

1 Illuminating a Contorted Slab with a Complex Intraslab 2 Rupture Evolution during the 2021 M_W 7.3 East Cape, New 3 Zealand Earthquake

4 Ryo Okuwaki^{1,2,3,=}, Stephen P. Hicks^{4, =}, Timothy J. Craig³, Wenyuan Fan⁵, Saskia
5 Goes⁴, Tim J. Wright³, and Yuji Yagi²

6 ¹Mountain Science Center, University of Tsukuba, Tsukuba, Ibaraki 305-8572, Japan

7 ²Faculty of Life and Environmental Sciences, University of Tsukuba, Tsukuba, Ibaraki 305-8572, Japan

8 ³COMET, School of Earth and Environment, University of Leeds, Leeds LS2 9JT, UK

9 ⁴Department of Earth Science and Engineering, Imperial College London, London SW7 2AZ, UK

10 ⁵Scripps Institution of Oceanography, UC San Diego, La Jolla, California 92093, USA

11 **Key Points:**

- 12 • A moment magnitude 7.3 2021 East Cape, New Zealand intraslab earthquake
13 comprised multiple rupture episodes with different faulting styles
- 14 • The complex rupture comprises components of shallow trench-normal exten-
15 sion and unexpectedly, deep trench-parallel compression in slab
- 16 • The trench-parallel compression likely reflects stress rotation at a buoyancy con-
17 trast that drives slab contortion

=Equally contributing author

Corresponding author: Ryo Okuwaki, rokuwaki@geol.tsukuba.ac.jp

18 **Abstract**

19 The state-of-stress within subducting oceanic plates controls rupture processes of deep
20 intraslab earthquakes. However, little is known about how the large-scale plate ge-
21 ometry and the stress regime relate to the physical nature of the deep-intraslab earth-
22 quakes. Here we find, by using globally and locally observed seismic records, that the
23 moment magnitude 7.3 2021 East Cape, New Zealand earthquake was driven by a com-
24 bination of shallow trench-normal extension and unexpectedly, deep trench-parallel
25 compression. We find multiple rupture episodes comprising a mixture of reverse, strike-
26 slip, and normal faulting. Reverse faulting due to the trench-parallel compression is
27 unexpected given the apparent subduction direction, so we require a differential-buoyancy
28 driven stress rotation which contorts the slab near the edge of the Hikurangi plateau.
29 Our finding highlights that buoyant features in subducting plates may cause diverse
30 rupture behavior of intraslab earthquakes due to the resulting heterogeneous stress
31 state within slabs.

32 **Plain Language Summary**

33 A key type of tectonic boundary is where two plates collide with one sinking into the
34 mantle beneath. These subduction zones generate the world's largest earthquakes. Quan-
35 tifying stress in the subducting plate ("slab") is important because slabs drive the global
36 plate-tectonic system, and large earthquakes can occur within them. These earthquakes
37 can cause strong shaking, and, when occurring near cities, can lead to damage. How-
38 ever, mapping stress is challenging as we cannot directly "see" inside deep slabs. Our
39 best indications of slab stress come from earthquakes themselves. A magnitude 7.3
40 earthquake north of New Zealand in 2021 generated a distinct pattern of seismic wave-
41 forms at seismometers installed worldwide. We used these seismic records to probe
42 the earthquake, providing a new view of stress in subduction zones. We found the earth-
43 quake generated both vertical and horizontal motions along faults, driven by compres-
44 sional and extensional stresses deep within the slab. The compressional part is ori-
45 ented 90 degrees from the subduction direction, which is opposite to the usual com-
46 pression in subduction zones, and has not been observed before. This unusual direc-
47 tion of compression can be explained by subduction of a thickened and buoyant part
48 of the Pacific plate, known as the Hikurangi plateau.

1 Introduction

Complex fault configurations and heterogeneous fault conditions, i.e., stress and strength states, govern earthquake rupture development and propagation (Avouac et al., 2014; Floyd et al., 2016; Elliott et al., 2016; Hamling et al., 2017). Such relations can be inferred from the fault geometry and long-term geodetic observations for shallow active faults (Simons et al., 2002; Williams et al., 2013; Elliott et al., 2016; Arai et al., 2016; Hamling et al., 2017; Hayes et al., 2018; Sippl et al., 2018). However, for intraslab earthquakes occurring below ~ 50 km depth, these physical controlling factors are difficult to assess because of challenges to map structure at such depths, and the general lack of seismicity there (Wiens, 2001; Ranero et al., 2005; Page et al., 2016; Dascher-Cousineau et al., 2020; Gomberg & Bodin, 2021). In particular, the internal stress state and its extensional-compression transition regime are often elusive in subducted slabs, although they directly impact intraslab earthquake occurrence and their faulting styles (Astiz et al., 1988; Ammon et al., 2008; Craig et al., 2014; Romeo & Álvarez-Gómez, 2018; Sandiford et al., 2019, 2020; Ye et al., 2021). Thus, imaging the rupture processes of large, deep intraslab earthquakes offers a rare window to investigate the slab configuration, and to understand fault interaction and rupture evolution of these earthquakes, illuminating heterogeneous stress fields.

An intraslab moment magnitude (M_W) 7.3 earthquake occurred offshore the East Cape in northern New Zealand on 4th March 2021, which was followed ~ 4 hours later by a series of the M_W 7.4 and M_W 8.1 earthquakes in the Kermadecs (~ 900 km to the north) (GeoNet, 2021). The M_W 7.3 2021 East Cape earthquake, which is the focus of this paper, may offer insight into the regional slab geometry because of its location and complex rupture process. The 2021 East Cape earthquake locates at the boundary between the southern end of Kermadec trench and the northern end of Hikurangi margin, where the Pacific plate subducts beneath the Australian plate and its convergence decreases and progressively rotates to oblique motion toward the south (Fig. 1) (Collot et al., 1996, 2001; Lewis et al., 1998; Wallace et al., 2009). The reported centroid depth of the earthquake was ~ 50 km (U.S. Geological Survey Earthquake Hazards Program, 2017; Duputel et al., 2012; Dziewonski et al., 1981; Ekström et al., 2012), and the focal mechanism indicates oblique-thrust motion, with the compressional axis oriented towards the north-south direction (Fig. 1) (U.S. Geological Survey Earthquake Hazards Program, 2017; Duputel et al., 2012; Dziewonski et al., 1981; Ekström et al., 2012). This compressional axis suggests the earthquake was not a simple shallow normal- or reverse-faulting event with the strike angle oriented parallel to the trench axis, as is typically seen in many subduction zones (Fig. 1) (U.S. Geological Survey Earthquake

85 Hazards Program, 2017; Duputel et al., 2012; Dziewonski et al., 1981; Ekström et al.,
86 2012). However, the earthquake produced observable tsunami signals at tide gauges
87 at the northern coast of New Zealand (GeoNet News, 2021), indicating seafloor de-
88 formation due to possible shallow slip. All these apparently inconsistent observations
89 (GeoNet, 2021; GeoNet News, 2021) suggest a complex rupture process of the East
90 Cape earthquake, possibly involving multiple faults at different depths.

91 Although the subduction-related deformation processes in the southern part of
92 the Hikurangi subduction zone have received a lot of scientific attention (e.g., Eberhart-
93 Phillips & Reyners, 1997; Wallace et al., 2009; Mochizuki et al., 2021), the northern
94 segment of Hikurangi margin, where it transitions to the Tonga-Kermadec arc, is less
95 well understood. In region north of East Cape, sporadic deep seismicity (>80-km depth)
96 contrasts with abundant shallow seismicity (<50-km depth) (Dziewonski et al., 1981;
97 Ekström et al., 2012; GeoNet Moment Tensors, 2021; U.S. Geological Survey Earth-
98 quake Hazards Program, 2017; GeoNet, 2021). Most of the shallow earthquakes are
99 normal faulting events within the top of the oceanic plate due to trench-normal ex-
100 tensional stress due to slab bending into the trench (Reyners & McGinty, 1999; Hen-
101 rys et al., 2006; Bassett et al., 2010). With these shallow earthquakes, the plate inter-
102 face and the surrounding materials have been imaged down to ~20 km depth (Davey
103 et al., 1997; Bell et al., 2010; Bassett et al., 2010, 2016), but the lithospheric structure
104 of the deep slab is poorly resolved. The apparent complex rupture process of the 2021
105 East Cape earthquake offers a unique opportunity to image the stress regime associ-
106 ated with the deeper subduction process.

107 Here we show that the rupture process of the 2021 East Cape earthquake involves
108 multiple rupture episodes with a mixture of reverse, strike-slip, and normal faulting
109 mechanisms. These episodes ruptured multiple faults through the subducted oceanic
110 lithosphere at various depths. The earthquake initiated at 70 km depth with an un-
111 expected trench-parallel compressional reverse faulting mechanism, and followed by
112 a slip episode at 30 km depth, which is likely governed by more usual slab-bending
113 trench-normal down-dip extensional stresses. Such a rupture process reflects a het-
114 erogeneous stress regime within the subducted slab, in response to a possible geomet-
115 ric change of the slab in depth due to either the subduction of a seamount associated
116 with the Ruatoria debris slide (Lewis et al., 1998; Collot et al., 2001; Lewis et al., 2004),
117 or a sharp change in slab buoyancy at the northern end of the subducting Hikurangi
118 oceanic plateau.

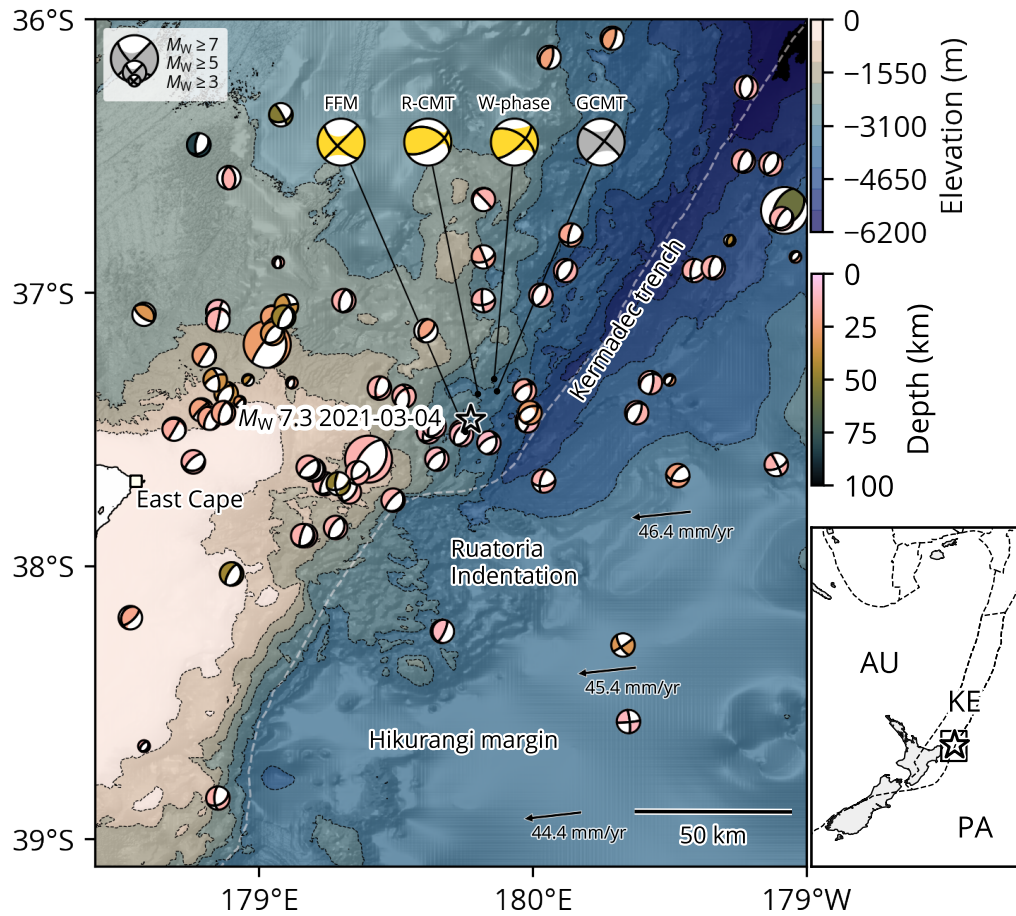


Figure 1. Seismo-tectonic overview of the study region in the north of East Cape, New Zealand. The star shows the relocated hypocenter of the M_W 7.3 2021 East Cape earthquake. Beach balls are the lower-hemisphere stereographic projection of the moment tensor solutions before the 2021 East Cape earthquake, colored by depth (Dziewonski et al., 1981; Ekström et al., 2012). Yellow beach balls are the moment tensor solutions for the 2021 East Cape earthquake obtained by this study (FFM; Finite-fault model, R-CMT; regional centroid moment tensor, W -phase; W -phase moment tensor). Background contours display the bathymetry (Mitchell et al., 2012). The arrows show the relative plate motions with the convergence rate of the Pacific plate (PA) towards the fixed Australian plate (AU) (DeMets et al., 2010). The dashed line gives the approximate location of the subduction trench (e.g., Bassett et al., 2010). The right map shows the wider setting of the study region. The rectangle shows the area of the left map. The star marks the epicenter. The dashed lines are the plate boundaries (Bird, 2003) between the Pacific (PA), the Australian (AU) and the Kermadec (KE) plates.

119 2 Hypocenter, aftershock relocation, and initial source estimates

120 We first determined the hypocenter of the East Cape earthquake by non-linear
121 inversion of P - and S -wave arrival times at regional distances using a 1D velocity model
122 appropriate for the region north of East Cape (Text S1; Fig. S1). Our relocated epi-
123 center lies along the trench axis, and is within 10 km of the GeoNet solution (GeoNet,
124 2021), and ~ 35 km ENE of the U.S. Geological Survey National Earthquake Informa-
125 tion Center (USGS-NEIC) solution (U.S. Geological Survey Earthquake Hazards Pro-
126 gram, 2017) which is consistent with the USGS-NEIC epicenters being systematically
127 shifted to the down-dip direction in subduction zones (e.g., Ye et al., 2017). Our maximum-
128 likelihood hypocenter depth is 72 km. Although this hypocenter depth may be thought
129 to be inherently uncertain due to the sub-optimal station coverage, it provides an ini-
130 tial hypothesis for testing our results of the more complex rupture configuration later.
131 If we instead fix our hypocentral depth at the fixed GeoNet/USGS estimates of 10–
132 12 km (GeoNet, 2021; U.S. Geological Survey Earthquake Hazards Program, 2017),
133 the root-mean-square residual of arrival times at the closest stations (< 200 km) increases
134 by 0.3 s, suggesting that a shallow depth is less compatible with the observations. How-
135 ever, no depth phases were reported in the International Seismological Centre Bul-
136 letin for this earthquake (International Seismological Centre, 2021), presumably due
137 to interference with the long source-time function.

138 Next, we used the COMLOC package (Lin & Shearer, 2005, 2006) to relocate earth-
139 quakes near the mainshock hypocenter. The algorithm uses the source-specific sta-
140 tion term (SSST) method to relocate the earthquakes, which can greatly improve the
141 relative locations of nearby events because of implementing empirical corrections to
142 neutralize the 3D velocity effects (Richards-Dinger & Shearer, 2000; Lin & Shearer,
143 2005). We focus on events occurring from January 1, 2021 to May 1, 2021 near the
144 source region of the 2021 East Cape earthquake as there were few events in the re-
145 gion prior to the earthquake. These events are relocated using both P - and S -wave phase
146 picks from GeoNet (2021) and a 1D velocity profile taken from the NZW2.2 model
147 (Eberhart-Phillips et al., 2010, 2020). We selected the L1-norm as the traveltimes-residual
148 misfit measure, and obtained locations for 3484 events (Fig. S2). We find that the dis-
149 tribution of aftershocks from one week after the mainshock (1486 events) is spread
150 across the whole lithosphere, from the seafloor down to ~ 100 km in depth. We no-
151 tice several peaks of the large uncertainty in the shallow (< 30 km depth) and deep
152 regions (> 50 km depth), which likely relate to the discontinuities in the velocity model.
153 However, the widespread seismicity across the whole lithosphere remains a persistent
154 pattern. In particular, the deep aftershocks corroborate our deep mainshock hypocen-

155 ter hypothesis, and the aftershock distribution indicates a possible multi-fault rup-
156 ture process of the East Cape earthquake.

157 Using a Bayesian bootstrapping centroid-moment tensor (CMT) inversion of low-
158 frequency (2.0–8.5 mHz) teleseismic waveforms for a single-point source (Text S2),
159 we find a mean centroid depth of 53 km, with a centroid position shifted 18 km NNE
160 of our relocated epicenter, and time shift from the origin time of +5 s (Fig. S3). How-
161 ever, the CMT solution has a large non-double couple component (DC=15%). Such
162 a low DC component is likely caused by geometric complexities of the earthquake that
163 may involve multiple faults within the subducted Pacific plate near the Hikurangi trench.

164 Finally, to test the hypothesised rupture complexity, we investigated the rupture
165 process of the earthquake with a multi-point centroid moment tensor (R-CMT) inver-
166 sion method using regional seismic waveforms (Text S3; Figs. S4 to S6). The approach
167 can resolve the first-order features of a complex rupture with few assumptions. Due
168 to the low-velocity accretionary wedge, the later part of the <25 s period surface waves
169 on the horizontal components at stations within ~400 km epicentral distance are poorly
170 fit (Figs. S5 and S6) due to basin resonance effects (Kaneko et al., 2019). We find that
171 the East Cape event can be best explained by two sub-events, with the largest sub-
172 event ($M_W \sim 7.3$) at 50–70 km depth occurring 8–10 s after the origin time, and the
173 second sub-event at 7–12 km depth and 6–8 s after the first sub-event. The second
174 sub-event significantly increases waveform variance reduction by 16–23%. The first
175 sub-event has an oblique-reverse mechanism. Conversely, the second sub-event has
176 a normal faulting mechanism. The shallow aftershock lineation (10–30 km depth) dips
177 to the west (Fig. S2), which suggests the fault plane is likely oriented along the trench
178 axis. Overall, our R-CMT solution corroborates a complex rupture scenario involving
179 at least two sub-events separated by ~40 km in depth: one in the top of the Pacific
180 plate, the other deep within the slab.

181 **3 Intermittent complex multiple rupture episodes with various focal mechanisms**

182 To better understand the rupture development, we applied a finite-fault potency-
183 density inversion method (Shimizu et al., 2020) to estimate the rupture evolution of
184 the 2021 East Cape earthquake (Text S4). The method can flexibly accommodate mul-
185 tiple faults with different geometries rupturing during the same event, which are in-
186 ferred from the spatiotemporal distribution of five-basis double-couple components
187 of the potency-density tensors (Kikuchi & Kanamori, 1991; Ampuero & Dahlen, 2005).
188 In our inversion formulation, the model parameters are objectively determined by min-
189 imizing Akaike’s Bayesian Information Criterion (ABIC) (Akaike, 1980; Yabuki & Matsu’ura,

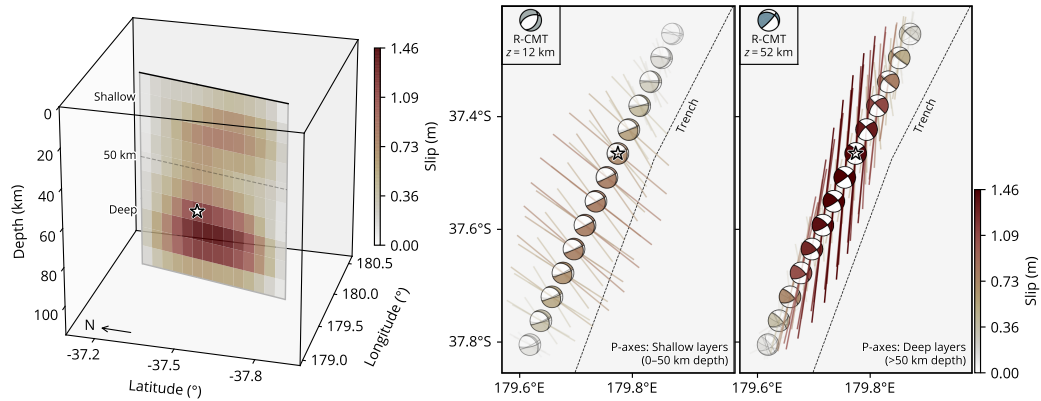


Figure 2. Static slip distribution. The left panel shows the total slip distribution in a 3D view, viewed from the south-west. The star represents our hypocenter. The black line shows the top of the model fault. The right panels show the map view of the slip distribution from shallow (<50 km) and deep depths (≥ 50 km), with beach balls representing double-couple components (Fig. S7), and corresponding P-axis azimuths (bars scaled by slip). The P-axis azimuth is extracted from the resultant double-couple solution for each sub-fault, which is represented by a lower-hemisphere stereographic projection. We show the beach balls from the slip patch corresponding to the fault element with the maximum slip within each given depth range. The inset shows the corresponding R-CMT solutions annotated with their depths (z). The dashed line is the subduction trench (Bird, 2003).

1992), and we do not adopt non-negative constraints for slip vectors. Such a procedure can effectively prevent over- or under-smoothing of the source model as theoretically shown in Fukuda and Johnson (2008). Particularly, we flexibly solve the potency density in a finite-fault domain instead of regularizing the model with possible inaccurate subjective assumptions (e.g., positivity constraints, and the prescribed fault geometry). The method has proven effective at resolving complex earthquake ruptures in a variety of tectonic settings (Shimizu et al., 2020, 2021; Okuwaki et al., 2020; Hicks et al., 2020; Tadapansawut et al., 2021; Yamashita et al., 2021). In practice, we parametrize a 2D vertical model domain along a 200° strike extending from 7- to 107-km depth with a total of 140 source elements (sub-faults) (Fig. 2). This parameterization is guided by the observed cluster of the near-trench-parallel aftershocks (Fig. S2). Although it is difficult to resolve the absolute locations of slip surfaces due to insufficient spatial resolution of the teleseismic body waves used in our finite-fault modeling, in the 2D model domain, we solve the fault-normal and shear-slip vectors at each source element, which are independent of the model domain geometry. In other words, we solve for distributed sources in the model domain that may have any type of faulting mechanism required by the data. The model domain therefore allows multiple faulting episodes of the earthquake and does not necessarily indicate a single fault plane cutting through the lithosphere in a continuous rupture. Our preferred slip model suggests that the earthquake initiated at 72 km depth (Fig. S12) corroborating the relocated hypocenter and the R-CMT solution.

Our preferred finite-fault model suggests that most slip occurred at 55 to 100 km depth and ~15 km south of the hypocenter, releasing 69% of the total moment (Fig. 2). Another patch of slip is observed at 20–40 km depth, much shallower than the hypocentral depth and comprising 31% of the total moment. The deeper slip is dominated by an oblique strike-slip faulting mechanism. The shallow slip involves a mixture of normal and strike-slip faulting mechanisms. The finite-fault model leads to a moment estimate of 1.7×10^{20} Nm (M_W 7.4). We evaluated the robustness and uncertainty of the finite-fault model by performing synthetic tests (Fig. S13). The result shows that both the slip pattern and the variation of faulting mechanism in the model domain are well reproduced. We will discuss in detail in a later section, but the focal mechanisms of the shallow and deep domains agree with the R-CMT solutions (Fig. 2), which show shallow normal faulting with the likely fault plane orienting along the trench axis and deep reverse faulting with the compressional axis orienting along the trench axis.

225 The rupture process of the East Cape earthquake involved at least four distinct
226 episodes (E1 to E4) with the deep- and shallow-slips corresponding to different fault-
227 ing types. The earthquake initiated as a reverse faulting with a strike-slip component
228 for the first 5 s (E1, Fig. 3). The rupture then propagated towards the south at 60–
229 100 km depth, releasing 20% of the total moment and lasting for about 5 s (E2, Fig.
230 3). This episode was dominated by thrust faulting. The third episode (E3) simulta-
231 neously ruptured several fault patches from 10 to 15 s, including a shallow patch at
232 ~25 km depth and a deep patch ~70 km depth (Fig. 3). The shallow part of E3 rup-
233 tured with a normal faulting mechanism, while the deep patch of E3 had a strike-slip
234 mechanism. The last major episode (E4) ruptured a fault patch beneath the hypocen-
235 ter for about 5 s with a dominant strike slip focal mechanism (Fig. 3). The remain-
236 ing 26% of the total moment was released by slips at both shallow and deep regions,
237 and the earthquake lasted for about ~30 s.

238 The four rupture episodes are compact in size and are spatially distinct from each
239 other. Given the varying focal mechanisms, the chaotic episodes likely do not result
240 from the same continuous rupture front, but more likely represent segmented slip on
241 different faults that may have interacted with, and triggered, each other.

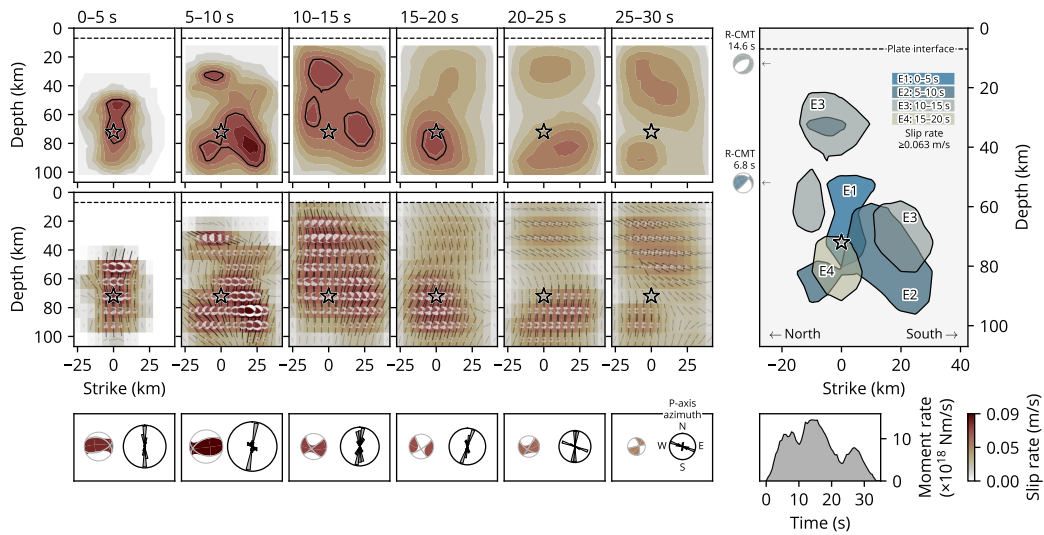


Figure 3. Slip evolution. The left panels show the cross sections of the spatio-temporal distribution of slip rate and the resultant moment-rate tensor solution, given in 5 s long windows. The star represents the hypocenter. The dashed line is the top of the subducting plate (Bassett et al., 2010). The black contour highlights faster slip rates (≥ 0.063 m/s; $\geq 70\%$ of maximum slip rate). The centroid moment tensor for each time window is shown at the bottom, together with the rose diagram of P-axis azimuths weighted by slip rate. All the beach balls of the moment-tensor solution are represented as a lower-hemisphere stereographic projection, not rotated according to the model geometry, but in map view. The right panel summarizes the slip-rate evolution. The color for each episode (E1 to E4) corresponds to the time window. The minor slip-rate events within the final two time windows (20–30 s) are not slipping fast enough to plot a contour on the right panel. R-CMT solutions are also shown at the corresponding depths, with their time shift given relative to the hypocentral time. The right-bottom inset is the total moment-rate function from the finite-fault model.

242 **4 Intralab stress rotation in depth**

243 The source process of the 2021 East Cape earthquake is characterized by spa-
244 tiotemporally disconnected, multiple episodes rupturing from deep to shallow within
245 the subducted slab (Fig. 2). For the shallow slip episode, its focal mechanism shows
246 a mixture of the normal faulting with a strike-slip component. The general trend of
247 the aftershock distribution (Fig. S2) suggests that the fault plane striking toward the
248 northeast-southwest direction likely ruptured during the later phase of the earthquake.
249 Although the limited station azimuth coverage could cause an artificially elongated
250 aftershock distribution, the major axis of the uncertainty ellipse of the mainshock re-
251 location, which shares the similar station coverage, is oriented W-E rather than SW-
252 NE (Fig. S1). It is noteworthy that some aftershocks (U.S. Geological Survey Earth-
253 quake Hazards Program, 2017; Dziewonski et al., 1981; Ekström et al., 2012; GeoNet
254 Moment Tensors, 2021) share similar focal mechanisms to the shallow rupture episode
255 (Fig. S8). Given the near-trench location of the East Cape earthquake, there is some
256 ambiguity regarding the exact faulting configuration. However, the aftershock distri-
257 bution indicates that the shallow slip episode likely ruptured a normal fault within
258 the downgoing plate. Additionally, in the absence of clear shallow slip with a reverse-
259 faulting mechanism, this normal faulting episode likely caused the observed tsunami.

260 The varying focal-mechanisms of the four slip episodes (E1–E4) show the com-
261 pressional stress orientation (the P-axis orientation) of the East Cape earthquake ro-
262 tated from the northwest-southeast direction to the north-south direction with a gap
263 in slip and approximate stress transition depth at ~50 km (Figs. 2 and 3). The nor-
264 mal faulting of the shallow slip episodes striking toward the northeast-southwest di-
265 rection agrees well with the extensional stress in the upper part of the subducted plate
266 due to the expected plate bending and pulling process (e.g., Astiz et al., 1988; Am-
267 mon et al., 2008; Craig et al., 2014; Romeo & Álvarez-Gómez, 2018; Sandiford et al.,
268 2020). Such a bending process seems to have caused most of the background seismic-
269 ity in this region, which has predominant normal faulting mechanisms (Fig. 1; Reyn-
270 ers & McGinty, 1999; Bassett et al., 2010). If the deep slip at 50–100-km depth dur-
271 ing the East Cape earthquake was driven by the same bending-related process, we would
272 expect a trench-normal P-axis orientation, which is typical for similar events at other
273 subduction zones, where deep trench-parallel reverse faulting is observed (e.g., Okada
274 & Hasegawa, 2003; Ohta et al., 2011; Ye et al., 2012; Todd & Lay, 2013; Ye et al., 2021).
275 However, the deep slip patches of the East Cape earthquake (E1 and E2, and R-CMT
276 Sub-event 1) have oblique-thrusting mechanisms, resulting in a trench-parallel com-

277 pression. This perplexing P-axis orientation indicates an additional regional factor that
278 may have modulated the rupture process of the East Cape earthquake.

279 The interactivity between various faulting episodes is a puzzling part of the East
280 Cape earthquake. Subduction zone earthquakes may involve multiple disconnected
281 subevents with different faulting types that can trigger and interact with each other
282 (Ammon et al., 2008; Lay et al., 2013; Hicks & Rietbrock, 2015; Lay et al., 2020). For
283 the East Cape earthquake, our preferred finite-fault model does not show a contin-
284 uous rupturing path from the deep to shallow episodes (Figs. 2 and 3). The shallow
285 rupture E3 is separated by ~ 40 km from the deep episodes and started ~ 5 s later (Fig.
286 3), suggesting an apparent rupture speed of ~ 8 km/s if the rupture was continuous.
287 Such a rupture speed would be close to the local P -wave speed (Table S1), which is
288 unlikely. More likely, slip episodes E1 and E2 triggered the following shallow episode
289 E3 due to either the static and/or dynamic stress change from the initial deep rup-
290 ture. A stress transition or strength contrast within the slab can work as an inhom-
291 ogeneous barrier (Das & Aki, 1977; Aki, 1979) to smooth propagation from deep to shal-
292 low rupture during the East Cape earthquake. Therefore, the rupture evolution of the
293 earthquake may have developed as discontinuous jumps by means of stress trigger-
294 ing (Miyazawa & Mori, 2005; Sleep & Ma, 2008; Fischer, Sammis, et al., 2008; Fischer,
295 Peng, & Sammis, 2008) across the apparent stress/strength barrier between the deep
296 and shallow rupture areas.

297 Large intraplate earthquakes within the downgoing plate in subduction zones
298 are typically caused either by the down-dip bending and unbending of the slab (e.g.,
299 Astiz et al., 1988; Craig et al., 2014; Sandiford et al., 2020), the reactivation of ma-
300 jor oceanic fabrics, including fracture zones (e.g., Abercrombie et al., 2003; Meng et
301 al., 2012; Yue et al., 2012), or the tearing of the slab (e.g., Tanioka et al., 1995). How-
302 ever, the orientation and rupture complexity of the 2021 East Cape event deviates from
303 these typical events. Two events with apparently similar deep trench-parallel com-
304 pression in the slab include 2003 M_W 7.9 Enggano and 2009 M_W 7.6 Padang earth-
305 quakes, offshore Sumatra (Abercrombie et al., 2003; Wiseman et al., 2012). However,
306 these events likely ruptured pre-existing fabrics in the downgoing plate (Abercrombie
307 et al., 2003), such as fracture zones (Wiseman et al., 2012). Both earthquakes poten-
308 tially represent the continuation of the diffuse deformation within the Wharton basin,
309 and both consistently ruptured orthogonal fabrics toward the top of the downgoing
310 plate both updip and downdip from the trench, where highly oblique convergence in-
311 herently causes a rotated state of the stress in the slab. In contrast, the 2021 East Cape
312 earthquake, which occurred deeper beneath the top of the slab, does not align with

313 the expected oceanic fabric, and is not obviously part of a wider, plate-scale, defor-
314 mation field, where there is no obvious oblique convergence nor are fracture zones
315 of an orientation consistent with the observed mechanisms subducted (Fig. 1). Instead,
316 the rupture processes may represent a unique case, highlighting a different type of
317 stress transition within the subducted slab.

318 **5 A contorted slab structure due to slab buoyancy variations?**

319 A key question is why does this part of the Hikurangi subduction zone exhibit
320 an atypical stress regime, as manifested in the rupture process of the 2021 East Cape
321 earthquake? Slab models of this region (Hayes, 2018; Hayes et al., 2018; Williams et
322 al., 2013) show a homogeneous planar structure (Fig. S9) which would be expected
323 to lead to a trench-normal compression in the deeper part of the slab. However, these
324 slab models are poorly constrained near the East Cape earthquake, largely because of
325 a lack of plate interface thrust earthquakes in the region (Fig. 1). The rupture pro-
326 cess of the East Cape earthquake therefore potentially offers new insight into the lo-
327 cal slab structure.

328 One possible explanation is that the slab surface warps downward north of the
329 hypocenter, forming a depression at the plate interface (Fig. 4). The warping is likely
330 a response to the buoyancy gradients in the subducting plate, which allows the less
331 buoyant parts of the slab to sink more rapidly than the buoyant parts. The internal
332 stress field from such a slab topology would be complex, leading to strong 3-D stress
333 rotations around the localized downwarp in a manner as shown in the 2021 East Cape
334 earthquake (Fig. 2). One contribution to the buoyancy gradients might be the sub-
335 duction of a large-scale seamount. About 30 km south-west from the epicenter, the
336 Quaternary Ruatoria seamount was obliquely subducted at the margin (Lewis et al.,
337 1998; Collot et al., 2001; Lewis et al., 2004), forming the characteristic bathymetry of
338 the Ruatoria indentation (Fig. 1). The Ruatoria seamount could deflect and bend the
339 slab, causing the intraslab stress state to rotate from trench-normal compression to
340 trench-parallel compression across the hypocentral area. Numerical models of slab
341 stress in the presence of subducted buoyant features in the oceanic plate support such
342 a stress rotation and lateral spreading mechanism (e.g., Mason et al., 2010). Trench-
343 parallel compression has also been seen in other parts in the Hikurangi subduction
344 zone, for example, McGinty et al. (2000) observed the strike-slip seismicity with trench-
345 parallel compression at depths 40–80 km offshore from the Raukumara Peninsula. Al-
346 though these earthquakes beneath the Raukumara Peninsula should reflect the stress
347 state once the plate is already subducted, rather than at the trench region which is

348 where the 2021 East Cape earthquake illuminates, it is possible they reflect stress het-
349 erogeneity due to pervasive seamount subduction along the northern Hikurangi sub-
350 duction zone (Barker et al., 2009).

351 An alternative explanation may arise from the location of the East Cape earth-
352 quake with respect to the transition between the Kermadec trench and Hikurangi mar-
353 gin, marked by the edge of the Hikurangi plateau, which is represented by a clear bathy-
354 metric scarp running along its northern boundary (Davy & Collot, 2000). This tran-
355 sition from the subduction of normal oceanic lithosphere to the north, to the subduc-
356 tion of the thickened oceanic crust associated with the igneous Hikurangi plateau likely
357 leads to a pronounced, short-wavelength flexural warping at the plateaus edge. The
358 superposition of this N-S flexural stress field with the stress field related to the down-
359 dip bending would produce a complex pattern that varies at short-length scales within
360 the subducted slab, and could impact on the rupture process seen in the compound
361 East Cape earthquake. It is noteworthy that in 2001, ~80 km northeast of the 2021
362 event, there was a M_W 7.1 earthquake deep in the Pacific plate (~60 km depth) show-
363 ing a reverse faulting mechanism with its P-axis oriented perpendicular to the Ker-
364 madec trench (Fig. S8), which was likely driven by conventional trench-normal down-
365 dip compression. This earthquake suggests that flexural warping due to the subduct-
366 ing Hikurangi plateau does not extend this far to the north.

367 Whilst there have been many studies on the impact of subducting buoyant fea-
368 tures on subduction megathrust coupling and interface seismogenesis (e.g., Wang &
369 Bilek, 2011; Nishikawa & Ide, 2014), there have been far fewer studies that have con-
370 sidered their impact on intraslab seismicity. The rarity of deep intraslab earthquakes
371 in the northern Hikurangi subduction zone makes it difficult to distinguish between
372 the seamount and plateau models of stress rotation. However, it is also possible that
373 both features play a concurrent role, with stress rotations superimposed from both.

374

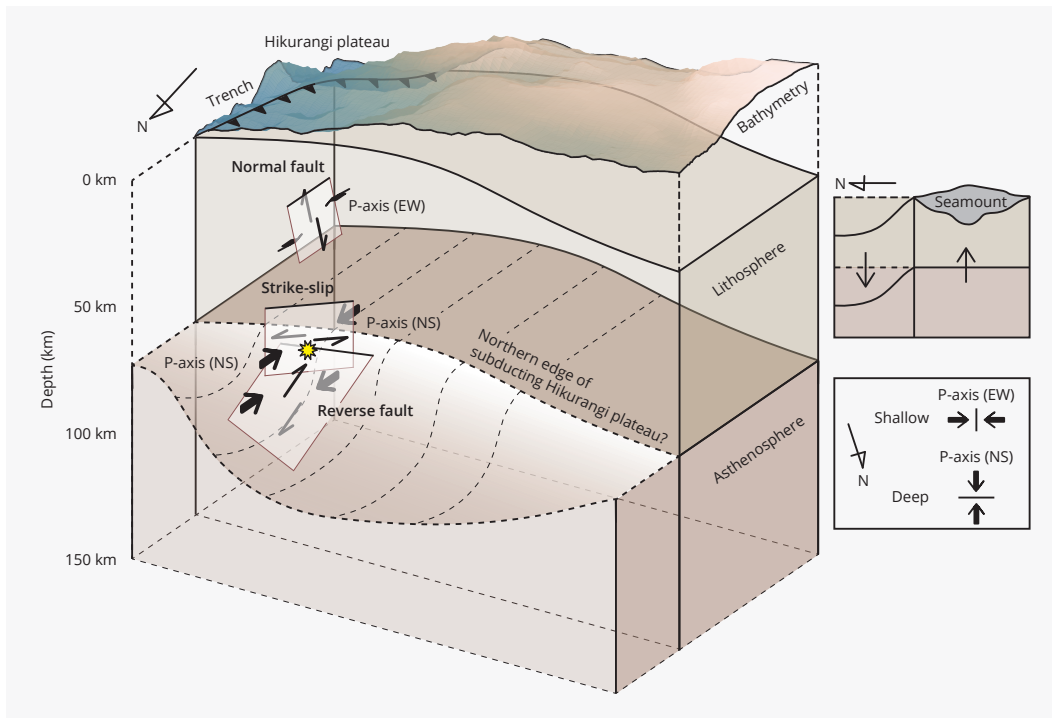


Figure 4. Schematic figure showing the inferred slab geometry, stress regimes and faulting styles based on our observations of the 2021 East Cape earthquake. The yellow marker shows the hypocenter. The arrow shows the compressional axis. The one-side arrow represents the fault motion. The bathymetry is from Mitchell et al. (2012) with its height being exaggerated $\times 15$. The upper right panel is a cross-section with the arrows showing the relative force applied in the slab. The lower right panel shows the compressional axes in a top view.

375 **6 Conclusions**

376 We determined the rupture geometry of the 2021 M_W 7.3 East Cape, New Zealand
377 earthquake using a novel finite-fault inversion technique. Our method does not re-
378 quire a-priori knowledge of the fault geometry and can flexibly resolve complex fault-
379 ing styles in large earthquakes. Therefore, it can uniquely illuminate the heterogeneous
380 stress state near the earthquake. We show that the East Cape earthquake has at least
381 four rupture episodes and likely ruptured multiple faults with various faulting styles.
382 We find distinct rupture episodes within the shallow (~ 30 km) and deep (~ 70 km)
383 parts of the subducted oceanic plate, with distinct mechanisms of normal and a mix-
384 ture of strike-slip and reverse faulting, respectively. The deep and shallow episodes
385 likely reflect components of a flexural stress field, separated by a low-stress barrier
386 in the middle of the plate. The rotation of P-axes suggests that the intraplate stress
387 state is locally rotated from trench-normal compression to trench-parallel compres-
388 sion. Such a stress rotation in depth requires the slab geometry to change sharply, which
389 may have been induced by a subducted seamount or the additional buoyancy of the
390 Hikurangi plateau. Our study suggests that understanding the generation of interme-
391 diate and deep intraslab seismicity requires a detailed treatment of localized varia-
392 tions in slab geometry caused by the subduction of heterogeneous features, such as
393 ocean plateaus and seamounts.

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412 **Data Availability Statement**

413 All the materials presented in this paper are archived and available at [https://doi.org/](https://doi.org/10.5281/zenodo.5386179)
414 [10.5281/zenodo.5386179](https://doi.org/10.5281/zenodo.5386179). All seismic data were downloaded through the IRIS Wilber
415 3 system (https://ds.iris.edu/wilber3/find_event) or IRIS Web Services ([https://service](https://service.iris.edu)
416 [.iris.edu](https://service.iris.edu)), including the following seismic networks: the GT (Global Telemetered Seis-
417 mograph Network (USAF/USGS); Albuquerque Seismological Laboratory (ASL)/USGS,
418 1993); the IC (New China Digital Seismograph Network; Albuquerque Seismological
419 Laboratory (ASL)/USGS, 1992); the IU (Global Seismograph Network (GSN - IRIS/USGS);
420 Albuquerque Seismological Laboratory (ASL)/USGS, 1988); the GE (GEOFON Seis-
421 mic Network; GEOFON Data Centre, 1993); the AU (Australian National Seismograph
422 Network (ANSN); Geoscience Australia (GA), 1994); the HK (Hong Kong Seismograph
423 Network; Hong Kong Observatory, 2009); the G (GEOSCOPE; Institut De Physique
424 Du Globe De Paris (IPGP) & Ecole Et Observatoire Des Sciences De La Terre De Stras-
425 bourg (EOST), 1982); the NZ (New Zealand National Seismograph Network; Institute
426 of Geological & Nuclear Sciences Ltd (GNS New Zealand), 1988; Petersen et al., 2011);
427 the AI (Antarctic Seismographic Argentinean Italian Network - OGS; Istituto Nazionale
428 Di Oceanografia E Di Geofisica Sperimentale, 1992); the II (IRIS/IDA Seismic Network;

429 Scripps Institution Of Oceanography, 1986); the C (Chilean National Seismic Network;
 430 Universidad de Chile Dept de Geofisica (DGF UChile Chile), 1991); the PS (Pacific21
 431 (ERI/STA); University of Tokyo Earthquake Research Institute (Todai ERI Japan), 1989).
 432 We used ObsPy (Beyreuther et al., 2010, version 1.1.0; [https://doi.org/10.5281/zenodo](https://doi.org/10.5281/zenodo.165135)
 433 [.165135](https://doi.org/10.5281/zenodo.165135)), Pyrocko (The Pyrocko Developers, 2017, <https://pyrocko.org/>), matplotlib
 434 (Hunter, 2007, version 3.0.3; <https://doi.org/10.5281/zenodo.2577644>), Generic Map-
 435 ping Tools (Wessel & Luis, 2017, version 6.1.0; <http://doi.org/10.5281/zenodo.3924517>);
 436 and Scientific colour maps (Crameri, 2018; Crameri et al., 2020, version 6.0.4; [http://](http://doi.org/10.5281/zenodo.4153113)
 437 doi.org/10.5281/zenodo.4153113) for data processing and visualisation. The NonLin-
 438 Loc software used for hypocenter relocation is available at <http://alomax.free.fr/nlloc/>.
 439 The Grond software (Heimann et al., 2018) used for *W*-phase CMT inversion is avail-
 440 able at <https://pyrocko.org/grond/docs/current/>. The ISOLA software used for R-CMT
 441 inversion is available at <http://seismo.geology.upatras.gr/isola/>. The COMLOC earth-
 442 quake location package (Lin & Shearer, 2005, 2006) for aftershock relocation is avail-
 443 able at <https://sites.google.com/view/guoqing-lin/products/comploc>.

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