

1 **Polar feedbacks in radiative-advective equilibrium from an air mass**
2 **transformation perspective**

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11 ABSTRACT: We develop a novel single-column model of clear-sky radiative-advective equilib-
12 rium where advective heating is internally determined by relaxing the column temperature and
13 humidity toward fixed midlatitude profiles, consistent with an air-mass transformation perspective.
14 The model reproduces observed polar temperature and advective heating rate profiles, and also
15 captures many of the climate-change responses found in climate models. Exploring the model's
16 physics, we show that the surface-based temperature inversion develops by ceding energy down-
17 wards to the surface, which then radiates this energy to space; we name this the "surface radiator
18 fin" effect. We use the model to address three outstanding questions regarding polar climate change:
19 (i) What mechanisms control polar lapse-rate change? (ii) What determines the known compen-
20 sation between changes in dry and moist energy transport? and (iii) What is the most physically
21 consistent way to decompose forcing and feedbacks at the poles? In answer to these questions,
22 we show that: (i) Three mechanisms control the lapse-rate response to warming: weakening of
23 the surface radiator fin, increased radiative cooling by free-tropospheric water vapor emission, and
24 relaxation toward the external profile anomaly; all three increase the lapse rate as climate warms.
25 (ii) Compensation between dry and moist advective heating results from a delicate balance be-
26 tween changes in the boundary layer and the free troposphere, with no constraints imposing precise
27 compensation. (iii) Remote advective influence on the poles should be considered a forcing, while
28 lapse-rate and advective heating changes should not be treated as separate feedbacks but rather as
29 part of the temperature feedback.

30 **1. Introduction**

31 The concept of radiative-convective equilibrium (RCE) and its embodiment in a single-column
32 model (Manabe and Strickler 1964; Manabe and Wetherald 1967) is the foundation of our un-
33 derstanding and quantification of climate sensitivity (see review by Jeevanjee et al. 2022). RCE
34 prevails when the atmosphere is heated from below and atmospheric radiative cooling to space is
35 balanced by upward turbulent fluxes at the surface. In RCE, surface and atmospheric temperature
36 are strongly coupled while atmospheric temperature is constrained to follow a moist adiabatic
37 profile, imposing a tight connection between surface temperature and top-of-atmosphere (TOA)
38 energy fluxes. As a result, a unit perturbation of TOA flux will give the same surface temperature
39 response regardless of which forcing or feedback agent provides the perturbation. This fungibility
40 motivates the now-conventional TOA forcing-feedback decomposition (Manabe and Wetherald
41 1980; Sherwood et al. 2015). This decomposition includes a separate lapse-rate feedback, which is
42 reasonable since in RCE the lapse-rate feedback is constrained by the moist adiabat and constitutes
43 a distinct physical mechanism.

44 The opposite limit to RCE is radiative-advective equilibrium (RAE), where convection is absent,
45 surface turbulent fluxes are small or downwards, and diabatic cooling is primarily balanced by
46 lateral energy flux convergence (Payne et al. 2015; Cronin and Jansen 2016). RAE prevails in the
47 polar regions, especially in winter (Miyawaki et al. 2022, 2023). RAE is therefore crucial to polar
48 amplification—the enhanced warming of the poles in response to global forcing that is a robust
49 but still not fully understood feature of Earth’s climate sensitivity (Previdi et al. 2021; Taylor et al.
50 2022). This motivates interest in developing a minimal model of RAE that robustly captures the
51 basic physics of high-latitude climate, as a counterpart to single-column RCE for lower latitudes.

52 Substantial progress has been made in this direction (Payne et al. 2015; Cronin and Jansen 2016;
53 Henry and Merlis 2020; Henry et al. 2021; Freese and Cronin 2021). This previous work shows
54 that RAE is profoundly different from RCE. In RAE, fungibility is lost: the surface response to
55 unit TOA forcing depends on the nature of the forcing. Also, different forcings affect the lapse rate
56 differently; for example, changes in greenhouse gases and in surface solar absorption both give a
57 bottom-amplified response, while changes in advective heating tend to stabilize the atmosphere.
58 This means that it no longer makes sense to think of lapse-rate feedback as a single, standalone
59 mechanism but rather as the residual of disparate effects. It also raises basic questions, such as why

60 a well-mixed gas like CO₂ should give a similar lapse-rate response to a surface forcing, and why
61 both of these are different from the response to advective heating. These are important questions
62 considering the major role attributed to lapse-rate feedback in explaining polar amplification by
63 the conventional TOA decomposition (Pithan and Mauritsen 2014; Hahn et al. 2021).

64 The central difficulty in formulating a single-column RAE model is how to specify advective
65 heating. Advection depends on horizontal gradients and is intrinsically non-local, contrary to the
66 locality of a single-column model. In the prior work cited above, this problem is circumvented
67 by simply prescribing a fixed profile of advective heating. But in RAE, advective heating must
68 balance diabatic cooling. A change to radiative cooling within the column—due for example to
69 changing greenhouse gas concentrations—will automatically result in changed advective heating.
70 Keeping advective heating fixed breaks this physical connection between polar energy convergence
71 and other forcings and feedbacks (Feldl et al. 2017; Russotto and Biasutti 2020; Beer and Eisenman
72 2022). Advective heating should be internally determined as part of the solution, but this requires
73 information about extra-polar fields not available in a single polar column.

74 A potential way out of this impasse is suggested by the results of climate model simulations where
75 radiative forcing is applied within limited latitude bands (Chung and Räisänen 2011; Yoshimori
76 et al. 2017; Shaw and Tan 2018; Stuecker et al. 2018; Semmler et al. 2020). These simulations
77 all show that while the poles respond strongly to forcing applied in lower latitudes, the opposite is
78 not true: midlatitude temperatures are to a first approximation unaffected by polar forcing. This
79 suggests that conditions at the poleward edge of the midlatitudes provide a boundary condition for
80 the polar climate. By appropriately applying this boundary condition to a single-column model,
81 it would be possible to simulate changes internal to the polar column while keeping this boundary
82 condition fixed, or simulate remote effects on the poles by changing the boundary condition, all
83 while allowing advective heating to adjust in a physically consistent way.

84 Here, our first aim is to search for a simple yet sufficiently realistic way to apply the boundary
85 condition. In Section 2, we show that advective heating can be approximated as a simple relaxation
86 toward specified temperature and humidity profiles representative of midlatitude conditions, and
87 provide empirical justification for this approximation. We implement it in a single-column model
88 using realistic radiation, a simple turbulence scheme and assuming clear-sky conditions. Testing
89 this model against reanalysis shows satisfactory results.

90 Our second aim is to explore the single-column model to better understand the nature of the
91 RAE regime and its response to local and remote perturbations (Sections 3–7). We address the
92 following specific questions:

- 93 1. What mechanisms control the polar lapse-rate response to global warming? More fundamen-
94 tally, why is there a climatological surface-based temperature inversion in the first place, and
95 what controls its strength?
- 96 2. Why do changes in moist and dry energy transport to the poles tend to compensate each other
97 (Hwang et al. 2011)—are there any strong constraints acting to enforce this compensation?
- 98 3. What is the best way to decompose forcing and feedbacks at the poles?

99 The relaxation approach used in the single-column model developed here connects directly with
100 the air-mass transformation perspective on polar climate (Pithan et al. 2018). In this perspective,
101 midlatitude maritime air masses are advected into the polar cap, cool diabatically, and exit as
102 polar air masses with lower temperature and humidity. The polar cap is continuously ventilated by
103 an ensemble of such transient air-mass transformation events, and the steady-state single column
104 model aims to capture the average effect of an ensemble of such events. We will emphasize
105 this perspective throughout the paper, as it proves useful in gaining intuitive understanding of the
106 model’s behavior.

107 **2. The single-column model**

108 *a. A simple expression for polar advective heating*

109 We begin by writing the temperature tendency $\partial_t T$ at a given point in the polar atmosphere as

$$\partial_t T = Q_{\text{rad}} + Q_{\text{dif}} + Q_{\text{dry}} + Q_{\text{lat}} \quad (1)$$

110 where Q_{rad} is the radiative cooling rate, Q_{dif} is the heating or cooling rate due to diffusive
111 energy fluxes by small-scale turbulence, Q_{dry} is the advective heating rate due to dry static energy
112 convergence by the large-scale flow, and Q_{lat} is the heating rate due to net condensation and latent
113 heat release. This expression assumes that the polar atmosphere is always statically stable and
114 there is no convective heating term.

115 In steady state, or for long-term averages, the net condensation rate equals the rate of moisture
 116 convergence. In this case, the last two terms on the r.h.s. can be written in terms of the moist static
 117 energy (MSE) convergence:

$$Q_{\text{adv}} \equiv Q_{\text{dry}} + Q_{\text{lat}} = -\frac{1}{c_p} \nabla \cdot (\mathbf{u}h) \quad (2)$$

118 where $\mathbf{u} = (u, v, \omega)$ is the three-dimensional large-scale wind and $h = c_p T + \ell_v q + gz$ is the MSE,
 119 with c_p the specific heat of air, ℓ_v the latent heat of condensation, q the specific humidity and
 120 gz the geopotential, and we have defined Q_{adv} as the total advective heating rate. Averaging (2)
 121 horizontally over a polar cap (i.e. the region poleward of a given latitude line) and using the
 122 divergence theorem yields

$$c_p \overline{Q}_{\text{adv}} = \frac{1}{L} [vh] - \partial_p \overline{\omega h} \quad (3)$$

123 where $\overline{(\cdot)}$ indicates an area average over the cap, $[\cdot]$ indicates a zonal average around the edge of
 124 the cap, and $L = C/A$ with C the circumference and A the area of the cap. Separating mean and
 125 eddy components, (3) can be rewritten as

$$c_p \overline{Q}_{\text{adv}} = \underbrace{\frac{1}{L} [v] \left([h] - \overline{h} \right)}_{\text{MMC}} - \underbrace{\frac{1}{L} [v^* h^*]}_{\text{Horizontal eddy}} - \underbrace{\partial_p \overline{\omega' h'}}_{\text{Vertical eddy}} \quad (4)$$

126 where stars and primes indicate deviations from the zonal and polar-cap mean respectively. The
 127 first two terms on the r.h.s. represent MSE convergence by the mean meridional circulation (MMC),
 128 the third term represents horizontal MSE convergence by eddies around the edge of the polar cap,
 129 and the last term represents vertical MSE redistribution by eddies within the polar cap.

130 The horizontal eddy term can further be rewritten in terms of inward- and outward-oriented
 131 fluxes defined as

$$v^{\text{in}} = [H(v^*) v^*], \quad h^{\text{in}} = \frac{1}{v^{\text{in}}} [H(v^*) v^* h], \quad h^{\text{out}} = \frac{1}{-v^{\text{in}}} [H(-v^*) v^* h], \quad (5)$$

132 where H is the Heaviside function and we have used $[v^* h^*] = [v^* h]$. In the Northern Hemisphere,
 133 v^{in} is the eddy mass flux flowing *into* the polar cap, while h^{in} and h^{out} are the mass-flux-weighted

134 mean MSE values of air flowing into and out of the cap respectively. With these definitions, the
 135 horizontal eddy term becomes

$$\frac{1}{L}[v^*h^*] = -\frac{1}{\tau}(h^{\text{out}} - h^{\text{in}}) \quad (6)$$

136 where

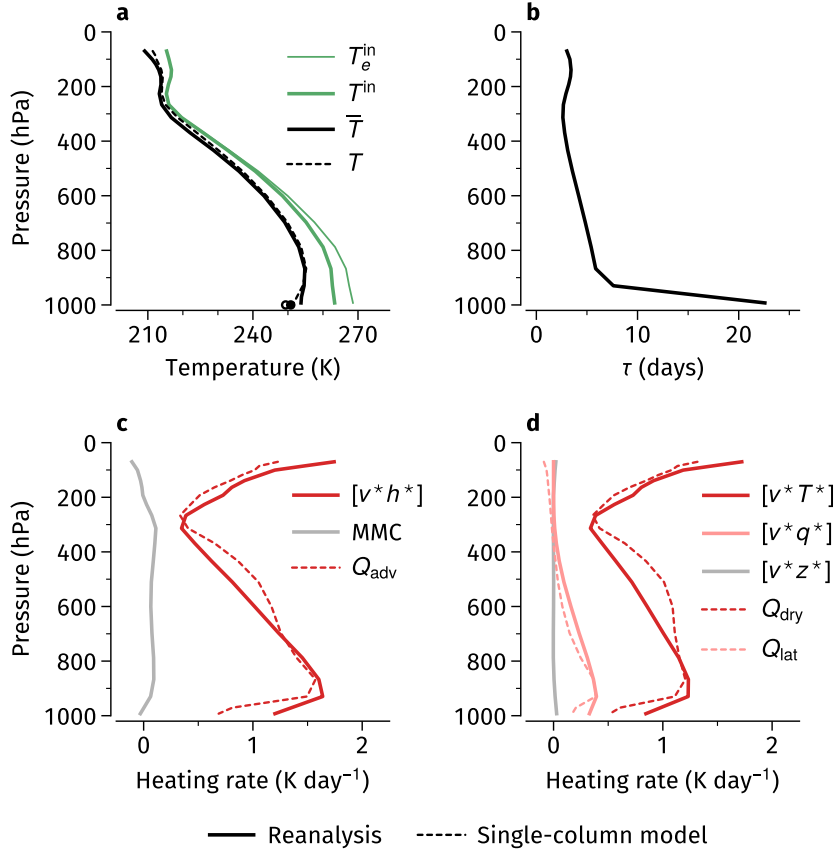
$$\frac{1}{\tau} = \frac{v^{\text{in}}}{L}.$$

137 To understand the relative importance of the various terms in (4), we evaluate them directly
 138 using the ERA-Interim reanalysis product. We use 6-hourly data on pressure levels, masking out
 139 ‘underground’ regions where pressure is greater than surface pressure. Following previous work
 140 (Overland and Turet 1994; Cardinale et al. 2021), the vertical mean is removed from $[v]$ to exclude
 141 spurious contributions from net mass convergence. Results at 65°N (Figure 1c) show that the MMC
 142 term in (4) is much smaller than the horizontal eddy term at all levels. Similar results are obtained
 143 for other latitudes of the equatorward edge of the polar cap between 60-80°N (not shown). The
 144 negligible role played by the MMC in the Arctic is very different from the situation in the tropics,
 145 where weak temperature gradient constraints mean that radiative cooling is mostly balanced by
 146 $\overline{\omega}\partial_p\overline{h}$ (Sobel and Bretherton 2000).

147 Separating the horizontal eddy term into its three MSE components (Figure 1d) shows that the
 148 geopotential convergence term is also negligible, which is not surprising since pressure levels are
 149 close to horizontal at a given latitude. Attempts to compute the vertical eddy term fail however,
 150 yielding unrealistically large values likely due to problems with local mass balance arising from the
 151 interpolation to pressure coordinates and from errors in the analysis itself which produce unphysical
 152 large-amplitude noise in the ω' field (Trenberth 1991).

158 Given these results, we make the following approximations: (i) neglect the MMC term; (ii)
 159 neglect the geopotential component of the MSE convergence; (iii) neglect the vertical eddy term.
 160 Approximation (iii) cannot be directly justified from our observational analysis, but will be validated
 161 a posteriori as discussed below. With these approximations, our final expression for the polar-mean
 162 advective heating rate becomes simply

$$\overline{Q}_{\text{adv}} \approx -\frac{1}{\tau}(T_e^{\text{out}} - T_e^{\text{in}}) \quad (7)$$



153 FIG. 1. (a) Temperatures, (b) ventilation timescale and (c,d) advective heating rates for the polar cap bounded
 154 by 65°N latitude. In all panels, solid lines show climatologies computed from the ERA-Interim reanalysis for
 155 winter (December-February) of 1980-2018, dotted lines show steady-state results for a single-column model
 156 simulation using the reanalysis T_e^{in} and τ profiles in (a,b) as input. In (a), dots along the bottom show surface
 157 temperature in reanalysis (filled) and model (hollow).

163 where

$$T_e = T + \frac{\ell_v}{c_p} q \quad (8)$$

164 is approximately the equivalent temperature at fixed pressure.

165 Expression (7) can be interpreted in two ways. From an Eulerian perspective, it can be seen as a
 166 coarse-grained advection, with a wind v^{in} acting on a gradient $(T_e^{\text{out}} - T_e^{\text{in}})/L$. From a Lagrangian
 167 air-mass transformation perspective, τ is a ventilation timescale, the typical time taken for an air
 168 parcel to cross the polar cap—note that L is roughly the diameter of the cap, and Figure 1b shows

169 $\tau \sim 5$ days at 800-900 hPa, consistent with the crossing timescale found in Lagrangian studies
 170 (Woods and Caballero 2016). Air parcels enter the polar cap with equivalent temperature T_e^{in} ,
 171 travel isobarically while cooling radiatively and diffusively for a time τ , and exit with the smaller
 172 equivalent temperature T_e^{out} ; the rate of energy convergence is proportional to the resulting energy
 173 drop. Both perspectives are equally valid, but we will emphasize the air-mass transformation
 174 perspective here since it makes explicit the tight connection between lateral energy convergence
 175 and diabatic cooling within the polar column.

176 *b. Model implementation*

177 We specify the single-column model as

$$\partial_t T = \underbrace{Q_{\text{rad}} + Q_{\text{dif}}}_{Q_{\text{dia}}} + \underbrace{Q_{\text{dry}} + Q_{\text{lat}}}_{Q_{\text{adv}}} \quad (9)$$

178 where T is a prognostic temperature profile controlled by the diabatic cooling rate $Q_{\text{dia}} = Q_{\text{adv}} + Q_{\text{dif}}$
 179 and the advective heating rate $Q_{\text{adv}} = Q_{\text{dry}} + Q_{\text{lat}}$. Using (7) and taking the outflow temperature
 180 T^{out} as the column temperature T , we obtain

$$Q_{\text{dry}} = -\frac{1}{\tau} (T - T^{\text{in}}), \quad Q_{\text{lat}} = -\frac{1}{\tau} \frac{\ell_v}{c_p} (\text{RH} q_{\text{sat}}(T) - q^{\text{in}}) \quad (10)$$

181 where T^{in} and q^{in} are prescribed inflow temperature and specific humidity, q_{sat} is saturation specific
 182 humidity and RH is a prescribed relative humidity.

183 Equation (10) realises the goal of expressing remote effects on the polar column as a relaxation
 184 to prescribed external temperature and humidity profiles, an approach originally suggested (though
 185 not developed) by Cronin and Jansen (2016). Note that since the column temperature is generally
 186 much colder than the inflow temperature, $q_{\text{sat}}(T) \ll q^{\text{in}}$ and the total advective heating rate can be
 187 approximated as $Q_{\text{adv}} \approx \tau^{-1} (T - T_e^{\text{in}})$, i.e. as a relaxation of the column temperature toward the
 188 inflow equivalent temperature T_e^{in} . However, we retain the full form of (10) in the model.

189 At its lower boundary, the column is coupled to a surface slab of fixed heat capacity c and
 190 temperature T_s :

$$c \partial_t T_s = F_{\text{rad}} + F_{\text{SH}} + F_s \quad (11)$$

191 where F_{rad} is the net surface longwave radiative flux and F_{SH} is the surface sensible heat flux,
192 computed using the bulk-aerodynamic formulation $F_{\text{SH}} = \gamma(T_0 - T_s)$ where T_0 is atmospheric
193 temperature at the lowest model level and γ is a fixed exchange coefficient. Surface latent heat flux
194 is neglected. As in previous work (Payne et al. 2015; Henry et al. 2021), we include a prescribed
195 surface energy source F_s to represent absorbed surface insolation, ocean energy convergence into
196 the slab, or the sum of both.

197 Radiative fluxes and cooling rate Q_{rad} are computed using the longwave radiative transfer scheme
198 of the NCAR CAM3 model (Collins et al. 2004), with only water vapor and CO_2 as radiatively-
199 active gases. We assume clear-sky conditions and neglect atmospheric solar absorption. Turbulent
200 fluxes and heating rate Q_{dif} are computed using a simple diffusive scheme with fixed diffusivity
201 applied to potential temperature, as described in Caballero et al. (2008). Humidity diffusion is
202 neglected.

203 The complete model is implemented in practice using the CliMT framework (Monteiro and
204 Caballero 2016; Monteiro et al. 2018, we use the “classic” version here). The column is discretized
205 into 26 levels using the native CAM3 model grid (Collins et al. 2004), which is non-uniform in
206 pressure with more tightly spaced levels near the surface, improving resolution in the boundary
207 layer. The model is time-marched until the temperature profile reaches steady state, and all results
208 shown below refer to this steady state. Note that all simulations presented here do in fact converge
209 to a fixed point and show no oscillatory or chaotic behavior.

210 *c. Design of simulations and forcing-feedback decomposition*

211 To define a simulation, the following parameters need to be specified: inflow equivalent temper-
212 ature T_e^{in} , ventilation rate $1/\tau$, CO_2 concentration, surface heat source F_s , relative humidity RH,
213 kinematic diffusivity ν for the turbulence scheme, and surface exchange coefficient γ . All simula-
214 tions in this paper use $\gamma = 6.55 \text{ W m}^{-2} \text{ K}^{-1}$ and a vertically uniform $\text{RH} = 80\%$. Diffusivity follows
215 an exponentially-decaying profile $\nu = \nu_s \exp(-(p_s - p)/\Delta p)$ with a surface value $\nu_s = 1 \text{ m}^2 \text{ s}^{-1}$ and
216 a decay rate $\Delta p = 400 \text{ hPa}$; this is done to avoid excessive diffusion around the tropopause. Other
217 parameters vary as described below.

218 To explore the model’s basic physics, we define a set of simulations using simplified settings: τ
219 is vertically uniform, and T_e^{in} is specified by defining T^{in} as a profile with a constant lapse rate of

220 6 K km^{-1} from a surface temperature T_0^{in} up to an isothermal stratosphere at 210 K, and q^{in} as the
221 corresponding specific humidity assuming $\text{RH} = 80\%$. We define the following simulations:

- 222 • A base simulation \mathcal{B} , intended to represent the preindustrial polar climate, with $\text{CO}_2 =$
223 280 ppm , $T_0^{\text{in}} = 0^\circ\text{C}$ (the observed annual-mean surface temperature at around 60°N), $F_s =$
224 50 W m^{-2} (roughly the annual-mean absorbed surface solar radiation averaged over the cap
225 poleward of 60°N), and $\tau = 10 \text{ days}$.
- 226 • A perturbed simulation \mathcal{P} , intended to represent the effects of a global doubling of CO_2 , with
227 $\text{CO}_2 = 560 \text{ ppm}$ and T_0^{in} increased by 3 K from the base state, consistent with central estimates
228 of global climate sensitivity to a doubling of CO_2 . Changes in surface heat source F_s are
229 a proxy for sea ice feedback in this model. For guidance, Arctic surface albedo feedback
230 is estimated at $\sim 3 \text{ W m}^{-2}$ per K of global warming in climate models (Andry et al. 2017),
231 suggesting $\Delta F_s = 10 \text{ W m}^{-2}$ is an appropriate round-number value for this perturbation.
232 Changes in τ depend on subtle changes in atmospheric dynamics which are difficult to specify
233 a priori, so we simply leave it unchanged.
- 234 • A set of single-perturbation simulations $\{\mathcal{P}_{\text{in}}, \mathcal{P}_s, \mathcal{P}_{\text{CO}_2}, \mathcal{P}_q\}$ where the perturbations of \mathcal{P}
235 are applied one at a time. These simulations are intended to provide a forcing-feedback
236 decomposition of the change from \mathcal{B} to \mathcal{P} , as done in Henry et al. (2021). They are conducted
237 with humidity held fixed: in $\mathcal{P}_{\text{CO}_2}$, \mathcal{P}_{in} , and \mathcal{P}_s the temperature is allowed to respond to
238 increased CO_2 , T_e^{in} , and F_s respectively, but q is held fixed at its value in \mathcal{B} . To evaluate the
239 water vapor feedback, \mathcal{P}_q has humidity fixed at its value in \mathcal{P} . Water vapor plays a dual role
240 in the model, affecting both radiative cooling Q_{rad} and latent heating Q_{lat} . These roles are
241 decoupled in the partial perturbation runs: humidity is fixed only the radiation component, so
242 as to isolate the purely radiative water vapor feedback.

243 *d. Testing the model against reanalysis*

244 To test the model's skill in reproducing observed temperature and heating profiles, we define a
245 simulation aimed to capture the modern Arctic climate. This simulation is identical to the base
246 simulation \mathcal{B} above, except that T_e^{in} and τ are taken from reanalysis (profiles shown in Figure 1a,b),
247 and CO_2 is set to 370 ppm, a typical value for the 1980-2018 period covered by the reanalysis data.

248 Results for this observationally-informed simulation are shown by dashed lines in Figure 1, where
249 they can be directly compared with corresponding reanalysis climatologies (solid lines). In view
250 of the model’s simplicity, its match to the data is surprisingly good. It reproduces the structure
251 and magnitude of the temperature profile with good accuracy (Figure 1a), except near the surface
252 where it overpredicts the intensity of the surface inversion and makes surface temperature too
253 cold. It also gives a good match to the advective heating rate (Figure 1c), in particular capturing
254 the location of peak heating at around 900 hPa and its decline below that level—note that this is
255 also the region where the ventilation timescale shows a sharp increase (Figure 1b). Perhaps most
256 surprisingly, the model also captures the partitioning between dry and latent heating quantitatively
257 well (Figure 1d), despite its very simple treatment of condensation. We note also that the good
258 match to observations provides a posteriori justification for the neglect of eddy vertical transport
259 in the derivation of Eq. (7).

260 3. The surface radiator fin

261 Results for the base simulation \mathcal{B} are shown by solid lines in Figure 2. The diabatic cooling
262 rate (blue line in Figure 2b) has a bottom-heavy structure, with a strong peak at the surface. This
263 bottom-amplified cooling rate structure makes the column temperature profile more stable than
264 the inflow temperature T^{in} throughout the troposphere, and an inversion develops near the surface
265 (Figure 2a).

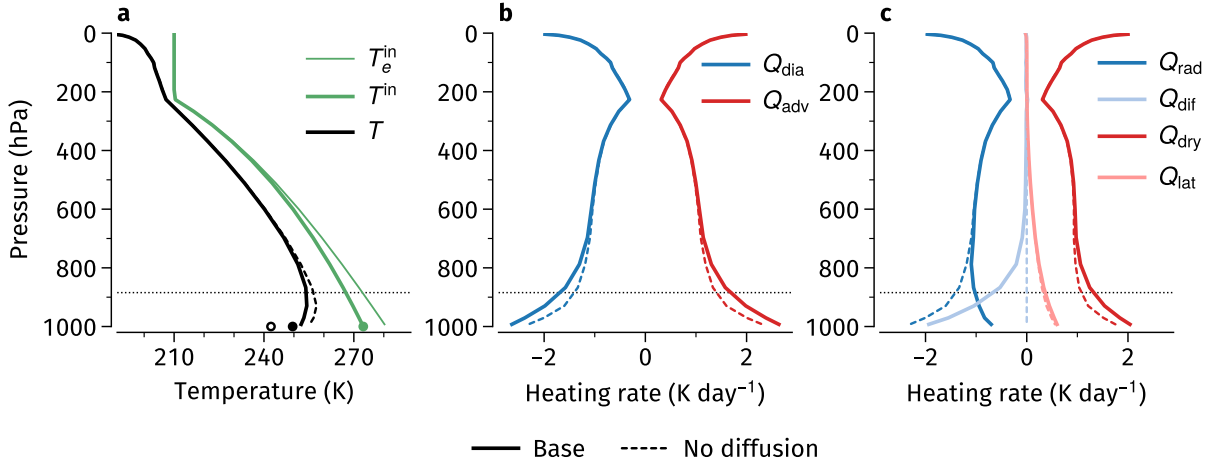
266 The advective heating rate profile (red line in Figure 2b) is just the mirror image of the cooling
267 rate: air parcels experience greatest cooling and converge most energy where the cooling rate is
268 strongest. The profile is qualitatively similar to that of the winter Arctic diagnosed from reanalysis
269 (Figure 1c), except that in reanalysis it peaks around 900 hPa instead of at the surface. We attribute
270 this difference to the different profile of the ventilation timescale τ , which is vertically uniform
271 in this simulation but peaks strongly near the surface in reanalysis (Figure 1b). Winds are more
272 sluggish near the surface and tend to recirculate around the Arctic (Papritz et al. 2023), reducing
273 the rate of energy convergence. The difference is not crucial, however; we have repeated all the
274 simulations described in this paper using the reanalysis τ profile and find no qualitative change in
275 our results.

276 Separating the diabatic cooling rate into its radiative and diffusive components (Figure 2c) shows
277 the latter contributes strongly to the surface peak, giving the impression that diffusion is essential
278 in creating the temperature inversion. This is not the case, however: repeating simulation \mathcal{B} with
279 diffusion deactivated (dashed lines in Figure 2) shows radiative cooling increasing to replace the
280 lost diffusive cooling. Total diabatic cooling remains essentially unchanged, and the temperature
281 inversion persists albeit with a much larger surface discontinuity. This interchangeability between
282 radiative and turbulent fluxes implies that the temperature inversion is a fundamental feature of the
283 polar climate, independent from the details of atmospheric energy transfer.

284 The ultimate cause of the temperature inversion is the intrinsic thermodynamic disequilibrium
285 between atmosphere and surface in the polar climate. Because the atmosphere is optically thin
286 while the surface is opaque, the surface can cool strongly by direct emission to space; this has
287 long been recognized as the basic reason for the existence of transient surface-based inversions
288 in polar regions (Wexler 1936; Curry 1983). If surface cooling is climatologically balanced only
289 by the weak polar insolation, the result is a steady-state surface temperature much colder than
290 the air flowing in from lower latitudes. Basic thermodynamics dictates that this disequilibrium
291 will generate downward energy fluxes from the atmosphere to the surface, which will warm the
292 surface and cool the atmosphere but cannot make the surface warmer than the atmosphere and
293 cannot remove the temperature inversion. The term *radiator fin* has been used in climate science
294 to describe a situation where one part of the atmosphere is cooled by energy transfer to another
295 part—the radiator fin—where it can be efficiently emitted to space (Pierrehumbert 1995). In this
296 sense, the surface serves as a radiator fin for the lower atmosphere.

301 To make this picture quantitative, we first separate the atmospheric longwave radiative flux into
302 two streams. One, denoted F_{atm} , consists of radiation absorbed and emitted by the atmosphere
303 and is responsible for atmospheric radiative cooling. The other, denoted F_{win} , consists of radiation
304 emitted by the surface which travels through the atmosphere with no interaction, largely in the
305 wavelength range containing the water vapor window. Profiles of the two streams, along with the
306 turbulent energy flux denoted F_{dif} , are shown in Figure 3a.

307 Under the dry, clear-sky conditions of this simulation, F_{win} is large and accounts for almost half
308 of the outgoing longwave radiation. Only F_{atm} and F_{dif} contribute to atmospheric cooling and to
309 atmosphere-surface energy exchange. F_{atm} is everywhere upward while F_{dif} is downward; their sum



297 FIG. 2. (a) Temperature and (b,c) heating/cooling rate profiles in the base simulation \mathcal{B} , as indicated by the
 298 legend in each panel (solid lines). Dashed lines show results for simulation \mathcal{B} performed with zero diffusivity. In
 299 (a), black dots show surface temperature in the standard (filled) and no-diffusion case (hollow), green dot shows
 300 surface inflow temperature T_0^{in} . Thin dotted lines indicate the zero-flux level.

310 crosses zero around 900 hPa, with net downward energy transport below this level. The zero-flux
 311 level coincides with the top of the temperature inversion (dotted line in Figure 2a), implying that
 312 the inversion layer is where the atmosphere is cooling primarily by energy transfer to the surface,
 313 rather than to space. Note that exactly the same result is obtained in the no-diffusion case, except
 314 that the downward flux to the surface is entirely carried by radiation (dashed lines in Figure 3a).

315 The surface energy budget (Figure 3b) shows that the surface extracts a total of 27 W m^{-2} from
 316 the atmosphere, which it then emits directly to space through F_{win} (together with 50 W m^{-2} from
 317 the surface heat source F_s), confirming the radiator fin picture. The radiator fin is not a large
 318 contributor to the total atmospheric energy budget, however, which is dominated by 113 W m^{-2} in
 319 dry atmospheric energy transport AHT_{dry} , defined as

$$\text{AHT}_{\text{dry}} = \frac{c_p}{g} \int_0^{P_s} Q_{\text{dry}} dp, \quad (12)$$

320 and a smaller contribution from moist transport $\text{AHT}_{\text{moist}}$ (defined similarly but with Q_{lat} replacing
 321 Q_{dry}), which are mostly balanced by 102 W m^{-2} emission to space. Nonetheless, the radiator fin

342 TABLE 1. Effective water vapor window width w and disequilibrium D (Eq. 13) in the base simulation (first
 343 column), and their change in perturbed simulations (remaining columns).

	\mathcal{B}	\mathcal{P}_{in}	\mathcal{P}_s	$\mathcal{P}_{\text{CO}_2}$	\mathcal{P}_q	\mathcal{P}
w	0.35	0.00	0.00	-0.01	-0.02	-0.03
D (K)	44	5	-10	-2	-3	-10

322 acts on a shallow layer and drives strong cooling there, and is essential in controlling the strength
 323 of the temperature inversion.

324 To give a quantitative measure for the strength of the radiator fin effect, we define a surface
 325 temperature T_s^* which would balance the surface heat source F_s in the absence of warming by
 326 energy transfer from the atmosphere: $w\sigma T_s^{*4} = F_s$, where w is the fraction of the surface upward
 327 radiation emitted directly to space and measures the effective width of the water vapor window.
 328 We can then define a temperature difference

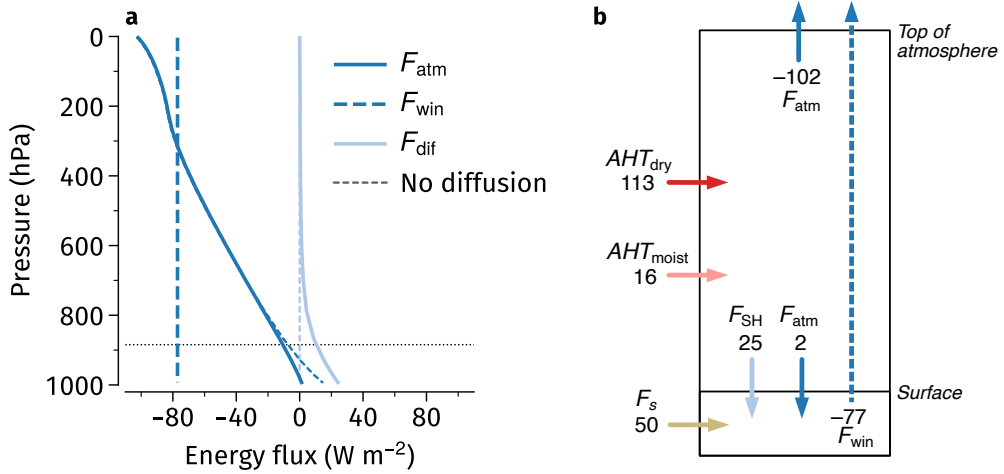
$$D = \langle T_e^{\text{in}} \rangle - T_s^* = \langle T_e^{\text{in}} \rangle - \left(\frac{F_s}{w\sigma} \right)^{1/4} \quad (13)$$

329 where $\langle \cdot \rangle$ is an average over the 900–1000 hPa layer. D gives a bulk measure of the thermodynamic
 330 disequilibrium discussed earlier in this section. Values of w and D are given in Table 1, with w
 331 diagnosed as $F_{\text{win}}/\sigma T_s^4$. The diagnosed magnitude of the window width w of 0.35 is comparable
 332 to Cronin and Jansen (2016)’s suggested 0.25 for clear-sky conditions, and the disequilibrium D
 333 of 44 K is approximately double the model’s contrast between equilibrated surface temperature
 334 ≈ 250 K and the inflow temperature ≈ 270 K. We expect that perturbations that increase the
 335 disequilibrium, such as a warming of the inflow, will increase the strength of the inversion, while
 336 an increase in F_s or a narrowing of the water vapor window will weaken the inversion. These
 337 expectations are tested in the next section.

344 4. Response to perturbations

345 a. Lapse rate

346 When the base state \mathcal{B} is perturbed by a simultaneous increase of T^{in} , CO_2 , and F_s to yield
 347 the perturbed state \mathcal{P} , the temperature profile warms throughout the troposphere and cools in the

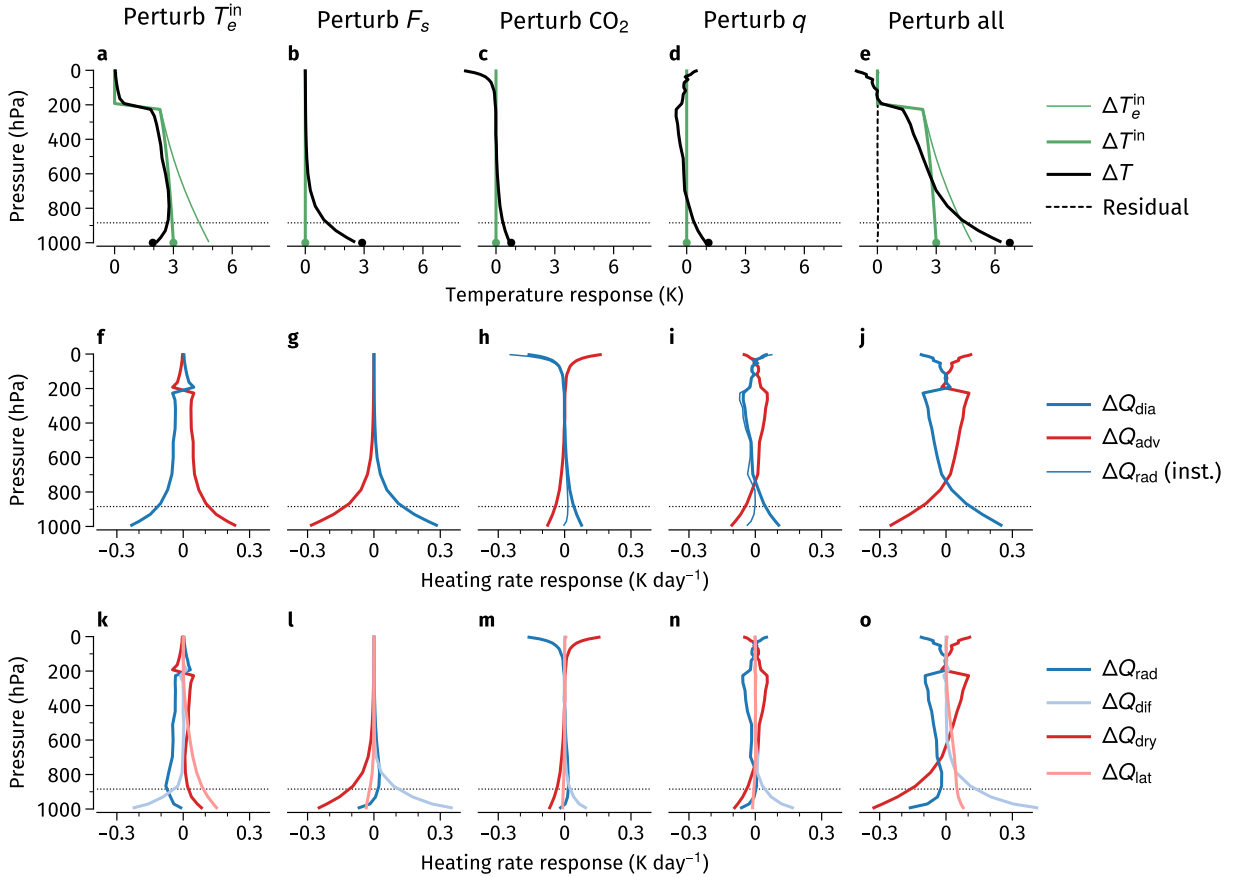


338 FIG. 3. (a) Radiative and diffusive energy fluxes, defined positive downwards, in the base simulation \mathcal{B}
 339 (solid and thick dashed lines, see text for definitions). Thin dashed lines show the corresponding fluxes in the
 340 no-diffusion simulation. (b) Column energy budget in \mathcal{B} . All fluxes in W m^{-2} , vertical fluxes defined positive
 341 downward.

348 stratosphere (Figure 4e). The warming has a bottom-heavy structure, with lapse rate increasing
 349 strongly near the surface and more weakly at upper levels. Comparing this response to the change
 350 in inflow temperature T^{in} (thick green line) gives a measure of the polar amplification between
 351 midlatitudes and the pole. Polar amplification is strong in the lower troposphere but negative at
 352 upper levels, where the pole warms less than midlatitudes. All these features agree with the results

353 of comprehensive climate models subject to global forcing (Previdi et al. 2021; Taylor et al. 2022),
 354 To understand the origins of this general destratification of the polar atmosphere, we examine
 355 the single-perturbation simulations \mathcal{P}_{in} , \mathcal{P}_s , $\mathcal{P}_{\text{CO}_2}$ and \mathcal{P}_q . They provide a forcing-feedback
 356 decomposition of the total response with near-zero residual (dashed line in Figure 4e), implying
 357 the decomposition is almost perfectly linear. In the following paragraphs we examine each of the
 358 perturbations in turn, starting with the response to increased surface heat source (\mathcal{P}_s), moving on
 359 to greenhouse gases ($\mathcal{P}_{\text{CO}_2}$ and \mathcal{P}_q), and ending with the response to inflow warming (\mathcal{P}_{in}).

360 The temperature response to increased F_s is strongly bottom-amplified in the lower troposphere
 361 and negligible above ~ 600 hPa (Figure 4b), implying a strong reduction in inversion strength and
 362 confirming our expectations based on the radiator fin picture of the previous section: increasing F_s



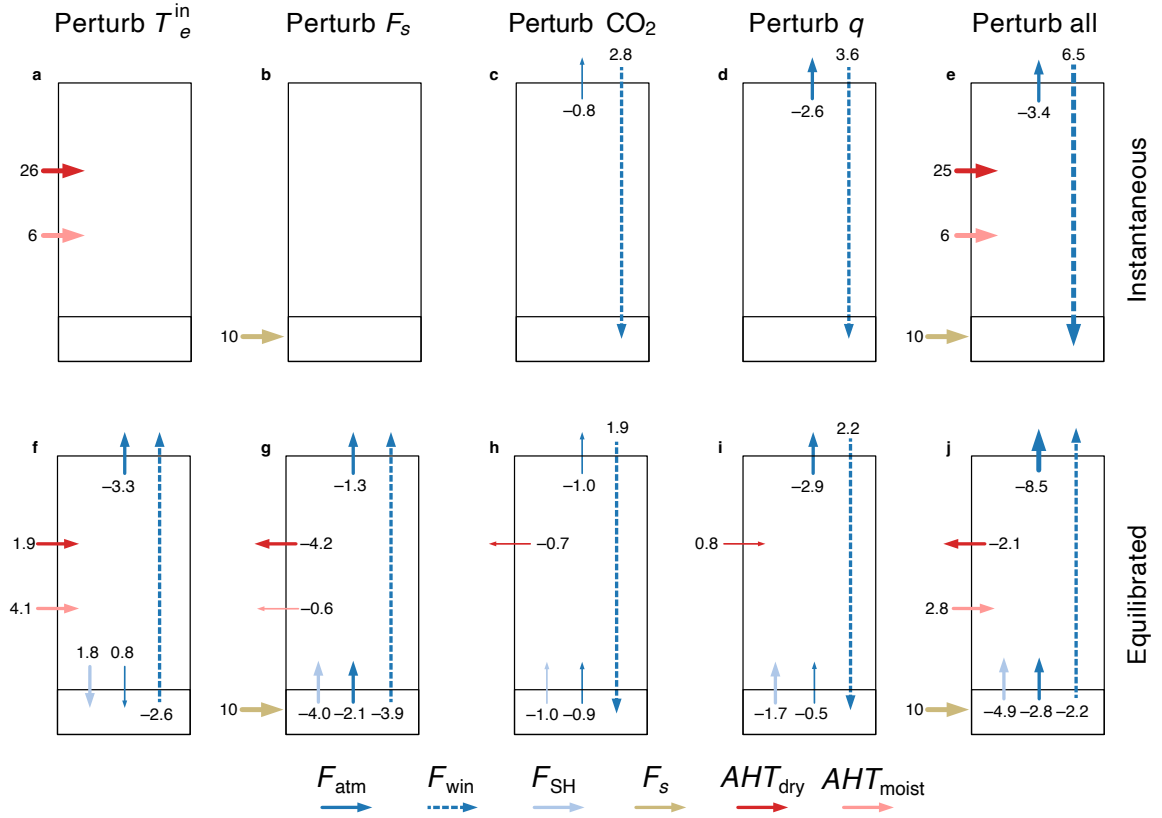
370 FIG. 4. Changes in temperature (top row) and heating/cooling rates (middle and bottom rows) from base
 371 simulation \mathcal{B} to perturbed simulation \mathcal{P}_{in} (first column), \mathcal{P}_s (second column), \mathcal{P}_{CO_2} (third column), \mathcal{P}_q (fourth
 372 column) and \mathcal{P} (fifth column). Dots in top row show surface temperature change in the inflow (green) and in the
 373 column (black). Dashed line in (e) shows the residual between the sum of individual responses in (a-d) and the
 374 full response in \mathcal{P} . Thin blue lines in (h,i) show the instantaneous response of the radiative cooling rate when
 375 the corresponding perturbation is applied. Thin dotted lines indicate the zero-flux level of the base simulation.

363 reduces atmosphere-surface disequilibrium D by 10 K (Table 1). Physically, air masses entering the
 364 polar cap now encounter a warmer surface, experience weaker diabatic cooling as they traverse the
 365 cap (Figure 4g), and therefore remain warmer. This effect is strongest in the inversion layer below
 366 the zero-flux level, which is directly coupled to the surface, but is communicated some distance
 367 upward by intra-atmospheric radiative and diffusive energy exchange. The upper troposphere
 368 experiences no forcing and remains unaffected. Reduced energy transfer from atmosphere to
 369 surface also implies an *upward* anomaly in surface radiative and turbulent fluxes (Figure 5g).

376 Turning to greenhouse gas forcing in $\mathcal{P}_{\text{CO}_2}$ and \mathcal{P}_q (Figure 4c,d), we see in both cases a bottom-
377 amplified structure similar to that in \mathcal{P}_s , at least in the near-surface layer. The instantaneous effect
378 of increasing either CO_2 or H_2O concentrations is to render previously transparent wavelengths
379 opaque, blocking direct surface emission to space within a certain wavelength range (Jeevanjee et al.
380 2021; Seeley and Jeevanjee 2021; Koll et al. 2023). The result is an effective narrowing of the water
381 vapor window. This leads to an instantaneous decrease in surface cooling by F_{win} (Figure 5c,d) and
382 thus a warming tendency on the surface (consistent with a surface vs. atmosphere decomposition
383 of reanalysis-based CO_2 forcing for Earth’s Arctic, Chen et al. 2023, their Figs. 10a,b). Hence the
384 similarity between the response to greenhouse gases and to direct surface warming by F_s : they both
385 weaken D (Table 1), making the surface radiator fin less efficient albeit by different mechanisms.

390 Differently from F_s , however, increased water vapor and CO_2 provide strong cooling responses
391 in the free troposphere and stratosphere respectively (Fig. 4c,d; ‘free troposphere’ here refers to the
392 layer between ~ 800 and 300 hPa). Increased CO_2 shifts radiative emission to space from the surface
393 to the stratosphere within a wavelength range on the flanks of the main 15 micron absorption band,
394 causing increased cooling in the stratosphere (Jeevanjee et al. 2021; Chen et al. 2024). Increased
395 humidity produces cooling in the upper troposphere. The interpretation is more subtle in this case.
396 H_2O produces radiative cooling to space throughout the troposphere, but the exponential decay of
397 humidity with height implies an abrupt decline of this cooling ability above a height where the
398 water path drops below a critical level (the upper-tropospheric “kink”, Jeevanjee and Fueglistaler
399 2020). This behavior can clearly be seen in Fig. 2c, which shows fairly uniform radiative cooling
400 rates between 800 and 400 hPa and a sharp decrease towards the tropopause at around 250 hPa.
401 The effect of increasing water vapor is to shift this profile upwards, yielding increased cooling
402 rates in the 250 – 400 hPa layer. This effect is of some importance since it emerges as a key cause
403 of free-tropospheric lapse rate change and of negative upper-level polar amplification, and would
404 be worth exploring further with a more accurate radiative scheme than employed here. The gray-
405 radiation based theory of Cronin and Jansen (2016) also produces a bottom-amplified temperature
406 response to increased atmospheric opacity, but this spectrally-informed picture is more faithful to
407 the balances at upper levels.

408 Finally, we examine the response to increased T_e^{in} . The entire troposphere warms in this case
409 (Figure 4a). Since the T_e^{in} perturbation is itself bottom-heavy (because of greater humidity at



386 FIG. 5. Instantaneous (top row) and equilibrated (bottom row) perturbation energy budget for the change from
 387 base simulation \mathcal{B} to perturbed simulation \mathcal{P}_{in} (first column), \mathcal{P}_s (second column), $\mathcal{P}_{\text{CO}_2}$ (third column), \mathcal{P}_q
 388 (fourth column) and \mathcal{P} (fifth column). Thick arrows show changes $> 1 \text{ W m}^{-2}$, thin arrows $< 1 \text{ W m}^{-2}$. Changes
 389 $< 0.5 \text{ W m}^{-2}$ are omitted for clarity.

410 low levels), and since the model essentially relaxes T to T_e^{in} (see Section 2b), we expect to see a
 411 similar bottom-heavy structure in the T response. This is indeed the case in the free troposphere,
 412 where the lapse rate increases somewhat. Upper-tropospheric warming also leads to increased
 413 atmospheric cooling to space (top-of-atmosphere F_{atm} increases by 3.3 W m^{-2} , Figure 5f). On the
 414 other hand, atmosphere-surface disequilibrium increases, enhancing the surface peak in diabatic
 415 cooling (Figure 4f) and strengthening the inversion (Figure 4a). Warming of the inflow increases the
 416 stratification the lower troposphere, counteracting the destratifying effect of the other perturbations.

417 Equivalently, this ‘forcing’ is not polar amplified at the surface, with ≈ 2 K warming compared to
 418 the imposed 3 K change in T^{in} .

419 *b. Dry and moist energy convergence*

420 A robust result of climate model simulations subject to global radiative forcing is that changes in
 421 vertically-integrated dry and moist energy transport to the poles compensate each other, yielding
 422 near-zero net change in transport (Hwang et al. 2011). This compensation is understood to
 423 result from opposite changes in temperature and moisture gradients: despite polar amplification,
 424 Clausius-Clapeyron scaling means moisture increases more in midlatitudes than at the poles, so
 425 moist transport increases while dry transport drops (Merlis and Henry 2018; Armour et al. 2019).
 426 This compensation also occurs in our all-perturbations simulation \mathcal{P} , where a $+2.8 \text{ W m}^{-2}$ change
 427 in vertically-integrated moist transport is offset by a -2.1 W m^{-2} change in dry transport (Figure 5j).
 428 In the rest of this section, we study how different forcings and feedbacks, and different layers in the
 429 atmospheric column, contribute to this overall compensation.

430 To provide a framework for this discussion, we use (9) and (10) to write the steady-state pertur-
 431 bation energy budget as

$$\frac{1}{\tau}(\Delta T^{\text{in}} - \Delta T) + \frac{1}{\tau}(\alpha^{\text{in}}\Delta T^{\text{in}} - \alpha\Delta T) = -\Delta Q_{\text{dia}} \quad (14)$$

432 where we have defined the Clausius-Clapeyron factor

$$\alpha(T) = \frac{\ell_v \text{RH}}{c_p} \left. \frac{dq_{\text{sat}}}{dT} \right|_T \quad (15)$$

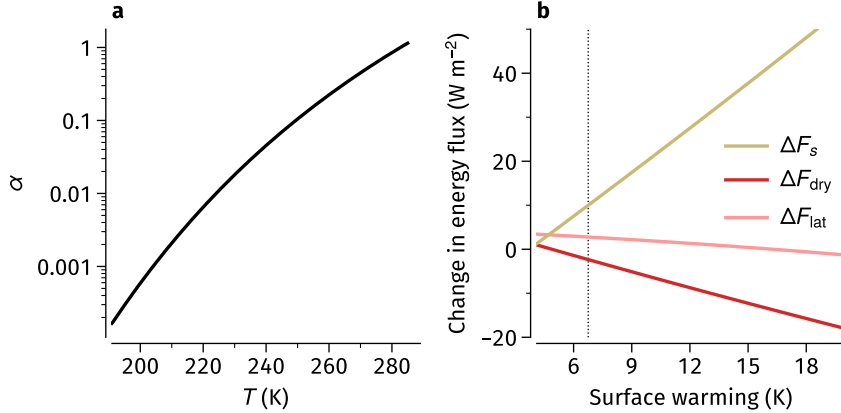
433 and $\alpha^{\text{in}} = \alpha(T^{\text{in}})$. As shown in Figure 6a, $\alpha \approx 1$ at 270 K and drops by an order of magnitude for
 434 every ~ 20 K drop in temperature.

435 In the upper troposphere, base-state temperatures are below 250 K (Figure 2), and both α and
 436 $\alpha^{\text{in}} \ll 1$. Moisture plays a negligible role, and changes in diabatic heating are entirely balanced by
 437 dry heating: specifically, dry heating increases to balance increased radiative cooling in \mathcal{P}_{in} and
 438 \mathcal{P}_q (Figure 4k,n). Physically, increased radiative cooling causes a larger temperature drop from
 439 inflow to outflow, increasing the dry energy convergence.

440 In the lower troposphere, on the other hand, $\alpha \ll 1$ but $\alpha^{\text{in}} \sim 1$. In \mathcal{P}_s , \mathcal{P}_q and $\mathcal{P}_{\text{CO}_2}$ there
 441 is no T_e^{in} perturbation, so (14) reduces to $\Delta T/\tau \approx \Delta Q_{\text{dia}}$ and decreased diabatic cooling is again
 442 balanced almost entirely by reduced dry heating (Figure 4 l,m,n). Physically, these perturbations
 443 warm the surface and reduce the radiator fin effect. The resulting drop in diabatic cooling results in
 444 warmer outflow temperature and reduced dry convergence, but outflow humidity is hardly affected
 445 by the warming so there is little change in moist convergence. In \mathcal{P}_{in} , however, (14) becomes
 446 $(\Delta T^{\text{in}} - \Delta T)/\tau + \alpha^{\text{in}} \Delta T^{\text{in}} \approx -\Delta Q_{\text{dia}}$. In this case, increased latent heating balances much of the
 447 increase in diabatic cooling (Figure 4k). Physically, increased inflow temperature increases the
 448 radiator fin effect; the resulting increase in diabatic cooling mostly consumes the increased latent
 449 heat of the inflow air, however, leading to a modest change in inflow-to-outflow temperature drop
 450 and hence in dry advective heating rate.

451 When added together (Figure 4o), the perturbations give free-tropospheric increase but lower-
 452 tropospheric decrease in dry heating, along with lower-tropospheric increase in latent heating
 453 (contributed entirely by the T_e^{in} perturbation). The vertically-integrated compensation between dry
 454 and moist transports is thus a delicate balance between positive and negative changes at different
 455 levels in the column responding to different physical processes. There is no obvious constraint
 456 imposing exact compensation. It is therefore not surprising that the degree of compensation is
 457 highly variable between climate models (Hwang et al. 2011; Hahn et al. 2021), which have varying
 458 F_s or T^{in} in our framework. Note also that the layer-wise compensation seen in the RAE single-
 459 column model cannot be captured in energy balance models, which parameterize all transport down
 460 moist- or dry-energy gradients based on surface temperature only (e.g., Feldl and Merlis 2021;
 461 Chang and Merlis 2022).

462 Moreover, the degree of compensation is sensitive to the surface heat source perturbation ΔF_s .
 463 If we repeat simulation \mathcal{P} but varying ΔF_s in the range 0–50 W m^{-2} , we find that dry transport
 464 decreases strongly while moist transport stays roughly constant as ΔF_s increases (Figure 6b). This
 465 happens because the negative contribution to dry heating given by the F_s perturbation grows
 466 while leaving latent heating largely unaffected (Figure 4l). Recalling that ΔF_s represents sea ice
 467 feedback in our model, we note that this result provides an explanation for the negative correlation
 468 between the strength of surface albedo feedback and atmospheric energy transport in climate model
 469 intercomparisons (Pithan and Mauritsen 2014; Hahn et al. 2021, their Figure 6).



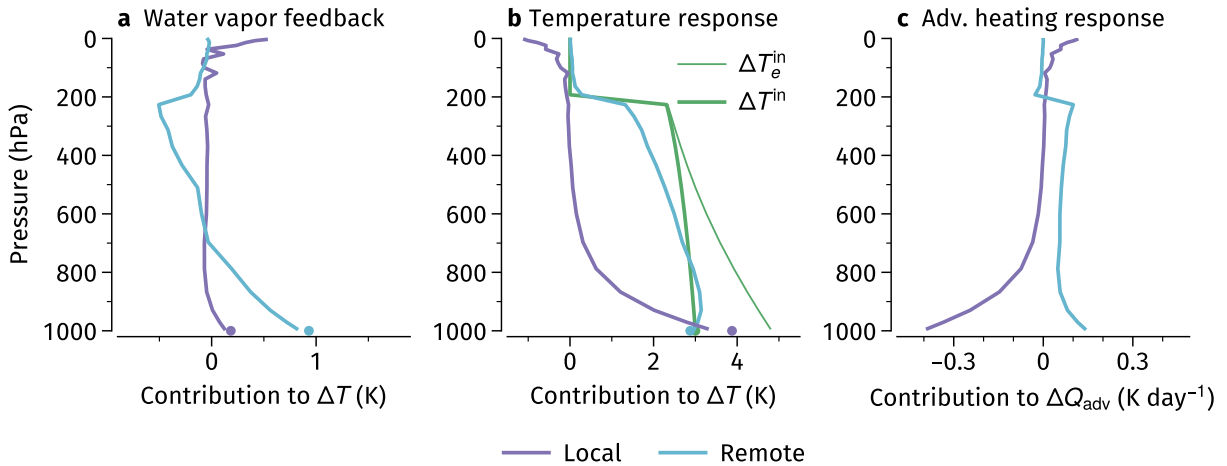
470 FIG. 6. (a) Behavior of the non-dimensional Clausius-Clapeyron factor α (see Eq. 15) as a function of
 471 temperature, assuming RH=80% and a pressure of 1000 hPa. (b) Behavior of the dry and moist advective heating
 472 perturbations in response to changing surface heat source perturbation, plotted as a function of surface warming.

473 5. Local and remote contributions to polar warming

474 Polar warming is driven by a combination of remote and local forcing, both amplified by local
 475 feedbacks (Screen et al. 2012; Stuecker et al. 2018; Park et al. 2018; Henry et al. 2021). Here,
 476 we partition the total warming seen in the all-perturbations simulation \mathcal{P} into remote and local
 477 contributions. Remote forcing in our model is encapsulated in the T_e^{in} perturbation. We take
 478 the remote warming contribution to be the sum of the direct response to this forcing (given by
 479 simulation \mathcal{P}_{in}), and the portion of the water vapor feedback driven by remote warming (Henry
 480 et al. 2021). We quantify this portion by performing an additional simulation identical to \mathcal{P}_{in}
 481 but allowing water vapor to adjust interactively at fixed RH. Local forcing is provided by the
 482 CO_2 and F_s perturbations, both amplified by corresponding portions of the water vapor feedback
 483 (again quantified by additional simulations). The F_s perturbation can be seen as this model's
 484 representation of sea ice feedback, which could be partly driven by remote warming. Nonetheless,
 485 we treat F_s as a purely local effect for consistency with previous work (Henry et al. 2021), while
 486 recognizing that this assumption overestimates the local contribution to total warming.

487 Results are presented in Figure 7. Partitioning of the water vapor feedback shows that it is almost
 488 entirely due to remote warming (Figure 7a), presumably because this warming is deep and promotes
 489 enhanced humidity throughout the column rather than in a near-surface layer. (Consistently with
 490 this argument, we also note that water vapor radiative kernels have small or even negative near-

491 surface values in the Arctic because of the climatological inversion, implying modest changes in
 492 outgoing longwave radiation for increased near-surface specific humidity (Soden et al. 2008; Kim
 493 et al. 2021).) Despite this contribution from water vapor feedback, the surface warming attributed
 494 to remote forcing remains smaller than that attributed to local forcing by about 1 K (Figure 7b). This
 495 differs from the results of regionally-forced climate model simulations, which show almost equal
 496 remote- and locally-driven warmings (Stuecker et al. 2018; Semmler et al. 2020). This difference
 497 is likely due to our attribution of the F_s contribution entirely to local forcing. Nonetheless, our
 498 results confirm that remote forcing plays a key role in driving strong polar amplification: if remote
 499 forcing had no effect on the poles, there would be very weak polar amplification.



500 FIG. 7. Decomposition of the (a) radiative water vapor feedback, (b) total temperature response, and (c)
 501 advective heating rate response into contributions due to local and remote forcings/feedbacks.

502 Remote forcing also drives increased advective heating—and therefore increased diabatic
 503 cooling—throughout the troposphere, while local forcing is responsible for the net drop in ad-
 504 vective heating in the lower troposphere (Figure 7c). This result is consistent with and helps
 505 interpret the findings in Audette et al. (2021), who examine the response of atmospheric energy
 506 transport and moist-isentropic circulation in atmospheric models subject to changing surface con-
 507 ditions. They find that remote sea-surface temperature warming leads to greater energy transport
 508 to the Arctic and greater isentropic mass flux. Both are consistent with the remote response in
 509 Figure 7c—note in fact that the poles constitute the subsiding branch of the isentropic circulation
 510 (Pauluis et al. 2010), and in isentropic coordinates subsidence is equal to the diabatic cooling

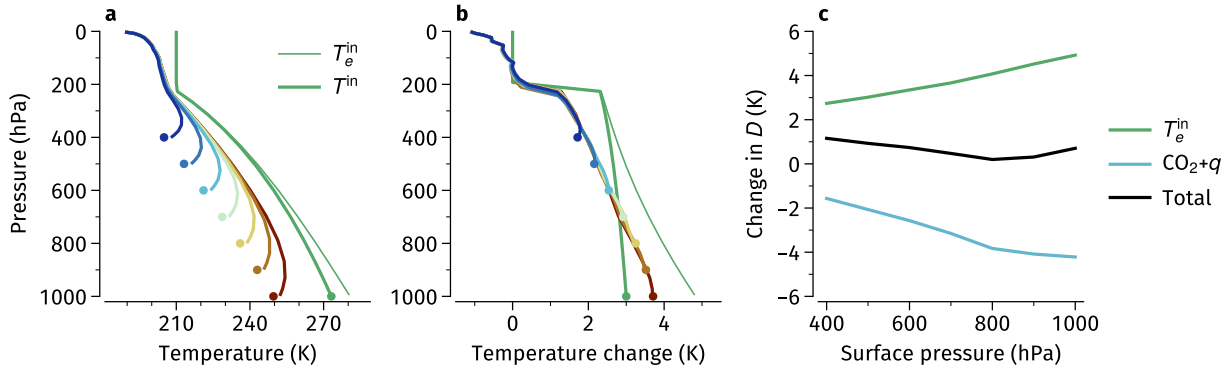
511 rate and related moisture loss by precipitation (it is simply the transformation of air masses from
512 higher to lower entropy or MSE classes). This isentropic picture also forms the basis of a feedback
513 analysis suitable to separating the distinctive upper- vs. lower-tropospheric warming contributions
514 in the Arctic (Feldl et al. 2020). Audette et al. (2021) further show that local polar forcing by
515 reduced sea ice cover drives reduced energy transport and a weakening of the isentropic mass
516 transport in the lower troposphere; both are again consistent with our results for local forcing, for
517 the same physical reasons. Moreover, they attribute this reduction in energy transport to warming
518 of the low-level outflow from the Arctic, consistent with the air-mass transformation perspective
519 discussed in Section 3b. In summary, our single-column model results suggest that changes in
520 poleward energy transport and in isentropic mass flux are just two sides of the same coin.

521 **6. Sensitivity to surface elevation: The Antarctic case**

522 Polar amplification is hemispherically asymmetric, being stronger over the Arctic than over
523 Antarctica. This asymmetry has been attributed in part to Antarctica’s high elevation: climate
524 model simulations in which Antarctica is flattened with no change in surface albedo show substan-
525 tially increased polar amplification (Salzmann 2017; Hahn et al. 2020).

526 This issue provides a useful test case for the single-column model and for the physical picture
527 developed in Sections 3 and 4. We perform a series of simulations identical to \mathcal{B} but with varying
528 surface pressure. The T_e^{in} profile prescribed in these simulations is identical to the portion of the
529 T_e^{in} profile of \mathcal{B} that is above the surface. The resulting series of base-state temperature profiles is
530 shown in Figure 8a. In agreement with Hahn et al. (2020), the surface inversion becomes stronger
531 but shallower as the surface pressure decreases.

536 We then perform a corresponding series of perturbed simulations which are identical to \mathcal{P} with
537 one exception: the surface heat source perturbation $\Delta F_s = 0$ in all cases, to mimic no change
538 in surface albedo. Profiles of temperature change from corresponding base states are shown in
539 Figure 8b. The lapse rate increases roughly uniformly throughout the column in these simulations,
540 without the lower-tropospheric enhancement seen in \mathcal{P} (Figure 4e). The reason is that without an
541 F_s perturbation, the reduction in atmosphere-surface disequilibrium D due to greenhouse gases
542 roughly cancels out the increase due to T_e^{in} (Figure 8c). There is therefore little change in radiator
543 fin strength, implying that near-surface lapse-rate changes in these simulations are not primarily



532 FIG. 8. (a) Base-state temperatures and (b) temperature response to perturbed T_e^{in} and CO_2 for simulations with
 533 varying surface pressure. Dots show surface temperature, plotted at the corresponding value of surface pressure.
 534 (c) Change in atmosphere-surface disequilibrium D from the base to the perturbed simulations as a function of
 535 surface pressure (black line), and its partitioning into contributions from increased T_e^{in} and in greenhouse gases.

544 due to the boundary-layer processes that control the surface inversion strength. Instead, lapse-rate
 545 changes are driven by relaxation towards the bottom-amplified T_e^{in} perturbation—note that the T
 546 perturbation profile is roughly parallel to that of T_e^{in} in Figure 8b—and by upper-tropospheric
 547 cooling by water vapor as discussed in Section 4a.

548 In summary, these results show that the model’s surface temperature response decreases with
 549 increasing surface elevation, in agreement with the climate model results of Salzmann (2017) and
 550 Hahn et al. (2020). Our physical interpretation is different from theirs, however, and points to the
 551 importance of lower-tropospheric latent heat release in yielding a bottom-amplified temperature
 552 response which enhances polar amplification.

553 7. Comparison with other forcing-feedback decompositions

554 Here we compare the forcing-feedback decomposition provided by our relaxation approach with
 555 alternative decompositions provided by the fixed-heating RAE approach (Henry et al. 2021) and
 556 by the conventional TOA decomposition. For the fixed-heating approach, we perform simulations
 557 with the same parameter settings specified in Section 2c, but prescribing a fixed advective heating
 558 rate diagnosed from simulations \mathcal{B} and \mathcal{P} . For the TOA decomposition, we use the partial radiative
 559 perturbation method (Colman et al. 2001): using the radiative transfer code offline, we compute the
 560 TOA radiative perturbation caused by replacing temperature, humidity and CO_2 values in \mathcal{B} with

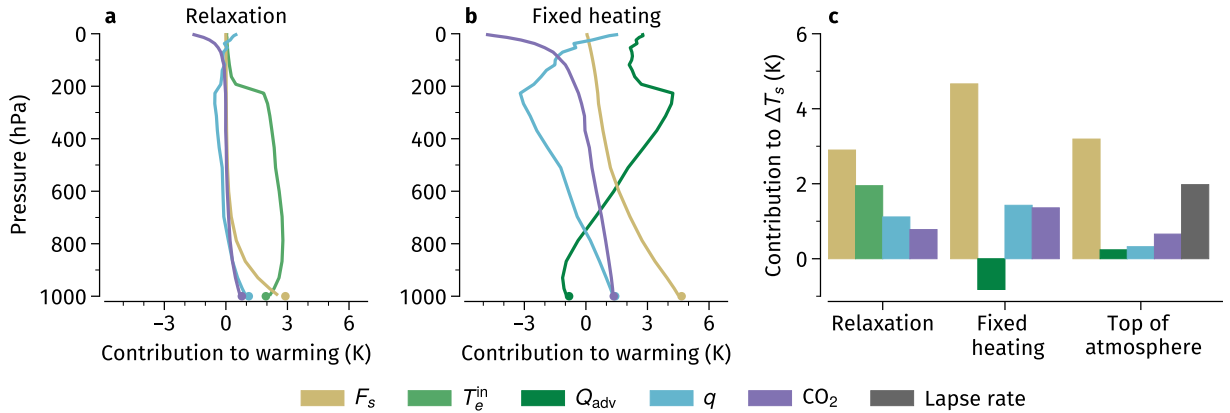
561 those from \mathcal{P} one at a time; we then divide by the Planck feedback to obtain as surface temperature
562 change contribution from each feedback. Contributions from changes in surface heat source and
563 atmospheric heat transport are computed by dividing ΔF_s and vertically-integrated ΔQ_{adv} by the
564 Planck feedback.

565 Results are presented in Figure 9. Temperature responses to F_s , CO_2 and q in the fixed-heating
566 approach are qualitatively similar to those in the relaxation approach, but with much greater
567 amplitude: since advective heating is not allowed to adjust, changes in diabatic cooling must
568 be entirely compensated by large temperature changes. Note in particular that the response to
569 F_s is positive all the way into the stratosphere in the fixed-heating approach. Moreover, the
570 negative lower-tropospheric lobe of ΔQ_{adv} (shown in Figure 4j) yields a large negative temperature
571 perturbation even at the surface, although vertically-integrated atmospheric heat transport actually
572 increases. These responses appear more difficult to interpret physically than in the relaxation
573 approach.

574 The TOA decomposition (Figure 9c) shows the largest contribution to surface temperature change
575 is from F_s , followed by lapse-rate feedback, while other terms play a smaller role; in particular,
576 atmospheric transport gives a small positive contribution. This is qualitatively consistent with
577 the relative roles of Arctic surface albedo, lapse-rate and atmospheric transport feedbacks in
578 diagnosed in climate models (Pithan and Mauritsen 2014; Hahn et al. 2021). ΔF_s is also the
579 largest contributor in the relaxation and fixed-heating approaches, though it is much larger in the
580 fixed-heating approach to compensate for the negative contribution from advective heating (recall
581 from Section 4b that ΔF_s drives the largest reduction in Q_{adv}). The two RAE approaches do
582 not have an explicit lapse-rate feedback contribution since it is implicitly partitioned among the
583 other contributions, making the CO_2 and q contributions larger than in the TOA approach. In
584 addition, the relaxation approach has no separate atmospheric transport feedback; instead it has
585 a substantial contribution from ΔT_e^{in} , which we consider a forcing, while changes in atmospheric
586 energy convergence are partitioned among all four contributions.

590 8. Summary and conclusions

591 We have developed a single-column model for clear-sky RAE in which heating by lateral energy
592 advection is represented as a relaxation toward a fixed midlatitude profile of temperature and



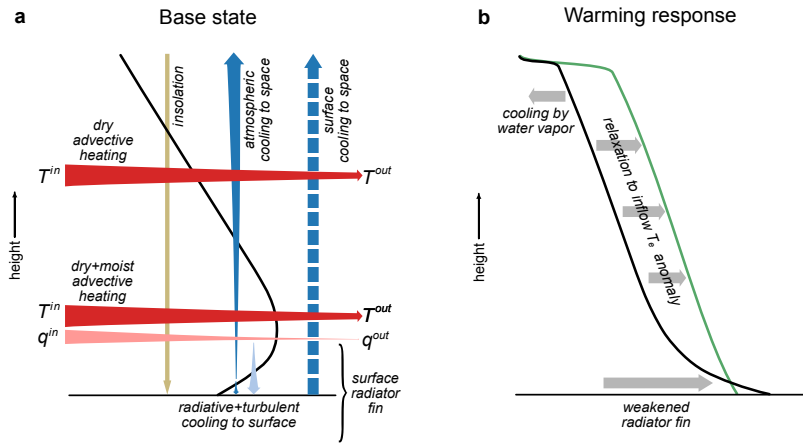
587 FIG. 9. Temperature responses to individual perturbations in the (a) relaxation and (b) fixed-heating approaches,
 588 and (c) contributions to surface temperature change according to the three decompositions. Dots in (a,b) show
 589 surface temperature change.

593 humidity, encapsulated in the equivalent temperature profile T_e^{in} . Despite its simplicity, the model
 594 is able to adequately reproduced observed Arctic temperature and energy convergence profiles.
 595 Analysis of the model’s steady-state energy balance, schematized in Figure 10a, and its response
 596 to a global-warming-like perturbation (Figure 10b), allows us to provide some answers to the key
 597 questions posed in the Introduction:

- 607 1. *Why is there a climatological surface-based inversion, and what mechanisms control the polar*
 608 *lapse-rate response to global warming?*

609 The essential reason for the existence of a climatological surface temperature inversion is the
 610 thermodynamic imbalance between the relatively warm air flowing into the polar cap and
 611 the cold surface temperature that results from strong surface cooling to space through the
 612 water-vapor window. As a result, the lower troposphere cools strongly to the surface; this
 613 cooling can be mediated by radiative or turbulent fluxes interchangeably, but necessitates a
 614 surface temperature inversion in either case. We refer to this surface cooling mechanisms as
 615 the surface radiator fin.

616 Changing inversion strength in response to global-warming-like perturbations can be readily
 617 predicted by thinking about their effects on the surface radiator fin. All else equal, a warming of
 618 incoming air will increase thermodynamic imbalance and strengthen the radiator fin, leading



598 FIG. 10. Schematics summarizing (a) the energy balances involved in the maintenance of the base state, and
 599 (b) the mechanisms controlling polar lapse rate response to a global warming perturbation. In (a), the black
 600 line indicates the climatological temperature and tapered arrows indicate convergent or divergent energy flows,
 601 emphasizing the difference between the surface inversion layer—where atmospheric cooling is mediated by
 602 energy transfer to the surface and subsequent radiative loss to space (the surface radiator fin)—and in the free
 603 atmosphere, where cooling occurs by direct atmospheric emission to space. In (b), the green line shows the
 604 imposed T_e^{in} anomaly (which is inherently bottom-heavy due to increased latent heat content near the surface),
 605 the black line shows the polar temperature response, and gray arrows indicate warming or cooling tendencies
 606 due to different mechanisms as in noted in the figure.

619 to a stronger inversion. Vice-versa, warming the surface through decreased albedo or blocking
 620 the water-vapor window by increased greenhouse gas concentration will weaken the inversion.
 621 As indicated in Figure 10b, these changes to the lower-tropospheric temperature structure are
 622 superposed on an overall increase in lapse rate throughout the column due to relaxation toward
 623 an equivalent temperature perturbation ΔT_e^{in} that is intrinsically bottom-heavy. Furthermore,
 624 increasing humidity results in increased upper-level radiative cooling, which tends to further
 625 increase the overall lapse rate.

626 2. *Why do changes in moist and dry energy transport to the poles tend to mutually compensate,*
 627 *and what constraints act to enforce this compensation?*

628 Given typical temperatures in Earth’s modern climate, warming the low-level inflow to the
 629 polar caps causes comparable changes in dry and latent energy content of the inflowing air

630 masses, while a similar perturbation to outflow temperature causes a much smaller change in
631 latent energy content. This means that essentially all additional moisture entering the polar cap
632 in a warmed climate will condense and release its latent heat—moist energy convergence can
633 increase, but not decrease in response to warming. On the other hand, the strong reduction of
634 radiator fin strength in response to warming (see point 1 above) requires an overall reduction in
635 energy convergence at low levels, which can only be accomplished by a warming of the outflow
636 and reduced dry energy convergence. Compensation between dry and moist energy transport
637 is therefore a robust, thermodynamically-constrained response at low levels. At upper levels,
638 both inflow and outflow temperatures are low enough that moisture plays a negligible role.
639 Increased upper-level radiative cooling in response to warming is thus balanced by increased
640 dry energy convergence. Overall, the precise degree of compensation between vertically-
641 integrated moist and dry transport depends delicately on radiative responses at different levels
642 and is not robust.

643 3. *What is the best way to decompose forcing and feedbacks at the poles?*

644 In agreement with previous work on RAE, our analysis suggests that lapse-rate feedback at
645 the poles does not constitute a well-defined standalone mechanism: different forcing and
646 feedback agents affect the lapse rate differently and through disparate mechanisms. More
647 fundamentally, in RAE there is no strong relationship between surface temperature and TOA
648 radiative fluxes, since much of the outgoing longwave radiation originates in the mid- to upper
649 troposphere which is decoupled from the surface. It makes more sense therefore to think only
650 in terms of a temperature response which includes a lapse-rate response whose structure is
651 controlled by the mechanisms explore above.

652 We go a step further, and argue that remote influence—represented here by the inflow equiv-
653 alent temperature profile T_e^{in} —should be considered an external forcing, since it affects polar
654 climate but is not affected by it to a first approximation (i.e., remote influence is felt as a
655 change in boundary conditions). Part of the temperature response to both local and remote
656 forcing is an adjustment to bring changes in diabatic cooling into equilibrium with changes
657 in advective heating. Just as in the case of the lapse-rate feedback, these adjustments are
658 different for different forcing agents, so again it does not make sense to think of a single,

659 standalone advective heating feedback, but rather of a temperature response which includes
660 the advective heating adjustment.

661 In conclusion, we believe that the single-column model explored here—and the concepts and
662 mechanisms elucidated by this exploration—provides a useful basic framework for thinking about
663 the polar climate. It is certainly an incomplete framework as it stands. It lacks a description
664 of cloud effects—in particular, high-opacity low-level clouds can be expected to substantially
665 affect the functioning of the surface radiator fin and could strongly affect the surface temperature
666 response (Cronin and Tziperman 2015; Dimitrelos et al. 2023), though much uncertainty still
667 surrounds the overall impact of clouds on polar climate (Kay et al. 2016). Our model also assumes
668 a homogeneous surface, lacking a description of partial sea-ice cover and an explicit surface-albedo
669 feedback. Understanding whether these additional effects lead to qualitatively different behavior,
670 or rather just a quantitative modification of the basic clear-sky picture developed here, provides an
671 interesting avenue for future work. In addition, our work provides a novel feedback decomposition
672 which can in principle be straightforwardly applied to analyse full climate model responses, using
673 only readily-available temperature and humidity profiles as input. Further exploration of this
674 possibility provides a further avenue for future work.

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676 *Data availability statement.* The CliMT modelling framework is available at
677 <https://github.com/CliMT/climt>. The ERA-Interim reanalysis product may be obtained
678 as detailed here: <https://confluence.ecmwf.int/display/CKB/How+to+download+ERA-Interim+data+from+the+ECMWF+data+archive>.
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