

1 Structure of the deep lithosphere between Pamir and Tarim

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24 **ABSTRACT**

25 The Pamir protrudes ~300-km between the Tajik and Tarim lithosphere of central Asia. It  
26 overlies a Wadati-Benioff earthquake zone connected to a low velocity zone interpreted as  
27 crustal rocks. Together with the mantle lithosphere it constitutes the arc-shaped Asian slab. We  
28 use new seismic data to better constrain the lithospheric architecture of the Pamir where it abuts  
29 the Tarim block and test competing models of its formation. With complemented local-seismicity  
30 and focal-mechanism catalogs and a P-wave velocity model that spans the Pamir and the western  
31 Tarim lithosphere, we infer the presence of a high velocity zone, interpreted as an Indian mantle  
32 lithosphere indenter, delaminating the Asian slab and overturning it in the eastern Pamir. The  
33 indenter bends down in the east under the northwestern Kunlun, where it terminates. The  
34 indenter–Tarim lithosphere interface is a compressive transform zone lined by a slice of Pamir  
35 Plateau crust. As the largest principal stress at depth parallels surface motion and both are highly  
36 oblique to the western Tarim margin, this crustal slice is likely dragged with the indenter and  
37 downward underneath the Tarim lithosphere.

38

39 **INTRODUCTION**

40 The Pamir—the northwestern prolongation of the Tibetan plateau—is bordered by the  
41 Tian Shan, the Tajik basin, and the Tarim basin, in the north, west, and east, respectively; the  
42 latter is a cratonic block (e.g., Lu et al., 2008). The northern Pamir and the Kunlun of  
43 northwestern Tibet comprise subduction-accretion-arc complexes accreted to and built on Asian  
44 continental basement. The central and southern Pamir and the Karakorum and Hindu Kush  
45 represent Gondwana-derived microcontinents and subduction-accretion-arc complexes (Fig. 1;  
46 Burtman and Molnar, 1993; Schwab et al., 2004). Beneath the Pamir, a band of intermediate-

47 depth (50–250 km) earthquakes extends from the southwestern Pamir northwestward into the  
48 central Pamir, bends eastward, and shows diminished earthquake activity beneath the eastern  
49 Pamir (Fig. 2; Pegler and Das, 1998; Sippl et al., 2013a). Receiver function images, seismic  
50 tomography, and the analysis of guided waves show that the earthquakes in the western and  
51 central Pamir reside in a 10–15 km thick, E- to S-dipping low velocity zone (LVZ) connected to  
52 the Asian lithosphere; seismic velocities indicate that the LVZ represents continental crust,  
53 constituting together with the underlying mantle lithosphere the Asian slab (Schneider et al.,  
54 2013; Sippl et al., 2013b; Mechie et al., 2019). Beneath the northwestern Kunlun, diffuse  
55 seismicity at 100–150 km depth was attributed to Tarim lithosphere underthrusting the Pamir  
56 (Fan et al. 1994; Pegler and Das, 1998).

57 Whether Asian lithosphere subducts as a narrow, back-rolling slab of thinned crust  
58 (Burtman and Molnar, 1993; Sobel et al., 2013) or whether forceful subduction/delamination of  
59 lower crust and mantle lithosphere due to indentation by cratonic Indian mantle lithosphere  
60 (Kufner et al., 2016; Metzger et al., 2017) occurs is debated. This debate impacts on the  
61 understanding of processes like continental subduction, indentation, delamination, and rollback.

62 If an indenter governs the shape of the Pamir orocline, its margins matter. Kufner et al.  
63 (2018) argued that a sinistral-oblique transform margin separates indenting cratonic Indian  
64 lithosphere beneath the Pamir from subducting Indian continental-margin lithosphere below the  
65 Hindu Kush. The most recent subduction model (Sobel et al., 2013) calls for rollback of a narrow  
66 Asian slab with thinned continental crust, involving mantle corner flow and a subduction-  
67 transform edge propagator fault separating the subducting Asian slab and its hanging wall from  
68 the Tarim block. However, geophysical data indicate that the hinterland crust is not thinned (>50  
69 km; Schneider et al., 2019). The delamination model (Kufner et al., 2016; Chapman et al., 2018)

70 calls for forced Asian slab subduction due to flat-slab underthrusting of a mechanically-strong  
71 Indian continental lithospheric mantle indenter, a process recently modeled for the Pamir (Kelly  
72 and Beaumont, 2021). The indenter is imaged by refraction seismics and local body wave  
73 tomography as a high velocity zone (HVZ) south of the Asian slab (Mechie et al., 2012; Sippl et  
74 al., 2013b). Teleseismic body and surface wave tomography shows that it connects with the  
75 exposed Indian craton (e.g., Li et al., 2008; Liang et al., 2020); its northern extent has remained  
76 unresolved due to the smearing of the HVZ with cratonic Asia.

77         Herein, intermediate-depth earthquakes, focal-mechanism stress data, and a P-wave  
78 velocity model derived from new and published local seismological data illuminate the  
79 lithospheric configuration of the central and eastern Pamir and the boundary zone with Tarim.  
80 We characterize the northern tip of an indenter—interpreted as a promontory of Indian mantle  
81 lithosphere—and its eastern edge, where it abuts on the lithosphere of the Tarim block. We use  
82 seismograms recorded with two new local seismic networks (Yuan et al., 2018a; 2018b) and  
83 additional regional stations (PMP International, 2005; SEISDMC, 2021) to locate seismicity in  
84 the eastern Pamir jointly with an existing catalog from the western and central Pamir (Sippl et  
85 al., 2013b), and invert for the 3-dimensional subsurface P-wave velocity structure. The full  
86 description of the data and methods (Fig. S1; Fig. S2), the seismicity catalog, and the velocity  
87 structure are presented in the Supplemental Material.

88

## 89 **SEISMICITY**

90         Crustal seismicity of the upper 30 km is dominated by the aftershock sequences of strong  
91 earthquakes that struck the Pamir in 2015/16 and is omitted from the main figures. The middle  
92 and lower crust (30–50 km depth) is essentially aseismic (Fig. S3). Intermediate-depth

93 earthquakes in the central and eastern Pamir outline three steeply-dipping, planar to curvilinear  
94 segments separated by regions of sparse seismicity (Fig. 2; Fig. 3).

95 Segment 1 begins at 72.8°E, 38°N, in continuation of the NE-striking, planar seismicity  
96 structure farther to the southwest (Fig. 2, Schneider et al., 2013; Sippl et al., 2013a). It forms a S-  
97 to SE-dipping band between 73°E and 74.3°E, and shows vigorous seismicity between 70–180-  
98 km-depth in its easternmost part (Fig. 3A; Fig. S2); farther east, seismic activity decreases.

99 Segment 2 in the eastern Pamir—in the direct continuation of segment 1—contains a few  
100 earthquakes at 50–80 km depth in a S-dipping structure (top dotted line in Fig. 3B). Below—at  
101 80–170 km depth—the earthquake-defined band dips N (Fig 2; bottom dotted line in Fig. 3B).  
102 Seismicity in segment 2 is less intense compared to segment 1 (Fig. S2). Focal mechanisms of  
103 segments 1 and 2 indicate a transpressional stress regime, with the maximum principal stress  $\sigma_1$   
104 trending N20°W and N12°W, parallel to the surface plate-motion directions, and a vertical  $\sigma_3$   
105 (Fig. 2).

106 Seismicity in segment 3 forms a continuous, ~ENE-dipping structure at 80–120-km-depth  
107 between 37°N and 38°N; it follows the northwestern Kunlun (Fig. 2; Fig. 3C). Seismic activity is  
108 comparably weak (Fig. S2). Focal mechanisms indicate transpression with  $\sigma_1$  trending N7°W,  
109 parallel to the surface plate-motion, and a down-dip  $\sigma_3$  (Fig. 2).

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## 111 **VELOCITY STRUCTURE**

112 In the shallow crust, northeast of the Main Pamir Thrust System (Fig. 3, overview map),  
113 the sediment fill of the Tarim basin forms a LVZ (<5 km/s, *TL* in Figs. 3B–D). In the middle–  
114 lower crust, the Tarim basement appears as a discontinuous HVZ (6.5–7.5 km/s, *TH* in Fig. 3C,  
115 Fig. 3E) at the poorly-resolved rim of the tomographic volume. A LVZ is located in the

116 uppermost mantle of northwestern Tarim (*AL* in Fig. 3G). An arcuate crustal LVZ extends below  
117 the northern Pamir, the Kongur Extensional System, and the northwestern Kunlun (5–6 km/s, *PL*  
118 in Figs. 3A–C and 3E). It is sandwiched between the Tarim basement HVZ, *TH*, and another  
119 crustal HVZ in the central Pamir (6–7 km/s, *PH* in Fig. 3A; Fig. 3E).

120 At mantle depths, dipping LVZs are located above the seismicity in segments 1–3 (7–8  
121 km/s, *L1*, *L2*, *L3* in Figs. 3A–C and 3F). The LVZs *L2* and *L3* of segments 2 and 3 appear  
122 continuous in map view (Fig. 3F), but are separated by the seismicity of segment 2 (Fig. 3B).  
123 The seismically active structures are underlain by HVZs (8.5–9.5 km/s, *H1*, *H2*, *H3* in Figs. 3A–  
124 C and 3G) and have the same dip as the LVZs above. In segment 1 and 2, the HVZs *H1* and *H2*  
125 are continuous along strike below ~105 km depth (Fig. 3G). In segment 2, the HVZs *H2* and *H3*  
126 touch, but are separated by seismicity in the same way as the LVZs *L2* and *L3* (Fig. 3B; Fig. 3G).  
127 The LVZs and HVZs of segment 1 (*L1* and *H1*; Fig. 3A) and segment 3 (*L3* and *H3*; Fig. 3C) dip  
128 in the same direction as the seismicity structures; those of segment 2 (*L2* and *H2*; Fig. 3B) dip  
129 oppositely.

130

## 131 **INTERPRETATION AND DISCUSSION**

132 We visualize our interpretation of the lithospheric architecture of the central and eastern  
133 Pamir in the block diagram of Figure 4. Sippl et al. (2013b) inferred eclogitization of the lower  
134 crust of segment 1 due to the sinking of the Asian slab and that this lower crust hosts the band of  
135 intermediate-depth earthquakes; in our tomogram, we interpret the LVZ *L1* as the lower crust and  
136 the HVZ *H1* as the mantle lithosphere of the Asian slab (Fig. 3A). The aseismic mid-crustal LVZ  
137 *PL* (Figs. 3A–C and 3E; see also Sippl et al., 2013b; Li et al., 2018), possibly connecting the  
138 upper crustal imbrication of the Main Pamir Thrust System with tectonic stacking along shear

139 zones in the middle crust (Fig. 1, cross section), may represent a heated rock volume, developed  
140 by excess radiogenic heat production in the thickened crust. Heating due to asthenospheric  
141 inflow in the hanging wall of a S-dipping subduction zone is unlikely, as the tomogram does not  
142 show a LVZ south of the seismic zone; in contrast, subcrustal P velocities are >8km/s with HVZs  
143 (>8.5 km/s) embedded (e.g., *H3*), indicating relatively cold and rigid lithospheric mantle south of  
144 the Asian slab.

145         Segment 2 appears to be the eastern continuation of segment 1 of the Asian slab because  
146 of the similar depth extent of the seismic zone and the continuity of the underlying HVZ (Fig. 2;  
147 Figs. 3A, 3B, and 3G). The seismically active structure is overturned below ~80 km depth. A tear  
148 likely separates segments 1 and 2 because of the short (~40 km) distance across which the slab  
149 dip changes and the separating seismicity gap. The Asian slab terminates in a seismicity cluster  
150 below the Kashgar-Yecheng Transfer System at 76.2°E (Fig. 2), where it appears torn off Tarim's  
151 lithosphere to the east. The dip beyond vertical of segment 2 may be an indication of indentation,  
152 because rollback alone cannot steepen the slab to more than vertical (Magni et al., 2013).

153         For segments 1–3,  $\sigma_1$  at depth is parallel to the ~NNW-oriented surface velocity of the  
154 Pamir crust (e.g., Zubovich et al. 2010, Ischuk et al., 2013, Metzger et al., 2020). The  
155 subhorizontal  $\sigma_1$  indicates that a NNW–SSE compressive stress field governs the deep structure  
156 of the Pamir, which favors a pushing indenter. In contrast, N–S extension should occur S of the  
157 slab if deformation below the Pamir was governed by a narrow Asian slab rolling back  
158 northward. Parallelism of the surface motion with  $\sigma_1$  at depth implies that the lithospheric mantle  
159 is coupled to the crust. For segments 1 and 2 it arises if collision occurs at an indenter tip.

160         In concert with the lack of thinned hinterland crust and the imaging of a HVZ at ~200 km  
161 depth below the Pamir-Karakorum that connects with the exposed Indian craton, the following of

162 our observations support the presence of an indenter below the Pamir: (1) the repeated detection  
163 of HVZ *H3* south of the Asian slab (Mechie et al., 2012; Sippl et al., 2013b; this study) that  
164 excludes asthenospheric inflow above a S-dipping, back-rolling subduction zone; (2) the  
165 overturned dip of the seismic plane of segment 2; (3) the NNW–SSE compressive stress field  
166 across the central and eastern Pamir at mantle depth that is coupled with surface motion.

167         The indenter is most likely cratonic Indian lithosphere, because the lithosphere of the  
168 central and southern Pamir terranes would be too weak to transmit enough force to delaminate  
169 and overturn the Asian slab (Kelly and Beaumont, 2021). We locate the delamination front at the  
170 base of the rheological weak mid-crustal LVZ *PL* (red line in Fig. 4). The present location and  
171 form of the Pamir and the Asian slab is in this interpretation governed by the shape of the  
172 indenter. Additional structural complexity, such as the location of slab tears or turn-overs, may be  
173 due to lateral changes in the strength of the indented Asian lithosphere or the along-strike  
174 variability of the indenter tip (Li et al., 2016; Kelly and Beaumont, 2021). For example, the mid-  
175 crustal HVZ *PH*, which overlies a distinctive Moho bulge in segment 1 (Fig. 3A; Schneider et  
176 al., 2019), may represent a lithosphere-scale anticline; in segment 1, the top of the indenter  
177 appears to rise higher than in segment 2 and in particular in segment 3 (Fig. 4).

178         In the northwestern Kunlun, the seismicity band of segment 3, the LVZ *L3*, and the HVZ  
179 *H3* dip ~ENE, indicating that Pamir crust and indenter mantle lithosphere underthrusts the Asian  
180 mantle lithosphere (Fig. 3C). The earthquakes may occur in thickened crust undergoing  
181 eclogitization. This crust is dragged to depth between the bulldozing indenter and the margin of  
182 the Tarim block. The underthrusting interpretation is supported by a doubled ~E-dipping Moho  
183 (Xu et al., 2021). The stress field of the earthquakes inside the underthrusting crust *L3* indicates  
184 that it moves with the NNW-ward moving indenter. The orientation of  $\sigma_1$  in segment 3 testifies

185 that underthrusting is highly oblique with respect to Tarim hanging wall. As the tomographic and  
186 receiver function Moho both dip ~WSW beneath the northwestern Kunlun east of LVZ L3 (Fig.  
187 3C; Xu et al., 2021), we infer that Tarim underthrusts the northwestern Kunlun as well, building  
188 a stack of Pamir and Kunlun–Tarim crust (Fig. 4C). This excess crust may be responsible for a  
189 positive anomaly in the isostatic gravity residual (Balmino et al., 2012; 20-mGal-contour in  
190 Fig. 2) that flanks the northern edge of the Tibet plateau (Fig. 2, inset), and was interpreted to  
191 represent thrusting of Tarim crust under the western and central Kunlun (Wittlinger et al., 2004).

192         The transpressive stress field of the deep seismic zone (segment 3) outlines a compressive  
193 lithospheric transform zone as the deep plate boundary between the Indian indenter and the  
194 Tarim block. It changes to a forced subduction/delamination boundary due to indentation under  
195 the central Pamir. The tear that separates the Asian slab from Tarim propagates northward with  
196 the advancing indenter. Indentation may have caused the capture and dragging along of the crust  
197 from the collision system into the transform zone (Fig. 4C). The transform margin likely  
198 transitions southeastward into a subduction plate boundary where the Tarim block underthrusts  
199 the western Tibet plateau. Our interpretation of the deep structure suggests a strong along-strike  
200 segmentation of the northern tip of the Indian plate; it subducts under the Hindu Kush (Kufner et  
201 al., 2021), indents in the Pamir (this study), and has variable dip angles and locations in the rest  
202 of Tibet (e.g., Zhao et al., 2011).

203

## 204 **CONCLUSION**

205 We located zones of intermediate-depth seismicity in the eastern Pamir and northwestern  
206 Kunlun, established their geometries, determined the principal stress orientations, and computed  
207 a seismic velocity model of the subsurface. We traced a subducting/delaminating Asian slab

208 eastward as far as the western edge of the Tarim block and showed that the eastern segment of  
209 the slab is overturned and torn from the central one. Together with the presence of a high  
210 velocity zone in front of the slab and the parallelism of the largest principal stress at depth with  
211 surface motion across the eastern and central Pamir, this geometry indicates underthrusting of  
212 Indian mantle lithosphere beneath the Pamir and delamination of the Asian slab. A slice of lower  
213 crust is dragged along with the indenter and smeared into the compressive transform boundary  
214 with the Tarim block at depth.

215

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231 Figure 1: Tectonic units of the Pamir in map view and as a schematic cross section along  $\sim 74^\circ\text{E}$ .  
232 MPTS: Main Pamir Thrust System; KYTS: Kashgar-Yecheng Transfer System; KES:  
233 Kongur Extensional System.

Figure 2: Seismotectonic map of the Pamir and northwestern Kunlun with seismic networks, seismicity, focal mechanisms, principal stress directions, earthquake P-, T-, N-axes, global navigation satellite system (GNSS) velocity field (Zubovich et al., 2010; Ischuk et al., 2013), and 20mGal positive isostatic gravity anomaly (Balmino et al., 2012). TJS, Tanymas-Jinsha suture.

Figure 3: Sections through the tomogram. A-C) Profiles shown on overview map. Magenta: Receiver function Moho (Schneider et al., 2019; Xu et al., 2021). D-G) Horizontal sections. TH, PH, H1, H2, H3: high velocity zones. TL, PL, L1, L2, L3, AL: low velocity zones.

Figure 4: Top: pre-collision geometry. Bottom: interpreted block diagram of the deep lithospheric structure beneath the Pamir and northwestern Kunlun. A-C) Interpreted cross sections of Fig. 3. '///' symbols mark the lower crust involved in the collision process.

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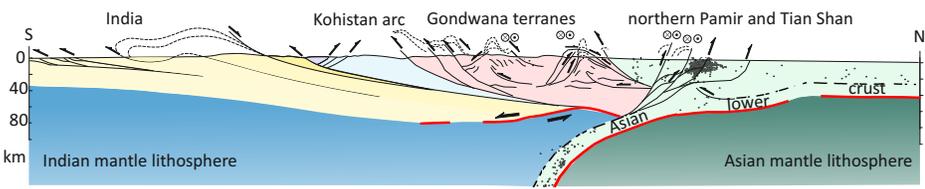
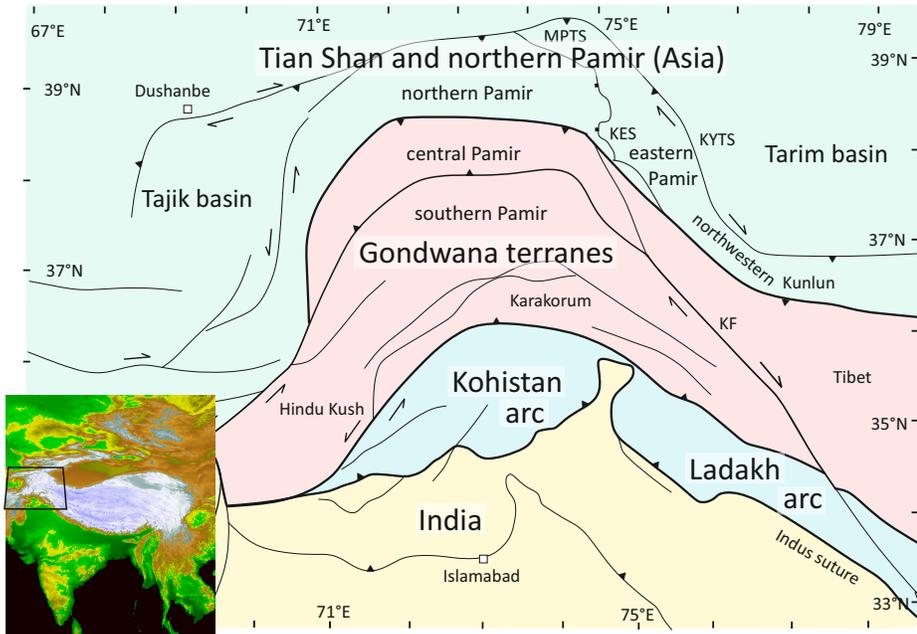
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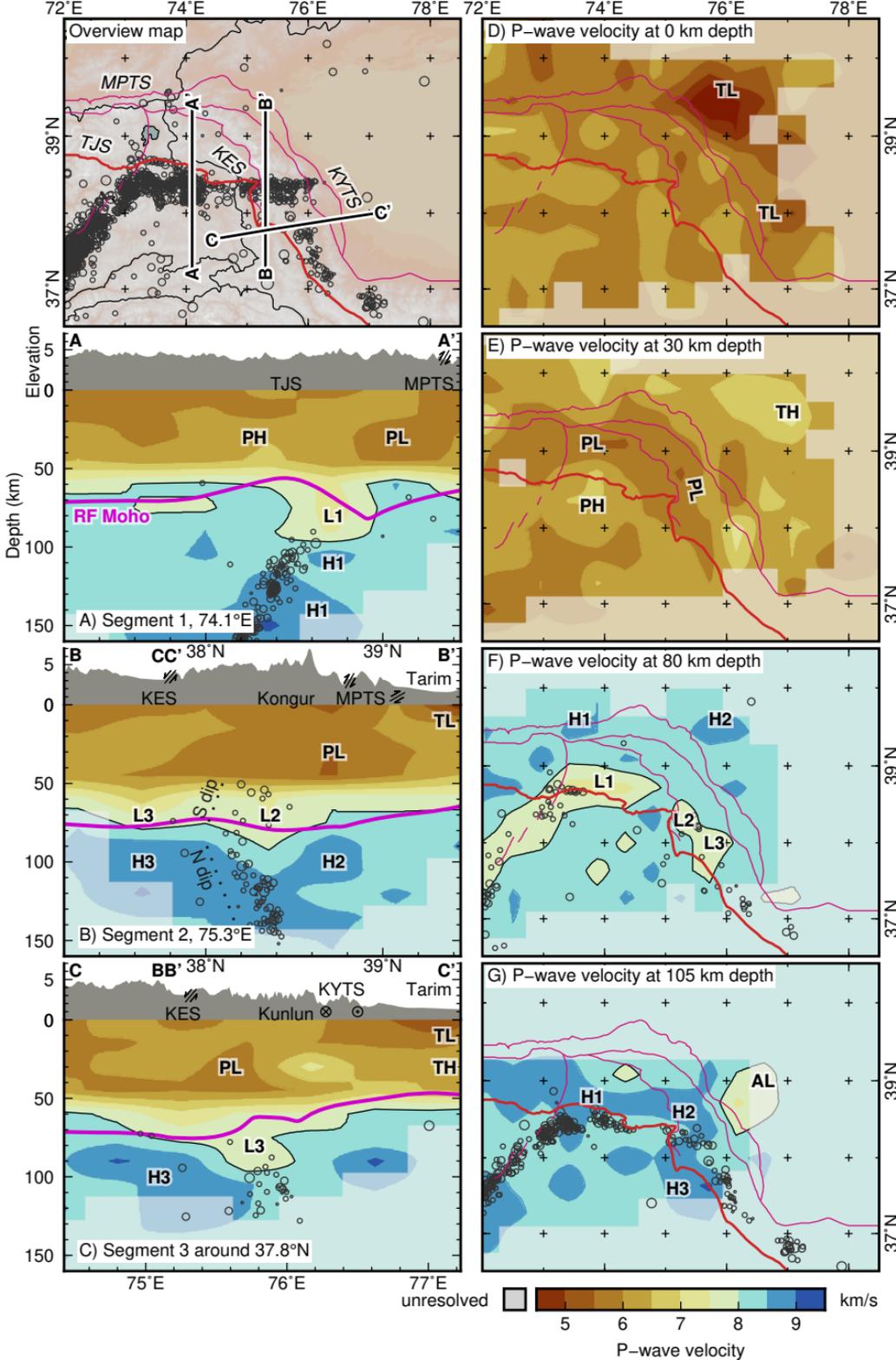
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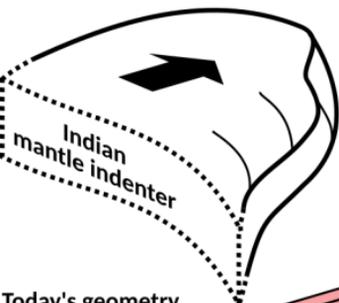
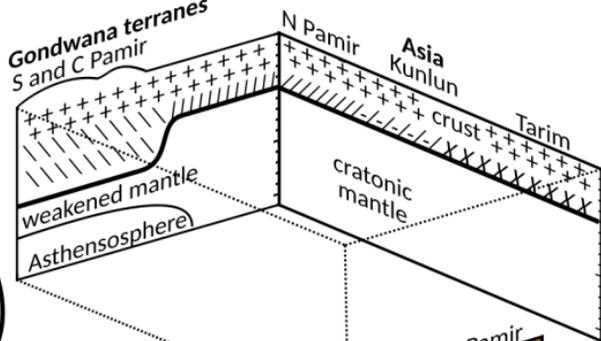
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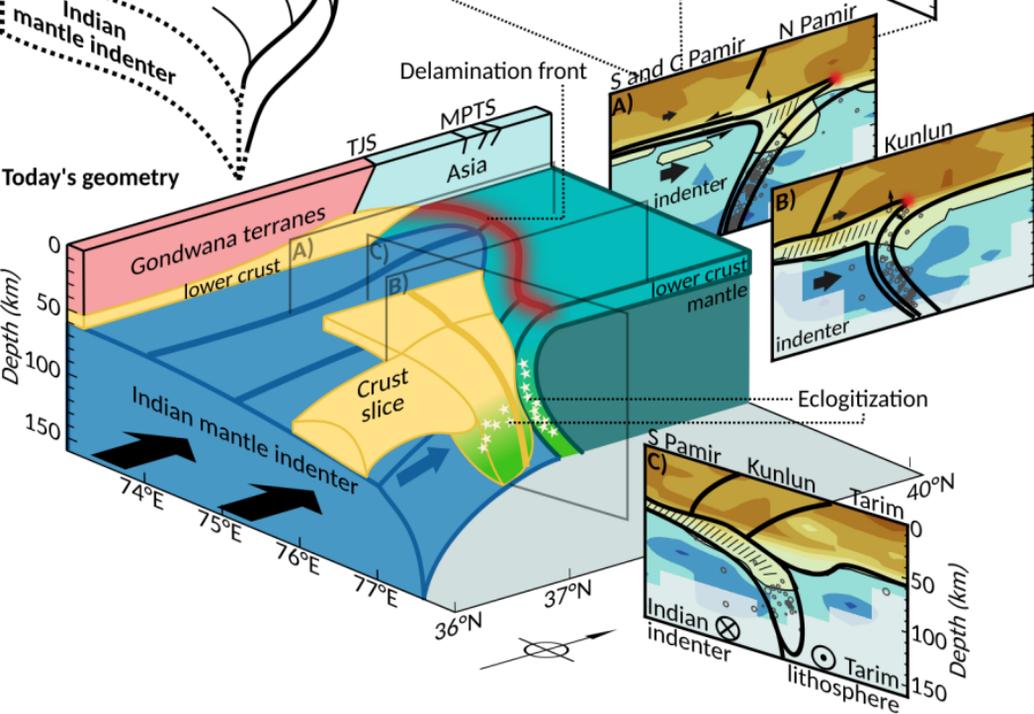




# Pre-collision geometry



# Today's geometry



<sup>1</sup>Supplement to

## <sup>2</sup>Structure of the deep lithosphere between Pamir and Tarim

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## 23 **METHOD**

### 24 **Data**

25 We operated the East Pamir seismic network (FDSN code 8H, Yuan et al., 2018a) with 30  
26 sites in the eastern Pamir, northwestern Kunlun, and northwestern Tarim basin between August  
27 2015 and July 2017, and the Sarez-Pamir aftershock seismic network (FDSN code 9H, Yuan et  
28 al., 2018b) with 10 sites in the central Pamir between February 2016 and July 2017. We used  
29 additional seismic waveform data from the Xinjiang regional seismic network (XJ, SEISDMC,  
30 2021) and the Tajik National Seismic Network (FDSN network code TJ; PMP International,  
31 2005; Fig. 2).

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### 33 **Seismic Event Detection, Phase Picking, and Initial Localization**

34 We detected 39,309 seismic events using the *Lassie* earthquake detector (Comino et al.  
35 2017), 10,900 of which at intermediate depth ( $>50$  km), and automatically picked P-wave arrival  
36 times with *MannekenPix* (Aldersons, 2004) and S-wave arrival times with *spicker* (Diehl et al.,  
37 2009). After each arrival time picking run, events were located with *hypo71* (Lee and Lahr,  
38 1972), and picks with the highest residuals were removed subsequently until the location root-  
39 mean-square misfit fell below a threshold of 2-s for P-waves only and 3-s for P- and S-waves  
40 combined. We then used a subset of 1,855 seismic events with best constrained arrival-time  
41 picks to invert for a depth-dependent 1-D velocity model and static station corrections using  
42 *velest* (Kissling et al., 1994). We again relocated all events in this model and removed those  
43 arrival times that yielded a residual 5 times larger than the standard deviation of all residuals of a  
44 certain seismic phase on a certain station. In total, we located 29,795 seismic events in the crust  
45 and in the mantle.

## 46 **Inversion for the Subsurface Velocity Field**

47 To derive a dataset suitable for tomographic inversion we augmented the catalog with  
48 events from Sippl et al. (2013b) and used a spatially declustered set of 2.264 events from the  
49 combined catalog with a total of 38.423 well-constrained P- and 15.910 S-arrival times.  
50 Inversion for the 3-D subsurface P-wave velocity structure was conducted using *simulps*  
51 (Thurber, 1983).

52 The seismic velocity field was parameterized as gradients between a rectangular grid of  
53 fixed nodes. After testing of various node configurations, we used a node spacing of 40-km in  
54 horizontal and 15-km in vertical direction (Figs. S1a and S3). The 1-D starting model was found  
55 by first inverting for the 1-D velocity gradients between vertical nodes and station corrections.  
56 Then, we constrained the velocities to increase with depth and that they do not exceed the  
57 velocity at 75-km depth (Fig. S1a). The model space was explored with various damping  
58 parameters (Fig. S1b) and the final model was found by first inverting solely for the velocity  
59 structure and earthquake parameters, and then allowing for minor adjustments by letting non-  
60 modeled residuals be taken up by station corrections. A checkerboard resolution test was used to  
61 assess the sensitivity of the model and mask poorly resolved regions (Fig. S3).

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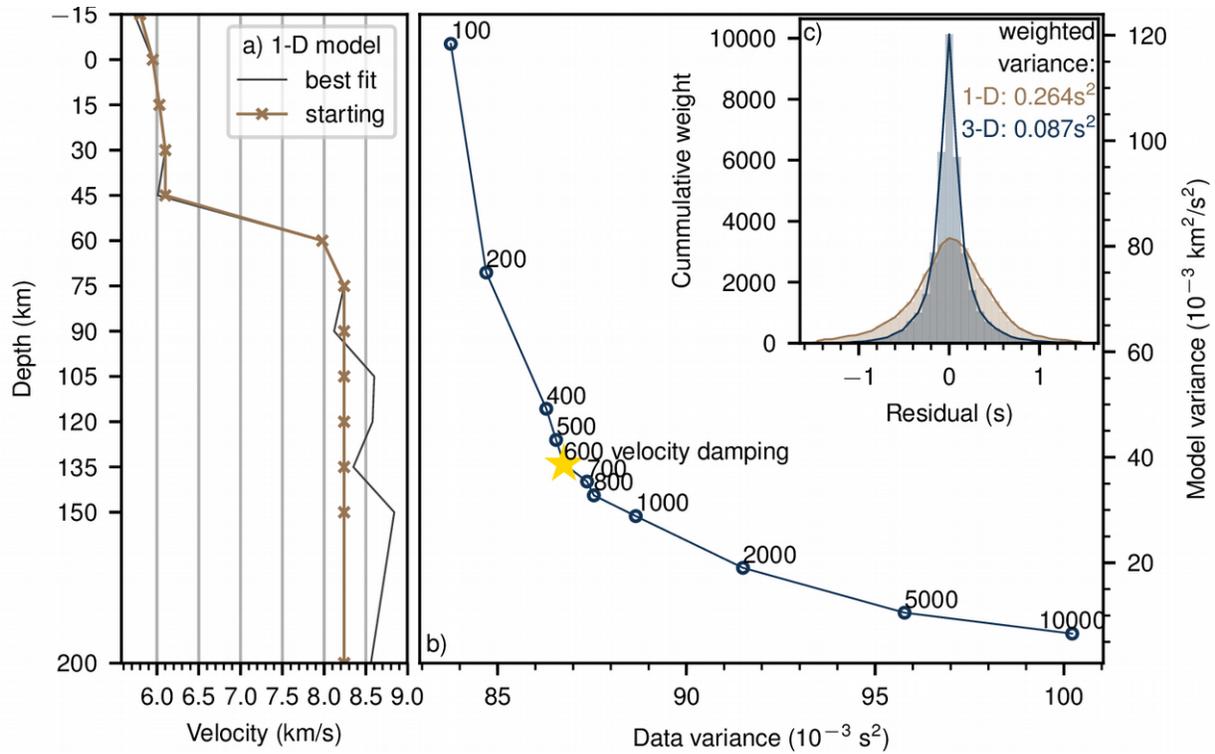


Figure S1: a) 1D models. Best fit: Minimum misfit model after 1-D inversion with simulps with station corrections. Starting: Starting model for the 3D inversion. We applied a positivity and a maximum velocity constraint to avoid pre-defining such essential structures in the 3-D inversion b) L-curve to find optimal velocity damping parameter. Star: chosen value c) Reduction of arrival time residuals and variance from 1-D starting model to the presented 3-D model.

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## 79 **Relocalization**

80 To focus on sub-crustal processes we discarded crustal earthquakes (<50-km depth),  
81 which were dominated by a strong earthquake sequence and are confined to the upper ~40-km  
82 depth. We added intermediate depth earthquakes with at least 4 S-picks that were previously  
83 excluded from the tomographic inversion. We then relocated all events with the *hypoDD*  
84 algorithm (Waldhauser and Ellsworth, 2000), yielding a unified catalog of 1.493 events at  
85 intermediate depth, consisting of newly detected events in the eastern and central Pamir and  
86 previously reported events from the western and central Pamir (Sippl et al, 2013b).

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## 88 **Focal Mechanisms and Stress Directions**

89 For 30 events, we estimated focal mechanisms using P-wave first motion polarities and P-  
90 to-S amplitude ratios using the *HASH* algorithm (Hardebeck and Shearer, 2003), and added 9  
91 moment tensors of Kufner et al., (2016). For the three spatially clearly separated seismicity  
92 segments we inverted for the principal stress directions using the *slick* algorithm (Gephart and  
93 Forsyth, 1984).

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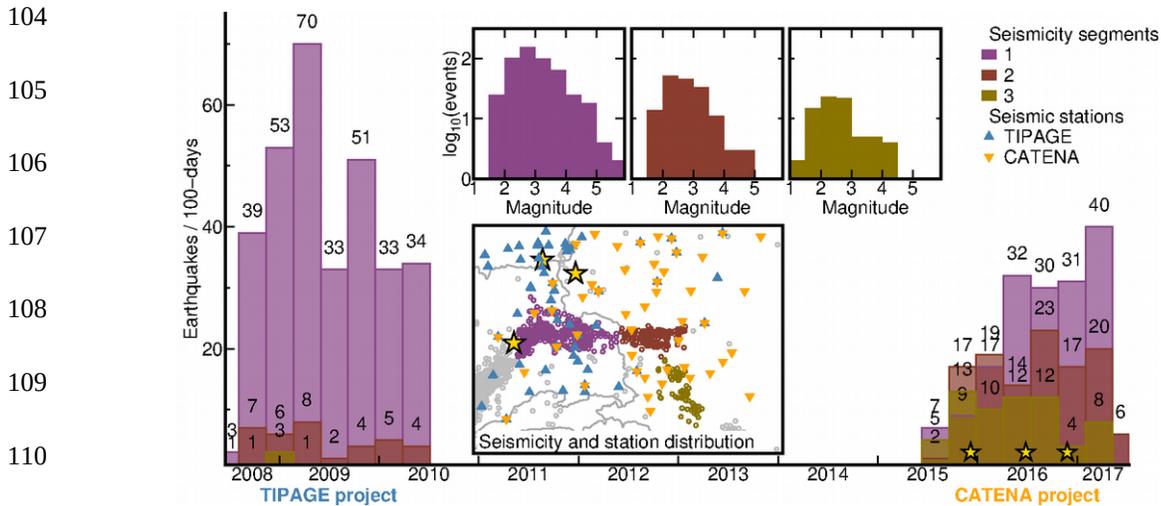
103 **PROPERTIES OF SEISMICITY**

Figure S2: Seismicity rate, local event magnitudes, and station distribution for the three seismicity segments discussed in the main article. Stations of the TIPAGE project (2008-2010, blue) were located in the Tajik Pamir and covered the central segment. Stations of the CATENA project (2015-2017, orange), including networks 8H, 9H and XJ, were located in the Chinese Pamir and Tarim basin and covered the eastern and south-eastern segment. Additional stations were placed in the Tajik Pamir in February 2016. Aftershock sequences of strong earthquakes (stars) in December 2015, June 2016, and November 2016 represent seismic noise that lowered the detection capability of intermediate depth seismicity. Magnitudes of events that occur outside one of the networks (especially in the south-eastern segment) tend to be overestimated. Event rate in the central segment is significantly higher compared to the eastern and south-eastern segment, despite the different network configuration and noise conditions.

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126 **COMPLE SEISMIC TOMOGRAPHY RESULTS**

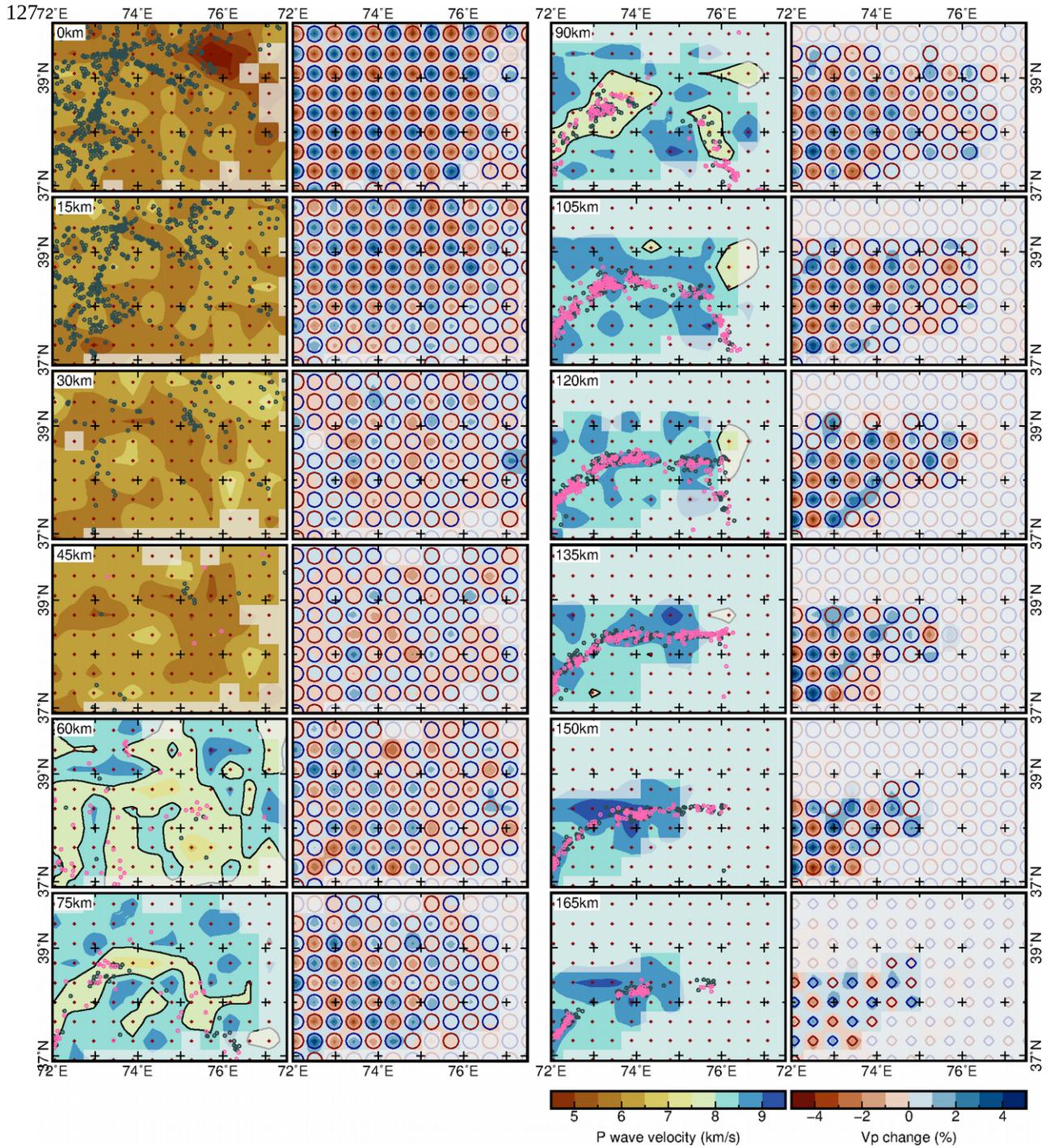


Figure S3: Horizontal slices through the tomogram at the node planes. Columns 1 and 3: Seismic velocities (colored background), grid nodes (red crosses), earthquakes used for tomographic inversion (gray circles), relocated earthquakes at intermediate depth (pink circles). Columns 2 and 4: Results of checkerboard recovery test: recovered model (colored background), input model ( $\pm 1\%$  contours).

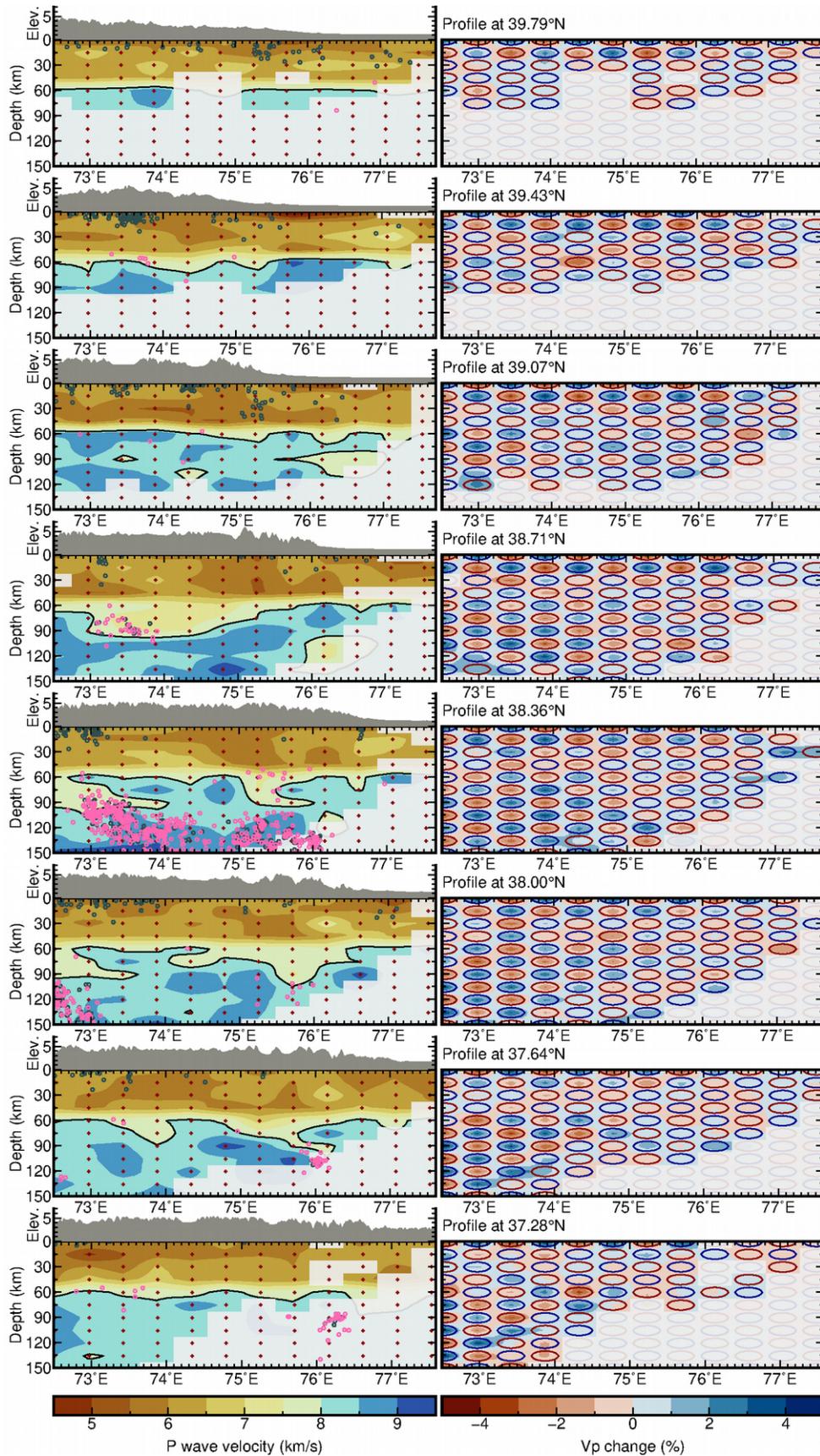


Figure S4: Same as Fig. S3, but with West-East-profiles.

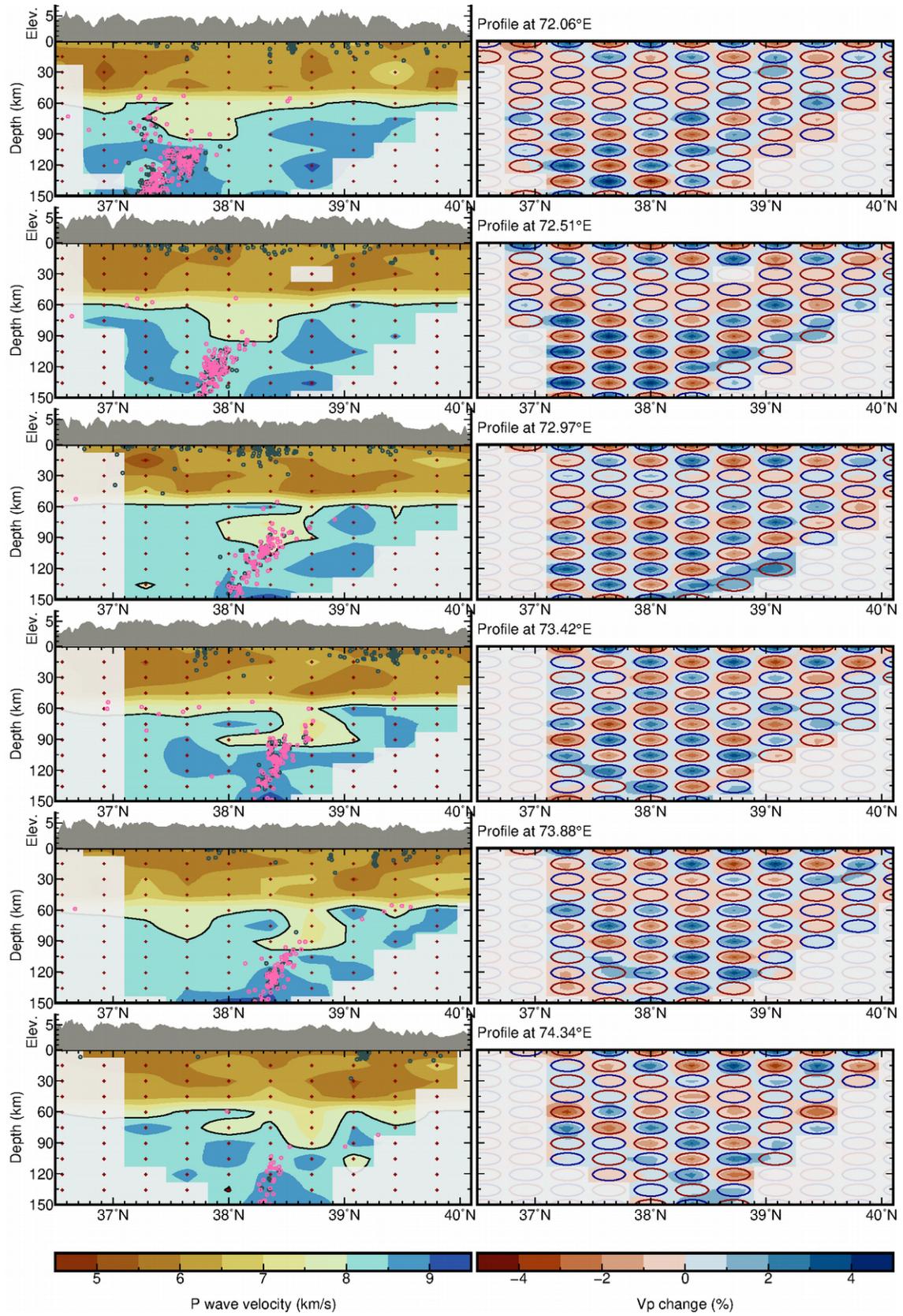


Figure S5: Same as Fig. S3, but with South-North-profiles.

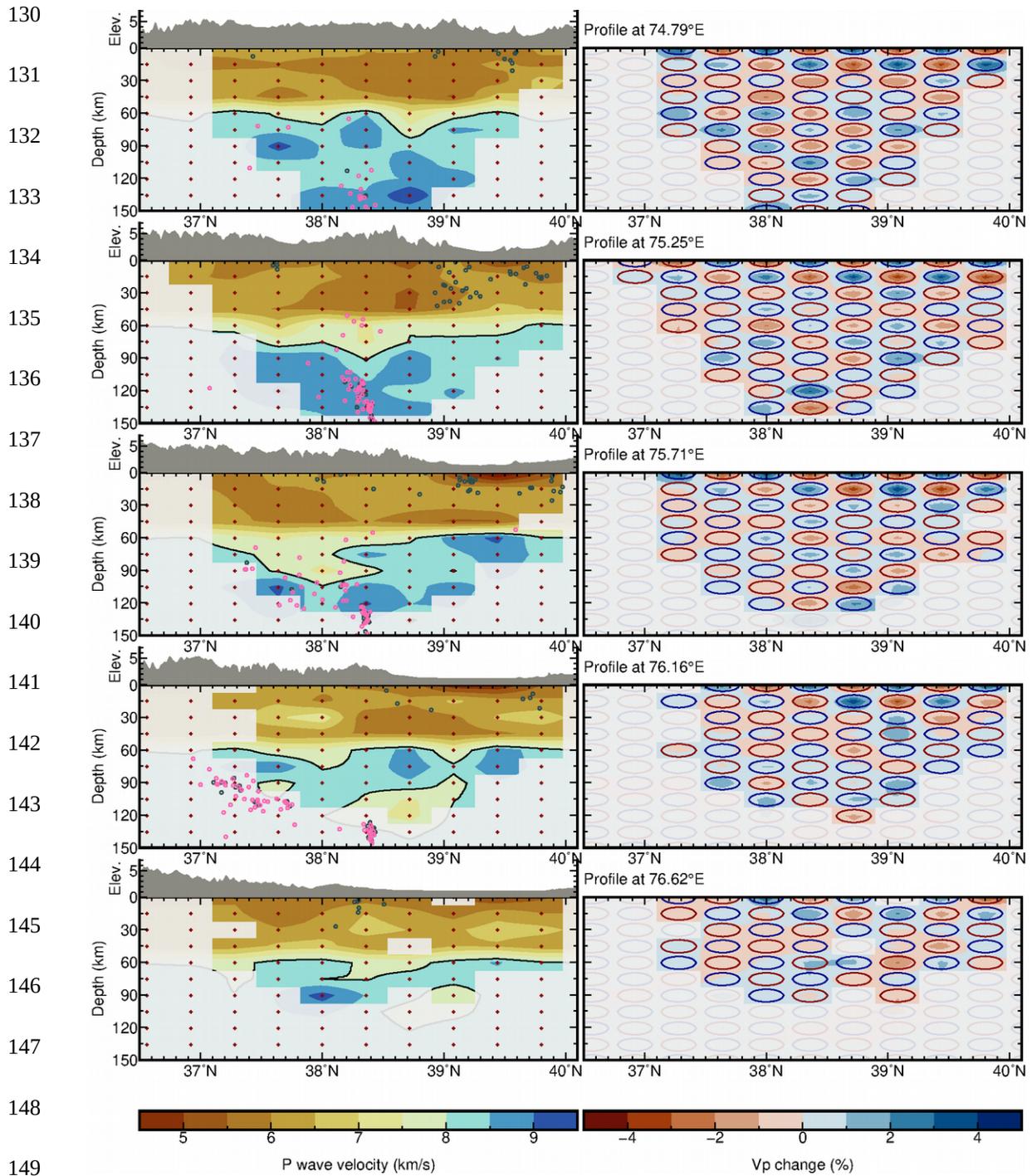


Figure S6: Fig. S5, continued

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