Backstress from dislocation interactions quantified

by nanoindentation load-drop experiments

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10 Key Points

- A nanoindentation load drop method was used to measure backstress in a material with a high
 dislocation density at sub-micron length scales.
- The backstresses measured in three geologic materials agree with theoretical predictions of Taylor
 hardening.
- Backstresses result from long-range dislocation interactions, an athermal process that can occur
 over a range of deformation conditions.

17 Abstract

18 Recent work has identified the importance of strain hardening and backstresses among dislocations 19 in the deformation of geologic materials at both high and low temperatures, but very few experimental 20 measurements of such backstresses exist. Using a nanoindentation load drop method and a self-similar 21 Berkovich tip, we measure backstresses in single crystals of olivine, quartz, and plagioclase feldspar at a 22 range of indentation depths from 100–1750 nm, corresponding to densities of geometrically necessary 23 dislocations (GND) of order 10¹⁴–10¹⁵ m⁻². Our results reveal a power-law relationship between backstress

and GND density, with an exponent ranging from 0.44 to 0.55 for each material, in close agreement with
the theoretical prediction (0.5) from Taylor hardening. This work provides experimental evidence of Taylor
hardening in geologic materials and supports the assertion that backstress must be considered in both highand low-temperature deformation.

28 Plain Language Summary

29 As a material is plastically deformed at room temperature, it often becomes stronger. In minerals, 30 this strengthening is typically caused by the accumulation of linear defects within the material. These 31 defects repel each other and push back with a strength predicted to be proportional to the square root of the 32 defect density, but this relationship has not typically been observed for geologic materials. We developed 33 a method to measure the strength of this pushback at very small scales for which the density of these defects 34 in the crystal is high. Our results for three common geologic materials agree with predictions from theory 35 and demonstrate that these defects must be considered when modeling deformation of rocks in Earth's 36 interior.

37 1. Introduction

The transient rheology of the upper mantle is inferred to control the dynamics of many geologic phenomena, including post-seismic deformation (e.g., Freed et al., 2012; Wang et al., 2012; Hu et al., 2016; Qiu et al., 2018). Several studies have presented models to describe the transient rheological behavior following large earthquakes (e.g., Masuti et al., 2016; Moore et al., 2017; Muto et al., 2019), but the physical mechanism that gives rise to this complex time-dependent rheology is not well-constrained. For example, Masuti et al. (2016) used a strain hardening coefficient to modify a stress element in their Burgers model, but noted that the functional form of the constitutive law was completely unknown.

Experiments on geologic materials have measured transient creep (e.g., Post, 1977; Durham et al.,
1979; Gangi, 1983; Duval et al., 1983; Smith & Carpenter, 1987; Hanson & Spetzler, 1994; Chopra, 1997;
Caswell et al., 2015; Hansen et al., 2020), but quantifying this rheological behavior using conventional
creep experiments is challenging because it may be caused by the interplay of multiple deformation

49 processes acting simultaneously. Examination of the microstructures in recent stress-reduction experiments on olivine single crystals by Hansen et al. (2020) suggested that time-dependent recoverable strain (i.e., 50 51 anelasticity) at high temperatures arises due to a combination of high-temperature deformation mechanisms, 52 dislocation glide, and long-range elastic interactions among dislocations. These authors presented a 53 microphysical model that arises naturally from the behavior of lattice dislocations and captures both 54 transient and steady-state rheology over a wide range of conditions. Specifically, Hansen et al. (2020) 55 suggested that geometrically necessary dislocations (GNDs), which are dislocations of the same sign 56 needed to accommodate lattice curvature or gradients in local strain, are an important defect type controlling 57 transient deformation at high temperature. These dislocations differ from statistically stored dislocations 58 (SSDs) in that the lattice distortion of GNDs is not cancelled by dislocations of the opposite sign. 59 Consequently, GNDs can exhibit long-range interactions over length scales of 1–100 microns (Wallis et 60 al., 2017; 2020a; 2020b). These interactions ultimately lead to a backstress which opposes further 61 deformation by dislocation glide.

62 Recent work also identified backstresses at much higher total GND densities in olivine deformed 63 by low-temperature plasticity (Hansen et al., 2019; Wallis et al., 2020a). In addition to identifying a length 64 scale effect in the yield stress (effectively the Hall-Petch effect), Hansen et al. (2019) also demonstrated the 65 presence of strain hardening and the Bauschinger effect, a well-known phenomenon in metallurgical 66 literature wherein the yield stress of a material is reduced after the deformation direction is reversed (i.e., 67 the yield stress in extension is reduced after initially yielding in compression, and vice versa). This 68 phenomenon is commonly attributed to the effect of an internal backstress from GND interactions that acts 69 in the opposite direction to the initial deformation (Dieter, 1986 Chapters 4.14, 6.16, and references therein). 70 Using high-angular resolution electron backscatter diffraction (HR-EBSD), Wallis et al. (2020a) measured 71 the GND density of a deformed single crystal of olivine from Hansen et al. (2019) and demonstrated that 72 the Bauschinger effect was indeed related to long-range elastic interactions among GNDs created during 73 strain hardening. Wallis et al. (2020a) also identified similar microstructures beneath indents in olivine 74 from Kumamoto et al. (2017), suggesting that the same physical mechanism (i.e., hardening due to

75 dislocation interactions) occurs during nanoindentation. However, due to the significantly larger stresses in 76 nanoindentation, the dislocation density was much higher than in samples deformed in Hansen et al. (2019). 77 In the present paper, we quantify the relationship between GND density and backstress in three 78 common geologic materials (olivine, quartz, and plagioclase feldspar) using a novel nanoindentation 79 method. Because nanoindentation localizes deformation in a small volume of material, the sample is 80 essentially self-confined, and extremely high stresses can be applied without inducing fracture. 81 Additionally, nanoindentation using a Berkovich (3-sided pyramid) tip offers a significant advantage in that 82 it can be used to probe different microstructures (i.e., GND densities) at the same strain (~8%) due to its 83 self-similar geometry. We utilize this technique to demonstrate excellent quantitative agreement between 84 our experiments and theoretical predictions of Taylor hardening (Taylor, 1934), which suggests that 85 backstress should scale as the square root of GND density.

86 **2. Methods**

87 We have developed a method to measure the backstress from GNDs created during nanoindentation 88 experiments. This method is similar to a stress-reduction test, a common technique used on macroscopic 89 samples to measure anelasticity (e.g., Takeuchi & Argon, 1976; Blum & Weckert, 1987; Caswell et al., 90 2015; Hansen et al., 2020), with one key difference. Because the indentation stress is controlled by the 91 mechanical response of the sample and not its physical dimensions, this type of experiment is more 92 accurately described as a "load-drop" test. Only the applied load is prescribed in the experiment, and neither 93 stress nor strain rate are controlled. Syed Asif and Pethica (1997) presented the only previous study that 94 utilized load drops to measure changes in indentation creep behavior, but they did not quantify the 95 backstress systematically in their study of tungsten and gallium arsenide single crystals.

Each of our experiments consisted of four parts: 1) an initial loading phase, 2) a short hold at constant load to measure indentation creep behavior, 3) a rapid load drop, and 4) another longer hold at a reduced constant load to measure the mechanical response of the sample. Segment 1 can be completed using any number of standard nanoindentation protocols, such as constant loading rate or constant nominal

strain rate, as the main function of this step is to set the initial microstructure (i.e., GND density) beneath the indenter tip. The GND density, ρ_{GND} , below the indenter tip for a pyramidal geometry is a function of the tip shape, the indentation depth, *h*, and the Burgers vector, *b*, of the material (e.g. Pharr et al., 2010) and is given by

$$\rho_{\rm GND} = \frac{3 \tan^2 \theta}{2bh},\tag{Eq. 1}$$

105 where θ is the angle formed between the surface and the indenter (19.7° for a Berkovich tip). Thus, deeper 106 indents formed by larger applied loads will result in a lower GND density.

107 In the results presented here, all experiments were performed in a load-controlled nanoindentation 108 apparatus with $\dot{P}/P = 0.2$ for segment 1, where *P* is the applied load and \dot{P} is its time derivative. The 109 indentation hardness, *H*, is the mean contact stress, defined as

$$H = \frac{P}{A},$$
 (Eq. 2)

where A is the projected contact area between the tip and the sample. The value of A is calibrated as a function of depth using a standard of known Young's modulus (usually fused silica) and given by the relationship

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$$A = C_1 h_c^2 + C_2 h_c + C_3 h_c^{\frac{1}{2}} + \dots + C_7 h_c^{\frac{1}{32}},$$
 (Eq. 3)

where C_1 , C_2 , C_3 ... C_7 are constants, and h_c is the contact depth (i.e., the true depth at which the tip and sample are in contact, with elastic deflection of the surface of the sample removed). The contact depth is given by

$$h_c = h - \epsilon \frac{P}{S}, \tag{Eq. 4}$$

where *h* is the measured indentation depth, ϵ is a constant associated with the geometry of the indenter (0.75 for Berkovich), and *S* is the contact stiffness. With known contact stiffness and contact area, the reduced elastic modulus, E_r , of the tip-sample contact can be determined using

$$E_r = \frac{\sqrt{\pi S}}{2\sqrt{A}}.$$
 (Eq. 5)

123 Utilizing known values of the elastic constants of the diamond tip and an assumed Poisson's ratio of the124 sample, we determined the sample's elastic modulus using

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$$\frac{1}{E_r} = \frac{1 - \nu_{\rm s}^2}{E_{\rm s}} + \frac{1 - \nu_{\rm i}^2}{E_{\rm i}}, \qquad (Eq. 6)$$

where *E* is the Young's modulus, *v* is Poisson's ratio, and the subscripts s and i refer to the sample and
indenter tip, respectively. Our experiments were performed using the continuous stiffness measurement
(CSM) method with a dynamic frequency of 110 Hz and a target dynamic displacement of 2 nm, which
allowed us to measure the contact stiffness (and therefore the contact depth, hardness, and elastic modulus
of the sample) continuously as a function of time (Li & Bhushan, 2002; Oliver & Pharr, 2004).

Segment 2 of our load-drop method is optional, but in these experiments we performed a 60-s hold to measure the creep behavior. Due to possible thermal drift of the instrument, this portion of the test and all subsequent measurements were obtained using the CSM method. In this portion of the test, and all following steps, we used the measured elastic modulus from Segment 1 and rearrange Eq. 5 to solve for contact area as

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$$A = \frac{\pi S^2}{4E_r^2}.$$
(Eq. 7)

This approach is preferable to relying on the depth measurement to acquire contact area using Eqs. 3 and 4 because the depth measurement is highly sensitive to temperature fluctuations. Thus, our subsequent measurements of hardness from Eq. 2 are calculated from the measured contact stiffness, the previously derived elastic modulus, and the current applied load.

Segments 3 and 4 are the additions of our method and encompass a load drop and subsequent hold. In Segment 3 of our experiments, we reduced the load linearly over 1 s by a prescribed amount, ranging from 1% to 99% of the maximum applied load. A small amount of dynamic overshoot occurred for large reductions in applied load, but these variations did not significantly influence any of our results. After the load drop, the new applied load was held constant for the duration of Segment 4. In the results presented here, we held the load at the reduced value for 3600 s before completely unloading the sample.

In summary, this method determines the hardness and elastic modulus as a function of indentation depth and the creep behavior during a short hold at high stress. In addition, by testing a range of reductions in load for a given peak load, we can determine the magnitude of the backstress in a material, as demonstrated below. Repeating a series of experiments at different peak loads and thus different maximum depths, corresponding to different GND densities, also allows us to explore the influence of microstructure on backstress.

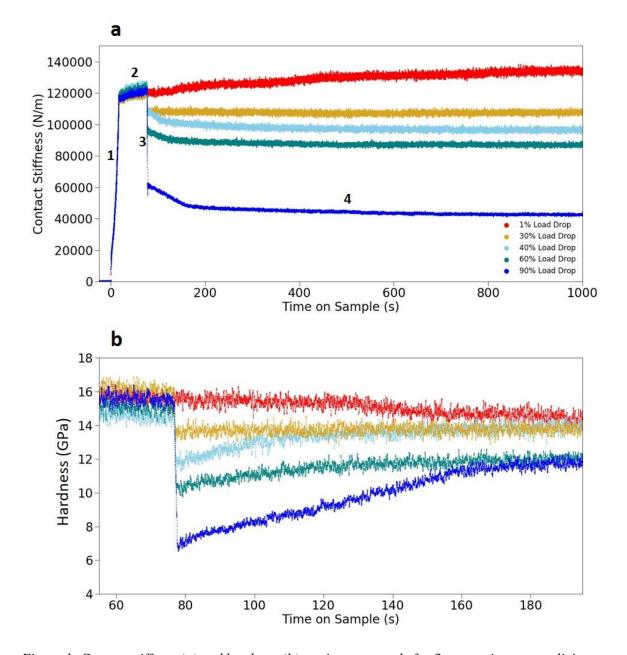
153 **3. Results**

We performed a total of 155 load-drop experiments on single crystals of San Carlos olivine, synthetic quartz, and natural plagioclase feldspar (labradorite). For each experiment, we recorded the applied load, indentation depth, and contact stiffness at a rate of 100 Hz, from which we derived the elastic modulus, hardness, and creep behavior at each point in the test.

158 For each material, Segments 1 and 2 were reproducible for a given maximum load (e.g., Figure 1a), 159 and the values obtained for the elastic modulus and scale-dependent hardness were consistent with previous 160 results on the same materials (Kumamoto et al., 2017; Thom et al., 2018). To discuss the results from 161 Segments 3 and 4, we examine a representative set of experiments on olivine presented in Figure 1. In each 162 experiment, the maximum applied load was 5 mN; thus the indentation depth (120 nm) and GND density $(29.6 \times 10^{14} \text{ m}^{-2})$ (Table 1) immediately prior to the load drops were approximately equivalent (Eq. 1). The 163 164 only difference among these experiments was the magnitude of the load drop during Segment 3 of each 165 test. Contact stiffness versus time for each experiment before and after the load drop are presented in Figure 166 1a, with each test segment labeled. An initial steep increase in contact stiffness occurs in Segment 1, and a 167 small increase over time occurs in Segment 2. The abrupt reduction in contact stiffness occurs as the applied 168 stress is reduced in Segment 3 and is associated with some elastic recovery of the material.

In all experiments, one of three behaviors was observed after the load drop: 1) the contact stiffness
increased with time (forward creep), 2) the contact stiffness decreased with time (backwards/reverse creep),
or 3) there was no change in contact stiffness (negligible/no creep). In the examples in Figure 1a, one test

demonstrates continued forward creep (1% load drop), three tests demonstrate backwards creep in the early
portions of the hold (40%, 60%, and 90% load drops), and one test exhibits no change in the stiffness (30%
load drop). The transition from backwards creep to no creep is taken to be the point at which the applied
stress is approximately equal to the backstress from dislocation interactions.



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Figure 1: Contact stiffness (a) and hardness (b) vs. time on sample for five experiments on olivine at a peak
load of 5 mN. The steep rise in stiffness at the beginning of the test in (a) represents Segment 1 of the
experiment and the slow increase in stiffness over time in Segment 2 is due to creep (both labeled). Upon

unloading by different percentages of the same peak load (Segment 3), both contact stiffness (a) and
hardness (b) decrease due to some elastic recovery of the samples. During Segment 4, contact stiffness
either continues to increase over time due to forward creep (e.g., for a 1% load drop), decreases due to
reverse creep (e.g., for a 90% load drop), or remains constant over time (i.e., no creep as shown by the
30% load drop). The corresponding response in hardness is shown in (b), where the hardness decreases
(forward creep), increases (backwards creep), or remains the same (no creep).

186 We use the measured contact stiffness, the elastic modulus calculated from Segment 1, and Eqs. 2 187 and 7 to determine the hardness in the experiments in Figure 1a. These data are presented in Figure 1b for 188 a portion of the experiments shortly before and after the load drop. For a load drop of 1%, hardness 189 decreases slightly over time due to forward creep, consistent with previous nanoindentation creep 190 experiments (e.g., Thom & Goldsby, 2019). Tests in which the backstress exceeds the applied stress result 191 in an increase in the measured hardness over time after the load drop (40%, 60%, and 90% load drops), and 192 the experiment with no creep (30% load drop) shows constant hardness with time. The hardness for the 193 experiment with the 30% load drop in Figure 1b is 13.8 GPa, which we infer to be the backstress associated 194 with the GND density in these experiments.

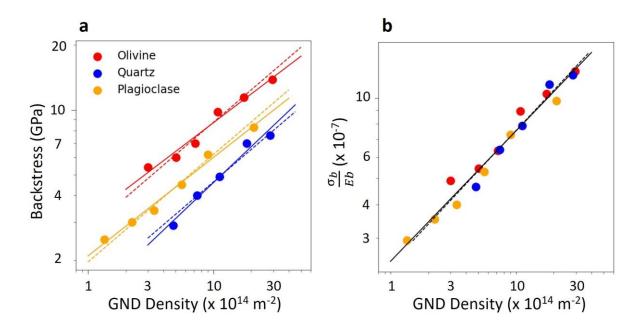
195 By varying the maximum applied load and thereby reaching different initial indentation depths, we 196 are able to probe the backstress of each material over GND densities varying by approximately one order 197 of magnitude. A summary of the data used to construct Figure 2a is presented in Table 1. Each data point 198 is derived from a series of experiments like those in Figure 1. For each material, a best-fit line is marked 199 by the solid line of the respective color, with power-law exponents of 0.44, 0.55, and 0.46 for olivine, 200 quartz, and feldspar, respectively. The average exponent across the materials is 0.49. In addition, a dashed 201 line of the same color is forced through the data with a slope of 0.5, representing the theoretical fit from the 202 hardening component of the Taylor equation (Taylor, 1934), which is given by

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 $\sigma_b = \alpha G b \sqrt{\rho}_{\rm GND},\tag{Eq. 8}$

where σ_b is the backstress associated with hardening from GNDs, α is a constant, *G* is the shear modulus, and *b* is the Burgers vector. For each material, the data are adequately fit by the dashed lines, but because

the data only span one order of magnitude in GND density, it is difficult to evaluate the robustness of the fits, similar to previous assessments of the Hall-Petch effect (Dunstan & Bushby, 2014; Li et al., 2016). Normalizing the backstress by the Young's modulus derived from the indentation tests and the Burgers vector of the material reveals remarkable data collapse, as shown in Figure 2b. A solid black line represents the best fit to all normalized data with a slope of 0.49, and a dashed black line is presented with a slope of 0.5 for comparison to the theoretical prediction. This agreement suggests that the value of α in the Taylor equation is the same for all materials tested here (approximately 3.7).



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214 Figure 2: Results of all experiments on olivine, quartz, and plagioclase feldspar demonstrating that 215 backstress (a) and normalized backstress (b) are a function of the initial microstructure, or GND density. 216 Each data point in (a) and (b) is found using a series of experiments like those depicted in Figure 1. The 217 solid lines in (a) are best fits to each individual set of data (slope of 0.44 for olivine, 0.55 for quartz, and 218 0.46 for plagioclase feldspar, with an average value of 0.49), and each dotted line is the forced fit of a line 219 with a slope of 0.5, which is predicted from the Taylor hardening equation. In (b), the backstress is 220 normalized by the Young's modulus derived from Segment 1 of the indentation test (200 GPa for olivine, 221 120 GPa for quartz, and 105 GPa for plagioclase feldspar) and the appropriate Burgers vector (0.55, 0.52,

- and 0.81 nm, respectively). The solid black line is a best fit to all the normalized data with a slope of 0.49,
- and the dashed black line is a forced fit to the data with a slope of 0.5.
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Table 1: Target maximum applied load, average maximum indentation depth, backstress, and GND density
 for all data presented in Figure 2a.

Sample	Maximum Load (mN)	Indentation Depth (nm)	Backstress (GPa)	GND Density (x 10^{14} m ⁻²)
Olivine	5	120	13.8	29.6
	15	200	11.4	17.6
	25	320	9.8	10.8
	65	480	7.0	7.2
	100	690	6.0	5.0
	300	1150	5.4	3.0
Quartz	5	130	7.6	28.4
	10	200	7.0	18.5
	25	330	4.9	11.2
	50	500	4.0	7.4
	100	780	2.9	4.8
Plag	2	110	8.3	21.1
	10	260	6.2	9.1
	25	420	4.5	5.6
	70	700	3.4	3.4
	150	1050	3.0	2.2
	400	1750	2.5	1.4

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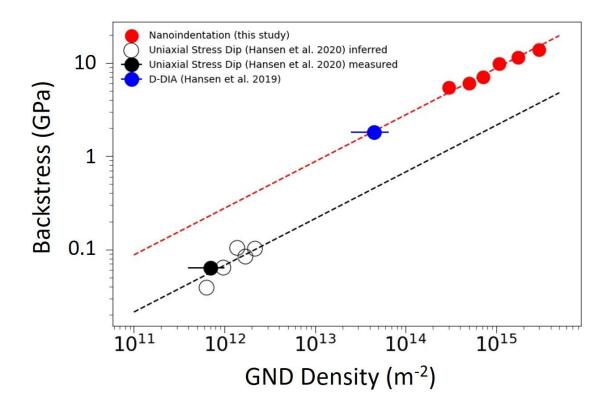
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232 **4. Discussion**

We compare our olivine data to other measurements of backstress and GND density in single 233 234 crystals of olivine in Figure 3. Data from this study are shown in red at high GND density, data from a 235 room-temperature deformation-DIA (D-DIA) experiment of Hansen et al. (2019) are shown in blue at 236 intermediate GND density, and data from the high-temperature (1573 K) experiments of Hansen et al. 237 (2020) are shown in black at the lowest GND density. The solid black data point represents a sample where 238 the GND density was directly measured, and the open black circles represent GND densities inferred by 239 using the dislocation density piezometer of Bai & Kohlstedt (1991) and assuming all dislocations are GNDs. 240 We note that the inferred GND density of the sample with a direct measurement is within the error bars, 241 suggesting our assumption of all dislocations being GNDs is reasonable. The dashed red line presented in 242 Figure 3 is the same as in Figure 2a (it is only fit to the nanoindentation data), while the black dashed line 243 is a forced fit of the Taylor equation to the high-temperature data. The room-temperature experiment of 244 Hansen et al. (2019) falls on the same line as the indentation data presented here, while the high-temperature 245 data appear to be systematically offset to lower backstresses (i.e., with a smaller value of α).

246 While we do not observe a universal relationship between high- and low-temperature experiments, 247 these results are consistent with the microphysical model presented by Hansen et al. (2020), in which 248 transient and steady-state rheology are captured by a combination of dislocation glide, elastic interactions 249 among GNDs, and recovery mechanisms. The value of α may be temperature-dependent or a function of 250 the differential stress, but more experiments at intermediate conditions are needed to resolve this subtlety. 251 However, this study provides direct evidence of Taylor hardening in geologic materials at room 252 temperature, and future work will explicitly link the Taylor equation (i.e., the evolution of backstress with 253 GND density) to transient rheology over a wide range of conditions. The presence of Taylor hardening in 254 all minerals tested here and the remarkable data collapse presented in Fig. 2b suggests that transient 255 deformation of other geologic materials may be parameterized in a similar manner to that in Hansen et al. 256 (2019; 2020), and that microstructural evolution models must incorporate the Taylor relationship.



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258 Figure 3: Compilation of backstress and GND density data from studies of single crystals of San Carlos 259 olivine which measure both values. Results from room temperature indentation tests (this study) are shown 260 in red, the room temperature D-DIA experiment from Hansen et al. (2019) analyzed by Wallis et al. (2020a) 261 is shown in blue, and the high temperature stress dip experiments from Hansen et al. (2020) are shown in 262 black (the direct GND measurement is represented by the solid circle, while inferred GND values are 263 represented by the open circles). Horizontal error bars reflect uncertainty in the average GND density 264 determined via HR-EBSD. The dashed red and black lines are fits of the Taylor hardening equation for the 265 nanoindentation and high-temperature stress dips, respectively.

266 5. Conclusions

We have performed nanoindentation load-drop experiments on single crystals of olivine, quartz,
and plagioclase feldspar to measure the backstress created by long-range elastic interactions among
dislocations. To vary the GND density, we applied a range of maximum loads using a self-similar

270 Berkovich indenter tip to achieve a range of indentation depths. Our results demonstrate that the 271 backstress in all three materials scales approximately with the square root of GND density, as predicted 272 from the Taylor hardening equation. The value of α in the Taylor equation is similar among all materials 273 tested here at room temperature but varies from that inferred in high-temperature experiments, suggesting 274 that recovery or stress may play a role in modifying the backstress. However, these results are consistent 275 with the microphysical model presented by Hansen et al. (2020), which suggests that backstress and its 276 evolution are important physical processes that must be considered in studies of deforming geologic 277 materials, including during transient deformation at both high- and low-temperature.

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