Publisher: GSA Journal: GEOL: Geology DOI:10.1130/G38158.1 Comparing submarine and fluvial channel kinematics:

2 Implications for stratigraphic architecture

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9 ABSTRACT

10 Submarine and fluvial channels exhibit qualitatively similar geomorphic patterns, 11 yet produce very different stratigraphic records. We reconcile these seemingly 12 contradictory observations by focusing on the channel-belt scale and quantifying the 13 time-integrated stratigraphic record of the belt as a function of (1) the geometric scale and 14 (2) the trajectory of the geomorphic channel, applying the concept of stratigraphic 15 mobility. By comparing 297 submarine and fluvial channel belts from a range of tectonic 16 settings and time intervals, we identify channel kinematics (trajectory) rather than 17 channel morphology (scale) as the first order control on stratigraphic architecture and 18 show that seemingly similar channel forms (in terms of scaling) have the potential to 19 produce markedly different stratigraphy. Submarine channel-belt architecture is 20 dominated by vertical accretion (aggradational channel fill deposits), in contrast to fluvial 21 systems that are dominated by lateral accretion (point bar deposits). This difference is 22 best described with the channel-belt aspect ratio, which is 9 for submarine systems and

23	72 for fluvial systems. Differences in channel kinematics and thus stratigraphic
24	architecture between the two environments appear to result from markedly different
25	coupling between channel aggradation and overbank deposition. The methodology and
26	results presented here are also applicable to interpreting channelized stratigraphy on other
27	planets and moons.
28	INTRODUCTION
29	Sinuous submarine and fluvial channels have qualitatively similar planform
30	morphologies, but very different preserved stratigraphic records (Flood and Damuth,
31	1987; Kolla et al., 2007). Sinuous fluvial channel belts are dominated by lateral migration
32	deposits, including point bars and oxbow cutoffs (Allen, 1965; Sun et al., 1996) and
33	undergo only minor aggradation (>1 channel depth of super-elevation) prior to avulsion
34	(Mohrig et al., 2000). Submarine channels, while displaying lateral migration (Abreu et
35	al., 2003; Kolla et al., 2012), tend to have a more significant component of vertical
36	aggradation (Peakall et al., 2000; Deptuck et al., 2007; Sylvester et al., 2011). Submarine
37	channel-belt deposits are commonly offset to vertically stacked, sand-rich channel fill
38	deposits (Macauley and Hubbard, 2013). This study quantifies the similarities and
39	differences between submarine and fluvial channel belts and explores the formative
40	processes that result in vastly different kinematics and stratigraphic architecture.
41	CHANNEL KINEMATICS: TRAJECTORY AND MOBILITY
42	Definitions and Methodology
43	Jerolmack and Mohrig (2007) introduced the channel mobility number (Equation
44	1) as a metric to characterize and understand channel deposits. The mobility number is

45 defined as the ratio of avulsion and lateral migration time scales. In a more general sense,

46	channel mobility describes a channel trajectory scaled by the dimensions of the
47	geomorphic channel form. For applications to modern rivers, channel trajectory can be
48	expressed as the ratio of temporal rates of lateral (V_c) and vertical (V_a) migration
49	(Jerolmack and Mohrig, 2007). Because we are interested in characterizing the preserved
50	stratigraphic record of channel trajectory where rate data (i.e., Va, Vc) are uncommon, we
51	propose a stratigraphic mobility number, M _s .
52	We recast the mobility equation, by substituting the temporal rates (V_c/V_a) with
53	the relative spatial displacements (L_c/L_a) of the channel as measured in a strike-oriented
54	cross section (Fig. 1; Equation 2). The two formulations (M and M_s) are conceptually
55	identical if considered over the same time-period. The 'local' stratigraphic trajectory
56	(L_c/L_a) can be thought of as spatially separated points that denote the spatial path of the
57	channel thalweg/centerline through time, where each point along the path represents an
58	easily identifiable location of the channel thalweg (Fig. 1C; cf. 'discrete migration
59	events' of Deptuck et al., 2007; Kolla et al., 2007). We also define an aggregate or belt
60	averaged stratigraphic mobility number, M _{sb} , using the channel belt dimensions
61	(Equation 3). Channel belt width (B_{cb}) and thickness (H_{cb}) are defined as the maximum
62	lateral and vertical extent of the belt (including the youngest channel form), respectively
63	(Fig. 1). Channel width (B) and thickness (H) were estimated from the final channel form
64	(Fig. 1). Note that B_{cb} and H_{cb} are minimum estimates because we do not include any
65	coeval overbank or levee deposits.

$$66 M = \frac{V_{\rm c}}{V_{\rm a}} \frac{\overline{h}}{B}, (1)$$

$$67 M_{\rm sl} = \frac{L_{\rm c}}{L_{\rm a}} \frac{H}{B}, (2)$$

68 M	$M_{\rm sb} = \frac{(B_{\rm cb} - B)}{(H_{\rm cb} - H)} \frac{H}{B}.$	(3)
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69	The local (M_{sl}) and belt-averaged (M_{sb}) methods calculate the stratigraphic
70	mobility number at the scale of individual channel migration events and the entire
71	channel belt scale, respectively (Fig. 1). While the stratigraphic record is biased toward
72	the preservation of net-aggradational channel belts that produce $M_s > 0$, negative values
73	of M _s describe degradational phases of channel belt evolution or net-degradational fluvial
74	and submarine channel belt deposits. Because M_{sl} is calculated using each L_c/L_a point
75	pair of the channel trajectory, it has a broader distribution of values than M_{sb} . In both
76	definitions, large values of M _s result from channels with abundant lateral migration but
77	little aggradation relative to the size of the geomorphic channel form.
78	Data Sources and Interpretation
79	This study compiles 297 channel trajectory and channel-form geometry
80	measurements from a global sampling of 21 submarine systems and 13 fluvial systems
81	(Fig. 1B; Table DR1 in the GSA Data Repository ¹). Data sources include seismic-
82	reflection cross-sections and outcrop exposures. In order to standardize measurements,
83	we utilized a simple set of guidelines based on observable seismic/outcrop facies and
84	geometries (Fig. 1C; see the Data Repository). We define a channel belt as a coherent
85	package of channel-related deposits that does not contain significant erosion (i.e., >1
86	channel depth). Thus, channel belts are separated by avulsion or significant erosion
87	events that reset the geomorphic channel surface. This definition of channel belt does not
88	imply an absolute temporal duration, only the relative time of channel belt formation,
89	which may vary by system.

90	Trajectory data (L_c , L_a) were collected for each channel belt at the basal
91	terminations of inclined reflectors/surfaces from selected cross sections, with the
92	assumption that these points closely approximate the coeval channel thalweg (Fig. 1).
93	The spacing of recorded trajectory points was dictated by observable reflectors/surfaces
94	(Fig. 1C). Channel forms were interpreted based on concave up geometries, internal lap-
95	out geometries, and vertical transition to horizontal, parallel, laterally continuous
96	reflectors (Fig. 1C). Some channel forms were truncated by subsequent erosion and thus
97	form minimum values of B and H. We acknowledge that the measurement of channel
98	form within the stratigraphic record can be difficult and at times may differ from the
99	geomorphic channel form. However, our measurements of B, H, and B/H (aspect ratio)
100	generally agree with measurements from modern topographic and bathymetric data (Fig.
101	DR1), indicating that better preservation and/or decompaction of the channel form would
102	not significantly alter the results of this study. Interestingly, the B/H data from Jerolmack
103	and Mohrig (2007) is quite different from all other sources, likely due to their focus on
104	anastomosing and distributary systems (see the Data Repository; Fig. DR1).

105 COMPARISONS OF SUBMARINE AND FLUVIAL DATA

106 Channel and Channel Belt Dimensions

107 Channel and channel-belt width (B, B_{cb}) are broadly similar for submarine
108 channels and rivers, with submarine channels tending to be somewhat wider than rivers
109 (Fig. 2; Fig. DR1). However, submarine channel and channel-belt thickness (H, H_{cb}) are
110 4–5× thicker than their fluvial counterparts (Fig. 2). While the absolute dimensions (Figs.
111 2A–D) display differences in width and thickness, normalized dimensions (Figs. 2E–G)
112 are more useful to evaluate differences in lateral and vertical channel migration at the

113	DOI:10.1130/G38158.1 channel-belt scale. Our data indicates that the median value of normalized channel belt
114	width (B_{cb}/B) for fluvial systems is 4.7, much greater than 2.1 for submarine systems
115	(Fig. 2E). Normalized channel belt thickness (H_{cb}/H) values have the opposite
116	relationship, with median values for submarine systems (2.9) being almost twice that of
117	fluvial systems (1.6; Fig. 2F). These results are summarized with the channel belt aspect
118	ratio (B_{cb}/H_{cb}) that describes the shape of the channel belt (Fig. 2G). Due to high
119	aggradation (i.e., low values of L_c/L_a), submarine channel belts tend to be thick and
120	narrow, with a median value of $B_{cb}/H_{cb} = 9$, whereas fluvial channel belts are thin and
121	wide, with a median value of 72 (Fig. 2G).
122	Channel Kinematics: Trajectory and Stratigraphic Mobility
123	Trajectory describes the shape of the path of a channel as it migrates in time and
124	space to form a channel belt. A plot of L_c versus L_a presents the shape of the trajectories
125	collected from seismic and outcrop channel belts (Fig. 3A). Fluvial and submarine
126	trajectories have broadly similar ranges of L_{c} but submarine channels have ${\sim}10{\times}$ larger
127	values of L _a (Fig. 3). Submarine channel trajectories clearly demonstrate a two-phase
128	evolution that results in a hockey-stick trajectory shape: (1) a phase of lateral migration
129	(sometimes with degradation), followed by (2) a phase of increasing L_a (i.e., increasing
129 130	(sometimes with degradation), followed by (2) a phase of increasing L_a (i.e., increasing aggradation).
130	aggradation).

134 vertical aggradation ($M_{sl} \ge 0$) is very robust for submarine channel belts (Fig. 3B).

135 Interestingly, the same trend is present for fluvial channel belts, albeit with 10× lower

136 values of aggraded channel depths.

137	At the belt scale, submarine systems have much smaller values of M_{sb} than fluvial
138	systems (Fig. 3C), with median values of 0.6 and 5.5, respectively. This order-of-
139	magnitude difference indicates that during channel belt formation, submarine channels
140	aggrade $\sim 10x$ more than fluvial channels, resulting in a thicker, narrower channel belt
141	(Fig. 2G) and thus lower M_{sb} values (Fig. 3C). If a submarine channel belt is evolving
142	within larger-scale (i.e., canyon) confinement, this trend would be further exaggerated.
143	CONTROLS ON CHANNEL KINEMATICS
144	Why Do Submarine Channels Evolve from Lateral Migration to Aggradation?
145	The hockey-stick shape of channel trajectory (i.e., decreasing M_{sl} through time in
146	Fig. 3B) is consistent with conceptual models of submarine channel evolution (e.g.,
147	Peakall et al., 2000; Deptuck et al., 2007; McHargue et al., 2011). However, this study is
148	the first to quantify the trend with a global data set. Various mechanisms have been
149	proposed to explain this evolution, including turbidity current flow properties (Kolla et
150	al., 2007), progressive levee growth (Peakall et al., 2000), sediment supply versus
151	accommodation (Kneller, 2003), and changes in equilibrium profile (Hodgson et al.,
152	2011). Many studies invoke complex interactions between the above mechanisms. While
153	we cannot exclude allogenic mechanisms, our data were collected over a range of

- 154 tectonic settings, geologic-time intervals, and sediment supply regimes. Thus, we limit
- 155 the present discussion to autogenic variables that must be present in every submarine
- 156 channel system, regardless of tectonic setting or other allogenic controls.

157	We interpret that the flow properties unique to submarine channels are
158	responsible for enhanced levee growth and the resultant aggradation. Flows in submarine
159	channels have $\sim 50 \times$ less density contrast between flow and ambient fluid than rivers
160	(Imran et al., 1999), enhancing super-elevation of the flow around bends. This increases
161	the potential for overspill and flow stripping, which result in overbank deposition and
162	levee growth (Piper and Normark, 1983; Straub et al., 2008). In addition, the velocity
163	maximum in the vertical profile of a characteristic submarine flow is located much closer
164	to the bed relative to its fluvial counterpart (Sequeiros et al., 2010), such that overbanking
165	has a lower potential shear stress. Combined, these factors promote levee growth and
166	discourage avulsion.

167 For a submarine channel to maintain a constant cross-sectional area locally, there 168 must be coupling such that the thalweg aggrades as the levees grow or vice versa (e.g., 169 Imran et al., 1999). If either levee deposition (or thalweg deposition) occurs in isolation, 170 the cross sectional area of the channel is perturbed, causing either flow expansion (or 171 acceleration) (Exner equation, see Paola and Voller, 2005). This results in local 172 deposition (or erosion) in the channel thalweg to return the cross sectional area to its 173 original, equilibrium state. This depositional feedback results in aggradation of the entire 174 channel belt. These processes are reflected in the high aggradational potential of 175 submarine systems, which results in systematically thicker channel belts compared to 176 fluvial systems and is reflected in larger values of H_{cb}/H (Fig. 2F). Dorrell et al. (2015) 177 suggest that aggradational submarine channels are inherently unstable; we do not 178 disagree, but argue that instability is a relative term and that submarine channels are 179 much more stable under aggradational conditions than fluvial channels.

180 **Resultant Stratigraphic Architecture**

181 Normalized channel belt dimensions allow us to plot channel belts of differing 182 scale to assess their 'shape' and spatiotemporal evolution (Fig. 4A). The threshold 183 separating the dominance of lateral accretion versus 'vertical accretion' (i.e., aggradation) 184 can be described by the equation $\frac{B_{cb}}{H_{cb}} = \frac{B}{H}.$ 185 (4) 186 In cases where $B_{cb}/H_{cb} \ll B/H$, vertical accretion is the dominant form of 187 stratigraphic preservation, and where $B_{cb}/H_{cb} >> B/H$, lateral accretion is dominant. 188 Equation 4 is plotted as a line in Figure 4A. All fluvial systems plot below the threshold 189 line (Fig. 4A), indicating that lateral accretion is the dominant kinematic form. 73% of 190 submarine systems plot above the threshold, indicating that vertical accretion (i.e., 191 aggradation) is dominant for the majority of submarine channel belts. 192 A schematic of the key differences in the evolution and channel belt dimensions 193 of submarine and fluvial systems is presented in Figure 4B. Values of B_{cb}/B are variable 194 for both submarine and fluvial systems, likely because B_{cb}/B is proportional to the belt 195 maturity and floodplain erodability (cf. Sun et al., 1996). However, values of H_{cb}/H for 196 submarine systems are commonly $2 \times$ and sometimes $10 \times$ larger than fluvial systems. The 197 low stratigraphic mobility (M_s) and high aggradational potential of submarine channel 198 belts promotes the preservation of sandy channel fills and muddy levee and overbank 199 deposits (e.g., Jobe et al., 2015), while high M_s and low aggradational potential of fluvial 200 channel belts results in the preservation of sandy point bars and muddy oxbow deposits 201 (Fig. 1).

202 CONCLUSIONS

203	Fluvial and submarine channels have qualitatively similar planform patterns, but
204	very different stratigraphic records. Fluvial channel belts are relatively thin and
205	dominated by lateral migration deposits, while submarine channel belts are very thick and
206	contain more vertical accretion (i.e., aggradational channel-fill) deposits. Using a global
207	data set, this study describes the dimensions, kinematics, and stratigraphic mobility of
208	submarine and fluvial channel belts. Both submarine and fluvial systems exhibit a two-
209	phase evolution of the channel trajectory, a phase of lateral migration (sometimes with
210	degradation) and a phase of increasing aggradation while lateral migration decreases.
211	However, submarine channel belts are $2 \times$ thicker and have $10 \times$ smaller stratigraphic
212	mobility numbers than their fluvial counterparts. The channel belt aspect ratio best
213	describes this relationship, with median values for submarine and fluvial systems of 9 and
214	72, respectively. These results can be used to help interpret channelized stratigraphy on
215	other planets and moons, where the distinction between fluvial and submarine deposition
216	is often difficult. These data are collected from a range of tectonic settings and time
217	intervals, suggesting that differences in channel kinematics and thus stratigraphic
218	architecture in submarine channel systems are caused by flow properties of turbidity
219	currents. We interpret that higher quantities of suspended sediment in upper portions of
220	the flow and the position of the velocity maximum close to the bed cause enhanced levee
221	development and thus aggradation of the channel belt.

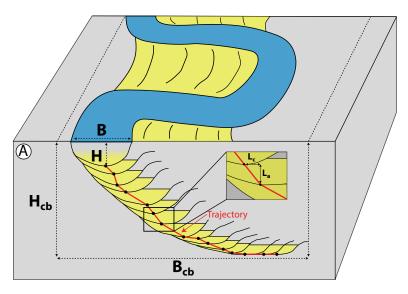
222 ACKNOWLEDGMENTS

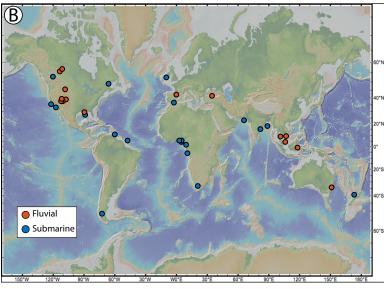
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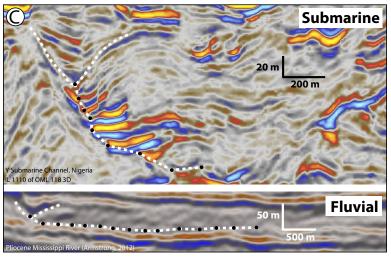
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- Figure 1. Kinematics of submarine and fluvial channels. A: Channel belt schematic.
- 230 Local stratigraphic mobility M_{sl} is calculated using relative spatial displacements (L_c/L_a),
- while belt-averaged $M_s(M_{sb})$ is calculated using channel belt width and thickness aspect
- ratio B_{cb}/H_{cb}. B: Map of the data set utilized in this study, including 21 submarine and 13
- 233 fluvial systems. C: Typical submarine and fluvial channel belts with interpretation
- 234 overlain. Submarine channels are more aggradational and thus have lower M_s values.

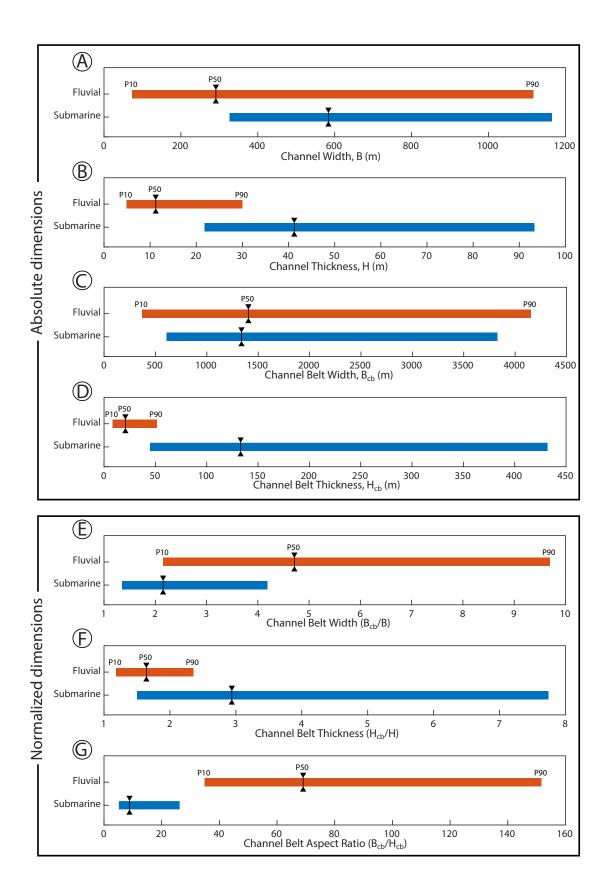




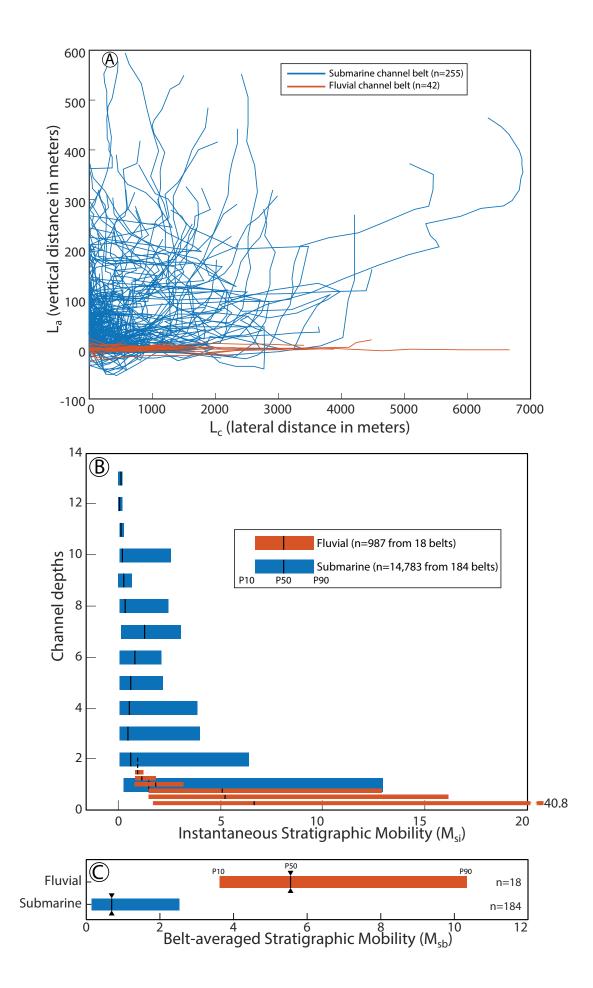


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- 237 Figure 2. Absolute (A–D) and normalized (E–G) channel and channel belt dimensions.
- 238 These data are summarized in the channel belt aspect ratio (G), where submarine channel
- 239 belts are $\sim 10 \times$ lower aspect (i.e., thick and narrow) as compared to fluvial channel belts.

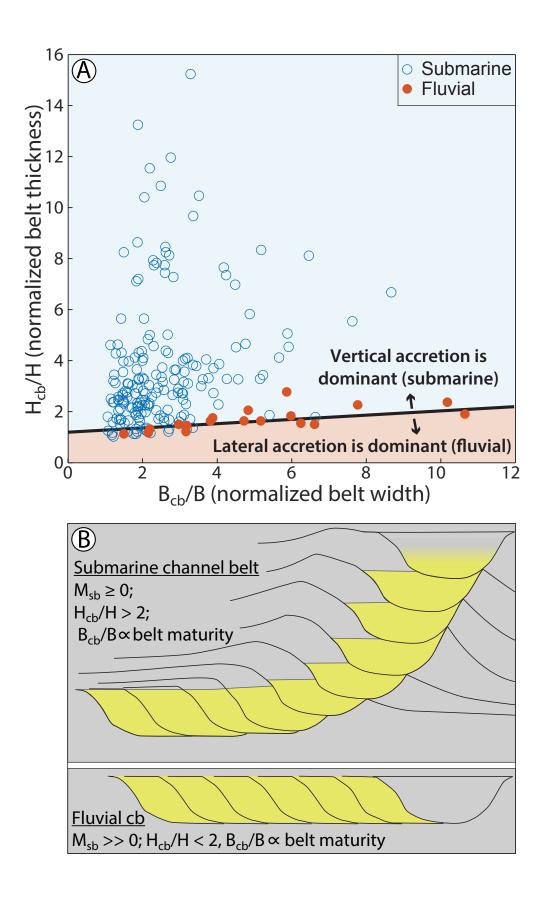


242	Figure 3. Stratigraphic trajectory and mobility measurements. A: Trajectories (i.e.,
243	kinematic paths) of submarine and fluvial channel belts. B: Plot of Local stratigraphic
244	mobility M_{sl} versus the height above the channel-belt base (z) normalized by the channel
245	thickness H. Submarine and fluvial channel belts have similar kinematic pathways, but
246	submarine channels have $\sim 10 \times$ more aggradation. C: Distribution of belt-averaged M _s
247	(M_{sb}), with submarine systems displaying 10× lower values (i.e., less lateral migration
248	and more aggradation) than fluvial systems.
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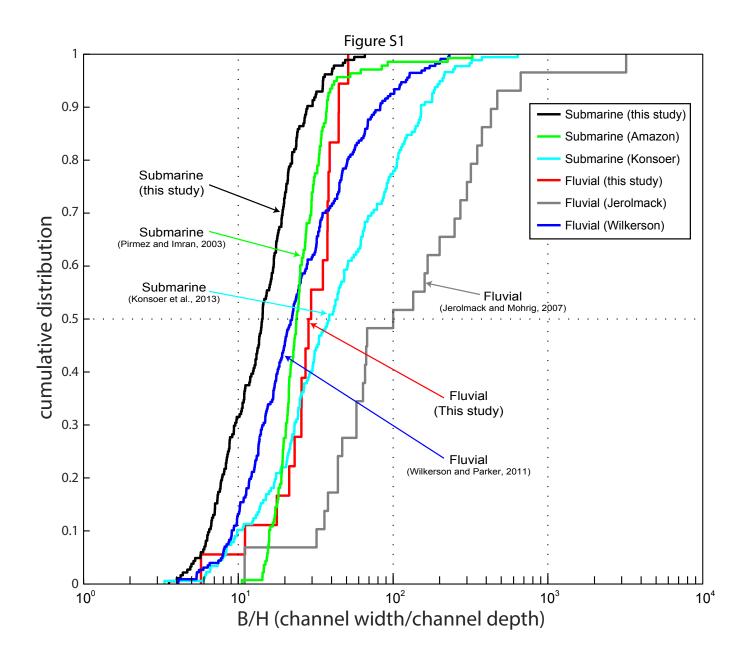
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- 251 Figure 4. A: Normalized channel belt dimension cross-plot. Dashed line separates the
- 252 dominance of lateral and vertical accretion deposits. Submarine channel belts are
- 253 dominated by 'vertical accretion' rather than lateral accretion. B: Summary diagram of
- the stratigraphic architecture of submarine and fluvial channel belts.



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- ¹GSA Data Repository item 2016xxx, data collection methodology and channel
- dimension data, is available online at http://www.geosociety.org/pubs/ft2016.htm or on
- 259 request from editing@geosociety.org.



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