1	Fault Growth and Interactions in a Multiphase Rift Fault Network: Horda					
2	Platform, Norwegian North Sea					
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4	Oliver B. Duffy ^{1*} , Rebecca E. Bell ¹ , Christopher A-L. Jackson ¹ , Rob L. Gawthorpe ² , Paul S.					
5	Whipp ³					
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7 8 9 10 11 12	 ¹Basins Research Group (BRG), Department of Earth Science & Engineering, Imperial College, Prince Consort Road, London, United Kingdom, SW7 2BP ²Department of Earth Science, University of Bergen, P.O. Box 7803, N-5020 Bergen, Norway ³Statoil ASA, Sandslivegen 90, 5254 Sandsli, Norway *Present Address of Corresponding Author: Bureau of Economic Geology, Jackson School of Geosciences, The University of Texas at Austin, University Station, Box X, Austin, Texas, 78713-8924, 					
13 14	USA (e-mail: oliver.duffy@beg.utexas.edu)					
15	Running Title: Fault Growth Characteristics in Multiphase Rifts					
16	Keywords: normal faulting, multiphase rifting, fault growth, fault interactions, fault throw, fault					
17	networks, North Sea					
18	Word Count: ca. 8500 (without abstract and acknowledgements)					
19	Abstract:					
20	Physical models predict that multiphase rifts that experience a change in extension direction between					
21	stretching phases will typically develop non-colinear normal fault sets. Furthermore, multiphase rifts					
22	will display a greater frequency and range of styles of fault interactions than single-phase rifts.					
23	Although these physical models have yielded useful information on the evolution of fault networks in					
24	map view, the true 3D geometry of the faults and associated interactions are poorly understood. Here,					
25	we use an integrated 3D seismic reflection and borehole dataset to examine a range of fault					
26	interactions that occur in a natural multiphase fault network in the northern Horda Platform, northern					
27	North Sea. In particular we aim to: i) determine the range of styles of fault interaction that occur					
28	between non-colinear faults; ii) examine the typical geometries and throw patterns associated with					
29	each of these different styles; and iii) highlight the differences between single-phase and multiphase					
30	rift fault networks. Our study focuses on a ca. 350 km ² region around the >60 km long, N-S-striking					

31 Tusse Fault, a normal fault system that was active in the Permian-Triassic and again in the Late Jurassic-to-Early Cretaceous. The Tusse Fault is one of a series of large (>1500 m throw) N-S-striking 32 faults forming part of the northern Horda Platform fault network, which includes numerous smaller 33 (2-10 km long), lower throw (<100 m), predominantly NW-SE-striking faults that were only active 34 35 during the Late Jurassic to Early Cretaceous. We examine how the 2nd-stage NW-SE-striking faults grew, interacted and linked with the N-S-striking Tusse Fault, documenting a range of interaction 36 styles including mechanical and kinematic isolation, abutment, retardation and reactivated relays. Our 37 results demonstrate that: i) isolated, non-interacting and abutting interactions are the most common 38 fault interaction styles in the northern Horda Platform; ii) pre-existing faults can act as sites of 39 nucleation for 2nd-stage faults or may form mechanical barriers to propagation; iii) the throw 40 distribution on reactivated 1st-stage faults will be modified in a predictable manner if they are 41 42 intersected or influenced by 2nd-stage faults; iv) sites of fault linkage and relay-breaching associated 43 with the first phase of extension can act as preferential nucleation sites for 2nd-stage faults; and v) the 44 development of fault intersections is a dynamic process, involving the gradual transition from one 45 style to another.

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47 **1. Introduction**

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49 Faults that develop during a single phase of extension typically strike sub-perpendicular to the extension direction and show an en échelon or colinear configuration (e.g. Gawthorpe and Leeder, 50 2000) (Fig 1). Faults with strikes that are oblique to the main rift trend (herein termed 'non-colinear 51 52 faults') can also develop during a single rift phase, commonly due to breaching of relay zones (e.g. 53 Trudgill et al., 2002), flexure and gravity-driven sliding of the cover above weak layers (e.g. overpressured mudstone or and salt; e.g. Stewart and Clark, 1999) and the development of 'release' 54 55 faults (e.g. Destro, 1995). Furthermore, non-colinear faults also develop in response to: i) perturbations in the local stress field around pre-existing or broadly synchronous normal faults 56

(Maerten et al., 1999; 2002); ii) compaction and dewatering, which in some cases leads to radiallyisotropic strain expressed as 'polygonal' faulting (e.g. Cartwright and Lonergan, 1996; Cartwright and
Dewhirst, 1998); and iii) the anisotropic effects of pre-existing fabrics that are oriented obliquely to
the extension direction (e.g. Morley et al., 2004) (*Fig. 1*; see also Reeve et al., 2015 for a synthesis).
However, the development of non-colinear faults in many of these cases is not pervasive across the
fault network and the range of styles of interaction and overall influence of fault interactions in the
evolution of the fault network is relatively low (*Fig. 1*).

64 In contrast, in multiphase rifts, and particularly where the extension direction during each rift 65 phase differs, faults formed in the first rift phase influence how strain is accommodated in the upper 66 crust in the second rift phase (e.g. Keep and McClay, 1997; Bellahsen and Daniel, 2005; Henza et al., 67 2011; Whipp et al., 2014). In this situation the later rift phase is characterised by reactivation of pre-68 existing faults from the 1st-rift stage and/or nucleation of newly formed, 2nd-stage faults in previously 69 unruptured crust, which generally strike sub-perpendicular to the new extension direction (e.g. Bailey 70 et al., 2005; Henza et al., 2010; 2011; Whipp et al., 2014). Fault networks in multiphase rifts are 71 therefore prone to comprise of pervasive non-colinear fault sets, with interaction and intersections 72 between the non-colinear faults common, as is observed in the Jeanne D'Arc rift (e.g. Sinclair and 73 Withjack, 2008), Gulf of Aden (Bellahsen et al., 2006), Gulf of Thailand (e.g. Morley et al., 2004, 74 2007), Alaska (Nixon et al., 2014) and the North Sea (Badley et al., 1998; Færseth, 1996; Odinsen et al., 2000; Whipp et al., 2014). 75

Much of our understanding of how non-colinear faults and fault interactions evolve in multiphase rifts is based on predictions from physical models (e.g. McClay and White, 1995; Bellahsen and Daniel, 2005; Henza et al., 2010; 2011; Chattopadhyay and Chakra, 2013). While these physical models provide important information on the plan-view evolution of faults and fault interactions, the true 3D geometry of the faults and interaction styles remain unknown. Furthermore, there is a general lack of observations of different fault interaction styles from outcrop or subsurface natural examples, although Nelson (2006) and Nixon et al. (2014) provide notable exceptions.

In this study we examine a fault network in a natural multiphase rift to: i) identify a range of styles of fault interaction and/or linkage between 1st and 2nd-stage faults; ii) examine the tipline 85 geometries, branchline characteristics and throw patterns associated with each interaction style; and iii) develop an understanding of how fault interaction styles evolve. To achieve this we integrate 86 observations from a 3D seismic reflection and borehole dataset that covers the northern Horda 87 Platform array, Horda Platform, northern North Sea. This setting is ideal for this study because 88 89 previous studies demonstrate the area was subject to two rift events, which resulted in the formation of fault sets with different dominant strikes (Badley et al., 1998; Færseth, 1996; Odinsen et al., 2000; 90 Whipp et al., 2014). Furthermore, the relatively shallow burial of the area means faults and 91 92 branchlines are well-imaged, and an abundance of borehole data allows us to constrain the age of growth strata adjacent to the faults, and hence constrain the temporal evolution of the fault array. 93 Using this information, we improve our understanding of how pre-existing faults influence the 94 95 development of subsequent fault networks and present a template of fault interaction styles that will 96 aid structural mapping in seismic datasets lacking such clear imaging of faults and their geometric 97 relationships.

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99 2. Geological Framework

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101 2.1 Regional Tectonic Evolution

102 The crystalline basement of the northern North Sea was influenced by contractional episodes in the 103 Caledonian (460-400 Ma) and Variscan (400-300 Ma) orogenies (e.g. Ziegler, 1975). During the Devonian, post-orogenic crustal relaxation resulted in the development of major extensional shear 104 105 zones and intermontane basins, such as those preserved onshore western Norway (e.g. Fossen, 1992; Vetti and Fossen, 2012). These extensional shear zones formed a crustal fabric which is interpreted to 106 107 have influenced the development of the North Sea basin by modifying the geometry of Mesozoic rift 108 systems and influencing the distribution of thermally-driven Cenozoic subsidence (e.g. Glennie et al, 1987; Ziegler, 1990; Stewart et al., 1992; Bartholomew et al., 1993; Smethurst, 2000). 109

The first main rift phase (herein termed 'Rift Phase 1') initiated in the Late Permian and
continued for 25-37 Myr before ceasing in the Early Triassic (e.g. Ziegler, 1982; Ziegler, 1990; 1992;

Ter Voorde et al., 2000). Based on the prevalence of large displacement (3-5 km), N-S-striking
Permian-Triassic fault systems, an E-W extension direction is inferred for Rift Phase 1 (Færseth,
1996; Færseth et al., 1997) (*Fig. 2*). Faults developed during Rift Phase 1 dip predominantly westward
and bound easterly-tilted half-grabens (e.g. Færseth, 1996; Bell et al., 2014) (*Fig. 2*).

116 Following a ca. 70 Ma period of relative tectonic quiescence and post-rift thermal subsidence, a second rift phase (herein termed 'Rift Phase 2') initiated in the Middle Jurassic (e.g. Badley et al., 117 1988; Underhill and Partington, 1993; Roberts et al., 1995; Coward et al., 2003; Cowie et al., 2005) 118 (Fig. 3). Rift Phase 2 continued until the Early Cretaceous, although the onset and cessation of active 119 faulting across the rift was diachronous (e.g. Coward et al., 2003; Cowie et al., 2005; Bell et al., 120 2014). Currently, no consensus exists on the direction of extension during Rift Phase 2 in the northern 121 122 North Sea; some studies invoke a continuation of the E-W extension experienced in Rift Phase 1 (e.g. 123 Stewart et al., 1992; Bartholomew et al., 1993; Brun and Tron, 1993) whereas others propose a 124 rotation of the extension direction to either NW-SE, WNW-ESE or NNE-SSW (e.g. Ziegler, 1990, 125 1992; Færseth, 1996; Dore et al., 1997; Færseth et al., 1997; Davies et al., 2001). Once Rift Phase 2 126 ceased, the northern North Sea experienced post-rift thermal subsidence, which was focused in the 127 axis of the Viking Graben (Odinsen et al., 2000).

The magnitudes of extension experienced in Rift Phases 1 and 2 were broadly similar (stretching factors of 1.4-1.5; Roberts et al., 1993; Færseth, 1996; Odinsen et al., 2000), although the way in which extension was distributed varied between phases. Some authors think that, during Rift Phase 1, extension was distributed evenly across the rift (Odinsen et al., 2000) whereas other postulate that extension was greatest in the region that is the present-day Horda Platform (Færseth, 1996; Ter Voorde et al., 2000). In contrast, during Rift Phase 2, extension in the northern North Sea was focused in the Viking Graben (Odinsen et al., 2000; Cowie et al., 2005).

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136 2.2. Geological Setting of the Horda Platform

137 The Horda Platform is a *ca*. 300 km long, N-S-trending structural high located along the eastern138 margin of the Norwegian North Sea, bounded to the west by the North Viking Graben and to the east

139 by the Øygarden Fault Complex (e.g. Færseth, 1996; Bell et al., 2014; Whipp et al., 2014) (Fig. 2). The northern part of the platform is dissected by a fault network that comprises a N-S-striking fault 140 set active during both Rift Phases 1 and 2, and a broadly NW-SE-striking set that was only active 141 during Rift Phase 2 (Fig. 2) (Whipp et al., 2014). The N-S-striking, basement-involved faults, which 142 143 include the Svartav, Tusse, Vette and Øygarden fault systems, dip westward, are up to >60 km long and have an average spacing of ca. 6-15 km (Fig. 2) (Whipp et al., 2014). These faults have up to 5 144 km of throw and define east-tilted half grabens filled with up to 3 km of Permo-Triassic sediments 145 (e.g. Færseth, 1996; Bell et al., 2014; Whipp et al., 2014) (Fig. 2). In contrast, the NW-SE-striking 146 faults are short (2-10 km), have low displacement (30-100 m), are closely-spaced (0.5-5 km), and are 147 stratabound, being restricted to post-Upper Triassic stratigraphy (Fig. 2) (Whipp et al., 2014). 148

149 During the Triassic, the Horda Platform experienced continental conditions, resulting in the deposition of sandstones and mudstones (e.g. Hegre Group; Fig. 3) (Lervik, 2006). In the Early 150 151 Jurassic to early Middle Jurassic, fluvio-deltaic-to-shallow-marine sediments of the Statfjord 152 Formation, and Dunlin and Brent groups were deposited, during a period of tectonic quiescence and post-rift thermal subsidence following Rift Phase 1; Fig. 3) (e.g. Helland-Hansen et al., 1992). The 153 154 diachronous onset of Rift Phase 2 was, in some places, coincident with deposition of the uppermost 155 part of the Brent Group (Fig. 3) (e.g. Helland-Hansen et al., 1992). An overall deepening of the basin, which was associated with increased fault-controlled subsidence in Rift Phase 2, led to the deposition 156 of the fully-marine Viking Group (Fig. 3). On the Horda Platform this consists of three stacked 157 shallow marine clastic wedges, the Krossfjord, Fensfjord and Sognefjord formations, which are 158 separated by major marine flooding events (Fig. 3) (e.g. Dreyer et al., 2005; Holgate et al., 2013). 159 160 Basinwide flooding during the Late Kimmeridgian to Late Berriasian led to the deposition of marine mudstones of the Draupne Formation, which is capped by the Base Cretaceous Unconformity (BCU) 161 (Fig. 3) (e.g. Rattey et al., 1993; Kyrkjebo et al., 2004). The clastic-dominated Jurassic stratigraphy 162 was shallowly buried and thus likely weakly lithified at the onset of Rift Phase 2 extension, thus 163 extensional forced folds and 'drag'-related folds are common in these units (Whipp et al., 2014). The 164 165 BCU is overlain by deep-water clastics and carbonates (Cromer Knoll and Shetland groups), which

are, in turn, overlain by a mud-dominated Cenozoic succession (*Fig. 3*) (e.g. Lepercq and Gaulier,
167 1996).

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169 **3. Dataset and Methodology**

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This study focuses on a ca. 350 km² region around the Tusse Fault System, in an area covered by 2D 171 and 3D time-migrated seismic reflection surveys (Fig. 2). The seismic data are zero-phase and reverse 172 polarity (SEG convention) with seismic sections presented such that troughs (blue reflections) 173 represent a downward increase in acoustic impedance. The 3D survey on which the majority of the 174 fault and horizon interpretation is based has a vertical sampling interval of 2 milliseconds two-way 175 time (ms TWT) and a record length of 3000 ms TWT, with inlines (NE-trending) and crosslines (NW-176 177 trending) spaced 18.75 m and 12.48 m, respectively. Within the Top Triassic to Early Cretaceous 178 interval of interest, the 3D seismic survey has a dominant frequency of ca. 50 Hz, thus, by assuming an average seismic velocity of 2000 m/s TWT we determine a vertical seismic resolution or 'limit of 179 separability' (1/4 wavelength) of ca. 10 m. The shallow burial of the Horda Platform means that the 180 resolution of the 3D data is sufficient for detailed fault and horizon mapping. The 2D seismic lines are 181 182 spaced approximately 1 km, have a record length of 5000-7000 ms TWT, and are used mainly to constrain the thickness of the Permian-Triassic succession and the depth to acoustic basement (Fig. 183 184 2a).

Eight key seismic surfaces, spanning the pre-, syn- and post-rift intervals, were identified based on stratal terminations and marked changes in seismic facies; these surfaces were mapped across the study area (*Fig. 3*) and were tied to eighteen wells using synthetic seismograms that helped constrain their ages (see Whipp et al., 2014). Faults, tiplines and branchlines were mapped on closelyspaced seismic sections, with care taken to accurately constrain fault-horizon cut-offs. Note that the term 'branchline' is used to define any line that joins two fault planes, irrespective of kinematic or age relationships between the faults. Styles of interaction and linkage between the non-colinear fault sets were identified and the geometry and kinematics of each style were examined in turn using evidencefrom TWT structure maps, isochron maps and seismic sections.

To determine how each interaction or linkage style evolved, we followed the approach of 194 Nelson (2006) by defining the geometry of the faults, tiplines and branchlines before systematically 195 196 examining throw patterns. First, to constrain how throw is distributed along-strike of key faults, throw-distance (T-x) measurements were taken on different structural surfaces (e.g. Peacock and 197 Sanderson, 1991). Second, to establish fault growth histories, throw-depth (T-z) plots were 198 199 constructed, where throw across faulted horizons is plotted against the depth to the midpoint between 200 the respective hanging-wall and footwall cut-offs (e.g. Muraoka and Kamata, 1983; Cartwright et al., 201 1995; Hongxing and Anderson, 2007; Baudon and Cartwright 2008a, b and c; Pochat et al., 2009). 202 Third, throw strike projections (cf. Walsh and Watterson, 1991) were constructed for key faults to 203 highlight the 3D distribution of throw at sites of interaction and linkage (see methods of Nelson, 2006; 204 Baudon and Cartwright, 2008a, b and c). Throw values were converted from time (ms TWT) to depth 205 (m) using a velocity model derived from time-depth curves from seven wells located within 6 km of 206 the Tusse Fault. These wells show a simple best-fit second-order polynomial relationship between 207 time and depth with an error margin of 50-120 m at the depth of interest (Fig. 2 and Appendix 1; see 208 methods of Whipp et al., 2014; Bell et al., 2014). Patterns of throw on the faults do not vary 209 significantly between the time and depth domains due to simple velocity structure in the overburden (cf. Baudon and Cartwright, 2008c; Conneally et al., 2014). 210

Unless otherwise stated in the text, the effect of fault-parallel folding on fault throw has been removed, such that total strain across the fault is calculated, whether accommodated by ductile (continuous) or brittle (discontinuous) deformation (e.g. Meyer et al., 2002; Long and Imber, 2010; Whipp et al., 2014). To achieve this, cut-offs were defined using an extrapolated line that follows the regional trend of the horizon prior to folding (e.g. Chapman and Meneilly, 1991; Mansfield and Cartwright, 1996; Wilson et al., 2013).

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4. Overview of the Northern Horda Platform Fault Network

220 The Top Sognefjord TWT-structure map best illustrates the geometry of the Northern Horda Platform 221 fault network because it records deformation associated with both reactivated Permian-Triassic faults 222 and new Middle Jurassic-Early Cretaceous faults (Fig. 4a). The Top Sognefjord horizon lies just 223 below the Rift Phase 2 pre-rift /syn-rift contact. Deformation is dominated by the N-S-striking, Wdipping Tusse Fault, along with a series of shorter, predominantly NW-SE-striking faults that are 224 present in both the hanging-wall and footwall of the Tusse Fault (Fig. 4a). These smaller faults show 225 226 varying degrees and styles of mechanical interaction and/or linkage with the Tusse Fault, including examples that are: i) isolated and non-interacting; ii) abutting; iii) exploiting relay-breaching faults; 227 228 and iv) retarded (Fig. 4a).

In plan view, the Tusse Fault is >33 km long, curvilinear and has an overall N-S strike, 229 230 although some small portions of the fault strike NE-SW or NW-SE (Fig. 4a). On dip-oriented cross-231 sections, the fault is basement-rooted with the upper tip typically located in uppermost Cretaceous or Tertiary strata, being overlain by a west-facing monocline (Fig. 5a). Throw is highest at the Top 232 Basement structural surface (>1400 ms), whereas at the Top Sognefjord structural surface, throw is 233 smaller 120-700 m (90-520 ms TWT) (Fig. 5a). Throw does not vary smoothly along-strike of the 234 235 Tusse Fault; instead, throw variations are 'step-like', and, locally, of large magnitude (up to 500 m) (Fig. 4b). These 'steps' in throw correlate with locations where: i) NW-SE-striking 2nd-stage faults 236 237 mechanically interact or link with the Tusse Fault; and ii) there are significant changes in the 238 magnitude of ductile deformation, calculated by subtracting the true throw from the projected throw, along-strike of the Tusse Fault (Fig. 4; see sections 5 and 6). 239

Permian-Triassic and mid-Upper Jurassic to Lower Cretaceous strata thicken towards the Tusse Fault (*Figs. 5a and 6*) and *T*-*z* profiles, taken at a range of locations along the Tusse Fault (including near sites of linkage with NW-SE-striking faults), show that, for both of these intervals of growth strata, throw increases with depth (*Fig. 7a*). These observations suggest the Tusse Fault was an active surface-breaking fault during Rift Phases 1 and 2 (see also Whipp et al., 2014). In contrast, the intervening Lower to mid-Upper Jurassic interval displays a relatively tabular geometry (*Figs. 5a*). *and* 6) and shows little variation in throw with depth (*Fig.* 7*a*). As such, we interpret that faulting in
this interval is post-sedimentary and the Early to mid-Late Jurassic was a time of fault inactivity and
burial (see also Whipp et al., 2014).

At the Top Sognefjord level, the broadly NW-SE-striking faults are typically 1-8 km long and 249 250 are mainly linear in map view, although some faults in the south of the study area curve to strike N-S in the immediate hanging-wall of the Tusse Fault (Fig. 4a). Fault throw is typically 30-100 m (ca. 20-251 70 ms TWT) (Fig. 5b), but locally up to 300 m (ca. 210 ms TWT). On time-migrated cross-sections, 252 the faults are planar with lower tips commonly located in uppermost Triassic sediments and upper tips 253 located in the Cretaceous or lowermost Tertiary succession (Fig. 5). Thus it is unlikely that: i) 254 255 structures or fabrics in the pre-Permian basement had any direct influence on the growth of the NW-256 SE-striking faults; or ii) lower faults were simply reactivated to form the upper faults.

257 Lower Cretaceous strata thicken towards most but not all of the NW-SE-striking faults, 258 suggesting some faults were active and broke surface during this time (Figs. 5 and 6). T-z profiles 259 constructed for some of the NW-SE-striking faults are broadly symmetrical or slightly skewed 260 towards the upper tip (cf. 'C-type' profiles of Muraoka and Kamata; 1983) (Fig. 7b). The points of 261 maximum throw on T-z profiles, often interpreted to represent the sites of fault nucleation of the fault 262 (Mansfield and Cartwright, 1996; Cartwright et al., 1998; Hongxing and Anderson, 2007), are typically located at the Top Sognefjord (mid-Upper Jurassic) stratigraphic level, with throw 263 decreasing to the upper and lower tips (Fig. 7b). We therefore interpret that the NW-SE-striking faults 264 nucleated in the mid Upper Jurassic succession, were only active during Rift Phase 2, and developed 265 mainly as a population of surface-breaking faults with some faults remaining blind (see also Whipp et 266 al., 2014). 267

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269 5. Fault Interaction and Linkage Styles

Here we examine variations in the fault tipline geometry, kinematics and throw patterns associated
with each of the styles of interaction and linkage that occur between the Tusse Fault and 2nd-stage
NW-SE-striking faults (F1-F16 on Fig 4). We initially examine mechanically and kinematically

isolated 2nd-stage faults (section 5.1), and then examples where 2nd-stage faults abut against the Tusse 273 274 Fault at relatively simple branchlines (section 5.2). We conclude by describing more complex styles, for example where 2nd-stage faults appear to reactivate 1st-stage relay-breaching faults (section 5.3) 275 or show evidence of being mechanically retarded by the Tusse Fault (sections 5.3 and 5.4, 276 277 respectively). For each of these styles, the plan-view structural style is described at the Upper Jurassic Top Sognefjord TWT structural surface. Furthermore, it is assumed that general characteristics (e.g. 278 279 periods faults were active and/or surface-breaking, upper and lower tip locations, stratigraphic level of nucleation) of the Tusse Fault and the 2nd-stage NW-SE-striking faults (F1-F16) respectively, are the 280 281 same as the type examples described in section 4. This section focuses on how interactions between 282 the non-colinear faults influence throw patterns as well as tipline and branchline geometry.

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284 5.1.Mechanically and Kinematically Isolated Faults

Fault F11 is representative of the numerous 2^{nd} -stage NW-SE-striking normal faults that are isolated, that is, they show no evidence of interaction or linkage with other NW-SE-striking faults or the Tusse Fault. Fault F11 has a linear trace in map view, dips to the NE and lies *ca*. 7 km into the hangingwall of the Tusse Fault (*Figs. 4a, 5c, 8a*). The tipline of F11 is quasi-elliptical with a flat upper tipline located in the lowermost Tertiary succession (*Fig. 8c*) and a lower tipline located in the uppermost Triassic interval. Maximum fault height at the centre of the fault ellipse is *ca*. 980 m (*ca*. 900 ms TWT) (*Fig. 8c*).

T-x profiles are smooth and symmetrical, with throw highest at the centre of the fault (Fig. 292 293 8b). On the fault surface, throw contours are quasi-elliptical and show a 'bullseye' pattern, centred on a single throw maximum (ca. 65-70 m or 50 ms TWT) that is located towards the upper centre of the 294 295 fault surface, in Middle to Upper Jurassic strata (Fig. 8c). Throw decreases in all directions away from 296 the throw maximum and towards the tipline, although higher throw gradients are observed towards the upper tip (Fig. 8c). This asymmetry is captured on a T-z plot taken from the centre of the fault that is 297 skewed towards the upper tip (Fig. 7b). There is minor thickening of the uppermost Jurassic and 298 Cretaceous succession in the hangingwall of the fault. 299

300 We interpret that the Rift Phase 2-related NW-SE-striking fault grew as an isolated structure based on the lack of any evidence of mechanical interaction or linkage with any other faults, and the 301 gradual decrease in throw away from the centre of the fault surface (Fig. 8) (cf. Barnett et al., 1987; 302 Walsh and Watterson, 1989; Nicol et al., 1996). The position of maximum throw suggests that the 303 304 fault nucleated in Middle to Upper Jurassic stratigraphy (Fig. 8b). Thickening of strata across the fault indicates that it was active and surface-breaking during the Late Jurassic and Cretaceous, an 305 interpretation supported by the flat upper tipline and high throw gradients near the upper tip, both of 306 which indicate that the upper tip was influenced by the free surface (*Figs. 5c, 7b and 8c*) (cf. Peacock 307 308 and Sanderson, 1991; Nicol et al., 1996; Childs et al, 2003; Baudon and Cartwright, 2008a, b and c).

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310 5.2 Abutting Fault Interactions

Fault F7 is a typical example of 'Y-shaped' intersection where one of the 2nd-stage NW-SE-striking 311 faults (F7), terminates ('abuts') against the Tusse Fault (Figs. 4a, 9a-b). Abutting interactions are the 312 313 most common linkage style along the Tusse Fault, occurring in both its hangingwall (e.g. Fault F4, 314 F14 and F16; Fig 4a) and footwall (e.g. Faults F5, F7 and F12; Fig 4a). Fault F7 lies in the footwall of the Tusse Fault, is NE-dipping and terminates against a NE-SW-striking portion of the Tusse Fault 315 at branchline w-w' (Figs. 4a and 9). The footwall block of F7 is shared with the footwall of the Tusse 316 Fault (Fig. 9b). Branchline w-w' plunges gently towards the NNE and has a height of 1100 m (ca. 970 317 ms TWT), which approximates to the maximum height of Fault F7 (Fig. 9b, d-e). In contrast to the 318 319 isolated, non-interacting faults, the tipline of F7 is semi- rather than fully-elliptical due to the physical 320 link with the Tusse Fault (cf. Figs. 8c and 9e).

At the Top Sognefjord surface, throw on Fault F7 is highest at branchline w-w' (*ca.* 90 m or 70 ms TWT) and decreases down to *ca* 30 m (23 ms TWT) 2.3 km away from the Tusse Fault (*Fig.* 9*c*). Along-strike of the Tusse Fault an abrupt southward increase in throw of *ca.* 90 m (70 ms TWT) is observed across branchline w-w' (*Fig.* 9*d*). The zone of higher throw corresponds with where the footwall of the Tusse Fault also lies in the footwall of Fault F7 (*Fig.* 9*d*). The strike-projected throw distribution on Fault F7 differs from that of isolated, non-interacting faults in two ways. Firstly, a single throw maximum, centred on Middle to Upper Jurassic stratigraphy, is located immediately adjacent to branchline w-w' rather than towards the centre of the fault, and secondly, throw contours are semi- rather than fully-elliptical (*Fig. 9e*). From the throw maximum at the branchline, throw decreases upwards, downwards and away from the branchline with the throw gradient being higher towards the upper tipline (*Fig. 9e*).

Fault F7 is one of the NW-SE-striking set and, as such, was active only during Rift Phase 2, 332 as shown by the fault having a single throw maximum, and interpreted nucleation site, in post-RP1 333 Middle to Upper Jurassic stratigraphy. The location of the throw maximum on Fault F7 suggests the 334 abutting fault nucleated at, or within a few hundred metres of branchline w-w', with the unrestricted 335 lateral tip propagating SE into the footwall of the Tusse Fault and the other lateral tip being pinned by 336 337 the Tusse Fault. Thickening in the hangingwalls of the Tusse Fault and Fault F7, as well as higher 338 throw gradients towards their upper tips, indicates both faults were surface breaking during the Late 339 Jurassic and Early Cretaceous. As F7 abuts against the Tusse Fault, that is, the Tusse Fault restricted 340 the propagation of F7 into its hangingwall, it follows that F7 nucleated either at the same time or after 341 the reactivation of the Tusse Fault. We note that the 'step' in throw on the Tusse Fault across branchline w-w' (ca. 90 m or 70 ms TWT) approximates the throw on Fault F7 near to the branchline 342 343 (Figs 9c and d). We suggest that the higher throw on the Tusse Fault to the south of the branchline is 344 due to the uplifted Tusse Fault footwall having received an 'extra' component of uplift from the uplifted footwall of Fault F7 (i.e. local throw enhancement), whereas the lower throw to the north of 345 the branchline is due to the effect of uplift in the footwall of the Tusse Fault being counteracted by 346 subsidence of the hanging wall block of Fault F7 (i.e. local throw reduction). 347

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349 5.3. Reactivated Relay Fault Interactions

Reactivated relay interactions are rare along the Tusse Fault, with Fault F1 being the only example (*Figs. 4a, 10a and b*). At this intersection the Tusse Fault consists of a *ca.* 1.1 km long, NW-SEstriking, SW-dipping segment that links two major N-S-striking, W-dipping segments; based on this geometric arrangement, we infer that the SW-dipping segment formed to accommodate breaching of a 354 relay zone developed between the two N-S-striking faults during Rift Phase 1 (Figs. 10a and b). This short NW-SE-striking part of the Tusse Fault plane is composite or 'shared' with part of the linear 355 356 Fault F1, with portions of the F1 fault plane extending to the northwest and southeast of the composite plane (Figs. 10a and b). Two southwesterly-plunging branchlines (x-x' and y-y') are developed on 357 358 Fault F1 and bound the composite fault plane (Fig. 10). Of these branchlines, x-x' is located in the northwest where the northern, N-S-striking part of the Tusse Fault intersects Fault F1, and y-y' is 359 located in the southeast where the southern N-S-striking part of the Tusse Fault intersects Fault F1 360 361 (Figs. 10b and d). Portions of Fault F1 to the northwest and southeast of the composite fault plane, 362 respectively, are semi-elliptical and have lower tiplines residing in the uppermost Triassic succession 363 (Fig. 10d). However, the lower tipline of the composite fault plane, as with the Tusse Fault 364 elsewhere, extends down into the basement (Fig. 10d).

365 On a T-x plot at the Top Sognefjord structural surface (Fig. 10c), throw on Fault F1 increases 366 from zero at the lateral tips to 50-80 m (37-55 ms TWT) at the branchlines with the Tusse Fault. On 367 the N-S-striking components of the Tusse Fault, to the north and south of where its plane is shared 368 with Fault F1, throw values reach up to 380 m (260 ms TWT) (Fig. 10c). In contrast, along the NW-369 SE-striking composite plane, composite throw values are higher 430-490 m (280-330 ms TWT) with 370 marked steps in throw coinciding with the locations of branchlines x-x' and y-y' (Fig. 10c), a trend also shown on strike-projected throw plots (Figs. 10d and e). A T-z plot taken in the centre of the 371 composite fault reveals a throw profile typical of the Tusse Fault, with throw decreasing steadily 372 upwards in the Permian-Triassic and in the Upper Jurassic-to-Early Tertiary successions, and showing 373 no significant variation with depth in the intervening Jurassic succession (Fig 7a). The throw 374 distributions on portions of Fault F1 to the northwest and southeast of the composite plane, display 375 semi-elliptical throw contours, with each portion having a throw maximum located adjacent to the 376 composite plane and centred on Middle to Upper Jurassic stratigraphy (Fig. 10d). Throw decreases 377 away from the maxima near the branchlines in the same way as for abutting 2nd-stage faults, with the 378 throw gradients higher towards the upper rather than the lower tipline (cf. Figs. 9e and 10d). 379

We interpret that the composite fault and the N-S-striking segments of the Tusse Fault were both active during Rift Phases 1 and 2 and buried and inactive during the Early to mid-Late Jurassic; this is 382 based on (i) the upward decrease in throw and the presence of growth beds in the Permian-Triassic and Upper Jurassic-Lower Cretaceous successions; and (ii) consistent throws with depth in the 383 intervening Lower and Middle Jurassic successions (Figs. 7a and 10e). Given their similar growth 384 history but their differences in strike, we interpret that, by the end of Rift Phase 1, the NW-SE-385 386 striking composite fault had breached a relay that separated the two N-S-striking segments, thus linking the two. In contrast, the portions of Fault F1 lying to the northwest and southeast of the 387 composite segment were only active during Rift Phase 2, as indicated by the presence of Upper 388 Jurassic-Lower Cretaceous (but not Permian-Triassic) growth strata. Given that throw is highest on 389 390 the composite NW-SE-striking fault segment and that the throw maxima on portions of Fault F1 391 outside of the composite fault lie immediately adjacent to the branchlines with the Tusse Fault (Figs. 392 10c-e), we propose that, during Rift Phase 2, the NW-SE-striking portion of the Tusse Fault, which 393 previously represented a relay-breaching fault, was reactivated. This segment was exploited as a 394 nucleation site for Fault F1 prior to the fault propagating away to the NW and SE. As such, the NW-SE-striking composite fault (the 'reactivated relay-breaching fault') accommodated throw that 395 396 accumulated on both the Tusse Fault and F1 during Rift Phase 2. We argue that the NW-SE-striking 397 'relay-breaching' fault was exploited as nucleation site of 2nd stage faults during Rift Phase 2 due to it 398 being: i) preferentially oriented with respect to the new local, possibly NE-SW extension direction; or 399 ii) a releasing bend formed due to left-lateral oblique slip on the reactivated 1st-stage fault (cf. Morley 400 et al., 2004).

401 The interaction style described above shares some broad similarities with the 'synthetic trailing fault interaction' described by Nixon et al. (2014). For example, both examples are associated with a 402 403 pre-existing (1st-stage) fault plane that displays locally high throw, bound by two branchlines associated with hangingwall and footwall segments (cf. Fig. 10 this study and Figs 15 and 16 in 404 Nixon et al., 2014). However, a series of key geometric and kinematic observations suggest that the 405 style of interaction documented here is in fact different to that documented by Nixon et al. (2014) for 406 'synthetic trailing faults'. The most critical observation is that 'synthetic trailing fault interactions' 407 408 form as two faults in the hangingwall and footwall of a pre-existing fault propagate towards, link with 409 (abut against), and eventually reactivate the pre-existing fault, thus resulting in a zone of locally high throw and the formation of a connecting 'trailing segment' between the abutting faults. In contrast, in the Horda Platform, it is the reactivated relay-breaching fault (or the 'trailing segment' of Nixon et al., 2014) that reactivates first during the 2nd-stage of extension, propagating as a single fault into its footwall and hangingwall. Given this fundamental kinematic difference, and that the dominant influence on this interaction style is the reactivation of the relay-breaching fault inherited from Rift Phase 1 and its continued propagation, we term this a 'reactivated relay fault' interaction style.

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417 5.4. Hybrid and Retarding Fault Interactions

Hybrid fault interactions are those that display evidence of more than one style of interaction or 418 419 linkage. Here we examine a particularly well-imaged example of a hybrid interaction that occurs 420 between the Tusse Fault and Fault F8. In plan view, at the Top Sognefjord structural surface, Fault F8 is linear and tips out ca. 200 m from the Tusse Fault (Figs. 11a and b). In the region between Fault F8 421 and the Tusse Fault a zone of intense ductile deformation is developed (Figs. 4a, 11a and b). In 422 contrast, at the Top Brent level, Fault F8 is hard-linked and abuts against the Tusse Fault at branchline 423 424 z-z'. Fault F8 downthrows to the SW, such that south of branchline z-z' the hangingwall block is shared with the Tusse Fault. 425

426 Away from the zone of ductile deformation (ca. 3 km from the Tusse Fault), the dip-oriented geometry of Fault F8 is typical of that of the other NW-SE-striking faults (Fig. 5c). In cross-section 427 428 the upper tipline resides in the lowermost Tertiary interval and has a sub-horizontal morphology, whereas the lower tipline, which is more poorly imaged, appears to be located in the Permian-Triassic 429 succession (Figs. 5c and 11e). Although the WNW tip of Fault F8 lies outside of the study area, 430 extrapolation of the tipline and strike-projected throw contours suggests the fault is semi-elliptical, a 431 432 function of having a branchline with the Tusse Fault (Fig. 11e). This branchline only extends for 50% 433 of the height of Fault F8, with the upper tip lying between the Top Brent and Top Sognefjord horizons 434 (Fig. 11e). The remaining upper section of Fault F8 does not share a branchline with the Tusse Fault 435 but instead is 'soft-linked' with the larger, pre-existing structure (Fig. 11e).

436 On a Top Sognefiord T-x plot, the projected throw (i.e. sum of brittle and ductile deformation) of Fault F8 gradually increases towards the Tusse Fault (Fig. 11c). In contrast, true throw (solely 437 brittle deformation) gradually increases up to a point ca. 1.3 km from the Tusse Fault before sharply 438 decreasing to zero ca. 200 m from the Tusse Fault (Fig. 11c). A Top Sognefjord T-x plot along-strike 439 440 of the Tusse Fault (Fig. 11d) highlights an abrupt southwards increase, a near doubling, of throw across the branchline with F8, that is, the transition from where the hangingwall of the Tusse Fault is 441 442 associated with the footwall of F8 to the portion where the hangingwall of the Tusse Fault and the 443 hangingwall of F8 are shared (Figs. 4b and 11d). Furthermore, Fig. 11c illustrates striking variations 444 in how throw is partitioned between ductile and brittle components across the intersection. First, the 445 summed amplitude of folding associated with F8 (grey shading) increases from ca. 25 m (ca. 20 ms 446 TWT) approximately 1.3 km from the Tusse Fault to 320 m (ca. 220 ms TWT) at the intersection with 447 the Tusse Fault (Fig. 11c). Second, the T-x plot along the Tusse Fault reveals a significant increase in 448 the summed amplitude of folding from 0 m to ca. 300 m moving southwards across the branchline 449 with F8 (Fig. 4b).

The throw distribution on Fault F8 shows a single maximum that is centred on Mid-to-Upper Jurassic stratigraphy (*Fig. 11e*) and is neither located in the centre of the fault, as with isolated, noninteracting faults, or immediately adjacent to the branchline with the Tusse Fault, as with abutting faults (*cf. Figs 8c and 9e*). Instead, the throw maximum is lobate in shape and, although throw is high near the branchline, the maximum throw is centred *ca.* 1.3 km into the hangingwall of the Tusse Fault (*Fig 11e*). Throw smoothly decreases away from throw maximum in all directions such that throw contours near the branchline are horizontal (*Fig. 11e*).

The location of the true throw maximum leads us to interpret that F8 nucleated *ca.* 1.3 km into the hangingwall of the Tusse Fault in the Mid-to Late Jurassic succession before propagating to the WNW and ESE. It is likely that, as the ESE tip of Fault F8 approached the Tusse Fault, the relative dips of Tusse Fault and Fault F8, in combination with the tipline geometry of Fault F8 meant that the Fault F8 only abutted against, and locally linked with the Tusse Fault along a short branchline and at relatively deep structural levels (i.e. below the Top Sognefjord horizon) (*Fig. 11e*). In contrast, at and above the Top Sognefjord horizon, Fault F8 did not abut against, or develop a branchline with the 464 Tusse Fault (Figs. 11a, b, c and e). Instead, we interpret that the combination of the intense ductile deformation ahead of the ESE tip of Fault F8 at shallow levels, the skew of true throw on Fault F8 465 towards the Tusse Fault and the high throw gradient near the branchline indicate that ESE-directed tip 466 propagation in the shallow portion was mechanically retarded by the Tusse Fault (cf. Manighetti et al., 467 468 2001; Nelson, 2006; Nixon et al., 2014). Despite the lack of hard-linkage between the Tusse Fault and Fault F8 at the Top Sognefjord level and above, when projected throw (i.e. that which sums ductile 469 and brittle deformation) is used to determine a Top Sognefjord T-x profile along the Tusse Fault, the 470 ductile deformation ahead of the ESE tip of Fault F8 ensures that a 'step' increase in throw towards 471 the shared hanging wall block (Fig. 11d). Given that Fault F8 shows evidence of both abutting against, 472 and being mechanically retarded by the Tusse Fault, this example has effectively been fossilised 473 during the transition from one interaction style to another, capturing two discrete stages in the 474 475 evolutionary sequence of fault intersections.

476

477 **6. Discussion**

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479 6.1. Styles of Fault Interaction and Linkage in Multiphase Rifts

In this study, 2nd-stage faults interact with the reactivated Tusse Fault to varying extents; some faults 480 481 are physically and kinematically isolated from the larger structure (ca. 60%), some abut against it (ca. 482 30%) or show evidence of having been retarded by it, whereas others exploit and reactivate earlier 483 relay zones (Figs. 4a, 8-11). The fault interactions observed from a natural multiphase system in this study are supported by findings from physical models as well as other natural systems (e.g. Bonini et 484 al., 1997; Keep and McClay, 1997; Bellahsen et al., 2005; Henza et al., 2010; 2011). First, we note 485 486 that reactivation of 1st-stage faults is broadly synchronous with the nucleation of 2nd-stage faults, a characteristic observed in physical models specifically created to investigate how the growth of 2nd-487 488 stage faults is influenced by the number and maturity of 1st-stage faults and changes in extension direction (<45°) (Henza et al. 2010; 2011). Second, our observation that some of the 2nd-stage faults 489

490 nucleated at reactivated 1st-stage faults, is supported by a range of studies which suggest that preexisting faults can act as nucleation sites for 2nd-stage faults (Figs. 8-12) (e.g. Meyer et al., 2002; 491 Walsh et al., 2002; Henza et al., 2010; 2011). Third, we observe 2nd-stage faults that abut against, or 492 show evidence of having been retarded by the reactivated 1st-stage fault (e.g. F6-F8 and F12-F14; 493 494 Fig. 4a) and some that curve into parallelism with the main structure when in close proximity (e.g. F15; Fig. 4a). These observations suggest the Tusse Fault has acted as mechanical barrier and 495 perturbed the regional stress field, thus restricting and influencing the propagation of later faults (cf. 496 Færseth et al., 1997; Færseth and Ravnås, 1998; Bellahsen et al., 2005; Nelson, 2006; Henza et al., 497 2011; Nixon et al., 2014). 498

499 Although there are similarities between the fault interactions in this study and those described 500 from physical modelling studies and other natural fault systems, there are also some differences. In 501 particular, in models D and E in Henza et al. (2011), where 1st-stage faults are well-developed before 502 the extension direction changes for the second rift phase, a high number of 2nd-stage faults cross-cut 1st-stage faults. However, we see no evidence of 2nd-stage faults cutting across and offsetting the 503 Tusse Fault (e.g. Fig 4a), which may be due to the restricted sample size of fault interactions in this 504 505 study relative to that in the models of Henza et al. (2011). Another potential cause for the absence of 506 cross-cutting interactions may be that, in our natural example, fault interactions were catalogued on 507 the Top Sognefjord surface, an essentially 'intra-rift' surface (i.e. deposited between Rift Phase 1 and 2). In contrast, in the models of Henza et al. (2011), syn-rift layers were not added during either phase 508 of extension, and hence fault interactions were catalogued on a true pre-rift surface. As such, the 509 reactivated Tusse Fault had to propagate upwards through overlying intra-rift sediments, potentially 510 reducing the opportunity for 2nd-stage faults to cross-cut it. 511

Based on map view geometry alone (*Figs. 10a and b*), the reactivated relay fault interaction could be mistaken for a simple cross-cutting fault relationship. However, kinematic analysis reveals that, during Rift Phase 2, the NW-SE-striking relay-breaching fault developed in Rift Phase 1 was reactivated and exploited as a nucleation site for NW-SE-striking Fault F1, which propagated to the NW and SE, away from the 'composite' fault plane (*Fig. 10*). We demonstrate that the 1st- and 2^{nd} - stage faults at the reactivated relay fault interaction were then active synchronously during Rift Phase2, such that the relay fault became a 'zone of shared throw'.

Given that the Tusse Fault was fully reactivated during Rift Phase 2, we do not document 519 520 2nd-stage faults cross-cutting and offsetting *inactive* 1st-stage structures (sensu Needham et al., 521 1996). Such interactions will be more common in multiphase rifts where the extension directions between the two rift phases are highly oblique (>45 $^{\circ}$), such that reactivation of 1st-stage faults is not 522 favoured (e.g. Nelson, 2006). We also speculate that, in general, a higher frequency of fault bends and 523 relay-breaching faults along 1st-stage faults, in combination with a favourable extension direction in 524 the second phase of extension, may result in more potential nucleation sites for 2nd-stage faults (cf. 525 526 Lezzar et al., 2002; Bellahsen et al, 2005; 2006).

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528 6.2. The Geometry and Throw Patterns of Faults in Multiphase Rifts

529 We have documented the styles of interaction that occur between non-colinear faults in a multiphase 530 fault network. In particular, we have demonstrated that a wide range of interaction styles and patterns 531 of throw develop in association with non-colinear faults, with the key relationships synthesised in Figure 12. The tipline geometries of 2nd-stage, non-colinear faults that interact with 1st-stage faults 532 may vary depending on the interaction style and whether the faults are blind or surface-breaking (Fig. 533 12). Flat upper tiplines are typically associated with surface-breaking faults and convex-upward upper 534 tiplines are associated with blind faults (Fig. 12) (e.g. Nicol et al., 1996; Childs et al. 2003; Baudon 535 and Cartwright, 2008). In the simplest scenario in which faults are blind, where a 2nd-stage fault 536 537 nucleates and propagates in isolation from a 1st-stage fault, both faults will tend towards having 538 elliptical tiplines (Fig. 12a). In the case that both faults are free from lithological restriction, both faults should theoretically tend towards an aspect ratio of 2 (e.g. Nicol et al., 1996). In contrast, where 539 a 2nd-stage fault is laterally restricted by a pre-existing fault (Figs. 12b and c), the geometry of the 540 2nd-stage fault tipline can be highly variable, although typically more asymmetric in form and, in the 541 542 case that the faults are blind, should have an aspect ratio <2. In cases where a 2nd-stage fault nucleates at a pre-existing fault, the tipline geometry of the 2nd-stage fault will be semi-elliptical, due
to the physical link with the pre-existing fault (*Figs. 12d and e*).

If we consider the characteristics of a 2D T-x profile taken along-strike of a reactivated 1st-545 stage fault (e.g. Fig. 4b), it can be seen that throw does not vary smoothly across the fault surface; 546 547 rather, it is characterised by 'steps' in throw where the Tusse Fault is influenced by physical or kinematic interactions with 2nd-stage faults. Thus, T-x profiles along reactivated structures that are 548 549 hard or soft-linked to newly-formed faults will differ from those from faults developed in response to 550 the growth of a single fault segment (cf. Watterson, 1986; Barnett et al., 1987; Nicol et al., 1996; Needham et al., 1996) or the linkage of smaller precursor segments (cf. Anders and Schlische, 1994; 551 552 McLeod et al., 2000; Young et al., 2001). We also note how the magnitude of ductile deformation along-strike of a reactivated 1st-stage fault also displays 'steps' in the profile, correlating with 553 554 locations where 2^{nd} -stage faults soft or hard-link with the 1st-stage fault (*Fig. 4b*). Furthermore, the 555 way in which throw is partitioned between interacting faults and across branchlines is dependent on 556 the interaction style (Figs. 8-12). For example, where a 2nd-stage fault is isolated from, and not laterally restricted by a 1st-stage fault, the throw maximum on the 2nd-stage fault is located towards 557 558 the fault centre, with throw decreasing smoothly and linearly towards the tips (Figs. 8 and 12a). 559 Where a 2nd-stage fault nucleates at and propagates away from a pre-existing structure, either into its 560 hanging-wall or footwall, the mutual hanging-wall or footwall block experiences an additional component of subsidence or uplift, respectively (Figs. 9, 12d and e). On the 1st-stage fault, this is 561 expressed by a sharp increase in the throw towards the shared hangingwall or footwall block (Figs. 562 12d and e) (sensu Nelson, 2006; Nixon et al., 2014). The 2nd-stage fault will be bound by a steep 563 branchline, along which the maximum throw occurs such that throw contours are semi-elliptical (Figs. 564 12d and e). In cases where the 2nd-stage fault grows towards and is retarded by the 1st-stage fault, the 565 throw maximum on the 2nd-stage fault will be located towards the laterally-restricted portion of the 566 567 fault, with high throw gradients developing near the restricted tip (Fig. 12b) (sensu Manighetti et al., 2001; Nixon et al. 2014). 568

The individual styles of fault interaction and linkage captured in this study, and those ofNixon et al. (2014), show discrete stages of interaction development. However, observations from

571 physical modelling studies (e.g. Henza et al., 2010; 2011) indicate that fault intersection development 572 is a dynamic process, involving a gradual transition from one style to another. For example, 2nd-stage faults which nucleate away from 1st-stage faults and grow initially as isolated 2nd-stage faults (e.g. 573 Figs. 8 and 12a), may propagate towards and be retarded by the 1st-stage fault resulting in higher 574 575 throw gradients towards the retarded tip (e.g. Figs. 11 and 12b) (sensu Manighetti et al., 2001; Nixon et al. 2014) prior to hard-linking with, and abutting against, the 1st-stage fault (e.g. Figs. 9 and 12c) 576 (see also Nelson et al., 2006). This study suggests that abutting faults are unlikely to evolve to cross-577 578 cut the earlier fault; in this study, cross-cutting is restricted to a breached fault segment boundary along-strike of the Tusse Fault (cf. Nelson, 2006). In contrast, in the case of 2nd-stage faults that 579 nucleate at and propagate away from 1st-stage faults (Figs. 12d and e), the branchline will be formed 580 581 relatively early, and the style of interaction at the abutting tip would not change once the full 582 branchline is developed.

583

584 6.3. Implications for the Evolution of Multiphase Rift Fault Networks

585 In the Northern Horda Platform both N-S- and NW-SE-striking faults were active synchronously during Rift Phase 2, even at complex intersections. It is thus likely that at least one, or possibly both, 586 of these fault sets experienced oblique slip. Our simplest and preferred explanation is that, at least 587 locally within the study area, the extension direction during Rift Phase 2 was reoriented to be NE-SW, 588 sub-perpendicular to the strike of the majority of the NW-SE-striking faults; if true, this implies that 589 the N-S-striking Tusse Fault may have been reactivated obliquely with a left-lateral sense of slip. The 590 strike-parallel component of any oblique slip is likely to have been fairly low as no strong evidence of 591 592 flower structures or laterally offset markers is noted in the 3D volume. In contrast, the observation of growth strata and vertical fault throw for the vast majority of faults in the array is evidence for a 593 594 significant amount of fault activity with a dip-slip component.

595 We have developed a conceptual model highlighting the key characteristics of multiphase rift 596 fault networks, drawing on observations from the northern Horda Platform, other natural rift fault 597 networks, and physical models (*Fig. 13*). By comparing figures 1 and 13, the significant differences 598 between non-colinear fault networks developed during single-phase and multiphase extension become 599 clear. For example, non-colinear faults are more pervasive in a multiphase network than would typically occur in a single-phase rift, and multiphase rift fault networks are more complex and 600 601 connected, being influenced by a larger number of fault interactions and wider range of interaction or 602 linkage styles (cf. Figs 1 and 13). However, we can also see how individual non-colinear fault relationships developed in single- and multiphase rift networks can appear geometrically similar (cf. 603 604 Figs 1 and 13). For example, abutting faults developed during a second phase of extension are, when 605 viewed individually, indistinguishable from splay faults and release faults developed during a single 606 rift phase; all strike oblique to the main fault and tend to have a nucleation site and throw maximum 607 near the main fault (e.g. Baudon et al., 2008a; Nixon et al. 2014) (cf. Figs 1 and 13). We suggest that, 608 determining the origin of non-colinear faults requires knowledge of the relative timing of fault 609 activity. In natural fault networks, this knowledge is best gained by studying data-rich areas where 610 borehole-constrained 3D seismic data allows constraints to be placed on the age of growth strata 611 adjacent to the faults. If the non-colinear fault in question is an abutting fault developed during a 612 second rift phase rather than a splay fault developed during a single rift phase, activity on this fault 613 should correspond to the second rift phase and hence post-date the initial activity on the main fault. In 614 addition to determining the relative timing of fault activity, the location of the interaction with regards 615 to the tips and segment centres of 1st-stage faults and/or the relative abundance of the interaction type within the network can also help distinguish between different causal mechanisms. For example: i) 616 617 relatively small splay faults will likely cluster at the tips of the main faults; ii) release faults will tend to be located at sites of throw maxima and minima along-strike of the main faults; and iii) abutting 618 619 faults developed due to a second phase of extension will be part of a pervasive non-colinear array (e.g. Reeve et al., 2015). 620

Overall, the approach to the analysis of fault interactions applied in this study and the key findings are applicable to any rift setting characterised by dip-slip non-colinear faults. We present new insights into the geometries, throw patterns and kinematics of faults associated with different fault interaction styles in a multiphase rift, providing a basis for future studies examining the how singlephase and multiphase rift fault networks evolve. 626

627 **7. Conclusions**

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Analysis of a 3D borehole-constrained seismic dataset from the northern Horda Platform reveals a network of non-colinear faults that developed due to multiple phases of extension. The fault network consists of a high-throw N-S-striking fault which was active during Rift Phases 1 and 2 and a series of shorter, NW-SE-striking faults which were only active during Rift Phase 2. We show that:

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In the northern Horda Platform fault network, a multiphase network that experienced a different local extension direction in each rift phase, non-colinear faults are more pervasive than in networks developed during a single phase of extension. Furthermore, the northern Horda Platform network is more complex and connected than a typical single-phase network, being influenced by a higher frequency of interactions between 1st and 2nd-stage faults.

A wide range of styles of fault interaction can occur between 1st- and 2nd-stage faults in multiphase rift fault networks that have experienced a different local extension direction in each phase. At the Top Sognefjord structural level in the northern Horda Platform network we document 2nd-stage faults that are isolated from the 1st-stage fault (*ca.* 60%), abut against it (*ca.* 30%), or those that exploit breached relay zones along the Tusse Fault or show evidence of the propagation of the fault having been retarded by it (*ca.* 10% combined).

645 3. In multiphase rift fault networks, the typical geometries of fault tiplines and the distribution of throw on fault surfaces are highly-variable, being controlled to a large extent by the style of 646 interaction between 1st-stage and 2nd-stage faults. In particular we note how: i) the tiplines of 647 many 2nd-stage faults are semi-elliptical due to the development of branchlines at sites of 648 intersection with 1st-stage faults; ii) the distribution of throw on reactivated 1st-stage faults 649 will be modified in a predictable manner if they are intersected or influenced by 2nd-stage 650 faults; iii) pre-existing faults can act as sites of nucleation for 2nd-stage faults as well as 651 mechanical barriers that restrict or alter the propagation pathways of 2nd-stage faults; and iv) 652

fault segment boundaries, and fault kinks or corrugations along first-stage faults, can act aspreferential nucleation sites for 2nd-stage faults.

- 4. The observation of a 2nd-stage fault that shows evidence of concurrently abutting against, and being mechanically retarded by a 1st-stage fault indicates fault interactions are not static and transition from one style to another. For example, 2nd-stage faults that nucleate away from, and propagate towards a 1st-stage fault may initially be isolated, before being mechanically
- retarded by, and eventually abutting and hard-linking with the 1st-stage fault.

660

- 661 Overall, we highlight how it is important to integrate borehole-constrained 3D seismic data with a
- 662 systematic approach to the analysis of fault geometry and throw distributions in a fault network. This
- approach will allow interpreters greater confidence in mapping fault intersections in seismic datasets
- that lack clear imaging of faults and their geometric relationships, as well as in determining whether
- 665 non-colinear fault networks developed during single– or multiple phases of rifting.

666

667 8. Acknowledgements

We thank Craig Magee, Casey Nixon, Atle Rotevatn and Haakon Fossen for constructive discussions 668 during this project, and Alissa Henza and an anonymous reviewer for constructive reviews. We thank 669 Nancy Cottington for help with figure editing. Schlumberger are thanked for providing an academic 670 license for Petrel. This contribution forms part of the MultiRift Project funded by the Research 671 Council of Norway (Project number 215591/E30) and Statoil to the University of Bergen and partners 672 673 Imperial College, University of Manchester and University of Oslo. We also thank Statoil and NPD for providing access to seismic and well data. Statoil are thanked for permission to publish the results 674 675 of this study. Conclusions from this paper do not necessarily reflect the views of Statoil or partners.

676

677 9. Figure Captions

Figure 1: Block model showing simple large-scale co-linear faults developed during a single-phase of
rifting as well as the typical locations of any non-colinear faults that may develop (RP1 = rift phase 1,
arrows indicate extension direction)

Figure 2: (a) Principal tectonic structures of the northern North Sea, after Færseth (1996) and Bell et al., (2014). The Horda Platform (HP), the focus of this study is outlined in red and the location of the regional interpretation shown in Figure 1c is shown by a bold black line. (b) Map showing the noncolinear fault sets in the northern Horda Platform fault array, colour-coded to highlight which faults were active in Rift Phase 1 (Permian-Triassic) and Rift Phase 2 (Late Jurassic – Cretaceous) (after
Whipp et al., (2014)). (c) Regional interpretation of the structure of the northern North Sea after
Færseth (1996).

688 Figure 3: Stratigraphic framework with a synthetic seismogram for well 31/6-6, showing the ages 689 and representative lithologies of the key Groups and Formations in the Horda Platform along with key seismic stratigraphic markers (after Faerseth (1996) and Whipp et al., (2014) and modified from Bell 690 691 et al., (2014)). Tectonic events based on the timing of activity of the Tusse Fault and nearby structures 692 (after Whipp et al., 2014). A representative section of seismic reflection data from a 2D survey is 693 shown to illustrate the typical seismic stratigraphy in the area. Colour coding of the seismic stratigraphic marker horizons and megasequences is continued throughout. P=Period and E=Epoch. 694 TD = Growth and deflation of the central North Sea thermal dome. *The timing of the initiation and 695 696 cessation of Syn-Rift Phase 2 is diachronous across the Horda Platform (see Bell et al., 2014 for more 697 details).

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Figure 4: (a) TWT structure map of Top Sognefjord Fm with key faults labelled. (b) *T-x* plot and distribution of ductile deformation (summed fold amplitudes) along-strike of the Tusse Fault system.
Note the 'steps' in throw at sites of interaction with NW-SE-striking faults and how throw and degree of ductile deformation correlate along-strike of the Tusse Fault.

Figure 5: Series of seismic profiles and geoseismic sections illustrating key structural characteristics of the Tusse Fault system and the NW-SE-striking faults (locations of sections shown in Fig. 4a). (a) Seismic section and geoseismic section oriented orthogonal to the Tusse Fault system in the south of the study area. (b) Seismic section and geoseismic section oriented orthogonal to the Tusse Fault system in the north of the study area. (c) Seismic section and geoseismic section oriented orthogonal to a series of NW-SE-striking faults in the study area.

Figure 6: TWT-thickness maps for a series of stratigraphic intervals: (a) Permian-Triassic (Rift Phase
1), (b) Lower Jurassic to mid Upper Jurassic (intra-rift cessation) and (c) mid Upper Jurassic and
Cretaceous (Rift Phase 2). Note how thickening across the Tusse Fault is observed only in (a) and (c).

Figure 7: (a) T-z plots taken at various locations along the N-S-striking Tusse Fault and b) T-z plots taken from various NW-SE-striking faults. Note that the locations of the plots in a) and b) are marked by stars on Fig 4a. These plots provide evidence that the Tusse Fault was active during Rift Phases 1 and 2 whereas NW-SE-striking faults only initiated during Rift Phase 2 (see text for more details).

716 Figure 8: Quantitative analysis of the isolated, non-interacting NW-SE-striking Fault F11. (a) Oblique view at the Top Sognefjord structural surface, image taken looking SE (V.E x5). (b) T-x717 profile along Fault F11 at the Top Triassic and Top Sognefjord structural surfaces, with the highest 718 719 throw located towards the centre of Fault F11. (c) Strike-projected throw distribution in ms TWT of 720 Fault F11 with no vertical exaggeration. A single throw maximum is located towards the upper centre 721 of the fault and throw contours are broadly elliptical. Projected fault cut-offs of key seismic 722 stratigraphic horizons are shown with solid lines marking hanging-wall cut-offs and dashed lines 723 footwall cut-offs (continued in Figures 9-11).

Figure 9: Quantitative analysis of the 'abutting' interaction between the Tusse Fault and Fault F7. (a) plan and (b) oblique views of the interaction at the Top Sognefjord structural surface (V.E x5). (c) *T-x* profile along Fault F7 at the Top Sognefjord horizon. (d) N-S *T-x* profile along the Tusse Fault near branchline w-w' with Fault F7 at the Top Sognefjord horizon. Note the step-like increase in throw immediately south of branchline w-w' in the region of the mutual footwall. Strike-projected throw distribution in ms TWT on abutting Fault F7 with no vertical exaggeration. The tipline and throw contours are semi-elliptical with a single maximum located near the branchline.

Figure 10: Quantitative analysis of the reactivated relay interaction between the Tusse Fault and Fault F1. (a) Plan and (b) oblique views of the intersection at the Top Sognefjord horizon (V.E x5). (c) T-x profile along both faults at the Top Sognefjord structural surface. Note the higher throw between

branchlines x-x' and y-y' in the portion of the fault plane that is shared with the Tusse Fault. (d) Strike-projected throw distribution in ms TWT of Fault F1 with no vertical exaggeration. The highest throw is located between branchlines x-x' and y-y'. On the portions of Fault F1 either side of branchlines x-x' and y-y', fault throw are highest nearer the branchline and throw contours are semielliptical. (e) Strike-projected throw distribution in ms TWT of the Tusse Fault with no vertical exaggeration. Throw is highest between branchlines x-x' and y-y'.

740 Figure 11: Quantitative analysis of the interaction between the Tusse Fault and Fault F8, a 'hybrid' 741 interaction that shows evidence of both abutment and retardation. (a) plan and (b) oblique views of the 742 intersection at the Top Sognefjord horizon (V.E x5). (c) T-x profile showing true throw along Fault F8 at the Top Brent horizon and both the true throw and projected throw along Fault F8 at the Top 743 Sognefjord horizon; the true throw at the Top Sognefjord horizon is skewed towards the Tusse Fault 744 745 suggesting the Tusse Fault has retarded the propagation of F8. (d) N-S T-x profile showing projected 746 throw at the Top Sognefjord structural surface along the Tusse Fault near 'apparent' branchline z-z' 747 with F8. Note the step-like increase in throw immediately south of the 'apparent' branchline z-z' in the region of the mutual hangingwall block. Strike-projected throw distribution in ms TWT of Fault 748 749 F8 with no vertical exaggeration. Note: i) the short branchline that marks the abutment of F8 against 750 the Tusse Fault; and ii) the area above the short branchline marked by ductile deformation is 751 interpreted to represent 'retardation' of Fault F8 by the Tusse Fault.

Figure 12: Conceptual models showing how different fault interaction styles influence fault tipline geometry and throw patterns in multiphase rifts. Colour-coding of throw projections: purple represents lowest throw; blue, yellow and orange represent increasing respective throw amounts and red represents the highest throw.

Figure 13: Conceptual model fault network in a multiphase rift showing typical locations of, and styles of interaction between non-colinear faults. The model assumes that the extension direction in Rift Phases 1 and 2 are different and that faults developed in Rift Phase 1 are reactivated during Rift Phase 2. (RP1 = rift phase 1, resulting in the formation of faults outlined in red; RP2 =Rift Phase 2, resulting in faults outlined in blue).

Appendix 1 – Time-depth plots for seven key wells in close proximity to the Tusse Fault and a best fit trendline which was used for depth conversion.

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Figure 1



Figure 2



Figure 3



Figure 4



Figure 5a



Figure 5b



Figure 5c







Figure 6



Figure 7



Figure 8



Figure 9



Figure 10



Figure 11

Interaction Style								
	(a) Isolated, non- interacting	(b) Retarded (2nd stage fault tips out near, and retarded by, 1st stage fault)	(c) Abutting (hangingwall) (2nd stage fault nucleates away from, but abuts against, 1st stage fault)	(d) Abutting (hangingwall) (2nd stage fault nucleates at 1st stage fault)	(e) Abutting (footwall) (2nd stage fault nucleates at 1st stage fault)	(f) Simple cross-cutting (1st stage fault not reactivated)		
Plan View	A 1st stage fault A 1st stage fault A 1st stage fault A A A A A A A A A A A A A A A A A A A	A B'Folding	A Mutual hangingwall	A A'	Mutual A B' footwall A B' A'	A • • B' • B		
Schematic T-x plot	$T = \begin{bmatrix} T \\ A \\ B \end{bmatrix} = \begin{bmatrix} A \\ B' \end{bmatrix} = \begin{bmatrix} A \\ B' \end{bmatrix}$	Skew on <i>B–B'</i> T A B X A' B'	Small step in throw T A X $A'B$ X' B'	Large step in throw T A A' B' A' B'	Large step in throw $T = \begin{bmatrix} A & A' \\ B & X & B' \end{bmatrix}$			
Throw strike- projection of 2nd stage fault (if blind)	• Aspect ratio ca. 2	Folding B B B B B B B C B C C C C C C C C C C C C C	 Short branchline Aspect ratio <2 	 B Semi-elliptical fault Long branchline Aspect ratio <<2 	• Semi-elliptical fault • Long branchline • Aspect ratio <<2	в 👘 в'		
Throw strike- projection of 1st stage fault (if blind)	 A A' Aspect ratio ca. 2 	A Control Ar	 A A' Higher throw and throw gradient in mutual hanging-wall (only affecting area adjacent to branchline) 	 A A' Higher throw and throw gradient in mutual hangingwall 	•Higher throw and throw gradient in mutual footwall	A CONA'		
Throw strike- projection of 2nd stage fault (if surface- breaking)	B B B'	Folding ahead of retarded tip	В	B	₿	B B'		
Throw strike- projection of 1st stage fault (if surface- breaking)	A A'	A COD A'	A A'	A CONA'	A CONA'			

Figure 12



Figure 13