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1 Rising not falling? Differential compaction of shelf-edge
2 trajectories and clinothem geometries

3

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14 **ABSTRACT**

15 Clinothems document the progradation of sedimentary strata. Their geometries allow us to define
16 shelf-edge trajectories, which are widely used to infer variations in relative sea-level, spatial and
17 temporal partitioning of depositional environments, and the timing of sediment delivery to the slope
18 and basin-floor. Here, we present a novel perspective on trajectory reconstruction of buried
19 successions, applying a decompaction technique that explicitly accounts for down-dip lithology
20 variations within clinothems. We show that preferential compaction of fine-grained foresets and
21 bottomsets results in a basinward rotation of trajectories and a distortion of primary clinothem
22 geometries. In some cases, shelf-edge trajectories change from rising to apparently falling after burial,
23 potentially leading to erroneous interpretations of original basin-margin physiography, relative sea
24 level fluctuations, and incorrect predictions for the timing and volume of sediment transfer to deep
25 water.

26 **INTRODUCTION**

27 A shelf-edge trajectory is the record of the shelf-to-slope rollover position through time in a basin-
28 margin clinothem succession. Theoretically, trajectories are proportional to the ratio of sediment
29 aggradation to progradation, and they can therefore be used to infer changes in the interplay between
30 sediment supply and relative sea-level changes, and to predict the timing and volume of sediment
31 transfer from continents to the oceans (Haq et al., 1987; Helland-Hansen and Martinsen, 1996;
32 Helland-Hansen and Hampson, 2009; Henriksen et al., 2011). Rising trajectories coincide with
33 significant topset aggradation and are associated with the deposition of fluvial channel deposits or
34 lagoonal depositional systems (Bullimore et al., 2005). In contrast, flat or falling trajectories signal
35 subaerial exposure of the continental shelf, fluvial incision of the shelf-slope rollover, and transfer of
36 coarse sediment to the slope and basin-floor (Helland-Hansen and Hampson, 2009; Dixon et al.,
37 2012).

38 Trajectory analysis can be undertaken on seismic reflection data (e.g. Anell and Midtkandal, 2015),
39 well-log correlation panels (e.g. Carvajal and Steel, 2012; Patruno et al., 2015a), or outcrops (Steel
40 and Olsen, 2002; Jones et al., 2015). In all cases, the studied successions are, or have been, deeply

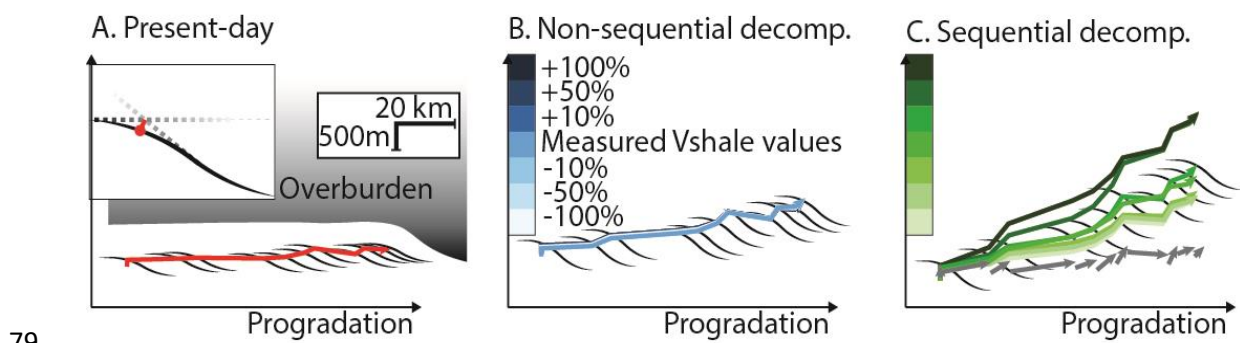
41 buried, and their clinothem geometries and associated trajectories have been distorted by loading and
42 sediment compaction. To account for this, for instance when estimating paleo-water-depth by
43 measuring clinothem heights (e.g. Plint et al., 2009; Patruno et al., 2015b), previous studies have
44 backstripped and decompacted the overburden overlying a succession of clinothems (herein called
45 “non-sequential decompaction”, e.g., Plint et al., 2009; Allen and Allen, 2013; Patruno et al., 2015a).
46 In some instances, this simple method is followed by the decompaction of each successive clinothem,
47 from youngest to oldest (herein called “sequential decompaction”; Steckler et al., 1999, Klausen and
48 Helland-Hansen, 2018). However, even in these cases, dip-oriented lithological heterogeneity, which
49 is common in almost all clinothem-bearing successions, are not accounted for despite likely being
50 significant. For example, porosity-depth curves for topset, foreset, and bottomset deposits identified in
51 well-log data in the Washakie Basin, USA (Carvajal and Steel, 2012), indicate that clay-rich foresets
52 and bottomsets compact twice as much as sandy topsets in the same clinothem when subjected to three
53 kilometers of burial (Selater and Christie, 1980; supplementary information 1). This is despite that fact
54 that the bottomsets in this particular succession are unusually sandy (Carvajal and Steel, 2012).
55 Motivated by this limited understanding of how lithological variability impacts trajectory analysis and
56 derived interpretations, our objectives are to: i) present a novel perspective to sequential decompaction
57 that accounts explicitly for lithological variations within clinothems; ii) apply this method to a broad
58 suite of datasets, including seismic reflection (Taranaki Basin, New Zealand), well-log (Washakie
59 Basin, USA), and outcrop datasets (van Keulenfjorden, Svalbard, Norway) to reconstruct pre-burial
60 clinothem trajectories and geometries; iii), quantify the effects of differences in the lithology fractions
61 during different stages of clinothem burial; and iv) discuss implications of this approach on shelf-edge
62 trajectory and clinothem geometry analysis.

63

64 **METHODS**

65 In this study, we consider siliciclastic clinothems consisting of sand- and claystone (often referred to
66 as “mudstone” or “shale”). The mix of these two rock types is captured by the “Vshale” value, wherein
67 0 represents pure sand and 1 represents pure clay. This is a widely used yet somewhat simplistic

68 approach as different depositional fabrics of clay mineralogies and silt grain types, such as floccs, result
 69 in a wide range of sorting arrangements, initial water content, and compaction behaviors (Potter et al.,
 70 2005). However, detailed mixed grain-size data are rarely reported from clinothems, and the key
 71 driver for differential compaction is the overall basinward fining from the topset to foreset/bottomset
 72 facies. This exists whether one chooses to implement simple or more complex grain size mixes. In our
 73 examples, V_{shale} values for topset, foreset, and bottomsets within individual clinothems are obtained
 74 from literature or, where available, derived directly from well-log or outcrop data (Johannessen et al.,
 75 2011; Carvajal and Steel, 2012). After determining V_{shale} values, a porosity/depth coefficient is
 76 calculated for each topset, foreset, and bottomset “compartment” using the empirically derived
 77 porosity/depth relations of Sclater and Christie (1980), although some have argued against the
 78 simplicity of these curves (Giles et al., 1998).



79
 80 *Figure 1. (A) Present shelf-edge trajectory (red) from Washakie Basin (Carvajal and Steel, 2012).*
 81 *Inset shows our geometric definition of the clinothem rollover point. (B) Non-sequentially*
 82 *decompacted trajectory (blue). (C) Sequentially decompacted trajectory (green), with unassembled*
 83 *trajectory increments shown as grey arrows (this step takes into account both the previous non-*
 84 *sequential decompaction and the successive application of the sequential decompaction of each single*
 85 *clinoform). V_{shale} values for topset, foreset, and bottomset are from Carvajal and Steel (2012).*
 86 *Colour gradients in B and C correspond to varying V_{shale} inputs. Note Low sensitivity in non-*
 87 *sequential decompaction and large sensitivity in sequential decompaction.*

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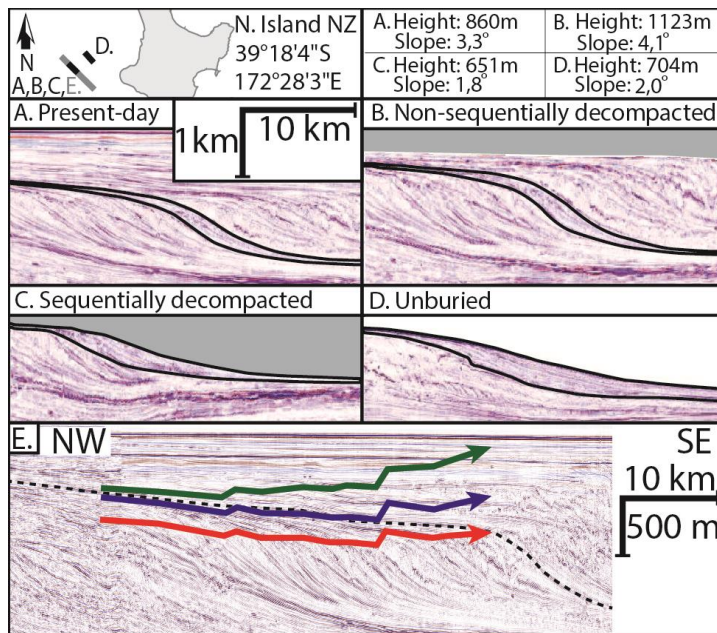
89 In our approach, we first backstrip, decompact, and unload all material overlying the target succession

90 ('non-sequential decompaction, e.g. Allen and Allen, 2013, Fig. 1B). This is followed by
91 backstripping, decompaction, and unloading each individual clinothem in the succession, from
92 youngest to oldest ('sequential decompaction', e.g. Steckler et al., 1999; Klausen and Helland-Hansen,
93 2018). This two-stage approach reconstructs each clinothem and its internal architecture back to its
94 primary, unburied geometry. The trajectory within each reconstructed clinothem captures one
95 increment of the complete trajectory that is reconstructed to its pre-burial state. The orientation and
96 position of each reconstructed trajectory increment is recorded, and the complete trajectory is finally
97 reconstructed by assembling all increments (Fig. 1C), which accounts for the effects of the continuous
98 load-induced subsidence occurring during and after deposition of each consecutive clinothem. Vshale
99 inputs for the non-sequential and sequential decompaction steps are the same. In both steps, a
100 horizontal datum, one hundred meters below the base of the succession, was set as 0 burial. We define
101 the location of the rollover point as the point of maximum curvature on the clinothem-bounding
102 clinoform (inset Fig. 1A). Before decompaction, seismic datasets are depth-converted using check-
103 shot data. We provide an extended outline of our methodology in the supplementary information (1).
104 To examine how lithological uncertainty impacts our reconstructions of shelf-edge trajectories, we
105 varied Vshale inputs by ± 10 , 50 and 100% (Fig. 1B and C). We do not account for the time-dependent
106 component of isostasy. Considering that the timescale of shelf-edge clinothem deposition (ca. 1-5
107 mm/yr; Patruno et al., 2015b), is approximately equal to or slower than that of isostatic adjustments
108 due to sediment load (ca. 1-8 mm/yr; Ivins et al., 2007), subsidence is expected to approach isostatic
109 equilibrium on the spatial and temporal scales considered in this study.

110 **RESULTS**

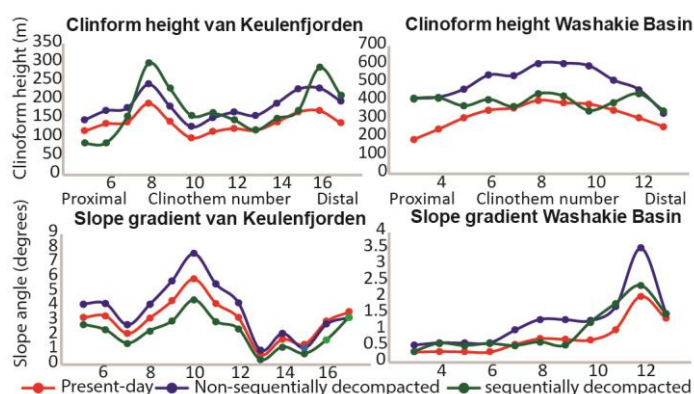
111 We first assess the accuracy of our workflow by comparing the reconstructed geometry of an ancient
112 clinothem to that of an unburied, geometrically similar clinothem in the same formation (Giant
113 Foresets Formation, Taranaki Basin, offshore New Zealand; Fig. 3). Similarities in the geometry,
114 height, and slope gradient between the reconstructed (Fig. 3C) and unburied (Fig. 3D) clinothems
115 suggest our method accurately reconstructs the overall geometry, internal architecture, and thus

116 trajectory of the buried clinothem. The effects of applying our workflow on clinothem heights and
 117 slope gradients from Washakie Basin and van Keulenfjorden are shown in Figure 2.



118
 119 *Figure 2. Buried (A) and unburied (D) clinothem geometries in the Taranaki Basin. (A) is located 60*
 120 *km NE of (D), lying within same formation. Grey infill in (B) and (C) shows backstripped area.*
 121 *Numbers in top-right are clinothem height and slope gradient. Non-sequential decompaction with*
 122 *down-dip variation in lithology (i.e., from A to B) uniformly increases the height and slope gradient,*
 123 *whereas sequential decompaction, accounting for down-dip variation in lithology (i.e., from B to C),*

124 decreases clinothem heights and slope gradients and results in a better similarity with the unburied
 125 geometry (D). Scale bar shown in (A) applies to B, C and D.



126
 127 *Figure 3. Graphs of present (red), non-sequentially (blue) and sequentially decompacted (green)*
 128 *clinothem heights and slope gradients from outcrop (van Keulenfjorden) and well-log (Washakie*
 129 *Basin) datasets. Clinothem heights are the vertical distance between the basin floor and the*
 130 *shelf/slope rollover. Slope gradients are the average gradient of the foreset. Not all clinothems in the*
 131 *successions are measured due to data limitations.*
 132 Clinothem geometries and their trajectory increments respond differently to the two steps of our
 133 decompaction methodology. Through step 1, the non-sequential decompaction, clinothem heights and
 134 slope gradients are overall uniformly increased (Fig. 2, from red lines to blue lines). Trajectory
 135 gradients also uniformly increase with respect to their present orientation (Fig. 3E). Although
 136 additional strata are backstripped during step 2, sequential decompaction, clinothem heights and slope
 137 gradients typically decrease rather than increase (Fig. 2, from blue lines to red lines). Overall, after
 138 non-sequential and then sequential decompaction, average trajectory gradients within each dataset are
 139 increased by 0.5° to 1.3° (Table 1).

Average trajectory gradient (degrees)	Present	Step 1: non-sequential decompaction	Step 2: sequential decompaction
Washakie Basin	0.3	0.7	1.3
van Keulenfjorden	1.1	1.8	2.4
Taranaki Basin	-0.1	0	0.4

140 *Table 1. Average gradients across the entire length of the measured trajectory. Values are in degrees.*

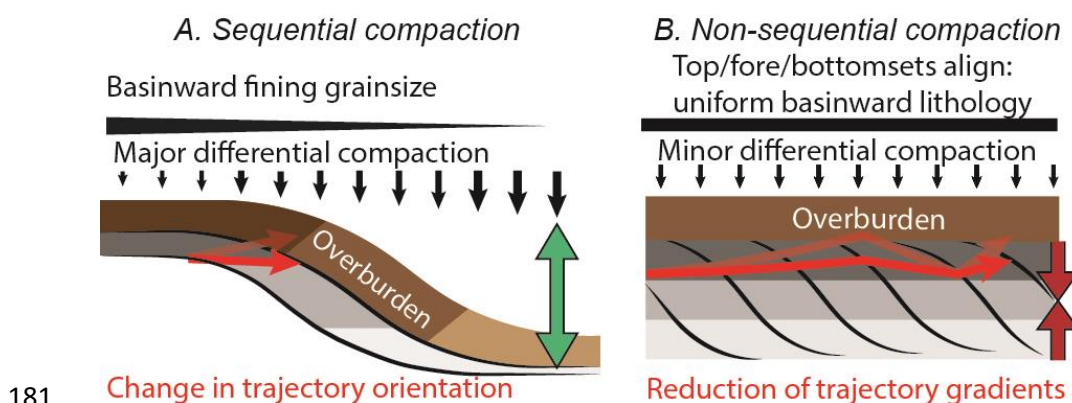
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142 Changes in shelf-edge trajectory reflect variations in the ratio of aggradation to progradation (Helland-
143 Hansen and Hampson, 2009). However, as we show here, the true shelf-edge trajectories change post-
144 depositionally in response differential compaction and continuous subsidence due to sediment loading
145 (Fig. 3E). For example, much of the presently falling trajectory (red arrow in Fig. 3E) in the Giant
146 Foresets Formation was actually rising during progradation (green arrow in Fig. 3E). In this area,
147 lithological data are available from nearby wells, though it should be noted that these data cannot
148 constrain lithological variability within all clinothem compartments. Because of this, there is some
149 uncertainty with regards to our V_{shale} inputs. However, the Washakie Basin sensitivity analysis tells
150 us that a $\pm 10\%$ change in V_{shale} input results in an increase or decrease in trajectory orientation of
151 0.3° . Since the calculated trajectory reorientation are outside of this margin of error, it can be
152 concluded that post-depositional trajectory reorientation has occurred here. Our interpretation that the
153 observed falling trajectory in Taranaki Basin was actually rising during deposition is supported by the
154 thick topset deposits, a stratigraphic architecture characterized by rising rather than falling trajectories
155 (Helland-Hansen and Hampson, 2009). We applied our workflow to other datasets containing
156 successive clinothems with falling trajectory (i.e. Columbus Basin, Trinidad, Chen et al. 2016; Karoo
157 Basin, South Africa, Poyatos-Moré et al., 2016; see supplementary information 2). After
158 decompaction, observed falling trajectory increments within both these datasets were reoriented to
159 reveal rising trajectories.

160 **DISCUSSION**

161 We recognize two distinct stages in the burial and compaction of clinothem strata: i) “early” sequential
162 compaction, which drives major differential (i.e. down-dip) compaction; and ii) “late” non-sequential
163 compaction, which is associated with only minor differential compaction. During the sequential
164 compaction stage, a basinward-fining clinothem is buried by a younger clinothem, and clay-rich
165 foresets and bottomsets compact more than sand-rich topsets; this drives a steepening of the foreset
166 strata, which is accompanied by vertical extension (i.e. an increase in height) of the clinothem (Fig.
167 4A). These observations contradict the results of a previous study by Deibert et al. (2003), who argue

168 differential compaction decreases the height and slope gradient of the clinothem. The likely
 169 explanation for this disparity is that Deibert et al. (2003) do not account for down-dip changes in
 170 lithology within their decompacted clinothems. Vertical extension of the clinothem during the first
 171 (sequential decompaction) stage is, in most cases, greater than the overall compaction, causing a net
 172 increase in clinothem height and slope gradient (Fig 2, from green lines to blue lines).
 173 The later non-sequential compaction stage starts when clinothems are buried below a simple,
 174 horizontally layered overburden, potentially consisting of shallow-marine shelf and coastal plain
 175 deposits. In this stage, the amount of differential compaction is much less than in the first, sequential
 176 decompaction stage. This is because, in most cases, during basin margin development, older, buried
 177 clinothems form sub-parallel belts of similar lithology due to the roughly horizontal alignment of
 178 topset, foreset, and bottomset compartments. This drives non-differential compaction, which decreases
 179 clinothem heights and slope gradients by evenly compressing the buried succession (Fig. 2, from blue
 180 lines to red lines, Fig. 4).



181
 182 *Figure 4. Impacts of (A) 'early', differential (i.e. sequential) compaction, and (B) 'late', non-*
 183 *differential (i.e. non-sequential) compaction on clinothem geometries and shelf-edge trajectories.*
 184 *Topset, foreset, and bottomset compartments indicated in gray shading. Note opposing effects with*
 185 *respect to clinothem height (decreases) and slope gradient (increases).*

186
 187 The two stages of compaction thus work in opposition with regards to their net effect on clinothem
 188 heights and slope gradients, meaning simple decompaction methodologies not including sequential

189 decompaction, or that do not account for lithological heterogeneities within clinothems, need revision.
190 In fact, previous application of previous methods may result in erroneous reconstructions of paleo
191 basin depth (Plint et al., 2009; Patruno et al., 2015b), progradation rates and depositional fluxes
192 (Patruno et al., 2015b), relative sea level fluctuations (Haq et al., 1987), and paleo slope gradients
193 (Deibert et al., 2003).

194 There is also a shift in the response of the shelf-edge trajectory between the two stages of compaction.
195 Sequential compaction causes a downward rotation of the trajectory due to differential compaction
196 (Fig. 4A). Furthermore, in the case of significant progradation, mass is disproportionately applied to the
197 area surrounding the inflection point, around the center of the foreset strata, causing additional
198 basinward rotation of trajectories. This may also, in some cases, slightly depress strata underlying the
199 clinothem foreset. Depression of strata underlying the inflection point can be seen in our reconstructed
200 and unburied case studies from Taranaki Basin (Fig. 3C, D). The amount of reorientation depends on
201 the rate and distribution of down-clinotherm fining, and the amount of progradation during each
202 increment. Non-sequential compaction then compresses the entire succession, and thereby roughly
203 uniformly reduces trajectory gradients, with steeper positive gradients being reduced more than
204 shallower ones (Fig. 4B; Patruno et al., 2015a). This difference in the response of the trajectory to the
205 two phases of compaction can also be seen in the results of our sensitivity analysis, which indicates
206 that the initial sequential compaction stage is especially sensitivity to lithological inputs (i.e. large
207 divergence in results in Fig. 1C), whereas non-sequential compaction proceeds virtually irrespective of
208 Vshale inputs (small divergence in results Fig. 1B), even though much more material is removed in the
209 non-sequential decompaction step.

210 The strong reduction in differential compaction at the end of the sequential compaction stage is shelf-
211 edge trajectory dependent. In the case of perfectly flat trajectories, non-sequential compaction will be
212 completely non-differential. However, in cases of steeply rising shelf-edge trajectories, topset, foreset,
213 and bottomset deposits will not be aligned perfectly within the clinothem successions. When this is the
214 case, down-dip lithological changes will persist, though less prominently, as indicated by our
215 sensitivity analyses that were performed on a trajectory with a rising orientation (Fig 1B). Future

216 experiments that use more complicated ranges and distributions of lithologies are thereby likely to
217 achieve even more accurate reconstructions of true shelf-edge trajectories and clinothem geometries.
218 Another important observation is that topset surfaces, which are sometimes used to estimate
219 paleohorizontal datums (e.g. Klausen and Helland-Hansen, 2018), can also be tilted basinward during
220 the sequential compaction stage. Because of this, apparently falling shelf-edge trajectories with tilted
221 topsets, such as the one from Taranaki Basin (Fig. 3E), are likely to have been reoriented due to
222 differential compaction and loading. Correcting for topset surface tilt, like estimating topset
223 aggradation, could therefore be used to estimate primary trajectory configurations without the need to
224 apply decompaction.

225 **CONCLUSIONS**

226 By explicitly accounting for dip-oriented lithological heterogeneities within clinothem-bearing
227 successions, we provide a novel refinement to the sequential decompaction workflow, using this to
228 reconstruct primary shelf-edge trajectory orientations. We show that differential compaction and
229 sediment loading cause major reorientations of the primary shelf-edge trajectory after burial. As a
230 result, recorded trajectories that are observed in stratigraphy differ from true trajectories, and are not
231 proportional to the rates of aggradation to progradation. These can lead to major differences, for
232 example with originally rising trajectories being modified to be apparently falling. These results
233 impact our ability to accurately reconstruct relative sea level fluctuations, infer depositional
234 environments and depositional rates, and to infer the timing of basinward transfer of coarse-grained
235 sediment. We also show that burial and geometric distortion of clinothems and their associated shelf-
236 edge trajectories occurs in two distinct stages, whereby each stage has an approximately opposite net-
237 effect with regards to the height and slope gradient of the clinothem. This emphasizes that simplistic,
238 yet widely used decompaction methodologies that do not account for lithological heterogeneities, as
239 well as the mass of individual clinothems in the succession, may need to be revised to ensure more
240 accurate reconstructions of syn-depositional clinothem heights and slope gradients.

241

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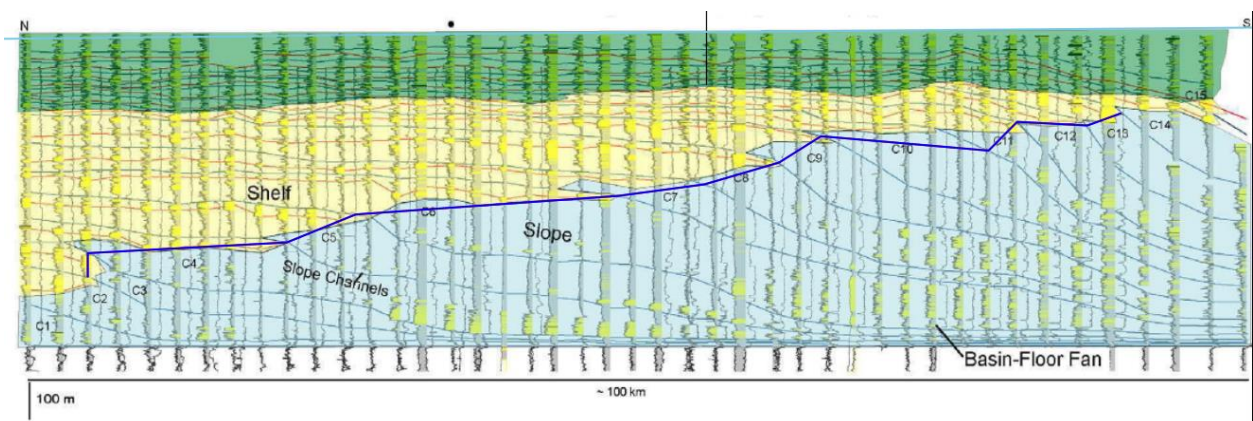
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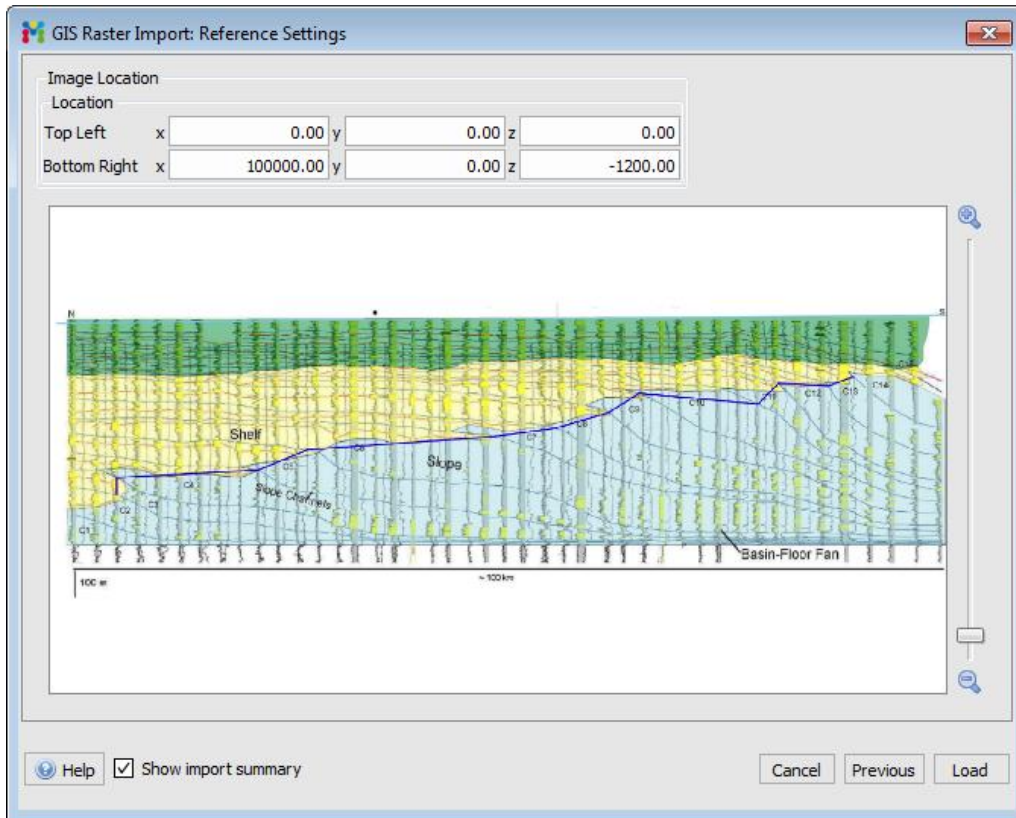
312 **Supplementary information 1**
 313

314 1) A dip-section image of a clinoform bearing succession is selected from literature.
 315 Example: Washakie Basin obtained from (Carvajal and Steel, 2012).

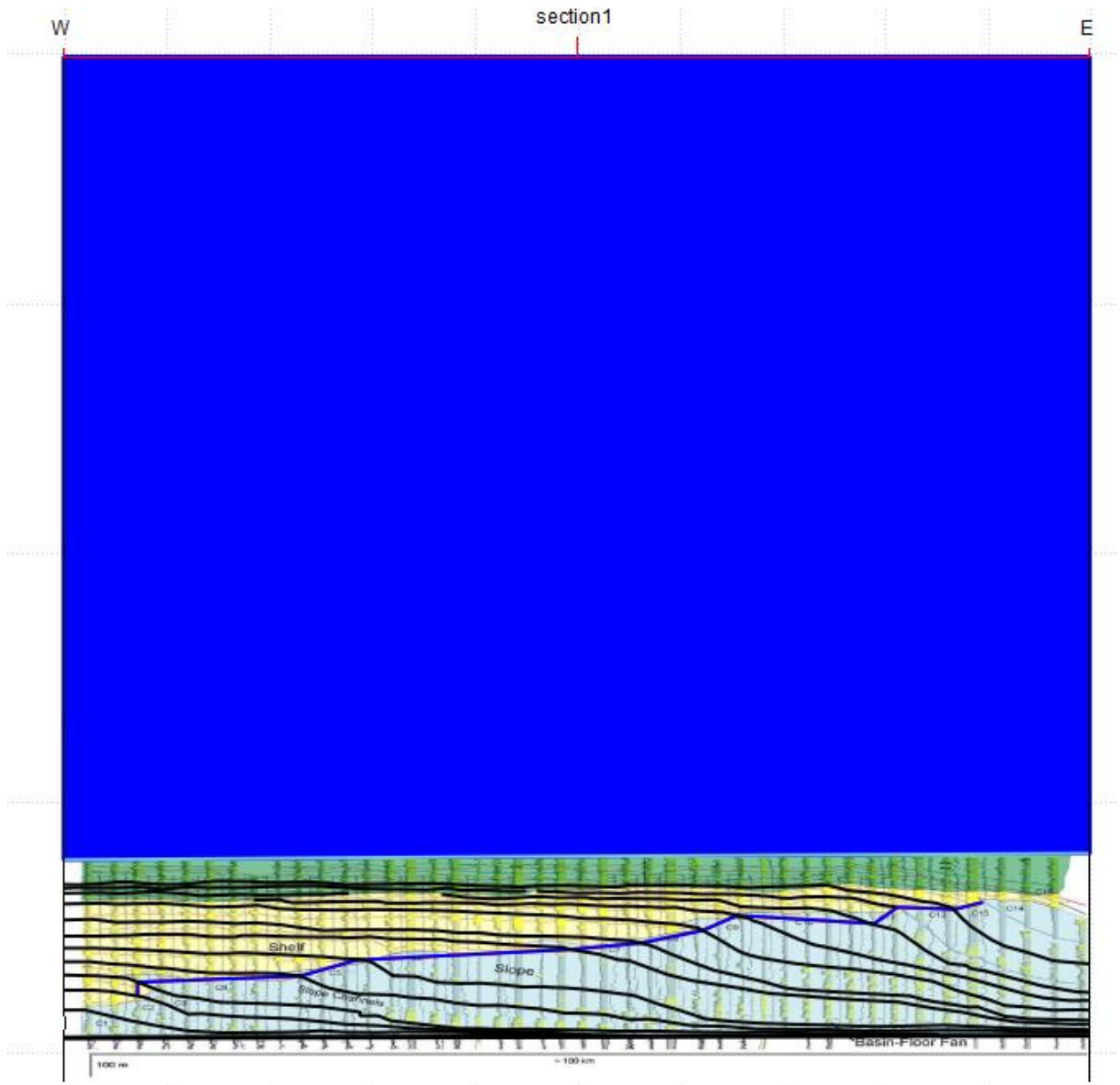


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- 317 2) The image is imported into Midland Valley Move software and scaled appropriately.
318 The basinal overburden is added (in this case 3300 m).

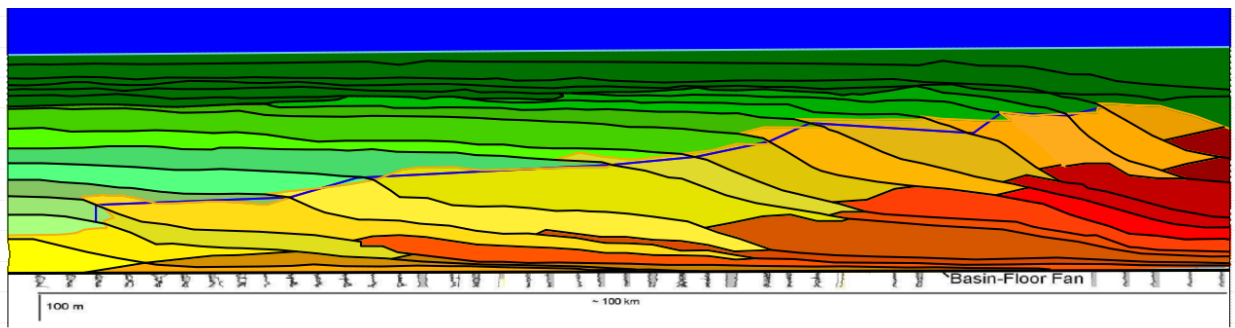


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320 3) Horizons are constructed to delineate clinothems. The overburden is constructed
321 (blue).



322
323
324

4. A polygon is constructed for each topset (green), foreset (yellow) and bottomset (red) compartment in the succession.



325

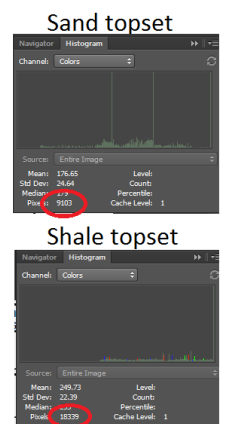
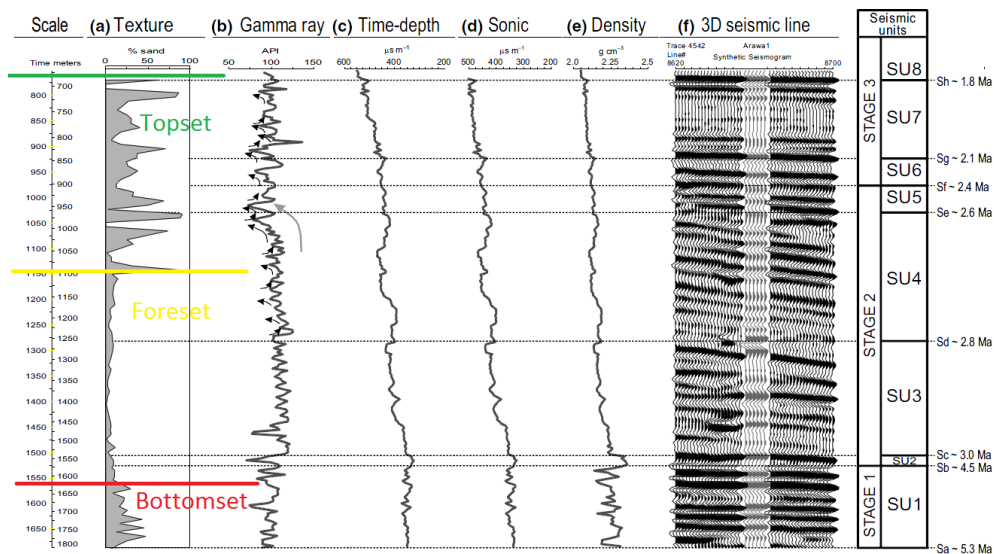
326 5a. Vshale ratios are obtained from literature, in this case (Carvajal and Steel 2012).

Table 7.1. Clinothem (C) volumes for sandstone (Vss), shale (Vsh), and coal (Vc). TOP = topset, SL = slope, BF = basin floor, and TOT = total (compartment areas may overlap, for instance at the shelf edge, see Fig. 7.4)

	A	Vss	Vss	Vsh	Vsh	Vc	TOT	TOT	Ss/Sh	Ss	Sh	TOT
	km ²	km ³	%	km ³	%	km ³	km ³	%	ratio	Mass	Mass	Mass
										× 10 ⁹ ton	× 10 ⁹ ton	× 10 ⁹ ton
1	TOP	0	0.0	0.0	0.0	0.0	0.0	0		0.0	0.0	0.0
	SL	71	1.3	23.7	4.8	5.0	6.1	6	0.28	2.2	11.0	13.3
	BF	8708	4.3	76.3	90.6	95.0	94.8	94	0.05	7.1	210.1	217.2
	TOT		5.6		95.4		100.9		0.06	9.4	221.1	230.5
2	TOP	159	2.2	8.9	4.4	3.8	6.7	5	0.50	3.7	10.3	14.0
	SL	403	12.1	48.4	27.5	23.5	39.7	28	0.44	20.4	63.9	84.2
	BF	8217	10.7	42.7	85.1	72.7	95.8	67	0.13	17.9	197.3	215.2
	TOT		25.0	100.0	117.1	100.0	142.1		0.21	42.1	271.4	313.5
3	TOP	234	5.6	33.2	5.1	3.4	10.8	6	1.10	9.4	11.9	21.3
	SL	1312	11.2	66.1	73.3	48.8	84.5	51	0.15	18.8	170.1	188.9
	BF	7308	0.1	0.7	71.8	47.8	71.9	43	0.00	0.2	166.4	166.6
	TOT		16.9	100.0	150.2	100.0	167.2		0.11	28.4	348.4	376.8
4	TOP	1688	24.8	24.7	33.2	9.6	58.4	13	0.75	41.6	77.0	118.6
	SL	1656	26.3	26.3	121.8	35.2	148.1	33	0.22	44.3	282.4	326.6
	BF	6888	49.1	49.0	191.2	55.2	240.3	54	0.26	82.5	443.4	525.9
	TOT		100.2	100.0	346.2	100.0	446.8		0.29	168.3	802.8	971.1
5	TOP	1916	39.4	54.9	75.4	20.5	114.8	26	0.52	66.2	174.7	240.9
	SL	1960	12.6	17.6	144.0	39.3	156.6	36	0.09	21.2	334.0	355.2
	BF	5131	19.7	27.5	147.4	40.2	167.2	38	0.13	33.2	341.8	375.0
	TOT		71.7	100.0	366.8	100.0	438.6		0.20	120.5	850.6	971.1
6	TOP	3008	68.0	43.7	111.7	23.4	180.0	28	0.61	114.3	259.0	373.3
	SL	2804	21.7	13.9	203.5	42.6	225.2	36	0.11	36.5	471.9	508.4
	BF	4059	65.9	42.3	163.0	34.1	228.9	36	0.40	110.7	378.0	488.7
	TOT		155.6	100.0	478.2	100.0	634.1		0.33	261.4	1108.9	1370.4
7	TOP	3394	55.6	65.6	98.4	37.9	154.3	45	0.57	93.5	228.2	321.7
	SL	2125	10.4	12.3	80.8	31.1	91.3	26	0.13	17.5	187.4	204.9
	BF	3645	18.8	22.2	80.5	31.0	99.3	29	0.23	31.6	186.8	218.3
	TOT		84.8	100.0	259.8	100.0	344.9		0.33	142.5	602.4	744.9

327

328 5b. In case Vshale numbers cannot be obtained from literature, they are derived from
 329 images of published well logs using image compartmentalization and color segmentation
 330 tools (magic wand tool in Adobe Photoshop). Number of pixels is counted in order to
 331 determine the relative contribution of sand vs shale. Example: Taranaki Basin, log published
 332 in (M. Salazar et. al 2015).

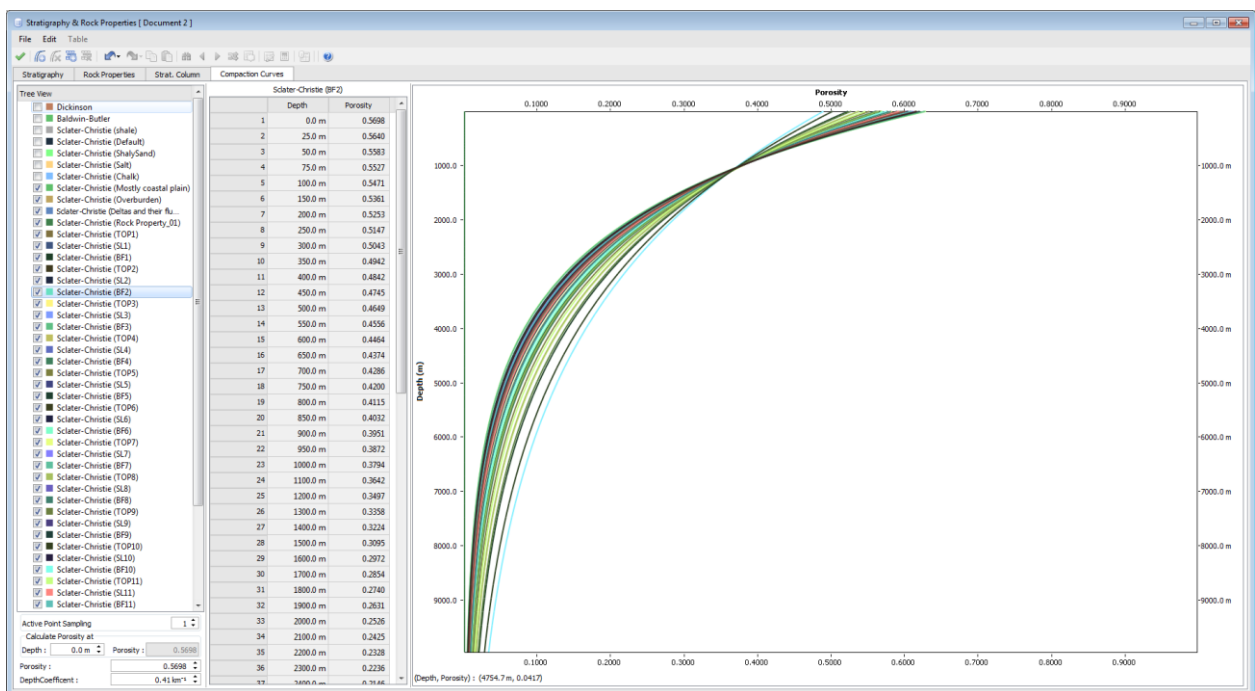


Vshale topset=33%

333

334 6. A Vshale number is designated for each compartment. Afterwards, compartmental
 335 compaction curves are constructed using empirically derived compaction relations from
 336 Sclater Christie, 1980: $f = f_0(e^{-cY})$ Where f is present day porosity at depth, f_0 is the
 337 porosity at the surface, c is the porosity-depth coefficient (km^{-1}) and Y is depth. The
 338 percentage of sandstone and shale is converted into surface porosities and depth coefficient
 339 values using the average decompaction values for North Sea sediments by Sclater and
 340 Christie (1980). The initial sandstone and shale percentages are multiplied by the
 341 appropriate surface porosity and compaction coefficient values from Sclater and Christie
 342 (1980). This resultant value (c) is used as the input value for the parameters in the
 343 decompaction algorithm.

344



345

346 7. Non-sequential compaction of the succession overburden is applied. During each
 347 decompaction experiment, 100-500 equally spaced, one-dimensional vertical columns along
 348 the succession are constructed. Afterwards, the overburden is backstripped. Volume
 349 increase is calculated by upscaling the length of the columns based on reducing porosity loss
 350 in accordance with the porosity/depth relation. The following animation shows non-
 351 sequential decompaction of the Washakie Basin dataset. The overburden was decompacted
 352 in three phases in order to show intermediate stages of non-sequential compaction. (Double
 353 click to open animation).



Non-sequential decompaction.mp4

354

355 8. Afterwards, each clinothem is decompacted successively starting from the youngest, most
356 distal to the oldest, most proximal clinothem. The following animation shows sequential
357 decompaction of the Washakie Basin dataset. In this example, polygons are visualized.
358 Section is from (Koo et al. 2016). (Double click to open animation).



Sequential decompaction.mp4

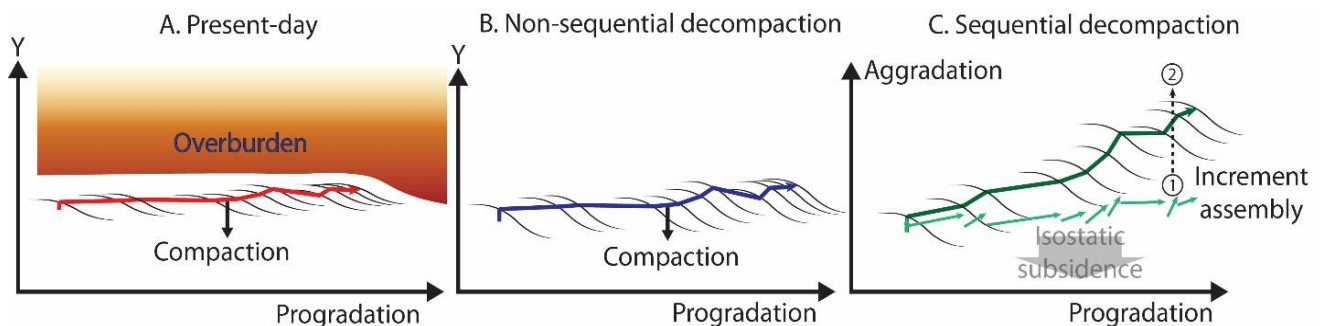
359

360 9. After each phase of decompaction, the position and orientation of every reconstructed
361 trajectory increment, one for every clinothem, is recorded.

362 10. Trajectory increments are assembled end-to-end. This corrects for the isostatic
363 readjustments that occur after each step. These Isostatic readjustments due to unloading
364 are calculated through applying an Airy isostasy (Airy, 1856). The following relation is
365 applied:

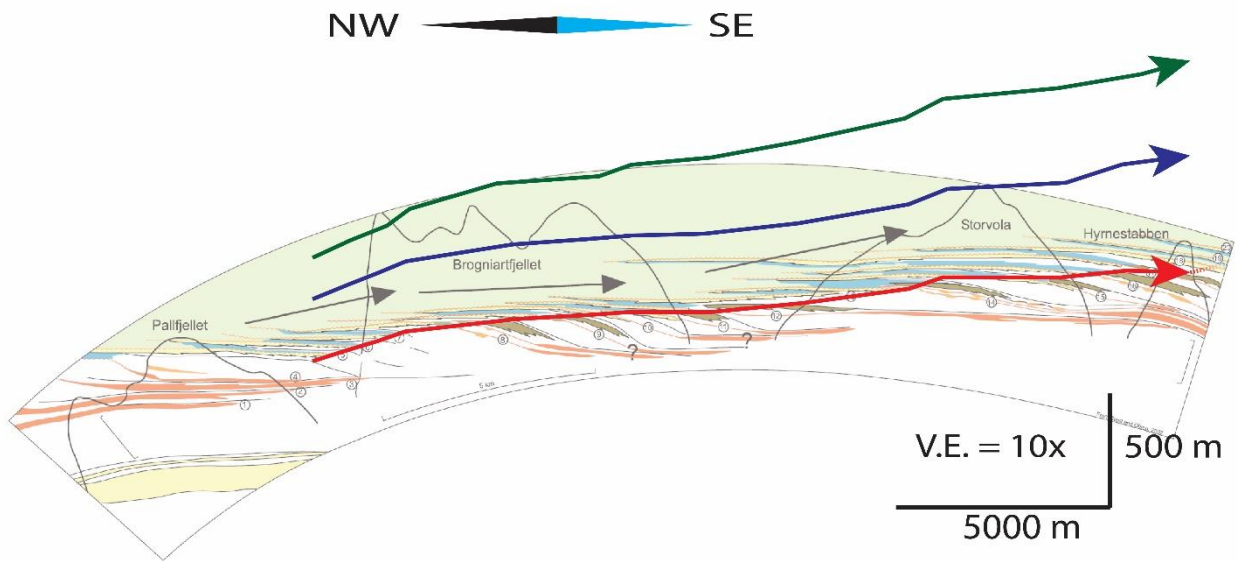
$$370 \quad Z = \frac{S - (H1 - H2)\rho_c - \rho_w}{\rho_m - \rho_w}$$

366 Where Z is the amount of subsidence (relative to a basement datum), S is the thickness of
367 the unloaded sediment. $H1$ is crustal thickness before sediment load, $H2$ crustal thickness
368 after sediment load. ρ_c , ρ_m and ρ_w are the densities of crust, mantle and water respectively.
369 As indicated by these models.



371

372 11. The present-day trajectory is compared to the non-sequentially and sequentially
 373 decompacted trajectories. Example: van Keulenfjorden (Steel and Olsen 2002).



374

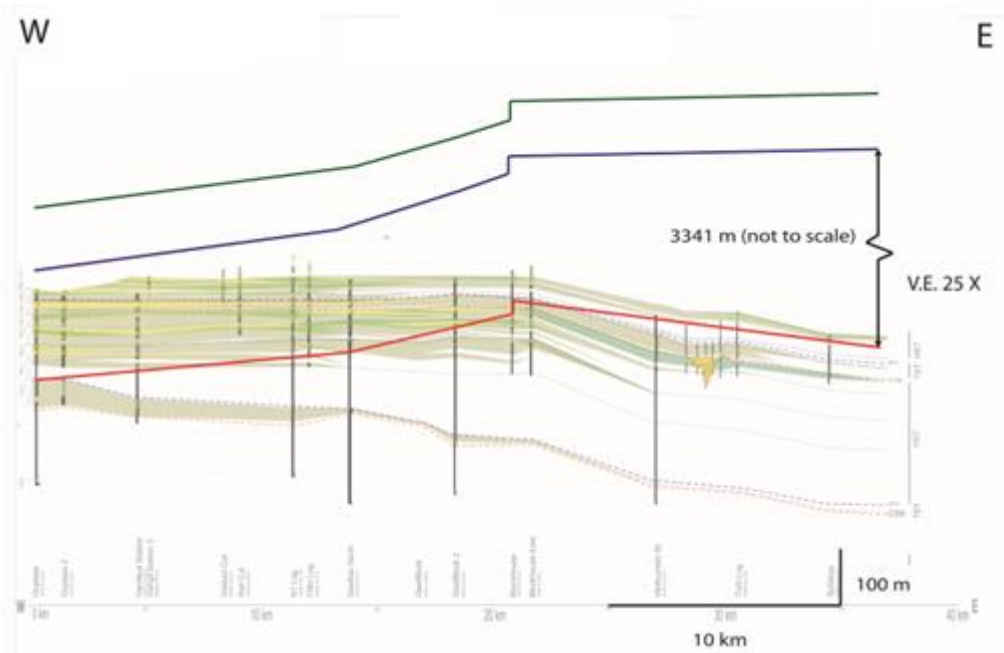
375

376 **Supplementary information 2**

377

378 Karoo, Ecca Group

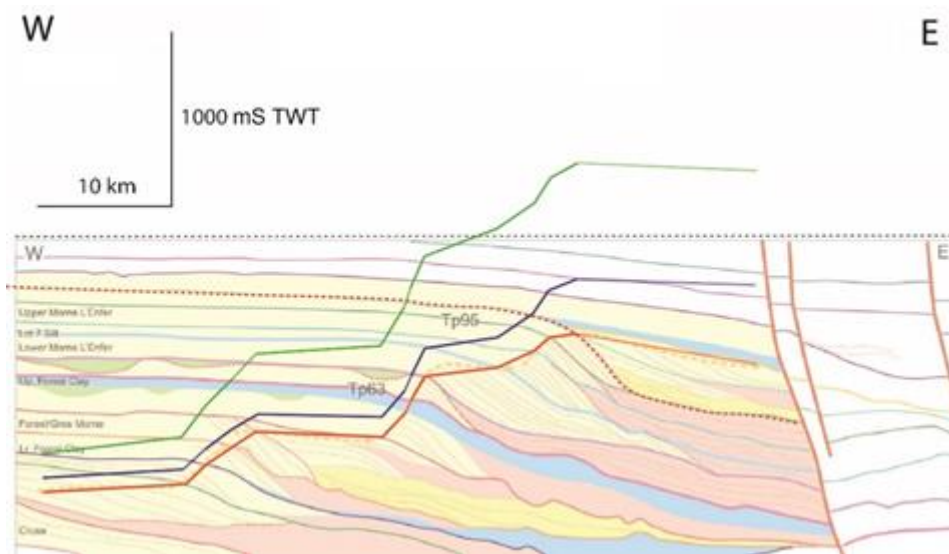
379 Removal of the 6300-meter overburden displaces the trajectory significantly. Moreover, Trajectory
 380 gradients are increased by decompaction. The main observation is that the slightly falling -0.30°
 381 distal end of the Bavians-North profile (w/c 5,6,7,8) is adjusted to a 0.05° flat trajectory (figure 11).
 382 Sequential decompaction indicates no significant alteration of syn-depositional clinoform
 383 geometries. A third observation is a loss of curvature and general flattening in the geometry of the
 384 unit F formation; the oldest formation in the Ecca-group clinoformal succession (Jones et al., 2015).



385

386 Columbus Basin

387 The Columbus Basin profile illustrates a stepwise aggradation dominated/progradation dominated
388 shelf-edge trajectory. Because there is a limited overburden, there is only a small change in the
389 trajectory following non-sequential decompaction. Sequential decompaction causes an overall
390 increase in gradient with a downward to upward trajectory adjustment in the fourth sequence of the
391 succession (TP44). Extremely steep sequentially decompacted trajectory intervals indicate extensive
392 aggradation, this is further exaggerated following decompaction. Note that the profile is not depth-
393 converted, this means that the absolute values for trajectory angles cannot be determined,
394 relative alterations in gradient and orientation after decompaction can however be recognised.



395
396

397 Chen, S., Steel, R.J. and Olariu, C., 2016. Upper-slope to shelf-edge delta architecture,
398 Miocene Cruse Formation, Orinoco shelf margin, Trinidad. *Journal of Sedimentary*
399 *Research*, 86(2), pp.87-106.
400 JONES, G. E., HODGSON, D. M. & FLINT, S. S. 2015. Lateral variability in clinoform trajectory, process
401 regime, and sediment dispersal patterns beyond the shelf-edge rollover in exhumed basin
402 margin-scale clinofans. *Basin Research*, 27, 657-680.
403 Poyatos-Moré, M., Jones, G.D., Brunt, R.L., Hodgson, D.M., Wild, R.J. and Flint, S.S., 2016.
404 Mud-dominated basin-margin progradation: processes and implications. *Journal of*
405 *Sedimentary Research*, 86(8), pp.863-878.

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