APPLICATION PAPER

Chemical Mechanism Motifs

Graph Characterization of Higher Order Structure in Atmospheric Chemical Reaction Mechanisms

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Abstract

Atmospheric chemical reactions play an important role in air quality and climate change. While the structure and dynamics of individual chemical reactions are fairly well understood, the emergent properties of the entire atmospheric chemical system, which can involve many different species that participate in many different reactions, are not well described. In this work, we leverage graph-theoretic techniques to characterize patterns of interaction ("motifs") in three different representations of gas-phase atmospheric chemistry, termed "chemical mechanisms". These widely used mechanisms, the Master Chemical Mechanism, the GEOS-Chem mechanism, and the Super-Fast mechanism, vary dramatically in scale and application but all generally aim to simulate the abundance and variability of chemical species in the atmosphere. This motif analysis quantifies the fundamental patterns of interaction within the mechanisms, which are directly related to their construction. For example, the gas-phase chemistry in the very small Super-Fast mechanism is entirely composed of bimolecular reactions, and its motif distribution matches that of an individual bimolecular reaction well. The larger and more complex mechanisms show emergent motif distributions that differ strongly from any specific reaction type, consistent with their complexity. The proposed motif analysis demonstrates that while these mechanisms all have a similar design goal their higher order structure of interactions differs strongly, and thus provides a novel set of tools for exploring differences across chemical mechanisms.

Impact Statement

Atmospheric chemistry regulates the abundance and variability of nearly all atmospheric pollutants and many greenhouse gases. These chemical processes are understood to be the result of a highly coupled system of reactions between a large number of chemical species. To models these processes, scientists have developed various "chemical mechanisms", which are mathematical and computational representations of this chemical reaction system. These mechanisms are fundamentally composed of individual chemical reactions that are coupled together in a highly nonlinear manner. This coupling process leads to an emergent structure in the system of chemical interactions. To date, that emergent structure has not been well characterized. This work addresses that research gap through the application of novel graph theoretical analyses. By enumerating mechanism motifs, or patterns of interaction in the mechanism, we are able to quantify the higher-order structure present in multiple different atmospheric chemical mechanisms. Our analysis provides a novel quantification of emergent structure in chemical mechanisms, and a new set of tools for comparing different atmospheric chemical mechanisms, and a new set of tools for comparing different atmospheric chemical mechanisms.

1. Introduction

Chemical reaction-driven variability in the composition of the atmosphere is a fundamental control on the modern environmental challenges of air pollution and climate change. These reactions are the dominant source of most pollution in urban areas and the primary loss process for many important greenhouse gases (Seinfeld & Pandis, 2016). As such, a detailed understanding of atmospheric chemical processes is necessary to understand the driving factors behind these modern environmental crises.

In nature, atmospheric chemistry involves at least tens of thousands of chemical species and hundreds of thousands of reactions. To gain understanding in light of this complexity, a variety of mathematical methods are used to model the chemical reactions in the atmosphere. These methods most commonly take the form of parameterized systems of coupled differential equations that define the chemical dynamics, which are then studied by solving the system from a given initial condition using various integration methods (e.g., Damian et al., 2002). In conjunction with these approaches, recent work has demonstrated the potential for methods from the graph theory literature to provide valuable complementary information on the structure and dynamics of chemical reactions in the atmosphere (Silva et al., 2021; Wiser et al., 2022).

These graph methods are based on analysis of chemical mechanisms – which are statements of all relevant chemical reactions thought to occur in the atmosphere. These mechanisms are treated as a graph (or a network), where chemical species and reactions can be represented as nodes and their interactions are represented as edges in a graph. Graph analysis of these mechanisms has led to useful scientific results in the atmospheric chemical sciences. Recent work by Silva et al. (2021) demonstrated that insights gained from graph theoretical analysis of these mechanisms are consistent with those from traditional differential equations-based methods. Dobrijevic et al. (1995) used graph methods to identify important reactions in chemical mechanisms of planetary atmospheres. Wiser et al. (2022) applied graph techniques from the combustion chemistry literature to develop new atmospheric chemical mechanisms for use in global atmospheric models.

These chemical mechanisms are all broadly designed with similar basic building blocks – a set of reactants reacting to form a set of products. Those products and reactants can then participate in further reactions, ultimately creating the highly coupled system present in most atmospheric chemical mechanisms. The emergent structure and dynamics of this complex and highly coupled chemical system can be difficult to characterize. This challenge arises due to the fact that the behavior of any individual chemical species is not fundamentally representative of the behavior of the overall chemical system. Instead, the emergent properties of the entire mechanism arise due to the coupling of species to each other. These complex couplings of species are represented as connectivity (or network structure) in a graph (Wilson, 2010).

Many methods exist to study the connectivity in graphs (e.g., Estrada, 2016). Here, we focused on so-called "motifs" present in the chemical mechanisms. Motifs are statistically significant repeating patterns of connectivity (also known as graphlets or subgraphs) within the larger graph structure, sometimes termed "fundamental building blocks" of complex systems (e.g., Masoudi-Nejad et al., 2012; Milo et al., 2002). Tracking the relative abundance of a particular motif in a graph can yield insight into the larger scale graph connectivity patterns, and ultimately the properties of the system being modeled by the graph (Blokhuis et al., 2002; Gonen & Shavitt, 2009; Simmons et al., 2019; Yeger-Lotem et al., 2004). For example, Milo et al. (2002) demonstrated how motifs represent basic processes in graphs of complex systems like food webs, neural circuitry, and gene transcription networks. Alon (2007) review the use of these motifs for studying gene and protein transcription networks, demonstrating how a motif-based graph analysis can help characterize the function of processes in these networks. In a chemical context, Tyson & Novák, (2010) study motifs in graphs of biochemical reactions, finding that the statistically significant motifs correspond to chemical regulation processes in the system. Blokhuis et al. (2020) derive motifs necessary for catalysis and autocatalysis in chemical reaction mechanisms, underscoring the key role characterizing graph motifs can play in the chemical sciences.

In this work we explored network motifs across atmospheric chemical mechanisms of varying complexity. For each mechanism, we counted all motifs containing three nodes, and compared their abundance to a structurally similar randomized baseline. Our results illustrate key emergent structural properties of these mechanisms and help explain differences in the dynamical predictions of these three representations of the atmospheric chemical system.

2. Graph Representation of Atmospheric Chemical Mechanisms

Chemical reaction mechanisms can be represented as a graph in a variety of ways (Bajczyk et al., 2018; Sakamoto et al., 1988; Wiser et al., 2022). As a brief overview, a graph G=(V, E), is a pair consisting of a set of unique entities represented as nodes or vertices in V, and a set of binary relations on nodes represented as edges in E. A directed graph is a graph where edges are directed or ordered between nodes. A bipartite graph is a graph where the node set can be partitioned into two subsets, such that edges can only exist between nodes in each subset, and never within nodes of the same subset. Here, we use the directed bipartite "species-reaction graph" framework (Feinberg, 2019; Silva et al., 2021). In a species reaction graph, there are two classes of nodes: species and reactions. Species nodes are connected to reaction nodes with a directed edge, representing reactions the species participates in as a reactant. Reaction nodes are connected to species that are a product of that reaction by a directed edge. This is summarized in Figure 1 for a hypothetical bimolecular reaction: A + B - > C + D.





Figure 1. Sample graph of a single bimolecular reaction.

While the species reaction graph in Figure 1 contains edges with directional arrows pointing only in one direction, these edges can be bidirectional. Bidirectional (or "reciprocal") edges do occur in atmospheric chemical mechanisms, where they are often used to approximate several chemical reactions in one reaction step.

We explored three different gas phase chemical mechanisms in this work: the Master Chemical Mechanism (MCM) v3.3, the GEOS-Chem v12.6 chemical mechanism, and the Super-Fast mechanism. Each of these mechanisms aims to reproduce the dynamics of the atmospheric chemical system, though are designed for very different use cases. The MCM is designed to represent chemical reactions in the atmosphere at a very high level of detail. It has 6,000 chemical species, and 17,000 reactions (Bloss et al., 2005; Jenkin et al., 2003; Saunders et al., 2003). The MCM is very computationally expensive and is primarily used as a 1-D box model to simulate chemical timescales of hours to days (Jenkin et al., 1997). The GEOS-Chem mechanism represents an intermediate complexity chemical mechanism, with approximately 200 chemical species and 750 reactions (Mao et al., 2013; Sherwen et al., 2016; Travis et al., 2016). GEOS-Chem is typically used to simulate the 3-D composition of the atmosphere on regional to global scales, for timescales of up to several years (Bey et al., 2001). The Super-Fast mechanism is a highly parameterized simplified mechanism with 18 chemical species and 20 reactions (Cameron-Smith et al., 2006). The orders of magnitude reduction in complexity makes Super-Fast the least computationally expensive mechanism studied here, enabling use cases in global 3-D climate models with simulation timescales of decades to centuries (Brown-Steiner et al., 2018; Cameron-Smith et al., 2006). In the graph representation of these mechanisms, SuperFast has 38 nodes and 81 edges, the GEOS-Chem mechanism has 612 nodes and 2,444 edges, and the MCM has 13,057 nodes and 257,245 edges.

3. Motif Counting

Motifs are repeating patterns of connectivity (also known as subgraphs or graphlets) within a larger graph. Here, we investigate the smallest possible set of motifs, those containing only 3 nodes. As in other studies of motifs (Masoudi-Nejad et al., 2012; Milo et al., 2002), we require a motif to have at least two edges (i.e., no isolated nodes). Additionally, since the networks we are studying are all bipartite graphs, there cannot be a 3-node motif

with three edges (i.e., a complete triangle), as that would require either species to interconnect or reactions to interconnect. With those qualifications, there are 6 potential combinations of nodes and edges that form motifs, each distinguished by the directionality of the edges. These 6 different combinations are often referred to as "isomorphism classes" in the literature (e.g., Milo et al., 2002; Pržulj, 2007), a term that we will use for the remainder of this manuscript. For each isomorphism class, there are two different subgraphs, one where the apex is a species ("species-centered") and one where the apex is a reaction ("reaction-centered"). All possible 3-node motifs for directed bipartite graphs, along with what they represent in chemical mechanisms, are shown in Figure 2.

Isomorphism Class	Reaction-Centered	Species-Centered
	Two species reacting	Two reactions forming the same species
2	Species reacting to form another species	Species as the product and reactant in separate reactions
3	Reaction with one of the two reactants also a product	Species formed by multiple reactions. In one reaction, the species is both a reactant and a product.
	A reaction with multiple products.	A species participating in multiple reactions as a reactant.
5	A reaction with multiple products, one of which is also a reactant.	Species reacts to form another species. The species is both a reactant and a product.
6	A reaction with multiple reactants that are also products.	A species formed by multiple reactions where it is both a reactant and a product.

Figure 2. All possible 3-node motif isomorphism classes studied in this work, along with species- and reaction-centered chemical explanations.

As a baseline example of motif counting, all motifs in the bimolecular reaction in Figure 1 are shown in Figure 3. Isomorphism class 1 appears once in this graph, isomorphism class 2 appears four times, and isomorphism class 4 appears once. In a bipartite reaction with *n* products, isomorphism class 1 appears once, isomorphism class 2 scales as 2n, and isomorphism class 4 scales as n(n-1)/2. Given that scaling, and so long as there are fewer than 5 products, a bimolecular reaction graph will have more class 2 motifs than class 4, and only one class 1 motif.



Figure 3. The three 3-node motifs present in the bimolecular reaction shown in Figure 1. Motifs are shown as red arrows, and their motif isomorphism classes are labeled (See Figure 2).

We use the igraph software package (Csardi & Nepusz, 2006) in this work for all graph analysis tasks, including motif counting.

4. Results and Discussion

We count and intercompare the motif prevalence in the Super-Fast, GEOS-Chem, and MCM chemical mechanisms. The total motif counts are summarized in the histograms in Figure 4. This motif count scales with the size of the mechanisms, with the large MCM having upwards of 5 orders of magnitude more total motifs than the compact Super-Fast mechanism.



Figure 4. Distribution of motifs for all 6 isomorphism classes across all three chemical mechanisms studied in this work.

In general, isomorphism classes 1, 2, and 4 are the most common in all three mechanisms. These are the basic building blocks of a bimolecular reaction and are all present in a basic bimolecular reaction with two products, $A + B \rightarrow C + D$, as shown in Figure 3. The other three classes (classes 3, 5, and 6) present in Figure 4 all have bidirectional edges, indicating reciprocal reactions. These are substantially less common because reciprocal

reactions are so rare in these reaction mechanisms. Our prior work quantified that only up to 10% of edges are bidirectional (Silva et al., 2021).

A bimolecular reaction generally contributes more motifs in isomorphism class 2 than class 1 or 4. The Super-Fast motif distribution is consistent with this bimolecular reaction motif occurrence pattern. However, the most common isomorphism class in the GEOS-Chem and MCM graphs is isomorphism class 1. Isomorphism class 1 is only present once in any bimolecular reaction and scales with the number of reactants as m(m-1)/2, where *m* is the number of reactants. Since most reactions have a reasonably small number of unique products (e.g., 2 or fewer), the only way isomorphism class 1 can dominate in the mechanism arises from the connectivity pattern in the graph – namely that many chemical species are reactants and products in more than one reaction.

Certain species in the chemical mechanisms participate in an outsized fraction of all chemical reactions. We investigate what fraction of the motif pattern in Figure 4 are related to the species that participate in the most reactions (i.e., with highest degree), namely the HO_x (OH and HO₂) and NO_x (NO and NO₂) chemical families. These chemical families represent 4 species that are highly connected in these graphs, participating in the bulk of the individual chemical reactions (Silva et al., 2021). The fraction of each isomorphism class attributable to motifs centered on HO_x and NO_x is shown in Figure 5. Motifs centered on the HO_x and NO_x chemical families represent more than 50% of most isomorphism classes. As the mechanism complexity increases, the fraction of motif classes centered on the HO_x and NO_x chemical families increases. The MCM shows nearly 100% of the isomorphism classes containing bidirectional edges (classes 3, 5, and 6) are centered on the HO_x and NO_x chemical families. This indicates that in the MCM, and to a lesser extent GEOS-Chem, nearly all reactions wherein a reactant is also a product are reactions that involve at least one of: OH, HO₂, NO, or NO₂.



Figure 5. The fraction of isomorphism classes centered on the HO_x and NO_x chemical families.

We further assess the motif prevalence in the graphs by comparison to the motif prevalence of structurally similar but randomly generate baseline graphs. For a useful 1:1 comparison, these random baselines must retain similar properties as the original graph being studied. To that end, we generated random graphs that were bipartite, had the same number of nodes and edges, and the same degree distribution of chemical species (both in- an out- degree) as the original chemical mechanism graphs. We generated 1,000 of these random graphs for each of the three chemical mechanisms studied in this work and counted the motifs in each of these baselines. Once the random baseline graphs were generated and motifs counted, we calculated the statistical significance of the motif prevalence through a standard z-score. We consider any motif isomorphism class with a z-score of greater than or equal to 1.645 (p <= 0.05) to be statistically significant.

The motif prevalence z-scores are summarized in Figure 6. Since the size of the three mechanisms studied here varies across several orders of magnitude, the direct comparison of z-scores across mechanisms is not meaningful. As such, we normalize them to the z-score associated with the first isomorphism class.



Figure 6. The scaled Z-score of the isomorphism class prevalence in each of the three mechanisms as compared to a random baseline. Transparent bars are not statistically significant.

For each of the three mechanisms, the first isomorphism class has the largest associated z-score, and is positive (i.e., more likely to occur than in a random baseline graph). This is consistent with the design of these mechanisms wherein multiple chemical compounds react and multiple reactions form the same compound. Most chemical species in atmospheric chemical mechanisms participate in multiple chemical reactions. The agreement in prevalence between chemical mechanisms disappears beyond the first isomorphism class. In some cases, the z-score may be in a similar direction (e.g., class 2, 3, and 5) but not all mechanisms have significant class prevalence or have wildly different magnitudes. In other cases, the z-score direction may change entirely between chemical mechanisms, as in isomorphism class 4, which is more likely to occur than random in the Super-Fast and MCM mechanisms, but less likely in the GEOS-Chem mechanism. The divergent behavior of the GEOS-Chem mechanism with respect to classes 2 and 4 is particularly noteworthy. Along with isomorphism class 1, these are the fundamental three motifs present in a bimolecular reaction and are explicating added to the mechanisms during construction (See Figure 3). However, in the GEOS-Chem mechanism, isomorphism class 2 is not statistically significantly represented in the connectivity pattern, and isomorphism class 4 is statistically significantly less likely to occur than random. The emergent structure of chemical interactions in these mechanisms differ substantially, despite the fact that all three mechanisms are dominantly composed of biomolecular reactions.

5. Summary and Broader Implications

The higher order structure in atmospheric chemical mechanisms arises due to the coupling of chemical species through chemical reactions. We quantified this emergent structure through exploring repeating patterns of connectivity known as graph motifs. We counted all 3-node motifs in three mechanisms of varying complexity: the MCM, GEOS-Chem, and the Super-Fast chemical mechanisms. These chemical mechanisms are largely constructed through coupling many individual (largely bimolecular) reactions together. That signature of bimolecular chemistry is present to some degree in the motif counts for each mechanism. However, we find substantial differences in motif class counts across the three mechanisms studies here. The total motif abundance in each mechanism is more complex than simply chaining a series of bimolecular reactions together, consistent with the high degree of chemical coupling and complexity present in atmospheric chemical mechanisms.

Overall, these results point to the fact that while there are some similarities between these chemical mechanisms (they are all simulating the same general system), higher order structural analysis indicates that they are fundamentally different. This is consistent with the notion that these chemical mechanisms have different

patterns of chemical interactions and represent a different set of underlying chemical dynamics (e.g., Brown-Steiner et al., 2018).

Graph structural analysis can provide key insight to enable detailed comparison and diagnosis of system behavior across the atmospheric and environmental sciences. Future work integrating additional processes into these graph mechanism representations (e.g., photolysis, heterogeneous chemistry, etc.) and work exploring the direct connection between motif prevalence and dynamical system behavior would be valuable. This would provide additional context for interpreting the implications of the differences shown in this comparative analysis.

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