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## On the influence of pressure, phase transitions, and water on large-scale seismic anisotropy underneath a subduction zone

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11	Key Points:
12	• Geodynamic subduction model with experiment-informed mantle fabric transitions.

- *P*-dependent olivine textures can explain the evolution of upper mantle anisotropy.
- A relatively wet upper transition zone could likely explain faster  $V_{SV}$  than  $V_{SH}$
- 15 speeds.

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#### 16 Abstract

Seismic anisotropy mainly originates from the crystallographic preferred orientation (CPO) 17 of minerals deformed in the convective mantle flow. While fabric transitions have been 18 previously observed in experiments, their influence on large-scale anisotropy is not well-19 documented. Here, we implement 2D geodynamic models of intra-oceanic subduction 20 coupled with mantle fabric modelling to investigate the combined effect of pressure (P)-21 and water-dependent microscopic flow properties of upper mantle and upper transition 22 zone (UTZ) minerals, respectively, on large-scale anisotropy. Our results for the upper 23 mantle correlate well with observations, implying that the *P*-dependence of olivine fab-24 rics is sufficient to explain the variability of anisotropy. Meanwhile, a dry UTZ tends to 25 be near-isotropic whereas a relatively wet UTZ could produce up to 1% azimuthal and 26  $\sim 2\%$  radial anisotropy. Because water facilitates CPO development, it is therefore likely 27 a requirement to explain the presence of anisotropy in the transition zone close to sub-28 ducting slabs. 29

#### 30

#### Plain Language Summary

Subduction causes the surrounding mantle to deform according to the movement 31 and pressure exerted by the plates. This influences the alignment of minerals making up 32 the mantle, which in turn, affects the speed and direction of seismic waves known as seis-33 mic anisotropy. In this study, we investigate the role of pressure in the upper mantle and 34 water in the transition zone on large-scale seismic anisotropy across a subduction zone. 35 In the upper mantle, we show that the patterns of anisotropy at places where deforma-36 tion is presumed to be large are affected by changes in pressure. In the transition zone, 37 anisotropy tends to favour a wetter environment. 38

#### <sup>39</sup> 1 Introduction

Understanding subduction dynamics is crucial as it regulates, to first order, the coupling between deep mantle convection and surface deformation. Changes in mineralogy and viscosity structure at designated mantle transition zone boundaries control the style of subduction, and to some extent, the overall dynamics of plate tectonics (Agrusta et al., 2017; Goes et al., 2017). A plethora of geophysical observables can be used to constrain mantle flow; one of them is seismic anisotropy.

Seismic anisotropy mainly results from the crystallographic preferred orientation 46 (CPO) in intrinsically anisotropic minerals upon progressive deformation along convec-47 tive flows (Long & Becker, 2010). The parameters  $\xi$  for S-wave radial anisotropy (i.e., 48 the ratio of the squares of  $V_{SH}$  and  $V_{SV}$  for horizontally-propagating S-waves) and  $a_z$ 49 for azimuthal anisotropy (i.e., directional-dependence of  $V_{SV}$ ) are simple yet intuitive 50 ways of quantifying seismic anisotropy, and hence, are often constrained in tomographic 51 imaging (e.g. Smith & Dahlen, 1973; Montagner, 1998; Panning & Romanowicz, 2006). 52 In a subduction zone, the mantle wedge is characterized by a layer of positive radial anisotropy 53  $\xi > 1$  (e.g. French & Romanowicz, 2014; Chang et al., 2015; Simmons et al., 2021) and 54 2-3% peak-to-peak azimuthal anisotropy (e.g. Yuan & Beghein, 2013; Debayle et al., 55 2016). Underneath the oceanic lithosphere away from the slab, the patterns of anisotropy 56 appear less complex exhibiting an age-independent distribution of  $\xi>1$  and  $a_{V_{SV}}$  2% 57 with maximum amplitudes appearing at  $\sim 150$  km (e.g. Yuan & Beghein, 2013; Debayle 58 et al., 2016; Chang et al., 2015). Reduction of seismic anisotropy is observed past  $\sim 250$  km 59 depth (e.g. Nettles & Dziewoński, 2008; Burgos et al., 2014). Across the upper transi-60 tion zone (UTZ, 410 - 520 km) around slabs,  $\xi\,<\,1$  and  $a_{V_{SV}}\,\sim\,1-2\%$  is generally 61 observed (e.g. Montagner et al., 2021). 62

The prevalent seismic anisotropy observed around subduction zones may be attributed either in terms of large strains that the entrained mantle adjacent to the slab experiences (Mainprice, 2010), structural layering of plate remnants (Karato, 1998), or possibly an

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66	interplay of both. Understanding the origin of anisotropy requires a multidisciplinary
67	approach involving geodynamic modelling with mineral physics constraints. Such meth-
68	ods have already been carried out in the previous decade (e.g. Faccenda, 2014; Sturgeon
69	et al., 2019) with some even accounting for the effect of small-scale isotropic heterogeneities
70	(Faccenda et al., 2019; Ferreira et al., 2019; Magali et al., 2021). Yet, the impact of fab-
71	ric transitions onto large-scale seismic anisotropy which has been observed experimen-
72	tally in mineral microstructures (e.g. Mainprice et al., 2005; Raterron et al., 2007), is
73	not fully investigated for realistic flows, especially in a subduction setting where strains
74	are large. While certain mantle conditions must be met to induce fabric transitions, we
75	focus on the effect of pressure in the upper mantle and water in the UTZ based on pre-
76	vious findings that $P$ -induced olivine slip transitions and water in the UTZ strongly in-
77	fluence the depth distribution of the observed radial anisotropy (Magali et al., $2024$ ). For
78	simplicity, we will not consider the effect of water on upper mantle anisotropy.
79	here, we build upon previous CPO modelling studies (e.g. Faccenda, 2014; Li et
80	al., 2014; Sturgeon et al., 2019; Fraters & Billen, 2021) by integrating mantle fabric tran-
81	sitions to predict radial and azimuthal anisotropy underneath a subduction zone. We

sitions to predict radial and azimuthal anisotropy underneath a subduction zone. We then apply elastic homogenization (Capdeville et al., 2015; Capdeville & Métivier, 2018) as a post-processing step, and compare the effective anisotropy with anisotropic tomography models across the Honshu arc. Two main problems will be addressed using our modelling strategy: (i) Determine whether P-induced slip transitions in olivine could sufficiently explain the variability of anisotropy in the upper mantle, and (ii) investigate the role of water in the development of anisotropy in the UTZ using the recently published texture data of wadsleyite (Ohuchi et al., 2014; Ledoux et al., 2023a).

#### 89 2 Methods

We carry out 2D 6000 km×1000 km thermo-chemical modelling of intra-oceanic subduction with phase transformations using the open software ASPECT (Kronbichler

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92	et al., 2012) (Figure S1a of Supplementary Text S1). The transition zone is character-
93	ized by phase transformations of olivine polymorphs that may either inhibit or assist sub-
94	duction: olivine to wadsley ite at ${\sim}410$ km, wadsley ite to ringwood ite at ${\sim}520$ km and
95	finally ringwood ite to bridgmanite at ${\sim}660$ km (Figure 1). As we are only interested in
96	upper mantle and UTZ anisotropy, we limit our modelling to a slab stagnating at $660$
97	km. We employ $\tt Perple_X$ (Connolly, 2005, 2009) coupled with the recently published
98	thermodynamic database of Stixrude and Lithgow-Bertelloni (2022) to estimate the den-
99	sity $\rho$ as a function of $P$ and $T$ assuming a pyrolitic mantle. Phase transition bound-
100	ary topography in the subduction model is inferred from the density map (Figure S2).

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#### 2.1 Mantle fabric modelling

Starting at the initial step along a pathline followed by a tracer, we estimate the local velocity gradient  $\mathbf{L}'$ , local total pressure (hydrostatic + dynamic) P', and local temperature T' by introducing a new velocity, total pressure, and temperature fields at the current time step t from ASPECT. Local density  $\rho'$  along the pathline is estimated with the help of the density map (Figure S2a). At the final time step  $t_{\text{final}}$ , tracers are regularly distributed inside the white dashed rectangle of Figure S2c where anisotropy has been calculated. We use the full  $\mathbf{L}'$  for strain accumulation.

To model mantle fabrics, we implement the modified viscoplastic self-consistent (VPSC) 109 method of Lebensohn and Tomé (1993) that incorporates P-induced slip transitions and 110 P-induced phase transformations (Magali et al., 2024). While kinematic models are less 111 computationally demanding and can replicate large-scale anisotropy features (e.g. Kamin-112 ski et al., 2004), VPSC offers the capability to work with an arbitrary number of inde-113 pendent slip systems. Furthermore, it explicitly accounts for variations in intragranu-114 lar stress and strain, resulting in more precise predictions of the mechanical behavior of 115 deforming polycrystals (Castelnau et al., 2008). Each tracer with density  $\rho'$  is composed 116 of 3000 initial randomly oriented grains with the following modal abundancies: Upper 117 mantle ( $\rho' < 3720 \text{ kg} \cdot \text{m}^{-3}$ ): 60% *P*-dependent olivine (Magali et al., 2024) and 40% 118

other phases (assumed isotropic), UTZ (3720  $\leq \rho' < 3850 \text{ kg} \cdot \text{m}^{-3}$ ): 60% wadsleyite (Ledoux et al., 2023a) and 40% garnet, and lower transition zone (LTZ, 3850  $\leq \rho' <$ 4170 kg  $\cdot$  m<sup>-3</sup>): 60% ringwoodite and 40% garnet. Both garnet and ringwoodite are deemed isotropic (e.g. Mainprice, 2007). The single crystal elastic constants of the phases at ambient conditions, including their *PT* derivatives are listed in Magali et al. (2024). Wadsleyite properties are more complex to incorporate and will henceforth be discussed below.

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## 2.2 An ersatz to compute water-dependent anisotropy in the transition zone

In this study, we assume that the ambient UTZ is dry and the slab, together with 128 the entrained mantle, is relatively wet. To do this, tracers are specified with either hy-129 drous (i.e., C<sub>wd</sub>-type) or dry wadsleyite (i.e., B<sub>wd</sub>-type) depending on their positioning 130 relative to the slab (Ledoux et al., 2023a). Tracers with T' < 1750 K envelope the cold 131 and slightly hydrated slab, and hence C<sub>wd</sub>-type CPO is calculated. Consequently, those 132 with  $T' \ge 1750$  K are prescribed with a B<sub>wd</sub>-type fabric. The latter corresponds to trac-133 ers scattered around the dry and ambient UTZ. We also test the effect of a fully dry UTZ 134 by computing the CPO of B<sub>wd</sub>-type wadsleyite aggregates across the entire UTZ. 135

P and T-dependent wadsleyite polycrystal elastic tensors are also computed us-136 ing Voigt-Reuss-Hill averaging around their single crystal counterparts. Hydrous and dry 137 elastic constants are inferred from Zhou et al. (2022) and Núñez-Valdez et al. (2013), re-138 spectively. Their PT derivatives are also listed in Magali et al. (2024). CPO of a tracer 139 crossing a phase transition boundary determined by the density crossovers is erased and 140 instead replaced with random textures according to experimental results of microstruc-141 tures induced by the olivine  $\rightarrow$  wadsleyite transition (Smyth et al., 2012; Ledoux et al., 142 2023b). Anisotropy calculations are ceased past  $\rho' = 4150 \text{ kg} \cdot \text{m}^{-3}$  (i.e., 660 km). Min-143 eral assignments are summarized in Figure 1. 144

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#### 145 **2.3 Elastic homogenization**

146	For a realistic comparison with anisotropic tomography models, we first apply the
147	fast-Fourier homogenization (FFH) algorithm (Capdeville et al., 2010, 2015) to obtain
148	an effective medium void of spatial heterogeneities whose scales are much smaller than
149	the minimum wavelength $\lambda_0$ of the observed wavefield. The result is a smooth tomographic
150	version of the elastic medium, similar to an image recovered by full waveform inversion
151	assuming perfect data coverage (Capdeville & Métivier, 2018). Finally, we apply the elas-
152	tic decomposition method of Montagner and Nataf $(1986)$ to compute radial anisotropy
153	and azimuthal anisotropy (Supplementary Texts S3 and S4).

154 **3 Results** 

## 155

## 3.1 Predictions of large-scale upper mantle anisotropy induced by subduction

The influence of P-induced slip transitions on anisotropy can be observed in the 157 subslab mantle (Figures 2a and 3a). Here, anisotropy strength decreases with depth; drop-158 ping to  $\xi~\sim~1.01$  and  $a_z~\sim~1\%$  at z~=~400 km. The presumed switch in primary ac-159 tivities from the [100](010) to the [001](010) slip systems may have caused this (Raterron 160 et al., 2014; Magali et al., 2024), as also evidenced by the slight re-alignment of the [100] 161 axes towards the (010) direction (Figure S3e-g). The mantle wedge mainly exhibits pos-162 itive radial anisotropy  $\xi~>~1$  and nonzero azimuthal anisotropy  $a_z~\sim~5\%.$  However, 163 the entrained mantle immediately beneath the back-arc basin (z  $\sim$  90 - 150 km) ex-164 periences rapid trench retreat motion due to a decreased upper plate forcing of a thin 165 overriding lithosphere (Agrusta et al., 2017). This creates a localized region of complex 166 anisotropy patterns with  $\xi < 1$  and  $a_z < 5\%$ . Negative radial anisotropy ( $\xi \sim 0.97$ ) 167 and near-zero azimuthal anisotropy are generated just above the upper transition zone 168 (UTZ) close to the slab (~ 290-400 km). At these depths, the lateral extent x of sub-169 horizontal FSE orientations cover  $\sim~2000~{\rm km}~\leq~x~\leq~3200~{\rm km}$  (Figure 1b). Li et al. 170

(2014) revealed aggregates submitted to subduction zone stresses exhibit olivine [100] axes that are approximately aligned with the FSE long axis. The existence of a negative radial anisotropy  $\xi < 1$  at these depths, where the fast directions are now sub-normal to the FSE, is also indicative of P-induced slip transitions in olivine.

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#### 3.2 Effect of water around the slab on mantle transition zone anisotropy

A wet UTZ near the slab is generally characterized by an accumulation of nega-176 tive radial anisotropy with  $\xi \sim 0.97$  above the slab and  $\xi \sim 0.98$  in the subslab area 177 (Figure 2a). A localized area of weak positive radial anisotropy ( $\xi \sim 1.01$ ) forms close 178 to the slab tip which can be attributed to the preferential alignment of the [100] axes 179 of the  $C_{wd}$ -type phase with the horizontal (Figure S3h) in response to rapid changes 180 in the deformation patterns of the entrained mantle close to the slab tip. Small amounts 181 of azimuthal anisotropy  $a_Z~\sim~1.1\%$  far from the slab tip and up to  $a_Z~\sim~1\%$  in the 182 remaining regions close to the slab can be found (Figure 3a). 183

Figures 2b and 3b show the results of the same calculations assuming a fully dry transition zone (i.e.,  $B_{wd}$ -type texture and elastic constants retrieved from Núñez-Valdez et al. (2013)). Such an assumption leads to an almost isotropic UTZ around the slab.  $a_Z \sim 1.1\%$  away from the slab tip can also be detected which means that dry fabrics can produce enough azimuthal anisotropy but may fail to generate observable radial anisotropy.

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## 3.3 Comparison with tomographic observations: a case for the Honshu arc

We select cross-sections of radial anisotropy and azimuthal anisotropy from SGLOBE-Rani (Chang et al., 2015) and 3DLGL-TPESv.v2022-11 (Debayle et al., 2016), respectively, for the Honshu subduction zone which, to some extent, displays a similar geometry and subduction style to our model. For comparison, we solely homogenize the CPO model with a wet UTZ since we find that no substantial anisotropy is developed assuming a fully dry UTZ, contrary to tomographic observations where anisotropy is present

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around slabs (e.g. Chang et al., 2015; Debayle et al., 2016; Montagner et al., 2021). Supplementary Figures S4 and S5 show the effective anisotropy models at different homogenization wavelengths  $\lambda_0$ .

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# 3.3.1 Effective radial anisotropy ( $\lambda_0=65~{ m km}$ ) comparison with SGLOBE-Rani

To get the effective radial anisotropy  $\xi^*$  comparable to SGLOBE-Rani, we choose 202 a homogenization wavelength of  $\lambda_0 = 65$  km (Figure 2c). Localized areas of the observed 203 negative radial anisotropy  $\xi_{\rm obs} < 1$  underneath the back-arc basin and just above the 204 stagnant slab is evident (Figure 2d). Whether these peculiar features are robust or not, 205 however, warrants regional tomography for better resolution. Nonetheless, their pres-206 ence can be reproduced with a geodynamic model that accounts for transient flows and 207 P-dependent fabrics in olivine (Figures 2c; 2e red and green dashed lines). Across the 208 subslab mantle, the decrease in  $\xi^*$  with depth correlates well with observations. In the 209 UTZ, modelling with wet wadsleyite fabrics captures the persistence of  $\xi_{obs} < 1$  near 210 the slab. P-induced phase transformations from olivine to wadsleyite at ~410 km, and 211 to ringwoodite at  $\sim$ 520 km introduce sharp velocity contrasts that when homogenized, 212 produce a thin layer of weak  $\xi^* > 1$  which is not observed in SGlobe-Rani. Finally,  $\xi^*$ 213 cannot explain the prevalence of  $\xi_{obs}$  in the LTZ. Small-scale heterogeneities unaccounted 214 for in our model such as petrological layering of transformed subducted material could 215 explain such observations (Karato, 1998). Smearing effects from the tomographic inver-216 sion could also lead to the presence of radial anisotropy in the LTZ. 217

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## 3.3.2 Effective azimuthal anisotropy ( $\lambda_0 = 164 \text{ km}$ ) comparison with 3DLGL-TPESv.v2022-11

<sup>220</sup> Choosing a longer homogenization wavelength ( $\lambda_0 \sim 165$  km) intensifies the spa-<sup>221</sup> tial averaging of small-scale heterogeneities in azimuthal anisotropy (Figure 3c). This <sup>222</sup> leads to a decrease in azimuthal anisotropy of about 1%. Comparison with the 3DLGL-

223	TPESv.v2022-11 tomographic model (Figure 3d) is not as robust as with our result from
224	$\xi^*$ with SG lobe-Rani. For instance, the consistent azimuthal anisotropy at depths above
225	$\sim 250~{\rm km}$ predicted from our model only appears in patches in 3DLGL-TPESv.v2022-
226	11. Furthermore, the predicted anisotropy in the UTZ is significantly underestimated
227	(Figure 3e). Several factors may be involved in the difference between $a_z^*$ and $a_z^{obs}$ . The
228	first may be related to ad-hoc constraints on regularization where the spatial distribu-
229	tion of $a_z^{\rm obs}$ is bounded to this uncertainty. Another factor relates to the dimensional-
230	ity of our model. Here, although the elastic tensors computed from VPSC are in 3D, the
231	latter relies on a 2D representation of thermo-chemical subduction. Thus, toroidal flow
232	was not taken into account which was shown to participate in the production of trench-
233	parallel anisotropy (Faccenda & Capitanio, 2012, 2013; Li et al., 2014), and hence a rather
234	complex distribution of azimuthal anisotropy (e.g. Rychert et al., 2012).

235 4 Discussion

### 236 237

## 4.1 Pressure-dependence of single-phase fabrics and its implications for the upper mantle

Laboratory studies have already reported the existence of pressure-dependence of 238 olivine microstructures (Mainprice et al., 2005; Raterron et al., 2007; Jung et al., 2009; 239 Ohuchi et al., 2011), and most recently of bridgmanite (Gay et al., 2024). To this day, 240 however, it is still not clear how textures evolve with hydrostatic pressure (Karato et al., 241 2008) since high-P experiments are also characterized by high differential stresses  $\sigma \sim$ 242 100-500 MPa which could contribute to fabric transitions (e.g. Katayama et al., 2004). 243 Deformed peridotites extracted from xenoliths gathered mostly from the Western US, 244 however, recorded lower differential stresses of about  $\sim 30$  MPa (Bernard et al., 2019). 245 Under low  $\sigma$ , Raterron et al. (2012) numerically demonstrated using the first-principles 246 approach of Durinck et al. (2007) the slip transition from [100](010) to [001](010) olivine 247

slip system in the deep upper mantle; consistent with Raterron et al. (2007); Jung et al.
(2009); Ohuchi et al. (2011).

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# 4.1.1 Can P-induced slip transitions be used as a proxy to describe the alphabet fabrics (i.e, A-, B-, C-, and E-type olivine)?

The response of strain-induced anisotropy on pressure becomes more evident in re-252 gions associated with large deformation (Magali et al., 2024); in our model, across the 253 mantle wedge and the subslab mantle where the entrained mantle experiences first-hand 254 the influence of slab pull. At low pressures, our implementation of P-induced olivine 255 fabric transitions emulates an A-type fabric because of increased activities at the [100](010)256 slip system. At high pressures, it somehow follows a B-type fabric due to the switch in 257 primary activities to the [001](010) slip system (Raterron et al., 2012, 2014). While P-induced 258 apparent B-type fabrics could explain the distribution of anisotropy around the slab at 259 high pressures, we could also not dismiss the effect of water on the generation of such 260 fabric at low confining pressures (Ohuchi et al., 2012). Proxies of a water-rich environ-261 ment in the convective flow are required to differentiate the possible origin (i.e. *P*-induced 262 or water-induced) of B-type fabrics; although there is still no apparent relationship be-263 tween olivine fabric types and water fugacity (Bernard et al., 2019). 264

Different conditions must be met to derive a suite of fabrics other than A- and Btype. Under low stresses and at increasing temperatures and a relatively dry mantle, an A-type transitions to an E-type<sup>1</sup> fabric, and increasing water content, to a C-type<sup>2</sup> fabric (Karato et al., 2008). Results from geodynamic simulations of upper mantle flow suggest  $\xi > 1$  for A, B, and E-type fabrics, with E-type exhibiting minimal strength, whereas  $\xi < 1$  for C-type, in the case of horizontal simple shear. As for  $a_z$ , all except B-type exhibit fast propagation directions parallel to the direction of shear (Long & Becker, 2010).

<sup>&</sup>lt;sup>1</sup> easiest slip system at [100](001)

<sup>&</sup>lt;sup>2</sup> easiest slip system at [001](100)

272	While it is tempting to infer the potential distribution of such fabrics across a sub-
273	duction zone based on the distribution of $\xi$ and $a_z$ , doing so requires an extension of a
274	depth-dependent model for anisotropy. Therefore, $P-{\rm dependent}$ olivine cannot be used
275	as a proxy to describe fabric types. Lateral dependence can be accomplished by track-
276	ing the effect of temperature and differential stresses on olivine slip systems CRSS, for
277	example, using first-principle calculations coupled with the Peierls–Nabarro formalism
278	for olivine plasticity (e.g. Durinck et al., 2007). Nevertheless, we anticipate that clas-
279	sifying fabrics using large-scale anisotropy models alone would be difficult to execute.
280	For better classification, textures derived from old fabrics must be completely overwrit-
281	ten by newer textures developed from a set of CRSS that reflect the current fabric.

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## 4.1.2 On the reduction of free-parameters to constrain patterns of largescale anisotropy

In recent years, models of upper mantle anisotropy are derived from carefully cho-284 sen methodologies such as: (a) implementation of a two-phase aggregate composed of 285 60% olivine and 40% enstatite reminiscent of a pyrolitic mantle (Ringwood, 1991), (b) 286 strain partitioning where a fraction accommodated by dislocation creep is used for CPO 287 development consistent with Karato and Wu (1993), and (c) the extension of homoge-288 nization methods for CPO modelling by incorporating dynamic recrystallization. Sev-289 eral studies have applied such methodologies in a subduction setting where the variabil-290 ity of radial anisotropy has been correctly predicted in certain places (Faccenda & Cap-291 itanio, 2012; Faccenda, 2014; Sturgeon et al., 2019; Ferreira et al., 2019). Implementa-292 tion of such methodologies, however, becomes increasingly difficult due to the sheer amount 293 of free parameters that control the variability of anisotropy. This is not to say that these 294 methods should not be implemented given that such values can be obtained from liter-295 ature. However, a more grounded approach should not be ruled out either. We argue that 296 a simple depth-dependent anisotropy of single-phase aggregates, without the need for 297 strain partitioning and additional mechanisms for CPO development, is enough to ex-298

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plain the variability of large-scale anisotropy in the upper mantle. This is especially true
given the uncertainty surrounding where dislocation creep should subjugate (Hirth &
Kohlstedf, 2003; Becker & Lebedev, 2021) and the inability of seismic waves to distinguish deformation from recrystallization textures (Wenk & Tomé, 1999).

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#### 4.2 Importance of water on the variability of transition zone anisotropy

In light of our conducted numerical experiments, a relatively wet UTZ subjected 304 to subduction stresses produces substantial radial anisotropy and about 1% azimuthal 305 anisotropy. Contrastingly, a fully dry UTZ appears mostly isotropic. The anisotropy dis-306 tribution in the hydrous model is thus consistent with source-side splitting observations 307 surrounding deep earthquakes, particularly in the western Pacific (Nowacki et al., 2015; 308 Mohiuddin et al., 2015). Our predictions, however, are not perfect, particularly  $a_z$  where 309 its amplitude appears underestimated. Around slabs, Moulik and Ekström (2014) mea-310 sured radial anisotropy of about  $\xi \sim 1.04$  underneath the circum-Pacific region; whereas 311 azimuthal anisotropy could reach up to  $a_z \sim 3\%$  according to Huang et al. (2019). There 312 are several propositions for the increased anisotropy around subduction zones aside from 313 wadsleyite CPO. Local enrichment of akimotoite may be the leading cause for source-314 side shear wave splitting observations underneath stagnant slabs (Foley & Long, 2011). 315 Dense hydrous magnesium silicates (DHMS) have also been shown to be very anisotropic 316 at UTZ conditions (Nowacki et al., 2015) but their abundance and stability remain in-317 conclusive (Hao et al., 2020). Although Nowacki et al. (2015) suggested shape preferred 318 orientation may contribute to the development of anisotropy, this may be unlikely since 319 elliptical inclusions must be periodically aligned vertically to match  $\xi < 1$  around sub-320 321 duction zones where horizontal laminations are more rampant instead (Faccenda et al., 2019; Magali et al., 2021). Furthermore, neither metastable olivine nor topotactical re-322 lationships between olivine and wadsleyite could be possible candidates due to their un-323 likely existence in hydrous environments (Smyth et al., 2012). It is thus plausible that 324 the amount of effective strains in our models did not achieve that of actual subduction 325

systems, and that our 2D setting relegates the complexity of deformation patterns which
 would explain the discrepancy in anisotropy strength (McKenzie, 1979). Even so, we assert that the patterns of UTZ anisotropy we predict remain robust.

The incorporation of water in wadsleyite promotes CPO development and there-329 fore captures the variability of anisotropy. This challenges the study of Chang and Fer-330 reira (2019) where it is inferred that a dry UTZ is likely the cause of substantial radial 331 anisotropy ( $\xi \sim 1.02 - 1.03$ ) across slabs underneath the western Pacific. While a dry 332 single crystal wadsleyite indeed contains larger intrinsic anisotropy, Zhou et al. (2022) 333 reported anisotropy increases with water content in the case of deformed wadsleyite ag-334 gregates, primarily due to increased crystallographic defects that weaken its rheology. 335 With enough deformation accumulated in the UTZ, we model, for the first time, the de-336 pendence of the distribution of large-scale anisotropy on water. The relatively misun-337 derstood effect of strong accumulation, however, precludes the prediction of anisotropy 338 strength with the degree of hydration in the UTZ. Further analyses are imperative to 330 reconcile seismic observations (e.g. Chang & Ferreira, 2019) and mineralogical exper-340 iments (e.g. Ohuchi et al., 2014; Zhou et al., 2022) with the help of additional constraints 341 such as electrical conductivity measurements (Kelbert et al., 2009; Karato, 2011). 342

#### 343 5 Conclusion

We have integrated pressure (P)-induced olivine fabric transitions and P-induced 344 phase transformations in CPO calculations to predict the distribution of large-scale anisotropy 345 around a subduction zone. Coupled with an elastic homogenization algorithm that acts 346 as a tomographic filter, depth-dependent anisotropy of a single-phase fabric is enough 347 to capture the variability of the observed anisotropy in the upper mantle. Strain par-348 titioning, modelling of multi-phase aggregates, and implementations of other potential 349 mechanisms for CPO development may not be warranted; reducing the number of free 350 parameters that need to be constrained. In the upper transition zone (UTZ), the CPO 351

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of deformed hydrous wadsleyite is likely the leading cause for the observed anisotropy 352 near the subducting slab. This opens a fresh perspective on how water is integral to its 353 deformation history. Discrepancies in the strength of anisotropy, however, remain an open 354 question. Further challenges therefore await such as identifying an empirical relation-355 ship between the amount of water and the strength of anisotropy in deformed aggregates. 356

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### **Open Research Section**

Subduction flow modelling was done using the open software ASPECT (https:// 358 aspect.geodynamics.org/), and fabric calculations were performed using VPSC (https:// 359 github.com/lanl/VPSC\_code) The Fast Fourier Homogenization (FFH) code can be made 360 available upon reasonable request to Y. Capdeville. Its foundation is based upon the fol-361 lowing in-text citation references: (Capdeville et al., 2015) and (Capdeville & Métivier, 362 2018). This study is entirely numerical. The input files for Aspect and VPSC, useful rou-363 times for calculating single crystal elastic constants and CRSS as a function of P and T, 364 and output elastic tensor files can be found in https://doi.org/10.5281/zenodo.12774418. 365

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Figure 1. (a) Distribution of mineralogical fabrics across the subduction zone at the present day: Ol - olivine, Wd - wadsleyite, Gt - garnet, Rw - ringwoodite. In the upper transition zone, the distribution of hydrous and dry Wd is solely determined by the evolution of the 1750 K isotherm (solid red line) that encapsulates the slab (in blue). Solid black lines are the predicted topographies of the phase transition boundaries. For a fully dry UTZ, dark green shades associated with  $C_{wd}$ -type wadsleyite cover the entire UTZ. (b) Second invariant of the strain rate tensor  $\varepsilon_{iI}$ . Arrowless vectors correspond to the orientation of the finite strain ellipse.



Figure 2. (a) Radial anisotropy  $\xi = (V_{SH}/V_{SV})^2$  for a mantle model with a wet UTZ. (b) Same as (a) but for a dry UTZ. (c) Effective radial anisotropy  $\xi^*$  at  $\lambda_0 = 65$  km for the wet UTZ model. The effective radial anisotropy in the case of a dry UTZ model is not shown since no significant anisotropy is produced. (d) Radial anisotropic tomography image across the Honshu arc retrieved from SGlobe-Rani Chang et al. (2015). (e) 1D radial anisotropy profiles from our model (in green and in red for dry and wet UTZ, respectively), across Honshu (in blue), and global average (in black). Individual depth profiles are taken at the back-arc basin. The choice of  $\lambda_0$  is a conservative estimate for the wavelength of the SS phase sampling the upper mantle and the UTZ.



Figure 3. (a) Peak-to-peak azimuthal anisotropy  $a_z$  for a mantle model with a wet UTZ. (b) Same as (a) but for a dry UTZ. (c) Effective azimuthal anisotropy after homogenization  $a_z^*$  at  $\lambda_0$ = 165 km for the wet UTZ model. Similarly, the effective azimuthal anisotropy in the case of a dry UTZ model is excluded as it produces near-zero amplitudes close to the slab. (d) Azimuthal anisotropic tomography image across the Honshu arc retrieved from 3DLGL-TPESv.v2022-11 Debayle et al. (2016). (e) 1D azimuthal anisotropy profiles from our model (in green and in red for dry and wet UTZ, respectively), across Honshu (in blue), and global average (in black). The chosen value of  $\lambda_0$  roughly corresponds to the wavelength of first overtones with maximum sensitivity kernels at that same depth range.

### Supplementary information for

## On the influence of pressure, phase transitions, and water on large-scale seismic anisotropy underneath a subduction zone

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### Contents of this file

Text S1 to S4

Figures S1 to S4

#### Text S1. Geodynamic modelling of intraoceanic subduction

To implement a 2-D geodynamic model of intra-oceanic subduction, we use the open software ASPECT (Kronbichler et al., 2012) that solves the conservation mass, momentum, and energy equations for an incompressible fluid and assume an infinite Prandtl number:

$$\boldsymbol{\nabla} \cdot \mathbf{u} = 0, \tag{1}$$

$$-\boldsymbol{\nabla} \cdot 2\eta_{\text{eff}} \dot{\boldsymbol{\varepsilon}}(\mathbf{u}) + \boldsymbol{\nabla} P = \rho \mathbf{g},\tag{2}$$

$$\rho C_p \frac{DT}{Dt} - \boldsymbol{\nabla} \cdot k \boldsymbol{\nabla} T = H, \qquad (3)$$

where  $\frac{DT}{Dt}$  is the material derivative, and  $\mathbf{u}$ ,  $\eta_{\text{eff}}$ ,  $\dot{\varepsilon}$ , P,  $\rho$ ,  $\mathbf{g}$ ,  $C_p$ , T, and k are the velocity, effective

viscosity, strain rate tensor, total pressure, density, gravitational acceleration, heat capacity, temperature, and thermal diffusivity, respectively. H refers to heat generation or consumption that takes into account adiabatic (through the extended Boussinesq approximation), latent, radiogenic, and shear heating effects.

We include four compositional fields reminiscent of Glerum et al. (2018): (a) overriding plate (OP), (b) subducting crust (SC), (c) subducting plate (SP), and (d) background mantle (M) whose time evolution follow an advection type equation. The computational domain is 6000 km  $\times$  1000 km and with adaptive mesh refinements incorporated, spatial resolutions vary from 5 km  $\times$  5 km across regions with sharp viscosity contrasts and across the slab up to 325 km  $\times$  325 km in regions of quiescence far from the slab.

The initial temperature field conforms to a half-space cooling model (Schubert et al., 2001) with a surface adiabatic temperature of 1573 K. The OP age evolves from 0 My at x = 0 km to 20 My at the trench (x = 3000 km). Meanwhile, the SP, initially dipping at 30°, age evolves from 0 My at x = 6000 km to 150 My at the trench. A linear mantle geotherm is then established from the lithosphere-asthenosphere boundary (LAB) to a depth of 1000 km. Fixed temperature boundary conditions are imposed at the top (293 K) and at the bottom (2100 K). Zero heat flux is imposed at the sidewalls. The initial compositional structure also follows an age-based plate model for OP and SP. A 7.5-km subducting crust is augmented to serve as a weak decoupling Newtonian layer. Free-slip boundary conditions are imposed across all boundaries. The initial setup is shown in Figure S1.

#### Text S1.1. Formulation of the viscoplastic rheology

We implement viscoplastic rheology where the viscoplastic effective viscosity  $\eta_{vp}$  is a harmonic average of viscous creeping and plastic yielding capped by a minimum and a maximum value,  $\eta_{min} = 1.0 \times 10^{20}$  Pa-s and  $\eta_{max} = 1.0 \times 10^{25}$  Pa-s, respectively:

$$\eta_{\rm vp} = \eta_{\rm min} + \left(\frac{1}{\eta_{\rm max}} + \frac{1}{\eta_{\rm df/dl/pl}}\right)^{-1},\tag{4}$$

with:

$$\eta_{\rm df/dl/pl} = \left(\frac{1}{\eta_{\rm df}} + \frac{1}{\eta_{\rm dl}} + \frac{1}{\eta_{\rm pl}}\right)^{-1}.$$
(5)

The first two terms in Eq. (5) correspond to the effective viscosities due to diffusion and dislocation creeps (Karato and Wu, 1993):

$$\eta_{\rm df/dl} = \frac{1}{2} A^{-\frac{1}{n}} \dot{\varepsilon}_{II}^{\frac{1}{n}-1} \exp\left(\frac{E+PV}{nRT}\right),\tag{6}$$

where  $\dot{\varepsilon}_{II}$  is the second invariant of the strain rate tensor, A is a prefactor, d is grain size, E and V are the activation energy and volume, P is hydrostatic pressure, R is gas constant, and T is temperature. The last term in Eq. (5) is the effective viscosity due to plastic yielding:

$$\eta_{\rm pl} = \frac{\sigma_y}{2\varepsilon_{II}},\tag{7}$$

where the yield strength  $\sigma_y$  follows a Drucker Prager criterion (Davis and Selvadurai, 2005):

$$\sigma_y = C\cos\theta + P\sin\theta,\tag{8}$$

in which C is the cohesion, and  $\theta$  is the internal friction angle. We set  $\theta = 0$  for the weak decoupling layer which ensues a constant yield stress (von Mises criterion). Table 1 summarizes the viscoplastic rheology parameter values chosen in this study.

#### Text S1.2. Formulation of the effective mantle viscosity

To further promote slab stagnation, we implement a depth-dependent compositing model for the ambient mantle (Mitrovica and Forte, 1997) whose effective viscosity  $\eta_0$  depends on depth z according to:

$$\eta_0(z) = \begin{cases} \eta_{\min} + (1.0 \times 10^{21} [\text{Pa-s}] - \eta_{\min}) \frac{z}{660 [\text{km}]} & \text{if } z < 660 \text{ km} \\ \\ 5.0 \times 10^{21} [\text{Pa-s}] & \text{if } x \ge 660 \text{ km} \end{cases}$$

Finally, the effective mantle viscosity  $\eta_{\text{eff}}$  is simply (Kronbichler et al., 2012):

$$\eta_{\text{eff}}(z, P, T, ..) = \eta_0(z) \frac{\eta_{\text{vp}}(P, T, ..)}{\eta_{\min}}$$

$$\tag{9}$$

Note that a viscosity jump by a factor of  $\sim 5$  is implicitly defined at 660 km (Čížková et al., 2012; Agrusta et al., 2017). We do not consider the effect of crystallographic preferred orientation (CPO) strength on viscosity. Figure S1b illustrates the effective mantle viscosity at the final time step of the simulation.

#### Text S1.3. Modelling pressure-induced phase transformations

Following the method of Christensen and Yuen (1985), ASPECT employs an analytical phase function X to approximate the time evolution of a fraction of a material that underwent phase transformation and calculate the entropy change  $\Delta S$  to calculate latent heat production. Both X and  $\Delta S$  depend on the Clapeyron slope  $\beta_{410}$  (positive for an endothermic process and negative for an exothermic process), phase transition temperature  $T_{410}$ , phase transition width w, phase transition density contrasts  $\Delta \rho_{410}$ , and phase transition depths  $z_{410}$ . The aforementioned parameters are initialized in the material model plugin (see Table 2).

#### Text S2. Textures at selected locations across the subduction zone

We select several locations along independent pathlines to examine the orientations of the crystallographic axes in the evolved CPO of olivine (i.e. Figure S3a-g) and wadsleyite (Figure S3h-j) aggregates.

#### Text S3. Tomographic filtering through elastic homogenization

The foundation behind elastic homogenization can be found in the studies of Capdeville et al. (2010, 2015) and Capdeville and Métivier (2018), and its application to anisotropic media are detailed in Magali et al. (2021) and Magali et al. (2024) for P-independent and P-dependent fabrics, respectively. Elastic homogenization is based upon the minimum wavelength theory in seismology where small-scale heterogeneities in a 3-D medium with no scale separation such as

Parameter	Symbol	SC	$\mathbf{SP}$	OP	$\mathbf{M}$	Unit
Density	ρ	3150	3350	3350	3350	${ m kg} \cdot { m m}^{-3}$
Thermal diffusivity	$\overset{\cdot}{k}$	$1.0 \times 10^{-6}$	$1.0 \times 10^{-6}$	$1.0 \times 10^{-6}$	$1.0 \times 10^{-6}$	$m^2 \cdot s$
Heat capacity	$C_p$	1250	1250	1250	1250	$\rm J\cdot K^{-1}\cdot kg^{-1}$
Dislocation creep						
Activation energy	E	0	$5.4 \times 10^5$	$4.3 \times 10^5$	$4.3 \times 10^5$	$J \cdot mol^{-1}$
Activation volume	V	0	$2.0  imes 10^{-5}$	$1.85 \times 10^{-5}$	$1.5  imes 10^{-5}$	$\mathrm{mol}^3\cdot\mathrm{mol}^{-1}$
Prefactor	V	$1.0  imes 10^{-19}$	$2.4\times10^{-16}$	$2.42\times10^{-16}$	$3.91\times10^{-15}$	$Pa^{-n} \cdot s^{-1}$
Stress exponent	n	1.0	3.5	3.0	3.0	—
Diffusion creep						
Activation energy	E	0	$3.0 \times 10^5$	$2.4 \times 10^5$	$2.4 \times 10^5$	$J \cdot mol^{-1}$
Activation volume	V	0	$5.0  imes 10^{-6}$	$5.0  imes 10^{-6}$	$2.5  imes 10^{-6}$	$\mathrm{mol}^3\cdot\mathrm{mol}^{-1}$
Prefactor	V	$1.0\times10^{-19}$	$6.08\times10^{-14}$	$6.08\times10^{-14}$	$3.74\times10^{-14}$	${\rm Pa^{-n}\cdot s^{-1}}$
Plastic yielding						
Cohesion	C	$1.0  imes 10^{15}$	$1.0 \times 10^6$	$1.0  imes 10^{15}$	$1.0 \times 10^6$	MPa
Internal friction angle	$\theta$	0	20	0	20	0

Table 1: Viscoplastic rheology parameters for each compositional field.

"SC" stands for the subducting crust, "SP" for the mantle part of the subducting plate, "OP" for the overriding plate, and "M" the background mantle.

Values are loosely based on Hirth and Kohlstedf (2003).

Other input parameters in the viscoplastic material model of ASPECT are set to their default values unless otherwise specified.

Table 2: Phase transition parameters at the 410 km seismic discontinu	ity	у
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Parameter	410 km	$520 \mathrm{~km}$	660 km	Unit
Clapeyron slope	$2.55 \times 10^6$	$5.05 \times 10^6$	$-2.07\times10^{6}$	${\rm Pa} \cdot {\rm K}^{-1}$
Density contrast	370	130	320	${ m kg} \cdot { m m}^{-3}$
Phase transition width	10	10	10	$\mathrm{km}$
Phase transition temperature	1750	1850	1900	Κ

Density contrast corresponds to the expected density of a pyrolitic composition.

the true Earth are replaced with effective properties when:

$$k_{\max} = \frac{1}{\epsilon_0 \lambda_0},\tag{10}$$

where  $k_{\text{max}}$  is the maximum wavenumber of the heterogeneities,  $\lambda_0$  is the minimum wavelength of the observed wavefield, and  $\epsilon_0$  is the scale separation constant which we set to  $\epsilon_0 = 0.5$ . Capdeville and Métivier (2018) numerically verified that seismic tomography can be represented by an operator  $\mathcal{H}$  that when applied to an elastic medium **S**, the resulting effective medium **S**<sup>\*</sup> is the best possible model one could obtain from seismic tomography assuming perfect data coverage:

$$\mathbf{S}^* = \mathcal{H}^{\lambda_0}(\mathbf{S}). \tag{11}$$

Of course in the limit  $\lambda_0 \to 0$ , that is a wavefield with an infinite frequency band, one obtains the true structure **S** assuming a homogeneous distribution of source-receiver pairs.

One method to test the reliability of our anisotropy model is by comparing it with anisotropic tomography images of a subduction zone. To date, SGlobe-Rani Chang et al. (2015) and 3DLGL-TPESv.v2022-11 Debayle et al. (2016) are two of the most comprehensive global anisotropy models with the former having over 100,000 free-surface reflected S waves as data that help to constrain transition zone structures, and the latter having over 2,000,000 Rayleigh wave observations up to the fifth overtone to constrain azimuthal anisotropy at upper and mid-mantle depths. In our work, we compare our results with tomographic images of the Honshu subduction zone whose subduction style and implied geometry resemble our geodynamic model of intraoceanic subduction.

#### Text S4. Expressions for large-scale seismic anisotropy

Once the effective medium is obtained, we use two parameters that are often recovered from anisotropic tomography as means to describe our anisotropy models namely, S-wave radial anisotropy  $\xi$ , and peak-to-peak azimuthal anisotropy  $a_z$ .

In a weakly anisotropic medium, Montagner and Nataf (1986) showed that  $\xi$  is simply the radial anisotropy associated with an azimuthally-average vertically transverse isotropic (VTI) medium whose elastic constants N and L relate to  $\xi$  through:

$$\xi = \frac{N}{L},\tag{12}$$

where:

$$N = \frac{1}{8}(S_{11} + S_{22}) - \frac{1}{4}S_{12} + \frac{1}{2}S_{66})$$
(13)

$$L = \frac{1}{2}(S_{55} + S_{66}). \tag{14}$$

Likewise,  $a_z$  describes horizontally-propagating SV waves in a horizontally-transverse isotropic (HTI) medium. It depends on elastic constants  $G_c$  and  $G_s$  through:

$$a_z = 2 \frac{G_c^2 + G_s^2}{L},$$
 (15)

where:

$$G_c = \frac{1}{2}(S_{55} - S_{44}) \tag{16}$$

$$G_s = S_{54}.\tag{17}$$

Effective radial and azimuthal anisotropies across the subduction zone are shown in Figures S4 and S5, respectively, at several homogenization wavelengths:  $\lambda_0 = [10 \text{ km}, 50 \text{ km}, 100 \text{ km}, 200 \text{ km}].$ 

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Figure S1: a.) Initial and boundary conditions, and simulation domain of our 2-D geodynamic model. Four compositional fields with distinct rheological properties are included namely, subducting plate (SP), subducting crust (SC), overriding plate (OP), and the background mantle (M) whose evolution follow an advection equation. The initial temperature field follows an agebased plate cooling model that increases from the leftmost part of the modelling domain to 20 My for the OP, and from the rightmost part to 150 My for the SP. Fixed temperature boundary conditions are imposed at the top (293 K) and at the bottom (2100 K). Free slip is imposed on all sides. Red box corresponds to the domain at which we calculate seismic anisotropy. b.) Effective mantle viscosity at the present day in log[Pa-s] units.



Figure S2: (a) Density map predicted from Perple\_X for a pyrolitic mantle composition. Black contour lines correspond to arbitrary density crossovers associated with the following phase transitions: Olivine  $\rightarrow$  wadsleyite ( $\sim$ 3720 kg  $\cdot$  m<sup>3</sup>), wadsleyite  $\rightarrow$  ringwoodite ( $\sim$ 3850 kg  $\cdot$  m<sup>3</sup>), and ringwoodite  $\rightarrow$  bridgmanite ( $\sim$ 4170 kg  $\cdot$  m<sup>3</sup>). (b) Predicted 1D density,  $V_P$  and  $V_S$  structure of pyrolite (solid lines) versus the preliminary reference Earth model, PREM (Dziewonski and Anderson, 1981) (dashed lines). (c) Density structure of our subduction model at the present time using (a). White dashed rectangle corresponds to the region at which seismic anisotropy is calculated. Solid black lines delineate the subducting slab.



Figure S3: Top panel: Predicted large-scale radial anisotropy ( $\xi = V_{SH}^2/V_{SV}^2$ ) across a stagnating oceanic lithospheric slab (solid black line). Solid gray lines delineate the presumed topography of the 410 and 520-km seismic discontinuities assuming a pyrolitic mantle. Arrows represent mantle flow velocity at the final time step. Bottom panel: Computed *P*-dependent olivine and hydrous wadsleyite aggregate textures at selected locations along the model, *a-g* for olivine and *h-j* for wadsleyite, respectively. M.u.d. refers to the multiples of uniform distribution which measures texture strength.



Figure S4: Effective radial anisotropy at varying homogenization wavelengths.



Figure S5: Effective azimuthal anisotropy at varying homogenization wavelengths.