

# 1 Palaeotidal atlas of the UK for the last 2 10,000 years

3 Jon Hill<sup>1</sup>

4 <sup>1</sup>Department of Environment and Geography, University of York. jon.hill@york.ac.uk

## 5 ABSTRACT

6 Over the past 10,000 years the UK has seen dramatic changes to its coastline due to sea-level  
7 rise. Past changes in sea level can be estimated from analysis of sedimentary deposits,  
8 including any microfossil assemblages found within. Once dated and the elevation is know,  
9 these data become sea level index points (SLIPs). In recreating past sea level in this way there  
10 is an implicit assumption of no change to the tidal regime, despite the fact we know this not to  
11 be true. Here, I present modelling simulations of the tides of the UK for the past 10,000 years  
12 based on current estimates of palaeoshorelines and bathymetry. I validate the tidal model on  
13 modern tidal gauges using the 0 m contour as a shoreline as well as modern shoreline data,  
14 before using the same model to create 30 day tidal simulations at 1,000 year intervals. This  
15 palaeotidal atlas can be used to estimate both maximum tidal heights and tidal range which in  
16 turn could be used to correct SLIPs. The results are consistent with previous estimates, despite  
17 differences in estimated palaeobathymetry, boundary conditions and numerical technology  
18 used. The tidal maps published will have a wide range of uses across Quaternary science.

19 Keywords: sea level, modelling, tides

20  
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## 27 INTRODUCTION

28 During the Holocene the Northwest European continental shelf sea has been transformed due  
29 to sea-level rise due to deglaciation of the Fendo-Scandinavian ice sheet. Eustatic sea level has  
30 risen some 130 m meters over the last 16,000 years with the majority of that change taking place  
31 between 16,000 and 7,000 years (Lambeck et al., 2014). Not only does the rise vary temporally,  
32 but due to isostatic rebound, relative sea level also varies spatially. This legacy is still relevant  
33 today as the UK is experiencing differential rates of relative sea level rise with the south of the  
34 UK experience much higher rates of relative sea level rise than the north (Shennan et al., 2018).

35 In order to assess past sea-level changes we need to find evidence of of where the sea level  
36 was in the past. This evidence can be geomorphological (e.g. raised beaches), palaeontological  
37 or sedimentological (e.g. marine sediments), archaeological (Shennan, 2015). By dating these  
38 data, along with accurate measurements of location, the direction sea level is moving in and  
39 height above/below modern mean water height (Shennan, 2015), the data can be terms a Sea  
40 Level Index Point (SLIP). However, most SLIPS are data within the tidal range; that is they  
41 represent some measure of water level, but not necessary the mean sea level (Hill, 2016; van de

42 [Plassche, 1986](#)). Therefore, to interpret the SLIP as mean sea level a tidal range is required.  
43 Without any other information available, modern tidal ranges are used.

44 Previous numerical modelling studies have already established that tidal range can change  
45 dramatically with changing sea levels. Previous studies have tended to focus on a smaller area,  
46 e.g. the Wash or have used relatively coarse resolution of several km over the NW European shelf.  
47 One of the first such model that used more than a simple  $M_2$  forcing was that of [Hinton \(1992\)](#)  
48 which modelled the southern North Sea coast of England using a 3 km regular grid. Hinton  
49 reconstructed palaeobathymetry simply by reducing or increasing sea level uniformly across the  
50 grid. Similar methods were employed by [Austin \(1991\)](#), who also examined the changes in tidal  
51 dissipation and tidal fronts. Models have since been developed that made use of GIA models,  
52 such as those of [Shennan and Horton \(2002\)](#) and [Neill et al. \(2010\)](#). The inclusion of a GIA  
53 model to estimate palaeobathymetric changes take into account the spatial nature of the changes.  
54 The most recent NW shelf model was that of [Ward et al. \(2016\)](#) which used a relatively coarse  
55 computational mesh of around 4.5 km (1/24 of a degree) and looked at changes to bed shear  
56 stress as well as tidal dynamics. All previous models show substantial changes in the Mean High  
57 Water Spring Tides and tidal range due to sea-level changes in the UK.

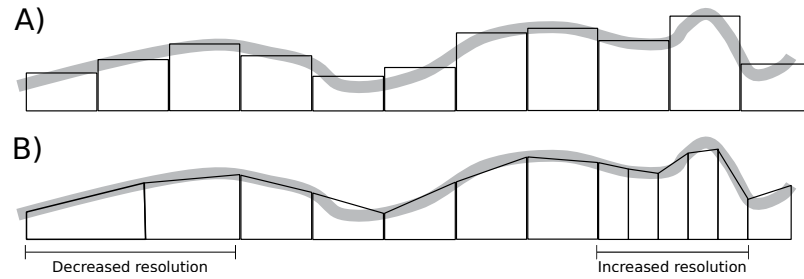
58 The result of palaeotidal models can be used to correct SLIPs for palaeo-tidal range. [Neill](#)  
59 [et al. \(2010\)](#) suggested this to be the case, but noted the inherent circularity of the problem –  
60 correcting SLIPs alters the GIA model, which in turn alters the palaeobathymetry and then the  
61 tidal range estimates. [Neill et al. \(2010\)](#) suggest a procedure whereby some SLIPs are held  
62 back from the GIA model used to define the palaeobathymetry of the tidal model to provide a  
63 verification-calibration study. [Ward et al. \(2016\)](#) agree that this methodology could be useful  
64 and also that higher resolution models are better suited to this as SLIPs are often found near  
65 coastlines or in estuaries.

66 Here, I use multiscale modelling on an unstructured mesh with resolution varying from  
67 20 km to 1.5 km around the coastlines, with palaeobathymetry derived from the 2011 GIA  
68 modelling of [Bradley et al. \(2011\)](#). This is the first time a multiscale approach has been used in  
69 this way and that all model outputs made freely available for further study. Unstructured mesh  
70 models have particular advantages when modelling complex coastlines and bathymetries as they  
71 avoid the ‘staircase effect’ ([Wells et al., 2005a](#)) typically seen in structured mesh models (Fig. 1).  
72 Increasing resolution to where it is needed (e.g. coastlines or rapid changes in bathymetry) means  
73 that the accuracy of a higher resolution model is obtained whilst minimising computational  
74 expense.

75 In this paper, I outline the details of the model set-up used before validating this model on  
76 the modern UK tidal gauge data. I then detail the set up for the palaeotidal models and then  
77 present results of the tidal atlas at 1,000 year intervals. Results are shown for a number output  
78 parameters including tidal stratification estimates. I conclude by discussing the implications  
79 of this study in terms of correcting the European SLIP database and how we could avoid the  
80 circularity problem.

## 81 **METHODS AND MATERIALS**

82 The palaeotides were calculated using the Fluidity model, which is a highly flexible finite  
83 element/control volume modelling framework which allows for the numerical solution of a  
84 number of equation sets ([Piggott et al., 2008](#)) and has been used in a variety of tidal studies,  
85 including both modern and ancient tides on regional and global scales ([Wells et al., 2005b,a,](#)  
86 [2007, 2010; Martin-Short et al., 2015; Collins et al., 2017, 2018](#)). One of the major advantages  
87 of Fluidity is the use of a multiscale mesh, which can resolve fine-scale details even in a regional  
88 setting using resolution down to metre-scale ([Martin-Short et al., 2015](#)).



**Figure 1.** Example of the ‘staircase effect’ when modelling bathymetry. The thick grey line is the actual bathymetry. In the structured grid model (A) this is represented as a value in a cell, resulting in sharp edges where bathymetry changes more quickly than the mesh size can resolve. In contrast an unstructured grid model can use linear functions within cells (or indeed higher order functions) and change resolution where needed. Unstructured mesh models typically take longer to solve for the same resolution, however.

## 89 Fluidity

Here, the depth-averaged shallow water equations are solved in a rotating reference frame in non-conservative form:

$$\begin{aligned} \frac{\partial u}{\partial t} + u \cdot \nabla u + fu^T - \nabla v \left[ \nabla u + (\nabla u)^T \right] + g \nabla \eta &= -c_b \frac{\|u\|u}{H}, \\ \frac{\partial \eta}{\partial t} + \nabla \cdot (Hu) &= 0, \end{aligned} \quad (1)$$

90 where  $u$  is the 2D, depth-averaged velocity vector,  $t$  represents time,  $\eta$  is the free surface  
 91 perturbation,  $H$  is the total water depth, and  $v$  is the kinematic viscosity. The Coriolis term,  
 92  $fu^T$ , consists of  $u^T$ , the velocity vector rotated counter-clockwise over  $90^\circ$ , and  $f = 2\Omega \sin(\zeta)$ ,  
 93 with  $\Omega$  the angular frequency of Earth’s rotation and  $\zeta$  the latitude. The dimensionless friction  
 94 coefficient  $c_b$  represent respectively the background bottom drag (assumed constant here).

95 The equations (1) are discretised on a mixed finite element pair, with a continuous Galerkin,  
 96 piecewise quadratic formulation for the free surface (P2) and a piecewise linear discontinuous  
 97 Galerkin approximation (P1<sub>DG</sub>) for velocity. The resulting P1<sub>DG</sub>P2 velocity/free-surface dis-  
 98 cretisation has a number of desirable properties described fully in [Cotter et al. \(2009a,b\)](#); [Cotter](#)  
 99 [and Ham \(2011\)](#). In addition to the discretisation of the linear shallow water terms described  
 100 therein, we employ a standard P1<sub>DG</sub>-discretisation with upwind fluxes and slope limiting for the  
 101 advection term and the Compact Discontinuous Galerkin scheme [Peraire and Persson \(2008\)](#), for  
 102 the viscosity term.

103 A two-level  $\theta$  method is employed for time-integration, combined with explicit subcycling  
 104 for the advection step. Here  $\theta = 0.53$ , which is close to the Crank-Nicolson scheme, and  
 105 therefore minimises wave dissipation whilst maintaining stability. Two Picard iterations per  
 106 time-step are used to linearise the nonlinearity in the advection and friction terms. Finally, the  
 107 linear discretised systems are solved using iterative sparse linear solvers available in PETSC  
 108 [Balay et al. \(2018\)](#). More details on the spatial and temporal discretisations available in Fluidity  
 109 are described in [Imperial College London AMCG \(2015\)](#) and [Piggott et al. \(2008\)](#).

## 110 Model setup

111 The model domain consisted of the entire NW European continental shelf, bordered by coastlines  
 112 and the Danish Straits (Fig. 2). For present day simulations two coastlines types were modelled.

113 One using the high resolution GSHHS coastline dataset (Wessel and Smith, 1996), the other  
 114 using the 0 m contour. For each timeslice from 1 ka to 10 ka, modern bathymetry derived from  
 115 GEBCO 2014 (Weatherall et al., 2015) was adjusted according to the glacio-isostatic adjustment  
 116 (GIA) model of Bradley et al. (2011) to create a palaeobathymetry. For each palaeobathymetry,  
 117 a coastline derived from the 0 m contour was created, which served as a numerical boundary.  
 118 This was trimmed to meet the western boundary and the boundary at the Denmark Straits. The  
 119 mesh resolution varied with highest resolution along coastlines (1.5 km triangles), 3 km along  
 120 other boundaries and 25 km between 50 and 100 km away from a boundary. In addition, a mesh  
 121 metric based on idealised wave celerity increased resolution in deeper water where the tidal wave  
 122 moves quickest (Lambrechts et al., 2008) via:

$$50000.0 * \sqrt{\frac{10.0}{h}} \quad (2)$$

123 where  $h$  is the water depth. All points on the coastlines and boundaries were joined using a  
 124 B-spline curve to produce a smooth boundary for the final mesh. All meshes were constructed in  
 125 (qmesh) (Avdis et al., 2018).

126 The coastlines and sea bed were set to no-normal flow with a Manning quadratic drag  
 127 formulation applied with a drag coefficient of 0.025. The open boundary was forced via free  
 128 surface using the FES2014 data (Lyard et al., 2006). A short boundary section between coastline  
 129 and the open boundary was set to a no-slip boundary. Bathymetry was ‘dredged’ to ensure the  
 130 minimum water depth was 6 m to prevent stability issues as the model does not include wetting  
 131 and drying. Each model was spun up for 30 days, before then being run for another 30 days. The  
 132 final 30 days were used for all subsequent analyses.

### 133 Modern validation

134 To assess model performance I compared the model against tide gauge data from around the UK  
 135 using the two different methods of coastlines generation for the present day (0 m contour and  
 136 GSHHS). The two modern models were forced along the boundary of the continental shelf using  
 137 FES 2014 data and eight principle tidal components,  $M_2$ ,  $S_2$ ,  $N_2$ ,  $K_2$ ,  $O_1$ ,  $Q_1$ ,  $K_1$ , and  $P_1$ . The  
 138 constituents  $M_2$  and  $S_2$  are the dominant components on the NW European continental shelf.  
 139 The model was run for a total of 60 days, with the first 30 days considered as ‘spin-up’. Free  
 140 surface height data were then analysed at each tidal gauge location to produce model estimates  
 141 of  $M_2$ ,  $S_2$ ,  $K_1$ , and  $O_1$  amplitude and phases and compared to the data from tide gauges. To  
 142 compare the model against the tide gauges we use the method of Cummins and Thupaki (2017),  
 143 whereby error,  $\xi$  is calculated over the  $L$  tidal gauges as:

$$\xi = L^{-1} \sum D_L \quad (3)$$

$$D_L = \left[ \frac{1}{2} (A_o^2 + A_m^2) - A_o A_m \cos(\phi_o - \phi_m) \right]^{\frac{1}{2}} \quad (4)$$

144 where  $A_m$  is the modelled amplitude,  $A_o$  is the observed amplitude,  $\phi_o$  is the observed phase and  
 145  $\phi_m$  is the modelled phase, at each tidal gauge location. A separate  $D$  is calculated for each tidal  
 146 constituent modelled.

147 In the modern day, the mode has an error of 0.27 - 0.39 cm for  $M_2$  and 0.06 - 0.03 cm for  
 148  $S_2$  across 40 or 41 tidal stations (0 m contour or GSHHS coastline respectively), corresponding  
 149 to a 0.14 - 0.22 and 0.06 - 0.09 % error respectively according to equation 4. Fluidity appears  
 150 to slightly under predict the  $O_1$  component and over predict the  $K_1$  component compared to

Model	M <sub>2</sub> error	S <sub>2</sub> error	K <sub>1</sub> error	O <sub>1</sub> error	No. Stations
GSHHS (%)	0.22%	0.06%	0.07%	0.08%	41
GSHHS (cm)	0.39	0.03	0.07	0.08	41
0m (%)	0.14%	0.09%	0.82%	0.87%	40
0m (cm)	0.27	0.06	0.08	0.08	40

151 tide gauges at higher amplitudes, but the mean semi-diurnal components show an excellent  
 152 agreement (Fig. 3). Both GSHHS and 0 m contour derived coastlines perform well overall.

153 The spatial distribution of the M<sub>2</sub> tide and tidal range matches previous modelling studies  
 154 (Fig. 4). A major control on sediment movement in the NW European shelf sea are tidal currents  
 155 (Fig 4). [Ward et al. \(2015\)](#) developed a proxy for tidally induced bed shear stress and sediment  
 156 grain size which attempts to account for additional controls on sediment movement such as  
 157 waves and storm events. Here, I use this proxy across the whole NW continental shelf to derive  
 158 grain size estimates from tidal bed shear stress. The modelling results (Fig. 4) show the North  
 159 Sea grain size as generally coarse sand, fining to very fine sand or less towards Norway. The  
 160 Celtic Sea is dominated by medium to coarse sand grains, with a ribbon of very coarse sand  
 161 running south from Scotland, through the Isle of Mann towards the Irish coast, before turning  
 162 more easterly towards Wales. Similarly, the Severn Estuary is also coarse sand. The English  
 163 channel is also dominated by coarse sands with some Gravel patches on the French coast. The  
 164 coarse sediment is discontinuous in the easterly direction with patches of medium sand. The  
 165 results in the Celtic Sea are entirely consistent with [Ward et al. \(2015\)](#) as well as observations by  
 166 [Bockelmann et al. \(2018\)](#).

## 167 PALAEOOTIDAL CHANGES

168 The M<sub>2</sub> tidal component is the dominant component over most of the of NW European continental  
 169 shelf. At 10 ka, an amphidromic point is situated near the palaeo-coastline in the North Sea  
 170 (Fig. 5). There is a further point further north near Norway. At this time there is a significant  
 171 reduction in M<sub>2</sub> amplitude across the whole seaway. When the land bridge between the UK and  
 172 mainland Europe forms around 9 ka, these points become separated by the land bridge with  
 173 a single amphidromic point in the English channel and two to the north and south of Dogger  
 174 Bank respectively. The shallowing of the Dogger Bank area in the southern North Sea creates  
 175 additional amphidromic points in the area which then precipitates a reduction in M<sub>2</sub> amplitude  
 176 in the English Channel. By the time Dogger Bank becomes emergent at around 8 ka, there are  
 177 complex tidal dynamics in the southern area of the North Sea, with four amphidromic points  
 178 occurring in the area. At 7 ka the amphidromic points shift towards the modern configuration,  
 179 with an additional point off the palaeo-coast of Denmark. Between 6 and 0 ka there is no major  
 180 shift in the amphidromic points and moderate changes in M<sub>2</sub> tidal amplitude. There is, however,  
 181 a minor shift at 4ka. The amphidromic point shifts towards the UK coast from the east of the  
 182 North Sea at this time. This then reduces the M<sub>2</sub> amplitude slightly on the eastern coast of  
 183 the UK. The driver for this appears to be sea-level change on the north coast of Europe. In  
 184 the modern, the Severn Estuary and Brittany coast experience high tidal ranges due to the M<sub>2</sub>  
 185 component. The modern North Sea shows amphidromic points (points where phase contours  
 186 converge) near the Danish coast and in the northern part of the English Channel.

187 Comparing to previous studies ([Neill et al., 2010](#)) and ([Ward et al., 2016](#)), the estimates  
 188 presented here show very similar spatial features as well as absolute values of M<sub>2</sub> tidal amplitude  
 189 and phase. There are minor variations in the location of amphidromic points. The models results  
 190 here show an additional amphidromal points off the coast of Norway at 10 ka compared to the  
 191 results of [Neill et al. \(2010\)](#) and ([Ward et al., 2016](#)). There is very little difference in the M<sub>2</sub>

192 amplitudes, however. At 8 ka all models show a complex set of amphidromic points in the  
193 southern North Sea, with similar patterns of  $M_2$  amplitude.

194 These changes in the  $M_2$  tide causes shifts in tidal range over the time period studies (Fig.  
195 6). The tidal range at 10 ka is much lower than modern day due to the much lower sea level.  
196 At 9 ka there is also an increase in tidal range in the Celtic Sea and the Severn Estuary closer  
197 to modern values. When the English Channel opens at 8 ka the tidal range is consistent with  
198 modern day. The tidal range stays generally consistent to the modern day ranges, apart from  
199 a minor change around 4 ka due to the changes in  $M_2$  described above. These results mirror  
200 those of Neill et al. (2010), which show a rapid reduction of tidal range between 0 and 10 ka  
201 with most of that change taking place at some point between 6 ka and 10 ka. However, the tidal  
202 range estimates presented here at 10 ka are slightly lower than that of Neill et al. (2010).

### 203 Tidal mixing

204 Tidal mixing occurs when the tidal currents are strong enough to induce turbulence via shear on  
205 the sea bed. There is therefore a relationship between water depth, tidal velocity and mixing in  
206 the water column which can be described using the Hunter-Simpson parameter,  $H_s$ ,

$$H_s = \log_{10} \frac{h}{u^3} \quad (5)$$

207 where  $h$  is the water depth (m) and  $u$  is the mean of tidal velocity magnitude (m/s) (Simpson and  
208 Hunter, 1974). Where tidal mixing occurs, it can flux nutrients from depth into the photic zone,  
209 thereby increasing primary productivity. This mixing occurs in the summer months when the  
210 solar radiation is sufficiently strong to induce stratification. Simpson and Hunter (1974) cite a  
211 value of between 1.5 and 2.0 for eq. 5 for where the transition between mixed and stratified water  
212 occurs; the tidal front, which has been confirmed with observations in the Celtic Sea (Simpson,  
213 1976). Fig. 7 shows the shift in the tidal fronts through time. For the period 10 ka to 7 ka  
214 there are widespread mixed areas in the English Channel and Southern North Sea. As sea level  
215 rises and becomes similar to modern day these fronts become very similar to those found today  
216 (Pingree and Griffiths, 1978), apart from those in the Celtic and Irish Seas. Those fronts develop  
217 around 6ka, but are absent at 4 - 1 ka.

### 218 Sediment grain size changes

219 Changes in sediment grain size largely follow the changes in tidal range (Fig. 8). Generally  
220 there is a increase in grain size deposited with time, with fine grains dominating 10 ka and areas  
221 becoming dramatically coarser by around 7 ka and then stabilising. The largest changes occur  
222 between 10 ka and 7 ka in the English channel. In the modern there are two main areas of very  
223 coarse sand deposition in the English channel - on in the narrow seaway between England and  
224 France and a large area between the south cost of England and Brittany. These a re largely  
225 stable until around 7 ka when the northern patch shrinks whilst the southern area grows. As the  
226 English Channel shrinks this southern patch of coarse sediment shifts southwards and eventually  
227 decreases in area by 10 ka. These results are similar to the tidal bed shear stress calculated by  
228 Neill et al. (2010) and Ward et al. (2016), though as with the tidal characteristics there are minor  
229 differences in places.

## 230 DISCUSSION

231 In order to calculate sea level since the Last Glacial Maximum we must first find data that  
232 indicate past sea level. These data points are located within a tidal range, however; so in order  
233 to place past mean sea level an estimate of past tidal range is required (Shennan, 2015). It is

234 important to understand past sea level changes as they relate directly to our estimates of the  
235 amount of water sequester by ice sheets during the Last Glacial maximum [Clark and Tarasov](#)  
236 [\(2014\)](#) and what drives local, regional and global sea level change through time ([Shennan et al.,](#)  
237 [2018](#)). Here, I present calculations of past tides of the NW European continental shelf using a  
238 finite element model on a multi-scale unstructured mesh. The output of these model simulations  
239 are available for other researchers to use.

240 The tidal characteristics of the European continental shelf show major changes over the past  
241 10,000 years. Most of those changes are associated with the flooding in the southern North Sea  
242 from 10 ka to 7 ka. From 7 ka to the present day most tidal properties show little variation. The  
243 exception to this is at 4 ka. At this time the amphidromic point for the  $M_2$  tide shifts westwards  
244 in the southern North Sea moving the corresponding  $M_2$  low amplitude with it. This in turn  
245 alters tidal range and bed shear stresses in the region. By 3 ka the amphidromic point shifts  
246 eastward again, closer to the modern day location.

247 The shifts in tidal characteristic also have implications in the primary productivity potential  
248 of the European shelf. From 10 ka to 7 ka there was a much larger mixed region in the English  
249 Channel with associated tidal fronts. These are associated with both shallower water and higher  
250 tidal velocities. These fronts would have increased the primary productivity in the region as tidal  
251 fronts are a significant percentage of primary productivity in the modern North Sea ([Heath and](#)  
252 [Beare, 2008](#)). This in turn has implications for changes in the biogeochemistry of the North  
253 Sea since the Last Glacial Maximum. The present day North Sea is thought to store around 250  
254 MT of Particulate Organic Matter (POC) in the top 10 cm of sediment ([Diesing et al., 2017](#)).  
255 Given that the North Atlantic biological pump increased the draw down of carbon during the  
256 Last Glacial Maximum ([Yu et al., 2019](#)), the increased number of tidal fronts may have had an  
257 impact on the POC stored in North Sea sediments.

258 The model results presented here have a number of limitations. Firstly, the boundary  
259 forcing along the continental shelf are derived from modern data with no corrections for global  
260 palaeobathymetric changes. This is in contrast to both [Neill et al. \(2010\)](#) and [Ward et al. \(2016\)](#).  
261 As the ice sheets in the northern hemisphere grew, they caused changes in the global tidal  
262 dynamics. However, the tidal forcing was still strong in this region and broadly comparable to  
263 modern tides at least until 10 ka, based on previous modelling of global tides ([Uehara et al.,](#)  
264 [2006](#)). Future work will use global tidal models to estimate the tidal boundary forcing on  
265 global palaeobathymetries to enable simulations to be carried out for reconstructions older than  
266 10 ka. Second, the model also lacks inundation of low-lying land due to tidal movement with  
267 bathymetry 'dredged' to a minimum of 6 m water depth. This is a particular problem in estuaries  
268 and where most SLIP data are collected. This is similar to both [Neill et al. \(2010\)](#) and [Ward et al.](#)  
269 [\(2016\)](#) as neither used any wetting and drying algorithms. Whilst the modelled tidal range is not  
270 significantly affected the tidal range must instead be taken from a nearby point rather than the  
271 precise location of the SLIP. Future work will correct this by adding inundation and increase the  
272 spatial resolution around the coast.

273 The results presented here form only part of the solution for correcting SLIPs for palaeo-tidal  
274 range. Once a SLIP is corrected for temporal variations in tidal range, the GIA models then  
275 need correcting as they use SLIPs as a constraint, which in turn alters the palaeobathymetry on  
276 which the tidal model is based. This presents something of a circular problem. [Neill et al. \(2010\)](#)  
277 proposed a methodology whereby some SLIPs are held back from a GIA model to provide a  
278 validation-calibration test. However, here, I have used a different palaeobathymetry to [Neill et al.](#)  
279 [\(2010\)](#) and modern forcing as opposed to palaeotidal estimates. Similarly, [Ward et al. \(2016\)](#)  
280 used updated GIA models (same as this work) and a higher model resolution than [Neill et al.](#)  
281 [\(2010\)](#). Despite these minor differences in boundary forcing, palaeobathymetric reconstructions,  
282 and numerical implementations, our estimates of tidal range changes are very similar. This is

283 encouraging as it means that tidal range estimates are not overly sensitive to minor variations in  
284 tidal forcing or palaeobathymetric estimates. It should therefore be possible to correct SLIPs  
285 for tidal range, alter the palaeobathymetry and proceed in an iterative fashion until there are no  
286 changes to the tidal estimates – in essence convergence onto our best estimate. Making use of  
287 modern numerical techniques such as adjoint solvers would aid in estimating the sensitivity of the  
288 tidal model to errors in palaeobathymetry. In turn the sensitivity and error across multiple models  
289 and bathymetric estimates could be used in a Bayesian framework similar to that proposed by  
290 (Cahill et al., 2016). It would then be possible to account for uncertainty and sensitivity in the  
291 SLIP height (including tidal range corrections and the uncertainties within those) and the dating  
292 method when deriving sea level estimates.

## 293 CONCLUSIONS

294 The results published here form a palaeotidal database made freely available for future researchers.  
295 The outputs of the model shows significant changes to tidal range, tidal sediment distribution  
296 and the tidal components on the NW European shelf area. These data are the first derived on an  
297 unstructured mesh model where the mesh resolution of the model can vary spatially, allowing  
298 focusing of results in areas of interest (here the coastline) whilst minimising computations time.  
299 Unstructured meshes also reproduce bathymetry and coastlines without staircase effects. This is  
300 an advance over previous modelling studies that used relatively coarse rectilinear grids.

## 301 DATA AVAILABILITY

302 Each time slice is available as a NetCDF file which contains tidal amplitudes and phases for  
303 each tidal component, maximum and mean bed shear stress and velocity vectors, along with  
304 a simple R script to extract nearest data from a list of points. These are available via: DOI:  
305 [10.6084/m9.figshare.6993956](https://doi.org/10.6084/m9.figshare.6993956).

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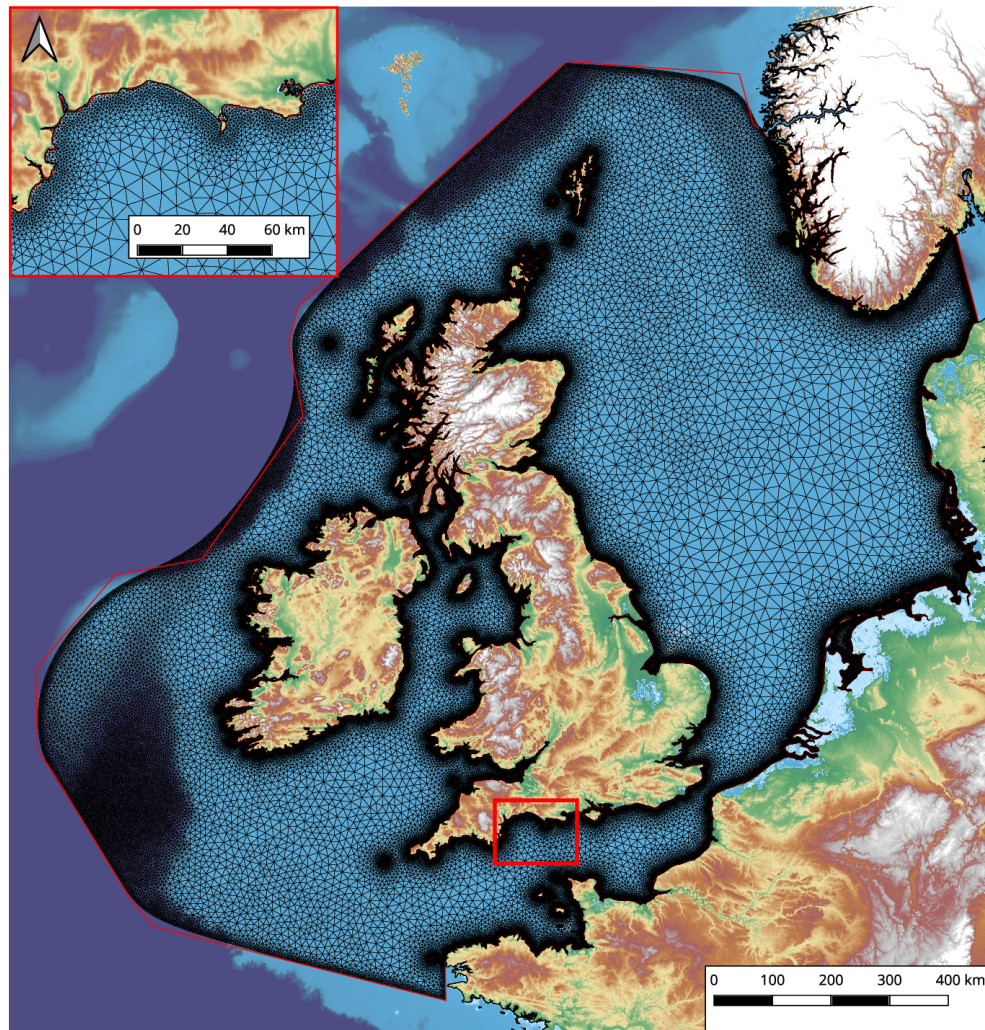
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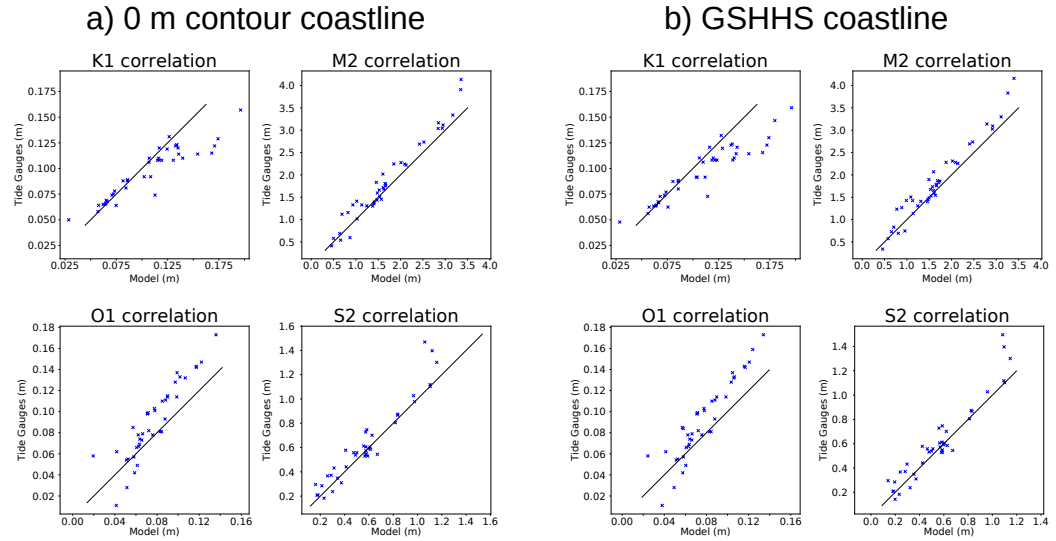


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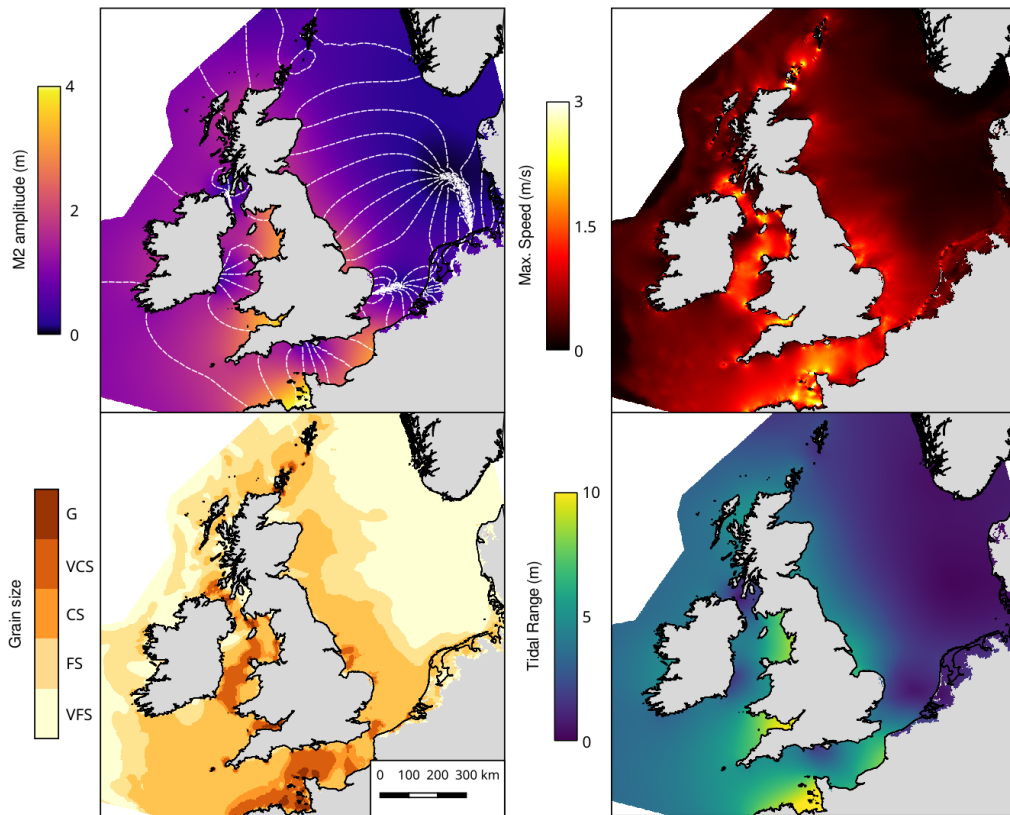
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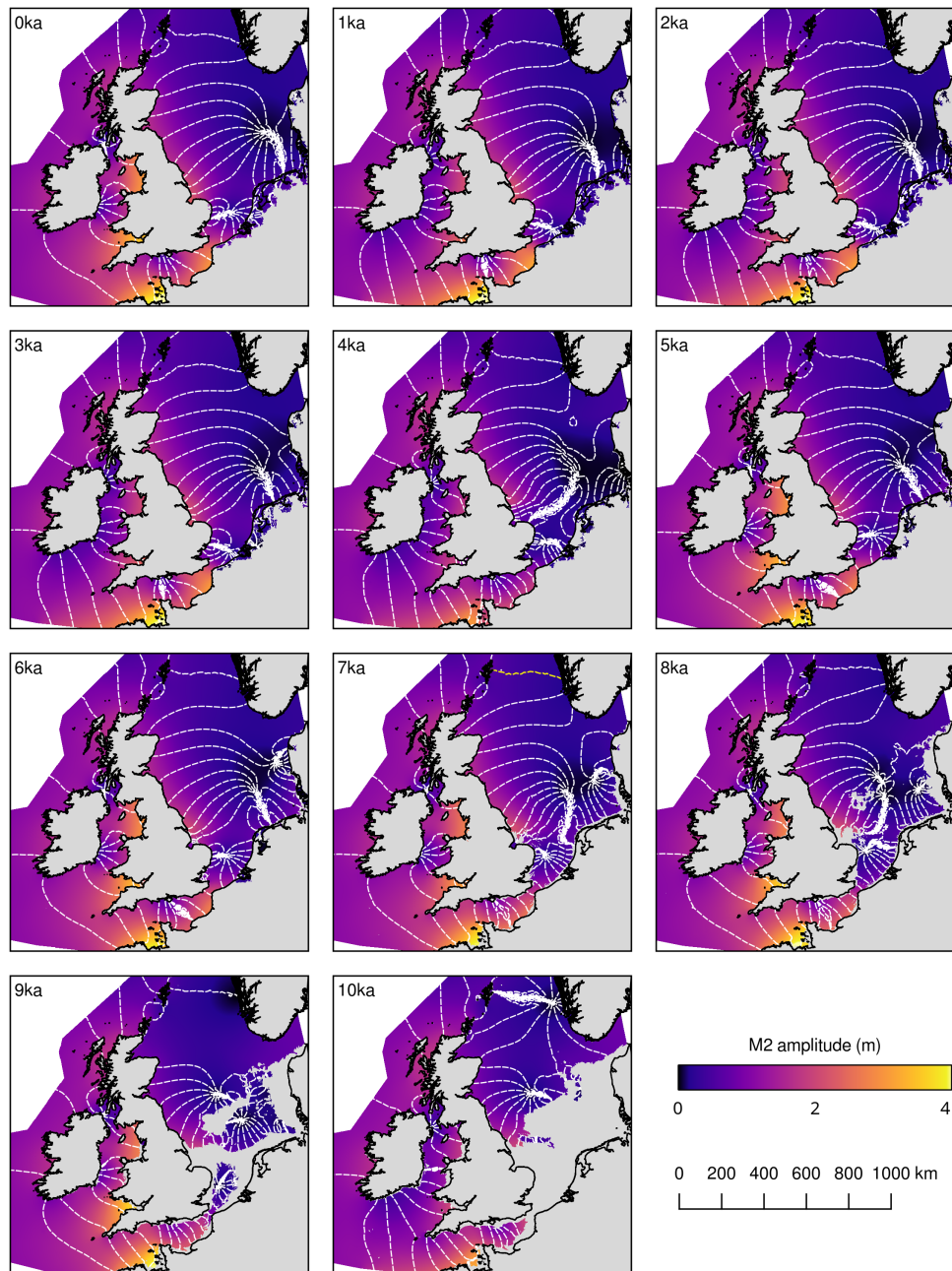
**Figure 2.** Modern multiscale mesh using GSHHS coastlines (high resolution). Mesh resolution is smallest around coastlines and deeper water. Red line shows the coastline from GSHHS, black is the mesh, and colours show height from the GEBCO bathymetry/topography. A close-up of the south coast of England is shown to highlight the mesh resolution change with respect to the coastline.



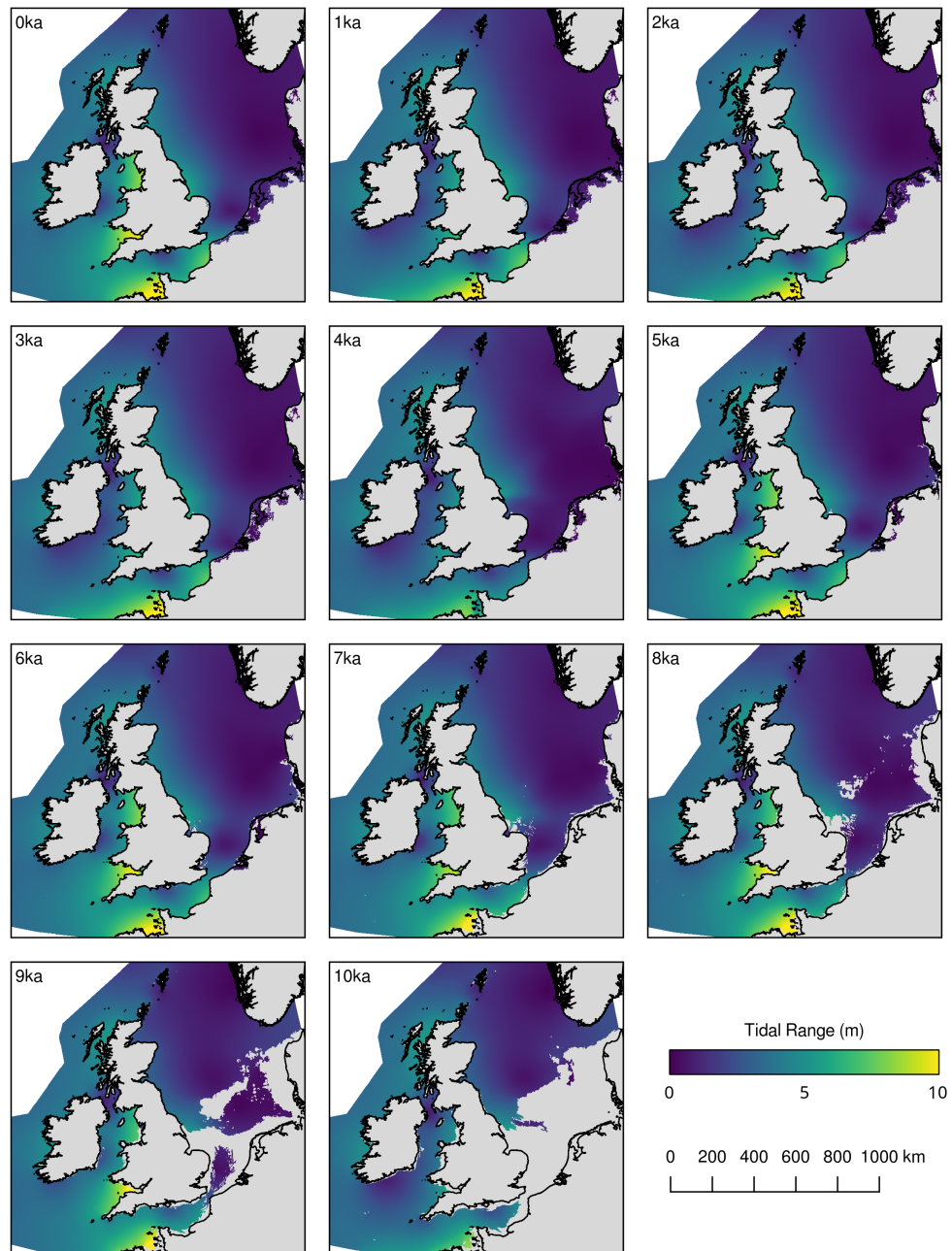
**Figure 3.** Cross plot of amplitudes generated from Fluidity against tide gauges for four main tidal components using either the 0 m contour (a) or high resolution GSHHS data (b) as the coastline.



**Figure 4.** Tidal properties of the present day. Top left: M<sub>2</sub> amplitude and phase. Top right: maximum speed over the 30 day simulation. Bottom left: grain size derived from maximum bed shear stress. Bottom right: tidal range.



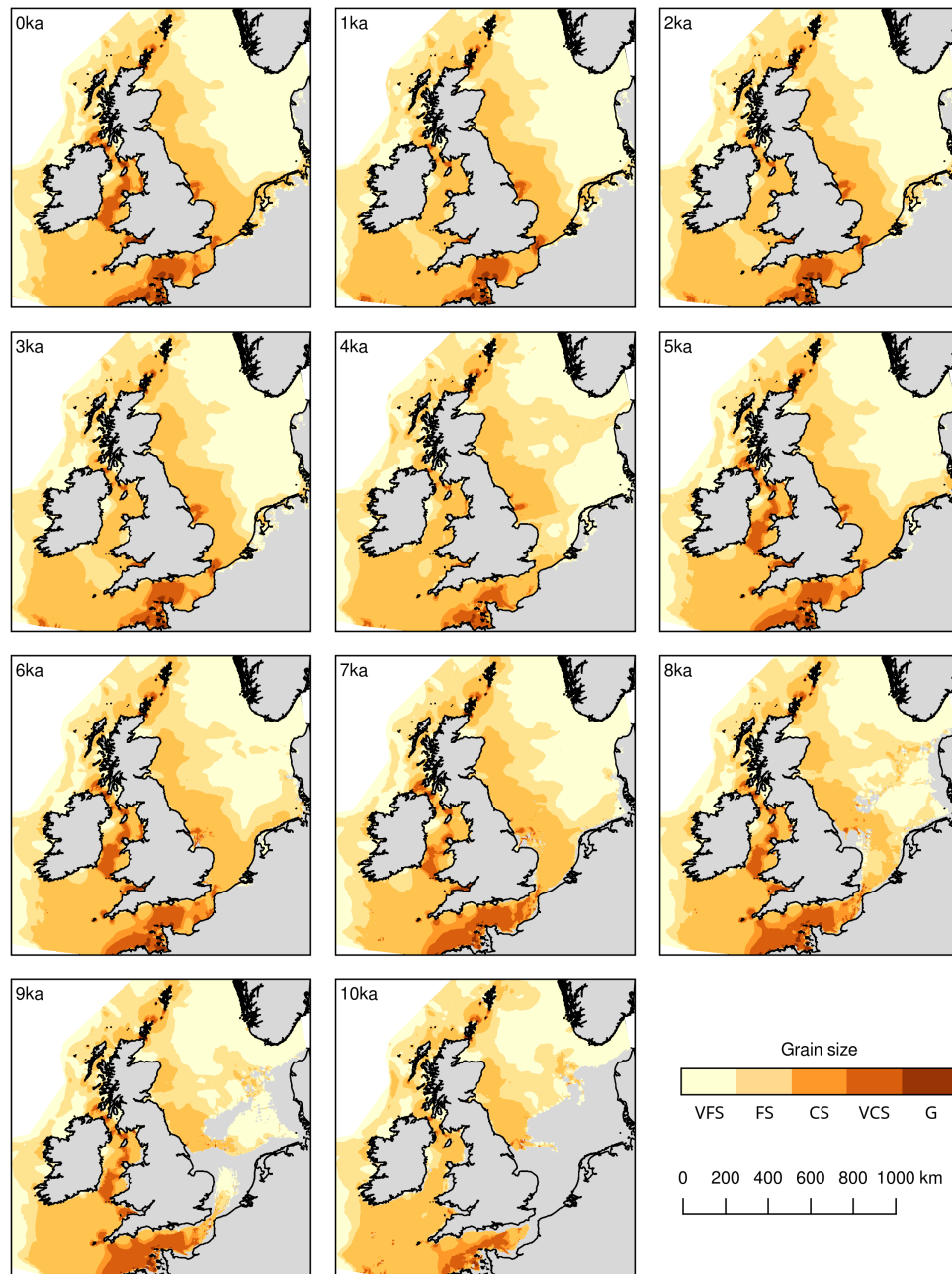
**Figure 5.** M<sub>2</sub> amplitude (colour bar) and phase (contour lines) for each of the time slices from present day to 10 ka. Grey shading indicates land and the modern coastline is shown in a thick black line.



**Figure 6.** Tidal range in the NW European shelf for each timeslice from present day to 10 ka. Add palaeo shorelines. Grey shading indicates land and the modern coastline is shown in a thick black line.



**Figure 7.** Estimates of the Hunter-Simpson parameter over the last 10,000 years. Blue colours show summer stratification and red show mixed regions. The transition through white colours shows the location of tidal mixing fronts. Grey shading indicates land and the modern coastline is shown in a thick black line.



**Figure 8.** Sediment grain size derived from maximum bed shear stress predicted from the tidal model corrected using the method detailed in [Ward et al. \(2015\)](#). Grey shading indicates land and the modern coastline is shown in a thick black line.