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Fast relocking and afterslip-seismicity evolution following the 2015 Mw 8.3 Illapel earthquake in Chile

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ABSTRACT

Large subduction earthquakes induce complex postseismic deformation, primarily driven by afterslip and viscoelastic relaxation, in addition to interplate relocking processes. However, these signals are intricately intertwined, posing challenges in determining the timing and nature of relocking. Here, we use six years of continuous GNSS measurements (2015-2021) to study the spatio-temporal evolution of afterslip, seismicity and locking after the 2015 Illapel earthquake (M_w 8.3). Afterslip is inverted from postseismic displacements corrected for nonlinear viscoelastic relaxation modeled using a power-law rheology, and the distribution of locking is obtained from the linear trend of GNSS stations. Our results show that afterslip is mainly concentrated in two zones surrounding the region of largest coseismic slip. The accumulated afterslip (M_w 7.8) exceeds 1.5 m, with aftershocks mainly occurring at the boundaries of the afterslip patches. Our results reveal that the region experiencing the largest coseismic slip undergoes rapid relocking, exhibiting the behavior of a persistent velocity weakening asperity, with no observed aftershocks or afterslip within this region during the observed period. The rapid relocking of this asperity may explain the almost regular recurrence time of earthquakes in this region, as similar events occurred in 1880 and 1943.

Introduction

Knowledge of the spatio-temporal evolution of kinematic processes at the subduction interface is essential for enhancing our understanding of the mechanisms underlying stress accumulation and release throughout the seismic cycle of major earthquakes. We know that during the interseismic period, the plate interface is heterogeneously locked¹⁻³, with certain segments fully locked and others undergoing aseismic slip, resulting in variable strain accumulation along strike and at different depths. These variations in the degree of locking appear to influence the characteristics of future earthquakes, as evidenced by a correlation between areas of observed coseismic slip and patchworks of geodetically-determined interseismically locked zones in the most significant earthquakes of the past nearly two decades¹⁻⁴. Therefore, the degree of locking when combined with historical earthquake data is a valuable tool for estimating the slip deficit, providing crucial information about the potential location and magnitude of future earthquakes. However, our knowledge of the temporal variations in locking is limited by the absence of long-term geodetic records that cover the entire seismic cycle, which can span from tens of years to centuries. This limitation hampers our ability to accurately assess slip deficits in subduction zones.

After large earthquakes, surface displacement occurs in the opposite direction compared to the interseismic period, exhibiting a gradual decay in the rate of displacement over time. These observations were first documented in Japan during the mid-20th century^{5,6}. Later, with the advent of space geodesy, these effects have been extensively documented⁷⁻¹¹. The postseismic processes are time-dependent, and their magnitude and relaxation time are controlled by the magnitude of the earthquake and the rheology of the fault- and lithosphere-asthenosphere-system^{7,11,12}. In addition, postseismic deformation processes

37 are influenced by the stress state of the surrounding volume and the evolution of stresses on the fault^{13,14}. Rapidly decaying
38 postseismic deformation (lasting days or years) in the near-field of the rupture can result from fault afterslip caused by the
39 frictional response of the subduction interface^{8,15}. Larger-scale processes with short- and long-term effects on the deformation
40 field (lasting from days to tens of years) include viscoelastic relaxation of the upper continental and oceanic mantle^{9,10,16},
41 which stresses the upper plate and results in trenchward displacement over a wide inland region¹⁷. Other processes that can
42 trigger postseismic deformation include crustal faulting in the upper plate¹⁸, and poroelastic deformation caused by fluid flow
43 in response to coseismic changes within the pore space¹⁹. Previous work^{20,21} has shown how difficult it is to distinguish these
44 processes in geodetic observations because they often act simultaneously.

45 When broken by a large earthquake, certain sections of the fault undergo frictional restrengthening (healing), resulting in
46 relocking processes, while other sections continue to experience a combination of seismic (aftershocks) and aseismic (afterslip)
47 slip. This complex behavior poses challenges in accurately identifying the exact moment of relocking, leading to ongoing
48 debates regarding the rate of fault healing and the timing of relocking. Some laboratory experiments and geodetic modeling
49 suggest that the plate interface can rapidly recover its interseismic locking state after a large slip, with recovery times ranging
50 from instantaneous to a period of one year^{21–23}. In contrast, experimental data from samples taken from the Hikurangi margin,
51 which experiences continuous slow earthquakes, indicate near-zero healing rates²⁴. Consequently, there is no widespread
52 agreement on the timing and controlling factors of healing, primarily due to the limited number of observations documenting
53 the relocking process and the challenges involved in extrapolating from experimental data. Additionally, the challenge of
54 estimating post-earthquake slip hampers our understanding of the relationship between aftershocks and afterslip. While it has
55 been proposed that aftershocks are triggered by stress perturbations resulting from afterslip²⁵, the considerable uncertainty in
56 afterslip models²⁶ leaves the connection between aftershocks and afterslip unclear. Obtaining new evidence on the timing of
57 the transition from rapid coseismic to slower afterslip and relocking is crucial for assessing the interaction between different
58 slip modes and their contribution to the overall slip budget in the seismic cycle.

59 In this study, we present evidence that the rupture zone of the 2015 Illapel earthquake, with a moment magnitude (M_w) of
60 8.3 in Chile, has been fully relocked since at least the third year after the event. We analyze and model data from 51 continuous
61 Global Navigation Satellite System (GNSS) stations (Fig. 1, S1, S2) spanning the first six years (2015–2021) after the September
62 16, 2015, Illapel earthquake to characterize postseismic deformation, its relationship to seismicity, and the degree of current
63 plate locking around the rupture zone. The Illapel region in north-central Chile is located at the plate boundary system of the
64 Nazca and South American plates (Fig. 1). This region is characterized by intense seismic activity, which has increased over the
65 last 20 years. The coseismic source of the 2015 Illapel earthquake has been extensively studied^{27–32}. This earthquake ruptured
66 an area of $\sim 200 \times 100$ km, ~ 300 km north of the 2010 Maule earthquake², and caused total slip peaks of 6–9 m^{27,31,32} (Fig. 1).
67 Earlier earthquakes similar to 2015 occurred in 1943 and 1880³³, suggesting some regularity in the accumulation and release of
68 seismic energy in this segment.

69 Previous studies have estimated the early postseismic deformation of the Illapel earthquake, considering short time windows
70 of 1 and 11 days³¹, 26 days³⁴, 43 days²⁹, 45 days^{35–37}, 60 days³⁸, 74 days³⁹, and 10 months⁴⁰. These studies mainly investigated
71 afterslip processes; only Guo et al. (2019)³⁵ included linear viscoelastic relaxation and afterslip models, while Yang et al.
72 (2022)³⁷ also considered poroelastic effects on afterslip distributions. Most of these studies agree on two main afterslip patches
73 located along the northern and southern edges of the coseismic rupture (Fig. 1), separated by the deepest part of the coseismic
74 rupture. Higher afterslip is generally observed in the northern patch, and afterslip during the first months after the earthquake is
75 equivalent to 12% to 13% of the coseismic moment²⁹. Frank et al. (2017)⁴⁰ suggest that the afterslip following the mainshock
76 rupture is the main driver of aftershocks. The purpose of this study is to take a step forward by investigating the spatio-temporal
77 slip behavior of the megathrust using continuous GNSS data, implementing a 4D forward numerical model, and applying the
78 least squares inversion with Equal Posterior Information Condition (EPIC) Tikhonov regularization⁴¹ to robustly resolve the
79 afterslip and locking degree. Finally, we updated the seismicity catalog of north-central Chile of Sippl et al. (2021)⁴² to cover
80 our entire observation period and compared it with the spatio-temporal evolution of afterslip and plate locking.

81 Results

82 Spatio-temporal evolution of the surface displacement field and seismicity

83 The curvature in the spatial path of ground motions in the years following a large earthquake such as Illapel 2015 (e.g., $M_w \sim$
84 8) (Fig. 1a) is a combination of transient postseismic processes and plate relocking signal. Initially, postseismic deformation
85 (including relaxation, relocking and locking in adjacent zones) dominates, but it decays rapidly in the nearshore areas where
86 the coupling signal begins to prevail, as observed in the interseismic rotation of the displacement vectors (Fig. 2). All stations
87 near the rupture zone show a rapid westward movement immediately after the Illapel earthquake (up to 18 cm in the first year),
88 which then gradually slows down in the following years, producing a clockwise rotation of the horizontal displacements until
89 they reach the interseismic direction. The segments north and south of the Illapel rupture zone are mainly affected by a short

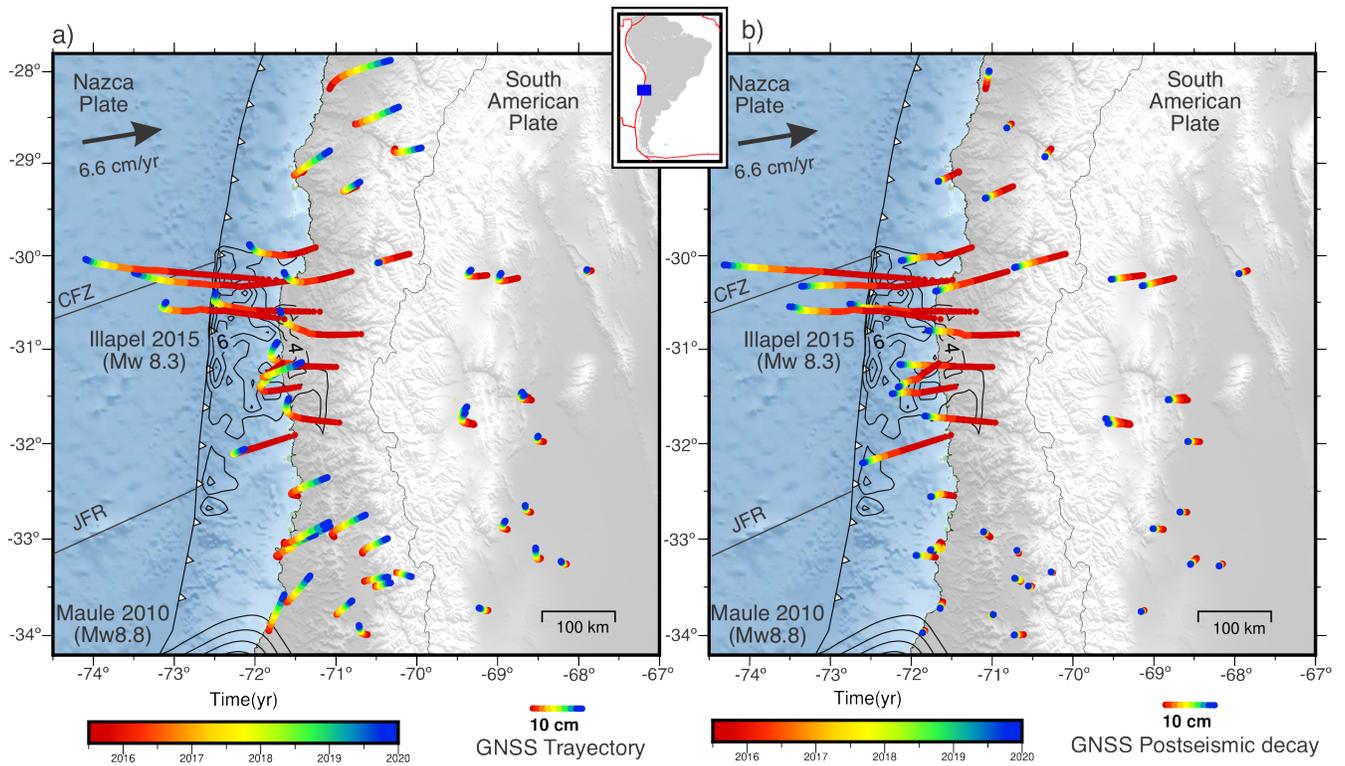


Figure 1. Map of the study area showing time colored cumulative postseismic ground displacements recorded by continuous GNSS stations during four years after the 2015 Illapel earthquake. Black contours show the coseismic slip model of the Illapel³² and Maule⁴³ earthquakes, with contour intervals of 2 m. a) Evolution of the horizontal trajectory at each station, considering the postseismic decay and the linear trend. b) Trajectory of postseismic deformation alone. JFR is the Juan Fernandez Ridge, and CFZ is the Challenger Fracture Zone.

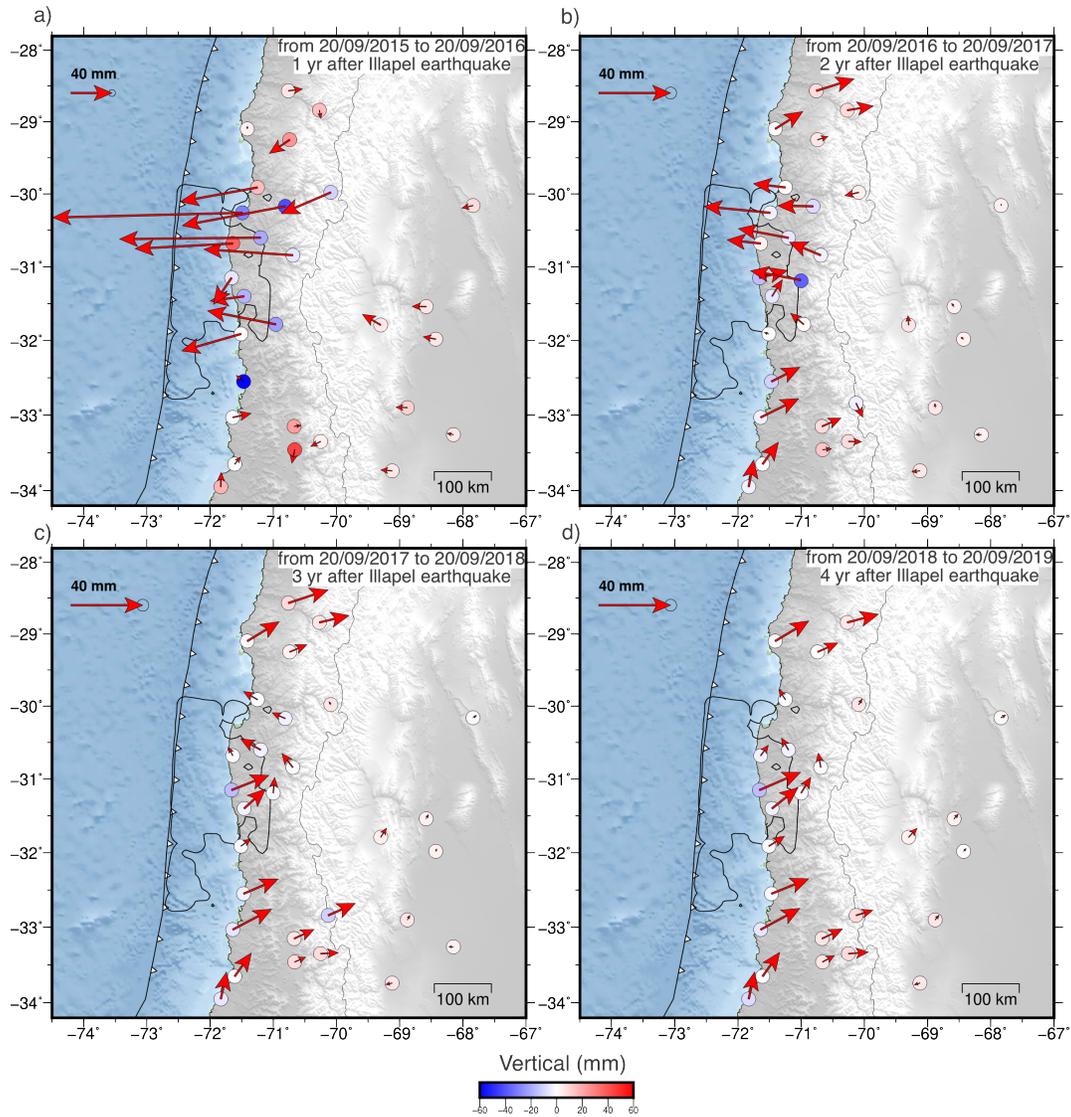


Figure 2. Annual cumulative horizontal and vertical displacements at GNSS stations between 20.09.2015 and 20.09.2019. They are the predictions of the linear trend and postseismic decay of the stations for years one to four after the earthquake (a-d). Black contour shows the area where coseismic slip is greater than 1 m³². Colored circles show vertical displacements. Note the different scale of the horizontal vectors in panel (a). We observe the evolution of the ground displacements and the change in their direction from a trenchward motion to a landward movement, the latter being the general behavior four years after the earthquake (d).

90 postseismic deformation, which quickly transitions after one year to an interseismic phase with movement in the direction of
91 plate convergence.

92 During the first year, the GNSS stations show significant subsidence (~ 6 cm) above the rupture downdip limit, and localized
93 uplift of about 4.6 cm at the coast. Gentle uplift is also observed in the Andean mountain range and backarc, forming a
94 long-wavelength lithospheric flexure pattern that decreases with time (Fig. 2). In the second year after the earthquake, GNSS
95 stations on the coast near the center of the rupture zone reverse the direction of their horizontal motion toward the interseismic
96 direction (northeast). This change indicates the beginning of the predominance of relocking over the postseismic signal in the
97 near field. Three and four years after the earthquake, the ground surface continues to move interseismically in the central part
98 of the rupture zone ($31^{\circ}\text{S} - 31.5^{\circ}\text{S}$), but is surrounded by areas with smaller displacement (Fig. 2c, d). Over four years after the
99 earthquake, the largest cumulative displacements toward the trench reach ~ 30 cm (Fig. 1a). In this period, the post-earthquake
100 deformation field is mainly concentrated in the Chilean forearc, between $\sim 29.8^{\circ}\text{S} - 32.2^{\circ}\text{S}$, around the rupture zone, without
101 significantly affecting the backarc.

102 We isolate the logarithmic decay components from the trajectory models, which represent postseismic deformation processes
103 (mainly afterslip and viscoelastic relaxation) until the end of 2019 at each station (Fig. 1b, Fig. 3). The postseismic ground
104 motion is rapid the first year after the earthquake, reaching more than 20 cm. Then, it becomes noticeably slower over the rest
105 of the observed period, reaching a cumulative maximum of ~ 27 cm (Fig. 3 and Fig. S3). To model the postseismic deformation
106 mechanisms, we divided the observation time into four time windows, T1-4, with durations of 11, 56, 294, and 1546 days to
107 obtain similar amplitude displacements and thus maintain the signal-to-noise ratio (Fig. 3). The separation of the postseismic
108 signal at each GNSS station into time windows with displacements of similar amplitude, allows quantifying the change in
109 the global deformation pattern over time, i.e., the relative behavior between the near and far-field. Thus, we can characterize
110 postseismic deformation patterns caused by postseismic relaxation of the mantle that affects mostly the far-field and by afterslip,
111 whose signal is concentrated near the rupture. To calculate the duration of the time windows T1-T4, we used only GNSS
112 time series covering the full observation period, including the first few days after the earthquake, when the most significant
113 displacements were recorded. Once these windows were set, we calculated the postseismic ground displacements of the GNSS
114 data, selecting only the stations with more than 95% of the data in that window.

115 The stations near the coast around the rupture zone have the largest horizontal postseismic displacements (cumulative
116 displacements greater than ~ 7 cm in each window). Stations in the backarc region show small but resolvable horizontal
117 displacements (~ 1 cm cumulative in T1, T2, and T3). Only in T4 (which spans a much longer time than the other windows)
118 the cumulative displacements in the backarc exceed ~ 3 cm, indicating that the decay time is longer in the far field than near
119 the rupture zone. The horizontal displacements change direction at the center of the rupture zone, a pattern that suggests the
120 development of two afterslip patches. The stations show continuous subsidence near the coast (> 2.5 cm accumulated in each
121 time window) and localized uplift inland of the maximum coseismic slip (~ 1 cm accumulated per time window).

122 The seismicity catalog, which covers the time interval from April 2014 to December 2021, shows that seismic activity
123 surrounds the rupture zone of the 2015 earthquake. There is an increased occurrence of seismic events directly below the
124 rupture area, as well as at shallower depths to the north and south (Fig. 4). Conversely, the area that experienced rupture during
125 the main shock displays notably lower seismic activity. Exponential decay of the aftershock rate occurs until ~ 50 days after the
126 Illapel earthquake, followed by a relatively constant rate of background seismicity. We do not observe clear changes in the
127 spatial distribution of seismicity between the early aftershock sequence and the later parts of the earthquake catalog, which can
128 be considered background activity.

129 **Afterslip and locking degree distributions**

130 To estimate the afterslip, we utilize geometric windows, which are time intervals where the accumulated postseismic surface
131 displacements exhibit equal amplitudes. We estimate the afterslip distribution at the plate interface using a combination of a 3D
132 geomechanical model and an inversion approach, similar to the method presented by Peña et al. (2020)⁴⁴. Accordingly, within
133 each individual geometric time window, we subtract the predicted postseismic decay based on a nonlinear viscoelastic relaxation
134 model⁴⁴ (Fig. S4, S5) from the measured displacements. By applying this correction within each geometric time window, we
135 derive the distributions of afterslip. We performed afterslip inversions constrained by postseismic decay displacements, as well
136 as those corrected by the effects of mantle viscoelastic relaxation (Fig. S6). To determine our preferred afterslip models, we
137 use the L-curve method⁴⁵ (Fig. S7). All afterslip inversions fit well to the accumulated displacements of each time window
138 (Fig. S8, S9).

139 The viscoelastic model based on the coseismic slip of Tilmann et al. (2016)²⁷ does not result in significant displacements
140 (< 2 cm) in the backarc region (Fig. S5). As a result, both the uncorrected displacements and those corrected using the Tilmann
141 et al. (2016)²⁷ slip-based model exhibit large displacements in the backarc, which, in turn, lead to afterslip at greater depths (Fig.
142 S5, Fig. S8). In contrast, the viscoelastic model based on the slip from Carrasco et al. (2019)³² predicts backarc displacements
143 that are of similar magnitudes as the GNSS observations, exceeding 3 cm. By correcting the observations using the predictions

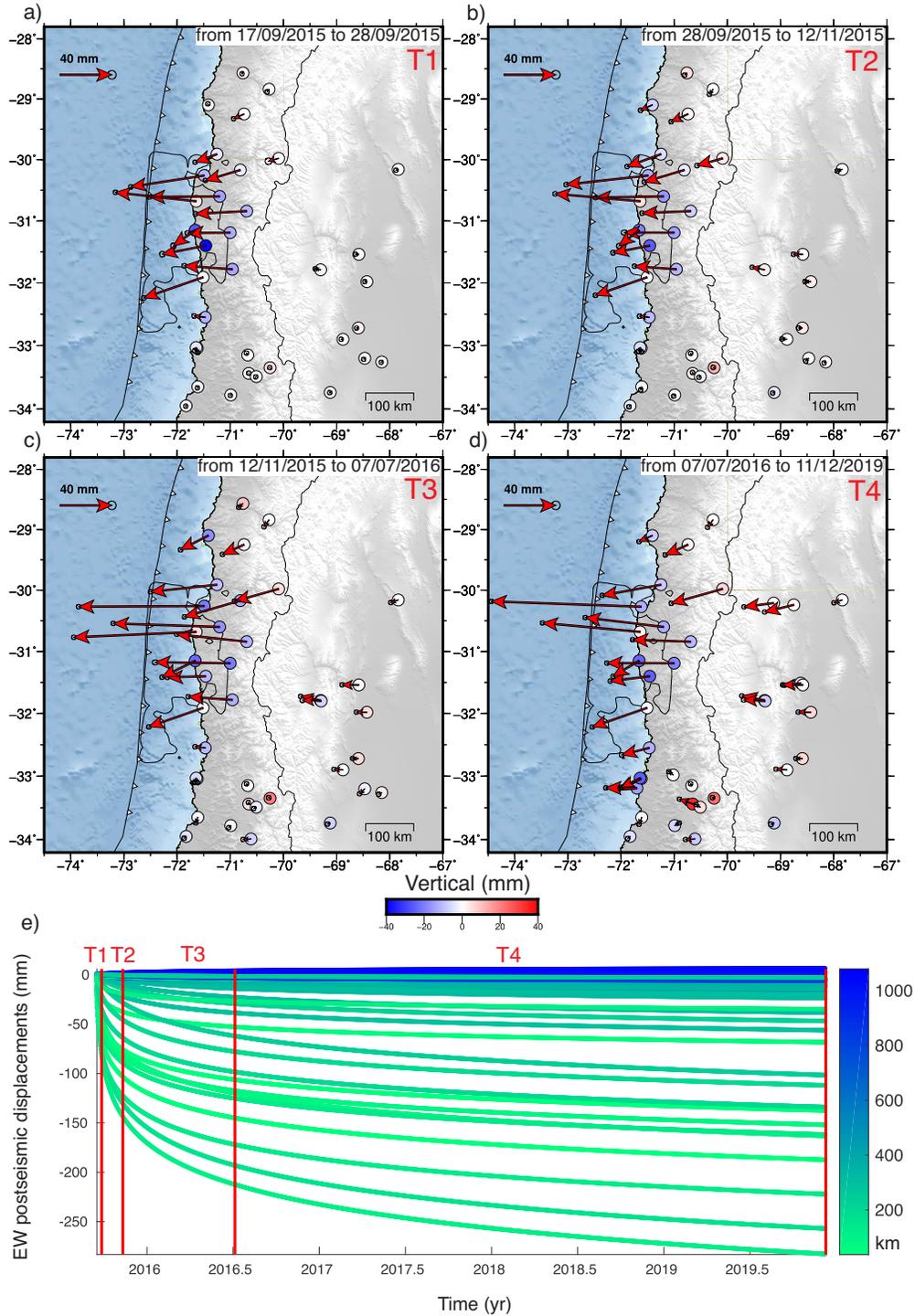


Figure 3. Cumulative postseismic displacements in the "equal-amplitude" (geometric) time windows T1 (a), T2 (b), T3 (c), and T4 (d), with duration of 11, 56, 294, and 1546 days, respectively. Horizontal and vertical displacements are shown as arrows and colored circles, respectively. Black contour shows the area where coseismic slip is greater than 1 m³². e) The cumulative postseismic horizontal (eastward) displacements of the GNSS station network as a function of time. The red lines indicate the temporal boundaries of the four geometric windows defining the analyzed periods of postseismic deformation. The lines are color-coded based on the distance of the stations from the epicenter of the 2015 earthquake. The displacements have similar amplitude ranges at all temporal windows.

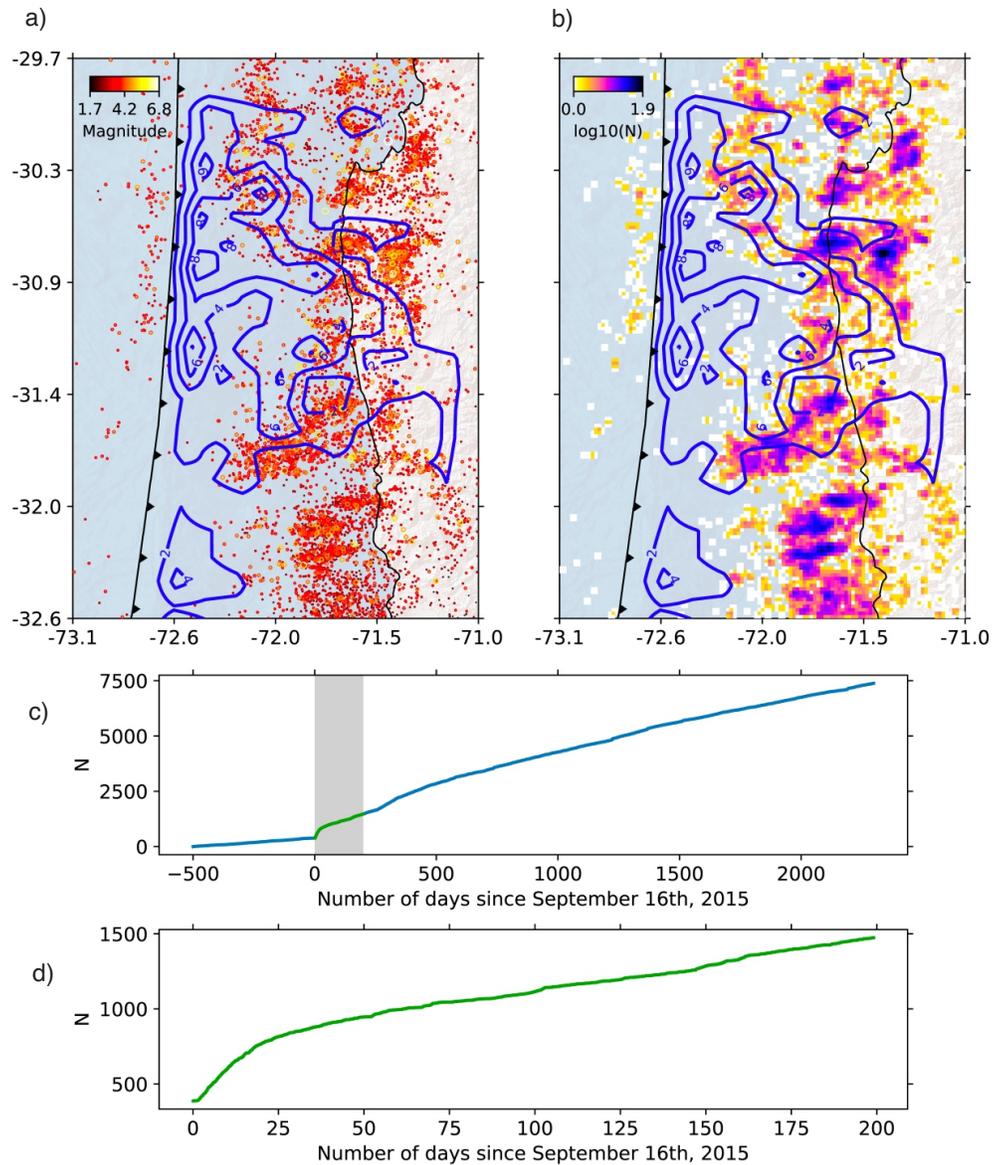


Figure 4. Catalog of microseismicity from April 2014 to December 2021. a) Map view plot of epicenters; circle sizes are scaled and colored by magnitude. b) Plot of seismicity density. In a) and b), the contours of coseismic slip³² are shown at intervals of two meters. c-d) Cumulative events in the region of the map view for the entire time interval covered by the catalog (c) and for 125 days after the Illapel earthquake (d).

144 of this viscoelastic model, we obtain afterslip distributions concentrated in the surroundings of the mainshock rupture (Fig. 5),
145 resulting in a better fit to the data in the far field. Therefore, we focus our analysis on the latter model.

146 The afterslip distributions in the T1, T2, and T3 time windows show similar first-order features in the inversions of the data
147 corrected for the predicted viscoelastic relaxation motions and in the uncorrected data. In these windows, afterslip consists of
148 two separate segments, one in the north of the rupture zone (with higher magnitude) and one in the south, both at similar depths.
149 In time windows T3 and T4, models of the uncorrected data increase the afterslip predictions at depths greater than 60 km,
150 which may be an artifact due to the absence of the viscoelastic component in the modeling. This is consistent with the increase
151 in displacements predicted by the viscoelastic models in the backarc during periods T3 and T4. The afterslip of period T4
152 becomes patchy (Fig. 5d), with the main afterslip lobes splitting apart, consistent with a large diminishing of afterslip rate in
153 that period.

154 Results from our preferred model (Fig. 5) show distributions of cumulative afterslip corresponding to moment magnitudes
155 (M_w) of 7.3, 7.3, 7.4, and 7.5 for time windows T1 (11 days), T2 (56 days), T3 (294 days), and T4 (1546 days), respectively.
156 The daily average of afterslip moment release for T1, T2, T3, and T4 are M_w 6.7, 6.2, 5.8, and 5.3, respectively. The northern
157 zone patch has a maximum dislocation of 0.52 m at T1, 0.38 m at T2, 0.52 m, and 0.65 m at T4. The northern patch has a
158 cumulative amplitude of 1.74 m and the afterslip has a magnitude M_w 7.8 in the observed period. In the T1 time window,
159 seismicity is mainly concentrated around the southern afterslip area. In T2 and T3, seismicity begins to surround the high
160 afterslip zones where seismicity is absent. In T4, a larger number of events, like the afterslip, show a more patchy distribution,
161 also accompanied with an increase in complexity of seismicity patterns that surround areas of high afterslip.

162 To obtain the velocities used in the locking calculation, we analyze the time series from 2018-2020 due to the presence
163 of post-seismic effects, data gaps, and artificial offsets prior to that period, which may introduce uncertainties in the velocity
164 measurements. The locking degree is then estimated using a method similar to Li et al. (2015)⁴⁶, with the exception that we
165 employ the same inversion method implemented for the afterslip distributions. Our best-fitting locking model reproduces the
166 horizontal and vertical velocities between 2018 and 2021 quite well (Fig. 6, Fig. S10). Our analysis suggests that the rupture
167 zone of the Illapel earthquake is highly locked between 2018 and 2020, with creeping zones located to the north and south of
168 the rupture area. North of the rupture zone, there is an approximately 50 km long corridor of creep, which gradually increases
169 its degree of locking north of 29°S, where the interface is highly locked offshore. South of 32°S, the model infers high locking
170 in the deeper part of the seismogenic zone and creeping near the trench, an area that may not be well resolved by the inversion.
171 Seismicity surrounds the highly locked zone and is concentrated in the creeping corridor.

172 We performed a clustering analysis using the agglomerative clustering algorithm implemented in sklearn-scikit⁴⁷ to
173 investigate the spatial relationship between the distributions of coseismic slip, afterslip, locking, and seismic moment estimate
174 to evaluate the kinematic behavior of the megathrust (Fig. 7). We chose an optimal number of four clusters (Fig. S11), which gives
175 a local minimum Bayesian Information Criterion (BIC). A larger number of clusters reduces the BIC values but overfits the
176 data. Accordingly, four zones with distinct kinematics at the plate interface can be characterized by clustering analysis (Fig. 7c,
177 Fig. S12). Cluster 1 groups the zones with high afterslip (average: 1.1 m), low coseismic slip (average: 2.2 m), moderate
178 locking degree (average: 0.5), and high seismic moment estimate (average: 13.1 log(Nm)). Cluster 2 is located in areas of low
179 locking and no seismicity, unaffected by the 2015 earthquake. Cluster 3 groups areas with high seismicity but low afterslip and
180 moderate locking. Cluster 4 groups areas with low afterslip (average: 0.14 m), high coseismic slip (average: 4.6 m), moderate
181 degree of locking (average: 0.9), and low seismic moment estimate (average: 6.7 log(Nm)).

182 Discussion

183 This work presents a comprehensive analysis of the evolution of ground displacements and seismicity following the 2015
184 (M_w 8.3) Illapel earthquake. Covering the period from 2015 to 2021, the study focuses on two specific aspects: the afterslip
185 analysis from 2015 to 2019 and the locking estimation from 2018 to 2021. By examining these observations over a span
186 of approximately six years post-earthquake, we gain valuable insights into the temporal and spatial patterns of viscoelastic
187 deformation, afterslip, relocking, and their correlation with seismic activity. The analysis of the spatiotemporal evolution of
188 ground motion reveals that the central region of the 2015 rupture zone exhibits the initial indications of interseismic contraction
189 and is the first zone to become relocked. This is evident through the observed shift in displacement direction, transitioning from
190 movement towards the trench to movement towards plate convergence two years after the earthquake (Fig. 1 and Fig. 2). These
191 findings are supported by the results obtained from the locking inversion, which indicate that the entire 2015 rupture zone is
192 fully coupled during the period from 2018 to 2021. On the contrary, postseismic deformation, characterized by displacements
193 towards the trench, predominates at the edges of the rupture zone and in the far-field backarc region (Fig. 3). This observation
194 strongly indicates that the distribution of afterslip is concentrated around the seismic rupture zone (Fig. 5), while the viscoelastic
195 relaxation of the mantle induces postseismic deformation in the backarc. These patterns of afterslip closely align with those
196 observed in previous studies based on early postseismic displacements³⁹. The viscoelastic relaxation and afterslip induced by
197 the Illapel earthquake exhibit distinct decay rates over time. In period T4, the far-field horizontal displacements show a higher

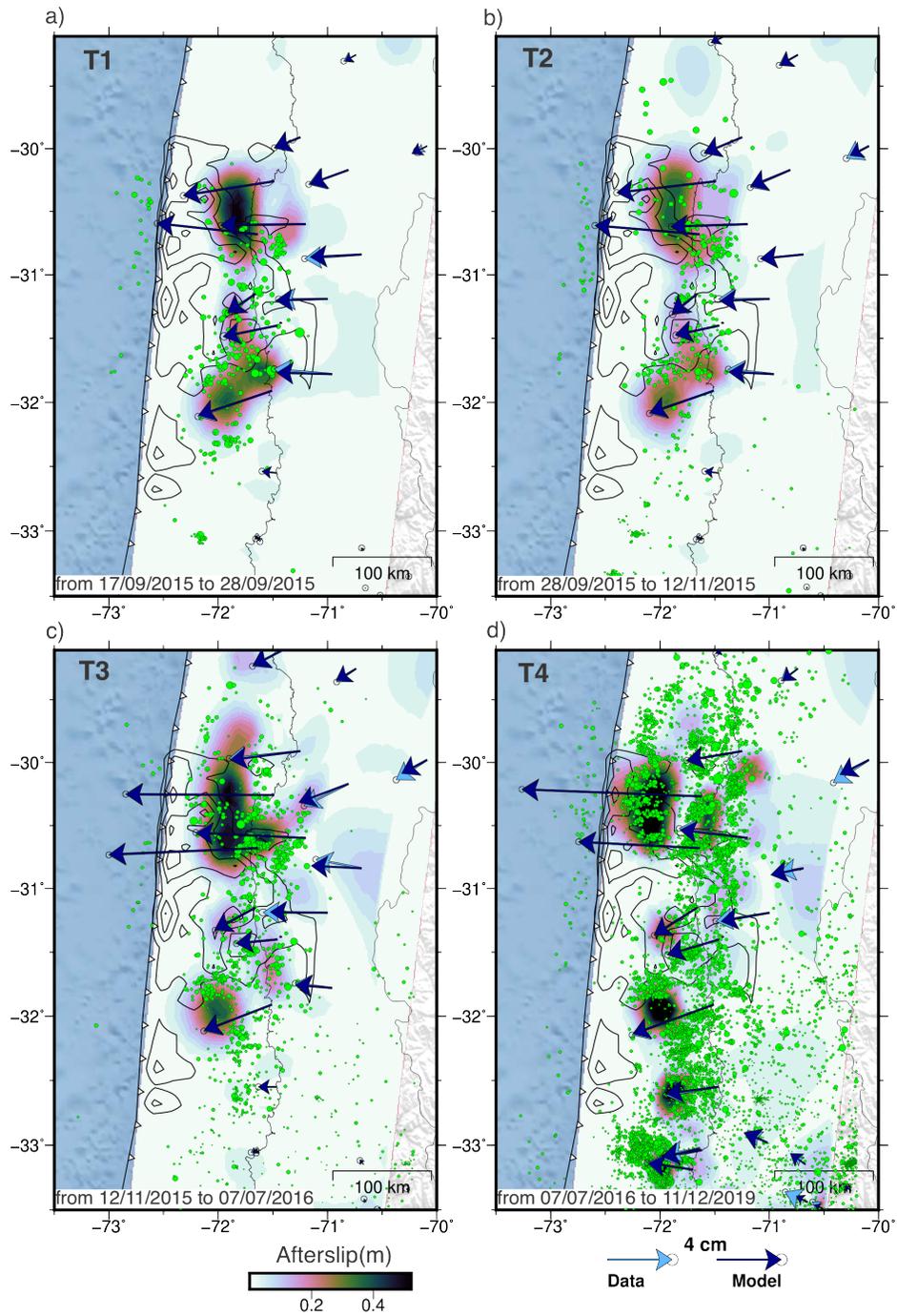


Figure 5. Modeled cumulative afterslip distribution for each time window. a-d) Afterslip distributions for T1 (a), T2 (b), T3 (c), and T4 (d). The black contours represent the Illapel 2015 rupture zone³² and the green dots the seismicity for each time window. The light blue and blue vectors show the observed and modeled horizontal displacements.

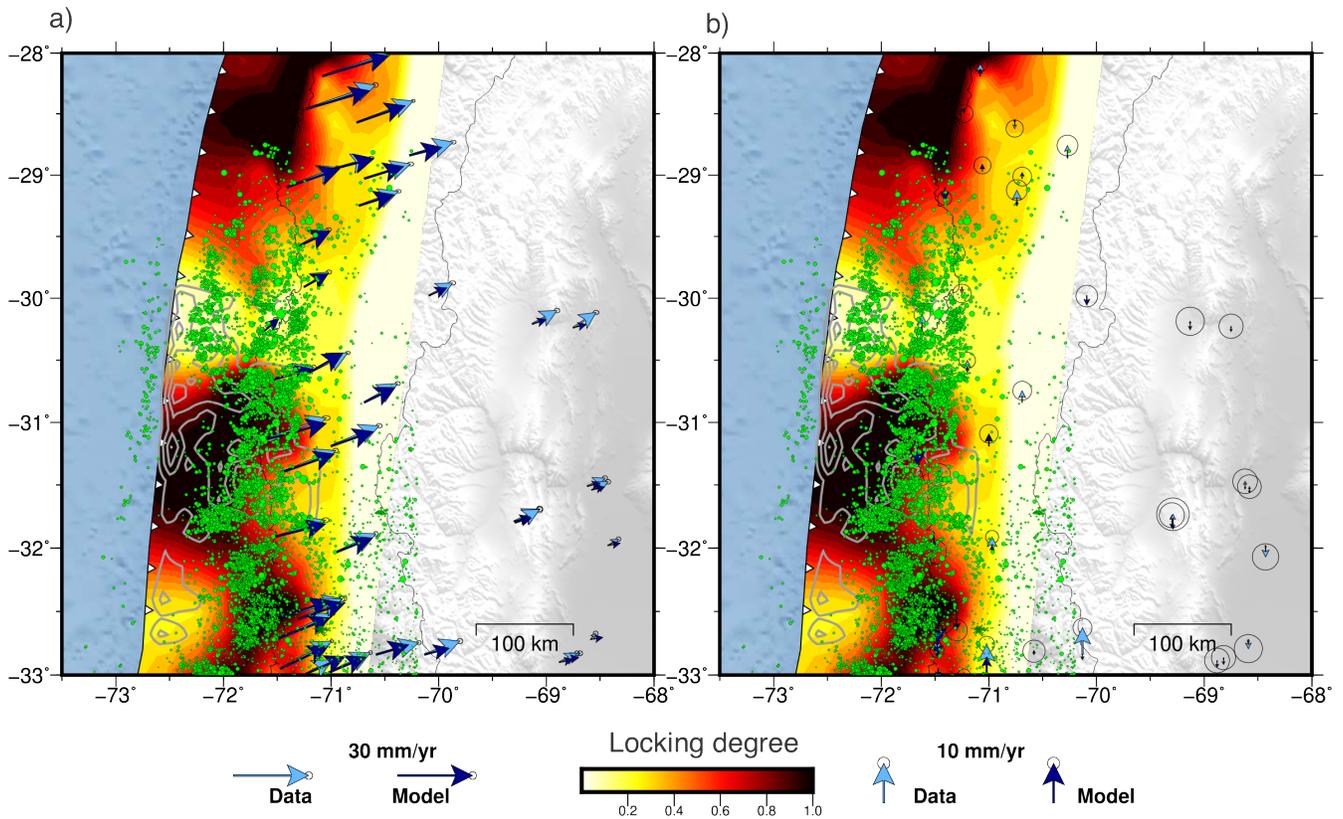


Figure 6. Degree of locking based on estimated secular velocities from 2018 to 2021. a) Horizontal and b) vertical GNSS secular velocities expressed in a stable South American reference frame. Bright and dark blue vectors represent observations and locking model predictions. Green circles show the updated seismicity catalog⁴², including events up to 2021. Gray contours represent the Illapel 2015 coseismic slip³².

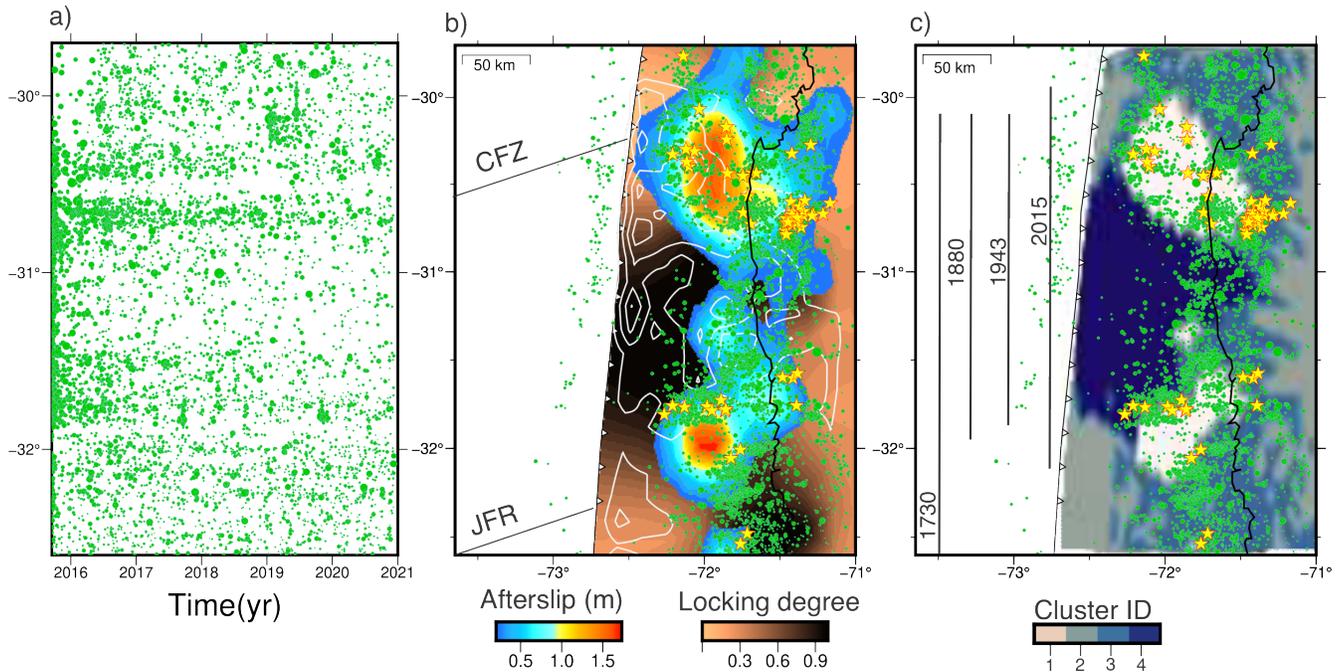


Figure 7. Comparison of the kinematic behavior of the interface (coseismic slip, afterslip, and locking degree) with the seismicity. a) Temporal evolution of the seismicity along latitudes. b) Accumulated afterslip between September 17, 2015 and December 11, 2019 and distribution of locking degree estimated from GNSS velocities between 2018 and 2022. JFR is the Juan Fernandez Ridge, and CFZ is the Challenger Fracture Zone. White contour lines represent the Illapel coseismic slip³². Green dots represent seismicity, yellow stars represent repeating earthquakes. c) Distribution of earthquake clusters based on an analysis of spatial correlations between coseismic slip, afterslip, locking degree, and seismic moment distributions. Black lines show estimated rupture lengths for historical and recent large earthquakes³³.

198 magnitude in comparison to earlier time windows (Fig. 3). This observation implies that the afterslip may have declined during
199 the analyzed period, while the effects of viscoelastic relaxation persist and continue to impact the far-field over an extended
200 duration.

201 Compared to the vertical pattern of the 2010 Maule earthquake, whose uplift mainly affected the Andes¹⁷, the post-Illapel
202 uplift is concentrated only on the coast near the rupture center (Fig. 3 and Fig. 4), an area surrounded by subsidence. This
203 vertical deformation pattern suggests that afterslip is the dominant process in nearshore ground motion, since megathrust
204 inverse slip beneath the coast can drive uplift along the coast. Therefore, probably due to the smaller magnitude of the Illapel
205 earthquake, it induces deformation dominated by viscoelastic processes mainly in the volcanic arc and backarc zones (far-field),
206 and by afterslip in the near field.

207 The afterslip distributions in the first three time windows are similar, consisting of two main afterslip zones, one to the
208 north (larger in size and slip) and one to the south of the rupture zone (Fig. 5). The amount of afterslip is similar in all time
209 intervals, but in the first two windows, the number of seismic events is relatively small compared to the T3 and T4 windows,
210 and therefore the postseismic slip in the first 67 days is predominantly aseismic. In the fourth time window (T4), we see that
211 afterslip breaks up into smaller areas, resembling a patchwork similar to the spatial distribution of seismicity in that period.
212 The northern patch propagates into the trench, triggering seismicity updip of the aseismic slip (Fig. 5d). Previous studies also
213 suggest that the afterslip from the northern path propagates toward the trench¹¹. The number of seismic events decays rapidly
214 in the first 50 days after the earthquake. In addition, the average daily moment magnitudes decreases significantly from M_w 6.7
215 in T1 to M_w 5.3 in T4. This, together with the reversal of the direction of horizontal displacements to the east three years after
216 the earthquake (Fig. 2) and the disintegration of the two main afterslip patches in T4 into smaller zones, suggests that afterslip
217 is waning. Thus, four years after the Illapel event, the deformation field is becoming dominated by interseismic contraction.

218 In all periods analyzed, seismicity and repeater earthquakes tend to concentrate at the edges of the afterslip patches, while
219 they are absent in areas of high afterslip (Fig. 5 and Fig. 7). The core of the afterslip patches remains aseismic throughout
220 the observation period (Fig. 7), confirming their aseismic behavior. This implies that the aftershocks might be a result of
221 tractions generated by the movements of these patches, suggesting that afterslip drives aftershocks²⁵. The distribution of
222 Illapel afterslip and seismicity never propagates into the zone of maximum coseismic slip, which is consistent with afterslip
223 models of other earthquakes where afterslip surrounds coseismic ruptures, e.g. Maule 2010^{21,48}, Tohoku 2011⁴⁹, and Sumatra
224 2005⁸. Earthquakes of $M_w < 8.5$ tend to produce relatively little afterslip, which decays rapidly. The percentage of the moment
225 magnitude of afterslip relative to the main earthquake is $\sim 20.8\%$ over four years for the Illapel event, which is consistent with
226 the afterslip magnitude of similarly sized events, such as the 1995 M_w 8.1 Antofagasta earthquake ($<20\%$ in 1 year)^{50,51} and
227 the 2007 M_w 8.0 Pisco earthquake (7-28% in 1.1 yr)⁵².

228 The distinct kinematic behavior and distribution of seismicity in the Illapel region megathrust suggests that the subduction
229 interface is frictionally heterogeneous (Fig. 7c). It is composed of patches exhibiting seismic behavior (highly locked with
230 high slip during earthquakes, cluster 4) and aseismic behavior (constant or episodic slip acting as a rupture barrier during large
231 earthquakes, concentrating afterslip, cluster 1), as well as patches displaying dual behavior that are moderately coupled and
232 concentrate background seismicity (cluster 3). Thus, the region of cluster 4 in Fig. 7c behaves as a persistent velocity-weakening
233 asperity that may have ruptured in a similar manner during the 1880, 1943, and 2015 earthquakes (Fig. 7)³³. Taking into account
234 the recurrence interval of approximately 60-70 years for the previous two characteristic earthquakes in this area, as well as the
235 evident indication of fault locking through surface displacements observed 3 to 5 years after the 2015 earthquake, we can infer
236 a rapid relocking within the seismic cycle. Consequently, the section of the plate boundary that exhibited significant locking
237 before the 2015 earthquake²⁷ rapidly reestablished its locked state following the event. The high degree of locking exhibited by
238 this asperity prior to the 2015 Illapel earthquake, along with its rapid reattachment, suggests that interseismic coupling in this
239 asperity is likely to remain high and consistent throughout the entire interseismic period.

240 The postseismic afterslip represents the response of the low-locked parts of the fault to the coseismic stress perturbation in
241 a zone governed by a rate-strengthening rheology (cluster 1). The kinematics of the zone appear to be related to permanent
242 frictional properties due to subduction of the Challenger Fracture Zone and the Juan Fernandez Ridge (Fig. 7b). The subduction
243 of these oceanic features may induce high pore fluid pressures⁵³, geometric complexities⁵⁴, and different frictional properties⁵⁵
244 that can act as barriers to the propagation of large earthquakes in the region. The megathrust region ruptured by the 2015
245 (M_w 8.3) Illapel earthquake seems to be capable of rapidly regaining frictional resistance. Therefore, we suggest it behaves
246 as a persistent frictional feature that accumulates elastic energy over 60-70 years, generating the characteristic type of large
247 earthquakes in the region ($M_w \sim 8$) at almost regular recurrence times (1848, 1943, and 2015).

248 **Methods**

249 **GNSS time series analysis**

250 The continental side of the Illapel rupture is well-covered by continuous GNSS stations⁵⁶, which monitor 3-D surface motions
251 from the coastline (only ~ 80 to 100 km away from the trench) to the Argentine far-field (>1000 km away from the trench, Fig. 1

and Fig. S1). We analyzed daily GNSS time series processed at the Nevada Geodetic Laboratory (NGL)⁵⁷ from September 17, 2015, to December 31, 2020. We selected GNSS stations with sufficient temporal coverage (i.e., more than two years of continuous observations), yielding 51 stations that are well distributed in both the near- and far-field (Fig S1, Fig. S2). We use the NGL time series in the International GNSS-14 Service Reference Frame (IGS14)⁵⁸. To account for the rigid-body rotation of South America, we transformed the estimated horizontal displacements and velocities to a reference system with respect to the stable part of the South American Plate by subtracting the angular velocity described by the Euler vector of 21.44°S, 125.18°W, 0.12°/Myr⁵⁹.

GNSS time series primarily reflect a sum of tectonic processes, such as coseismic jumps, interseismic velocities, transient signals (e.g., postseismic motions and slow earthquakes), along with components related to seasonal oscillations (e.g., hydrologic forcing), instrumental failures (e.g., antenna replacement) and instrumental noise⁶⁰. We use a trajectory model⁶⁰ to describe the motion of a GNSS station and characterize the postseismic decay and secular velocities. This model decomposes the motion $x(t)$ on each direction (i.e., east, north, up) of a GNSS station into four components as

$$x(t) = \underbrace{A + v(t - t_R)}_{(1) \text{ secular}} + \underbrace{\sum_{i=1}^{n_i} B_i H(t - t_i)}_{(2) \text{ jumps}} + \underbrace{\sum_{j=1}^{n_{eq}} C_j \log \left(1 + \frac{t - t_{eq_j}}{\tau} H(t - t_{eq_j}) \right)}_{(3) \text{ postseismic}} + \underbrace{\sum_{k=1}^2 \left[D_k \cos(2\pi \frac{t}{T_k}) + E_k \sin(2\pi \frac{t}{T_k}) \right]}_{(4) \text{ seasonal}} + \xi(t) \quad (1)$$

where the different terms of the model correspond to: (1) a linear component representing secular deformation processes – e.g., interseismic velocity v – with respect to a reference time t_R ; (2) subdaily jumps representing displacements caused by earthquakes or antenna changes occurring at times t_i ; (3) a logarithmic decay – with characteristic decay time τ – representative of postseismic deformation due to fault afterslip induced by an earthquake occurred at time t_{eq_j} ; (4) seasonal signals with annual (T_1) and semi-annual (T_2) periods. H is the unitary Heaviside step function and $\xi(t)$ represents formal uncertainties in the positional GNSS time series. Here, the parameters A , v , B_i , C_j , D_k and E_k are estimated by fitting the trajectory model to the observed time series using a linear weighted least squares method⁶⁰. The decay parameter τ cannot be solved using the linear inversion, as the trajectory model (Equation 1) has a nonlinear dependence on τ . Therefore, we use a grid-search approach to find the optimal value of τ for each time series, where several solutions with different values of τ are evaluated. We then choose the value of τ that produces the lowest weighted root-mean-square (wrms) residual for each time series.

The trajectory model is fitted to each of the GNSS positional time series accounting for their formal uncertainties. However, it does not account for the Common Mode Error (CME), a spatially correlated error between different GNSS stations of a regional network. CME introduces a spatially coherent bias in the position of the GNSS stations due to uncertainties in the reference frame realizations, satellite orbits and clocks, as well as related to large-scale environmental effects⁶¹. To estimate the CME, we perform a stacking of the residual of the fitted trajectory models. We first use a mean motion filter to remove any low frequencies from the residuals, and compute the stacking after filtering. Finally, we remove the estimated CME from the data to recompute the different components of the trajectory model. The trajectory models for each of the series used are shown in Fig. S2.

282 Earthquake Catalog

283 In the present study, we extended the seismicity catalog of Sippl et al. (2021)⁴², which covers the time interval from April
 284 2014 to December 2018 and contains 11,931 events for the north-central Chile region ($\sim 29.5^\circ$ - 34.5° S). Using data from 32
 285 permanent seismic stations operated by the Centro Sismologico Nacional (CSN)⁶², we have extended this catalog to the end
 286 of 2021 using the same automated processing as described in Sippl et al. (2021)⁴². The newly obtained catalog includes
 287 21,293 double-difference relocated earthquakes, the majority of which occurred at depths of ≤ 60 km on or near the megathrust.
 288 We also searched for repeating earthquakes by station-wise cross-correlating event pairs using the criterion of Uchida and
 289 Matsuzawa (2013)⁶³, which requires a cross-correlation coefficient of ≥ 0.95 at two or more stations (repeaters shown in Fig. 7).
 290 As the station network was extended in the first part of the covered time interval (years 2014 and 2015), the event catalog
 291 should be less complete for the first two years, so that event numbers before the Illapel earthquake as well as in the early part of
 292 the aftershock series are likely underestimated (Fig. 4b, c).

293 Non-linear viscoelastic response using power law rheology

294 We use a finite element method (FEM) model to compute the nonlinear viscoelastic response due to the stress changes induced
 295 by the Illapel main shock (Fig. S4). The essential components of our mechanical model have been previously documented⁴⁴, and
 296 here we describe the relevant aspects of our analysis. It is a forward geomechanical model considering power-law rheology with
 297 dislocation creep processes in the crust and upper mantle; it takes into account the slab geometry⁶⁴ and the Moho discontinuity.
 298 The model domain is discretized into finite elements with a length of 4 km close to the region of coseismic slip, while we
 299 use a coarser element resolution at larger distances (~ 50 km length). As a result, the model domain is large enough to avoid
 300 boundary artifacts (Fig. S4). This model has already been extensively tested and used^{19,44}.

We implement a temperature controlled power law rheology (Table S1) for the entire model domain described by the equation:

$$\dot{\epsilon} = A\sigma^n \exp(-Q/RT) \quad (2)$$

where $\dot{\epsilon}$ is the strain rate, A is a pre-exponent parameter, σ is the differential stress, n is the stress exponent, Q is the activation energy for creep, R is the gas constant, and T is the absolute temperature⁶⁵. We use rock material properties that can explain the observed geodetic data in southern Chile^{9,44,66} and north-central Chile where the Illapel earthquake occurred. The values of the rheological properties are summarized in Table S1. The nonlinear viscoelastic parameters we used can also explain the first-order surface deformation recorded after the 2010 Maule event⁶⁶. The resulting numerical problem is solved using the commercial FEM software ABAQUSTM, version 6.11. For each window, we compute the nonlinear viscoelastic response due to the stress changes induced by the 2015 Illapel earthquake and subtract it from the observed geodetic measurements. We then use the residuals to estimate the afterslip distribution at each time window.

Afterslip and locking degree distributions across the megathrust fault

The fault slip is parameterized on a non-planar triangulated surface representing the contact between the Nazca and South American plates in the study region as defined by SLAB2⁶⁴, ranging from the trench to a depth of 90 km.

The afterslip physical model is represented by Green's functions (GFs) that are calculated assuming triangular dislocations in a homogeneous elastic half-space with Poisson's ratio 0.25 and using the methodology of Nikkhoo and Walter (2015)⁶⁷. Here, an ad-hoc point source located at the centroid of each triangle is used to calculate the surface displacements due to a dislocation along the strike and dip directions. For the degree of locking, we use a viscoelastic FEM model to construct GFs, following the procedure and viscosity values for the continental and oceanic mantle used by Li et al. (2015)⁴⁶ and the software Pylith⁶⁸.

We use the least squares method with EPIC Tikhonov regularization⁴¹ to estimate afterslip and locking degree. The EPIC defines a spatially variable smoothing prior to compensate for the spatial variability of the observational constraints on fault slip. In this sense, it produces robust slip estimates that are less smoothed in the fault regions that are better constrained by the data, and more smoothed in regions that are less constrained by such observations. For this purpose, the following optimal problem is solved

$$\min_{\mathbf{m}} \|\mathbf{W}_\chi(\mathbf{G}\mathbf{m} - \mathbf{d})\|_2^2 + \|\mathbf{W}_h \nabla^2 \mathbf{m}\|_2^2 \quad (3)$$

where \mathbf{d} is the data vector (displacements or velocities), \mathbf{G} is the Green's function, \mathbf{m} the model parameters to estimate (afterslip or coupling degree), \mathbf{W}_χ the data misfit weight matrix, \mathbf{W}_h is the matrix of regularization weights computed according to the EPIC, and ∇^2 is a finite-difference approximation of the Laplacian operator applied to fault slip along the dip and strike directions. We impose positivity constraints on fault slip along the dip direction (dip slip ≥ 0). Using the L-curve method⁴⁵, we map the trade-off between data misfit and regularization for each time window (Fig. S7) and determine the preferred model searching to balance both terms. We used the Monte Carlo propagation method to estimate the uncertainties of the optimal model.

The obtained afterslip estimates are constrained by the corrected accumulated 3D postseismic displacements measured at the GNSS stations in each time window. The displacements are corrected by subtracting the prediction of the modeled viscoelastic response caused by the mainshock slip of either Carrasco et al. (2019)³² or Tilmann et al. (2016)²⁷ (Fig. S5). We also compare these results with inversions using postseismic displacements without viscoelastic corrections (Fig. S6, Fig. S8, Fig. S9). The estimated locking degree (Fig. 6) is constrained by interseismic rates. To obtain such rates, we subtract the postseismic component from each of the GNSS time series and use the trajectory model to estimate the linear trend for the period from 2018 to 2021 (i.e., four years of observation). We chose this period for the locking analysis because most of the postseismic deformation has drastically decreased.

Clustering analysis

Clustering is an unsupervised machine learning method used to autonomously evaluate the data distribution in feature space. We use the agglomerative clustering algorithm implemented in sklearn-scikit⁴⁷. This is a hierarchical clustering with a bottom-up approach. The algorithm first treats each object as a single cluster. Then, the pairs of clusters are successively merged until all clusters are merged into one large cluster containing all objects. We use the Ward linkage criterion, which merges clusters that cause the least increase in intra-cluster variance. We use a homogeneous grid to extract the values of coseismic slip, afterslip, locking, and seismic moment of $M_w < 7$ events and use these four datasets as features in the cluster analysis. We fit Gaussian Mixture models applying the BIC to determine the optimal number of clusters. We assume that the data points come from multi-dimensional Gaussian distributions, so the lower the BIC values, the better the model.

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494 **Author contributions statement**

495 Conceptualization: J.H., M.M., F.O-C. Methodology: J.H., M.M., F.O-C., C.P., C.S. Writing original draft: J.H., M.M., F.O-C.
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497 **Ethics declarations**

498 **Competing interests**

499 The author(s) declare no competing interests.

500 **Additional information**

501 **Data availability:** The daily GNSS time series analyzed in the current study are available in the Nevada Geodetic Laboratory
502 (NGL)⁵⁷ repository (<http://geodesy.unr.edu/NGLStationPages/gpsnetmap/GPSNetMap.html>). All GNSS time series used in
503 this study can be found in the Supplementary Information.

504 **Codes availability:** The slip inversion codes used in the current study are available from the corresponding author upon
505 reasonable request.