

15 **Fluid-driven transport of round sediment particles:**
16 **from discrete simulations to continuum modeling**

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24 **Key Points:**

- 25 • Resolved particle-scale bedload transport simulations agree with flume experiments.
26 • Simulations probe the small-scale mechanisms and parameter dependences in the
27 transport relation.
28 • Particle simulations guide continuum model development for turbulent sediment
29 transport and bed creep.

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Abstract

Bedload sediment transport is ubiquitous in shaping natural and engineered landscapes, but the variability in the relation between sediment flux and driving factors is not well understood. At a given Shields number, the observed dimensionless transport rate can vary over a range in controlled systems and up to several orders of magnitude in natural streams. Here we (1) experimentally validate a resolved fluid-grain numerical scheme (Lattice Boltzmann Method - Discrete Element Method or DEM-LBM), and use it to (2) explore the parameter space controlling sediment transport in simple systems. Wide wall-free simulations show the dimensionless transport rate is not influenced by the slope, fluid depth, mean particle size, particle surface friction, or grain-grain damping for gentle slopes ($0.01 \sim 0.03$) at a medium to high fixed Shields number. (3) Examination of small-scale fluid-grain interactions shows fluid torque is non-negligible for the entrainment and sediment transport near the threshold. And (4) the simulations guide the formulation of continuum models for the transport process. We present an upscaled two-phase continuum model for grains in a turbulent fluid and validate it against bedload transport DEM-LBM simulations. To model the creeping granular flow under the bed surface, we use an extension of the Nonlocal Granular Fluidity (NGF) model, which was previously shown to account for flow cooperativity from grain-size-effects in dry media. The model accurately predicts the exponentially decaying velocity profile deeper into the bed.

Plain Language Summary

Sediment transport caused by particles rolling, sliding, and hopping on a river bed is called bedload transport. Semi-empirical formulas to predict bedload sediment flux from the driving factors, known as the transport relation, can be highly inaccurate. This paper uses simulations where the sediment particles are fully resolved to examine the particle parameters to find if the predictions can be improved by considering more parameters. After validating the numerical scheme against flume experiments, it is used to simulate bedload transport under many conditions, and its results show that at a fixed relative bed shear stress, varying river slope (on gentle slopes), fluid depth, mean particle size, particle surface sliding friction coefficient, and grain-grain damping coefficient cause almost no variation of the transport rate. We examine how the fluid torque on particles helps initiate rolling and subsequent grain transport. We further use the numerical scheme to guide development of a continuum framework that can predict the flow profiles in the rapid zone as well as the creep flow beneath the bed surface. The continuum approach is a more tractable way to model large-scale bedload sediment transport problems.

1 Bedload transport of spherical grains

Fluid-driven sediment transport, in which a flow passing over a loose granular bed entrains and moves the grains, plays a pivotal role in many natural and engineered landscapes. Common scenarios that require the calculation of sediment transport rates include conveyance of sediment through engineered channels, infilling of artificial reservoirs, dispersal of stored sediment following dam removal, and long-term sediment transport that shapes natural rivers (Gomez, 1991; Yalin & da Silva, 2001). Applications like these create a demand for sediment transport models that can be applied over a wide range of flow conditions and sediment characteristics.

However, calculation of sediment transport rates over a wide range of conditions is a challenging task. Sediment transport at the scale of a river channel depends on the fine-scale interaction of a turbulent flow with many individual sediment grains. Moreover, variations in these fluid-grain interactions through time, or with height above or below the sediment bed, can create different regimes of grain motion (Houssais et al.,

Table 1. Widely used bedload transport relations.

Author(s)	Dimensionless transport rate q^*	Critical Shields # τ_c^*
Meyer-Peter and Müller (1948)	$q^* = 8(\tau^* - \tau_c^*)^{3/2}$	$\tau_c^* = 0.047$
Ashida and Michiue (1973)	$q^* = 17(\tau^* - \tau_c^*)(\sqrt{\tau^*} - \sqrt{\tau_c^*})$	$\tau_c^* = 0.05$
Engelund and Fredsøe (1976)	$q^* = 18.74(\tau^* - \tau_c^*)(\sqrt{\tau^*} - 0.7\sqrt{\tau_c^*})$	$\tau_c^* = 0.05$
Fernandez-Luque and Van Beek (1976)	$q^* = 5.7(\tau^* - \tau_c^*)^{3/2}$	$\tau_c^* = 0.037 \sim 0.0455$
Wong (2003)	$q^* = 3.97(\tau^* - \tau_c^*)^{3/2}$	$\tau_c^* = 0.0495$

2015), including creep of closely packed grains, a rapidly shearing slurry, or a dilute sus-
pension.

Bedload sediment flux, in which grains move by rolling, sliding or hopping along the bed, is practically described by field-scale sediment transport models which are typically derived semi-empirically by comparing the bulk characteristics of flows, such as average bed shear stress, with observations of bulk sediment transport rates from laboratory flume experiments (Meyer-Peter & Müller, 1948; Ashida & Michiue, 1973; Fernandez-Luque & Van Beek, 1976; Wiberg & Smith, 1989; Wong, 2003). Less commonly, field monitoring studies are used (Bagnold, 1980; Gomez, 1991). Some widely used bedload transport relations are listed in Table 1, where the dimensionless sediment transport rate (the Einstein number) is

$$q^* \equiv q_s / \left(d_p \sqrt{\frac{\rho_s - \rho_f}{\rho_f} g d_p} \right), \quad (1)$$

with q_s the sediment volume flux per unit flow width, d_p the grain diameter, and ρ_s and ρ_f the sediment and fluid densities. The dimensionless bed shear stress, often referred to as the Shields number, is

$$\tau^* \equiv \tau_b / [(\rho_s - \rho_f) g d_p], \quad (2)$$

with τ_b the bed shear stress and g the gravitational acceleration. Most bedload transport relations have a critical value of the Shields number τ_c^* at which grains begin to move (Shields, 1936), and most converge to a power law of 3/2 for $\tau^* \gg \tau_c^*$, but differ if τ^* is close to the threshold of grain motion (Lajeunesse et al., 2010). Recently, Pächtz and Durán (2020) proposed a formula in which q^* scales with $\tau^* - \tau_c^*$ linearly for $\tau^* \rightarrow \tau_c^*$ and quadratically for $\tau^* \gg \tau_c^*$ through numerical simulations, indicating the 3/2 power law may be an approximation between these two ends.

These semi-empirical models have the desirable characteristic that they are easy to apply in natural and experimental settings, and they are therefore widely used. However, even under controlled laboratory conditions, empirical bedload transport expressions commonly over- or under-predict sediment flux by more than a factor of two (Lajeunesse et al., 2010); and larger disagreements in natural settings are common: Reid and Laronne (1995) compiled the data from 6 streams and found that q^* can vary by a factor of 10 across tests with τ^* fixed at $\tau^* = 0.02$ and more than 100 (up to 1000) when $\tau^* \sim 0.1$. Correction factors for q^* , τ^* and τ_c^* for steep slopes can be obtained from recent works (Maurin et al., 2018; Pächtz & Durán, 2020). However, the variability is evident even in sediment transport experiments on gentle slopes, such as Meyer-Peter and Müller (1948) in which the slope $S < 0.02$ and the above slope correction factors are close to 1. What is causing the variation in flux (q^*) for a given Shields number (τ^*) on gentle slopes? The empirical transport expressions are also remarkable for what they do not contain, such

113 as any dependence on sediment geometric or surface characteristics other than a repre-
 114 sentative grain diameter. There are reasons to expect that grain-scale phenomena influ-
 115 ence channel-scale sediment transport, but which grain-scale phenomena do we need to
 116 consider?

117 One way to address this question is to simulate the grain-scale mechanisms that
 118 entrain and transport sediment. Recent computational and methodological advances have
 119 made it feasible to numerically investigate the mutual interactions of many sediment grains
 120 and a turbulent flow, allowing for interrogation of transport phenomena at a level of de-
 121 tail that is difficult to achieve even in well-instrumented experiments. Simulations in which
 122 the sediment particles are treated as discrete elements can be classified into two types
 123 based on the way the fluid-particle interaction is handled: (1) the fluid grid size is much
 124 smaller than the particle size so that the fluid-particle interaction can be resolved (Derksen,
 125 2015). And (2) the fluid grid size is comparable to or larger than the particle size and
 126 the fluid-particle interaction is modeled by a drag (hydrodynamic force) law (Schmeeckle,
 127 2014, 2015), and potentially also a hydrodynamic torque model (Finn et al., 2016; Guan
 128 et al., 2021). Most of the simulations examining the sensitivity of the transport relation
 129 to the microscopic particle parameters adopt the second type for the higher computa-
 130 tional efficiency; e.g. recent studies (Maurin et al., 2015; Elghannay & Tafti, 2018; Pächtz
 131 & Durán, 2018b, 2018a) have found that the transport relation is insensitive to the par-
 132 ticle surface friction coefficient and the restitution coefficient. But these simulations do
 133 not include the hydrodynamic torque on particles, which may be important since rolling
 134 has lower threshold than sliding in entrainment events (Dey & Ali, 2017). The lack of
 135 fluid-particle angular momentum exchange may cause problems in the other direction
 136 as well: the rotation of a single sediment particle near the bed surface influences the fluid
 137 vortex structure nearby which in return changes the hydrodynamic forces (C. Zhang et
 138 al., 2017). Also, for grains near the bed surface where we would want the most accuracy,
 139 the separation of length scales presumed in a drag model might not be applicable due
 140 to the jump in volume fraction, which could render the drag model less accurate. These
 141 questions matter most for sediment transport close to τ_c^* . Laminar transport simulations
 142 (Derksen, 2011), which resolve the fluid-particle linear and angular momentum exchange,
 143 have shown that the rolling mode in the incipient motion requires nonzero surface fric-
 144 tion coefficient, but the specific value of the friction coefficient has only marginal influ-
 145 ence. But its effect is still not known in turbulent sediment transport. These consider-
 146 ations motivate revisiting the parameter space, especially the microscopic particle pa-
 147 rameters (such as the friction coefficient and the restitution coefficient), using turbulent
 148 sediment transport simulations which resolve the fluid-particle interaction at a sub-grain
 149 scale.

150 However, even if grain-resolving simulations give us all the answers, they are cur-
 151 rently impractical to implement at field scale (i.e. the scale of a river channel). So one
 152 option, as a complementary approach, would be to use them to help parameterize/validate
 153 a continuum model that could be scaled up more easily and captures the rheological be-
 154 havior of grains and fluid in different regions of the bed and the flow. As noted previ-
 155 ously, a given fluid stress can cause grains at different heights below or above the sed-
 156 iment bed to move in different granular flow regimes, ranging from a thick creeping layer
 157 to a dense slurry to a dilute suspension. Houssais et al. (2015) analyze the threshold of
 158 grain motion from this perspective, and show in a set of laboratory experiments that the
 159 transition from no motion to bedload transport as τ^* increases is a gradual transition
 160 (as opposed the discontinuous transition implicitly assumed by equations in Table 1) char-
 161 acterized by progressive quickening of granular creep throughout a layer that extends
 162 many grain diameters below the bed surface. They additionally propose a regime dia-
 163 gram for sediment transport in which the style of grain motion (creep, bedload, or di-
 164 lute) depends on the height relative to the bed surface and the transport stage, τ^*/τ_c^* .
 165 This alternate perspective on sediment transport implies that it may be possible to im-
 166 prove predictions of sediment flux by describing these granular regimes with appropri-

167 ately coupled rheological models rather than fitting a single function to experimental data
 168 over a range of $\tau^* - \tau_c^*$.

169 In this paper, in order to understand the variability of sediment flux (q^*) at a given
 170 Shields number (τ^*), we examine three questions: (i) How important is fluid-particle an-
 171 gular momentum transfer and in which part of the flow and in which regime of the sed-
 172 iment transport is it important? We fully resolve the grain-scale spherical particle move-
 173 ment and study the fluid-particle angular momentum exchange studied in an entrain-
 174 ment event. Then it is quantified as a “rotation stress” whose profile is examined in dif-
 175 ferent transport stages and further correlated to the transport relation. Our work here
 176 is benchmarked by flume experiments (Deal et al., 2021; Benavides et al., 2021) in which
 177 grain-scale motions were tracked. (ii) What is (not) responsible for the variability in the
 178 observed sediment transport relation? We explore the parameter space (macroscopic
 179 river settings such as slope, and most importantly microscopic particle parameters such
 180 as the mean size, surface roughness, and grain contact damping) to see what is respon-
 181 sible for the variability in the relation between the Einstein number and the Shields num-
 182 ber in turbulent sediment transport. (iii) How can we formulate a useful model broadly
 183 applicable at different scales across the range of bedload sediment transport behaviors?
 184 We use the DEM-LBM simulation data to derive continuum models of sediment trans-
 185 port that apply to a range of flow conditions and sediment characteristics. For simplic-
 186 ity, we will limit our investigation to the bedload sediment transport of mono-disperse
 187 particles without considering vegetation (Vargas-Luna et al., 2015; C. Liu et al., 2021),
 188 external agitation of the turbulence (Sumer et al., 2003; Ojha et al., 2019; Cheng et al.,
 189 2020), or channel morphology that is known to influence the transport relation, such as
 190 bedform patterns (Venditti, 2013; Venditti et al., 2017) or the presence of large (possi-
 191 bly not fully submerged) boulders (Yager et al., 2007).

192 2 Discrete simulations

193 A few geoscience-oriented studies have begun to probe the physics of grain-scale
 194 sediment motion through numerical experiments (Schmeeckle & Nelson, 2003; Schmeeckle,
 195 2014, 2015; Hill & Tan, 2017). Schmeeckle (2014) pioneered this approach in geomor-
 196 phology by coupling discrete element method (DEM) simulations of grain motion with
 197 large-eddy simulations (LES) of turbulent flow. He found that coherent flow structures
 198 impinging on the bed are a major cause of sediment entrainment, and he measured a power-
 199 law relationship between q^* and τ^* that is similar to (but somewhat steeper than) the
 200 widely used bedload transport expression (Wong & Parker, 2006; Meyer-Peter & Müller,
 201 1948). The LES-DEM approach employed by Schmeeckle (2014), a variant of the gen-
 202 eral CFD-DEM method (CFD: computational fluid dynamics) for the fluid and parti-
 203 cles, does not explicitly model flow around grains or particle-scale pressure variations (e.g.
 204 lubrication forces). Instead, the flow and grains are coupled with spatially averaged body
 205 forces. Nonetheless, his promising results suggest that direct simulations of sediment trans-
 206 port with tighter fluid-grain coupling will yield even more insight into the controls on
 207 bedload flux. In recent years, more researchers have studied sediment transport prob-
 208 lems using similar CFD-DEM simulations. For example, Hill and Tan (2017) studied the
 209 influence of the added fine particles on the mobilization of gravel beds using LES-DEM.
 210 Maurin et al. (2018) and Pächtz and Durán (2020) studied slope influence in sediment
 211 transport and have proposed slope corrections for q^* , τ^* and τ_c^* for steep slopes. Finn
 212 et al. (2016) simulated particle dynamics on wavy bottoms. Most recently, Guan et al.
 213 (2021) studied Kelvin–Helmholtz vortices’ influence on local and instantaneous bedload
 214 sediment transport with the same numerical method as Finn et al. (2016).

215 For sub-particle resolution of the fluid-grain interaction, the Lattice Boltzmann Method
 216 (LBM) (H. Chen et al., 1992) is able to resolve the fluid-particle interaction at the mov-
 217 ing particle boundaries (Boutt et al., 2007; Derksen, 2015; Amarsid et al., 2017) by treat-
 218 ing the fluid material as hypothetical fluid particles marching in space and colliding with

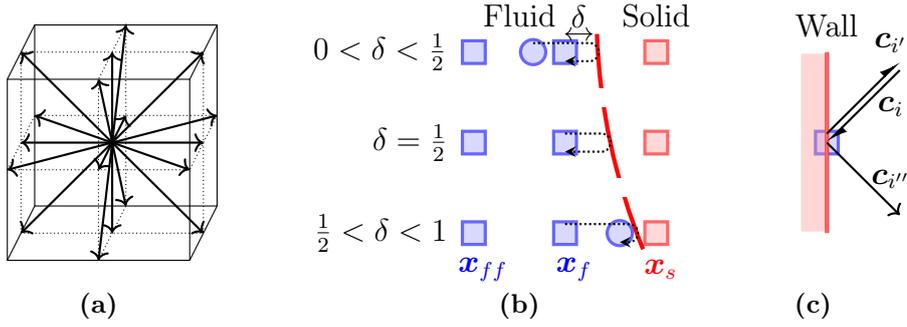


Figure 1. Lattice Boltzmann Method: (a) The velocity set of D3Q19: 18 velocities streaming out from the node to the next nearest nodes in the velocity directions and a rest velocity staying at the original node (b) Particle boundary treatment in LBM, depending on δ the distance from the last fluid node to the boundary in terms of lattice units. \mathbf{x}_f is the fluid node next to a solid node \mathbf{x}_s , and \mathbf{x}_{ff} is the neighbor fluid node upstream. (c) Related velocities near a stationary wall (the fluid node is aligned with the wall): the fluid parcel coming in \mathbf{c}_i will be bounced back into the opposite direction $\mathbf{c}_{i'}$ at a no-slip wall, and will be reflected specularly into $\mathbf{c}_{i''}$ at a free-slip wall.

219 the solid particle boundaries. Coupled DEM-LBM simulations can fully resolve the fluid-
 220 particle interaction in sediment transport problems and offer more understanding about
 221 the grain-scale mechanisms.

222 In the following discussion of the particle-scale simulations, we first introduce the
 223 DEM-LBM numerical method. Second, we present simulations matching the conditions
 224 of flume experiments (Deal et al., 2021; Benavides et al., 2021) to provide a relevant many-
 225 particle test of the methodology. Third, we present wide wall-free simulations in order
 226 to study the factors that can potentially cause the variability seen in experimental trans-
 227 port data on gentle slopes.

2.1 Method: DEM-LBM

229 The translation and rotation of the sediment particles in our DEM-LBM simula-
 230 tions are integrated from the equations of motion of individual particles using the Ve-
 231 locity Verlet method (Swope et al., 1982), which is widely used in DEM simulations of
 232 granular materials and is implemented in common software such as LAMMPS (Plimpton,
 233 1995) and LIGGGHTS (Kloss et al., 2012). The particle-particle interaction is elastic
 234 with damping effects in the normal direction, which can be simulated as a spring-dashpot
 235 model, and the interaction is elastic with friction in the tangential direction.

236 The DEM algorithm is fully coupled to a LBM solver, which can resolve the trac-
 237 tion over many moving boundaries (grain surfaces in our case). S. Chen and Doolen (1998)
 238 review the history of this numerical method, and Aidun and Clausen (2010) review the
 239 application of LBM to complex flows. Inspired by the Boltzmann-Maxwell Equation, LBM
 240 recovers the Navier-Stokes equations (H. Chen et al., 1992) by treating the fluid mate-
 241 rial as hypothetical fluid packets that collide and stream in a discrete set of directions.
 242 The method is particularly advantageous for solving problems with many moving bound-
 243 aries and the simple form makes implementation straightforward.

244 In a standard LBM algorithm, the domain is discretized into a uniform orthogo-
 245 nal grid. The fluid material exists in the 3D domain only on the nodes in a certain dis-
 246 cretized dimensionless velocity set $\{\mathbf{c}_i\}$. In this work, we choose a discretization com-

247 posed of 19 directions, known as D3Q19, as shown in Figure 1(a). The fluid material
 248 at a point is represented by “fluid parcels” streaming in 18 directions with magnitudes
 249 that move the parcels to the nearest node in the velocity direction through each LBM
 250 timestep (with the 19th parcel just resting at the original node). Each of the parcels cor-
 251 responds to a distribution function component f_i satisfying $\sum_{i=0}^{18} f_i = 1$. In a fluid timestep,
 252 as shown in Eq 3, the fluid undergoes a collision (right-hand side) and a streaming op-
 253 eration (left-hand side) sequentially:

$$\underbrace{f_i(\mathbf{x} + \mathbf{c}_i, t + 1) - f_i(\mathbf{x}, t)}_{\text{Streaming}} = \frac{1}{\tau} \underbrace{[f_i^{eq} - f_i]}_{\text{Collision}}, \quad (3)$$

254 where \mathbf{x} is the dimensionless position, τ is the dimensionless relaxation time and f_i^{eq}
 255 is the equilibrium distribution function. All the quantities are nondimensionalized by the
 256 grid size dx , LBM timestep dt_f , and ρ_f . In the collision operation, f_i^{eq} is a function of
 257 the macroscopic fluid velocity and density, and τ is a function of the local fluid kinematic
 258 viscosity ν (Yu et al., 2005):

$$\tau = \frac{1}{2} + \frac{3\nu}{dx^2/dt_f}. \quad (4)$$

259 For turbulent flow, a Large Eddy Simulation (LES) method (Yu et al., 2005) can model
 260 the subgrid-scale eddies. We use the Smagorinsky turbulent closure (Smagorinsky, 1963):

$$\nu = \nu_f + \nu_t, \quad \nu_t = (C_s \cdot dx)^2 \dot{\gamma}_f, \quad (5)$$

261 where ν_f is the kinematic viscosity of the pure fluid, ν_t is the turbulent viscosity, C_s Smagorin-
 262 sky constant, and $\dot{\gamma}_f$ the fluid local shear rate. C_s is shown to be dependent on the dis-
 263 cretization and geometry (Yoshizawa, 1993; Hou et al., 1994). We calibrate $C_s = 0.27$
 264 in the flume geometry (see Appendix A for details and for validation of the pure fluid
 265 simulations) with grid size $dx = 0.5\text{mm}$. The value of C_s and the grid spacing are used
 266 throughout this paper for the simulations in which the fluid is water. Body forces such
 267 as gravity can be taken into account by adding an extra term to the collision step (Z. Guo
 268 et al., 2002). More details on how to construct a macroscopic variable such as $\dot{\gamma}_f$ from
 269 the distribution $\{f_i\}$ can be found in (Yu et al., 2005).

270 For a post-collision distribution function component f_i^c at the fluid node \mathbf{x}_f next
 271 to a solid node \mathbf{x}_s , when the corresponding parcel hits a fixed solid boundary that sits
 272 in the middle of a link, it will bounce back and end up with the opposite direction $f_{i'}(\mathbf{x}_f, t +$
 273 $1) = f_i^c(\mathbf{x}_f, t)$, where $f_{i'}$ denotes the component in the opposite direction of f_i . As shown
 274 in Figure 1(b), when δ the distance from the last fluid node to the boundary is not ex-
 275 actly 0.5, the component $f_{i'}(\mathbf{x}_f, t + 1)$ can be interpolated (Bouzidi et al., 2001). For
 276 $0 < \delta < \frac{1}{2}$, the interpolation happens before the streaming

$$\begin{aligned} f_{i'}(\mathbf{x}_f, t + 1) &= f_i^c(\mathbf{x}_f + (2\delta - 1)\mathbf{c}_i, t) \\ &= 2\delta f_i^c(\mathbf{x}_f, t) + (1 - 2\delta) f_i^c(\mathbf{x}_{ff}, t), \end{aligned} \quad (6)$$

277 whereas for $\frac{1}{2} \leq \delta \leq 1$, interpolation happens after the streaming

$$\begin{aligned} f_{i'}(\mathbf{x}_f, t + 1) &= \frac{1}{2\delta} f_{i'}(\mathbf{x}_f + (2\delta - 1)\mathbf{c}_i, t + 1) + \frac{2\delta - 1}{2\delta} f_{i'}(\mathbf{x}_{ff}, t + 1) \\ &= \frac{1}{2\delta} f_i^c(\mathbf{x}_f, t) + \frac{2\delta - 1}{2\delta} f_{i'}^c(\mathbf{x}_f, t), \end{aligned} \quad (7)$$

278 For moving solid boundaries, the no-slip boundary condition can be modified according
 279 to the velocity of the particle boundary due to translation and rotation (Bouzidi et al.,
 280 2001). In our flume simulations (Section 2.2), since the thickness of the boundary layer
 281 at the glass side walls is smaller than (or comparable to) the grid size dx , we developed
 282 a new boundary technique that accounts for the boundary layer implicitly through a matched

283 slip boundary condition. See Appendix A for more details. At a free-slip boundary, the
 284 parcel will specularly reflect instead of bounce back (Ladd, 1994) as shown in Figure 1(c).
 285 As indicated above, all the LBM boundary conditions are processed in the streaming op-
 286 eration.

287 The local parcel momentum changes can be used to integrate the force and torque
 288 on individual particles exerted by the fluid (Mei et al., 2002). In this way, the fluid feels
 289 the moving particles through the moving interfaces, and the particles feel the fluid via
 290 the integrated hydrodynamic forces and torques. These will be used in the DEM scheme
 291 to update the linear and angular acceleration of the particles. Note that the timestep
 292 of the DEM dt to resolve the elastic interaction of particles (Da Cruz et al., 2005; Kam-
 293 rin & Koval, 2012) is smaller than the timestep of the LBM $dt_f = dx/c_s$, where c_s is
 294 the fluid sound speed. dt_f is chosen so that the corresponding sound speed $c_s = dx/dt_f$
 295 guarantees that the maximum Mach number is below 0.3, in the incompressible limit (Succi,
 296 2001), and the distance a particle travels in a “free flight” is less than $0.02dx$ (mostly
 297 $< 0.01dx$) (Derksen, 2015). In the DEM-LBM simulations presented in this paper, a LBM
 298 step is called every 50 DEM steps to update the hydrodynamic forces and torque. If the
 299 DEM algorithm uses the particle-wise hydrodynamic forces (and torque) in the current
 300 LBM steps to update the particles’ linear and angular acceleration, the interstitial fluid
 301 may experience numerical oscillations. As a remedy, the particle-wise hydrodynamic forces
 302 (and torque) in the current and the previous LBM steps are averaged when conducting
 303 the DEM update. When a particle is close to another particle or a wall, the algorithm
 304 searches for the upstream fluid information $f_i^c(\mathbf{x}_{ff}, t)$ or even $f_i^c(\mathbf{x}_f, t)$ in Eq 6 and Eq
 305 7 which may be no longer physically available. Special care must be taken to update the
 306 fluid domain information as well as to calculate the corresponding fluid-solid momen-
 307 tum exchange. For these near contact scenarios, the needed upstream fluid distribution
 308 function component, $f_i^c(\mathbf{x}_{ff}, t)$ or $f_i^c(\mathbf{x}_f, t)$, is evaluated as the (Maxwell) equilibrium
 309 distribution using the grain velocity at the node if the search for the upstream fluid node
 310 goes into a node occupied by another particle. If the search goes out of the wall of the
 311 flume, then it comes back to the domain (see \mathbf{c}_i'' as shown in Figure 1(c)).

312 By refining the resolution of LBM with respect to the particle size d_p , Feng and
 313 Michaelides (2009) and Derksen (2014) have shown that a resolution of $dx \leq d_p/6$ or
 314 $dx \leq d_p/8$ is adequate for sufficiently accurate results. Here in this paper, $dx \leq \sim d_p/10$
 315 is kept to guarantee enough accuracy. To run our method, we have extended a custom-
 316 written program described in Mutabaruka et al. (2014) and Mutabaruka and Kamrin (2018).

317 The DEM-LBM algorithm is validated at the grain scale in tests of the particle-
 318 fluid linear and angular momentum exchange as well as the resolved lubrication force be-
 319 tween close moving solid boundaries. See Appendix B for more details.

320 2.2 Comparison with laboratory flume experiments

321 Deal et al. (2021) and Benavides et al. (2021) conducted bedload sediment trans-
 322 port experiments with glass spheres in a narrow flume, and recorded high-speed videos
 323 of the grains, allowing for precise tracking. This provides abundant details of the par-
 324 ticle motion. We performed corresponding DEM-LBM simulations as validation specifi-
 325 cally to test the accuracy of our method in sediment transport problems. We begin by
 326 comparing the time-averaged sediment transport rates as a first verification of our sim-
 327 ulations, and then do a more detailed comparison of the time-averaged velocity profiles
 328 and particle velocity fluctuation profiles.

329 The schematic diagram of the flume experimental setup of Deal et al. (2021) and
 330 Benavides et al. (2021) is shown in Figure 2 (a). In each experiment, mono-disperse glass
 331 spheres and water are fed into the inclined flume from the upstream end at a given com-
 332 bination of volume flux rates. After the initial period of sphere deposition, the granu-
 333 lar bed builds up and steady state is reached. Then the slope of the free water surface

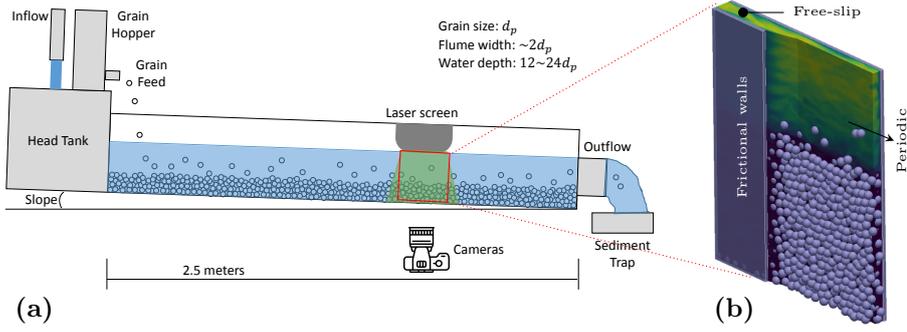


Figure 2. Setup of the sediment transport tests in the narrow flume. (a) Experimental setup (Deal et al., 2021; Benavides et al., 2021). (b) The simulated domain corresponds to the videoed zone in the experiment as shown in the red box.

334 S as well as the water depth are measured, and the particle motion is recorded by the
 335 high-speed cameras in the middle section of the flume. The flume is 10.2mm, slightly wider
 336 than two particle diameters ($d_p = 4.95\text{mm}$). The density of the spheres is $\rho_s = 2550\text{kg/m}^3$.
 337 The elastic constants for the normal and tangential contacts are set to be $20\,000\text{N m}^{-1}$
 338 and 5714N m^{-1} , respectively, guaranteeing the spheres are in hard limit. The friction
 339 coefficients of sphere-sphere and sphere-sidewall contacts are measured to be 0.50 and
 340 0.45 respectively. The dry restitution coefficient of the particles is 0.93. The sensitivity
 341 of the results to the choice of the particle surface parameters is low.

342 DEM-LBM simulations are set up with the same flume geometry and material prop-
 343 erties. The simulated domain, as shown in 2 (b), has a length $L = 24d_p$ and height $30d_p$.
 344 When all the spheres are deposited (in total 969 particles), the thickness of the bed is
 345 $18d_p$. The thickness of the bed reduces to $15d_p$ for the largest Shields number tested, as
 346 some of the spheres are entrained by the fluid. The LBM lattice has homogeneous grid
 347 size $dx = 0.5\text{mm}$. The first and last nodes across the flume align with the side walls,
 348 and the simulated flume width is adjusted slightly to have $W = 10.5\text{mm}$. The top of
 349 the simulated domain uses a free-slip (zero gradient) boundary condition. Note that in
 350 this narrow flume configuration, the fluid velocity far above the granular bed surface ap-
 351 proaches a constant value due to sidewall shear. The bottom uses a no-slip boundary
 352 condition and the two sides perpendicular to the flow direction use periodic boundary
 353 conditions. For the two side walls of the flume, since the thickness of the boundary layer
 354 is smaller than the grid size dx , no-slip boundary conditions with LES is not enough to
 355 resolve the near-wall flow field correctly. Instead, we developed a new boundary tech-
 356 nique: assuming the second layer of nodes from the wall are out of the boundary layer,
 357 we extrapolate the law-of-the-wall flow relationship to the wall, and treat this value as
 358 a slip velocity at the wall, which we implement in DEM-LBM using Navier-type bound-
 359 ary conditions used in other studies (Uth et al., 2013; K. Wang et al., 2018, see Appendix
 360 A for more details). The gravity $g = 9.8\text{m/s}^2$ is applied at an angle of slope S with
 361 respect to the vertical axis of the simulated domain. The flow is driven by the tilted “hor-
 362 izontal” gravity component.

363 For the calculation of τ^* , the bed shear stress τ_b is calculated as $\tau_b = \rho_f g S \frac{HW}{2H+W}$,
 364 where H is the water depth measured down to the bed surface and W is the flume width.
 365 Mindful of the lengthy compute times for each simulation, we chose to perform simula-
 366 tions at 5 different slopes, corresponding to $\tau^* = 0.023, 0.028, 0.047, 0.063$ and 0.068 ,
 367 which covers the experimental range. For the calculation of q^* , the sediment volume flux
 368 per unit width q_s is counted in the whole domain as $q_s = \sum_i \frac{\pi}{6} d_p^3 V_{i,x} / LW$, where $V_{i,x}$
 369 is the streamwise velocity of the i -th particle and L is the length of the simulated do-

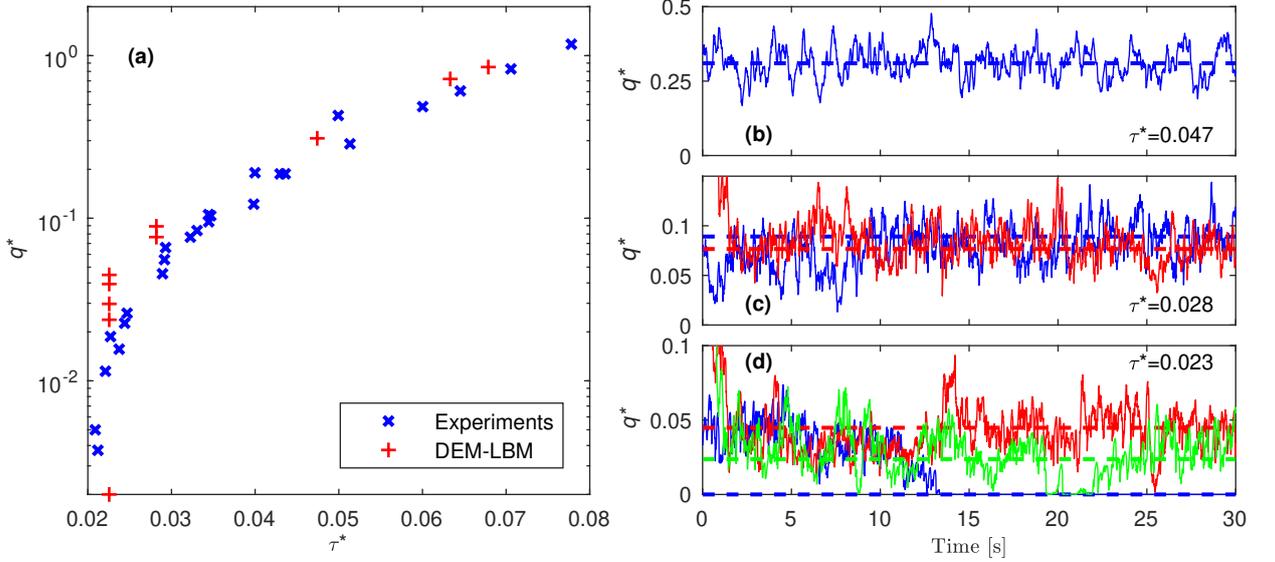


Figure 3. Dimensionless sediment transport rate q^* from DEM-LBM simulations. (a) Comparison with the q^* vs τ^* relation from experiments. The critical Shields number in the flume experiments is found to be 0.026 ± 0.002 (Benavides et al., 2021). At the lowest Shields number $\tau^* = 0.023$, the results show strong intermittency near τ_c^* . The standard initialization gives $q^* = 0$ (shown as 0.002 on the log scale), while the other four cases initialized with the steady flow fields of higher τ^* give different q^* values. Time series of q^* at (b) $\tau^* = 0.047$ (movie08 in SI), (c) $\tau^* = 0.028$ (movie06 and 07) and (d) $\tau^* = 0.023$ (showing 3 out of the 5 initializations, movie01, 02 and 05) are shown in thin curves. The thick dashed lines show the mean of the last 10s. The colors distinguish the initializations: blue—standard, red & green—steady flow of $\tau^* = 0.068$ and $\tau^* = 0.063$ respectively.

370 main. The resulting transport relation compared with the experimental results is shown
 371 in Figure 3(a). The standard initial condition sets the particles uniformly distributed
 372 in the whole domain with no velocity and stationary fluid. As each simulation runs, grav-
 373 ity drives the fluid and grains, resulting in the ultimate formation of a particle sediment
 374 bed and a transverse fluid flow profile, which transports the near surface particles. For
 375 the low Shields numbers, besides the standard initial condition just described, we also
 376 run tests where the initial particle positions and initial particle and fluid velocity are as-
 377 signed from a snapshot taken at the end-phase of a higher Shields number simulation.
 378 The simulations are all carried out for at least 30s of simulation time and the last 10s
 379 of the simulations are taken to calculate the time averaged values and standard devia-
 380 tion of the integrated flux. The Rouse number ranges from 11.4 to 20.9, indicating the
 381 sediment transport is in the bedload regime.

382 Overall, in terms of the q^* vs τ^* transport relation, the DEM-LBM simulations are
 383 consistent with the experiments. At the lowest Shields number simulated, $\tau^* = 0.023$
 384 (τ_c^* found to be 0.026 ± 0.002 (Benavides et al., 2021)), we observe strong intermittency
 385 (see movie01 in the Supporting Information). With the standard initialization, the trans-
 386 port of particles eventually ceases, giving $q^* = 0$ (marked as 0.002 in Figure 3(a) due
 387 to semi-log). The additional data shown at this slope correspond to simulations using
 388 different initializations as described in the prior paragraph. Each of these tests produced
 389 low transport rates at steady state, seemingly not correlated to the flow rate of the ini-
 390 tialization. Time series data of the transport rate for different initializations are shown
 391 in Figure 3(d). With the current sampling duration, the standard deviation of q^* at $\tau^* =$
 392 0.023 is on the same order of magnitude as the time averaged q^* . The fact that the vari-
 393 ation of the sampled q^* is inversely proportional to the sampling duration (Ancy & Pas-
 394 cal, 2020) implies that reducing the relative uncertainty to 15% of the mean q^* at this
 395 lowest transport stage may require the simulations to be run for an additional 200s, which
 396 would be too costly for us to run. The intermittency observed could arise from internal
 397 variability or potentially from the existence of multiple attractors allowing flowing and
 398 non-flowing steady solutions to coexist at low slopes. At the second lowest simulated trans-
 399 port stage, $\tau^* = 0.028$, the intermittency is less obvious and the transport is continu-
 400 ous as shown in 3(c). The standard initialization (movie06 in SI) gives $q^* = 0.089$ with
 401 standard deviation 0.019 while the case with the fastest initialization (movie07 in SI) gives
 402 $q^* = 0.077$ with standard deviation 0.017. As τ^* increases further from the critical Shields
 403 number, the relative uncertainty of the measured q^* goes down to 16% at $\tau^* = 0.047$
 404 (see 3(b)), 11% at $\tau^* = 0.063$ and 9% at $\tau^* = 0.068$.

405 One may notice that transport is observed for very low τ^* values. On one hand,
 406 we use the hydraulic radius to estimate the bed shear stress which tends to underesti-
 407 mate the value (J. Guo, 2015). On the other hand, a similar low threshold for sediment
 408 transport is also observed in a related experimental setup (Heyman et al., 2016) and it
 409 has been shown to not be a result of the sidewall influence on turbulence (Rousseau &
 410 Ancy, n.d.). Also as seen in the movies (Movie01 to Movie05) of the simulations, the
 411 behavior of the particles at the lowest τ^* values seems to correspond to the Intermittent
 412 Bulk Transport regime (Pächt & Durán, 2018a) in which τ^* is above the rebound thresh-
 413 old but below the impact entrainment threshold, and the transported particles rebound
 414 for a relatively long period on the bed surface before depositing. Due to the periodic bound-
 415 ary conditions applied in the streamwise direction, the simulations have a larger auto-
 416 correlation. As a result, the simulations might overpredict q^* when particles are bound-
 417 ing on the bed surface.

418 Despite the limitation at the low Shields number, the simulations still provide mi-
 419 croscopic details when a particle is solely entrained by the turbulent flow. In the inter-
 420 mittent flows shown in Figure 3(d), the green curve (corresponding to movie05 in SI) in-
 421 dicates that the sediment transport comes to a full stop at around 20s and then resumes
 422 at 21s when a particle on the bed surface is entrained (rolling) by the turbulent fluid.

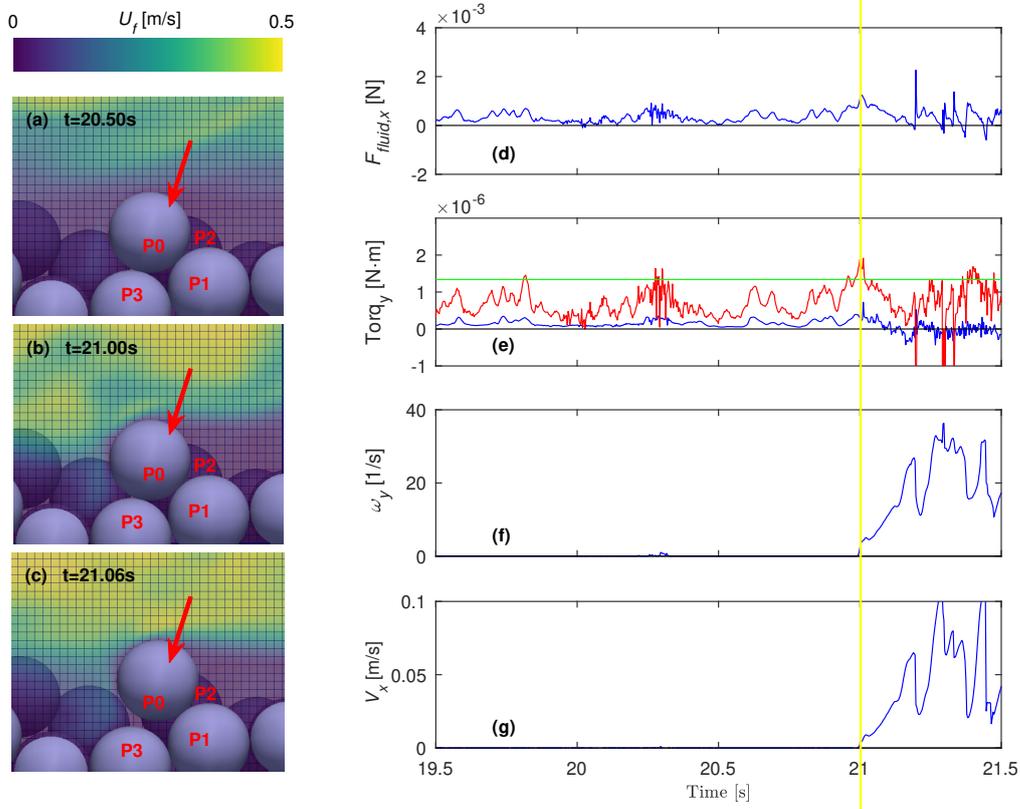


Figure 4. Examination of a near-threshold entrainment event (see movie05 in SI). (a) $t = 20.50s$, particle P0 (highlighted with red arrow) in contact with neighbors P1, P2 and P3 and the side wall. (b) $t = 21.00s$, the start of the entrainment of P0. (c) $t = 21.06s$, particle P0 gets entrained by the fluid, rolling over P1 and P2, and loses contact with P3 and the wall. Each contour shows the fluid velocity field on the plane going through the center of P0. The fluid traction over the particle surface can be treated equivalently as a single force and pure moment (couple) acting at the center of the particle. The detailed information about particle P0 around the entrainment event is displayed: (d) hydrodynamic force in the downstream direction, (e) fluid torque (blue: fluid couple, red: fluid couple + net hydrodynamic force induced torque), with respect to the hinge connecting the contact points of (P0, P1) and (P0, P2), compared with the critical torque (green) estimated by the submerged weight of P0, (f) rotational velocity (axis into the paper) and (g) downstream velocity.

423 As shown in Figure 4(a,b,c), the entrained particle P0 is sitting stationary on the bed
 424 surface, in contact with particle P1, P2, P3 and the side wall of the flume before 21s. Un-
 425 der the influence of a turbulent burst, P0 rolls over P1 and P2, losing contact with P3
 426 and the wall.

427 Using DEM-LBM’s capability of resolving fluid-grain traction, we now detail the
 428 processes taking place during this prototypical near-threshold entrainment event. The
 429 fluid traction over the particle surface can be treated equivalently as a single force and
 430 pure moment (couple) acting at the center of P0. Figure 4(d) shows the hydrodynamic
 431 force in the downstream direction. Figure 4(e) shows the fluid torque (into the paper com-
 432 ponent) with respect to the hinge connecting the contact points of (P0, P1) and (P0, P2).
 433 The torque is evaluated as the integration of the cross products of the lever arm vector
 434 and the hydrodynamic force vector along the surface of the particle. For reference, the
 435 green line shows the “critical” fluid torque to maintain the particle free of contact with
 436 P3 and the side wall, estimated from the submerge weight. According to Figure 4(f,g),
 437 when the fluid torque exceeds the critical value near 20.3s, P0 wiggles but still falls back.
 438 The entrainment happens at 21s when the fluid torque goes above the critical value and
 439 lasts long enough to transfer enough angular momentum to roll P0 out of the spot, which
 440 may correspond to an angular momentum criterion similar to the impulse criterion in
 441 literature (Diplas et al., 2008). The fluid torque comes from the fluid traction on the sur-
 442 face of P0, which is equivalent to a net hydrodynamic force on the center of P0 plus a
 443 fluid couple. The blue curve in Figure 4(e) shows the contribution of the fluid couple,
 444 which is about 1/4 of the total fluid torque (shown in red). Equivalently, the fluid trac-
 445 tion can be simplified solely as a net force acting on the point $d_p/6$ away from the center
 446 on the far side from the hinge. The non-negligible role of the fluid couple shows that
 447 fluid-particle angular momentum transfer plays a role in the entrainment. Thus, com-
 448 bined fluid-DEM simulation methods that utilize only a fluid-particle drag force may be
 449 missing some relevant physics, at least at the low Shields regime. Other particles exam-
 450 ined on the bed surface have also shown a similar $\sim 1/4$ contribution on the total fluid
 451 torque from the net fluid couple. More quantitative examinations can be found in the
 452 next subsection.

453 Next, we examine the flow profiles of the particles. To get the flow fields as func-
 454 tions of the height z with respect to the bed surface, we need to homogenize the flow fields
 455 along the flow direction and then average the profiles over time. The homogenization is
 456 carried out in three steps. The first step is to identify the particles to be used in the ho-
 457 mogenization. In the experiments, since the motion of the particles are recorded by a
 458 camera from one side of the flume, which is slightly wider than $2d_p$, only one layer of the
 459 particles can be recognized in the images. In the post-processing of the simulations, the
 460 particles are projected onto a 2D plane which is discretized into square pixels of $d_p/25$
 461 to mimic the images taken in the experiments. In an effort to match the experimental
 462 post-processing method, if more than 60% of the length of the perimeter is covered by
 463 particles in front of it, that particle will be labeled as invisible. For the particles left, if
 464 two projected particles are closer than $d_p/6$, only the front one is visible. The particles
 465 labeled as visible will be used in the next steps of homogenization. In the experiments,
 466 due to the refraction, the edges of the particles in the back may confuse the particle recog-
 467 nition in experiment images in rare cases. The resultant areal fractions can therefore be
 468 slightly different. For the bed surface, any pixel that is occupied by a particle for half
 469 a second is marked as static and then the position of the bed surface can be decided as
 470 the outline of the static pixels, as the thick black curves show in Figure 5. The vertical
 471 position z of a particle is defined as the vertical distance between the center of the par-
 472 ticle and the bed surface. The second step is to calculate the areal fraction and parti-
 473 cle mean velocity as functions of z . The areal fraction profile is calculated as the pack-
 474 ing fraction of the particles labeled as visible. The velocity homogenization is obtained
 475 from the linear momentum of the layer at z . The third step is to calculate the granu-
 476 lar temperature based on the particle-wise velocity deviation in each snapshots. More

477 details about the last two steps of the homogenization can be found in Q. Zhang and Kam-
 478 rin (2017). The images of the particles in experiments are post-processed in the same
 479 way after the particles are recognized. The fluid velocity field is also averaged tempo-
 480 rally and spatially using a similar method to the solid velocity homogenization, based
 481 on the linear momentum of a layer of nodes at a given z .

482 The simulated and experimental flow profiles are very similar at a medium Shields
 483 number $\tau^* = 0.028$ and a high Shields number $\tau^* = 0.068$, as shown in Figure 5. The
 484 bed structures and the motion of the particles look similar at both Shields numbers (see
 485 movie06 and movie10 in SI). The velocity profiles match the experiments and even the
 486 granular temperature, which is a higher order variable agrees; granular temperature may
 487 be key to understanding sub-surface granular creep (Q. Zhang & Kamrin, 2017; Kim &
 488 Kamrin, 2020). The areal fraction profiles differ slightly, but are still similar to the ex-
 489 periment results. One reason may be that the particle recognition technique used in the
 490 experiments is not easy to replicate in the simulation post-processing, e.g., due to the
 491 refraction effects. Fortunately as long as enough particles are sampled for a given height,
 492 this difference theoretically does not change the averaged particle velocity or granular
 493 temperature; see Figure 5 (e) & (f). With the results described above, the simulations
 494 are deemed to provide a useful description of observed sediment transport processes, and
 495 we proceed to perform numerical experiments to study sediment transport problems from
 496 bulk to grain-scale.

497 2.3 Wide wall-free cases

498 We conduct a parameter study using the simulations to see what properties affect
 499 the transport rate. Namely, how much do certain details about the grains, such as par-
 500 ticle surface friction and damping coefficient, matter versus geometric properties such
 501 as fluid depth, slope and average grain size? Wide wall-free (WWF) simulations (inspired
 502 by wide rivers, without the physical side walls like in the flumes), as shown in Figure 6(a),
 503 are a simple and useful geometry to use toward this end. The wide wall-free simulations
 504 also produce 1D solution fields and serve as benchmark cases to test the continuum mod-
 505 eling in Section 3.

506 What are the independent variables that can influence the transport rate in sed-
 507 iment transport problems? Putting the grain shape and size distribution aside, the vari-
 508 ables are the gravity g , fluid density ρ_f , fluid viscosity η , slope S , water depth H , par-
 509 ticle density ρ_s , particle diameter d_p , particle surface friction coefficient μ_p , particle damp-
 510 ing coefficient g_p and particle stiffness k_p , which means the sediment transport rate q_s
 511 can be estimated by a ten-input function Ψ_0 as shown below:

$$q_s = \Psi_0(H, S, \rho_f, \eta, g, \rho_s, d_p, \mu_p, g_p, k_p). \quad (8)$$

512 The dependent (1) and independent (10) variables in Eq 8 can be non-dimensionalized
 513 by ρ_f , η and g using the below relations:

$$[M] = \frac{\eta^2}{\rho_f g}, \quad [L] = \left(\frac{\eta^2}{\rho_f^2 g} \right)^{1/3}, \quad [T] = \left(\frac{\eta}{\rho_f g^2} \right)^{1/3}. \quad (9)$$

514 Since there are three dimensions involved in these 11 variables, the variables can be nondi-
 515 mensionalized into 8 dimensionless groups, as shown in Table 2, and the transport rela-
 516 tion can be expressed as:

$$\Pi_0 = \Psi_1(\Pi_1, \Pi_2, \Pi_3, \Pi_4, \Pi_5, \Pi_6, \Pi_7). \quad (10)$$

517 We are free to operate on these dimensionless groups so that some of them become ex-
 518 isting widely used dimensionless numbers: Π_0 can be modified into the Einstein num-
 519 ber $q^* = \frac{\Pi_0}{\Pi_4^{3/2}(\Pi_3-1)^{1/2}}$, Π_1 into the Shields number $\tau^* = \frac{\Pi_1 \Pi_2}{\Pi_4(\Pi_3-1)}$, and Π_4 into the

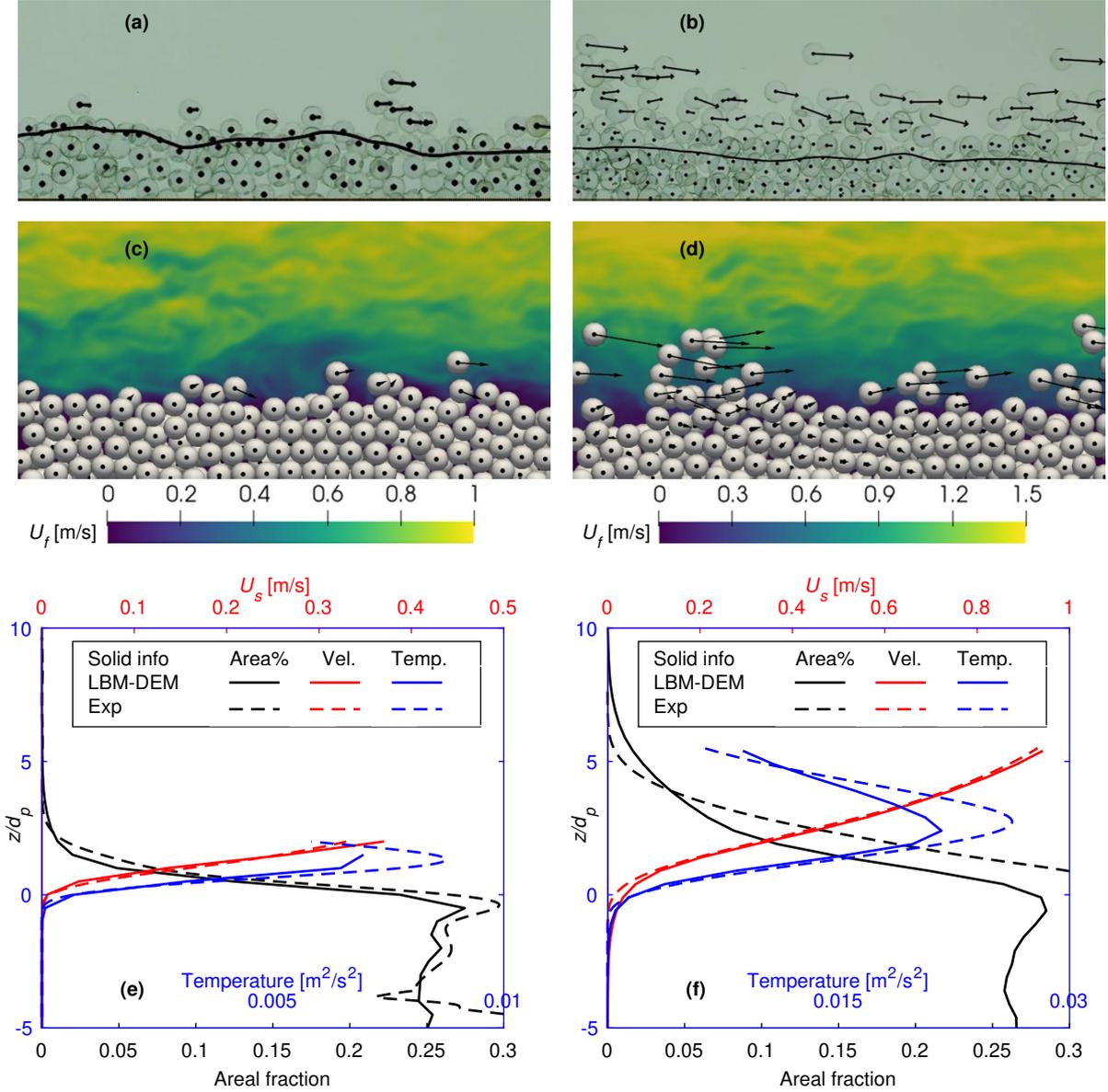


Figure 5. Comparisons between the flume experiments and DEM-LBM simulations at Shields number $\tau^* = 0.028$ (left column), and $\tau^* = 0.068$ (right column). (a) & (b) Snapshots of the flume experiments, particle in-plane velocity represented by the arrows. The black curves represent the bed surface. (c) & (d) Snapshots of the DEM-LBM simulations, particle in-plane velocity represented by the arrows, fluid field colored by the fluid velocity magnitude on the center-plane of the flume. (e) & (f) Experiments vs DEM-LBM simulations comparison in terms of the solid phase profiles as a function of the height from bed surface: areal fraction, particle velocity and granular temperature.

Table 2. Non-dimensionalization of the dependent and independent variables in sediment transport problems (Var: variables, Dim: dimensions, DN: dimensionless numbers)

Var	q_s	H	S	ρ_f	η	g	ρ_s	d_p	μ_p	g_p	k_p
Dim	$\frac{L^2}{T}$	L	-	$\frac{M}{L^3}$	$\frac{M}{LT}$	$\frac{L}{T^2}$	$\frac{M}{L^3}$	L	-	$\frac{M}{T}$	$\frac{M}{T^2}$
DN	$q_s \frac{\rho_f}{\eta}$	$H \left(\frac{\rho_f^2 g}{\eta^2} \right)^{\frac{1}{3}}$	S	1	1	1	$\frac{\rho_s}{\rho_f}$	$d_p \left(\frac{\rho_f^2 g}{\eta^2} \right)^{\frac{1}{3}}$	μ_p	$\frac{g_p}{\eta} \left(\frac{\rho_f^2 g}{\eta^2} \right)^{\frac{1}{3}}$	$\frac{k_p}{\eta} \left(\frac{\rho_f}{\eta g} \right)^{\frac{1}{3}}$
Symbol	Π_0	Π_1	Π_2	-	-	-	Π_3	Π_4	Π_5	Π_6	Π_7

Galileo number $Ga = \frac{\sqrt{gd_p^3}}{\eta/\rho_f} = \Pi_4^{3/2}$. Also, since $\Pi_2 = S$, $\Pi_3 = \frac{\rho_s}{\rho_f}$ and $\Pi_5 = \mu_p$ are simple enough, we just use the original variables:

$$q^* = \Psi_2(\tau^*, S, \frac{\rho_s}{\rho_f}, Ga, \mu_p, \Pi_6, \Pi_7). \quad (11)$$

For sediment transport on Earth's surface, ρ_f and η are given as the values for water and $g = 9.81\text{m/s}^2$. We limit our discussion to the transport of silica-based media like sand (ρ_s/ρ_f is fixed). For river bed sediment transport problems, the sand particles are in the hard limit (the particle deformation is negligible), which means $\Pi_7 \rightarrow \infty$, and thus it does not influence the transport rate. Then we have reduced the input set to five variables:

$$q^* = \tilde{\Psi}(\tau^*; S, Ga, \mu_p, \Pi_6). \quad (12)$$

Considering the empirical transport relation q^* vs τ^* , q^* can be seen as a function of τ^* parameterized by S , Ga , μ_p and Π_6 (dimensionless particle damping coefficient).

Besides the dimensionless groups above, previous researchers consider dimensionless numbers that are not included in Table 2. Here we comment on how these numbers are related to our dimensionless groups or why some of them are not included in this study. One dimensionless group commonly found in literature is the settling Reynolds number (Lajeunesse et al., 2010) $Re_s = \frac{\rho_f w_s d_p}{\eta}$ with the characteristic settling velocity $w_s = \sqrt{gd_p(\rho_s - \rho_f)/\rho_f}$, which can be written as $Re_s = Ga\sqrt{\Pi_3 - 1}$. The particle Reynolds number (Lajeunesse et al., 2010) can be written as $Re_p = \frac{\rho_f \sqrt{\tau_b/\rho_f} d_p}{\eta} = Ga\sqrt{(\Pi_3 - 1)\tau^*}$. The Rouse number (Chauchat & Guillou, 2008) can be written as $Ro = \frac{w_s}{\kappa\sqrt{\tau_b/\rho_f}} = \frac{1}{\kappa\sqrt{\tau^*}}$, where $\kappa = 0.41$ is the Von Kármán constant. Some papers (Sekine & Kikkawa, 1992; Niño et al., 1994) also use the dimensionless saltation length and saltation height, but these are actually outputs in our study and as such arise from the choice of input parameters above. Wong and Parker (2006) use the dimensionless Chezy resistance coefficient to account for the influence of the channel sidewalls, which is not necessary in this dimensional analysis for the case of wide rivers.

A new set of DEM-LBM simulations are performed without sidewalls to study the influence of the five dimensionless numbers on the sediment transport relation. The geometry of the simulated domain is shown in Figure 6(a), compared with the classical 3/2 power law. The granular bed is $24d_p$ long and $8d_p$ wide. The height of the granular bed when all the particles have settled is $10d_p$ (in total 2884 particles). The domain height is set according to the water depth H . Periodic boundary conditions are adopted at the four side boundaries. For fluid, the top boundary is a free slip boundary condition whereas the bottom is a no-slip boundary condition. The gravity is tilted by a slope S . The domain is still discretized with the grid size $dx = 0.5\text{mm}$ for LBM. Simulations are performed at gentle slopes $S = 0.010, 0.016, 0.030$ with monodisperse particles whose density is $\rho_s = 2550\text{kg/m}^3$. The simulations are in the bedload transport regime, with Rouse

Table 3. Parameters of the wide wall-free simulations. (The base parameters are red.)

Group	S	$d_p(\text{mm})$	Ga	μ_p	$g_p(\text{m/s})$	Π_6
WWF1	0.016	5	1378	0.5	0.09	4.2E3
WWF2	0.010	5	1378	0.5	0.09	4.2E3
WWF3	0.030	5	1378	0.5	0.09	4.2E3
WWF4	0.016	8	2789	0.5	0.09	4.2E3
WWF5	0.016	5	1378	0.1	0.09	4.2E3
WWF6	0.016	5	1378	0.5	2.11	9.8E4

number $\sim 17.4 - 30.0$. Corresponding to the dimensionless groups, the simulation parameters are designed to vary the dimensionless numbers one by one (as shown in Table 3) so that we can identify their influence on the q^* vs τ^* relation. The bed shear stress in this geometry can be calculated as $\tau_b = \rho_f g H S$. Water depth H is varied to set the Shields number τ^* to values ranging from 0.046 to 0.141. Each simulation is performed for 30s and the results of the last 10s are averaged, as shown in Figure 6. The averaged solid phase shear stress matches the equilibrium solution, suggesting the steady state has been reached. WWF1 is the reference group using the exact same particles as the flume tests. WWF2 and WWF3 change the macroscopic geometrical parameter S . WWF4, WWF5 and WWF6 vary the microscopic particle parameters: particle size d_p (corresponding to Ga), μ_p , and the damping coefficient g_p (corresponding to Π_6). The value in WWF6 $g_p = 2.11$ m/s corresponds to a dry restitution coefficient of $e = 0.10$ while $g_p = 0.09$ m/s in the other groups corresponds to $e = 0.93$. The integrated transport relation $q^* - \tau^*$ at steady state is shown in Figure 6(b) and (c).

The results of the DEM-LBM simulations from WWF1, WWF2 and WWF3 with different S overlap on top of each other, indicating S has little influence on the dimensionless sediment transport rate on gentle slopes (when τ^* is fixed) and is likely not responsible for the variation in flux (q^*) for a given Shields number (τ^*) in experiments (Meyer-Peter & Müller, 1948). The data sets with varied Ga , μ_p and Π_6 also appear very much the same as the transport relation of WWF1 as shown in Figure 6(c), except for some discrepancy at the smallest Shields number tested $\tau^* = 0.0471$ near the threshold: smaller μ_p gives slightly larger q^* whereas larger Ga , and Π_6 give smaller q^* .

2.4 Fluid-grain torque interactions

We can also further examine the fluid-solid angular momentum transfer in the wide wall free cases. The net fluid couple (when the origin is picked at the center of the particle) exerted on the i th particle is $\mathbf{T}_i = \oint_{A_i} r \hat{\mathbf{r}} \times (\boldsymbol{\sigma}_f \hat{\mathbf{r}}) dA$, where A_i is the surface area of the particle, $r = d_p/2$ is the radius, $\hat{\mathbf{r}}$ is the unit normal vector pointing out, and $\boldsymbol{\sigma}_f$ is the fluid stress tensor. The fluid traction also has a contribution to the solid phase stress tensor on the i th particle:

$$\boldsymbol{\sigma}_{s,i}^f = \frac{3}{4\pi r^3} \oint_{A_i} (\boldsymbol{\sigma}_f \cdot \hat{\mathbf{r}}) \otimes r \hat{\mathbf{r}} dA. \quad (13)$$

While the stress tensor is generally a symmetric quantity, its various contributions may not be even if the total stress still is. Here, \mathbf{T}_i is related to the skew part of $\boldsymbol{\sigma}_{s,i}^f$ through $T_{i,l} = \sigma_{s,i,mm}^f \epsilon_{lmn}$, where ϵ_{lmn} is the 3D Levi-Civita symbol. In this study, we are most interested in the y component (into the paper) of the torque: $\sigma_{s,i,xz}^f - \sigma_{s,i,zx}^f = 3T_{i,y}/4\pi r^3$. We call $\sigma_{s,i,xz}^f - \sigma_{s,i,zx}^f$ the ‘‘rotation stress’’ and calculate the homogenized profile as a function of z , as shown in Figure 7(a), compared with the solid total stress, fluid stress and the packing fraction ϕ . The maximum value of the rotation stress occurs at the bed

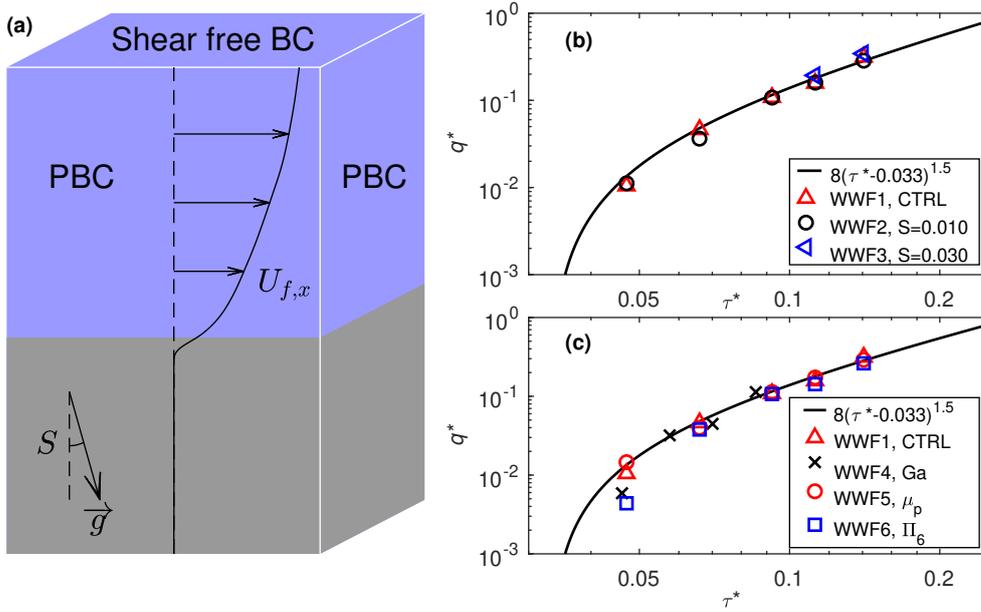


Figure 6. (a) Geometry and boundary conditions of the wide wall-free (WWF) simulations (PBC: periodic boundary condition). The simulated domain size is $24d_p \times 8d_p \times \sim 20d_p$. (b) Sediment transport relation from the wide wall-free simulations with the macroscopic geometrical parameter S varied. (c) Sediment transport relation from the wide wall-free simulations with the microscopic particle parameters Ga , μ_p and Π_6 varied. WWF1 is the control group while the other groups vary the dimensionless groups in Table 3 one by one, as denoted in the legends. The black curve is $q^* = (\tau^* - 0.033)^{1.5}$.

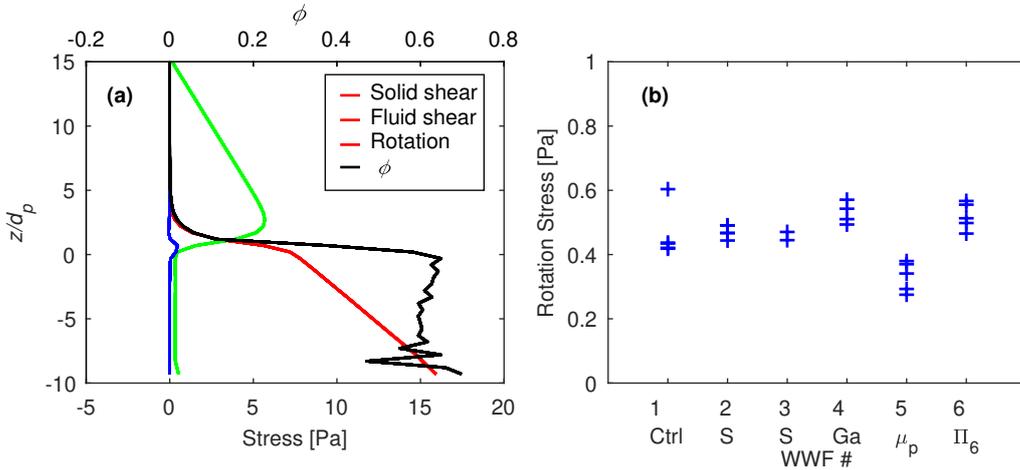


Figure 7. Examination of the rotation stress in wide wall free cases. (a) Flow profiles (WWF2 at $\tau^* = 0.085$) as a function of the height above the bed surface: solid shear stress, fluid shear stress, rotation stress and packing fraction. (b) The maximum rotation stress in different wide wall free groups.

591 surface, corresponding to the intuition that the exposed particles on the sediment bed
 592 surface sustain the largest fluid torque with the “help” (resistance) of the bed particles.
 593 So the rotation stress is not only a measure of the fluid torque exerted on the particles,
 594 but also an indicator of the resistive torque provided by the neighbour particles, which
 595 balance each other on average at steady state. The maximum rotation stress in the shown
 596 case is 0.47Pa, much smaller than the solid shear stress (5.62Pa) at the same position.

597 Figure 7(b) shows the maximum value of each rotation stress profile across differ-
 598 ent wide wall free simulation groups. Each data point comes from the profile of simu-
 599 lation with a unique set of physical parameters. The values from WWF1, WWF2 and
 600 WWF3 are close to each other, suggesting the slope has minor influence on the maxi-
 601 mum rotation stress. The maximum rotation stress values of WWF4 and WWF6 are slightly
 602 higher than those in WWF1, WWF2 and WWF3, while the values of WWF5 are lower.
 603 Looking back at Figure 6(c) at the smallest Shields number $\tau^* = 0.0471$, the q^* val-
 604 ues from different groups are inversely correlated to the corresponding maximum rota-
 605 tion stress in Figure 7(b) — WWF5 has the smallest rotation stress corresponding to
 606 the largest q^* while WW4 and WWF6 have larger rotation stress corresponding to smaller
 607 q^* values. Also considering that the values seem not to be correlated to the Shields num-
 608 ber over the tested range $0.0471 \sim 0.1408$ and mostly a constant in each group, it in-
 609 dicates the torque resistance of the bed is like a material property of the particles. While
 610 the maximum rotation stress can be seen as a measurement of the bed resistance, on the
 611 other hand it is a driving factor for the particle motion. For the particles on the sedi-
 612 ment bed surface, there are two driving factors countering the resistance from the neigh-
 613 bor particles in contact: collision with moving particles and fluid interactions (fluid net
 614 couples and hydrodynamic forces as illustrated by Figure 4). Since the maximum rota-
 615 tion stress is almost a constant in the tested Shields number range whereas the hydro-
 616 dynamic force is correlated to τ^* , the influence of the maximum rotation stress of the
 617 material on q^* is most evident near the threshold. The maximum rotation stress of WWF5
 618 is slightly below the control group because the low surface friction coefficient reduces the
 619 amount that particle contacts can resist the couple. In WWF6, the collisions of the par-
 620 ticles on the bed surface dissipates more energy, which in return increases the resistance,
 621 giving rise to higher rotation stress.

622 3 Continuum modeling

623 While the DEM-LBM simulations in the last section are useful for gaining under-
 624 standing, the drawback from a modeling perspective is obvious: resolving individual grains
 625 and running the LBM with a resolution of one tenth of a particle diameter makes for a
 626 method that is computationally expensive. For example, a half-minute long wide wall
 627 free simulation can take more than a week. These simulations are only affordable for small
 628 scale problems or rheological studies. For large scale problems, continuum models with
 629 proper closures can be applied for reasonable computational cost.

630 DEM-LBM simulations do, however, provide a prime tool for developing and ex-
 631 tracting continuum models, offering certain advantages over experiments alone. Some
 632 of the desired experiments would be difficult to conduct in the lab setting and some of
 633 the quantities that are important in developing the continuum model are not easily ac-
 634 cessible from experiments, such as the bulk fields of stress and velocity in the fluid and
 635 granular phase, as well as granular temperature.

636 In this section, we present a two-phase continuum model for steady-state behav-
 637 ior based on a recent mixture theory framework, turbulent-particle interaction closures,
 638 and known granular rheology principles. It is validated/calibrated directly from our DEM-
 639 LBM simulations. Close comparisons are made between the results from DEM-LBM sim-
 640 ulations and the proposed continuum model in terms of the sediment transport relation
 641 and the detailed flow profiles of both fluid and solid phases. Besides the relatively fast

642 motion of the transported particles and the fluid, the last subsection will also discuss the
 643 modeling of creep beneath the bed surface.

644 3.1 Method

645 A promising approach for continuum modeling of fluid-grain mixtures is to use a
 646 two-phase mixture theory (Bandara & Soga, 2015; Maurin et al., 2016; Chauchat, 2018;
 647 Baumgarten & Kamrin, 2019) that contains mass and momentum balances for both fluid
 648 and solid phases, and three closures: constitutive relations for fluid and solid phase stresses
 649 and a drag-law that transfers momentum between solid and fluid phases. As mentioned
 650 at the beginning, since the granular flow in sediment transport problems covers multi-
 651 ple regimes, the granular constitutive relation is crucial to making accurate predictions.

652 The framework of the continuum model presented here is based on a recent mix-
 653 ture model which spans dilute to dense regimes (Baumgarten & Kamrin, 2019), with the
 654 addition of a turbulent closure as well as an enhanced drag law and granular rheology.
 655 The solid and fluid phases of the fully immersed mixture are considered as overlapping
 656 continuum bodies with volume fractions ϕ and porosity $n = 1 - \phi$ respectively. The
 657 Cauchy stress tensor of the mixture is defined as the sum of the phase-wise Cauchy stresses:
 658 $\boldsymbol{\sigma} = \boldsymbol{\sigma}_s + \boldsymbol{\sigma}_f$. The fluid and solid phase-wise Cauchy stress can be expressed as

$$\boldsymbol{\sigma}_f = \boldsymbol{\tau}_f - n p_f \mathbf{1} \quad (14)$$

$$\boldsymbol{\sigma}_s = \tilde{\boldsymbol{\sigma}} - \phi p_f \mathbf{1}, \quad (15)$$

659 where $\boldsymbol{\tau}_f$ is the deviatoric part of $\boldsymbol{\sigma}_f$, $p_f = -\text{tr}(\boldsymbol{\sigma}_f)/3n$ is the fluid pore pressure, and
 660 $\tilde{\boldsymbol{\sigma}}$ is the solid effective stress which drives the granular plastic flow.

661 The motion of the mixture in steady state is governed by the mass balance equa-
 662 tions

$$\mathbf{U}_s \cdot \text{grad}(\phi \rho_s) + \phi \rho_s \text{div} \mathbf{U}_s = 0 \quad (16)$$

$$\mathbf{U}_f \cdot \text{grad}(n \rho_f) + n \rho_f \text{div} \mathbf{U}_f = 0 \quad (17)$$

663 and momentum balance equations

$$\phi \rho_s \mathbf{U}_s \cdot \text{grad}(\mathbf{U}_s) = \phi \rho_s \mathbf{g} - \mathbf{f}_d + \text{div} \tilde{\boldsymbol{\sigma}} - \phi \text{grad}(p_f) \quad (18)$$

$$n \rho_f \mathbf{U}_f \cdot \text{grad}(\mathbf{U}_f) = n \rho_f \mathbf{g} + \mathbf{f}_d + \text{div} \boldsymbol{\tau}_f - n \text{grad}(p_f), \quad (19)$$

664 where \mathbf{f}_d is the drag force density from the solid phase to the fluid phase. The buoyancy
 665 is built in to the grad pressure terms.

666 Besides the equations of mass and momentum balances, three closures (constitu-
 667 tive laws) are needed to solve the system: granular rheology for $\tilde{\boldsymbol{\sigma}}$, turbulent closure for
 668 $\boldsymbol{\tau}_f$ and inter-phase drag law for \mathbf{f}_d .

669 3.1.1 Granular flow rule

670 For the steady flow of submerged granular materials, based on suspension rheolog-
 671 ical experiments, Boyer et al. (2011) proposed a rheology in which the packing fraction
 672 ϕ and granular stress ratio $\mu = \bar{\tau}/p_p$ are functions of only the dimensionless viscous num-
 673 ber $I_v = \eta \dot{\gamma}/p_p$, where $\dot{\gamma}$ is the solid equivalent shear strain rate, granular pressure $p_p =$
 674 $-\text{tr}(\tilde{\boldsymbol{\sigma}})/3$, and granular shear stress $\bar{\tau}$ is defined as the magnitude of the deviatoric part
 675 of $\tilde{\boldsymbol{\sigma}}$. Similarly, in the rheology of dry granular materials, ϕ and μ are solely functions
 676 of the inertial number $I = \dot{\gamma} d_p / \sqrt{p_p / \rho_s}$ (Jop et al., 2006). Trulsson et al. (2012) pro-
 677 posed a combination of I_v and I to unify the rheology based on 2D simulations, which
 678 covers both the viscous regime proposed for suspensions and the inertial regime when
 679 fluid resistance is minimal. Later, Amarsid et al. (2017) modified the combination as the

680 mixed inertial number $I_m = \sqrt{2I_v + I^2}$ and expressed ϕ and μ in terms of I_m . Recently,
 681 inspired by the work of Boyer et al. (2011) and Amarsid et al. (2017), Baumgarten and
 682 Kamrin (2019) proposed a granular flow model that unifies dilute suspension rheology,
 683 dense suspension rheology, and inertial flow rheology.

684 Starting from the latter model, we analyze and fit the granular material param-
 685 eters with additional DEM-LBM tests in simple shear geometries (Boyer et al., 2011) un-
 686 der varied packing fractions. In the simple shear simulations, there is no gravity and the
 687 mixture is confined between the top and bottom walls which are made of particles. The
 688 bottom wall is fixed whereas the top wall is assigned a constant horizontal shear veloc-
 689 ity. All the side boundaries are periodic. The volume fraction of the particles is varied
 690 test-by-test from 0.03 to 0.6. The particles are exactly the same as the previous wide wall-
 691 free tests and flume tests. Instead of water, a more viscous fluid ($\eta = 0.417 \text{ Pa} \cdot \text{s}$) is
 692 used in the simple shear tests to avoid turbulence for now. In post-processing, σ_s is ho-
 693 homogenized from the stress in each particle, which arises from grain-grain contact forces
 694 σ_s^c , particle velocity fluctuations σ_s^{dv} and fluid-solid interaction σ_s^f . The contributions
 695 from contacts and fluctuations can be calculated according to Da Cruz et al. (2005). Since
 696 DEM-LBM provides the fluid-grain momentum exchange along the grain surfaces, these
 697 can be used to calculate the fluid-force contribution to the particle-wise stress tensor (see
 698 Eq 13).

699 The DEM-LBM simple shear test results are shown in Figure 8, leading to an en-
 700 hanced granular flow rule as follows:

$$\mu = \mu_1 + \frac{\mu_2 - \mu_1}{1 + b/I_m} + \frac{5}{2} \frac{\phi I_v}{a I_m} + \frac{5}{2} \phi I_v, \quad (20)$$

$$\phi = \frac{\phi_m}{1 + a I_m}, \quad (21)$$

701 where $a = \sqrt{2}/2$ is a constant and the material parameters are calibrated as $\mu_1 = 0.37$, $\mu_2 =$
 702 0.70 , $\phi_m = 0.62$, $b = 5$, as shown in Figure 8 (a,b). Eq 20 gives the solid phase stress
 703 ratio when the material is flowing ($\dot{\gamma} \neq 0$ or $I_m, I_v \neq 0$). When the granular material
 704 is not flowing, the solid shear stress is limited by the flow criterion: $\bar{\tau} - \mu_1 p_p < 0$.

705 Maurin et al. (2016) have shown that the drag law in bedload transport problems
 706 can be fitted by the $\mu(I)$ rheology which is originally for dry granular materials. In our
 707 cases as well, the dry inertial number I dominates the mixed inertial number $I_m = \sqrt{2I_v + I^2}$
 708 with the ratio $I^2/2I_v = \dot{\gamma} d_p^2/2\nu$ greater than 10 above the bed surface. We find the
 709 last two terms of Eq 20 contribute less than 5% to the value of μ for $\phi > 0.05$; these
 710 terms serve primarily to recover the suspension effective viscosity in the dilute limit. As
 711 shown in Figure 8(c), the I_m based rheology predictions for the bedload flow are still con-
 712 sistent with the DEM-LBM results. In contrast, Figure 8(d) shows the $\mu(I)$ relation is
 713 consistent with the bedload data, but does not match the rheological simple shear tests
 714 when $I^2/2I_v$ is low. In this two-phase framework, we choose to use the more universal
 715 $\mu(I_m)$ relation because it can be generalized more easily to suspended load in sediment
 716 transport or even other particle laden flow scenarios, as suggested by Baumgarten and
 717 Kamrin (2019). Note that neither rheology predicts the observed behavior for $\mu < \mu_1$
 718 in Figure 8(c,d), which are caused by nonlocal effects, which will be modeled in an up-
 719 coming section.

720 The last term in Eq 20 for the solid phase stress was previously attributed to the
 721 fluid shear stress in (Baumgarten & Kamrin, 2019). We have some freedom in choosing
 722 which phase includes this contribution — the phase-wise stress decomposition is not to-
 723 tally known. Its placement does not affect the total stress nor the model’s ability to span
 724 dilute suspensions, dense suspensions, and dry granular flows (see Baumgarten and Kam-
 725 rin (2019) for more details about how these regimes are recovered). That said, it is rea-
 726 sonable to include as part of the solid stress since it induced by fluid traction on the grains
 727 and Eq 20 matches our DEM-LBM data more closely.

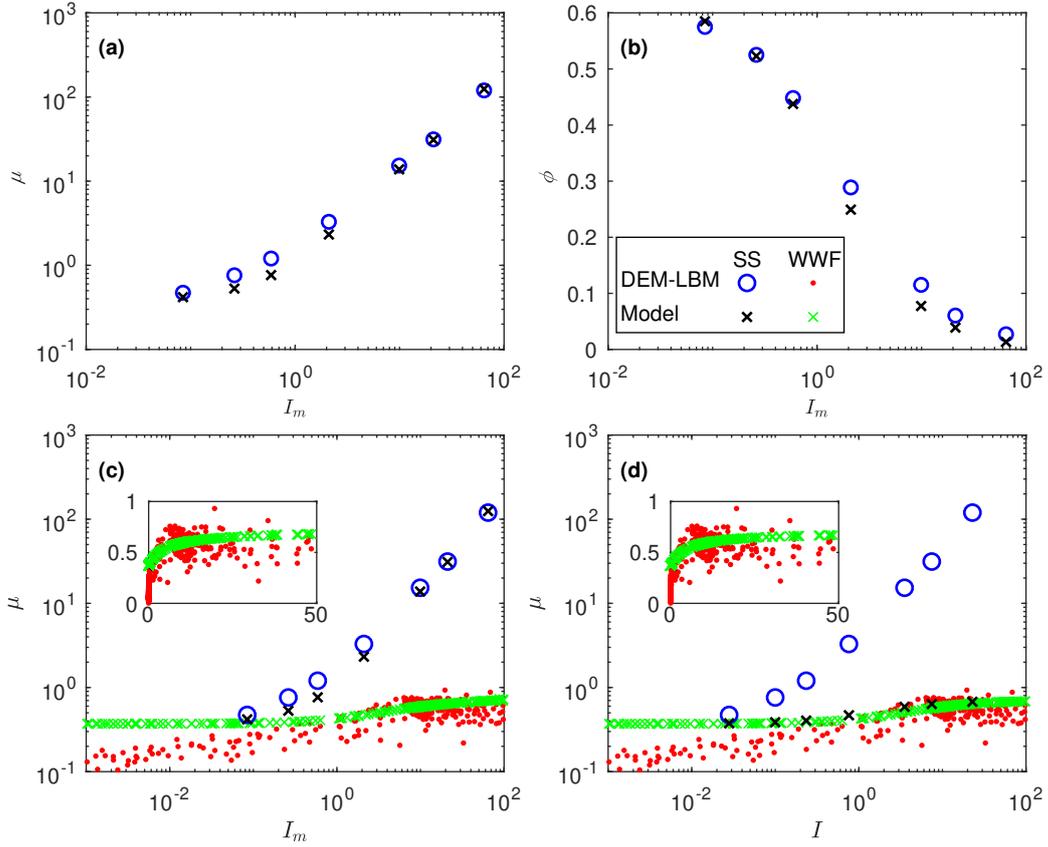


Figure 8. Granular flow rule from simple shear SS simulations: (a) the dependence of stress ratio μ on the mixed inertial number I_m , (b) packing fraction ϕ as a function of I_m . Fitted granular flow rule validated with the data from the wide wall free (WWF) simulations: (c) Scatter plot of μ versus I_m , (d) scatter plot of μ and I (dry rheology). Each data point of DEM-LBM comes from a set of homogenized values at a elevation in a WWF test (in total 27 included).

3.1.2 Turbulent closures

Turbulence in the fluid produces Reynolds shear stresses and turbulent effects on particle drift, which can both influence sediment transport. The Reynolds shear stress can be modeled using mixing length models (L. Li & Sawamoto, 1995; Revil-Baudard et al., 2015; Berzi & Fraccarollo, 2015). Here we use that of (Berzi & Fraccarollo, 2015) where the mixing length is fully determined by the local granular packing fraction ϕ without integrating or calculating the distance from the bed surface, which can be challenging in complex 2D or 3D cases. The turbulent viscosity is modeled as

$$\eta_t = n \rho_f l_m^2 \|\mathbf{D}_{0f}\|, \quad (22)$$

with the mixing length formulated as

$$l_m = 3 d_p (\phi_m - \phi)^3. \quad (23)$$

ϕ_m is the random close packing fraction of the particles which is $\phi_m = 0.62$ for the DEM grains. The deviatoric part of the fluid stress is then calculated as $\boldsymbol{\tau}_f = 2(\eta + \eta_t)\mathbf{D}_{0f}$. Experiments (Ni & Capart, 2018) have shown $l_m/d_p \geq 0.2$ is a lower limit of the mixing length at high packing fraction, where wake effects dominate the vertical mixing of momentum, so we use $l_m/d_p \geq 0.2$ as the lower bound of Eq 23.

Due to the velocity fluctuations of the turbulent flow, the particles experience an additional drift velocity \mathbf{u}_d (Simonin, 1989), which is crucial to recover the Rouse profile (Rouse, 1937) in sheet flows Chauchat (2018). Here we formulate the model in a general vectorial form:

$$\mathbf{u}_d = -\frac{\eta_t}{\rho_f \Sigma_s \phi} \text{grad}\phi, \quad (24)$$

where Σ_s is the turbulent Schmidt number and has been shown to be a constant above a certain height from the bed surface in the sheet flow (Chauchat, 2018). When implemented into a two-phase solver, we use $\Sigma_s = 0.3$.

3.1.3 Drag law

The interphase drag force density \mathbf{f}_d can be modeled using the common drag form

$$\mathbf{f}_d = \frac{18\phi(1-\phi)\eta}{d_p^2} F(\phi, Re_d) \Delta\mathbf{U}. \quad (25)$$

For turbulent flows, the velocity difference above is modified to account for turbulent drift as $\Delta\mathbf{U} = \mathbf{U}_s - \mathbf{U}_f + \mathbf{u}_d$. The function $F(\phi, Re_d)$ is the dimensionless drag function with $Re_d = (1-\phi)\rho_f \|\Delta\mathbf{U}\|/\eta$. The Stokes drag law for a single sphere implies $F(0, 0) = 1$. One typical way to determine $F(\phi, Re_d)$ is to measure $F(0, Re_d)$ with a single particle and then account for hindrance effects from neighbouring particles, such as the Schiller (1933) model:

$$F_1(\phi, Re_d) = F(0, Re_d)(1-\phi)^{-1-h_{\text{Exp}}}, \quad (26)$$

where the exponent h_{Exp} is taken as a constant value of 2 in a recent work on the continuum modeling of sediment transport (Chauchat et al., 2017) and the expression for $F(0, Re_d)$ is evaluated as $1 + 0.15Re_d^{0.687}$ for $Re_d \leq 1000$ and $\frac{0.44}{24}Re_d$ for $Re_d > 1000$. Alternatively, $F(\phi, Re_d)$ can also be determined in the Stokes flow limit as $F(\phi, 0)$ and then extended by adding a term related to Re_d . For example, Beetstra et al. (2007) proposed the expression below from fitting

$$F_2(\phi, Re_d) = \frac{10\phi}{(1-\phi)^2} + (1-\phi)^2(1 + 1.5\sqrt{\phi}) + \frac{0.413Re_d}{24(1-\phi)^2} \left(\frac{(1-\phi)^{-1} + 3\phi(1-\phi) + 8.4Re_d^{-0.343}}{1 + 10^3\phi Re_d^{-(1+4\phi)/2}} \right). \quad (27)$$

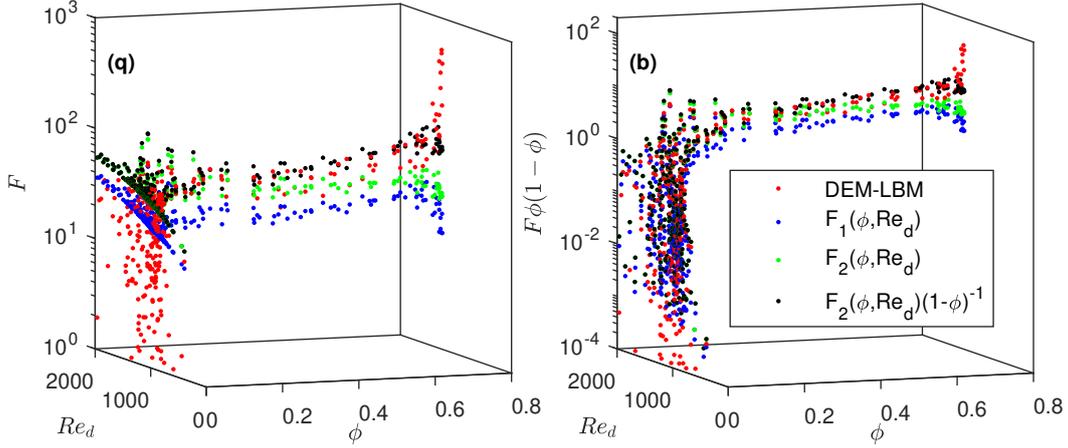


Figure 9. Comparison of different dimensionless drag coefficient formulas $F_1(\phi, Re_d)$, $F_2(\phi, Re_d)$ and the modified $F_2(\phi, Re_d)(1 - \phi)^{-1}$ against the DEM-LBM results: (e) The dimensionless drag coefficient F as a function of ϕ and Re_d . (f) $F\phi(1 - \phi)$ as a function of ϕ and Re_d . The formulas are evaluated at the same ϕ and Re_d values as the DEM-LBM data. F_1 and F_2 tend to underestimate the drag whereas $F_2(\phi, Re_d)(1 - \phi)^{-1}$ gives better fitting. Each data point of DEM-LBM comes from a set of homogenized values at an elevation in a WWF test (in total 27 included).

763 The data from DEM-LBM simulations can serve as a tool to test/validate these
 764 two drag laws. The drag force density can be extracted from the net fluid force per par-
 765 ticle in our DEM-LBM wide wall-free simulations, and then homogenized layer-wise at
 766 each z and averaged over time to produce F . Similarly, ϕ and Re_d can be homogenized
 767 layer-wise. The measured dimensionless drag coefficient is compared with the predictions
 768 of F_1 and F_2 evaluated at the same ϕ and Re_d values, as shown in Figure 9(a). Accord-
 769 ing to Eq 25, F will be multiplied by $\phi(1-\phi)$ when used to calculate the drag force den-
 770 sity \mathbf{f}_d , so the comparison of $\phi(1-\phi)F$ is also included in Figure 9(b). F_1 and F_2 tend
 771 to underestimate the drag because Eq 26 and Eq 27 arise from considering a fluid flow-
 772 ing through a fixed, isotropic array of grains. When it comes to mobile particles in sed-
 773 iment transport problems or fluidized granular beds, the actual drag forces are claimed
 774 to be higher than this relation due to granular velocity fluctuations (Wylie et al., 2003;
 775 Kriebitzsch et al., 2013), packing heterogeneity (Derksen, 2014), and/or packing anisotropy
 776 (Holloway et al., 2012; Ma et al., 2020). We account for this effect as follows. The agree-
 777 ment presented in the single sphere settling tests, as shown in Appendix B, indicates that
 778 $F_1(0, Re_d)$ should be recovered in the DEM-LBM simulations. Thus, a simple way to
 779 modify the drag law but keep this limit is to multiply $F_1(\phi, Re_d)$ or $F_2(\phi, Re_d)$ above
 780 with a correction that is a power of $(1-\phi)$ as an hindrance coefficient (Richardson &
 781 Zaki, 1954; Di Felice, 1994). We find the error of the drag law in our system can be re-
 782 duced by choosing the additional factor to be $(1-\phi)^{-1}$, i.e.,

$$F(\phi, Re_d) = F_2(\phi, Re_d)(1 - \phi)^{-1}. \quad (28)$$

783 The proposed formula F fits the DEM-LBM results better than the original formula F_2
 784 for fixed grain arrays.

785 3.2 Wide wall-free cases

786 The continuum model with the calibrated material parameters described above has
 787 been implemented in a 1D two-phase solver to model the wide wall-free cases. The equa-

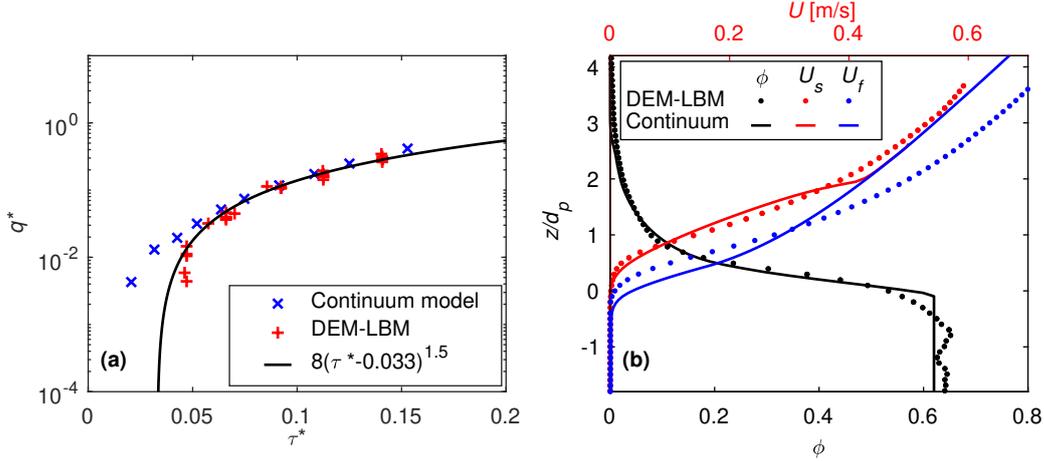


Figure 10. Comparison between DEM-LBM simulations and the continuum model for the wide wall-free geometry: (a) sediment transport relation, and (b) flow profiles (WWF2 at $\tau^* = 0.085$) as a function of the height above the bed surface: fluid velocity, solid velocity and solid packing fraction.

788 tions are solved with transient terms and a granular dilation rule (Pailha & Pouliquen,
 789 2009) using the finite volume method. When the steady state is reached, the transient
 790 terms and dilation rule vanish so that the solution is not influenced.

791 The wide wall-free cases are solved with a given slope S and varied water depth
 792 H . The transport relation from multiple solutions is shown in Figure 10(a). Each data
 793 point represents a single solution for a given H or τ^* . The transport relation from the
 794 continuum model matches with that from DEM-LBM simulations, giving a good fit to
 795 the widely used (albeit flawed) 3/2 power law. Figure 10(b) shows the comparison of the
 796 flow profiles from continuum modeling and DEM-LBM simulations. The modeled solid
 797 packing fraction profile ϕ matches the simulation almost exactly and the solid velocity
 798 profile also matches .

799 One difference in Figure 10(b) is that the solution of the continuum model predicts
 800 U_s and U_f to merge into the same profile for $\phi < 0.05$ by observation while in DEM-
 801 LBM U_s is always lagging behind U_f . The reason for this deviation is that in the DEM-
 802 LBM simulations the very top layer of the particles in the dilute suspension always come
 803 up from the granular flow below and they are always slower than the local ambient fluid
 804 flow (accelerating streamwise all the way up). On the other hand, there is no such verti-
 805 cal momentum mixing effects (in steady state) in our current continuum model. More-
 806 over, \mathbf{u}_d predicted by the continuum model is large enough for the lift force to cancel
 807 out the submerged weight of the solid phase, so that the local un-pressurized solid phase
 808 sustains no shear stress and co-moves with the fluid phase. For the granular material gov-
 809 erned by a frictional flow rule, $p_p = 0$ means the material is suspended and free to be
 810 sheared. As a result, there is no drag force in the flow direction (so no velocity lag) for
 811 the very dilute layers. For a remedy, there are two future research directions: (1) enhanc-
 812 ing the drift velocity formula so that the submerged weight does not fully cancel out, or
 813 (2) a granular flow rule for the very dilute regime that considers the vertical mixing of
 814 solid phase momentum due to the granular temperature, packing fraction gradient, ve-
 815 locity gradient, and perhaps the gradient of the velocity gradient. Another problem is
 816 the abrupt transition to the maximum concentration near bed surface, resulting from
 817 the previously mentioned granular flow rule with a flow criterion given by μ_1 . The kink
 818 corresponds to the elevation where $\mu = \mu_1$, which gives $\phi = \phi_m$ and $\dot{\gamma} = 0$ for all the

819 points below it. Incorporating a nonlocal rheology into the two-phase model may im-
 820 prove the solution near and below the bed surface. As mentioned previously, the drag
 821 force density on mobile sheared particles is larger than that on fixed randomly packed
 822 particles. More analytical work on this would shed light on the interaction between fluid
 823 and solid phases in such flow problems. Finally, we note that this model, which utilizes
 824 a standard mixture theoretic decomposition of the stress, is not equipped to model the
 825 details of the different stress contributors in each phase beyond the splitting shown in
 826 Eqs 14 and 15. A higher order mixture model could incorporate a micropolar form for
 827 the different contributions (Cosserat & Cosserat, 1909; Kamrin, 2019) to permit coun-
 828 terbalancing rotation stresses within each phase to account for the near-bed-surface be-
 829 havior in Sec 2.4, which can be a future research direction.

830 3.3 Creep modeling

831 For the very dense flow region $\phi \sim \phi_m$ under the bed surface, creep flow (expo-
 832 nential decay of \mathbf{U}_s) is also observed in DEM-LBM simulations, which is known to be
 833 driven by nonlocal effects arising from finite grain size (Silbert et al., 2003; Mueth, 2003;
 834 Bonnoit et al., 2010). Creep flow is not contributing much to the $q^* - \tau^*$ transport re-
 835 lation for τ^* far from τ_c^* . However, its effect can matter over the long term, e.g. creep
 836 may lead to vertical grain size sorting in river beds (Ferdowsi et al., 2017), and thus ac-
 837 curate modeling of the creeping flow could be helpful to predict river bed armouring.

838 In the creep zone, the velocities of the particles and the fluid, as well as the rela-
 839 tive velocity between the two phases, are so small that the drag forces and lubrication
 840 forces from fluid are tiny. One may wonder, hence, if a rheology for the creep of dry gran-
 841 ular materials will also work here. We consider the Nonlocal Granular Fluidity model
 842 (NGF) (Kamrin & Koval, 2012; Kamrin & Henann, 2015), which is able to model creep
 843 flow in dry granular materials in many cases. In the NGF constitutive model, a phase
 844 field called the fluidity, g , is postulated to exist, which satisfies the dynamical partial dif-
 845 ferential equation:

$$846 \quad t_0 \dot{g} = A^2 d_p^2 \nabla^2 g - (\mu_2 - \mu_1) \left(\frac{\mu_1 - \mu}{\mu_2 - \mu} \right) g - b \sqrt{\frac{\rho_s d_p^2}{p_p}} \mu g^2 \quad (29)$$

847 where the nonlocal amplitude $A = 0.43$ is a dimensionless constant given by the grain
 848 geometry and t_0 is a time-scale. The fluidity then directly controls the stress-flow rhe-
 849 ology by the relation $\dot{\gamma} = g\mu$. The “unexpected” flow (i.e. creep) of the solid phase in
 850 the region where the load is below the local flow criterion comes from the diffusion term
 851 in Eq 29, which is scaled directly by the grain size d_p . Recent research (Q. Zhang & Kam-
 852 rin, 2017; Kim & Kamrin, 2020) shows that g is very likely to be related to the veloc-
 853 ity fluctuations of the particles. Thus, the physical picture for the creep flow is as fol-
 854 lows: the high granular temperature region of fast flow at the bed surface is a source of
 855 g that diffuses downward and “warms up” the cold zone deeper into the bed so that it
 856 too can flow. The NGF model parameters are usually fitted from the inertial flow rule
 857 for dry granular materials mentioned in 3.1.1. Equation (18) then closes the system of
 equations.

858 We solve the NGF model in the wide wall-free flow geometry with some aid from
 859 the DEM-LBM results. Since Eq 18 needs the fluid forcing, $-\mathbf{f}_d - \phi \text{grad}(p_f)$, which is
 860 not computed from NGF, we simply extract this field directly from the fluid forces in
 861 the corresponding DEM-LBM simulation. The g field also needs reasonable boundary
 862 conditions. We set $g = 0$ at the bottom of the bed ($z = -10d_p$) and set the g value
 863 at $z = -2d_p$ from DEM-LBM tests (using $g = \dot{\gamma}/\mu$) at $z = -2d_p$. Then the velocity
 864 of the solid phase can be integrated from the fixed bottom using the solved g field. Fig-
 865 ure 11 gives the solid phase velocity profile comparison between the DEM-LBM wide wall-
 866 free simulation ($d_p=5\text{mm}$, $S = 0.016$) and the corresponding steady state NGF solu-
 867 tion. The NGF result shows an exponential decay with a decay length of $\sim 2.5d_p$, in

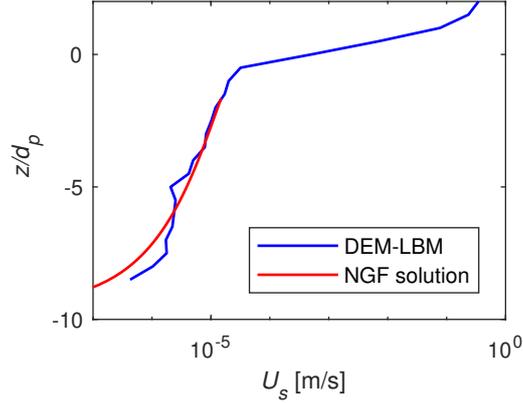


Figure 11. The solid phase velocity profile comparison between a DEM-LBM wide wall-free simulation ($d_p=5\text{mm}$, $S = 0.016$) and the corresponding steady state NGF solution.

868 agreement with our DEM-LBM results as well as separate experimental measurements
 869 from immersed sediment beds (Allen & Kudrolli, 2017) and dry granular beds (Siavoshi
 870 et al., 2006) in similar geometries. This confirms our expectation that the minimal ef-
 871 fect of fluid in the deeper zones causes the material to creep as a dry media would.

872 4 Discussion

873 With regard to the motivating questions asked in the introduction, our study pro-
 874 vides the following outlook.

875 4.1 How important is fluid-particle angular momentum transfer and in 876 which part of the flow and in which regime of the sediment trans- 877 port is it important?

878 Our simulations resolve the fluid traction over the particle surfaces, leading to a
 879 hydrodynamic net force on the center of each particle along with a fluid net couple. Ex-
 880 amination of particles entrained by fluid on the bed surface in intermittent sediment trans-
 881 port flume simulations show that nearly 1/4 of the total fluid torque to roll over neigh-
 882 boring grains comes from the net fluid couple, which is non-negligible especially near the
 883 transport threshold. In each wide wall free simulations, the rotation stress, which mea-
 884 sures the skewness of the fluid-imposed stress contribution in a grain, seems to be con-
 885 centrated near the sediment bed surface where it is balanced by the torque resistance
 886 arising from the enduring contact with other bed particles. The maximum rotation stress
 887 seems not correlated to the Shields number (in the tested range from 0.0471–0.1408),
 888 which can be seen as a material indicator of how much fluid net couple the sediment bed
 889 can sustain (on the other hand, it is part of the hydrodynamic driving). On the other
 890 hand, the fluid net force per grain appears correlated to τ^* . As a result, the influence
 891 of the fluid net couple (or the defined rotation stress) is most evident for $\tau^* \rightarrow \tau_c^*$ and
 892 is negligible for $\tau^* \gg \tau_c^*$, which is shown in this study in terms of the sediment trans-
 893 port relation. This analysis suggests fluid-DEM simulation methodologies that do not
 894 explicitly model the small scale fluid-grain interaction may need to use a closure for the
 895 angular momentum transfer, such as in Finn et al. (2016) and Guan et al. (2021), espe-
 896 cially when close to the sediment transport threshold.

4.2 What is (not) responsible for the variability in the observed sediment transport relation?

The dimensional analysis and the relevant parameter space exploration with DEM-LBM simulations lead to several conclusions, though limited to the simplest geometry (a infinite long and wide straight river) without considering vegetation or external agitation. In terms of macroscopic factors, the bed slope has little influence on the dimensionless sediment transport rate on gentle slopes (when τ^* is fixed) and is likely not responsible for the variation in flux (q^*) for a given Shields number (τ^*) in experiments (Meyer-Peter & Müller, 1948). This is not a surprise, in agreement with recent theoretical works (Maurin et al., 2018; Pächtz & Durán, 2020) about the influence of (steep) slopes on the transport relation, which give correction factors of q^* , τ^* and τ_c^* very close to 1 for gentle slopes ranging from 0.01 to 0.03.

In terms of microscopic particle properties on which this study focuses, tests that independently varied the mean particle size, surface friction coefficient, and surface damping coefficient do not appear to produce transport relations that differ much compared to the reference case at medium to high transport stages. When it is close to the transport threshold, the q^* values in these different simulation groups seem to be inversely correlated to the rotation stress which is correlated to the surface friction coefficient and damping coefficient of the particles.

Following the previous logic regarding the competition between driving factors to dislodge bed particles (collisions and interactions with fluid) countering the resistance from the contact interactions, if we look back at the factors we isolated at the beginning of this analysis, the grain shape (Kock & Huhn, 2007; Pächtz et al., 2021) as well as the hydrodynamic interaction (Camenen, 2007), and size distribution (including effects such as small particles hiding behind large neighbors), may have contributions to the variation in the transport relation. From a different perspective, large particles on river beds also control morphological stability (MacKenzie & Eaton, 2017; MacKenzie et al., 2018), which is possibly another reason. This agrees with the findings of the companion experimental work (Deal et al., 2021), in which the $q^*-\tau^*$ relation is parameterized primarily by the repose angle of the sediment particles and the ratio of the effective drag coefficient to the drag coefficient of the volume-equivalent sphere. Though the particle surface friction coefficient μ_p influences the repose angle, the influence for round particles is very limited when $\mu_p > 0.05$ (Walton, 1994; Wiacek et al., 2012; Kamrin & Koval, 2014), consistent with the fact that μ_p has a minor influence on the value of the maximum rotation stress. As a result, μ_p has negligible influence on the transport of spherical sediment particles, but may potentially have more influence on the transport of non-spherical particles.

Besides the microscopic particle properties, other factors that may also play important roles in the variation of the transport relation include the presence of external agitation (Sumer et al., 2003; Ojha et al., 2019; Cheng et al., 2020) and vegetation (Vargas-Luna et al., 2015; C. Liu et al., 2021). It should also be noted that here we have only considered the case of simple channel geometry, whereas in actual riverbeds there are a number of channel morphologic features we have not considered that can make a difference, including bedforms (Parker, 1978) and the ratio of grain diameter to flow depth, especially if boulders are present that are not fully submerged (Yager et al., 2007; Venditti, 2013; Venditti et al., 2017).

4.3 How can we formulate a useful, broadly applicable model at different scales and regimes in bedload sediment transport?

The two-phase continuum framework shown here can be used to predict the bedload transport relation with proper closures: a granular flow rule, a turbulent closure, and a drag law. The transport relation predicted by the model in the wide wall-free cases

948 matches with that from DEM-LBM simulations, giving the classical power law of $3/2$.
 949 The modeled solid packing fraction profile matches the simulation almost exactly and
 950 the solid velocity profile also matches .

951 For creep flow beneath the bed surface, the success of the NGF model, which has
 952 previously been used for dry media, suggests that the physics of cooperative grain motion
 953 giving rise to creep in fluid-submerged dense packings may be similar to that in dry
 954 packings. In our implementation here, drag forces from the fluid were homogenized from
 955 DEM-LBM simulations and applied to the NGF domain as a body force and the fluid-
 956 ity value is specified on the top as the boundary condition. Note that the NGF model
 957 does not require $\mu > \mu_1$ anywhere for non-zero flow to exist. As long as there is a fi-
 958 nite fluidity boundary condition, flow can happen all beneath μ_1 . For example, the pre-
 959 sented solution in Section 3.3 is obtained by solving the solid field in the creep zone $z \leq$
 960 $-2d_p$ with $\mu < \mu_1$ everywhere. Finite fluidity occurs at the bed surface even if $\mu <$
 961 μ_1 there because the turbulent fluid imparts fluctuations to the bed surface particles re-
 962 sulting in a fluidity source. This interpretation utilizes the result in Q. Zhang and Kam-
 963 rin (2017) that shows fluidity is in fact a measure of grain fluctuations, so any agency
 964 that imparts grain fluctuations can be a source for fluidity in a granular system. We have
 965 inferred the fluidity boundary condition from the DEM-LBM simulations, but in prin-
 966 ciple one could identify a model for the fluidity boundary conditions that depends on
 967 the turbulence. In the future we could extend the granular rheology used in our two-phase
 968 mixture model to incorporate NGF in the creeping regime, so that fluid flow and gran-
 969 ular flow fields are simultaneously computed down to the creeping flow regime. We also
 970 acknowledge that creep flows can happen when μ is below μ_1 everywhere (Houssais et
 971 al., 2015; Allen & Kudrolli, 2018), the boundary values may be what we want to predict
 972 instead of an input. See the review paper (Pächtz et al., 2020) for more insights.

973 The continuum tools we have used make a number of direct ties to the particle-scale
 974 information, which can be exploited to apply the model to other bed materials. For ex-
 975 ample some of the parameters in the drag law at the dilute limit can be calibrated with
 976 single particle settling tests. The critical stress ratio μ_1 can be approximated by the static
 977 angle of repose of the grains (even if dry). Other parameters in the granular flow rule
 978 can be calibrated with basic flow tests. For example, the nonlocal amplitude used in the
 979 creep flow model can be inferred from the decay length of the mean particle velocity in
 980 wall-bounded chute flows (Komatsu et al., 2001; D. Liu & Henann, 2017) or from an-
 981 nular Couette flow tests (Kamrin & Koval, 2012, 2014).

982 5 Conclusion

983 In this paper, sub-grain scale resolved DEM-LBM simulations of mono-disperse spher-
 984 ical sediment particles were performed and the results compared closely with data from
 985 flume experiments. The simulations was shown to match the experiments in terms of the
 986 transport relation and the detailed flow profiles of the granular material. With valida-
 987 tion in hand, the DEM-LBM tool was then used as the basis for an in-depth modeling
 988 study of sediment transport. Wide wall-free simulations were performed in order to eval-
 989 uate the factors that can potentially affect the transport relation on gentle slopes ($0.01 \sim$
 990 0.03). The slope, the mean particle size, the surface friction coefficient, and the damp-
 991 ing coefficient did not appear to influence the dimensionless transport rate for medium
 992 to high Shields number when the Shields number was fixed, for spherical sediment par-
 993 ticles. Instead, the parameters not included in the dimensional analysis may be respon-
 994 sible for a substantial fraction of the variability in the experimental transport relation
 995 on gentle slopes, including particle parameters such as the particle shape and size dis-
 996 tribution as well as vegetation, external agitation, bed forms and so on. The particle-
 997 resolved simulations also provided details about the fluid-particle angular momentum
 998 exchange. The fluid couple with respect to the center of the grain, resulting from the fluid
 999 traction over the particle surface, was shown non-negligible for the fluid entrainment near

1000 the threshold. The fluid couple was further quantified as the rotation stress, which was
 1001 found mostly concentrated near the bed surface and not correlated to the Shields num-
 1002 ber. Particle properties (e.g. surface friction coefficient) changed the observed rotation
 1003 stress, which was anti-correlated to q^* near the transport threshold, suggesting fluid-particle
 1004 angular momentum transfer may play a role in transport behavior near the threshold.
 1005

1006 **Appendix A Wall boundary condition for flume tests (boundary layer** 1007 **treatment)**

1008 To ensure the fluid velocity in the DEM-LBM simulations, it is correct is crucial
 1009 to recover the transport relation of the sediment particles. In the flume experiments (Deal
 1010 et al., 2021; Benavides et al., 2021), the flumes are narrow and tall so that the cross-sectional
 1011 fluid streamwise velocity far from the granular bed can be approximated by the law of
 1012 the wall when fully developed. According to the law of the wall, the velocity near the
 1013 wall (viscous sublayer, $y^+ < 10.8$) is linear to the wall distance $u^+ = y^+$ with $y^+ =$
 1014 $y_w u_\tau / \nu_f$, $u_\tau = \sqrt{\tau_w / \rho_f}$ and $u^+ = u / u_\tau$, where y_w is the distance to the closest wall
 1015 of the channel and τ_w is the wall shear stress. Beyond the viscous sublayer, the fluid av-
 1016 erage velocity not too close to the walls ($y^+ \geq 10.8$) can be formulated as $u^+ = \ln y^+ / 0.41 +$
 1017 5.0 . The goal of this appendix is to explain how we can recover the turbulent pure fluid
 1018 cross-sectional velocity profile in the channel without having to directly resolve the bound-
 1019 ary layer.

1020 LBM has shown the capability to simulate homogeneous isotropic turbulent flows
 1021 accurately (Yu et al., 2005), either on a high resolution mesh whose grid spacing is no
 1022 larger than Kolmogorov length scale δx_K (as known as Direct Numerical Simulations or
 1023 DNS), or a relatively coarse mesh with a turbulent closure (LES). Various papers on LBM
 1024 (Banari et al., 2015; L. Wang et al., 2016; Eshghinejadfard et al., 2017) have shown DNS
 1025 can recover the turbulent fluid velocity profile in a channel with two parallel walls. How-
 1026 ever in LBM with LES such as our simulations, the thickness of the viscous sublayer of
 1027 the boundary layer is smaller than or comparable with the grid spacing dx , leading to
 1028 a velocity jump near the boundaries. LBM based LES with a no-slip boundary condi-
 1029 tion will underestimate the fluid velocity in the channel. Here, we present a new bound-
 1030 ary technique, relating the velocity jump across the boundary layer as a slip velocity in
 1031 a Navier slip boundary condition formulation.

Uth et al. (2013) and K. Wang et al. (2018) have provided the implementation method
 of the Navier slip boundary condition in LBM. The slip boundary condition is charac-
 terized by a scalar s_{sl} , the slip length defined as the distance from the wall at which the
 linearly extrapolated relative velocity is 0. At the boundary, if f_i corresponds to the oblique
 velocity \mathbf{c}_i going into the wall, the distribution component coming out of the wall in the
 opposite direction can be made up as

$$f_{i'}(\mathbf{x}_w, t + 1) = r_1 f_i^c(\mathbf{x}_w, t) + (1 - r_1) f_{i''}^c(\mathbf{x}_w, t) \quad (\text{A1})$$

with

$$r_1 = \frac{1}{1 + \frac{s_{sl}}{dx(\tau - 1/2)}} \quad (\text{A2})$$

where $f_{i''}$ corresponds to the velocity going into the wall in the specular reflection di-
 rection (the opposite direction of $\mathbf{c}_{i''}$, see Figure 1 (c)) and the superscript ‘‘c’’ denotes
 the post-collision distribution. Substituting Eqn (4) and $s_{sl} = u_{sl} / \dot{\gamma}_{f,w}$ gives

$$r_1 = \frac{1}{1 + \frac{u_{sl}}{\dot{\gamma}_{f,w} \nu} \frac{dx}{3dt_f}} = \frac{1}{1 + \frac{u_{sl}}{\tau_w} \frac{dx \rho_f}{3 dt_f}} \quad (\text{A3})$$

where u_{sl} is the slip velocity and $\dot{\gamma}_{f,w}$ the fluid shear rate at the boundary. Since the node
 is at the wall, τ_w equals the local shear stress

$$\tau_w = ((C_s \cdot dx)^2 \dot{\gamma}_{f,w} + \nu_f) \dot{\gamma}_{f,w} \quad (\text{A4})$$

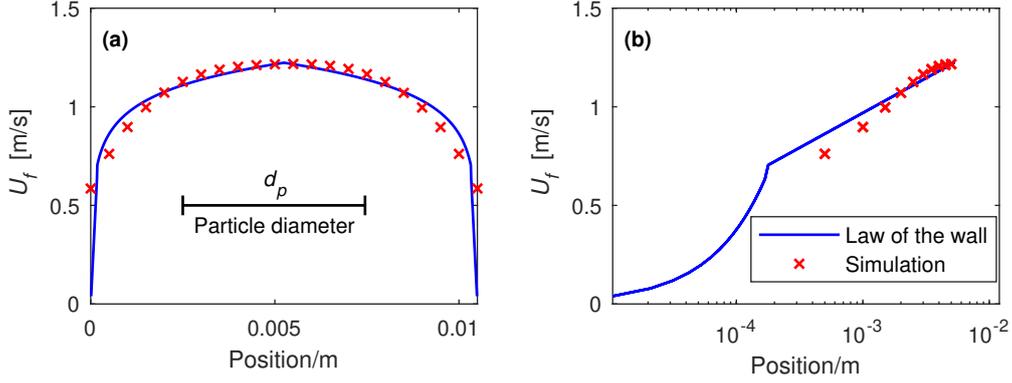


Figure A1. Turbulent pure fluid velocity across the channel: the law of the wall (solid blue line) compared with an LBM based large eddy simulation with the proposed Navier’s slip boundary condition (red crosses), in (a) linear plot, and (b) semi-log plot. The inclined angle of the flume corresponds to a moderate Shields number $\tau_* = 0.047$ in Figure 3. Note the channel is as wide as $\sim 2d_p$.

Assuming the second layer of nodes from the wall are right out of the viscous sublayer ($y^+ = 10.8$), then the dimensionless velocity there is 10.8. Extrapolating the logarithmic law to the wall gives the slip velocity as

$$u_{sl} = 2.35u_\tau. \quad (\text{A5})$$

1032 Then Eqn (A1,A3,A4,A5) together give the analytical Navier’s slip boundary condition
1033 for turbulent channel flow in LBM based LES.

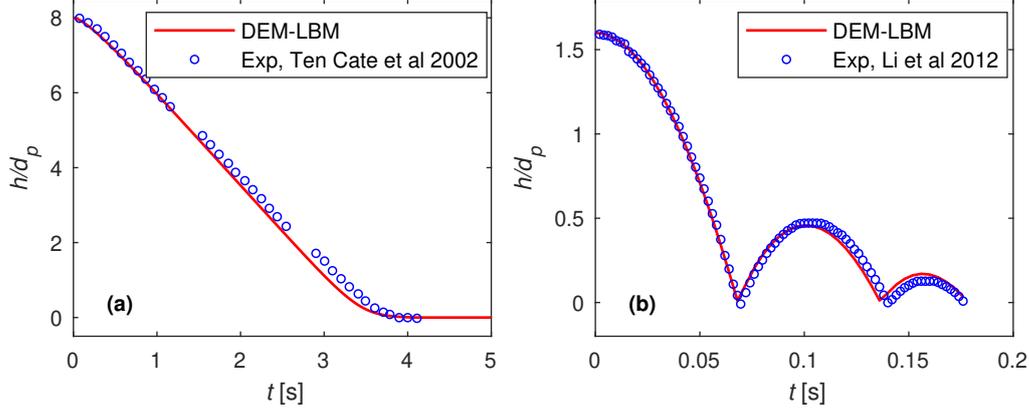
1034 Figure A1 shows the comparison between the law of the wall and an LBM based
1035 large eddy simulation with the proposed Navier’s slip boundary condition. The simu-
1036 lated fluid velocity match the law of the wall very well. This simulation also serves as
1037 a tool to calibrate the value of $C_s = 0.27$ with the resolution of $dx = 0.005\text{m}$. The
1038 value of C_s and the grid spacing are used throughout this paper for the simulations in
1039 which the fluid is water. With the help of the proposed boundary condition, the shown
1040 LBM simulation whose resolutions dx is equivalent to $\sim 15\delta x_K$, is much faster than DNS
1041 without losing much accuracy on the fluid velocity.

1042 Appendix B Validation of the DEM-LBM algorithm: single sphere set- 1043 tling, bouncing and rotation

1044 As a validation of the DEM-LBM algorithm, single particle tests are performed to
1045 examine the linear and angular momentum exchanges between fluid and solid. When an
1046 immersed particle impacts a flat surface perpendicularly, the restitution coefficient is in-
1047 fluenced by the Stokes number on collision $St_{im} = (1/9)(\rho_s d_p V_{im}/\eta)$, where V_{im} is the
1048 impact velocity (Gondret et al., 2002). Particularly, as shown by Ten Cate et al. (2002),
1049 when St_{im} is small, the sphere settles onto the surface gently without bouncing back.
1050 The bounce starts and the restitution coefficient increases as St_{im} increases above 10,
1051 and it approaches the dry value as St_{im} increases even further above 400 (X. Li et al.,
1052 2012). Herein we set up DEM-LBM simulations corresponding to the experiments in which
1053 $St_{im} = 0.19$ (a Nylon bearing in silicon oil) and $St_{im} = 65$ (a steel sphere in an aque-
1054 ous glycerol solution), representing the settling and moderate bouncing regimes respec-
1055 tively. The sphere is initially stationary and then released to descend under gravity be-
1056 fore impacting the bottom wall. The material properties are listed in Table B1.

Table B1. Material properties in the single sphere tests

		Settle	Bounce	Rotate
ρ_f	[kg·m ⁻³]	970	1203	1000
η	[Pa·s]	0.373	0.0502	0.833
ρ_s	[kg·m ⁻³]	1120	7780	2550
d_p	[mm]	15	9.5	5.2

**Figure B1.** Results of the single sphere tests as Validation of DEM-LBM. Sphere normal trajectory comparisons with experiments for (a) settling and (b) bouncing.

1057 In Figure B1 (a), the sphere is slightly denser than the surrounding viscous fluid
 1058 and settles gently at the bottom. The match of the terminal velocity (slopes of the tra-
 1059 jectories, within 5% relative error), which is reached long before landing, indicates that
 1060 the linear momentum exchange between fluid and solid is correct. The velocity of the
 1061 simulated sphere decreases slowly when it is approaching the bottom in agreement with
 1062 the experiment, showing the hydrodynamic lubrication force is resolved correctly when
 1063 solid boundaries are getting close. In Figure B1 (b), the sphere bounces multiple times
 1064 and the simulation matches the first three collisions. Capturing the above two impact
 1065 problems shows the DEM-LBM algorithm is capable of simulating the immersed parti-
 1066 cle interaction problems accurately, regardless of particle speed relative to the ambi-
 1067 ent fluid.

1068 Besides the linear momentum exchange, we also need to examine how accurate the
 1069 angular momentum is resolved because torque transfer can be evident due to the shear
 1070 flow near the bed surface in sediment transport problems. Simulations in which an im-
 1071 mersed single sphere is rotating at a fixed position are tested with the rotational vel-
 1072 ocity Ω varied by 1000 times. The fluid torque experienced by the sphere is compared with
 1073 the analytical solution of the Stoke's flow solution $T = 8\pi\eta\Omega R_p^3$ as shown in Figure B2.
 1074 The maximum relative error is smaller than 11% over the wide span of the tested rota-
 1075 tional speeds. The slight error is mostly from the discrete representation of the spheri-
 1076 cal boundaries on the fluid lattice, which could be reduced further by refining the mesh.

1077 Open Research

1078 The data, DEM-LBM solver and the continuum models are available via the fol-
 1079 lowing link: <https://doi.org/10.6084/m9.figshare.16832560> (Q. Zhang et al., 2022).

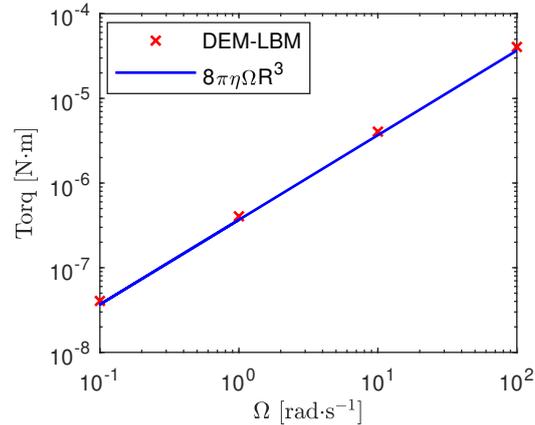


Figure B2. Fluid torque exerted on a rotating sphere over a large span of rotational velocity.

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