

A labeling intercomparison of retrogressive thaw slumps by a diverse group of domain experts

I.Nitze¹, J.Van der Sluijs², S.Barth^{1,3,4}, P.Bernhard⁵, L.Huang⁶, M.J.Lara⁷, A.Kizyakov⁸, N.Nesterova^{1,3}, A.Runge^{9,1},
A.Veremeeva¹, M.Ward Jones¹⁰, C.Witharana¹¹, Z.Xia^{12,7}, A.K. Liljedahl¹³

Affiliations

1 Alfred Wegener Institute, Permafrost research section, Potsdam, Germany, ingmar.nitze@awi.de,
sophia.barth@awi.de, nina.nesterova@awi.de, aleksandra.veremeeva@awi.de

2 NWT Centre for Geomatics, Government of Northwest Territories, Yellowknife, Canada,
jurjen_vandersluijs@gov.nt.ca.

3 University of Potsdam, Institute of Geoscience, Potsdam, Germany

4 Joint Research Center, Ispra, Italy

5 Department of Civil Environmental and Geomatic Engineering, ETH Zurich, Switzerland,
bernhard@ifu.baug.ethz.ch.

6 Institute of Space and Earth Information Science, The Chinese University of Hong Kong, Shatin, N.T., Hong
Kong SAR, China, lingcaohuang@cuhk.edu.hk.

7 Department of Plant Biology, University of Illinois at Urbana-Champaign, Urbana, Illinois, USA; Department of
Geography, University of Illinois at Urbana-Champaign, Urbana, Illinois, USA, mjlara@illinois.edu.

8 Lomonosov Moscow State University, Department of Cryolithology and Glaciology, Faculty of Geography,
Moscow, Russia, akizyakov@mail.ru.

9 GFZ German Research Centre for Geosciences, Remote Sensing and Geoinformatics, Potsdam, Germany
alexandra.runge@gfz-potsdam.de.

10 Water and Environmental Research Center (WERC), University of Alaska Fairbanks, PO Box 755910,
Fairbanks, AK 99775-5910, mkwardjones@alaska.edu.

11 Department of Natural Resources and the Environment, University of Connecticut, Storrs, CT 06269, USA,
chandi.witharana@uconn.edu.

12 Earth System Science Programme, Faculty of Science, The Chinese University of Hong Kong, Hong Kong SAR,
China, ZhuoxuanXIA@link.cuhk.edu.hk.

13 Woodwell Climate Research Center, 149 Woods Hole Road, Falmouth 02540-1644, MA, United States,
aliljedahl@woodwellclimate.org.

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Highlights

- Labeling experiment of retrogressive thaw slumps by a group of international domain experts
- Noticeable variation between domain experts and study sites
- Variation driven by regional knowledge and scientific objective of experts
- Common guidelines highly recommended to achieve higher consensus

42 **Abstract**

43 Deep-learning (DL) models have become increasingly beneficial for the detection of retrogressive thaw slumps (RTS)
44 in the permafrost domain. However, comparing accuracy metrics is challenging due to unstandardized labeling
45 guidelines. To address this, we conducted an experiment with 12 international domain experts from a broad range of
46 scientific backgrounds. Using 3m PlanetScope multispectral imagery, they digitized RTS footprints in two sites. We
47 evaluated label uncertainty by comparing manually outlined RTS labels using Intersection-over-Union (IoU) and F1
48 metrics. At the Canadian Peel Plateau site, we see good agreement, particularly in the active parts of RTS. Differences
49 were observed in the interpretation of the debris tongue and the stable vegetated sections of RTS. At the Russian
50 Bykovsky site, we observed a larger mismatch. Here, the same differences were documented, but several participants
51 mistakenly identified non-RTS features. This emphasizes the importance of site-specific knowledge for reliable label
52 creation. The experiment highlights the need for standardized labeling procedures and definition of their scientific
53 purpose. The most similar expert labels outperformed the accuracy metrics reported in the literature, highlighting
54 human labeling capabilities with proper training, site knowledge, and clear guidelines. These findings lay the
55 groundwork for DL-based RTS monitoring in the pan-Arctic.

56 **Keywords:** retrogressive thaw slumps, deep learning, remote sensing, uncertainty estimation, permafrost, hillslope
57 thermokarst

58 **Introduction**

59 The northern high latitudes are affected by a rapidly changing climate (Chylek et al., 2022; Serreze & Barry, 2011)
60 with further warming and wetting expected over the coming decades (Meredith et al., 2019). This will have an impact
61 on vulnerable permafrost landscapes, with a potential increase in permafrost thaw and degradation. Many regions with
62 ice-rich ground are already affected by hillslope thermokarst, such as retrogressive thaw slumps (RTS). RTS are
63 dynamic geomorphological mass-wasting features prevalent across ground-ice-rich permafrost regions around the
64 Arctic and Qinghai-Tibetan Plateau. The landform is triggered by thawing and collapsing ice-rich ground, which
65 continues to propagate upslope via the process of ice ablation (Burn & Lewkowitz, 1990). RTS are typically confined
66 to regions with ice-rich permafrost. RTS as a geomorphological feature, contain distinct parts, such as a headwall,
67 scar zone, and debris tongue (Fig 1). Their size can range from a few m² to approximately two km². They are
68 temporally variable and often exhibit polycyclic (i.e., recurring over time) dynamics (Kerfoot, 1969; Mackay, 1966),
69 which are influenced by weather, climate, and local geomorphological conditions. In most cases they are located close
70 to water bodies, such as rivers, sea coasts or lake shores, as well as dynamic morphological gradients, such as valleys
71 and slopes. In their immediate vicinity and in downstream environments they can have a strong impact on hydrology,
72 geomorphology, and various biogeochemical cycles (Kokelj et al., 2021). With drastically changing climate in the
73 arctic and high-mountain regions, RTS dynamics have rapidly accelerated over the past decades as determined through
74 manual mapping approaches (Lantz & Kokelj, 2008; Segal et al., 2016; Van Der Sluijs et al., 2023; Ward Jones et al.,
75 2019).

76 Conventional mapping initiatives for RTS rely heavily on manual mapping and detailed local geomorphological
77 knowledge and/or semi-automated mapping approaches (Kokelj et al., 2017, 2021; Lantz & Kokelj, 2008; Lewkowicz
78 & Way, 2019; Mackay, 1966; Swanson & Nolan, 2018). The science community have just begun to produce pan-
79 Arctic datasets of mapped RTS (Huang et al., 2023) as more automated, machine-learning (ML) or deep learning (DL)
80 based approaches have become popular over the past decade (Nitze et al., 2018; Runge et al., 2022). In combination
81 with large improvements in the availability of satellite imagery (Wulder et al., 2022) and computational power, such
82 as cloud- or high performance computing, fine-resolution large-domain products are now possible. Typically, most
83 DL workflows are supervised approaches, requiring a high quantity and quality of manually produced training labels
84 (Rädsch et al., 2023). However, the availability and usability of labels acquired across various spatial, spectral, and
85 temporal scales is still limited as of now. Therefore, manual labeling has often been used to increase the number of
86 training labels in DL applications. As many labels are required (preferably in the thousands), distributing this work
87 within a team or even across an entire science community becomes an important and necessary step for scaling. To
88 support effective community-wide label synthesis, clear definitions and guidelines on how to label target features are
89 required. In addition, efforts to evaluate the label variability among analysts will be critical to maintain data quality
90 and consistency (Plank, 2022). While anthropogenic objects, such as buildings or airplanes have distinct and clear
91 boundaries and well-understood ontologies, natural object boundaries are much more variable and often ambiguous
92 or dependent on the particular use case and definition. Particularly labeling dynamic geomorphological features that
93 initiate and expand over time, such as RTS, is often challenging due to variable atmospheric (i.e. haze, clouds, smoke)
94 and environmental conditions (i.e. plant pheno-period and soil moisture availability). Beyond these externally
95 changing conditions, inherent RTS processes during initiation (e.g vegetation removal and exposure of bare earth),
96 growth (e.g mud slurries, expanding boundaries), and stabilization (revegetation) means that a RTS as a landform can
97 appear very differently through time, affecting its abstract representation and consistency of DL labeling efforts.

98 With the increasing popularity of DL (Ma et al., 2019; Zhu et al., 2017), label availability and quality becomes an
99 increasingly important topic. Over the past decades the permafrost and RTS research community has increased in
100 diversity from a traditional earth science and geomorphology people to a broader group, with different domain
101 backgrounds such as ecology, remote sensing, and computer science. Experience in field work has also diversified,
102 which may influence labeling consistency and quality. Thus, the scope of RTS research has also broadened to more
103 diverse objectives and analyses such as large-scale mapping, change detection, and environmental impacts, which
104 may lead to different definitions or classifications of which parts belong to an RTS.

105 Recent DL initiatives for mapping RTS across different locations within the permafrost extent, such as Siberia (Yang
106 et al., 2023), Tibetan Plateau (Huang et al., 2020, 2021; Xia et al., 2022), Northern Canada (Witharana et al., 2022),
107 various localities across the Arctic (Nitze et al., 2021), or the entire Arctic (Huang et al., 2023), used different methods
108 and imagery sources, to train and validate their models. For example, (Huang et al., 2020, 2021; Nitze et al., 2021;
109 Witharana et al., 2022; Xia et al., 2022) created their own hand-drawn labels, while (Yang et al., 2023) used a
110 combination of newly hand-drawn labels and already existing external sources e.g. (Nitze et al., 2021). However, they
111 all achieved accuracy metrics using IoU (intersection over Union), which ranged from low to very good agreement:
112 0.15-0.58 (Nitze et al., 2021), 0.71-0.74 (Yang et al., 2023) or F1 of 0.25-0.73 (Nitze et al., 2021), 0.85 (Huang et al.,

113 2020) and 0.75-0.85 (Witharana et al., 2022). As these values are relative to validation data based on self-created
114 hand-drawn labels, and not independent benchmark datasets, accuracy metrics are difficult to compare across methods
115 and geographical regions. Using different image sources further complicates the comparison of the different studies.
116 Furthermore, sampling strategies (e.g. grid, random, stratified, manual) exacerbate the difficulties of comparing RTS
117 segmentation studies as landscapes produce a wide variety of RTS expressions due to differing topographical, sub-
118 surface, and climate settings. This could result in undersampling of particular RTS morphologies and activity levels
119 (e.g., small, lakeside RTS or large inactive RTS landforms) that limit the generalizability of DL frameworks when
120 these are applied outside of the domain area, and may lead to false predictions. As one of the end goals of remotely-
121 sensed detection and delineation is to inform scientists, practitioners, and communities of new RTS locations or RTS
122 growth, false negatives/positives or differing delineations may be artifacts of disparate methods and slump ontology
123 rather than actual change (Van Der Sluijs et al., 2023). These model artifacts can have considerable implications when
124 DL output products are subsequently used for landscape vulnerability assessments such as RTS growth forecasts, or
125 upscaling environmental impacts to larger areas (e.g., carbon/methane).

126 Compared to other domains, such as everyday imagery with *imagenet* (Deng et al., 2009) or *BigEarthNet* for standard
127 earth observation imagery (Sumbul et al., 2021), there is neither a benchmark set for RTS boundaries nor any
128 intercomparison of RTS labeling results between domain experts to better understand the variability of human-derived
129 training data in the context of RTS mapping efforts using DL. To determine the necessity and properties of such
130 benchmark datasets, we set up an experiment to let domain experts manually label RTS boundaries within satellite
131 imagery and evaluate the degree of agreement or disagreement among them. Such experiments have been conducted
132 for a few other domains such as terrestrial (Guzzetti et al., 2012) or subaqueous (Clare et al., 2019) landslides. The
133 availability of clear instructions, visual examples and professional labeling experience has helped to improve the label
134 quality of biomedical images (Rädsch et al., 2023).

135 Here we specifically evaluate the consistency and accuracy of labels between twelve international domain experts
136 from various backgrounds, who are all contributors to the International Permafrost Association (IPA) action group
137 on RTS (RTSInTrain). From these results we infer the potential impact on efforts to harmonize and pool pan-Arctic
138 scale training and validation datasets as well as past and future DL-based RTS mapping efforts.

139



140
 141 Figure 1: Oblique aerial image of a typical bowl-shaped retrogressive thaw slump (RTS) in NW Canada (67.2588°,-
 142 135.2453°). Typical labeling strategies indicated: 1) only highly active regions close to the headwall in green, 2) active
 143 areas with wet bare soils including headwall and scar zone in light yellow, 3) RTS footprint including inactive and
 144 vegetated parts in orange, and 4) complete RTS including debris tongue in red. Photo: J. Van der Sluijs.

145 **Data and Study Sites**

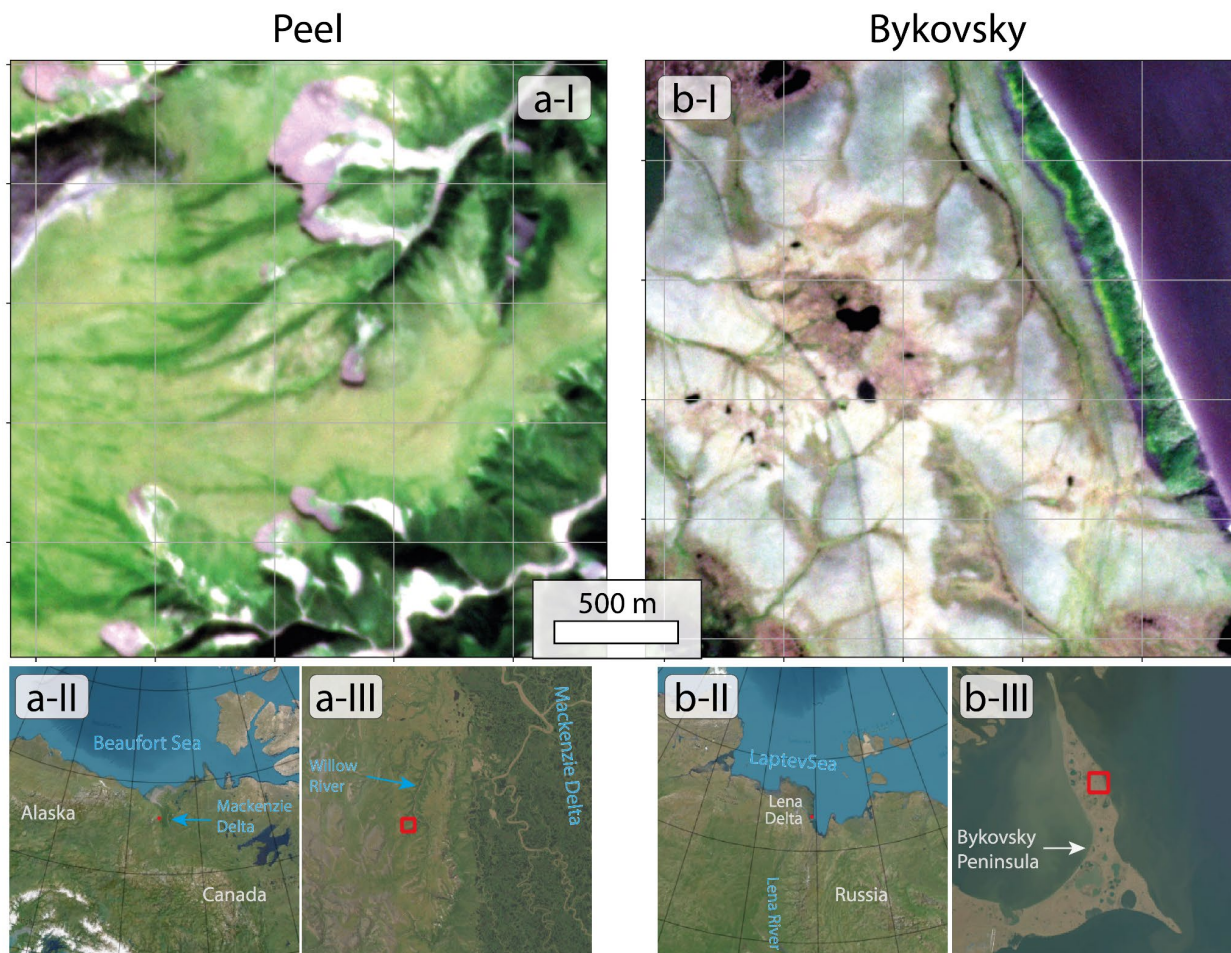
146 *Data*

147 For this experiment we used two study sites, one on the Peel Plateau in Northwestern Canada and a second on the
 148 Bykovsky Peninsula close to the Lena Delta in Northeast Siberia (Fig 2). Both sites contain the target landscape
 149 features, RTS of different sizes and are located in different landscape settings. These specific sites were chosen as
 150 they represent different types of RTS morphologies and landscape settings. As the main data source, we used
 151 PlanetScope (Planet Team, 2017) multispectral imagery OrthoTiles, with a spatial resolution of 3.15m per pixel and
 152 four spectral bands (Blue, Green, Red, Near-infrared). We used single acquisitions for each site. The scenes were
 153 acquired on 2021-08-04 (OrthoTile 4763844_0870513_2021-08-04_2416) for Peel and 2021-07-21 for Bykovsky
 154 (OrthoTile 4713120_5272315_2021-07-21_2463) and represent cloud-free and good-quality images. Both scenes
 155 were clipped to a size of 2.5x2.5 km, to minimize the labeling efforts and maximize participation of volunteers. To
 156 support digitization we added the ArcticDEM (Porter et al., 2018) as well as lower spatial resolution Landsat-8 with
 157 30m and Sentinel-2 with 10m spatial resolution.

158 The Peel site is located on the Peel Plateau at 68.052°N 135.668°W in the Beaufort Delta region of Northwestern
159 Canada (Fig 2a). This region is located in a formerly glaciated area (Kokelj et al., 2017; Segal et al., 2016) with distinct
160 terrain morphology of hills and valleys. The terrain is pronounced with deeply incised valleys and an elevation range
161 of 250 to 500 m. The Peel Plateau is in the tundra-taiga ecotone. Active RTS in this area have a typical round bowl
162 like shape, and a large scar zone with significant volumes of debris, which partially fill the valley downstream (see
163 Fig 2a-I, Figs S1-S2) (Kokelj et al., 2021). In the Beaufort Delta region the location and morphology of active RTS
164 are closely linked to inactive RTS whereby the majority of active thaw slumping processes have occurred in
165 association, or within the footprint, of past disturbances (Van Der Sluijs et al., 2023). This region has been subject to
166 a substantial amount of research (Kokelj et al., 2015, 2017, 2021; Lacelle et al., 2010; Segal et al., 2016) and is well
167 known to the RTS research community.

168 The Bykovsky site is located at 71.881°N 129.293°E on the Bykovsky Peninsula on the Laptev Sea coast southeast of
169 the Lena Delta in Northeastern Siberia (Fig 2b). Permafrost here is dominated by late Pleistocene syngenetic ice-rich
170 Yedoma Ice Complex deposits with a thickness of up to 50 m (Shmelev et al., 2017). In contrast to the Peel site, this
171 area has not been glaciated and the cryostructure of deposits is different and characterized by the large polygonal ice
172 wedges. RTS along this coastline typically have an elongated shape and mostly contain a narrow scar zone along the
173 top slope, known as thermodenudation (Günther et al., 2013), and a stabilized, vegetated zone in the middle and lower
174 slopes (Fig 2b-I, Figs S3-S4). The vegetation is dominated by sparse tundra with differences between undisturbed
175 tundra and recently disturbed areas, such as stabilized RTS scar zones. The terrain is undulating with elevation from
176 sea level to approx. 40 m. This region has been subject to few past studies in the context of slumping and coastal
177 dynamics (Grosse et al., 2005, 2007; Günther et al., 2013; Lantuit et al., 2011).

178



179
 180 Figure 2: PlanetScope Satellite images of the study sites a) Peel and b) Bykovsky as a real color composite (RGB)
 181 with 3.15m nominal spatial resolution, and with overview maps (a/b-II/III) of the locations. Background Map: ESRI
 182 Satellite.

183

184 **Methods**

185 Twelve domain experts, who are all members of the International Permafrost Association (IPA) funded action group
 186 on RTS (RTSInTrain), volunteered to participate in this experiment. They have different scientific backgrounds such
 187 as geomorphologists, geologists, remote sensing scientists to computer scientists. Furthermore, the current scientific
 188 focus varied from geomorphological analysis, to mapping spatial and/or volume changes. Participants come from
 189 different countries (Germany, Russia, Canada, USA, China, Switzerland) and have variable experience of RTS
 190 fieldwork from none to extensive (see Table S1). The participants' spatial focus and experience also varied strongly
 191 from single specific regions such as NW Canada or Tibetan Plateau, to pan-Arctic. For the analysis we anonymized
 192 the participants names and assigned each one a random number between 1 and 13 (#01-#13).

193 *Digitization*

194 The participants were requested to manually digitize RTS using a GIS software of their choice and on the provided
195 imagery. The PlanetScope image was supposed to be used as the main labeling source. We further provided the
196 ArcticDEM elevation model and the temporally nearest Landsat and Sentinel-2 scenes. We requested that participants
197 cover each identified RTS by a polygon geometry. We did not provide further instructions to better understand and
198 quantify the individual differences in the absence of specific rulesets (e.g. how to label RTS based on specific
199 geomorphic features).

200 *Evaluation*

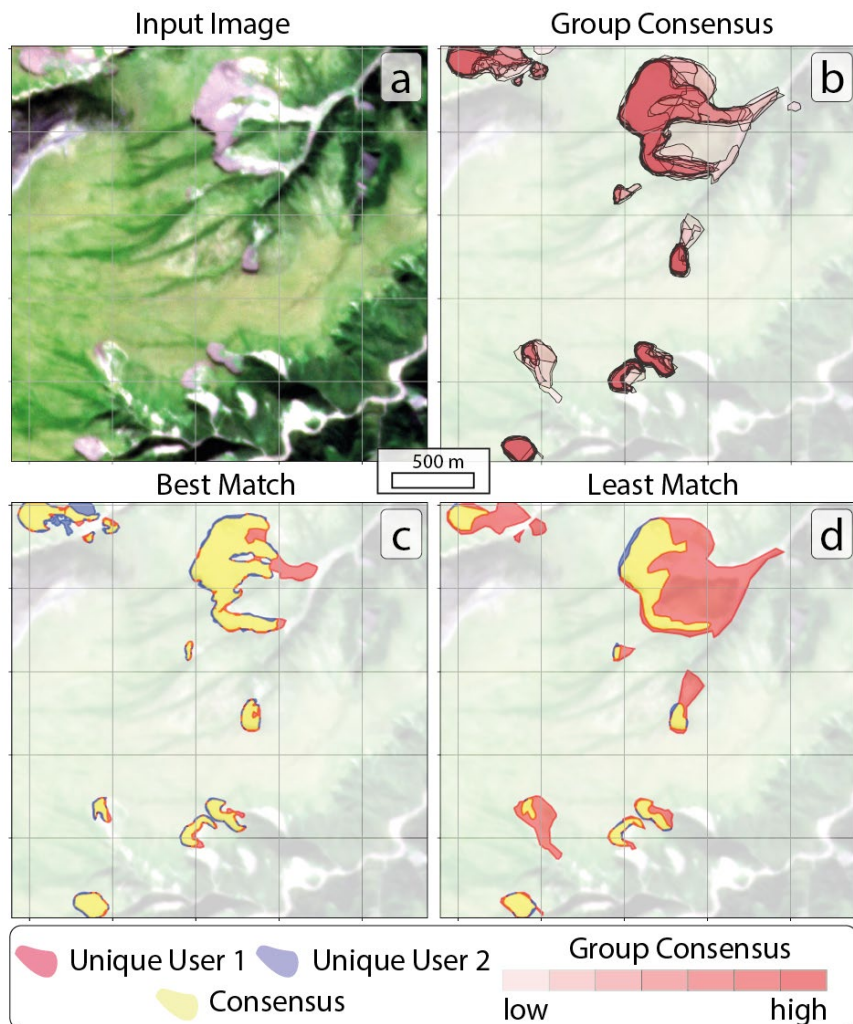
201 For quantifying the similarity, we used standard remote sensing and image segmentation metrics, such as Intersection-
202 over-Union, F1, precision and recall. Typically, these metrics are used to validate a prediction versus a ground truth.
203 In our case we validated all unique output combinations against each other. For this we used the digitized vector files
204 and calculated the metrics using the *geopandas* python package. All geospatial data were projected in the respective
205 local UTM zone, Peel in zone 8N (EPSG:32608) and Bykovsky in zone 52N (EPSG:32652).

206 **Results**

207 *Peel Plateau*

208 In the Peel Plateau (Fig 3) the participants generally identified the same RTS and digitized similar features. The
209 number of identified individual objects ranged from 7 to 11, with a mode (highest frequency) of 8 and 11 RTS labeled
210 by three people each. The mean \pm standard deviation IoU Score is 0.59 ± 0.09 ranging from 0.77 to 0.34 for individual
211 label pairs (Fig 5a). The F1 score is on average 0.74 ± 0.08 and ranges from 0.87 to 0.51. Detailed analysis of each
212 individual combination is provided in Supplementary Table TS2. The best combination was achieved by participants
213 #01 and #03 which happens to be part of the same scientific organization and with internal digitization guidelines in
214 place based on past initiatives (Fig 3c).

215 In this region differences arise in the digitization of specific features within RTS. All participants digitized the
216 apparently active part close to the headwall with freshly exposed soil and debris. Differences become apparent in the
217 lower parts, most notably the scar zone, which was digitized by almost all participants (11 of 12). The debris tongue
218 and flows were only included by three (#s 05, 09 and 12) of 12 participants. Inactive parts were also treated differently
219 (Fig 3d). Minor differences in label agreement also appear due to slight differences in user created geometries even
220 though digitizing the same feature, e.g. the headwall (Fig 3c). The visual differences in Fig 3b showcase the differences
221 in geomorphological interpretation.

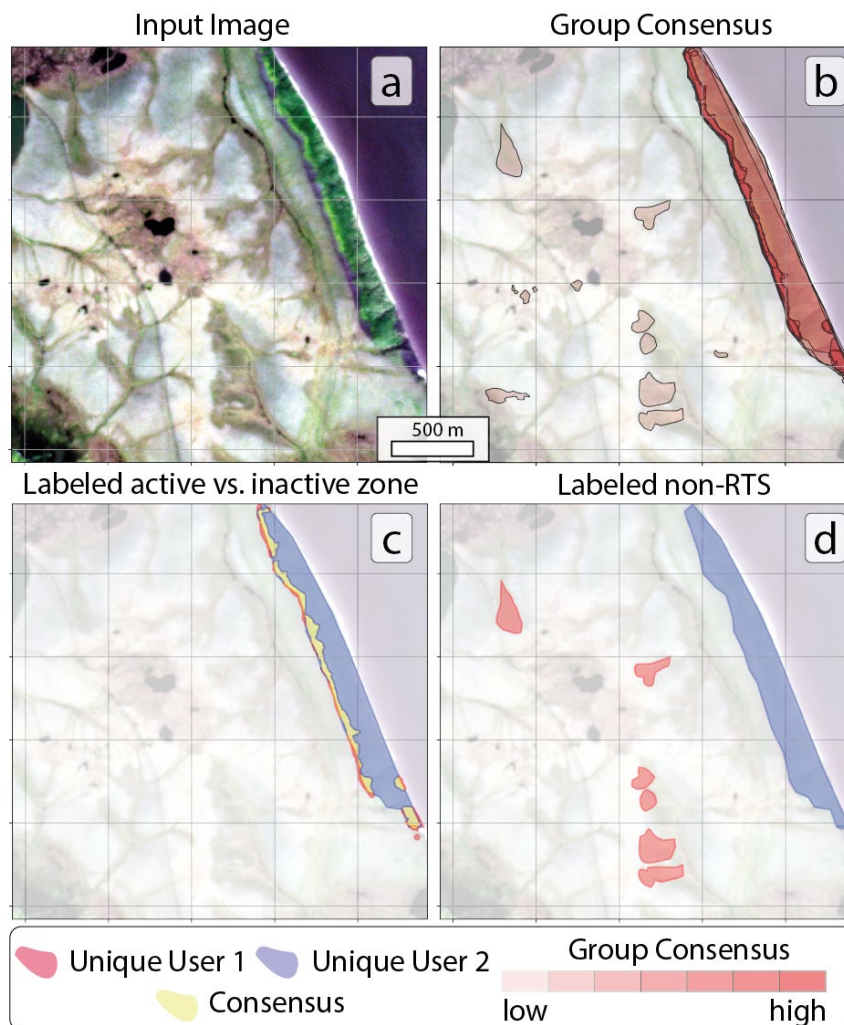


222
 223 Figure 3: a) PlanetScope satellite image of the study area as a real color composite (RGB), b) the spatial group
 224 consensus, the consensus between c) the best matching (users #03 vs. #01), and d) least matching pairs (users #05 vs.
 225 #08).

226
 227 *Bykovsky*
 228 In Bykovsky (Fig 4) the RTS mapping experiment resulted in considerably different observations than the Peel site
 229 with on average less overlap and a lot more variance. The total number of identified individual RTS objects ranged
 230 from 1 to 11, with a mode of one large single RTS labeled by four out of 10 people. The mean IoU Score is 0.21 ± 0.31
 231 ranging from 0.92 to 0 (Fig 5b). The F1 score, which is on average 0.26 ± 0.34 ranges from 0.96 to 0. Generally, the
 232 results come in three clusters. Cluster 1 recognized the RTS, which are in a terraced shape, and digitized the active
 233 scar zone and additionally the stabilized, vegetated parts (Fig 4b-c). The four participants who followed this strategy
 234 (#s 04, 05, 09, 10), have high similarity scores/metrics (IoU 0.78-0.92). Similarly, there is a second group (#s 01, 03,
 235 06), who homogeneously digitized only the active scar zones, which results in high similarity within this group (IoU
 236 0.63-0.7). While three of four members of the first group typically have a focus on geomorphology and landform

237 analysis, all members of the second group have a strong focus on mapping RTS (see Tab TS-1). Scores between group
 238 1 and 2 are comparably low with IoU from 0.16 to 0.25 due to the large extent of the stabilized zone, although both
 239 groups detected the same general features (Fig 4c), which are spatially intersecting. Instead of one large object,
 240 common among group 1, members of the second group labeled smaller, but a higher number of individual objects,
 241 typically 4 or 5, in one case 11. Detailed analysis of each individual combination is provided in Supplementary Table
 242 TS3.

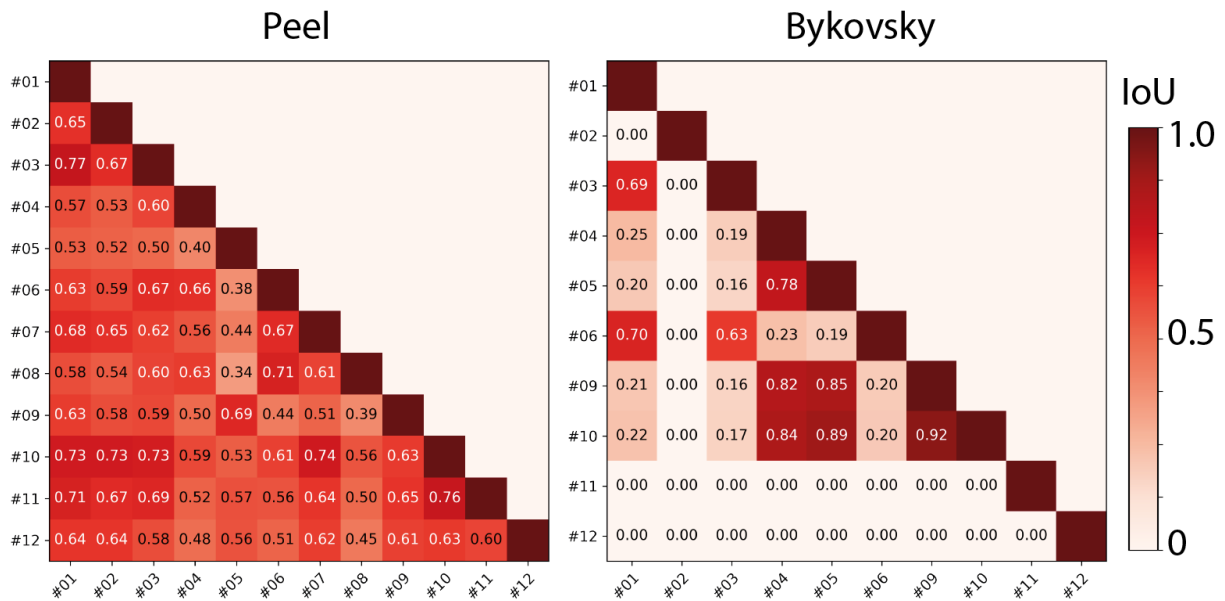
243 The third group (#s 02, 11, 12) digitized some other non-RTS features. Thus, all scores in a comparison to other
 244 participants, within this group or each of the other participants, were 0 due to no overlap (Fig 4d). All members of this
 245 group only have experience in non Siberian sites but medium to high experience in field work. Two participants (#s
 246 07, 08) rejected the digitization task in Bykovsky, due to being unsure if there are any RTS apparent. Both participants
 247 have none or little field experience.



248

249 Figure 4: a) PlanetScope satellite image of the study area as a real color composite (RGB), b) the spatial group
 250 consensus, the consensus between c) two users mapping with and without the inactive zone, with a narrow band of

251 overlap (users #01 vs. #05), and d) least matching pairs with false labeled non-RTS areas (red patches) (users #02 vs.
 252 #05).



253
 254 Figure 5: Matrix of Intersection-over-Union (IoU) results for each expert combination in the a) Peel and b) Bykovsky
 255 study sites.

256

257 Discussion

258 *Landscape settings and RTS types*

259 The labeling experiment highlighted the strong heterogeneity of digitization results of domain experts for RTS. We
 260 can therefore conclude that there is a need for a set of guiding principles and standards for consistent RTS labeling
 261 across the Arctic, as well as a need for harmonized benchmark datasets. This heterogeneity was seemingly influenced
 262 by the shape and geographic setting of the RTS, which became apparent by the differences between both study sites.
 263 While the results were more homogenous among all participants in the Peel study site, results in the Bykovsky study
 264 site were much more variable with cases of no-overlap at all for some user combinations. This can be attributed to the
 265 typical bowl shape of active RTS of the Peel site, a region familiar to most participants due to its extensive literature
 266 and visual media showcasing RTS. The Bykovsky site in contrast featured more elongated RTS with a considerable
 267 vegetated component in the disturbed footprint, which are typical for Yedoma upland slopes with baydzherakhs
 268 (residual thermokarst mounds formed due to the thawing of ice wedges) in Northeastern Siberia and Northwestern
 269 America, that are perhaps less well-known. The shape and vegetated component of these RTS are likely considerable
 270 drivers of variability among participants as these are more challenging to differentiate with undisturbed tundra.
 271 Likewise, their elongated morphology challenges the distinction between neighboring RTS features. In the Russian-
 272 language literature there is a specific-term for these elongated-shape RTS, called thermoterrace, there is no such term

273 in the English-language literature (Nesterova et al., 2024). We therefore hypothesize that the limited detection can be
274 attributed to the lack of regional knowledge and experience of several participants working on coastal RTS, but also
275 stronger exposure to these specific shapes to scientists exposed to Russian terminology.

276

277 *Local RTS morphology*

278 The second major effect that we observed in this experiment is related to the inclusion or exclusion of certain
279 morphological parts and processes of the mapped RTS. The highly active erosion zone close to the headwall was
280 included with consensus among all participants, with the exception of non-detections in Bykovsky. The consensus
281 decreased with distance from the headwall (see Figs 2c, 3c). While most participants included the non-vegetated scar
282 zone, only few included vegetated parts, such as stabilized parts of RTS. Due to the intentional lack of instructions
283 given, we expected these deviations to some extent. There were two participants previously working together in a
284 team with common labeling guidelines. This pair of researchers produced the highest overlap in the Peel region, and
285 one of the highest in Bykovsky (rank #08) showing the effect of clear instructions in previous work. Providing clear
286 instructions has been also shown to be important in medical labeling exercises (Rädsch et al., 2023). As a second
287 effect, the differences between the participants can be likely attributed to the scientific background and target
288 objectives of the participants. On the one hand, several participants with a focus on geomorphology participated. This
289 group is typically interested in the landform and its local effects and disturbance history, thus including inactive parts
290 and the full debris tongue similar to conventional landslide delineation works (Guzzetti et al., 2012). On the other
291 hand, participants with a strong focus on remotely sensed mapping of RTS typically digitized bare surfaces, which are
292 much easier to distinguish from the (disturbed) vegetated land surface in optical remote sensing data. Furthermore,
293 one participant has a strong remote sensing focus on temporal and episodic volumetric changes, and thus constrained
294 the labeled polygons to the most active area close to the headwall where subsidence or loss of volume is most easily
295 detected. The effect of choice of morphological units on the IoU is so strong, that it may mask an actually good overlap
296 in terms of number of features. Thus including the number of overlapping features is important to identify the object
297 detection performance and accuracy.

298 More knowledge of local conditions and awareness of landscape history, e.g. inactive RTS, will certainly benefit the
299 labeling performance and confidence. This can be achieved with supporting information, such as photos, geospatial
300 datasets and communication with people with local knowledge. Particularly adding visual examples and the use of
301 hillshaded DEMs can help to improve labeling quality (Rädsch et al., 2023; Van Der Sluijs et al., 2023) especially for
302 people with limited site-specific experience. Assigning labeling confidence, e.g. low, medium, high, and adding
303 further comments, can help to better quantify and understand the label quality, particularly for label data coming from
304 different groups.

305 In terms of cascading effects of inconsistent labeling, the inclusion of inactive landslide parts by some participants
306 will increase the challenge of remotely-sensed detections of RTS if done automatically, while digitizations of only
307 active RTS will vastly underreport the number (and area) of RTS on a landscape. Thirdly, volumetric changes further
308 away from the immediate headwall zone also constitute important RTS processes, which should not be missed in the
309 calculation of sediment budgets (Kokelj et al., 2021; van der Sluijs et al., 2018). Thus, the results of this work indicated

310 that differences in RTS labeling will also arise among participants depending on the purpose of the mapping effort,
311 and therefore, what the object needs to portray. These differences are not easily reconciled as an adherence to one
312 labeling standard would limit the usefulness of the labels for specific purposes mentioned. Therefore multiple specific
313 label definitions and target purposes for further application should be provided instead of defining a single standard.

314

315 *Comparison to published accuracies*

316 The best label combination results with IoU of 0.77 and F1 of 0.87 in the Peel site as well as IoU of 0.92 and F1 of
317 0.96 in the Bykovsky site, indicate the upper limits of human labeling consistency which we can expect for these sites.
318 The best matching label combinations captured the same features and only minor deviations due to differences in
319 digitization precision. The morphological differences and RTS properties (number, area, shape) between our study
320 sites also highlight the impact of landscape configuration and image content and thus upper envelope of accuracies.
321 Finally, it is expected that spatial resolution has an effect on inter-mapper (human) IoU and F1 scores, as the scores
322 observed in this study (using 3 m PlanetScope) are likely higher than if a similar experiment would be attempted with
323 Sentinel/Landsat imagery (10-30 m), or alternatively, lower than if very high resolution aerial photography and
324 hillshaded LiDAR derived DEMs would be used (Fig. S1).

325 Previous studies reported maximum IoU values of 0.58 (Nitze et al., 2021), and 0.74 (Yang et al., 2023) or F1 values
326 of 0.73 (Nitze et al., 2021), 0.75-0.85 (Witharana et al., 2022) and 0.85 (Huang et al., 2020). These previous studies
327 typically used calibration and validation data from one or a few participants, thus the maximum IoUs reported reflect
328 the degree to which DL frameworks can mimic the participants' ontological understandings and delineation tendencies.
329 Furthermore, input imagery of different types and spatial resolution complicates the comparison of accuracy metrics.
330 Those DL IoUs are not directly comparable to the human IoU's presented in this work as a range of ontological
331 understandings of RTS are directly compared, rather than against a single source of truth. The experiment's best
332 labeling consistency exceeded all published automated detections, by a slight margin. Generally we can expect human
333 consistency (best combination) as the more or less natural maximum which can be achieved with automated methods.
334 However, we expect that the manual labeling consistency can be further improved with labeling standards in place,
335 which will lead to more consistent and comparable DL mapping results and accuracy assessments.

336 With a sample of two study sites we unfortunately cannot perform a better uncertainty estimation of the maximum
337 potential performance, yet. However, the strong variation between domain experts shows the drawbacks of human
338 labeling efforts with different ontological understandings or delineation goals and rules. The conclusion from our work
339 underscores the need for caution when pooling calibration and validation data from multiple authors.

340 **Conclusion**

341 Based on our findings there is an obvious need for standards and guidelines for consistent RTS labeling across the
342 Arctic, as well as a need for harmonized benchmark datasets. With clear instructions on which RTS parts to include
343 depending on the mapping objective (e.g., only scar zone, scar zone with inactive/vegetated parts, with or without

344 debris tongue) human labeling consistency can be enhanced. Adding these instructions with visuals and examples will
345 aid the labeling process, as shown in other scientific domains (Rädsch et al., 2023).

346 The decision on which parts to include should be carefully based on existing RTS landform and process literature, as
347 few mapping and reporting objectives will be met if RTS descriptions are limited to what can be remotely sensed
348 through automated procedures (i.e., bare surfaces). Furthermore, it is important that RTS benchmarking datasets are
349 carefully reviewed by experienced geomorphologists and ecologists to ensure that a field-based understanding of
350 landform, process, and environmental impact forms the basis on which any future automated detection effort through
351 remote sensing is built.

352 Creating these guidelines is one of the main deliverables of the RTSInTrain Action group with the International
353 Permafrost Association (IPA). After having specific guidelines we plan to conduct another experiment and compare
354 the results to the initial experiment. Overall, conducting this experiment provided us with a great insight of the RTS
355 labeling process used in past and more current works, and how a diverse group of domain experts thinks about what
356 to label. This will directly lead to the community driven standardization of this process to create consistent labeled
357 datasets, which are essential to train representative DL models.

358

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372

373 **Data**

374 Due to licensing restrictions, we are not allowed to publicly share the commercial PlanetScope input data sources.

375 **Code**

376 https://github.com/initze/RTSIn_experiment (currently private repository) - ask Ingmar (ingmar.nitze@awi.de) to be
377 added

378

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Supplement to:

A labeling intercomparison of retrogressive thaw slumps by a diverse group of domain experts

Nitze et al.

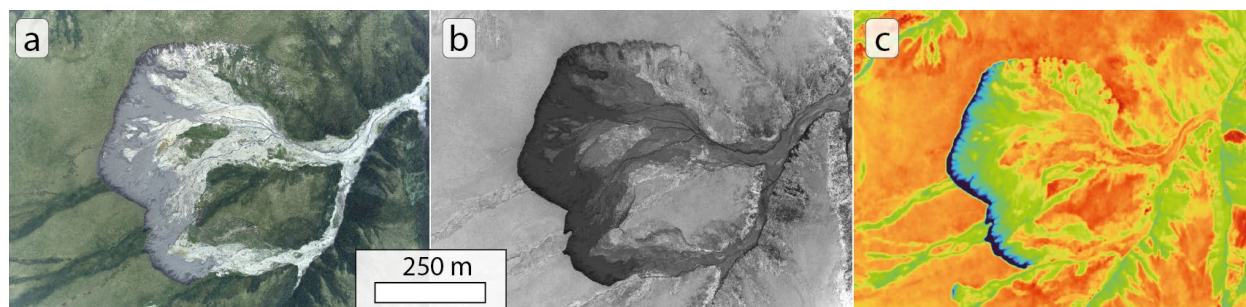


Figure S1: Aerial imagery of the large RTS in the Peel site in a) Real-color, b) Near-infrared, and c) thermal-infrared, acquired on 2023-07-07. Imagery acquired during AWI PermaX23 aerial imaging campaign.



Figure S2: Oblique aerial image of the large RTS in the Peel site, acquired on 2023-07-07. Imagery acquired during AWI PermaX23 aerial imaging campaign. Photo: I.Nitze



Figure S3: Upper part of the coastal RTS with vegetation cover in the stabilized part, complex of vegetation and bare soil in the scar zone and ice-rich headwall on Bykovsky Peninsula in the study area taken in Summer 2016. Photo A.Kizyakov. See persons for scale.



Figure S4: RTS base with visible vegetation in stabilized parts and headwall with overhanging peat cover on Bykovsky Peninsula in the study area taken on 2014-08-21. Person for scale. Photo I.Nitze

SUPPLEMENTARY TABLE TS1

LIST OF PARTICIPATING EXPERTS AND THEIR SCIENTIFIC BACKGROUND, FIELDWORK EXPERIENCE AND MAIN OBJECTIVES

creator_id	Scientific Background (Topic)	Field Experience	Spatial focus regions	Thematic Focus	Affiliation Region
#01	Physical Geography, Remote Sensing, Geoinformatics	medium	Arctic	Mapping (2D)	Central Europe
#02	Earth Science, Geoinformatics	medium	Tibetan Plateau, Arctic	Mapping (2D)	North America / East Asia
#03	Physical Geography	little	Russia/Siberia	Mapping (2D)	Central Europe
#04	Physical Geography	high	Russia/Siberia	Geomorphology	Russia
#05	Physical Geography	medium	Russia/Siberia	Geomorphology	Central Europe / Russia
#06	Earth Science, Geospatial Data Science, Remote Sensing	none	Arctic	Mapping (2D)	North America
#07	Remote Sensing	little	Tibetan Plateau	Mapping (2D)	East Asia
#08	Physics	none	Arctic	Mapping (3D)	Central Europe

#09	Physical Geography, Remote Sensing	high	Canada	Geomorph. + Mapping	North America
#10	Geography, Earth Observation and Geo-Information Science	little	Russia/Siberia	Mapping (2D)	Central Europe
#11	Ecology and Remote Sensing	high	Alaska	Geomorphology	North America
#12	Physical Geography	high	Canada	Geomorphology	North America

SUPPLEMENTARY TABLE TS-2

OVERVIEW OF RESULTS FOR ALL EXPERT LABELING COMBINATIONS IN THE PEEL STUDY SITE

Link: [Peel correlation summary.html](#) (formatted table, please download and open in browser)

SUPPLEMENTARY TABLE TS-3

OVERVIEW OF RESULTS FOR ALL EXPERT LABELING COMBINATIONS IN THE BYKOVSKY STUDY SITE

Link: [Bykovsky correlation summary.html](#) (formatted table, please download and open in browser)

Zipped archives of data analysis output (figures)

Peel (308MB):

https://drive.google.com/file/d/1I0qo08rs23zMf9MKcPORxA34hERq_Q0f/view?usp=sharing

Bykovsky (240MB):

https://drive.google.com/file/d/1Hqkch9ZOourVIT1shQ6_nmDkaY55W6Wa/view?usp=sharing

Code for data analysis and figures

https://github.com/initze/RTSIn_experiment