1	Ultraviolet camera measurements of passive and explosive (strombolian) sulphur
2	dioxide emissions at Yasur volcano, Vanuatu
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20	
21	Abstract
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23 Here, we present the first ultraviolet (UV) camera measurements of sulphur dioxide (SO₂) flux from Yasur volcano, Vanuatu, for the period $6^{th} - 9^{th}$ July 2018. These data yield the first direct 24 gas measurement-derived calculations of explosion gas masses at Yasur. Yasur typically 25 exhibits persistent passive gas release interspersed with frequent strombolian explosions. We 26 27 used compact forms of the 'PiCam' Raspberry Pi UV Camera system (Wilkes et al., 2017, 28 2016) powered through solar panels to collect images. Our daily median SO₂ fluxes range from 4.0 - 5.1 kg s⁻¹, with a measurement uncertainty of -12.2% to +14.7%, including errors from: 29 30 gas cell calibration drift, uncertainties in plume direction and distance, as well as plume 31 velocity. This work highlights the use of particle image velocimetry (PIV) for plume velocity 32 determination, which was preferred over the typically used cross-correlation and optical flow 33 methods because of the ability to function over a variety of plume conditions. We calculate SO_2 masses for strombolian explosions of 8 - 81 kg (mean of 32 kg), which is, to our 34 35 knowledge, the first budget of explosive gas masses from this target. Through the use of a 36 simple statistical measure using the moving minimum, we estimate that passive degassing is 37 the dominant mode of gas emission at Yasur, supplying an average of ~69% of the total gas 38 released. Our work further highlights the utility of UV camera measurements in volcanology and, in particular, the benefit of the multiple camera approach in error characterisation. This 39 40 work also adds to our inventory of gas-based data to characterise the spectrum of strombolian 41 activity across the globe.

- 42
- 43 Highlights

- Long time series data collected using portable solar chargeable UV cameras.
- Particle image velocimetry (PIV) used for plume velocity measurements.
- Daily median SO₂ fluxes of 4.0-5.1 kg s⁻¹.
- SO₂ masses produced by strombolian explosions range 8 to 81 kg (mean 32 kg).
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1. Introduction

50

51 Strombolian volcanism is one of the more common forms of basaltic explosive activity 52 globally, associated with the rapid ejection of hot pyroclasts from a vent in a single impulsive 53 burst (Blackburn et al., 1976; Taddeucci et al., 2015), with event frequencies ranging from seconds to minutes (Pering and McGonigle, 2018). Volcanoes with frequent strombolian 54 55 activity include: the archetypal Stromboli, Italy (Patrick et al., 2007; Ripepe et al., 2002); Pacaya, Guatemala (Battaglia et al., 2018; Dalton et al., 2010); Erebus, Antarctica (Ilanko et 56 57 al., 2015; Johnson and Aster, 2005; Oppenheimer et al., 2009; Sweeney et al., 2008); and 58 Yasur, Vanuatu (Bani and Lardy, 2007; Kremers et al., 2013; Oppenheimer et al., 2006), the subject of this study. Other volcanoes also known to produce strombolian activity include: 59 60 Etna, Italy (Aiuppa et al., 2016; Branca and Del Carlo, 2005; Pering et al., 2015) Villarrica, 61 Chile (Shinohara and Witter, 2005); Arenal, Costa Rica (Garcés et al., 1998; Szramek et al., 62 2006); Batu Tara, Indonesia (Gaudin et al., 2017a; Laiolo et al., 2018); and Shishaldin, USA 63 (Vergniolle et al., 2004).

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65 Classically, this style of behaviour has been related to the ascent from depth of elongated and 66 over-pressured bubbles, termed gas slugs (Taylor bubbles), which rapidly expand in length as they approach the surface, (Del Bello et al., 2012; James et al., 2008; Seyfried and Freundt, 67 2000; Taddeucci et al., 2015). However, recent research has suggested that the causal 68 69 mechanisms may be far more diverse (Barth et al., 2019; Suckale et al., 2016; Woitischek et 70 al., 2020), and that the presence of crystal-rich layers in the magmatic column is important in 71 the mechanism of strombolian explosions. To test these hypotheses, it is useful to investigate 72 the spectrum of strombolian activity at volcanoes, including Yasur, where this behaviour is 73 typical. In addition, recent studies have highlighted the importance of eruption frequency in 74 determining the behaviour of ascending gas slugs (Gaudin et al., 2017a) as well as inter-slug 75 interactions (Pering et al., 2017, 2015). This has led to a classification of behaviour styles 76 ranging from rapidly bursting slugs which may interact with one another during ascent, through 77 to single bursting slugs (Pering et al., 2017; Pering and McGonigle, 2018).

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79 There are several methods to obtain information about individual strombolian explosions, 80 based on capture of: seismic (Chouet et al., 2003; Ripepe et al., 2002), infrasonic (Dalton et al., 2010; Delle Donne et al., 2016; Johnson and Ripepe, 2011; Marchetti et al., 2009), thermal 81 82 (Patrick et al., 2007; Ripepe et al., 2002), and gas-derived (McGonigle et al., 2009; Pering et 83 al., 2015; Pering et al., 2016; Tamburello et al., 2012) data. Here, we focus on gas emission rate measurements, using the ultraviolet (UV) camera, an instrument frequently used to 84 quantify gas release from persistently outgassing volcanoes (McGonigle et al., 2017; Pering et 85 al., 2019a). The UV camera is able to resolve rapid fluctuations in the release of sulphur dioxide 86 87 (SO₂) gas. When the camera is used in tandem with an in-situ multi-component gas analyser

- 88 (Multi-GAS) to measure gas ratios within a volcanic plume (Aiuppa et al., 2005; Shinohara et 89 al., 2015), it is possible to estimate the total gas emission rate (Pering et al., 2014). An important parameter with respect to causal mechanisms for strombolian explosions is the ratio of gas 90 91 released during explosions to that released passively (Barth et al., 2019; Jaupart and Vergniolle, 1988, 1989; Parfitt, 2004; Suckale et al., 2016; Vergniolle and Jaupart, 1986). This 'active' to 92 93 passive degassing ratio also provides information about conduit fluid dynamics (Gaudin et al., 94 2017a, 2017b; Pering et al., 2015; Pering et al., 2016). For example, Tamburello et al., (2012) discovered that the most efficient mode of degassing at Stromboli was actually the passive 95 degassing, supplying ~77% of gases released, demonstrating the dominance of passive gas 96
- 97 release (Carn et al., 2017) and the smaller gas bubbles within a volcanic conduit.



Figure 1: Activity at Yasur Volcano, Vanuatu, during the July 2018 field campaign. (a) Image 98 99 of the gas plume rising from the summit crater. Large gas pulses are associated with explosions; (b) a night-time view with the south crater in the foreground and incandescence from the north 100 101 crater in the background. Several vents are visible in the south crater with one producing a strombolian explosion; (c) ash-rich gas plumes formed by strombolian explosions occurred 102 103 from the north crater and ash-poor gas plumes from explosions from the south crater; (d) a day-104 time view into the north crater, showing the crater floor topography divided by a septum into 105 northern and southern craters.

107 UV camera derived SO₂ masses from strombolian explosions (Delle Donne et al., 2016; Mori
108 and Burton, 2009; Pering et al., 2015; Tamburello et al., 2012) can be combined with gas ratio
109 data (e.g., from Multi-GAS), to generate total gas masses and volumes for individual explosive

- events (Burton et al., 2007; Pering et al., 2016). These data provide parameters for analytical
- and computational models of gas flow in conduits, which yield further information about the

112 activity and mechanisms; for example, slug length, explosive vigour, and categorisation of

- burst behaviour using fluid dynamics (Del Bello et al., 2012; James et al., 2009, 2008; Peringand McGonigle, 2018).
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116 Here, we demonstrate the use of a portable, solar-chargeable, version of the low-cost Raspberry 117 Pi ultraviolet camera (Wilkes et al., 2017, 2016) combined with a new approach to estimate 118 plume velocity using UV camera imagery to obtain SO₂ fluxes. We present the first UV camera measurements at Yasur, providing the first gas-based estimate of explosive strombolian gas 119 120 masses, key to unravelling information on the spectrum of behaviours on this style of activity 121 globally. Furthermore, we illustrate the use of statistical methods to differentiate between 122 passive and explosive gas release, and finally apply mathematical models to estimate driving 123 slug dimensions of the strombolian explosions at Yasur volcano.

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- 2. Yasur volcano and observed activity during 5th to 11th July 2018
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127 Yasur (Vanuatu) is a basaltic stratovolcano, located on the southeast of Tanna Island, which is 128 thought to have been predominantly persistently active for at least ~800 years (Firth et al., 129 2014). The main volcanic edifice is a cone with a crater area of 350-450 m diameter, divided 130 by a septum into northern and southern craters, each containing multiple active vents. During the measurement period an ashy plume was present throughout the week, related to ash-rich 131 132 strombolian explosions arising from both craters (Fig 1). From the summit, multiple vents 133 displaying incandescence were visible within the southern crater, each exhibiting different 134 styles of explosive behaviour (Fig 1c). Gas release from the summit vents was constantly visible, occasionally including 'puffing' (described elsewhere by Gaudin et al., 2017b, 2017a; 135 136 Pering and McGonigle, 2018; Tamburello et al., 2012). The northern crater contained at least 137 two vents, but access to its rim was precluded by safety concerns, due to ballistic ejecta from 138 the crater's strombolian explosions, which also appeared to be more ash-rich than those from the southern crater. From the southern crater (Fig 1d) we directly observed explosions from at 139 140 least three vents, each of which had different behaviours, two with jet-like characteristics (i.e., with a strong vertical component to the trajectory of ejecta), hinting at the potential influence 141 of the conduit wall during the explosion process, i.e., the explosion (slug burst) happens deeper 142 within the conduit, providing a vertical direction to the released material (Delle Donne and 143 Ripepe, 2012; Salvatore et al., 2020). Another vent exhibited parabolic transport of 144 145 incandescent pyroclasts (without initial jet), as though an ascending bubble burst within an over-topped magma column (Del Bello et al., 2012), or within a flared conduit geometry 146 147 (Dibble et al., 2008), i.e., allowing the lateral expansion of bubble prior to burst. Interestingly 148 these strombolian explosions also differed in the noise generated, with the hemispherical shaped (non-jet-like) explosions associated with a deeper booming sound. During 8-9 July, 149 150 explosions were frequently associated with visible shockwaves propagating through the 151 condensed plume. The supplementary video highlights a snapshot of typical activity captured from the both craters. Throughout the measurement period, the morphology of the crater was 152 153 dynamic, with spatter and ash accumulating around vents leading to changes in the size, shape, and position of vents. 154

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156 A number of studies on Yasur have focused on the characteristics of strombolian activity and, 157 in particular, its dynamism. Multi-vent basaltic volcanoes are known to exhibit vent-specific behaviours which can change through time, e.g., as shown by Salvatore et al. (2018) on 158 Stromboli. Simons et al., (2020) discuss systematic changes in behaviour at individual vents 159 within the southern crater at Yasur, with switching from bomb-rich (incandescent pyroclasts) 160 161 through to ash-rich explosions. They also discuss conduit branching and the possibility of a single bubble (i.e., gas slug) driving paired explosions from separate vents at Yasur, with the 162 potential for eruption styles to diverge at different vents due to cooling of the magma in the 163 upper conduit branches. La Spina et al., (2016) observed two decoupled styles of degassing 164 165 from infrasound data: puffing, which was near-constant, and strombolian explosions. Meier et al., (2016) highlighted the ash-rich and ash-poor (or bomb-rich), styles and their similarity at 166 167 Yasur to those of Stromboli (Gaudin et al., 2014b; Patrick et al., 2007; Ripepe et al., 2005; Ripepe and Marchetti, 2002; Taddeucci et al., 2012). Kremers et al. (2013) were able to 168 169 calculate the lengths of gas slugs generating the strombolian explosions on Yasur as ranging 170 from 59 to 244 m, with mean and median values of 112 m and 103 m respectively.

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SO₂ fluxes at Yasur ranged from 2.5 to 17.2 kg s⁻¹ from April 2004 to November 2005, with a 172 mean of 7.9 kg s⁻¹ based on differential optical absorption spectroscopy (DOAS) traverses 173 174 (Bani and Lardy, 2007). Between August 2007 and December 2008, SO₂ fluxes at Yasur were 1.3 to 11.1 kg s⁻¹, with a mean and median of 7.2 kg s⁻¹ and 7.1 kg s⁻¹ respectively (Bani et al., 175 2012). In October 2007, a mean SO₂ flux of 8.0 ± 3.8 kg s⁻¹ across four days of traverses was 176 reported by Métrich et al. (2011). A satellite-derived SO₂ flux of 6.8 to 23.3 kg s⁻¹ was 177 estimated between 2000-2015, with a mean and median of 16.3 kg s⁻¹ and 19.2 kg s⁻¹ 178 respectively (Carn et al., 2017). Comparisons in gas flux between different periods of 179 180 observations and between methods must be treated with caution; they may, in discrete 181 campaigns such as presented in this study, not represent broader changes through time.

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183 **3.** UV camera methods

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Low-cost Raspberry Pi ultraviolet (UV) camera systems ('PiCams') were used to measure 185 volcanic SO₂ outgassing, (Wilkes et al., 2017, 2016); in this case the units were modified to 186 include 'PiJuice' hardware and software (https://github.com/PiSupply/PiJuice) to provide power 187 to the Raspberry Pi boards at the heart of the camera system, see also (Pering et al., 2020). The 188 PiJuice units provide continuous supplies of power via lithium-polymer mobile phone batteries, 189 190 which can be recharged using solar panels. In the field, both 1600 mAh and 2300 mAh batteries 191 were used. With continuous solar charging (via 40 W solar panels for each Pi board) this 192 configuration readily enabled field data acquisition for at least 6 to 7 hours per day in this location. This camera setup omitted the GPS module in the prior generation of the PiCam 193 system, which automatically provided time synchronisation for the Raspberry Pi computers on 194 195 start-up. Instead, GPS time synchronisation was performed manually via the command line, expedited by the PiJuices' on board real-time-clocks. The PiCam systems were equipped with 196 197 two Edmund Optics Inc. filters (of full width at half maximum - 10 nm), centred around 310 198 and 330 nm, respectively, one for each lens, corresponding to spectral regions where SO₂ does 199 and does not absorb incident UV radiation. As detailed further elsewhere, UV imaging systems in volcanic gas monitoring are predicated upon contrasting image intensities in these two
wavebands, to isolate absorption in the image cause by sulphur dioxide absorption; for further
details please see: (Gliß et al., 2017; Kantzas et al., 2010; Kern et al., 2015; McGonigle et al.,
2017; Mori and Burton, 2006; Platt et al., 2015).

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205 Two separate PiCams (Camera 1 and Camera 2) were operated simultaneously (enabling assessment of error and comparison of two plume angles), viewing the plume from a position 206 southwest of the summit crater from the Treehouse Site (~1900 m from the plume) at the Jungle 207 Oasis, on 6th and 7th July, and from the Ash Plain Site (~2300 m from the plume) to the north-208 northwest on 8th and 9th July (see Figure 2 for locations). The UV cameras were also operated 209 210 on the 11th July, however, inclement weather and grounding of the plume prevented reliable 211 data processing for that day. During the measurement days, the plume direction varied from 212 west to northwest, with dry and predominantly cloud-free weather (bar a brief period of rain 213 on 9 July). Of the five days on which measurements were attempted, we acquired high-quality 214 data on four of the days, amassing 16 hours of imagery across these days.

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216 The camera images were captured with acquisition rates of 0.5 - 0.25 Hz, with additional collection of clear sky images prior to the plume sequences' capture, which are required in the 217 218 processing routine to account for vignetting effects. Dark images were acquired per sequence 219 too, to enable subtraction of dark noise. We conducted frequent calibrations using gas cells 220 with known SO₂ column densities (0 ppm m, 412 ppm m, and 1613 ppm m, with a manufacturer 221 quoted error of 10%) between measurement sequences at least every 1-1.5 hours, with more 222 frequent calibration when light conditions changed more rapidly. The data were then processed 223 following the commonly applied protocols, already extensively described in the literature (D'Aleo et al., 2016; Kantzas et al., 2010; Kern et al., 2014; McGonigle et al., 2017), i.e., 224 225 aligning images; selecting a clear sky background region; and choosing a plume cross-section along which to determine integrated column amounts (ICA), before multiplying by plume 226 227 speed to calculate flux. For the resulting flux data time series, we determined data distribution 228 statistically with the Kolmogorov-Smirnov normality test to inform on appropriate measures of central tendency. The data were all non-normally distributed, therefore the median was used 229 230 in the further calculations, detailed below. However, we continue to detail both mean and median values. 231

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233 A goal of this study was to attempt to differentiate degassing fluxes from each of the vents. 234 However, it was not possible to do this rigorously and at all times, given that changes in wind 235 shear and crater-derived eddying led to time-varying separation/overlap of individual plumes 236 (Pering et al., 2019b; Tamburello et al., 2013), creating difficulties in resolving emissions from the individual vents. Indeed, the plume predominantly appeared well-mixed on emergence 237 238 from the summit crater (Figure 2c). However, at times, the view from the Ash Plain Site did allow us to identify gas pulses from two distinct sources, likely corresponding to the two 239 craters, associated with explosions, where distinct gas pulses could be spatially resolved 240 241 (Figure 2d).



Figure 2: (a) An elevation-based perspective of the low summit of Yasur volcano, along with measurement positions and prevailing plume transport direction with inset (b) showing a closeup of the summit crater. In (c) there is a typical view of the plume with red colours representing higher concentrations of SO₂ showing clear mixing between plumes from different vents, and (d) shows an example of where it was possible to differentiate between emissions from both craters. Imagery is from Google Earth®.

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250 3.1. Particle Image Velocimetry (PIV) for plume velocity determination.

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252 One of the most significant, and yet frequently overlooked, errors in UV camera image analysis is that associated with plume velocity determination, for which three main methods are 253 254 commonly used: cross-correlation (McGonigle et al., 2005; Williams-Jones et al., 2006), 255 optical-flow (Delle Donne et al., 2019, 2017; Gliß et al., 2017; Kern et al., 2015; Peters et al., 2015; Peters and Oppenheimer, 2018), and manual tracking (Ilanko et al., 2019). The optimal 256 method will largely be determined by the plume conditions, as no single method is ideally 257 258 suited to all situations. Manual tracking is suitable for stable plumes travelling at slow 259 velocities, or for measurements at greater distances from the plume, where cross-correlation and optical-flow are less desirable, as the plume is more dilute and fewer pixels containing SO₂ 260 261 are available for the analysis. Cross-correlation is preferred for broadly homogenous plumes that are well-mixed and undergo little turbulence (e.g., whereby eddying can cause SO₂ within 262 parts of the plume to travel backwards relative to the bulk plume vector of motion e.g., the 263 264 wind direction). Optical-flow methods are well suited to high velocity plumes, where the velocity field over the plume profile is non-constant, e.g., due to pulsed gas outputs from 265 craters, associated with strombolian explosions or puffing (Delle Donne et al., 2019, 2017; Liu 266 267 et al., 2019; Peters et al., 2015). 268



Figure 3: (a) example plume vectors generated during PIV analysis for movement from one
frame to the next, superimposed over an SO₂ absorption image; and (b) example median plume
velocity across the integration line and SO₂ fluxes for a time interval of 2500 seconds on 7 July
2018, showing clear accelerations in plume velocities during strombolian explosions.

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In this study, we encountered difficulties in using these traditional methods. In particular, efficient mechanisms for tracking pulses of gas in a large dataset were required. Indeed, crosscorrelation (which tracks the delay time between two integration lines of known distances) sometimes failed, likely as a result of turbulent motion in the plume. Furthermore this approach does not cope well with the transient increases in gas velocity associated with impulsive gas release during strombolian explosions; hence, this method is probably the least favourable in 281 this context. A lack of structure in the plume appeared to lead to the failure of the Farneback 282 optical flow algorithm (Gliß et al., 2017; Peters et al., 2015; Wilkes et al., 2017). We therefore instead adopted the use of Particle Image Velocimetry (PIV) for plume velocity determination, 283 as briefly discussed in Kern et al., (2014). Previous use of PIV in a volcanic context has 284 included tracking of lava lake velocity at Masaya (Pering et al. 2019) and it is similar to the 285 286 pyroclast tracking velocimetry of (Gaudin et al., 2014a, 2014b). Here, we used PIVlab, a userfriendly MATLAB toolbox and app (Thielicke, 2014; Thielicke and Stamhuis, 2014). PIV 287 288 works by comparing image pairs in sequences and looking for differences between them through two methods: direct cross-correlation and through the correlation of Fourier 289 transforms. Both of these methods are conducted on integration areas (here we used three), 290 291 with decreasing size on each pass. The end result is a velocity grid for the whole plume image, 292 similar to those produced during the application of optical flow (Gliß et al., 2017; Peters et al., 293 2015), see Figure 3a.

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295 We found that using PIV we were able to detect velocity differences in even the more homogenous plumes (i.e., with a quasi-uniform SO₂ distribution across most of the plume, 296 297 except during strombolian explosions). PIV was used to extract velocity components 298 corresponding to each image pixel perpendicular to the integration line used in the ICA 299 determination. In this case, rather than using a single plume speed perpendicular to the integration line, therefore, the plume velocity vectors per pixel were multiplied by the pixel's 300 SO₂ column amount, and these ICAs per-pixel were then summed over the plume profile (see 301 Figure 3). The PIV analyses show temporal and spatial variability in plume velocity, capturing 302 303 a heterogeneity which is a real feature of the plume motion, yet not captured by crosscorrelation or manual tracking. We report error for PIV analysis as the length of the integration 304 305 line at given distance to the plume, corresponding to each pixel, divided by the lowest image 306 capture frequency; for the Ash Plain Site this equates to an error of 2 ± 0.3 ms⁻¹ or ~ $\pm 15\%$. and for the Treehouse Site an error of 5 ± 0.6 ms⁻¹ or ~9±%. These error estimates are based 307 308 on typical plume speeds for each site.

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310 3.2. Estimation of a total UV camera measurement error

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Here, we highlight the range of possible error sources, and perform additional analyses on our
data pertaining specifically to calibration curve drift, plume orientation, and plume distance.
The final determined values for error are our best possible estimates on the basis of the available
information and protocols applied in-the-field, which, wherever possible, were designed to
minimise error.

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The effects of light dilution have been quantified at a range of volcanic gas plume targets: SO_2 mass column amounts may be underestimated by ~10-60% over a range of distances (2.1 km to 6.5 km) and conditions from hazy through to very clear (Campion et al., 2015). Light dilution has a larger effect during hazier conditions, which were not present during our successful measurement days. Ilanko et al., (2019), calculated that at ~10.3 km distance from the plume (during clear conditions at Sabancaya volcano, Peru) SO_2 fluxes could be underestimated by 2.5 times, and at 4.25 km by 1.5 times (which would correspond to ~1.18 times [18%] at our

- 325 maximum distance of 2300 m at Yasur). It is important to note that light dilution estimates are 326 very specific to each measurement location and conditions, and given our range of distances to the plume and clear measurement conditions we suggest therefore that error relating to light 327 dilution is <+20%. We also note that the plume was not optically thick, except following ash-328 rich strombolian explosions. Unfortunately, exact errors due to scattering of UV by ash are 329 330 currently not quantifiable, but ash within the plume will likely lead to an underestimation of SO₂ column amounts (Kern et al., 2013; Tamburello et al., 2012).We attempted to minimise 331 this error by integrating away from the summit area, where the plume is visibly less ash-rich, 332 333 and more transparent. We also further note that the peaks in gas flux from strombolian 334 explosions are well defined within the resulting dataset (Figure 3).
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336	Table 1: A summary of errors on UV camera measurements of SO ₂ fluxes at Yasur Volcano
337	in July 2018, including short comments and total RMS error.

	Treehouse	Ash Plain	Comments
Distance	1900 m	2300 m	-
Description	Error	Error	-
Light Dilution	+20%	+20%	Underestimation only, low given plume
			proximity.
Gas Cell	±10%	±10%	Manufacturer quoted
Concentration			
Calibration drift	±15%	±15%	Changing calibration conditions (see text)
Plume Velocity	±9	±15%	Based on pixel size (see text)
Plume Direction	±5%	±5%	Based on coincident UV camera data
Plume Distance	±18%	±18%	Based on plume deviation of 200 m.
Ash content	-	-	Underestimation, not quantifiable
RMS Error	-11.2% /	-12.2% /	Note the higher error related to
	+13.9%	+14.7%	underestimation (positive error).



Time From First Measurement [HH:MM:SS]

Figure 4: Example calibration slope coefficients (derived from regressions of gas cell
concentrations against apparent absorbance) from two days of data. Timings are from the time
of the first calibration on each of these measurement days. Note that the coefficient peaks
towards solar noon.

343 Gas cell calibrations change throughout the day in response to position of the sun and changing illumination as a result of background clouds, with changes in gas-cell calibrations potentially 344 leading to over-estimation in SO₂ column densities of up to 60% (Lübcke et al., 2013). Figure 345 346 4 shows the change in calibration slope coefficient (between regressions of apparent absorbance coefficient and column density) throughout the day from time of first calibration 347 (rather than using UTC), showing a variation from 1.22×10^{-4} to 1.46×10^{-4} in this parameter. 348 When taking into account this characterised range in slope of 2.4 x 10^{-5} , and the broad 349 350 assumption (for indicative purposes) that there is a linear change between the first point and 351 the highest point (corresponding to maximum solar zenith angle) we arrive, over the 122 minutes between these points, at a value of 1.97×10^{-7} increase in slope coefficient per minute. 352 This would equate to a potential change in error of ~ 0.16% per minute, which expanded over 353 354 an hour could become 9.6% - or, for our maximum inter-calibration interval of ~95 minutes, 355 an error of 15.2%. It is possible therefore that any underlying trends in apparent gas emission rates below these thresholds are not differentiable from this error, i.e., an increase or decrease 356 357 in flux at a rate of <~0.16% per minute. We suggest therefore that errors from cell calibration (notwithstanding the $\sim \pm 10\%$ manufacturer quoted cell content error) amount to a maximum of 358 $\pm 15\%$ for our measurement period. 359





Figure 5: (a) Example period of overlapping data from two separately acquiring synchronous 362 363 cameras, viewing the plume from slightly different orientations. One dataset has been shifted by the lag value which generated the maximum correlation coefficient, following cross-364 365 correlation between the two series, in an attempt to best temporally match the data. Note that there are differences in the magnitudes of peaks and troughs in the different dataseries, even 366 367 when shifted relative to one another in this way, due to smoothing or turbulence during plume movement through the atmosphere and the slightly different views of the units through the 368 plume. In (b) a linear regression model ($R^2 = 0.4$) is shown, demonstrating the best fit between 369 370 time series data from the two cameras, as well as confidence intervals. The statistical 371 parameters are similar, but there are differences in peaks and troughs between the two datasets. 372

373 We used fixed distances of 1900 m and 2300 m from the camera to the plume for our retrieval 374 calculations in the cases of data from the Treehouse and Ash Plain Sites respectively. By repeating the same retrievals at different distances, for the Ash Plain data, we determined that 375 376 a 100 m error in plume distance leads to a < 5% difference in computed gas masses across the 377 plume cross section (with underestimation in this distance corresponding to underestimation in gas mass), and a 200 m error in distance to < 9% error. Comparisons of the same test dataset 378 379 with different velocities in PIV analyses corresponding to the different distances showed variations from 1 - 7 % with the 100 m error and 5 - 11% in the 200 m case. The combined 380 381 effect of distance uncertainties on mass and velocity gives a 7-10% error in fluxes for 100 m 382 distance to plume error, and 16-18 % for 200 m. We therefore take the maximum value here of ~18% and apply this conservatively, to our entire dataset. 383

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Time [UTC - Month / Day / Time]
Jul 08 Time [UTC - Month / Day / Time]
Figure 6: (a) through (d) show retrieved gas fluxes, where clear peaks correspond to strombolian explosions, for all the image data captured during the observation period; also highlighted are periods where the plume was grounded in (a) and heavy rainfall was encountered in (d). Inset in (c) is an example of explosive mass determination, where integration occurs below the explosion peak (e.g., shaded blue area), above background levels.

392 Given changes in plume direction, the orientation with which the integration line bisects the plume is also relevant in consideration of measurement uncertainty (Klein et al., 2017). To 393 investigate this, we use overlaps between data from two synchronously-acquiring cameras 394 (Figure 5), which had slightly different plume views and hence integration line orientations 395 relative to the plume geometry. This simulates the time-dependent effect of the plume moving, 396 in response to changing wind conditions, with respect to a fixed integrated column amount line. 397 In this case the two datasets were cross-correlated and shifted by the lag corresponding to the 398 maximum correlation to account for different transport times from the source to the two 399 400 cameras' different integration lines. The calculated difference in flux retrieval from the two 401 units, based on comparing the acquired median values per unit is $\sim \pm 5\%$.

402

In addition, we also report computed flux data in Figure 6 (which documents the retrieved data from the entire campaign) during periods when the plume grounded, e.g., the integration line could not cover the entire plume cross section, as well as episodes of heavy rainfall. During these periods, median SO₂ fluxes were underestimated significantly by ~4.3-4.4 and 5.6-7.3 times, respectively, based on comparison with median values of retrieved fluxes either side of these episodes. Whilst the data captured under these circumstances were not used in the

- 409 foregoing analysis, nor considered representative of the volcanic outgassing, they are reported
- 410 here, to illustrate the significant error to which these effects give rise.
- 411
- **Table 2.** A summary of measurement durations and SO₂ flux statistics for daily UV camera
 - Date (UTC) 05-06/07/18 06-07/07/18 08/07/18 08-09/07/18 Date (Local) 06/07/18 07/07/18 08/08/18 09/08/18 Time series duration (hh:mm) 4:15 04:42 03:54 03:33 Total time (hh:mm) 05:01 05:31 04:14 04:17 Mean (kg/s) 5.2 5.5 4.5 4.1 Median (kg/s) 4.7 4.2 4.0 5.1
- 413 measurements at Yasur Volcano in July 2018.

415 4. Results and Discussion

4.1 SO₂ fluxes and estimates of the masses of gas emitted during strombolian explosions 416 Time series gas fluxes are shown in Figure 6, with a summary of daily statistics in Table 1. The 417 418 median flux across the four days of measurements was 4.5 kg s⁻¹ and the mean was 4.9 kg s⁻¹, reflecting the peaks in SO₂ flux associated with frequent strombolian explosions. These gas 419 fluxes correspond to a daily median and mean of 389 and 423 t d⁻¹ across the measurement 420 421 period. Daily statistics are given in Table 2: median SO₂ fluxes ranged between 4.0 to 5.1 kg s^{-1} across the measurement days and the daily means were 4.1 to 5.5 kg s^{-1} . The timeseries data 422 are suggestive of gradual changes in background SO₂ emissions over several hours, but it is 423 424 not clear whether these are real or a product of artefact error. A shift in activity is, however, 425 plausible based on the observation of large strombolian explosions with visible ballistics and 426 shockwaves, particularly on 8 and 9 July, when lower fluxes were measured.

427

428 Masses of SO₂ released during each strombolian explosion were calculated by integrating beneath the explosive pulse and summing the total SO₂ released, after Tamburello et al., (2012), 429 430 see Figure 6c. However, a challenge here is that the onsets of strombolian explosions were not 431 visible within the imagery (i.e., vents were at depth within the crater). We use two methods to 432 determine when explosions occurred within the UV camera imagery: firstly, gas pulses in the 433 camera images must be observed to originate and visibly accelerate above the rim of the summit 434 crater (see Figure 1a) to confirm that an explosion occurred; secondly, where gas burst traces 435 are manifested in the flux time series, showing the characteristic coda (a period of elevated flux following a strombolian explosions which gradually declines) detailed in Pering et al., (2016), 436 437 see Figure 6c. The number of explosions is probably underestimated using these methods; however, the resulting estimation of SO₂ released during each explosion is useful for 438 comparison to literature values (Table 3). Overall, SO₂ masses released were estimated for 135 439 explosions, across five days. Mean masses of SO₂ released increased from 6th to 9th July 2018, 440 441 which is consistent with visual observations of more powerful explosions on 8 and 9 July 2018. 442

Table 3: A breakdown of daily SO₂ explosion mass data. Also displayed are percentages
indicating the partitioning of gas masses between passive and explosive degassing. Lower and
Upper_-ratios refer to the ranges indicated in determined active molar ratios by (Woitischek et

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446	al., 2020; Table 3 -	$CO_2/SO_2 = 2.85 \pm 0.17$; $H_2O/SO_2 = 315 \pm 71$.8; SO ₂ /HCl = 1.6 ± 0.22). ¹
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447 These values are from the statistical calculation of this paper (section 4.2).

448

Date (UTC)	05/07/2018	06/07/2018	07/07/2018	08/07/2018	09/07/2019	Total
Explosions Counted	8	43	39	36	9	135
						Mean
SO ₂ Min (kg)	10.2	8.9	8	12	10	9.8
SO ₂ Mean (kg)	26.9	22.1	27	39	45	32.0
SO ₂ Max (kg)	64.1	44.9	62	81	69	64.2
Passive ¹ %	66	64	70	78	68	69
Explosive ¹ %	34	36	30	22	32	31
Masses from Lower Ratios						
Total – Min (kg)	712	625	575	822	721	691
Total – Mean (kg)	1884	1550	1892	2713	3164	2241
Total – Max (kg)	3020	3148	4370	5678	4813	4206
Masses from Mean Ratios						
Total – Min (kg)	940	824	759	1084	952	912
Total – Mean (kg)	2486	2046	2497	3579	4175	2957
Total – Max (kg)	5929	4153	5767	7493	6350	5938
Masses from Upper Ratios						
Total – Min (kg)	1167	1024	942	1347	1182	1132
Total – Mean (kg)	3088	2541	3102	4446	5186	3673
Total – Max (kg)	7365	5159	7163	9307	7888	7376

449

450 The range of SO₂ masses released during strombolian explosions at Yasur, of 8 - 69 kg (mean 451 32 kg) are similar to those estimated by Tamburello et al., (2012) at Stromboli, who found a 452 range of 2 - 55 kg (mean of 20 kg); but higher than those observed at Etna during mild strombolian activity (Pering et al., 2015), which ranged from 0.1 to 14 kg. Gas ratios (SO₂, 453 454 H₂S, H₂O and CO₂) derived from a combined Fourier transform infrared spectroscopy (FTIR) 455 and Multi-GAS study from 6 to 16 July 2018 show distinct gas compositions during passive and explosive activity (Woitischek et al., 2020). Gas emitted during active (strombolian) 456 457 activity had molar ratios of: $CO_2/SO_2 = 2.85 \pm 0.17$; $H_2O/SO_2 = 315 \pm 71.8$; $SO_2/HCl = 1.7 \pm 1.7$ 0.22. Using these data we can estimate total gas slug masses, shown in Table 3. The mean total 458 gas mass emitted during strombolian explosions at Yasur is 2960 kg, with a range of 910 -459 460 5940 kg. These estimates are similar to the 170 - 1674 kg for strombolian explosions at Pacaya 461 (Dalton et al., 2010) whereas at Stromboli, explosion masses range from 44 - 238 kg according 462 to Barnie et al. (2015) and 2 to 1425 kg as determined by Delle Donne et al. (2016).





Figure 7: (a) Separation of passive and explosion gas release for a period on the 7th July with (inset) a zoomed illustration of the simple statistical moving minimum based model, showing oscillation in background passive degassing overtopped by explosive contributions; (b) the ratio of passive to explosive degassing; and (c) a cumulative plot showing the division between passive and explosive gas release, here passive and explosive release have been cumulatively summed to show the change through time at the sampling frequency. The passive to explosive ratio is then the ratio of the final sum of gas release.

4.2. Simple Statistical Separation of Passive and Explosive Degassing

Others have studied the ratios of explosive to passive release during strombolian explosions on 475 476 Stromboli (Tamburello et al., 2012) and Etna (Pering et al., 2015). Here, we attempt to expand 477 on this by using a simple statistical measure involving the moving minimum (which traces the 478 lower values in dataset over a defined window, much as the moving mean), to estimate the 479 passive release of gas through time, which, when subtracted from total flux, provides an approximate estimate of passive vs. explosive release. This was necessary as our manual 480 481 selection of events missed or excluded several strombolian explosions. Our approach is similar 482 to the automated method of Delle Donne et al., (2017), which involved finding local peaks in 483 timeseries data. For an example period (Figure 7) we highlight the moving minimum, which is 484 set to a window size of 20 s, which is generally the characteristic timeframe of large peaks and troughs associated with strombolian explosions (Delle Donne et al., 2017; Pering et al., 2016). 485 486 Note that, using this moving minimum method, an oscillation (non-uniform) background is 487 apparent. Delle Donne et al., (2017), also showed fluctuation in passive background between strombolian explosions, and this background is used as a best estimate solely to extract the 488 489 explosive contribution. In this instance, at Yasur, a moving minimum over this window proved 490 best, given the higher frequency of explosive events; however, with a greater timeframe 491 between events, the moving median may be a better measure. We also prefer this statistical 492 estimation technique over using our estimated SO₂ masses, given that the latter required manual 493 selection of strombolian explosions. This simple moving minimum approach could be readily 494 and simply automated for routine monitoring of activity from strombolian explosion producing 495 volcanic systems.

496

497 Daily estimates of the passive and active degassing contributions are shown in Table 3, with a 498 mean of 69% passive to 31% explosive. These estimates are similar to those estimated at 499 Stromboli: 77% passive to 23% explosive (termed active which also includes puffing); and 500 Etna: 67% passive to 33% explosive (Pering et al., 2015). These datasets serve to illustrate the dominance of passive degassing in the gas emission budget at volcanoes that exhibit 501 strombolian activity. On the 8th July 2018 we calculated a higher passive degassing 502 contribution, at 78%. This day was characterised by higher SO₂ masses emitted during 503 individual explosions, but lower overall SO₂ fluxes. These features may be consistent with a 504 degassing magma column beneath a thicker, more viscous and impermeable crystal-rich plug, 505 506 requiring a higher gas mass to drive more powerful explosions (Polacci et al., 2012; Simons 507 et al., 2020; Woitischek et al. 2020), which is consistent with visual observations.

508

509 4.3.Models of gas slug behaviour

510

511 Using our determined values for total slug mass, we can estimate slug lengths using the static 512 pressure model of (Del Bello et al., 2012). We use fixed values of 2600 kg m³ and 1000 Pa s⁻¹ 513 for density and viscosity, respectively, with an atmospheric pressure of 101,325 Pa. The only 514 parameter we vary in the model is that of conduit diameter, which we step from 3 m to 7 m. 515 We use only the mean explosive gas ratios and masses (and not the range obtained when 516 including error) for simplicity. It should be noted that the molar H₂O/SO₂ ratio is high and

- 517 variable (Woitischek et al., 2020). As water is the gas contributing most to the mass of the slug, 518 it is likely that our determined total gas masses are an overestimation. Our results are summarised in Table 4. We determine slug lengths ranging 188 - 609 m (median and mean of 519 520 347 m and 366 m respectively) for a conduit diameter of 3 m, however, this reduces to 76 -260 m (median and mean of 146 and 154 m respectively) for a conduit diameter of 7 m. 521 522 Kremers et al. (2013) calculated lower values of 59 – 244 m using seismo-acoustic data, and it 523 would therefore seem that a larger conduit diameter may be more plausible at Yasur, which 524 may bifurcate or split at very shallow depths (Simons et al., 2020).
- 525

Table 4: A summary of gas slug volumes and lengths using the model of Del Bello et al.

(2012) and based on gas flux and composition data acquired during strombolian activity atYasur Volcano in July 2018.

Statistic	Slug Volume (m ³)	$\mathbf{D} = 3 \mathbf{m}$	$\mathbf{D} = 4 \mathbf{m}$	$\mathbf{D} = 5 \mathbf{m}$	$\mathbf{D} = 6 \mathbf{m}$	D = 7 m
Min	4286	188	139	110	90	76
Median	14055	347	259	205	170	146
Mean	15556	366	272	217	180	154
Max	42337	609	455	364	303	260

529

530 5. Summary and Conclusions

531

532 In this work we highlighted the utility of using low-cost solar-powered Raspberry Pi UV cameras for prolonged field campaigns. We continuously imaged the volcanic plume to yield 533 both velocity, using a PIV method (Thielicke, 2014; Thielicke and Stamhuis, 2014), and SO₂ 534 fluxes over periods of several hours per day, at temporal resolutions of up to 0.5 Hz with brief 535 pauses for calibration. SO₂ fluxes were determined, with daily means of $4.1-5.5 \text{ kg s}^{-1}$ (medians 536 from 4.0-5.1 kg s⁻¹) which are within the ranges of those measured previously at Yasur using 537 ground-based methods of 2.5 to 17.2 kg s⁻¹ (Bani et al., 2012; Bani and Lardy, 2007). SO₂ 538 masses emitted during individual strombolian explosions ranged from 8-81 kg, similar to 539 540 events at Stromboli, which were associated with the emission of $2-55 \text{ kg SO}_2$ (Tamburello et al., 2012). By using a simple statistical measure we estimate that passive degassing, at 69%, is 541 the dominant mode of degassing at Yasur, compared to 31% explosive. Observations suggest 542 that periods of lower gas output are associated with conduit sealing and more violent 543 544 explosions, however, a longer dataset would be needed to test this hypothesis substantively. By 545 combining SO₂ explosion masses with gas ratios (Woitischek et al., 2020) we determined total 546 explosion gas masses of mean 910-5940 kg, which correspond to slug lengths, using the model 547 of Del Bello et al. (2012) of 76-260 m, if a larger conduit diameter of 7 m is used. Smaller 548 conduit diameters lead to longer slug lengths ~188-600 m at 3 m diameter, larger than those estimated previously of $\sim 59 - 244$ m (Kremers et al., 2013). The data presented here represent 549 550 an important addition to our gas data based characterisation of the spectrum of strombolian 551 activity across the globe. 552

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557

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