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# Flexural strike-slip basins

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## ABSTRACT

Strike-slip faults are classically associated with pull-apart basins where continental crust is thinned between two laterally offset fault segments. We propose a subsidence mechanism to explain the formation of a new type of basin where no substantial segment offset or syn-strike-slip thinning is observed. Such “flexural strike-slip basins” form due to a sediment load creating accommodation space by bending the lithosphere. We use a two-way coupling between the geodynamic code ASPECT and surface-processes code FastScape to show that flexural strike-slip basins emerge if sediment is deposited on thin lithosphere close to a strike-slip fault. These conditions were met at the Andaman Basin Central fault (Andaman Sea, Indian Ocean), where seismic reflection data provide evidence of a laterally extensive flexural basin with a depocenter located parallel to the strike-slip fault trace.

## 26 **MOTIVATION**

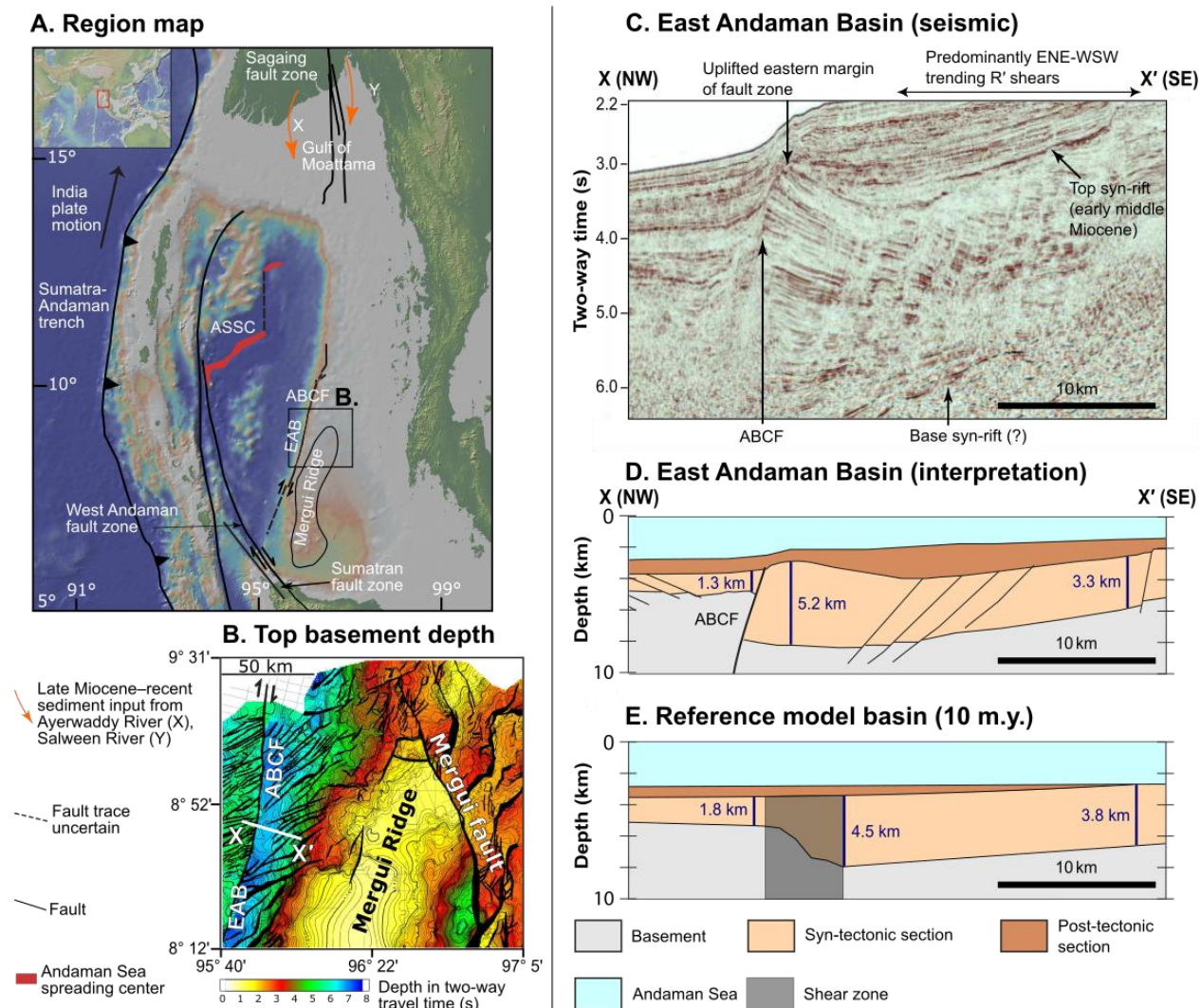
27 Near plate boundaries, accommodation space for sedimentary basins is created by (1) litho-  
28 spheric stretching or cooling, which controls rift-basin formation at divergent boundaries, and (2)  
29 lithospheric flexure such as in foreland basins in convergent settings and cratonic sag basins in  
30 continental interiors (Allen and Allen, 2013). Pull-apart basins at transform plate boundaries are  
31 thought to be related to the first process.

32 Pull-apart basins form between laterally offset strike-slip fault segments (Mann et al., 1983;  
33 Gürbüz, 2010). During strike-slip motion, the area between the offset faults is extended and  
34 basement subsidence occurs in this area due to crustal thinning (van Wijk et al., 2017). Pull-apart  
35 basins lengthen over time and form as long thin basins with a depocenter that is bounded by the  
36 strike- or oblique-slip segments (Seeber et al., 2004). While there are many pull-apart basin  
37 examples (e.g., the Dead Sea Basin: Garfunkel and Ben-Avraham, 1996; Death Valley Basin:  
38 Serpa et al., 1988), there has not been much discussion on other types of strike-slip basins.

39 Flexural basins form when an overlying load deflects the lithosphere, e.g., during mountain  
40 building, where an orogenic load creates accommodation space for sediment infill. However, under  
41 conditions without an orogenic load, basement subsidence may be a consequence of lower-crustal  
42 flow triggered by enhanced sedimentation in deep basins (Morley and Westaway, 2006; Clift et  
43 al., 2015), e.g., the fans of the Red River (Clift and Sun, 2006) and Pearl River (Dong et al., 2020;  
44 both examples are located at the northern continental margin of the South China Sea).

45 We infer that the creation of sedimentation-induced accommodation space requires and is  
46 enhanced by (1) an easily deformable tectonic environment, and (2) focused sedimentation. Both  
47 can occur in regions of prior tectonic subsidence. Furthermore, because strike-slip faults may  
48 represent highly weakened plate boundaries (Zoback et al., 1987; Provost and Houston, 2003) and  
49 transform continental margins commonly follow a phase of thinning (Jourdon et al., 2021), we  
50 formulate the key hypothesis of this study: regions near strike-slip faults can represent a  
51 combination of factors whereby significant basement subsidence is driven by sedimentary loading.  
52 The positive feedback between focused sedimentation and flexural subsidence leads to the creation  
53 of a previously unrecognized type of basin that we term “flexural strike-slip basin”. We test our  
54 hypothesis by (1) numerical forward modeling of a strike-slip system subjected to asymmetric

55 sedimentation, and (2) seismic reflection interpretation from the East Andaman Basin (EAB) in  
 56 the Andaman Sea (Indian Ocean).



57  
 58 **Figure 1. (A) Andaman Sea map. ASSC—Andaman Sea spreading center; ABCF—Andaman Basin Central**  
 59 **fault; EAB—East Andaman Basin. (B) Depth to the top of the basement in two-way travel time. (C) Seismic**  
 60 **data of the EAB. See B for profile location. (D) Depth interpretation of C. (E) Modeled basin. Post-tectonic**  
 61 **sediment is computed by adding basement subsidence from 5 to 10 m.y. to the topography at 5 m.y.**

## 62 GEOLOGICAL SETTING OF THE ANDAMAN SEA

63 During the Cenozoic, the Andaman Sea formed a transtensional backarc basin when India  
 64 coupled with western Myanmar (Curry, 2005). Multiple strike-slip faults exist in the region,  
 65 including the active, dextral, Sagaing fault (Fig. 1; 18 mm/yr: Vigny et al., 2003; Maurin et al.,  
 66 2010) in the northeast of the Andaman Sea that connects southwestward to the Andaman spreading

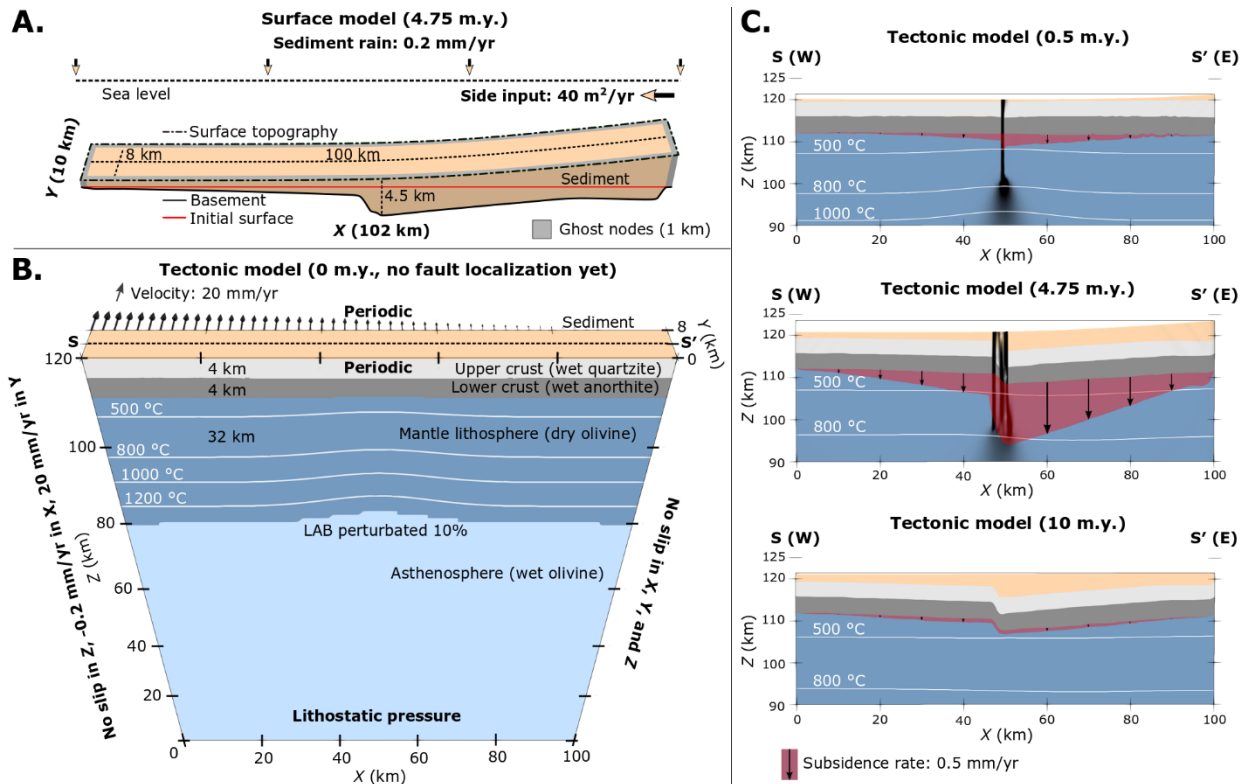
67 center (Curry, 2005). South of the Sagaing fault is the inactive Andaman Basin Central (strike-  
68 slip) fault (ABCF; Morley, 2016, 2017; Mahattanachai et al., 2021).

69 The Andaman Sea's transtensional motion led to subsidence and a submarine environment,  
70 causing the area to act as a sediment trap. Fault trends suggest the region near the ABCF expe-  
71 rienced WNW-ESE extension in the Oligocene that shifted to NNW-SSE transtensional strike-slip  
72 motion during the early to mid-Miocene (lasting ~5 m.y.; Morley, 2017). The ABCF follows a  
73 previous necking zone of hyperextended continental crust (7–10 km thick; Morley, 2017;  
74 Mahattanachai et al., 2021). During strike-slip motion, the easterly Mergui Ridge was partially  
75 subaerial and, along with peninsular Thailand, acted as an asymmetric clastic sediment source for  
76 the EAB located along the ABCF (Mahattanachai et al., 2021).

77 The geometry of the EAB in relation to the ABCF is described in detail by Mahattanachai et al.  
78 (2021), who concluded that the long (>200 km), deep (>4 km), westward-thickening basin on the  
79 east side of the sub-vertical fault did not fit classic extensional or pull-apart basin characteristics.

## 80 **MODEL SETUP AND EVOLUTION**

81 We reproduce the key aspects of the ABCF region, namely that of a submarine environment,  
82 thin lithosphere, and asymmetric sedimentation, using a viscoplastic  $100 \times 8 \times 120$  km ( $X, Y, Z$ )  
83 three-dimensional box model via a two-way coupling of the tectonic code ASPECT ([https://](https://aspect.geodynamics.org)  
84 [aspect.geodynamics.org](https://aspect.geodynamics.org), version 2.3.0-pre, commit 886749d) (Figs. 2B and 2C; Kronbichler et al.,  
85 2012; Heister et al., 2017; Glerum et al., 2018; Bangerth et al., 2019; Text S1 in the Supplemental  
86 Material) and the surface-processes code FastScape (<https://fastscape.org>) (Braun and Willett,  
87 2013; Yuan et al., 2019b, 2019a; Text S2). We assume that a previous extensional event left the  
88 region submarine with thinned, 40-km-thick lithosphere. The model is initialized with 4 km of  
89 upper crust, 4 km of lower crust, 32 km of mantle lithosphere, and 80 km of asthenosphere (Fig.  
90 2B; Fig. S1 in the Supplemental Material). The eastern boundary (right edge in Fig. 2B) has no  
91 slip in any direction, the western boundary (left edge in Fig. 2B) has no slip in the  $Z$  direction, 20  
92 mm/yr in the  $Y$  direction to induce strike-slip motion, and is given a small (0.2 mm/yr) extensional  
93 component in the  $X$  direction that helps avoid bending-induced compression but does not affect  
94 the presented results (Fig. S2). To simulate an infinitely long strike-slip fault with minimal along-  
95 strike variation, the northern and southern boundaries are periodic, in that any material advected  
96 out of the northern boundary will flow into the model from the southern boundary, or vice-versa.



97 **Figure 2. (A) Surface-processes model at 4.75 m.y. and 2× vertical exaggeration. Sediment (beige) is the area**  
 98 **between topography (dash-dot line) and basement (solid black line). Ghost nodes (gray) are a single cell-size**  
 99 **(1 km in X and Y) layer surrounding the surface processes model implemented for periodic advection along**  
 100 **the Y direction and to control sedimentary side input, surround the surface model and do not interact with**  
 101 **the tectonic model. (B) Initial tectonic setup. Colors represent composition; white isotherms represent**  
 102 **temperature distribution. Arrows indicate total velocity magnitude. The northern and southern boundaries**  
 103 **are periodic, indicating that material flow out one boundary will become inflow on the opposing boundary.**  
 104 **LAB—lithosphere-asthenosphere boundary. (C) Cross sections of the top 30 km of the tectonic model along**  
 105 **S-S' in B showcase the formation of a flexural strike-slip basin in response to sedimentation. Subsidence rate**  
 106 **at the Moho is indicated in red. See Movies S1 and S2 in the Supplemental Material.**  
 107

108 The initial lithostatic pressure at a reference location is prescribed on the bottom boundary to allow  
 109 for outflow in response to sedimentation. The strike-slip fault forms self-consistently above an  
 110 initial perturbation of the lithosphere-asthenosphere boundary (10% reduction of lithosphere  
 111 thickness) in the center of the model that acts as a weak zone for deformation to localize.  
 112 Accumulated plastic strain over an interval of 0–1 weakens the angle of friction from an initial  
 113 value of 30° to a final value of 7.5°, promoting brittle localization.

114 The surface-processes code FastScape is coupled to the top of the tectonic model (Text S3).  
 115 The model is submarine and sediment is transported via diffusion with a coefficient of 500 m<sup>2</sup>/yr,  
 116 consistent with open-marine environments in previous modeling studies (Rouby et al., 2013).  
 117 Sediment is supplied to the domain in two ways: (1) the entire surface experiences 0.2 mm/yr of  
 118 pelagic and/or hemipelagic “sediment rain” sedimentation; and (2) ghost nodes (Fig. 2A) at the

119 eastern boundary are uplifted each time step to prescribe a constant sediment flux of  $40 \text{ m}^2/\text{yr}$ ,  
120 mimicking an off-model sediment source similar to the Mergui Ridge for the EAB.

121 The models are run for 10 m.y., where the first 5 m.y. represent the syn-tectonic stage with  
122 strike-slip motion and sedimentation to mimic the  $\sim 5$  m.y. during which the ABCF was active.  
123 The final 5 m.y. constitute the post-tectonic stage with no prescribed motion or sediment supply,  
124 although sediment transport continues (for setup details, see Text S4).

## 125 **REFERENCE MODEL RESULTS**

126 In the reference model, strain localizes on a vertical fault near the model center (at  $\sim 0.5$  m.y.;  
127 Fig. 2C). Both sides of the fault subside due to the influx of sediment, with the eastern side sinking  
128 faster ( $1.0$  versus  $0.4 \text{ mm/yr}$  at  $4.75$  m.y.). By  $5$  m.y., the eastern side has subsided more than the  
129 western side ( $3.6$  versus  $1.0 \text{ km}$ ), rotating the strike-slip fault to subvertical. After strike-slip  
130 motion and sedimentation have ceased, the subsidence rate declines to  $0.08 \text{ mm/yr}$  as the sediment  
131 hill at the eastern boundary is distributed across the surface. By  $10$  m.y., both sides have subsided  
132 another  $0.4 \text{ km}$ , showing a synformal thickening geometry along the fault.

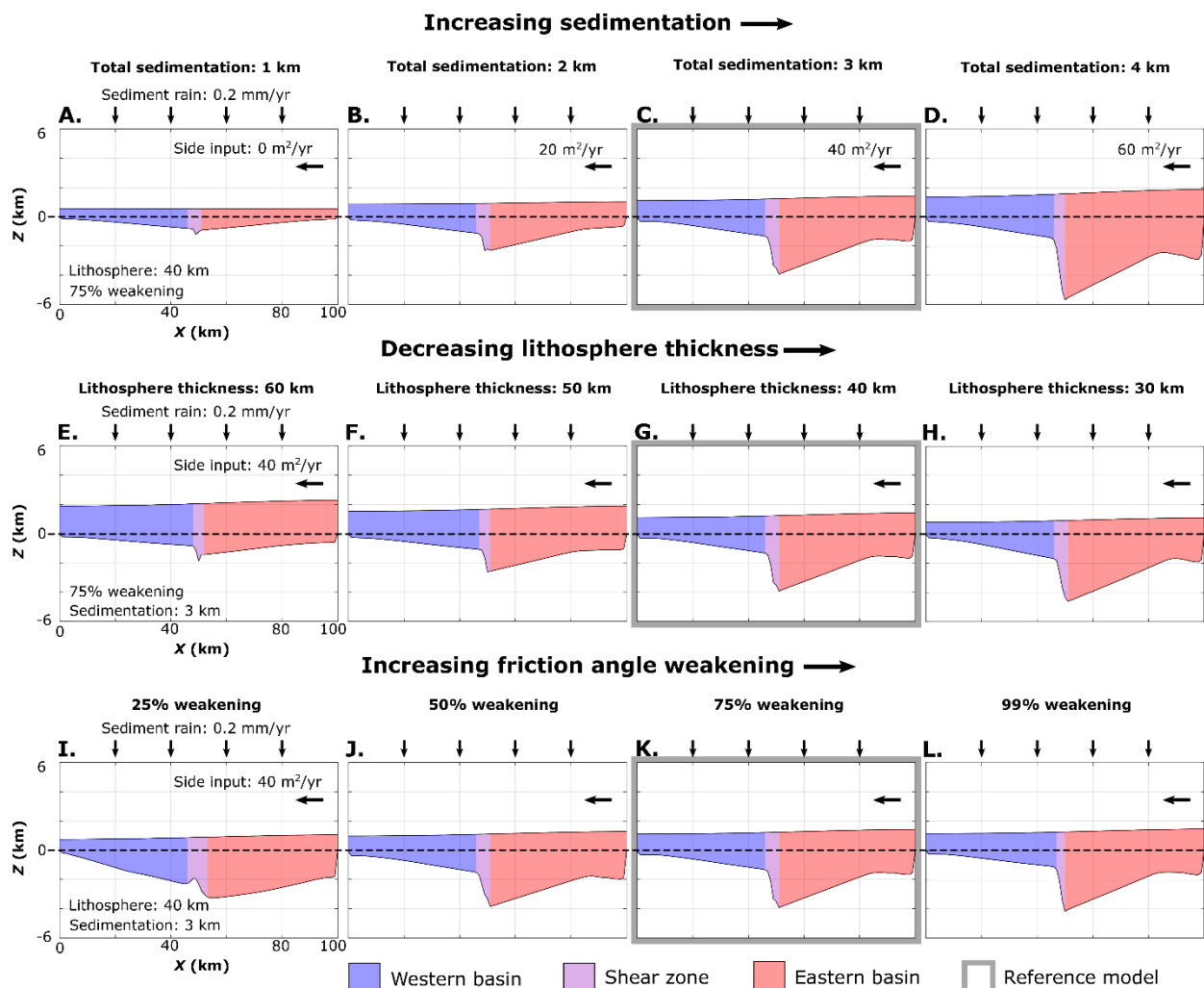
133 The model indicates that a flexural strike-slip basin emerges due to sedimentation above thin  
134 lithosphere close to a strike-slip fault, wherein the fault acts as a weak zone where subsidence  
135 focuses. In contrast to classical half-graben or pull-apart geometries, these basins form without a  
136 significant extensional component (i.e., without crustal thinning as seen in pull-apart basins).

## 137 **CONTROLS ON FLEXURAL STRIKE-SLIP BASIN FORMATION**

138 To test controls on flexural strike-slip basin formation, we ran a series of models varying in  
139 sedimentation rate, lithospheric thickness, and fault strength. Sedimentation rate was changed by  
140 altering the eastern-side influx from  $0$  (i.e., only sediment rain) to  $60 \text{ m}^2/\text{yr}$  (Figs. 3A–3D). With  
141 no lateral input, both sides subsided evenly, forming a synformal basin that is thickest at the fault  
142 (Fig. 3A). This suggests that reference-model basin asymmetry is affected primarily by  
143 sedimentation and not by the initial perturbation. At higher lateral input, the eastern side subsided  
144 more, from a maximum basement deflection of  $0.9 \text{ km}$  with no input to  $5.7 \text{ km}$  for  $60 \text{ m}^2/\text{yr}$  of  
145 input (Fig. 3D). The western side shows a less-pronounced deflection with higher sediment input  
146 ( $0.8$ – $1.6 \text{ km}$ ), suggesting either that the sides are not fully decoupled or that more sediment reached  
147 the western side.

148 The effects of varying the lithospheric thickness from 60 to 30 km (Figs. 3E–3H) reduce the  
 149 basement flexural deflection on the eastern side of the fault from 4.6 km at 30 km to 1.4 km at 60  
 150 km, suggesting that deep flexural basins are unlikely to form in regions with thick lithosphere.

151 The final key variable is friction-angle weakening (Figs. 3I–3L). This shows that fault strength  
 152 affects flexural subsidence (4.2 versus 3.3 km deflection at 99% and 25% weakening,  
 153 respectively), suggesting that regions with no weakening or without strike-slip motion (Fig. S3)  
 154 would experience much less subsidence. Further, weak faults promote lithospheric decoupling and  
 155 basin asymmetry related to asymmetric sedimentation.



156  
 157 **Figure 3. Modeled basin formation when subject to variable sediment input (A–D), lithosphere thickness (E–**  
 158 **H), and fault weakening (I–L). Dashed lines along  $Z = 0$  show initial model elevation. Total sedimentation is**  
 159 **sediment thickness assuming an even distribution across the model.**



## 160 FLEXURAL STRIKE-SLIP BASINS IN THE ANDAMAN SEA

161 Seismic data suggest that the EAB is an asymmetric basin that spans both sides of the ABCF  
162 (Mahattanachai et al., 2021). On the western side, basin thickness is fairly uniform (1–2 km; Fig.  
163 1D). Along the fault on the eastern side, the basin is substantially thicker (~5 km) and thins  
164 eastward toward the sediment source areas of the Mergui Ridge and peninsular Thailand.

165 The Gulf of Moattama Basin formed along the active Sagaing fault and is a more ambiguous  
166 example where a deep (>10 km) depocenter formed in the past ~6 m.y., although strike-slip fault  
167 activity in the area probably dates to the Oligocene (Morley and Arboit, 2019). Although a gentle  
168 releasing-bend geometry is present in the offshore fault trace, the basin did not undergo dramatic  
169 subsidence until the latest Miocene–Pliocene, when a major transgression followed structural  
170 uplift and inversion of basins onshore (e.g., Morley and Alvey, 2015). We suggest the axial  
171 sediment influx along the Gulf of Moattama Basin resulted in the flexural strike-slip mechanism  
172 enhancing the effects of the fault geometry.

173 The primary requirement for flexural strike-slip basin formation is weak or thin lithosphere and  
174 high sedimentation rates. There are two basin types, controlled by the sedimentation pattern: (1)  
175 symmetric, where both sides receive a similar sediment load (Fig. 3A); and (2) asymmetric, where  
176 the two distinct basin sides subside at different rates dependent on the sediment load they receive  
177 (Fig. 3C). In both types, the maximum flexure and basin depocenter occur along the fault trace and  
178 the basin thins strike-perpendicularly.

179 The Andaman Sea provides likely examples for each flexural strike-slip basin type:

180 (1) The Gulf of Moattama Basin, where northern axial sedimentation provided even sedi-  
181 mentation to each side of the fault and formed a *symmetric flexural basin*. While sedimentation  
182 was not purely uniform, a synformal geometry developed centered along the fault zone, as in  
183 Figure 3A.

184 (2) The EAB (Fig. 1D), where perpendicular sedimentation from the east forced greater flexure  
185 on the eastern side of the fault, forming an *asymmetric flexural basin*. The EAB and reference  
186 model basin both have a change in sediment thickness across the fault and basin thinning toward  
187 the sediment source. Furthermore, basin thicknesses (excluding post-tectonic sediment) along the

188 fault's eastern side (4.5 versus 5.2 km in the model and EAB, respectively) and western side (1.8  
189 versus 1.3 km) are comparable between the model and the basin.

190 Despite the similarities, there are discrepancies between the modeled basin and the EAB.  
191 Eastward thinning of the sediment layer is less pronounced in the model. Given that the basement  
192 slope is affected by the lithosphere thickness and sediment load, three possible explanations are:

193 (1) The ABCF is capped by a regional unconformity with the post-tectonic sediments  
194 (Srisuriyon and Morley, 2014; Morley, 2017), and the fault may have received more sediment  
195 while active than expected from the seismic data.

196 (2) Given that the fault formed within a necking zone and the lithosphere thickness is not well  
197 constrained, the lithosphere may have varied spatially (rheologically or in thickness) and been  
198 thinner than the 40 km value used here.

199 (3) A more significant syn-strike-slip extensional component would have further deepened the  
200 basin along the fault (Sobolev et al., 2005).

201 Also, our models do not consider basin translation with strike-slip motion. This is justified by  
202 comparison with the EAB, where the thicker eastern basin is located on the same side as the Mergui  
203 Ridge and is not affected by the translation. For the western basin, the ~350-km-long Mergui  
204 Ridge is longer than the total dextral strike-slip translation of ~90 km from the early to mid-  
205 Miocene.

206 We focused on the Andaman Sea, but the key requirements for flexural strike-slip basins—thin  
207 lithosphere, focused sedimentation, and a weak fault—are possibly also met in the New Guinea  
208 Basin in the Bismarck Sea (southwestern Pacific Ocean; Fig. S4; Martinez and Taylor, 1996) and  
209 the Yinggehai Basin in the South China Sea (Fig. S5; Clift and Sun, 2006), although new seismic  
210 data are needed to test this. Another candidate is the Navassa Basin in the Jamaica Passage  
211 (Caribbean Sea; Fig. S6; Corbeau et al., 2016), an asymmetric strike-slip basin that is not located  
212 between offset segments. The basin likely formed during strike-slip motion and does not contain  
213 older sedimentary units found in nearby basins along the fault.

## 214 CONCLUSION

215 Our study suggests a new class of flexural basins that form along strike-slip faults. These basins  
216 are characterized by a fault-parallel depocenter and sediment that thins strike-perpendicularly. The  
217 basins can be classified in two types, which are both represented in the Andaman Sea: (1)  
218 *symmetric flexural basins*, where axial sedimentation causes a synformal shape, as seen in the Gulf  
219 of Moattama Basin; and (2) *asymmetric flexural basins*, where asymmetric sedimentation forces  
220 one basin side to subside more than the other, as seen in the EAB.

221 Flexural strike-slip basins form due to a strike-slip fault that acts as a weak zone facilitating  
222 differential subsidence due to sediment loading. The fault decouples the lithosphere sides, allowing  
223 them to respond independently to the sediment load they receive, determining basin symmetry.  
224 For a flexural strike-slip basin to form, two criteria must be met: the strike-slip fault must (1) cut  
225 through thin lithosphere, and (2) be subjected to a sufficient tectonic load.

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- 344

# 1 Supplementary Information

## 2 Flexural strike-slip basins

3  
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### 12 **Contents of this file**

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### 26 **Additional supporting information (uploaded separately)**

27 Video S1

28 Video S2

29

30 **Text S1: ASPECT Methods**

31 **1.1 Governing equations**

32 We perform numerical simulations of a 3D strike-slip system using the open source finite-element  
 33 code ASPECT (Advanced Solver for Problems in Earth's ConvecTion, version 2.3.0-pre, commit  
 34 886749d; Heister et al., 2017; Kronbichler et al., 2012; Rose et al., 2017; Bangerth et al., 2019).  
 35 ASPECT solves the following incompressible conservation equations assuming an infinite Prandtl  
 36 number (i.e., without the inertial term),

37 
$$-\nabla \cdot (2\eta\dot{\epsilon}) + \nabla P = \rho \mathbf{g}, \quad (1)$$

38 
$$\nabla \cdot (\mathbf{u}) = 0, \quad (2)$$

39 
$$\bar{\rho} C_p \left( \frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T \right) - \nabla \cdot \mathbf{k} \nabla T = \bar{\rho} H \quad (3)$$

40 
$$+ \alpha T (\mathbf{u} \cdot \nabla P),$$

41 
$$\frac{\partial c_i}{\partial t} + \mathbf{u} \cdot \nabla c_i = q_i, \quad (4)$$

42 where equation (1) represents the conservation of momentum, with  $\eta$  the effective viscosity,  $\dot{\epsilon}$  the  
 43 deviator of the strain rate tensor (defined as  $\frac{1}{2}(\nabla \mathbf{u} + (\nabla \mathbf{u})^T)$ ),  $\mathbf{u}$  the velocity,  $P$  the pressure,  $\rho$  the  
 44 density, and  $\mathbf{g}$  gravity. Equation (2) describes the conservation of volume. Equation (3) represents  
 45 the conservation of energy where  $\bar{\rho}$  is the reference adiabatic density,  $C_p$  the specific heat capacity,  
 46  $T$  the temperature,  $\mathbf{k}$  the thermal conductivity,  $H$  the radiogenic heating, and  $\alpha$  the thermal  
 47 expansivity. As right-hand-side heating terms, we include radioactive heating and adiabatic  
 48 heating, in that order. Finally, we solve the advection equation (4) for each compositional field  $c_i$   
 49 (e.g., upper crust, lower crust, and accumulated plastic strain) with reaction rate  $q_i$  nonzero only  
 50 for the plastic strain field.



## 51 1.2 Rheology

52 We use a visco-plastic rheology (Glerum et al., 2018), which additionally includes plastic  
53 weakening based on accumulated plastic strain. In the viscous regime, we use a composite of  
54 diffusion and dislocation creep (Karato and Wu, 1993), formulated as:

$$55 \quad \eta_{\text{eff}}^{\text{diff|dis}} = \frac{1}{2} A_{\text{diff|dis}}^{-1} d^m \dot{\epsilon}_e^{\frac{1-n}{n}} \exp\left(\frac{(E_{\text{diff|dis}} + PV_{\text{diff|dis}})}{nRT}\right), \quad (5)$$

56 where  $A$  is a scalar prefactor,  $d$  the grain size,  $\dot{\epsilon}_e$  the square root of second invariant of the  
57 deviatoric strain rate,  $E$  the activation energy,  $P$  the pressure,  $V$  the activation volume,  $R$  the gas  
58 constant,  $T$  the temperature, and  $n$  the stress exponent. For diffusion,  $n = 1$  and the equation  
59 becomes independent of strain rate. For dislocation creep, the grain size exponent  $m$  vanishes,  
60 rendering dislocation creep independent of grain size. Values for  $A$ ,  $E$ ,  $V$ , and  $n$  used in our models  
61 are composition-dependent and can be found in supplementary Table S1.

62 In the plastic regime, when viscous stresses exceed the yield stress, we use the Drucker-Prager  
63 yield criterion (Davis and Selvadurai, 2002). The effective plastic viscosity is given by

$$64 \quad \eta_{\text{eff}}^{\text{pl}} = \frac{\frac{6C \cos\phi}{\sqrt{3}(3-\sin\phi)} + \frac{6P \sin\phi}{\sqrt{3}(3-\sin\phi)}}{2\dot{\epsilon}_e}, \quad (6)$$

65 where  $C$  is the cohesion and  $\phi$  the internal angle of friction. The accumulation of plastic strain is  
66 tracked as a compositional field. This field is used to linearly weaken  $\phi$  from an initial value of  
67  $30^\circ$  to a final value of  $7.5^\circ$  over the accumulated plastic strain interval of 0 to 1. The time-integrated  
68 value of the strain reaction rate  $q_i$  is approximated as  $\dot{\epsilon}_e \cdot dt$  when plastic yielding occurs (with  $dt$   
69 the current timestep size).

## 70 **Text S2: FastScape Methods**

71 FastScape is a landscape evolution code that changes the topographic surface through uplift,  
 72 advection, the stream-power law, and hillslope diffusion (Braun and Willett, 2013). It can  
 73 additionally deposit fluvial sediment (Yuan et al., 2019a) and include a marine component, which  
 74 handles marine sediment (sand/silt) transport and deposition, and layer compaction based on  
 75 sand/silt porosity (Yuan et al., 2019b). It uses a 2D horizontal mesh with a uniform resolution. For  
 76 simplicity, we here assume that the entire model surface is submarine, with uniform properties  
 77 (i.e., sand and silt transport coefficients are the same), and that there is no compaction (porosity is  
 78 zero). Hence, FastScape deforms the surface through the uplift rate and marine diffusion equation  
 79 only as

$$80 \quad \frac{dh}{dt} = \mathbf{U} + K_m \nabla^2 h, \quad (7)$$

81 where  $h$  is the topographic elevation,  $\mathbf{U}$  the uplift rate and  $K_m$  the marine sediment diffusion  
 82 coefficient.

## 83 **Text S3: ASPECT/FastScape coupling**

84 In this paper we use a two-way coupling of the tectonic ASPECT code and the landscape evolution  
 85 FastScape code. For this coupling, a FastScape shared library is called by an ASPECT plugin to  
 86 deform its surface as described in the previous section. The plugin has three main components: 1)  
 87 Copy the surface height and velocity values from ASPECT. 2) Initialize and run FastScape at a  
 88 resolution equivalent to or greater than the one used at the surface of ASPECT. If it is the first  
 89 timestep of the tectonic model run, FastScape is initialized using height and velocity values from  
 90 ASPECT. In subsequent timesteps, as FastScape runs separately and can be at a higher resolution  
 91 than ASPECT, only the velocity values from ASPECT are transferred to FastScape. Before

92 running FastScape, the initial topography values are saved. After running FastScape, the new and  
93 previous topography are compared to determine a nodal vertical (Z) velocity,

$$94 \quad \mathbf{V}_z = \frac{h_c - h_p}{dt_a}, \quad (8)$$

95 where  $h_p$  is the surface height at the start of the timestep (previous surface), and  $h_f$  the surface  
96 height after FastScape has been run (current surface), and  $dt_a$  the ASPECT timestep. 3) Using the  
97 overarching mesh deformation functionality (see Rose et al., 2017), the Z velocity field is  
98 interpolated onto the ASPECT surface to determine the displacement of the mesh surface and  
99 interior. From there, ASPECT responds to the change in topography calculated by FastScape due  
100 to the induced change in forces that is included in the Stokes equations. At the beginning of the  
101 next timestep, the updated velocities computed in the previous timestep are sent to FastScape once  
102 again.

103 The FastScape mesh includes an additional element-size layer of ghost nodes compared to the  
104 ASPECT surface mesh. The values of surface height on these nodes are not considered when  
105 interpolating the surface back to ASPECT and are used primarily to avoid FastScape boundary  
106 artifacts being sent to the ASPECT model (e.g., the boundaries do not uplift from advected  
107 topography). To avoid possible erroneous sediment flux out or into the model from artificial  
108 slopes, each timestep the ghost nodes are updated with the topography and velocity values of the  
109 nearest inward node (an ASPECT boundary node).

110 Besides passing ASPECT's uplift velocities, we use the plugin's FastScape interface to supply  
111 additional input to the surface process model in two ways: 1) to add marine background  
112 sedimentation via the sediment rain effect, and 2) to add a boundary sediment flux using the ghost  
113 nodes. For the sediment rain, at each nodal point we update FastScape with a flat height increase

114 every ASPECT timestep. Through the diffusion component in equation (7), we prescribe a constant  
115 sediment flux at the boundary, assuming that

$$116 \quad \mathbf{Q} = K_m S, \quad (9)$$

117 where  $\mathbf{Q}$  is the sediment flux and  $S$  the slope. Since  $K_m$  and  $Q$  are user-set parameters, to achieve  
118 this we alter  $S$  by uplifting the boundary ghost nodes every ASPECT timestep so that  $\mathbf{Q}$  remains  
119 constant.

#### 120 **Text S4: Model setup**

121 In this study we examine how a strike-slip fault responds to sedimentation. We therefore set up a  
122 3D box model with dimensions 100×8×120 km ( $X$ ,  $Y$ , and  $Z$ , where  $Z$  is the vertical component)  
123 and 5 compositions representing a wet quartzite upper crust (Rutter and Brodie, 2004), wet  
124 anorthite lower crust (Rybacki et al., 2006), dry olivine lithospheric mantle, wet olivine  
125 asthenosphere (Hirth and Kohlstedt, 2003), and a sediment layer that has rheologic parameters  
126 identical to wet quartzite, but with density and temperature parameters consistent with sediment  
127 (Sippel et al., 2017). The total crustal thickness is set to 8 km (4 km upper crust, 4 km lower crust)  
128 based on crustal estimates of the area (7-10 km; Mahattanachai et al., 2021). The lithospheric  
129 mantle extends between the Moho and the lithosphere-asthenosphere boundary (LAB) at 40 km  
130 depth. The LAB depth, like the crust, has been perturbed by a previous extensional period. The  
131 remaining material beneath the LAB is considered asthenosphere (Fig. S1). While there is no initial  
132 sediment layer, the top boundary is fixed to a sediment composition so that any top-inflow of  
133 material due to topography changes other than uplift is sediment.

134 The ASPECT model mesh consists of two element sizes: 1 km and 2 km. The upper 8 km of the  
135 model is refined at 1 km to best resolve the crust and the forming sediment layer. This high-

136 resolution area additionally extends to a depth of 35 k from  $X = 42$  km to  $X = 52$  km to better  
137 resolve the strike-slip fault. All other areas are kept at 2 km resolution.

138 The initial temperature above the LAB is determined by a steady-state geotherm (Turcotte and  
139 Schubert, 2013), and below by a mantle adiabat. For simplicity, an initial weak zone is seeded  
140 through a small perturbation: we raise the LAB locally by 10% of the lithospheric mantle thickness.  
141 We fix the top boundary temperature at 0 °C and the bottom boundary at the temperature initially  
142 determined from the mantle adiabat at that depth. All other boundaries are set to zero heat-flux.

143 The coupled model is run for 10 Myr, where the model in the first 5 Myr includes non-zero velocity  
144 boundary conditions. During this time, the western boundary is given a strike-slip component of  
145 20 mm/yr (in Y), and an extensional component of 0.2 mm/yr (in X), while the Z-component of  
146 velocity is set to no-slip. This gives a total of 100 km of dextral strike-slip motion and 1 km of  
147 extension. The small extensional component is introduced to avoid compressional pop-ups that  
148 form at the shear zone as the lithosphere subsides due to the sediment load (Fig. S2). The exact  
149 extensional value is chosen to accommodate horizontal stress forces related to isostatic  
150 compensation. From 5-10 Myr, extension and strike-slip motion stop as the western boundary is  
151 set to no-slip in all directions. All other boundary conditions are constant for the entire model run,  
152 with the eastern boundary being no-slip in all directions, the north and south boundaries set to  
153 periodic to simulate an infinitely long strike-slip fault, the initial lithostatic pressure computed at  
154 a reference location prescribed on the bottom boundary to allow for outflow in response to  
155 sedimentation, and the top boundary deformed through the use of FastScape.

156 FastScape is set up with an arbitrarily high sea level so that the entire model is considered  
157 submarine. This setup leads to a model with no acting stream power law, and sediment being  
158 moved solely through marine sediment diffusion. For simplicity, we additionally assume that there

159 is no compaction and no difference between sand and silt. As such, we use a diffusion coefficient  
160 of  $500 \text{ m}^2/\text{y}$  for both, a value consistent with open marine environments in previous modelling  
161 studies (e.g., Rouby et al., 2013). During the syn-strike-slip phase of the tectonic model (0-5 Myr)  
162 we supply sediment to the model in two ways: 1) To account for pelagic/hemipelagic  
163 sedimentation (sediment rain), we deposit at a constant and uniform sedimentation rate of 0.2  
164 mm/yr. 2) We assume there is an asymmetric off-model source of sediment, similar to the eastern  
165 Mergui Ridge for the East Andaman Basin, that inputs sediment into the system from the eastern  
166 boundary at a rate of  $40 \text{ m}^2/\text{yr}$ . This is done through equation (9), wherein we uplift the ghost nodes  
167 at each timestep so that a constant flux is prescribed through marine diffusion. After this syn-  
168 tectonic stage spanning 5 Myr, sediment supply to the system is halted, although marine diffusion  
169 continues to work on the topography.

170

Parameter	Symbol	Units	Sediment	Upper crust	Lower crust	Lithospheric mantle	Asthenosphere
Reference density (at surface conditions)	$\rho_0$	kg m <sup>-3</sup>	2520	2700	2850	3280	3300
Thermal expansivity	$\alpha$	K <sup>-1</sup>	$3.7 \cdot 10^{-5}$	$2.7 \cdot 10^{-5}$	$2.7 \cdot 10^{-5}$	$3.0 \cdot 10^{-5}$	$3.0 \cdot 10^{-5}$
Thermal diffusivity	$\kappa$	m <sup>2</sup> s <sup>-1</sup>	$7.28 \cdot 10^{-7}$	$9.26 \cdot 10^{-7}$	$5.85 \cdot 10^{-7}$	$8.38 \cdot 10^{-7}$	$8.33 \cdot 10^{-7}$
Heat capacity	$C_p$	J kg <sup>-1</sup> K <sup>-1</sup>	1200	1200	1200	1200	1200
Heat production	H	W m <sup>-3</sup>	$1.2 \cdot 10^{-6}$	$1.5 \cdot 10^{-6}$	$0.2 \cdot 10^{-6}$	0	0
Cohesion	C	Pa	$20 \cdot 10^6$	$20 \cdot 10^6$	$20 \cdot 10^6$	$20 \cdot 10^6$	$20 \cdot 10^6$
Internal friction angle (unweakened)	$\phi$	°	30	30	30	30	30
Strain weakening interval	-	-	[0,1]	[0,1]	[0,1]	[0,1]	[0,1]
Strain weakening factor	$\phi_{wf}$	-	0.25	0.25	0.25	0.25	0.25
Creep properties			Sediment	Wet quartzite	Wet anorthite	Dry olivine	Wet olivine
Stress exponent (dis)	n	-	4.0	4.0	3.0	3.5	3.5
Constant prefactor (dis)	$A_{dis}$	Pa <sup>-n</sup> s <sup>-1</sup>	$8.57 \cdot 10^{-28}$	$8.57 \cdot 10^{-28}$	$7.13 \cdot 10^{-18}$	$6.52 \cdot 10^{-16}$	$2.12 \cdot 10^{-15}$
Activation energy (dis)	$E_{dis}$	J mol <sup>-1</sup>	$223 \cdot 10^3$	$223 \cdot 10^3$	$345 \cdot 10^3$	$530 \cdot 10^3$	$480 \cdot 10^3$
Activation volume (dis)	$V_{dis}$	m <sup>3</sup> mol <sup>-1</sup>	0	0	$38 \cdot 10^{-6}$	$18 \cdot 10^{-6}$	$11 \cdot 10^{-6}$
Constant prefactor (diff)	$A_{diff}$	Pa <sup>-1</sup> s <sup>-1</sup>	$5.79 \cdot 10^{-19}$	$5.79 \cdot 10^{-19}$	$2.99 \cdot 10^{-25}$	$2.25 \cdot 10^{-9}$	$1.5 \cdot 10^{-9}$
Activation energy (diff)	$E_{diff}$	J mol <sup>-1</sup>	$223 \cdot 10^3$	$223 \cdot 10^3$	$159 \cdot 10^3$	$375 \cdot 10^3$	$335 \cdot 10^3$
Activation volume (diff)	$V_{diff}$	m <sup>3</sup> mol <sup>-1</sup>	0	0	$38 \cdot 10^{-6}$	$6 \cdot 10^{-6}$	$4 \cdot 10^{-6}$
Grain size (diff)	d	m	0.001	0.001	0.001	0.001	0.001
Grain size exponent (diff)	m	-	2.0	2.0	3.0	0	0

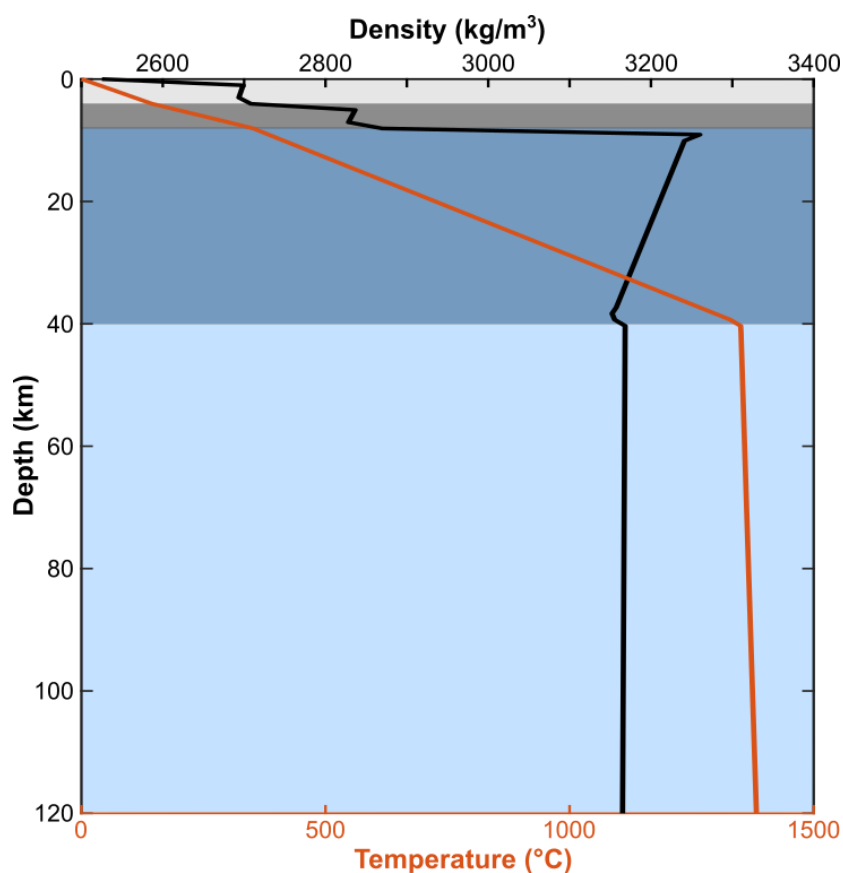
171 **Table S1:** ASPECT model parameters. Abbreviations: dis – dislocation creep, diff – diffusion  
172 creep.

173

Parameter	Symbol	Unit	Value
Marine sand transport coefficient	$K_{\text{sand}}$	$\text{m}^2/\text{yr}$	500
Surface sand porosity	$\varphi_{\text{sand}}$	-	0
Sand e-folding depth	$z_{\text{sand}}$	m	0
Marine silt transport coefficient	$K_{\text{silt}}$	$\text{m}^2/\text{yr}$	500
Surface silt porosity	$\varphi_{\text{silt}}$	-	0
Silt e-folding depth	$z_{\text{silt}}$	m	0
Sand-shale ratio	F	-	1
Thickness of transport layer	L	m	100
Sea level	$h_{\text{sea}}$	m	5000

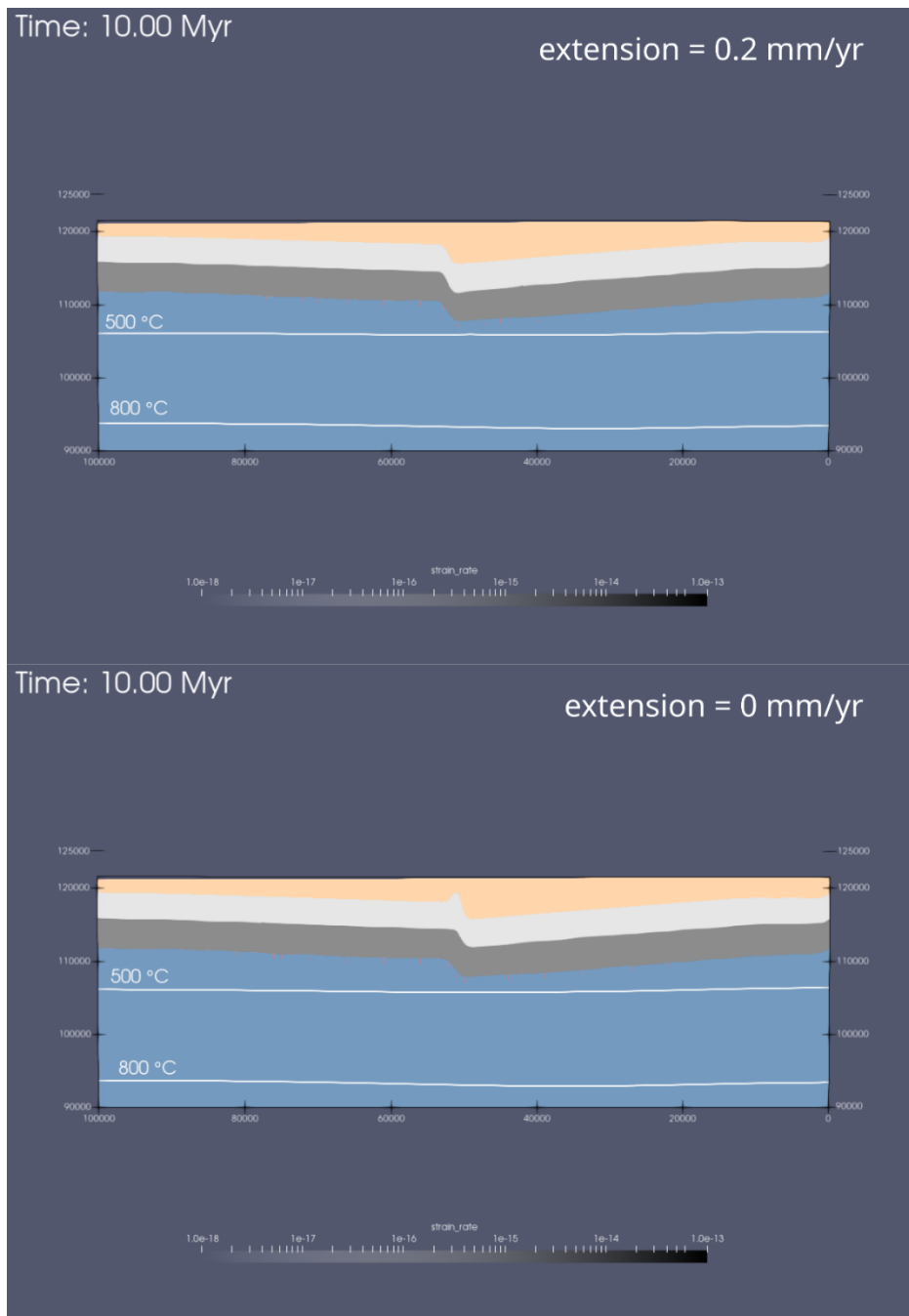
174 **Table S2:** FastScape model parameters.

175



176 **Figure S1:** Initial density (black) and temperature (red) profiles with depth. Colored backgrounds  
 177 represent the initial compositions, with light gray representing the upper crust, dark gray the lower  
 178 crust, dark blue the mantle lithosphere, and light blue the asthenosphere.





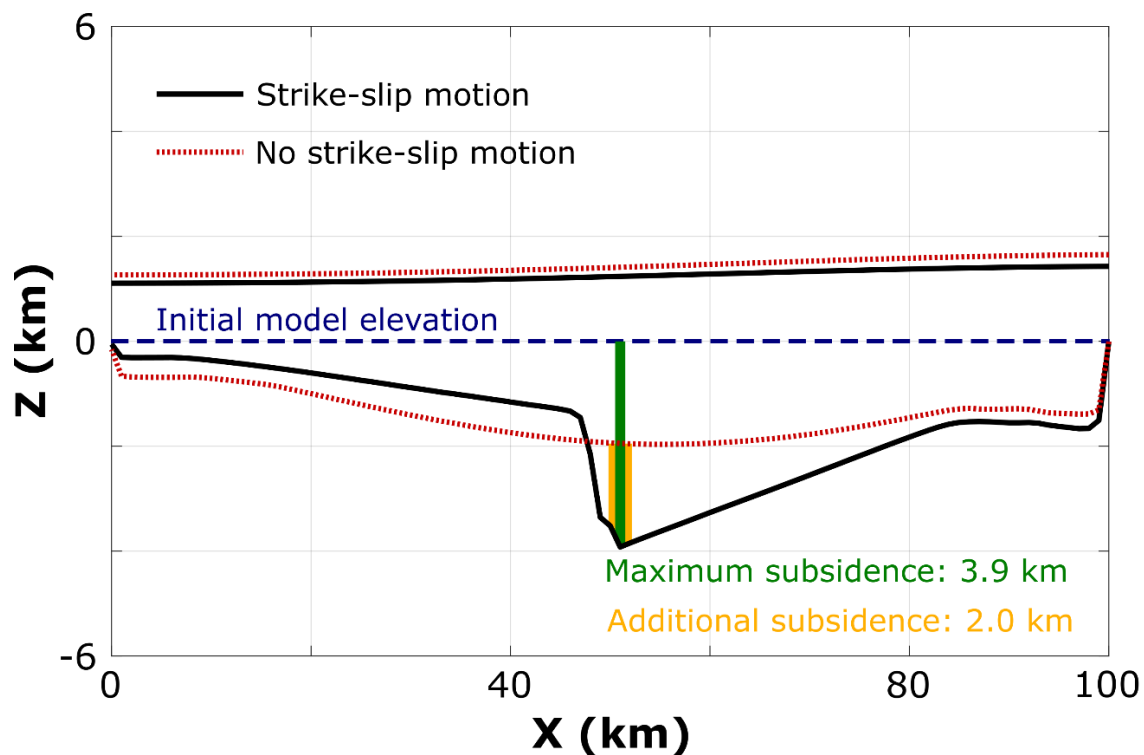
179

180 **Figure S2:** Comparison showing the reference model with A) a 0.2 mm/yr extensional component.

181 B) no extensional component, leading to the formation of a small compressional pop-up in the

182 center.

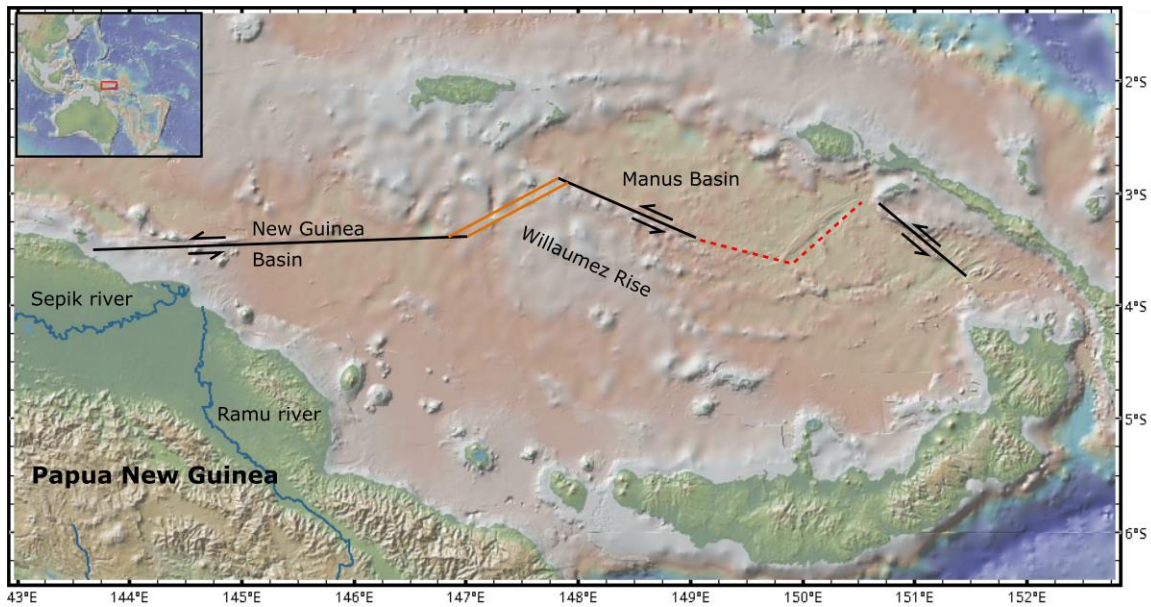
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184

185 **Figure S3:** Comparison of the FastScape basement and topography from two models runs: The  
 186 black curves represent the reference model; the dotted red curves show the reference model without  
 187 strike-slip motion. The dashed blue line represents the initial model elevation, the green line  
 188 indicates the total subsidence in the reference model with strike-slip motion, and the yellow line  
 189 shows the difference in subsidence when comparing models with and without strike-slip motion.  
 190 In the case without strike-slip motion, maximum subsidence and basin asymmetry are both greatly  
 191 reduced.

192

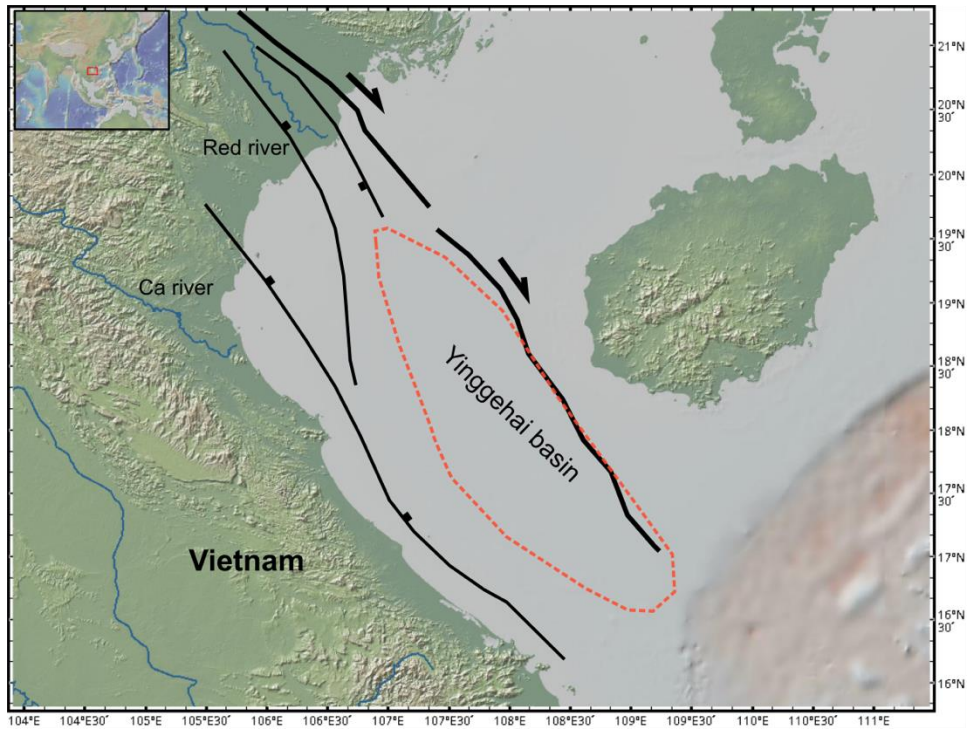


193

194 **Figure S4:** Regional map of the Manus back-arc region, with fault locations based on Fig. 1 in  
195 Martinez and Taylor, 1996. Black lines indicate strike-slip faults, parallel orange lines spreading  
196 centers, dashed red lines lava fields, and blue lines major rivers. This figure was made using  
197 GeoMappApp ([www.geomapp.org](http://www.geomapp.org); Ryan et al., 2009).

198

199



200

201 **Figure S5:** Regional map showing the Red River Fault Zone and location of the Yinggehai basin.

202 Fault locations based on Fig. 10 in Noda, 2013. Black lines show faults, blue lines major rivers,

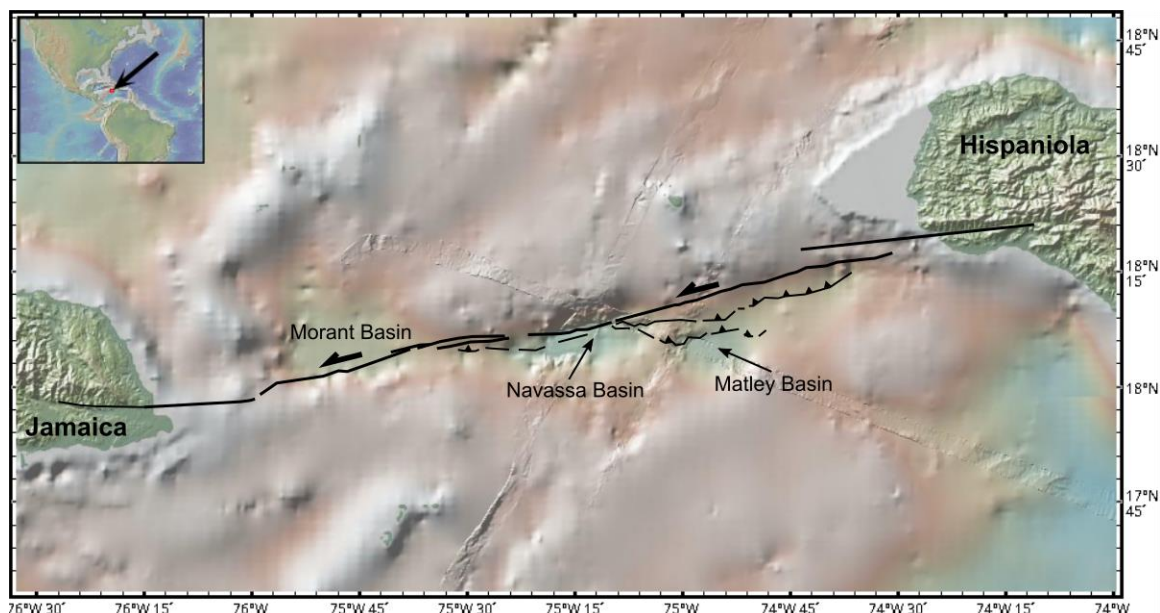
203 and the Yinggehai basin is outlined in the dashed orange circle. This figure was made using

204 GeoMappApp ([www.geomapp.org](http://www.geomapp.org); Ryan et al., 2009).

205

206

207



208  
 209 **Figure S6:** Regional map of the Jamaica Passage showing the Navassa strike-slip basin along the  
 210 Enriquillo-Plantain-Garden Fault Zone. Fault locations based on Fig. 6 in Corbeau et al., 2016.  
 211 This figure was made using GeoMappApp ([www.geomapapp.org](http://www.geomapapp.org); Ryan et al., 2009).

212  
 213 **Video S1:** Full evolution of the tectonic reference model (Fig. 2C,K,G). Colors represent  
 214 composition where tan is sediment, light gray is upper crust, dark gray is lower crust, dark blue is  
 215 mantle lithosphere, and light blue is the asthenosphere. The white lines are temperature contours,  
 216 gray-scale the strain rate, and arrows indicate the total velocity magnitude.

217  
 218 **Video S2:** Evolution of the middle slice of the top 30 km of the reference tectonic model. Colors  
 219 represent composition where tan is sediment, light gray is upper crust, dark gray is lower crust,  
 220 dark blue is mantle lithosphere, and light blue is the asthenosphere. The white lines are temperature

221 contours, gray-scale the strain rate, and red arrows indicate the subsidence rate (Z velocity) along  
 222 the 8 km depth contour.

223

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