A new approach to inferring basal drag and ice rheology in ice streams, with applications to West Antarctic ice streams

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ABSTRACT. Drag at the bed and along the lateral margins are the primary forces resisting flow in outlet glaciers. Simultaneously inferring these parameters is challenging since basal drag and ice viscosity are coupled in the momentum balance, which governs ice flow. Here, we test the ability of adjoint-based inverse methods to infer the slipperiness coefficient in a power-law sliding law and the flow-rate parameter in the constitutive relation. We modify existing inversions by including surface strain rates into the regularization of the inversion. Using synthetic data generated with physically-motivated variations in basal drag and ice rheology, we show that this allows for more accurate inferences. We apply this method to Bindschadler and MacAyeal Ice Streams in West Antarctica. Our results show relatively soft ice in the shear margins and spatially varying basal drag, with an increase in drag with distance upstream of the grounding line punctuated by localized areas of relatively high drag. We interpret the former to reflect a combination of heating through viscous dissipation and changes in the crystalline structure. These results suggest that adjoint-based inverse methods can provide inferences of basal drag and ice rheology when the regularization is informed by strain rates.

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28 INTRODUCTION

²⁹ Mass loss from outlet glaciers in Antarctica is a primary source of uncertainty in sea-level rise projections ³⁰ (Cornford and others, 2015; DeConto and Pollard, 2016). A prerequisite to reliable projections of mass loss ³¹ from Antarctica is understanding what sets the flow speed of ice streams and outlet glaciers. The driving ³² force of ice streams is gravity, due to the sloped topography of the ice surface. However, the resisting forces ³³ of ice flow in ice streams are not fully constrained in Antarctica, and this contributes to the uncertainty of ³⁴ the response of outlet glaciers to changes in climate.

The resistance of ice streams is largely controlled by drag at the bed (Echelmeyer and others, 1994), 35 commonly related to the basal velocity through a sliding law. A typical form of the sliding law, and the form 36 taken in this study, relates the basal drag to a power of the basal velocity, with a prefactor denoted here 37 as basal slipperiness (Weertman, 1957). Basal drag represents resistance to slip at the ice-bed interface, 38 and so basal slipperiness represents the lack of resistance to slip at the ice-bed interface. Inversions for 39 the sliding-law prefactor in ice streams in Antarctica suggest that the prefactor in the sliding law can vary 40 spatially and temporally over a wide range of values due to variations in bed composition, roughness, and 41 water pressure (Joughin and others, 2004; Morlighem and others, 2013; Isaac and others, 2015). 42

The flow of ice is also constrained by viscous forces within the ice. On long timescales, ice flows as a non-43 Newtonian fluid with a viscosity that is a function of strain rate and a flow-rate parameter (the prefactor 44 in the constitutive relation). The flow-rate parameter is dependent on ice temperature, crystal size and 45 orientation, porosity, interstitial liquid water content, and the density of the ice, among other factors 46 Cuffey and Paterson, 2010). These dependencies suggest that the flow-rate parameter is not constant in 47 space or time, as deformation softens the ice through viscous dissipation and evolution of the crystalline 48 structure, further affecting deformation rates (Alley, 1988; Jacobson and Raymond, 1998; Minchew and 49 others, 2018). 50

Previous studies have used inverse methods to infer basal friction or the flow-rate parameter from suites of observations. Inverse methods are a class of methods that use observations to infer parameters of a model. The classical inverse method involves the construction of a cost function and a subsequent optimization step to minimize the misfit between the output of a model and the observations (MacAyeal, 1993). The inversions done to infer basal properties and ice rheology make use of surface velocity data, relying on the fact that basal friction and ice rheology affects surface velocity. These inverse methods also require estimates of ice thickness, surface elevation, and ice density. Gudmundsson (2003) as well as Raymond and Gudmundsson (2005) describe the effect of basal properties on surface velocity and topography, suggesting that surface velocity datasets, along with surface topography and ice thickness data, might be sufficient to infer basal properties (basal drag and basal topography). A later study confirmed that accurate inferences of basal properties can be achieved using surface velocity and topography data (Gudmundsson and Raymond, 2008).

Initial studies conducted inversions to infer a single parameter, assuming that other parameters are known (MacAyeal, 1992, 1993; MacAyeal and others, 1995; Larour and others, 2005; Morlighem and others, 2010; Habermann and others, 2012; Morlighem and others, 2013). However, there are uncertainties in multiple parameters that are not incorporated into these single inversions. In particular, both basal friction and the flow-rate parameter are unknown parameters. Assuming one is known introduces errors into the single inversion. Since both basal slip and ice rheology act as controls on the speed of flow, inferring both basal friction and the flow-rate parameter simultaneously is necessary (Arthern and others, 2015).

Previous studies have resolved multiple parameters using inverse methods. Gudmundsson and Raymond 70 (2008) used surface topography and surface velocity data to estimate basal topography and the basal drag 71 coefficient using a Bayesian inverse method. Raymond and Gudmundsson (2009) conducted the same 72 Bayesian inversion through the use of nonlinear optimization and transfer functions. Perego and others 73 (2014) inferred the basal slipperiness coefficient and basal topography using adjoint-based optimization for 74 model initialization. Other studies have inverted for basal friction and the flow-rate parameter. Arthern 75 (2015) and Arthern and others (2015) performed this inversion using Bayesian methods and iterative 76 methods with regularization. Arthern and Gudmundsson (2010) inverted for viscosity and basal friction 77 to initialize ice-flow models. Cornford and others (2015) inferred a coefficient of ice viscosity and basal 78 friction for large-scale ice sheet simulations. Hoffman and others (2018) implemented inversions for viscosity 79 and basal friction following Perego and others (2014) in a land-ice model. Finally, Gudmundsson and 80 others (2019) inferred basal slipperiness and the flow-rate parameter, in a similar method used here, over 81 Antarctica to estimate mass loss due to ice shelf thinning. 82

While these joint inversions have been accomplished using surface velocity data, no study has yet examined the performance and accuracy of jointly inferring the flow-rate parameter and basal friction. Up until now, it has been unclear whether it is possible to separate out the effects of these two parameters inferring both parameters in the same spatial location from a single dataset (Habermann and others, ⁸⁷ 2012; Arthern, 2015). In this study, we introduce a new method that incorporates strain rates into the ⁸⁸ regularization to minimize any mixing between the two parameters in the inversion. We use synthetic ⁸⁹ experiments designed to resemble natural ice streams to determine how accurate these methods are in ⁹⁰ terms of constraining both the magnitude and the distribution of the slipperiness coefficient and the flow-⁹¹ rate parameter. After showing that the inferred values agree with the true value, we apply our inversion ⁹² method to data collected over Bindschadler and MacAyeal Ice Streams, West Antarctica.

93 MODEL AND INVERSE METHOD

For this study, surface velocities are modeled using a finite element ice flow model Úa, that solves the shallow-shelf approximation (SSA; Gudmundsson and others, 2012), a vertically integrated version of the momentum equations. The following is a summary of the model and the inverse method as implemented in Úa.

Governing Equations

⁹⁹ Ice flow is governed by the Stokes equations, a reduced form of the momentum equations that neglects ¹⁰⁰ inertial terms, yielding a balance between the stress divergence and body forces:

$$\nabla \cdot \boldsymbol{\sigma} + \rho \mathbf{g} = 0 \tag{1}$$

where $\boldsymbol{\sigma}$ is the Cauchy stress tensor, ρ is the mass density of the ice, and \mathbf{g} is gravitational acceleration. The Cauchy stress σ_{ij} is related to the deviatoric stress by $\tau_{ij} = \sigma_{ij} - p\delta_{ij}$, where $p = \frac{1}{3}\sigma_{kk}$ is the mean isotropic pressure (summation notation is implied for repeated indices). We assume that ice is incompressible, such that $\nabla \cdot \mathbf{u} = 0$, where $\mathbf{u} = (u, v)$ is the velocity of the ice.

The momentum balance can be vertically integrated to obtain a reduced form of the momentum balance equations. The primary assumptions of SSA are that the vertical shear and bridging stresses (horizontal gradients of the vertical shear stresses) are negligible, ice thickness is much smaller than the length and width of the ice stream (the thin-film approximation), and the normal stresses are lithostatic, of the form $\sigma_{zz} = -\rho g(s-z)$, where s is the height of the ice surface and z is parallel to the gravity vector and positive upward, with z = 0 at the bed. The lithostatic assumption ensures σ_{zz} is zero at the ice surface. The : This manuscript is a non-peer-reviewed preprint, submitted to Journal of Glaciology, April 2020. 5

¹¹¹ resulting shallow-shelf approximation equations are:

$$\frac{\partial}{\partial x} \left[H(2\tau_{xx} + \tau_{yy}) \right] + \frac{\partial}{\partial y} \left[H\tau_{xy} \right] + \tau_{b_x} = \tau_{d_x} \tag{2}$$

$$\frac{\partial}{\partial y} [H(2\tau_{yy} + \tau_{xx})] + \frac{\partial}{\partial x} [H\tau_{xy}] + \tau_{by} = \tau_{dy}$$
(3)

where *H* is ice thickness, $\tau_b = [\tau_{b_x}, \tau_{b_y}]$ is the basal drag vector and $\tau_d = [\tau_{d_x}, \tau_{d_y}] = -\rho g H \nabla s$ is the driving stress (MacAyeal, 1989). The deviatoric stresses are related to strain rates by (Glen, 1955):

$$\tau_{ij} = 2\eta \dot{\epsilon}_{ij} \tag{4}$$

$$\eta = \frac{1}{2} A^{-\frac{1}{n}} \dot{\epsilon_e}^{\frac{1-n}{n}} \tag{5}$$

where $\dot{\epsilon}_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$ is the strain rate tensor, $\dot{\epsilon}_e = \sqrt{\frac{1}{2}} \dot{\epsilon}_{ij} \dot{\epsilon}_{ij}$ is the effective strain rate, A is the flowrate parameter, η is dynamic viscosity, and n is the stress exponent commonly taken to be 3, a reasonable assumption for the temperatures and pressures relevant to this study (Jezek and others, 1985; Barnes and others, 1971). Applying the constitutive relation (Equation 4), the momentum equations (Equations 2 and 3) can be rewritten in terms of dynamic viscosity η (and consequently, the flow-rate parameter A) and velocity gradients:

$$\frac{\partial}{\partial x} \left[2\eta H \left(2\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] + \frac{\partial}{\partial y} \left[\eta H \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right] + \tau_{b_x} = \tau_{d_x} \tag{6}$$

$$\frac{\partial}{\partial y} \Big[2\eta H \Big(2\frac{\partial v}{\partial y} + \frac{\partial u}{\partial x} \Big) \Big] + \frac{\partial}{\partial x} \Big[\eta H \Big(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \Big) \Big] + \tau_{by} = \tau_{dy} \tag{7}$$

120 Boundary Conditions

¹²¹ Mass conservation is enforced through:

$$\rho \frac{\partial H}{\partial t} + \frac{\partial}{\partial x} (\rho H u) + \frac{\partial}{\partial y} (\rho H v) = \rho a \tag{8}$$

where $a = a_s + a_b$, the sum of accumulation and ablation. A no-stress condition is applied at the surface $\boldsymbol{\sigma} \cdot \hat{\mathbf{n}} = \mathbf{0}$, where $\hat{\mathbf{n}}$ is the outward-pointing normal to the surface.

Slip at the bed is characterized by the sliding law, which relates basal velocity \mathbf{u}_b to the basal drag vector $\boldsymbol{\tau}_b$:

$$\mathbf{u}_b = -c |\boldsymbol{\tau}_b|^{m-1} \boldsymbol{\tau}_b \tag{9}$$

where m is the scalar sliding law exponent and c is the scalar basal slipperiness (representing the lack of 126 resistance the bed provides to the ice slipping over it). The sliding law exponent can vary widely, from 127 negative values to infinity for a perfectly plastic bed (Schoof, 2005, 2010; Minchew and others, 2016). This 128 exponent is commonly assumed to be m = n, which reduces the number of free parameters in the model 129 and represents viscous flow of ice around obstacles in the absence of leeward cavitation. In practice, m = 3130 describes a sliding law used for hard-bed sliding (Weertman, 1957), currently most commonly-used in ice-131 sheet modeling, and constraining the value of the sliding exponent is an area of active research (Joughin 132 and others, 2019). 133

134 Inverse Method

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The inverse method is implemented in Úa and the setup is summarized here. This method minimizes a cost function J = I + R where I is the misfit of the surface velocities:

$$I = \frac{1}{2\Omega} \int \int \left[\left(\frac{|u - u_{obs}|}{u_{err}} \right)^2 + \left(\frac{|v - v_{obs}|}{v_{err}} \right)^2 \right] dxdy \tag{10}$$

where (u, v) are the modeled surface velocities, (u_{obs}, v_{obs}) are the observed surface velocities, (u_{err}, v_{err}) are the formal errors in the observed surface velocities, and Ω is the area of the model domain. These inversions are ill-posed, and thus regularization is needed, particularly in the presence of measurement errors or errors in estimation of ice thickness (Habermann and others, 2012). Here, we use a Tikhonov regularization term defined as:

$$R = \frac{1}{2\Omega} \iint g_{a_A} (A - A_p)^2 + g_{a_c} (c - c_p)^2 + g_{s_A} (\nabla (A - A_p))^2 + g_{s_c} (\nabla (c - c_p))^2 dx dy$$
(11)

where A is the current estimate of the flow-rate parameter and A_p is the prior value of the flow-rate parameter. Similarly, c is the current estimate of the slipperiness coefficient and c_p is the prior value of the slipperiness coefficient. Prior values represent the information known about the parameters prior to the inversion. Tikhonov regularization encourages smooth solutions that are close to the prior values.

The regularization coefficients $g_{a_A}, g_{a_c}, g_{s_A}, g_{s_c}$ can be chosen to ensure the regularization terms remain of a similar magnitude to each other and to the misfit term. The regularization coefficient g_{a_i} , where i = [A, c], controls the departure from the prior (A_p, c_p) , and the coefficient g_{s_i} controls the gradient. The minimization problem $\min_{c,A} J(c, A)$ is solved using a quasi-Newton method (Gudmundsson and others, 2012). The adjoint method is a computationally effective method of computing the gradient of the cost function with respect to A and c. More details on the use of adjoints and Lagrange multipliers in inverse problems are provided in Joughin and others (2004) and Morlighem and others (2013).

153 SYNTHETIC EXPERIMENTS

154 Synthetic Ice Stream

To test the inverse methods described above, we constructed a synthetic ice stream that resembles Antarctic 155 ice streams in terms of the geometry and mechanical properties. The synthetic ice stream is 20 km wide 156 and 200 km long. The ice is 1 kilometer thick upstream and decreases downstream, similar to ice streams 157 in Antarctica (Fretwell and others, 2013). The boundary conditions on the lateral margins are no-slip, and 158 the upstream and downstream boundary conditions are given by a prescribed input flux and hydrostatic 159 pressure, respectively (Gudmundsson and others, 2012). The model domain encompasses the grounded ice 160 stream with the domain boundary located immediately downstream of the grounding line. The resolution 161 of the forward model is higher than the variability of the inferred fields. 162

The true values of basal slipperiness and the flow-rate parameters are set to mirror natural fluctuations in these parameters (first column of Figure 1). Since relatively rapid rates of deformation occur in shear margins enabling multiple processes that enhance creep, we expect ice to be softer in the margins. We approximate the structure of the flow-rate parameter by a transversely-varying cosine curve, in which the flow-rate parameter is highest in the margins of an ice stream and reaches a minimum in the middle of an
ice stream. Thus, we set the true value of the flow-rate parameter in the synthetic ice stream to be

$$A_{\rm true} = A_r - \frac{A_r}{2}\cos(\frac{2\pi y}{L_y}) \tag{12}$$

where L_y is the width of the ice stream (such that $-\frac{L_y}{2} \le y \le \frac{L_y}{2}$) and $A_r = 1.6729 \times 10^{-7} \text{ a}^{-1} \text{ kPa}^{-3}$, a tabulated value for temperate ice (Cuffey and Paterson, 2010).

The magnitude of the slipperiness coefficient varies spatially. Previous inversions have found sticky patches in which basal slipperiness is low and fast-flowing patches in which basal slipperiness is high (MacAyeal, 1992; Joughin and others, 2004). Here, we approximate this spatial variation this through Gaussian bumps representing "slippery patches", or localized increases in basal slipperiness:

$$c_{\text{true}} = 1 + \sum_{i} a_{i} \exp\left\{-\frac{(x-x_{i})^{2}}{s_{x}} - \frac{(y-y_{i})^{2}}{s_{y}}\right\}$$
(13)

where a_i are a series of coefficients that determine the magnitude of slipperiness in m a⁻¹ kPa⁻³, x_i and y_i are the spatial coordinates of the Gaussian bump, and s_x, s_y determine the width of the bump in the xand y-direction. The values of a_i, x_i, y_i are given in Table S1 of the Supplement.

178 Results of Synthetic Experiments

To test whether current inversion methods can resolve ice rheology parameters and basal slipperiness in 179 both space and magnitude, we generate synthetic observations by using the true parameters defined in 180 Equations 12 and 13 in the forward model. The synthetic observed velocity, which we use without added 181 measurement errors, mirrors surface velocity of many ice streams in Antarctica: a parabolic across-flow 182 profile arises due to no-slip boundary conditions in the lateral margins and the flow velocity increases 183 towards the grounding line due to the sloped surface. Surface velocity misfit is defined as the difference 184 between the observed and modeled surface velocity scaled by data errors. For the synthetic tests, we 185 assume errors are 1 m a^{-1} . The stopping criterion for the inversion used here is based on the magnitude of 186 the surface velocity misfit: the inversion is considered finished when the difference between observed and 187 inferred velocity falls below data errors (in the synthetic case, the absolute value of the misfit is less than 188

189 unity).

We set spatially constant prior values: $A_p = A_r, c_p = 1 \text{ a}^{-1} \text{ kPa}^{-3}$. This is equivalent to assuming little 190 prior knowledge of the structure of basal slipperiness and some prior knowledge of the ice temperature. 191 since we can compute the magnitude of the flow-rate parameter based on tabulated values for ice of a 192 given temperature (Cuffey and Paterson, 2010). The results of two synthetic tests are shown in the second 193 and third columns of Figure 1 respectively. The first test is the standard inversion with spatially constant 194 regularization values (shown in Table S2 of the Supplement). The second test considers the use of strain 195 rates in the regularization as a method of spatially separating the parameters in the inversion (values also 196 shown in Table S2 of the Supplement). 197

198 Classical Regularization

For an inversion with spatially constant priors and regularization values (second column of Figure 1), the misfit (defined as the difference between observed and modeled surface velocities, scaled by data errors) falls between -1 and 1. The inferred slipperiness distribution captures the spatial variability of the true distribution. It contains all the Gaussian peaks prescribed in the true distribution. However, the errors (true - inferred) in slipperiness are approximately of the same order as the highest peaks in the true distribution, suggesting that the classical inversion method fails to resolve fully the variability in magnitude.

This classical inversion was also able to resolve the broad characteristics of the spatially distributed 205 flow-rate parameter. There are localized areas with overestimated values of the flow-rate parameter in the 206 trunk of the ice stream. The highest scaled error is in the centerline. This high error in the centerline is 207 likely due to the peaks in the slipperiness distribution being picked up in the flow-rate parameter. We refer 208 to this behavior as mixing, which we define as misattribution of structure from one parameter to another. 209 This test suggests that this inversion on a synthetic ice stream can resolve the broad properties of 210 spatial distributions of both the slipperiness parameter and the flow-rate parameter, though with some 211 error. In particular, the inversion struggles to capture high magnitude in the slipperiness coefficient and 212 results in mixing between the two estimates. 213

214 Regularization with Strain Rates

We now test whether the inclusion of strain rates in the regularization of the inversion might mitigate mixing between the two parameters we are inverting for. We weigh the coefficients for the flow-rate



Fig. 1. Results from two tests of the inverse method conducted on a synthetic ice stream. The left column shows "observed" velocity (synthetic velocity set as measured velocity in the inversion), the prescribed "true" slipperiness distribution (with slippery spots represented as Gaussian spikes), and the prescribed "true" flow-rate parameter distribution (with high values in the lateral shear margins, where ice is softer due to viscous deformation). The middle and right column present results of tests, with velocity misfit defined as the difference between the observed and inferred surface velocity, scaled by data errors (in this case, $u_{err} = 1 \text{ m a}^{-1}$). The middle column presents results with spatially constant regularization coefficients, in which the inversion captures the spatial variability of both distributions but there is mixing in the centerline of the flow-rate parameter distribution. The right column presents results from an inversion where the flow-rate parameter regularization coefficients are scaled by strain rates (Equation 14). Employing strain rates in the inversion reduces the mixing in the flow-rate parameter distribution and improves the estimation of the magnitude of slippery spots in the slipperiness distribution. Figure S1 of the Supplement shows the strain rate field.

parameter g_{s_A}, g_{a_A} in grounded ice by the inverse of the strain rates. This effectively penalizes changes in the flow-rate parameter in areas with low strain rates, such as near or along the centerline, which creates spatial disjointness in the inversion. The inversion puts more weight on the slipperiness parameter in the centerline, where most of the changes in the slipperiness parameter are focused, and more weight on the flow-rate parameter in areas of high deformation rates, such as the lateral shear margins. Rheology can be inferred most accurately in rapidly deforming regions, so prioritizing estimates of the flow-rate parameter in small areas of high shear is physically justifiable as well as methodologically sound. On the ice shelf, there is negligible basal drag $(c \to \infty)$, so we only apply the strain rates in the regularization to grounded ice. The resulting regularization function is

$$R = \frac{1}{2\Omega} \int \int \frac{g_{a_A}}{k_1 f + (1-f)\dot{\epsilon}_e} (A - A_p)^2 + g_{a_c}(c - c_p)^2 + \frac{g_{s_A}}{k_2 f + (1-f)\dot{\epsilon}_e} |\nabla(A - A_p)| + g_{s_c} |\nabla(c - c_p)| dxdy$$
(14)

where $\dot{\epsilon}_e$ is the observed effective strain rate, f is a flotation mask, where f = 1 denotes floating ice and f = 0 denotes grounded ice. The terms $\frac{g_{a_A}}{k_1}$ and $\frac{g_{s_A}}{k_2}$ give the regularization coefficients that would be used without strain rates, to ensure that the regularization balance is maintained across the grounding line. The regularization coefficients are presented in Table S2 of the Supplement and the variation in the coefficients over the ice streams is visualized in Figure S1 of the Supplement.

The third column of Figure 1 shows the result of the inversion that includes strain rates in the reg-220 ularization. The misfit decreases to a small value in comparison to the average velocity. The inversion 221 continues to capture the spatial variability of the slipperiness field when including the strain rates. The 222 errors in some of the peaks of the slipperiness distribution are smaller with the strain rates than without, 223 suggesting that the strain rates may have enabled more accurate resolution of magnitude. This inversion 224 also captures the spatial variability of the flow-rate parameter, with relatively high values in the margins. 225 There is decreased mixing in the centerline, suggesting that the inclusion of strain rates in the regular-226 ization partitions the domain into regions where ice is deforming relatively rapidly and the model is more 227 sensitive to values of the flow-rate parameter, and regions where there is little deformation in the ice and 228 thus low sensitivity to the values of the flow-rate parameter. However, there is systematic overestimation 229 of the flow-rate parameter near the grounding line by about a factor of 2. This is likely due to increasing 230 strain rates towards the grounding line (Supplement Figure S1), and may be mitigated by a more spatially 231 variable regularization coefficient. We expect that for such a small overestimate (less than a factor of 2), 232

the effect on the results for Antarctic ice streams is likely to be minimal. We reserve further exploration of this overestimate for future work.

This synthetic test considers the case of high frequency spatial variability in basal slipperiness, which 235 is often the case for some Antarctic ice streams. However, many ice streams have lower frequency spatial 236 variability in basal slipperiness. We conducted tests on a slipperiness field with smaller (in magnitude of 237 the peak) Gaussian spikes and a long-wavelength background field that increases the slipperiness closer 238 to the grounding line. The regularization coefficients are presented in Table S3 of the Supplement, the 239 regularization coefficients in Figure S3 of the Supplement, and the results in Figure S3 of the Supplement. 240 The inversion resolves spatial distributions in both parameters, with less dramatic mixing even in the case 241 without strain rates. The minimization of mixing may be because the two parameters vary in different 242 directions (basal slipperiness varies along the flow and the flow-rate parameter varies across flow) and thus 243 there is an inherent spatial disjointness in the inversion. Because of the lower magnitude of the Gaussian 244 spikes, the inversion is slightly better at resolving variations in magnitude. We consider here only the case 245 of ice streams and reserve for future work a thorough investigation of more complex spatial variations in 246 basal slipperiness, the flow-rate parameter, and the geometry of the glacier that may be expected in areas 247 other than ice streams. 248

While in these synthetic tests, we approximate "slippery patches" in the basal slipperiness field, in which 249 the magnitude of the Gaussian bumps are larger than the mean field, many studies have found evidence 250 of "sticky patches" in Antarctic ice streams, a localized decrease in basal slipperiness. Figure S4 in the 251 Supplement presents the results of a similar test with "sticky patches", in which the Gaussian bumps are 252 less than the mean field. Here, we see similar results to the test presented here. The inversion captures 253 all of the spatial variation in basal slipperiness, with the exception of one misplaced sticky spot. The 254 inversion captured the sharp increase in the flow-rate parameter in the shear margins and the flow-rate 255 parameter field shows little mixing between the estimates, likely due to the inclusion of strain rates in the 256 regularization. 257

The above tests are conducted without added errors in observed velocities. Surface velocity datasets, widely available, are extensive in coverage and have errors much smaller than the magnitude of surface velocity on Antarctica (Gardner and others, 2018). However, any uncertainties in the surface velocity datasets would impact the results of the inversion. Results from a synthetic inversion using measurement errors suggest that, while errors in surface velocity would add noise to the inferred distribution, the large: This manuscript is a non-peer-reviewed preprint, submitted to Journal of Glaciology, April 2020. 13 scale structure and magnitude of basal slipperiness and the flow-rate parameter would still be quite accurate.

264 BINDSCHADLER AND MACAYEAL ICE STREAMS

The ice streams on the Siple Coast, West Antarctica, are of particular interest to the study of ice flow in outlet glaciers because these ice streams slip over weak sediment, introducing the possibility that shear stress in the lateral margins plays a significant role in controlling ice flow (MacAyeal, 1992; Echelmeyer and others, 1994; Joughin and others, 2004). As a result, the ice streams on the Siple Coast are appealing targets for applying the methods developed above and offer natural laboratories for studying shear-margin processes. Here, we infer basal slipperiness and ice rheology over two Siple Coast ice streams, Bindschadler and MacAyeal Ice Streams, using inverse methods that include strain rates in the regularization term.

272 Model and Data

Previous studies have applied inverse methods similar to those described above with "classical" regulariza-273 tion (e.g., Joughin and others, 2004), but increased quantity and quality of satellite data in the last few 274 years enables more accurate inversions. Inversions require data on bed topography, surface elevation, and 275 surface velocity. Ice-penetrating radar data are used to derive bed topography, and in Figure 2c we show 276 the radar coverage for Bedmap2, overlaid with contours of observed surface velocity (magenta line; Gard-277 ner and others (2018)). While extensive in the ice streams, particularly in Bindschadler Ice Stream, radar 278 coverage contains gaps evident in the shear margins. Fretwell and others (2013) estimates the uncertainty 279 in the bed elevation to be approximately 60 meters in the Siple Coast. We use surface topography data 280 from the Reference Elevation Model of Antarctica (REMA) (Figure 2b), which computes surface elevation 281 from satellite imagery (Howat and others, 2019). Here, we use the filled elevation data with a spatial res-282 olution of 200 m. The elevation error is estimated to be approximately 0.15 m to 1.2 m in the Siple Coast 283 (Howat and others, 2019). Ice thickness (Figure 2f) is computed from the difference of REMA elevation 284 data (Figure 2b) and basal topography from Bedmap2 (Figure 2d) (Fretwell and others, 2013; Howat and 285 others, 2019). 286

Surface velocities (Figure 2e) are found from Landsat 7 and 8 satellite data from 2013-2015 and the velocity uncertainties are taken on average to be 30 m a^{-1} (Gardner and others, 2018), which is the error we set for the inversion. The fast flowing regions are approximately 600 m a^{-1} , and the branches of the ice stream are around 300 m a^{-1} . The observed grounding line are defined from Bedmap2 (Fretwell and others, 2013) and is outlined in green in all panels. The effective strain rates (Figure 2g), computed from the gradient of the observed velocity fields, demonstrate the high levels of deformation found in the margins. The mean driving stress (Figure 2h) is 20kPa and shows a generally decreasing trend with increasing surface velocity, indicating that slip along the bed is the dominant flow regime (Supplement Figure S6).

The model domain, boundary conditions, and mesh represent the grounded ice streams and proximal 295 regions of the ice shelf. The mesh of the model, constructed in Úa, is refined using observed effective strain 296 rates. We use a relatively fine mesh of approximately 24,000 nodes and 48,000 elements, resulting in a 297 spatially varying spatial resolution of a few kilometers (between 1 to 10 kilometers, with finer resolution 298 in areas of high strain rates). The grounding line in Ua is defined by the flotation condition and closely 299 matches the grounding line of Bedmap2 for the given geometry, though it does not capture some pinning 300 points on the ice shelf, because these features are not represented in the Bedmap2 bathymetry (Figure 2d). 301 The boundary conditions are prescribed to be no-slip at the edges of the grounded model domain, which is 302 chosen to lie only in areas with slow-flowing ice, and are set to be the observed velocities where the model 303 domain is over floating ice. 304

The inversion is initiated with spatially constant priors. Based on tabulated values of the temperaturedependent flow-rate parameter (MacAyeal and others, 1995; Cuffey and Paterson, 2010), we estimate the ice temperature to be -10° C, leading to an initial, spatially constant value of the flow-rate parameter $A_0 = 1.15 \times 10^{-8} \text{ a}^{-1} \text{ kPa}^{-3}$ (Cuffey and Paterson, 2010). We prescribe the initial value of the slipperiness coefficient to be $c_0 = 0.01 \text{ m a}^{-1} \text{ kPa}^{-3}$ everywhere. We use strain rates in the regularization coefficients as in Equation 14 and show the regularization coefficients in the Supplement Figure S5.

311 **Results**

Inferred values of basal slipperiness and the flow-rate parameter yield a relatively good fit to the observed velocity fields (Figure 3). The surface velocity misfit (defined as the difference between the observed and modeled surface velocity scaled by $u_{err} = 30 \text{ m a}^{-1}$) is within (-2, 2) (Figure 2a), with no obvious structure to the misfit. Areas of high misfit are generally collocated with gaps in radar coverage (Figure 2c) and errors in the modeled grounding line (Figure 3a), so we do not expect further reductions in the misfit.

Higher values of the slipperiness distribution extend along the two ice streams. Areas of particularly high slipperiness occur in fast-flowing regions. The maximum slipperiness is approximately $25 \text{ m} \cdot \text{a}^{-1} \cdot \text{kPa}^{-3}$ near where Bindschadler and MacAyeal Ice Streams merge. Elevated slipperiness extends 120km upstream



Fig. 2. Model domain and data used in the inversion: (a) the red outline in the inset shows the location of the model domain, with grounded ice in light grey and floating ice in dark grey. Optical imagery of Bindschadler and MacAyeal Ice Streams from Mosaic of Antarctica (Scambos and others, 2007), (b) surface elevation from the Reference Elevation Model of Antarctica (REMA), (c) radar coverage used to produce bed topography, (d) bed topography from Bedmap2, (e) surface velocity derived from a combination of Landsat 7 and Landsat 8 satellite imagery (Gardner and others, 2018), (f) ice thickness computed as the difference of surface elevation from REMA and bed topography from Bedmap2, (g) effective strain rates ($\dot{\epsilon}_e = \sqrt{\frac{1}{2}\dot{\epsilon}_{ij}\dot{\epsilon}_{ij}}$) computed from surface velocity observations (panel e), (f) driving stress computed from the product of ice thickness (panel f), ice density, and surface slope.



Fig. 3. Model misfit and inferred values of basal slipperiness (c) and the flow-rate parameter (A). (a) The velocity misfit (the difference of observed and modeled surface velocity divided by data errors) is within the data errors (|misfit| < 1) over most of the model domain. High misfit regions line up with areas of poor radar coverage (Figure 2c) while areas of good radar coverage have |misfit| < 1. (b) The estimate of basal slipperiness shows increased slipperiness towards the grounding line of Bindschadler Ice Stream and highest values of slipperiness nearest the grounding line. (c) The estimate of the flow-rate parameter has high values that line up with the margins of the ice streams and a less pronounced southern shear margin on the ice shelf of Bindschadler Ice Stream. Dashed lines in panels b and c represent 100 m \cdot a⁻¹ velocity contour.

in Bindschadler Ice Stream with little spatial variability and tapers off as the ice stream narrows. Lower values of slipperiness along MacAyeal correspond to sticky spots that have been identified by previous inversions (MacAyeal, 1993; MacAyeal and others, 1995; Joughin and others, 2004) and are colocated in areas with steep surface slopes (Figures 2a,h).

The flow-rate parameter is higher in the lateral shear margins of both ice streams. Rapid rates of deformation manifest in the margins, which can result in high rates of work. Some of this work is irreversibly converted to heat, which warms cold ice and melts temperate ice (e.g. Schoof (2004, 2012); Perol and Rice (2015); Schoof and Hewitt (2016)), while the rest is accounted for by recrystallization processes. The flow-rate parameter increases with temperature, liquid water content, and development of fabric, and thus is higher in the shear margins.

Some spatial variability in the inferred flow-rate parameter may be a product of the inversion. In particular, variability on the ice shelf may be due to errors in the modeled grounding line (Figure 3a). There is a sudden decrease in the flow-rate parameter where there is a lack of radar coverage (Figure 2c) and an increase in velocity misfit (Figure 3a). Given the results of synthetic tests, values of the flow-rate parameter near the grounding line may be overestimated and the values upstream may be underestimated. However, with inclusion of strain rates, the variability in the centerline of Bindschadler and MacAyeal is likely due to ice deformation rather than mixing or other errors.

337 Discussion

338 Basal Processes

We compute basal drag (Figure 4a) from basal slipperiness through the sliding law (Equation 9) and find 339 basal drag in the slower-flowing regions upstream to be between 120 kPa and 160 kPa, while basal drag in 340 fast-flowing regions is of order 1-10 kPa. These results are consistent with previous studies: MacAyeal and 341 others (1995) found basal stress values to vary from 0.01 kPa to 100 kPa along MacAyeal Ice Stream, while 342 Joughin and others (2004) expanded this study to both Bindschadler and MacAyeal Ice Streams, finding the 343 maximum of basal stress values to be approximately 120 kPa. Outside of the ice streams, drag is generally 344 higher (~ 100 kPa), with the exception of the ridges and southern shear margin of Bindschadler Ice Stream, 345 where surface slopes are shallow. There is increased basal drag south of the southern Bindschadler shear 346 margin immediately upstream of the grounding line, which may direct the flow inward as the ice stream 347 flows onto the ice shelf, thereby playing an important role in controlling the width of the ice stream. 348

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Spatial variability of basal drag is higher in MacAyeal Ice Stream than in Bindschadler Ice Stream. In particular, sticky spots are evident along MacAyeal Ice Stream as localized points of high drag and coincide with steep surface topography (Figure 2a,h). These sticky spots have been identified in past work as well (MacAyeal, 1993; MacAyeal and others, 1995; Joughin and others, 2004). These sticky spots are colocated with changes in bed topography (Figure 2d), and previous studies suggest that they are a result of topographic changes, rather than changes in the subglacial hydrologic systems (MacAyeal, 1992; MacAyeal and others, 1995).

To the best of our knowledge, the ice streams on the Siple Coast are underlain by deformable till (Kamb, 1991; MacAyeal and others, 1995). Past studies suggest that this till is water-saturated, and thus basal drag does not balance the driving stress (MacAyeal and others, 1995; Joughin and others, 2004). Our results support this supposition: the ratio of basal drag to driving stress is less than one over most of the ice streams (Figure 4b). The fact that driving stress is insufficient to balance the driving stress indicates lateral shear stress at the margins is an important factor in controlling the flow. This is further discussed in the next section.

Laboratory tests indicate that the subglacial till collected from beneath some ice streams in West 363 Antarctica can be well approximated as a perfectly plastic material, meaning that the shear strength of 364 the till is independent of the rate of deformation (Kamb, 1991; Iverson and others, 1998; Tulaczyk and 365 others, 2000b,a; Zoet and Iverson, 2018). This has been further supported by model results: Iverson and 366 Iverson (2001) found that displacement profiles of till are well reproduced from a plastic bed. The yield 367 stress of a perfectly plastic material τ_* can be described by the Mohr-Coulomb criterion $\tau_* = c_0 + \mu N$ 368 (Kamb, 1991; Tulaczyk and others, 2000b), in which c_0 is the apparent cohesion, $\mu = \tan \phi$ is the internal 369 friction coefficient (with ϕ being the internal friction angle), and $N = \rho g H - p_w$ is the effective pressure, 370 where p_w is pore water pressure. From laboratory tests, Tulaczyk and others (2000a) and Iverson (2010) 371 found that cohesion is negligible and $\mu \approx \frac{1}{2}$. The yield stress then becomes $\tau_* = \frac{1}{2}N$. We assume that 372 deformation of the bed facilitates fast flow (MacAyeal and others, 1995) and thus take the basal stress 373 beneath Bindschadler and MacAyeal Ice streams to be equal to the yield stress. We then compute the 374 effective pressure (Figure 4c) and pore water pressure (Figure 4d) from the inferred basal drag. 375

The effective pressures are low along the length of the ice streams compared to the overburden pressure (overburden pressure is of order 10 MPa, effective pressure is of order 100 kPa). The pore water pressure is comparable to the overburden pressure, supporting the notion that the bed is water-saturated and helping



Fig. 4. Estimates of (a) basal drag, which shows low drag over most of the fast-flowing regions and prominent sticky spots along MacAyeal, (b) the ratio of basal stress to driving stress, indicating that basal drag does not balance driving stress over much of the ice streams. High frequency variations in the ice streams arise from disparities in spatial resolution. (c) log of effective pressure, which shows, among other things, the sticky spots in MacAyeal Ice Stream, (d) log of pore water pressure, which is roughly equivalent to the overburden pressure, suggesting water-saturated till beneath Bindschadler and MacAyeal Ice Streams. Dashed lines represent 100 m \cdot a⁻¹ velocity contour. The ice shelf is shown in grey where basal drag is negligible and not inferred in the inversion.

to explain how comparatively low driving stresses can result in high surface velocity. Engelhardt and Kamb (1997) used borehole measurements to determine the effective pressure of the till underneath Whillans Ice Stream (located to the south of Bindschadler and MacAyeal Ice Streams) and found the effective pressure to range from -30 kPa to 160 kPa, which supports our findings of an effective pressure orders of magnitude less than the overburden pressure.

Estimates of effective pressure are only valid where the assumption of a yielding bed is valid. This occurs in the fast-flowing sections of the ice streams (seen by the contours of velocity in Figure 4). Outside of the ice stream, this assumption does not hold and thus estimates of effective pressure and pore water pressure are not reliable.

Spatial variability in effective pressure (Figure 4c) may be a result of variations in pore water pressure 388 and ice thickness. Due to low gradients in pore water pressure (Figure 4d), the southern shear margin 389 appears to be pinned by locally elevated effective pressures that arise from locally elevated overburden 390 pressure, rather than locally reduced pore water pressure. The importance of overburden pressure in 391 elevating the effective pressure is in contrast to the findings of Meyer and others (2018), who proposed that 392 the margin was pinned by a locally reduced pore water pressure facilitated by a subglacial channel fed by 393 meltwater from the shear margin. However, the coarse spatial resolution of our inferences, the gap in radar 394 coverage (Figure 2c), and the smoothness in the slipperiness distribution imposed by the regularization do 395 not necessary contradict the findings of Meyer and others (2018). 396

From the small gradients of the pore water pressure, we infer relatively low flux of water at the bed. This is consistent with low rates of meltwater production and a saturated bed. However, these results are constrained by the resolution of our estimates and the fact that the regularization imposes smoothness and thus inferences of the gradient of pore water pressure may not capture high-frequency spatial variability.

401 Shear Margin Processes

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Since the basal stress does not balance the gravitational driving stress (Figure 4b), lateral shear stresses in the margins are important resistances to the flow. Therefore the flow of the ice stream does a lot of work on the ice in the shear margins. The rate of work done during viscous deformation is $\Phi = \sigma_{ij} \dot{\epsilon}_{ij}$ (Jacobson and Raymond, 1998; Schoof, 2004; Schoof and Hewitt, 2016; Hewitt and Schoof, 2017), where σ_{ij} is the Cauchy stress tensor (Equation 1). Under the assumption of incompressibility and applying the constitute : This manuscript is a non-peer-reviewed preprint, submitted to Journal of Glaciology, April 2020. 21 relation for ice (Equation 4):

$$\sigma_{ij}\dot{\epsilon}_{ij} = \tau_{ij}\dot{\epsilon}_{ij} \tag{15a}$$

$$=2A^{-\frac{1}{n}}\dot{\epsilon}_{e}^{\frac{1+n}{n}} \tag{15b}$$

Rates of deformation are highest in the lateral shear margins, and so the work rate is higher in the shear margins than in the trunk of the ice streams and surrounding ridges (Figure 5a). Since the work done on the ice goes into recrystallization processes or is dissipated as heat, we expect heating and the evolution of crystalline fabric to be higher in the margins as well, resulting in softer ice in lateral shear margins. The variability in the work rate on the ice shelf also reflects the variability in the inferred flow-rate parameter (Figure 3c) and the observed effective strain rates (Figure 2g).

Higher inferred values of the flow-rate parameter in the shear margins suggests localized warming of ice 408 (Jezek and others, 1985; Suckale and others, 2014). Localized warming can occur from internal heating due 409 to viscous deformation (Jacobson and Raymond, 1998; Schoof, 2004, 2012), which may generate interstitial 410 meltwater, enabling enhanced deformation of the ice (Hewitt and Schoof, 2017; Haseloff and others, 2019). 411 Observational evidence supports internal heating in areas of high deformation (Harrison and others, 1998) 412 and gaps in the radar coverage in the shear margins (Figure 2c) are consistent with higher radar attenuation 413 in warming ice (Schroeder and others, 2016). Our findings are also consistent with previous modeling 414 studies. For example, Jacobson and Raymond (1998), Suckale and others (2014), and Perol and Rice 415 (2015) use thermomechanical models to suggest that heat generated may be significant enough to produce 416 temperate ice in shear margins of Antarctic ice streams, and Meyer and others (2018) and Meyer and 417 Minchew (2018) show this may be true in Bindschadler Ice Stream. 418

Internal heating may have implications for ice stream dynamics beyond the softening of ice in the shear 419 margins. Previous studies have proposed the interaction between heating in shear margins and drainage 420 at the bed as a mechanism for control of shear margin location. Perol and Rice (2015) and Perol and 421 others (2015) suggested the temperate ice in shear margins may support less lateral stress than the colder 422 ice towards the center of the ice stream, necessitating an increase in basal strength. They attribute this 423 increase in basal strength to the development of a channelized drainage system at the bed, which should 424 result in a decrease of pore water pressure in margins of ice streams. Meyer and others (2018) applied 425 this theory to the southern shear margin of Bindschadler Ice Stream and found evidence for a channelized 426



Fig. 5. (a) Work rate (computed from the inferred flow-rate parameter), which is high in the margins where there are increased levels of deformation and thus heat generation through viscous dissipation. (b) The ratio of inferred flow-rate parameter to the flow-rate parameter for temperate ice $A_0 = A_r = 1.67 \times 10^{-7} \text{ a}^{-1} \cdot \text{kPa}^{-3}$, which is greater than 1 in some regions of the lateral shear margins. (c) An estimate of the flow-rate parameter ("effective A_T ") found from the 1D thermomechanical model derived in Meyer and Minchew (2018). (d) The ratio of effective A_T to the inferred A found by the inversion.

drainage system near temperate zones and locally decreased pore water pressure. They suggest this may be
a control on the width of Bindschadler Ice Stream. The formation of these drainage systems are dependent
on significant meltwater production in shear margins.

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However, internal heating may not be the sole softening mechanism. The formation of crystallographic 430 preferred orientation (fabric) can also soften ice. In Figure 5b, we compare the ratio of our inferred 431 flow-rate parameter to the flow-rate parameter value corresponding to temperate ice $(A_r, \text{ given by Cuffey})$ 432 and Paterson (2010)). There are large regions, localized mainly along the shear margins, where the ratio 433 $A > A_r$. Since the temperature of ice cannot exceed the melting temperature throughout the ice column, 434 the regions where the ratio exceeds one are difficult to explain simply by ice temperature. These high 435 values may be explained by the presence of interstitial meltwater, enabling faster flow as described above. 436 This could also be evidence of ice softening due to the existence of fabric. The existence of fabric would 437 suggest that not all of the work done through viscous deformation is dissipated as heat. 438

We find evidence for potential fabric effects on the flow-rate parameter by comparing the depth-averaged 439 value of the flow-rate parameter given by a thermomechanical model to that inferred in our inversions. We 440 use a model of ice temperature from Meyer and Minchew (2018), which considers the effects of vertical 441 advection and diffusion, to find a depth-averaged flow-rate parameter ("effective A_T "), assuming a solely 442 temperature-dependent flow-rate parameter (Figure 5c). The ice shelf is not considered here since the 443 thermomechanical model can not account for spatial variability in the inferred values of the rate factor in 444 areas of the ice shelf that do not show high shear strain rates. The structure of effective A_T is similar to 445 the flow-rate parameter estimated by our inversion, providing a check that our inversion results agree with 446 a thermomechanical model. 447

The effective A_T values in the shear margins are on average two orders of magnitude lower than those 448 found by our inversion in the shear margins (Figure 5d). This could either suggest that inversion is 449 overestimating the flow-rate parameter throughout the ice stream margins or may be evidence that fabric 450 effects play a significant role. The results of synthetic tests (Figure 1) lead us to believe that we are 451 not overestimating the flow-rate parameter throughout the margins (if any overestimation is occurring, 452 it is likely concentrated near the grounding line). These results agree with Minchew and others (2018), 453 who found that changes in fabric increases the flow-rate parameter by an order of magnitude, consistent 454 with a single maximum fabric. Fabric development, influenced by recrystallization processes and resulting 455 in anisotropy, are potential mechanisms for ice softening (van der Veen and Whillans, 1994; Duval and 456

⁴⁵⁷ Castelnau, 1995; Cuffey and others, 2000a,b) that are often not considered when modeling the development
⁴⁵⁸ of rheology in shear margins, and these results establish an initial hypothesis that anisotropy and dynamic
⁴⁵⁹ recrystallization may be important mechanisms to consider in Antarctic ice streams.

There is insufficient evidence to accurately attribute inferred softening to any particular mechanism, 460 but more accurate estimates of the flow-rate parameter presented here are a step forward in being able 461 to understand heating and recrystallization and their influence on ice rheology in shear margins. An 462 examination of the dominant softening mechanisms in shear margins is a desired direction for future 463 research, following work done by Jacobson and Raymond (1998); Suckale and others (2014); Haseloff and 464 others (2015); Meyer and Minchew (2018); Minchew and others (2018) on shear margins and work done by 465 Alley (1992): van der Veen and Whillans (1994); Duval and Castelnau (1995); Cuffey and others (2000a.b) 466 (among many others) on fabric effects on ice flow. Future work will delve more deeply into the specific 467 mechanisms acting in glacier shear margins. 468

Results of synthetic tests presented here suggest that inverse methods can provide accurate estimates of 469 basal slipperiness and the flow-rate parameter in Antarctic ice streams similar to those in the Siple Coast. 470 Our synthetic tests assume an ice stream geometry, in which the width is much smaller than the length 471 of the glacier, and no-slip lateral margins that are consistent with Antarctic ice streams. Furthermore, 472 our synthetic tests assume certain structures of the flow-rate parameter and basal slipperiness that are 473 found in observations and previous inversions on Antarctic ice streams. Further testing would be required 474 to ascertain whether these inverse methods apply to other outlet glaciers with different glacier geometries 475 or to other glaciers that may have different structures of basal slipperiness and the flow-rate parameter. 476 The need for further studies is particularly important where basal slipperiness and ice rheology might be 477 expected to vary with the same spatial pattern. However, the results shown here enable us to make use of 478 inverse methods to improve our understanding of Antarctic ice streams. 479

480 SUMMARY AND CONCLUSION

As more satellite data become available, inverse methods are increasingly critical in accurately modeling ice flow from outlet glaciers. Here, we conduct a systematic study with synthetic data to determine how accurate these methods are for inversions of basal slipperiness and the flow-rate parameter simultaneously in ice streams. By considering spatial variations in basal slipperiness and the flow-rate parameter consistent with those expected in ice streams, we show that these methods can accurately resolve both parameters ⁴²⁶⁶ using surface velocity data and given a knowledge of bed topography and surface elevation. We determine ⁴⁸⁷⁷ that some mixing occurs between the two parameters due to the non-uniqueness of the problem, and further ⁴⁸⁸⁸ show that including strain rates in the regularization term in the cost function reduces mixing and enables ⁴⁸⁹⁰ a more accurate decoupling of the flow-rate parameter and slipperiness coefficient. Thus, inverse methods ⁴⁹⁰ are a useful class of techniques to infer basal slipperiness and the flow-rate parameter in ice streams. This ⁴⁹¹ is a critical first step to using the results of these simultaneous inversions to understand and predict ice ⁴⁹² flow.

We apply these methods to Bindschadler and MacAyeal Ice Streams in the Siple Coast of West Antarc-493 tica to find estimates of basal slipperiness and the flow-rate parameter. Estimates of basal slipperiness 494 indicate spatial variability and low basal drag values, which support previous findings that the Siple Coast 495 ice streams sit on weak, deformable, water-saturated till and exhibit sticky spots. Estimates of the flow-rate 496 parameter show high values in the margins of both ice streams that diminish as the ice streams advect over 497 the grounding line. Estimates of the viscous work rate support past findings that the rates of deformation 498 in some portions of the shear margins in Bindschadler and MacAyeal Ice Streams may be sufficient to 499 produce temperate ice and changes in crystallographic fabric and grain size in shear margins. Further re-500 search is needed to understand rates of heating through viscous dissipation and dynamic recrystallization. 501 and the relative influence of softening of the ice through heating, interstitial melting, grain rotation and 502 recrystallization, and macroscopic damage. 503

While successful in synthetic experiments, the methods we present here remain constrained. In par-504 ticular, these methods are subject to uncertainties in ice thickness and bed topography. Both of these 505 datasets lack complete and uniform coverage in Antarctica and many areas have high uncertainties in the 506 estimates that do exist. Thus, while our approach to inverting for basal drag and ice rheology produces 507 viable results in well-constrained areas such as the Siple Coast, areas with more sparse data coverage may 508 prove challenging. As more accurate remote sensing data comes in and more sophisticated techniques 509 become widely available, these datasets will become more accurate and these inverse methods will become 510 increasingly useful in more geographic locations. 511

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3706624. The code to run the inversions can also be found there. The code that generates the ice streams
and defines the parameters for the inversions for the synthetic tests and Bindschadler and MacAyeal can
be found at https://github.com/megr090/Inversion_BasalDragIceRheology.