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Resolving microscale surface temperature variability during a heatwave using a dense sensor network

Mark T. Ireland^{1*}, Hector G. Barnett¹, Abdullah Kahraman^{2,3} and Charles K. Dunham¹

¹School of Natural and Environmental Science, Newcastle University

²School of Engineering, Newcastle University, Newcastle upon Tyne, UK

³Tyndall Centre for Climate Change Research, Newcastle University, Newcastle upon Tyne, UK

*Corresponding author: mark.ireland@newcastle.ac.uk

20 **Abstract**

21 High-resolution observations of near-surface temperature variability are essential for
22 understanding heat exposure during extreme weather events, yet are rarely available
23 from dense, regularly spaced in situ measurement grids, with most existing observations
24 derived from unevenly distributed sensor networks. Here, we analyse temperature
25 measurements derived from a dense network of over 3,000 nodal seismometers
26 deployed across a 6 km² area in North Yorkshire, UK, during the July 2022 heatwave, using
27 data from embedded microcontroller sensors. Although the embedded microcontroller
28 sensors provide incidental environmental measurements at unprecedented spatial and
29 temporal resolution, with over 80 million logged temperatures recorded at 100 s intervals
30 for 34 days.

31 Microcontroller derived temperature measurements were statistically corrected using
32 co-located meteorological observations to account for systematic biases introduced by
33 the thermal response of the sensor housing to closer approximate true near-surface
34 temperatures across the network. The corrected dataset reveals strong spatial
35 heterogeneity in surface temperatures, with mean differences of up to 3.6 °C at distances
36 of 100–200 m and extreme contrasts exceeding 17 °C during peak heating conditions.
37 Spatial variability is interpreted to be strongly modulated by meteorological forcing, with
38 daytime heatwave conditions exhibiting the greatest heterogeneity, while nighttime
39 periods show substantial homogenisation. Systematic but modest differences are
40 observed between land-use classes (~0.1 °C), expressed primarily through variations in
41 persistence and extremes rather than mean temperature alone.

42 The results highlight the importance of sub-kilometre variability in near surface
43 temperature fields and demonstrate the potential of repurposing incidental
44 environmental sensing to characterise microclimate environments at scales relevant to
45 ecosystem dynamics and human exposure. More broadly, the findings open the
46 potential, with improved calibration, that dense geophysical arrays could provide unique
47 insights into fine-scale meteorological dynamics with implications for the interpretation
48 of satellite-derived land surface temperature, the development of high-resolution
49 modelling approaches, and the assessment of heat-related risks.

50 1 Introduction

51 Spatial and temporal variations in both air and land surface temperature have
52 implications for Earth systems, including climate systems (e.g. Betts et al., 1996),
53 biogeochemical cycles (e.g. Burke et al., 2003) and the interaction with the built
54 environment (e.g. Nuruzzaman, 2015). It is widely documented that land use and the built
55 environment impact air and surface temperatures within the Earth system (Tran et al.,
56 2017), and specifically, in the context of urban areas that built up areas are known to
57 exert a significant influence on their local climate, and are generally warmer than their
58 surroundings (e.g. Kershaw et al., 2010). While modelling approaches are widely used to
59 investigate microclimates, understanding fine-scale variability requires high-resolution
60 field observations (Yang et al., 2013). Such measurements provide direct evidence of
61 microclimate processes and are essential for quantifying their impacts. This is
62 particularly important in ecological contexts, where fine-scale thermal variability
63 influences habitat conditions (Kemppinen et al., 2024) and for human health, where local
64 temperature extremes affect heat exposure and associated risks (Schinasi et al., 2018).

65 The heterogeneity of surface temperature affects the surface energy and water budgets,
66 as well as the land-atmosphere exchanges of momentum, heat, water and other
67 constituents (Giorgi & Avissar, 1997). Land surface temperature (LST) derived from
68 satellite thermal infrared observations provides valuable spatial coverage at moderate
69 resolution, ranging from 1 km for MODIS (Hulley & Hook, 2017) down to 70 m for
70 ECOSTRESS (Earth Science Data Systems, 2025); however, their relatively low temporal
71 frequency and sensitivity to cloud contamination limit their ability to fully resolve short-
72 term and fine-scale thermal variability in urban environments (Huang et al., 2013). This
73 often leads to a low temporal resolution or intermittent temporal coverage. To resolve this
74 lack of data at the finer scale, the use of modelling is commonplace (e.g. de La Flor &
75 Dominguez, 2004), however this is reliant on calibration data. Recently there have been
76 efforts to accurately estimate air temperature with low-cost devices (Maclean et al.,
77 2021), however the dedicated development and deployment of high density and spatially
78 extensive sensor networks remains logistically challenging, particular in terms of
79 operation, maintenance and data retrieval. As such there is a lack of case studies that
80 use in situ measurements to reveal the fine scale spatial variability in land surface
81 temperature.

82 Many sensor systems and electronic devices record environmental variables, such as
83 chip temperature, as a secondary function of their routine operation. These
84 measurements can potentially enable incidental environmental sensing, although there
85 are limited studies examining temperatures from devices to investigate environmental
86 processes (e.g. Arachchige et al., 2023). Here, temperature measurements that were
87 recorded principally for instrument health and performance are repurposed to
88 investigate near-surface thermal variability.

89 We investigate the spatial and temporal variations in near-surface temperature within a
90 mixed land use setting during the July 2022 heatwave in northwest Europe. During this
91 event, a new UK record daily maximum temperature of 40.3 °C was recorded on 19 July,
92 representing the most extreme heatwave conditions seen in the instrumental record
93 (Yule et al., 2023). The study utilises temperature measurements acquired from
94 microcontroller-based sensors embedded within seismic nodes deployed during a
95 geophysical survey at RAF Leeming, North Yorkshire, UK in July 2022 (**Figure 1**). Although
96 the survey was not designed for environmental monitoring, the high spatial density and
97 extent of the array provide a unique opportunity to resolve near-surface temperature
98 variability at microscales during a period of extreme heat.

99 The resulting dataset, covering approximately 6 km², represents one of the densest in situ
100 measurements of near-surface temperature reported to date. These data are used to
101 characterise spatial and temporal temperature variability and are evaluated against
102 observations from a co-located meteorological station. The results provide insight into
103 fine-scale thermal variability across a mixed land-use environment under extreme
104 heatwave conditions.

105

106 **2 Data and Methodology**

107 **2.1 Data acquisition and experimental design**

108 Temperature measurements were obtained from microcontroller sensors embedded
109 within the STRYDE seismic nodes deployed as part of a geophysical survey in North
110 Yorkshire, UK (**Figure 1**). A total of 3,218 seismic nodes were distributed across an
111 approximately 6 km² area between 7 July and 5 August 2022. Temperature data from
112 3,083 were used in this study, with the remaining nodes excluded due to incomplete
113 records arising from issues relating to deployment and retrieval or damage. The
114 deployment geometry comprised 25 lines, predominantly oriented east–west and
115 spaced at 100 m intervals, with nodes positioned at 10 m spacing along each line. One
116 line followed an access road to the site and was oriented approximately north–south.

117 The seismic nodes were deployed using a hand auger to embed the device into the
118 ground so that the top of the device was nearly flush with the surface. In all cases devices
119 were only deployed on unbuilt ground (grass or soil) and the lowest part of the device was
120 located at a maximum of 10 cm depth. The position of the microcontroller within the
121 device is such that it was positioned approximately 5 cm beneath surface. Each device
122 logged temperature at 100 s intervals, with a nominal precision of ±1 °C and integer
123 output. The resulting dataset comprises more than 80 million individual recorded
124 temperatures. Throughout this study these temperatures are referred to as *raw sensor*
125 *temperatures*.



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Figure 1. Location of the dense seismic array deployed at RAF Leeming, North Yorkshire, UK. (a) Location of 3,083 seismic nodes across the study area overlaid on aerial imagery (sourced from ESRI). The weather station used for calibration and comparison is indicated by the white star, while the red rectangle denotes the area shown in panel (b). (b) Detailed view of the sensor array surrounding the weather station, including the three calibration sensors (red symbols) used to develop the temperature bias-correction model. (c) Location of the study area within the United Kingdom. Coordinates are shown in the British National Grid

The internal temperature sensor is integrated within an STM32L431 microcontroller. The sensor generates a temperature-dependent voltage that is digitized through the on-chip ADC and converted to temperature using factory calibration constants. Because the

138 sensor measures microcontroller die temperature, recorded values could reflect both
139 environmental temperature and internal self-heating. To assess the latter, diagnostic
140 metadata describing node operation were extracted from three calibration nodes and
141 compared with measured temperatures. Metadata describing signal, timing, and data-
142 quality characteristics were extracted from the SEG-D headers of the three nodes used
143 in the temperature correction workflow. Pearson correlation coefficients were then
144 calculated between each metric and internal node temperature.

145 A permanent Met Office ground-based weather station located within the deployment
146 array provided reference meteorological observations, including near-surface and grass
147 temperature, enabling calibration and validation of sensor-derived measurements. The
148 Met Office station data is available from CEDA hosted Met Office Integrated Data Archive
149 System (MIDAS) (Met Office, 2012). Heatwave periods were identified following the Met
150 Office definition ('What is a heatwave?', n.d.) as periods of at least three consecutive days
151 with daily maximum air temperature exceeding 25 °C, the threshold applicable to North
152 Yorkshire. Throughout this study these temperatures are referred to as *weather station*
153 *temperatures*. The UK Hadley Centre Central England Temperature (HadCET) dataset
154 provides the daily temperatures to describe the wider meteorological conditions across
155 the British Isles during the heatwave.

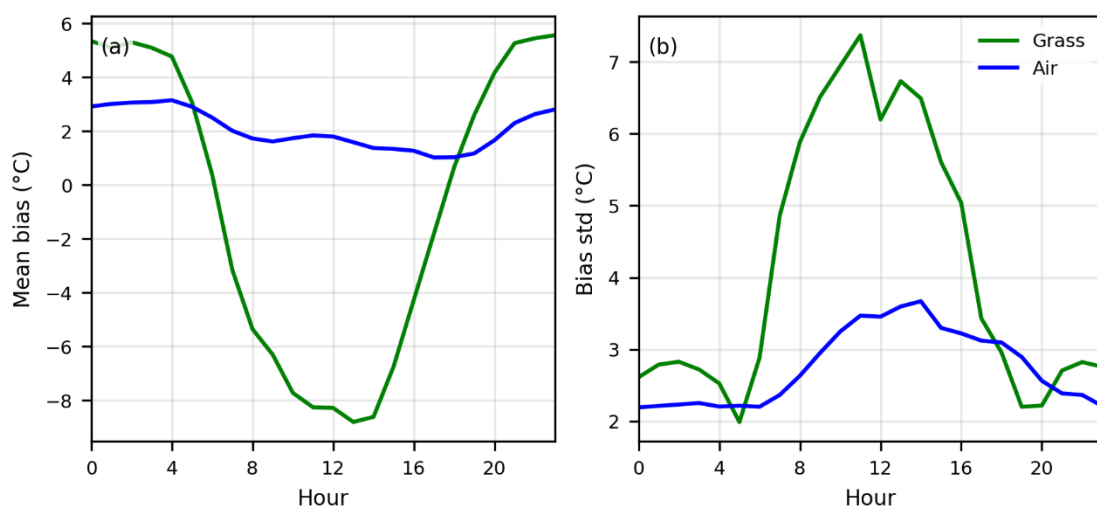
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157 **2.2 Reference Temperature Correlation**

158 The raw sensor temperatures have been used here opportunistically as they were logged
159 as metadata throughout the duration of the geophysical surveying. Because the
160 temperature measurements were recorded as part of routine instrument operation rather
161 than for environmental monitoring, no dedicated pre-deployment temperature
162 calibration was undertaken beyond the manufacturer's factory calibration. Comparison
163 with co-located weather station measurements shows that the sensor data exhibit
164 systematic bias relative to the grass reference temperature (**Figure 2**), which cannot be
165 explained by spatial separation which is <30m for the nearest device. This bias is primarily
166 associated with differences between the temperature measured by the seismic node and
167 the ambient environmental temperature. The node records temperature using an
168 internally calibrated microcontroller sensor located within the device enclosure rather
169 than a dedicated meteorological temperature sensor. Consequently, the recorded
170 temperatures are influenced by the thermal environment within the housing, including
171 shielding from direct radiative forcing and modest differences in the timing and
172 magnitude of the measured diurnal temperature cycle relative to standard
173 meteorological observations. To account for these biases, a systematic evaluation of the
174 raw sensor temperature data and co-located weather station observations was
175 undertaken.

176 Although raw sensor temperatures exhibit a slightly stronger correlation with air
177 temperature than with grass temperature ($R^2 \approx 0.40$ vs 0.33), the bias relative to air
178 temperature is weakly structured with respect to time and therefore less reliably
179 modelled ($R^2 \approx 0.1$ – 0.2). In contrast, bias relative to grass temperature exhibits strong
180 diurnal structure and can be effectively modelled using a statistical approach ($R^2 \approx 0.8$)
181 (Figure 2). Consequently, correction relative to grass temperature yields a substantially
182 greater reduction in error and is therefore adopted.

183 Variance decomposition further supports this distinction, indicating that approximately
184 70% of the variance in bias relative to grass temperature is explained by diurnal structure,
185 whereas only ~10% of the variance in bias relative to air temperature is structured, with
186 the remainder dominated by within-hour variability.



187

188 **Figure 2. Diurnal variation in bias relative to grass and air temperature. Bias relative to grass temperature exhibits**
189 **a clear diurnal structure, whereas bias relative to air temperature shows weak temporal organisation.**

190

191 Throughout this study, the corrected temperatures are interpreted as near-surface
192 environmental temperatures that most closely approximate grass temperature rather
193 than standard 2 m air temperature or remotely sensed land surface temperature.

194

195 2.3 Data preprocessing

196 Raw sensor temperature time series were first collated and associated with spatial
197 metadata (location and elevation). To reduce the influence of probable anomalous
198 measurements, a spatial consistency filter was applied. For each sensor, the nearest
199 sensor was identified, and observations were removed where the absolute difference
200 between paired raw sensor temperatures exceeded a 5°C threshold. This step exploits
201 the high spatial density of the array to identify physically improbable deviations.

202 To reduce high-frequency noise and sensor-specific variability, each time series was
203 smoothed using a Gaussian kernel filter. For each observation, a weighted average of
204 neighbouring values within a temporal window (± 3 bandwidths) was computed, with
205 weights defined by a Gaussian function of temporal distance. The bandwidth parameter
206 controls the degree of smoothing and defines the effective temporal scale of the filter.
207 The smoothed time series were subsequently resampled to regular hourly intervals by
208 averaging all observations within each interval. This ensured temporal alignment across
209 all sensors and with Met Office meteorological datasets.

210 Additional variables were derived to support subsequent analysis and calibration. Sensor
211 locations were used to calculate the distance to the reference weather station, providing
212 a measure of separation from calibration source. Each observation was also classified as
213 daytime or nighttime based on solar position, calculated from location and timestamp.
214 This enables differentiation of diurnal effects in sensor behaviour.

215 All datasets, including sensor measurements and weather station observations, were
216 standardised to a common hourly resolution and a continuous time index was
217 constructed over the study period with all datasets were merged onto this index.

218

219 **2.4 Bias adjustment of sensor temperatures**

220 A subset of three sensors, located <50m from the Met Office station, were chosen based
221 on the consistency of their temperature records relative to the neighbouring sensors for
222 the bias correction. The permanent ground-based weather station located within the
223 study area provided reference meteorological observations, including grass temperature,
224 humidity, wind speed and incoming radiation. These data were temporally aligned with
225 the sensor measurements and used as the reference dataset for calibration and
226 evaluation.

227 Using these sensors, four different regression models were trained to predict the bias
228 between the microcontroller temperature and the reference grass temperature initially
229 as a function of: i) smoothed sensor temperature; ii) distance to the weather station; iii)
230 sensor elevation and iv) cyclic representations of time (sine and cosine transforms of
231 hour of day). Separate tests of humidity, wind speed and incoming radiation were
232 evaluated as predictor variables. The four regression models tested were: Random
233 Forest, Extra Trees, Gradient Boosting, and Histogram Gradient Boosting. These
234 represent two classes of tree-based methods: bagging approaches, which reduce
235 variance through averaging (Random Forest, Extra Trees), and boosting approaches,
236 which iteratively improve predictions by correcting residual errors (Gradient Boosting,
237 Histogram Gradient Boosting) (James et al., 2023). All models were trained using the
238 same feature set and training dataset and evaluated using consistent performance
239 metrics. After preprocessing and filtering, 1,913 hourly observations were retained, of

240 which 80% were used for training and 20% for testing. Model performance is reported on
241 the held-out test set.

242 The regression models were employed to capture non-linear relationships between
243 predictors and reference temperature. All models were implemented using the scikit-
244 learn Python library (Pedregosa et al., 2011). Model-specific hyperparameters were either
245 tuned using cross-validation (for Gradient Boosting) or set to regularised values. Bias
246 predictions were constrained using percentile-based filtering applied on an hourly basis
247 to limit extreme values while preserving diurnal variability. Model performance was
248 evaluated using standard metrics, including root mean squared error (RMSE) and
249 coefficient of determination (R^2), mean absolute error (MAE) and mean bias error (MBE).
250 The trained models were subsequently applied to all raw sensor temperatures in the array
251 to generate corrected sensor temperature estimates, thereby accounting for systematic
252 bias and improving comparability with reference measurements. The parameters for
253 each model can be found in the Supplementary Material 1. Throughout this study these
254 temperatures are referred to as *corrected sensor temperatures*.

255

256 **2.5 Spatial processing and interpolation**

257 Spatial structure in the temperature field was quantified using semi-variograms
258 calculated independently for each hourly time step. For each hourly timestamp, pairwise
259 distances between all sensor locations were computed in projected coordinates, and the
260 semi-variance was evaluated as half the squared difference in temperature between
261 sensor pairs. Semi-variances were grouped into discrete lag bins (20 m width) up to a
262 maximum separation distance of 800 m and mean semi-variance values were calculated
263 for each bin, with bins containing fewer than 50 pairs excluded to reduce statistical noise.
264 From each variogram, the nugget was defined as the semi-variance at the smallest lag,
265 the sill as the mean semi-variance of the upper 20% of lag distances, and the range as
266 the distance at which the semi-variance reached 95% of the sill. This was repeated for all
267 time steps ($n = 687$), enabling temporal analysis of spatial correlation length scales.
268 Summary statistics of the variogram parameters were then used to characterise the
269 typical spatial structure of the temperature field and to inform subsequent interpolation,
270 with the median range providing a constraint on the spatial scale of correlation.

271 The high spatial density of the array enables detailed mapping of near-surface
272 temperature variability. To generate continuous temperature fields, point measurements
273 were interpolated using inverse distance weighting (IDW). This method assigns weights
274 to observations based on distance, preserving local variability and exploiting the
275 relatively uniform sensor spacing. Interpolation was performed independently for each
276 time interval. The resulting gridded datasets enable interpretation of spatial temperature
277 patterns at sub-kilometre scales, exceeding the resolution of commonly available
278 satellite-derived land surface temperature products. Spatial and temporal variability in

279 temperature were analysed using a combination of statistical techniques. Spatial
280 clustering was assessed using metrics such as Moran's I, while gradients in temperature
281 were evaluated using first-order spatial derivatives. Temporal periodicity was examined
282 using Fourier-based spectral analysis.

283

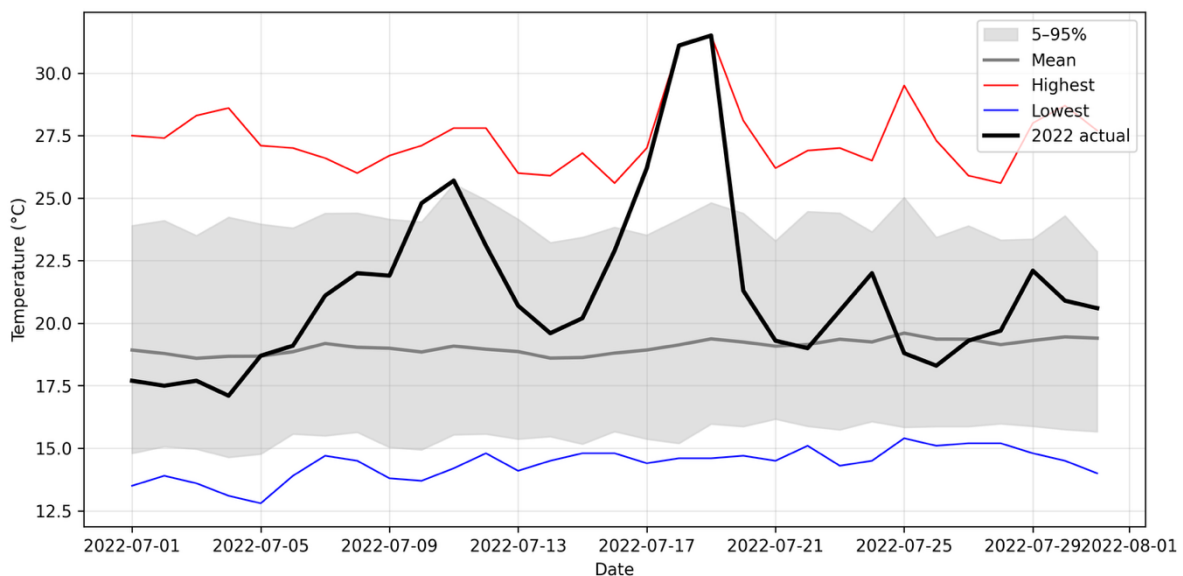
284 3 Results

285 3.1 Meteorological Conditions

286 3.1.1 July 2022 heatwave

287 In July 2022, the UK exceeded 40 °C for the first time in the instrumental record, with the
288 previous national maximum of 38.7 °C surpassed at 46 stations across England from
289 south to north. The UK mean daily maximum temperature also exceeded 30 °C for the
290 first time, and 18–19 July became the hottest days recorded (Figure 3). According to the
291 Met Office, a heatwave is defined as at least three consecutive days with daily maximum
292 temperature meeting or exceeding a location-specific threshold (Met Office, n.d.). These
293 county-level thresholds range from 25 to 28 °C and are based on the 1991–2020
294 climatology of daily maximum temperature at the midpoint of meteorological summer.
295 The event developed as a high-pressure system moved across the UK during 16–17 July,
296 allowing temperatures to rise progressively from the mid-20s to the low 30s °C across
297 much of England and Wales. As the high shifted eastwards, exceptionally hot continental
298 air was advected northwards, producing a synoptic configuration highly favourable for
299 extreme heat across parts of the UK.

300



301

302 **Figure 3. UK maximum temperature during 2022 July (thick black line) and the historical context. 1991-2020 is**
303 **used as the base period.**

304

305 From 1878 to 2022, both the number of days exceeding the 90th percentile in
306 temperature and the occurrence of heat waves have increased (Yule et al., 2023) .
307 Remarkably, between 1994 and 2022, 79% of years experienced at least one summer
308 heat wave, more than any earlier 29-year period, reflecting a steady rise in monthly
309 average temperatures (Yule et al., 2023). According to a recent model-based study,
310 experiencing a day over 40 °C is currently a 1-in-24 year event, though this probability is
311 rising quickly (Kay et al., 2025) . Additionally, the UK's hottest summer days have warmed
312 at a rate more than three times faster than global averages over the past century (Hawkins
313 et al., n.d.).

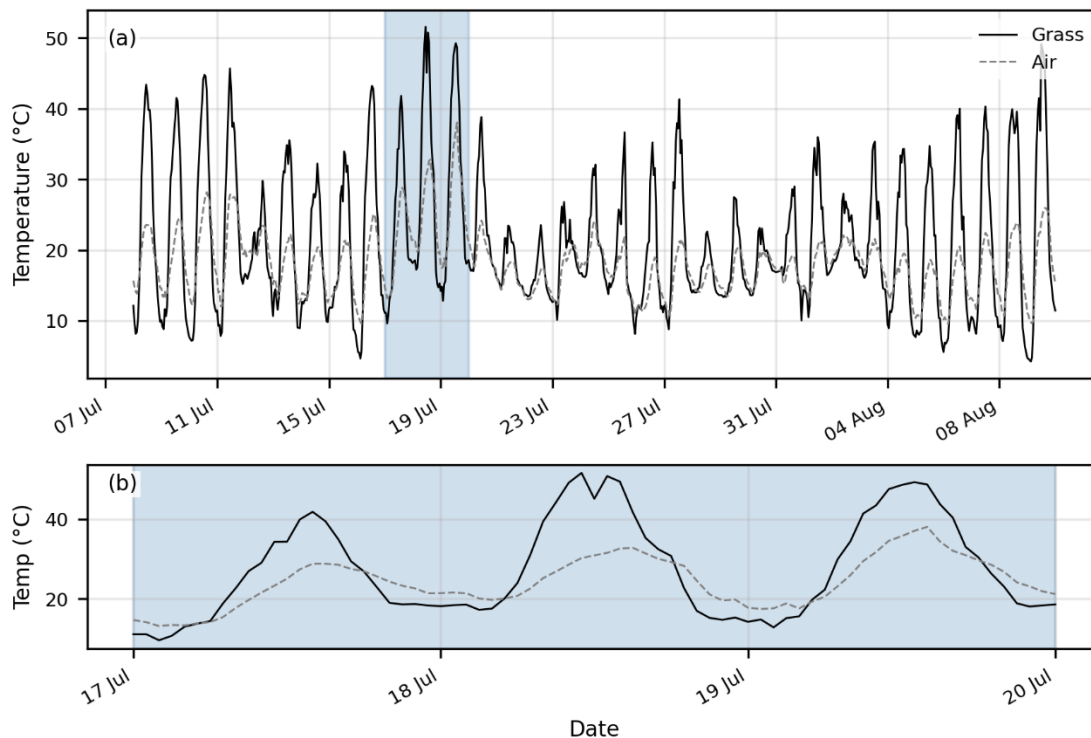
314 The heatwave exerted significant effects across various sectors. It contributed to
315 widespread fires in London and other regions (John & Rein, 2025) , with a six-fold increase
316 in the probability of very high fire danger projected due to warming trends (Burton et al.,
317 2025) . In London alone, 370 out of 1,773 fatalities have been attributed to the heatwave
318 (Simpson et al., 2024). There were also effects on public health and overall well-being
319 (e.g. Savu, 2025). Additionally, the event impacted transportation, energy supply,
320 education (Howarth et al., 2024), and food systems (Davie et al., 2023).

321

322 *3.1.2 Observations at the site*

323 While air temperature is conventionally recorded at an elevation of 2 m to meet standard
324 meteorological requirements, surface and soil temperatures diverge from these readings
325 and are influenced by the distinct properties of soil, vegetation, and built environments.

326 The Met Office weather station located at RAF Leeming recorded a maximum grass
327 temperature of 51.6°C at 2022-07-18 11:30:00 and a minimum 4.41°C at 2022-07-16
328 04:00:00. The same station data defines three heat wave periods during the survey,
329 Heatwave from, 2022-07-08 to 2022-07-20, 2022-07-24 to 2022-07-27 and 2022-07-31 to
330 2022-08-03. Incoming shortwave radiation, humidity and wind speed varied substantially
331 over the survey period, providing the primary drivers of near-surface temperature
332 dynamics analysed in subsequent section.



333

334 *Figure 4. Time series of grass (solid black line) and air (dashed line) temperatures measured at RAF Leeming*
 335 *during the study period. (a) Full record from 7 July to 10 August 2022 showing strong diurnal variability in both*
 336 *grass and air temperatures. The light blue shading highlights the period of 17–20 July, which is expanded in (b).*
 337 *(b) Four-day zoom-in (17–20 July 2022) illustrating diurnal temperature cycles during the July 2022 heatwave, with*
 338 *daytime grass temperatures frequently exceeding 40 °C and substantially exceeding air temperatures.*

339

340 3.2 Temperature Bias Correction

341 The raw temperature measurements exhibited a positive relationship with Mean DC
 342 offset across three nodes used for bias correction. The Mean DC increased
 343 systematically with increasing temperature, whereas RMS amplitude showed only weak
 344 associations with temperature. The relationship between Mean DC and temperature was
 345 consistent across the three nodes examined. Correlations between temperature and
 346 operational metrics were generally weak ($r < 0.21$ for RMS amplitude, timing corrections,
 347 synchronization corrections and data-gap statistics), while a moderate positive
 348 correlation was observed between temperature and Mean DC offset ($r = 0.61$) (see
 349 Supplementary Material 2)

350 Several machine-learning models were evaluated to correct the systematic bias between
 351 microcontroller die temperature and ambient environmental temperature, including
 352 Random Forest, Extra Trees, and gradient boosting approaches. The gradient boosting
 353 models performed best, with the subsampled GBT achieving the highest accuracy,
 354 followed by the histogram-based variant (Table 1). Tree-based ensemble methods
 355 (Random Forest and Extra Trees) showed lower performance and higher error (Table 1).
 356 Differences in bias structure and diurnal behaviour remained evident. Boosting

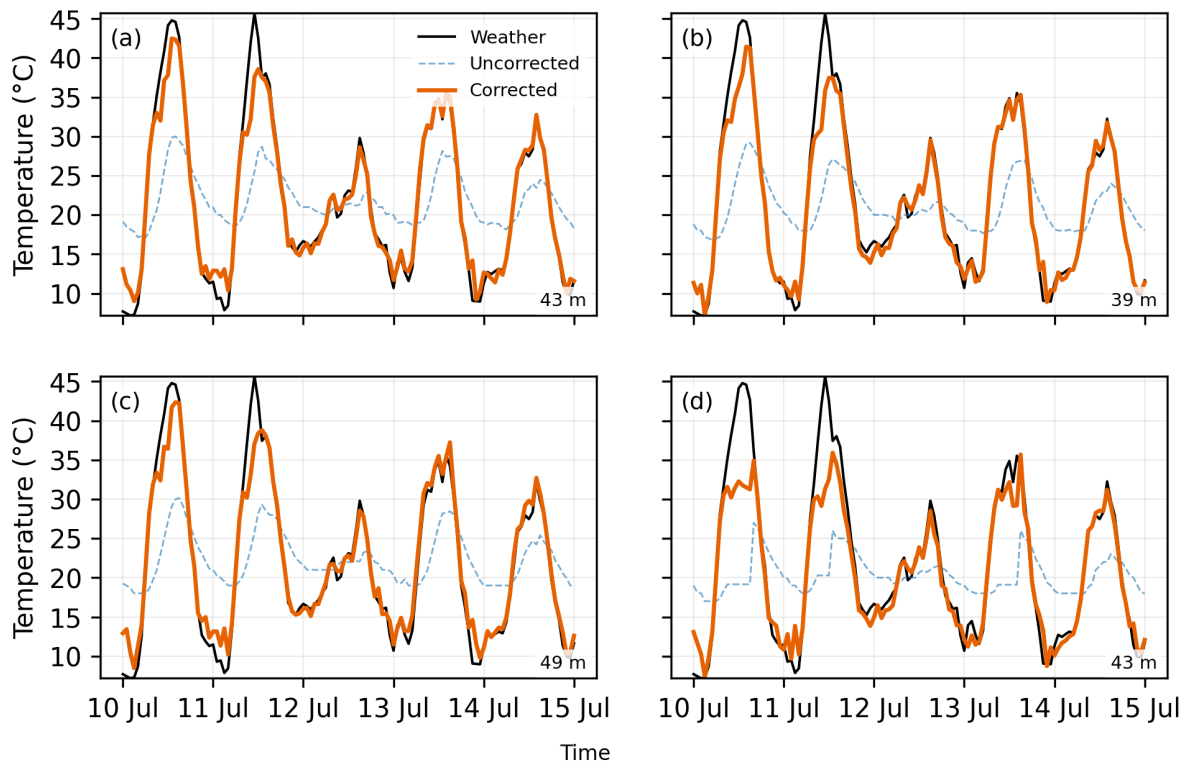
357 approaches produced near-zero mean bias (-0.004 to -0.067°C), whereas Random
 358 Forest and Extra Trees exhibited systematic positive bias (~+1.26 to +1.34°C). These
 359 differences were most pronounced in the diurnal cycle: boosting approaches captured
 360 stronger nocturnal cooling and more moderate daytime heating, while bagging-based
 361 models overestimated daytime heating and underestimated nocturnal cooling (Table 1).
 362 Additionally, Random Forest and Extra Trees produced higher maximum temperatures,
 363 indicating likely overestimation of extremes relative to boosting approaches. Although
 364 performance differences between GBT and HGBT models were modest, the GBT model
 365 was selected for subsequent analysis due to its slightly improved predictive performance
 366 and consistent behaviour. All corrected temperatures presented subsequently use the
 367 subsampled GBT model.

368

369

Model	R2	MSE	Bias mean	Bias std	Day mean	Night mean	Max temp	Diurnal range	Bias mean
GBT	0.922	3.143	-0.004	6.509	2.795	-6.045	63.048	8.84	0.004
HGBT	0.912	3.578	-0.067	6.495	2.738	-6.122	62.818	8.86	0.067
RF	0.882	4.78	1.342	6.297	3.988	-4.371	63.95	8.359	1.342
ET	0.882	4.807	1.258	6.357	3.898	-4.439	64.13	8.336	1.258

370 **Table 1. Comparison between regression model performance. GBT: Gradient boosted tree with subsampling;**
 371 **HGBT: Histogram boosted tree; RF: Random Forest; ET: Extra trees**



373

374 *Figure 5. Comparison of uncorrected and corrected microcontroller die temperatures with reference grass*
 375 *temperature measurements from the meteorological station. (a-c) three sensors, 2300042571, 2300037527,*
 376 *2300041806 respectively, used to train the GBT correction model. (d) nearest sensor, 2300113496, excluded from*
 377 *model calibration. The correction substantially reduces the daytime warm bias and improves agreement with*
 378 *the reference temperature record.*

379

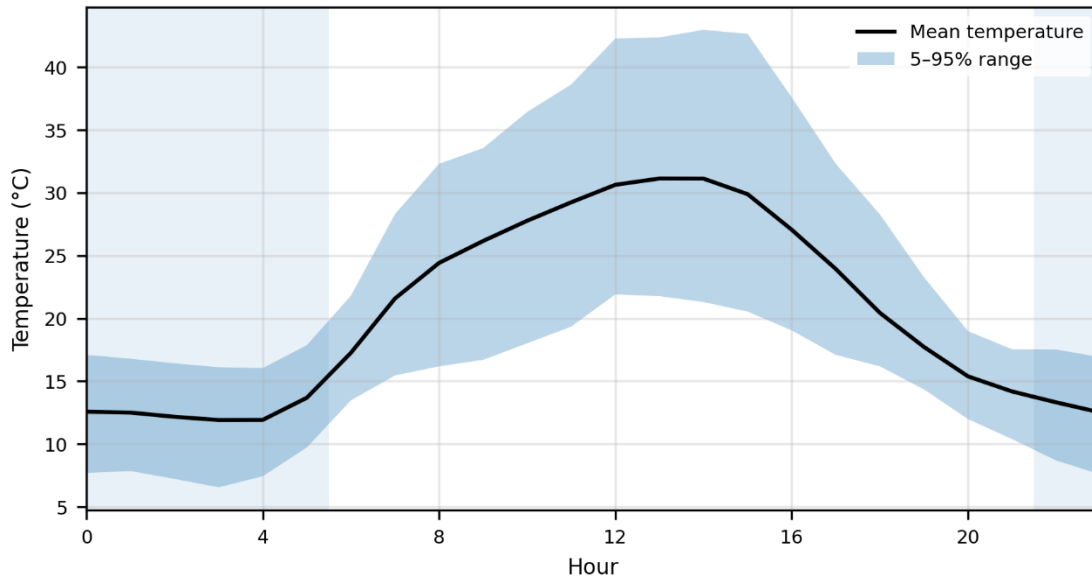
380 3.3 Temporal Characteristics of Near Surface Temperatures

381 3.3.1 Diurnal Behaviour and Extremes

382 The three sensors used for training the models were located within 50 m of the reference
 383 meteorological station and the corrected temperatures more closely reproduce the
 384 magnitude and temporal variability of the reference grass temperature than the
 385 uncorrected microcontroller die temperatures (Figure 5 a-c). Similar behaviour is
 386 observed for both the calibration sensors (Figure 5a-c) and the nearest sensor (serial
 387 2300033336) not used during model training (Figure 5d). The corrected temperature at
 388 this sensor exhibits comparable extremes relative to the meteorological observations,
 389 with a maximum of 44.9 °C and a minimum of 6.7 °C.

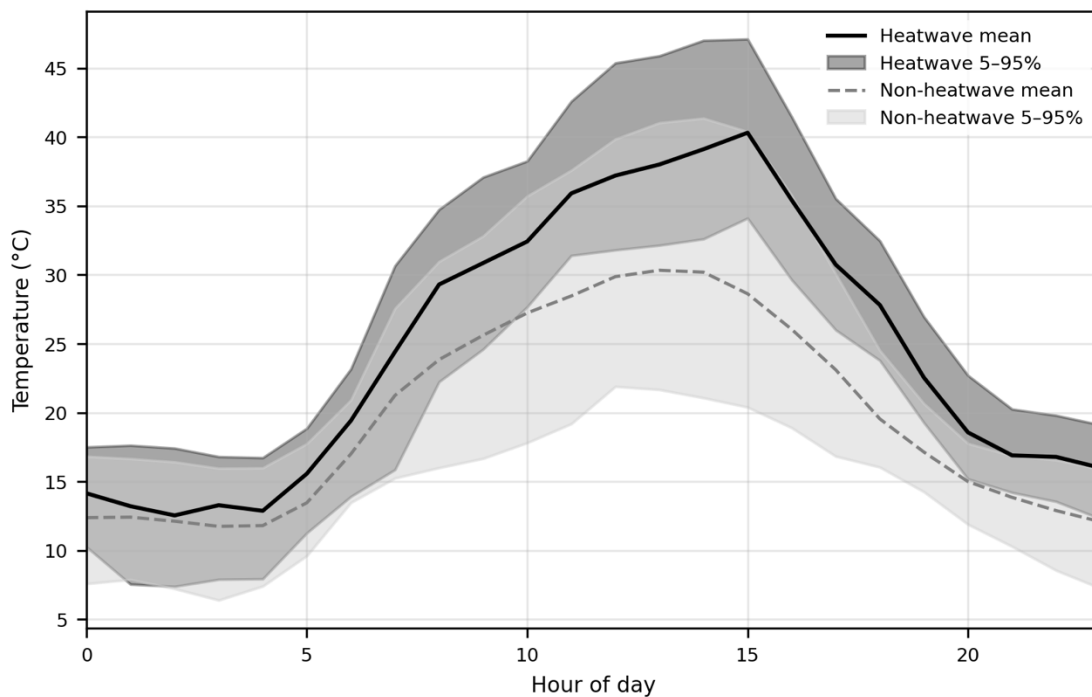
390 Across the full sensor network, the maximum corrected temperature was 63.1 °C (serial
 391 2300057433), while the minimum was -3.1 °C (serial 2300030249). The maximum
 392 diurnal temperature range was 26.8 °C (serial 2300035843), indicating substantial

393 temporal variability in near-surface conditions, whereas the minimum diurnal range was
394 12.3 °C (serial 2300041694).



395

396 **Figure 6. Diurnal Behaviour and Extremes, the light blue shading represents the ‘nighttime’ hours.**



397

398 **Figure 7. Diurnal behaviour split by heatwave days and non-heatwave days.**

399 3.3.2 Spatial contrasts during extreme conditions

400 Spatial temperature variability, quantified using pairwise temperature differences (ΔT),
401 shows clear contrasts across regimes and spatial scales. At the adjacent scale (≤ 15 m),
402 mean ΔT is highest during heatwave daytime conditions (1.89°C), compared to non-
403 heatwave daytime (1.28°C), indicating enhanced fine-scale thermal heterogeneity during

404 extreme heating. This contrast is less pronounced at night, where heatwave conditions
 405 exhibit lower variability (1.41°C) than non-heatwave conditions (1.52°C). At the larger
 406 (range) scale (80–200 m), mean ΔT increases across all regimes, with heatwave daytime
 407 again showing the strongest spatial gradients (2.36°C), followed by non-heatwave
 408 daytime (1.49°C). Night-time variability remains lower overall, with heatwave night
 409 (1.66°C) and non-heatwave night (1.70°C) showing similar magnitudes.

410 The distributions of pairwise temperature differences also vary between regimes. During
 411 heatwave daytime conditions, the upper tail of the distribution is substantially elevated,
 412 with p95 values reaching 3.67°C (adjacent) and 4.80°C (range), compared to 2.99°C and
 413 3.72°C respectively under non-heatwave conditions. Maximum observed ΔT values are
 414 also elevated during daytime, particularly at the range scale (5.48°C for heatwave vs
 415 5.36°C for non-heatwave), indicating the occurrence of strong localised thermal
 416 contrasts. In contrast, night-time distributions are more constrained, with lower p95
 417 values ($\leq 2.36^\circ\text{C}$) and reduced maxima, especially during heatwave conditions where
 418 variability is notably suppressed (maximum 1.94°C at adjacent scale). Overall, these
 419 results indicate that heatwave conditions amplify spatial thermal heterogeneity during
 420 the day, while promoting more spatially uniform conditions at night.

421

Regime	Scale	Mean	Median	p95	max
Heatwave day	adjacent	1.89	1.66	3.67	4.19
Heatwave day	range	2.36	2.00	4.80	5.48
Heatwave night	adjacent	1.41	1.32	1.89	1.94
Heatwave night	range	1.66	1.55	2.26	2.31
Non heatwave day	adjacent	1.28	1.05	2.99	4.36
Non heatwave day	range	1.49	1.20	3.72	5.36
Non heatwave night	adjacent	1.52	1.50	2.08	3.29
Non heatwave night	range	1.70	1.73	2.36	4.97

422

423 *Table 2. Statistical comparison of corrected temperatures at different distances and times. Adjacent refers to*
 424 *between pairs 10m apart, range refers to pairs between 100 and 300m apart.*

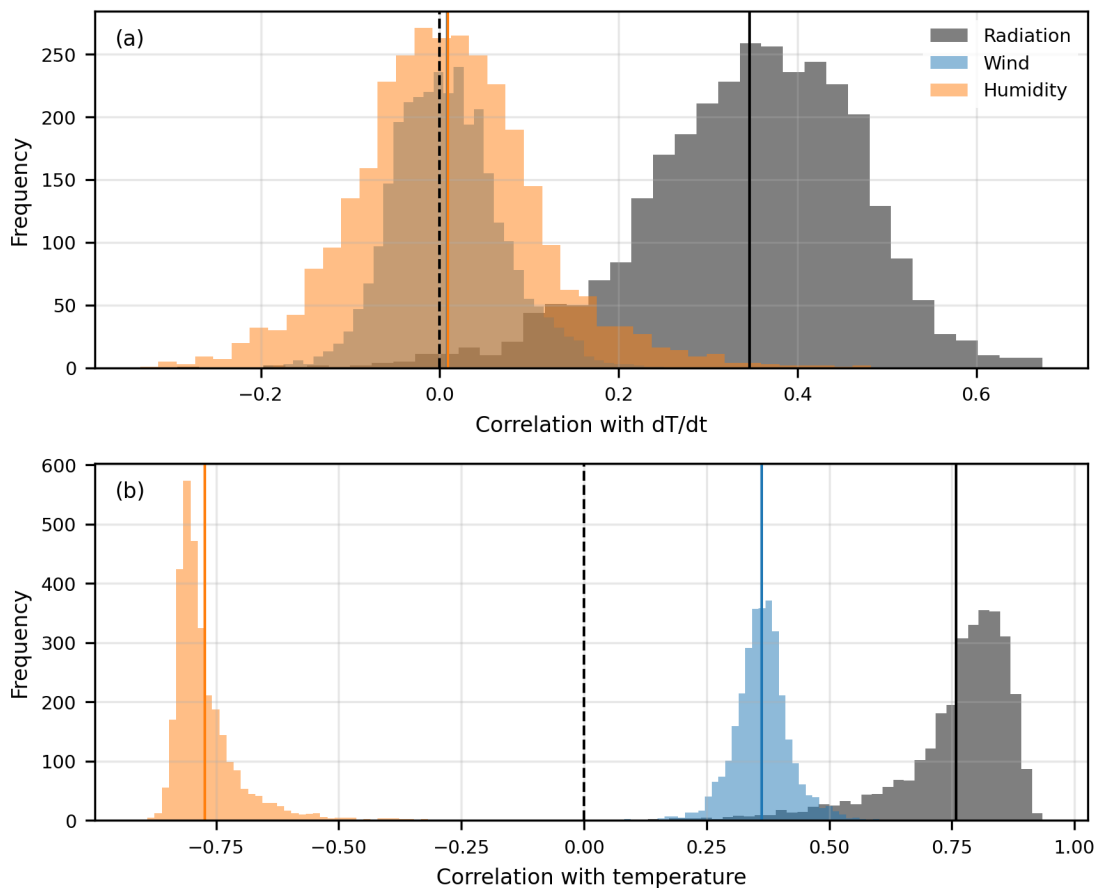
425 3.3.3 Forcing response relationships

426 The gradient boosting model demonstrated strong predictive performance on withheld
 427 observations ($R^2 = 0.92$, MAE = 1.38 °C, RMSE = 1.77 °C, MBE = -0.27 °C). These metrics
 428 should be interpreted in the context of the limited calibration dataset and the temporal
 429 autocorrelation inherent within environmental time series. In the uncorrected data,
 430 radiation exhibited a relatively strong positive correlation with temperature change (mean
 431 $r = 0.346$), while wind speed and humidity showed weak and variable relationships (mean
 432 $r = 0.008$ and $r = 0.009$, respectively), with approximately equal proportions of positive
 433 and negative values. Following correction, the correlation with radiation was
 434 substantially reduced (mean $r = 0.020$), while wind showed a consistent negative

435 correlation (mean $r = -0.123$, 0% positive) and humidity a consistent positive correlation
436 (mean $r = 0.229$, 100% positive) across sensors. Correlations with meteorological
437 variables were generally consistent across the sensor network, with temperature
438 showing positive relationships with solar radiation and negative relationships with
439 humidity (**Figure 8**). Temporal lag analysis indicated that these responses occurred with
440 little delay, suggesting that corrected temperatures primarily reflect contemporaneous
441 environmental conditions. Because radiation is included as a predictor in the correction
442 model, relationships involving radiation are not fully independent. The observed
443 reduction in temperature–radiation correlation therefore reflects, in part, the model’s
444 removal of radiation-related bias and is consistent with the removal of radiation related
445 artefacts.

446

447



448

449 **Figure 8. Distribution of correlations between temperature change (dT/dt) and radiation, wind and humidity as**
450 **measured at the weather station.**

451

452 3.4 Spatial Variability in Temperature Response

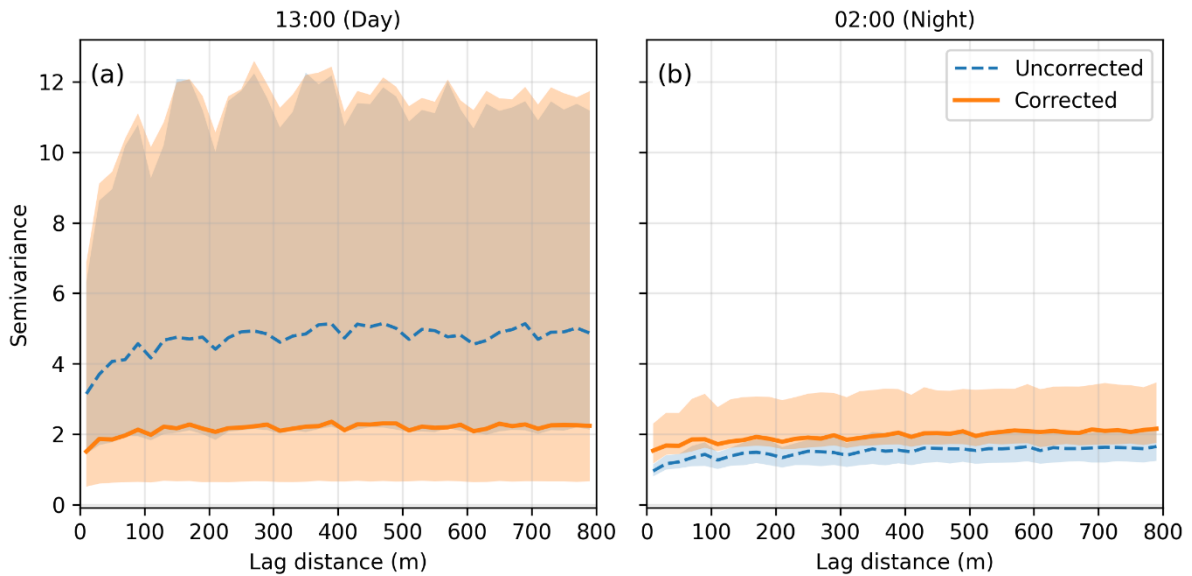
453 Spatial structure exhibits clear regime dependence, as indicated by both variogram
454 metrics (**Figure 9**) and Moran's I. Variogram analysis shows that correlation lengths are
455 short during daytime conditions, with median ranges of approximately 90 m for both
456 heatwave and non-heatwave periods. Although substantial temporal variability is present
457 (95% interval 70–415 m during heatwaves and 10–370 m during non-heatwave periods),
458 the typical spatial correlation scale remains short. Correlation lengths increase
459 substantially at night, reaching median values of ~170 m under non-heatwave conditions
460 (95% interval 50–452 m) and ~270 m during heatwaves (95% interval 90–520 m),
461 indicating greater spatial coherence of nighttime temperature fields. In contrast, sill
462 values are highest during heatwave daytime conditions (median ~4.8 °C²; mean ~6.7 °C²),
463 indicating strong spatial variability, and lowest during non-heatwave daytime conditions
464 (median ~1.3 °C²). These patterns are consistent with Moran's I, which indicates generally
465 weak but non-zero spatial autocorrelation across all regimes, with slightly higher values
466 at night and during heatwave conditions, demonstrating that the temperature fields are
467 characterised by short-range spatial dependence with a substantial local variance
468 component.

469 Local Moran's I (LISA) analysis further demonstrates that this spatial structure is highly
470 heterogeneous and spatially fragmented. Approximately 26% of sensors exhibit
471 statistically significant local autocorrelation ($p < 0.05$), with High–High and Low–Low
472 clusters accounting for ~20% of observations, indicating the presence of localised zones
473 of coherent warming and cooling. However, the majority of sensors (~74%) show no
474 significant spatial association, confirming that spatial dependence is limited in extent.
475 The presence of High–Low and Low–High outliers (~7%) further indicates sharp local
476 gradients, consistent with fine-scale variability in surface and microclimatic conditions.

477 The spatial variability from variogram analysis and LISA results show that while
478 temperature fields exhibit identifiable spatial organisation, this structure is patchy and
479 confined to relatively short distances. To assess whether the correction procedure
480 altered the underlying spatial organisation of temperatures, LISA analyses were
481 performed on both corrected and uncorrected datasets. Cluster classifications showed
482 high agreement between datasets (mean agreement 85–96% across all regimes),
483 indicating that the correction primarily adjusted temperature magnitudes while
484 preserving the dominant spatial patterns. This suggests that the observed thermal

485 patchiness and clustering are inherent features of the temperature field rather than
486 artefacts introduced by the bias-correction procedure.

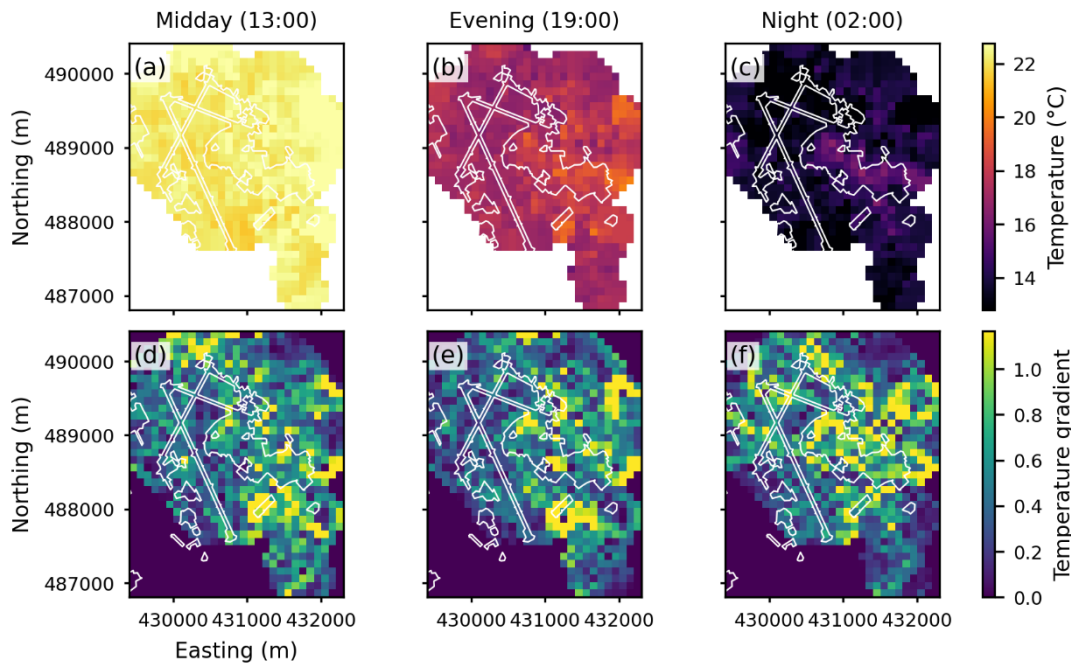
487 Spatial coherence increases under nocturnal and heatwave conditions, but remains
488 insufficient to produce a fully continuous spatial field, with local heterogeneity
489 dominating the observed temperature patterns.



490

491 **Figure 9. Variograms for day and night showing both uncorrected and corrected temperature data.**

492



493

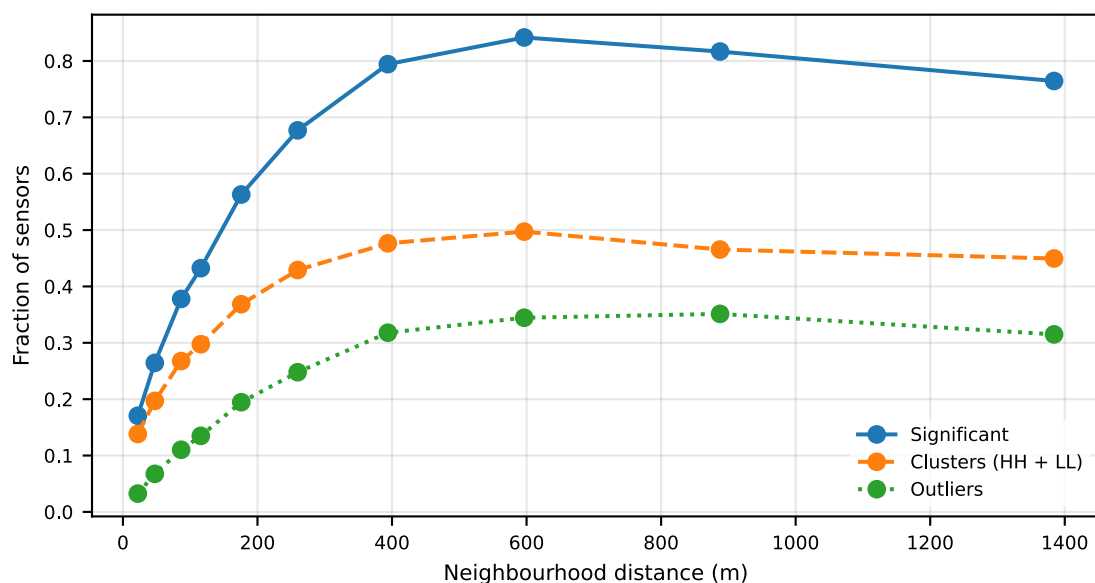
494 **Figure 10. Representative gridded maps of temperature across the survey area. White polygon represents the**
495 **aggregated outline of the built-up urban areas across the survey area.**

496

497 Near-surface temperature fields exhibit pronounced fine-scale heterogeneity.
498 Correlation lengths are short during daytime conditions (~90 m median range), indicating
499 that thermal anomalies are spatially confined and highly localised. At night, correlation
500 lengths increase substantially (~170–270 m), reflecting a transition towards more
501 spatially coherent temperature fields. Spatial variability remains substantial ($\sigma \approx 2.2$ °C;
502 equivalent to typical cross-site differences of several degrees). Spatial autocorrelation is
503 generally weak at the sensor scale due to strong local variability, but coherent clustering
504 emerges when observations are aggregated over distances exceeding ~50 m. Together,
505 these results demonstrate a clear day–night transition from patchy local thermal
506 structure to broader, more organised spatial patterns. Gridded temperature show clear
507 day – night differences, transitioning from patchy local structure to broader more
508 organised patterns (**Figure 10**).

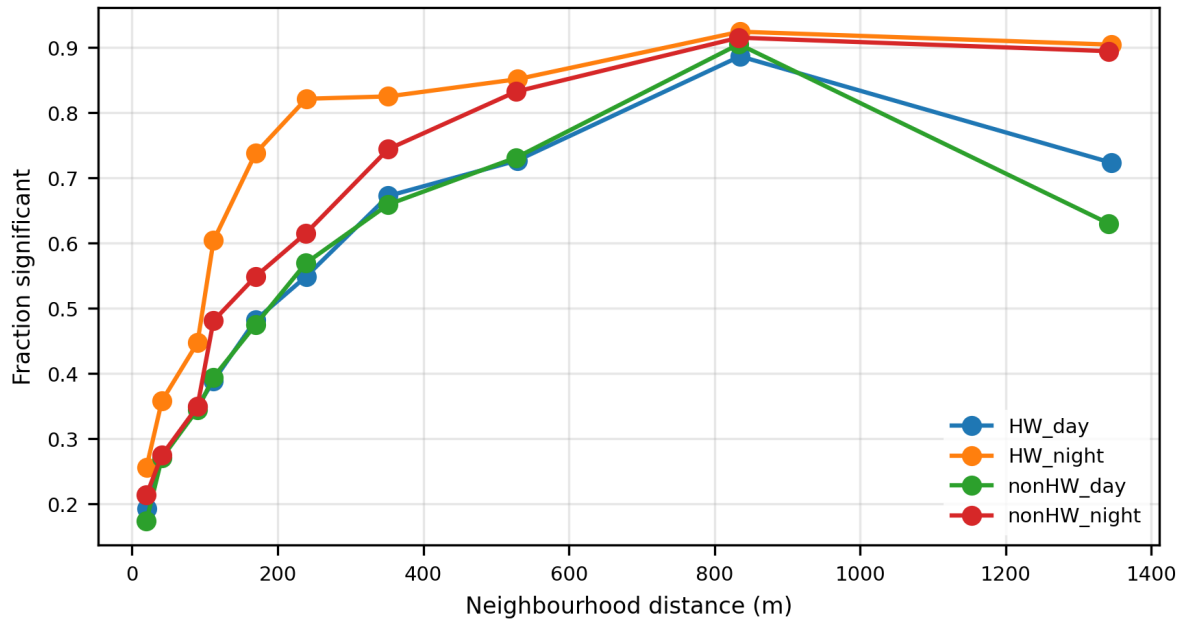
509 Multi-scale LISA analysis demonstrates strong scale dependence in spatial clustering
510 (**Figure 11** and **Figure 12**). The proportion of sensors exhibiting statistically significant
511 local spatial association increases systematically with neighbourhood size across all
512 regimes, indicating that fine-scale thermal heterogeneity is embedded within broader
513 coherent structures. Heatwave night conditions exhibit the strongest spatial
514 organisation, with significant clustering increasing from 0.26 at $k = 4$ to >0.9 at $k = 1024$.
515 In contrast, daytime regimes remain comparatively heterogeneous, with lower clustering
516 fractions across equivalent scales. Significant associations are dominated by High–High
517 and Low–Low clusters, whereas High–Low and Low–High outliers remain relatively
518 uncommon, indicating persistent hotspot and cool-zone structures across multiple
519 spatial scales.

520



521

522 **Figure 11. Fraction of sensors exhibiting significant spatial association, coherent clusters (High – High and Low**
523 **– Low), and spatial outliers (High – Low and Low –High) as a function of neighbourhood distance**



525

526 *Figure 12. Fraction of sensors classified as statistically significant local clusters (High-High and Low-Low) and*
 527 *spatial outliers (High-Low and Low-High) as a function of neighbourhood size for heatwave (HW) and non-*
 528 *heatwave (nonHW) daytime and nighttime temperature fields.*

529

regime	N_sensors	N_timesteps	cluster50_distance_m	HH_at_50pct	LL_at_50pct
HW_day	3072	55	239.2	0.147	0.197
HW_night	3072	55	112.0	0.231	0.211
nonHW_day	3083	360	238.8	0.139	0.226
nonHW_night	3083	360	169.5	0.192	0.182

530 *Table 3. Summary table of LISA statistics for aggregated mean temperatures. N_sensors = number of sensors;*
 531 *N_timesteps = number of observations used to calculate the mean field; cluster50_distance_m = neighbourhood*
 532 *distance at which significant local clustering exceeds 50% of sensors; HH_at_50pct and LL_at_50pct = fractions*
 533 *of sensors belonging to High-High and Low-Low clusters, respectively, at that scale.*

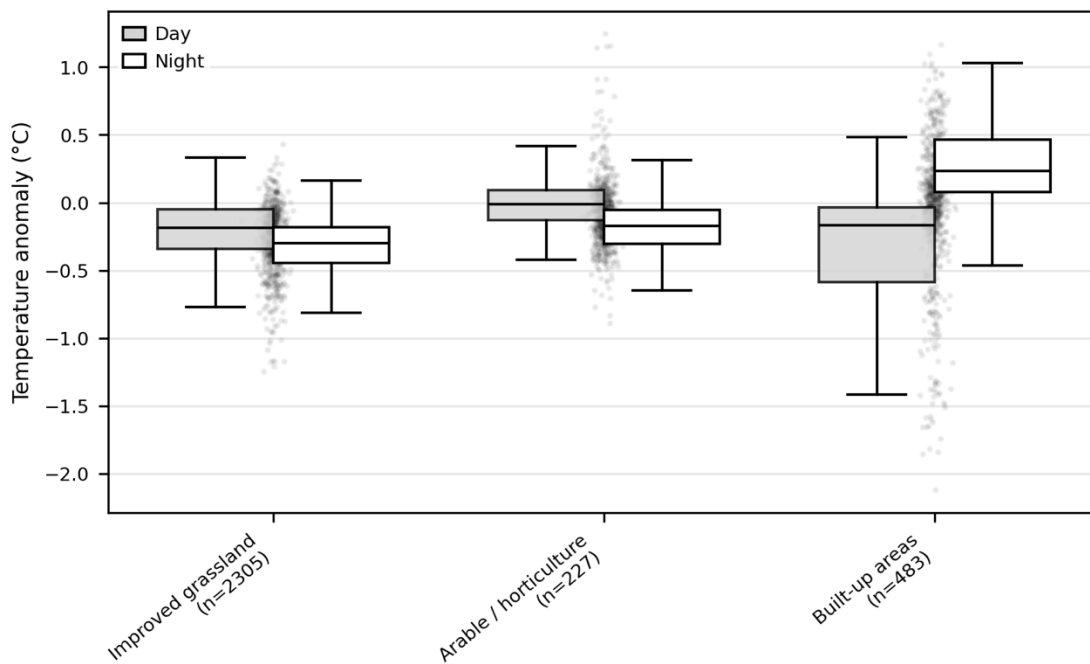
534

535 3.5 Influence of Environment and Land Use on Thermal Variability

536 The distribution of temperature anomalies varies systematically across land-use classes,
 537 as shown in **Figure 13** and summarised in **Table 4**. Thermal anomalies exhibit strong
 538 land-use and diurnal dependence. Built-up areas show a pronounced reversal between
 539 daytime and nighttime conditions, with negative mean anomalies during the day (≈ -0.35
 540 $^{\circ}\text{C}$) but positive anomalies at night ($\approx +0.29$ $^{\circ}\text{C}$) relative to the woodland reference class.
 541 In contrast, improved grassland exhibits consistently negative anomalies during both
 542 daytime and nighttime periods, with the strongest cooling observed nocturnally (≈ -0.32
 543 $^{\circ}\text{C}$). Persistence metrics similarly demonstrate enhanced nocturnal thermal retention

544 within built environments, where positive anomalies occur more frequently (≈ 0.61) than
545 in grassland environments (≈ 0.34). Differences are also evident in the upper tails of the
546 distributions, with built-up areas exhibiting elevated nighttime extremes ($p95 \approx 1.90$ °C),
547 whereas grassland environments display comparatively suppressed nocturnal extremes
548 ($p95 \approx 0.82$ °C). Woodland environments exhibit the greatest overall variability ($\sigma \approx 1.09$ –
549 1.11 °C), reflecting strong local thermal fluctuations around the reference condition.
550 Together, these results indicate that land-use controls on temperature anomalies are
551 strongly regime dependent and are dominated by nocturnal heat retention and
552 persistence rather than daytime mean temperature contrasts alone. The persistence
553 metrics are unlikely to be substantially influenced by thermal inertia of the sensor
554 housing. As an example, for one of the sensors used in the GBT model, the mean absolute
555 temperature-change rates recorded by the node and the reference weather station were
556 2.19 °C h^{-1} and 2.15 °C h^{-1} , respectively, yielding a ratio of 1.02 . Hourly temperature-
557 change rates were also strongly correlated ($r = 0.79$), indicating similar rates of warming
558 and cooling between the node and the reference station.

559



560

561 **Figure 13. Box plot of mean daily temperature anomaly by land use classification**

Land use type	period	mean	ci95_low	ci95_high	std	persistence	p95	N_values	n_sensors
Arable / horticulture	day	0.022	-0.004	0.049	0.251	0.446	0.498	344	227
Arable / horticulture	night	-0.181	-0.201	-0.161	0.192	0.405	0.118	343	227
Broadleaf woodland	day	-	-	-	-	0.464	-	344	68
Broadleaf woodland	night	-	-	-	-	0.457	-	343	68
Built-up areas	day	-0.351	-0.402	-0.299	0.485	0.360	0.131	344	483
Built-up areas	night	0.287	0.258	0.317	0.281	0.605	0.791	343	483
Improved grassland	day	-0.239	-0.269	-0.209	0.285	0.357	0.122	344	2305
Improved grassland	night	-0.322	-0.343	-0.300	0.202	0.336	-0.034	343	2305

562

563 *Table 4. Summary of temperature anomaly by land use type*

564 **4 Discussion**

565 This study presents what is thought to be the highest density of in situ surface
566 temperatures reported to date, comprising over 80 million measurements from 3,083
567 sensors covering 6 km². The dataset is unique in that it coincides with an extreme
568 heatwave, capturing conditions rarely observed at such spatial resolution. This unique
569 dataset enables quantification of the sub 100 m variability including spatial contrasts and
570 capturing the diurnal evolution of heterogeneity. The data demonstrate the potential of
571 using incidental environmental measurements from non-dedicated sensors to
572 complement existing crowdsourced weather data and the associated corrections which
573 often rely on machine-learning algorithms (e.g. Beele et al. 2022, Brousse et al. 2023).

574 Previous studies have shown that within cities air temperature differences can reach ~8–
575 9 °C during extreme heat events, indicating substantial spatial variability at the urban
576 scale (Cao et al., 2021). The results here demonstrate differences of several degrees also
577 occur over distances of tens of metres, revealing significant thermal heterogeneity exists
578 at much finer spatial scales than typically resolved. This suggests that urban temperature
579 variability is not only a large-scale phenomenon but is also strongly expressed at sub 100
580 m scales. The fine-scale variability identified here highlights the potential for remotely
581 sensed land surface temperature (LST) products to overlook local temperature contrasts
582 because they represent spatially aggregated surface conditions.

583

584 **4.1 Measurement artefacts and thermal response**

585 The uncorrected sensor data exhibit strong correlations with radiation and weak or
586 inconsistent relationships with wind speed and humidity, that are interpreted as
587 indicating the temperatures respond primarily to radiative exposure and diurnal
588 covariance. The absolute values are modified by the thermal characteristics of the
589 seismic node housing. The housing modifies the radiative environment experienced by
590 the temperature sensor and introduces some thermal buffering, resulting in a reduced
591 diurnal temperature range relative to the reference weather station. Daytime maxima are
592 likely moderated by shielding of the internal temperature sensor from direct solar
593 radiation, while slightly elevated nocturnal temperatures may reflect reduced radiative
594 cooling and a small background thermal offset associated with the node electronics and
595 enclosure. Comparison of hourly temperature change rates between the nearest node
596 not used in calibration (2300033336) and the reference weather station showed very
597 similar rates of warming and cooling (2.19 and 2.15 °C h⁻¹, respectively), indicating that
598 the sensor housing is unlikely to introduce substantial delays in thermal response.
599 Radiation-induced bias in unshielded sensors is strongly correlated with diurnal
600 temperature range (Berk et al., 2025; Yang et al., 2025). The raw sensor temperature
601 reflects both environmental forcing and biases associated with radiative exposure and

602 the thermal properties of the housing. The GBT correction accounts for systematic
603 measurement biases associated with radiative exposure and sensor configuration,
604 improving the correspondence between node temperatures and external environmental
605 forcing.

606

607 **4.2 Limitations of analysis**

608 The results demonstrate consistent differences in surface temperatures across land-use
609 classes, particularly in terms of persistence and extremes. However, there are limitations
610 in calibration and data resolution that constrain the extent to which these dynamics can
611 be fully resolved from this survey data.

612 While sub-hourly sensor data reveal rapid thermal dynamics, attempts to apply
613 correction models at this resolution are limited by the temporal resolution of the
614 calibration data. In this study, only the temperatures from meteorological station were
615 available on sub hourly intervals, with all other properties, including radiation, available
616 only at hourly intervals. Consequently, efforts to apply sub-hourly correction did not yield
617 as reliable estimates of temperature change rates. However, the raw sensor data indicate
618 the presence of high-frequency variability, indicating that, with appropriately resolved
619 meteorological forcing (e.g. sub-hourly radiation and atmospheric measurements),
620 dense sensor networks could be calibrated to capture fine-scale temporal dynamics.

621 While the temperature reflects the thermal state of the device rather than ambient air
622 temperature directly there is limited evidence to indicate that internal electronic heating
623 influences the recorded temperatures (see Supplementary Material 2). The positive
624 relationship observed between internal temperature and Mean DC offset is interpreted
625 as temperature-dependent drift in electronic offsets within the acquisition circuitry
626 rather than evidence of temperature changes induced by node activity. Although Mean
627 DC offset increased with temperature, it is a diagnostic metric and not a direct indicator
628 of energy consumption. The weak association between temperature and RMS signal
629 amplitude suggests that the node activity did not systematically coincide with higher
630 temperatures. We conclude that environmental forcing, rather than operational self-
631 heating, dominates the recorded temperature signal.

632 The correction model was developed using 1,914 hourly observations (1,530 used for
633 training) from three calibration sensors. While this provides sufficient data for tree-based
634 learning, the effective sample size is reduced by temporal autocorrelation. A limitation of
635 the approach is that calibration data were derived from sensors located within a relatively
636 small area surrounding a single reference station. Consequently, the model assumes
637 that the relationship between microcontroller die temperature and ambient
638 environmental temperature remains consistent across the wider survey area and under
639 different local environmental conditions. While the calibration produced internally

640 consistent results across the array, future deployments should evaluate calibration
641 performance across a broader range of land-use types and microclimatic settings to
642 determine whether a single reference station is sufficient or whether multiple calibration
643 locations are required to account for spatially variable environmental influences on
644 sensor behaviour.

645 More broadly, calibration is derived from a limited subset of locations and is not explicitly
646 stratified across land-use types, meaning that potential land-use-specific biases in
647 sensor response or microclimatic forcing may not be fully resolved. This is particularly
648 relevant for unshielded low-cost temperature sensors, which can exhibit non-linear
649 biases associated with solar radiation loading, housing thermal inertia, and diurnal
650 temperature range. Berk et al., (2025) demonstrated that such biases can vary
651 systematically with environmental conditions and may not be fully removed through
652 calibration against a single reference station. Consequently, while the broad spatial
653 patterns, land-use differences, and clustering behaviour identified in this study are
654 considered robust, the magnitude of the most extreme daytime temperature anomalies
655 and upper-tail statistics should be interpreted with appropriate caution.

656 In addition, land-use classification was based on broad polygon datasets that may not
657 capture fine-scale heterogeneity at the resolution of the sensor deployment (e.g. 10m),
658 and corrected temperatures were not independently validated against additional in situ
659 reference measurements. These limitations indicate that the results should be
660 interpreted as a demonstration of capability rather than a definitive quantification of
661 land-use effects.

662 With appropriate calibration, temperature measurements from embedded
663 microcontroller sensors could provide a low-cost, scalable complement to conventional
664 meteorological monitoring networks. Future work should consider implementing a
665 metadata-based quality control protocol, as seen in dense crowdsourced weather
666 networks such as 'Leuven.cool' (Beele et al., 2022) or Netatmo-based studies (Chapman
667 et al., 2016). This could further improve distinguishing environmental signal from
668 artifacts based on siting characteristics (e.g., proximity to buildings, sensor height).

669

670 **4.3 Magnitude and structure of spatial temperature variability**

671 The results demonstrate strong regime dependence in both the magnitude and spatial
672 organisation of near-surface temperature variability, consistent with behaviour reported
673 in existing studies of urban climate systems (e.g. Roth et al., 2022). Spatial temperature
674 differences are largest during daytime heatwave conditions and substantially reduced at
675 night, consistent with behaviour reported in urban climate studies and numerical
676 modelling experiments (Shreevastava et al., 2021). During daytime heatwave conditions,
677 mean temperature differences reach approximately 3.0 °C at broader spatial scales and

678 2.35 °C between adjacent sensors, compared with approximately 2.3 °C and 1.91 °C
679 respectively during nighttime periods. Extreme contrasts are also observed, with
680 maximum differences exceeding 17 °C during peak daytime heatwave conditions. Upper-
681 end temperature differences (95th percentile) remain high during daytime heatwaves,
682 reaching approximately 7.7 °C at broader spatial scales and 5.9 °C at adjacent scales,
683 indicating that substantial thermal contrasts occur across large portions of the study
684 area rather than being restricted to isolated outliers.

685 Spatial analyses further demonstrate that the temperature field is structured rather than
686 random. Variogram analysis indicates short daytime correlation lengths (~90 m median
687 range) and substantially longer nighttime correlation lengths (~170–270 m), reflecting a
688 transition from locally heterogeneous daytime conditions to more spatially coherent
689 nighttime temperature fields. Multi-scale LISA analysis similarly shows that coherent
690 thermal clustering strengthens systematically with neighbourhood scale, with nighttime
691 heatwave conditions exhibiting the strongest spatial organisation. More than 90% of
692 sensors exhibit statistically significant local clustering at the largest neighbourhood
693 scales during nighttime conditions, while daytime conditions remain comparatively
694 fragmented and locally variable. Cluster analysis also identifies persistent high-high and
695 low-low thermal regions, indicating that coherent hotspots and cool zones emerge
696 across the landscape rather than forming purely stochastic spatial patterns.

697 The observed land-use dependence provides a likely mechanism for these spatial
698 behaviours. Built-up areas exhibit a strong diurnal reversal, with negative daytime
699 anomalies relative to woodland environments but positive nighttime anomalies and
700 substantially greater nocturnal persistence. In contrast, grassland environments exhibit
701 consistently negative anomalies and reduced nighttime persistence, indicating more
702 efficient cooling and reduced thermal storage. These contrasts suggest that the observed
703 nighttime spatial coherence is partly driven by differential thermal retention between
704 land-use classes, producing organised mesoscale thermal structures that persist after
705 sunset. During daytime heatwave conditions, however, strong radiative forcing and fine-
706 scale surface heterogeneity generate highly localised temperature contrasts that reduce
707 overall spatial coherence despite large thermal gradients.

708 The dense sensor array captured fine-scale thermal heterogeneity that may not be
709 resolved by conventional remote sensing approaches or coarser monitoring networks.
710 Although remotely sensed land surface temperature products commonly identify broad
711 urban-rural thermal gradients, the present results demonstrate that substantial
712 temperature variability persists at scales below ~100 m, particularly during daytime
713 heatwave conditions. Consequently, assessments of heat exposure, ecosystem stress,
714 and thermal refugia based solely on coarse spatial products may underestimate the
715 magnitude and persistence of local thermal contrasts experienced at scales relevant to
716 ecosystems and human exposure.

717

718 **4.4 Implications for modelling approaches**

719 Many models of urban climate and meteorological conditions for human health or
720 ecology are developed to produce results at km-scale resolution, with models used for
721 human health extending to down to ~250 m resolution (Schinasi et al., 2018; e.g. Yi et al.,
722 2022) and in ecology even down to 25 m (Kempainen et al., 2024; Haesen et al., 2023).
723 However rarely do comparative observational datasets with such high spatial resolutions
724 exist. The equipment deployment here enabled distinguishing spatial heterogeneity as
725 fine as 10 m between individual pairs and the reliable construction of gridded
726 temperature maps with 100 m cell size. These data enable the identification of clear sub-
727 kilometre variability and at hourly intervals. The results indicate that the use of incidental
728 environmental sensing could provide a basis calibrating or independently validating
729 modelling results.

730 The results also provide insights into the interaction between meteorological forcing and
731 surface characteristics (Dickinson, 1995; Nicholson, 1988). Observations indicate
732 diurnal and heatwave forcing dominate variability demonstrated by strong day–night
733 contrast (~40% reduction at night) with the amplification of this during heatwave periods
734 (~15–20%). The different land use types and surface characteristics act as secondary
735 modifiers tending to influence magnitude, not primary structure. Spatial patterns reflect
736 local response to atmospheric forcing, not static land classification alone. This implies
737 that when aggregated land surface classification is useful first-order predictor of thermal
738 behaviour, but is insufficient to explain short-term dynamics

739 The data here reveal short-lived but intense local temperature extremes that are unlikely
740 to be captured by high temporal resolution from single meteorological station data, or
741 from spatially extensive, but lower and temporal resolution averages from remote
742 sensing. This has implications for understanding, for example, the public health risks
743 associated with heat exposure (Pan et al., 2024), urban planning (lungman et al., 2023)
744 and ecosystem responses (Piano et al., 2017). The results from our study evidence that
745 there are isolated and short-term local variability during heat wave events that current
746 approaches may not capture.

747

748 **4.5 Value of opportunistic and distributed sensing**

749 The results demonstrate the feasibility of repurposing non-dedicated sensors for
750 environmental monitoring, with obvious key advantages in terms of sensor density,
751 spatial coverage, and cost-effectiveness. This suggests that existing distributed sensor
752 networks represent a largely underutilised resource for characterising environmental
753 conditions at high spatial resolution. These could also be utilized to verify existing

754 methods for correcting dense crowd-sourced weather data, such as spatially explicit ML-
755 based corrections (Beele et al., 2022; Brousse et al., 2023)).

756 Calibration of low-cost environmental sensors using statistical and machine learning
757 approaches is well established, with studies demonstrating substantial improvements in
758 data quality through co-location with reference instruments and the inclusion of
759 environmental predictors such as radiation and temperature (Nan et al., 2025). Recent
760 work has also highlighted the importance of temporal correction and spatial consistency
761 in distributed temperature measurements (Xu et al., 2025), reinforcing the need to
762 address systematic sensor biases. There are limitations of unshielded, non-aspirated
763 sensors, such as used in this study; specifically, the challenges regarding thermal inertia
764 and residual radiation bias that persist despite statistical correction, and as recent work
765 (e.g. Yang et al., 2025) suggests these can impact measurements even after correction.

766 There is significant potential to integrate the use of non-dedicated sensing with existing
767 IoT networks and infrastructure monitoring systems, to enable dense, cost-effective
768 environmental sensing at spatial scales that are difficult to achieve using conventional
769 meteorological instrumentation alone. This study demonstrates that temperature
770 measurements acquired by semiconductor temperature sensors embedded within
771 geophysical instrumentation can provide meaningful environmental observations
772 alongside their primary function. For geophysical surveys, opportunities exist to exploit
773 temporary high-density terrestrial arrays, such as in seismic acquisition, for
774 microclimate and meteorological monitoring, while similar approaches could potentially
775 be extended to the marine environment, where ocean-bottom seismic instrumentation
776 may provide complementary observations of seafloor temperature variability. More
777 broadly, the widespread deployment of instrumented sensor networks for engineering,
778 and infrastructure monitoring suggests an opportunity to develop large-scale
779 opportunistic environmental observing systems that leverage existing hardware and
780 deployments rather than relying solely on dedicated meteorological networks.

781

782 **5 Conclusions**

783 This study demonstrates the feasibility of using dense networks of non-dedicated
784 sensors to resolve surface temperature variability at spatial and temporal scales that are
785 not routinely captured by conventional meteorological instrumentation or satellite
786 observations. By repurposing temperature measurements from microcontrollers within
787 over 3,000 nodal seismometers, and applying a statistical bias-correction, it has been
788 possible to characterise micro-scale thermal variability across a 6 km² area during an
789 extreme heat event.

790 The analysis shows that raw sensor measurements are strongly influenced by radiative
791 exposure effects, resulting in inflated relationships with radiation and weak or

792 inconsistent responses to other meteorological variables. Application of a machine
793 learning-based correction substantially reduces radiative and exposure-related
794 artefacts and yields a temperature signal that is consistent with co-located weather
795 observations. Although differences in sensor configuration and enclosure design result
796 in a reduced diurnal temperature range relative to the reference station, comparison of
797 warming and cooling rates indicates that the sensor nodes respond rapidly to
798 environmental temperature variations. Nevertheless, some uncertainty remains
799 regarding the influence of sensor exposure and enclosure characteristics on the absolute
800 magnitude of temperature extremes.

801 The work highlights the potential of leveraging existing distributed sensor networks as a
802 cost-effective approach to environmental monitoring, offering significant advantages in
803 terms of spatial density and coverage. Application of a Gradient Boosting Tree correction
804 substantially reduced radiation-related measurement artefacts and produced
805 temperatures that closely matched reference observations. The corrected dataset
806 revealed strong fine-scale thermal heterogeneity, with temperature differences
807 exceeding 5 °C over distances of only a few hundred metres during heatwave conditions
808 and substantially greater nocturnal thermal persistence within built-up areas than
809 grassland environments (0.61 versus 0.34).

810 Such approaches complement conventional high-precision meteorological
811 observations and provide new insight into thermal environments at scales relevant to
812 human exposure, ecosystems and infrastructure. Future work should focus on improving
813 calibration across a wider range of environmental conditions and land-use types, as well
814 as integrating higher-temporal-resolution meteorological forcing to better resolve rapid
815 thermal dynamics. More broadly, there is significant potential to extend this approach
816 through integration with IoT and infrastructure monitoring systems, enabling large-scale,
817 high-resolution environmental sensing using existing sensor deployments.

818

819 **6 Acknowledgements**

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822 Newcastle University students employed on campus (SEOC) who supported the
823 deployment and retrieval of the geophysical survey. We thank STRYDE for providing
824 support and expertise for the use of their seismic nodes, including during survey planning
825 and acquisition and the specifics of the device performance.

826

827 **7 Data availability**

828 The data used in this study and ML models are available from the follow repositories:

- 829 • Hourly weather station observations [10.25405/data.ncl.32786229]
- 830 • Raw temperature records [10.25405/data.ncl.32785947]
- 831 • Corrected hourly temperatures [10.25405/data.ncl.32785986]
- 832 • Device operation metadata and Supplementary Material S2
- 833 [https://doi.org/10.25405/data.ncl.32786010]
- 834 • Land use classifications, building geometries, and the digital terrain model used
- 835 in this study are available via Digimap [https://digimap.edina.ac.uk].
- 836 • Code used in the machine learning models and Supplementary Material S1
- 837 (parameters used in ML) [10.25405/data.ncl.32786229]

838

839 **8 Author Contributions**

840 Mark Ireland (MI): Conceptualization; Methodology; Software; Formal analysis; Writing –
841 original draft; Writing – review & editing.

842 Hector Barnett (HB): Methodology; Software; Data curation; Writing – review & editing.

843 Abdullah Kahraman (AB): Writing – review & editing.

844 Charles Dunham (CD): Conceptualization; Methodology; Data curation; Writing – review
845 & editing.

846

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853

854 **10 Conflict of interest**

855 The authors declare no competing interests.

856

857 **11 References**

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