

## Cover Sheet

Title: Self-replicating subduction zone initiation by polarity reversal

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# 1 Self-replicating subduction zone initiation by polarity reversal

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## 10 11 **Abstract:**

12 Subduction zones have recurrently formed on Earth. Previous studies have, however,  
13 suggested that they are unlikely to start in the interior of a pristine ocean. Instead, they  
14 seem to be more likely to form from another pre-existing subduction zone. One widely  
15 cited conceptual model to start new subduction zones is polarity reversal, resulting from  
16 the shutdown of a pre-existent subduction zone due to the arrival of a buoyant block at  
17 the trench. However, the dynamic conditions by which this process occurs remain elusive.  
18 Here, we present 3D numerical models of subduction zone initiation by polarity reversal  
19 resulting from the arrival of an oceanic plateau at the trench. Our results show that this  
20 process is more likely to occur for old subducting plates and narrow plateaus, and that  
21 new subduction zones can form from previous ones in a self-replicating manner, without  
22 requiring any other external tectonic forcing.

## 23 24 **Introduction**

25 Subduction zone initiation (SZI) constitutes one of the main unsolved problems in  
26 geodynamics. Multiple mechanisms have been previously proposed to explain SZI,  
27 differing on their assumed geometries, kinematics and driving forces (Stern, 2004; Stern

28 and Gerya, 2018; Cramer *et al.*, 2020; Lallemand and Arcay, 2021). These include the  
29 formation of subduction zones by mantle plumes(Gerya *et al.*, 2015; Whattam and Stern,  
30 2015), or by the reactivation of lithospheric scale weaknesses, such as transform  
31 faults(Zhou *et al.*, 2018; Arcay *et al.*, 2019), old subduction zone interfaces(Faccenna *et*  
32 *al.*, 2018) and passive margins(Cloetingh, Wortel and Vlaar, 1989; Marques *et al.*, 2013).  
33 One commonly proposed mechanism for subduction zone initiation is subduction polarity  
34 reversal(Stern, 2004; Stern and Gerya, 2018; Cramer *et al.*, 2020). This assumes that  
35 the arrival of a buoyant terrane(Harris *et al.*, 2014; Tetreault and Buiter, 2014; Mortimer  
36 *et al.*, 2017) at the trench of an active intraoceanic subduction zone is capable of causing  
37 the local termination of the subduction system, and to force the overriding plate to subduct  
38 in the opposite direction. This type of SZI has been proposed to have occurred in several  
39 different natural instances(Cooper and Taylor, 1985; Mann and Taira, 2004; Miura *et al.*,  
40 2004; Konstantinovskaya, 2011). For example, it has been suggested(Mueller and  
41 Phillips, 1991) that polarity reversal SZI represents one of the modes by which subduction  
42 zones can be transferred from Pacific-type into Atlantic-type oceanic basins (a process  
43 generally referred to as subduction infection<sup>17</sup> or invasion<sup>18</sup>). However, the dynamic  
44 factors that govern the switch in the subduction polarity are still poorly understood. A  
45 reversal of subduction polarity must arise from the balance between driving forces(Gurnis,  
46 Hall and Lavier, 2004) (e.g., slab pull force), resisting forces(Gurnis, Hall and Lavier,  
47 2004) (e.g., positive buoyancy of plate segments, and viscous resistance of plates and  
48 mantle), and facilitating/weakening mechanisms(Korenaga, 2007; Thielmann and Kaus,  
49 2012; Dymkova and Gerya, 2013; Gerya *et al.*, 2015) (e.g., grain size reduction, presence  
50 of fluids or shear heating).

51 Here, we investigate the dynamics of subduction initiation by polarity reversal using 3D  
52 self-consistent visco-elasto-plastic geodynamic models that include a free surface (see  
53 Methods). In these models, an oceanic plateau is incorporated into the subducting plate  
54 (Supplementary Figure 1), eventually colliding with an oceanic overriding plate. Model  
55 plate velocities are never externally imposed in any of the experiments, arising instead  
56 from the evolving dynamic balance between internal driving and resisting forces. The only  
57 relevant driving force in our system is the slab pull ( $F_{SP}$ ), which results from the negative  
58 buoyancy of the subducting plates. This driving force is opposed by the viscous resistance

59 forces of the plates/mantle and the by the deformation of the overriding plate during  
60 plateau collision.

61 We show that polarity reversal subduction initiation by plateau collision is geodynamically  
62 viable in the absence of external driving forces, but that it is limited by the along-trench  
63 width of the oceanic plateau. Also, the duration of the polarity reversal event is strongly  
64 controlled by the along-trench plateau width and by the age of the subducting plate.

65

## 66 **Modelling rationale**

67 The objective of this work is to understand the dynamics of the processes governing  
68 subduction initiation by polarity reversal. Specifically, we aim to understand the time-  
69 evolving force balance between the slab pull and the resisting forces that are implied in  
70 the deformation of the overriding plate during the collision with an oceanic plateau. Hence,  
71 we varied the following parameters/conditions to better understand how these influence  
72 the force balance as to trigger polarity reversal SZI:

- 73 1. Along-trench width of the oceanic plateau ( $W_{SP}$ ). Wider plateaus imply not only a  
74 higher volume of material that resists subduction when arriving at the trench, but  
75 also a smaller active subducting trench after collision (increasing effective slab-pull  
76  $F_{SP}/W_{SP}$ ). Consequently, varying the width of the plateau along the subduction  
77 trench allows us to simultaneously assess the impact of a narrower active  
78 subduction zone on the triggering of a new one by polarity reversal.
- 79 2. Age of the overriding and subducting plates. While  $F_{SP}$  is the main driving force of  
80 a subduction zone, its effects are balanced by the relative strength of the  
81 intervening plates, which is directly correlated to the plate's thermal age. Thus, to  
82 understand how the relative plate strength influences the evolution of the  
83 subduction system, we used different combinations of initial overriding and  
84 subducting plate ages. In our simulations, the oceanic plateau has the same age  
85 as the subducting plate, which means that a change in plate age directly (and  
86 proportionally) affects the implied  $F_{SP}$ .

87 3. Presence or absence of a positively buoyant magmatic arc along the tip of the  
88 overriding plate. These alternative conditions were considered to assess the  
89 potential role of the volcanic arc in the development of a new subduction zone by  
90 polarity reversal.

91 A total of eleven model runs were conducted (see Supplementary Table 1). All models  
92 were run considering half of a symmetrical domain (see detailed explanation in Methods).  
93 In all but one model, a new subduction zone is initiated on the overriding plate by polarity  
94 reversal, after the arrival of an oceanic plateau at the trench (plateau collision).

95 We monitored several parameters in each of the different models: the evolution of the  
96 emerging trench-normal subducting plate velocity ( $V_{SP}$ ), as a proxy for the subduction  
97 dynamics; the migration of the original and the newly formed subduction zones, to track  
98 the plate organization of the model; and the ratio ( $W_R$ ) between the length of the newly  
99 formed subduction zone ( $L_{NSZ}$ ) and the width of the oceanic plateau ( $W_P$ ; Supplementary  
100 Figure 1B), to measure the efficiency of the plateau in triggering a new subduction zone.

## 101 **Results and Discussion**

### 102 ***Geodynamics of subduction polarity reversal***

103 The evolution of the reference model, comprising 70 Myr old overriding and subducting  
104 plates, a 600 km wide plateau ( $W_P = 600$  km) and a buoyant magmatic arc, is shown in  
105 figure 1 (and Supplementary Movie 1). In this model, we distinguish four different phases  
106 recognized in most numerical simulations: I) evolution of the original subduction zone  
107 (Fig. 1a); II) arrival of the plateau at the trench (i.e., plateau collision - Fig. 1b); III) polarity  
108 reversal and subduction initiation of the former overriding plate (Fig. 1c); IV) development  
109 of an opposite verging subduction system (Fig. 1d and Fig. 2).

110 During Phase I, the initial subduction zone develops as the original slab progressively  
111 sinks into the upper mantle resulting in an increase of the subduction velocity (see Figs.  
112 1a and 3a). At around 4.7 Myr, the slab reaches the upper-lower mantle discontinuity, at  
113 660 km depth (Figs. 1a-b). This causes a deceleration in the subducting plate velocity  
114 ( $V_{SP}$ , Fig. 3a), which is followed by a new period of slight acceleration as consequence of  
115 slab draping (backwards bending and accumulation along the upper-lower mantle

116 transition(Schellart *et al.*, 2007)). Shortly after, at around 6 Myr, the plateau arrives at the  
117 trench and resists subduction (Phase II in Fig. 1; diamonds in Fig. 3a-b). This happens  
118 not only because of the plateau's positive buoyancy, but also because of its relatively  
119 higher viscosity which makes it harder to bend (see Supplementary Figure 2). This  
120 obstruction eventually leads to the termination of the original subduction zone in this  
121 domain (Fig. 1b-c) and to the tearing of the initial slab beneath the oceanic plateau (Fig.  
122 1c-d). Driven by the slab pull implied by the ongoing initial subduction, the oceanic plateau  
123 and buoyant arc are pushed against and above the overriding plate forcing it to bend  
124 downwards and to start subducting in the opposite direction (Phase III in Fig. 1; triangles  
125 in Fig. 3 and Supplementary Figure 3). Plateau collision causes a shift in trench migration  
126 from pre-collision rollback to post-collision motion towards the overriding plate (Fig. 3b).  
127 From ca. 8.8 Myr onwards, there are two fully developed opposite verging subduction  
128 zones (Phase IV; Fig. 1d and Fig. 2). The newly formed opposite dipping slab initially  
129 accelerates quickly into the upper mantle (Fig. 3a) before entering a steady roll-back  
130 stage (Fig. 3b).

131 As the (initial) overriding plate sinks into the mantle, it is deformed and bent around the  
132 oceanic plateau (Fig 1d and 2a-b). This causes the mantle flow to be laterally funnelled  
133 beneath the curved (and necked) magmatic arc (Fig. 2b-d), assisting the trench retreat  
134 lateral propagation of the newly formed subduction zone (Fig. 2b). Such a propagation  
135 occurs simultaneously with local mantle upwelling, which in nature could correspond to  
136 the formation of an oceanic basin (see example discussed below). The implied trench  
137 retreat and slab rollback (compare Fig. 2b-d), further enhances the flow of mantle material  
138 in a positive feedback loop. Bifurcation of the laterally funnelled mantle flow also drives  
139 incipient propagation of the original subduction zone to the back of the oceanic plateau  
140 (Fig. 2d). Given sufficient time, it is likely that this would aid to fully propagate the original  
141 subduction zone behind the plateau, leading to the development of two bordering side by  
142 side, opposite verging subduction zones.

143 This general model evolution shows that upon arrival of the plateau at the trench its  
144 viscous resistance to bending, and its positive buoyancy eventually determine the local  
145 shutdown of the original subduction zone. The initial main subduction zone, however,

146 remains active laterally away from the collision zone, and its implied slab pull is enough  
147 to initiate thrusting of the plateau above the overriding plate, eventually causing this plate  
148 to subduct into the mantle. This is enabled by an initially strong dynamic coupling between  
149 the pre-existent and the emerging subduction systems, which allows the first to work as  
150 the source of the stress that drives the initial underthrusting and sinking of the overriding  
151 plate. However, such a dynamic coupling wanes as the original overriding plate  
152 progressively sinks into the mantle, and a new dynamically self-sustained subduction  
153 system is formed, driven by the slab pull force of the new subducting slab.

154 A similar evolution has previously been described in the context of a plateau-continent  
155 collision setting (Moresi *et al.*, 2014; Betts *et al.*, 2015). In these cases, the continental  
156 nature of the overriding plate prevents it from subducting. However, under the modelling  
157 conditions addressed by Moresi<sup>21</sup>, plateau-continent collision can trigger the lateral  
158 formation of an extensional basin on the continental overriding plate, by favouring trench-  
159 rollback to the side of the collisional domain, in the lateral active segment of the  
160 subduction zone. Continued convergence subsequently forces the subduction zone to  
161 migrate to the back of the plateau, accreting it to the overriding continental plate. While  
162 our results show comparable lateral extensional basin formation, we infer that the new  
163 opposite dipping subduction zone dissipates part of the energy that would otherwise  
164 assist a consistent rollback of the original subduction zone.

165

### 166 ***The role of the plateau's along-trench width***

167 To understand the influence of the effective slab pull force of the original subduction zone  
168 ( $F_{SP}/W_{SP}$ ) in the formation of a new opposite dipping one, four different initial along-trench  
169 widths of the plateau were tested (between 300 and 2400 km, see Supplementary Table  
170 1 and Supplementary Figure 1). Note that a wider plateau implies a narrower active lateral  
171 subduction zone after plateau collision, which in turn leads to a stronger slab pull (higher  
172 effective slab pull  $F_{SP}/W_{SP}$ , see Supplementary Table 2). The evolution of these models  
173 can be seen in Supplementary Movies 1-4.

174 The evolution of the initial subduction zone is identical for all models until the arrival of  
175 the plateau at the trench (Fig. 3a). However, from the plateau collision onwards, the  
176 subducting plate velocity ( $V_{SP}$ ), and its variation along time, is consistently higher/steeper  
177 in models with narrower plateaus (i.e., with lower  $W_P$  widths and correspondingly higher,  
178 trench parallel, subduction zone lengths - Fig. 3a). It has been previously shown (Schellart  
179 *et al.*, 2007; Guillaume *et al.*, 2010) that for the same volume of subducted slab, a  
180 narrowing of the subduction zone (i.e., the decrease of its trench-parallel length -  $W_{SP}$ )  
181 causes an increase in both  $V_{SP}$  and trench migration velocity, due to a resulting higher  
182 effective slab pull force at the surface. However, this is strikingly contrary to what we  
183 observe in Fig. 3a. In the present case, the decrease of the subduction trench length in  
184 the models comprising wider plateaus is proportionally compensated by an increase in  
185 the width of the collision zone. This yields higher levels of horizontal resisting  
186 forces/stresses at the front of the plateau (see Supplementary Figure 4), which are  
187 capable of blocking the system, resulting in lower values of  $V_{SP}$  and trench velocity in  
188 these cases. In Supplementary Table 2 we list the buoyancy force and the effective slab  
189 pull force available to drive the polarity reversal. These show that higher effective slab  
190 pull forces are implied by wider plateaus as expected. However, the new subduction zone  
191 to be initiated is also much longer in these cases, since it will extend along the wider  
192 collisional front of the plateau, thus requiring even higher forces to nucleate along the  
193 whole of its width ( $W_P$ ). This is readily illustrated when considering the available buoyancy  
194 force divided by the length of the new subduction zone (Supplementary Table 2), which  
195 unambiguously shows that the resulting driving force available to initiate the new  
196 subduction zone is lower for cases comprising wider plateaus. For plateaus with the  
197 highest considered width ( $W_P = 2400$  km) the collision area corresponds to ca. 80% of  
198 the whole model width, which renders only 25% of the slab pull force (per collision zone  
199 length) available to initiate the new subduction system. As a result, no new subduction  
200 zones are formed in this case, and instead, a complete termination of the whole  
201 subduction system occurs (as shown in Supplementary Movie 4).

202 Furthermore, the duration of the polarity reversal event – i.e., the time interval between  
203 the initial stages of collision (diamonds in Fig. 3) and the full achievement of polarity  
204 reversal (triangles) – is consistently longer for wider plateaus. Slower trench migrations



205 (Fig. 3b) and lower indentation ratios (expressed by the time variation of  $W_R$  in Fig. 3c)  
206 are also observed for collisions with wider plateaus, in compliance with a more efficient  
207 dissipation of  $F_{SP}$  in these cases.

### 208 ***The role of plate age contrast***

209 We have also investigated the effect of changing the age contrast between the overriding  
210 and subducting plates, by testing different initial age combinations for the same plateau  
211 width ( $W_P = 600$  km, see Supplementary Table 1, and Supplementary Movies 1 and 9 to  
212 11). Changing the thermal age of the subducting plate directly affects the negative  
213 buoyancy of the slab, thus allowing to modify  $F_{SP}$  without changing the width of the  
214 plateau or the implied indentation area.

215 Similar to the reference model, triggering a polarity reversal event requires the  
216 contribution of the driving slab pull force of a pre-existing subduction zone to bend the  
217 overriding plate. Therefore, a weaker and thinner overriding plate would, in principle, be  
218 easier to subduct (Kemp and Stevenson, 1996; Gurnis, Hall and Lavier, 2004; Irvine and  
219 Schellart, 2012; Ulvrova *et al.*, 2019) and hence favour polarity reversal subduction  
220 initiation. Our results confirm this assumption by showing that in models with relatively  
221 weaker/thinner overriding plates, but identical subducting plate ages, polarity reversal  
222 occurs earlier (see Fig. 4).

223 For the same considered width of the plateau ( $W_P = 600$  km) and for equal initial ages of  
224 the subducting plate, the resulting driving forces should also be similar. However, in  
225 models with younger overriding plate thermal ages their corresponding lower strength and  
226 lower thickness facilitate, not only a more efficient indentation by the plateau, but also an  
227 earlier development of polarity reversal SZI (see Fig. 4). In accordance, the models with  
228 younger overriding plates also show an overall higher  $V_{SP}$  (see Fig. 4a). This higher  
229 velocity of the subduction plate cannot be ascribed to an increase in the available driving  
230 forces, but can instead be easily explained by a relatively weaker and thinner overriding  
231 plate, and therefore an implied lower dissipation of  $F_{SP}$  during and after the collision.

232 By contrast, models with younger, and therefore weaker, less negatively buoyant  
233 subducting plates, but identical overriding plate ages, show an overall slower evolution

234 (see Fig. 4). At the start of the model, the younger subducting plates have a lower density  
235 contrast with the underlying mantle and, consequently, a lower  $F_{SP}$  (ca. 17% lower, see  
236 Supplementary Table 4). Therefore, there is a delay in the initial sinking phases of the  
237 original subduction (see Fig. 4b, and Supplementary Movie 11), resulting in an overall  
238 slower evolution of the system.

239

240

### 241 ***The role of a mature volcanic arc***

242 Lastly, we ran a set of models with the same variation of plateau widths ( $W_P$ ), but without  
243 the buoyant magmatic arc on the overriding plate. This allowed for a straightforward  
244 comparison between the two sets of experiments (with and without arc), in which any  
245 observed difference must derive from the missing arc. Regardless of the considered ( $W_P$ )  
246 width of the plateau, models without an arc developed convergent double sided  
247 subduction systems, in which both the overriding and the subducting plates sink into the  
248 ambient mantle (see Supplementary Figure 5 and Supplementary Movies 5-8). Different  
249 nuances of this same conspicuous double-sided subduction mode have been previously  
250 reported in several other numerical studies, although this type of subduction was never  
251 recorded in the Earth's lithosphere (Gerya, Connolly and Yuen, 2008).

252 In the present models, during the formation of the original subduction zone, the  
253 lithospheric mantle at the tip of the overriding plate is dragged downwards by the slab,  
254 forming a slab-dominated asymmetric double-sided subduction (i.e., the direction of  
255 subduction is controlled by the slab, see Supplementary Movie 5-8). During collision, the  
256 original subduction zone is terminated in front of the oceanic plateau and, as in previous  
257 models, the overriding plate begins subducting. However, unlike in the previous models,  
258 no extensional basin is formed on the overriding plate in this case. Rather, the polarity  
259 reversal event is triggered along the entire width of the plate, resulting in a nearly model-  
260 wide symmetrical double-sided subduction zone (see Supplementary Figure 5 and  
261 Supplementary Movie 5-8). Thus, under the assumed model conditions, we argue that  
262 the buoyant magmatic arc on the tip of the overriding plate plays a fundamental role, not

263 only in stabilizing this plate by avoiding it being initially dragged into the mantle by the  
264 original subducting plate, but also in preventing the immediate plate-wide propagation of  
265 the newly formed subduction after the collision with the plateau, and the consequent  
266 formation of a double-sided subduction zone also at this later stage.

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268

269

### 270 ***Natural systems and tectonic implications***

271 The objective of the present generic numerical modelling study was not to explore the  
272 specific geodynamic constraints of a natural case, but rather to gain new insight on the  
273 main underlying dynamics governing the occurrence of polarity reversal SZI.  
274 Nevertheless, we consider our results to be comparable to one of the most well studied  
275 cases of subduction initiation by polarity reversal, the Vanuatu subduction zone in the  
276 southwest Pacific (Schellart, Lister and Jessell, 2002; Mann and Taira, 2004; Miura *et al.*,  
277 2004; Schellart, Lister and Toy, 2006) (Fig. 5).

278 Here, a new subduction system was initiated as a consequence of the Late Miocene  
279 arrival of the Ontong-Java plateau at the trench. This oceanic plateau, carried by the 150  
280 to 120 Myr old Pacific plate, was driven to collide with the 49 to 25 Myr old overriding  
281 Australian plate (Schellart, Lister and Jessell, 2002; Mann and Taira, 2004; Schellart,  
282 Lister and Toy, 2006). While these ages are not in accordance with the modelled  
283 conditions, the event sequence in our models generically agree with this natural example.  
284 The collision of the oceanic plateau triggered the initiation of the Vanuatu subduction zone  
285 with an opposite (northwards) polarity in front of the Ontong-Java plateau (Mann and Taira,  
286 2004; Schellart, Lister and Toy, 2006). As this system continues to propagate across the  
287 front of the plateau, we argue that the present-day Solomon arc setting (west side) is  
288 likely to closely mimic what was observed in the Late Miocene along the eastern side of  
289 the plateau. Under this assumption, during the collision, the Ontong-Java plateau would  
290 have been forced to overthrust the Australian plate. Consequently, this plate would have  
291 been wedged between the plateau and the Pacific plate (see cross-section in Fig. 5a).

292 This geometric configuration is coherently observed in equivalent frontal-plateau sections  
293 in our models (see model inset in Fig. 5a).

294 The collision of the Ontong-Java plateau with the ancient Solomon subduction zone, and  
295 consequent reversal of the subduction polarity, is a good example of the transmission of  
296 a subduction zone from one plate to another, in this case, from the Pacific plate to the  
297 Australian plate. Our modelling results support the geodynamic viability of such a  
298 transmission and show that this is possible to occur in the absence of any external forcing  
299 mechanism, just due to the interplay between the driving and resisting forces that govern  
300 a subduction system. This bears fundamental implications for the understanding of the  
301 elusive process of subduction initiation throughout the history of our planet. It has been  
302 shown that subduction zones require unrealistic forces to initiate along Atlantic-type or  
303 passive oceanic margins(Gurnis, Hall and Lavier, 2004), i.e. ocean-continent transitions  
304 without a subduction zone. Our work shows that once a subduction system has initiated,  
305 it has all the ingredients to dynamically self-replicate and to transfer subduction zones  
306 from one plate to another, and ultimately from ocean to ocean, without the need for  
307 external forces. Another example may be the Lesser Antilles in the Atlantic. Here, SZI by  
308 polarity reversal may have resulted from the collision of an oceanic plateau with the East  
309 Pacific subduction system, leading to the local shut down of the subduction zone and  
310 initiation of a new one in the Atlantic. This mechanism, by which a subduction zone is  
311 forced to start in a pristine ocean by the action of a nearby subduction zone, has been  
312 dubbed as subduction infection(Mueller and Phillips, 1991) or invasion(Duarte, Rosas,  
313 Terrinha, Schellart, Boutelier, M.-A. M. A. M.-A. Gutscher, *et al.*, 2013), and polarity  
314 reversal provides an efficient mechanism for the introduction of new subduction zones in  
315 pristine Atlantic-type oceans.

316

317 New subduction zones can be born from the interplay between slab pull of a subduction  
318 zone and resistive forces implied by an oceanic plateau collision. Oceanic plateaus are  
319 common features on the Earth's oceans and may arrive frequently at intra-oceanic  
320 trenches, leading to the formation of new subduction zones. If one assumes that  
321 subduction initiation was easier in the past because the Earth was hotter and plates were

322 weaker(Rey, Coltice and Flament, 2014; Gerya *et al.*, 2015), subduction may have  
323 persisted on Earth by self-sustaining and self-replicating mechanisms such as subduction  
324 initiation by polarity reversal induced by plateau collision.

325

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336

## 337 **Author contributions**

338 J.A. and N.R. designed and carried out the numerical models. J.A. conducted the post-  
339 processing analysis. B.K. contributed to the development of the numerical code. J.A.,  
340 N.R, F.M.R. and J.C.D. discussed the implications for subduction initiation dynamics. All  
341 authors contributed equally to writing the paper.

342

## 343 **Competing interests**

344 The authors declare no competing interests. J.C.D. is an Editorial Board Member for  
345 *Communications Earth & Environment*, but was not involved in the editorial review of, nor  
346 the decision to publish this article.

347

348 **Data availability**

349 The raw model outputs relative to this article can be found at  
350 <https://www.doi.org/10.17605/OSF.IO/XSVZ3>.

351

352 **Code availability**

353 The source for the LaMEM modelling code can be accessed at  
354 <https://bitbucket.org/bkaus/lamem/src/master/>.

355

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484



## 486 **Methods**

### 487 **Numerical approach**

488 All numerical models were run using the LaMEM code(Kaus *et al.*, 2016), with no  
489 artificially imposed forcing. The models are visco-elasto-plastic and self-consistent (i.e.,  
490 internally driven), in which the only driving force is the slab pull exerted by the subducting  
491 slab.

492 LaMEM employs a finite difference staggered grid discretization coupled with a particle-  
493 in-cell approach(Kaus *et al.*, 2016) to solve the equations of conservation of mass,  
494 momentum, and energy (eq. 1-3), assuming conditions of incompressibility.

$$\frac{\partial \mathbf{v}_i}{\partial x_j} = 0 \quad (1)$$

$$-\frac{\partial P}{\partial x_i} + \frac{\partial \tau_{ij}}{\partial x_j} + \rho \mathbf{g}_i = 0 \quad (2)$$

$$\rho C_p \left( \frac{\partial T}{\partial t} + \mathbf{v}_i \frac{\partial T}{\partial x_i} \right) = \frac{\partial}{\partial x_i} \left( \kappa \frac{\partial T}{\partial x_i} \right) + H_R + H_S \quad (3)$$

495 Here,  $\mathbf{v}_i$  is the velocity,  $x_i$  the cartesian coordinates,  $P$  the pressure,  $\tau_{ij}$  the shear stress,  
496  $\rho$  the density,  $\mathbf{g}$  the gravitational acceleration,  $C_p$  the specific heat,  $T$  the temperature,  $t$   
497 the time,  $\kappa$  the thermal conductivity, and  $H_R$  and  $H_S$  represent the radiogenic and shear  
498 heating components, respectively. The shear heating component is defined as:

$$H_S = \tau_{ij} (\dot{\epsilon}_{ij} - \dot{\epsilon}_{ij}^{\text{elastic}}) \quad (4)$$

499 Here,  $\dot{\epsilon}_{ij}$  is the total strain rate tensor and  $\dot{\epsilon}_{ij}^{\text{elastic}}$  is the strain rate imposed by the elastic  
500 deformation.

501 Our models were run using non-linear visco-elasto-plastic rheology constitutive  
502 equations(Kaus *et al.*, 2016; Piccolo *et al.*, 2020).

$$\dot{\epsilon}_{ij} = \dot{\epsilon}_{ij}^{\text{viscous}} + \dot{\epsilon}_{ij}^{\text{elastic}} + \dot{\epsilon}_{ij}^{\text{plastic}} = \frac{\tau_{ij}}{2\eta_{eff}} + \frac{\dot{\tau}_{ij}}{2G} + \dot{\gamma} \frac{\partial Q}{\partial \tau_{ij}} \quad (5)$$

$$\overset{\circ}{\tau}_{ij} = \frac{\partial \tau_{ij}}{\partial t} + \tau_{ik} \omega_{kj} - \omega_{ki} \tau_{kj} \quad (6)$$

$$\omega_{ij} = \frac{1}{2} \left( \frac{\partial v_j}{\partial x_i} - \frac{\partial v_i}{\partial x_j} \right) \quad (7)$$

503 Here,  $\eta_{eff}$  is the effective viscosity,  $\overset{\circ}{\tau}_{ij}$  is the Jaumann objective stress rate,  $\omega_{ij}$  is the spin  
504 tensor,  $G$  is the elastic modulus and  $Q$  is the plastic flow potential.

505 The effective viscosity,  $\eta_{eff}$ , is calculated according to the following model:

$$\eta_{eff} = \frac{1}{2} A^{-\frac{1}{n}} \times \dot{\epsilon}_{II}^{\frac{1}{n}-n} \times \exp\left(\frac{E_a + V_a P}{nRT}\right) \quad (8)$$

506 Here,  $A$  is the diffusive or dislocation pre-exponential factor,  $n$  is the stress exponent,  $\dot{\epsilon}_{II}$   
507 is the second invariant of the strain rate tensor (eq. 5),  $E_a$  is the activation energy,  $V_a$  is  
508 the activation volume and  $R$  is the gas constant. For phases where both dislocation and  
509 diffusive creep laws are defined (see Supplementary Table 5), the viscosity is calculated  
510 using the two sets of values at each timestep. The lowest value is defined as the effective  
511 viscosity after a simple comparison.

512 Plastic flow is ensured by employing a Drucker-Prager yield criterion (Drucker and Prager,  
513 1952):

$$\sigma_{II} = C \cos(\phi) + P \sin(\phi) \quad (9)$$

514 Here,  $\sigma_{II}$  is the second invariant of the stress tensor,  $\phi$  is the internal friction angle and  
515  $C$  is the cohesion. Plastic weakening occurs when mantle materials accumulate at least  
516 10% of total plastic strain and stops once at least 60% of total plastic strain has been  
517 accumulated. During softening, the materials' cohesion and internal friction angles are  
518 linearly reduced to 1% of their initial values. The weakening is not applied to crustal  
519 materials as they are defined as being frictionless, allowing them to act as subduction  
520 interface layers (see Supplementary Table 5).

521 The age dependence of the thermal profiles of the plates follows the half-space cooling  
522 model:

$$T = T_{surface} + (T_{mantle} - T_{surface}) \times \operatorname{erf}\left(\frac{y}{\sqrt{\kappa t}}\right) \quad (10)$$

523 Here,  $T_{surface}$  is the temperature at the surface of the model (273 K),  $T_{mantle}$  is the  
524 temperature at the lithosphere-asthenosphere boundary (1523 K),  $y$  is the depth,  $\kappa$  the  
525 diffusivity, and  $t$  is the age of the plate. The effective (rheological) lithosphere thickness  
526 throughout the model is set by the 1523 K (1250 °C) isotherm. The upper mantle thermal  
527 profile follows the mantle adiabat, with a gradient of 0.5 K/km.

528 All material densities are temperature and pressure dependent:

$$\rho = \rho_0 + \alpha(T - T_0) + \beta(P - P_0) \quad (11)$$

529 Here,  $\rho_0$  is the density of the material at the reference temperature  $T_0$ ,  $\alpha$  is the thermal  
530 expansibility and  $\beta$  is the compressibility.

531

### 532 ***Experimental setup***

533 Models were run in 3D conditions, simulating the arrival of an oceanic plateau to an active  
534 subduction system. The prescribed model domain was 4000 km long, 3000 km wide and  
535 710 km thick (see Supplementary Figure 1A and B) discretized along a 256x96x192  
536 resolution grid. The model includes a 50 km thick sticky-air layer which acts as a free  
537 surface. The top boundary is open, ensuring a free movement of this layer. All other  
538 boundaries are free slip, allowing for motion along the direction of the boundary but not  
539 across it.

540 The initial subduction was prescribed from the start in all numerical runs by always  
541 considering that the slab was already present at a depth of 300 km (initial slab  
542 configuration in Supplementary Figure 1c), along the entire width of the model. Such an  
543 initial setting allowed for a gravity driven, fully dynamic, model as the weight of the slab  
544 is enough to create a self-sustained steady state subduction (Stegman *et al.*, 2006;  
545 Stegman, Farrington and Capitanio, 2010; Riel, Capitanio and Velic, 2017), as required  
546 for any model of induced subduction initiation (Stern, 2004; Stern and Gerya, 2018). The  
547 original interface between the two plates was prescribed as a thin, weak layer with very  
548 low viscosity and denser than the surrounding oceanic plate crust (see Supplementary

549 Table 5). This initial weak layer is subducted during the onset of the run and does not  
550 interfere with the original subduction zone. The sticky-air free surface is an insulating layer  
551 with a low density ( $1000 \text{ kg/m}^3$ ) and constant low viscosity ( $10^{19} \text{ Pa.s}$ ).

552 Both overriding and subducting plates are oceanic and assumed to be composed of  
553 olivine. The crust and lithospheric mantle have maximum thicknesses of 15 and 90 km,  
554 respectively (see inset of Supplementary Figure 1C). The base density ( $\rho_0$ ) of both layers  
555 is  $3300 \text{ kg/m}^3$ . Their initial thermal profiles (i.e., vertical temperature distribution) were  
556 defined following the half-space cooling model (eq. 10). The oceanic plate crustal  
557 materials follow a plagioclase viscous creep law but, due to their low cohesion and lack  
558 of friction coefficient (see Supplementary Table 5), they are controlled by plastic flow. This  
559 allows crustal materials to act as subduction interfaces once the initial weak layer is  
560 subducted.

561 All lithospheric and sub-lithospheric mantle materials follow a dry olivine creep law  
562 (Supplementary Table 5), standard for the depleted upper mantle. On the trailing edges  
563 of both plates, the isotherms are tapered, allowing for ascension of material, defining a  
564 pair of corresponding initial ridge centres (see Supplementary Figure 1C). This allows for  
565 free plate migration and prevents the otherwise strong downwelling of cold material  
566 formed at the edges of the model, that would perturb the mantellic flow (Capitanio *et al.*,  
567 2010; Riel, Capitanio and Velic, 2017). Note that these correspond to initial geometric  
568 conditions and that no continuous spreading rates were prescribed. Any spreading  
569 observed is entirely caused by the adjacent subduction zone and the respective slab pull  
570 force.

571 The modelled oceanic plateau was defined with a parallelepipedal geometry, with four  
572 different along-trench widths ( $W_P$  in Supplementary Figure 1A and Supplementary Table  
573 1). The plateau is located along a free slip mirror symmetry plane boundary, which divides  
574 the model into two halves along its middle length, with the modelled domain  
575 corresponding only to one of them. As such, calculations are performed in just half of the  
576 whole conceptual domain (Stegman, Farrington and Capitanio, 2010). As an example, a  
577 600 km wide plateau in the model would correspond to a 1200 km wide plateau in nature.  
578 The plateau crust and the plateau lithospheric mantle have thicknesses of 20 and 90 km

579 and base densities of 2800 kg/m<sup>3</sup> and 3220 kg/m<sup>3</sup>, respectively (see inset in  
580 Supplementary Figure 1C). The crust follows a quartzite law viscous creep law (see  
581 Supplementary Table 5), with a higher cohesion and friction angle than the surrounding  
582 oceanic plate crust. This setup allows for our oceanic plateau to be both less dense than  
583 the underlying asthenosphere (i.e., positively buoyant - see inset on Supplementary  
584 Figure 1C) and simultaneously stronger than the surrounding oceanic plate crust.

585 The arc was modelled using a trapezoidal geometry which spans the entire length of the  
586 model, has a trench-normal width of 200 km, with a maximum crustal thickness of 9 km  
587 and a maximum lithospheric mantle thickness of 90 km (see Supplementary Figure 1A  
588 and C). It represents a mature volcanic arc and is less dense than the underlying  
589 asthenosphere (see inset in Supplementary Figure 1C and Supplementary Table 5).

590 The initial strength depth and thermal profiles for the different model phases can be seen  
591 in Supplementary Figure 2.

592 The slab pull force(Schellart, 2004) is estimated using:

$$F_{SP} = (\rho_{slab} - \rho_{asthenosphere})gV_S \quad (12)$$

593

594 where  $F_{SP}$  represents the slab pull force,  $g$  is the gravity acceleration,  $\rho_{slab}$  is the average  
595 density of the subducted slab,  $\rho_{asthenosphere}$  is the density of the underlying asthenosphere,  
596 and  $V_S$  represents the volume of subducted slab. The effective slab pull force is only c.a.  
597 10% of the calculated value(Schellart, 2004). The calculated values for the effective slab  
598 pull forces in all models can be found in Supplementary Tables 2 and 3.

599



600 **Figure/table captions:**

**Figure 1 – Reference model evolution of polarity reversal subduction initiation.** The mantle flow is illustrated with arrows: trench-normal mantle flow is shown in white arrows; along-trench flow is marked by blue arrows. Subduction trenches are marked by dashed lines: initial subduction in black, newly formed opposite dipping subduction in white. **a) Phase I** – Early evolution of the original subduction. During this stage, the plateau is still moving towards the active subduction trench and a mantle-wide trench-normal flow is observed. **b) Phase II** - Initial plateau collision. During this stage, the plateau arrives at the subduction trench and, due to its positive buoyancy, blocks it. Laterally, the initial subduction is still active and continues to steadily rollback. **c) Phase III** - Subduction polarity reversal. Driven by the slab pull exerted by the laterally ongoing original subduction, the plateau is forced onto the overriding plate. Consequently, the overriding plate is underthrust and, eventually forced to subduct in the opposite direction. The original slab is broken-off below the plateau. **d) Phase IV** – Opposite polarity double subduction system. At this stage, both subduction zones are dynamically maintained by the slab pull of each of their sinking slabs. As the newly formed subduction undergoes trench rollback and migrates laterally, a mantle upwelling forms below the plateau (see Fig. 2).

601 **Figure 2 - Reference model post polarity reversal evolution lateral migration of the newly formed**  
602 **subduction zone.** To better visualize the sub-lithospheric mantle flow in the area marked by a square in  
603 Fig. 1d., the plateau was made semi-transparent in the depicted evolutionary stages, which comprise: **a)**  
604 Initial opposite verging double subduction system (same stage as in Fig. 1d). **b)** Early lateral migration of  
605 the newly formed SZ, aided by mantle flow funnelling beneath the arc. The arc itself is strongly strained,  
606 showing signs of necking. **c)** Evolving lateral migration with mantle upwelling. **d)** Bifurcation of mantle flow  
607 enhances incipient propagation of the original subduction zone behind the oceanic plateau. This is similar  
608 to what has been previously described for plateau-continent collisions (Moresi *et al.*, 2014; Betts *et al.*,  
609 2015).

610

611 **Figure 3 – Graphical depiction of the evolution of the model monitored parameters for the different**  
612 **considered plateau widths ( $W_P$ ).** The coloured diamonds indicate the moment at which collision with the  
613 plateau is initiated, while the coloured triangles indicate the time at which full polarity reversal is achieved.  
614 The subducting plate velocity ( $V_{SP}$ ) is measured at the trailing edge of the subducting plate, along  
615 longitudinal sections both near the mirror symmetry boundary that cuts through the plateau (c.f. section A-  
616 A' in Supplementary Figure 1), and along the opposite model boundary that crosses only the initial intra-  
617 oceanic subduction zone. **a)** Evolution of subduction plate velocity ( $V_{SP}$ ) over time (subduction plate  
618 acceleration), for the original subduction zone (full lines), and for the newly formed opposite dipping one  
619 (dashed lines). Note that narrower plateaus imply a smaller indentation area and accompanying lower

620 energy dissipation, resulting in both higher  $V_{SP}$  values and plate accelerations. Narrower plateaus also lead  
621 to an early trigger of polarity reversal events, expressed by the diminishing distance between diamonds  
622 and triangles in the graph. **B)** Subduction trench migration as a function of time (trench velocity), for the  
623 original subduction zone (full lines) and for the newly formed subduction trench (dashed lines). The plateau  
624 collision event causes an abrupt migration of the newly forming trench towards the overriding plate (OP),  
625 even before the new opposite dipping subduction zone is fully formed. **c)** Plateau indentation efficiency,  
626 expressed by the time evolution of the  $W_R$  ratio (see Supplementary Figure 1B) between the growing length  
627 of the new subduction zone ( $L_{NSZ}$ ) and the original along-trench width of the plateau ( $W_P$ ). As no new  
628 subduction zones are formed before the collision of the plateau with the overriding plate,  $W_R$  values prior  
629 to this event are always zero. Narrower plateaus create notably longer subduction zone trenches relative  
630 to their initial widths. The  $W_P = 2400$  km line was not included in c) due to the lack of a polarity reversal  
631 event. SZ – Subduction Zone; OP – Overriding plate; SP – Subducting plate;  $L_{NSZ}$  – Length of new  
632 subduction zone.

633

634 **Figure 4 – Graphical depiction of the evolution of the model monitored parameters for the different**  
635 **considered (initial) plate age contrast between the overriding and the subducting plates (OP and SP**  
636 **age respectively).** Coloured diamonds and triangles, as well as  $V_{SP}$  measurements, with the same  
637 meaning, and obtained in the same way, as explained in the caption of Fig. 3. **a)** Evolution of subduction  
638 plate velocity ( $V_{SP}$ ) over time (subduction plate acceleration), for the original subduction zone (full lines),  
639 and for the newly formed opposite dipping one (dashed lines). Note that older subducting plates show faster  
640 evolutions, expressed by the steeper variations over time, derived from their higher negative buoyancy and  
641 effective slab pull (see Supplementary Table 4). **b)** Subduction trench migration as a function of time (trench  
642 velocity), for the original subduction zone (full lines) and for the newly formed subduction trench (dashed  
643 lines). The plateau collision event causes an abrupt migration of the trench towards the overriding plate  
644 (OP). Younger subducting plates show longer time gaps between plateau collision and the polarity reversal  
645 event. **c)** Plateau indentation efficiency, expressed by the time evolution of the  $W_R$  ratio (see Supplementary  
646 Figure 1B and caption of Fig. 3c). As no new subduction zones are formed before the collision of the plateau  
647 with the overriding plate,  $W_R$  values prior to this event are always zero. Despite the fact that older subducting  
648 plates trigger polarity reversal at earlier stages, plate age appears to have no relevant influence in the  
649 effectiveness of plateau indentation (expressed by a similar steepness of all the curves). SZ - Subduction  
650 Zone; OP - Overriding plate; SP – Subducting plate;  $L_{NSZ}$  – Length of new subduction zone.

651

652 **Figure 5 – Comparison between the carried-out reference model and the formation and early**  
653 **evolution of the Vanuatu subduction zone. a)** Incipient formation of the Vanuatu subduction zone. During  
654 the late Miocene, the Ontong-Java plateau (OJP) begins to dock along the Pacific trench triggering the  
655 initiation of the subduction of the Australian plate with an opposite polarity. The currently observed cross-

656 section along the Solomon Islands arc (inset), still allows the recognition of the incipient new subduction  
657 zone corresponding to the initial development of the Vanuatu SZ. This configuration is also coherently  
658 observed in the shown model (Model 1, 70 Myr overriding and subducting plate and  $W_P = 600$  km). **b)**  
659 Formation of an extensional basin in the Pacific plate after termination of the original subduction zone. The  
660 trench rollback/lateral migration of the newly formed Vanuatu subduction zone triggers extension in the new  
661 overriding plate area, forming an extensional basin ridges between this subduction zone and the Ontong-  
662 Java plateau(Schellart and Lister, 2005). This consistent with our models, along the A-A' cross-section,  
663 where a newly formed basin is found between two subduction zones of opposite polarity. The proposed  
664 mantle inflow at that time(Heyworth *et al.*, 2011) as well as the end of the Pacific subduction zone in front  
665 of the Ontong-Java plateau are also mirrored by the model results.

666

667