

UNSEEN trends: Detecting decadal changes in 100-year precipitation extremes

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This is a preprint of an article published in Npj Climate and Atmospheric Science. The final
authenticated version is available online at: <https://doi.org/10.1038/s41612-020-00149-4>.

Sample sizes of observed climate extremes are typically too small to reliably constrain non-stationary behaviour. To facilitate detection of non-stationarities in 100-year precipitation values over a short period of 35 years (1981-2015), we apply the UNprecedented Simulated Extreme ENsemble (UNSEEN) approach, by pooling ensemble members and lead times from the ECMWF seasonal prediction system SEAS5. We generate a 3500-year UNSEEN dataset of autumn 3-day extreme precipitation events across Western Norway and Svalbard. The UNSEEN ensemble shows that an event of 1.5 times the magnitude of the most severe flood episode recorded in Western Norway can arise with a return period of ~2000 years. Applying the novel UNSEEN-trends approach, we demonstrate that for Svalbard the 100-year event in 1981 could be expected to occur with a return period of around 40 years in 2015. These new insights have important implications for current design-level practices and for understanding the underlying causes of non-stationarities.

Handling the non-stationarity of climate extremes is an active area of research¹⁻³ that is confounded by the brevity and sparsity of observational records⁴⁻⁶. Non-stationary precipitation analyses typically focus on detecting multidecadal to centennial changes in annual precipitation maxima⁷⁻⁹.

33 However, annual maximum precipitation events do not necessarily cause high impacts and hence, a
34 potentially more pressing research challenge is the detection of changes in larger extremes^{10,11}, such
35 as the 1-in-100-year event. Furthermore, the impacts of abrupt warming in recent decades may not
36 yet be detectable in short precipitation records. Therefore, robust detection of short-term (decadal,
37 rather than centennial) trends in climate extremes may provide valuable and actionable information.

38 An emerging alternative to traditional observation-based extreme value analysis is to pool ensemble
39 members from numerical weather prediction systems^{12–22} – the UNprecedented Simulated Extreme
40 ENsemble (UNSEEN) approach^{20,22}. This technique creates numerous alternative pathways of reality,
41 thus increasing the event sample size for statistical analysis. The larger sample size offers a broader
42 view of present-day hazard and, therefore, has potential to improve design-levels. For example, the
43 2013/14 winter flooding in the UK had no observational precedent, but could have been anticipated
44 with the UNSEEN approach²². Similarly, estimates of storm surge levels of the River Rhine^{12,13}, global
45 ocean wind and wave extremes^{15,16,18}, and losses from extreme windstorms¹⁹ have all been improved
46 with the UNSEEN approach. UNSEEN can also enhance food security through better drought
47 exposure estimates^{14,21} and can assist policy makers and contingency planners by quantifying and
48 explaining the most severe events possible in the current climate, such as heatwaves in China²⁰.
49 However, validating the UNSEEN method is a well-recognised difficulty in existing studies, and
50 UNSEEN has not yet been used to facilitate detection of non-stationarity in climate extremes over
51 short periods of several decades.

52 Here, we provide a framework to systematically evaluate the robustness of the UNSEEN approach
53 and we present a novel UNSEEN-trends approach, where we aim to provide confident short-term
54 trend estimates by using the larger event sample to better constrain changes in climate extremes.
55 We do this in a storyline context²³, where we take observed flood episodes as a starting point for our
56 analysis. We select the west coast of Norway and the Svalbard Archipelago as study regions; two
57 contrasting areas in terms of precipitation extremes. Western Norway faces the highest extremes
58 within Europe²⁴ and has a dense station network^{25,26}, whereas Svalbard is a semi-desert with only a
59 few observation stations²⁷. Both regions have faced severe damages from recent extreme events,
60 such as the September 2005²⁸ and October 2014²⁹ floods over Western Norway and the slush-
61 avalanche inducing extreme precipitation event over the Svalbard Archipelago in 2012³⁰. The
62 extreme events were driven by atmospheric rivers^{27–29} (ARs), which cause heavy precipitation over a
63 prolonged period. As AR-related floods predominantly occur in autumn and frequently strengthen
64 over a period of several days^{28,29}, we select autumn (September to November) spatial averaged
65 (Supplementary fig. 1) three-day extreme precipitation (SON-3DP) as target events.

66 Previous UNSEEN studies have used the Hadley Centre global climate model, HadGEM3-GC2^{14,20–22}
67 and the European Centre for Medium-ranged Weather Forecasts (ECMWF) ensemble prediction
68 systems^{15–18} and earlier version of the seasonal prediction system^{12,13,19}. Here, we are the first to use
69 the latest ECMWF seasonal prediction system SEAS5³¹ for its high-resolution, large ensemble, long
70 homogeneous hindcast period (1981-2015) and open access. The ECMWF atmospheric model has
71 shown skill in simulating atmospheric rivers for Northern Europe³², giving confidence in the realism
72 of these extreme events in SEAS5, hence is a good candidate for the UNSEEN method. We use the 25
73 ensemble members across lead times of 2-5 months, resulting in a sample of 100 members (called
74 the UNSEEN ensemble) and evaluate the independence and stability of the pooled sample for SON-
75 3DP events across Western Norway and Svalbard. We then use the UNSEEN-trends approach to
76 identify unprecedented extreme precipitation events and to detect trends in 100-year precipitation
77 events over the last 35 years. These findings will help understanding the robustness of current
78 design levels and may improve our understanding of physical processes driving climate extremes and
79 their non-stationarity.

80 **Ensemble member independence and model stability**

81 The independence of ensemble members is an important requirement for the UNSEEN approach, as
82 dependent members would artificially inflate the sample size, without adding new information.
83 Previous studies have assessed the independence of ensemble members for lead times 9-10
84 days^{15,16,18}, but to the best of our knowledge, no independence test has yet been performed in
85 UNSEEN studies of seasonal prediction systems.

86 For the regions studied here, the ensemble members from lead times beyond one month are not
87 dependent on atmospheric initial conditions, because the synoptic patterns related to ARs are
88 known not to be predictable beyond two weeks^{32,33}. However, predictability on a seasonal timescale
89 may be found through slowly varying components of the ocean-atmosphere system. Therefore,
90 while the ensemble members might represent unique weather events because of the independency
91 to the atmospheric initial conditions, the weather events could have a conditional bias induced by
92 favourable conditions in the slowly varying components of the ocean-atmosphere system.

93 To test the seasonal dependence of SON-3DP, we first select the seasonal maximum event for each
94 forecast then concatenating these events to create a 35-year timeseries (Fig. 1a,b,c). To robustly
95 assess the independence between each of the ensemble members, we calculate the Spearman rank
96 correlation coefficient (ρ) for every distinct pair of ensemble members (Fig. 1d), resulting in 300 ρ
97 values for each lead time. The value of ρ ranges from ca. -0.6 to 0.6, and the median correlation is
98 close to zero for all lead times for both Western Norway and Svalbard (Fig. 1e,f). The range in ρ

99 values is expected due to the large number of correlation tests, and none of the lead times fall
100 outside the range that would be expected for uncorrelated data for the West Coast of Norway (Fig.
101 1e). For Svalbard, slightly higher ρ values are found, with the median correlation still within the
102 expected range, but the interquartile range just exceeding the upper boundary of the confidence
103 intervals for the first two lead times (Fig. 1f). The small correlations found for Svalbard might be
104 driven by the trend that we detect for this region (UNSEEN-trends section), and thus, the UNSEEN
105 ensemble members represent unique events that follow the slowly evolving climate signal, as
106 desired.

107 A second potential issue for generating the UNSEEN ensemble could be a drift in the simulated
108 climatology^{34,35}, which may alter precipitation extremes over longer lead times. Therefore, model
109 stability is a requirement for pooling lead times. Model stability is assessed by comparing the
110 distribution of predicted SON-3DP events across different lead times. For both regions, the
111 probability density functions of the pooled SON-3DP events for the considered lead times are
112 remarkably similar (Fig. 2a,b). Moreover, the empirical extreme value distributions of the individual
113 lead times fall within the uncertainty range of the distribution of all lead times pooled together and
114 thus, the model can be considered stable over lead times (Fig. 2c,d).

115 **Fidelity of UNSEEN extremes for Western Norway**

116 Confidence in simulated 'unprecedented extremes' in large ensembles is complicated by the inability
117 to validate extremes, given the limited sample sizes of observations. Here, we evaluate the UNSEEN
118 ensemble with 1) rank histograms, commonly applied in ensemble forecast verification³⁶ and 2) by
119 bootstrapping the ensemble into datasets of 35 years and assessing whether observations fall within
120 the range of the bootstrapped distribution, following previous UNSEEN studies^{20,22} (see Methods).
121 We perform this analysis for the SEAS5 UNSEEN SON-3DP ensemble over Western Norway, because
122 the dense station network of the country^{25,26} facilitates model evaluation (unlike in Svalbard). For a
123 comprehensive global model validation of SEAS5, see Johnson *et al.*³¹.

124 The rank histograms clearly indicate an under-forecasting bias of the absolute SON-3DP values
125 within the UNSEEN ensemble (Supplementary Fig. 2). This is confirmed by the bootstrapping test,
126 that shows that the observed mean and standard deviation fall outside the 95% confidence intervals
127 of the UNSEEN ensemble (Supplementary Fig. 3). The UNSEEN SON-3DP anomalies and standardized
128 anomalies do show rank uniformity, and thus are suggested to be reliable (Supplementary Fig. 2).
129 Such under-forecasting biases precipitation extremes are not uncommon in global Earth System
130 Models³⁷, especially for a mountainous region like Western Norway.

131 As the UNSEEN SON-3DP deviations from the mean show good agreement to the observed values
132 (Supplementary Fig. 2), the ratio between the mean observed extremes and the mean simulated
133 extremes (1.74) is applied as a constant bias correction to generate the bias corrected UNSEEN
134 ensemble (henceforth referred to as UNSEEN-BC). Note that we found little sensitivity to using the
135 median (1.72), 5-year (1.69) or 20-year (1.70) values in the bias correction procedure and, hence
136 chose a constant value to avoid extrapolations beyond the quantile range. The bootstrapping test
137 shows that the statistics derived from the observed precipitation fall within the 95% intervals of
138 UNSEEN-BC for timeseries of 35 years (Supplementary Fig. 4), i.e. the precipitation of the single
139 realization of reality is one of the plausible realizations of UNSEEN-BC and, therefore, UNSEEN-BC is
140 indistinguishable from the observed values.

141 We then fit the GEV distribution to the observations, the UNSEEN and the UNSEEN-BC ensemble (see
142 Methods and Fig. 3). Interestingly, the fitted distributions show that the UNSEEN-BC ensemble
143 diverges from the observed values for return periods above ~35 years. To evaluate the discrepancy,
144 we test the sensitivity of the results to the choice of extreme value distribution (Supplementary Fig.
145 5). Whilst the Gumbel distribution (shape parameter $\xi = 0$) shows a relatively good fit to the
146 observations and a similar distribution to the UNSEEN ensemble, the fit is not as good as using a full
147 GEV with fitted shape parameter, as suggested by Supplementary Fig. 5 and confirmed by the
148 likelihood ratio test (p -value = 0.03 for the observed and p -value = $1.54 \cdot 10^{-7}$ for the UNSEEN
149 ensemble). In addition, results are also very sensitive to outliers, as can be seen when the observed
150 extreme value distribution is fitted on a sample where the largest value is increased by 10%
151 (Supplementary Fig. 5). This confirms the challenge associated with estimating the magnitude of
152 events of long return periods (greater than 20 years) from an observed time series of only 35 years,
153 with more trust in estimations resulting from the larger UNSEEN sample.

154 We find that the 2005 and 2014 observed extreme events (two largest events in Fig. 3) are similar in
155 magnitude and represent events with return periods of 21 years (CI of 19-24 years) when compared
156 with the extreme value distribution of UNSEEN-BC. Based on the observed values, the return period
157 estimate of 60 years for the events would be very uncertain, with the lower confidence interval
158 never reaching the event magnitude (CI of 18 - ∞ years). Moreover, the highest UNSEEN-BC event is
159 1.5 times higher than the highest observed event, with an estimated return period of ~2000 years (CI
160 of 1150-4800 years). The estimated return period of this event based on the observations is
161 completely dominated by the uncertainties (~5000, 600 - ∞ years) and can only be statistically
162 modelled, while for the UNSEEN estimate, it is a physically simulated 'empirical' event within 3500
163 years of data. The observed flood episode caused flooding and landslides with severe damage²⁸ and

164 UNSEEN-BC indicates what kind of events beyond the observed record are plausible in the present
165 climate.

166 **UNSEEN-trends in 100-year precipitation over last 35 years**

167 Climate models can be used to detect changes³⁸⁻⁴¹ or to attribute extreme events to human causes⁴²,
168 but are less suited to detecting trends over the recent past such as the last 35 years. By design,
169 climate model simulations are initialized once at the beginning of a centennial run. Contrastingly,
170 here we use seasonal forecasts that are initialized every month, and thus are more constrained by
171 real-world climate variability than climate model simulations. Consequently, seasonal forecasts
172 sample a smaller range of climate conditions but are closer to reality than climate model
173 simulations. This means that their use is consistent with analysing trends over the recent past
174 described by the available forecast period (for SEAS5, currently 35 years). Furthermore, the model
175 setup and version are the same for the entire hindcast simulation, ensuring that, with respect to the
176 models and initialization, SEAS5 is a homogeneous dataset and thus suitable for climate analysis and
177 detection of UNSEEN-trends.

178 With a 36 km resolution and 25 members, the ECMWF SEAS5 reforecast set used here is based on a
179 modelling system of high resolution and associated with a large ensemble compared to current high-
180 resolution global climate models⁴³. SEAS5 greenhouse gas radiative forcing captures the long-term
181 trends in emissions³¹, and we show that the global mean temperature trend in SEAS5 follows ERA5⁴⁴
182 (Supplementary Fig.6). Whilst regionally, we find a cold bias over the Norwegian study domain, the
183 trend is consistent with ERA5 for both Western Norway and Svalbard (Supplementary Fig. 6),
184 confirming the capacity of SEAS5 to detect recent trends.

185 To illustrate the added value of UNSEEN-trends, we extend the GEV distribution to include a time
186 covariate and fit this distribution to the observed and UNSEEN SON-3DP (see Methods). Using the
187 observations, we find an increase in 100-year SON-3DP of 4% over 1981-2015 in Western Norway,
188 but associated with large uncertainties ranging from -27% to 34% (Fig. 4 a,b). The UNSEEN-trend
189 estimate of 2% is more constrained due the larger sample size, with confidence intervals ranging
190 from -3% to 7%. A negative trend is thus statistically possible, indicating that the trend over Western
191 Norway is not significant. For Svalbard, we find a significant positive UNSEEN-trend of 8%, with
192 uncertainty bounds ranging between 4-12%.

193 In addition to the trend in 100-year SON-3DP events, we illustrate the change in all return values by
194 plotting the GEV distribution with the covariates 1981 and 2015 (Fig. 4 c,d). The likelihood ratio test
195 shows that the GEV distribution including a time covariate improves the model fit for Svalbard (p-

196 value = $2.7e-07$). We find that the frequency of the event that used to be a 100-year event in 1981
197 has an expected return period of 41 years in 2015 (Fig. 4 c,d). For Western Norway, the GEV
198 distribution including a time covariate does not improve the model fit for either the observed (p-
199 value = 0.58) or the UNSEEN-ensemble (p-value = 0.65), and thus, the stationary GEV distribution, as
200 presented in Fig. 3, is most appropriate.

201 **Discussion and Conclusion**

202 In this study, we test the robustness of the UNSEEN approach and we use the large sample to
203 constrain short-term UNSEEN-trends in high-impact precipitation events for Western Norway and
204 Svalbard. We show that with SEAS5, the effective sample size of autumn 3-day precipitation (SON-
205 3DP) events in Western Norway and Svalbard can be increased by a factor of 100 compared to
206 observations, because ensemble members are independent and the model is stable over lead times.
207 Validating UNSEEN events and trends is a complex task, but our approach reproduces observed
208 extremes well after bias correction for Western Norway, a region with extensive records²⁶.

209 The insights presented in this study are specific to Western Norway and Svalbard SON-3DP but the
210 independence, model stability and model fidelity tests applied to the UNSEEN approach could be
211 transferred to other regions, temporal resolutions and spatial extent of the events, seasons and
212 climate variables. Global validation of the UNSEEN ensemble will highlight in which regions the
213 approach may enhance the robustness of design level estimation, with a potentially high value in
214 supporting data scarce regions⁴⁵. Furthermore, the large sample size may allow estimation of
215 extremes using empirical approaches that avoid assumptions about underlying distributions and
216 their non-stationarity, thereby offering the possibility of improved design estimates¹⁰ and empirical
217 attribution of physical mechanisms. A wide range of scientific disciplines might benefit from the
218 UNSEEN method by forcing seasonal prediction systems into impact models to assess
219 unprecedented impacts and improve understanding of the physical mechanisms leading to these
220 events.

221 The results from the two study areas highlight the value of both the UNSEEN and the UNSEEN-trends
222 approach. For the well-monitored Norwegian domain, we are able to bias correct the UNSEEN
223 ensemble (UNSEEN-BC) and therefore we can better estimate the return period of the 2005 and
224 2014 flood episodes. We find that the flood episodes are not rare exceptions; rather they might be
225 expected to occur once in 20 years under a stationary climate. Furthermore, the UNSEEN-BC
226 ensemble shows that an event of 1.5 times the magnitude of the highest observed event could arise.
227 The September 2005 and October 2014 flood episodes were identified as high-impact events in
228 previous end-user engagement sessions within the Translating Weather Extremes into the Future

229 (TWEX) project, and thus, the results found from the UNSEEN-BC ensemble are of high relevance to
230 decision makers and end-users. This application of the UNSEEN approach is similar to previous
231 research on the 2013/14 winter floods in the UK²² and for the 1990 windstorm losses over Germany
232 and the UK¹⁹. A difference to the previous studies is that we run the analysis on a three-day
233 resolution, whereas monthly averages have been used so far. The observed record and the UNSEEN-
234 trend show that there is no significant trend over Western Norway between 1981-2015, and
235 therefore justify using the stationary GEV distribution.

236 Contrastingly, for Svalbard, the UNSEEN-trends approach shows that what was a 100-year event in
237 1981 is to be expected to return once in 41 years in 2015. The trend in extreme precipitation over
238 Svalbard could not be detected from observation-based studies due to the sparse observation
239 network in this area²⁷. Despite very few precipitation extremes being recorded in the Svalbard
240 Archipelago, it is assumed that their frequency and magnitude are increasing in a warming
241 climate^{27,30,46}, which is confirmed by our UNSEEN-trends analysis. Those precipitation extremes are
242 connected to the inflow of relatively warm air and, thus, can cause severe landslides and so-called
243 rain-on-ice events³⁰. Both could have significant impacts on people living in the Arctic and on the
244 local ecosystem.

245 In due course, the drivers of changes in climate extremes could be investigated with the UNSEEN-
246 trends approach. For example, to assess the non-stationarity of extreme precipitation, covariates
247 other than time could be selected, such as ocean temperatures, modes of climate variability, or
248 indicators of large-scale synoptic weather systems. This may improve our physical understanding of
249 the non-stationary processes and could provide insight into potential model biases, thereby
250 improving confidence in detected trends. Century-long seasonal hindcasts, such as the ASF-20C
251 global atmospheric seasonal hindcasts⁴⁷, might prove useful in assessing the sensitivity of UNSEEN-
252 trends to different time windows over a longer time period.

253 Our results for Western Norway highlight the strength of UNSEEN in estimating design-levels and
254 present-day climate hazards, backed by a growing body of literature^{12,13,22,14-21}, and the results for
255 Svalbard emphasise the significance of our novel UNSEEN-trends approach in estimating non-
256 stationarities in climate extremes. Both underline the need to rethink current design-level estimates
257 based upon observations alone. We think further applications can 1) help estimate design values,
258 especially relevant for data scarce regions; 2) improve risk estimation of natural hazards by coupling
259 UNSEEN to impact models; 3) detect trends in rare climate extremes, including variables other than
260 precipitation; and 4) increase our physical understanding of the drivers of non-stationary climate
261 extremes, through the possible attribution of detected trends.

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412

413 **Methods**

414 **Data.** We use the fifth generation of the ECMWF seasonal forecasting system SEAS5 to generate the
415 UNSEEN ensemble. SEAS5 is a global coupled ocean, sea-ice, and atmosphere model, which has been
416 introduced in fall 2017³¹. The atmospheric component is based on cycle 43r1 of the ECMWF
417 Integrated Forecast System. The spatial horizontal resolution is 36 km and it has 91 vertical levels.
418 The ocean (Nucleus for European Modelling of the Ocean, NEMO⁴⁸) and sea-ice (Louvain-la-Neuve
419 Sea Ice Model, LIM2⁴⁹) models run on a 0.25-degree resolution. The atmosphere is initialized by ERA-
420 Interim⁵⁰ and the ocean and sea-ice components are initialized by the OCEAN5 reanalysis⁵¹. ECMWF
421 provides a re-forecast (also known as hindcast) dataset for calibration of the operational forecasting
422 system SEAS5. The data are initialized monthly with 25 ensemble members, each with 7-month

423 forecast length on a daily resolution, covering the years 1981-2016³¹. The ensemble members are
424 generated from perturbations to the ocean and atmosphere initial conditions and from stochastic
425 model perturbations.

426

427 In the UNSEEN approach, ensemble members and initialization dates are pooled to increase the
428 sample size of the variable of interest. Here, we generate an UNSEEN ensemble for the west coast of
429 Norway and for the Svalbard Archipelago to focus on recent atmospheric river (AR) related severe
430 events²⁷⁻²⁹. ARs have been connected to precipitation extremes in the observed records for both
431 Norway^{52,53} and Svalbard²⁷ and occur in September to March. AR-related floods mostly occur in
432 autumn, because snowfall during winter precipitation events results in storage rather than runoff.
433 One-day and five-day precipitation are a common diagnostic for extreme analysis^{6,54}. ARs frequently
434 strengthen over a period of several days^{28,29} and therefore multi-day diagnostics prevent splitting
435 events. Following the 2014 flood episode²⁹, we have chosen three-day total precipitation in this
436 study. We thus select autumn (September to November) 3-day extreme precipitation (SON-3DP) as
437 target events.

438

439 Since the forecasts are initialized every month on the first of the month and run over 7-months
440 length, there are five initialization months (May-September) available to forecast the entire target
441 autumn season (September-November). The first month is removed to avoid potentially dependent
442 events. In the end, 100 forecasts, based on 25 ensemble members with 4 initialization dates are
443 used to forecast the autumn season of each year (Fig. 1a-c). The window of 35 years between 1981
444 and 2016 leads to a total of 3500 forecasts of autumn weather conditions that could have occurred.
445 We extract the maximum 3-day cumulative precipitation within autumn from the 3500 forecasts
446 (SON-3DP), using the xarray package⁵⁵ in Python. To focus on the large-scale systems as experienced
447 in recent severe events, we use only the large-scale precipitation output of the model. The west
448 coast of Norway is mountainous and characterised by large topographic variations. Catchment-scale
449 processes in these mountainous areas cannot be resolved by a global model with 36 km resolution.
450 Therefore, the precipitation timeseries presented in this study are spatial averages where the 200-
451 year precipitation exceeds 90 mm for the west coast of Norway (4-7° E, 58-63° N) and 35 mm for
452 Svalbard (8-30° E, 76-80° N) (Supplementary Fig. 1).

453

454 To evaluate the precipitation extremes simulated by SEAS5, we use a 1x1 km gridded station-based
455 precipitation product for Norway²⁵. The data have recently been corrected for underestimation
456 caused by wind-induced under catch and uses more information in the interpolation scheme for

457 data-scarce areas, resulting in higher precipitation in data scarce areas²⁶. We upscale this gridded
458 dataset to the same resolution as SEAS5 and extract SON-3DP values for the same spatial domain
459 over 1981-2016. Note, for the Svalbard Archipelago no gridded precipitation dataset is available as a
460 reference dataset. We use ERA5⁴⁴ for the global and regional temperature evaluation of SEAS5.

461

462 **Ensemble member independence testing.** The method for independence testing applied in this
463 study is inspired by previous research on potential predictability: the ability of the model to predict
464 itself^{32,36}. The potential predictability of a model is calculated by using one of the forecast ensemble
465 members as the observations and the mean of the other ensemble members as the forecast. The
466 correlation between the 'observed' ensemble member and the mean of the other ensemble
467 members is calculated for every ensemble member and this range gives an estimate of the ability of
468 the model to forecast itself. Because this method assesses the correlation between ensemble
469 members, it can be used to find the degree of ensemble members' dependence. In seasonal
470 forecasting, this method is used to identify any predictability in the seasonal prediction system. In
471 contrast, here we seek to demonstrate that there is no potential predictability in the system for the
472 ensemble members to represent independent, unique events.

473 An illustration of our method to test for independence is shown in Fig. 1. A potential predictability
474 test is performed but instead of correlating an ensemble member to the mean of the other
475 ensemble members, a pairwise correlation test is applied between all ensemble members to
476 robustly assess the individual ensemble member dependence. Indeed, we concatenate the seasons
477 together member by member, even though they do not necessarily originate from the same run.
478 This approach was chosen because the underlying initialization method remains the same for each
479 member over different seasons.

480 For the 25 ensemble members, there are 300 distinct pairings in the correlation matrix for each of
481 the four lead times being analysed (may-August). We calculate the spearman ρ statistics on the
482 standardized SON-3DP anomalies (deviation from mean divided by the standard deviation) for each
483 distinct pair. From the 300 ρ values for each lead time, boxplot statistics are calculated: the
484 whiskers, the interquartile range and the median. When testing for significance of the 300 ρ values,
485 care must be taken not to falsely detect significant correlations because of the large number of tests.
486 For example, with a confidence interval of 5%, 15 out of the 300 correlations would be expected to
487 be significant by chance alone. To avoid these problems, a permutation test is performed. The
488 dataset, which previously consisted of 25 timeseries (members) of 35 datapoints (years) for four
489 initializations months (lead times), is resampled into 100 timeseries of 35 datapoints, with

490 datapoints randomly picked from all members, years and lead times to remove potential
 491 correlations. This randomized dataset is split into four pseudo lead times of 25 timeseries, in order
 492 to calculate the boxplot statistics from the same amount of correlation coefficients (300) as before.
 493 The data are resampled 1000 times (without replacement), resulting in 4000 boxplot statistics (4
 494 pseudo lead times * 1000 resampled series), from which the confidence intervals are calculated
 495 based on a 5% significance level (the 2.5 and 97.5 percentiles).

496

497 **Model stability.** The extreme precipitation distribution must be similar over lead times in order to
 498 generate the UNSEEN ensemble. We use four initialization months (May-August) forecasting the
 499 target autumn season with lead times 2-5 months. For each lead time, 25 ensemble members over
 500 35 years result into an 875-year long dataset and the pooled ensemble into 3500 years. To compare
 501 the distributions, we first plot the probability density function for each of the lead times using
 502 ggplot2⁵⁶. Secondly, we plot the extreme value distributions, focussing more on the tails of the
 503 distribution. We calculate empirical quantiles of the extreme precipitation ensemble without
 504 assuming any distribution a priori, to avoid problems regarding statistical modelling of the
 505 extremes^{10,57}. The quantile (Q) of a distribution is the inverse of the distribution function ($F(x)$):

$$506 \quad Q(p) = F^{-1}(p) = \inf \{x: F(x) \geq p\}, \quad 0 < p < 1 \quad (1)$$

507 Where the return value is associated with the quantile of percentile (p):

$$508 \quad p = 1 - \frac{1}{T} \quad (2)$$

509 With T being the return period. We use the quantile function in R⁵⁸ to compute the empirical return
 510 values and we refer to Hyndman & Fan⁵⁹ for more specifics.

511

512 **Fidelity of the UNSEEN ensemble for Western Norway.** We first evaluate the UNSEEN ensemble and
 513 then compare UNSEEN design-levels to observation-based design-levels. As a first assessment of the
 514 biases within the SON-3DP UNSEEN ensemble, we use rank histograms. Rank histograms indicate
 515 over-dispersion or under-dispersion and over-forecasting or under-forecasting bias³⁶. Here, we have
 516 100 members (4 lead times and 25 ensemble members) for each year over 1981-2015. The rank of
 517 the observations within the 100 ensembles is calculated for each year and the resulting 35 ranks are
 518 plotted as a histogram over the range 1-100. If the observations are mostly in the upper (lower)
 519 ranks, this indicates that the observed values are higher (lower) than the forecasted values and
 520 therefore the forecasts are under-forecasting (over-forecasting). Similarly, when the observations

521 are mostly in the outer (inner) ranks, this indicates that the observed values show more (less)
 522 variability and thus the forecasts are under-dispersed (over-dispersed). We create rank histograms
 523 for the raw SON-3DP UNSEEN ensemble, for the anomalies from the mean and for the standardized
 524 anomalies, where the anomalies are divided by the standard deviation.

525 To compare UNSEEN to the observed record in more detail, we apply a bootstrap test presented in
 526 previous studies^{20,22}. We bootstrap 10,000 timeseries of 35 years with replacement from all
 527 ensembles (100 x 35 years) and calculate the mean, standard deviation, skewness and kurtosis for
 528 each. We test whether the four distribution statistics derived from the observed precipitation time
 529 series over the period 1981-2015 fall within the 95% confidence intervals for the statistics derived
 530 from the bootstrapped timeseries.

531 We then fit the Generalized Extreme Value (GEV) distribution, described by a location ($-\infty < \mu <$
 532 ∞), scale ($\sigma > 0$) and shape ($-\infty < \xi < \infty$) parameter⁶⁰:

$$533 \quad F(x) = \exp \left[- \left(1 + \xi \left(\frac{x-\mu}{\sigma} \right) \right)^{-\frac{1}{\xi}} \right], \quad \left(1 + \xi \left(\frac{x-\mu}{\sigma} \right) \right) > 0 \quad (3)$$

534 And we test the sensitivity to using the Gumbel distribution with $\xi = 0$, simplifying the distribution
 535 to:

$$536 \quad F(x) = \exp \left[- \exp \left(- \left(\frac{x-\mu}{\sigma} \right) \right) \right], \quad -\infty < x < \infty \quad (4)$$

537 The quantiles of the distribution can again be obtained by inverting the distribution:

$$538 \quad x_p = \begin{cases} \mu - \frac{\sigma}{\xi} [1 - \{-\log(1-p)\}^{-\xi}], & \text{for } \xi \neq 0 \\ \mu - \sigma \log\{-\log(1-p)\} & , \quad \text{for } \xi = 0 \end{cases} \quad (5)$$

539 Where the return value x_p corresponds to the return period 1/probability (p). For all statistical
 540 model fits in this study (including non-stationary fits described in the next section), we apply
 541 Maximum Likelihood Estimation (MLE) to estimate the parameters of the distributions, utilizing the
 542 extRemes package⁶¹ in R⁵⁸. The 95% confidence intervals of the distributions are calculated based on
 543 the normal approximation, which is the default of the extRemes package.

544

545 **UNSEEN-trends.** In this study, we present the idea of performing trend analysis on seasonal
 546 hindcast, as the seasonal hindcasts provide a larger sample than observations and a higher
 547 resolution than climate models (see the UNSEEN-trends section for more details). We apply well-
 548 established extreme value theory^{60,62,63}, by allowing the location (μ) and scale (σ) parameters of the

549 GEV distribution (given in equation 3) to vary linearly with time (t). Because the scale parameter
550 needs to be positive, a log-link function is used:

$$551 \quad \mu(t) = \mu_0 + \mu_1 t \quad (6)$$

$$552 \quad \ln \sigma(t) = \phi_0 + \phi_1 t \quad (7)$$

553

554 This approach selects one block maximum per year, leading to 35 data points over the years 1981-
555 2015 based on observed records. With UNSEEN-trends, we have 100 times more values for each
556 year and thus increase confidence in the regression analysis (see Fig.4a,b for illustration). As for the
557 stationary method, we use MLE to estimate the parameters of the distributions and the normal
558 approximation to find the 95% confidence intervals of return values. We focus on the changes in the
559 100-year quantiles, because these are associated with the design-levels mostly used in flood
560 defence⁶⁴. The trend in the 100-year return value is defined as the percentual change between 1981
561 and 2015:

$$562 \quad \Delta x_T = 100 * \left(\frac{x_T(\mu_{2015}, \ln \sigma_{2015}, \xi) - x_T(\mu_{1981}, \ln \sigma_{1981}, \xi)}{x_T(\mu_{1981}, \ln \sigma_{1981}, \xi)} \right)$$

563 Where x_T is defined by equation (5).

564 The robustness of the trends to experiment decisions like the block size and the regression method
565 can be further investigated but are beyond the scope of this research. For example, 6-month blocks
566 can be selected at the expense of the ensemble size. This will result in 25 realizations, in comparison
567 with 3-month blocks, which contain 100 realizations. A block size of three months (September-
568 November) is chosen in this study. A linear trend in time is assumed in this study. With the large
569 amount of data, more complex regression methods can be explored. The ECMWF SEAS5 seasonal
570 prediction system is used in this study, but other seasonal prediction systems with available
571 hindcasts could also be assessed to test the model sensitivity to return value and trend estimation.

572 **Acknowledgements**

573 We greatly thank A.V. Dyrddal, J. Sillmann, A. Weisheimer, and the anonymous reviewers for their
574 input that helped improve the paper. T.K. acknowledges support from NERC CENTA Doctoral
575 Training Partnership and funding from both the Norwegian Meteorological Institute and
576 Loughborough University. M.M. acknowledges funding from the TWEX project (grant 255037).

577 **Data and code availability**

578 SEAS5 re-forecast data was accessed through the MARS Catalogue. This catalogue has restricted
579 access, it is available for National meteorological services of ECMWF Member and Co-operating
580 States. Other users can request access here: [https://www.ecmwf.int/en/about/contact-](https://www.ecmwf.int/en/about/contact-us?subject=Gain%20access%20to%20archive%20data)
581 [us?subject=Gain%20access%20to%20archive%20data](https://www.ecmwf.int/en/about/contact-us?subject=Gain%20access%20to%20archive%20data). Alternatively, SEAS5 re-forecast data on 1-
582 degree resolution, as well as ERA5 data, are openly available from the Copernicus Climate Change
583 Service (C3S) Climate DataStore (<https://cds.climate.copernicus.eu/>). The SeNorge daily total
584 precipitation data are available at <https://doi.org/10.5281/zenodo.2082320>. The extracted SON3DP
585 UNSEEN ensembles as well as the extracted SON-3DP observations, along with all code to reproduce
586 the analysis in this paper are available on GitHub: <https://github.com/timokelder/UNSEEN-trends>.

587 **Author contributions**

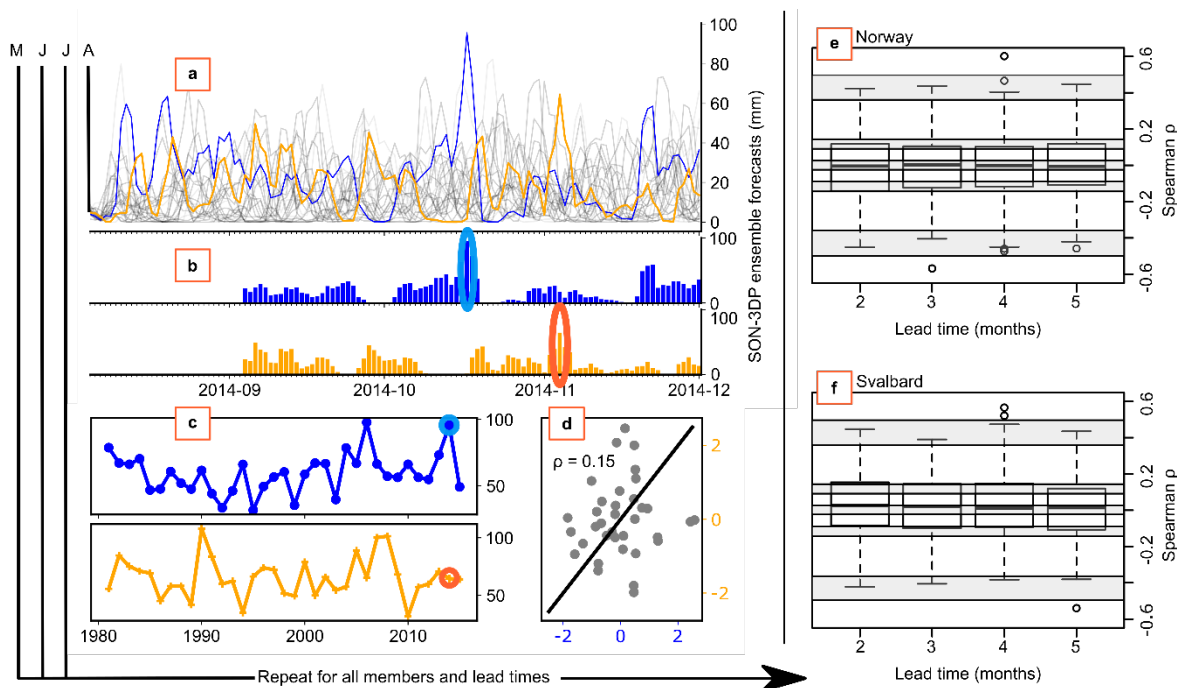
588 T.K. and M.M. conceived and T.K, M.M, L.J.S., T.M., R.L.W., C.P., P.B. designed the study. T.K. drafted
589 the paper with extensive contributions from L.J.S., T.M., R.L.W., C.P. and M.M.. T.K. analysed the
590 data with input from all authors. M.M. acquired the data. T.K. produced the figures; L.F. produced
591 Supplementary Fig. 6.

592 **Competing interests**

593 The authors declare no competing interests.

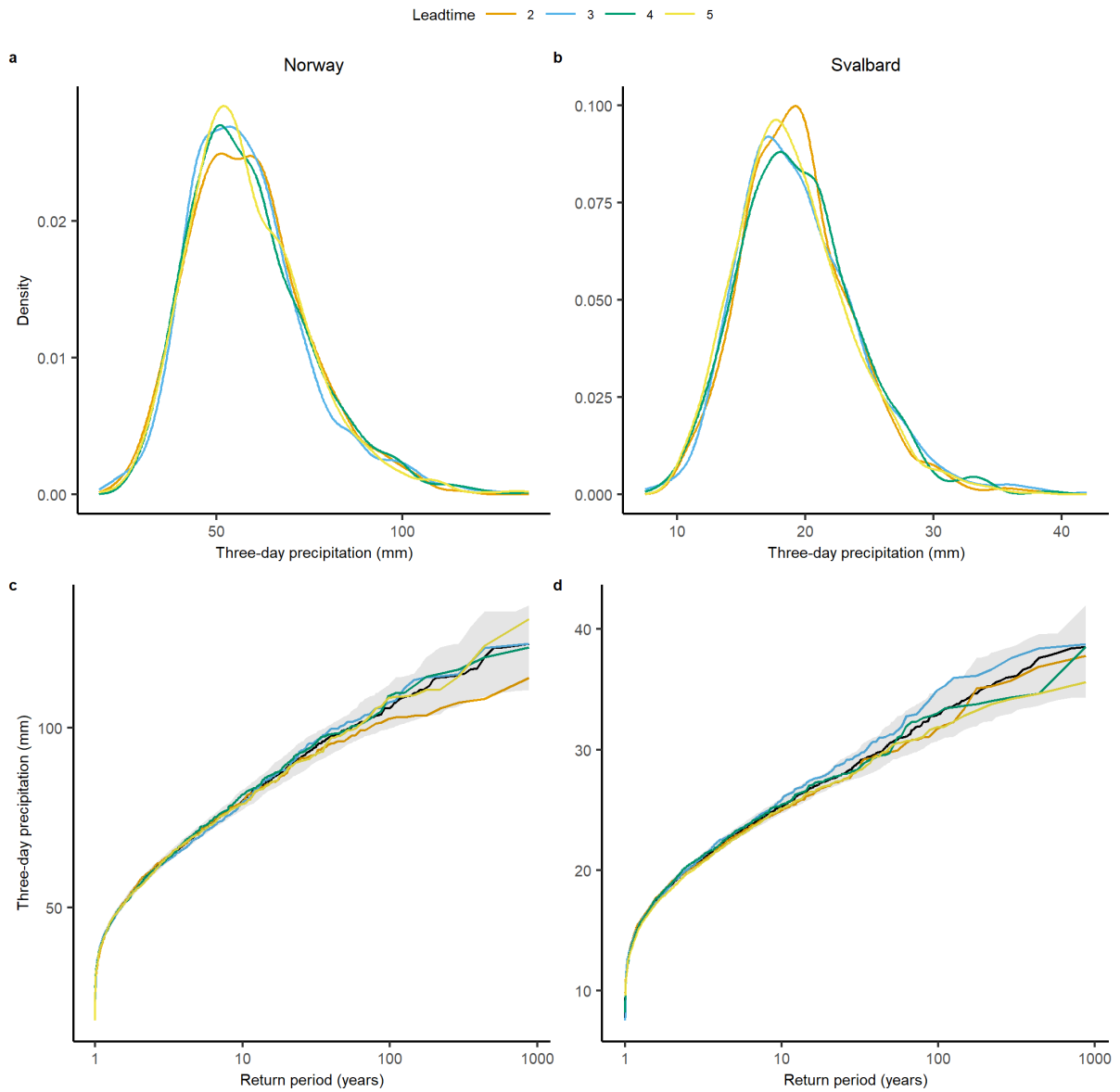
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595 **Figures**



596
 597 **Fig. 1 | A workflow for analysing ensemble member dependence.** **a**, August 2014 initialized 25-
 598 member seasonal forecasts of 3-day precipitation time series over the SON forecast horizon.
 599 Ensemble members 0 and 1 are shown in blue and orange, respectively. **b**, From the forecast
 600 members 0 and 1, the September-November (SON) maximum value for the 2014 season is selected.
 601 **c**, A series of the maximum 3-day precipitation values for the SON season for each year in the
 602 hindcast record is created for member 0 and member 1. The 2014 maximum, as illustrated in **b**, is
 603 encircled. **d**, The standardized anomaly of the maximum 3-day precipitation series for the two
 604 members are correlated. Spearman's ρ correlation is shown. This process is repeated for the 300
 605 distinct ensemble member pairings for each of the four lead times (May-August). **e,f**, Boxplots of the
 606 resulting 300 Spearman's ρ correlations for each lead time over Norway (**e**) and Svalbard (**f**). Grey
 607 shading shows the confidence intervals of the boxplot statistics (whiskers, interquartile range and
 608 median), based on a permutation test with 5% significance level.

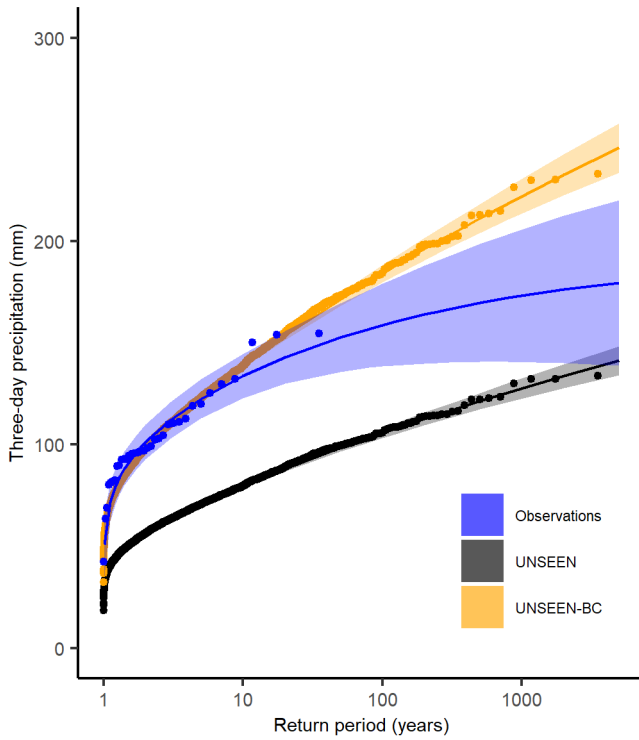
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615 **Fig. 2 | SEAS5 model stability of extreme precipitation over Western Norway and Svalbard.** The
 616 empirical probability density (**a,b**) and extreme value (**c,d**) distribution of SON-3DP for each lead time
 617 and for all lead times together (in black), for the West Coast (**a,c**) and Svalbard (**b,d**) domains. Grey
 618 shading in **c,d**, illustrates the 95% confidence intervals of the distribution of the pooled lead times,
 619 bootstrapped to timeseries of similar length to the individual lead times with $n = 10,000$.

620



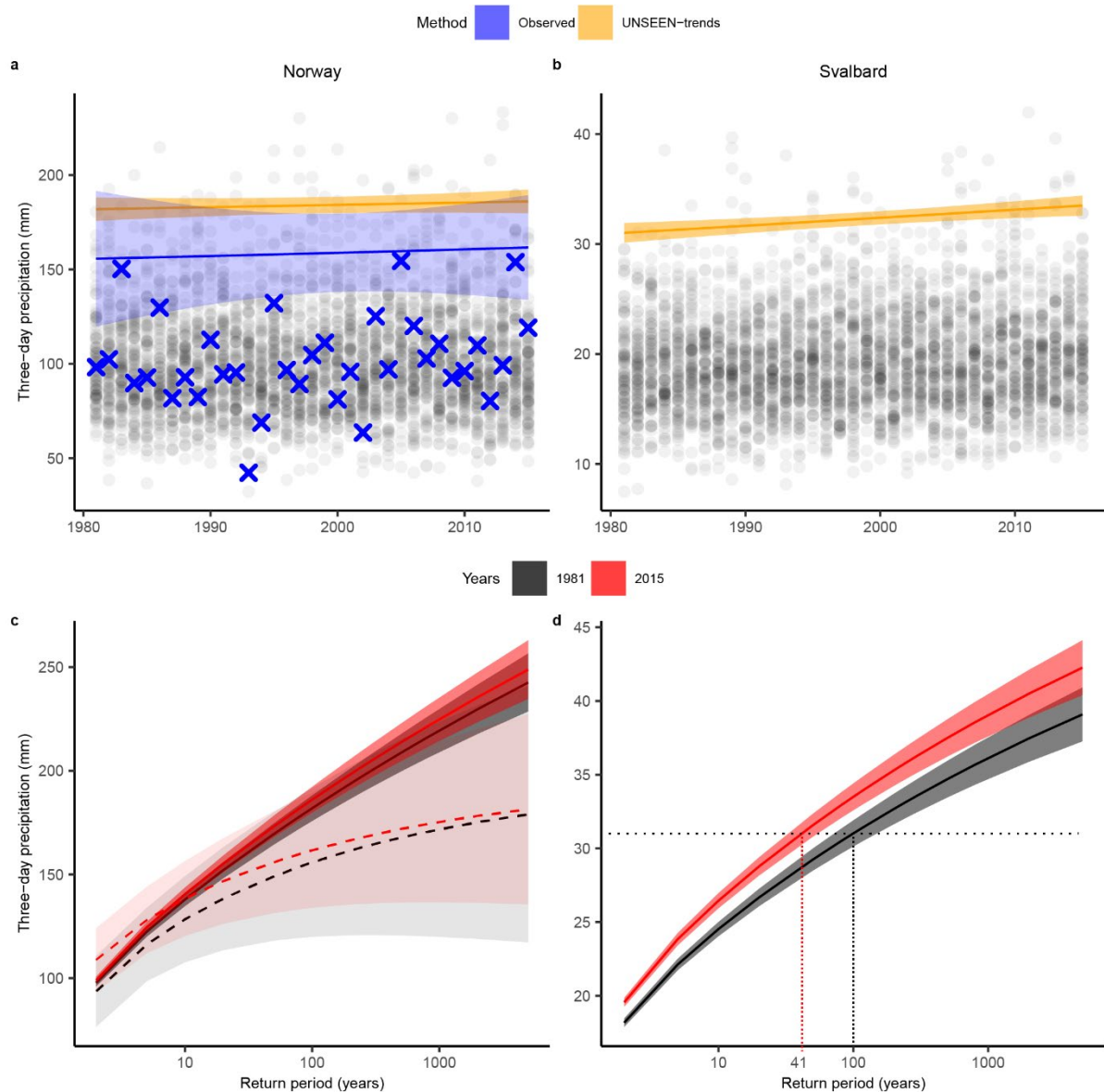
621

622 **Fig. 3 | The extreme precipitation distribution for UNSEEN and UNSEEN-BC, as compared to the**
 623 **precipitation record over Western Norway.** The data points show the SON-3DP events and the solid
 624 lines show the GEV fitted to the data, including 95% confidence intervals.

625

626

627



628

629 **Fig. 4 | UNSEEN-trends in extreme precipitation, as compared to trend analysis based on the**
 630 **precipitation record. a,b,** The change in 100-year SON-3DP over 1981-2015 is shown for (a) Western
 631 Norway and (b) Svalbard. The data points show the SON-3DP events in the observed record (blue
 632 crosses) and in the UNSEEN-ensemble (black circles). Note, for Svalbard no gridded precipitation
 633 record is available and for Norway the bias-corrected UNSEEN-BC is used. **c,d,** In addition to the
 634 change in 100-year precipitation, the entire GEV distribution is plotted for the covariates 1981 and
 635 2015 over (c) Western Norway and (d) Svalbard. Solid lines and dark shading indicate the trend and
 636 uncertainty of the UNSEEN-trends approach and dashed lines with light shading (in c) indicates the
 637 trend and uncertainty range based on observations. In d, the magnitude of the event with a return
 638 period of 100 years in 1981 is illustrated with black dotted lines and the event of similar magnitude
 639 corresponding to a return period of 41 years in 2015 is illustrated with a red dotted line.