

# Prediction in Ungauged Basins with Long Short-Term Memory Networks

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## Key Points:

- Overall accuracy of LSTMs in ungauged basins is comparable to standard hydrology models in gauged basins
- There is sufficient information in catchment characteristics data to differentiate between catchment-specific rainfall-runoff behaviors

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**Abstract**

Long Short-Term Memory (LSTM) networks offer unprecedented accuracy for prediction in ungauged basins. We trained and tested an LSTM on the CAMELS basins (approximately 30 years of daily rainfall/runoff data from 531 catchments in the US of sizes ranging from 4  $km^2$  to 2,000  $km^2$ ) using k-fold validation, so that predictions were made in basins that supplied no training data. This effectively ‘ungauged’ model was benchmarked over a 15-year validation period against the Sacramento Soil Moisture Accounting (SAC-SMA) model and also against the NOAA National Water Model reanalysis. SAC-SMA was calibrated separately for each basin using 15 years of daily data (i.e., this is a ‘gauged’ model). The out-of-sample LSTM had higher median Nash-Sutcliffe Efficiencies across the 531 basins (0.69) than either the calibrated SAC-SMA (0.64) or the National Water Model (0.58). We outline several future research directions that would help develop this technology into a comprehensive regional hydrology model.

**1 Introduction**

We are firmly in the age of Machine Learning (ML). ML models currently out-perform state-of-the-art techniques at some of the most sophisticated domain problems across the Natural Sciences (e.g., AlQuraishi, 2019; He et al., 2019; Liu et al., 2016; Mayr, Klambauer, Unterthiner, & Hochreiter, 2016). In Hydrology, the first demonstration of ML out-performing a process-based model that we are aware of was by Hsu et al. (1995), who compared a calibrated Sacramento Soil Moisture Accounting Model (SAC-SMA) against a feed-forward artificial neural network across a range of flow regimes. More recently, Nearing et al. (2018) compared neural networks against the half-hourly surface energy balance of several hydrometeorological models used operationally by several international weather and climate forecasting agencies, and showed that the former generally out-performed the latter at out-of-sample FluxNet sites. Kratzert et al. (2019) showed that regionally-trained Long Short-Term Memory Networks (LSTMs) out-perform basin-specific calibrations of several traditional hydrology models.

There has been a long-standing discussion in the field about the relative merits of data-driven vs. process-driven models (e.g., Klemeš, 1986). In their summary of a recent workshop on ‘Big Data and the Earth Sciences’ Sellars (2018) noted that “*Many participants who have worked in modeling physical-based systems continue to raise caution about the lack of physical understanding of machine learning methods that rely on data-driven approaches.*” It is often argued that data-driven models have the potential to under-perform relative to models that include explicit process representations in conditions that are dissimilar to training data (e.g., Kirchner, 2006; Milly et al., 2008; Vaze, Chiew, Hughes, & Andréassian, 2015). While this may be true, in any case where an ML model *does* out-perform against a process-based model we can conclude that the process-based model does not take advantage of the full information content of the input/output data (Nearing & Gupta, 2015). At the very least, such cases indicate that there is potential to improve the process-based model. In the Discussion section (*Section 5*) of this technical note we offer some thoughts about how the community might leverage the unprecedented ability of modern ML algorithms to find useful patterns and information in data with the decades of domain science that supports our current hydrological simulation models.

One of the situations where the accuracy of out-of-sample predictions matter is for Prediction in Ungauged Basins (PUB). PUB was the decadal problem of the International Association of Hydrological Sciences (IAHS) from 2003-2012 (Hrachowitz et al., 2013; Sivapalan et al., 2003). State-of-the-art regionalization, parameter transfer, catchment similarity, and surrogate catchment techniques (e.g., Parajka et al., 2013; Razavi & Coulibaly, 2012; Samaniego et al., 2017) result in streamflow predictions that are significantly less accurate than from models calibrated individually in gauged catchments.

66 Current community best-practices for PUB center fundamentally around obtaining de-  
 67 tailed local knowledge of a particular basin (Blöschl, 2016), which is expensive for in-  
 68 dividual catchments and impossible for large-scale (e.g., continental) simulations like those  
 69 from the US National Water Model (NWM) (Salas et al., 2018) or the streamflow com-  
 70 ponent of the North American Land Data Assimilation System (NLDAS) (Xia et al., 2012).  
 71 Moreover, reliable streamflow predictions from lumped catchment models typically re-  
 72 quire at least two to three years of gauge data for calibration (Vrugt et al., 2006). PUB  
 73 remains an important challenge because the majority of streams in the world are either  
 74 ungauged or poorly gauged (Goswami, Oconnor, & Bhattarai, 2007; Sivapalan, 2003),  
 75 and the number of gauged catchments, even in the US, is shrinking (Fekete et al., 2015).

76 In this technical note, we demonstrate an ML strategy for PUB. Our results show  
 77 that out-of-sample LSTMs out-perform, on average, a conceptual model calibrated in-  
 78 dependently for each catchment (SAC-SMA), and also a distributed process-based model  
 79 (NWM). The purpose of this demonstration is twofold. First, to show that there is suf-  
 80 ficient information in the available hydrological data record to provide meaningful pre-  
 81 dictions in ungauged basins - at least a significant portion of the time. Second, to show  
 82 that ML offers a promising path forward for PUB. The current authors are unaware of  
 83 any existing model that performs as well on average as the LSTMs that we demonstrate  
 84 here in ungauged basins. At the end of this technical note we offer some thoughts - both  
 85 philosophical and practical - about future work that could be done to advance the util-  
 86 ity of ML in a complex systems science like Hydrology.

87 To state our primary findings succinctly, ML in *ungauged basins* out-performs, on  
 88 average (i.e., in more catchments than not) a calibrated lumped model in *gauged basins*,  
 89 and also a state-of-the-art distributed process-based model. This rapid correspondence  
 90 is intended to highlight initial results that might motivate continued development of these  
 91 and similar techniques - this is not intended to be a comprehensive analysis of the ap-  
 92 plication of LSTMs to PUB, which will appear in an upcoming full-length manuscript.

## 93 2 Data

94 Experimental data for our analysis came from the publicly available Catchment At-  
 95 tributes and Meteorology for Large-Sample Studies (CAMELS) data set curated by Na-  
 96 tional Center for Atmospheric Research (NCAR) (Addor, Newman, Mizukami, & Clark,  
 97 2017a; A. Newman et al., 2015, n.d.). CAMELS consists of 671 catchments in the con-  
 98 tinental US ranging in size from 4  $km^2$  to 2,000  $km^2$  (median basin size is 336  $km^2$ ). These  
 99 catchments were chosen from the available gauged catchments in the US due to the fact  
 100 that they are largely natural and have long gauge records (1980-2010) available from the  
 101 United States Geological Survey National Water Information System. CAMELS includes  
 102 daily forcing from Daymet, Maurer, and NLDAS, as well as several static catchment char-  
 103 acteristics related to soils, climate, vegetation, topography, and geology (Addor et al.,  
 104 2018). It is important to point out that these catchment characteristics were derived from  
 105 maps, remote sensing products, and climate data that are generally available over the  
 106 continental US and, either exactly or in close approximation, globally. For this project,  
 107 we used the same 531 (of 671 total) catchments that were used for model benchmark-  
 108 ing by A. J. Newman et al. (2017).

109 The CAMELS repository also includes daily streamflow values simulated by 10 SAC-  
 110 SMA models calibrated separately in each catchment using Shuffled Complex Evolution  
 111 (SCE) (Duan, Gupta, & Sorooshian, 1993) with 10 random seeds. Each SAC-SMA was  
 112 calibrated on 15 years of data in each catchment (1980-1995). This calibration was per-  
 113 formed as part of previous work at NCAR (A. Newman et al., 2015). We used this en-  
 114 semble of SAC-SMA models as a benchmark for our LSTMs. In addition, we benchmarked  
 115 against the NWM reanalysis, which spans the years 1993-2017 ([https://docs.opendata](https://docs.opendata.aws/nwm-archive)  
 116 [.aws/nwm-archive](https://docs.opendata.aws/nwm-archive)). All performance statistics that we report are from the water years

117 1996-2010, so that the SAC-SMA models were tested out-of-sample in time but at the  
 118 same basins where they were calibrated.

### 119 3 Methods

120 LSTMs are a type of Recurrent Neural Network (RNN) first proposed by Hochre-  
 121 iter and Schmidhuber (1997). LSTMs have memory cells that are analogous to the states  
 122 of a traditional dynamical systems model, which make them potentially useful for sim-  
 123 ulating natural systems like watersheds. Kratzert, Klotz, Brenner, Schulz, and Herrneg-  
 124 ger (2018) applied LSTMs to the problem of streamflow forecasting, and later demon-  
 125 strated that the internal memory states of the network were highly correlated with ob-  
 126 served snow and soil moisture states without ever seeing snow or soil moisture data (Kratzert,  
 127 Herrnegger, Klotz, Hochreiter, & Klambauer, 2018).

128 The LSTMs used in this study take as inputs at each timestep the following NL-  
 129 DAS meteorological forcing data:

- 130 • 2 meter daily mean air temperature [ $^{\circ}C$ ],
- 131 • precipitation [ $mm/day$ ],
- 132 • surface incident solar radiation [ $W/m^2$ ], and
- 133 • vapor pressure [ $P_a$ ]

134 Additionally, at each timestep, the meteorological inputs were augmented with the fol-  
 135 lowing catchment attributes:

- 136 • soil depth (Pelletier),
- 137 • soil depth (STATSGO),
- 138 • soil porosity,
- 139 • soil conductivity,
- 140 • maximum water content,
- 141 • soil sand fraction,
- 142 • soil silt fraction,
- 143 • soil clay fraction,
- 144 • mean elevation,
- 145 • mean slope,
- 146 • catchment area,
- 147 • annual mean precipitation,
- 148 • annual mean potential evaporation,
- 149 • precipitation seasonality index,
- 150 • annual mean snow fraction,
- 151 • aridity index,
- 152 • frequency of high-intensity precipitation ( $> 90^{th}$  percentile of annual flow),
- 153 • average duration of high-intensity precipitation events,
- 154 • frequency of low-intensity precipitation ( $< 20^{th}$  percentile of annual flow),
- 155 • average duration of low-intensity precipitation events,
- 156 • forest cover fraction,
- 157 • annual maximum leaf area index,
- 158 • annual maximum greenness vegetation fraction,
- 159 • annual difference between maximum and minimum leaf area index,
- 160 • annual difference between maximum and minimum greenness vegetation fraction,
- 161 • carbonate rocks fraction,
- 162 • geological permeability.

163 These catchment attributes are described in detail by Addor et al. (2018); Addor, New-  
 164 man, Mizukami, and Clark (2017b) and remain constant in time throughout the simu-  
 165 lation (training and testing). In total we used 31 LSTM inputs at each daily timestep:  
 166 4 meteorological forcings and 27 catchment characteristics.

167 We trained and tested three types of LSTM models:

- 168 1. **Global LSTM without static features:** LSTMs with only meteorological forc-  
 169 ing inputs, and without catchment attributes, trained on all catchments simulta-  
 170 neously (without k-fold validation).
- 171 2. **Global LSTM with static features:** LSTMs with both meteorological forc-  
 172 ings and catchment characteristics as inputs, trained on all catchments simulta-  
 173 neously (without k-fold validation).
- 174 3. **PUB LSTM:** LSTMs with both meteorological forcings and catchment charac-  
 175 teristics as inputs, trained and tested with k-fold validation ( $k = 12$ ).

176 The third model is the one we want to test. The second model sets an upper bench-  
 177 mark for our PUB LSTMs - comparison against this model tells us how much informa-  
 178 tion is lost due to prediction in out-of-sample basins. The first model lets us evaluate  
 179 the value of adding catchment attributes to the model inputs, since these are what will,  
 180 at least potentially, allow the model to be transferable between catchments. For each model  
 181 type we trained and tested an ensemble of  $N = 10$  LSTM models to match the 10 SCE  
 182 restarts of the SAC-SMA model. All metrics reported in Section 4 are calculated from  
 183 the mean of the 10-member ensembles, except for the NWM reanalysis.

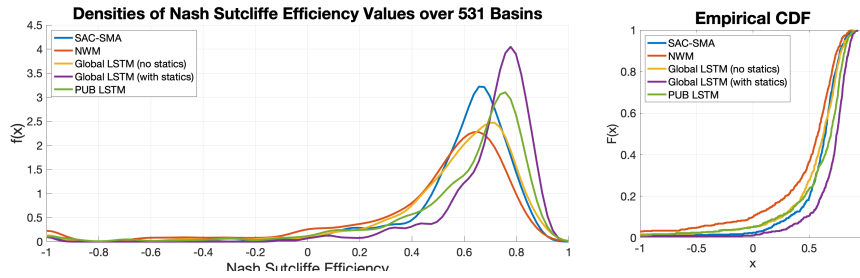
184 All LSTM models were trained on the first 15 years of CAMELS data (1981-1995  
 185 water years) - this is the same data period used to calibrate SAC-SMA. And all mod-  
 186 els (LSTMs, SAC-SMA, and NWM) were evaluated on the last 15 years of CAMELS data  
 187 (1996-2010 water years). LSTMs were trained and evaluated using a k-fold approach ( $k =$   
 188  $12$ ). The training loss function was the average Nash-Sutcliffe Efficiency (NSE) over all  
 189 training catchments; this is a squared-error loss function that, unlike a more traditional  
 190 MSE loss function, does not overweight catchments with larger mean streamflow values  
 191 (i.e., does not overweight large, humid catchments) (Kratzert et al., 2019).

## 192 4 Results

193 A comparison between interpolated frequency distributions over the NSE values  
 194 from 531 CAMELS catchments from all three LSTM models and both benchmark mod-  
 195 els (SAC-SMA, NWM) is shown in **Figure 1**. Mean and median values of several per-  
 196 formance statistics are given in **Table 1**. **Interpolation was done with kernel den-  
 197 sity estimation using Gaussian kernels and an optimized bandwidth.**

198 The primary result is that the out-of-sample PUB LSTM ensemble performed at  
 199 least as well as both of the in-sample benchmarks in more than half of the catchments  
 200 against all four performance metrics that we tested, except that the basin-calibrated SAC-  
 201 SMA has a slightly lower average difference between 95<sup>th</sup> percentile flows (both SAC-  
 202 SMA and the PUB LSTM underestimated peak flows to some extent. The PUB LSTM  
 203 had a higher NSE than SAC-SMA in 307 of 531 (58%) catchments, and higher than the  
 204 NWM in 347 of 531 (66%) catchments. The PUB LSTM ensemble also had higher mean  
 205 and maximum NSE scores than the the benchmark models, however SAC-SMA tended  
 206 to out-perform the PUB LSTM in catchments with low NSE values (see the CDF plot  
 207 in **Figure 1**).

208 There is some amount of stochasticity associated with training the LSTMs, espe-  
 209 cially through the random weight initialization of the LSTMs, but also by the weight op-  
 210 timization strategy (we used an ADAM optimizer (Kingma & Ba, 2014)). Because of this,



**Figure 1.** Frequencies of NSE values from 531 catchments given by ‘gauged’ and ‘ ungauged’ LSTMs, calibrated (gauged) SAC-SMA, and the National Water Model reanalysis.

211 the LSTM-type models give better predictions when used as an ensemble. It is not necessarily the case that if one particular LSTM model performs poorly in one catchment  
 212 that a different LSTM trained on *exactly the same data* will also perform poorly. In our case, we used an ensemble of  $N = 10$  (the same size as the SAC-SMA ensemble developed by A. Newman et al. (2015) that was used here for benchmarking). **Figure 3** shows  
 213 the NSE values for each ensemble member for the PUB LSTM models. In total, there were 103 basins with at least one PUB LSTM ensemble member with an NSE score of  
 214 below zero. Only 9 of these 103 basins have all  $N = 10$  ensemble members with NSE  $< 0$ , while 55 of the 103 have at least one ensemble member with NSE  $> 0.5$ . As an example,  
 215 one of the basins (USGS basin ID: 01142500, which is basin number 232 in **Figure 3**) had 9 of 10 ensemble members with NSE  $< 0$ , but one ensemble member with  
 216 NSE  $> 0.7$ . This indicates that a substantial portion of the uncertainty in these LSTM models is due to randomness, rather than to systematic model structural error.  
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224 The global LSTM model with static catchment attributes performs better than all other models against the metrics that we tested. **Figure 2** compares the performance  
 225 of the Global LSTM with other benchmark models (all except the PUB LSTM) in all catchments. The Global LSTM performs better in most - but not all - catchments. This  
 226 indicates two things. First, the comparison between the Global LSTM with and without static catchment attributes indicates that although there is useful information in the  
 227 catchment attributes, in some catchments having this data actually hurts us. This indicates a need for future work to understand how uncertainty in catchment attributes  
 228 data can be quantified and mitigated in this context. Second, the comparison between the Global LSTM and SAC-SMA indicates that there is substantial room to improve SAC-SMA  
 229 overall. This is probably not a surprise to any working Hydrologist, but this analysis clearly shows that the LSTM is finding rainfall-runoff relationships in individual catch-  
 230 ments that SAC-SMA cannot emulate. However, the fact that SAC-SMA performs better in some catchments indicates the potential value of having physical constraints in a  
 231 hydrological model. The LSTM in these cases are either overfitted or are not able to behaviors of certain similar catchments in the training data set.  
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## 240 5 Discussion

241 The results illustrated in the previous section tell us three things:

- 242 1. The process-driven hydrology models that we used here as benchmarks could be improved. The LSTM often finds a better functional representation of rainfall-runoff  
 243 behavior in most catchments than either SAC-SMA or the NWM.
- 244 2. The argument that process-driven models may be preferable in out-of-sample conditions may not hold water. Modern ML methods are quite powerful at extract-  
 245  
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**Table 1.** Summary of Benchmark Statistics for All Models across 531 Catchments

	Median	Mean	Minimum	Maximum
<b>Nash Sutcliffe Efficiency:</b>	$(-\infty, 1]$ – values close to 1 are desirable.			
SAC-SMA:	0.64	0.51	-12.28	0.88
NWM:	0.58	0.31	-20.28	0.89
Global LSTM (no statics):	0.63	0.45	-31.72	0.90
Global LSTM (with statics):	0.74	0.68	-1.78	0.93
PUB LSTM:	0.69	0.54	-13.02	0.90
<b>Fractional Bias:</b>	$(-\infty, 1]$ – values close to 0 are desirable.			
SAC-SMA:	0.04	0.02	-1.76	0.71
NWM:	0.05	-0.01	-4.80	1.00 <sup>c</sup>
Global LSTM (no statics):	0.01	-0.03	-3.01	0.77
Global LSTM (with statics):	-0.01	-0.04	-2.19	0.49
PUB LSTM:	-0.02	-0.09	-4.86	0.72
<b>Standard Deviation Ratio<sup>a</sup>:</b>	$[0, \infty)$ – values close to 1 are desirable.			
SAC-SMA:	0.83	0.87	0.10	3.76
NWM:	0.86	0.93	0.00 <sup>c</sup>	4.04
Global LSTM (no statics):	0.74	0.81	0.10	5.83
Global LSTM (with statics):	0.88	0.89	0.17	1.96
PUB LSTM:	0.86	0.91	0.10	3.23
<b>95<sup>th</sup> Percentile Difference<sup>b</sup>:</b>	$(-\infty, 1]$ – values close to 0 are desirable.			
SAC-SMA:	0.02	-0.05	-3.98	0.83
NWM:	0.07	-0.07	-8.59	1.00 <sup>c</sup>
Global LSTM (no statics):	0.12	0.02	-4.97	0.81
Global LSTM (with statics):	0.03	-0.03	-3.30	0.63
PUB LSTM:	0.03	-0.08	-5.26	0.78

<sup>a</sup>Ratio of the standard deviation of simulated vs. observed flows at each catchment.

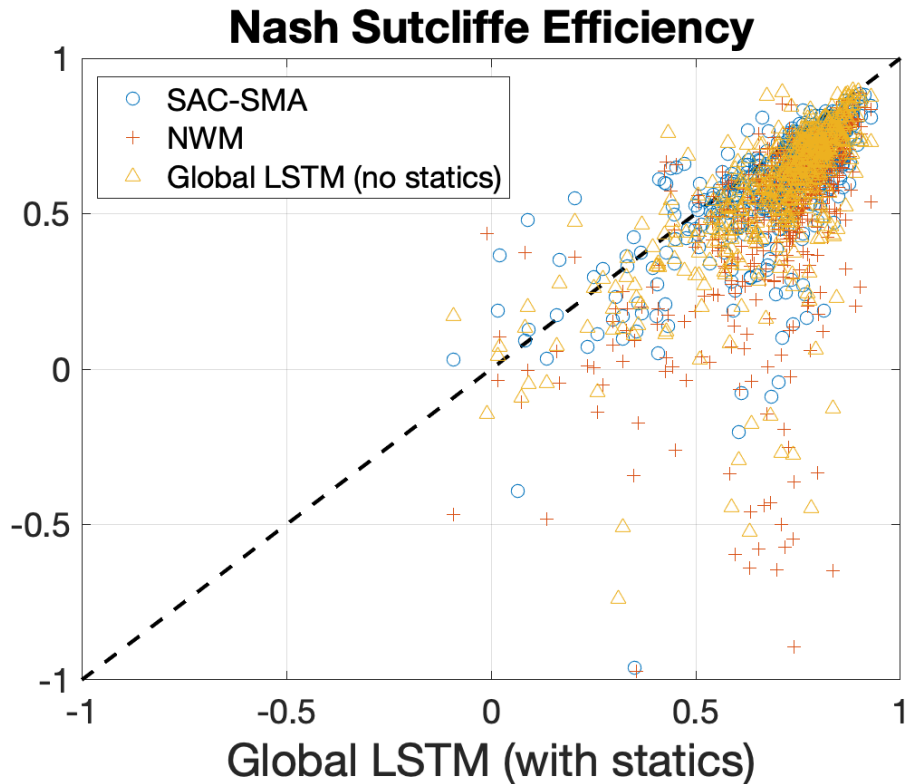
<sup>b</sup>Difference between the values of the observed vs. simulated 95<sup>th</sup> percentile flows divided by the observed 95<sup>th</sup> percentile flows at each catchment.

<sup>c</sup>Values of zero and one in the NWM max/min statistics are due to rounding. In particular, for one basin (USGS basin ID: 2108000) the NWM simulates a 95<sup>th</sup> flow percentile of  $\sim 1 \times 10^{-3}$  [mm/day] whereas the 95<sup>th</sup> percentile of observed flow is  $\sim 4$  [mm/day]

247 ing information from large, diverse data sets under a variety of hydrological con-  
248 ditions.

249 3. The comparison between models with and without static catchment attributes as  
250 inputs demonstrates that there is sufficient information contained in catchment  
251 attribute data to distinguish between different rainfall-runoff relationships in at  
252 least most of the US catchments that we tested.

253 Related to the third conclusion, the challenge going forward is about how to ex-  
254 tract the useful information from catchment attributes data for regional modeling. One  
255 of the historical reasons why this has been a hard problem is because we have often tried  
256 to use observable catchment attributes or characteristics to identify parameters of con-  
257 ceptual or process-based simulation models (e.g., Blöschl, 2016; Hrachowitz et al., 2013;  
258 Prieto, Le Vine, Kavetski, Garca, & Medina, 2019). This is hard because of strong in-  
259 teractions in high-dimensional parameter spaces (Beven & Freer, 2001; ?). There are many  
260 strategies for circumventing this issue - notably a family of methods that Razavi and Coulibaly  
261 (2012) called ‘model independent’ methods, however we are unaware of any approach  
262 that is as effective as LSTMs at extracting this information for streamflow simulation.  
263 Kratzert et al. (2019) compared similar LSTMs with a state-of-the-art regionalization



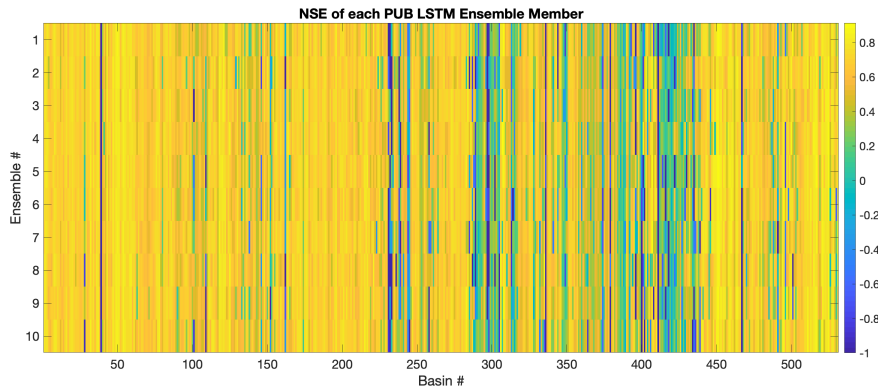
**Figure 2.** Comparison between the Global LSTM model and all other models used in this study (except the PUB LSTM).

264 method in gauged catchments. Again, the catchment attribute data we used here were  
 265 derived from maps available over the entire continental US (Addor et al., 2017a).

266 Related to the first and second conclusion, the Hydrological Sciences community  
 267 must take these results seriously. We have a long history in our community of preferring  
 268 process-based insight and process-based models over black-box or data driven models  
 269 (e.g., Kirchner, 2006; Klemeš, 1986; Milly et al., 2008; Vaze et al., 2015), but the reality  
 270 of the situation is that these models often perform worse than data-driven models,  
 271 even out-of-sample. We would argue that the hydrological modeling community does not  
 272 currently have a robust understanding of where, when, and under what conditions process-  
 273 based insight is useful or necessary for hydrological prediction. At present, the arguments  
 274 are largely philosophical. For our discipline to continue to provide value to operational  
 275 forecasting efforts, the onus is on us to clearly delineate (i) cases and situations where  
 276 process-based insight is critical for accurate modeling (e.g., perhaps under climate change),  
 277 and (ii) how to best use this type of process-based insight in modeling systems that *also*  
 278 utilize the now-undeniable power of sophisticated methods for learning from large data  
 279 sets.

280 Theory-guided data-science, sensu Karpatne et al. (2017), is the idea of using the  
 281 scientific insights and knowledge to augment and guide data-driven methods like machine  
 282 learning. Examples for this line of research are physically bounded black-boxes, hybrid-  
 283 modelling approaches or, as shown here, model benchmarking and/or hypothesis testing.  
 284 Optimally, a reciprocal relationship will form over time in which data-driven meth-  
 285 ods inform the development of “classical” methods and vice-versa. We encourage the hy-





**Figure 3.** NSE scores for all PUB LSTM ensemble members. In some number of basins, certain ensemble members perform well and certain ensemble members perform poorly. This motivates the use of ensembles of LSTMs.

286 hydrological modelling community to adapt these techniques and hope to provide a mo-  
 287 tivating example for accelerating their use in Hydrology.

## 288 6 Code and Data Availability

289 CAMELS data, including SAC-SMA simulations, are available from NCAR at [https://](https://ral.ucar.edu/solutions/products/camels)  
 290 [ral.ucar.edu/solutions/products/camels](https://ral.ucar.edu/solutions/products/camels). National Water Model reanalysis data  
 291 are available from the NOAA Big Data Repository at [https://registry.opendata.aws/](https://registry.opendata.aws/nwm-archive/)  
 292 [nwm-archive/](https://registry.opendata.aws/nwm-archive/). All code used for this project is available at [https://github.com/kratzert/](https://github.com/kratzert/lstm_for_pub)  
 293 [lstm\\_for\\_pub](https://github.com/kratzert/lstm_for_pub).

## 294 Acknowledgments

295 The project relies heavily on open source software. All programming was done in Python  
 296 version 3.7 (van Rossum, 1995) and associated libraries including: Numpy (Van Der Walt,  
 297 Colbert, & Varoquaux, 2011), Pandas (McKinney, 2010), PyTorch (Paszke et al., 2017)  
 298 and Matplotlib (Hunter, 2007). This work was supported by Bosch, ZF, and Google. We  
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