

1 **Fracture and Weakening of Jammed Subduction Shear**
2 **Zones,**
3 **Leading to the Generation of Slow Slip Events**

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7 **Key Points:**

- 8 • Fracturing of clasts in a mélange with viscosity contrasts of 10^3 occurs at applied
9 stresses 80% lower than for a homogeneous fault
- 10 • Fracturing of clasts in load-bearing force chains leads to stress redistribution into
11 the viscously creeping matrix
- 12 • A transient reduction in clast strength by 75% can increase mélange strain-rate
13 by $8\times$, potentially generating a slow slip event

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Abstract

Geodetic data have revealed that parts of subduction interfaces creep steadily or transiently. Transient slow slip events (SSEs) are typically interpreted as aseismic frictional sliding. However, SSEs may also occur via mixed visco-brittle deformation, as observed in exhumed shear zones containing mixtures (*mélange*) of strong fractured clasts embedded in a weak visco-brittle matrix. We test the hypothesis that creep in a subduction *mélange* occurs through distributed matrix deformation, where flow is modified and impeded by load-bearing clast networks. Our numerical models demonstrate that bulk *mélange* rheology can be dominated by the strong clasts in the absence of fracturing, while at high driving stresses or low frictional strength, clast fracturing redistributes deformation into the matrix, leading to high bulk strain-rates. *Mélange* stress is highly heterogeneous, fracturing some clasts even when the bulk *mélange* stresses are only 20% of the clast yield strength, though with minor strain-rate increase due to clast stress redistribution. Transient strain-rate increases have previously been modelled as periods of lowered frictional strength. *Mélange* clasts must weaken significantly ($\sim 75\%$) in order to increase strain-rate by 8x. Frictional weakening could occur through the formation of extension or extensional-shear fractures in clasts, as observed within shear networks in exhumed *mélange* outcrops. We outline a model where high bulk strain-rates are generated when pervasive fracturing occurs, but further slip is limited by viscous processes. Incorporating such viscous damping into models may widen the conditions under which SSEs can occur while preventing development of seismic slip.

Plain Language Summary

While some subduction zones are responsible for generating large, devastating earthquakes, others creep steadily or episodically. This range of deformation styles may correspond to the varying interaction of viscous creep and frictional failure, as observed in exhumed subduction shear zones, which are typically mixtures (*mélanges*) of strong fractured and weak viscous materials. We use computer models to explore how *mélange* strength and deformation style varies when the frictional material fractures. Load-bearing networks of unfractured strong material contribute significantly to *mélange* strength, so the onset of fracturing redistributes some deformation into the weak viscous material. As the force distribution in these networks is complicated, the onset of frictional failure alone is insufficient to completely unload the strong material. However, if the frictional ma-

46 terial weakens considerably, as may occur when fractures open, *mélange* may undergo
 47 a period of rapid, predominately viscous deformation. Cycles of viscous deformation may
 48 correspond to episodic creep events. If creep events do occur primarily by a viscous mech-
 49 anism, this may explain why they can occur routinely in some regions without transi-
 50 tioning to seismic slip.

51 **1 Introduction**

52 The rheology and frictional properties of the subduction thrust interface exert a
 53 first-order control on the generation of major earthquakes (Scholz, 1998) and the max-
 54 imum sustainable stresses and deformation rates at a convergent margin (Duarte et al.,
 55 2015; Behr & Becker, 2018). The down-dip limit of a subduction thrust seismogenic zone
 56 is often thought to be limited by the onset of steady viscous creep at temperatures $>350^\circ$
 57 (e.g. Hyndman et al., 1997). Slow slip events (SSEs), episodes of aseismic slip $\sim 0.1 - 1$
 58 m/year (faster than plate velocities) and commonly associated with tectonic tremor, have
 59 been observed in this transition zone (Rogers & Dragert, 2003; Schwartz & Rokosky, 2007).
 60 These events require an evolution in our understanding of the gradual spatial transition
 61 between the seismogenic zone and deeper, steady aseismic creep. SSEs have been pri-
 62 marily considered to arise due to frictional dynamics (Liu & Rice, 2005; Leeman et al.,
 63 2018). It has also been proposed that SSEs are the result of dynamic interaction between
 64 viscous and frictional deformation (Ando et al., 2012; Fagereng et al., 2014; Hayman &
 65 Lavier, 2014), though it is still unclear which visco-brittle rheological model is most ap-
 66 propriate.

67 *Mélange*, a mixture of strong clasts embedded in a weak matrix, is commonly found
 68 in exhumed subduction-related shear zones and in some places preserves a mixture of
 69 contemporaneously formed brittle and ductile structures resulting from the interplay be-
 70 tween strong (brittle) clasts and weak (ductile) matrix (Fagereng & Sibson, 2010). Ma-
 71 trix deformation is typically distributed, likely as a result of a predominately creeping
 72 process such as pressure solution, as observed at the μm scale in fine-grained phyllosil-
 73 icates, quartz and calcite, in combination with dilation of frictionally weak phyllosilicate
 74 cleavage (Bos & Spiers, 2001; Kitamura et al., 2005; Rowe et al., 2011; Wassmann & Stöckhert,
 75 2013; Fagereng & den Hartog, 2016). Such pressure solution may be responsible for sub-
 76 duction interface creep. Fractures within the *mélange*, predominately found in clasts, are
 77 indicative of locally high strength and stress (in the absence of extreme pore pressure

78 variation). Depending on the connectivity of these high stress clasts, there may be no
79 connected matrix pathways for simple shear to occur, in which case the *mélange* rheol-
80 ogy will be strong (referred to as jammed) and dependent on clast fracturing. Such load-
81 bearing networks are called force chains and their reorganisation is responsible for stick-
82 slip events in granular materials (Hayman et al., 2011). As a result of force chain dy-
83 namics, the observed viscous and brittle *mélange* deformation may preserve cycles of al-
84 ternating deformation mechanisms, perhaps generating SSEs.

85 Viscous creep, for example pressure solution of quartz, can stabilise sliding along
86 adjacent frictional minerals (Niemeijer, 2018), producing velocity-strengthening behaviour.
87 Velocity-strengthening parts of a subduction interface can produce an SSE by dampen-
88 ing an otherwise unstable rupture initiating in velocity-weakening material (Skarbek et
89 al., 2012; Luo & Ampuero, 2018). Analogue models show that slow stick-slip events can
90 occur in a macroscopically homogeneous viscoplastic material likely due to reorganisa-
91 tion of microgel force chains (Reber et al., 2015; Birren & Reber, 2019). Microscopically,
92 these events are related to reorganisation of force chains, while macroscopically they cor-
93 respond to episodic opening of tensile fractures, which grade into shear fractures and vis-
94 cious deformation accommodating overall simple shear. In contrast, slow stick-slip events
95 have been produced in rock experiments at normal stresses of < 10 MPa and high (>0.9)
96 apparatus to critical stiffness ratios (Kaproth & Marone, 2013; Scuderi et al., 2017; Lee-
97 man et al., 2018). Visco-brittle interactions are difficult to quantify in such experiments,
98 but microstructural observations indicate that frictional instabilities occur when defor-
99 mation localizes in shear bands, and slip style may be controlled by the interplay between
100 the rheology of such shear bands and the surrounding fault rock (Scuderi et al., 2017).
101 It is, however, still unclear if ductile and brittle interactions are necessary to produce
102 strain-rate transients such as SSEs, and if rheological interactions do occur, what are the
103 fundamental processes and scales at which they operate.

104 *Mélange* rheology can be dominated by weak matrix constituents if there are con-
105 nected matrix shear pathways that accommodate bulk simple shear (Handy, 1994). How-
106 ever, finite element models (Webber et al., 2018; Beall et al., 2019) demonstrate that mi-
107 nor shear strain of *mélange* with around 50% or more ellipsoidal clasts leads to the for-
108 mation of clast force chains which block matrix pathways (Fig. 1a), switch the *mélange*
109 to clast-dominated deformation (jamming), and consequently decrease strain-rate by more
110 than an order of magnitude. We explore the hypothesis that such force chains may be

111 disabled through the fracturing of clasts as their yield strength is reached after jamming
 112 (Fig. 1b), which redistributes stress into the matrix. This increase in matrix stress would
 113 consequently increase the bulk shear zone strain-rate. If this hypothesis is correct, mélange
 114 deformation would temporarily switch between being limited by frictional failure and be-
 115 ing controlled by viscous creep, as proposed in previous models (Lavier et al., 2013; Re-
 116 ber et al., 2015). Geological evidence for such visco-brittle interaction indicates this pro-
 117 cess could occur from centimetre up to 100s of metre scales (Fagereng & Sibson, 2010;
 118 Fagereng, 2011a; Rowe et al., 2011; Grigull et al., 2012; Hayman & Lavier, 2014). To in-
 119 tegrate shear zone dynamics into large scale models, mélange deformation must be pa-
 120 rameterized into a bulk rheology relating effective stresses to strain-rates and/or strain
 121 (see Section 2, below).

122 Mélangé clasts are commonly fractured, despite the low differential stress implied
 123 by creep of adjacent matrix. While fracturing is typically thought to indicate near-lithostatic
 124 pore-pressure (e.g. Sibson, 1996), Beall et al. (2019) showed that clast shear stress can
 125 be increased by $> 3\times$ due to the viscosity contrast between clasts and matrix, even in
 126 the absence of a force chain network. These models did not incorporate fracturing, so
 127 it is unclear how pervasive fracturing would be and how it affects mélange rheology. Mélangé
 128 fracture kinematics are typically consistent with matrix simple shear (Fagereng, 2011b).
 129 Fractures are also commonly confined to clasts or transition into terminating shear frac-
 130 tures in the matrix (Fisher & Byrne, 1987; Raimbourg et al., 2009; Fagereng, 2013). While
 131 these observations support a model of contemporaneous frictional and viscous deforma-
 132 tion, it is unclear how frictional failure would affect the bulk mélange rheology. In this
 133 study, we incorporate fracturing into our numerical mélange models and quantify both
 134 1) how pervasive clast fracturing is at varying shear zone stress, and 2) whether fractur-
 135 ing could effectively disable force chains and increase shear zone strain-rates.

136 **2 Bulk Rheology of a Subduction Interface: Theoretical Mixture Model** 137 **Predictions**

138 Geodynamic models of visco-brittle subduction interface deformation typically com-
 139 bine one viscous and one brittle rheology into a composite rheology (Karato, 2012), fol-
 140 lowing the assumption that both rheologies experience either the same stress (the Reuss
 141 model) or the same strain (the Voigt model). The choice of Reuss or Voigt model dic-
 142 tates which rheology dominates at low and high stress (Fig. 1c).

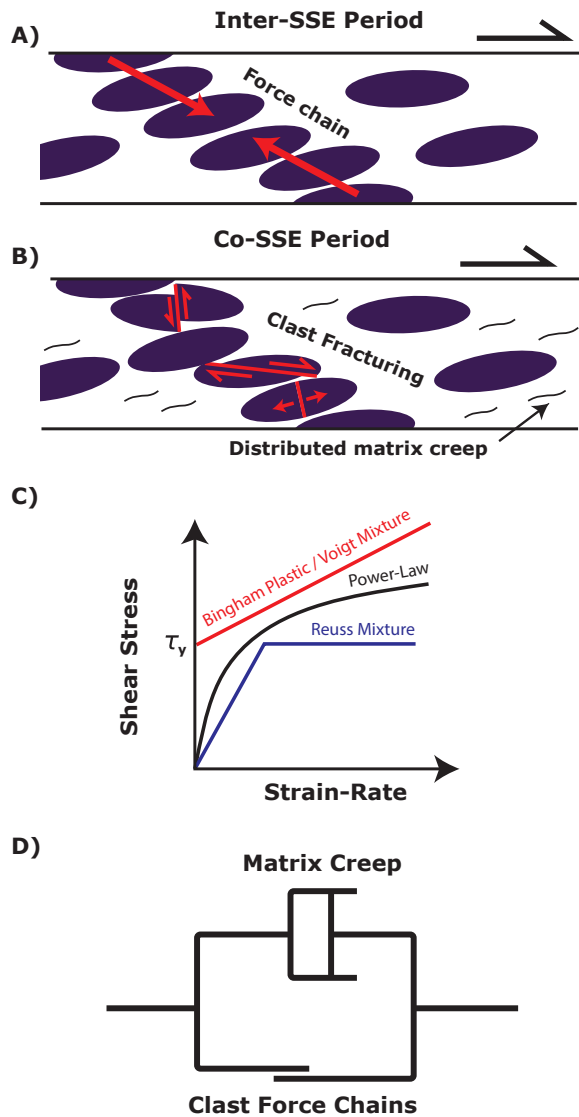


Figure 1. A) Periods of low megathrust creep in-between SSEs are hypothesised to be due to the formation of clast force chains, which prevent viscous matrix deformation. B) When clasts fracture, stress may be redistributed to the weak matrix, switching the mélange to predominately viscous deformation with a high strain-rate. C) Schematic comparison of the Voigt (equivalent to Bingham plastic) and Reuss mixture models (and comparison to power-law rheology). When fracturing begins at $\tau = \tau_y$ (or lower if stress amplification is considered), the Voigt model is rate-limited by viscous deformation, while the Reuss model becomes stress-limited by frictional deformation (which may be modestly rate-strengthening or weakening, or constant as shown here). D) We hypothesise that the rheology of a jammed mélange can be modelled as a viscous dashpot (matrix creep) in parallel with a frictional slider (fracture of clasts, neglecting their slow viscous creep), equivalent to a Bingham plastic.

143 The Reuss model represents material that can always viscously flow (though slowly
 144 for high viscosities), but switch to frictional deformation if a yield stress is reached. For
 145 predominately viscous slip transients to occur in a Reuss mixture, the viscous rheology
 146 must be highly non-linear (e.g. incorporating shear heating; Goswami & Barbot, 2018).
 147 The Voigt model, which is equivalent to a Bingham plastic when one of the materials
 148 is frictional (Fig. 1c), represents a material that does not deform at all until frictional
 149 sliding occurs, at which point viscous deformation becomes rate-limiting and a low vis-
 150 cosity may produce high strain-rates (used by Ando et al., 2012; Lavier et al., 2013).
 151 Stress-dependent viscous deformation is generally captured by the power-law rheology
 152 $\dot{\epsilon} \propto \sigma^n$ (Fig. 1c) for maximum shear strain-rate $\dot{\epsilon}$ and stress τ (Karato, 2012). The mag-
 153 nitude of the stress exponent n dictates how stress-dependent the rheology is, for exam-
 154 ple $n \approx 3$ for dislocation creep and $n \rightarrow \infty$ for a plastic material with a yield strength.
 155 It is unclear which model best captures the rheology of a subduction interface shear zone.

156 If a *mélange* only deforms when clasts in a force chain can deform, then assuming
 157 that clast and matrix strain is equal will give the Voigt / Bingham model. This model
 158 is supported by GPS records, which generally show that inter-SSE locking is high on in-
 159 terface patches hosting SSEs (e.g. Wallace & Beavan, 2010). If clast and matrix stresses
 160 are each homogeneously defined by constants τ_{clast} and τ_{matrix} , their stresses are related
 161 to the bulk stress by $\tau = \phi\tau_{clast} + (1 - \phi)\tau_{matrix}$. If clasts are purely frictional, τ_{clast}
 162 is limited to a yield stress τ_y , and if τ_{matrix} is controlled by Newtonian viscous creep $2\eta\dot{\epsilon}$
 163 (e.g. pressure solution creep), then an effective rheology is given by Eq. 1, i.e. a Bing-
 164 ham rheology (Fig. 1c-d), where viscous creep occurs if bulk *mélange* stress $\tau \geq \phi\tau_y$.

$$\tau = \phi\tau_y + 2(1 - \phi)\eta\dot{\epsilon} \quad (1)$$

165 This simple model predicts that frictional failure and the activation of viscous flow
 166 occurs at a bulk stress which is lower than the frictional clast strength, as stress is fo-
 167 cussed into only the clast volume (controlled by ϕ). This stress amplification has been
 168 shown to occur in models with complex force chain geometries, where frictional yield oc-
 169 curs for bulk stresses well below the clast yield limit due to the clast-matrix viscosity con-
 170 trast (Beall et al., 2019). Eq. 1 also predicts that the viscous strain-rate will be zero when
 171 frictional failure first occurs, as $\tau_{matrix} = 0$ when $\tau = \phi\tau_y$, unless τ_y is dynamically
 172 decreased or τ is increased further. Clast stresses are not, however, likely to be homo-

173 geneous for realistic force chain geometries and matrix strain-rate will not be completely
 174 zero, so the predicted stress for the onset of visco-brittle deformation is an approximate
 175 guide.

176 **3 Methodology**

177 The modelling methodology is adapted from Beall et al. (2019), in which a New-
 178 tonian viscous *mélange* was modelled as lens-shaped clasts embedded in a matrix, where
 179 the clasts had a viscosity $10\text{--}10^4\times$ higher than the matrix. The velocity at the top bound-
 180 ary was derived by applying a constant driving stress, allowing an effective strain-rate
 181 and bulk viscosity to be calculated, as well as the *mélange* stress distribution, as a func-
 182 tion of the viscosity contrast, clast proportion ϕ and shear zone thickness. Jamming of
 183 *mélange* with a viscosity contrast of 10^3 resulted in an effective viscosity increase of 2--
 184 $7\times$ and clast shear stress of $6\text{--}9\tau$ (for applied driving stress τ), over the range $0.5 \leq$
 185 $\phi \leq 0.64$. Here, we build upon these previous models by incorporating frictional fail-
 186 ure into the clast rheology. This study also follows Webber et al. (2018), though is more
 187 simplified in order to characterise *mélange* rheology in a generalised manner.

188 Shear zone deformation is modelled as incompressible creeping viscous flow, via the
 189 continuum-mechanics finite-element particle-in-cell code Underworld, which solves the
 190 Stokes equations. The matrix has a Newtonian viscosity η_m , representing diffusion creep
 191 processes such as the pressure solution observed in quartz-phyllsilicate mixtures (Bos
 192 & Spiers, 2001; Fagereng & den Hartog, 2016; Niemeijer, 2018) at temperatures of $\geq 100^\circ\text{C}$
 193 and within a range of fine-grained metamorphic assemblages at lower crustal conditions
 194 (Wassmann & Stöckhert, 2013). Frictional failure is incorporated by checking if each point
 195 within the clast material has a maximum shear stress $\tau_{max} = (\sigma_1 - \sigma_2)/2$ (where σ_1
 196 and σ_2 are the in-plane principal stresses) exceeding a frictional strength τ_y , in which
 197 case an effective viscosity is iteratively calculated at that point in order to satisfy $\eta_f =$
 198 $\frac{1}{2}\tau_y/\dot{\epsilon}_{max}$ (for maximum shear strain-rate $\dot{\epsilon}_{max}$ at that point in space and time; follow-
 199 ing Fullsack, 1995; Moresi & Solomatov, 1998). The yield stress is either set to a con-
 200 stant or to the Coulomb failure criteria Eq. 2, for friction coefficient μ , cohesion C and
 201 effective mean stress σ_{eff} (Jaeger et al., 2007).

$$\tau_y = \frac{\mu\sigma_{eff} + C}{\sqrt{1 + \mu^2}} \quad (2)$$

Table 1. Summary of model-sets and parameters.

Model-set	Frictional Parameters	Clast Proportion (ϕ) and Maximum Width (D_{max})
A	$\mu = 0.7, C = 50\text{MPa}$ ($\tau_y \approx 160\text{MPa}$)	$\phi = 0.3, 0.5, 0.61$ ($D_{max} = 0.14$), $\phi = 0.61$ ($D_{max} = 0.28$)
B	$\tau_y = 200\text{MPa}$	$\phi = 0.61$ ($D_{max} = 0.14$)
C	$\tau_y = 50\text{MPa}$	$\phi = 0.61$ ($D_{max} = 0.14$)

202 σ_{eff} is calculated as $(p + \rho gz)(1 - \lambda)$, where p is a dynamic pressure deviation from
 203 the lithostatic pressure, ρ is the average overburden density set to 2650 kg m^{-3} , g is grav-
 204 itational acceleration, z is depth and λ is the prescribed ratio of pore-pressure to litho-
 205 static pressure. We study deformation at a depth of $z = 40 \text{ km}$, roughly matching the
 206 depth of SSEs in Cascadia (Rogers & Dragert, 2003), southern Hikurangi (Wallace &
 207 Beavan, 2010) and the deep SSEs in Nankai (Obara et al., 2004). We assume $\lambda = 0.8$,
 208 which is intermediate between hydrostatic and lithostatic (Saffer & Tobin, 2011). This
 209 gives $\sigma_{eff} \approx 208 \text{ MPa}$ (when $p = 0$) for the models .

210 The model dimensions can be rescaled, in order to explore a wider parameter space.
 211 We assume that the model stress can be non-dimensionalised as Eq. 3. The accuracy of
 212 this scaling should vary depending on the degree to which the bulk strain-rate of the mélange
 213 is a function of τ_y . We test the applicability of this scaling for jammed mélange. It then
 214 follows that time t (and therefore strain-rate) can be non-dimensionalised as Eq. 4.

$$\tau' = \frac{\tau}{\tau_y} \quad (3)$$

$$t' = t \frac{\tau_y}{\eta_m} \quad (4)$$

215 We set $\mu = 0.7$ and $C = 50 \text{ MPa}$, representing frictionally strong clasts (e.g. un-
 216 fractured sandstone or basalt) close to Byerlee's law (Jaeger et al., 2007). Clast regions
 217 which do not meet the failure criterion have a Newtonian viscosity set to $\eta_c = 10^3 \eta_m$,
 218 representing a large viscosity contrast in the mélange. We also run models with either
 219 a high or low constant τ_y in order to explore frictional weakening and test our scaling
 220 predictions (parameters summarised in Table 1).

221 As incompressibility is assumed, deformation involving tensile fracture cannot be
 222 calculated, but the onset of tensile failure can be predicted. The calculations with vary-
 223 ing τ_y and the scaling approach allow us to explore how mélangé rheology depends on
 224 clast yield stress, where clast yield includes tensile fracture if it occurs. Tensile failure
 225 is assumed to occur when minimum in-plane principal stress $\sigma_2 = T$ for a constant ten-
 226 sile strength T . This tensile yield criterion can be rewritten as Eq. 5.

$$\tau_y = \sigma_{eff} + T \quad (5)$$

227 At a specific depth, the Coulomb and tensile failure criteria can be approximated
 228 by a constant τ_y by assuming that the normal stress is equal to the effective lithostatic
 229 pressure (setting $p = 0$). This neglects normal stress variations within the mélangé, which
 230 are likely to be small compared to the lithostatic pressure for the 40 km depth modelled.

231 A constant shear traction τ is applied to the top model wall, representing the bulk
 232 shear stress to drive deformation (e.g. Webber et al., 2018). A highly viscous Newtonian
 233 material with viscosity $10^3\eta_m$ is included in the upper 5% of the model domain, in or-
 234 der to distribute this stress within the underlying mélangé. As the bulk rheology of the
 235 mélangé is of primary interest, a bulk shear strain-rate $\dot{\epsilon}$ is calculated as $0.5V_{av}/L$ for
 236 average horizontal velocity on the top wall V_{av} and model height L . We set $L = 100\text{m}$,
 237 a typical active subduction shear-zone thickness (Rowe et al., 2013) and the model width
 238 to $4L$ with periodic boundary conditions. The velocity magnitude is set to zero on the
 239 lower boundary. The element resolution is 2048×512 , equivalent to a mesh node spac-
 240 ing of 4.9 cm for $L = 100\text{m}$.

241 The ratio of the clast short-axis length to the shear zone width ($L = 100\text{m}$) is de-
 242 fined as D . Within most models, D varies from over $0.05 \leq D \leq 0.14$ (labelled as $D_{max} =$
 243 0.14 , Table 1). This choice of D_{max} results in a force chain length scale which is smaller
 244 than L and therefore a conservative estimate of jamming (Beall et al., 2019). A model
 245 with clasts of size $0.1 \leq D \leq 0.28$ is also included ($D_{max} \leq 0.28$) for $\phi = 0.64$, with
 246 identical model resolution and dimensions, in order to test whether the choice of D_{max}
 247 affects the bulk visco-brittle rheology. All clasts have a short to long axis ratio of 3. Their
 248 sizes are chosen to follow a power-law distribution with exponent -2, reflecting clast size
 249 distributions in visco-brittle shear zones (Fagereng, 2011a; Grigull et al., 2012). As the
 250 clast geometries are fractal (though limited to a minimum clast size due to the limited

251 mesh resolution), the clast sizes can be scaled up to thicker shear zones with larger clasts
 252 or down to cm-m scale shear zones. Calculations of stress-strain-rate relationships are
 253 therefore scale-invariant, provided our clast geometries and simplified rheologies hold.
 254 Such scaling is limited at the large scale by the largest clast dimension (blocks up to 100
 255 m long have been observed; Grigg et al., 2012) and the breakdown of the simplified rhe-
 256 ology at the small scale (grain-scale processes are critical at and below the mm scale; Fagereng
 257 & den Hartog, 2016).

258 As the clasts are originally randomly orientated and with minimal force chains present,
 259 a setup model is run for each volumetric clast proportion ϕ up to a shear strain of $\epsilon =$
 260 2 to generate a strained *mélange* with force chains (if ϕ is sufficiently high). This is used
 261 as a starting material distribution for the main model experiments. The setup runs ne-
 262 glect clast fracturing, for both computational efficiency (numerical iterations are not re-
 263 quired) and to provide identical starting conditions for all models with a given ϕ . The
 264 setup strain is sufficient for force chains to form (where ϕ is high enough), though fur-
 265 ther jamming may occur at higher strain. *Mélange* formation through disaggregation of
 266 stratigraphy and significant simple shear has been inferred to occur before and during
 267 lithification (Fagereng, 2011b; Festa et al., 2012). Our initial conditions could therefore
 268 apply to any depth.

269 4 Results

270 4.1 Simplified Force Chain Model

271 We firstly test the applicability of Eq. 1, an idealised Voigt (iso-strain) mixture /
 272 Bingham rheology, to an idealised numerical model. The visco-brittle clast rheology is
 273 assigned to one column orientated at 45° to the horizontal in the direction of greatest
 274 compressive stress. This column represents a force chain, is assigned a constant $\tau_y =$
 275 170 MPa, a width giving $\phi = 0.1$ and is embedded in a viscous matrix (Fig. 2a). Eq.
 276 1 predicts onset of creeping for a bulk stress of 17 MPa. In the numerical model, the in-
 277 stantaneous strain-rate was calculated for a variety of boundary shear stress magnitudes.
 278 The simple force chain model almost exactly matches Eq. 1, with the minor exception
 279 of a non-zero, though negligible, strain-rate when $\tau < \phi\tau_y$ due to the model clast rhe-
 280 ology being viscoplastic rather than perfectly plastic (i.e. in the numerical model creep
 281 is allowed when $\tau_{max} < \tau_y$). The Bingham rheology therefore has the potential to cap-

282 ture the bulk rheology of a numerical model when the iso-strain (Voigt) assumption holds.
 283 Whether this holds for complicated force chain geometries is explored in the following
 284 sections.

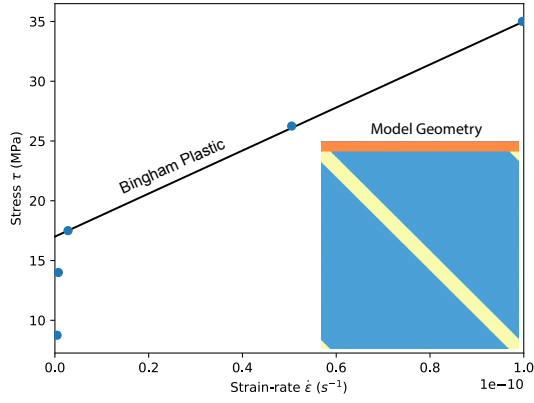
285 4.2 Melange Fracturing at Low Melange Boundary Stress

286 We use Model-set A (Table 1) as a strong end-member to test whether stress-amplification
 287 leads to significant fracturing even at bulk stresses much lower than the clast yield stress.
 288 For a depth of 40 km, fluid-pressure ratio $\lambda = 0.8$ and in the case that $p = 0$, the fric-
 289 tional parameters for set A give a yield stress $\tau_y = 160$ MPa (Eq. 2). Results show that
 290 all models, including for applied stress as low as $\tau = 21$ MPa (non-dimensionalised $\tau' =$
 291 0.13), involved some clast yielding, in which case the clast η_{eff} locally reduces by at least
 292 an order of magnitude (in order to satisfy $\tau_{max} = \tau_y$). As we are interested in how frac-
 293 turing affects dynamics at the shear-zone scale, a better measure of the lower threshold
 294 for fracturing is the lowest bulk stress τ modelled for which there is a chain of fractur-
 295 ing clasts spanning L . In this case, fracturing occurs at $\tau \geq 35$ MPa ($\tau' \geq 0.22$, Fig.
 296 3) for $\phi = 0.5$, $D_{max} = 0.28$ and $\phi = 0.61$, $D_{max} = 0.14$, while fracturing requires
 297 $\tau \geq 70$ MPa ($\tau' \geq 0.44$) for $\phi = 0.5$ and $\phi = 0.3$, $D_{max} = 0.14$. This shows that sig-
 298 nificant fracturing can occur when applied stress τ is substantially less than τ_y , partic-
 299 ularly for jammed melange and a volumetric clast proportion $> 50\%$, owing to stress
 300 amplification in the clasts.

301 Clast fracturing occurs at low ratios of driving stress to clast yield stress, $\tau' = 0.22$.
 302 The occurrence of fracturing only depends on τ' (as demonstrated in Section 4.4) and
 303 can therefore be used to calculate the driving stress τ required to generate fracturing for
 304 a specified τ_y , including for tensile failure. Assuming $T = 3.5$ MPa (the ratio of C to
 305 T is typically ≈ 15 for sandstone and greater for crystalline rocks; Jaeger et al., 2007),
 306 then the corresponding yield stress for tensile failure is $\tau_y = 211$ MPa (Eq. 5). A driv-
 307 ing stress of $\tau = 42$ MPa (equivalent to $\tau' = 0.22$), could then generate tensile frac-
 308 turing. Driving shear stresses of ~ 10 MPa are therefore sufficient to generate shear and/or
 309 tensile fracturing of clasts at $z = 40$ km when $\lambda = 0.8$ (the dominant fracture mode
 310 depending on the orientation of existing weak planes).

311 The Coulomb failure criterion may be satisfied by shear in two conjugate directions.
 312 However, simple shear is expected to be accommodated by sliding predominately along

A)



B)

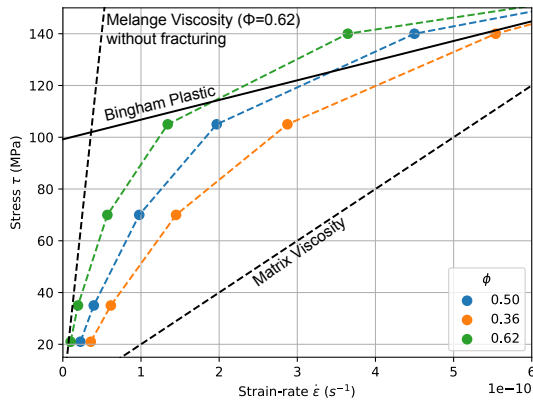


Figure 2. Comparisons of idealised (A) and mlange (B) force chain models to the Bingham plastic rheology. A) Model geometry, inset, of clast material (yellow, $\phi = 0.1$) embedded in matrix (blue) with high viscosity 'grip' material on top (orange). Measurements of τ (points) follow the Bingham plastic rheology (solid line, Eq. 1). B) Model-set A data (for $D_{max} = 14\text{m}$), compared to the Bingham rheology and mlange viscosity in the absence of fracturing, for $\phi = 0.62$, as well as η_m .

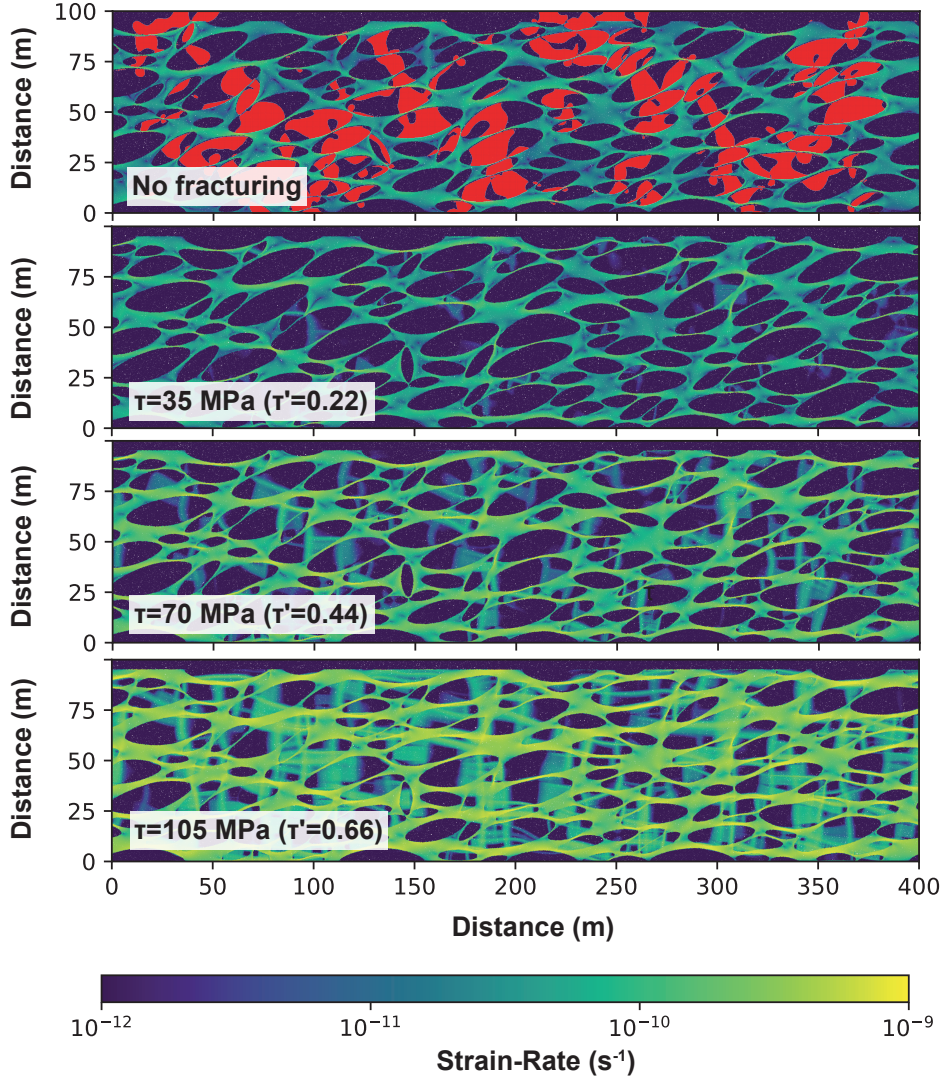


Figure 3. Mélange from model-set A with $\phi = 0.62$, $D_{max} = 14\text{m}$ and $\eta_m = 10^{17}$ Pa s. For reference, a model with $\tau = 35$ MPa, fracturing prevented and regions with maximum shear stress increased above τ by $\geq 5\times$ colored red. Models with τ varying from 35 to 105 MPa are also shown, demonstrating that the number of clasts reaching the frictional failure criterion increases dramatically with increasing τ and contributes to a significantly higher matrix strain-rate at high τ' compared to a linear rheology.

313 planes sub-parallel to the shear zone boundary in order to satisfy mass conservation in
 314 a homogeneous shear zone with constant thickness. Shear along planes sub-parallel to
 315 the shear zone boundary is also the most efficient way of localising simple shear defor-
 316 mation, as no rotation or fracture network is required. Yielding in the models, however,
 317 is localised into conjugate sets of failure planes (Fig. 3). Conjugate sets should be sym-
 318 metrical around σ_1 (which is 45° clock-wise from the shear zone boundary for the dex-
 319 tral shear sense modelled), which is generally observed in the models (with minor de-
 320 viation due to stress rotation). In contrast to a homogeneous incompressible material,
 321 the shear failure accommodates pure shear of the clasts, which are extended in the di-
 322 rection of σ_2 , as evident in the final clast geometries. Localised pure shear of the clasts
 323 occurs in the incompressible model because it is compensated by simple shear within the
 324 viscous matrix.

325 The Coulomb failure criteria predicts that failure will predominately occur on planes
 326 orientated at angles $\pm \tan^{-1}(\mu)/2 = \pm 17.5^\circ$ to σ_1 . Numerical models only reproduce
 327 this Coulomb failure angle when a high resolution is used relative to initial stress per-
 328 turbations and shear bands (Kaus, 2010), otherwise shear failure occurs on planes ori-
 329 entated closer to $\pm 45^\circ$ to σ_1 (called the Roscoe angles). Yielding zones localise in our
 330 models due to the pressure-dependence of the Coulomb criteria, however are still rela-
 331 tively broad ($< 10m$) as no strain softening was incorporated. Failure occurs along bands
 332 orientated at a range of angles between the Coulomb and Roscoe angles. The deviation
 333 from the Coulomb angles may be due to the mesh resolution being too coarse in places
 334 to sufficiently resolve stresses inside the clasts, though this deviation should not signif-
 335 icantly affect clast deformation or stress magnitude.

336 4.3 General Mélange Rheology

337 Each model in model-set A (Table 1) was repeated with the imposed stress bound-
 338 ary condition varying through $\tau = 21, 35, 70$ and 140 MPa, in order to characterise the
 339 effective mélange rheology (Figs. 2b and 4). The models share some of the character-
 340 istics of the Bingham rheology; at low applied stress the effective mélange viscosity can
 341 be much higher than η_m ($< 15\times$ for these models, depending on ϕ) and at high applied
 342 stress the behaviour is dominated by viscous matrix deformation (the slope $d\tau/d\dot{\epsilon}$ is sim-
 343 ilar to that of the Bingham plastic prediction in Fig. 2b). However, for $\phi = 0.61$ and
 344 $\tau = 70$ MPa the fracturing causes the bulk strain-rate to be about $2\times$ higher than ex-

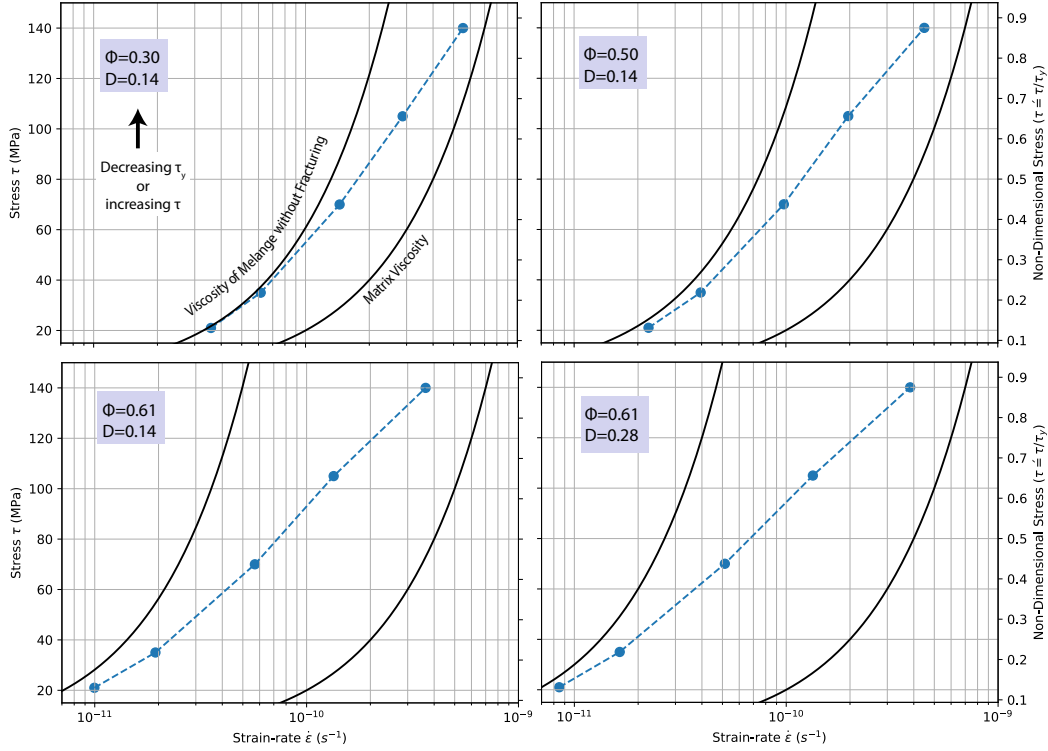


Figure 4. Rheologies of the models in model-set A, demonstrating that strain-rate increases exponentially with stress with a viscosity spanning that of *mélange* without fracturing at low τ , to η_m at high τ . The highest and lowest jamming occurs for $\phi = 0.61$ and 0.30 respectively, which correspond to the highest and lowest strain-rate variation.

345 expected for the jammed *mélange*. This heralds a transition to predominately visco-brittle
 346 deformation, which occurs at a lower stress than the 100 MPa predicted for the simpli-
 347 fied Bingham rheology. This is due to the heterogeneous stress distribution in the clasts,
 348 compared to the homogeneous stress assumed in the simplified model.

349 While the Bingham rheology is dominated by its viscous constituent when fractur-
 350 ing occurs, the corresponding *mélange* rheology at high stress is non-Newtonian and strain-
 351 rate increases exponentially with stress (i.e τ appears to be logarithmically dependent
 352 on $\dot{\epsilon}$) for $\tau \geq 35$ MPa ($\tau' = 0.22$). Accordingly, fitting a power-law relationship of $\dot{\epsilon} \propto$
 353 σ^n (though an exponential form provides a superior fit) gives $n \sim 2$, rather than the
 354 $n > 10$ that would correspond to a highly non-linear rheology appropriate for a Reuss
 355 mixture.

356 Mélange viscosity should always be greater or equal to the matrix viscosity when
 357 $\tau \leq \tau_y$ and less or equal to an identical mélange in which fracturing is prohibited (i.e.
 358 a model without frictional failure incorporated). These limits represent the strength end-
 359 members (solid black curves, Fig. 4). All of the model bulk rheologies, regardless of ϕ ,
 360 follow a similar transition from one approximating the strong end-member (no fractur-
 361 ing) at the lowest τ (21 MPa or $\tau' = 0.13$), to resembling the weak end-member (matrix-
 362 dominated) for $\tau' \approx 0.75 - 0.9$ (the higher end of the range for greater ϕ). This rheo-
 363 logical trend demonstrates that all mélange models, regardless of jamming, are weakened
 364 by fracturing even when $\tau < \tau_y$. While the bulk behaviour is bounded by the fracturing-
 365 free and clast-free viscosity end-members, fracturing of a jammed mélange results in higher
 366 strain-rate variation compared to these limiting cases (Fig. 4).

367 The exponential rheology $\tau \propto \ln(\dot{\epsilon})$ arises because stress is not homogeneously
 368 distributed across force chains. The probability distribution of clast points with a partic-
 369 ular maximum shear stress are shown in Fig. 5 for models with a range of τ . For $\tau =$
 370 21 and 35 MPa, the most common stress corresponds to the bulk shear stress τ . More
 371 clast particles have a stress higher than τ , than those with a stress lower than τ , result-
 372 ing in a skewed normal distribution. Stresses higher than τ result from stress ampli-
 373 fication within force chains, which occurs to a varying degree. The normal distribution
 374 shows, for example, that a stress amplification of $2\times$ is more common than $5\times$. Only a
 375 small number of force chains therefore fail when $\tau \ll \tau_y$. For an incremental increase
 376 in scaled stress τ' (corresponding to a τ increase or a τ_y decrease), a much higher num-
 377 ber of clasts will fracture due to the non-linear stress distribution, resulting in a non-
 378 linear rheology. Stress cannot exceed the failure criterion (it has the appearance of do-
 379 ing so only due to the pressure-dependence introduced by μ), so with increasing τ , clast
 380 stress becomes more uniform as it is redistributed, resulting in a peak at τ_y in Fig. 5.
 381 By $\tau = 70\text{MPa}$ ($\tau' = 0.44$), most clasts are likely to be undergoing frictional failure.

382 4.4 Frictional Weakening and Scaling

383 Two extra sets of models with $\phi = 0.61$ and a constant yield stress τ_y were run
 384 (B and C, Table 1), for $\tau_y = 50\text{MPa}$ and $\tau_y = 200\text{MPa}$, to explore how the visco-
 385 brittle mélange rheology depends on the magnitude of clast frictional strength. These
 386 models are used to test the hypothesised scaling relationships Eqns. 3 and 4, which can
 387 then be used to rescale the existing models for any τ_y and η_m .

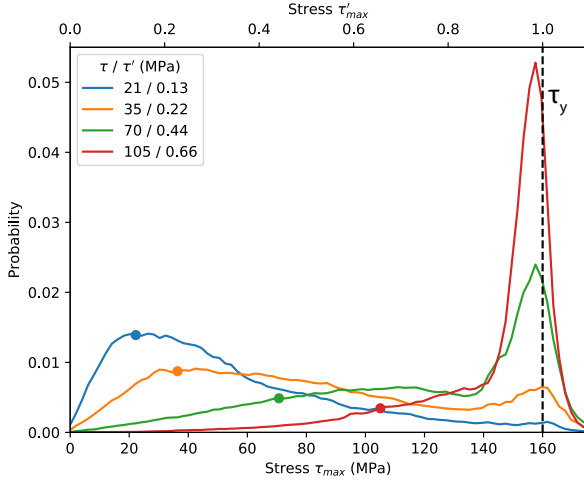
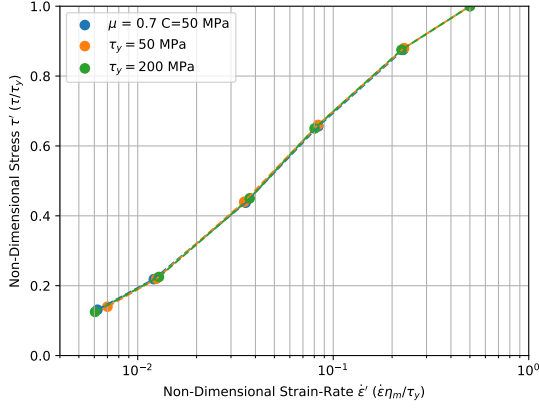


Figure 5. Maximum clast shear stress probability distribution, calculated from all Lagrangian particles identified as clast material, for $\phi = 0.61$, $D_{max} = 14\text{m}$, $\tau_y \approx 160\text{MPa}$ (model-set A) and τ ranging from 21 to 105 MPa (bulk stresses shown by points). At low τ , stress follows a skew normal distribution, capturing heterogeneous stress amplification in force chains. At high τ , stress is limited by τ_y .

388 When non-dimensionalised, all model-sets with $\phi = 0.61$ collapse onto the same
 389 curve as predicted by scaling relations (Fig. 6a). The non-dimensionalised datasets with
 390 $\mu = 0$ and $\mu = 0.7$ (pressure independent and dependent τ_y respectively) are identi-
 391 cal, indicating that the pressure-dependence of the frictional law and therefore the op-
 392 timal angle of frictional failure, does not influence the modelled bulk m \acute{e} lange viscosity.

393 Fig. 6b demonstrates how strain-rate, and therefore velocity at the shear zone wall,
 394 would increase if τ_y were decreased for all of the clasts from 200 MPa to 50 MPa. The
 395 scaling relationships are also used to calculate an intermediary case of $\tau_y = 80$ MPa.
 396 For $\eta_m = 5 \times 10^{17}\text{Pa s}$ (assumed for Fig. 6b) and $L = 100\text{m}$, the average shear zone
 397 boundary velocity V_{av} is about 2 cm/yr when $\tau = 50$ MPa and $\tau_y = 200$ MPa. This
 398 is equivalent to $\tau' = 0.25$, which is sufficient for fracturing of clasts in the force chains
 399 with the highest stress amplification (similar to Fig. 3b). In order to increase the veloc-
 400 ity to 4 cm/yr, the clast yield strength needs to be reduced to $\tau_y = 80$ MPa, for ex-
 401 ample due to extreme strain-weakening as clasts fracture and distribute stress more evenly
 402 across the force chains. Should τ_y decrease to $\tau_y = 50$ MPa, the velocity would increase
 403 up to 16 cm/yr and the matrix would have a similar stress state to the clasts. This ex-

A)



B)

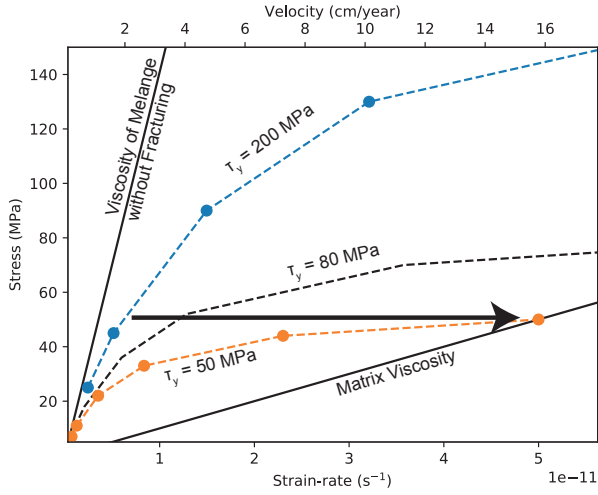


Figure 6. A) Model-sets A-C for $\phi = 0.62$ and $D_{max} = 14$ m, plotted for non-dimensional variables τ' and ϵ' (Eqs. 3 and 4). All data collapses onto one curve, confirming the scaling of stress using τ_y . B) Model sets B and C, with a third case for $\tau_y = 80$ MPa plotting using the scaling relationship and assuming $\eta_m = 5 \times 10^{17}$ Pa s. Velocity is calculated assuming $L = 100$ m. In the case of a constant $\tau = 50$ MPa, deformation of mélangé containing clasts with a high frictional strength, $\tau_y = 200$ MPa, results in a velocity of 2 cm yr^{-1} . Reducing the clast frictional strength to 50 - 80 MPa (indicated by arrow) would increase this to 4 - 16 cm yr^{-1} .

ample demonstrates that τ' must be initially relatively low in order to generate a large strain-rate transient.

5 Discussion

We previously predicted, and have tested here, that fracturing could occur at relatively low applied shear stress in a *mélange* due to stress amplification, and this stress amplification could lead to a transient period of high strain-rate until the *mélange* jams again (Beall et al., 2019, Fig. 1a-b). Fracturing of clasts involved in force chains does indeed occur at low bulk stress, lowering the stress within the most load-bearing force chains. The fracturing also allows surrounding matrix to creep by releasing the jammed portion of the *mélange*. We found that clast fracturing can occur when $\tau \approx 35$ MPa and $\lambda = 0.8$, even at 40 km depth. More generally, fracturing of multiple force chain clasts (Figs. 3 and 5) occurs when $\tau > 0.22\tau_y$. Fracturing of clasts within a *mélange* therefore may be just as indicative of a large strength contrast between the matrix and clast minerals, as extreme pore pressure (e.g. Webber et al., 2018).

The models verify that deformation of jammed *mélange* switches from clast to matrix dominated with increasing bulk stress, as predicted by the Bingham model. In a mixture of strong frictional clasts and weak viscous matrix, mixed visco-brittle deformation may record periods of high stress and/or weakened clasts and therefore high strain-rates (creating slip transients, e.g. SSEs), the duration of which may be related to transient effective stress and healing of fractures. Fracturing at low τ does not, however, result in the dramatic switch to viscous deformation predicted by the Bingham model. This is because clast stresses follow a skew normal distribution and weakening of a force chain with the highest stress amplification does not weaken the force chains with less stress amplification (Fig. 5). This effect does, however, result in a non-linear bulk rheology, as each increment of stress weakens a greater number of force chains at higher stress. The highest strain-rate variation therefore results from changes to the proportion of clasts undergoing frictional failure. As force chains in a jammed material are critically organised, weakening of one force chain will lead to stress redistribution and an entire shear zone can be unjammed if clast weakening is high.

Compared to the weak stress-dependence of frictional sliding, viscous systems are extremely damped (stress-dependent). For example, the viscous strain-rate in a Bing-

435 ham material increases from zero, when fracturing begins, to $\dot{\epsilon} \propto (\tau - \phi\tau_y)/\eta$ (Eq. 1).
 436 A large $\dot{\epsilon}$ therefore requires a large stress increase, large yield stress decrease, or a small
 437 viscosity. Ando et al. (2012) inferred that τ_y dynamically decreases by a similar mag-
 438 nitude to the SSE stress drop (typically only 10-100 kPa; Brodsky & Mori, 2007) and
 439 as a result predicted an extremely low $\eta_m \sim 10^{11}$ Pa s in order to reproduce SSE ve-
 440 locities. Stress drop in this system, however, could instead be limited by the viscous strain
 441 during the SSE and is not necessarily related to τ_y (as would be the case in a Reuss mix-
 442 ture). A large dynamic decrease in τ_y could drive the viscous strain-rate increase. In our
 443 models, the frictional clast strength would need to reduce by $\sim 75\%$ to result in an $8\times$
 444 increase in strain-rate (Fig. 6). Should large local variations in τ_y occur, then velocities
 445 could transiently increase from 2 up to 16 cm yr⁻¹ (plate velocity rates and higher) across
 446 a 100 m thick *mélange* shear zone with $\eta_m = 5 \times 10^{17}$ Pa s for $\tau = 50$ MPa (Fig. 6).
 447 The predicted matrix viscosity is relatively low, but can be reconciled with pressure-solution
 448 creep (Niemeijer, 2018) or phyllosilicate flow laws (Mares & Kronenberg, 1993; Hilairet
 449 et al., 2007).

450 Though the degree of frictional weakening predicted is significantly higher than the
 451 $\sim 1\%$ weakening typical of frictional sliding at $\sim 10^{-4}$ m s⁻¹ (Marone et al., 1990), it
 452 could be explained by opening of extension or extensional-shear fractures in clasts, as
 453 an opened fracture becomes a free surface. Such through-going fractures with a tensile
 454 component are commonly observed in *mélange* clasts (Fig. 7a), and can be confined to
 455 the clasts and form at an angle of 80° to discrete shear surfaces parallel to the shear zone
 456 S-fabric (Fagereng, 2011b, 2013). These fractures accommodate extension of the clasts
 457 (pure shear), which is kinematically consistent with simple shear partitioned into and
 458 accommodated by the matrix. The *mélange* models also deform by this combination of
 459 clast pure shear and matrix simple shear. If tensile fracturing were incorporated and favourable
 460 over shear failure, the modelled conjugate failure planes would likely be replaced with
 461 single tensile fractures. Localised visco-brittle clast deformation grades into distributed
 462 viscous matrix deformation in the models, due to the choice of rheologies. These rhe-
 463 ologies reflect observed *mélange* deformation, where fractures within and at the edges
 464 of clasts grade into distributed matrix deformation at both thin-section and outcrop scale
 465 (Fagereng & Sibson, 2010; Hayman & Lavier, 2014).

466 Simple shear of *mélange* may occur by combined deformation of a network of visco-
 467 brittle matrix shears and connecting tensile fractures as described in several field exam-

468 ples (Fig. 7b; Sibson, 1996; Meneghini & Moore, 2007; Fagereng et al., 2010; Ujiie et al.,
 469 2018). Such shear-fracture meshes within a ductile matrix are analogous to our model,
 470 which is rate-limited by viscous deformation when clast fracturing occurs. This model
 471 of local fracturing limited by surrounding ductile creep applies when there is no inter-
 472 connected network of frictional material in the direction of simple shear. In our mod-
 473 els, this condition is guaranteed by the assumption of a viscous matrix, however, extrap-
 474 olation to nature requires that any fractures within the matrix (not modelled here) do
 475 not extend/connect to form a more extensive shear fracture network. If localized shears
 476 do develop in the matrix, experiments indicate that these may favour development of
 477 frictional instabilities, but slip speed is still modulated by their interaction with surround-
 478 ing creeping matrix (Scuderi et al., 2017).

479 Stress drop is controlled by the bulk shear zone simple shear strain, which unloads
 480 the elastic upper plate. The stress drop in the Bingham model is therefore limited by
 481 the magnitude of finite viscous strain during a strain transient, which is limited by the
 482 period over which τ_y is weak (i.e. healing). Significant weakening of τ_y does not then nec-
 483 essarily correspond to a large stress drop. Force chain clasts may fracture and weaken,
 484 elastically loading the viscous matrix (through elastic strain which was neglected in our
 485 models), before regaining their strength at a similar time-scale to viscous creep.

486 Slow slip events are often modelled as frictional ruptures governed by the empiri-
 487 cal rate-and-state laws (Rubin, 2008). In these models, seismic rupture is prevented by
 488 the similar strengths of the velocity strengthening and weakening parts, a weak stress-
 489 dependence (rate-and-state properties $a - b \approx -10^{-2}$ to -10^{-3}), and the effective
 490 normal stress being extremely small (on the order of kPa). A \sim kPa normal stress also
 491 implies megathrust shear stresses of similar order, which is difficult to reconcile with es-
 492 timates of 10 MPa order from geodynamic models (Lamb, 2006) and from creep rheol-
 493 ogy and piezometry near the brittle-ductile transition (Angiboust et al., 2015). In con-
 494 trast, in the rheologies used here, provided that the matrix material in the mélange is
 495 velocity-strengthening, the strain-rate will always be limited by the matrix viscosity. In
 496 our model, the effective normal stress can be \sim 10 MPa provided it is low enough so that
 497 clast fracturing can occur by local stress amplification (assuming high viscosity contrast
 498 and ϕ). Recent rupture models incorporating a microphysical model with viscous creep
 499 were able to generate a combination of aseismic and seismic slip events, with an effec-
 500 tive normal stress < 50 MPa (van den Ende et al., 2018). Incorporating viscous damp-

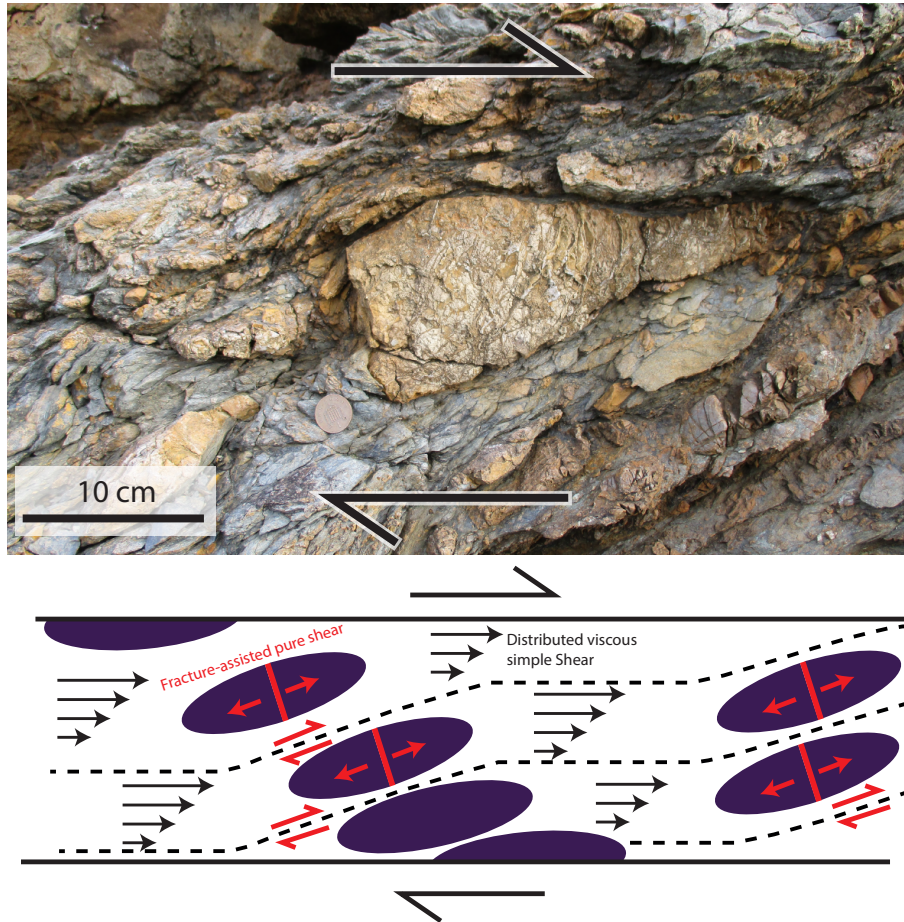


Figure 7. Top) Example of a fractured clast in the Gwna mélangé, Cemaes Bay, Anglesey, UK. This is the mélangé type locality region (Greenly, 1919) and is interpreted as a subduction accretionary complex (Kawai et al., 2007). Tensile fractures are confined to clasts and are kinematically consistent with distributed matrix shear strain. Bottom) Schematic of hypothesised strain-accumulation mechanisms. Mélangé simple shear is accommodated by pure shear of the clasts, which can occur through the opening of extension or extensional-shear fractures, and simple shear within the matrix.

501 ening into SSE models may therefore be a way to reconcile SSEs with regional stresses
 502 of MPas, and help to explain their ubiquity in global subduction zones.

503 **6 Conclusion**

504 We have characterised the bulk rheology of a *mélange* consisting of strong visco-
 505 brittle clasts embedded in a weak viscous matrix using numerical visco-plastic finite el-
 506 ement models. When the clasts form a stress-bearing force-chain network, the bulk vis-
 507 cosity of the *mélange* can be more than an order of magnitude stronger than the matrix
 508 viscosity, in the absence of clast fracturing. When fracturing is allowed, clasts within the
 509 most load-bearing force chains undergo frictional failure in models with bulk stress far
 510 below the clast frictional strength, $\tau \geq 0.22\tau_y$, because of the stress amplification that
 511 occurs within a shear zone with high viscosity contrasts. The fracturing of clasts acts
 512 to homogenize stress in the force chain network and redistribute stress into viscous ma-
 513 trix deformation. As deformation is limited by clast friction at low stress and rate-strengthening
 514 viscous matrix creep at high stress, *mélange* rheology resembles a Bingham plastic. How-
 515 ever, unlike a Bingham plastic, the switch from brittle to viscous deformation occurs across
 516 a gradual transition, due to the heterogeneity of force chain stresses. This transition re-
 517 sults in an effective rheology in the form of $\dot{\epsilon} \propto \ln(\tau)$, as the number of clasts fractur-
 518 ing is more stress-sensitive at higher stress. This gradual transition also requires a large
 519 stress increase or clast yield strength decrease ($> 70\%$) in order to produce significant
 520 bulk strain-rate increase ($\sim 8\times$).

521 The models demonstrate how damped (i.e. significantly rate-strengthening) a visco-
 522 brittle shear zone can be when no frictional slip surface spans it. Such a damped sys-
 523 tem could still generate a period of high strain-rate with a negligible stress drop and at
 524 ~ 10 MPa shear stress, if frictionally failing clasts temporarily lose most of their strength.
 525 In this case, a matrix viscosity of $< 5 \times 10^{17}$ Pa s could be reconciled with SSEs, com-
 526 parable to rheological estimates. We suggest that this frictional weakening could occur
 527 due to the opening of extension or extensional-shear fractures. This prediction needs to
 528 be tested through future modelling incorporating tensile fracturing and elasticity. Sim-
 529 ple shear across the modelled shear zone is accommodated by extension of clasts (pure
 530 shear) and simple shear of the matrix. This model is supported by observed shear net-
 531 works in exhumed *mélange*. The incorporation of viscous dampening into SSE rupture

532 models is likely to permit aseismic SSEs for a wider range of conditions than presently
 533 thought, explaining their ubiquity in subduction zones globally.

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 542 and model parameters required to replicate the results are detailed in the manuscript.

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