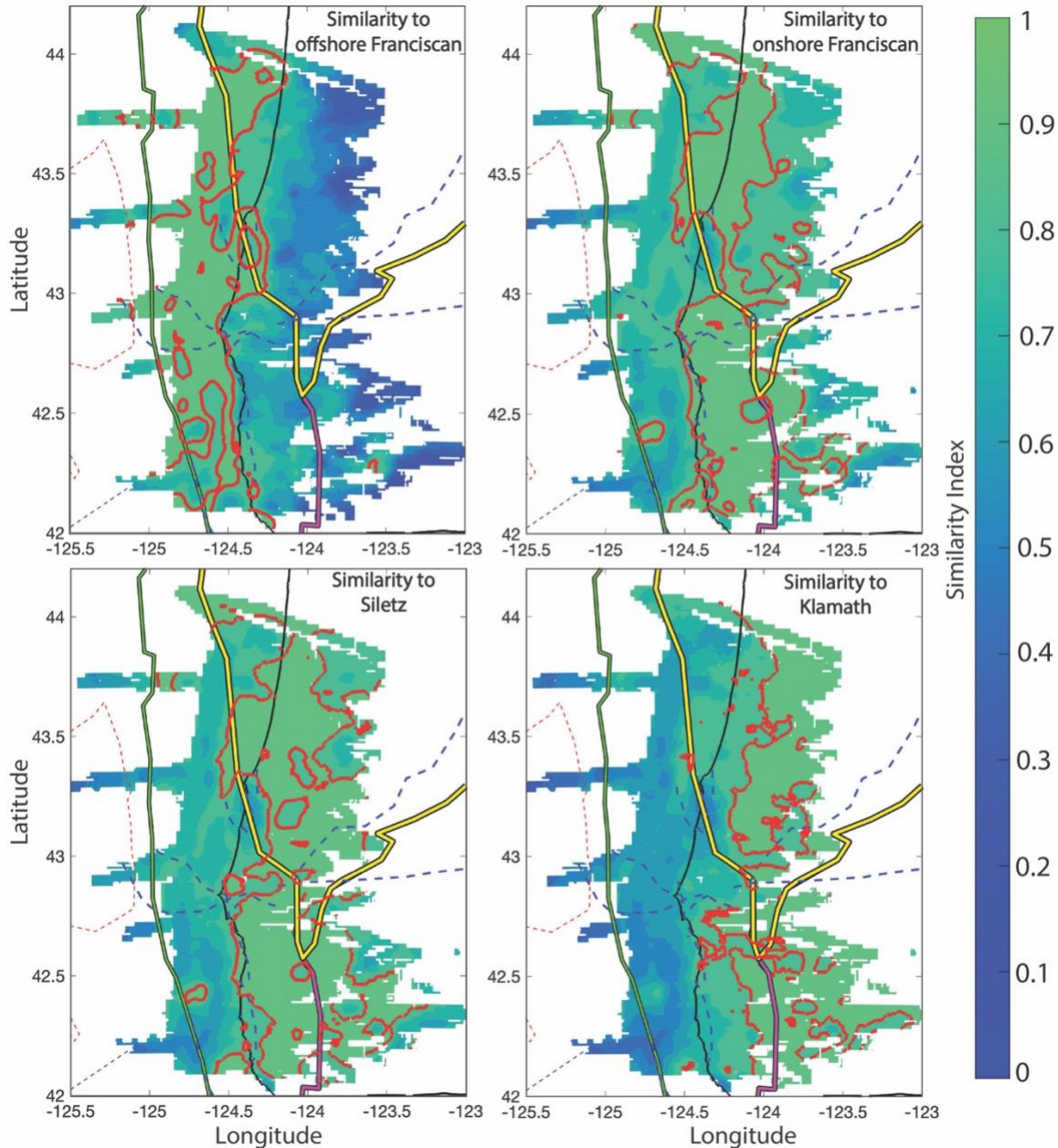


**Fig. S6.**

Cross-sections of the  $V_p$  tomographic model along all the east-west offshore seismic shotlines and onshore dense nodal stations. The symbology and colorbar follow **Figs. 2, 3, S4**.

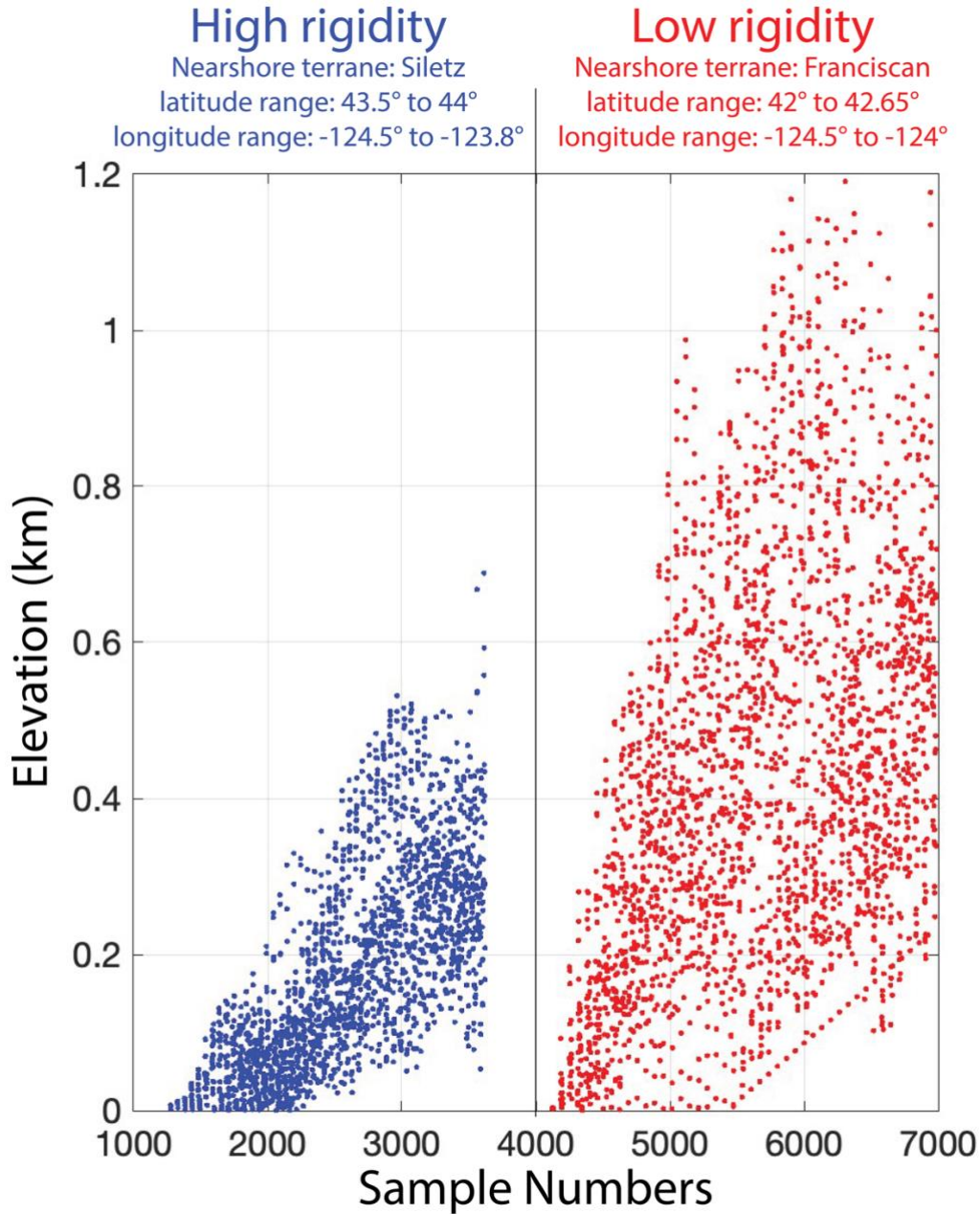
**Fig. S7.**

Comparison of surface geology and our seismic velocity model. (a) Surface geology of the study area (as in **Fig. 1b**) resampled to match the grid spacing of the tomographic model. (b) Pseudo-Vp map generated for a depth of 4 km based on empirical lithology-velocity relationships (see Supplementary Text S2) derived from surface geology. (c) Tomographic Vp model at 3.5 km depth (refer to **Fig. S5** for other map sections of the model). The panel to the right provides a latitudinal comparison of predominant nearshore Vp ranges (km/s) between the pseudo and tomographic Vp. Notes highlight if the surface-based estimates underrepresent subsurface geology and whether our knowledge of regional geology has to be invoked to better constrain expected Vp at depth. The dashed circles in 'b' and 'c' connected by black arrows represent regions with similar velocity between pseudo and tomographic-Vp which illustrate that surface geology based Vp calculation can closely approximate the Vp from tomographic modeling.

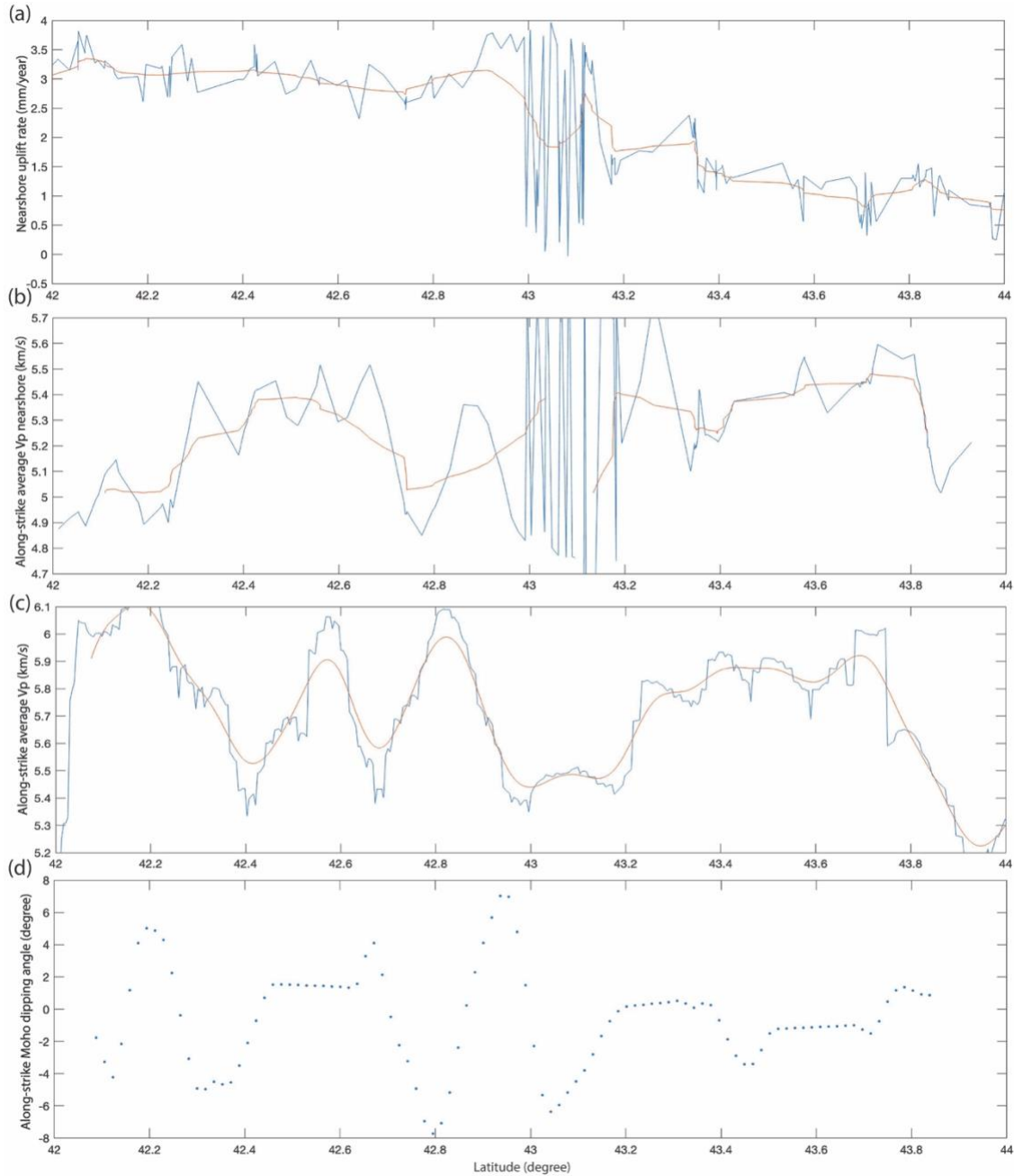


**Fig. S8.**

Similarity analysis between tomographic velocity structure and terrane-averaged reference profiles. Maps show the spatial distribution of the similarity index (0–1) between local 1-D  $V_p$ –depth profiles extracted from the 3-D tomographic model and terrane-averaged reference velocity profiles for the offshore Franciscan, onshore Franciscan, Siletz, and Klamath terranes. Warmer colors indicate higher similarity. Red contours outline regions exceeding a high similarity threshold ( $\geq 90\%$ ), highlighting areas where the depth-dependent velocity structure closely matches the corresponding terrane. Major tectonic boundaries, coastline, and mapped faults are overlain for reference; symbology follows **Fig. 1**. The four panels illustrate the lateral partitioning of velocity structure among terranes and the offshore–onshore and along-strike variability resolved by the similarity analysis.

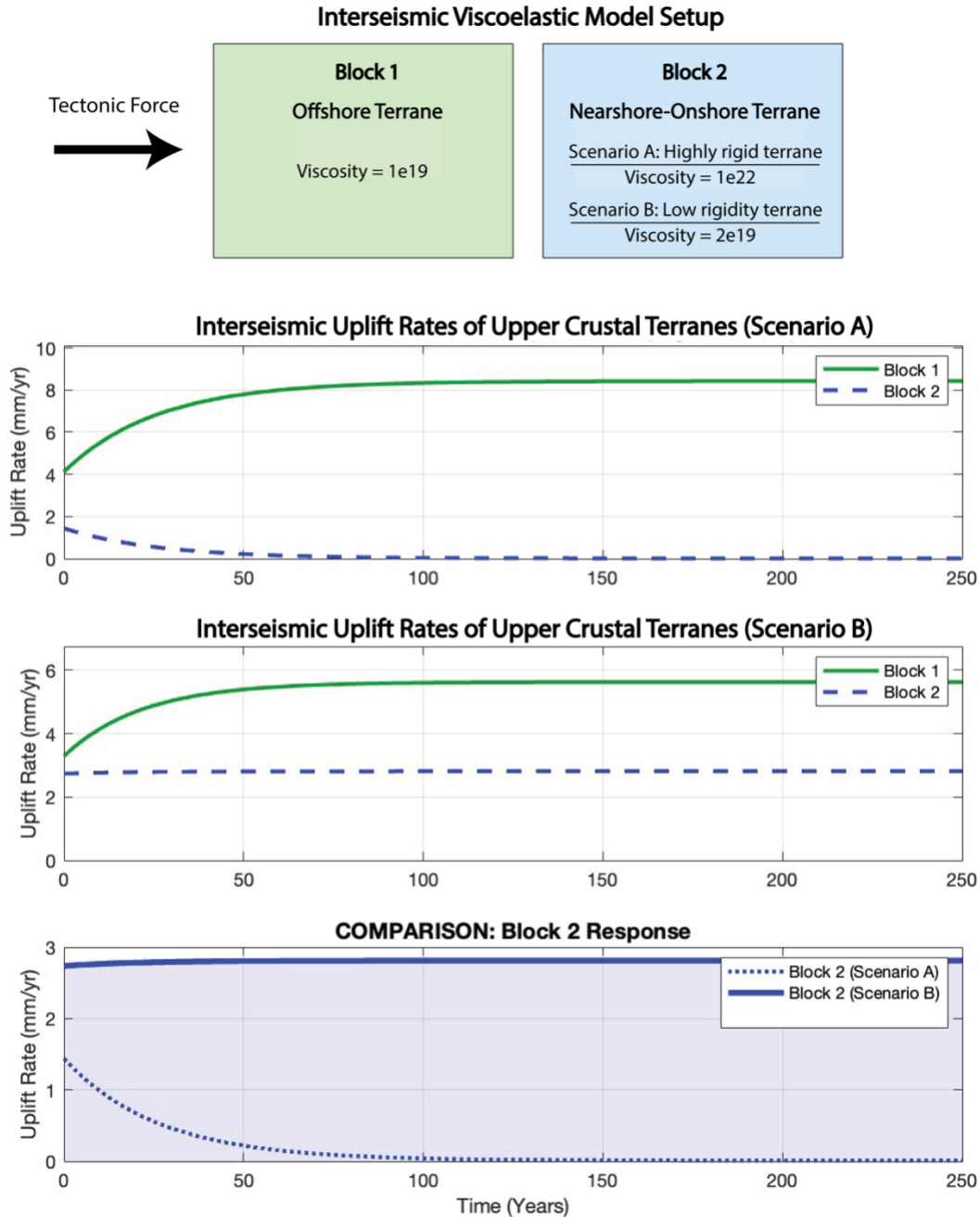
**Fig. S9.**

Elevation distributions of high- and low-rigidity onshore regions. Comparison of topographic relief between the Siletz terrane (high rigidity; blue) and the Franciscan terrane (low rigidity; red). Data were sampled at a 0.01° interval across the latitude and longitude ranges specified at the top of the figure. The Franciscan domain exhibits significantly higher topographic relief, with elevations exceeding 1.1 km, compared to the Siletz domain which remains mostly below 0.5 km.

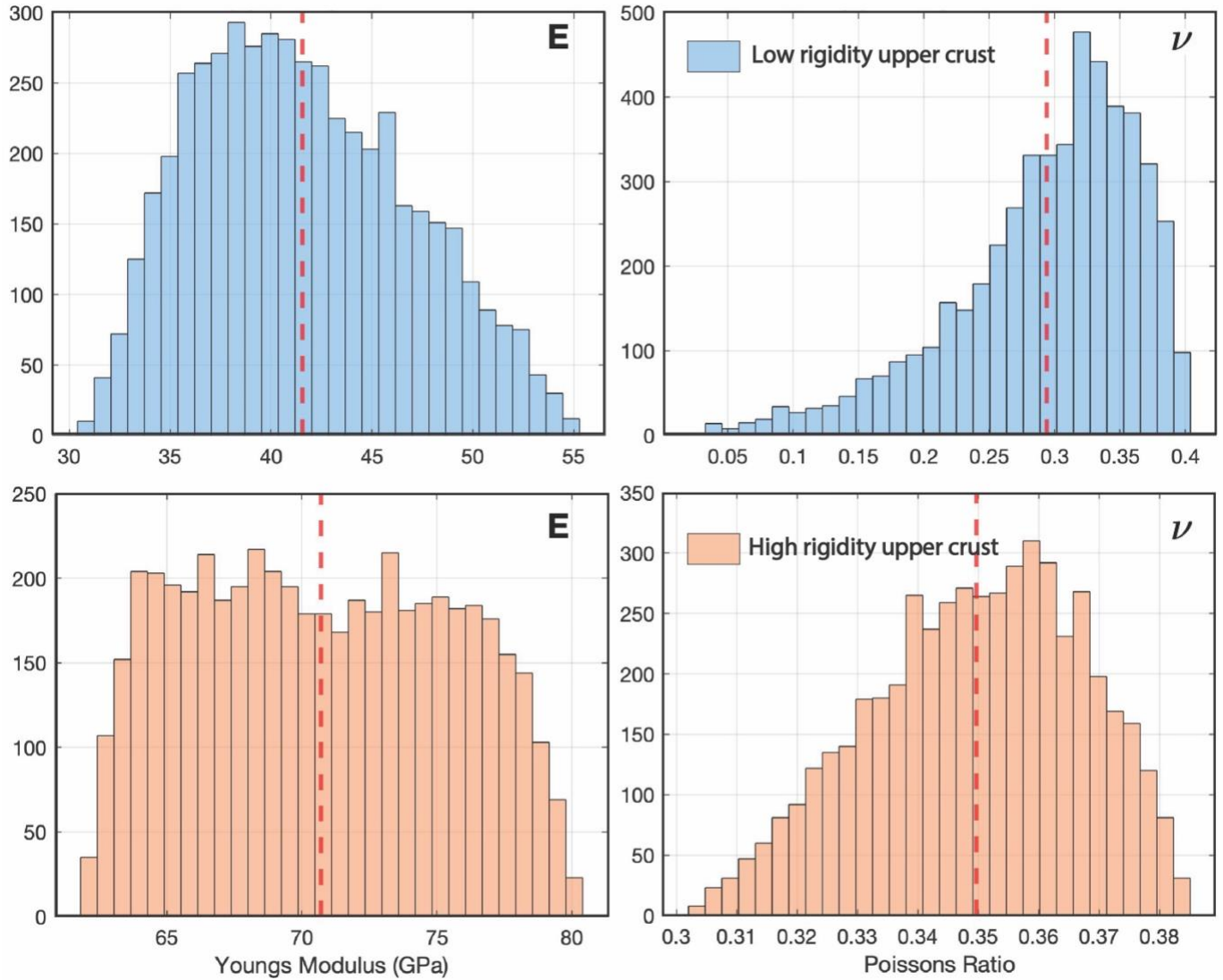


**Fig. S10.**

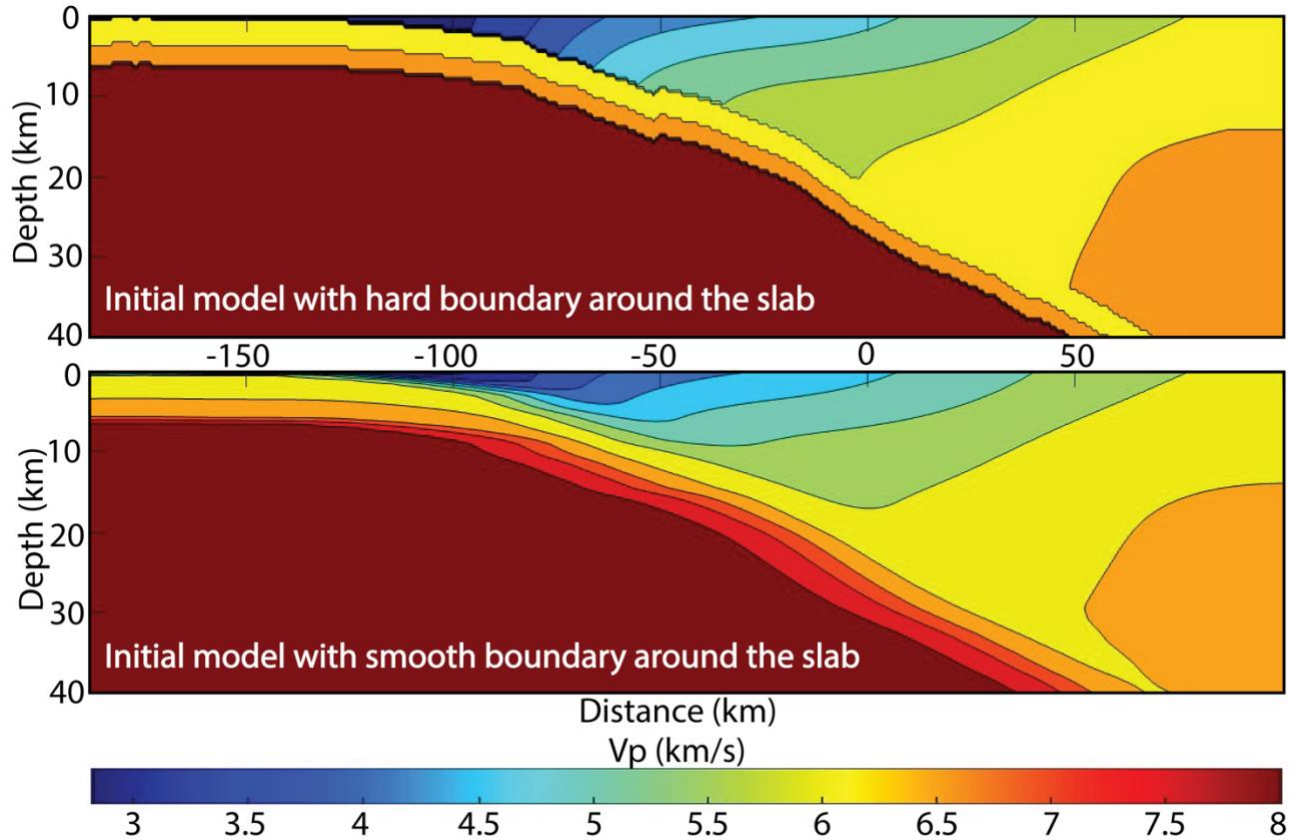
Calculation of different trends along-strike direction of the subducting slab. Values are averaged within each latitude interval (blue lines in panels a–c; blue dots in panel d). For panels a–c, a smoothed mean trend is also shown (orange line), obtained by applying a Gaussian mean to the averaged values. Only these mean trends are shown in **Fig. 5**. The y-axis labels in each panel indicate the corresponding data type. See the caption of **Fig. 5** for a detailed description of the datasets.

**Fig. S11.**

Dynamic force evolution and time-dependent uplift response in a two-block Maxwell viscoelastic model of the forearc. Top panel illustrates the model setup, in which an offshore terrane (Block 1; viscosity =  $10^{19}$  Pa·s) and a nearshore–onshore terrane (Block 2) are mechanically coupled and subjected to constant tectonic forcing representing interseismic convergence. Two rheological scenarios are explored for Block 2: (A) a high-rigidity terrane (viscosity =  $10^{22}$  Pa·s) and (B) a low-rigidity terrane (viscosity =  $2 \times 10^{19}$  Pa·s). Middle panels show the time evolution of uplift rates for each block over a 250-year interseismic interval. The bottom panel compares the uplift response of Block 2 between scenarios, illustrating how contrasts in Maxwell relaxation time govern interseismic strain partitioning.

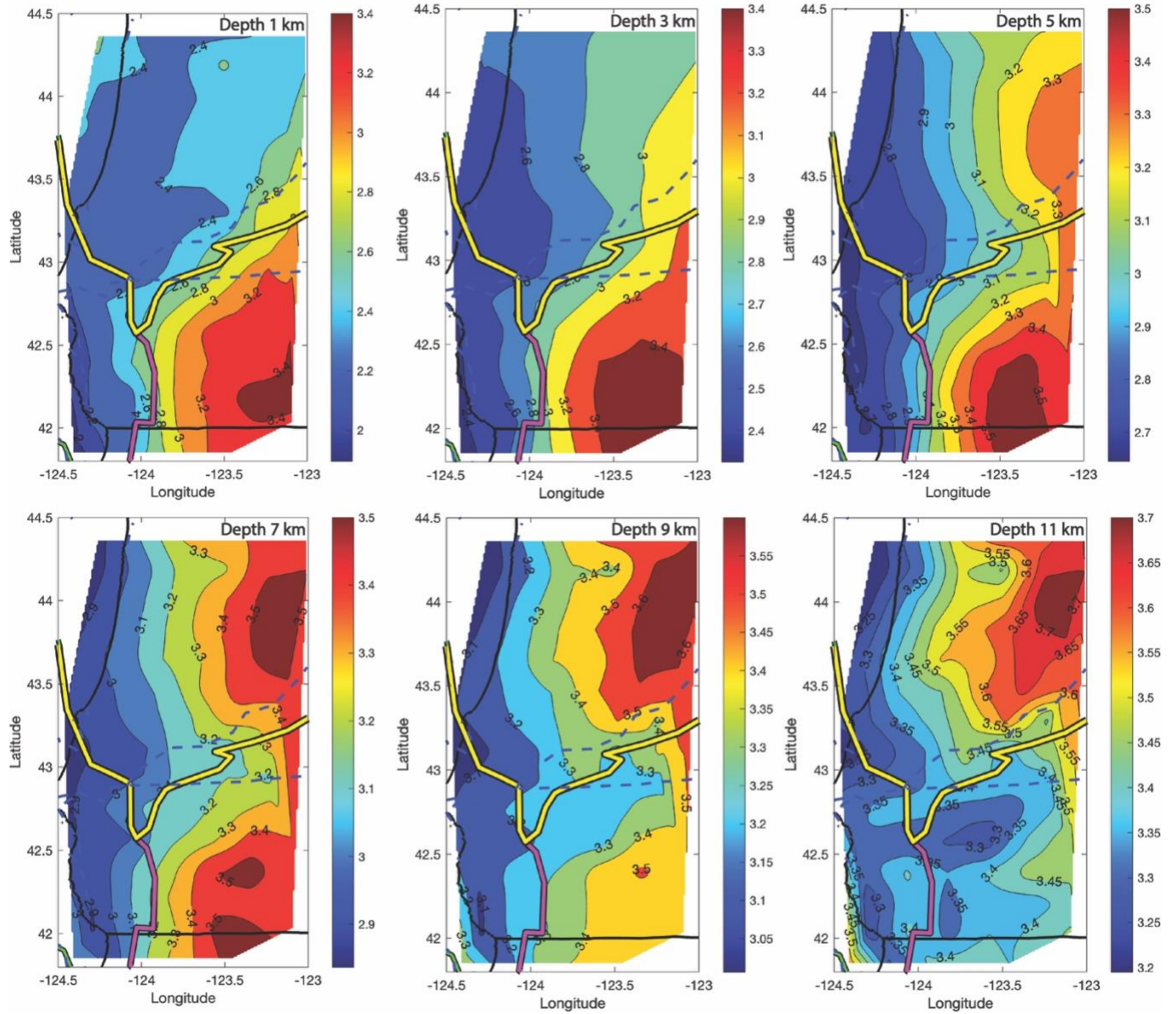
**Fig. S12.**

Distributions of elastic parameters in Monte Carlo simulations based on tomography-derived  $V_p$  range. Histograms show the range of Young's modulus (E) and Poisson's ratio ( $\nu$ ) sampled for the low-rigidity (top row, blue) and high-rigidity (bottom row, orange) upper-crustal domains.



**Fig. S13.**

Initial velocity models used for the tomographic inversion. Top section shows initial model with a hard, step-like velocity boundary imposed at the slab interface. Bottom section shows the initial model in which velocity contrasts around the slab are smoothed by convolving the upper part of the model with a moving-average filter, producing a gradual transition across the slab interface. The smoothed initial model is adopted to reduce artificial gradients at sharp boundaries and to ensure stable convergence of the inversion without prescribing slab geometry a priori.



**Fig. S14.**

S-wave velocity ( $V_s$ ) maps in our study area from the regional model of the Cascadia Region Earthquake Science Center.