

1 A satellite-monitoring research agenda for urban stormwater
2 infrastructure: capabilities, gaps, and a
3 community-benchmark proposal

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9 **Abstract**

10 Urban stormwater best management practices (BMPs) are a core component of urban-resilience
11 portfolios worldwide. Per-asset performance monitoring, however, is both limited and difficult
12 to enumerate at the global scale. We argue that publicly available satellite Earth observation has
13 reached the capability point at which the resulting accountability gap can be closed at portfolio
14 scale, and that the binding constraint on this transition is now community benchmark data rather
15 than satellite data. We identify three operational capabilities available now. First, Human-in-the-
16 loop segmentation efficiently yields survey-grade asset footprints. Second, the BMP type, histor-
17 ically the most difficult to discriminate, is recoverable from learned multi-physical embeddings.
18 Third, per-asset spectral departures beyond seasonality and regional weather are detectable. All
19 three capabilities share the same underlying gap: a lack of community benchmark data that limits

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20 operationalization. This is the single research-agenda priority capable of converting present-day
21 satellite capability into deployable accountability for a major class of urban environmental infras-
22 tructure that today operates with little per-asset verification.

23 **The accountability gap**

24 Urban stormwater best management practices (BMPs) are the engineered mechanisms through
25 which urbanized watersheds meet nutrient, sediment, and metals loading targets under regula-
26 tory frameworks such as the US Total Maximum Daily Load (TMDL) program¹. Driven by TMDL
27 and similar programs globally, retention ponds, detention basins, bioswales, and constructed wet-
28 lands are deployed at scale across jurisdictions and embedded in private development under post-
29 construction stormwater permits. These assets are subject to progressive aging, sediment and de-
30 bris accumulation, and a corresponding loss of treatment capacity over their service life²⁻⁴. Ex-
31 cess nitrogen and phosphorus alone are estimated to drain billions of US dollars per year from
32 the US economy through depressed property values, lost recreation, and elevated drinking-water
33 treatment costs^{5,6}. Despite the financial costs, asset performance monitoring remains rare and
34 fragmented^{7,8}.

35 The monitoring gap is structural in origin. Flow-weighted composite sampling at a single BMP
36 station needs flow measurements, chemical testing, and sample collections, all of which are expen-
37 sive to operate⁹. The most comprehensive public repository we could identify for urban stormwa-
38 ter, the International Stormwater BMP Database (IBMPDB)¹⁰, contains sustained inflow/outflow
39 monitoring for fewer than 800 sites, and we are not aware of any aggregated count of BMPs un-
40 der sustained monitoring at a national or global scale. Nation-scale enumeration is similarly par-
41 tial. The US EPA's Municipal Separate Storm Sewer System (MS4) Phase II permit, a Clean Water
42 Act programme regulating stormwater discharges from small MS4 operators, covers more than

43 6,800 entities, each typically managing hundreds to thousands of post-construction BMPs, with
44 operations-and-maintenance, rather than design, failure dominating performance loss in those set-
45 tings where it has been studied^{11,12}. Regulatory compliance, in the absence of sustained monitor-
46 ing, relies on static, type-averaged removal efficiencies drawn from the literature, with no account
47 taken of site-specific hydrology, maintenance history, or ecological transitions^{13,14}.

48 The accountability gap is widening. Cities across South and Southeast Asia are deploying stormwa-
49 ter infrastructure at unprecedented rates under sponge-city programs¹⁵, and analogous national
50 urban-resilience missions (such as Indonesia’s National Urban Flood Resilience Project and In-
51 dia’s Atal Mission for Rejuvenation and Urban Transformation (AMRUT) 2.0) are extending to
52 sub-Saharan Africa and Latin America through multilateral climate-adaptation finance from the
53 World Bank and Green Climate Fund^{16,17}. These programs embed measurement, reporting, and
54 verification (MRV) requirements that track project-level outcomes; meeting MRV at the per-asset
55 resolution where performance loss occurs is currently infeasible by in-situ means at scale. In many
56 recipient cities, structured BMP monitoring is sparse, and asset inventories are unevenly covered.
57 The verification gap appears widest in precisely those settings where the deployment rate is high-
58 est.

59 This Perspective advances three claims. **First**, satellite Earth observation has reached a point where
60 portfolio-scale BMP accountability is technically feasible, as we demonstrate in a 36-site empirical
61 pilot. **Second**, each capability is accompanied by a caveat that does *not* identify a missing satellite,
62 sensor, or algorithm, but rather points to a single underlying gap. The field lacks a community
63 benchmark dataset comparable to those provided by CAMELS¹⁸ and Caravan¹⁹ for catchment hy-
64 drology. **Third**, the construction of such a benchmark, undertaken in partnership with the mu-
65 nicipal programs and multilateral funders that already manage these assets, is the single research-
66 agenda priority capable of converting capability into both regulatory deployment and scientific

67 tractability. Given the investment in these stormwater assets and the global stakes around their
68 performance, the incentive is high for the field to close this gap; this is a high-value, near-term
69 opportunity, and the resulting accountability would benefit both regulators and scientists.

70 **Where the satellite stack stands today**

71 Satellite Earth observation (EO) has closed analogous accountability gaps in agriculture^{20,21},
72 forestry^{22,23}, global surface-water extent²⁴, and inland water quality²⁵. These successes share
73 characteristics, namely large spatial extent and distinctive phenology, that stormwater BMPs lack.
74 Individual BMP footprints are small, often <2 ha, are spectrally similar to adjacent greenspace,
75 and have no shared management calendar. The remote-sensing community has accordingly given
76 them comparatively little attention, despite their dominant role in engineered nonpoint nutrient
77 removal in developed watersheds.

78 Several elements of the satellite and climate-reanalysis stack have nonetheless matured over the
79 past decade: free 10-m optical imagery (Sentinel-2) at sub-weekly revisit, cloud-penetrating C-
80 band synthetic-aperture radar (SAR; Sentinel-1), ERA5-Land global climate reanalysis²⁶, PRISM
81 4-km gridded climate over the conterminous United States²⁷, and sub-meter commercial imagery
82 (PlanetScope, SkySat, Airbus) at task-on-demand cadence. To this stack has recently been added
83 AlphaEarth Foundations, a 64-dimensional per-pixel learned embedding that distills Sentinel-2,
84 Sentinel-1 SAR, Landsat, and ERA5-Land observations into a globally consistent multi-physical
85 representation²⁸. The resulting stack is freely available, global, and operational.

86 The fundamental difficulty of the BMP target itself, by contrast, has not changed. The asset is
87 small relative to the satellite footprint, surrounded by spectrally similar land cover, and its pri-
88 mary function—removal of dissolved pollutants from water—is rarely visible in optical reflectance.
89 Closing the accountability gap, therefore, requires what we term *operational decomposition*: separat-

90 ing the questions a satellite can plausibly answer with today’s sensors (where the asset is, what
91 type it is, whether its state has changed) from those it cannot (the instantaneous concentration
92 of its outflow). Each of those operations interacts differently with the choice of feature substrate—
93 spectral indices, raw spectral bands, or learned embeddings—and the substrate that is appropriate
94 for one operation may be wrong for another. We treat the resulting substrate–operation matrix as
95 an organizing principle for satellite-based BMP monitoring.

96 We illustrate this organizing principle with a 36-site empirical pilot across 12 US states, comprising
97 25 retention ponds, 7 wetland basins, and 4 detention basins observed during 2018–2024 (Meth-
98 ods and Supplementary Tables S1–S3). The pilot is intended as a capability test rather than a
99 deployment. Given the limited sample size and the class imbalance across BMP types, the numer-
100 ical results that follow should be read as existence proofs of operational tractability rather than as
101 generalization estimates of deployable accuracy. Within that interpretive frame, three capabilities
102 emerge in sequence, each accompanied by a caveat that identifies the binding constraint preventing
103 its full operational realization.

104 **Capability 1: Inventory is deployable today**

105 We delineated all 36 BMP sites in 0.6-m National Agriculture Imagery Program (NAIP) four-band
106 imagery using the Segment Anything Model (SAM, ViT-H backbone)²⁹ as implemented in `sam-`
107 `geo`³⁰. The workflow is human-in-the-loop at the labeling stage. SAM’s automatic mask generator
108 (ViT-H backbone, 12-point-per-side grid; Supplementary Methods) segments each NAIP tile into
109 candidate objects without prompts, and an operator then selects the segment corresponding to
110 the BMP and labels three to four adjacent reference objects (tree, grass, crop, impervious, open
111 water); the labeled polygons are saved as GeoJSON. Multi-component sites yielded 75 polygons
112 across the 36 sites, spanning approximately 500 m² to 8.26 ha (median 0.37 ha; Supplementary Fig-

113 ure S1). Labeling required, on average, less than 2 minutes per site. The polygons are released
114 as GeoJSON and, to our knowledge, constitute the first publicly available footprint dataset for this
115 number of monitored BMPs, since the IBMPDB contains only point coordinates, and municipal
116 asset databases are non-uniform in coverage.

117 A two-minute-per-site labeling rate is sufficient to inventory thousands of post-construction BMPs
118 over a period of days, rather than the months required by ground-based surveying. We used
119 U.S. National Agriculture Imagery Program (NAIP) imagery³¹. NAIP coverage is restricted to the
120 United States. Outside the United States, Planet Skysat and other commercial very-high-resolution
121 archives³² provide functionally equivalent inputs. The inventory capability is therefore operational
122 at portfolio scale today.

123 Full automation, in which the BMP segment is identified among SAM's candidate masks without
124 the operator's selection-and-labeling step, would require a labeled training set on the order of hun-
125 dreds to thousands of BMPs in order to fine-tune the foundation model for what is a small-target,
126 low-contrast detection task, and a training set of that scale does not yet exist in the public domain.
127 The 36-polygon dataset released alongside this article constitutes an initial contribution toward
128 such a corpus rather than a sufficient one.

129 **Capability 2: Type is recoverable from the spectral-temporal substrate**

130 BMP type determines hydrologic function and the expected biogeochemical pathway. Common
131 BMP types include: Retention ponds (RP) that maintain a permanent pool with stable surface
132 water; detention basins (DB) that drain dry between events and exhibit pronounced vegetation
133 seasonality; and wetland basins (WB) that maintain a dynamic stage driven by both temperature
134 and hydroperiod. The taxonomy contains numerous additional types, and we have selected these
135 three as representative examples. Municipal asset databases lack standardized type-coding con-

136 ventions, so any portfolio-scale monitor must first answer “*what kind is this?*” solely from imagery.
137 Whether the spectral-temporal substrate carries enough information to do so has been an open
138 question.

139 We evaluated three feature substrates in direct comparison on the 36-site pilot. Track A consists of
140 six commonly used handcrafted indices (NDVI, NDWI, EVI, SAVI, NDMI, BSI) paired with 100-m
141 annular-buffer residuals (BMP minus buffer, to remove regional context variance; Supplementary
142 Methods), yielding 36 features per site. Track B comprises the BMP-side annual means of the
143 12 raw Sentinel-2 bands (12 features per site); separately, all 66 two-band normalized-difference
144 indices were screened univariately as a control (Supplementary Methods). Track C employs Al-
145 phaEarth Foundations’ annual 64-dim embeddings, mean-pooled per BMP polygon. For each
146 substrate, three pairwise type discriminations were scored by area under the receiver-operating-
147 characteristic curve (AUC) under leave-one-out logistic regression, with bootstrap confidence in-
148 tervals and permutation-null mutual information.

149 The result is unambiguous in direction (Fig. 1; Table 1). The handcrafted spectral substrate
150 (Track A) recovers the easier permanent-water-vs-vegetated-wetland pair but underperforms
151 on the detention-basin pairs. The raw Sentinel-2 bands together with an exhaustive search over
152 all 66 two-band normalized-difference indices (Track B) recover only the same easy pair, and
153 only marginally: no single data-derived index survives correction for the 66-index search, and
154 both detention-basin contrasts remain at chance. The difficulty, therefore, lies in discriminating
155 between detention basins, which no linear treatment of the spectral bands can resolve. The
156 learned multi-physical substrate (Track C) clears all three pairwise discriminations above chance,
157 including the wetland-vs-detention pair that hinges on hydroperiod and surface-water dynamics.
158 Post-hoc per-site correlations confirm that the AlphaEarth axes are physically grounded, with
159 individual axes tracking vegetation greenness, water-vs-vegetation contrast, and bare-soil and

160 moisture signatures (Supplementary Table S9). The 64-dimensional representation contains the
 161 physical signals that hand-crafted indices encode, along with Sentinel-1 SAR backscatter and
 162 ERA5-Land climate context, which are absent from optical-only indices.

163 The numerical AUCs at this n are not generalization estimates. The wetland-vs-detention discrim-
 164 ination is evaluated on 11 sites, and the retention-vs-detention discrimination on 29 sites, with a
 165 25/7/4 imbalance overall. The pilot establishes that the *substrate carries the information*. To deter-
 166 mine the field’s achievable classifier accuracy in deployment, a substantially larger labeled sample
 167 is required. A *deployable* type classifier, as distinct from substrate-level recoverability, would re-
 168 quire hundreds of labeled BMPs across the type taxonomy and climate–hydrology gradient. The
 169 IBMPDB’s 820 BMPs lack standardized type labels and polygon footprints. Assembling a labeled
 170 training set is therefore a benchmarking task rather than a satellite-engineering one.

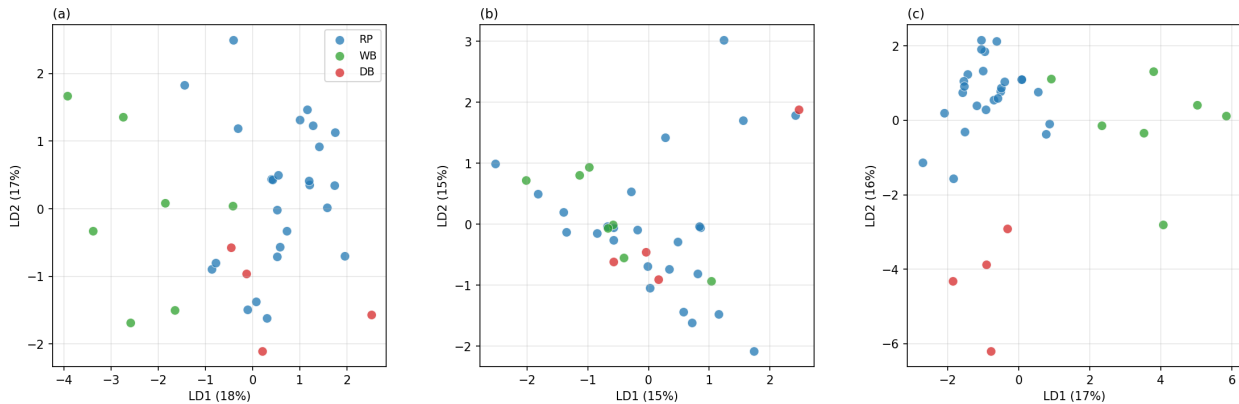


Figure 1: Fig. 1 | BMP type information is recoverable from learned multi-physical substrates. Linear discriminant analysis projects each per-site feature vector onto the two axes that maximize between-class versus within-class variance. (a) Hand-crafted indices (Track A); WB and DB are partially separate from RP but not from each other. (b) Raw S2 bands (Track B); little structure is evident. (c) AlphaEarth (Track C) shows visible three-way separation, with DBs concentrated in a distinct lower-left region, consistent with the Track C AUCs reported in Table 1. Per-site classification confidence on Track C ranges from 0.00 to 1.00, with 21 of 36 sites at confidence > 0.85 and three sites at confidence < 0.30 (Supplementary Table S4).

Table 1: Table 1 | Pairwise type-discrimination AUC (95% bootstrap CI) and mutual-information permutation p-value, per substrate.

Pair	Track A (hand-crafted indices)	Track B (S2 raw bands)	Track C (AlphaEarth, 64-d)
RP-vs-WB ($n = 32$)	AUC 0.87 (0.70–1.00) , $p = 0.052$	AUC 0.65 (0.38–0.87), $p = 0.42$	AUC 0.79 (0.55–0.98), $p = 0.008$
WB-vs-DB ($n = 11$)	AUC 0.57 (0.18–0.90), $p = 0.54$	AUC 0.29 (0.00–0.67), $p = 0.33$	AUC 1.00 (1.00–1.00) , $p = 0.004$
RP-vs-DB ($n = 29$)	AUC 0.36 (0.07–0.69), $p = 0.79$	AUC 0.04 (0.00–0.15), $p = 0.83$	AUC 0.71 (0.33–0.96) , $p = 0.052$

171 **Capability 3: Within-asset change is detectable beyond seasonality and weather**

172 Change detection is the operational endpoint of portfolio-scale monitoring. Inventory establishes
 173 which assets exist; type identifies their intended hydrologic function; only change detection estab-
 174 lishes whether that function is being maintained. The empirical difficulty is that the failure modes
 175 of interest, such as sediment accumulation, vegetation overgrowth or die-off, outlet clogging, and
 176 partial structural failure^{3,33,34}, produce spectral signatures that are small relative to the seasonal cy-
 177 cle and the regional weather variability common to every BMP regardless of condition, generating
 178 the false-positive load that has discouraged prior remote-sensing efforts at this asset class.

179 Distinguishing asset-specific signal from regional context is therefore the central methodological
 180 problem of this capability. We address it through a two-stage residualization that targets the two
 181 dominant sources of shared variance: (i) the recurring annual cycle and any long-term drift at the
 182 asset itself, and (ii) the asset’s response to the regional climate context shared with surrounding
 183 land cover. Sequential removal of these components yields a per-asset, per-feature residual whose

184 remaining variance cannot be attributed to season, drift, or shared weather, and on which the
185 change-detection question can be posed.

186 Concretely, for each (site, role, feature) on the monthly tracks, a per-asset harmonic regression

$$y_t = a + bt + c \sin(2\pi t/12) + d \cos(2\pi t/12) + \varepsilon_t$$

187 is fit to the 2018–2024 series, and the residual ε_t is retained. The BMP-and-buffer paired differ-
188 ential of these residuals is then regressed against PRISM monthly precipitation and temperature
189 anomaly z-scores at lags of 0, 1, and 3 months, and the second-stage residual η_t is retained as the
190 BMP-specific spectral departure. The within-site temporal standard deviation $\tilde{\sigma}$ of η_t furnishes a
191 per-asset, per-feature noise floor that adapts to portfolios spanning an order of magnitude in size,
192 surrounding land cover, and local climate. Variance accounting for the two stages (Supplemen-
193 tary Table S8) confirms both contribute, with substrate-dependent asymmetry. The pipeline runs
194 identically when ERA5 reanalysis is substituted for PRISM, the natural global generalization.

195 We aggregate the standardized residuals across substrate-internal features into a root-mean-square
196 z-score

$$M_t = \sqrt{\text{mean}_f \left[(\eta_{f,t} / \tilde{\sigma}_f)^2 \right]}$$

197 and define an event as a maximal contiguous run of $M_t > 1.5$ persisting for ≥ 2 periods. Both
198 the threshold and the persistence requirement are illustrative defaults at pilot scale and would be
199 tuned to portfolio characteristics and operator risk tolerance in deployment. The squared-deviation
200 aggregation yields interpretive consistency across substrates of different feature counts (6, 12, or
201 64).

202 Results across the 36-site pilot are summarized in Fig. 2 and Table 2, and they exhibit the diagnostic

203 behavior of a sensitive but not yet specific monitor. The monthly substrates flag within-asset depar-
204 tures at 44–61% of sites, a portfolio-level rate too high to act upon without further triage; raising the
205 threshold suppresses the small genuine signals that motivate the monitoring effort. We address
206 triage through a second filter, *cross-substrate consistency*, defined as the same site being flagged by
207 another substrate within ± 6 months. The premise is that a real condition change should leave a
208 coordinated fingerprint across feature representations, with the underlying physical mechanisms
209 (water encroachment, vegetation stress, surface darkening, sediment plume settling) affecting dif-
210 ferent bands at temporally offset lags rather than simultaneously. In the present pilot, the resulting
211 shortlist comprises four physical assets: Shop Creek Pond (RP, CO), Carver County Dry Detention
212 Pond (DB, MN), Cottonwood Wetlands (WB, CO), and Natomas Basin 4 (RP, CA), with event sig-
213 natures detailed in Supplementary Table S6. Because Tracks A and B both derive from Sentinel-2
214 reflectance, this filter is a cross-substrate *consistency* check rather than independent confirmation.

215 The annual AlphaEarth substrate (Track C), which dominated the type-discrimination problem,
216 flags only one event across 2017–2024 and contributes zero cross-substrate-consistent events when
217 paired with the monthly tracks. The binding constraint is temporal cadence, not substrate quality:
218 the annual representation cannot resolve the monthly variability that within-asset change detec-
219 tion requires. This is an artifact of AlphaEarth’s annual release rather than a limitation of learned
220 multi-physical representations; foundation models such as Clay³⁵ and Prithvi^{36,37} operate at finer
221 cadence and could in principle support both operations from a single representation. The broader
222 point for benchmark design holds nonetheless. No single representation is simultaneously op-
223 timal across the inventory, type, and change-detection operations at the cadences each requires,
224 and the appropriate substrate must therefore be selected per operation rather than chosen once for
225 the portfolio. A community benchmark must accommodate the full range of cadences and feature
226 dimensionalities in the satellite stack, rather than tuning to whichever representation happens to

227 dominate a single benchmark task. Complete event listings for all three substrates are provided in
 228 Supplementary Tables S5–S6.

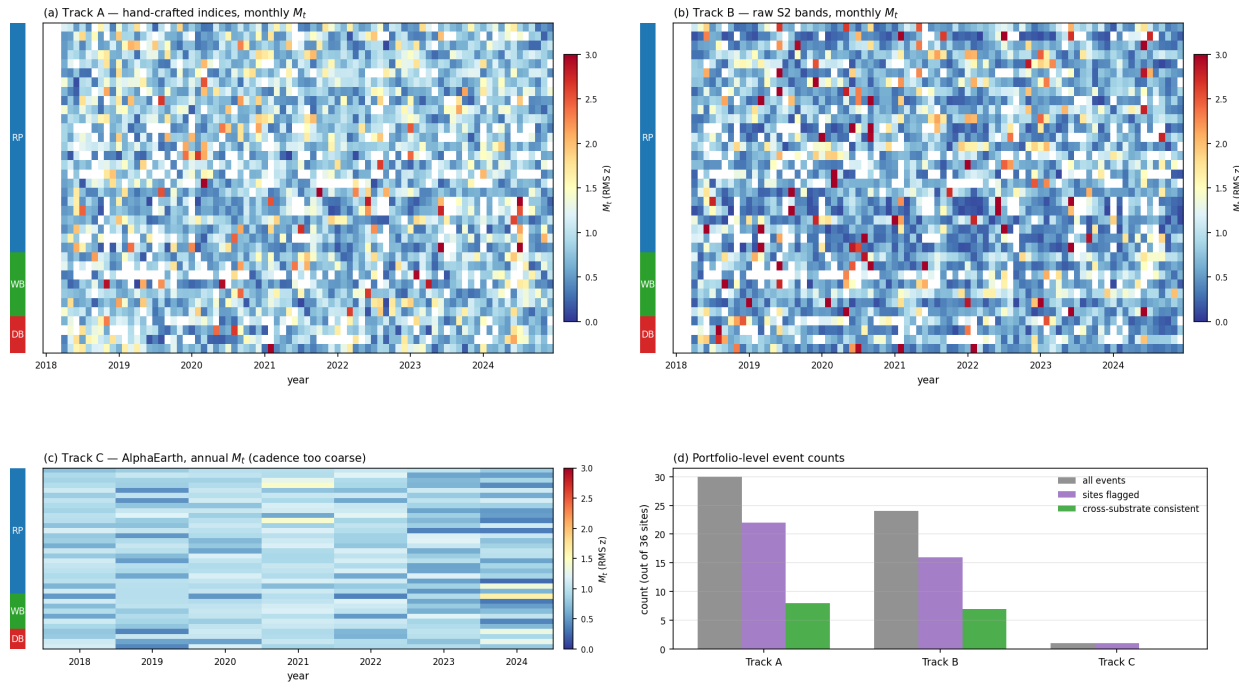


Figure 2: Fig. 2 | Within-asset departures are detectable from monthly spectral substrates after two-stage residualization. (a, b) Per-site monthly departure magnitude M_t (RMS z-score across substrate-internal features) for Track A (hand-crafted indices) and Track B (raw S2 bands), 2018–2024; rows are sites grouped by type (RP/WB/DB), and columns are months. Red cells exceed the $M_t > 1.5$ event threshold. (c) Track C (annual AlphaEarth) over the same site set, illustrating that the annual cadence is too coarse to surface within-asset events. (d) Portfolio-level event counts per substrate, including total events, sites flagged, and cross-substrate-consistent events (a site flagged by another substrate within ± 6 months). The substrate that performs best on type discrimination (Track C) is the substrate least suited to change detection at the relevant timescale, and temporal cadence is the dimension along which this trade-off is most evident.

Table 2: Table 2 | Per-substrate change-detection portfolio summary. Cross-substrate consistency is defined as another substrate flagging the same site within ± 6 months (or within the same year for Track C). Five IBMPDB BMPIDs corresponding to four physical assets carry consistent events; Shop Creek Pond is one physical asset monitored across two non-overlapping IBMPDB epochs.

Substrate	Cadence	Events	Sites flagged (% of 36)	Cross-substrate consistent events
Track A (hand-crafted indices)	monthly	30	22 (61%)	8

Substrate	Cadence	Events	Sites flagged (% of 36)	Cross-substrate consistent events
Track B (S2 raw bands)	monthly	24	16 (44%)	7
Track C (AlphaEarth, 64-d)	annual	1	1 (3%)	0

229 A flagged event is not an identified cause. Sediment accumulation, vegetation overgrowth, out-
230 let clogging, scheduled mowing, planned retrofit, and climate stress can all produce residualized
231 departures of similar magnitude and duration. Attribution requires *paired field-condition records* (in-
232 spections, maintenance logs, bathymetric and vegetation surveys) at scale and with explicit dating,
233 which exist within individual operating jurisdictions but have not been aggregated into a commu-
234 nity resource. In each of the three capabilities, satellite capability terminates where ground-paired
235 data is required; the limiting factor is the community’s data infrastructure, not the satellite stack.

236 At Cottonwood Wetlands, the only pilot site with continuous water-quality monitoring overlap-
237 ping the satellite era (391 outflow records across five analytes, 2018–2022, aggregated to monthly
238 medians), monthly outflow nitrogen and phosphorus correlate strongly with raw spectral state
239 but collapse to $|r| \leq 0.221$ after harmonic deseasonalization (Supplementary Fig. S2). The case
240 bounds what single-site spectral monitoring can deliver against ground truth: seasonal coupling
241 is recoverable, within-season concentration is not³⁸. A single coupling at a single site cannot sub-
242 stitute for the population-level relationships a community benchmark would reveal.

243 **The binding constraint and a community-benchmark response**

244 Each of the three preceding capability assessments terminates at the same boundary. Inventory au-
245 tomation requires labeled BMP polygons at scale; type classification requires more labeled BMPs
246 distributed across the climate–hydrology gradient; and change attribution requires paired field-
247 condition records with explicit dating. None of these requirements represents a satellite-side limi-
248 tation, and each of them represents a community-data limitation.

249 Catchment hydrology faced an analogous bottleneck a decade ago. CAMELS¹⁸ and its global exten-
250 sion Caravan¹⁹ assembled standardized large-sample bundles of catchment attributes paired with
251 hydrometeorological time series. The community-benchmark format unlocked a body of work that
252 fragmented per-study datasets could not previously support. Among the contributions that fol-
253 lowed are large-sample LSTM rainfall-runoff models that outperformed conceptual process-based
254 hydrology³⁹, prediction in ungauged basins, hydrologic-similarity classification, and large-sample
255 diagnosis of those regimes in which conceptual models systematically fail. The cost of CAMELS
256 was assembly rather than collection, since most of the constituent records already existed, scattered
257 across agencies and formats, and the scientific dividend has continued to compound with growth.
258 The same pattern repeated in inland water-quality remote sensing with AquaSat⁴⁰, which paired
259 in-situ samples with co-located satellite reflectance and unlocked a body of EO-based water-quality
260 work that per-study datasets had not supported.

261 The scientific dividend of an analogous benchmark for urban stormwater would be of the same
262 character. Whether the type-averaged removal efficiencies that anchor TMDL regulation are empir-
263 ically defensible at the population scale is today untestable; with paired type, climate, age, design,
264 and performance records across hundreds to thousands of BMPs, that question becomes tractable
265 with direct regulatory consequence. Within-type variance decomposition (the climate, mainte-

266 nance, design, and site-idiosyncratic share of asset performance) is similarly out of reach without
267 large-sample data. Failure-mode attribution mapping spectral departures to physical mechanisms
268 requires paired, dated condition records that do not exist at scale; without them, a portfolio screen
269 cannot serve as a diagnostic instrument. Method development across the operational decomposi-
270 tion is data-bottlenecked rather than algorithm-bottlenecked. Cross-study replication, today essen-
271 tially impossible because every BMP study employs its own protocol and pipeline, would become
272 routine once a standardized per-asset record exists. The benchmark would therefore carry dual
273 value: regulatory accountability for asset operators and funders, and scientific accountability for
274 the field's own claims about what BMPs do, under what conditions, and for how long.

275 Urban stormwater BMPs occupy the same position that the catchment-hydrology community
276 occupied before CAMELS. Records exist (IBMPDB monitoring data; municipal MS4 asset inven-
277 tories with maintenance histories; state department-of-transportation (DOT) BMP databases;
278 private-development as-builts; multilateral-funder MRV reporting), but they are fragmented,
279 non-standardized, and not paired with the satellite-derived attribute layers that data-driven
280 monitoring requires.

281 A CAMELS-for-stormwater benchmark would assemble, per asset, the following five layers.

- 282 1. **Delineated polygon footprints** (the limiting input for satellite-derived attribute extraction;
283 producible today by SAM in two minutes per site).
- 284 2. **Multi-sensor time series** (Sentinel-2 indices and bands; Sentinel-1 SAR; PlanetScope, where
285 available; AlphaEarth annual embeddings) extracted identically over the BMP footprint and
286 a standardized reference buffer.
- 287 3. **Type and design attributes** (drainage area, treatment volume, outlet configuration), com-
288 prising the static metadata that the IBMPDB already partially carries, in standardized form.

289 4. **Gridded climate context** (PRISM in the United States; ERA5-Land globally) at the lags the
290 residualization pipeline requires.

291 5. **Field-condition records with dates** (inspections, bathymetry, vegetation surveys, mainte-
292 nance interventions, retrofits, water-quality grab samples, and continuous monitoring where
293 available).

294 Layer 5 is the most institutionally distributed of the five. It is also the layer that converts spectral
295 departures into causal claims, and therefore the layer that converts the capability statement “satel-
296 lites can monitor BMPs” into deployable accountability. The institutional substrate for layer 5 may
297 already exist in distributed form. In the US, Municipal MS4 programs are required to maintain
298 inspection records; state DOTs operate hundreds to thousands of BMPs each under documented
299 maintenance schedules; and multilateral climate-adaptation finance (GCF, World Bank) is increas-
300 ingly conditioning disbursement on standardized MRV reporting. The inputs to a community
301 benchmark, therefore, already exist in jurisdiction-specific archives. What does not yet exist is the
302 assembly, harmonization, and curation effort that would render those archives collectively usable.

303 **Global stakes and a deployment pathway**

304 The benchmark gap is most acute in settings with the highest deployment rates. China’s sponge-
305 city program covers more than 30 pilot cities¹⁵; India’s AMRUT 2.0 mission funds urban stormwa-
306 ter and water-resilience infrastructure across more than 500 cities⁴¹; World Bank urban-resilience
307 portfolios are deploying multi-billion-dollar pipelines under MRV requirements that in-situ moni-
308 toring cannot meet at scale⁴²; and the Green Climate Fund’s nature-based-solutions windows carry
309 similar verification mandates. The satellites are in orbit, the climate reanalyses are running, and
310 the analytical framework demonstrated here is constructed from globally available inputs. The
311 next methodological step is replication of the residualization pipeline on global climate reanalyses

312 (substituting ERA5-Land for PRISM) in order to confirm transferability outside the conterminous
313 United States. Without a benchmark, the framework remains a capability rather than an account-
314 ability instrument.

315 Kigali (Rwanda) illustrates a near-term deployment pathway. The city has 37 inventoried urban
316 wetlands⁴³, World Bank-financed stormwater infrastructure⁴⁴, ESA satellite-monitoring support⁴⁵,
317 and newly engineered retention features whose construction signatures are well-suited to the
318 residualized anomaly pipeline. A Kigali-scale pilot would be small enough for first-principles
319 MRV instrumentation, large enough to populate a benchmark layer, and sufficiently high-leverage
320 to anchor a multilateral-funder verification standard. We highlight Kigali as illustrative rather
321 than exclusive, since analogous opportunities exist across South and Southeast Asian, sub-Saharan
322 African, and Latin American cities currently entering large-scale stormwater deployment cycles.

323 **A research agenda**

324 We propose three concrete actions, ordered by increasing scope.

- 325 1. **Standardize the per-asset record format.** A delineated polygon, a multi-sensor extraction
326 recipe, a climate residualization protocol, and an event/inspection schema should be pub-
327 lished openly so that independent groups can produce comparable records. The 36-site
328 dataset and code released with this Perspective offer a starting format.
- 329 2. **Aggregate existing records into a v0 benchmark.** The IBMPDB, municipal MS4 inventories,
330 state DOT BMP databases, and multilateral-funder MRV reports already contain layers 3–5
331 in fragmented form. Federation under a common schema, following the model that Car-
332 avan established by federating CAMELS, CAMELS-AUS, CAMELS-BR, CAMELS-CL, and
333 CAMELS-GB, can produce a v0 community resource at hundreds to low thousands of sites
334 within an achievable timeframe.

335 3. **Pair the benchmark with deployment partnerships.** A CAMELS-for-stormwater benchmark
336 without operational uptake will remain academic. Co-development with one or two MS4
337 programs, one state DOT, and one multilateral climate-finance window would tie benchmark
338 expansion to concrete verification needs and create the institutional pull required to sustain
339 data flow over time.

340 A major class of urban environmental infrastructure should not operate without per-asset veri-
341 fication, and the technical instruments required to address that condition (satellites, climate re-
342 analyses, learned global representations, and foundation-model segmentation) are now available
343 in operational form. What remains absent is the community-data substrate that would convert
344 those instruments into deployable monitoring and convert present-day spectral observations into
345 testable answers to population-scale scientific questions about how BMPs perform, age, and fail
346 under realistic operating conditions. We have argued that the assembly of such a substrate is a
347 tractable and time-bounded task, and that the response of the research and operating communi-
348 ties over the coming decade will determine whether urban stormwater accountability follows the
349 trajectory that catchment hydrology established with CAMELS in the 2010s, or instead remains a
350 structural blind spot through the urban-resilience deployment wave of the 2020s and 2030s.

351 **Methods**

352 Thirty-six BMP sites were selected from the IBMPDB across 12 US states and three types (25
353 RP, 7 WB, 4 DB), each with documented type, verifiable coordinates, a multi-year monitoring
354 record, and a footprint of at least 0.05 ha. Footprints were delineated in 0.6-m NAIP imagery
355 using SAM³⁰, and a 100-m annular buffer served as the per-asset reference. Three feature
356 substrates were extracted at the BMP and buffer for 2018–2024, namely (A) six hand-crafted
357 indices computed from monthly Sentinel-2 L2A composites, (B) the 12 Sentinel-2 bands

358 (BMP-side annual means), with all 66 two-band normalized-difference indices screened sep-
359 arately as a univariate control, and (C) annual AlphaEarth Foundations 64-dim embeddings
360 (GOOGLE/SATELLITE_EMBEDDING/V1/ANNUAL;²⁸). Each monthly Sentinel-2 composite
361 is the per-band median of L2A scenes with scene-level cloud cover below 20 percent, without a
362 per-pixel cloud mask, so per-site temporal completeness varies with regional cloud climatology,
363 ranging from 47 to 84 of the 84 possible months across the pilot. The per-asset harmonic deseason-
364 alization requires at least eight valid monthly observations per series, a threshold satisfied at every
365 site. Type-discrimination AUCs were computed by leave-one-out logistic regression with shrink-
366 age and 1,000-sample bootstrap confidence intervals (conditional on the leave-one-out scores,
367 quantifying ranking stability rather than model-refit uncertainty; Supplementary Methods),
368 and mutual-information significance was assessed against a 500-permutation null. Within-asset
369 change detection used per-asset harmonic deseasonalization combined with PRISM climate
370 residualization at lags of 0, 1, and 3 months, aggregated to a per-substrate departure magnitude
371 M_t (the RMS z-score across features) with an $M_t > 1.5$ threshold and a ≥ 2 -period persis-
372 tence requirement. All polygons, time series, residualized signals, code, and figure-generation
373 scripts are released in the accompanying repository. Full methods, including AlphaEarth axis
374 interpretability, residualization variance accounting, and the Cottonwood water-quality coupling
375 analysis, are provided in the Supplement.

376 **AI use declaration.** Large language model assistants [Claude Opus 4 (Anthropic) and ChatGPT
377 (OpenAI; GPT-5)] were used during manuscript preparation for prose editing, structural revision,
378 and code development under author supervision. All scientific claims, analytical choices, citations,
379 and final wording were verified by the authors.

380 **Data availability**

381 The derived data supporting this study — the extracted multi-sensor time series, the residualized
382 per-asset signals, the 36 BMP polygon and reference-buffer labels, and the separability and change-
383 detection outputs — are available in the project repository at [https://github.com/skp703/bmp-eo-](https://github.com/skp703/bmp-eo-monitoring)
384 monitoring, released as a seed contribution toward a CAMELS-for-stormwater community bench-
385 mark (derived data tables and polygon labels under CC-BY-4.0). The raw inputs are not redis-
386 tributed but are publicly available from their original sources — Sentinel-2, NAIP, AlphaEarth
387 Foundations, and PRISM via Google Earth Engine; PlanetScope via Planet Labs; and the Interna-
388 tional Stormwater BMP Database via bmpdatabase.org — and the repository provides scripts to
389 acquire each.

390 **Code availability**

391 All analysis code is available in the project repository at [https://github](https://github.com/skp703/bmp-eo-monitoring)

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