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A Labeling Intercomparison of Retrogressive Thaw Slumps by a Diverse Group of Domain Experts

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ABSTRACT

Deep-learning (DL) models have become increasingly beneficial for the detection of retrogressive thaw slumps (RTS) in the permafrost domain. However, comparing accuracy metrics is challenging due to unstandardized labeling guidelines. To address this, we conducted an experiment with 12 international domain experts from a broad range of scientific backgrounds. Using 3 m PlanetScope multispectral imagery, they digitized RTS footprints in two sites. We evaluated label uncertainty by comparing manually outlined RTS labels using Intersection-over-Union (IoU) and F1 metrics. At the Canadian Peel Plateau site, we see good agreement, particularly in the active parts of RTS. Differences were observed in the interpretation of the debris tongue and the stable vegetated sections of RTS. At the Russian Bykovsky site, we observed a larger mismatch. Here, the same differences were documented, but several participants mistakenly identified non-RTS features. This emphasizes the importance of site-specific knowledge for reliable label creation. The experiment highlights the need for standardized labeling procedures and definition of their scientific purpose. The most similar expert labels outperformed the accuracy metrics reported in the literature, highlighting human labeling capabilities with proper training, site knowledge, and clear guidelines. These findings lay the groundwork for DL-based RTS monitoring in the pan-Arctic.

1 | Introduction

The northern high latitudes are affected by a rapidly changing climate [1, 2] with further warming and wetting expected over the coming decades [3]. This will have an impact on vulnerable permafrost landscapes, with a potential increase in permafrost thaw and degradation. Many regions with ice-rich ground are already affected by hillslope thermokarst, such as retrogressive thaw slumps (RTS). RTS are dynamic geomorphological mass-wasting features prevalent across ground-ice-rich permafrost regions around the Arctic and Qinghai-Tibetan Plateau. The landform is triggered by thawing and collapsing ice-rich ground, which continues to propagate upslope via the process of ice ablation [4]. RTS are typically confined to regions with ice-rich permafrost. RTS as a geomorphological feature, contain distinct parts, such as a headwall, scar zone, and debris tongue (Figure 1). Their size can range from a few m^2 to approximately 2 km^2. They are temporally variable and often exhibit polycyclic (e.g., recurring over time) dynamics [5, 6], which are influenced by weather, climate, and local geomorphological conditions. In most cases, they are located close to water bodies, such as rivers, seacoasts, or lake shores, as well as dynamic morphological gradients, such as valleys and slopes. In their immediate vicinity and in downstream environments they can have a strong impact on hydrology, geomorphology, and various biogeochemical cycles [7]. With drastically changing climate in the arctic and high-mountain regions, RTS dynamics have rapidly accelerated over the past decades as determined through manual mapping approaches [8–11].

Conventional mapping initiatives for RTS rely heavily on manual mapping and detailed local geomorphological knowledge and/or semi-automated mapping approaches [6–8, 12–14]. The science community has just begun to produce pan-Arctic datasets of mapped RTS [15] as more automated, machine learning (ML), or deep learning (DL) based approaches have become popular over the past decade [16, 17]. In combination with large improvements in the availability of satellite imagery [18] and computational power, such as cloud- or high performance computing, fine-resolution large-domain products are now possible. Typically, most DL workflows are supervised approaches, requiring a high quantity and quality of manually produced training labels [19]. However, the availability and usability of labels acquired across various spatial, spectral, and temporal scales is still limited as of now. Therefore, manual labeling has often been used to increase the number of training labels in DL applications. As many labels are required (preferably in the thousands), distributing this work within a team or even across an entire science community becomes an important and necessary step for scaling. To support effective community-wide label synthesis, clear definitions and guidelines on how to label target features are required. In addition, efforts to evaluate the label variability among analysts will be critical to maintain data quality and consistency [20]. While anthropogenic objects, such as buildings or airplanes have distinct and clear boundaries and well-understood ontologies, natural object boundaries are much more variable and often ambiguous or dependent on the particular use case and definition. Particularly labeling dynamic geomorphological features that initiate and expand over time, such as RTS, is often challenging due to variable atmospheric (e.g., haze, clouds, and smoke) and environmental conditions (e.g., plant pheno-period and soil moisture availability). Beyond these externally changing conditions, inherent RTS processes during initiation (e.g., vegetation removal and exposure of bare earth), growth (e.g., mud slurries and expanding boundaries), and stabilization (revegetation) means that a RTS as a landform can appear very differently through time, affecting its abstract representation and consistency of DL labeling efforts.

FIGURE 1 | Oblique aerial image of a typical bowl-shaped retrogressive thaw slump (RTS) in NW Canada (67.2588°, −135.2453°). Typical labeling strategies indicated: (1) only highly active regions close to the headwall in green, (2) active areas with wet bare soils including headwall and scar zone in light yellow, (3) RTS scar zone including inactive and vegetated parts in orange, and (4) complete RTS including debris tongue in red. Photo: J. Van der Sluijs. [Colour figure can be viewed at wileyonlinelibrary.com]

With the increasing popularity of DL [21, 22], label availability and quality become an increasingly important topic. Over the past decades, the permafrost and RTS research community have increased in diversity from traditional earth science and geomorphology people to a broader group, with different domain backgrounds such as ecology, remote sensing, and computer science. Experience in field work has also diversified, which may influence labeling consistency and quality. Thus, the scope of RTS research has also broadened to more diverse objectives and analyses such as large-scale mapping, change detection, and environmental impacts, which may lead to different definitions or classifications of which parts belong to an RTS.

Recent DL initiatives for mapping RTS across different locations within the permafrost extent, such as Siberia [23], Tibetan Plateau [24–26], Northern Canada [27], various localities across the Arctic [28], or the entire Arctic [15], used different methods and imagery sources, to train and validate their models. For example, [24–28] created their own hand-drawn labels, while [23] used a combination of newly hand-drawn labels and already existing external sources [28]. However, they all achieved accuracy metrics using IoU (Intersection over Union), which ranged from low to very good agreement: 0.15–0.58 [28], 0.71–0.74 [23] or F1 of 0.25–0.73 [28], 0.85 [25] and 0.75–0.85 [27]. As these values are relative to validation data based on self-created hand-drawn labels, and not independent benchmark datasets, accuracy metrics are difficult to compare across methods and geographical regions. Using different image sources further complicates the comparison of the different studies. Furthermore, sampling strategies (e.g., grid, random, stratified, and manual) exacerbate the difficulties of comparing RTS segmentation studies as landscapes produce a wide variety of RTS expressions due to differing topographical, sub-surface, and climate settings. This could result in undersampling of particular RTS morphologies and activity levels (e.g., small, lakeside RTS or large inactive RTS landforms) that limit the generalizability of DL frameworks when these are applied outside of the domain area and may lead to false predictions. As one of the end goals of remotely sensed detection and delineation is to inform scientists, practitioners, and communities of new RTS locations or RTS growth, false negatives/positives or differing delineations may be artifacts of disparate methods and slump ontology rather than actual change [10]. These model artifacts can have considerable implications when DL output products are subsequently used for landscape vulnerability assessments such as RTS growth forecasts, or upscaling environmental impacts to larger areas (e.g., carbon/methane).

Compared with other domains, such as everyday imagery with *imagenet* [29] or *BigEarthNet* for standard earth observation imagery [30], there is neither a benchmark set for RTS boundaries nor any intercomparison of RTS labeling results between domain experts to better understand the variability of human-derived training data in the context of RTS mapping efforts using DL. To determine the necessity and properties of such benchmark datasets, we set up an experiment to let domain experts manually label RTS boundaries within satellite imagery and evaluate the degree of agreement or disagreement among them. Such experiments have been conducted for a few other domains such

as terrestrial [31] or subaqueous [32] landslides. The availability of clear instructions, visual examples, and professional labeling experience has helped to improve the label quality of biomedical images [19].

Here, we specifically evaluate the consistency and accuracy of labels between 12 international domain experts from various backgrounds, who are all contributors to the International Permafrost Association (IPA) action group on RTS (RTSInTrain). From these results, we infer the potential impact on efforts to harmonize and pool pan-Arctic scale training and validation datasets as well as past and future DL-based RTS mapping efforts.

2 | Data and Study Sites

2.1 | Data

For this experiment, we used two study sites: one on the Peel Plateau in Northwestern Canada and a second on the Bykovsky Peninsula close to the Lena Delta in Northeast Siberia (Figure 2). Both sites contain the target landscape features, RTS of different sizes, and are located in different landscape settings. These specific sites were chosen as they represent different types of RTS morphologies and landscape settings. As the main data source, we used PlanetScope [33] multispectral imagery OrthoTiles, with a spatial resolution of 3.15 m per pixel and four spectral bands (blue, green, red, and near-infrared). We used single acquisitions for each site. The scenes were acquired on 2021-08-04 (OrthoTile 4763844_0870513_2021-08-04_2416) for Peel and 2021-07-21 for Bykovsky (OrthoTile 4713120_5272315_2021-07-21_2463) and represent cloud-free and good-quality images. Both scenes were clipped to a size of 2.5 × 2.5 km to minimize the labeling efforts and maximize participation of volunteers. To support digitization, we added the ArcticDEM [34] as well as lower spatial resolution Landsat-8 with 30 m and Sentinel-2 with 10 m spatial resolution.

2.2 | Study Sites

The Peel site is located on the Peel Plateau at 68.052°N 135.668°W in the Beaufort Delta region of Northwestern Canada (Figure 2a). This region is located in a formerly glaciated area [9, 12] with distinct terrain morphology of hills and valleys. The terrain is pronounced with deeply incised valleys and an elevation range of 250 to 500 m. The Peel Plateau is in the tundra-taiga ecotone. Active RTS in this area have a typical round bowl-like shape, and a large scar zone with significant volumes of thawed debris, which partially fill the valley downstream (see Figure 2a-I, Figures S1–S2) [7]. In the Beaufort Delta region, the location and morphology of active RTS are closely linked to inactive RTS whereby the majority of active thaw slumping processes have occurred in association, or within the footprint, of past disturbances [10]. This region has been subject to a substantial amount of research [7, 9, 12, 35, 36] and is well known to the RTS research community.

The Bykovsky site is located at 71.881°N 129.293°E on the Bykovsky Peninsula on the Laptev Sea coast southeast of the
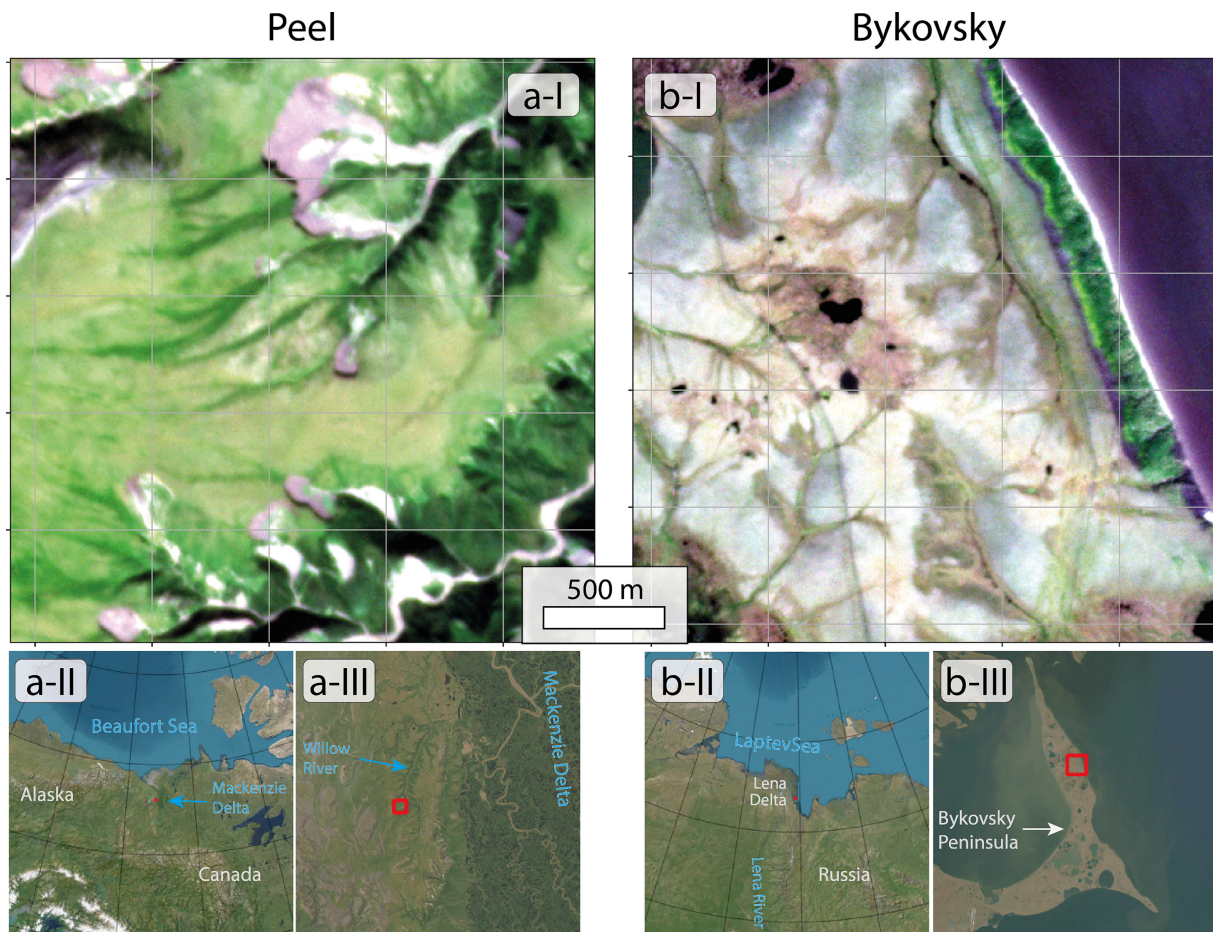
FIGURE 2 | PlanetScope Satellite images of the study sites (a) Peel and (b) Bykovsky as a real color composite (RGB) with 3.15 m nominal spatial resolution, and with overview maps (a/b-II/III) of the locations. Background map: ESRI Satellite. [Colour figure can be viewed at wileyonlinelibrary. com]

Lena Delta in Northeastern Siberia (Figure 2b). Permafrost here is dominated by late Pleistocene syngenetic ice-rich Yedoma Ice Complex deposits with a thickness of up to 50 m [37]. In contrast to the Peel site, this area has not been glaciated, and the cryostructure of deposits is different and characterized by the large polygonal ice wedges. RTS along this coastline typically have an elongated shape and mostly contain a narrow scar zone along the top slope, known as thermodenudation [38], and a stabilized, vegetated zone in the middle and lower slopes (Figure 2b-I, Figures S3–S4). The vegetation is dominated by sparse tundra with differences between undisturbed tundra and recently disturbed areas, such as stabilized RTS scar zones. The terrain is undulating with elevation from sea level to approximately 40 m. This region has been subject to few past studies in the context of slumping and coastal dynamics [38–41].

3 | Methods

Twelve domain experts, who are all members of the International Permafrost Association (IPA) funded action group on RTS (RTSInTrain), volunteered to participate in this experiment. They have different scientific backgrounds such as geomorphologists, geologists, remote sensing scientists to computer scientists. Furthermore, the current scientific focus varied from geomorphological analysis, to mapping spatial and/or volume changes. Participants come from different countries (Germany, Russia, Canada, United States, China, and Switzerland) and have variable experience of RTS fieldwork from none to extensive (see Table S1). The participants' spatial focus and experience also varied strongly from single-specific regions, such as NW Canada or Tibetan Plateau, to pan-Arctic. For the analysis, we anonymized the participants names and assigned each one a random number between 1 and 12 (#01 to #12).

3.1 | Digitization

The participants were requested to manually digitize RTS using a GIS software of their choice and on the provided imagery. The PlanetScope image was supposed to be used as the main labeling source. We further provided the ArcticDEM elevation model and the temporally nearest Landsat and Sentinel-2 scenes. We requested that participants cover each identified RTS by a polygon geometry. We did not provide further instructions to better understand and quantify the individual differences in the absence of specific rulesets (e.g., how to label RTS based on specific geomorphic features).

3.2 | Evaluation

For quantifying the similarity, we used standard remote sensing and image segmentation metrics, such as Intersection-over-Union, F1, precision and recall. Typically, these metrics are used to validate a prediction versus a ground truth. In our case, we validated all unique output combinations against each other. For this, we used the digitized vector files and calculated the metrics using the *geopandas* python package. All geospatial data were projected in the respective local UTM zone, Peel in zone 8N (EPSG:32608) and Bykovsky in zone 52N (EPSG:32652).

4 | Results

4.1 | Peel Plateau

In the Peel Plateau (Figure 3) the participants generally identified the same RTS and digitized similar features. The number of identified individual objects ranged from 7 to 11, with a mode (highest frequency) of 8 and 11 RTS labeled by three people each.

The mean $\pm$ standard deviation IoU Score is 0.59 ± 0.09 ranging from 0.77 to 0.34 for individual label pairs (Figure 5a). The F1 score is on average 0.74 ± 0.08 and ranges from 0.87 to 0.51. Detailed analysis of each individual combination is provided in Table S2. The best combination was achieved by participants #01 and #03, which happens to be part of the same scientific organization and with internal digitization guidelines in place based on past initiatives (Figure 3c).

In this region, differences arise in the digitization of specific features within RTS. All participants digitized the apparently active part close to the headwall with freshly exposed soil and debris. Differences become apparent in the lower parts, most notably the scar zone, which was digitized by almost all participants (11 of 12). The debris tongue and flows were only included by three (#s 05, 09, and 12) of 12 participants. Inactive parts were also treated differently (Figure 3d). Minor differences in label agreement also appear due to slight differences in user created geometries even though digitizing the same feature, for example, the headwall (Figure 3c). The visual differences in Figure 3b showcase the differences in geomorphological interpretation.
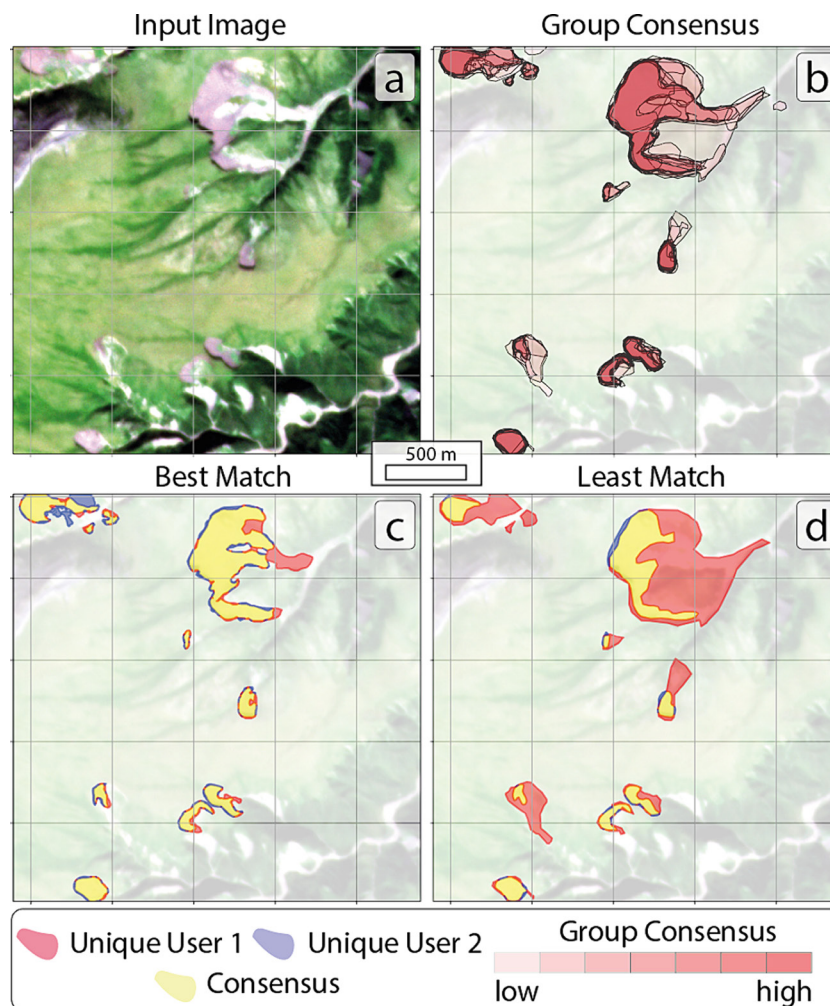

FIGURE 3 | (a) PlanetScope satellite image of the study area as a real color composite (RGB), (b) the spatial group consensus, the consensus between (c) the best matching (users #03 vs. #01), and (d) least matching pairs (users #05 vs. #08). [Colour figure can be viewed at wileyonlinelibrary. com]

4.2 | Bykovsky

In Bykovsky (Figure 4), the RTS mapping experiment resulted in considerably different observations than the Peel site with on average less overlap and a lot more variance. The total number of identified individual RTS objects ranged from 1 to 11, with a mode of one large single RTS labeled by four out of 10 people. The mean IoU Score is 0.21 ± 0.31 ranging from 0.92 to 0 (Figure 5b). The F1 score, which is on average 0.26 ± 0.34 ranges from 0.96 to 0. Generally, the results come in three clusters. Cluster 1 recognized the RTS, which are in a terraced shape, and digitized the active scar zone and additionally the stabilized, vegetated parts (Figure 4b,c). The four participants who followed this strategy (#s 04, 05, 09, and 10), have high similarity scores/metrics (IoU 0.78–0.92). Similarly, there is a second group (#s 01, 03, and 06), who homogeneously digitized only the active scar zones, which results in high similarity within this group (IoU 0.63–0.7). While three of four members of the first group typically have a focus on geomorphology and landform analysis, all members of the second group have a strong focus on mapping RTS (see Table S1). Scores between group 1 and 2 are comparably low with IoU from 0.16 to 0.25 due to the large extent of the stabilized zone, although both groups detected the same general features (Figure 4c), which are spatially intersecting. Instead of one large object, common among group 1, members of the second group labeled smaller, but a higher number of individual objects, typically 4 or 5, in one case 11. Detailed analysis of each individual combination is provided in Table S3.

The third group (#s 02, 11, and 12) digitized some other non-RTS features. Thus, all scores in a comparison to other participants, within this group or each of the other participants, were 0 due to no overlap (Figure 4d). All members of this group only have experience in non-Siberian sites but medium to high experience in field work. Two participants (#s 07 and 08) rejected the digitization task in Bykovsky, due to being unsure if there are any RTS apparent. Both participants have none or little field experience.

5 | Discussion

5.1 | Landscape Settings and RTS Types

The labeling experiment highlighted the strong heterogeneity of digitization results of domain experts for RTS. We can therefore conclude that there is a need for a set of guiding principles and

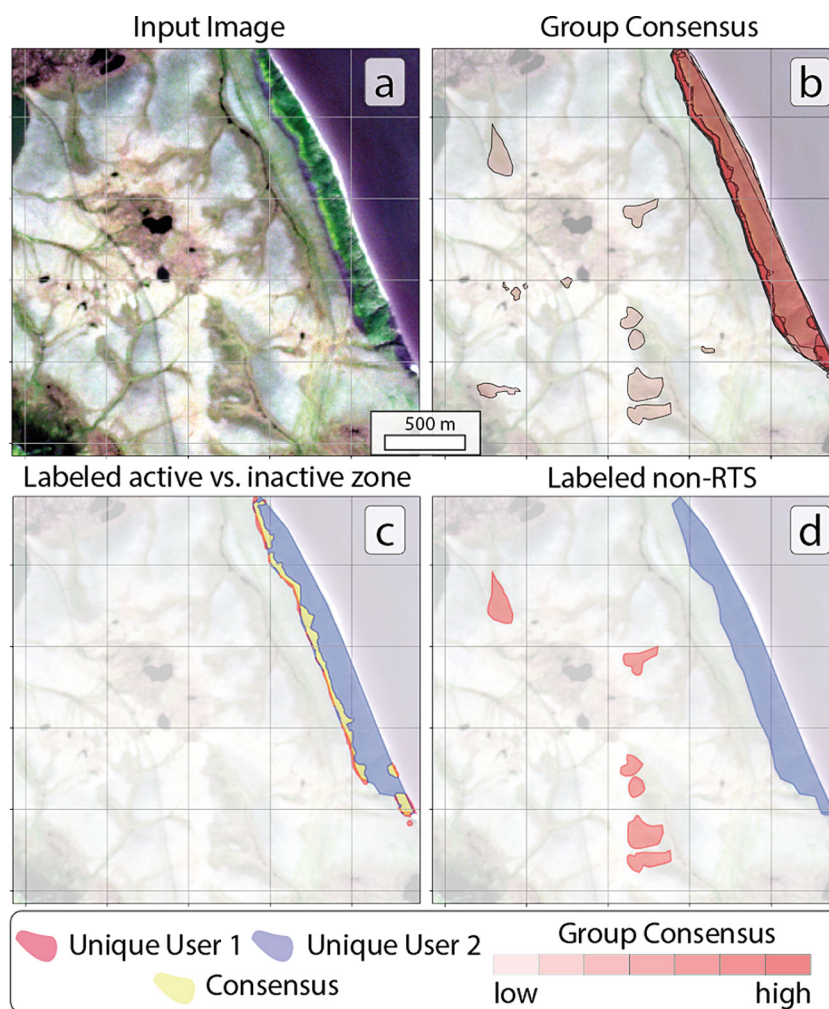**FIGURE 4** | (a) PlanetScope satellite image of the study area as a real color composite (RGB), (b) the spatial group consensus, the consensus between (c) two users mapping with and without the inactive zone, with a narrow band of overlap (users #01 vs. #05), and (d) least matching pairs with false labeled non-RTS areas (red patches) (users #02 vs. #05). [Colour figure can be viewed at wileyonlinelibrary.com]
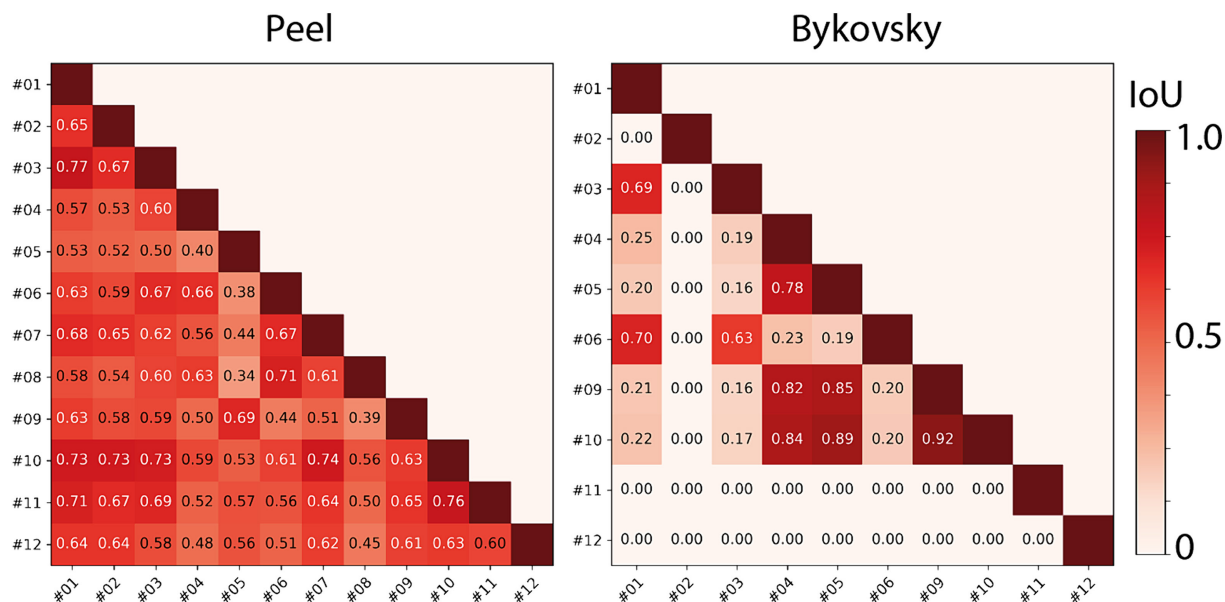
FIGURE 5 | Matrix of Intersection-over-Union (IoU) results for each expert combination in the (a) Peel and (b) Bykovsky study sites. [Colour figure can be viewed at wileyonlinelibrary.com]

standards for consistent RTS labeling across the Arctic, as well as a need for harmonized benchmark datasets. This heterogeneity was seemingly influenced by the shape and geographic setting of the RTS, which became apparent by the differences between both study sites. While the results were more homogenous among all participants in the Peel study site, results in the Bykovsky study site were much more variable with cases of no-overlap at all for some user combinations. This can be attributed to the typical bowl shape of active RTS of the Peel site, a region familiar to most participants due to its extensive literature and visual media showcasing RTS. The Bykovsky site in contrast featured more elongated RTS with a considerable vegetated component in the disturbed footprint, which are typical for Yedoma upland slopes with baydzherakhs (residual thermokarst mounds formed due to the thawing of ice wedges) in Northeastern Siberia and Northwestern America, that are perhaps less well-known. The shape and vegetated component of these RTS are likely considerable drivers of variability among participants as these are more challenging to differentiate with undisturbed tundra. Likewise, their elongated morphology challenges the distinction between neighboring RTS features. In the Russian-language literature, there is a specific term for these elongated-shape RTS, called thermoterrace; there is no such term in the English-language literature [42]. We therefore hypothesize that the limited detection can be attributed to the lack of regional knowledge and experience of several participants working on coastal RTS, but also stronger exposure to these specific shapes to scientists exposed to Russian terminology.

5.2 | Local RTS Morphology

The second major effect that we observed in this experiment is related to the inclusion or exclusion of certain morphological parts and processes of the mapped RTS. The highly active erosion zone close to the headwall was included with consensus among all participants, with the exception of non-detections

in Bykovsky. The consensus decreased with distance from the headwall (see Figures 2c and 3c). While most participants included the non-vegetated scar zone, only few included vegetated parts, such as stabilized parts of RTS. Due to the intentional lack of instructions given, we expected these deviations to some extent. There were two participants previously working together in a team with common labeling guidelines. This pair of researchers produced the highest overlap in the Peel region, and one of the highest in Bykovsky (rank #08) showing the effect of clear instructions in previous work. Providing clear instructions has been also shown to be important in medical labeling exercises [19]. As a second effect, the differences between the participants can be likely attributed to the scientific background and target objectives of the participants. On the one hand, several participants with a focus on geomorphology participated. This group is typically interested in the landform and its local effects and disturbance history, thus including inactive parts and the full debris tongue similar to conventional landslide delineation works [31]. On the other hand, participants with a strong focus on remotely sensed mapping of RTS typically digitized bare surfaces, which are much easier to distinguish from the (disturbed) vegetated land surface in optical remote sensing data. Furthermore, one participant has a strong remote sensing focus on temporal and episodic volumetric changes and thus constrained the labeled polygons to the most active area close to the headwall where subsidence or loss of volume is most easily detected. The effect of choice of morphological units on the IoU is so strong that it may mask an actually good overlap in terms of number of features. Thus, including the number of overlapping features is important to identify the object detection performance and accuracy.

More knowledge of local conditions and awareness of landscape history, for example, inactive RTS, will certainly benefit the labeling performance and confidence. This can be achieved with supporting information, such as photos (e.g., Figures S2–S4), very high resolution aerial (e.g., Figure S1) or satellite imagery,

additional geospatial datasets, such as elevation data, and communication with people with local knowledge. Particularly adding visual examples and the use of hillshaded DEMs can help to improve labeling quality [10, 19] especially for people with limited site-specific experience. Assigning labeling confidence, for example, low, medium, high, and adding further comments, can help to better quantify and understand the label quality, particularly for label data coming from different groups. However, the availability of additional data sources, particularly in very high resolution, is often limited.

In terms of cascading effects of inconsistent labeling, the inclusion of inactive landslide parts by some participants will increase the challenge of remotely-sensed detections of RTS if done automatically, while digitizations of only active RTS will vastly underreport the number (and area) of RTS on a landscape. Thirdly, volumetric changes further away from the immediate headwall zone also constitute important RTS processes, which should not be missed in the calculation of sediment budgets [7, 43]. Thus, the results of this work indicated that differences in RTS labeling will also arise among participants depending on the purpose of the mapping effort, and therefore, what the object needs to portray. These differences are not easily reconciled as an adherence to one labeling standard would limit the usefulness of the labels for specific purposes mentioned. Therefore, multiple specific label definitions and target purposes for further application should be provided instead of defining a single standard.

5.3 | Comparison to Published Accuracies

The best label combination results with IoU of 0.77 and F1 of 0.87 in the Peel site as well as IoU of 0.92 and F1 of 0.96 in the Bykovsky site, indicate the upper limits of human labeling consistency which we can expect for these sites. The best matching label combinations captured the same features and only minor deviations due to differences in digitization precision. The morphological differences and RTS properties (number, area, shape) between our study sites also highlight the impact of landscape configuration and image content and thus upper envelope of accuracies. Finally, it is expected that spatial resolution has an effect on inter-mapper (human) IoU and F1 scores, as the scores observed in this study (using 3 m PlanetScope) are likely higher than if a similar experiment would be attempted with Sentinel/Landsat imagery (10–30 m), or alternatively, lower than if very high resolution aerial photography and hillshaded LiDAR derived DEMs would be used (Figure S1).

Previous studies reported maximum IoU values of 0.58 [28], and 0.74 [23] or F1 values of 0.73 [28], 0.75–0.85 [27] and 0.85 [25]. These previous studies typically used calibration and validation data from one or a few participants; thus, the maximum IoUs reported reflect the degree to which DL frameworks can mimic the participants' ontological understandings and delineation tendencies. Furthermore, input imagery of different types and spatial resolution complicates the comparison of accuracy metrics. Those DL IoUs are not directly comparable to the human IoU's presented in this work as a range of ontological understandings of RTS are directly compared, rather than against a single source of truth. The experiment's best labeling consistency exceeded all published automated detections, by a slight margin. Generally,

we can expect human consistency (best combination) as the more or less natural maximum, which can be achieved with automated methods. However, we expect that the manual labeling consistency can be further improved with labeling standards in place, which will lead to more consistent and comparable DL mapping results and accuracy assessments.

With a sample of two study sites, we unfortunately cannot perform a better uncertainty estimation of the maximum potential performance, yet. However, the strong variation between domain experts shows the drawbacks of human labeling efforts with different ontological understandings or delineation goals and rules. The conclusion from our work underscores the need for caution when pooling calibration and validation data from multiple authors.

6 | Conclusion

Based on our findings there is an obvious need for standards and guidelines for consistent RTS labeling across the Arctic, as well as a need for harmonized benchmark datasets. With clear instructions on which RTS parts to include depending on the mapping objective (e.g., only scar zone, scar zone with inactive/vegetated parts, with or without debris tongue) human labeling consistency can be enhanced. Adding these instructions with visuals and examples will aid the labeling process, as shown in other scientific domains [19].

The decision on which parts to include should be carefully based on existing RTS landform and process literature, as few mapping and reporting objectives will be met if RTS descriptions are limited to what can be remotely sensed through automated procedures (e.g., bare surfaces). Furthermore, it is important that RTS benchmarking datasets are carefully reviewed by experienced geomorphologists and ecologists to ensure that a field-based understanding of landform, process, and environmental impact forms the basis on which any future automated detection effort through remote sensing is built.

Creating these guidelines is one of the main deliverables of the RTSInTrain Action group with the International Permafrost Association (IPA). After having specific guidelines we plan to conduct another experiment and compare the results to the initial experiment. Overall, conducting this experiment provided us with a great insight of the RTS labeling process used in past and more current works, and how a diverse group of domain experts thinks about what to label. This will directly lead to the community-driven standardization of this process to create consistent labeled datasets, which are essential to train representative DL models.

Data Availability Statement

Due to licensing restrictions, we are not allowed to publicly share the commercial PlanetScope input data sources. The input data, the hand-digitized labels, and analysis notebook are available in a publicly available github repository: https://github.com/initze/RTS_digitization_experiment.

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Supporting Information

Additional supporting information can be found online in the Supporting Information section.