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Efficient Carbon Dioxide and Methane Flux Monitoring in Soil Microcosms Using an Automated Chamber with a Cartesian Robot

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STATEMENT

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DATA AVAILABILITY

Data used in the study and supplementary information is available for download on Zenodo at <https://doi.org/10.5281/zenodo.13826352>. Code used to process and analyse data are archived in the Github repository at https://github.com/loyalhow/automated_chamber.

AUTHOR'S CONTRIBUTIONS

H.L. and Z.C. conceived the project idea; H.L. and Y-N.Z. developed an early prototype under the supervision of Z.C. and R.G.; Z-Y.L. and H.L. modified and refined the design; H.L. constructed the final prototype with input from Y-N.Z.; S-Y.Z. and B-D.C. tested the system and collected data in the laboratory; H.L. wrote the manuscript, which was reviewed by Z.C. and R.G. All authors contributed critically to the drafts and gave final approval for publication.

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Keywords:	automated chamber, gas flux measurement, soil incubation, microcosm experiment, carbon dioxide, methane, Cartesian robot
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1 ABSTRACT

2 1. Accurate measurement of carbon dioxide (CO₂) and methane (CH₄) emissions from soil is crucial
3 for understanding carbon dynamics and developing strategies to mitigate climate change. Traditional
4 chamber techniques and soil incubation experiments each have limitations that hinder their
5 efficiency and accuracy. This study aims to overcome these challenges by integrating automated
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23 DATA/CODE FOR PEER REVIEW

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25 <https://doi.org/10.5281/zenodo.13826352>. Code used to process and analyse data are archived in
26 the Github repository at https://github.com/loyalhow/automated_chamber.

27

28 KEYWORDS

29 automated chamber, gas flux measurement, soil incubation, microcosm experiment, carbon dioxide,
30 methane, Cartesian robot

31

32 1 INTRODUCTION

33 Carbon dioxide and methane emissions from soil are key components of the global carbon cycle
34 (Brevik, 2012). Accurate measurement of these gas fluxes is critical for understanding ecosystem
35 carbon dynamics, particularly in the context of climate change (Andrews, et al., 2014; Wangari, et al.,
36 2022). Although various techniques have been developed over the past decades to monitor soil
37 respiration and methane emissions in both laboratory and field settings (Bond-Lamberty, et al.,
38 2024; Oertel, et al., 2016), each method has limitations and cannot fully address research questions
39 alone (Maier, et al., 2020; Yu, et al., 2015). Optimizing current methods and developing new
40 approaches are vital for improving the accuracy of terrestrial carbon models (Phillips, et al., 2016).
41 These innovations provide more precise data on the global carbon cycle, supporting effective climate
42 change mitigation strategies and sustainable management of agricultural and forest ecosystems
43 (Maier, et al., 2020).

44 Soil incubation experiments have a long history as a key method for studying greenhouse gas
45 emissions, offering the advantage of tightly controlled environmental conditions such as
46 temperature, moisture, and nutrient levels, allowing for causal analysis of specific factors

47 (Berglund & Berglund, 2011; Hossain, et al., 2017; Schaufler, et al., 2010). These experiments also
48 enable the investigation of short-term dynamics over days, weeks, or even months, with relatively
49 simple and repeatable procedures that facilitate data collection and analysis (Hodgkins, et al., 2015;
50 Treat, et al., 2015). Moreover, they provide valuable insights into the mechanisms underlying CO₂
51 and CH₄ emission from soil, such as microbial community structure and enzyme activity (Wu, Jia,
52 Wang, Chang, & Startsev, 2013). However, incubation experiments have limitations, including
53 significant differences from natural environments, such as the absence of plant roots, litter, and soil
54 fauna, which can limit the applicability of results to real ecosystems. Additionally, they are
55 constrained by small spatial scales and are less capable of evaluating long-term processes like
56 vegetation succession and soil carbon turnover. High equipment and material costs further restrict
57 the scale and number of experiments. Recent advancements aim to improve incubation techniques
58 through the development of more advanced instrumentation and experimental designs that better
59 mimic natural conditions, often in combination with other field-based techniques such as chamber
60 methods to enhance the understanding of soil greenhouse gas emissions (Oertel, et al., 2016).

61 Current methods for determining greenhouse gas fluxes during soil incubation experiments have
62 several limitations. Typically, soil samples incubated in vials or open microcosms are sealed for
63 measurement periods ranging from 15 min to tens of hours. The gas accumulated in the headspace
64 is then sampled at discrete times and analyzed using gas chromatography coupled with specific
65 detectors. However, these samplings and post-sampling analysis are time-consuming. Moreover, the
66 prolonged sealing may introduce interferences, such as altered gas concentration gradients that
67 affect microbial activity and gas exchange processes. Consequently, these methods may fail to
68 capture the rapid dynamics of greenhouse gas emissions, leading to results that deviate from natural

69 soil systems. An automated novel method could significantly enhance laboratory studies by
70 providing continuous, real-time monitoring with minimal disturbance to the system. Automated
71 chamber methods have been employed in field studies for a long time, demonstrating several
72 advantages over manual chambers despite challenges related to high cost and complexity.
73 Integrating automated chamber technology into soil incubation experiments presents a promising
74 solution to overcome the current methodological limitations and achieve more accurate and
75 representative measurements.

76 In this study, we present a novel application of an automated closed dynamic chamber system,
77 operated by a Cartesian robot, for use in controlled soil incubation experiments. This is the first time
78 the automated chamber method, previously used mainly in field studies, has been integrated into
79 microcosm experiments for precise and efficient monitoring of CO₂ and CH₄ fluxes. In this work, we
80 validated the method's robustness and repeatability through repeated chamber measurements
81 across different soil types incubated in open microcosms. Additionally, we explored the potential to
82 shorten the measurement duration, aiming to enhance experimental efficiency and throughput. Two
83 examples of microcosm experiments, involving treatments with leaf litter and plastic films,
84 demonstrate the applicability of this method in laboratory studies.

85

86 **2 METHODS**

87 **2.1 Design of the Cartesian robot, chamber, and microcosms**

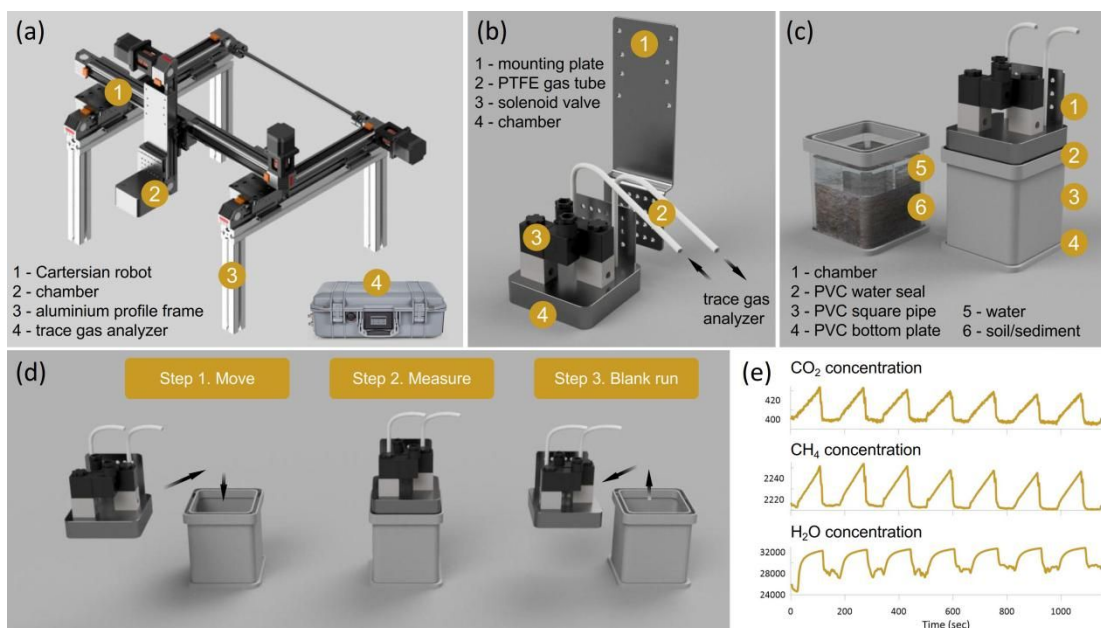
88 The gas flux measurements were conducted using an automated system that incorporated a
89 Cartesian robot (Figure 1a), a closed dynamic chamber (Figure 1b) and open microcosms (Figure 1c).
90 For real-time detection of CO₂, CH₄, and H₂O concentrations, the system was equipped with the

91 LI-7810 trace gas analyzer (LI-COR, Lincoln, NE, USA), which provided continuous online monitoring
92 of gas concentrations. This setup was designed to allow precise, repeatable, and efficient
93 measurements of gas fluxes from soil incubation experiments.

94 The Cartesian robot forms the core of the automated gas flux measurement system, designed for
95 precise movement of the chamber. It is mounted on an aluminum profile frame, which provides
96 stability and serves as a stand, creating space to position the microcosms beneath the robot. The
97 robot operates within a working range of 600 mm in X, 500 mm in Y, and 150 mm in Z. Its motion is
98 programmed and controlled by a 4-axis motion controller, ensuring accurate and automated
99 movement during the experiment.

100 The closed dynamic chamber is used for real-time gas flux measurements and is securely mounted
101 on the Cartesian robot system via a mounting plate. Constructed from aluminum, the chamber is
102 designed to provide an airtight seal with minimal gas adsorption during operation. Two PTFE gas
103 tubes connect the chamber to the LI-7810 trace gas analyzer (LI-COR, Lincoln, NE, USA), functioning
104 as the gas inlet and outlet. Additionally, two solenoid valves are controlled by the 4-axis motion
105 controller to regulate pressure balance between the inside and outside of the chamber when sealing
106 or opening the microcosms.

107 The open microcosms were constructed using PVC square pipes with dimensions of 100 mm x 100
108 mm x 120 mm, which held the soil or sediment samples. The top of each microcosm featured a PVC
109 water seal, which was filled with pure water prior to measurements. During the gas flux
110 measurements, the closed dynamic chamber was positioned into the water seal, creating a
111 temporary gas-tight headspace for accurate gas flux analysis. This setup ensured that ambient air did
112 not interfere with the gas emissions measured from the incubated soils.



113
114 FIGURE 1 | Schematic representation of the automated chamber system for gas flux measurements.

115 (a) Overview of the Cartesian robot system equipped with a measurement chamber. (b) Close-up of
116 the closed dynamic chamber system. (c) Setup of the open microcosm during incubation (left) and
117 the gas flux measurement configuration (right). (d) Representation of the three-step operational
118 cycle of a single gas flux measurement. (e) Example of real-time CO₂, CH₄, and H₂O concentration
119 data measured using the closed dynamic chamber automated by the Cartesian robot.

120

121 2.2 The three-step measurement cycle

122 Each measurement cycle comprises three distinct steps. In the first step, the Cartesian robot
123 positions the closed dynamic chamber directly above the selected microcosm and lowers it into the
124 water seal. During this process, the solenoid valves are opened to balance the internal and external
125 pressure, minimizing any disturbances. Once the chamber is sealed, the solenoid valves are closed,
126 initiating the second step—a 90-s measurement period during which real-time concentrations of
127 CO₂, CH₄, and H₂O are continuously recorded. In the final step, the solenoid valves are reopened,
128 allowing the chamber to be lifted and moved away from the microcosm. A blank run of 60 to 75 s is

129 then performed to account for background levels of ambient air and to clear the system before the
130 next measurement. This cycle is repeated until all microcosms have been processed.

131

132 **2.3 Data analysis and software**

133 Raw data were processed using Python to calculate gas fluxes for CO₂, CH₄, and H₂O. These raw
134 concentration data files were first merged with relevant metadata to associate each dataset with the
135 respective experimental conditions. Gas fluxes were calculated by determining the slope of the gas
136 concentration over time during the sealed chamber measurement period. Specifically, the rate of
137 change in gas concentration was obtained through linear regression analysis. The resulting slope was
138 then used to compute the gas flux based on the chamber volume, the surface area of the
139 microcosms, and the ambient temperature and pressure. The processed data and calculated fluxes
140 were saved to CSV files for further analysis and interpretation. The Python code used for data
141 processing is available via a Github repository https://github.com/loyalhow/automated_chamber.

142

143 **3 RESULTS**

144 **3.1 Validation of gas flux measurements**

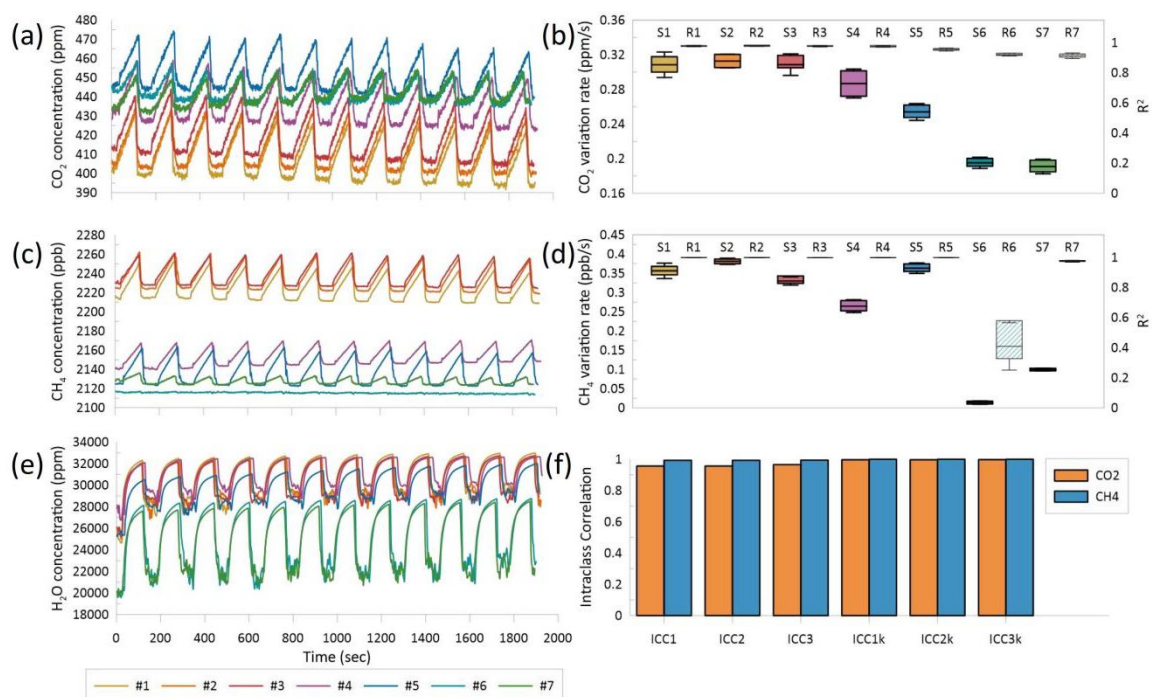
145 The raw concentration data of CO₂, CH₄, and H₂O from 12 repeated measurements across 7 soil
146 microcosms, with each measurement lasting 90 s, are presented in Figure 2a, 2c, and 2e. The CO₂
147 concentration data (Figure 2a) display periodic peaks, which are consistent across the repeated
148 measurements but vary in magnitude between different microcosms, indicating differences in
149 background concentrations. A similar trend is observed for CH₄ (Figure 2c), where the peak patterns
150 remain consistent across repeated measurements for each microcosm, while the background levels

151 differ between microcosms. In contrast, the peak shape of water vapor (Figure 2e) differs
152 significantly from CO₂ and CH₄. The sharp ascending front of the water vapor peak is due to the high
153 flux intensity, followed by a slowing and flattening of the concentration increase as the chamber's
154 headspace becomes saturated. Despite these differences in peak shapes and background
155 concentrations between microcosms, the consistency in peak patterns across repeated
156 measurements suggests steady-state fluxes for CO₂ and CH₄ within each microcosm. These results
157 validate the method's robustness in capturing stable gas fluxes over multiple measurement cycles.

158 The slopes and R^2 values (correlation coefficient calculated using X) of the linear fitting curves for
159 repeated measurements of CO₂ and CH₄ fluxes across 7 soil microcosms are shown in Figure 2
160 (subplots 2b and 2d), respectively. The slopes (S1-S7) and R^2 values (R1-R7) indicate the rate of
161 change in gas concentrations and the goodness of fit for the linear regression models. Both CO₂ and
162 CH₄ measurements display low relative standard deviations in the variation rates of gas
163 concentration, and the regression quality is high, with R^2 values consistently greater than 0.90, and
164 often exceeding 0.95. As these R^2 values are close to 1 they demonstrate excellent fitting accuracy,
165 highlighting the reliability of the method for capturing flux dynamics. There is only one exception,
166 where the CH₄ flux is extremely low (near zero for S6), leading to a lower R^2 value. This result
167 suggests that the method is statistically robust and capable of producing highly repeatable and
168 accurate flux measurements, even across varied microcosms, with minimal deviation in the observed
169 flux rates.

170 The repeatability of the gas flux measurements from soil incubation microcosms was further
171 assessed using the Intraclass Correlation Coefficient (ICC). The dataset comprised 7 soil incubation
172 microcosms, with 12 repeated measurements per microcosm. ICC values were calculated to evaluate

173 the consistency of the measurements across repeated trials. The results demonstrated excellent
 174 reliability, with ICC values for single raters (ICC1 and ICC2) of 0.956, indicating strong agreement
 175 between individual measurements. Furthermore, when considering the average of the repeated
 176 measurements (ICC1k, ICC2k, ICC3k), the ICC values exceeded 0.996, suggesting near-perfect
 177 consistency and repeatability of the method. The narrow confidence intervals ([0.89, 0.99] for
 178 individual measurements and [0.99, 1.00] for averaged measurements) further confirm the
 179 robustness and reliability of the measurement protocol. These findings indicate that the method
 180 provides highly repeatable results, whether using individual or averaged measurements, supporting
 181 its validity for gas flux quantification in soil incubation experiments.



182
 183 **FIGURE 2 |** The raw concentration data and validation results for the flux measurements of carbon
 184 dioxide, methane and water vapor over 12 repeated measurements across 7 microcosms. Plots
 185 represent (a) CO₂ (ppm) (c) CH₄ (ppb) and (e) H₂O (ppm) concentrations over time. Each colored line
 186 represents an individual microcosm (#1-#7), with measurements taken repeatedly over time. (b)
 187 Boxplots of CO₂ flux variation rates (slopes, S1-S8) and their corresponding R² values (R1-R8),

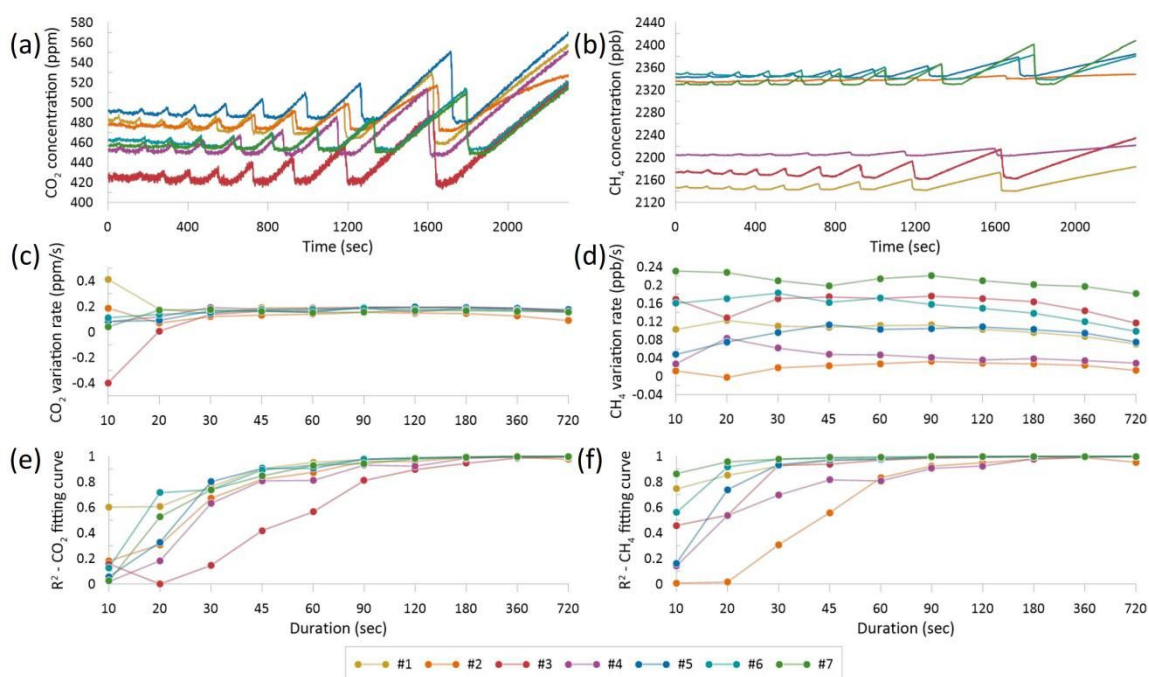
188 illustrating the quality of linear regression fits. (d) Boxplots of CH₄ flux variation rates (slopes, S1-S8)
189 and their corresponding R² values (R1-R8), showing the fitting quality for CH₄ measurements. (f)
190 Intraclass correlation coefficients (ICC) for repeated measurements of CO₂ and CH₄ fluxes,
191 demonstrating the reliability and repeatability of the developed method.

192

193 **3.2 Effect of measurement duration on accuracy**

194 The measurements of CO₂ and CH₄ concentrations over different durations were conducted to
195 assess the effect of measurement duration on the accuracy of flux determinations (Figure 3a, 3b).
196 The slopes of the linear fitting curves, which act as proxies for gas fluxes, were plotted as a function
197 of measurement duration, showing how flux estimates stabilize over time (Figure 3c, 3d). At shorter
198 durations (10–30 s), both CO₂ and CH₄ slopes showed significant variability, especially for methane,
199 where some microcosms exhibited near-zero or even negative values. For example, microcosms #2
200 and #3 for CH₄ had notably inconsistent slopes at these shorter durations. However, after 90 s, the
201 slopes for both gases stabilized, indicating reliable flux measurements. The R² values of the linear
202 fitting curves were also plotted to assess the quality of the regressions across different durations
203 (Figure 3e, 3f). The R² values steadily increased with duration for both gases, with values surpassing
204 0.90 at 90 s for most microcosms and exceeding 0.95 in many cases, further confirming the accuracy
205 of flux estimates. By 90 s, the CO₂ slopes for all microcosms had converged to consistent values
206 (around 0.19–0.22 ppm/s), and the CH₄ slopes had stabilized as well (around 0.15–0.22 ppb/s),
207 reflecting reliable flux rates. These results explore the potential for shortening measurement cycles
208 to increase experimental throughput. The combination of high R² values and stable slopes at 90 s
209 indicates that this duration is sufficient for reliable gas flux measurements. This duration is

210 significantly shorter than those required by other methods, allowing for faster data acquisition
 211 without compromising measurement reliability.



212
 213 FIGURE 3 | Validation of CO₂ and CH₄ flux measurements over different measurement durations
 214 across seven microcosms. (a) CO₂ concentration (ppm) and (b) CH₄ concentration (ppb) as a function
 215 of time, with different durations (10, 20, 30, 45, 60, 90, 120, 180, 360, and 720 s) shown for each
 216 microcosm (#1-#7). (c) CO₂ flux variation rates (ppm/s) and (d) CH₄ flux variation rates (ppb/s) as a
 217 function of measurement time, illustrating how the slope of the flux curve stabilizes with longer
 218 durations. (e) R^2 values for the CO₂ flux fitting curves, and (f) R^2 values for the CH₄ flux fitting curves,
 219 plotted against different measurement duration, showing improved fitting accuracy with increased
 220 measurement time.

221

222 3.3 Demonstration with leaf litter and plastic film treatment

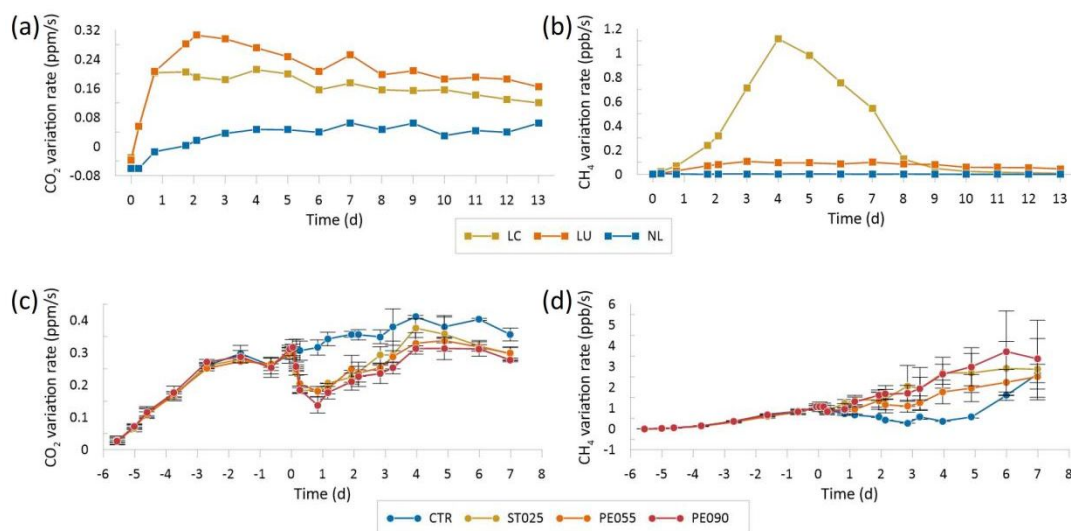
223 The flux variations of CO₂ and CH₄ were monitored over two-week incubation periods for two
 224 distinct experimental setups: the addition of dried leaf litter and the application of different plastic

225 films. In the leaf litter experiment (Figure 4a, 4b), CO₂ fluxes varied significantly between the
226 treatments. The uncovered leaf litter (LU) resulted in the highest CO₂ emissions, peaking at 0.32
227 ppm/s around day 2 before gradually declining, while the treatment with leaf litter covered by a thin
228 soil layer (LC) showed consistently lower but still elevated CO₂ fluxes, stabilizing around 0.18 ppm/s.
229 The control group (NL) with no leaf litter maintained low, stable fluxes near zero throughout the
230 experiment. CH₄ fluxes displayed a distinct trend, with the LC treatment showing a significant peak in
231 emissions on day 4, reaching 1.2 ppb/s before declining rapidly. In contrast, both the LU and NL
232 treatments exhibited negligible CH₄ fluxes.

233 In the plastic film experiment (Figure 4c, 4d), the addition of plastic films had a distinct impact on
234 CO₂ fluxes. After the plastic film treatments at day 0, CO₂ fluxes declined by more than 50% in the
235 first two days for all treatment groups—ST025 (0.025-mm-thick starch-based bioplastic), PE055
236 (0.055-mm-thick polyethylene), and PE090 (0.090-mm-thick polyethylene)—compared to control
237 group (CTR). This was followed by a gradual recovery, with the CO₂ fluxes narrowing the gap
238 between the CTR and the treated groups, but remaining consistently lower for the plastic-treated
239 microcosms throughout the remainder of the incubation. In contrast, the control group showed a
240 steady increase in CO₂ emissions during the same period, with fluxes remaining higher than the
241 treatment groups post-treatment. CH₄ fluxes showed a pronounced response to the plastic films,
242 with PE090 demonstrating the highest emissions, exceeding 5 ppb/s by day 7. The PE055 and ST025
243 treatments also showed elevated CH₄ fluxes, though to a lesser extent, while the control group
244 exhibited minimal CH₄ emissions throughout the incubation.

245 Together, these experiments highlight the applicability of the flux measurement method across
246 different treatment conditions and experimental setups. The method successfully captured both CO₂

247 and CH₄ flux variations in response to different types of organic matter and plastic films, offering a
 248 reliable means to monitor gas flux dynamics over time. The ability to detect subtle differences
 249 between treatments demonstrates the robustness of the method and its potential for broader
 250 applications in greenhouse gas flux studies, both in controlled experiments and potentially in field
 251 settings. By allowing for repeated measurements with high temporal resolution, this method
 252 provides a valuable tool for researchers investigating soil-atmosphere gas exchange under various
 253 environmental and experimental conditions.



254
 255 **FIGURE 4 |** Application of the flux measurement method in two different microcosm experiments.
 256 (a) CO₂ variation rate (ppm/s) and (b) CH₄ variation rate (ppb/s) over a two-week incubation for leaf
 257 litter treatments. NL represents the control group with no leaf litter, LC represents leaf litter covered
 258 by a thin soil layer, and LU represents uncovered leaf litter. (c) CO₂ variation rate (ppm/s) and (d) CH₄
 259 variation rate (ppb/s) over a two-week incubation for plastic film treatments. CTR represents the
 260 control group with no plastic film, ST025 represents the treatment with 0.025-mm-thick
 261 starch-based bioplastic, PE055 represents the treatment with 0.055-mm-thick polyethylene, and
 262 PE090 represents the treatment with 0.090-mm-thick polyethylene.

263

264 **4 DISCUSSION**

265 The findings presented in this study underscore the efficacy and reliability of the automated
266 chamber method for measuring greenhouse gas fluxes from soil ecosystems. This method,
267 controlled and operated by a Cartesian robot system, represents a significant advancement in the
268 automation of gas flux measurements. The integration of an automated closed dynamic chamber
269 system, which has been traditionally used in field applications, with controlled soil incubation
270 experiments is introduced here for the first time. The Cartesian robot system automates the entire
271 measurement process, enabling precise, repeatable and thus robust measurements while
272 minimizing manual intervention and reducing potential human error. The robustness and
273 repeatability of this method are evident in the consistent peak patterns observed across repeated
274 measurements for CO₂ and CH₄, despite variations in background concentrations between different
275 microcosms. This consistency not only validates the method's capacity to capture stable gas fluxes
276 but also demonstrates its potential applicability across a wide range of environmental conditions
277 and soil types.

278 A key advancement highlighted in this study is the shortened measurement duration, made possible
279 by the automation provided by the Cartesian robot system. With this precise robotic control,
280 measurement cycles can be as short as 90 s, representing a significant improvement in gas flux
281 measurement techniques . which in other systems typically take 10-15 min per cycle. Importantly,
282 this reduction in measurement time does not compromise the accuracy of the flux estimates, as
283 evidenced by the high R² values and stable slopes obtained for both CO₂ and CH₄ at this duration.
284 The ability to collect reliable data in a fraction of the time typically required by conventional

285 methods has profound implications for increasing experimental throughput and minimizing
286 disturbance to the ecosystems under study.

287 The excellent fitting accuracy, with R^2 values consistently greater than 0.90 and frequently exceeding
288 0.950, further reinforces the reliability of the automated chamber method. Additionally, the ICC
289 values exceeding 0.996 for averaged measurements confirm the method's near-perfect consistency
290 and repeatability. These findings suggest that the automated chamber method, operated via a
291 Cartesian robot system, is a robust tool for capturing gas flux dynamics with minimal deviation, even
292 across diverse microcosms.

293 The applicability of this method for studying the mechanisms underlying greenhouse gas emissions
294 from various ecosystems is highly promising. The demonstration using leaf litter and plastic film
295 treatments illustrates the method's ability to detect subtle differences in gas fluxes in response to
296 environmental changes. The variability in CO_2 and CH_4 emissions observed between treatments
297 underscores the sensitivity of the method and its capacity to track flux dynamics over time, making it
298 particularly useful for studies investigating the impacts of both natural and anthropogenic factors on
299 gas emissions.

300 However, this method does have limitations. One notable limitation is its current inability to
301 measure nitrous oxide (N_2O), another potent greenhouse gas, due to the current instrumentation.

302 Since N_2O is an important component of soil-atmosphere gas exchange, particularly in agricultural
303 systems, future improvements should focus on implementing detectors capable of measuring N_2O
304 and other relevant gases. Expanding the system's detection capabilities would significantly broaden
305 the scope of the Cartesian robotic system and enhance its applicability across a wider range of
306 ecosystems and research questions. Additionally, while the system performs well in controlled lab

307 environments, the complexity of natural ecosystems, such as soil heterogeneity and fluctuating field
308 conditions, may present challenges in field applications that require further exploration and
309 adaptation of the system.

310

311 **5 CONCLUSIONS**

312 In conclusion, the automated chamber method presented here represents a significant
313 advancement in the measurement of greenhouse gas fluxes in soil incubation experiments. The
314 integration of a Cartesian robot system has shortened measurement cycles, increased throughput,
315 and maintained high accuracy and repeatability, making this method an invaluable tool for both
316 laboratory and field studies. The potential for broader applications in greenhouse gas flux studies is
317 clear, and future research can build upon these findings to further explore the underlying
318 mechanisms of gas emissions in diverse ecosystems. Improvements, such as the inclusion of N₂O
319 detection and adaptations for more complex field conditions, will further strengthen the utility of
320 this method in ecology and environmental sciences.

321

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