

Simulating fully-integrated hydrological dynamics in complex Alpine headwaters: potential and challenges

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Key Points:

- An integrated model of two adjacent steep, snow-dominated, geologically complex Alpine headwaters was developed and calibrated automatically
- Spatio-temporal dynamics and interdependencies of snow, surface water, groundwater, and evapotranspiration processes were represented
- Employing alternative, commonly used subsurface simplifying assumptions strongly affected simulated dynamics

1 **Abstract**

2 Highly simplified approaches continue to underpin hydrological climate change impact assessments across the
3 Earth's mountainous regions. Fully-integrated surface-subsurface models may hold far greater potential to represent
4 the distinctive regimes of steep, geologically-complex headwater catchments. However, their utility has not yet been
5 tested across a wide range of mountainous settings. Here, an integrated model of two adjacent calcareous Alpine
6 headwaters that accounts for 2D surface flow, 3D variably-saturated groundwater flow, and evapotranspiration is
7 presented. An energy balance-based representation of snow dynamics contributed to the model's high-resolution
8 forcing data, and a sophisticated 3D geological model helped to define and parameterize the subsurface structure. In
9 the first known attempt to calibrate a catchment-scale integrated model of a mountainous region automatically,
10 numerous uncertain model parameters were estimated. The salient features of the hydrological regime could
11 ultimately be satisfactorily reproduced – over an 11-month evaluation period, the Nash-Sutcliffe efficiency of
12 simulated streamflow at the main gauging station was 0.76. Spatio-temporal visualization of the forcing data and
13 simulated responses further confirmed the model's broad coherence. Presumably due to unresolved local subsurface
14 heterogeneity, closely replicating the somewhat contrasting groundwater level signals observed near to one another
15 proved more elusive. Finally, we assessed the impacts of various common model simplifications and assumptions on
16 key simulated outputs, finding strongly affected model performance in many cases. Although certain outstanding
17 challenges must be overcome if the global uptake of integrated models in mountain regions is to increase, our work
18 demonstrates the feasibility and benefits of their application in such complex systems.

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21 **Key words:** *Mountain hydrology; integrated hydrological modelling; snow; geology; calibration; spatio-temporal*

22 1. Introduction

23 Mountainous water resources are crucial for many human societies and ecosystems around the world (Immerzeel et
24 al., 2020; Viviroli et al., 2020). However, in the European Alps as elsewhere, two key hydrological system
25 components – the glaciers and snowpacks – are declining rapidly due to ongoing warming (Beniston et al., 2018).
26 Reliable projections of Alpine hydrological system behavior are therefore urgently required to design and implement
27 sound mitigation and adaptation measures.

28
29 In terms of their complexity and dynamics, mountain hydrological systems have few equivalents. For instance,
30 considerable elevation gradients and rugged topography drive pronounced spatio-temporal variability in
31 meteorological conditions, and inherently complex bedrock and unconsolidated sediment architectures can strongly
32 influence subsurface flow patterns and storage dynamics, and therefore broader hydrological system functioning.
33 Contemporaneous changes in other system components such as forests and permafrost could modulate more direct
34 climate-driven hydrological changes (e.g. Evans et al., 2015). Unfortunately, the quantity and spatial
35 representativeness of environmental data in such environments is often notoriously limited (Thornton, Palazzi, et al.,
36 2021).

37
38 Despite this high complexity, but probably also partly due to limited data, most mountainous hydrological climate
39 change impact assessments rely on highly simplified “box-type” conceptual hydrological models (e.g. Jenicek et al.,
40 2018; Wagner et al., 2017). More physically-based models such as the Cold Regions Hydrology Model (CRHM)
41 and Alpine3D are now being increasingly applied (e.g. DeBeer and Pomeroy, 2017; Brauchli et al., 2017). However,
42 both model classes have important limitations with respect to the representation of subsurface flows and exchanges
43 between surface and groundwaters. Typically, only shallow “soil zones” are represented, combined with spatially
44 lumped “groundwater reservoirs”. Storage-discharge relationships are generally assumed to be linear, and both
45 lateral flows and subsurface-surface exchanges are routinely neglected (Gallice et al., 2016; Fatichi et al., 2015).

46
47 Elsewhere, partial differential equation-based, spatially distributed, fully-integrated (or fully-coupled) surface-
48 subsurface models are becoming more popular; reported applications now span a considerable range of research
49 questions, environmental settings, and spatial scales (Ala-aho et al., 2015; Hwang et al., 2018; Jaros et al., 2019;
50 Maxwell et al., 2015; Smerdon et al., 2007; Sulis et al., 2011; Tolley et al., 2019). These codes can mechanistically
51 simulate most relevant hydrological processes including 2D surface flow, 3D variably-saturated groundwater flow,
52 and evapotranspiration in a physically-based, distributed, transient, and internally coherent fashion. In contrast to
53 traditional groundwater models, recharge does not have to be prescribed externally. Runoff generation can arise
54 from arbitrary combinations of infiltration overland flow, saturation excess overland flow, and groundwater
55 discharge), meaning that dominant runoff generation mechanisms need not be assumed *a priori*.

56
57 Integrated models would appear to be especially well-suited to simulating distinctive mountain hydrological
58 regimes. As 3D information on the arrangement of subsurface formations can be incorporated, they should be able to
59 explicitly capture the influence of complex Alpine geologies on broader hydrological dynamics. Surface water
60 flows, which are important in terms of flood risk and sediment transport in steep terrain, are simultaneously
61 accounted for. In addition, the free, bi-directional exchange between the surface and subsurface domains can be
62 represented. As such, unlike most hydrological models which require fixed stream locations to be defined, fully-
63 integrated codes like HydroGeoSphere (HGS; Aquanty Inc., 2016) allow the stream network to evolve dynamically
64 according to the topography, boundary conditions, and surface and subsurface properties prescribed. This could be
65 useful because many headwater torrents and streams are intermittent (Durighetto et al., 2020; Van Meerveld et al.,
66 2019) and/or demonstrate strong spatio-temporal variability in patterns of loss and gain more generally.

67
68 Several progressively comprehensive and complex studies seeking to exploit the capabilities of advanced coupled
69 and integrated surface-subsurface models in mountainous contexts have emerged over recent years (Gleeson and

70 Manning, 2008; Huntington & Niswonger, 2012; Voeckler et al., 2014; Markovich et al., 2016; Pribulick et al.,
71 2016; Ala-aho et al., 2017; Penn et al., 2016; Carroll et al., 2019; Maina & Siirila-Woodburn, 2020). Whilst these
72 examples attest to much progress, they predominantly focused on crystalline or other low permeability/storage
73 bedrock catchments in western North America, and generally still involved substantial structural simplifications.

74
75 For instance, some previous studies simply assumed bedrock to be entirely impermeable (i.e. a no-flow boundary
76 was imposed at its upper surface; Ala-aho et al., 2017; Camporese et al., 2019). Alternatively, single bedrock zones
77 with homogeneous hydraulic conductivity (Markovich et al., 2016; Voeckler et al., 2014) or a few sub-parallel
78 geological layers (Huntington & Niswonger, 2012) were considered sufficient, although Engdahl and Maxwell
79 (2015) employed a more detailed representation. Even where bedrock flow was permitted, domains were typically
80 limited vertically to only a few tens of meters below the surface, potentially limiting groundwater circulation depth.
81 Although hydraulic conductivity may indeed decline strongly with depth in crystalline settings (Welch & Allen,
82 2014), field evidence for deep flows is increasing (Frisbee et al., 2017).

83
84 The uptake of integrated models in other, potentially even more complex, mountainous regions remains extremely
85 limited. For instance, the topographic, geological, and process complexity of hydrological systems in the European
86 Alps is arguably higher than that of mountainous basins in the Western U.S. and Canada, partly because the range is
87 geologically younger. As such, certain assumptions made in previous mountain integrated modelling studies may be
88 even more strongly challenged by Alps' steep, snow-dominated, and geologically complex nature. Indeed, in
89 calcareous parts, sequences of limestones, shales, and marls have been folded and faulted into complex
90 arrangements. In these regions, groundwater flowpaths can be deep, with patterns strongly influenced by aquifer-
91 aquitard interface geometries (Thornton et al., 2018). Consequently, integrated models here should ideally be based
92 on 3D representations of structural geology, but 3D datasets possessing the requisite attributes for
93 hydrological/hydrogeological modelling have traditionally been lacking (e.g. Thornton et al., 2018).

94
95 Similarly, in steep, rugged terrain, forcing datasets should be highly resolved in space and time (i.e. on the order of
96 10s – 100s of meters, and at hourly time-steps). However, running complex integrated models of real-world
97 catchments with such highly-resolved spatially distributed and transient boundary conditions remains uncommon,
98 and so its feasibility is unclear. On this note, it is worth mentioning that fully-integrated model generally lack the
99 convenient pre-processing routines to correct (e.g. for precipitation undercatch) and spatially interpolate
100 meteorological station data. As reanalysis products are generally still too coarse and unreliable to be applied directly
101 in small, rugged headwaters, this may hinder their usability. Other code limitations may pose further problems; for
102 example, GSFLOW (Markstrom et al., 2008) runs exclusively at daily time-steps.

103
104 Adequately representing snow dynamics, and therefore spatio-temporal patterns of meltwater arrival at the land
105 surface, is also imperative. The main challenges in this regard are associated with high process variability and
106 complexity alongside limited and uncertain meteorological data. Integrated models generally offer only index-based
107 snowmelt estimation approaches (an exception is ParFlow.CLM which supports an energy-balance scheme). For
108 example, the study of Voeckler et al. (2014), alongside other integrated model applications in less mountainous but
109 nevertheless strongly snow-influenced settings (Cochand et al., 2019; Schilling, Park et al., 2019) involved such
110 empirical schemes, while Ala-aho et al. (2017) neglected snow processes altogether. Integrated surface-subsurface
111 code do not yet incorporate snow redistribution processes. As such, advancements in distributed snowpack
112 simulations – for example using physics-based, multi-layered snow models (Brauchli et al., 2017), more hybrid
113 physical-empirical models conditioned on various snow observations (Thornton, Brauchli, et al., 2021), and other
114 similar efforts (e.g. Griessinger et al., 2019; Schattan et al., 2020) – have yet to be combined with integrated
115 descriptions of surface-subsurface flow dynamics.

116
117 Finally, integrated models are notoriously computationally intensive. Long runtimes (often days to weeks; Miller et
118 al. 2018) can confound formal automated calibration and uncertainty analyses, which require many forward

119 iterations (von Gunten et al., 2014). Of all the mountainous integrated modelling studies discussed hitherto, only
 120 Ala-aho et al. (2017) attempted automated calibration, with others relying on – if anything – manual calibration
 121 and/or simple sensitivity analyses (see also Foster and Maxwell, 2019). Nonetheless, because “mountains do not
 122 give up their secrets easily” (Klemeš, 1990), the importance of calibration is arguably higher here than elsewhere.

123
 124 In summary, meeting the goal of developing robust and informative simulations of Alpine systems using fully-
 125 integrated models would appear to require progress beyond established practices in several areas. In this context, we
 126 sought to develop and calibrate a fully-integrated model of two adjacent steep, snow-dominated, and geologically-
 127 complex headwater catchments in Switzerland to gain insights into two initial research questions:

- 128 1. How feasible is the development and application of integrated models employing minimal structural
 129 simplification in complex Alpine terrain?
- 130 2. To what extent can such models be calibrated automatically using streamflow and groundwater level time-
 131 series data?
 132

133 Then, bearing in mind the structural simplifications applied in previous studies (and the general neglect of
 134 structural uncertainty), we developed several structurally simplified model versions (mimicking common
 135 approaches) which were applied in a series of sensitivity experiments to address a further research question:

- 136 3. Taking the calibrated “full complexity” model as a reference, to what extent do structural simplifications
 137 affect model performance, and what can be inferred about the degree of model complexity required in such
 138 settings?
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140 Being able to address this third question is a key corollary benefit of developing holistic, complex models in the first
 141 instance. Pursuing this research theme more extensively could help to close the gap between simpler and coarser
 142 models that can be applied efficiently across large areas and timescales but which may not yield locally meaningful
 143 or useful predictions, and more detailed and sophisticated models that able to exploit multiple local datasets but
 144 which are currently less amenable to extension across larger areas.

145 2. Methods

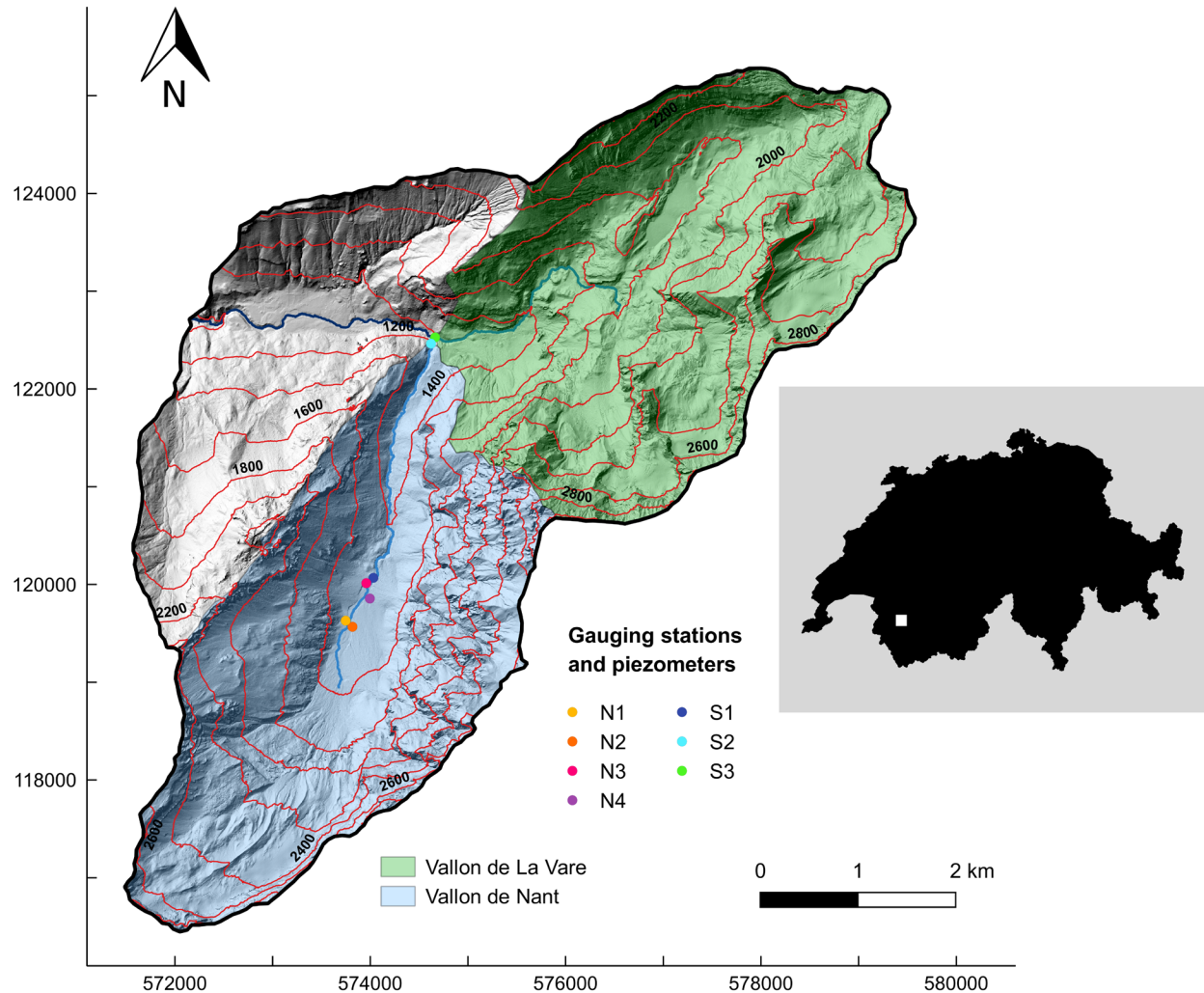
146 2.1. Study area and field instrumentation

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 148 The ~37 km² study area encompasses two adjacent headwater catchments in the western Swiss Alps – the Vallon de
 149 Nant and the Vallon de La Vare (Figure 1). Elevations range from 950 m to >3,050 m a.s.l, slopes are steep, and the
 150 topography is rugged. The Vallon de Nant has been designated a Natural Reserve since 1969, and the wider area
 151 remains in a highly natural state. Land cover is varied; with increasing elevation, dense forest progressively gives
 152 way to open alpine pastures, regions of unconsolidated rock, and bedrock outcrops/cliffs. Debris flows and
 153 avalanches occur frequently. Apart from in the valley bottoms, soils are generally thin or non-existent, whilst small
 154 glaciers persist in the highest sheltered, north-facing sections. Some permafrost is present at the highest elevations
 155 (Giaccone et al., 2019), but is unlikely to be extensive. Various unconsolidated Quaternary sedimentary features
 156 overly the bedrock in places and are thought to function as aquifers.

157
 158 Approximately 40% of annual precipitation (≥ 1400 mm) falls as snow. Snowmelt dominates total annual streamflow
 159 and contributes significantly to groundwater recharge. Intensive convective storms occur regularly in summer. The
 160 surface hydrology of the Vallon de Nant is characterized by numerous temporary torrents, whose discharge responds
 161 rapidly to rainfall and snowmelt. Streams and other surface water features are less conspicuous in the upper part of
 162 the Vallon de La Vare, probably because of its more permeable near-surface bedrock. Lack of long-term, systematic
 163 hydrometeorological observations and severely restricted vehicular access (due to environmental regulations)
 164 represented challenges to model development.

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Geologically, the region lies within the Nappe de Morcles; the lowest of a series of large nappe thrust folds that together constitute the Helvetic Nappes. Alternating sequences of fairly permeable and – in places – probably karstified limestones are interspersed with much lower permeability marls and shales (Badoux, 1971). These Mesozoic sequences have been folded and faulted into complex arrangements by tectonic forces, such that the geometries of the various (non-planar) aquifer-aquitard interfaces are expected to strongly influence groundwater flow patterns. As alluded to above, the two sub-catchments lie within different zones of the first-order fold structure. Thornton et al. (2018) provide further information on the area’s geology and known or hypothesized hydrological / hydrogeological functioning.



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Figure 1. The study area and its location within Switzerland. Stream discharge (S1-S3) and groundwater level (N1-N4) measurement station locations are indicated. Coordinates are in the CH1903 system (m). The catchment center is at approximately: N46.23, E7.10.

A concrete weir exists downstream of Pont de Nant (S2 in Figure 1, see also Figure S1a). Such gauging stations are rare on low-order Alpine streams, especially upstream of any anthropogenic influences. Automatic water level measurements were combined with a salt-dilution derived rating curve (Ceperley et al., 2018) to generate a fairly complete record of hourly discharge from April 2016 onwards. Shifting streambed configurations immediately upstream of the regular cross-section undermine the consistency of the record somewhat, leading to potential biases

185 and/or uncertainties affecting both high and low flow estimates. Stream level measurements were also made at two
186 additional locations, S1 and S3, but the resultant discharge series here are shorter and more uncertain as the cross-
187 sections were not fixed.

188

189 Four small-diameter shallow (up to 6.5 m deep) groundwater piezometers (or observation wells) were installed in
190 the vicinity of the large alluvial fan system in the central part of the Vallon de Nant (N1-N4 in Figure 1; see also
191 Figure S1). The piezometers were screened over at least their lower halves, and were equipped with the pressure
192 loggers in June 2017. They yield half-hourly observations, although at three of the four sites groundwater levels fell
193 below the piezometer base elevations for considerable periods.

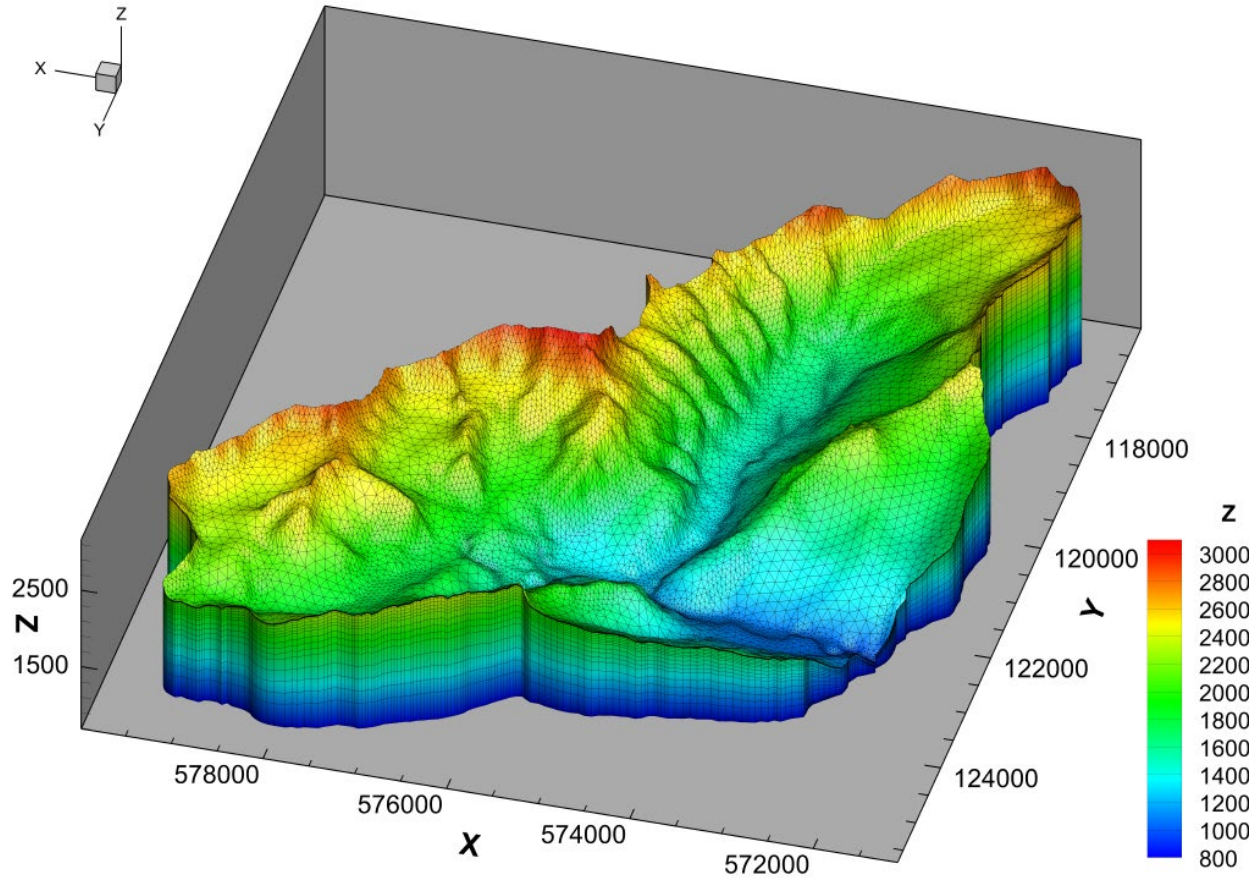
194 2.2. Model setup

195 HGS (Aquanty Inc., 2016) is a fully-integrated simulator that simultaneously solves the diffusion wave
196 approximation to the Saint-Venant equations for shallow 2D surface flow and a modified form of Richards' equation
197 for 3D variably-saturated subsurface flow. The surface-subsurface coupling was conceptualized here using the first-
198 order-exchange method (Ebel et al., 2009). Although some formations are expected to be karstified and soil
199 macropores also likely present, the subsurface was treated as an Equivalent Porous Media (EPM). As such,
200 parameters values must be considered effective at the elemental scale. Interception and evapotranspiration are
201 simulated according to Kristensen and Jensen (1975) as a function of atmospheric demand (i.e. potential
202 evapotranspiration; ET_p), surface and near-surface moisture conditions, and vegetation properties. HGS was chosen
203 over possible alternatives on account of its support for (partially, in this case) unstructured finite element meshes
204 which – compared with regular discretization schemes – allow better representation of the study area's complex
205 topography and other physical features than regular discretization schemes. Additionally, as noted earlier, the stream
206 network is free to evolve “naturally” in HGS.

207 2.2.1. Finite element mesh generation

208 Several meshes were initially developed and tested to achieve an appropriate balance between the representation of
209 physical features, good numerical convergence, and the total number of nodes/elements. Catchment boundary and
210 theoretical stream polylines generated via a terrain analysis acted as the primary geometrical constraints. In the final
211 2D triangular surface mesh (Figure S2), which was generated using multi-level optimization and Delaunay
212 refinement in Algomesh (HydroAlgorithmics, 2016), nodes were spaced at approximately 20-25 m intervals along
213 the streamlines to capture the morphology of the incised watercourses, with separation distance then increasing
214 away from riparian areas. The mesh was further refined in very steep areas, and nodes were placed at precisely the
215 same locations as the *in situ* instruments. Overall, a fairly high surface mesh resolution was required to minimize
216 potential biases that can be induced in such terrain if low-order streams and ridges are smoothed out (Wang et al.,
217 2018). Typical terrain pre-processing (Käser et al., 2014) was not carried out due to the presence of topographically
218 closed basins in the limestone landscape of the Vallon de La Vare. Rather, surface node elevations were simply
219 extracted directly from the swissALTI^{3D} Digital Terrain Model (DTM) (horizontal resolution = 2 m). Thereafter, the
220 mesh was extruded vertically in 23 layers, resulting in a 3D mesh comprised of 272,376 nodes (507,771 prismic
221 elements) (Figure 2). (Note: under the “dual nodes” approach applied, HGS automatically creates a duplicate surface
222 node sheet).

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226 **Figure 2.** The partially-unstructured 3D prismic mesh. The Z-variable denotes elevation in meters above sea level
227 (a.s.l.). The surface mesh was refined close to the streams and in very steep areas. Discretization in the vertical plane
228 was finest near the surface and coarsened with depth. Coordinates are in the projected CH1903 system (m).
229

230 Vertical resolution was maximal near the surface, with sheets created at 0.25, 0.5, 1.0, 2.0, 4.0, and 6.0 m depths to
231 ensure that near-surface wetting / drying fronts could be captured, that layers coincided with the assumed soil
232 thicknesses (see next subsection), and that nodes were located at the approximate depths of the groundwater pressure
233 transducers. The next three layers were spaced at 5 m intervals everywhere, except within the extents of major
234 unconsolidated features (in these areas, the lowermost of these layers corresponds to the estimated feature base
235 geometries – that is, depth to bedrock in all apart from the Nant alluvial fan – and the remaining two layers equally
236 divided the remaining distance up to the 6.0 m deep layer; see also Supplementary Text S1). Across the entire
237 domain, the spacing between the 14 remaining sub-parallel layers increased with depth until the constant specified
238 base elevation of 800 m a.s.l. was reached. Given the regional geology (folded and faulted sequences of
239 hydraulically contrasting formations, including some thin layers), such an extensive and highly resolved vertical
240 mesh sought to ensure that potential deep flow paths were not artificially curtailed, and that loss of structural
241 information during the transfer of the continuous 3D geological model onto the mesh was minimized.

242 2.2.1. Definition of surface and subsurface zones

243 A land cover map developed from swisstopo data (see Figure S3) defined the surface and evapotranspiration zones
244 (i.e. spatial regions assigned uniform parameter values). As the map resolution exceeded that of the mesh, faces
245 were assigned to distinct zones according to the dominant land cover classes (Tables S1 and S2). Estimated
246 permafrost extent in both consolidated and unconsolidated sediments, mapped using the methodology of Deluigi et
247 al. (2017), was superimposed upon this classification (i.e. permafrost presence was treated as a sub-category in the

248 zonation scheme). The consolidated component of the permafrost map was binary because permafrost presence in
249 rock walls depends strongly on air temperature and can therefore generally be determined confidently. Predicting the
250 spatial distribution of permafrost occurrence in unconsolidated sediments is much more demanding, and so the map
251 of permafrost occurrence in unconsolidated sediments was probabilistic. Only pixels with probabilities > 0.5 were
252 treated as permafrost in the model, however.

253
254 Subsurface zones were defined according to three sources. The first was a 3D model of bedrock geology that
255 represents 18 distinct formations and associated features like faults and secondary folds (Thornton et al., 2018;
256 Figure S4). To transfer the bedrock information on the mesh, geological formation identifiers (see Table S3) at each
257 element centroid were extracted. As with the land cover map, some information loss was inevitable during this
258 process. The second source was estimated geometries of five unconsolidated Quaternary features likely to be
259 important aquifers. These geometries were derived via a simple geomorphometrical method, which was
260 complemented by inferences from geophysics for the main alluvial fan aquifer (Nant) feature (see Supplementary
261 Text S1). The formation identifiers of any elements whose centroids fell within these volumes were overwritten with
262 those of the respective Quaternary formation, this reassignment being necessary because all elements were initially
263 assigned an identifier from the bedrock model (i.e. the bedrock model was “filled” to the surface). Wherever
264 bedrock did also not outcrop according to surficial geological maps beyond these major unconsolidated formation
265 extents, a generic “cover” layer with an assumed thickness of 2 m was defined to represent the thin superficial cover.
266 The third information source – a simple assumed soil depth map (Figure S5) – was prepared in the absence of more
267 detailed information on the spatial distribution of soil depths and their associated textural or hydraulic properties; the
268 existing “official” spatially distributed soil data (OFAG, 1980) were considered dated and of questionable
269 suitability. Soils were considered as a single, homogenous zone, and the same “overwriting” process as described
270 above was applied. Whilst the soil zone is very small compared to the unconsolidated and consolidated geological
271 formations volumetrically, it likely exerts a disproportionately strong hydrological influence via its influence on the
272 partitioning of incident liquid water at the surface. In total, 24 distinct subsurface zones were defined. The main
273 remaining structural uncertainties relate to the soil and unconsolidated aquifer volumes. All these zones were
274 considered fixed in the full complexity reference model.

275 2.2.3. Boundary conditions

276 HGS currently provides no meteorological station data pre-processing capabilities, and offers only a simple
277 temperature-index snow module. We therefore elected to apply forcing datasets that were generated externally, but
278 specifically for use in this model (Thornton, Brauchli, et al., 2021). For the snow component, a spatially distributed
279 energy balance-based model that additionally accounts for gravitational snow redistribution from steep slopes was
280 used to generate hourly snowmelt data at 25 m resolution. In that model, several uncertain snow parameters were
281 optimized against snow extent maps derived from Landsat 8 imagery and reconstructed snow water equivalent
282 (SWE) time-series. Commensurate datasets pertaining to glacier melt, rain falling on snow / ice free surfaces, and
283 ET_p (based on the Penman-Monteith method) datasets were also produced. For further details, readers are referred to
284 (Thornton, Brauchli, et al., 2021). The datasets corresponding to the period 1 October 2014 – 30 September 2019,
285 and therefore partially coinciding with the streamflow and groundwater level observations, were compiled to give
286 gridded representations of i) “all liquid water arriving at the land surface” (i.e. snowmelt, ice melt, firn melt, and
287 rain), and ii) ET_p , which were then applied in HGS as “rain” and “potential evapotranspiration” boundary conditions,
288 respectively. Aggregations to daily and monthly values were also produced.

289 To allow water to leave the domain, a “critical depth” boundary condition was applied to all surface boundary nodes
290 (Aquanty, 2016). This condition forces the flow depth at these locations to be equal to the critical depth, which is the
291 depth at which at which specific energy is minimal for a given discharge. It corresponds to the condition of critical
292 flow for which the Froude number is equal to one (Hornberger et al., 2014). The base and sides of the domain were
293 treated as “no flow” boundaries (i.e. flow across these faces was assumed to be negligible).

338
 339 where w_{GWL} , $w_{Q_{S2}}$, and $w_{Q_{S1,3}}$ are the relative weights that were assigned to each “observation group”, i.e. the
 340 groundwater levels, the streamflows at S2, and the streamflows at S1 and S3, respectively. Here, $w_{GWL} = 0.38$,
 341 $w_{Q_{S2}} = 5.50 \times 10^{-5}$, and $w_{Q_{S1,3}} = 9.00 \times 10^{-5}$. GWL_{sim} and GWL_{obs} , $Q_{S2_{sim}}$ and $Q_{S2_{obs}}$, and $Q_{S1,3_{sim}}$ and $Q_{S1,3_{obs}}$ are the
 342 corresponding simulated and observed values at N1-4, S2, and S1 and S3, respectively.

343
 344 Given the contrasting number, magnitudes, and units of observations within the different groups, as well as the
 345 unknown degree of initial mismatch, the final weighting scheme used in the OF (i.e. the weights to apply to the
 346 observations in each of the three groups) could only be determined after running the model once with the initial
 347 parameters and arbitrary weights, and is inherently somewhat subjective. Usually, one would seek to roughly
 348 equilibrate the respective contributions of each observation group to the OF. Although the streamflow measurements
 349 (being spatially integrated) and groundwater level measurements (being spatially explicit) can be considered
 350 complementary (Paniconi & Putti, 2015), in complex unconsolidated settings, groundwater levels can be heavily
 351 influenced by extremely local phenomena. In this case, because the four piezometers were located within a single
 352 model zone, we realized that it would be essentially impossible to reproduce the distinctly different groundwater
 353 responses observed in these nearby wells without introducing sub-zone heterogeneity, which was beyond the present
 354 scope. Therefore, to prevent the calibration process magnifying this deficiency in model structure, the groundwater
 355 levels were weighted relatively lightly such that their combined contribution to the initial OF was only around 11%.
 356 In other words, whilst each observation group maintained at least some “visibility” in the calibration, most emphasis
 357 was placed on streamflows.

358
 359 Various additional model simplifications were necessary to facilitate automated calibration (cf. Ala-aho et al. 2017).
 360 Firstly, the re-initialization and calibration periods described above were relatively short. Whilst this naturally
 361 facilitated the multiple runs required, longer periods would of course have been preferable. That said, the length of
 362 the calibration period specifically was largely dictated by observational data availability and a desire to maintain an
 363 independent evaluation period. That said, given the pronounced seasonality of these catchments’ hydrological
 364 regimes, it was considered crucial that the calibration period should exceed one year.

365
 366 Runtimes were found to increase substantially with the forcing data’s temporal resolution. Therefore, in a second
 367 simplification, the calibration runs were undertaken using only monthly (but still distributed, 25 m) forcings.
 368 Perhaps slightly surprisingly, simulated seasonal dynamics were not highly sensitive to monthly vs. daily data
 369 (Figures S8 and S9), which provides some justification for this strategy. In another simplification aimed at reducing
 370 runtimes, the unsaturated zone (pressure head–saturation, and saturation–relative hydraulic conductivity)
 371 relationships for all subsurface zones except the soil were made less non-linear and represented in tabular form using
 372 a small number of data points. The poorly understood nature of these relationships in consolidated, potentially
 373 fractured, and/or karstified bedrock supports this approach. For the soil, van Genuchten parameters (van Genuchten,
 374 1980) were applied (see Table S1).

375
 376 The slope term in the surface water flow equations was assumed equal to the topographic slope, and thereby also
 377 linearized. Furthermore, the HGS model’s convergence criteria were relaxed for calibration (Newton absolute =
 378 1×10^{-3} m, Newton residual = 500 m) before being re-tightened for the subsequent runs with optimized parameters
 379 (Newton absolute = 1×10^{-3} m, Newton residual = 150 m). The latter settings led to a mean mass balance error,
 380 expressed as a percentage of liquid water input, of $\lesssim 5\%$. Finally, the “coupling length” parameter for all surface
 381 zones except the streambed was set to a somewhat higher (and fixed) value (0.1 m) than is ordinarily the case;
 382 values closer to zero are generally recommended to approximate the Continuity of Pressure (COP) approach, but
 383 typically increase runtimes (Liggett et al., 2012). Tests revealed model outputs of interest to be fairly insensitive to
 384 this choice. To represent the enhanced surface-subsurface disconnection that the fine silty streambed sediments we
 385 observed in the field could induce, the streambed zone coupling length was fixed to 1.0 m.

386

387 The calibration runs were carried out on a Windows machine (Intel(R) Xeon(R) CPU E-2699 v4 @ 2.20 GHz, 64.0
 388 GB RAM, 44 cores with 12 agents running in parallel). Each HGS instance was also distributed across two cores.
 389 Despite the simplifications and calibration challenges, parameters from all three “domains” could be calibrated, and
 390 the value of the multi-component OF was reduced somewhat, indicating modest success. Two runs were then made
 391 using the optimized model: i) the full four-year period was simulated with daily forcing, and ii) the final two-year
 392 period was simulated with hourly forcing. The latter enabled the impact of forcing frequency on simulated
 393 hydrological responses to be further assessed.

394

395 2.4. Systematically simplifying the reference model

396 A series of sensitivity experiments were then undertaken to investigate the impacts of making various structural and
 397 process simplifications or assumptions on key model predictions. In each case, simulated streamflow and
 398 groundwater levels were compared to those generated by the reasonably calibrated full complexity model forced
 399 with daily data (the reference model). In this sense, the reference model parameters should simply be considered
 400 reasonable values that can be applied in conjunction with changed structures. The modified model elements are
 401 listed below; all other aspects remained as per the reference model. No re-calibration of these simplified models was
 402 undertaken because this could have allowed parameters to take on surrogate values to compensate for flawed model
 403 structures. In other words, we sought to isolate the influences of the selected model structural and process
 404 assumptions (see also Wen et al., 2021). We could have addressed the alternative question of *how does optimal*
 405 *model performance and/or how do parameter values change as a function of simplification?* by re-calibrating each
 406 of the simplified models, but that was not the intention here.

407

408 *Impermeable subsurface, no ET (Scenario A):* This extreme end-member scenario simply assumes that the
 409 subsurface is entirely impermeable (i.e. no infiltration or groundwater processes can occur), and additionally that no
 410 water is returned to the atmosphere via *ET*. As such, all liquid water incident at the surface (i.e. rainfall + snowmelt
 411 + ice melt) flows directly overland according to the discretized topography and surface parameters.

412

413 *Limited vertical extent (Scenario B):* This scenario involves limiting the vertical extent (or “watershed thickness”) of
 414 the reference integrated model (with *ET*) to a uniform of 30 m. All elements with centroids beneath this depth were
 415 deactivated, which is equivalent to applying a “no flow” boundary condition at 30 m depth. Whilst such shallow
 416 model configurations are fairly common in both catchment and larger scale modelling studies (e.g. Foster &
 417 Maxwell, 2019), a need has been identified to further elucidate the consequences of such choices in terms of
 418 simulated hydrological dynamics (Condon et al., 2020).

419

420 *Spatially uniform forcing (Scenario C):* Catchment-scale integrated models are sometimes forced with spatially
 421 uniform meteorological boundary conditions (e.g. Ala-aho et al., 2017). Where distributed meteorological/snowmelt
 422 data are unavailable, measurements made at a single station within or near a given study catchment might be
 423 considered representative of conditions across it. Alternatively, depending on its size, an entire individual catchment
 424 may correspond to only a single pixel of a given historical reanalysis product or climate model projection. This
 425 uniform assumption is likely to be reasonable in very small and/or fairly flat catchments, but is likely to be less
 426 appropriate in larger and more topographically complex mountain headwaters. Thus, for this scenario, the
 427 distributed (25 m resolution) daily forcings of the reference model were averaged across the Vallon de Nant sub-
 428 catchments. (Note this was only done for the Vallon de Nant).

429

430 *Near-surface geology from global maps (Scenario D):* Several very coarse resolution, continental- to global-scale
 431 integrated modelling efforts have applied global hydrogeological maps to define subsurface hydraulic properties (de
 432 Graaf et al., 2019; Reinecke et al., 2019). Whilst it is becoming increasingly clear that predictions made in this way
 433 are often severely limited with respect to local and perhaps even regional observations (Reinecke et al., 2020), the
 434 role of the subsurface representation itself has not yet been isolated, especially in mountainous terrain. We therefore

435 substituted subsurface information from the GLHYHMPS 2.0 (Huscroft et al., 2018) dataset into our otherwise
436 detailed and high resolution model.

437
438 Specifically, we used this dataset to define hydraulic conductivities and effective porosities in the uppermost 10 m.
439 To parameterize deeper elements/layers, previous larger scale studies using such datasets have typically employed
440 an exponential decline in conductivity with depth whose rate is dependent upon the surface slope (Fan et al., 2013).
441 However, as the parameters of this empirical function are highly scale-dependent, they cannot be directly transferred
442 to the present, high-resolution model. To mimic the decline in conductivity traditionally imposed nevertheless, the
443 conductivities of all elements below the uppermost 10 m were set to half their near-surface values. As such, under
444 this scenario, the detailed 3D structures of the reference model were entirely removed.

445
446 *No permafrost (Scenario E)*: A “no permafrost” simulation was undertaken in which the coupling length parameter
447 in permafrost areas was set back (from 50 m) to the value of 0.1 m assigned elsewhere.

448 **3. Results**

449 3.1. Full complexity integrated model

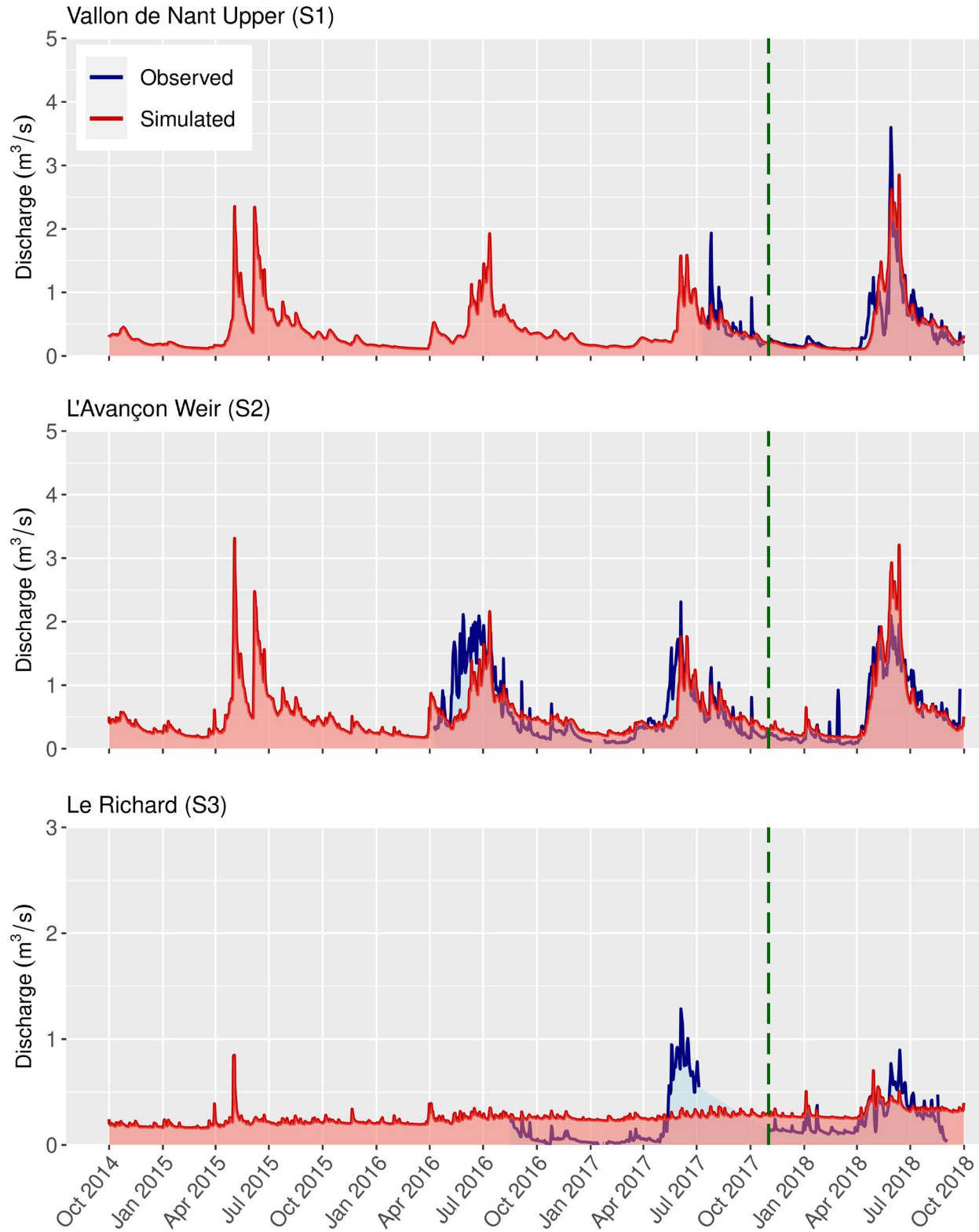
450 3.1.1. Daily forcing data

451 Figures 3 and 4 show streamflow and groundwater level time-series simulated by the calibrated, “full complexity”
452 integrated model using daily forcing data against the corresponding observations. The annual water balance
453 dynamics of the areas contributing to S1 and S2 seems to have been well captured, although the onset of high spring
454 flows does sometimes appear delayed, most notably at S2 during spring 2016. While baseflow levels are replicated
455 very closely at S1, they appear slightly overestimated at S2. It should be remembered, however, that even at the
456 concrete weir of S2, low flow measurements (which are really only estimates) can be associated with considerable
457 uncertainty due to shifting channel configurations immediately upstream, the relative effects of which are greater
458 than at higher flows. At the principal gauging station (S2), the Nash-Sutcliffe Efficiency (NSE) obtained over the
459 evaluation period (November 2017 – September 2018 inclusive) was 0.76 (see Table 1). At S3, the fit is noticeably
460 poorer; this is discussed further shortly.

461
462 The observed groundwater levels (Figure 4) at N3 and N4 especially also demonstrate strong seasonality, with
463 pronounced snowmelt-driven peaks being followed more gradual recessions at each site. Importantly, although the
464 four sites are situated fairly close to one another, their respective observed dynamics are quite contrasting. In
465 comparison, the simulated groundwater level dynamics across the four sites are too consistent or similar. More
466 specifically, whilst the general observed seasonality is represented in the simulations at all sites, the distinctive
467 signals at N2 and to a lesser extent N1 could not be reproduced well. At N4, the groundwater level trends, if not the
468 precise levels themselves, are generally satisfactorily captured. At N3, the simulated head is above the land surface,
469 which corresponds to exfiltration (also discussed in due course). Despite these differences, Figure S7 suggests that
470 overall, water table elevations across the alluvial fan zone were approximated reasonably well by the model.

471

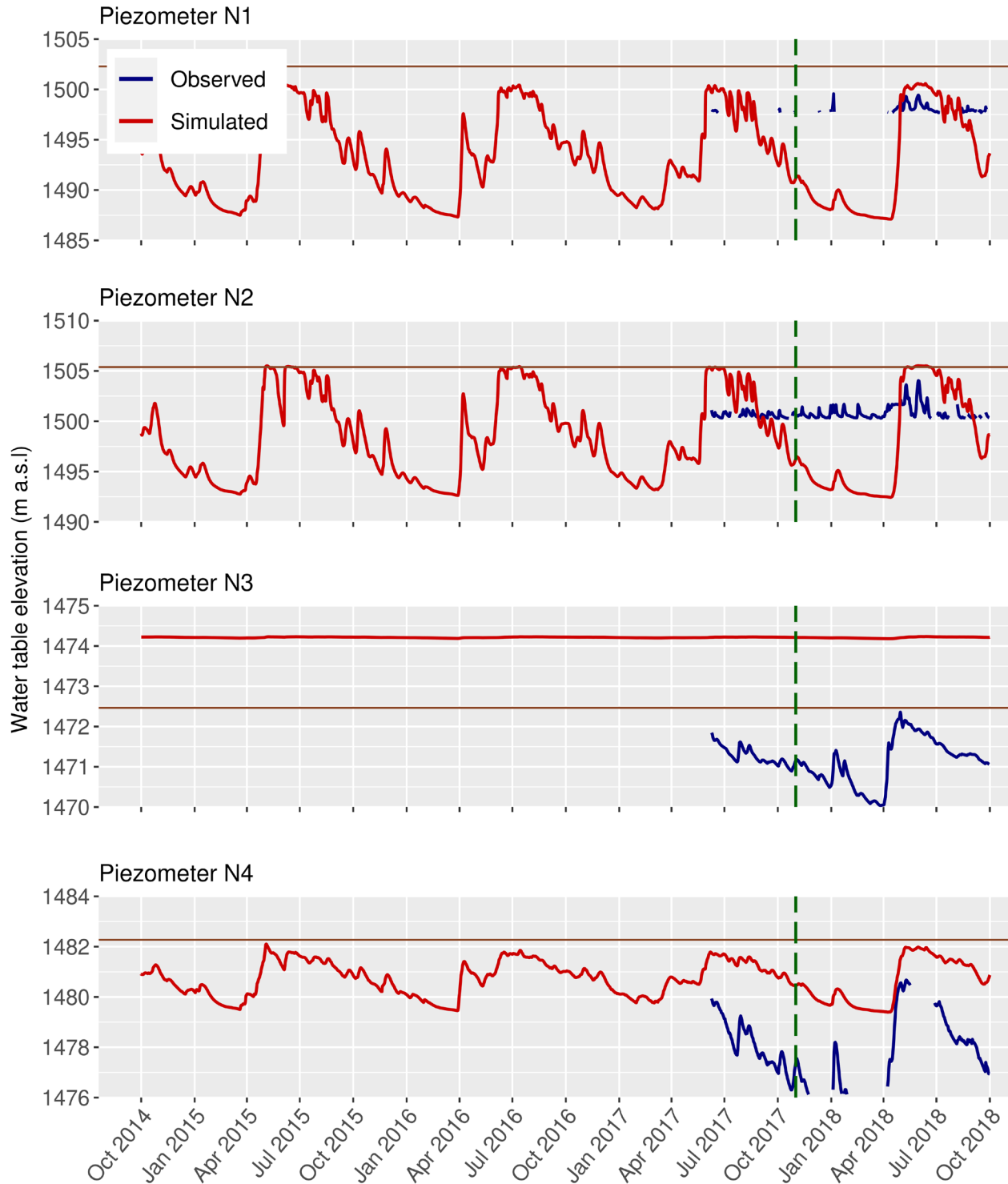
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Figure 3. Streamflows simulated by the fully-integrated model using daily 25 m resolution forcing data at the three gauging station locations and daily mean observations for the period 1 October 2014 – 1 October 2018. The dashed green line distinguishes the calibration (left) and evaluation (right) periods.

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Figure 4. Groundwater levels at the four piezometer locations simulated by the fully-integrated model using daily 25 m resolution forcing data and daily mean observations for the period 1 October 2014 – 1 October 2018. The horizontal brown line corresponds to the surface elevation. The dashed green line distinguishes the calibration (left)

485 and evaluation (right) periods. Gaps in observations occur when groundwater levels fell below the bases of the
486 shallow piezometers.

487
488 Although the groundwater level fits are not exceptional, Figures 3 and 4 together underline the unique capabilities of
489 integrated models to yield predictions of both streamflows and groundwater levels from a single consistent
490 framework. In this sense, integrated models are clearly far more suited than traditional surface water models to
491 simulate groundwater levels and vice versa. In simulating such a large range of variables, where additional in situ
492 measurements exist (e.g. ET_a and/or soil moisture), further point-scale comparisons can readily be made.

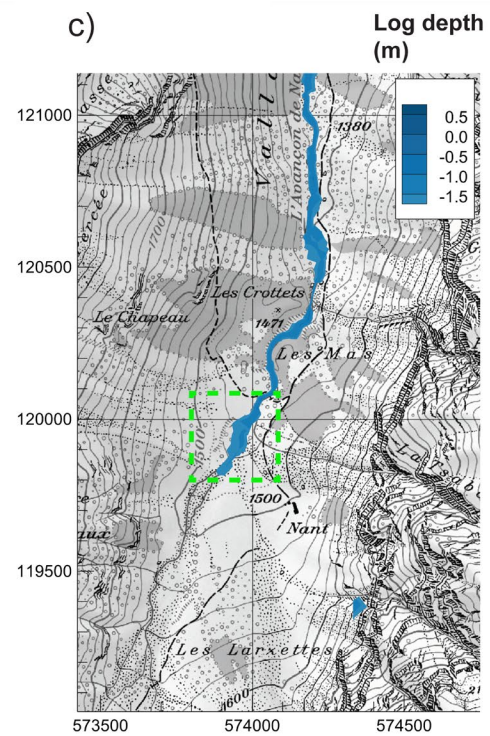
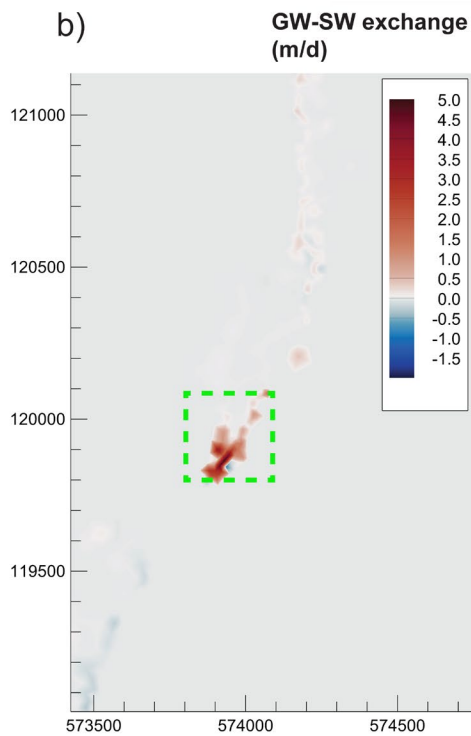
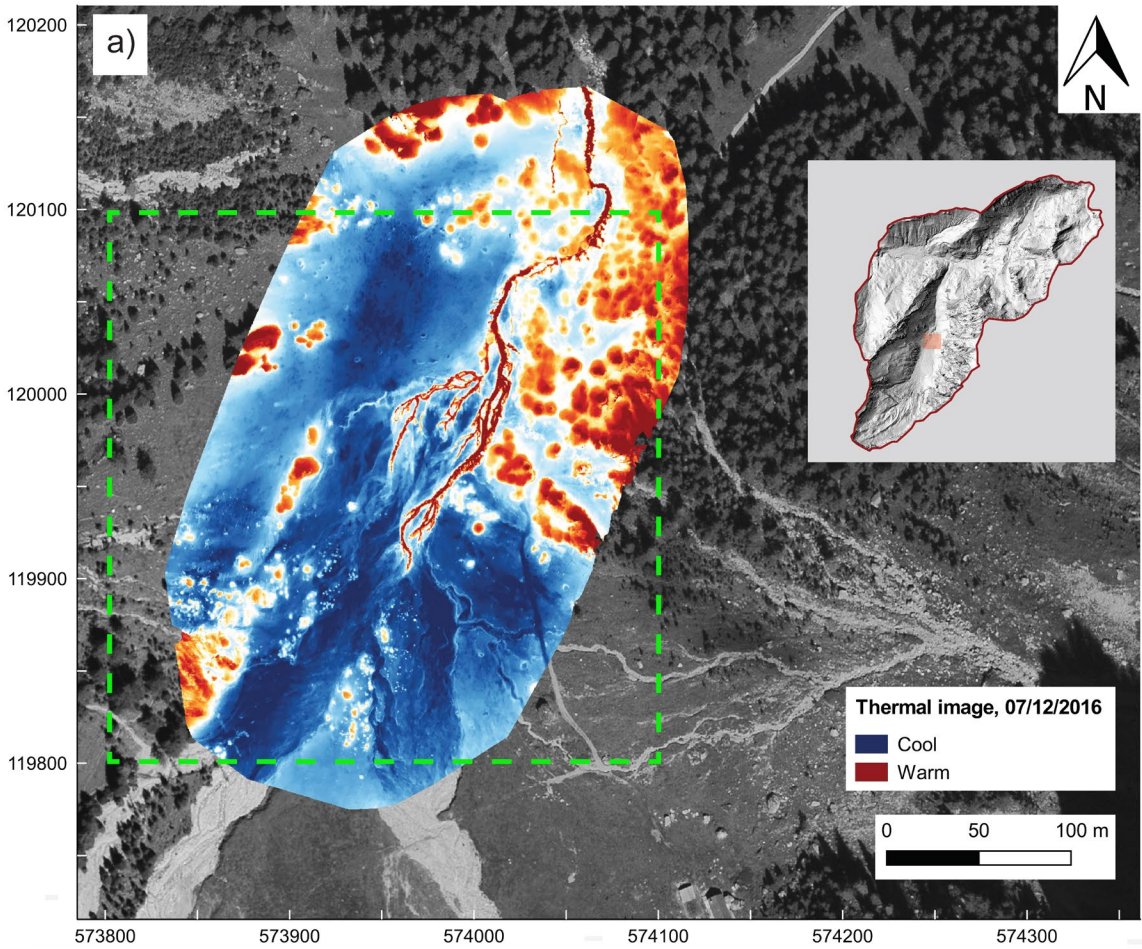
493
494 Another key advantage of comprehensive integrated models is that comparisons and diagnostics are not limited to
495 time-series or scatterplots at observation point locations. Rather, spatio-temporal patterns in forcing data and
496 numerous simulated state variables pertaining to the different “domains” (i.e. the surface, subsurface, and
497 evapotranspiration) can be visualized and/or extracted as required. Visualizing these model datasets and evaluating
498 their consistency with prior knowledge of the system enables the coherency of the numerical representation can be
499 assessed at a conceptual level. In addition, comparisons can be made with independent spatially distributed (or
500 spatially integrated datasets), either in calibration itself or simply for evaluation, further demonstrating the potential
501 of such a simulation approach. To illustrate these varied possibilities, three brief examples from the integrated model
502 forced with daily data are considered.

503
504 Firstly, Movie S1 (see Supporting Information) shows the spatio-temporal dynamics of the model’s meteorological
505 boundary conditions (“all liquid water” and potential evapotranspiration) and two important simulated response
506 variables – surface water depth and actual evapotranspiration (ET_a) – over the hydrological year 2017/2018. During
507 the initial period, dynamics are subdued as the catchment gradually drains. As snowmelt onset occurs at
508 progressively higher locations, the surface water network begins to expand. A strong elevational influence is visible
509 in both the prescribed ET_p and the simulated ET_a . Some surface water bodies do still form in parts of the Vallon de
510 Le Vare, including at the locations of a high elevation lakes/wetland (e.g. 578653, 123594).

511
512 Secondly, Movie S2 shows the interplay between simulated saturation, both at the surface and (using slices) at
513 depth, and the simulated surface water level response in the stream at S2. Throughout the snowmelt period, near-
514 surface saturation levels gradually increase, followed by the arrival of the annual simulated water level peak. These
515 patterns correspond closely with our general knowledge and understanding of the system. Movie S2 also clearly
516 shows that the water table is generally lower in the Vallon de La Vare than the Vallon de Nant, and so could indicate
517 a possible cause of the poorer performance at S3.

518
519 Finally, a thermal image of the central part of the Vallon de Nant obtained by drone early in the morning on 7
520 December 2016 is introduced. No precipitation had fallen in the preceding 10 days, and – unusually for the time of
521 year – the ground remained snow free. As such, all water in the channel could be confidently and exclusively
522 identified as emergent groundwater. As groundwater is several degrees warmer than the dry land surface under these
523 circumstances (i.e. early morning in winter), the region of groundwater exfiltration from the streambed into the
524 channel can be clearly identified (Figure 5a). A comparison can thus be made between this image and the simulated
525 spatial patterns of exchange flux and surface water presence on the same day (Figures 5b and c). Groundwater is
526 seen to emerge at approximately the same location in the model as in reality. Moreover, surface water is present
527 from this point downstream in the simulation, which is again consistent with the thermal image (in which the
528 discrete “warm” region continues northwards downstream). This demonstrates that integrated models are uniquely
529 suited to answer questions such as “where do significant volumes of groundwater exfiltration, or streamflow
530 generation, occur?”

531
532



534 **Figure 5.** Spatial patterns of (a) relative surface temperature in the distal part of the Nant alluvial fan in the early
535 morning of 7 December 2016 from which “observed” subsurface-surface exchange flux and surface water presence
536 were inferred (note that the stream appears warmer than the surroundings, and that red circular patterns correspond
537 to trees that also appear warmer because of solar illumination), (b) subsurface-surface exchange flux simulated by
538 the fully-integrated model on the same date (positive values correspond to surface water exfiltration), and (c)
539 simulated surface water presence, indicated by the simulated surface water depth, again on the same data. The
540 dashed green box indicates the common area.

541
542 Further exploiting the many possibilities that exist to extract and/or visualize data from integrated models offers a
543 viable path to developing improved understanding of complex hydrological systems. For instance, such an approach
544 may help the identification of the regards in which, or reasons for which, a given numerical representation may
545 remain deficient.

546

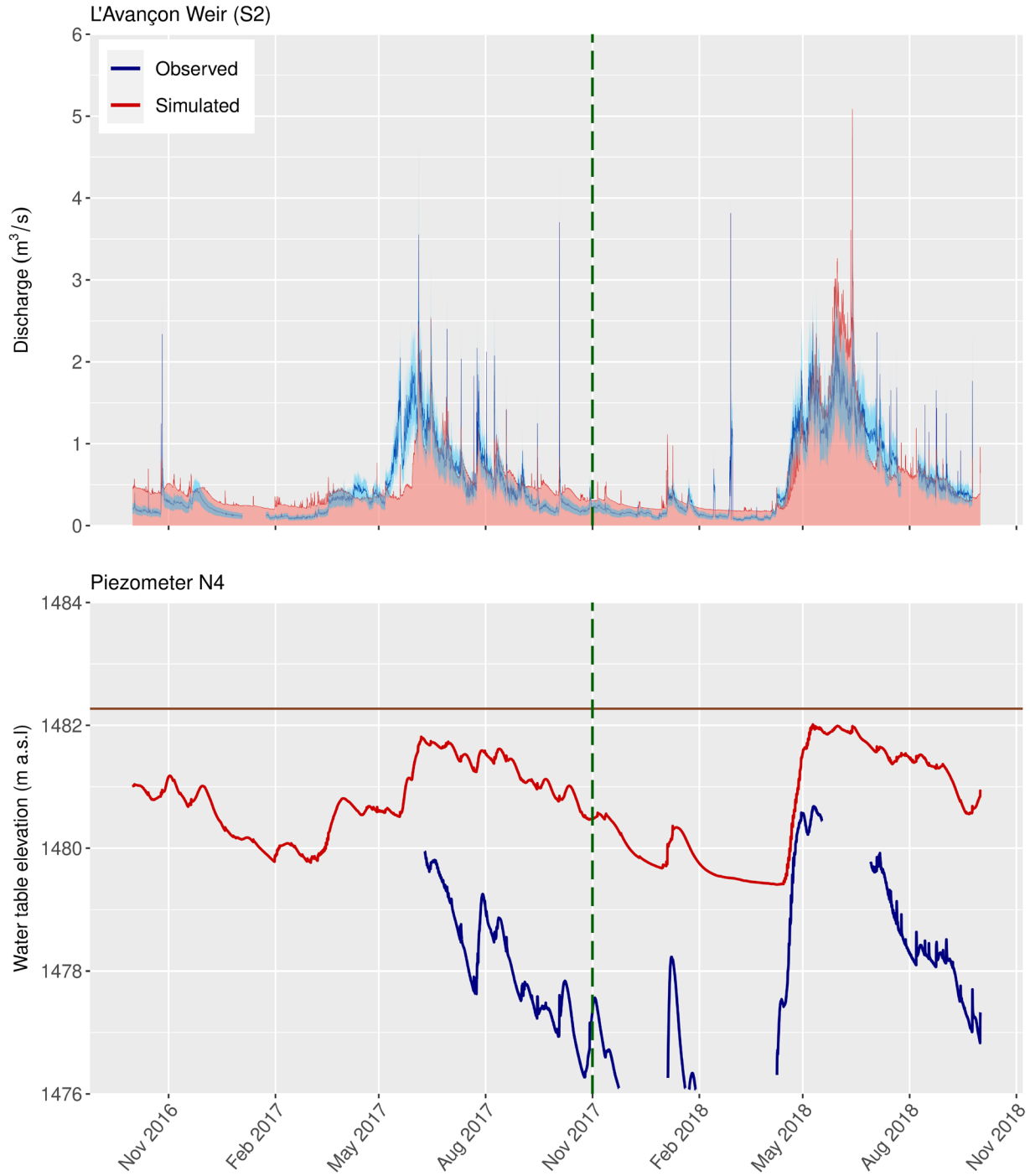
547 *3.1.2. Hourly forcing data*

548 Figure 6 presents streamflows and groundwater levels simulated by the calibrated integrated model forced with
549 hourly data at S2 and N4, respectively. In this case, the NSE coefficient attained over the evaluation period at S2,
550 0.73 (Table 1), was slightly lower than in the daily forcing case, but still denotes good performance. Sharp flow
551 peaks associated with convective thunderstorms are represented a little better than in the daily case (in which the
552 rainfall totals are distributed evenly over 24-hour periods) but remain insufficiently accentuated compared with the
553 observations. To illustrate the high frequency variability more clearly, Figure 7 focuses on a reduced period (spring
554 and summer 2018); one observes that diurnal variations in both streamflow and groundwater levels associated with
555 spring snowmelt (and potentially also ice melt and evapotranspiration) can be reproduced.

556

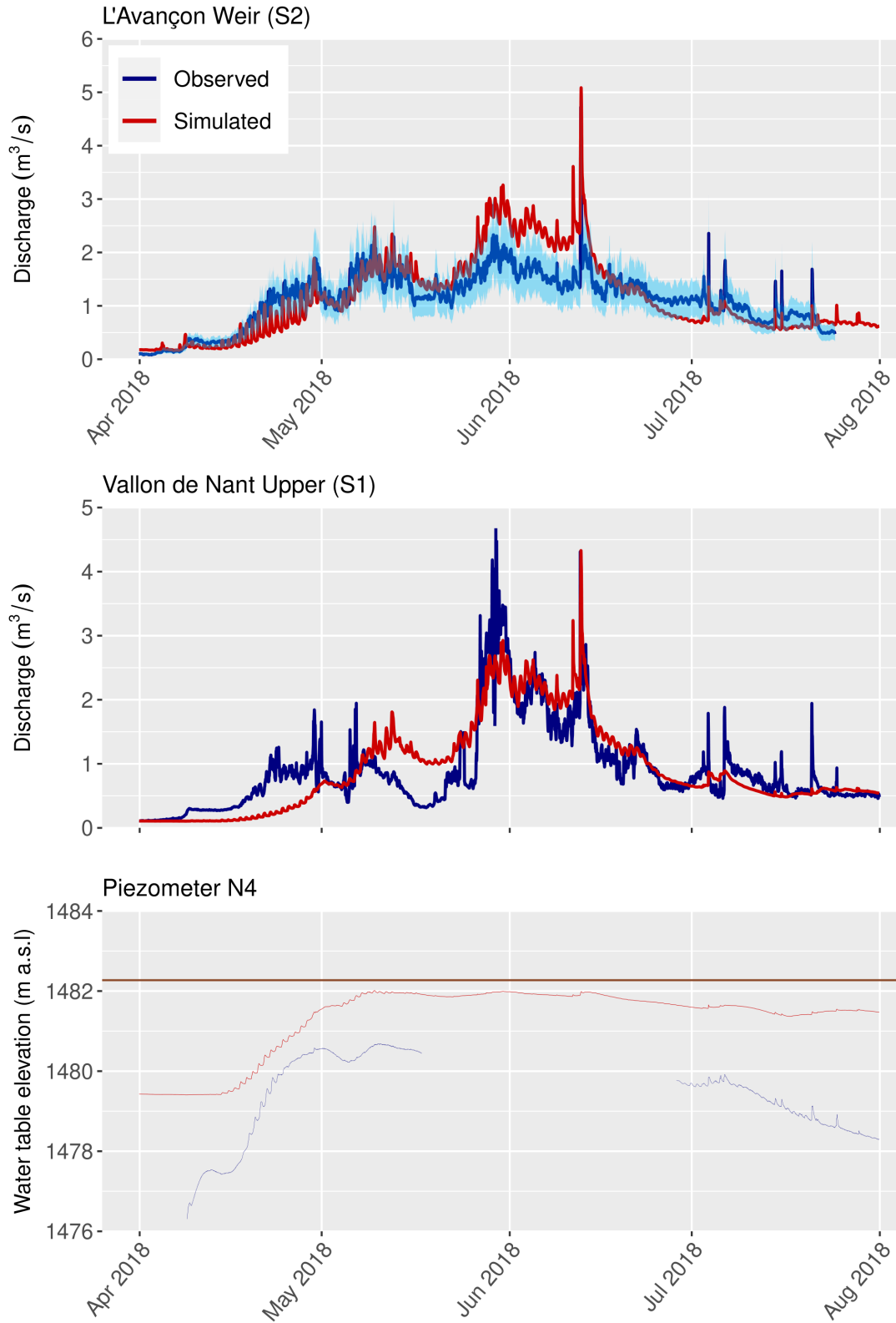
557 Figure 8 shows the catchment water balance over spring and summer 2018; this is another informative type of
558 output that can be obtained from integrated models. (In HGS, the water balance can also be obtained for spatial
559 subsets of the domain by specifying shapefile extents, but that here we look at the entire catchment). The rate of
560 incoming liquid water is seen to exceed the rate of simulated infiltration during the early melt season, causing
561 accumulation in the overland domain. With time, the rate of groundwater exfiltration also increases. Later in the
562 season, the infiltration begins to exceed that of incoming liquid water, which presumably corresponds to infiltration
563 from surface water bodies that can occur as near surface saturation levels decline from their snowmelt induced
564 peaks. Groundwater exfiltration declines a little but remains noticeable.

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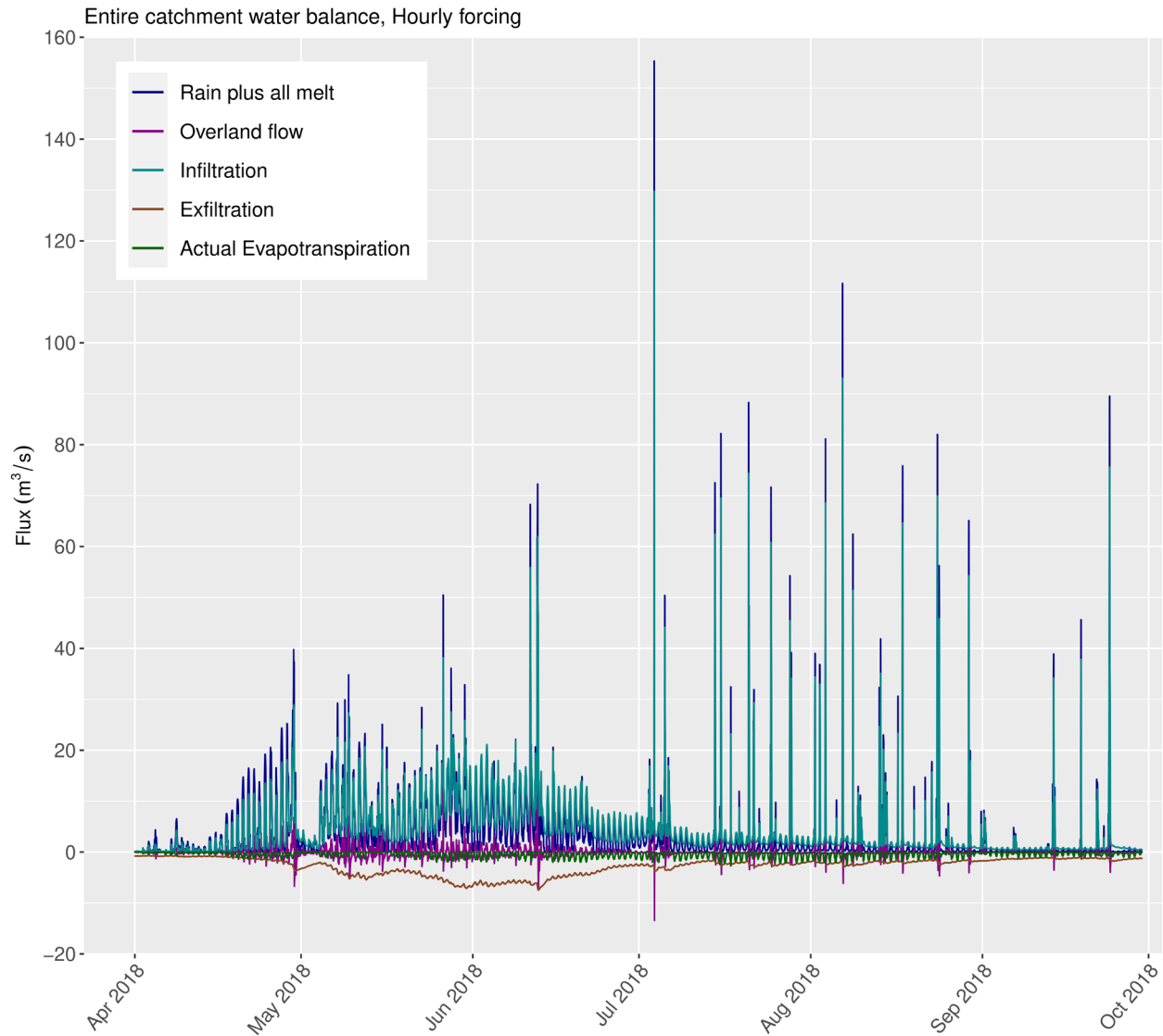
Figure 6. Streamflow and groundwater levels at S2 and N4, respectively, simulated by the fully-integrated model using hourly 25 m resolution forcing data and hourly mean observations for the period 1 October 2016 – 1 October 2018. The light blue are in the upper pane reflects a potential uncertainly range of +/- 30% around the observations, whilst the pink shading beneath the simulated line in shown simply to enable the two time-series to be compared more easily.



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Figure 7. Streamflow and groundwater levels simulated by the fully-integrated model using hourly 25 m resolution forcing at S2, S1, and N4, respectively, and hourly mean observations for the period 1 October 2016 – 1 October 2018.

579



580

581

582 **Figure 8.** Catchment-scale water balance simulated by the fully-integrated model using hourly 25 m resolution
 583 forcing for the period 1 April – 30 October 2018. Note that the “overland flow” line represents that the rate of fluid
 584 accumulation in the overland domain.

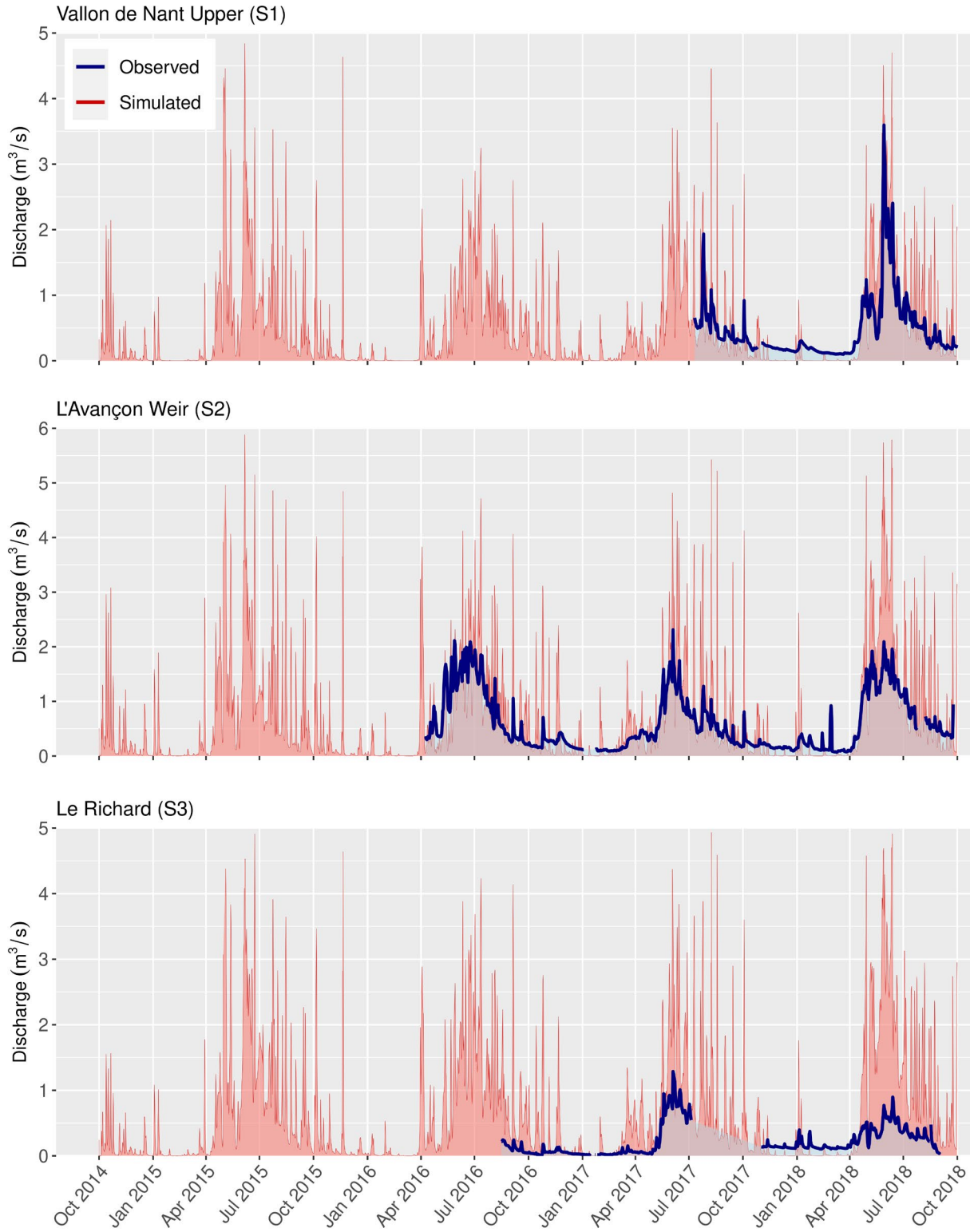
585

586 3.2. Simplified models

587 3.2.1. Impermeable subsurface, no ET (Scenario A)

588 Figure 9 presents streamflows simulated under the “impermeable matrix” assumption (with *ET* also deactivated),
 589 using daily forcing data. Close correspondence between simulated and observed peak timing is observed, which
 590 provides further reassurance that the previously generated liquid water inputs (Thornton, Brauchli, et al., 2021) are
 591 reasonable. Entirely expectedly, simulated flows under this assumption are overestimated with respect to
 592 observations during high flow periods and underestimated during lower flow periods. Interestingly, the degree of
 593 overestimation is much more pronounced at S3 than S1 and S2, which clearly demonstrates that the actual runoff
 594 ratio of this geologically complex sub-catchment is considerably lower than that of the others in reality. The spatial

595 outputs from this simulation (not shown) reveal that, again unsurprising, a substantial lake forms in the topographic
 596 depression of La Varre (~576859,123516). No such lake exists in reality, although a wetland is located in this area.
 597



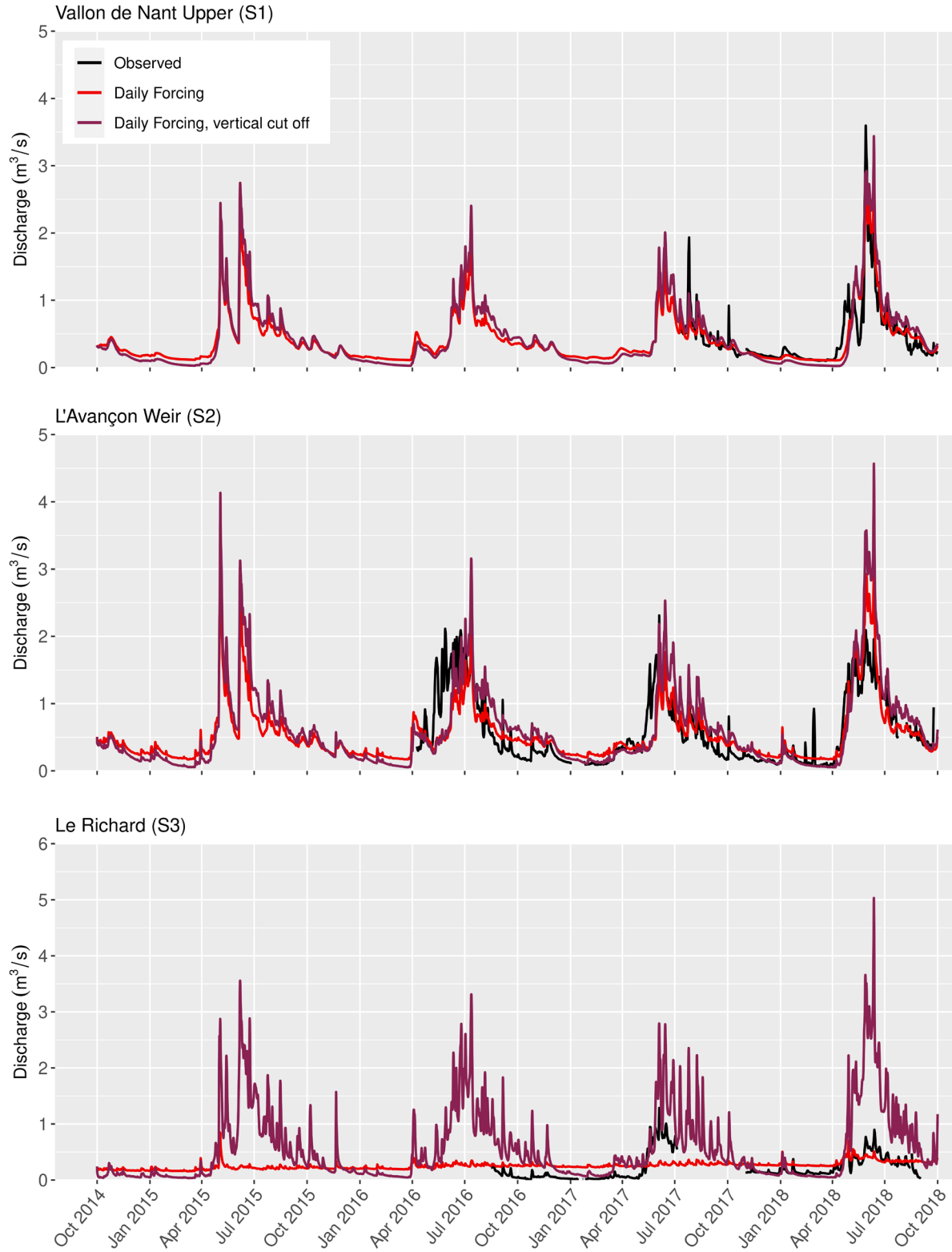
598

599 **Figure 9.** Simulated streamflow at each of the three gauging stations under the “impermeable matrix” assumption
600 (i.e. “surface only”, with infiltration, subsurface flow, and evapotranspiration (*ET*) all deactivated) using daily 25 m
601 resolution data, and daily mean observations.

602 *3.2.2. Limited vertical extent (Scenario B)*

603 Compared with the reference simulation, limiting the model’s vertical extent to 30 m accentuates peak flows
604 appreciably, reduces baseflows, and leads to more pronounced recessions (i.e. the regime becomes “flashier”; Figure
605 10). Minimum groundwater levels are lower under this scenario than in the reference case. As in Scenario A, the
606 streamflow simulations at S3 are extreme overestimations, most especially during 2018. Annual peak groundwater
607 levels in the Vallon de Nant piezometers are hardly affected, but recession rates are noticeably more rapid and
608 annual minima are lower (Figure 11). Figure S16 shows the main catchment water balance fluxes for this scenario
609 with respect to the baseline model. One observes in particular that, as expected, both overland flow and groundwater
610 exfiltration are more pronounced under Scenario B.

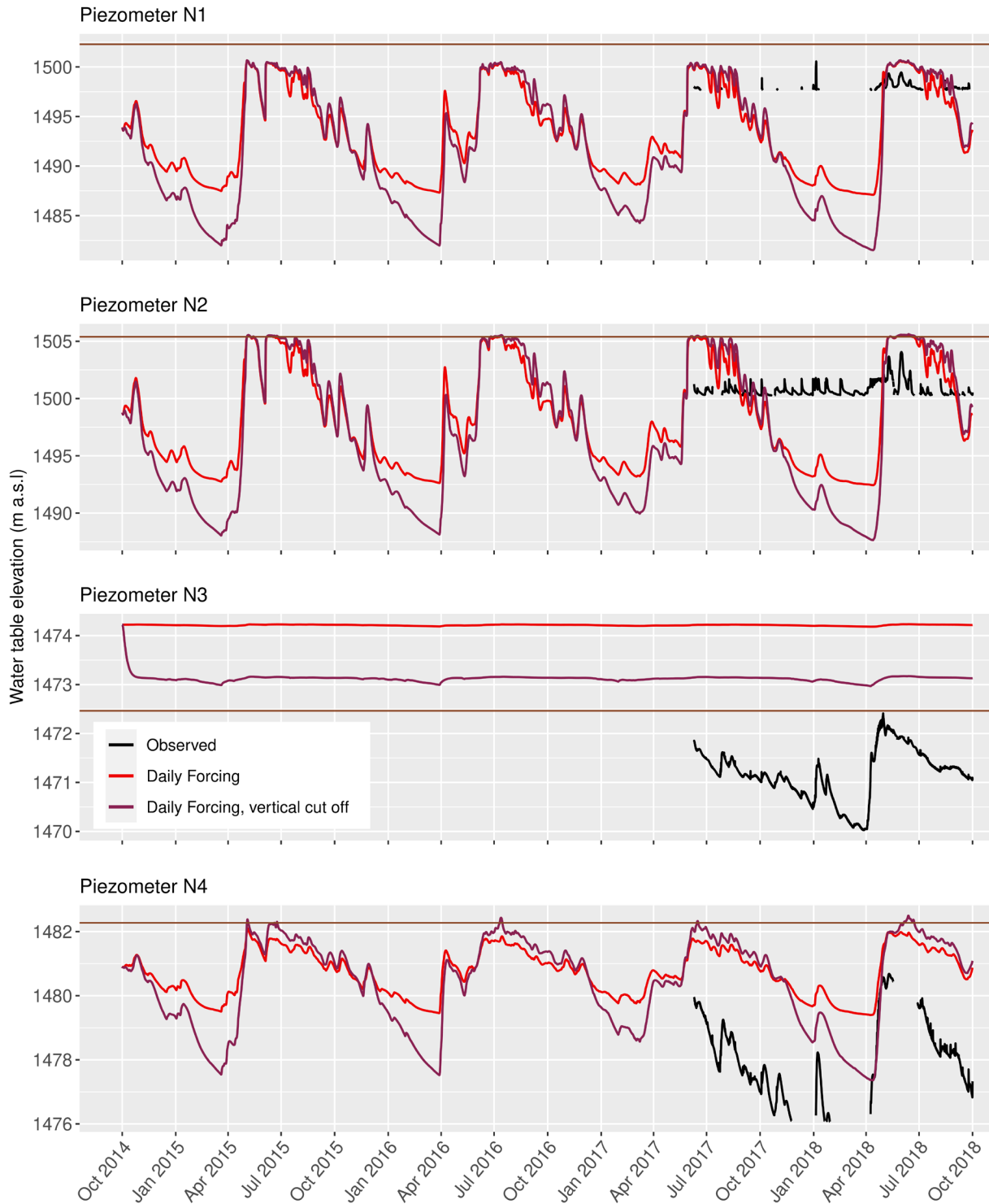
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Figure 10. Streamflows simulated with a version of the fully integrated model whose depth (i.e. vertical extent) was limited to a uniform thickness of 30 m below the surface. Daily 25 m resolution forcing data were applied, and daily mean observations are also plotted.

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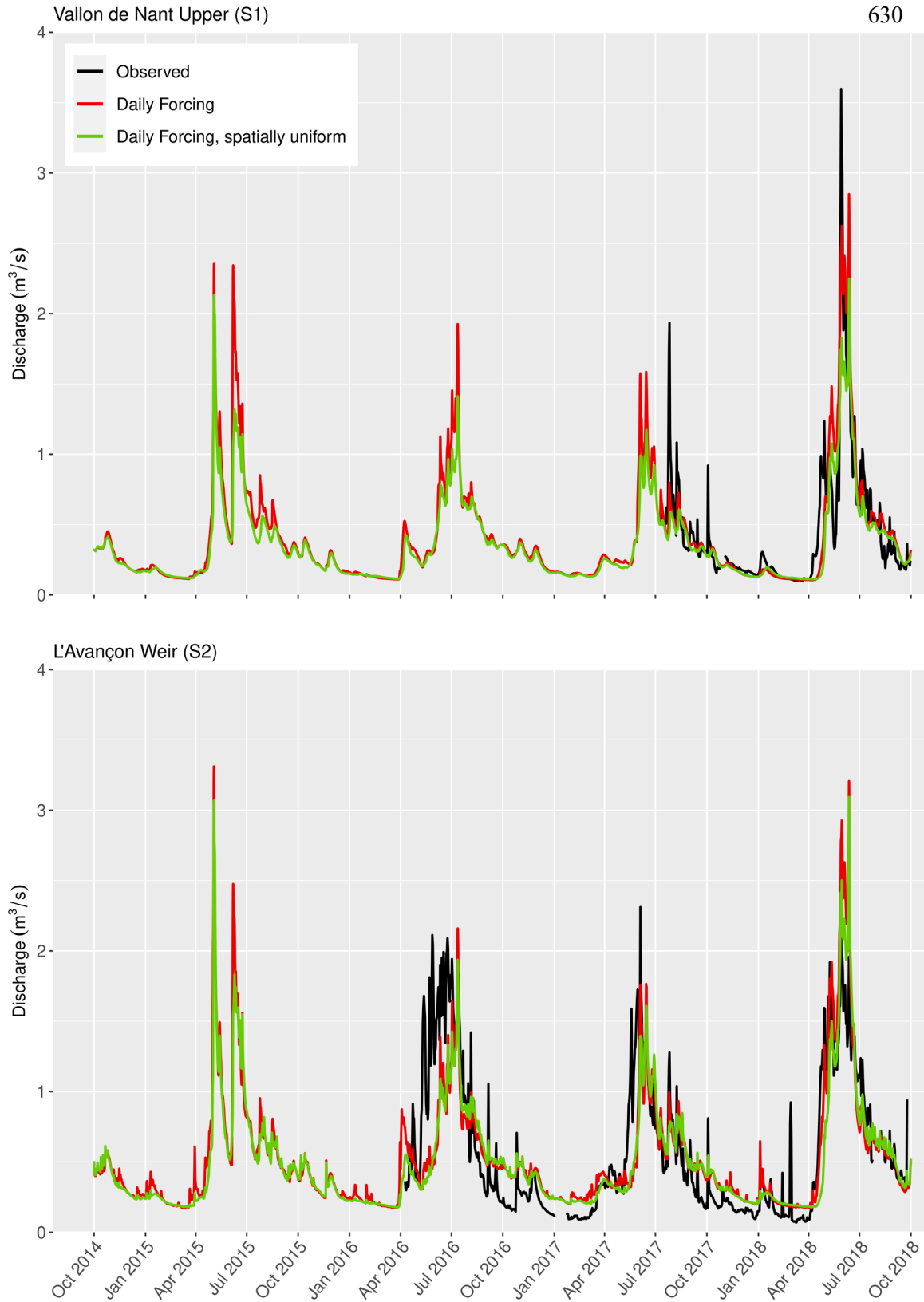


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Figure 11. Groundwater levels simulated with a version of the fully integrated model whose depth (i.e. vertical extent) is limited to a uniform thickness of 30 m below the surface. Daily 25 m resolution forcing data were applied, and daily mean observations are also plotted.

624 3.2.3. *Spatially-uniform forcing (Scenario C)*

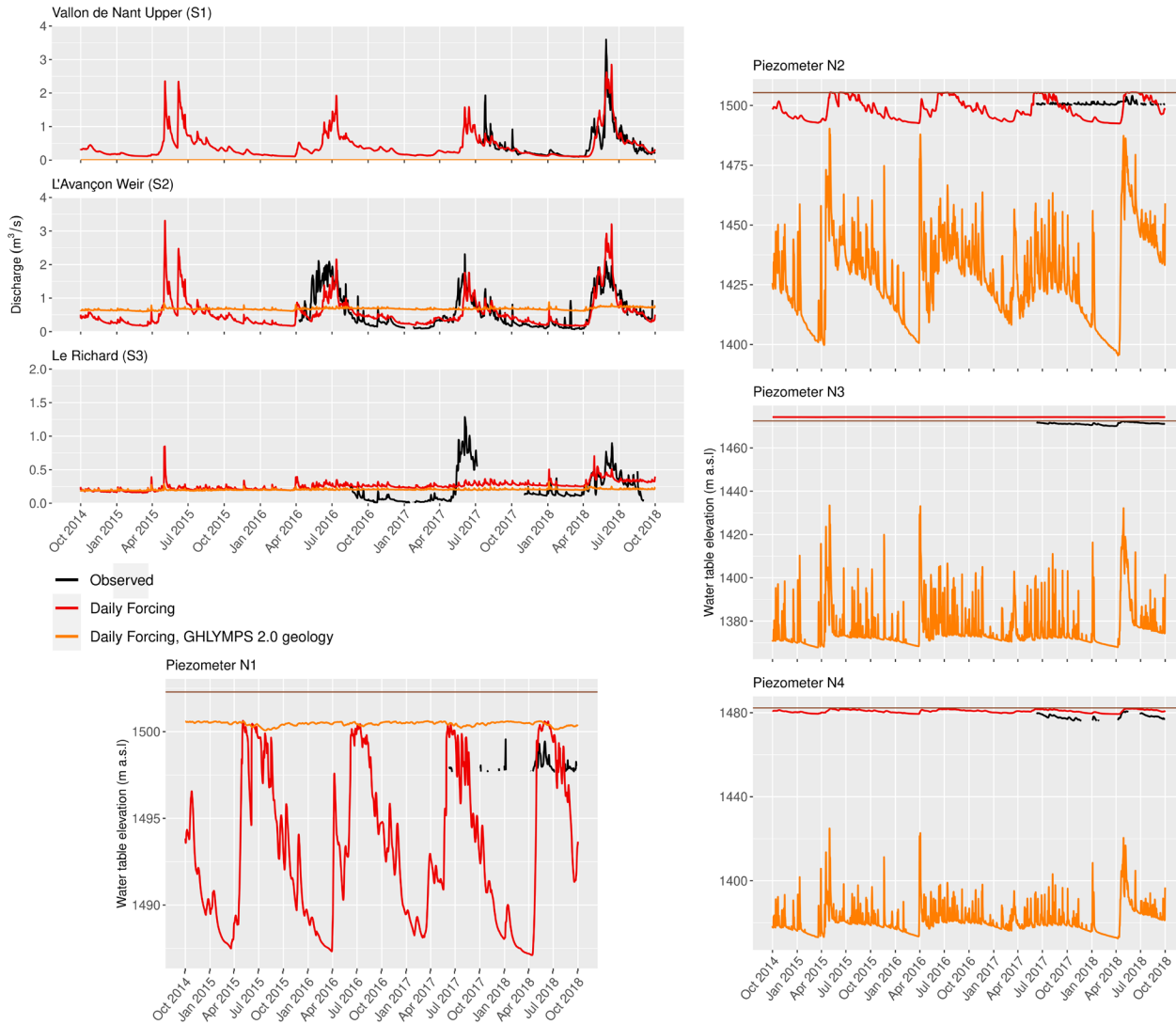
625 Applying spatially uniform forcing data across the Vallon de Nant sub-catchment produces noticeably lower spring
 626 peaks, especially at the higher elevation site (S1; Figure 12), compared with the reference model (see also Table 1).
 627 The impact on groundwater levels is both more modest and less variable over the annual cycle, and is therefore not
 628 shown.
 629



631 **Figure 12.** Comparison of simulated streamflows generated using 25 m resolution spatially distributed forcing data
 632 and spatially uniform (i.e. sub-catchment-averaged) forcing data. In both cases, the frequency was daily.
 633

634 3.2.4. *Geology from global maps (Scenario D)*
 635

636 Figure 13 illustrates the simulations that result from using the GHLYMPS 2.0 map to define 2D near surface
 637 porosity and hydraulic conductivity values, with conductivities decreased by a factor of two for all elements with
 638 centroids greater than 10 m beneath the surface.
 639



640 **Figure 13.** Comparisons between simulated streamflows at groundwater levels at S2 and N4 generated from the full
 641 complexity reference model and the model whose key subsurface parameters were derived from GLHYMPS 2.0. In
 642 both cases, the forcing data was of daily frequency.
 643
 644

645 In this case, the simulations bear little resemblance to either the observations, with seasonal streamflow and
 646 groundwater level dynamics being far too subdued and groundwater levels generally too low, leading to no
 647 streamflow whatsoever being simulated at S1.
 648
 649

650 3.2.5. No permafrost (Scenario E)

651 Compared with the reference model, the final simplification – “no permafrost” – led no discernible visual or
 652 statistical differences with the reference model at the various observation points. As such, no plots are presented
 653 here. An additional “end member” simulation (also not shown) in which the coupling length parameter was set to the
 654 “permafrost value” of 50 m across the entire catchment produced only relatively minor differences with the
 655 reference simulation.

657 3.2.5. Statistical comparison of the scenarios

658 Table 1 presents a statistical comparison of the various scenarios against observations.

	S1 (NSE)		S2 (NSE)		S3 (NSE)		N1 (SE)		N2 (SE)		N3 (SE)		N4 (SE)	
	EP	EV	EP	EV	EP	EV	EP	EV	EP	EV	EP	EV	EP	EV
Full complexity integrated model (daily forcing) vs. daily observations	0.32	0.36	0.62	0.76	0.10	0.30	4.39	4.45	5.23	5.91	3.08	3.14	3.00	2.83
Full complexity integrated model (hourly forcing) vs. hourly observations	0.30	0.34	0.60	0.73	0.09	0.25	3.96	4.04	5.24	5.93	3.08	3.13	3.02	2.85
Scenario A (daily forcing) vs. daily observations	-0.46	N/A	-1.30	N/A	-15.73	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
Scenario B (daily forcing) vs. daily observations	0.28	N/A	0.35	N/A	-8.03	N/A	5.72	N/A	7.24	N/A	2.00	N/A	3.13	N/A
Scenario C (daily forcing) vs. daily observations	0.25	N/A	0.61	N/A	N/A	N/A	4.59	N/A	5.04	N/A	3.09	N/A	2.95	N/A
Scenario D (daily forcing) vs. daily observations	-0.93	N/A	0.02	N/A	0.02	N/A	2.34	N/A	75.16	N/A	94.15	N/A	94.59	N/A
Scenario E (daily forcing) vs. daily observations	0.32	N/A	0.62	N/A	0.10	N/A	4.40	N/A	5.24	N/A	3.08	N/A	2.99	N/A

660
 661 Table 1. Statistical comparison of correspondence between simulations and observations for the various model
 662 scenarios. The Nash Sutcliffe Efficiency (NSE) is used to compare the model fits for streamflow, whilst the standard
 663 error (SE) is used for groundwater levels. “EP” denotes “entire period”, whilst “EV” denotes “evaluation period
 664 only”. Because the simplified versions were not calibrated, it does not make sense to consider the results only over
 665 the evaluation period. In addition, when interpreting these results across sites for a given scenario, it should be
 666 remembered that the number and temporal coverage of observations differ.

667

668 The streamflow performance metrics of the (uncalibrated) simplified models are universally lower than those of
669 their full complexity (calibrated) counterparts. This is generally also the case for the groundwater levels, and the
670 exceptions (Scenario C at N2, Scenario B at N3, and Scenario C and N4) could simply be down to chance. Whilst
671 the fit scores of the simplified models with respect to both streamflow and groundwater levels could probably have
672 been improved somewhat via calibration, because the model structures employed in these scenarios are either
673 obviously (Scenarios A and C) or very likely (Scenarios B and D) unrealistic in such terrain, parameter values would
674 likely have had to take on implausible values or surrogate roles to achieve this; a situation that would inevitably
675 have adverse consequences for any subsequent predictions. The fits are worst for Scenario D. Overall, these results
676 can be taken to demonstrate the relative value of the full complexity reference model.

677 **4. Discussion**

678 4.1. Assessing the historical time-series simulated by the full complexity model

679 In light of the study region's characteristics, in the initial phase of model development, we sought to establish a
680 forcing configuration and model structure that was as comprehensive and constrained as possible. Specifically, all
681 the processes and components omitted in the early synthetic study of Gleeson and Manning (2008) – that is,
682 “evapotranspiration, the role of the orographic effects on precipitation, the seasonal effects of snow accumulation
683 and melting, ...transient conditions, such as perched ground-water conditions...[and] the role of alpine glaciers or
684 permeable surficial geology units” – were incorporated. Parameterization and calibration were then conducted
685 “given” this preferred structure.

686
687 Each of the main phases, from obtaining the extensive data necessary to build the model, ensuring its smooth and
688 sufficiently fast execution, and finally calibrating it such that the available observations could be reproduced with
689 some skill, were challenging. In addition, because it is possible to constrain the parameters of integrated models to
690 physically plausible values (as was done here), it is to be expected that the levels of fit attainable are often lower
691 than those that can be achieved with simpler, more data-driven alternatives (Mendoza et al., 2015) in which these
692 constraints are less strong or entirely lacking. More generally, since simulating mountain hydrological systems using
693 integrated models remains an emerging discipline, we argue that statistical benchmark levels of fit (corresponding to
694 “good”, “acceptable”, “poor”, etc.) remain to be established for different variables and different types of physical
695 setting. Catchment size also likely influences expected performance levels. For instance, simulating streamflow
696 presence, absence, and level using integrated models in relatively small and steep alpine headwaters is more
697 challenging than in larger catchments. This is because in larger catchment, variability is more “smoothed out”. In
698 other words, outputs would be expected to demonstrate far less sensitivity to small scale (changes in) model
699 structure and parameterisation.

700
701 Accordingly, it is satisfying that using the daily forcing data, observed streamflow dynamics at S1 and S2 were
702 generally reproduced acceptably (Figure 3). The improved correspondence between observations and simulations
703 over the evaluation period compared with the calibration period may seem slightly counterintuitive, but could
704 simply be explained by the forcing data having been better estimated over this period (e.g. due to more
705 complete/local input data being available) (Thornton et al., 2021). Another interesting feature of Figure 3, providing
706 it is not a reflection of bias in the observations, is that baseflows appear to be overestimated more at S2 than S1.
707 This could indicate some issue or scope for improvement in the geometries and/or parameterizations of zones
708 (surface or subsurface) that influence flow exclusively (or proportionally more) downstream of S1.

709
710 The lower fit at S3 is likely due to the great geological complexity of this sub-catchment, on which data remains
711 lacking, being insufficiently represented in the model. In reality, the high, topographically closed basin of La Varre,
712 which is naturally dammed to a height of around 20 m, must drain through the subsurface. This is because no lake is
713 present in the depression in reality, but merely a wetland (576859,123516). It is possible that, in attempting to

714 prevent a lake forming here in our model, we set the initial effective hydraulic conductivities in this region were too
715 high, which led to an unduly low water table across much of the Vallon de La Vare sub-catchment. Such a water
716 table state naturally favors infiltration and recharge at the expense of more rapid surface and shallow subsurface
717 runoff, ultimately leading to an overly stable hydrograph. In other words, it seems that the model was unable to
718 capture these both aspects (no deep lake but still a rather flashy streamflow response) in a single conceptualization.
719 The problem is therefore likely a structural one. In fact, La Varre is believed to drain via a discrete fracture that
720 bypasses several otherwise impermeable formations, as well as potentially the site of S3 (Lugeon & Gagnebin,
721 1928). To represent flows through such fractures or karstic conduits, it would probably be necessary to superimpose
722 discrete fractures or conduits on the porous media domain. Whilst this is theoretically possible in HGS, obtaining
723 data to locate and parameterize these features is difficult in remote Alpine settings.

724
725 Another possible (or perhaps partial) explanation is simpler. At S3, observed flow levels are much lower in 2018
726 than 2017. However, the opposite situation occurs at S1 and S2, and winter 2017/2018 was known to be remarkably
727 snow rich more generally. Given that these catchments are adjacent, there could simply be a hitherto undiagnosed
728 issue in the calibration period measurements at S3 (simply measuring streamflow reliably in such settings is often
729 difficult). Of course, it would be undesirable for model calibration to compensate for, and thereby “hide”, and such
730 possible structural or data issues, meaning the mismatch could be less concerning than it may initially appear.

731
732 The nature and practical implementation of the inversion algorithm could represent additional limiting factors. It is
733 possible that the solution to the inverse problem (i.e. the calibration) reached a local minimum, and/or that the
734 bounds imposed on the effective parameter values of subsurface formations in the Vallon de La Vare region were
735 too restrictive. It is furthermore conceivable that even if improved within-bound parameter values (i.e. those which
736 would ordinarily have produced a more rapid streamflow response and hence a better match at S3) were proposed by
737 PEST, the 18-month re-initialization period simulated prior to each calibration run may have been too short to allow
738 the internal storages to fully re-equilibrate with the adjusted parameters. Ideally, a longer re-initialization period
739 would have followed every change in parameter values, strictly continuing until a (close to) perfect “dynamic steady
740 state” was re-established. However, given the model’s runtimes (which, incidentally, also depend on the parameter
741 values), such an approach would have precluded automated calibration altogether in this case. The interplay between
742 initial conditions, parameter updates, and re-equilibration within automated optimization frameworks have received
743 very little attention in the integrated modelling literature to date, and should be investigated more thoroughly. The
744 availability of longer time-series could also have led to a more reliable calibration, but would again have increased
745 the computational load. In any case, longer timeseries could not be obtained within the scope of this project, which
746 followed a concurrent “measure and model” philosophy. In summary, some combination of deficient model
747 structure, limitations associated with the parameter estimation approach, and relatively short and perhaps even
748 uncertain observations could explain the difficulties the full complexity model has to reproduce the observations at
749 S3. Nevertheless, as is discussed shortly, these results are still far superior to those generated in the simplified cases,
750 which underlines the challenging nature of this sub-catchment.

751
752 Of the four groundwater observation points, N4 can probably be considered the most spatially representative, since
753 it is located closest to the main gravelly part of the alluvial aquifer. It is therefore reassuring that the simulated
754 dynamics at N4 generally correspond with observations, even if the simulated level is slightly higher (Figure 4).
755 Besides the general points related to the calibration discussed above, the influence of local-scale heterogeneity in
756 hydraulic properties is probably the main reason why the agreement between simulated and observed groundwater
757 levels is relatively limited. Whilst all the piezometers are located nearby one another (and moreover in only a small
758 part of the entire model domain), as highlighted already, the observed signals at each are rather contrasting. The
759 flashy response of groundwater above a constant lower level at S2, for instance, probably arises because the
760 piezometer samples a former stream channel comprised of coarse sediments with a relatively impermeable
761 underlying clay-rich layer. Crucially, since all the piezometers are situated within a single model zone (the “Nant”
762 alluvial fan system), to which homogenous material properties were assigned, it is unsurprising that the contrasting

763 responses observed at each could not be reproduced. Indeed, as mentioned earlier, the groundwater level data were
764 deliberately de-weighted to reduce the chance of the calibration process compensating for this structural deficiency
765 at the expense of the broader coherence of the model. Improving these fits would require the introduction of sub-
766 zone heterogeneity. One way to achieve this could be using the Iterative Ensemble Smoother (IES) method of White
767 (2018), which theoretically enables a very large number of parameters to be estimated (e.g. hydraulic conductivity
768 per element) with relatively few model runs. Additional fine-scale heterogeneity may not substantially affect
769 simulated catchment-scale dynamics, however.

770
771 At N3, groundwater levels are overestimated by approximately 3 m, which places the simulated level above the land
772 surface. However, N3 is extremely near the significant zone of exfiltration shown in Figure 5, so lack of small scale
773 topographic or subsurface feature representation could be responsible for the difference. The general overestimation
774 of the groundwater levels in this zone also explains why the zone of exfiltration occurs at a slightly higher elevation
775 in the model than in reality (Figure 5).

776
777 Whilst using extremely highly resolved (hourly) forcing data, which is rarely done with integrated models, brings
778 some benefits in terms of reproducing diurnal fluctuations and sharp streamflow peaks (Figures 6 and 7), the overall
779 performance metrics are slightly lower than in the daily forcing case. This is presumably because the model was
780 calibrated at a highly contrasting frequency (monthly). Had the simplified Scenario A simulation not been
781 conducted, one could have hypothesized that the underestimation of sharp peaks by the hourly model could be due
782 either to intense localized convective rainfall events having been “missed” by the gauge network from which the
783 forcing datasets were generated, or the geometries of the many small torrents that are able to rapidly transmit rainfall
784 and snowmelt to the main channel not having been represented sufficiently in the mesh (cf. Ala-aho et al., 2017).
785 However, the fact that streamflow peak timing is reproduced even with only daily forcing under Scenario A (Figure
786 9) largely eliminates these possibilities; this is an example of the insights that employing complex and simplified
787 models in combination can yield. Instead, it would appear more likely that in the hourly reference model, surface
788 and near-surface permeabilities generally remain too high, and/or interception and evaporative losses are
789 overestimated (both leading to insufficient overland flow generation). Whatever the reason, Movie S1 indeed
790 suggests that small flowing torrents do not appear to form extensively enough in the model compared with field
791 experience, at least with daily forcing data. A clear limitation of the present study is that the monthly data used for
792 calibration did not contain information on these high-frequency dynamics, which prevented improved peak flow
793 matching. Resolving the topography of small torrents in even more detail could certainly have also helped, but
794 would have resulted in an even larger mesh and hence longer runtimes.

795
796 Finally, the relatively low observed and simulated water levels / discharges during baseflow periods at all sites (see
797 e.g. Figure 3 and Movie S2) suggest that even under present climatic conditions, the stream network is fairly close to
798 becoming (more) intermittent or ephemeral. Small shifts in climate and vegetation conditions could induce
799 threshold-like responses in terms of stream intermittency which would have important implications for ecosystems
800 and human societies (e.g. via reduced hydropower production) alike.

801
802 **4.2. Insights from the simplified models**

803 The simplifications in the final phase to assess output sensitivity pertain to both subsurface representation and
804 spatio-temporal forcing data resolution. Whilst commonly made, they have not previously been extensively tested.
805 Only by developing complex models as reference cases is it possible to assess the impacts of subsequent
806 simplifications via sensitivity analyses (see also Rapp et al., 2020; Schreiner-McGraw & Ajami, 2020). One
807 example along these lines was already mentioned in the previous section. Here, we further discuss each of the
808 simplified scenarios in turn.

809

810 In Scenario A (*Impermeable subsurface, no ET*; Figure 9), the temporal pattern under/overestimation with respect to
811 the observations are as expected; with infiltration and subsurface storage and discharge precluded, the simulated
812 spring and summer rainfall peaks are higher than their observed counterparts, whilst baseflows later in the year
813 (which are of course sustained by groundwater discharge in reality) are underestimated. Indeed, these results
814 unambiguously demonstrate that even ignoring any *ET* losses, streamflow would frequently become negligible in
815 summers/autumns following snow-poor winters such as 2016/2017 were it not for the sustaining influence of
816 groundwater discharge. As such, they confirm the importance of groundwater discharge to sustaining baseflows in
817 this catchment (Figure 5).

818 Although incomplete observed time-series preclude temporally integrated volumetric comparisons, the general
819 tendency for overestimation at S1 and S2 under Scenario A make sense as the fraction of incident precipitation that
820 in reality is returned to the atmosphere via ET_a and hence never becomes streamflow is neglected in this scenario.
821 The most remarkable result, though, is the extreme overestimation of streamflow relative to observations at S3 when
822 all water is forced to flow overland. This result clearly indicates that the runoff-ratio of the Vallon de La Vare is
823 considerably lower than that of the Vallon de Nant. As the land cover in the two catchments is broadly comparable
824 (Figure S3), the difference can be confidently attributed to the presence of more permeable bedrock types in the
825 Vallon de La Vare (see also Thornton et al., 2018). In reality, subsurface flow paths (in the upper part especially)
826 must be longer and deeper. Indeed, the early tracer test by Lugeon and Gagnebin (1928) mentioned earlier proved a
827 hydrogeological connection between the topographically closed basin of La Varre and La Chambrette – a spring
828 which joins the main channel below S3. This means that some water must actually bypass the station entirely,
829 although the relative volumes remain unclear. In light of these results and evident complexity, the results of the
830 reference model at S3 seem less disappointing. This further underscores the importance of considering the context,
831 including climatic and geological conditions, catchment size, and model type, when evaluating statistical fit metrics
832 of hydrological model (Seibert et al., 2018).

833 The shift in dynamics due to the imposition of a “no flow” boundary at 30 m depth (Scenario B; *Limited vertical*
834 *extent*; Figures 10, 11, and S16) (enhanced runoff during snowmelt and intense rainfall, more pronounced
835 recessions, etc.) can be explained by reduced maximum subsurface storage volumes. Although less so than in
836 Scenario A, that streamflow is still grossly overestimated at S3 (Figure 10) indicates that under both Scenarios A
837 and B, simulated streamflow dynamics are far too rapid and overestimate discharge considerably (and moreover
838 almost certainly involve incorrect flowpaths). In contrast, in the reference case, the simulated dynamics were too
839 suppressed; improved simulations must therefore lie somewhere in between. Whilst it is impossible to state
840 definitively whether the full depth model structure in the Vallon de La Vare is preferable to that of Scenario B, our
841 prior understanding of the region's geology, plus these results, suggest that it is likely the case. More generally,
842 because it is common for vertical domain extents to be limited when applying computationally intensive integrated
843 hydrological models to real mountainous catchments, the degree of sensitivity demonstrated represents an important
844 finding. In some previous studies, manual calibration may have (fully or partially) compensated for this effect, but
845 such action could compromise any subsequent predictions. The sensitivity of integrated model outputs to assumed
846 vertical extent should therefore be assessed more routinely (see also Condon et al., 2020).

847
848 The noticeable differences between the respective simulations during spring periods in Figure 12 (Scenario C;
849 *Spatially-uniform forcing*) suggest that it is necessary to employ spatially distributed forcing to reproduce annual
850 flow peaks, especially at higher points along mountain stream networks. This makes sense because while the
851 elevations and slope aspects at which snowmelt is generated naturally evolve over time, these spatial patterns are
852 lost when catchment-averaged data are applied. In even larger catchments, these differences would be exacerbated.
853 It should also be emphasized that the spatially uniform forcing dataset used here was generated by averaging the
854 distributed outputs produced by Thornton et al. (2021) at each time-step. As such, the differences may have been
855 larger if “truly uniform” forcing dataset had been applied.

856

857 Meanwhile, Scenario D (*Geology from global maps*) reveals that one cannot parameterize groundwater and
858 integrated models based directly on global map products – as is currently done in many global-scale groundwater
859 and integrated modelling studies – and obtain acceptable simulation results at local, management-relevant scales.
860 The considerable challenge of how to define sufficiently good 3D subsurface structures and associated parameter
861 values must therefore be addressed if the goal of developing practically useful global groundwater predictions is
862 ever to be realized.

863
864 Finally, the results of Scenario E (*No permafrost*; not shown) suggest that, probably due to its limited extent in this
865 region, permafrost thaw is not expected to have a major impact on streamflows. However, a full “thermally enabled”
866 simulation that accounts for pore water freeze-thaw and thermally modified hydraulic conductivities, rather than the
867 simple coupling length approach used here, would probably be necessary undertaken to verify this assertion.

868 4.3. Main novelties

869 The full complexity integrated model presented is associated with several novelties. Firstly, in incorporating an
870 accurate, high-resolution 3D model of bedrock geology (Thornton et al., 2018) – supplemented by a dedicated
871 analysis of unconsolidated sediment geometries and represented on a vertically-extensive and fairly finely resolved
872 mesh – the model’s subsurface structure is more refined than that of previous integrated models of mountainous
873 catchments. Yes given the extreme geological complexity of La Vare, further detail may still be required.

874 Secondly, the snowmelt component of the model’s forcing dataset – generated in a prior study using an energy
875 balance-based snow model that additionally accounts for gravitational redistribution and was conditioned upon two
876 complementary types of snow observations (Thornton, Brauchli, et al., 2021) – extends well beyond the approaches
877 usually taken to develop forcing data for integrated surface-subsurface models. The highly spatially and temporally
878 resolved nature of the forcing datasets more generally can be regarded as a further novelty. Besides enabling the
879 pronounced spatio-temporal dynamics that characterize such environments to be represented more faithfully in the
880 hourly version of the full model than is typically the case, it was also possible to quantify the impacts of
881 downgrading the forcing data’s temporal frequency and spatial resolution.

882 Detailed HGS models of real (as opposed to synthetic) mountainous catchments have not previously been presented
883 in the literature. This is important because in contrast to some other integrated codes, HGS permits the free
884 evolution of surface water network. HGS also supports flexible tetrahedral meshes, which arguably enable the
885 representation of complex topography more efficiently than the regular, structured meshed employed by other
886 popular integrated codes (but see Maxwell, 2013). Equally importantly, this study represents the first known attempt
887 to calibrate any integrated hydrological model of a mountainous catchment in an automated fashion.

888 Finally, in contrast to many related previous studies (e.g. Carroll et al., 2019; Engdahl & Maxwell, 2015; Markovich
889 et al., 2016; Penn et al., 2016; Pribulick et al., 2016), explicit time-series comparisons between simulations and
890 historical observations, and associated statistical metrics, are presented. This goes beyond the status quo in much
891 integrated modelling whereby simulated historical hydrological baselines are only compared with projections made
892 under modified conditions (rather than with historical observations as well). Whilst the physical basis of the models
893 involved means that such an approach is not invalid, actually demonstrating that (with plausible parameter values)
894 historical observations can be reproduced satisfactorily by carefully developed integrated models, as is done here,
895 enhances confidence in the robustness and suitability of the approach. The spatio-temporal visualization of different
896 aspects of the simulations was also helpful in this regard. Integrated model results should be presented using both
897 techniques (i.e. time-series comparisons and full visualization) more routinely.

898 4.4. Fully-integrated hydrological models in complex mountainous settings: potential next steps

899 Based upon this work, numerous recommendations for future research, some of which have already been alluded to,
900 can be made. Firstly, the interplay between initial conditions, parameter updates, and (minimum) re-initialization
901 period length (i.e. the period that should be (re)simulated with every new set of parameters prior to the
902 commencement of calibration) in the automated calibration of integrated hydrological models should be investigated
903 more systematically. Secondly, when employing integrated model codes that support unstructured meshes in such
904 topographically and geologically complex settings, there is likely scope to increase mesh efficiency. The mesh
905 employed here – in which the same (surface constrained) layer was replicated vertically – was a limiting factor.
906 Ideally, fully-unstructured meshes that are constrained / refined according to surface features (streams, topography,
907 etc.) in the upper few meters only, but then transition to being exclusively concordant with geological formation
908 interfaces beneath this, could be developed and applied. To ensure numerical stability, high quality element shapes
909 would have to be maintained, however, which is unlikely to be trivial (depending on the degree of surface and
910 subsurface complexity). If possible, the attendant runtime improvements could open many more possibilities for
911 automatically calibrating such models, including over longer periods and using higher frequency forcing data.

912
913 Accurate, spatially continuous (3D) data pertaining to the subsurface remains severely lacking in both mountain
914 regions and elsewhere. This is a major impediment to the more widespread uptake of integrated models involving
915 detailed subsurface structures. Few catchment- or regional-scale 3D bedrock models with appropriate attributes for
916 groundwater or integrated hydrological models currently exist in mountain regions, although they can now be
917 developed (Thornton et al., 2018). Improved approaches to estimate the geometries and properties of numerous
918 unconsolidated sedimentary features (i.e. across entire rugged, inaccessible headwaters) are also required (see
919 Supplementary Text S1). With continued developments in satellite remote sensing, the already considerable
920 disparity between the amount and quality of data available pertaining to the surface and that pertaining to the
921 subsurface is widening. 3D (or even 2D) data on soil hydraulic properties are also scarce, even in relatively densely
922 populated and developed mountain ranges such as the European Alps. As already noted, soils control water
923 partitioning at the land surface, and so high-quality soil representations data are crucial for reliable simulations.

924
925 As we have hopefully helped to demonstrate, the extensive (2D-3D) visualization capabilities of integrated models
926 enable users to evaluate the coherence of a given numerical representation to be assessed in a conceptual sense, for
927 instance in relation to known theory and/or understanding of a given system developed in the first. This approach
928 can enable users to identify where a given model may require or benefit from the introduction of additional data, the
929 reappraisal of the conceptual model, or other improvements as part of an iterative development process. More
930 formally, the considerable number of simulated variables that can be extracted at any point(s) in space and time from
931 within the model domain provide enormous scope for a much wider variety of observational datasets, both in situ
932 and remotely sensed, to be introduced in their calibration and evaluation (in a multi-objective fashion).

933
934 Such datasets could include remotely-sensed *ET* maps (e.g. Allen et al., 2007; Li et al., 2009) or gravimetric
935 estimates of seasonal groundwater storage (e.g. Arnoux et al., 2020). The latter in particular would provide more
936 spatially integrated, representative information than the piezometer measurements used here (see also Schilling,
937 Cook et al., 2019). One could also constrain integrated models using snapshot maps of the evolving stream network
938 extent (e.g. captured using drone photography) (see also Stoll & Weiler, 2010). Combining integrated models and
939 many diverse datasets in this fashion should ultimately reduce the extent to which equifinality afflicts model
940 predictions, and thus help to finally realize the vision of Grayson & Blöschl (2001). However, what constitutes an
941 acceptable level of model-data fits for such models, given the characteristics of such terrain and in a metric-specific
942 fashion, must be established by the community. As noted above, we recommend these evaluation activities include
943 time-series comparisons where relevant.

944 5. Conclusions

945 We have presented a fully-integrated surface-subsurface hydrological model of a steep, snow-dominated
 946 mountainous catchment that incorporates a dedicated 3D model of bedrock geology and an energy balance-based
 947 representation of snow processes; two structural advancements over previous mountain integrated modelling efforts
 948 that, given the study area's characteristics, were deemed important. Establishing and running such a model was
 949 found to be feasible, if challenging. In the first known attempt for an integrated model of a mountainous catchment,
 950 automated calibration was undertaken with respect to observed streamflows and groundwater levels.

951
 952 Following calibration, the system's hydrological dynamics could generally be satisfactorily replicated, suggesting
 953 that integrated models do indeed have utility in complex Alpine settings. When high-frequently (hourly) forcing
 954 data were applied, diurnal fluctuations in streamflows and groundwater levels could be reproduced, suggesting that
 955 such temporal resolution is necessary for certain applications. Visualizing the model's forcings and simulated
 956 response variables in time and space, and the outcome of a "soft evaluation", in which simulated patterns of surface-
 957 subsurface exchanges flux was compared with a flux pattern inferred from a thermal drone image, further reinforced
 958 our view of the model's broad coherence and ability to capture observed surface-subsurface flow dynamics.

959
 960 The model struggled to closely replicate observed streamflows at one location (S3). This can be attributed with
 961 reasonable confidence to fact that our model does not explicitly represent the discrete karstic features of the
 962 upstream sub-catchment, although unreliable streamflow observations could be a factor in the poor correspondence.
 963 Replicating the distinctive signals of groundwater levels that were observed nearby one another also proved elusive,
 964 likely due to unrepresented local scale heterogeneities in subsurface hydraulic properties. This suggests that in such
 965 settings, local-scale variability in shallow in situ groundwater level observations can adversely affect their utility in
 966 the catchment-scale groundwater and integrated model calibration. Even notwithstanding any such data issues or
 967 data-model scale mismatch, as with most calibration exercises, a risk of post-calibration non-uniqueness remains.
 968 This could not be addressed with the present scope, with the long model runtimes representing the main impediment.

969
 970 Subsequently simplifying the full complexity reference model in a series of sensitivity tests revealed that:

- 971
- 972 • In this study area, without groundwater discharge, streamflow would frequently become negligible in
 973 summers following snow-poor winters;
 - 974 • Limiting the model's vertical extent significantly increased the "flashiness" of simulated streamflows and
 975 groundwater levels, indicating that care should be taken to ensure that simulation domains are sufficiently
 976 deep – especially in more permeable geological settings (otherwise, the risk of overestimating streamflow
 977 peaks could be considerable);
 - 978 • Applying spatially uniform forcing data led to reduced simulated annual (snowmelt-related) streamflow
 979 peaks, most noticeably at higher elevation points along the stream network;
 - 980 • Satisfactory simulations (with respect to observations) were not obtained when we substituted the model's
 981 subsurface structure and parameterization with information derived from existing, global-scale maps,
 982 thereby demonstrating the importance of carefully defining locally meaningful subsurface structures and
 983 calibrating their associated parameters within physically plausible limits; as such, the suitability of global
 984 products for large-scale groundwater/integrated modelling efforts which nevertheless require locally
 985 meaningful predictions, especially without model calibration, requires further detailed assessment across
 986 many different settings; and,
 - 987 • Complete permafrost thaw would be expected to have an almost indistinguishable impact on hydrological
 988 variables such as streamflows and groundwater levels, although the fairly simplistic way in which
 989 permafrost was represented in the reference model limits our confidence in this assertion somewhat.

990 Relative to the simpler alternatives tested, the value of our full complexity model lies not only in the generally
 991 improved fit metrics, but crucially in the fact that they were generated via a more plausible model structure. In
 992 addition, considering the relatively complex and more simplified approaches alongside one another yielded insights
 993 that could not have been obtained using either approach independently. We therefore conclude that physically-based
 994 integrated flow models provide a strong basis for exploring the impacts of different simplifications, assumption, and
 995 other approaches that are used across the full spectrum of hydrological model, including those implemented in more
 996 widely used tools.

997
 998 Several recommendations for future integrated modelling research in climatologically, topographically, and
 999 geologically complex mountainous settings have emerged, including the needs to develop dedicated methods to
 1000 generate more efficient, fully-unstructured meshes; develop and apply improved methods describe the 3D
 1001 geometries and hydraulic properties of unconsolidated subsurface formations; routinely test the sensitivity of model
 1002 predictions to assumed watershed base depth or thickness; investigate the interplay between initial conditions and re-
 1003 initialization simulation times in automated calibration; better exploit the possibilities to introduce a range of
 1004 complementary variables (in situ and remotely sensed, spatially distributed and spatially integrated, fully
 1005 quantitative and “softer” data, etc.) into multi-objective calibration and evaluation; and establish more refined model
 1006 performance criteria, for several variables and associated metrics, that account for factors such as catchment type,
 1007 catchment area, model type, plausibility of simulated spatial patterns, and credibility of subsurface structure for use
 1008 in model evaluation and intercomparison exercises.

1009
 1010 In summary, our contribution both attests to the considerable potential of fully-integrated models in complex
 1011 mountain settings and elucidates several outstanding challenges (especially those concerning data requirements and
 1012 calibration). Even despite these challenges, the strong physical basis of integrated models should already facilitate
 1013 hydrological climate change impact assessments across the European Alps and other rapidly changing mountain
 1014 regions that are more reliable and holistic (e.g. include both plausible future climate and vegetation scenarios) than
 1015 those hitherto possible. For practical reasons, initial applications could focus on exceptionally important or
 1016 ecologically sensitive catchments, or else catchments for which much of the requisite data already exists.

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 1024 conflict of interest. The calibrated model with daily forcing data, the files that can be substituted to generate the
 1025 various simplified scenarios, the animations, and supplementary figures are available at:
 1026 <https://doi.org/10.6084/m9.figshare.14974623.v1>. A HydroGeoSphere license would be required to run the models
 1027 (contact sales@aquanty.com). Note that the models must be initiated by running them iteratively several time
 1028 (updating the input heads with the previous outputs). The hourly simulation is not provided in the repository due to
 1029 the size of the forcing data, but can be obtained from the corresponding author.

1030 **Author contributions**

1031 J.M.T. conducted the majority of the work, including making the groundwater measurements, sourcing the inputs
 1032 datasets, setting up and calibrating the model, planning and executing the subsequent simulations, preparing the
 1033 figures (except Figure S12), and writing the manuscript. R.T. provided advice and technical contributions regarding
 1034 HydroGeoSphere. N.L. enabled the geophysics fieldwork and conducted the geophysical inversion. P.B. and G.M.

1035 were responsible for funding acquisition and provided support and advice at all stages. All authors contributed to the
 1036 finalization of the manuscript.

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Supporting Information for

Simulating fully-integrated hydrological dynamics in complex Alpine headwaters

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Introduction

This file contains supplementary figures, describes the methods taken to estimate unconsolidated sedimentary formation geometries, and provides captions for supplementary tables and animations.



Figure S1. Photographs showing a) the concrete weir gauging station S2, and b) the installation of piezometer N4.

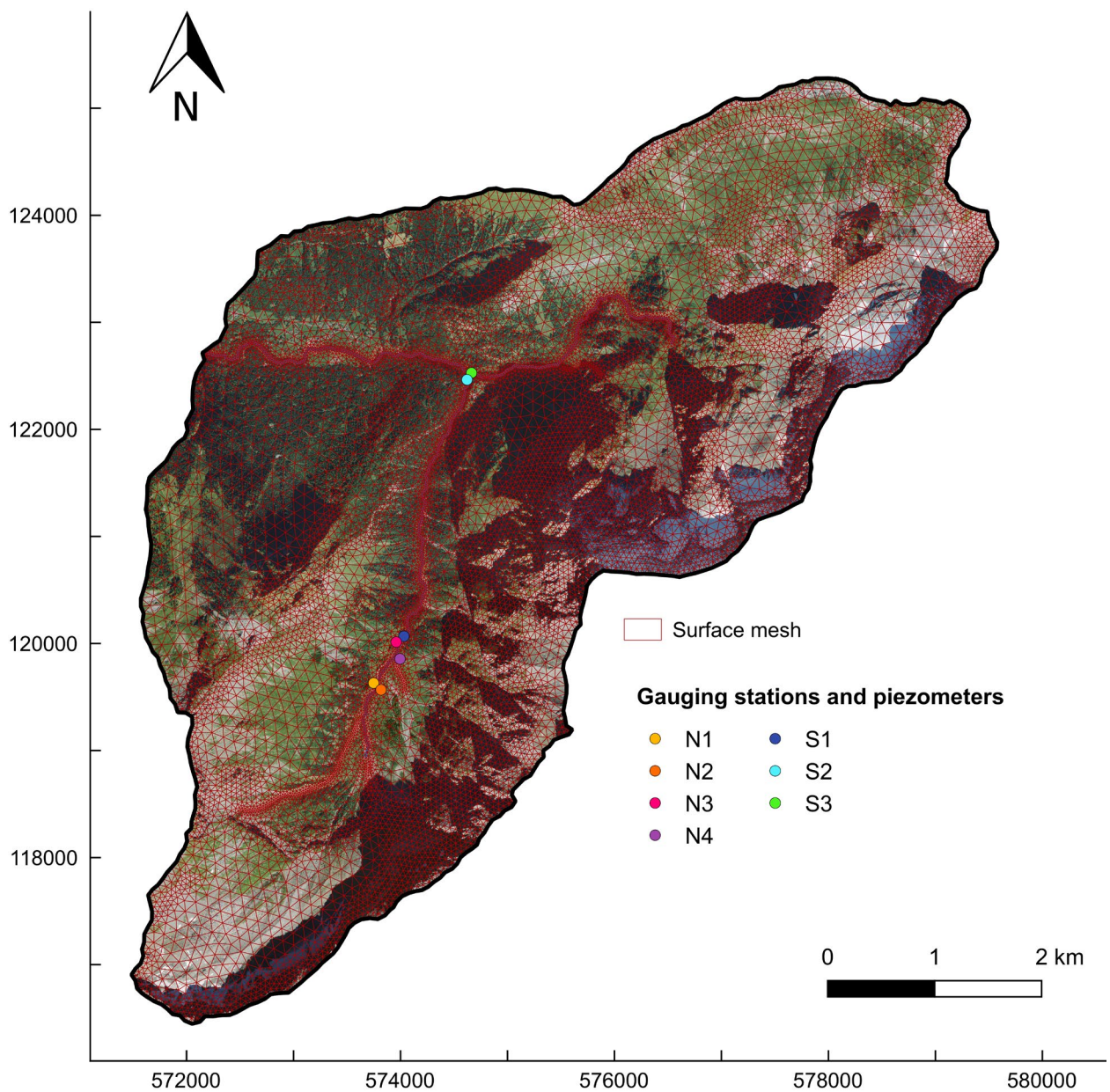


Figure S2. The 2D surface triangular mesh, underlain by a high-resolution aerial photograph (Source: ©swisstopo). Refinement is highest in the riparian zone and in steep areas. Care was also taken to ensure that nodes were placed at the precise coordinates of the observation points (piezometers, denoted by N, and streamflow gauging stations, denoted by S).

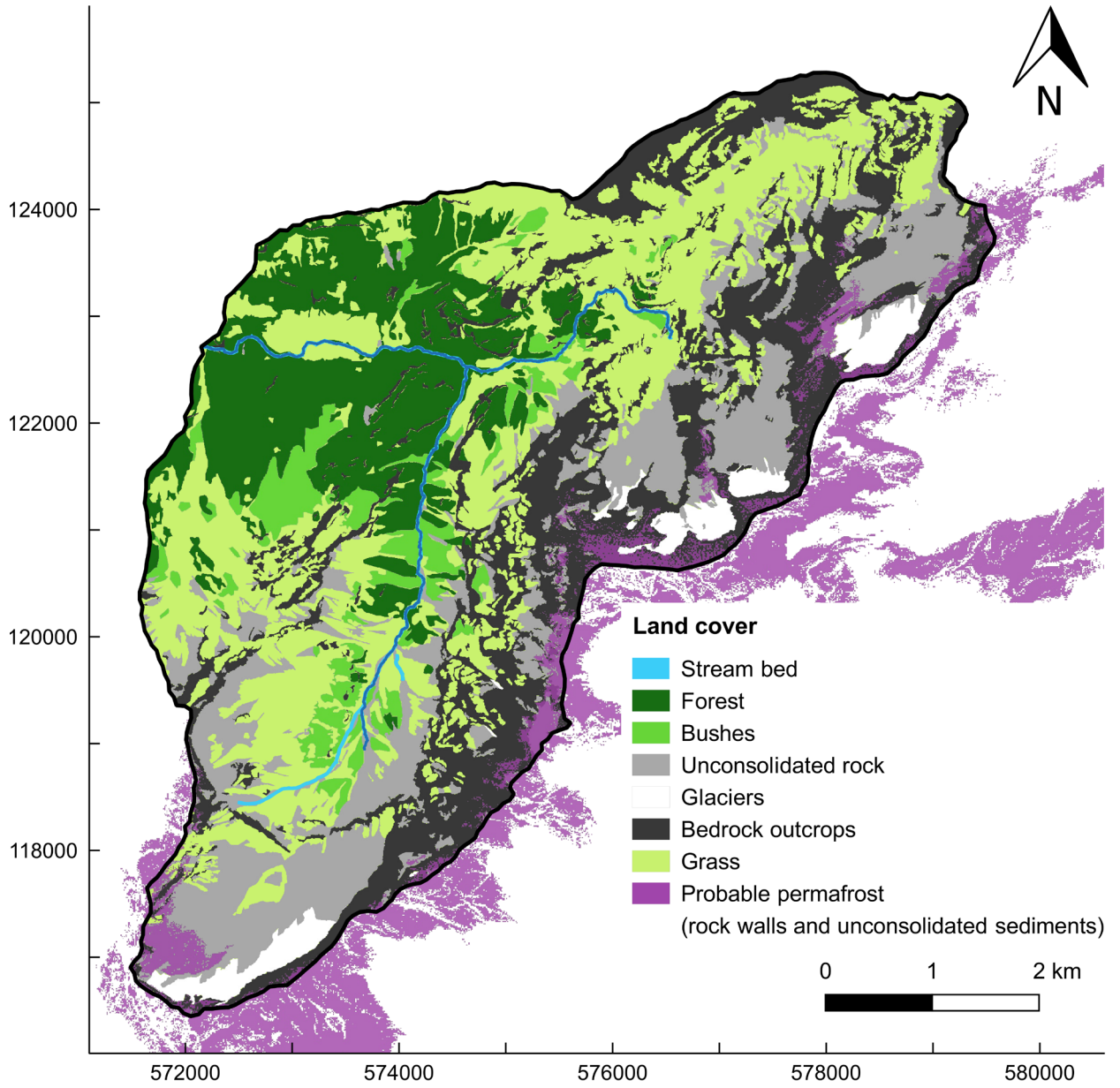


Figure S3. Land cover map of the study area, including estimated (present) permafrost distribution, that was used to define surface and evapotranspiration zones in the integrated model.

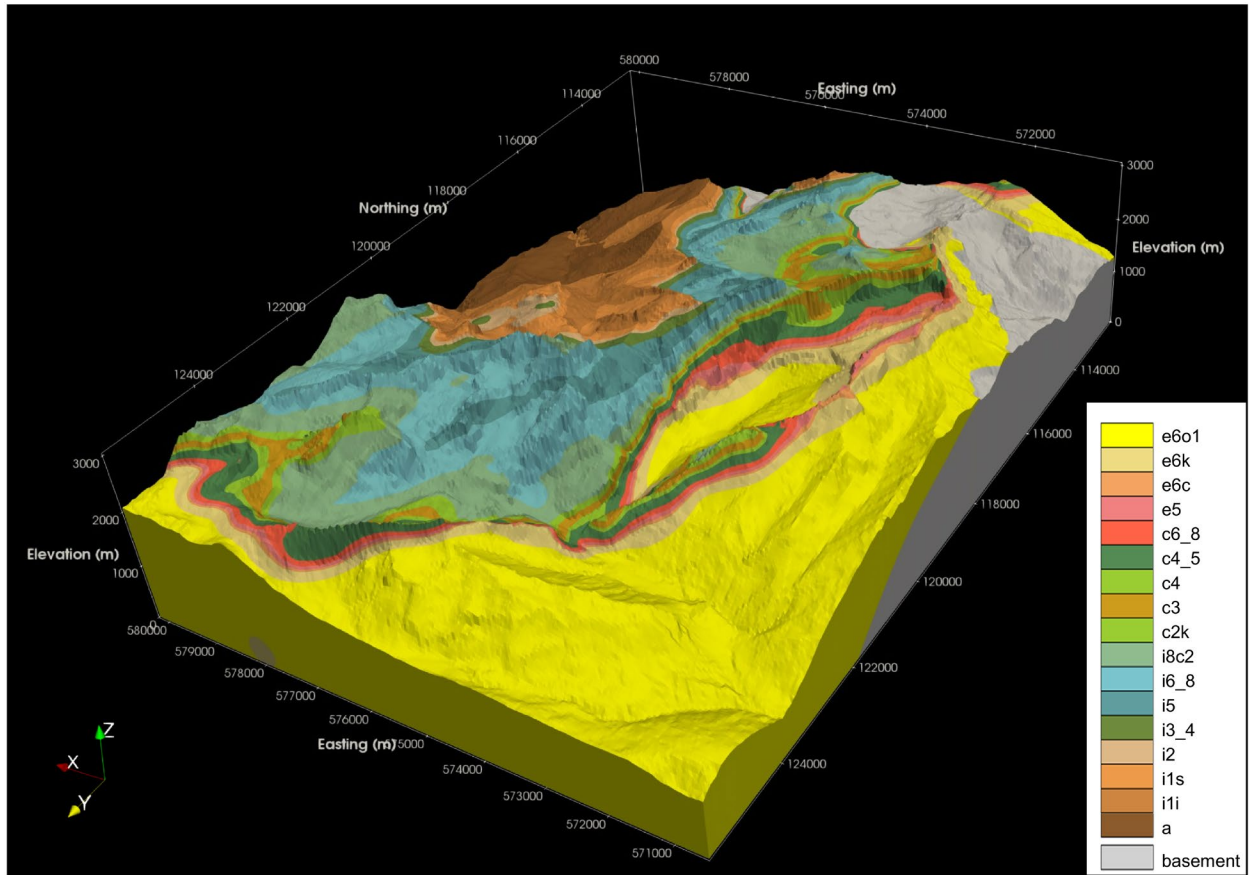


Figure S4. Illustration of the 3D bedrock geological model that contributed to the definition of subsurface zones in the integrated flow model. Source: Thornton et al. (2018).

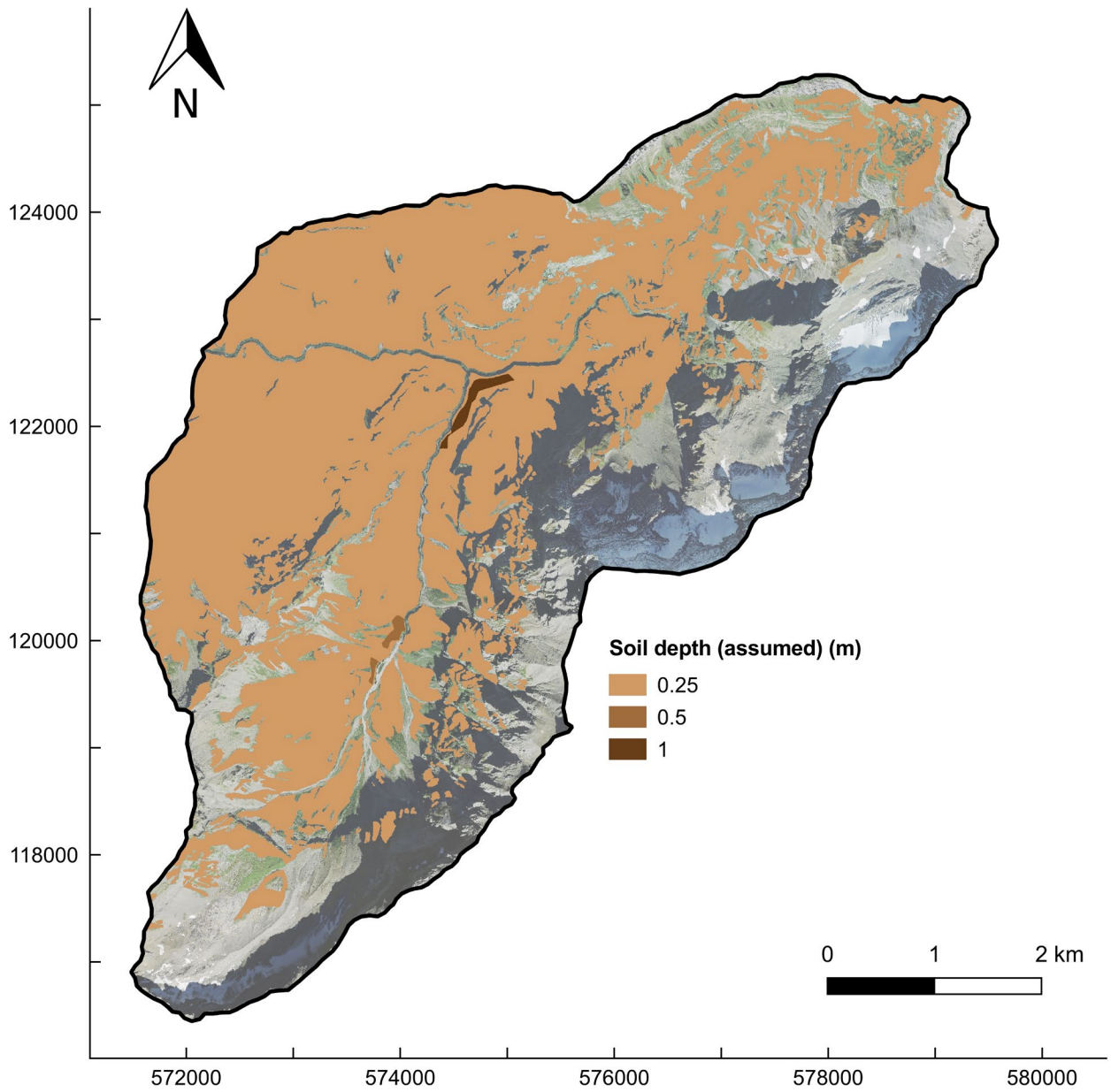


Figure S5. The spatial distribution of soil depth that was assumed in the integrated model in the absence of any detailed, high-resolution spatial information on soil depths and properties. Where the underlying aerial imagery is visible, no soil layer is represented.

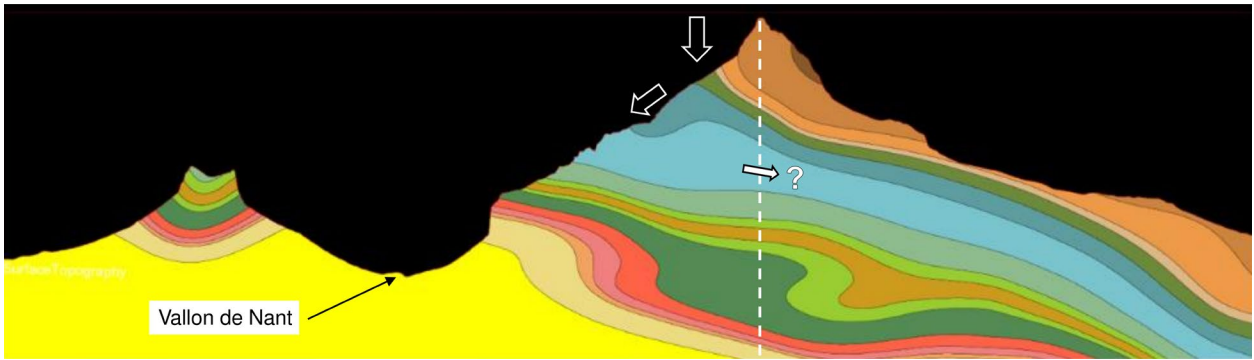


Figure S6. Cross-section through the 3D bedrock geological model showing the possibility for groundwater exportation across the topographic divide on the eastern flank of the Vallon de Nant, which is illustrated using the dashed white line (i.e. across the no-flow boundary in the model).

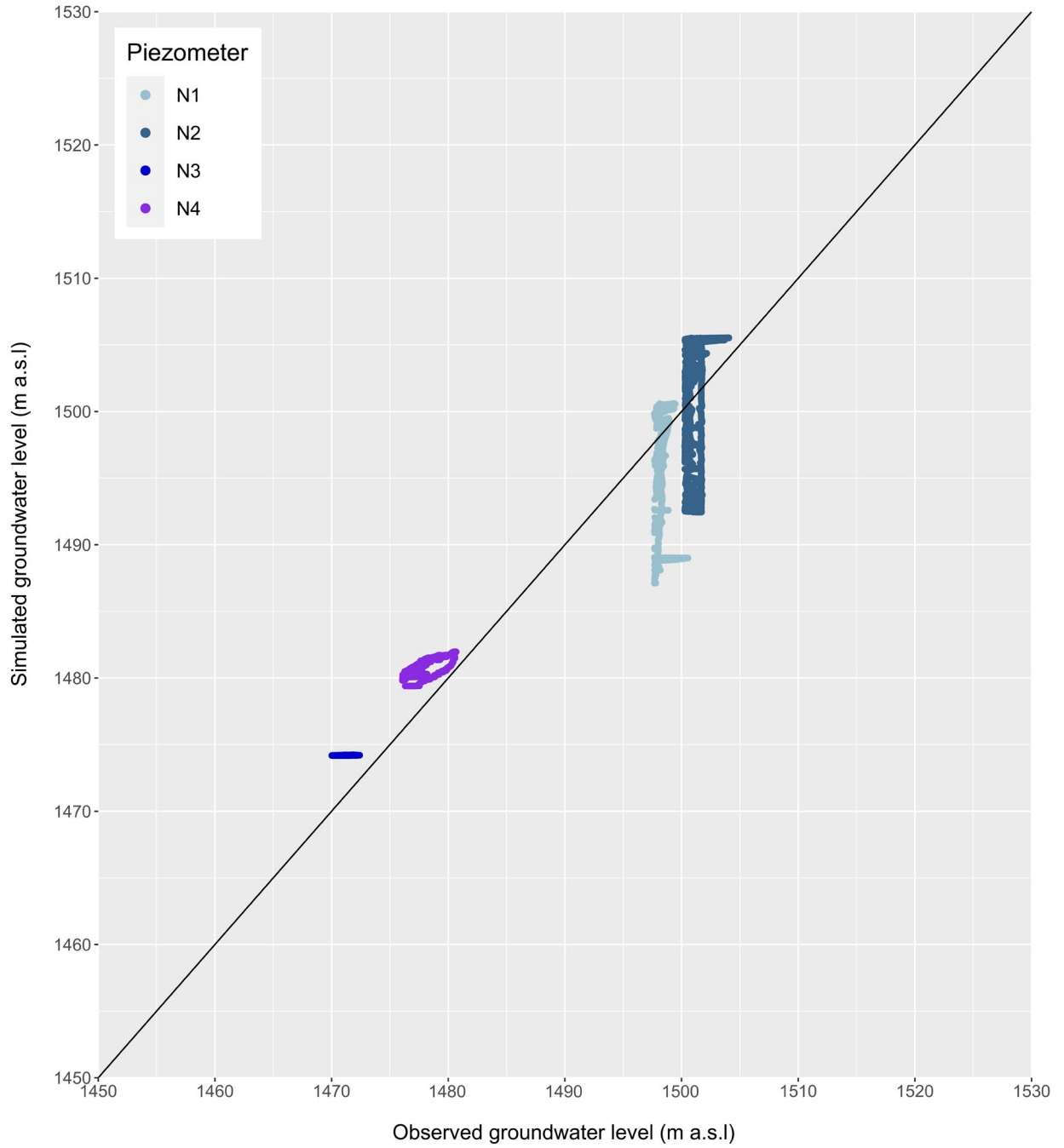


Figure S7. Pairwise plot of observed and simulated groundwater levels. The simulated levels were generated using the version of the model forced by daily frequency data. Model outputs were interpolated in time onto the half-hourly observation time-step to facilitate the plot.

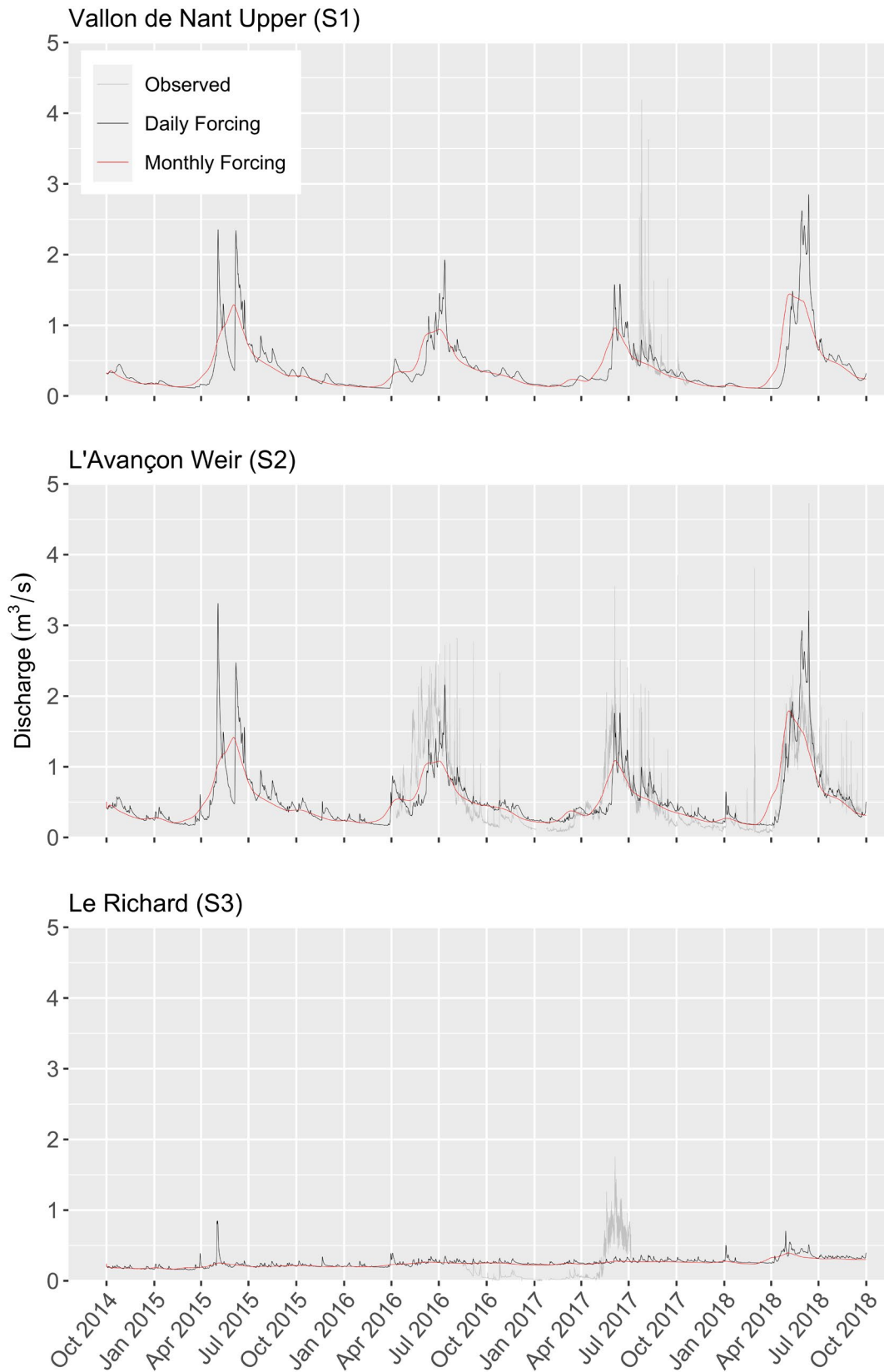


Figure S8. The impact of moving from monthly to daily frequency forcing on streamflow predictions generated by the fully-integrated model.

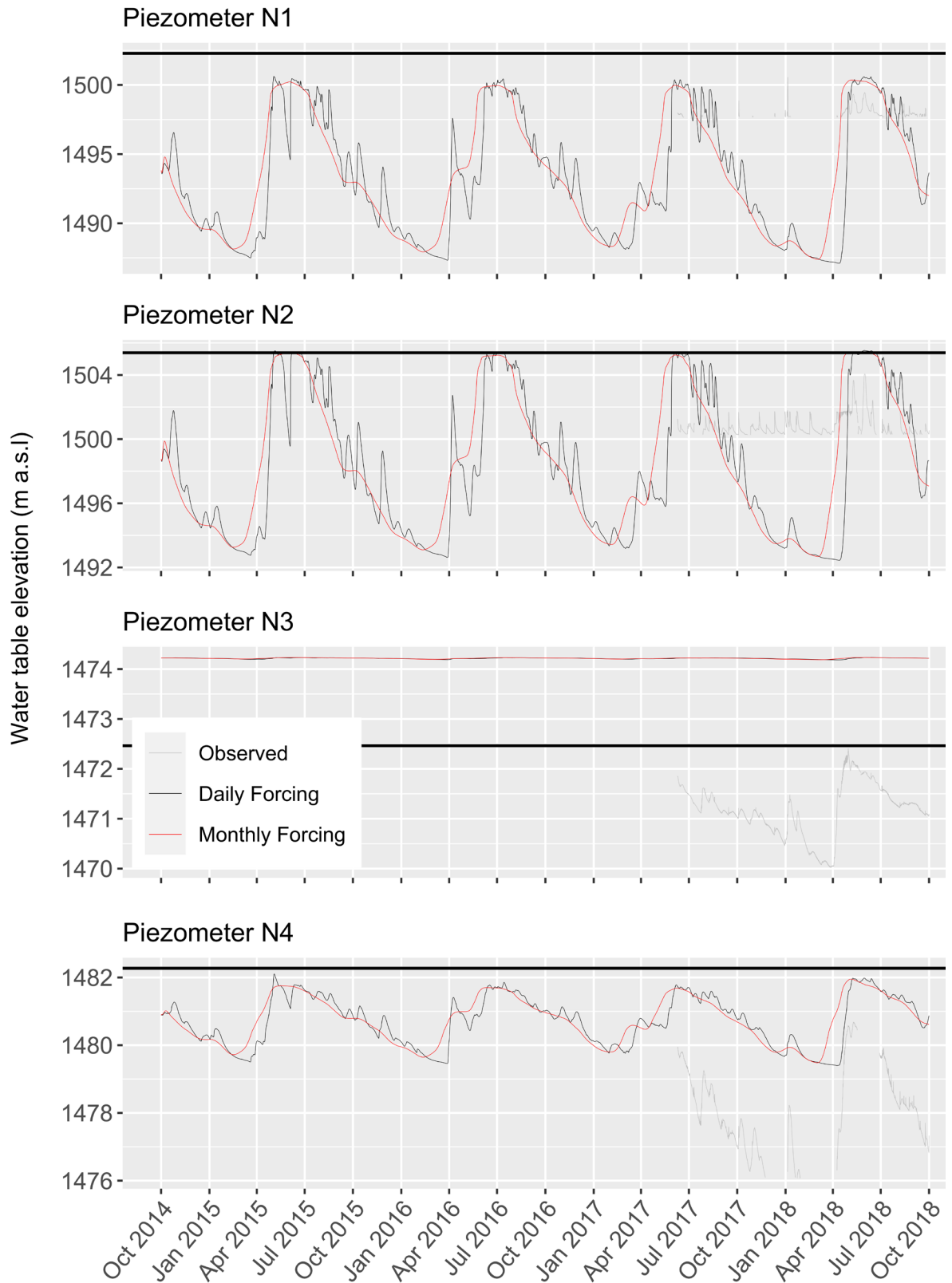


Figure S9. The impact of moving from monthly to daily frequency forcing on groundwater level predictions generated by the fully-integrated model.

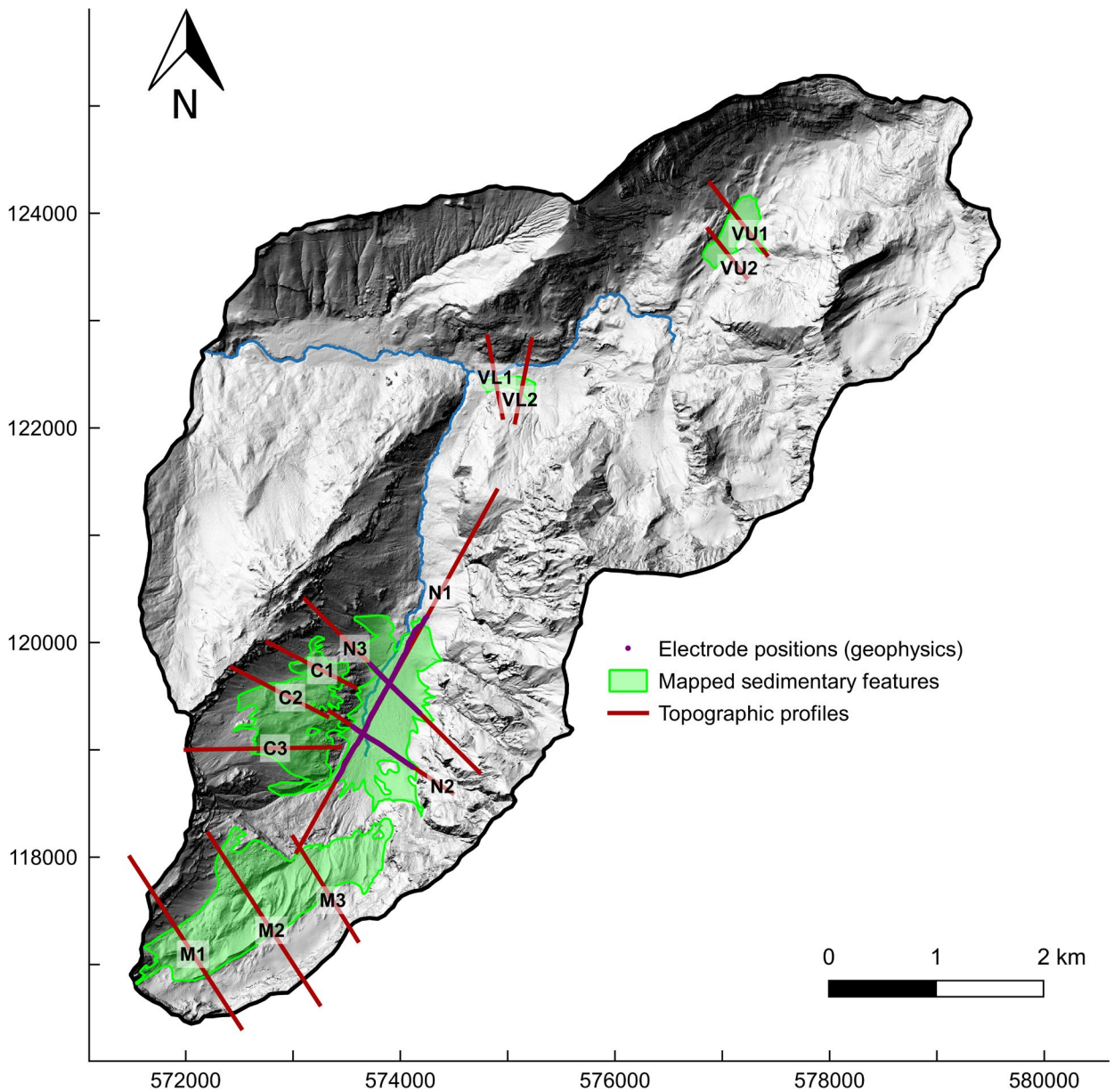


Figure S10. The major unconsolidated sedimentary feature extents considered in this study. The locations of electrodes that were placed during the geophysics campaign and the topographical cross-sections that were established as a basis for interpolating the bedrock interfaces are also shown. N denotes *Nant*, M *Martinets*, C *La Chaux*, and VU *Vare Upper*, and VL *Vare Lower*. The underlying hillshade map was generated from the swissALTI^{3D} digital terrain model © swisstopo).

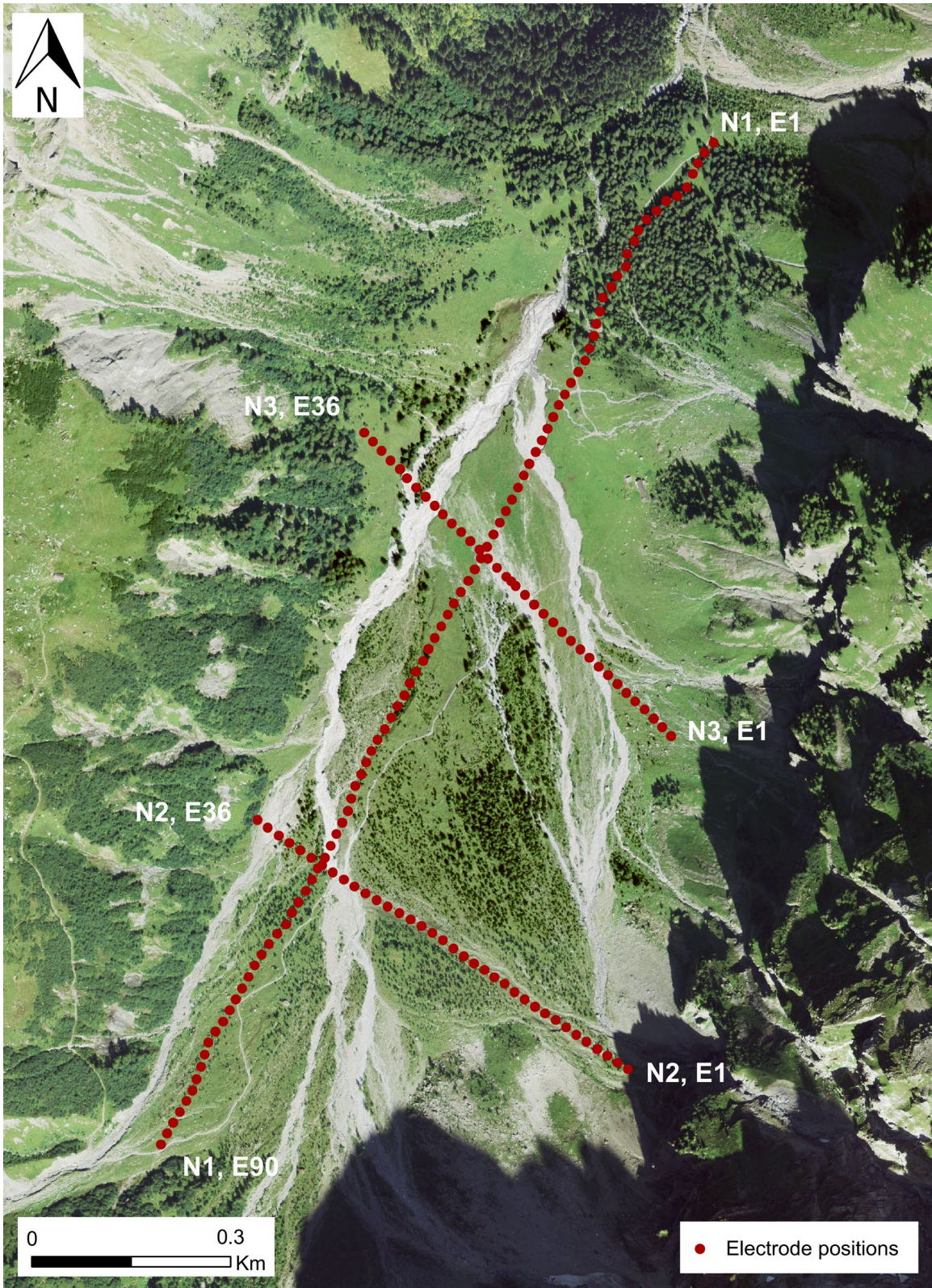


Figure S11. The arrangement of electrodes along the three transects in the Nant alluvial fan that were surveyed using electrical resistivity tomography (ERT). The profiles were named N₁, N₂, and N₃, and the electrodes were numbered sequentially along each profile.

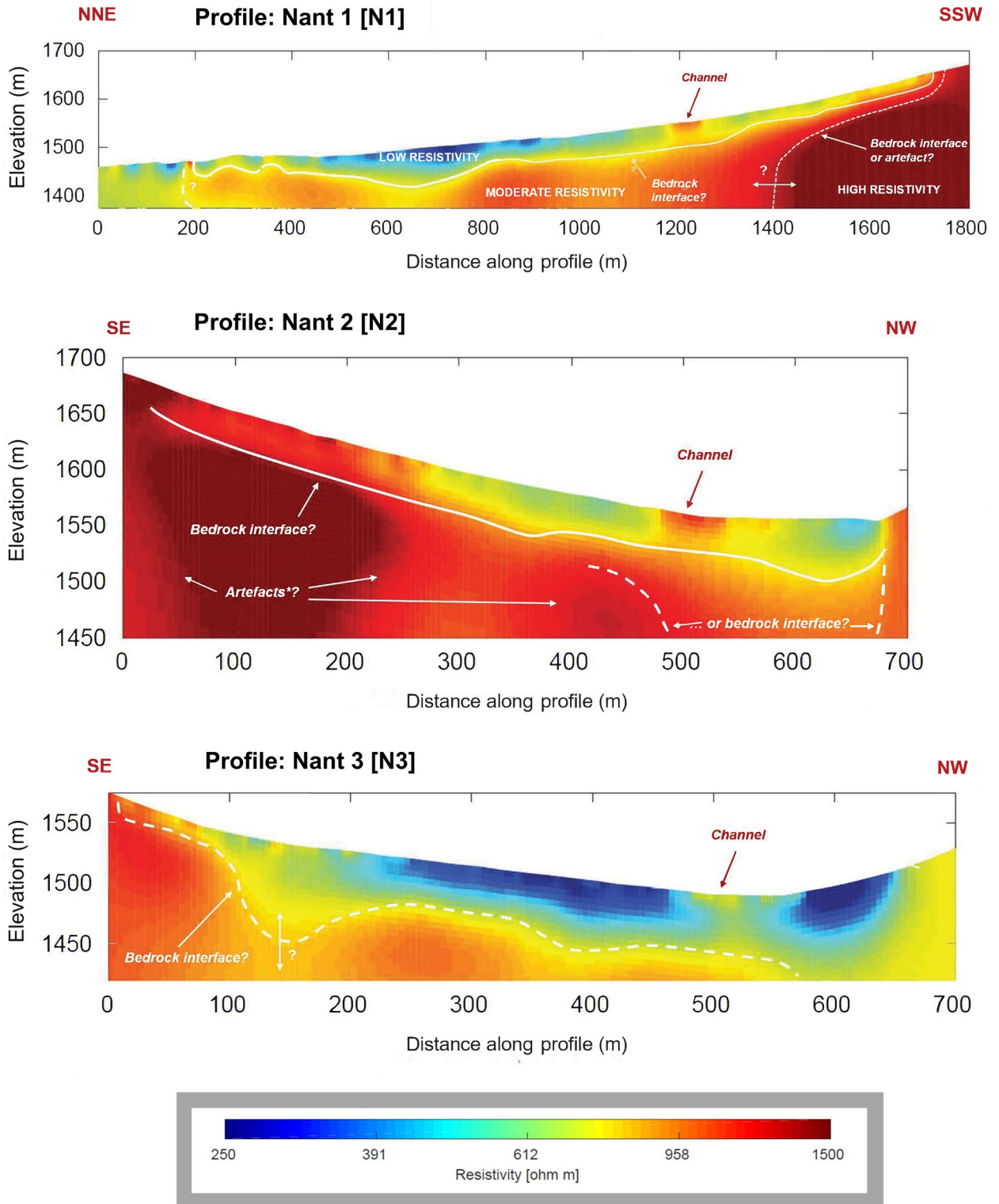
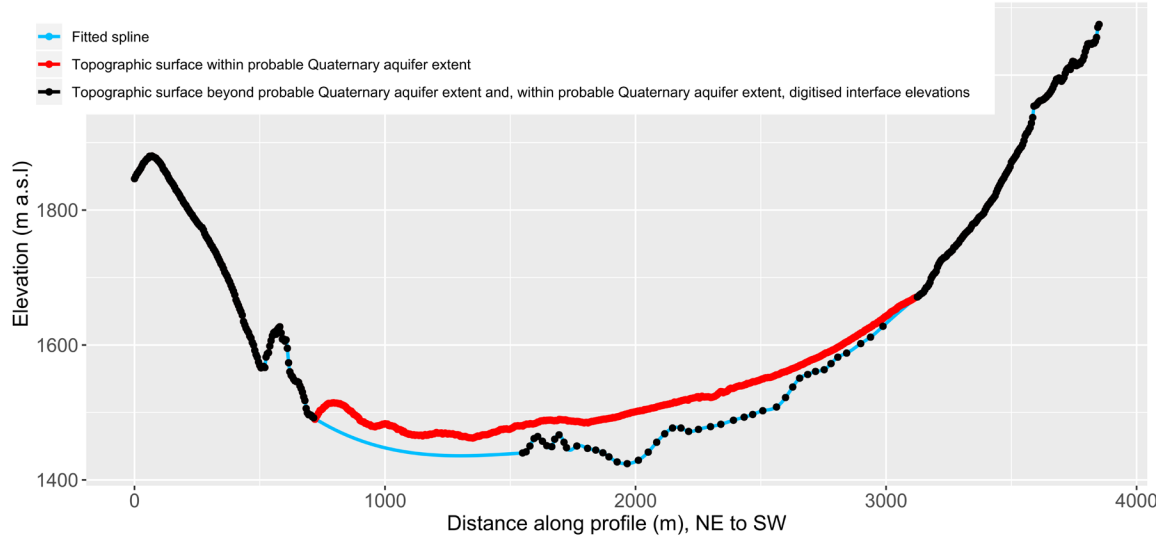
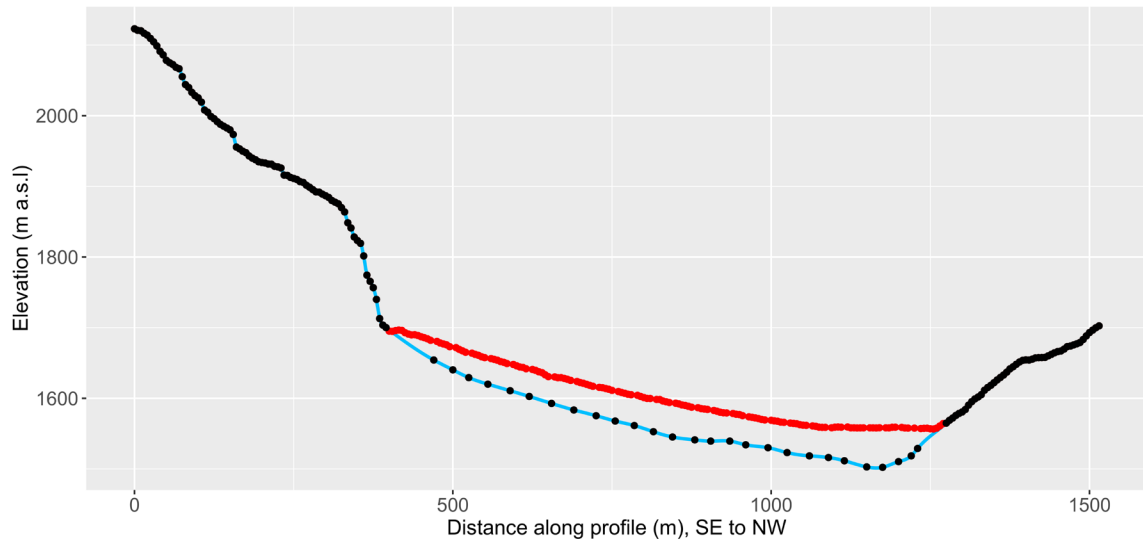


Figure S12. Inverted electrical resistivity fields for each of the three surveyed profiles in the Nant alluvial fan. A common resistivity scale is used. Annotations indicate the inferred bedrock interface and other interpretations, which in some cases are only tentative.

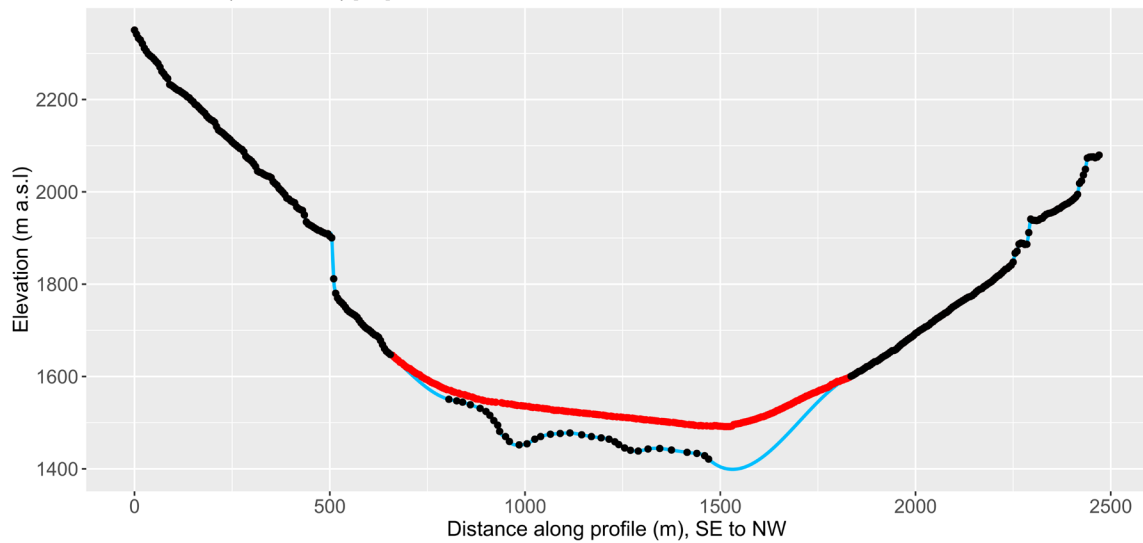
Profile: Nant 1 (GEOelectric) [N1]

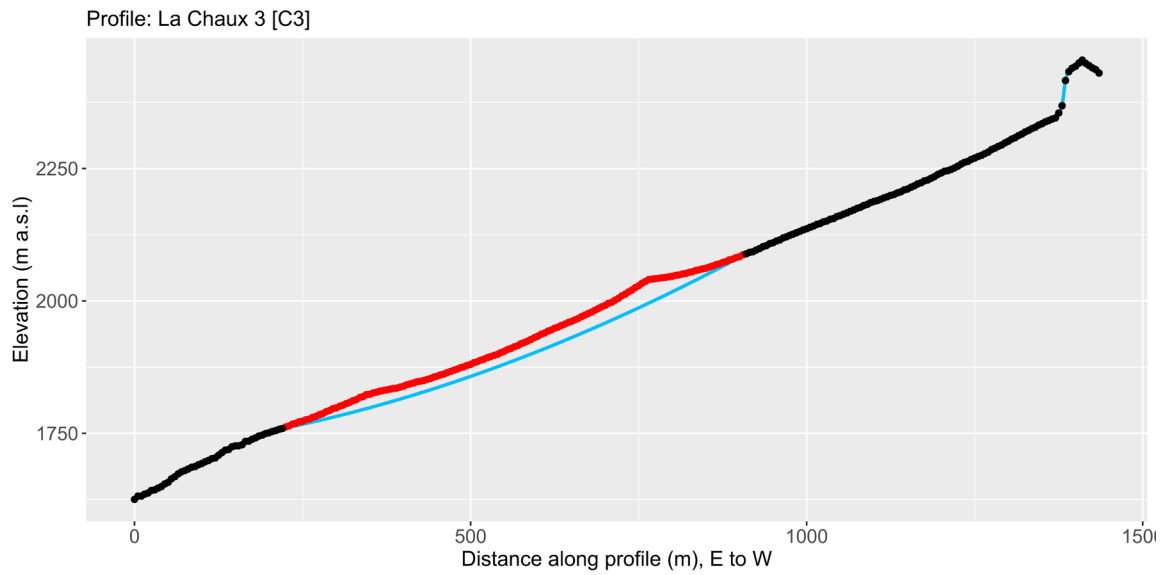
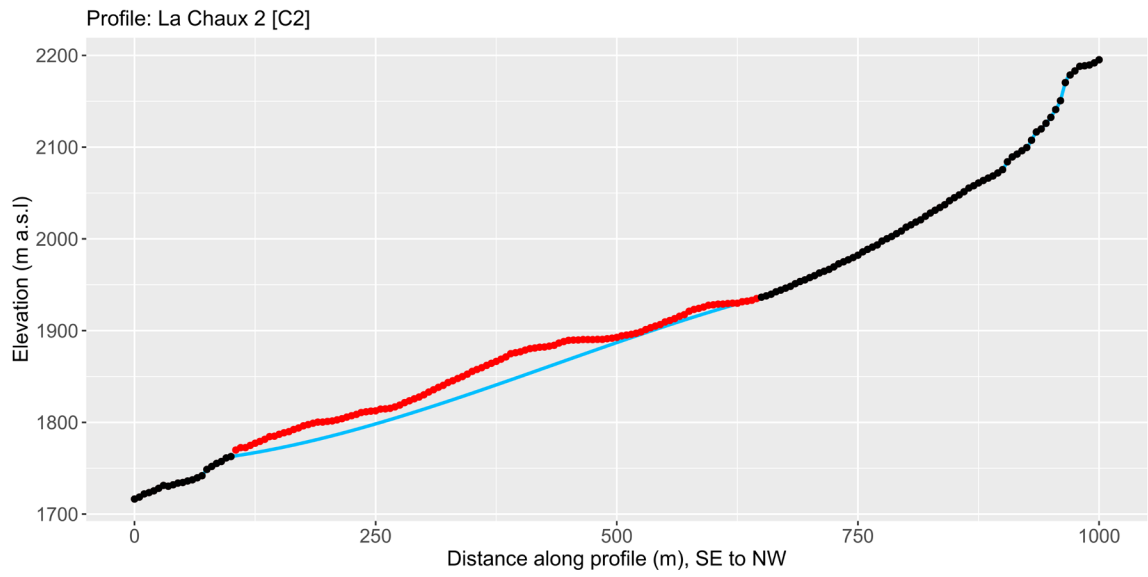
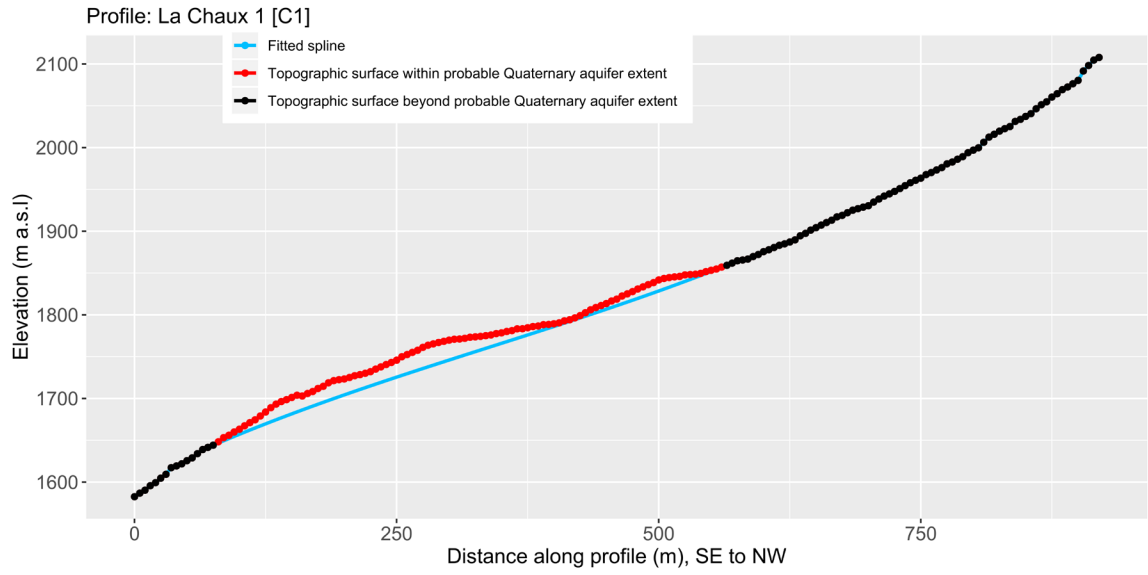


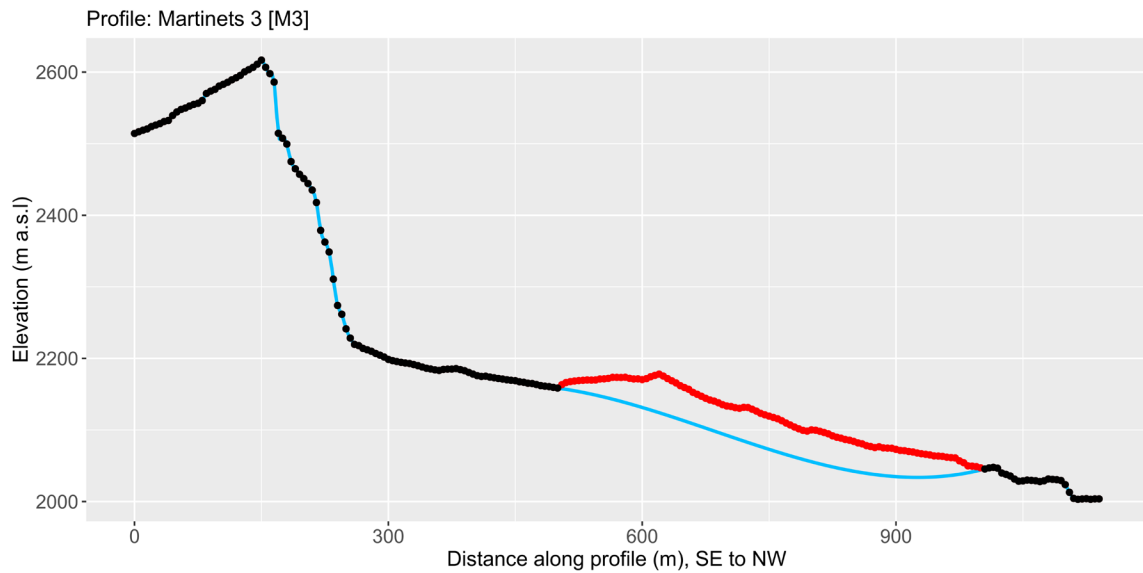
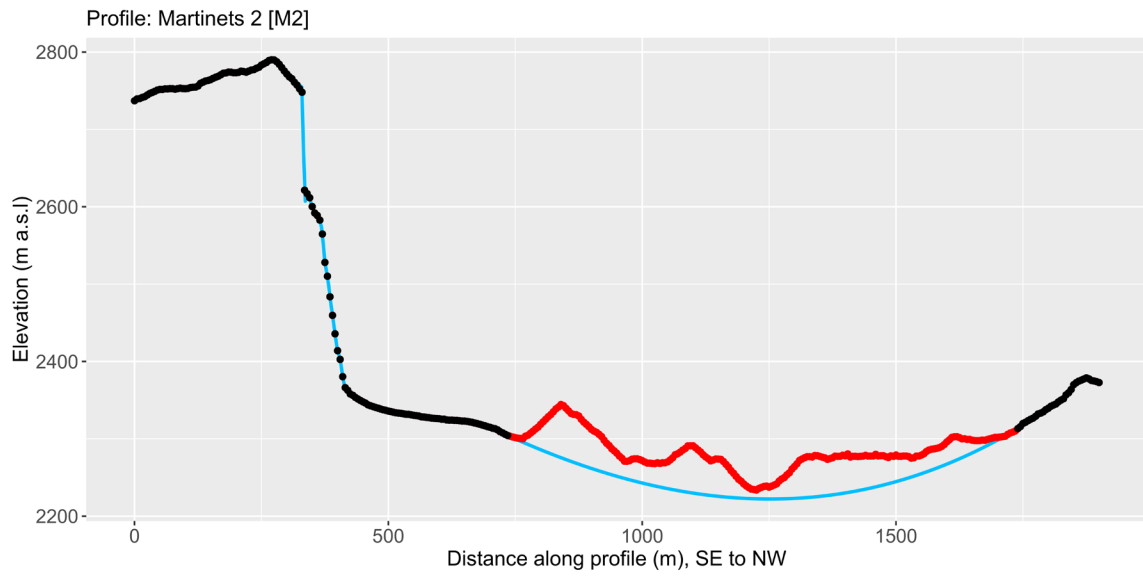
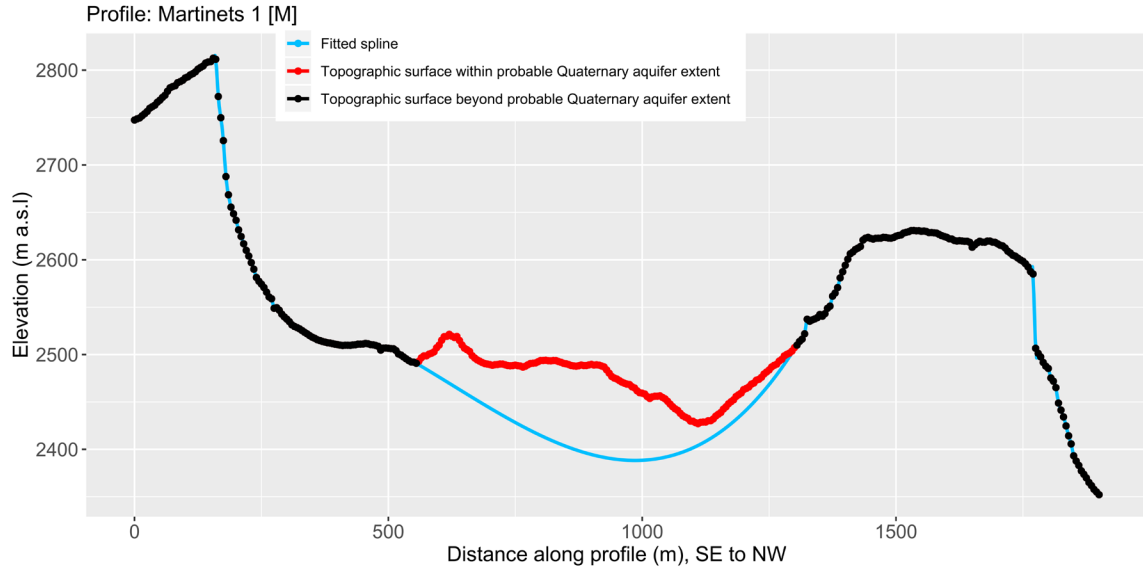
Profile: Nant 2 (GEOelectric) [N2]

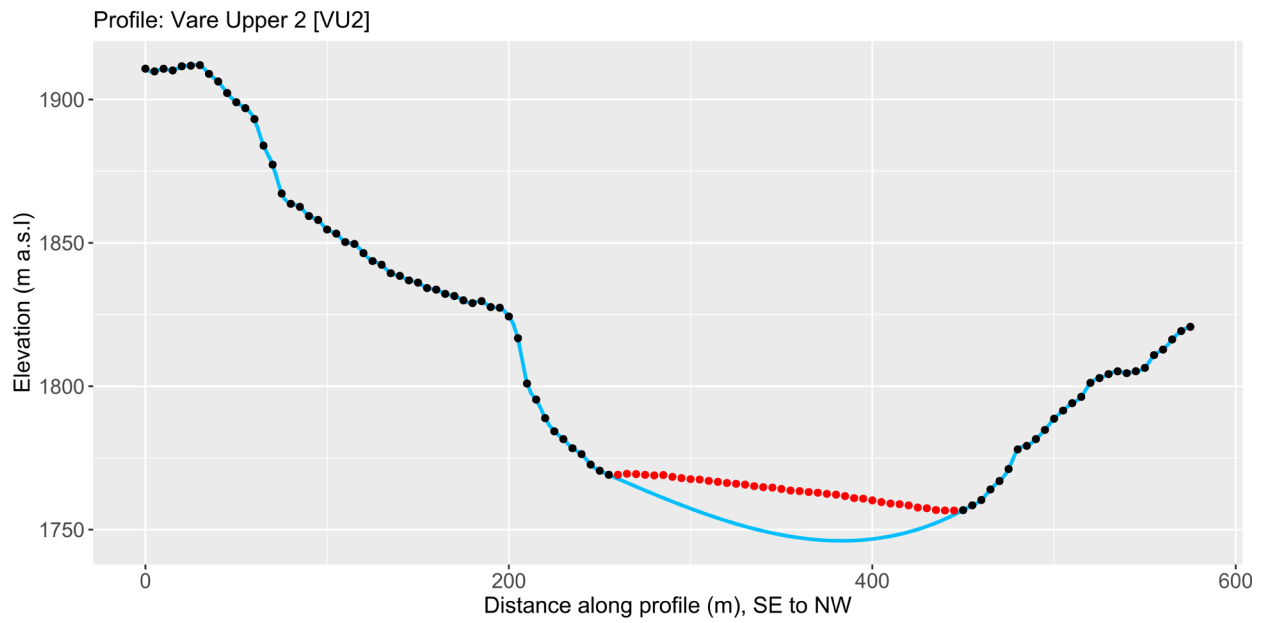
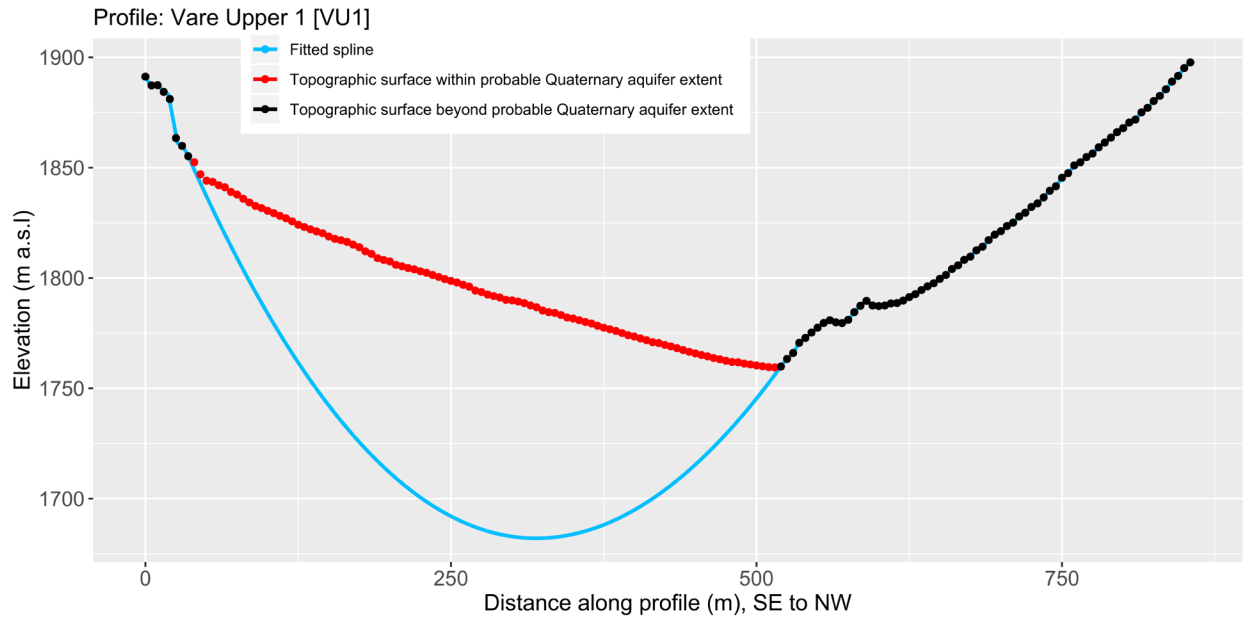


Profile: Nant 3 (GEOelectric) [N3]









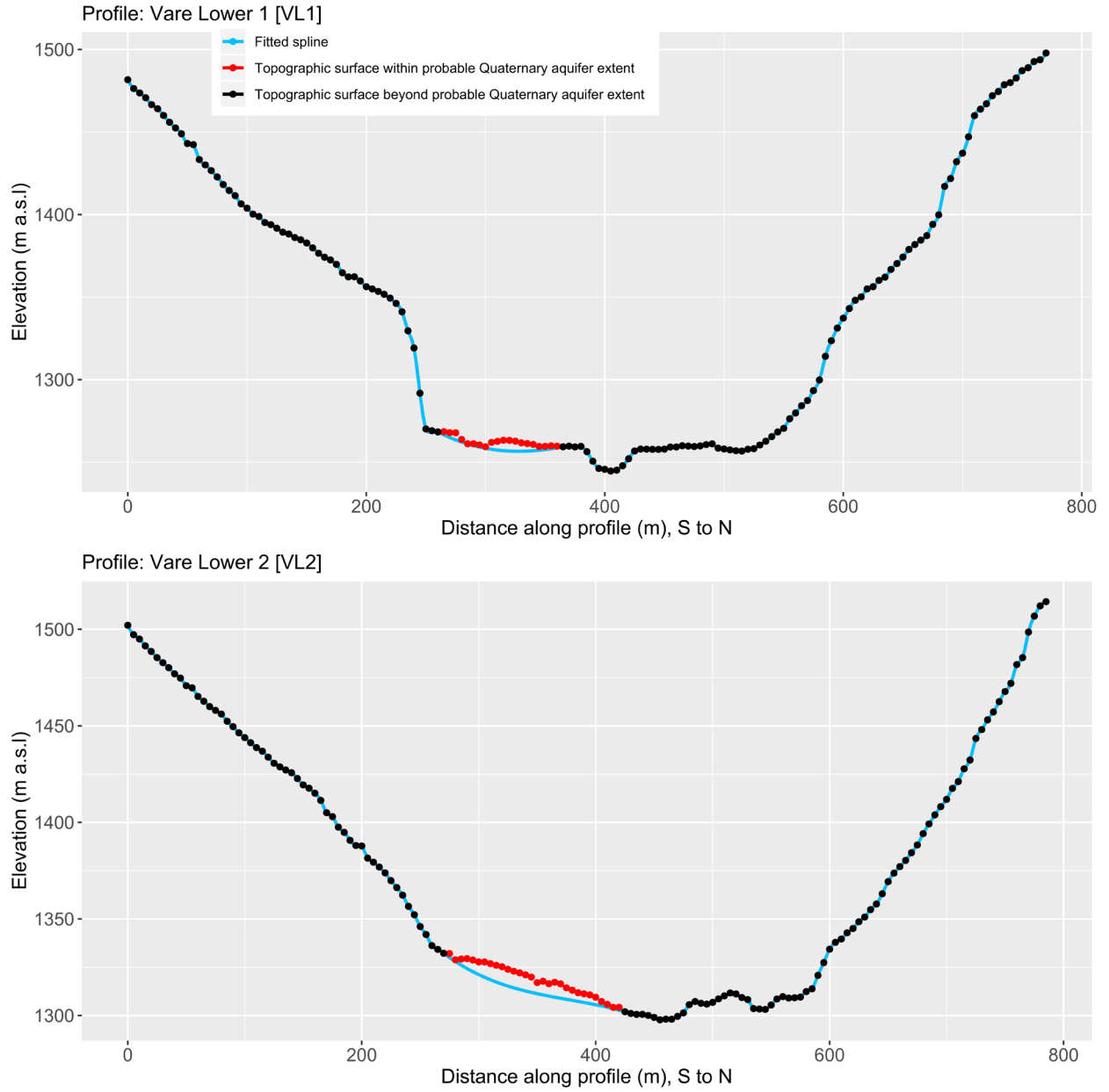


Figure S13. Interpolated 2D cross-sections for each of the 13 topographical transects. For the three profiles pertaining to Nant, interfaces derived from the geophysical surveys were included in addition to the topographic points immediately outside the sedimentary features in order to constrain the estimated 2D bedrock interface. Elsewhere, the 2D interpolations were informed solely by the bedrock gradients immediately beyond the sedimentary feature in question.

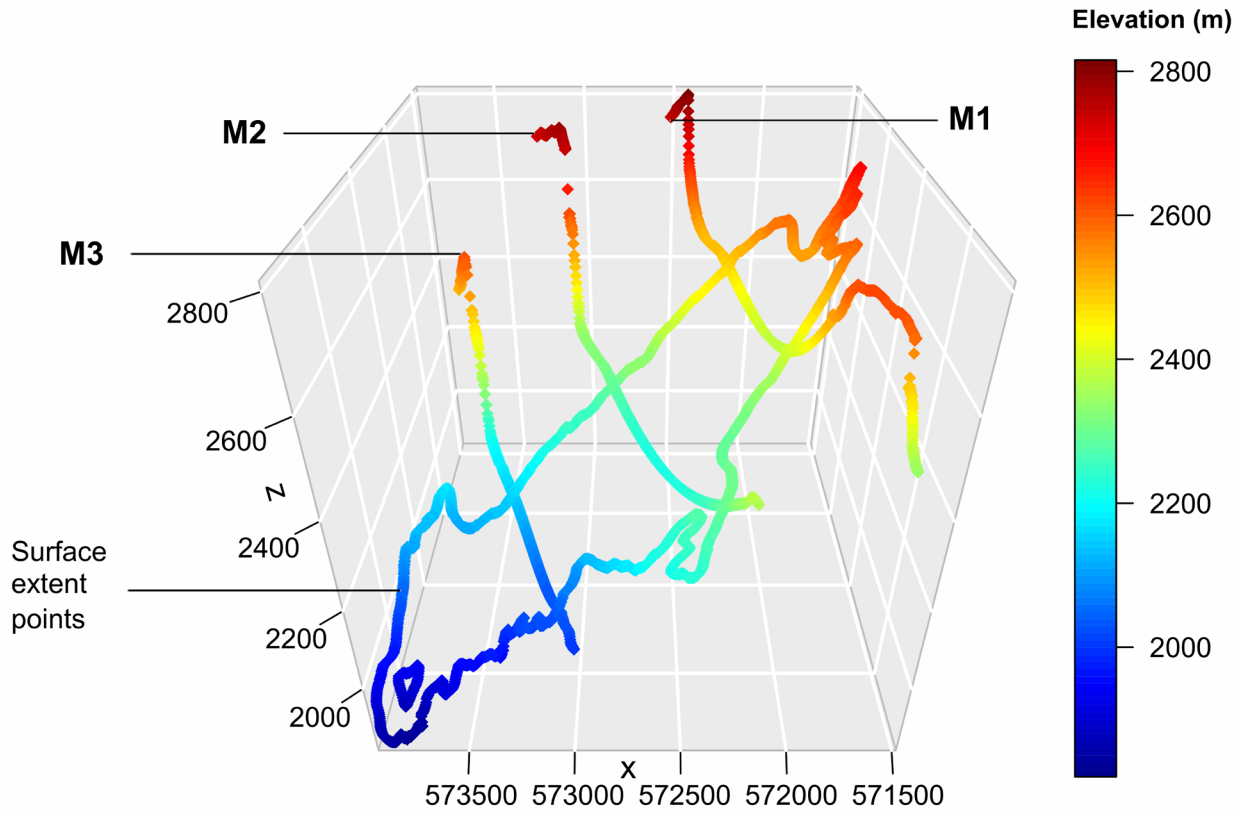


Figure S14. 3D points forming the input to the Thin Plate Spline (TPS) interpolation of the bedrock interface beneath the moraines of Les Martinets, looking due south.

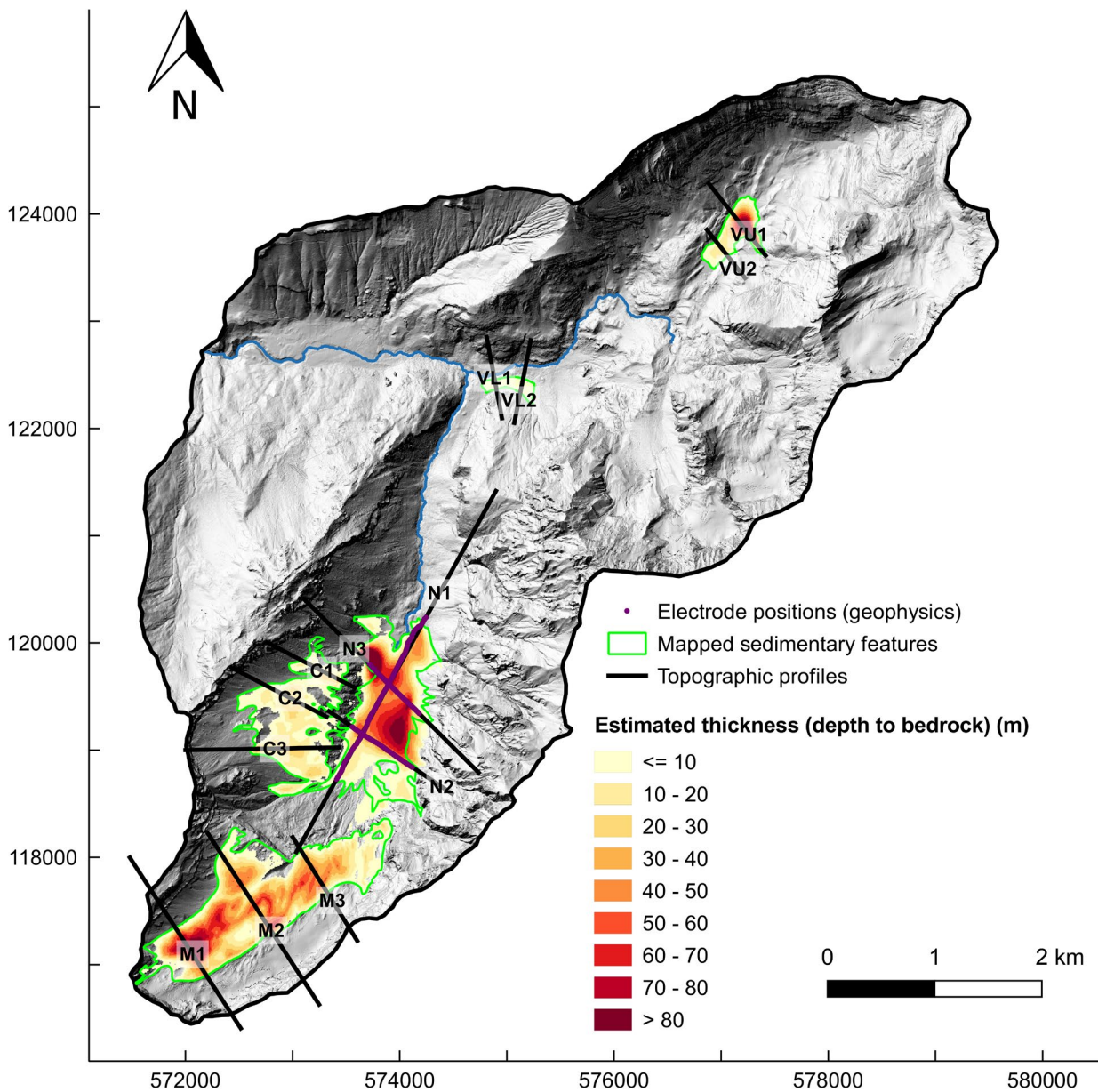


Figure S15. Estimated depth to bedrock within unconsolidated sedimentary features that were identified as potentially to host important aquifers. In the case of Nant, the result was generated by combining bedrock interfaces inferred from electrical resistivity images along the three profiles and the results from the geomorphometric method. The remaining features could not be practically surveyed with geophysics, and so the purely desk-based geomorphometric method was used here.

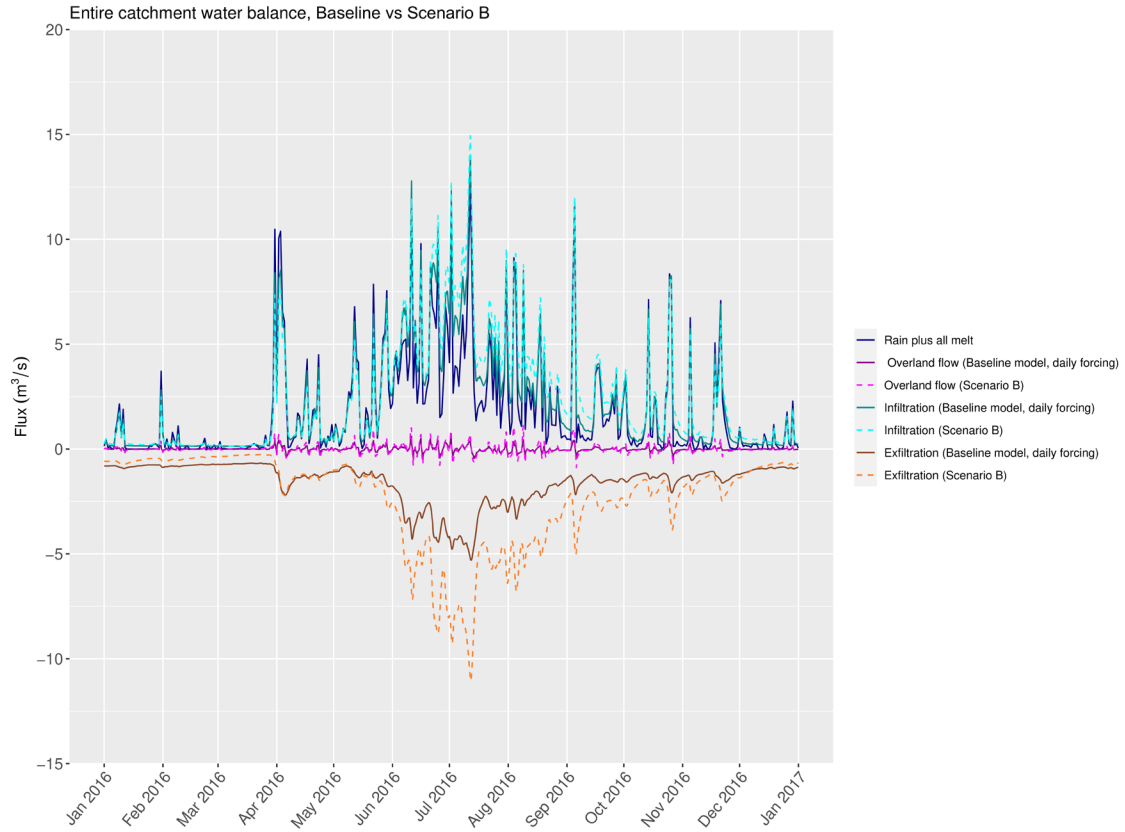


Figure S16. Comparison of the catchment water balance simulated under the fully-complexity integrated model with daily data, and the model whose vertical extent was limited to 30 m (Scenario B).

Text S1. Estimating geometries of potential unconsolidated Quaternary aquifers

Recent dedicated field campaigns have elucidated the hydrological importance – in the sense of having the capacity to store and then subsequently release substantial quantities of groundwater – of various individual unconsolidated Quaternary sedimentary features, such as talus slopes, moraines, alluvial fans, and rock glaciers, that are commonly encountered in alpine settings (Hayashi, 2019; Somers & McKenzie, 2020). However, researchers have few practical, cost-effective methods at their disposal to accurately estimate the 3D geometries of several such features across entire rugged, largely inaccessible mountainous headwater catchments. This is problematic because model structures should ideally be constrained as tightly as possible initially in order to limit the potential for parameter values to take on values that compensate for poor structures to reproduce the “right answers”, but for the “wrong reasons” (which could have severe implications for subsequent predictions).

In absence of borehole information, geophysical methods (e.g. Sass, 2006; McClymont et al., 2011, 2012) generally yield the strongest geometrical constraints. Whilst therefore recommendable in principle, they are also very labour intensive. Given this and the fact that the routinely generated resultant data 2D, it is generally not possible to survey more than perhaps one or two such features with sufficient density to provide meaningful 3D insights. In addition, environmental protection measures in sensitive mountain regions may preclude the use of certain geophysical techniques (e.g. seismic methods).

Traditional desk-based geomorphometrical methods, meanwhile, are certainly more efficient across larger areas, but the accuracy of the resultant estimate may be compromised, especially in light of the distinctive characteristics of alpine terrain. Several geomorphometrical approaches to estimating the sediment/bedrock interface along 2D cross-sections perpendicular to the main valley axis have been considered. Perhaps the most straightforward approach involves simply projecting hillslope gradients into the subsurface (Hinderer, 2001). The fitting of power laws (Svensson, 1959) and quadratic functions (Wheeler, 1984) to empirical cross-section data have also proved rather popular (James, 1996; Li et al., 2001), even if much of this work was undertaken in attempts to try to better understand valley formation processes, whereby the fitted parameter values are interpreted (e.g. a power law exponent, b , approaching two is taken to be indicative of parabolic “U-shaped” glacial valleys, whilst values closer to one are considered to signify fluvially-incised “V-shaped” valleys), rather than current geometries.

Nevertheless, if elevation points along the profiles corresponding to the sedimentary fill are removed prior to curve fitting, erosional upper bedrock surfaces can be reconstructed (Harbor & Wheeler, 1992). A fairly dense array of cross-sections must usually be considered to capture any longitudinal variability in the 2D profiles, and a final interpolation undertaken to produce a 3D result. Schrott et al. (2003), for instance, took such an approach in a small catchment in the Bavarian Alps, Germany, but found that the surfaces produced by polynomial fitting overestimated sediment thicknesses compared to coincident seismic refraction surveys. Not dissimilarly, Rogger et al. (2017) used a geomorphometrical approach to augment geophysical insights; sediment thicknesses were estimated at many different cross-sections by “extending the bare rock surface below the sediment deposit through a parabola fitted to the bedrock slopes at the outcrop boundaries”.

Major drawbacks have been identified with both the power law and quadratic methods, however (Harbor & Wheeler, 1992; Pattyn & Van Huele, 1998). Specifically, power law functions must be fitted to both sides of a given valley cross-section independently, since the variable representing horizontal distance cannot

take negative values. Additionally, power law functions must pass through the origin of the coordinate system used, yet where this location should be is generally unknown at the outset – above all when the very aim is to interpolate the bedrock surface beneath sedimentary fill deposits. This issue renders the results sensitive to the choice of origin. The logarithmic transformation that is typically applied to solve for the constants of power law equations compounds the problem, since it causes more weight to be placed upon those points located near the origin than those towards the profile's extremities. Quadratic functions, meanwhile, assume that the cross-sectional form is parabolic and symmetrical, and are hence poorly suited to representing any form of asymmetry in such profiles.

A more modern but related approach to the estimation of glacial valley bedrock forms is the Sloping Local Base Level (LSBL) method (Jaboyedoff & Derron, 2005). This technique requires a digital terrain model (DTM) as input. Via the iterative calculation of quadratic parabolas, the topographic surface within the region of sedimentary fill is then progressively “excavated”, leaving a curved 3D bedrock surface. A crucial impediment to the wider implementation of this technique is that the maximum expected depth to bedrock, must be specified *a priori* (Otto et al., 2009), yet this is typically a key unknown to be determined. More recently, Mey et al. (2015) presented an approach to the estimation of valley fill thickness/bedrock surface topography that revolves around training a machine learning algorithm using geometrical landscape data – specifically, the sectoral distance to the nearest bedrock hillslope, with the training data being generated by artificially filling DTMs. The approach hinges on the morphological similarity of the hillslope above the valley fill and the bedrock interface beneath it. Whilst results were promising with respect to estimating the thicknesses of sediments stored in the floor of large, almost horizontal intermontane valleys, the method would appear to be less immediately applicable to smaller alpine headwater catchments with their steeper sloping deposits.

As this last point alludes to, a further limitation of all the aforementioned geomorphometrical methods – and one which is particularly important given the complex nature of the bedrock geology at the present study site – is that geometric similarity above and below the fill level is assumed. In other words, no account is taken of lithological contrasts which, where present, bring about discontinuities in the cross-sectional profiles and terrain morphology more generally. The geostatistical approach developed by Castilla-Rho et al. (2014) used splines – a geomorphometrical technique that is better able to account for cross-sectional variability – in conjunction with various other datasets to estimate the bedrock interfaces of fluvial valleys.

As a consequence of these issues, it remains challenging to establish the extent to which the combination of these unconsolidated features contributes to the hydrological functioning of the broader catchment systems within which they are embedded, including their contributions to streamflow. Indeed, in integrated and other similar numerical model applications in mountainous areas, it remains common to rely on extremely simplified representations of potential unconsolidated aquifers (e.g. spatially uniform thicknesses) to be applied (Floriantic et al., 2018; Smoorenburg, 2015).

From this brief review, it seems unlikely that any ideal solution to this challenge presently exists, and that a combination of a geomorphological approach with constraints from geophysics might therefore represent a pragmatic compromise. As such, with a view to informing development of the integrated model described in the main paper, a simple 2D and 3D spline-based geomorphometrical approach involving the targeted extraction of digital terrain and geological map data is presented. This is fairly similar to the approach of Castilla-Rho et al. (2014), but without stochastic quantification of uncertainty (which fell beyond our scope). It is shown that, where available, bedrock interface constraints inferred from

geophysics – in the case of an electrical resistivity tomography (ERT) survey – can easily be incorporated. Ultimately, it is hoped that the approach provides a means by which catchment-scale groundwater and integrated surface-subsurface model structures can be refined compared to present practices.

The first step of the methodology involved identifying any major sedimentary features with the potential to act as aquifers (i.e. can store and subsequently release meaningful quantities of water) and establishing their surficial extents. This step required some general understanding of the hydrogeological system – especially qualitative knowledge of where the major aquifers are located. This understanding was developed by basic field measurements and reviewing various existing datasets.

More specifically, feature identification placed reliance on existing detailed (pre-digitised) surface geological maps (the swisstopo GeoCover25 dataset; https://shop.swisstopo.admin.ch/en/products/maps/geology/GC_VECTOR) and a high (2 m) resolution terrain “hillshade” map which was developed from the swissALTI^{3D} dataset (https://shop.swisstopo.admin.ch/en/products/height_models/alti3D). Unconsolidated sedimentary deposits were marked on the geological maps, and are furthermore clearly discernible in the “hillshade” map. Previous studies pertaining to the hydrogeological function of certain types of features (e.g. proglacial moraines) were also consulted as necessary. In this way, the following five principal features were identified:

- A large alluvial fan system, referred to henceforth as *Nant*;
- High proglacial moraine sediments of the Glacier des Martinets – *Les Martinets*;
- Glacial drift sediments – *La Chaux*;
- Generic unconsolidated fill sediments in a karstic, topographically closed depression (i.e. a doline) – *Vare Upper*, and;
- Generic unconsolidated fill sediments – *Vare Lower*.

These five features were treated as distinct zones so that in the subsequent integrated model, different hydraulic properties reflecting their specific histories and constituent materials could be assigned to each in the integrated flow model. The spatial extents of these features were extracted as shapefiles from the GeoCover25 maps and verified with reference to the hillshade map. The resultant areas are presented in Figure S10. In a final preliminary step, the x, y , and surface elevation, z , attributes of points spaced at 5 m intervals along the feature boundaries (i.e. where sediment thickness = 0) were extracted from the DTM, and the resultant coordinate triplets recorded along with an identifier of the feature to which they correspond.

As previously discussed, in seeking to estimate Quaternary aquifer geometries, as much geophysics as possible should ideally be conducted. That said, the practical and monetary constraints to such approaches are elevated in rugged alpine terrain. With such considerations in mind, and within the very broad scope of this study, only one geophysical technique could be deployed here, and only a single unconsolidated formation surveyed. Since the main alluvial fan in the central part of the Vallon de Nant (i.e. Nant) was believed to constitute the most important unconsolidated formation in hydrological terms, attention was focussed here. This feature also happened to be comparatively accessible; having obtained the necessary special permissions, off-road vehicular access was possible as far as Chalet Nant – a now uninhabited farm building in the alpine pasture.

The survey's primary objective was to determine the spatial distribution of depth to bedrock; any potential insights that could be gleaned with regards to internal structure would be considered a bonus. Seismic methods (used by Schrott et al., 2003, amongst many others) were discounted due to the Natural Reserve's regulations, whilst the depth of information provided by ground-penetrating radar is too limited. Finally, we decided to rely on ERT, which we expected could provide information about the lithological structure down to depths ~100-200 m. A four-day long field campaign was conducted in favourable meteorological (dry and sunny conditions) in September 2018 – the first attempt to image the subsurface of this pristine Alpine valley.

With the objectives in mind, the intended profile layouts and electrode spacings were planned in advance. Three separate profiles were identified; one long one of 1,780 m running approximately parallel to the main valley axis (N1), and two shorter perpendicular profiles of 700 m each (N2 and N3) (Figure S11). The former sought to capture any longitudinal variability in the bedrock interface (i.e. along the valley axis), for instance due to glacial over-deepening, which is common in such settings. The two intersecting transverse profiles sought to provide some 3D constraints on the morphology of the upper bedrock surface (and hence the unconsolidated sediment thickness); the ultimate goal being to develop a 3D flow model after all. In order to image comparatively deep, a 20-m electrode spacing was chosen.

Once in the field, where conditions allowed, the stainless-steel electrodes were hammered in to a depth of 10-20 cm. The length of N1 necessitated a "roll-along" technique. At locations without soil cover (see e.g. Figure 4.8b), electrodes were positioned firmly in the silty sediments between larger boulders and pebbles, and sponges dampened with salt water were applied to decrease the contact resistance. Typically, contact resistances between electrodes of less than 5 kOhm were achieved. The electrode positions were measured accurately using a Leica Differential GPS device; these are plotted in Figure S11. Relatively straight profiles could be maintained, and so any corresponding 3D distortive effects in the results should be minimal.

The apparent resistivity measurements were acquired in both dipole-dipole and Wenner-Schlumberger configurations using an IRIS Syscal Pro instrument. The current injection cycles (500 ms) were repeated four times and the measurements were stacked in order to improve the signal-to-noise ratios. Prior to inversion, the data from the Wenner-Schlumberger and dipole-dipole surveys were combined, giving a total of 3,353 measurements for N1, and 793 measurements for N2 and N3, before any measurements whose standard deviation exceed 3% were removed. The inversions were performed in a fairly standard fashion using the code BERT (Günther, Rücker and Spitzer, 2006). Robust data reweighting and compact inversion using iteratively-reweighted least-squares were employed to reduce the influence of outliers and to image sharper interfaces, respectively. The inversion process converged in 10 iterations, with a final relative root-mean square error of <5%.

The three resultant resistivity images (Figure S12) were interpreted both independently and in combination. To facilitate the latter, they were georeferenced and visualised in conjunction with the surface topography within a virtual environment (Movie 3). This step also enabled the coherence of the inversion results near the profiles' intersection points to be verified. Next, a plausible bedrock interface was tentatively identified and annotated on the images (along with other possible interpretations). Finally, the spatial coordinates (x,y,z) of points placed at regular intervals along the identified subsurface interface were extracted.

The next phase of the methodology was to make a series of 2D interpolations at the various cross-sections. To achieve this, the geophysical transects and other topographical profiles were first extended, points were generated at 5 m intervals along the full profiles, the surface elevation (z) extracted from the DTM, and the horizontal distance from the respective profile start points calculated. Then, for each feature independently, the surface elevation points were plotted against the horizontal distances, and any points falling within the unconsolidated sediment extents (identified via spatial intersection with the feature shapefiles) were removed. These points are represented in red in Figure S13.

Following that, cubic splines were fitted to interpolate between the remaining points. As a class of functions, splines are local interpolators which seek to fit the empirical data points exactly (or extremely closely, by minimising the sum of the squared residuals) whilst simultaneously maximising smoothness, by penalising roughness (Mitas and Mitasova, 1999). They are generally favoured over high-order polynomials because the latter can result in strong oscillations. The specific technique of cubic spline fitting involves establishing piecewise third-order polynomials that pass through all of the control points. In this way, the upper bedrock surfaces along each transect were estimated. For the three profiles in the *Nant* feature, the additional subsurface interface derived from the geophysics results were included in the 2D interpolations in the same fashion as the topographic points beyond feature extents.

The smoothness of the resultant interpolations makes splines well-suited to the task of reconstructing “U-shaped” glacial valleys; the smooth interfaces they propose beneath the sediment-obscured regions correspond to the simplest possible models. Simultaneously, in being able to follow sharp elevation discontinuities in the bedrock outcrops, which arise here due to lithological contrasts, these points do not influence the reconstructed interfaces. In other words, the upper bedrock surface estimates along each transect were consistent with the bedrock gradients immediately beyond the feature extents. It follows that should any lithological “steps” occur beneath the zones of sediment fill, these would not be captured. Such “steps” are generally not too problematic in this case, however.

In certain instances, the interpolated interfaces did demonstrate a fairly high degree of sensitivity to the elevation gradients immediately beyond the sedimentary feature extents, and hence to the inclusion/exclusion of sampled points near the sediment/bedrock interfaces. This is similar to the finding of Mey et al. (2015), who also noted a certain sensitivity to the accuracy of the mapped feature “mask”. In fact, here, there was no hard condition to stipulate that the resultant interpolated surface should remain beneath the topographic surface. That said, the original surficial extent mapping (and hence the distinction between which points lay within the unconsolidated region and which lay beyond it) was certainly not perfect. This observation justified the manual additional removal of a few points in certain cases in these boundary regions, leading to interface profiles that were i) more consistent with prior expectations, and ii) were sufficiently coherent with others in the same feature. The final resultant splines are shown as the light blue lines in Figure S13.

The surface coordinates (i.e. x,y) of regular points along the interpolated spline function beneath the sedimentary fill were calculated using trigonometry and recorded along with the elevation estimates (z). Finally, the triplets (x,y,z) were grouped by feature, and pooled with the corresponding surficial extent triplets (i.e. where thickness = 0) that had been generated already. For illustration, Figure S11 shows all points prior to 3D interpolation for the *Les Martinets* feature.

Finally, the 3D interpolations could be undertaken. For each feature independently, all 3D (i.e. x,y,z) points which corresponded to an observed or estimated sediment thickness of zero (i.e. the bedrock interface) were interpolated using Thin Plate Spline (TPS) functions – which imitate thin steel sheets forced to pass through the points – to give a spatially continuous 3D surface (with 10 m horizontal resolution). The smoothing parameter was identified automatically by generalised cross-validation. Where necessary, the resultant raster dataset was clipped to the feature boundaries. The final estimated unconsolidated sediment thickness distribution is shown in Figure S12.

Given the relative ambiguity of the bedrock interface from the geophysical results (essentially due to their being no strong contrasts in resistivity – the clay rich Flysch bedrock apparently having fairly similar properties to the unconsolidated materials), as well as the potential for the internal structure, which could not be determined using the large electrode-spacing used here, having potentially high hydrological importance (for instance, a very shallow clay layer could be observed in the field in regions of the main alluvial fan aquifer at *Nant* after an erosive flow event), the entire depth to bedrock beneath the alluvial fan was not defined as being eminently permeable for the purposes of the subsequent numerical modelling. Instead, only the upper third of the total thickness was considered as such, with the lower permeability till/clay assumed to comprise the remaining volume. This is essentially akin to defining the alluvial fan base according to a lower resistivity isosurface than the bedrock interface in S12; somewhere in the light blue region. Such an approach is justified by the fact the ERT appears to be mapping the fan and the till as a common low-resistivity feature above the bedrock interface. The technique is also known to have a tendency to somewhat overestimate the size of conductive anomalies – in this case the coarse gravel region of the fan. Since the geomorphometrical method provided no insight whatsoever in the other formations, they were assumed “hydrologically active” to their full depth.

For an extended description of the method and results, readers are directed to Chapter 4 of Thornton (2020). This doctoral thesis is currently under embargo but can be provided confidentially by the corresponding author upon request.

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Table S1. Evapotranspiration parameter values in the integrated model, rounded to two significant figures. d_e is evaporation depth, d_r root depth, LIA range gives the annual minimum and maximum Leaf Area Index (with monthly variability between these values), C_1 , C_2 , and C_3 are transpiration fitting parameters, and H_{wp} , H_{fc} , H_{ol} , and H_{al} are the pressure heads at the wilting point, field capacity, oxic limit, and anoxic limits, respectively. H_{etz} is the pressure head below which evaporation is zero, and H_{etz} the pressure head above which full evaporation can occur. c_{int} is the canopy storage parameter. For parameters that were subjected to calibration, the initial values, lower and upper bounds permitted, and the final value obtained are specified. Evaporation from the bedrock, glaciers, unconsolidated rock, and streambed zones was deactivated in the model. All free parameters were log-transformed to improve the numerical robustness of the process.

Table S2. Surface parameter values in the integrated model, rounded to two significant figures. n_{xy} is the Manning's roughness coefficient, h_{ds} is the depression (or rill) storage height, h_o is the obstruction storage height, l_{exch} is the surface-subsurface coupling length. For parameters that were subjected to calibration, the initial values, lower and upper bounds permitted, and the final value obtained are specified. *Except where permafrost, in which case l_{exch} was assigned a value of 50 m. All free parameters were log-transformed to improve the numerical robustness of the process.

Table S3. Subsurface parameter values in the hydrological model, rounded to an appropriate degree of precision. k_{xy} is horizontal saturated hydraulic conductivity, k_z is vertical saturated hydraulic conductivity, θ is effective porosity, S_s is specific storage, and α and β are parameters of the Van Genuchten unsaturated retention functions. These functions were simplified for all subsurface formations except soils. For parameters that were subjected to calibration, the initial values, lower and upper bounds permitted, and the final value obtained are specified. The "subsurface.mprops" file in the Supplementary Materials details the simplified unsaturated parameterization applied in non-soil zones. $k_z = k_{xy}$, except where indicated. All free parameters were log-transformed to improve the numerical robustness of the process.

Movie S1. Upper: The evolution the daily frequency forcing data prescribed to the fully-integrated model (left: all liquid water inputs, i.e. rain + snowmelt + icemelt, and right: potential evapotranspiration). Lower: actual evapotranspiration (right) and surface water depth (left) simulated using the fully integrated model with daily frequency forcing data. The period shown is the 2017/2018 hydrological year, and the time-step of the animation is half-daily. The "days" are days from 1 October 2014. Note that the ET_p and ET_a scales are inverted because HGS writes the latter as a negative flux by default.

Movie S2. The evolution of catchment (surface) saturation (left) and the response of water level at gauging station S2 (right) over the course of the 2017/2018 hydrological year simulated using the fully-integrated model with daily frequency forcing. The time-step of the animation is half-daily (the “days” are days from 1 October 2014).

Movie S3. Animation illustrating the three electrical resistivity profiles that were obtained for the Nant feature. To provide additional context to the georeferenced profiles, the surface topography according to the Alti^{3D} digital terrain model is also represented. The bedrock interface was interpreted to be located around the transition from an upper region of lower resistivity to a lower region of higher resistivity (see the annotations on the profiles). This interface, which appears to be consistent between the profiles, was digitized (pink dots).