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Internal Planetary Feedbacks, Mantle Dynamics, and Plate Tectonics

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Abstract

Isolating planetary feedbacks, and feedback analysis, are prevalent aspects of climate and Earth surface process science. An under appreciation of internal planet feedbacks, and feedback analysis for plate tectonics research, motivate this chapter. We review feedbacks that influence the Earth's thermal evolution and expand them to include magmatic history and planetary water budgets. The predictions from feedback models are shown to be consistent with petrological constraints on the Earth's cooling. From there, we isolate feedbacks that connect structural elements within the mantle dynamics and plate tectonics system. The feedbacks allow for a reciprocal causality between plates, plumes, the asthenosphere, and mantle flow patterns, with each element being co-dependent on the others. The linked elements and feedbacks define plate tectonics are part of a self-sustaining flow system that can bootstrap itself into existence. Within that framework, plate tectonics involves the co-arising of critical system factors. No single factor is the cause of another. Rather, they emerge with the links between them and the generation of functional elements coincides, within relatively narrow time windows, with the co-emergence of factors that are critical for the maintenance of the elements themselves. What emerges is not a tectonic state but a process. That is, a set of feedbacks that can transform the tectonics of a planet and/or maintain plate tectonics. The feedback functions are not permanent but can operate over extended time frames such that plate tectonics can remain stable. The nature of the feedbacks, and their stability, can be studied at various levels of detail but questions of origin can become ill-defined. Observational tests of a feedback framework for plate tectonics and mantle dynamics are presented, along with research paths that apply feedback methodology to solid planet dynamics and comparative planetology.

1 **1. Introduction**

2 The concept of feedback is prevalent within climate science, Earth surface
3 science, and studies of the Earth's biosphere. Introductory textbooks on
4 the subjects now routinely discuss feedback analysis. The same can not be
5 said for solid-earth science. The relative under-appreciation of solid planet
6 feedbacks motivates this chapter. Our pragmatic goal is to highlight several
7 solid planet feedback processes. Our more meta-goal is to argue that feedback
8 analysis is a useful tool for research into mantle dynamics and plate tectonics
9 and can provide a means to cast new light on old questions.

10 Feedback occurs when a cause initiates a chain of events that ultimately
11 leads to an effect on the initial cause itself. If the cause is enhanced, then the
12 cycle is a positive feedback (also referred to as an amplifying feedback). If the
13 initiating cause is damped, then its is a negative feedback (also referred to
14 as a buffering and/or regulating feedback). Discussions of feedback appear
15 throughout history but a modern appreciation started within engineering
16 [Maxwell, 1868]. Feedback became a foundational concept for cybernetics
17 and general systems theory [Weiner, 1948; von Bertalanffy, 1968]. Systems
18 theory, systems science, and a systems approach expanded into a wide range
19 of fields [Jantsch, 1980; Meadows 1982; 2009; Laszlo, 1996]. An historical
20 overview of how systems theory expanded into, and intertwined with, the
21 Earth sciences can be found in Steffan et al. [2020].

22 Systems can be defined in different ways. A general definition is that “A
23 system is a set of interacting units or elements that form an integrated whole
24 that performs some function [Skyttner, 1996].” Links and interactions lead to
25 order, pattern, and structure that dynamically maintains itself and generates
26 functions not inherent in any of the single elements, often expressed as the
27 whole being greater than the sum of its parts and/or the idea that ‘more
28 is different’ [Anderson, 1972]. A more precise definition comes from Ackoff
29 [1981] who defines a system as a set of elements that satisfy the following
30 conditions: 1) The behavior of each element has an effect on the behavior of
31 the whole; 2) The behavior of the elements and their effects on the whole are
32 interdependent; 3) However subgroups of the elements are formed, all have
33 an effect on the behavior of the whole but none has an independent effect
34 on it. All of the definitions implicate feedbacks as critical to distinguishing a

35 system from an aggregate of elements. That feedbacks can generate collective
36 system properties not inherent in system elements also connects feedback to
37 studies of self-organization and emergent phenomena [Holland, 1998; Fromm,
38 2004].

39 Earth systems science, which rose to prominence in the 1980s, was founded
40 on an appreciation of feedbacks in the natural world. An example is the
41 silicate-weathering feedback, which provides a means for a planet to regu-
42 late atmospheric greenhouse gas concentrations [Walker et al., 1981]. That
43 feedback is connected to the carbon cycle. Figure 1a shows a schematic of
44 the cycle [Berner, 1983]. The schematic serves as a visual motivation for this
45 chapter. The Earth’s interior is conceptualized as a source and a sink for
46 materials that enter into atmosphere, hydrosphere, and biosphere feedbacks.
47 This example is not overly contrived and Earth systems literature often has
48 the Earth’s mantle conceptualized as an arrow that points to feedback loops
49 outside of the mantle itself (Figure 1b). The potential of feedbacks within our
50 planets interior has not been appreciated to the level that surface feedbacks
51 have come to be appreciated.

52 The under appreciation of solid-planet feedbacks is perplexing given some
53 historical serendipity. In 1974 a paper appeared that would set into motion
54 an appreciation of feedbacks that could regulate the surface temperature of a
55 planet [Lovelock and Margulis, 1974; Watson and Lovelock, 1983]. Two years
56 earlier a paper appeared about a feedback that could regulate the internal
57 temperature of a planet [Tozer, 1972]. The former is seen as foundational to
58 an appreciation of feedbacks in the natural world and the rise of a systems
59 approach to earth science [Steffan et al., 2020]. The later is less appreciated
60 as a step toward the application of feedback thinking to natural systems.
61 As such, it provides a good starting point for discussions of solid planet
62 feedbacks. From there, we will spring board into discussions of additional
63 feedbacks that can play roles in mantle dynamics and the operation of plate
64 tectonics.

65 **2. Thermal Cycles, Thermal-Hydro Cycles, and Internal Earth** 66 **Cooling Feedbacks**

67 The the cooling of the Earth is a problem with a rich history [Kelvin,
68 1863; England et al., 2007]. Plate tectonics set Earth cooling within a mo-
69 bilist view. Plate tectonics is a surface expression of mantle convection and
70 convective plate overturn is a principal means of interior cooling.

71 The first generation of thermal history models, based on convective cool-
 72 ing, came out in the late 1970s to early 1980s [Sharpe and Peltier, 1979;
 73 Schubert, 1979; 1980; Davies, 1980]. The models are based on a global en-
 74 ergy balance that tracks the decay of internal mantle heat sources and surface
 75 heat loss. Heat loss is parameterized in terms of a relationship between con-
 76 vective heat flux (Nu) and a mantle Rayleigh number (Ra), a measure of
 77 convective vigor. That relationship is given by

$$Nu \sim Ra^\beta \quad (1)$$

78 where

$$Ra = \frac{\rho g \alpha \Delta T Z^3}{\kappa \eta} \quad (2)$$

79 and ρ is density, α is thermal expansivity, g is the acceleration due to gravity,
 80 ΔT is the driving temperature, Z is the thickness of the convecting layer, κ
 81 is the thermal diffusivity and η is the mantle viscosity. The scaling exponent,
 82 β , parameterizes the effects of physical factors on the efficiency of convective
 83 cooling. In particular, it depends on physical processes that resist convective
 84 motion and the overturn of tectonic plates. The first generation of thermal
 85 history models assumed that mantle viscosity is the dominant resistance
 86 to plate overturn. That leads to a β value near the high-end limit of 1/3
 87 [Schubert et al., 1980]. Together with an exponential dependence of mantle
 88 viscosity on temperature, this allows for a feedback isolated by Tozer [1972].
 89 Arguably, it was an appreciation of that feedback that set modern thermal
 90 history modeling into motion.

91 Figure 2a shows a causal loop diagram of the Tozer feedback. Arrows
 92 labelled as positive indicate that an increase/decrease of the factor at the
 93 base of the arrow leads to an increase/decrease of the factor at the head of
 94 the arrow. Arrows labelled as negative indicate that an increase/decrease of
 95 the factor at the base of the arrow leads to a decrease/increase of the factor
 96 at the head of the arrow. Multiplying positive and negative effects around
 97 an entire feedback loop leads to the overall sign of the feedback, which ap-
 98 pears in parenthesis at the loop center. The Tozer feedback is a negative
 99 feedback: If heat loss becomes low/high relative to internal heat generation,
 100 then the mantle will heat/cool, viscosity will decrease/increase, and heat
 101 flux will increase/decrease (due to increased/decreased tectonic plate over-
 102 turn associated with lower/higher viscous resistance). This regulates mantle
 103 temperature against large and/or long-lived fluctuations. For that reason it
 104 is also referred to as a thermostat feedback.

105 Although the Tozer feedback influenced thermal history modeling, whether
106 it leads to mantle self-regulation has been called into question [Korenaga,
107 2016]. The ability of the feedback to regulate mantle evolution depends
108 on two times scales (Figure 2a). One is associated with the decay rate of
109 radiogenics in the mantle. That time scale, referred to as a secular time, is
110 on the order of a billion years. The second is the time over which the feedback
111 operates. That time scale relates to the reactance time of a system [Seely,
112 1964; Close et al., 2001]. Reactance time characterizes a systems response to
113 perturbations.

114 Mantle reactance time depends on the relationship between heat loss
115 and convective vigor. In thermal history models this relates to the assumed
116 value of β in Equation 1. Figure 3a plots results from a reactance time
117 analysis applied to a range of thermal history models [Seales, 2019]. Models
118 with β near $1/3$ have a relatively short reactance time that allows interior
119 cooling to evolve along a self-regulated path [Davies, 1980]. Those models
120 assume that viscosity is the dominant resistance to plate motions. If plate
121 and/or plate margin strength also plays a significant role, then β has been
122 argued to be closer to 0.15 [Conrad and Hager, 1999]. That still allows
123 for self-regulation but fluctuations can be longer lived. If mantle viscosity
124 plays no role in plate motions and plate strength remains constant, then β
125 is zero and there is no feedback or self-regulation [Christensen, 1984; 1985].
126 If plate strength increases with convective vigor, then β can be negative
127 [Korenaga, 2003; 2008]. A feedback exists but, unlike the Tozer feedback,
128 it is a positive feedback (Figure 2b). Positive feedbacks do not regulate a
129 system. Instead, they allow perturbations to be amplified and/or be very
130 long lived; different initial conditions and/or fluctuations along a cooling
131 path can influence a planets evolution over time scales longer than a secular
132 time. The implications for planetary thermal histories are significant (Figure
133 3b).

134 If the Tozer feedback is operative, then the damping of thermal perturba-
135 tions/fluctuations maintains the ratio of heat generation to heat loss, termed
136 the Urey ratio (Ur), near unity [Schubert1980]. Stated another way, the
137 mantle convection system has low thermal inertia such that any large de-
138 viations from thermal equilibrium are damped and interior cooling evolves
139 along a series of quasi-equilibrium steps [Davies, 1980]. Such models can-
140 not account for updated constraints on Earth’s cooling history [Christensen,
141 1985; Korenaga, 2008]. In particular, data constraints place Ur between
142 0.2 and 0.5 [Jaupart et al., 2007], i.e., heat loss and heat generation are far

143 from equilibrium. This has been used to argue that mantle convection is not
144 self-regulated [Korenaga, 2016].

145 The argument that low Ur is not consistent with thermal self-regulation is
146 robust but it does not rule out self-regulation altogether. The appreciation
147 that mantle viscosity depends on temperature lead classic thermal history
148 models to focus on thermal-regulation. What has gone under appreciated
149 is that the critical assumption at their core is viscosity-regulation. That is,
150 changes in viscosity dominate changes in the Earth's Rayleigh number and,
151 over time scales shorter than secular decay times, viscosity, and by association
152 the Rayleigh number, can be approximated as remaining constant (a quasi-
153 equilibrium assumption). This is a critical assumption in using $Nu \sim Ra^\beta$
154 scaling relationships to begin with, as they are based on theory, experiments,
155 and/or numerical simulations carried out under constant Ra values [Moore
156 and Lenardic, 2015]. If viscosity depends only on temperature, then a lack
157 of thermal-regulation rules out self-regulation. If that is not the case, then
158 self-regulation remains viable. The dependence of mantle viscosity on water
159 opens this possibility [Mackwell, 1985; Li et al., 2008].

160 Early thermal history models that considered the role of water predicted
161 Ur values greater than one or comparable to classic models [Jackson and
162 Pollack, 1987; McGovern and Schubert, 1989]. The former enforced a net
163 loss of water from the Earth's interior. The latter assumed that Ur should
164 be 0.8 and, as such, calibrated free parameters to keep mantle water content
165 nearly constant. Crowley et al. [2011] showed that a larger range of behavior
166 is possible if imbalances in mantle dewatering (D) and rewatering (R) are
167 allowed for. Mantle dewatering occurs principally via melting at mid-ocean
168 ridges. Mantle rewatering occurs at subduction zones, where descending
169 slabs carry some of their bound water into the mantle. If mantle viscosity
170 depends on temperature (T) and water content (χ), then the time rate of
171 change of mantle viscosity can be written as

$$\frac{d\eta}{dt} = \frac{\partial\eta}{\partial T} \frac{dT}{dt} + \frac{\partial\eta}{\partial\chi} \frac{d\chi}{dt}. \quad (3)$$

172 Conservation of energy leads to

$$\frac{dT}{dt} = \frac{1}{\rho C_p V} (H - Q_s) \quad (4)$$

173 where C_p is specific heat, V is mantle volume, H is mantle heat production,

174 and Q_s is surface heat flow. Conservation of mantle water content leads to

$$\frac{d\chi}{dt} = \frac{1}{\rho V}(R - D). \quad (5)$$

175 If viscosity remains statistically steady, relative to the time scale over which
176 significant changes occur in internal heat generation, then the Urey ratio is
177 given by

$$Ur \approx 1 - \frac{\eta_\chi}{\eta_T} \frac{C_p}{Q_s}(R - D), \quad (6)$$

178 where $\eta_\chi = \frac{\partial \eta}{\partial \chi}$ and $\eta_T = \frac{\partial \eta}{\partial T}$. If R exceeds D , then the Earth can be out
179 of thermal equilibrium and low values of Ur are viable without requiring a
180 weak, or negative, relationship between heat loss and Ra . A simplified causal
181 loop diagram (Figure 4a) can help elucidate how imbalances in water cycling
182 can drive the mantle out of thermal equilibrium. The analysis of Crowley et
183 al. [2011] re-opened the possibility of planetary self-regulation but it did not
184 investigate whether it was consistent with petrological constraints on Earth
185 cooling. A recent study has addressed that question [Seales et al., 2021].

186 Seales et al. [2022] explored thermal and deep-water cycling models con-
187 strained to match thermal cooling paths consistent with petrological data
188 [Herzberg et al., 2010, Condie et al., 2016, Ganne and Feng, 2017]. The
189 models were also constrained by the present day Urey ratio and surface wa-
190 ter content. Variable β values were allowed for. For each thermal path,
191 one-hundred different combinations of Ur and β were sampled, within data
192 bounds, and inverted for mantle water content. This involved converting
193 a forward model of coupled thermal and water history [Sandu et al., 2011;
194 Seales and Lenardic 2020b] into an inverse model [Seales et al., 2022]. Figure
195 4b shows the full causal loop diagram for the coupled thermal and water cy-
196 cling model. With the data constraints, the evolution of mantle and surface
197 water content was determined throughout Earth’s history. This procedure
198 produced over 10,000 evolution paths.

199 Figure 5a shows mantle cooling paths that met a goodness of fit crite-
200 ria with petrological data, allowing for data uncertainties. Figure 5b shows
201 the density of successful $Ur - \beta$ space. Successful models gathered towards
202 the lower Ur bound with $\beta \geq 0.2$. Figure 5c shows mantle water evolution.
203 Model and data uncertainties demand that outputs be calculated as prob-
204 ability distributions. The median of the distribution is depicted as a thick
205 black line. The darker region is bounded by the upper and lower quartiles.

206 The lighter region extends to one and half times the interquartile range. Suc-
207 cessful models experienced an early period of net mantle dewatering followed
208 by net rewatering. The water-cycling switch is reflected in the evolution of
209 mantle viscosity (Figure 5d).

210 The combined effects of thermal and water cycle feedbacks lead to mild
211 variations in the mantle Rayleigh number over model evolution time (Figure
212 6a). Mild Rayleigh number variations, in the face of declining internal heat
213 sources, is indicative of a self-regulated mantle evolution. Another measure
214 of self-regulation is the ratio of the mantle geotherm to the mantle solidus,
215 termed a homologous temperature (T_H). The greater the thermal distance
216 between mantle temperature and the solidus, the greater the value of T_H
217 and the greater the potential of mantle melt generation. When T_H drops
218 below unity, melting is predicted to cease. Figure 6b shows T_H evolution
219 for successful models. The decrease over the first few billion years coincides
220 with net mantle dewatering, which increases the solidus [Katz et al., 2003].
221 The change from net mantle dewatering to rewatering alters the behavior
222 of T_H . The flattening of the slope around 2 Ga indicates that the mantle
223 geotherm becomes locked to the solidus and the two co-evolve, i.e., mantle
224 melt potential is self-regulated.

225 One might assume that a drop in T_H over the first 2 billion years of
226 evolution would be due to mantle cooling. However, data constraints show
227 that, over this time, mantle cooling is mild, if at all (Figure 5a). That mild
228 cooling stage is critical to a low present-day Urey ratio, which indicates that
229 mantle heat flow is high relative to heat generation. This requires a period
230 of low heat flow in the past to retain heat that is then available to supply
231 elevated present day heat flow. Successful models allow for this via a switch
232 from net mantle dewatering to rewatering, which also leads to an initial drop
233 in T_H followed by a self-regulated phase. The change from net dewatering
234 to rewatering is associated with a change in the dominant sign of the water-
235 cycling feedback.

236 Figure 4c isolates the water cycle from the full thermal-hydro system
237 (Figure 4b). It shows that the water cycle allows for two feedback loops.
238 Under hotter mantle conditions, the negative loop dominates which allows
239 melting to lower mantle water content. This works against thermal effects on
240 mantle cooling. As a result, the full cycle maintains a near constant mantle
241 temperature. As mantle water content drops, mantle cooling can accelerate.
242 This leads to colder subduction which recycles more water into the mantle
243 [Iwamori, 2007]. The water cycle becomes dominated by its positive feedback

244 loop (right loop of Figure 4c). This increases mantle water content over time
245 and lowers the mantle solidus which, together with coupled thermal effects,
246 regulates melt potential (Figure 6). In short, coupled thermal and water
247 cycling feedbacks allow for a self-regulated mantle evolution consistent with
248 data constraints.

249 Before moving to the next feedbacks, it is worth taking an aside to point
250 out how isolating feedbacks can expose ill-posed questions. If the feedbacks of
251 Figure 2a or Figure 4 are operative, then the question “Does mantle viscosity
252 regulate plate velocity or does plate tectonics regulate mantle viscosity?” is
253 misleading. It is a ‘flat-earth question’. That analogy stems from medieval
254 times when people would point to the horizon and ask “does it go on forever or
255 is there an edge?”. Flat-earth questions assume mutually exclusive answers.
256 Feedback shatters that assumption. Causal loop analysis provides a means
257 to isolate layers of reciprocal causality versus linear causality (e.g., A causes
258 B). Reciprocal causality, in turn, can highlight ill-posed research questions
259 and/or cast new light on old questions. Readers may wish to pause and
260 consider other questions that have been posed in a similar form, e.g., “Do
261 plates drive mantle motions or do mantle motions drive plates?”

262 **3. Mantle Dynamics and Mantle Viscosity Structure Feedbacks**

263 The feedbacks of the previous section connected to the temperature- and
264 hydration-dependence of mantle viscosity. Two additional viscosity-related
265 factors allow for added mantle feedbacks: 1) Mantle viscosity allows for non-
266 Newtonian behavior; 2) Topography, gravity, and geoid constraints show that
267 mantle viscosity increases with depth [Richards and Hager, 1984].

268 Mineral physics constraints indicate that upper mantle viscosity is non-
269 Newtonian (a power law viscosity that displays shear weakening) while the
270 lower mantle is Newtonian [Burgmann and Dresen, 2008; Hirth and Kohlstedt,
271 2015]. A non-Newtonian upper mantle allows low viscosity regions to
272 emerge in response to mantle flow. This leads to a feedback as changes in
273 mantle velocity gradients alter local viscosity structure which, in turn, affects
274 velocity and velocity gradients. The feedback allows localized zones of low
275 viscosity to emerge within the mantle [Billen and Hirth, 2007; Andrews and
276 Billen, 2009; Jadamec and Billen, 2010; Stadler et al., 2010; Alisic et al.,
277 2012; Jadamec, 2016]. It also allows for a more global effect in which depth-
278 variable mantle viscosity can be dynamically generated and maintained.

279 King [2016] showed that a non-Newtonian upper mantle could lead to a
280 global viscosity structure characterized by a low viscosity upper mantle above
281 a high viscosity lower mantle. Semple and Lenardic [2018; 2020a; 2020b]
282 used a similar approach to explore how a non-Newtonian upper mantle could
283 impact global mantle dynamics. The models showed that upper mantle flow
284 channelization could emerge dynamically (Figure 7). It had previously been
285 shown that upper mantle flow channelization, into an imposed low viscosity
286 layer, would alter the global energy balance of mantle convection [Busse et al.,
287 2006; Lenardic et al., 2006]. The non-Newtonian models showed that similar
288 effects could emerge without a pre-existing low viscosity region. An added
289 feedback was identified as the emerging channel promoted long wavelength
290 mantle flow which increased mantle velocity and shear gradients. This, in
291 turn, increased the viscosity variation between the upper and lower mantle.
292 The enhanced viscosity variation favored longer wavelength flow. Figure 8a
293 shows a loop diagram of the feedback cycles.

294 The two right side loops of Figure 8a are positive feedbacks. The system
295 can not, however, runaway as geometry limits the maximum wavelength of
296 mantle convection (the potential effects of continents can also provide wave-
297 length limits [Zhong et al., 2007]). Another limiter can come from a negative
298 feedback (the left loop of Figure 8a). Longer wavelengths will be associ-
299 ated with tectonic plates of greater lateral extent. Those plates will have
300 greater ages when they enter subduction zones. The greater ages can lead
301 to greater plate thickness and enhanced resistance to plate bending, which
302 tends to lower plate velocity [Conrad and Hager, 1999]. That potential is in
303 line with results from the previous section which showed that models with
304 plate strength contributing to cooling efficiency, along with mantle viscosity,
305 are consistent with data constraints (Figure 5).

306 Figure 8a provides an example of how isolating feedbacks can cast new
307 light on old questions. Seismic tomography and geoid modeling are consistent
308 with long wavelength mantle convection [Su and Dziewonski, 1992; Hager and
309 Richards, 1989]. Long-wavelength convection is not the norm at the level of
310 convective vigor inferred for the mantle. This presented a question: What
311 allows for long-wavelength convection? A potential solution came from nu-
312 merical simulations that generated long wavelength convection by imposing
313 a viscosity increase from the upper to the lower mantle [Bunge et al., 1996,
314 1997; Hansen et al., 1993; Tackley, 1996; Zhang and Yuen, 1995; Zhong et al.,
315 2000]. The physical mechanism behind this observation was elucidated via
316 boundary layer theory [Busse et al., 2006; Lenardic et al., 2006]. In a convect-

317 ing layer, with no internal viscosity variations, long-wavelength cells become
318 unstable because lateral viscous dissipation dominates over vertical dissipa-
319 tion. Lateral dissipation increases with cell wavelength. Depth-variable vis-
320 cosity changes the mantle global energy balance such that vertical dissipation
321 can become dominant over a broader wavelength range. As mantle depth is
322 fixed, the vertical term does not increase in the same way as the lateral term
323 does with increasing flow wavelength. This allows long wavelength convec-
324 tion to remain stable over a broader wavelength band (a prediction confirmed
325 via numerical stability analysis [Ahmed and Lenardic, 2010]). It also allows
326 convective velocities to increase with wavelength [Hoink and Lenardic, 2008;
327 2010; Hoink et al., 2011].

328 Following the progression above, could lead to answering the question
329 of ‘what is the cause of long wavelength mantle convection?’ with ‘depth-
330 variable viscosity’. Figure 12 shows what can be missed by applying that
331 mode of thinking to a feedback process. Linear cause and effect thinking
332 could limit one from considering the potential that depth-variable viscosity
333 could, itself, be a property that is dependent on long wavelength flow. In
334 the reciprocal causality view, depth-variable viscosity is connected to long
335 wavelength flow but it is not necessarily the cause of it. The ‘cause’ could be
336 an internal fluctuation that initiates an amplifying feedback which, in turn,
337 leads to a system restructuring characterized by co-dependent depth-variable
338 viscosity and long-wavelength flow. Readers may again wish to pause and
339 consider other questions that have been framed in a linear cause and effect
340 manner, e.g., ‘What is the cause of plate tectonics?’

341 The feedback of this section can be connected to the previous section.
342 A non-Newtonian upper mantle feedback provides an amplifier for a water
343 cycling feedback (Figure 8b). Relatively small changes in upper mantle wa-
344 ter content can enhance plate velocities and associated upper mantle shear.
345 Increased shear will further lower viscosity on a relatively rapid time scale.
346 This feeds back on the water cycle and lowers its reactance time. A lower re-
347 actance time, in turn, enhances the effectiveness of the water cycle feedback.

348 **4. Boundary Layer Interactions and Plate-Plume Feedbacks**

349 Mantle convection is driven from the decay of radioactive elements (in-
350 ternal heating) and heat flowing into the mantle from the core (basal heat-
351 ing). A range of studies have mapped similarities and differences between
352 mixed mode heating and internal or basal heating end-members [Schubert

353 and Anderson, 1985; Grasset and Parmentier, 1998; Sotin and Labrosse,
 354 1999; Moore, 2008; Shahnas et al., 2008; Choblet and Parmentier, 2009;
 355 Wolstencroft et al., 2009; O’Farrell and Lowman, 2010; Choblet, 2012; De-
 356 schamps et al., 2010; 2012; O’Farrell et al., 2013; Stein et al., 2013; Weller
 357 et al., 2015; Korenaga, 2017; Vilella and Deschamps, 2018; Vilella et al.,
 358 2018]. A recently identified difference is that, in a mixed heating layer, sur-
 359 face velocity can decrease with increasing internal heat sources [Lenardic et
 360 al., 2020]. That observation connects to a mantle dynamics feedback and
 361 associated feedbacks between tectonic plates and mantle plumes.

362 Figure 9a shows a representative case from a suite of numerical convec-
 363 tion experiments driven by a mix of internal and basal heating [Lenardic et
 364 al., 2020]. The presence of two heat sources means that a bottom heating
 365 (Ra) and an internal heating Rayleigh number (Ra_i) characterize the sys-
 366 tem. Figure 9b plots surface velocities and rms system velocities, from the
 367 experimental suite, as functions of the two Rayleigh numbers. Decreasing
 368 velocities, with increased internal heating, is not an expectation based on
 369 classic ideas as to how velocity should scale with mantle heat sources [Schu-
 370 bert et al., 2001].

371 Classical convective scalings assume that thermal boundary layers behave
 372 in a self-determined manner [Howard, 1966]. Under that assumption, scaling
 373 trends can be derived via a local stability criteria that governs boundary
 374 layer thickness. A local Rayleigh number, Ra_δ , can be defined for the upper
 375 thermal boundary layer as

$$Ra_\delta = \frac{\rho g \alpha (T_i - T_s) \delta^3}{\kappa \eta} \quad (7)$$

376 where δ is the boundary layer thickness. For constant surface temperature
 377 (T_s), the internal temperature of the convecting layer (T_i) provides a measure
 378 for the temperature drop across the boundary layer. When Ra_δ exceeds a
 379 critical value, given by Ra_c , convective instabilities form and lower portions of
 380 the boundary layer detach. This maintains the boundary layer at a critical
 381 thickness and a statistically steady state is achieved with $Ra_\delta = Ra_c$. A
 382 prediction that follows is that $\delta \sim Ra^{-1/3}$. A second prediction is that
 383 $\delta \propto \Delta T^{-1/3}$. The connection to boundary layer velocity (u) comes from a
 384 balance of conductive and advective time scales. The time it takes heat to
 385 diffuse across the boundary layer is given by τ . This leads to $\delta = \sqrt{\kappa \tau}$. An
 386 advective time scale can be defined as aD/u , where a is the aspect ratio
 387 of a convection cell. If the boundary layer becomes unstable at a critical

388 thickness, then the two time scales are equal and $\delta \propto u^{-1/2}$. This amounts
389 to applying Howards criteria [1966] to cellular convection. Boundary layer
390 theory, which explicitly solves for velocity as a function of aspect ratio, leads
391 to an equivalent relationship between δ and u [Turcotte and Oxburgh, 1967].
392 In combination, the above predicts that $u \propto \Delta T^{2/3}$. Increasing internal
393 temperature is predicted to increase boundary layer velocity. The thermal
394 history community has leaned on this prediction for decades [Schubert et al.,
395 2001].

396 A decrease in upper boundary layer velocity with increased internal heating
397 (Figure 9b) suggests that the concept of a self-determined boundary layer
398 may be incomplete. For bottom heated, high Reynolds number convection it
399 has been shown that a self-determined boundary layer regime is not achieved
400 even at what are considered to be very high Rayleigh numbers [Castaing et
401 al., 1989]. This behavior connects to an inertial wind that shears the upper
402 boundary layer and prevents it from achieving a critical thickness [Kadanoff,
403 2001]. Although inertial effects are absent in mantle convection, bound-
404 ary layer interactions can occur [Weinstein et al., 1989; 1990; Lenardic and
405 Kaula, 1994; Labrosse, 2002; Galsa and Lenkey, 2007; Vilella and Deschamps,
406 2018]. Moore [2008] has argued that such interactions will short-circuit self-
407 determined boundary layer behavior.

408 Self-determined boundary layers require weak interactions between upper
409 and lower boundary layers. At very high degrees of convective vigor this
410 will be achieved as upwelling plumes, for example, will dissipate before they
411 impact the upper boundary layer. Moore [2008] noted that discrepancies
412 between classic scaling predictions and experimental results, even at values
413 considered to be high Ra , indicate that mantle convection may not reach that
414 limit. For example, the numerical experiments of Lenardic and Moresi [2008]
415 indicated that classic scaling trends are approached asymptotically for $Ra >$
416 10^9 . If boundary layers do interact, then the upper thermal boundary layer
417 may not reach a critical thickness as per the theory of Howard [1966]. All
418 other factors being equal, a decrease in boundary layer interaction could then
419 lead to a decrease in boundary layer velocity. Increased internal heating, in a
420 mixed heated layer, could progressively reduce boundary layer interactions as
421 thermal upwellings become weaker and have less effect on the upper thermal
422 boundary layer [Labrosse, 2003; Vilella and Deschamps, 2018].

423 The conceptual idea above can be formalized [Lenardic et al., 2020]. The
424 theory of Moore [2008] predicts that the temperature drop across the upper

425 thermal boundary layer (ΔT_{top}) scales as

$$\Delta T_{top} = 0.499 + 1.33Q^{3/4}Ra^{-1/4} \quad (8)$$

426 and that the non-dimensional heat flow (Nu) across the upper boundary
427 scales as

$$Nu_{top} - 1 = Nu_{bot} - 1 + Q = 0.5Q + 0.206(Ra - Ra_c)^{0.318} \quad (9)$$

428 where Q is the ratio of internal to bottom heating Rayleigh numbers. An
429 upper boundary layer thickness (δ) can be derived from the ratio of ΔT_{top}
430 and Nu_{top} . Recalling that $\delta \sim u^{-1/2}$, this predicts that the upper boundary
431 velocity scales as

$$\frac{u}{U} = \left(\frac{0.5Q + 0.206(Ra - Ra_c)^{0.318}}{0.499 + 1.33Q^{3/4}Ra^{-1/4}} \right)^2 \quad (10)$$

432 where U is a scaling constant. The theory predicts that regions exist, within
433 Ra and Q space, over which increased internal heating leads to a decrease in
434 upper boundary layer velocity. This occurs despite the fact that surface heat
435 flux increases. The predictions were shown to be consistent with suites of
436 numerical convection experiments [Lenardic et al., 2020; Weller and Lenardic,
437 2016; Weller et al., 2016].

438 Figure 10a places the ideas above into a feedback context. As an exam-
439 ple sequence, consider an increase in upper boundary velocity. This lowers
440 internal temperature, via enhanced cooling, which increases the temperature
441 drop across the lower thermal boundary layer. That increases the velocity
442 of plumes that form from the boundary layer. The plumes interact with the
443 upper boundary layer and affect its velocity. That sequence applies to the in-
444 ner, positive feedback loop at the right of Figure 10a. The outer loop, which
445 connects to plume thickness, is a negative feedback. At very high degrees
446 of convective vigor plumes become very thin and can dissipate before they
447 can interact with the upper boundary layer. The other way a no boundary
448 layer interaction limit can be hit is if the temperature drop across the lower
449 boundary layer goes to zero, i.e., the pure internal heating limit. Before that
450 limit is hit, the feedbacks of Figure 10a allow upper boundary layer velocity
451 to decrease as the ratio of internal to basal heating increases.

452 Figure 10a applies to isoviscous convection. For application to the man-
453 tle, boundary layer feedbacks will connect to viscosity feedbacks. Figure

454 10b shows an example. The coupled feedbacks allow the effect of increased
455 radiogenic heating on lowering mantle viscosity to outweigh its effect on in-
456 creasing the internal to basal heating ratio. As such, plate velocities can
457 increase with increased radiogenic heating, in a mixed heating mantle, for
458 strongly temperature-dependent viscosity and weak plate margins [Lenardic
459 et al., 2020]. None the less, boundary layer feedbacks remain operative and
460 continue to affect plate velocity. The full trade-offs, between all the system
461 parameters that come into play, remain to be worked out, i.e., it is an avenue
462 for future research.

463 Boundary layer interactions relate to the potential influence of mantle
464 plumes on tectonic plates. The motion of tectonic plates has long been
465 connected to a low viscosity layer in the upper mantle, i.e., the asthenosphere.
466 The idea that the viscosity of the asthenosphere could be influenced by mantle
467 plumes was not originally considered as indicative of a mantle feedback but,
468 we will argue, it is part of a larger feedback loop between tectonic plates and
469 mantle plumes.

470 Figure 11a shows a conceptual model that attributes the Earth’s astheno-
471 sphere to a plume generated thermal inversion [Deffeyes, 1972]. Morgan et al.
472 [1995; 2013] expanded the model to include newer insights regarding plume
473 dynamics [Olson and Singer, 1985; Richards et al., 1989; Davies, 1990; Loper,
474 1991]. Figure 11b is from Morgan et al. [1995; 2013] with an addition high-
475 lighting the type of plumes required for a plume fed asthenosphere.

476 To create a low viscosity asthenosphere, plumes must be hotter than
477 the background mantle they rise through. Excess temperatures, inferred for
478 present-day mantle plumes, are roughly 200 degrees [Jellinek and Manga,
479 2004]. This implies a viscosity variation of two orders of magnitude between
480 plumes and the background mantle [Kohlstedt et al., 1995]. Under such con-
481 ditions, plume morphology is characterized by a large plume head and a thin
482 low viscosity tail that connects the plume to the basal thermal boundary
483 layer it originates from. The tail is associated with upwelling velocities sig-
484 nificantly greater than background flow [Loper and Stacy, 1983; Sleep, 2004;
485 Thayalan, 2006]. Plumes of that type are termed cavity plumes [Olson and
486 Singer, 1985].

487 Once a cavity plume head has risen and impacted the lithosphere, the
488 tail can remain in place as a low viscosity conduit that maintains a high flow
489 velocity and brings hot material from the core mantle boundary to the base
490 of plates with little thermal loss [Richards et al., 1989]. If the tail moved
491 slower, due to a viscosity value closer to that of the mantle, diffusion could

492 lower the thermal anomaly plumes could maintain at the base of plates.

493 A plume-fed, or plume-influenced, asthenosphere is an added means by
494 which the lower boundary layer of mantle convection (a plume source) can
495 influence the motion of tectonic plates. On its own, that does not constitute
496 a feedback processes. A feedback requires that plate motion, in turn, influ-
497 ences the lower boundary layer and plumes that originate from it. That link
498 connects to the existence of plumes with a viscosity significantly lower than
499 background mantle, i.e., to the existence of cavity plumes in the mantle.

500 Nataf [1981] first highlighted the difficulty of generating cavity plumes
501 in a mantle with temperature-dependent viscosity. Temperature-dependent
502 viscosity can lead to a stagnant lid mode of convection - an analog for a
503 single plate planet. In that mode, the upper boundary layer absorbs the
504 bulk of the total system viscosity contrast. As a result, mantle upwellings,
505 in a single plate mode, are expected to have nearly the same viscosity as
506 the mantle they rise through [Solomatov and Moresi, 2000; Labrosse, 2002].
507 Such thermals can not generate and maintain a low viscosity region below
508 plates.

509 The lack of cavity plumes, in stagnant lid convection, points toward the
510 need for plate subduction and associated mantle cooling [Lenardic and Kaula,
511 1994; Jellinek et al., 2002; Thayalan et al., 2006]. Figure 12a is from Robin
512 et al. [2007] who used numerical and laboratory experiments to show how
513 introducing overturn of the cold upper boundary layer, to a system that was
514 initially in a stagnant lid mode, could lead to a morphological change in man-
515 tle upwellings. During the transition, thermals and cavity plumes coexisted
516 in the experiments. As the system moved toward a statistically steady-state,
517 thermals were globally replaced by cavity plumes due to the large tempera-
518 ture, and associated viscosity, variation across the lower thermal boundary
519 layer. The numerical experiments included internal heating, as well as basal
520 heating, which prevented thermals from reaching the upper boundary layer.
521 Once cavity plumes formed they did reach the base of the upper thermal
522 boundary layer.

523 The link above completes a feedback loop that connects tectonic plates
524 to mantle plumes (Figure 12b). As well as isolating feedbacks, Figure 12b
525 provides pointers to research questions that contain *a priori* assumptions
526 about system dynamics that may not be correct and, as such, could lead to
527 blind alleys. For example: ‘Do mantle plumes initiate plate-tectonics?’; ‘Do
528 mantle plumes lead to an asthenosphere?’; ‘Is the lack of plate tectonics on
529 Venus due to the lack of an asthenosphere?’. The last question, as a specific

530 example, would be changed by an appreciation of a feedback cycle in which
531 the existence of an asthenosphere depends on plate tectonics and acts to
532 maintain plate tectonics.

533 The discussion above also provides an example of how linear cause and
534 effect thinking can influence the way observational data is interpreted. Ob-
535 servational data indicates that Venus lacks plate tectonics and lacks gravity-
536 topography signatures indicative of an asthenosphere [Kaula and Phillips,
537 1981; Kiefer et al., 1986]. From the earliest days of mapping Venus' topogra-
538 phy and gravity, and into the present day, the dominant interpretation has
539 been that this indicates that a lack of an asthenosphere leads to a lack of
540 plate tectonics on a terrestrial planet [Smrekar et al., 2007]. An equally valid
541 interpretation is that a lack of plate tectonics leads to the lack of an astheno-
542 sphere. A third, data consistent, interpretation is that plate-tectonics and
543 an asthenosphere are co-dependent components of a broader system. Our
544 intent is not to argue that the last interpretation is correct but to show how
545 an under-appreciation of feedbacks can limit the generation and exploration
546 of multiple working hypotheses [Chamberlin, 1897].

547 **5. Plate Tectonics-Mantle Dynamics Feedbacks and Bootstrap Hy-** 548 **potheses**

549 A thermal inversion leading to a low viscosity upper mantle, as per Fig-
550 ure 11, does not require mantle plumes. It can also be generated by a sub-
551 adiabatic thermal gradient [Stein and Hansen, 2008]. Several studies have
552 argued that a sub-adiabatic thermal gradient exists in the Earth's mantle
553 [Jeanloz and Morris, 1987; Lenardic and Kaula, 1994; Bunge et al., 2001;
554 Matyska and Yuen, 2001; Sleep, 2003; Bunge, 2005; Sinha and Butler, 2007;
555 Moore, 2008; Weller et al., 2016]. A consistent result is that increased inter-
556 nal heating favors a sub-adiabatic mantle, i.e., a hot upper mantle above a
557 cooler lower mantle. This allows a thermal inversion to be maintained with
558 increased internal heating even though that increase weakens the potential
559 of a plume-fed inversion (Figure 10).

560 Increased internal heating favors a sub-adiabatic mantle via an asym-
561 metry between upwelling and downwelling velocities. In a dominantly in-
562 ternally heated mantle, broad background upwelling balances concentrated
563 downwellings associated with subducting slabs. Slabs can deposit cold fluid
564 to the system base with little heating on descent. The slower moving, broad
565 upwelling can experience heating as it rises. As a result, the mantle interior

566 becomes sub-adiabatic [Jeanloz and Morris, 1987]. Mass balance suggests
567 that longer aspect ratio cells can enhance sub-adiabatic gradients. The area
568 of diffuse mantle upwelling increases with wavelength, which decreases its
569 velocity. As a result, heating of the upwelling as it rises tends to increase.
570 That prediction is consistent with numerical convection experiments [Höink
571 and Lenardic, 2008; 2010; Lenardic et al., 2019]. Figure 13a shows thermal
572 profiles from spherical geometry experiments. Figure 13b shows results from
573 Cartesian experiments that allowed for a systematic exploration of wave-
574 length effects by varying the lateral extent of the modeling domain.

575 The experiments of Figure 13 generated long wavelength flow by imposing
576 a high viscosity lower mantle. Experiments with temperature-dependent
577 viscosity showed that long wavelength flow could be maintained without an
578 imposed viscosity variation [Lenardic et al., 2019]. Figure 14a (top) shows an
579 example. The experiment has a temperature-dependent mantle viscosity and
580 a rheology that allows for the formation of near surface weak zones that are
581 analogs for plate margins [Moresi and Solomatov, 1998]. The weak margins
582 allow the otherwise high viscosity upper boundary layer, a plate analog, to
583 subduct and cool the interior mantle (an active lid mode of convection).
584 Also shown is a case that did not allow for the formation of plate margins,
585 i.e., a stagnant lid mode (Figure 14a, bottom). Internal viscosity variations
586 are shown at the left of each image. The active lid case lead to an upper
587 mantle with a viscosity that was significantly lower than the mid-mantle.
588 That variation resulted from a sub-adiabatic mantle and was dynamically
589 maintained by the active-lid mode of convection. In a stagnant-lid mode
590 (single plate planet), the lack of cold sinking slabs lead to a nearly uniform
591 internal temperature. As a result, internal viscosity variations were mild.

592 Experiments of the type in Figure 14a build off of Lowman et al. [2001]
593 and King et al. [2002] who proposed the existence of a hot mantle layer
594 below tectonic plates. Together with temperature-dependent viscosity, a hot
595 upper mantle can generate a low viscosity layer and flow channelization below
596 plates [Lenardic et al., 2019]. Channelization allows long-wavelength cells to
597 remain stable, as per the theoretical expectations of Busse et al. [2006]. Also
598 consistent with theory, flow channelization allows long wavelength cells to be
599 more efficient in cooling the interior than would be the case if mantle flow did
600 not channelize. The novel aspect, compared to experiments previously used
601 to test theoretical predictions [Lenardic et al. [2006], is that no imposed
602 increase in viscosity is required. Rather, depth-variable viscosity emerges
603 dynamically and contributes to long wavelength flow as well as be influenced

604 by long wavelength flow. An added effect relates to the maintenance of weak
605 plate margins.

606 Figure 14b plots results from two experimental suites with different val-
607 ues of a convective stress level required to generate weak plate boundary
608 zones. If plate margins can be created under any level of convective veloci-
609 ties, then wavelength effects on velocity will not feed into the generation of
610 plate margins (the low margin strength suite of Figure 14b). If plate margins
611 require a critical kinetic energy level, which relates to available work, then
612 flow wavelengths associated with greater convective velocities will favor the
613 generation of plate margins (the medium margin strength suite of Figure
614 14b). The specific tradeoffs between flow wavelength and margin generation
615 will depend on the particular rheology used to model plate margin processes
616 [Bercovici, 2015; Crowley and O’Connell, 2012]. However, the general results
617 of Figure 14b only require that a critical condition on available convective
618 work exists and that increased wavelength can lead to increased convective
619 velocities.

620 Figure 15a shows a loop diagram for the feedbacks of this section. The
621 feedbacks lead to the hypothesis that subduction generates a sub-adiabatic
622 mantle and an associated increase of viscosity with depth. As a result, a low
623 viscosity layer forms in the upper mantle which leads to flow channelization.
624 Channelization feeds into generating long wavelength mantle flow and plate
625 margins. Both stabilize plate tectonics. Plates, an asthenosphere, and a
626 long wavelength component of mantle flow all depend on each other and are
627 critical to the existence of each other. Hypotheses of that type are referred
628 to as bootstrap hypotheses as they argue that no critical entity, for the
629 particular aspect of nature a hypothesis is applied to, can exist independent
630 of other entities, i.e., there are no ‘fundamental entities’ that the system can
631 be reduced to [Chew, 1968; Cahill and Klinger, 2005; Kazansky, 2004; 2010].

632 Starting a self-sustaining system, whose operative entities are all co-
633 dependent, can seem as difficult as pulling oneself up by ones own bootstraps.
634 A well known example is that in order to boot up a computer, computer soft-
635 ware must be loaded and initiated by computer software. When operational,
636 the system is self-sustaining but the operational loops that allow for that need
637 to be activated. To start a computer, a small amount of relatively simple
638 code is needed to progressively load more complex code until the computer
639 becomes self-operational. Once functioning, the boot up code is no longer
640 needed and its presence does not show up in the system operation. The
641 connection to plate tectonics will be taken up in the next section.

642 **6. Discussion and Conclusion**

643 The theory of plate tectonics, as formulated, is a kinematic one [McKenzie
644 and Parker, 1967; Morgan, 1968; LePichon, 1968]. Extending it to a dynamic
645 theory became a research avenue soon after the plate tectonics revolution and
646 it remains so to this day [Cox, 1973; Coltice et al., 2017; Hawkesworth and
647 Brown, 2018]. In efforts to extend plate tectonics, there are statements along
648 the lines of “plate tectonics is due to water induced rock-weakening”, “plate
649 tectonics is due to a rheology that allows for weak plate margins”, “plate
650 tectonics is due to the presence of an asthenosphere”, “plate tectonics is
651 triggered by continental spreading”, “mantle plume initiate plate tectonics”,
652 “impacts initiate plate tectonics”. An even handed referencing, of hypotheses
653 along those lines, would fill pages and our intent is to single out a common-
654 ality rather than particulars. The shared underpinning is the idea that there
655 are some key factors that allow for plate tectonics - if a planet has those fac-
656 tors, then plate tectonics will follow. Tracking down the causal factors is one
657 research avenue for addressing the question of what allows a planet to have
658 plate tectonics. The existence of planetary feedbacks leads to an alternate
659 way of framing the problem.

660 If the factors that allow for plate tectonics owe their existence to plate
661 tectonics, then the solid Earth system cannot be broken down to causal
662 chains. It needs to be approached from the standpoint of self-sustaining
663 feedbacks and reciprocal causality. Figure 15b encapsulates that framework
664 with a loop diagram that connects all the feedbacks previously discussed. A
665 feedback framework does not imply that certain conditions are not required
666 for the potential of plate tectonics: A planet must have sufficient internal
667 energy to allow for surface deformation, the strength of rock can not be such
668 that failure, and associated generation of plate margins, could not occur
669 under any level of internal energy. A feedback framework does, however,
670 lead to the conclusion that a planet can have all the “necessary conditions”
671 and not have plate tectonics. The added requirement is that internal feedback
672 loops become operative and stable.

673 The phrase “booting up plate tectonics” relates to the conjecture that
674 plate tectonics is defined by internal feedbacks that, once operational, lead
675 to the formation of non-separable system components [Lenardic et al., 2019].
676 Under this conjecture, plate tectonics involves the co-arising of critical sys-
677 tem factors (one factor does not cause another - they emerge collectively
678 with the links between them). Co-arising is not spontaneous but, from a

679 practical standpoint, it can refer to situations in which functional elements
680 that emerge coincide, within relatively narrow time windows, with the co-
681 emergence of factors that are critical for the maintenance of the elements
682 themselves [Chiatti, 2012]. From an observational standpoint, co-arising can
683 lead to a rethinking of what is meant by ‘the origin of plate tectonics’. The
684 feedback loops of Figure 15b can be activated by a number of factors includ-
685 ing internal fluctuations associated with chaotic convection in the mantle -
686 fluctuations that, for all observational intent and purpose, would need to
687 be viewed as stochastic [Weller et al., 2015; Wong and Solomatov, 2016;
688 Lenardic et al., 2016]. Once the self-sustaining process is booted up, its
689 operation can erase evidence of the boot up itself and what is left, observa-
690 tionally, is the workings of the self-sustaining process. The dynamics of the
691 feedback loops can be studied at various levels of detail as can the factors
692 that are required for their stability. Questions of “origin”, on the other hand,
693 require reconsideration.

694 A rethinking of origins for self-sustaining feedbacks, particularly in light
695 of observational limits, is a common theme in the study of emergent phe-
696 nomena [Holland, 1998; Fromm, 2004]. One can hear it stated that plate
697 tectonics is an emergent phenomena or the closely related statement that
698 plate tectonics is a self-organized system [Anderson, 2002; Morowitz, 2002].
699 Statements of that sort, and associated discussions, are often presented in a
700 metaphorical form with no mention of feedback. If we ask ‘what is it that
701 emerges’ and the answer is ‘plate tectonics’ then we run the risk of falling
702 into regress. To avoid that pitfall, we need to be clear about what exactly
703 emerges in phenomena we choose to label as emergent. We take the view
704 that what emerges is structure/pattern. That is, a set of relationships and
705 feedbacks resulting in functions with a level of continuity and the capability
706 to transform and/or maintain phenomena. The feedback functions are not
707 permanent but can operate over extend time frames such that a phenomena
708 can remain stable over a related time frame. What emerges is not a thing,
709 or a state, but a process [Bridgman, 1943]. If we apply this to plate tec-
710 tonics, then a research avenue is to isolate operative feedback functions and
711 determine their stability. Only then can we can ask how feedbacks could
712 be activated and we must remain open to the possibility that the operative
713 feedbacks could erase evidence of their initiation, i.e., multiple activation
714 scenarios will be viable.

715 Figure 15b is a step towards the above. A couple of things are worth call-
716 ing out. The first is system redundancies. Structural elements are maintained

717 by more than a single feedback loop. Those redundancies enhance system
718 stability. The value of redundancy can break a tendency toward looking for a
719 single cause for a structural element and highlight the value in isolating new
720 feedbacks, even if they feed into structures that can be maintained in other
721 ways. The second thing of note is the co-existence of negative and positive
722 feedbacks. In earth systems literature there tends to be a focus on isolating
723 negative feedbacks as they can regulate system conditions in favorable ways.
724 For example, a silicate-weathering feedback and/or a biology-albedo feedback
725 can regulate planetary surface temperature in ways that are conducive to life
726 [Walker et al., 1981; Watson and Lovelock, 1983]. Positive feedbacks, on the
727 other hand, are associated with amplifications and instabilities that lead to
728 system runaways. They can, however, be beneficial for the development of
729 structure and patterns that define emergent processes. Positive feedbacks
730 allow for time-scales needed for the emergence of co-depended elements that
731 can lead to new system structure(s). Negative feedbacks, which often oper-
732 ate on slower time scales, can then stabilize the emergent structure(s) [Levin,
733 2000]. We note this to make it clear that isolating new positive feedbacks, in
734 the plate tectonics system, does not necessarily lower the inferred stability
735 of plate tectonics. It could bolster the hypothesis that plate tectonics is an
736 emergent process.

737 To be clear, we can not, at this stage, say that plate tectonics is an emer-
738 gent process. It may be that the fundamental entities for the operation of
739 plate tectonics could be reduced to internal energy and lithosphere rheology
740 and a linear cause and effect theory for the origin of plate tectonics may
741 be viable. In that view plate tectonics may emerge in time but it is not
742 an emergent phenomena if we hold to the view that emergent phenomena
743 depend on feedback processes that maintain a particular structure. Not all
744 hold to that view and, as noted above, one can find discussions of emergent
745 plate tectonics that make no mention of feedbacks. However, if abandon the
746 view that internal feedbacks are a defining characteristics of emergent phe-
747 nomena, then anything that initiates at some point in time, or transforms in
748 some way, would be termed emergent and one could well wonder if we are
749 not wandering to tautology (i.e. what emerges is emergent).

750 At this stage, we hold to the view that the feedbacks of Figure 15b, and
751 the idea that plate tectonics depends on feedbacks, provide frameworks for
752 future research. A general research path is to isolate added internal planet
753 feedbacks and, as appropriate, connect them to surface feedbacks. This can
754 enhance an appreciation that tools developed for general feedback analysis

755 have utility for solid planet dynamics [Astrom and Murray, 2008]. A more
756 specific path relates to how different the evolution of planets that allow for
757 self-regulation is from planets that do not (Figure 3). This motivates a focus
758 on collecting new data constraints, and re-examining existing ones, with the
759 target of discriminating between the hypotheses that the Earth’s evolution
760 did or did not involve self regulation. Added research lines are to provide
761 constraints on the operative times scales of feedbacks and stability analysis
762 of individual loops in Figure 15b. A focus on feedback stability provides a
763 useful flip on the question of what maintains plate tectonics by posing the
764 question of what would be required to break the operation of plate tectonics.

765 The hypothesis of emergent plate tectonics provides for added research
766 avenues that extend into planetary science. If plate tectonics is emergent,
767 then it is possible that planets could experience episodes of subduction that
768 do not activate and stabilize feedback loops needed to maintain plate tec-
769 tonics. As the system is booting up, it is at its lowest state of resilience
770 and nascent plate tectonics could become unstable. As feedbacks become
771 operational, plate tectonics becomes more resilient. The implication is that
772 boot up cycles may or may not run to completion based on the particulars
773 of a planet’s evolution path during the boot up sequence and when, in a
774 planet’s geologic life time, boot up sequences are activated. Stated another
775 way, a planet can have the necessary factors for plate tectonics and still not
776 have plate tectonics based on historical contingencies affecting the formation
777 and stability of internal feedback loops. This connects the idea of emergent
778 plate tectonics to the hypothesis of bistable tectonics [Sleep, 2000; Tackley,
779 2000; Crowley and O’Connell, 2012; Weller and Lenardic, 2012; Lenardic
780 and Crowley, 2012; Lenardic et al., 2016].

781 Bistability allows different tectonic modes to exist under the same physi-
782 cal/chemical conditions and planetary age. Which mode is realized depends
783 on historical contingency (not to be confused with randomness [Bohm, 1957]).
784 The seeds of that idea go back to a model of subduction initiation - if multiple
785 stable modes can exist, then subduction initiation could require a large ampli-
786 tude perturbation to move from one attracting mode to another [McKenzie,
787 1977]. That initial shift away from one mode (e.g., a single plate planet) can
788 lead to the dynamic enhancement of the attractor for another mode (e.g.,
789 plate tectonics) via the formation of internal feedback loops. Before feed-
790 backs are stabilized, the tendency of the system will be to move back to a
791 single plate mode, i.e., the plate tectonic attractor may be weak. The activa-
792 tion of feedback loops can deepen the plate tectonic attracting well making

793 it progressively more stable. If the sequence runs to completion, then there
794 is a transition. If not, then the system falls back to the single plate mode.
795 There are two research lines that connect to observational support for the
796 ideas of the last two paragraphs. One connects to Earth history. The other
797 to forth coming planetary observations.

798 As laid out above, emergent plate tectonics allows for failed boot-up se-
799 quences in the Earth’s past. The idea that the Earth has experienced episodes
800 of ‘failed plate tectonics’ has recently been put forward [O’Neill et al., 2018].
801 A focus on collecting data to confirm or refute that idea could provide a
802 fruitful research path for understanding our own planets evolution and for
803 comparative planetology. Forth coming missions to Venus will provide for a
804 research line aimed at confirming or refuting the idea that localized subduc-
805 tion occurred in Venus’ past even though plate tectonics did not [Davaille
806 et al., 2017]. As well as testing the idea of failed boot-up sequences, this
807 could support the idea of planetary bistability. Forthcoming observations of
808 terrestrial exoplanets also have the potential to test that hypothesis as the
809 statistical distribution of planetary properties will be different if planets do
810 or do not allow for bistability [Bean et al., 2017; Checlair, 2019; Lenardic
811 and Seales, 2021]. Whatever the result, the range of potential solid planet
812 feedbacks laid out in this chapter highlight the value of feedback analysis for
813 a range of solid planet research problems. That serves as a conclusion and a
814 motivation for future work that connects feedback to mantle dynamics and
815 plate tectonics.

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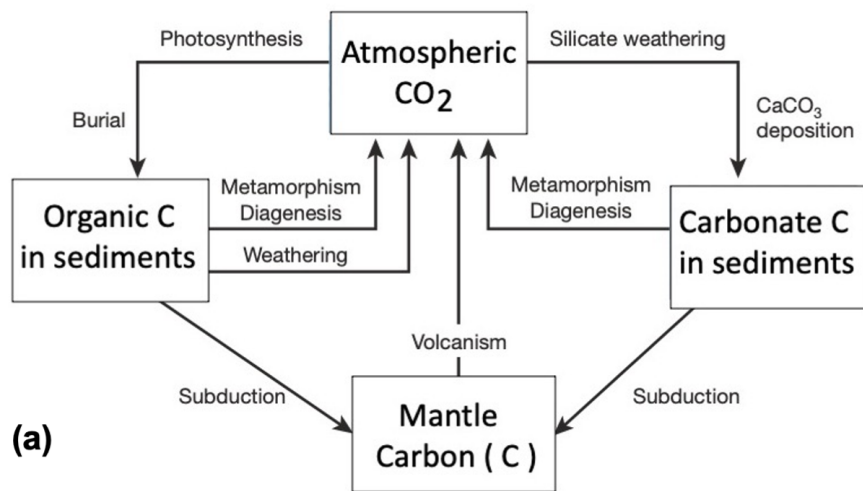
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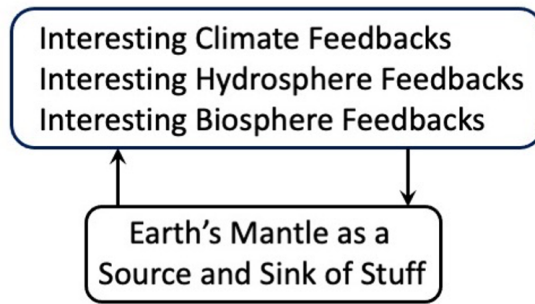
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1328 **Acknowledgements**

1329 We thank the editor for feedback.



(a)



(b)

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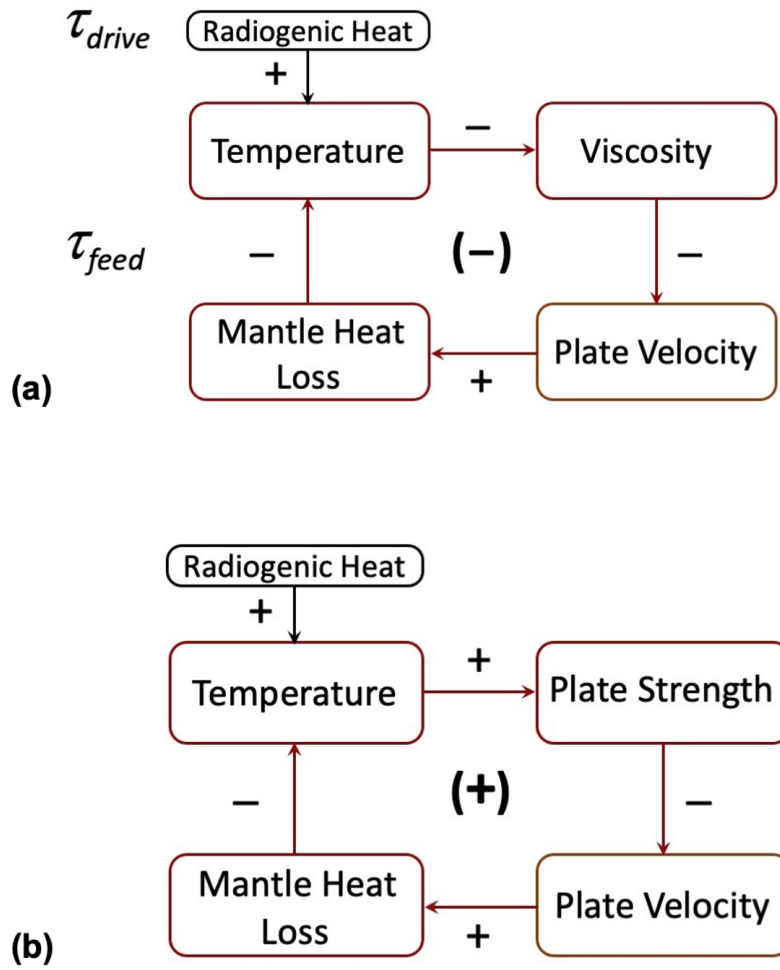


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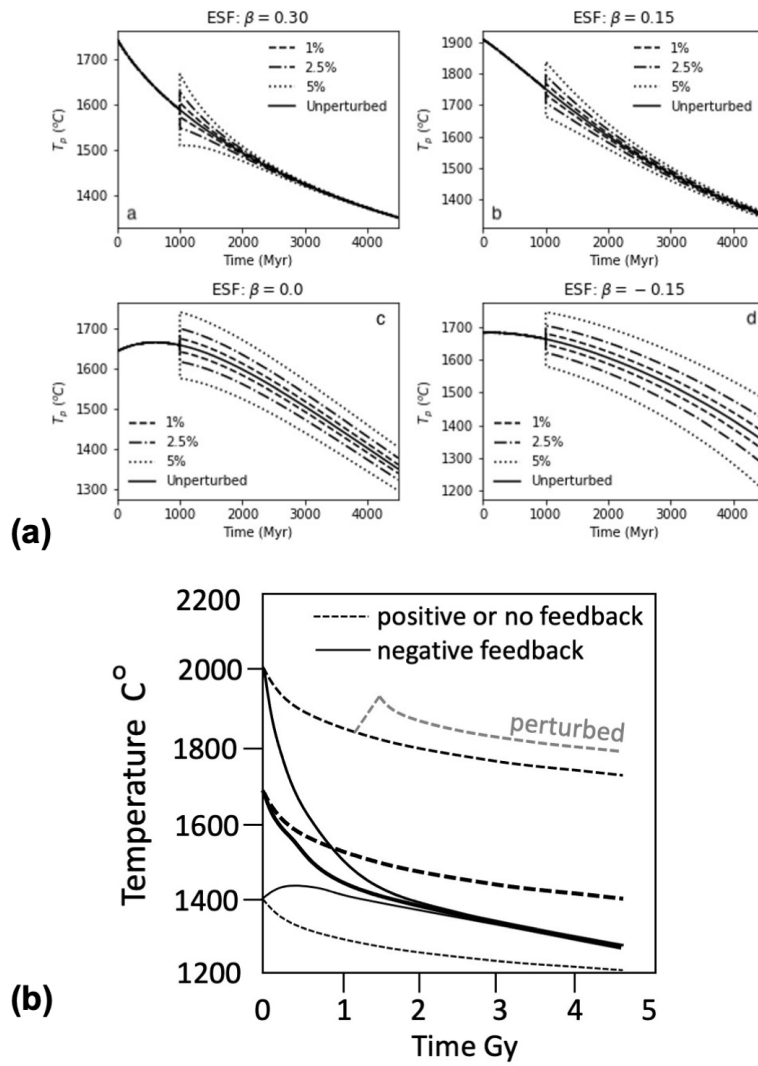


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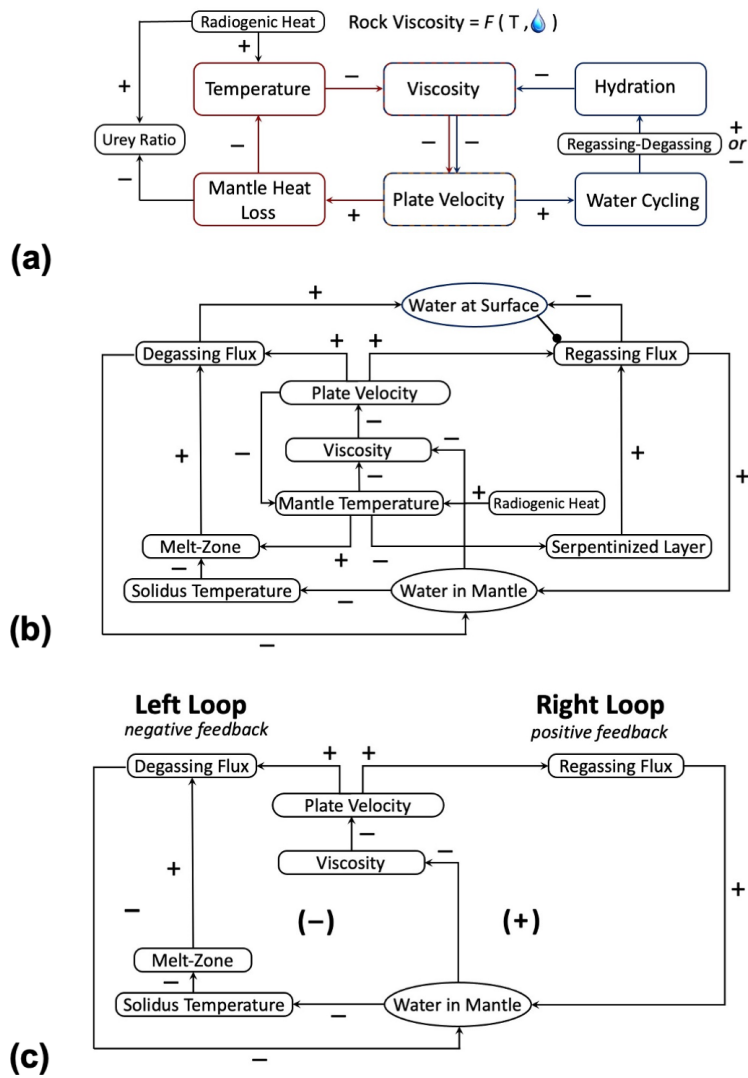


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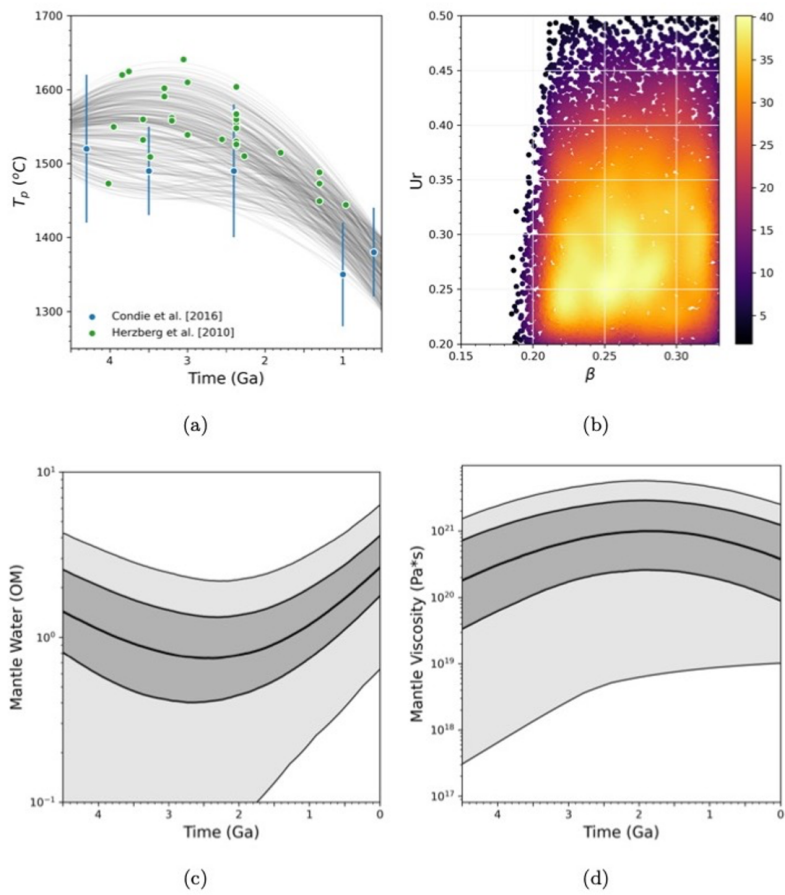


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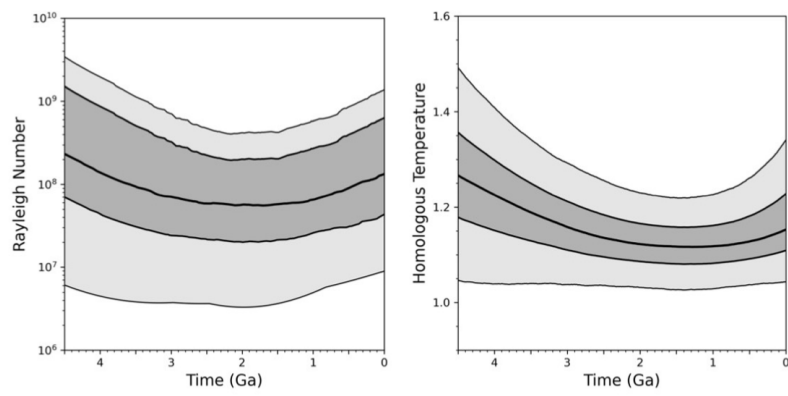


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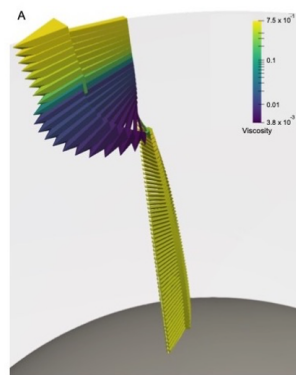
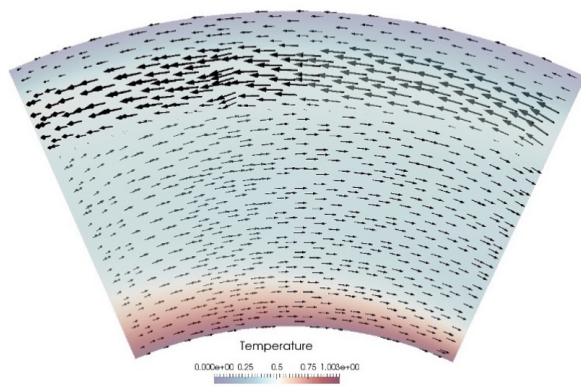


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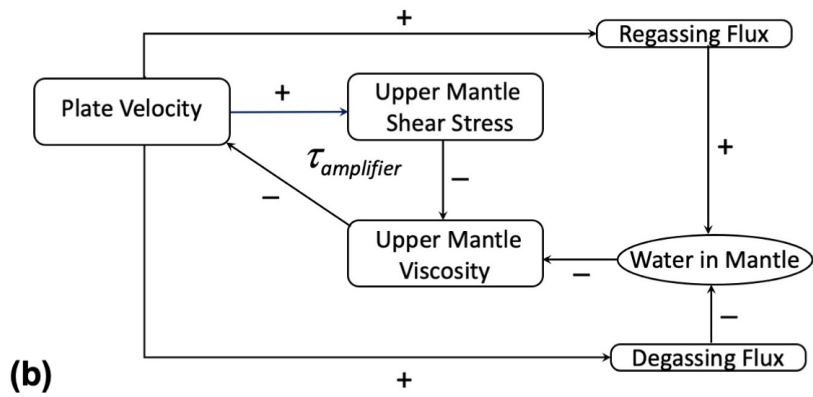
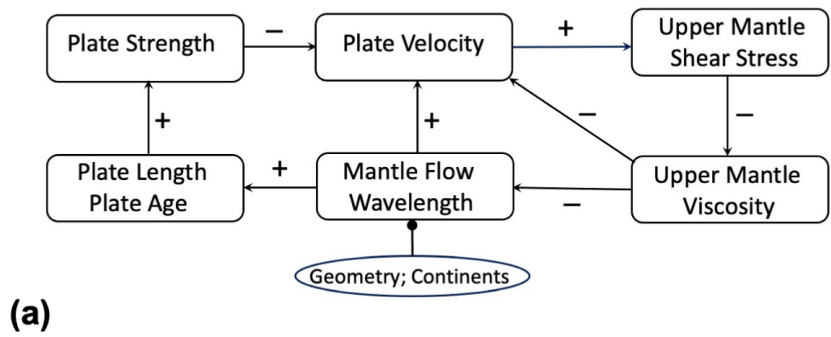
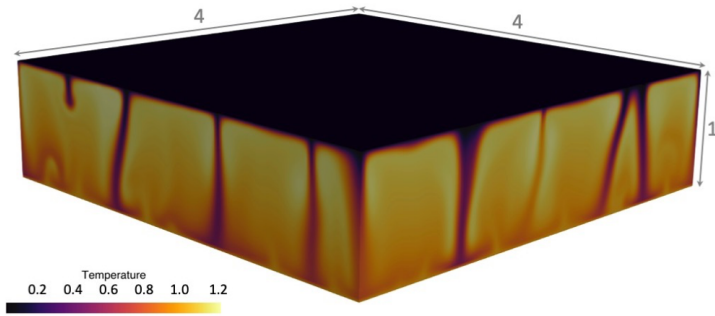
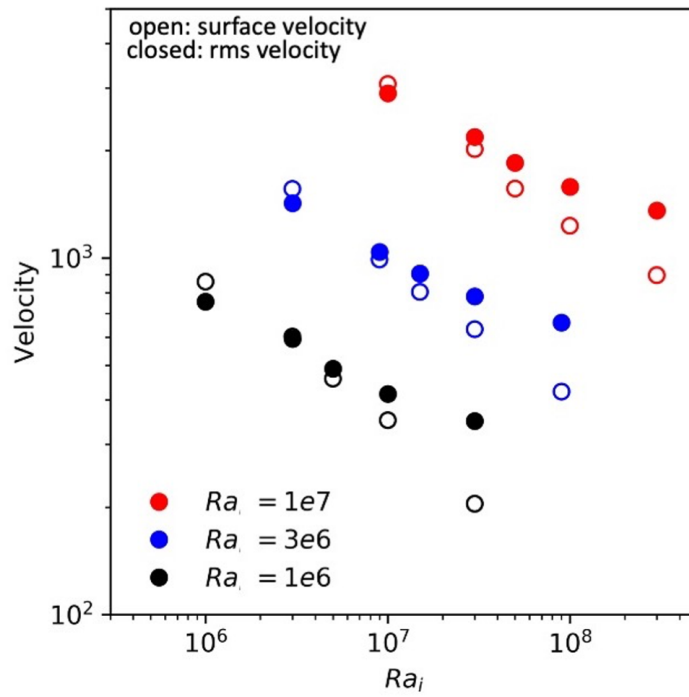


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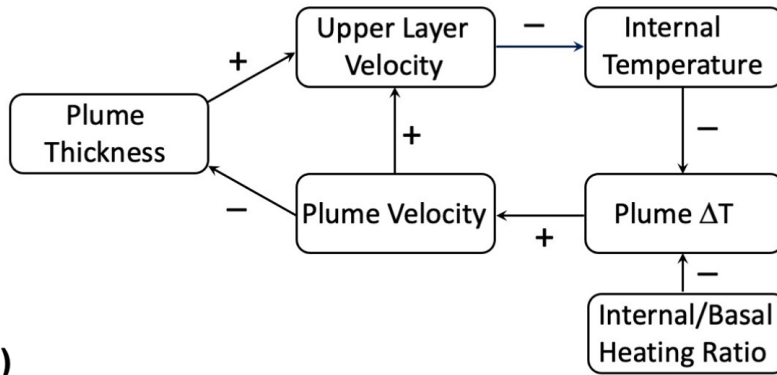


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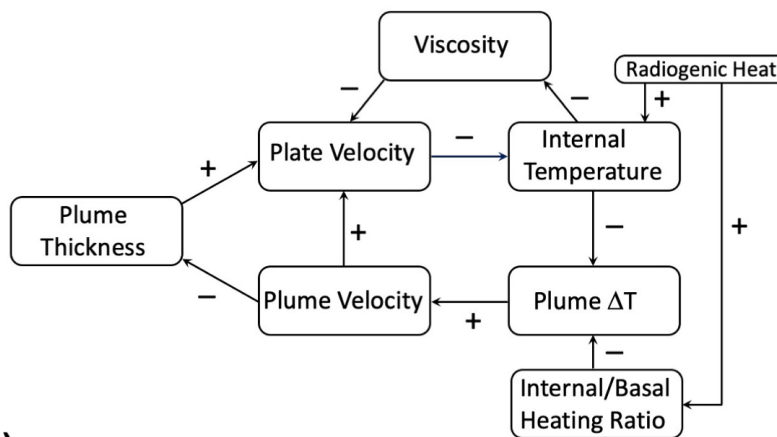


(b)

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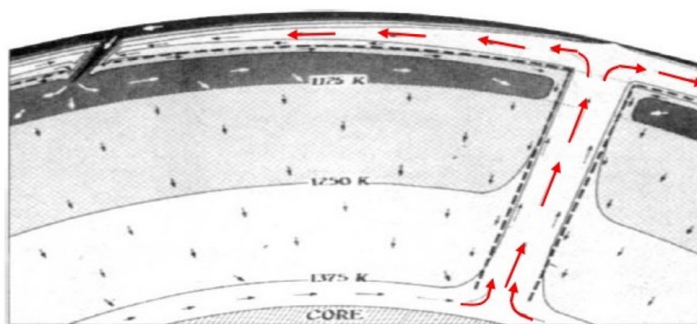


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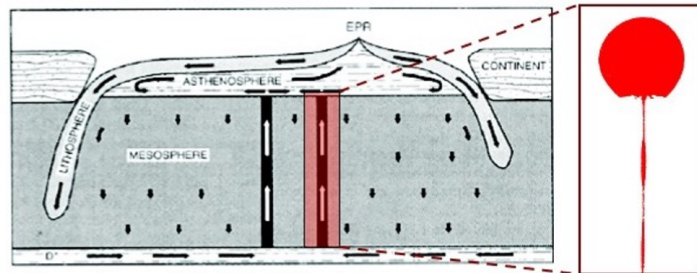


(b)

Figure 10:



after *Deffeyes, 1972*



after *Phipps-Morgan et al., 1995*

Cavity Plume

Figure 11:

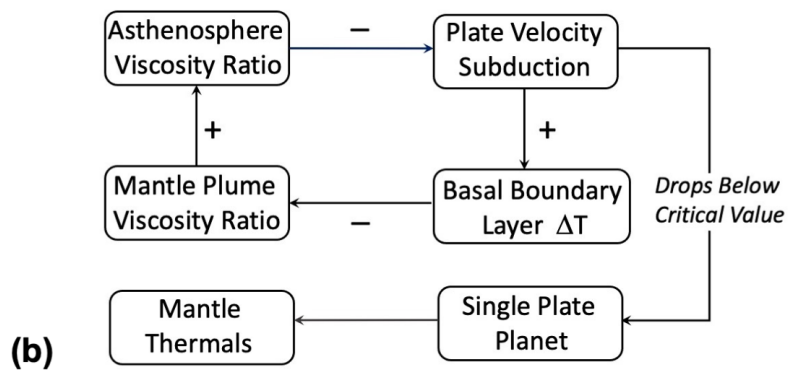
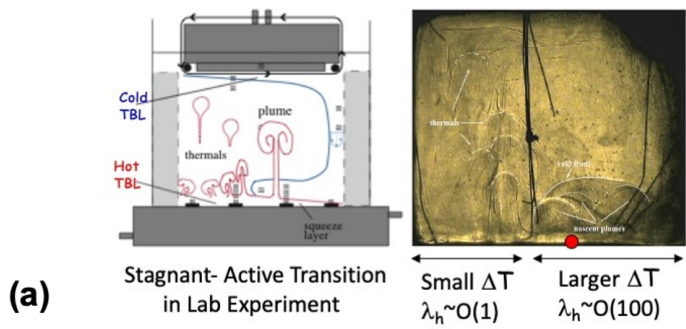
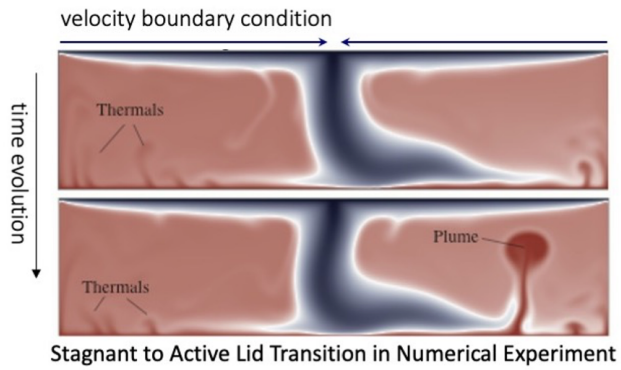


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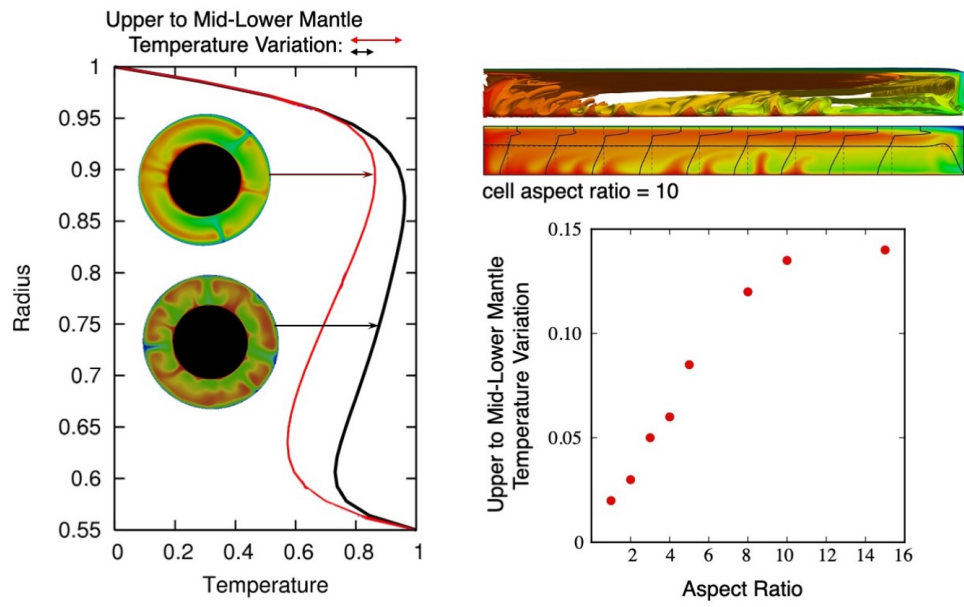


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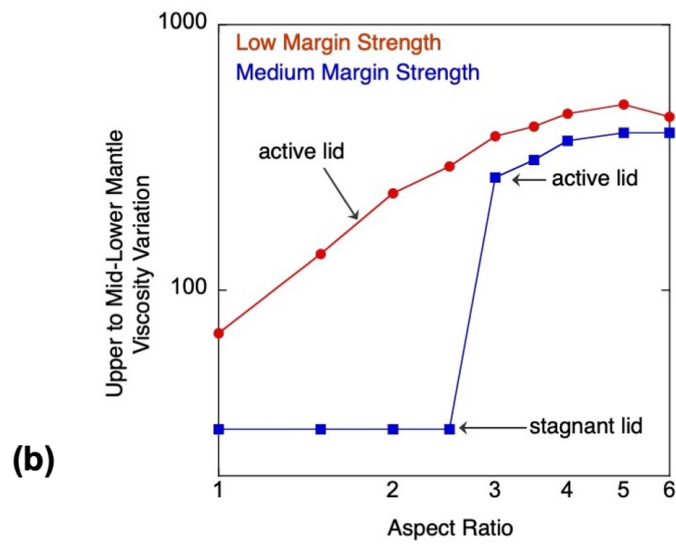
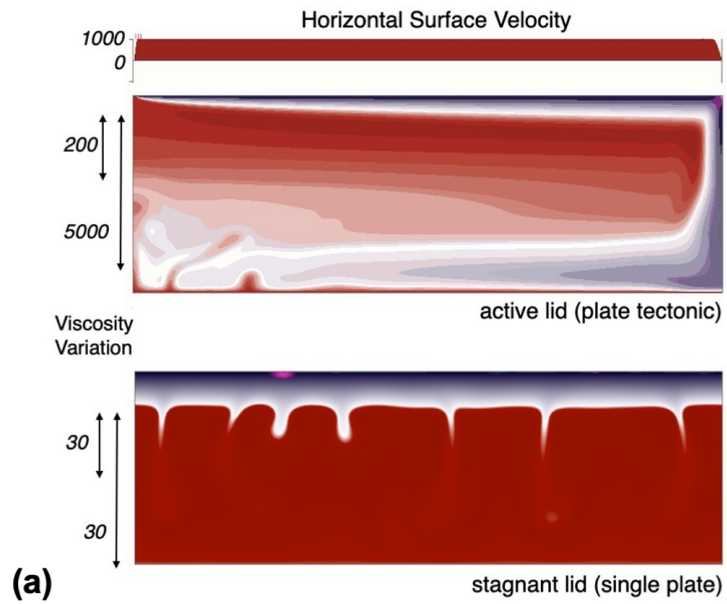


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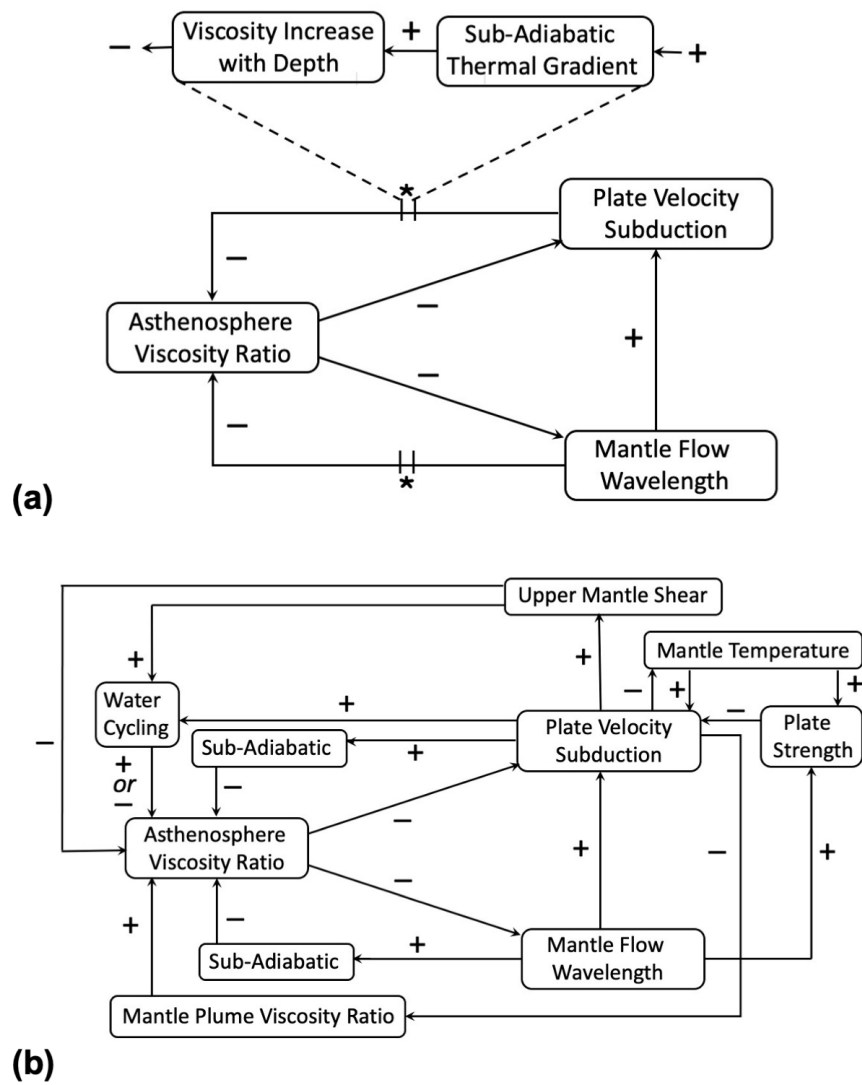


Figure 15:

1330 **Figure 1** (a) A diagram of the carbon cycle. (b) A schematic of how the
1331 Earth’s interior is often conceptualized in Earth systems science papers and
1332 text books.

1333 **Figure 2** (a) A causal loop diagram of the Tozer feedback. Arrows labelled
1334 positive indicate a direct dependence between linked factors. Arrows la-
1335 belled negative indicate an inverse dependence. The full feedback is negative
1336 and, as such, buffers/regulates mantle cooling. (b) A causal loop diagram
1337 of a positive feedback for mantle cooling. The feedback allows perturba-
1338 tions/fluctuations to be amplified and the effects of different initial conditions
1339 to be very long lived.

1340 **Figure 3** (a) Results from reactance time analysis for a number of thermal
1341 history models [Seales et al., 2019]. The analysis applies variable amplitude
1342 perturbations to thermal history paths and tracks perturbation decay. The
1343 slower the decay, the longer the reaction time of a model. Models with long
1344 reactions times have large structural uncertainties and the potential of being
1345 structurally unstable [Guckenheimer and Holmes, 1983]. That is, small fluc-
1346 tuations, that would result from physical factors not included in the models,
1347 would have long lived effects on model prediction (e.g., the effects of planetary
1348 impacts over the first billion years of Earth history could effect model predic-
1349 tions for the Earth’s present day thermal conditions and, given the stochastic
1350 nature of impact histories, this leads to large model structural uncertainties).
1351 (b) A diagram of the qualitative difference between thermal history models
1352 that allow for self-regulation, via negative planetary feedbacks, versus models
1353 that do not.

1354 **Figure 4** (a) A simplified feedback loop diagram that highlights how coupled
1355 thermal and deep-water cycling can influence mantle cooling and the mantle
1356 Urey ratio. (b) A full feedback loop diagram of the coupled thermal and deep-
1357 water cycling system. The new symbol that appears between the surface
1358 water and regassing boxes is a limiter. If an the value of an element at
1359 the base of a limiter drops to zero then the element at the head of the
1360 limiter symbol, at the filled circle, can not be operative. (c) An loop diagram
1361 that isolates the water cycle component of the full thermal and deep-water
1362 cycling system. The existence of two feedback loops allows the ratio of mantle
1363 regassing to degassing to vary over system evolution, which feeds into the
1364 evolution of a mantle Urey ratio (Figure 4a).

1365 **Figure 5** (a) Mantle cooling trajectories consistent with petrological con-

1366 straints. (b) Successful Ur - β parameter space colored by relative point den-
1367 sity with higher values meaning the density of successful models is larger.
1368 (c) Evolution of mantle water content and (d) mantle viscosity from suc-
1369 cessful models, shown as distributions about their median values. The dark
1370 gray highlights values falling between the upper and lower quartiles and the
1371 lighter gray constraining the maximal and minimal limits.

1372 **Figure 6** Evolution of the mantle Rayleigh number (a) and a homologous
1373 temperature (b) from the models of Figure 5.

1374 **Figure 7** (left) A slice through a 3-D spherical mantle convection model with
1375 a non-Newtonian upper mantle. Velocity arrows are plotted over the model
1376 thermal field. (right) A depth profile of velocity from a full 3-D model. The
1377 profile is from the central region of a model plate and shows velocity arrows
1378 over a color plot of mantle viscosities. A low viscosity upper mantle results
1379 from mantle shear, driven by surface plate motion, together with a non-
1380 Newtonian rheology. The plots show that upper mantle flow channelizes into
1381 the low-viscosity region below plates. Convection remains of whole mantle
1382 type but upper mantle velocity is significantly greater than lower mantle
1383 velocity.

1384 **Figure 8** (a) A feedback loop diagram of a non-Newtonian upper mantle
1385 viscosity feedback process that links tectonic plate velocities, depth-variable
1386 mantle viscosity, and the wavelength of mantle flow. The right two loops are
1387 both positive feedbacks that can increase mantle flow wavelength towards a
1388 high-end limit that will be set by the geometric extent of the mantle and/or
1389 by the distribution of continents . The left loop is a negative feedback that
1390 can limit mantle flow wavelength via a feedback on plate velocity. (b) A loop
1391 diagram showing how a non-Newtonian upper mantle viscosity feedback can
1392 act as an amplifier for a mantle water-cycling feedback.

1393 **Figure 9** (a) Thermal field from a numerical mantle convection experiment
1394 driven by a combination of internal and basal heating. (b) Velocity results
1395 from a suite of numerical experiments of the type shown in Figure 9a. The
1396 experiments show that surface velocities and rms interior velocities can de-
1397 crease with increased internal heating, i.e., with an increase in the internal
1398 heating Rayleigh number (Ra_i).

1399 **Figure 10** (a) A feedback loop diagram of boundary layer interactions in a
1400 convecting layer driven by internal and basal heating. (b) A feedback loop
1401 diagram of mantle plume and tectonic plate interactions.

1402 **Figure 11** Cartoons depicting conceptual models of how mantle plumes can
1403 potentially generate and maintain the Earth's asthenosphere.

1404 **Figure 12** (a) Numerical (upper) and lab tank (lower) experiments showing
1405 how plate subduction can alter the morphology of mantle plumes. (b) A feed-
1406 back loop diagram of an internal mantle feedback that links tectonic plates,
1407 mantle plumes, and an asthenosphere. The plume viscosity ratio is mantle
1408 plume viscosity divided by background mantle viscosity. The asthenosphere
1409 viscosity ratio is asthenosphere viscosity divided by background mantle vis-
1410 cosity. Both viscosity ratios are assumed to always be less than or equal to
1411 unity.

1412 **Figure 13** (a) Temperature profiles from numerical experiments, along with
1413 temperature slices from the experiments shown as inset images. One exper-
1414 iment assumes an isoviscous mantle and leads to relative short wavelength
1415 convection and a mildly sub-adiabatic mantle. The other impose a factor
1416 of thirty viscosity increase from the upper to the lower mantle and leads to
1417 longer wavelength flow and a steeper sub-adiabatic mantle thermal gradient.
1418 (b) Thermal field from a numerical convection experiment (top) and a plot of
1419 temperature variations from the upper to the mid lower mantle as a function
1420 of cell wavelength from a suite of experiments (bottom).

1421 **Figure 14** (a) Thermal fields for numerical experiments with a six order
1422 of magnitude, temperature-dependent viscosity variation from the hottest to
1423 the coldest system temperature and a rheology that allows for the formation
1424 of weak plate margins. The top experiment had a yield condition that allowed
1425 for weak plate margins and associated plate like behavior, as reflected in the
1426 surface velocity plot. The bottom experiment had a higher yield condition
1427 and plate margins did not form. (b) Internal viscosity variations versus
1428 convective cell aspect ratio from two experimental suites.

1429 **Figure 15** (a) A feedback loop diagram that links plate subduction, a sub-
1430 adiabatic mantle, increasing mantle viscosity with depth, and mantle flow
1431 wavelength. (b) A causal loop diagram that links all of the feedbacks dis-
1432 cussed in this chapter.