

Uncertainties as a Guide for Global Water Model Advancement

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Abstract

Global water models increasingly allow us to explore the terrestrial water cycle in earth-sized digital laboratories to support science and guide policy. However, these models are still subject to considerable uncertainties that mainly originate from three sources: (1) imbalances in data quality and availability across geographical regions and between hydrologic variables, (2) poorly quantified human influence on the water cycle, and (3) difficulties in tailoring process representations to regionally diverse hydrologic systems. New, more accurate, and larger datasets, as well as better accumulated and even improved knowledge, will help to reduce these uncertainties and eventually lead to model advancement. In this review, we explore sources of uncertainty critical to global water models and define actions to reduce them where possible, therefore providing a guide for global model advancement. Following this

44 path will increase the robustness of model outputs, which is urgently needed to tackle key scientific and
45 societal challenges.

46 **1 Introduction**

47 In 1972, the Blue Marble picture showed us, for the first time, a color image of Earth from space, laying
48 bare its vulnerability and interconnectedness through the water cycle (Eagleson, 1991). It suggested that
49 we require an understanding of the past, present, and future of Earth's freshwater resources to safeguard
50 the blue planet for future generations. Global water models (GWMs) are a central tool to foster this
51 understanding by simulating the global terrestrial water cycle with the help of computer programs. From
52 the first coarse-resolution models with simple process representation in the 1990s, these models have
53 evolved tremendously due to remote sensing (Chahine, 1992; Wulder *et al.*, 2022) and an increased
54 process understanding from regional hydrologic research (Shuttleworth, 1994) (for a history of GWM
55 evolution see Fig. S1). They can now be run at high temporal (hourly-daily) and spatial (up to 1 km)
56 resolutions and include an increasing range of hydrologic processes and anthropogenic influences
57 (Sellers *et al.*, 1997; Pokhrel *et al.*, 2016; Arheimer *et al.*, 2020; Müller Schmied *et al.*, 2021; Hoch *et*
58 *al.*, 2023). Until recently, these models have been solely based on (sometimes very simplified)
59 representations of hydrological processes, but machine learning and hybrid approaches are starting to
60 emerge (Feng *et al.*, 2023). Here, we use three classes of models representative of GWMs: global
61 hydrological, land surface, and dynamic vegetation models, which have evolved in parallel (Bierkens,
62 2015). While all three classes were initially built for different purposes, they all model the global
63 terrestrial water cycle and are used to answer questions related to global hydrology (Haddeland *et al.*,
64 2011; Gudmundsson & Wagener *et al.*, 2012; Schewe *et al.*, 2019; Pokhrel *et al.*, 2021). We chose to
65 jointly discuss them as GWMs as all model classes benefit from a more accurate representation of the
66 terrestrial water cycle, and they all suffer from uncertainties specific to modeling these processes on a
67 global scale.

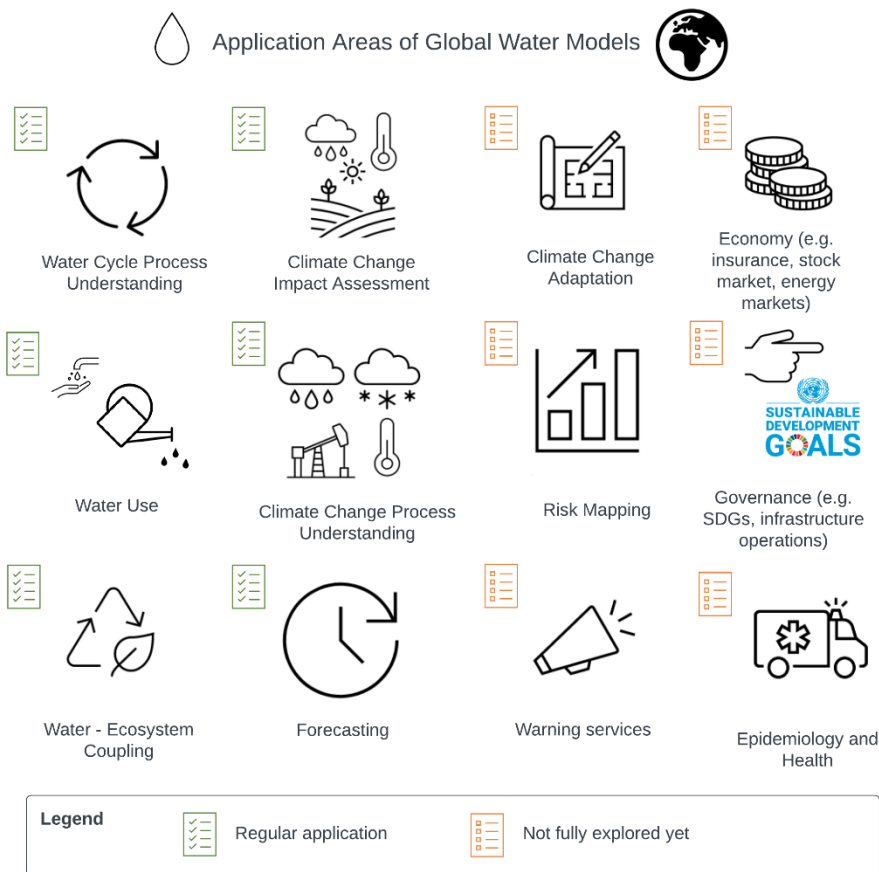
68
69 Because water connects all spheres of the Earth, GWMs have a wide range of applications and offer
70 opportunities for future use in many fields (Fig. 1). In contrast to models of specific places or regions
71 (e.g., catchments or river basins), the capacity of GWMs to generate continuous and consistent global
72 hydrological time series for variables such as streamflow, soil moisture, evapotranspiration, or snow
73 water equivalent makes them a valuable resource. Their global coverage allows usage in regions with
74 limited or no observations, they help to understand spatiotemporal patterns of hydrological extremes
75 (Ward *et al.*, 2014; Emerton *et al.*, 2017; Arheimer *et al.*, 2020) in support of global early warning
76 systems and risk maps (Emerton *et al.*, 2016; He *et al.*, 2020), and they help to assess future risks such
77 as water scarcity, and explore possible adaptation measures (Veldkamp *et al.*, 2016; van Vliet *et al.*,
78 2021). Other research fields have used GWMs to assess issues related to the Water-Energy-Food nexus
79 (Lodge *et al.*, 2023) or the impacts of climate change on freshwater ecosystems (Döll & Zhang, 2010;
80 Bartosova *et al.*, 2021). Furthermore, GWMs have improved the representation of the Earth system in
81 climate and weather models, because one of the primary outputs of water models, streamflow, naturally
82 integrates various terrestrial hydrological processes and can thus be used to evaluate mass balances of
83 other models (Zsoter *et al.*, 2019; Boussetta *et al.*, 2021).

84 While GWMs provide global coverage of multiple water cycle components, current uncertainties and
85 their poor quantification may limit their value (e.g., for global change impact analysis) as the reliability
86 of model estimates remains unclear (Wagener *et al.*, 2022). For example, the sixth IPCC assessment
87 report concluded that our knowledge of climate change impacts on groundwater is still poor partly
88 because groundwater remains inadequately presented in many models (IPCC, 2023). Even if

89 implemented, uncertainty of groundwater levels remains high (Reinecke *et al.*, 2024). Complex process
90 interrelationships such as atmospheric CO₂ fertilization and its long-term impact on global water
91 availability are poorly known (Milly & Dunne, 2016), while current representations of anthropogenic
92 impacts such as irrigation, groundwater abstractions (Arheimer *et al.*, 2020; Puy *et al.*, 2021; McDermid
93 *et al.*, 2023), and river regulation (Arheimer *et al.*, 2017) are still in their infancy. This has direct
94 consequences for other impact assessments, such as assessing the economic impacts of floods (Willner
95 *et al.*, 2018) or vulnerability to food insecurity (Betts *et al.*, 2018).

96 Here, we argue that by identifying and quantifying uncertainties, we can efficiently guide the efforts of
97 the global hydrological community to build better GWMs and, as a result, provide better information
98 to policymakers. By better we mean models that are more consistent with observations and with our
99 system understanding (perception). While we cannot expect global models to represent local
100 observations as well as a locally calibrated model, we have a need for models of the entire terrestrial
101 surface, which can realistically represent our process understanding across diverse hydrologic
102 landscapes and enable a credible (though always uncertain) look into the future across different what-
103 if scenarios.

104 Much has been said about the topic of uncertainty in the context of local and regional models (Wagener
105 & Montanari, 2011; Beven, 2016; Nearing *et al.*, 2016), but what are the problems and solutions specific
106 to global water models? We focus on so-called epistemic uncertainty, defined by Walker *et al.* (2003)
107 as “uncertainty due to the imperfection of our knowledge, which may be reduced by more research and
108 empirical efforts.” If we can identify those uncertainties that can be reduced, they can guide
109 advancements of GWMs and our scientific hydrological understanding in general. Based on a critical
110 review of the current literature, we identify three key sources of uncertainty specific to modeling the
111 terrestrial water cycle on a global scale. We then outline how these uncertainties affect our
112 understanding of past, present, and future water cycles, and suggest ways to reduce them and thus
113 advance GWMs.



114
 115 **Figure 1:** Global water models are relevant for a wide range of applications, but their potential has
 116 not been extensively explored in all possible areas. References to examples (for their regular
 117 application) and further explanations of potential future applications (not fully explored category in
 118 the figure) can be found in Table S1.

119 2 Uncertainties in building, forcing, and evaluating global water models

120 In this section, we discuss the main sources of epistemic uncertainty in GWMs and explore from where
 121 they originate during the building, forcing, and evaluation stages of the modeling process. All models
 122 are subject to uncertainties, as they are, by definition, an approximation and, thus, an imperfect
 123 representation of reality. Knowing when, where, and why models are uncertain is a starting point for
 124 refinement and improved scientific understanding (Eyring *et al.*, 2019; Gleeson *et al.*, 2021).
 125 Importantly, uncertainties can affect the robustness of and confidence in impact assessments, policies,
 126 and decisions derived from model results (Haddeland *et al.*, 2011; Puy *et al.*, 2022). Insufficient and
 127 inaccurate quantification and communication of existing uncertainties may lead to overconfident
 128 decisions and potentially to loss of trust in models (Beven, 2018).

129
 130 We focus our discussion on uncertainties that relate to developing and implementing GWMs, though
 131 additional uncertainties originate from the natural variability of human and environmental systems.
 132 Such aleatory uncertainties represent variability, imprecision, and randomness, or factors that can
 133 generally be modeled as probabilities in statistical frameworks (Beven *et al.*, 2018). In addition,
 134 uncertainties might arise when testing specific intervention strategies to guide policymaking, such as
 135 land use change or water use scenarios, which cannot be assessed against observations. What is

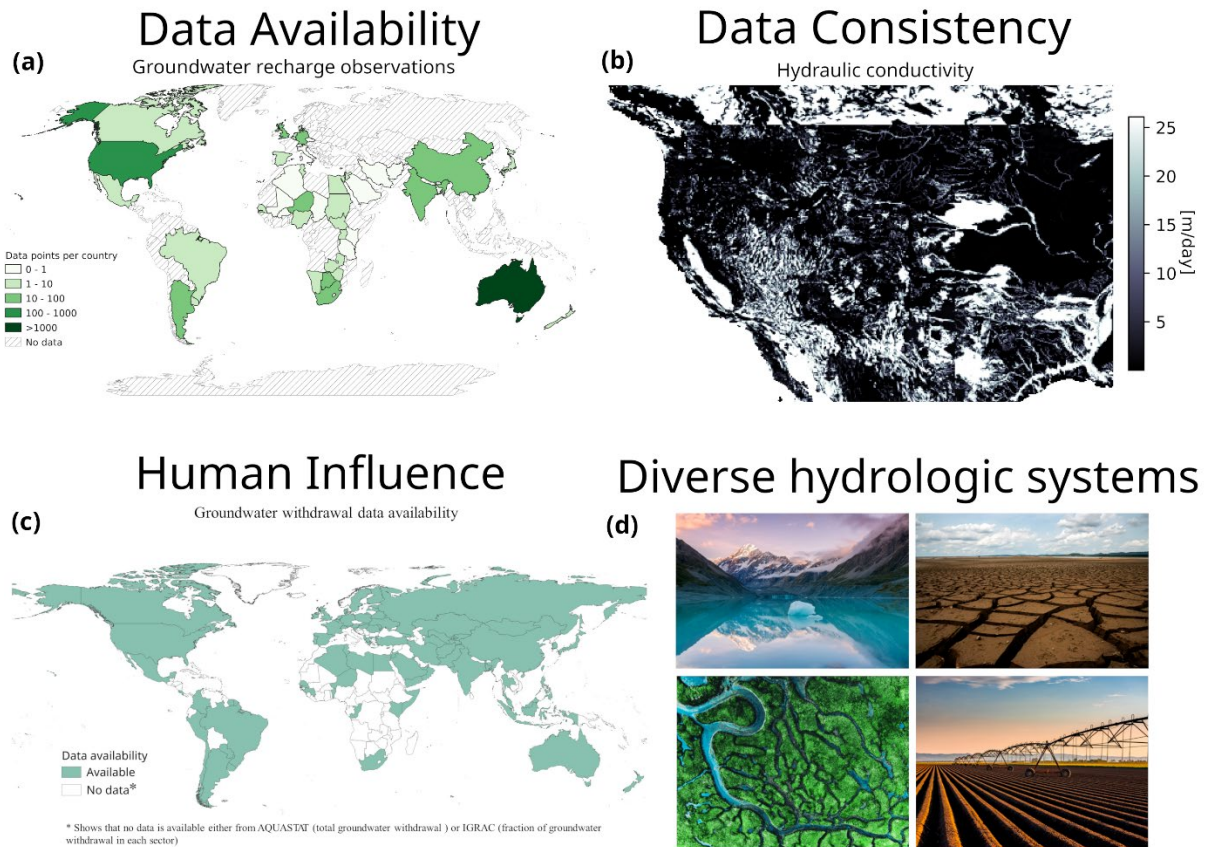
136 important for our discussion here is that many of the uncertainties currently impacting GWMs originate
137 from a lack of knowledge, i.e., they are epistemic and can be reduced (in principle) through new or
138 better utilized (e.g., through new algorithms or different models) observations, or through new
139 knowledge (Beven *et al.*, 2018). They exist because we lack system understanding, because we cannot
140 measure certain variables in all places, at all times, at the right scale or at all, and because measurements
141 themselves carry uncertainties (Sivapalan, 2018; Condon *et al.*, 2021). In addition, we are often
142 interested in future system states that are possibly very different from the past and thus may lack
143 historical analogs (e.g., due to climate or land use change).

144
145 Since GWMs cover the entire terrestrial area of the globe, the degree of uncertainty and potential
146 approaches to address them differ from local and regional hydrologic models. One key problem global
147 models experience more than local or national models is data consistency. Given that GWMs are meant
148 to represent the whole terrestrial hydrology, a key issue is that data support and the uncertainty present
149 will vary hugely between regions. Thus, it is likely that the approaches taken to reduce uncertainty will
150 have to vary as well.

151
152 We find that uncertainties largely originate from three sources (Fig. 2): (1) imbalances in data
153 quality/availability across geographical regions and between hydrologic variables, (2) poorly quantified
154 human alterations of the water cycle, and (3) difficulties in tailoring models to regionally diverse
155 hydrologic systems. Imbalances in existing datasets create considerable problems in our ability to assess
156 how consistent models and real-world dynamics are. For example, (in-situ) data availability in
157 temperate regions such as Europe and North America tends to be high, and we generally have more
158 data in regions with higher population densities (Krabbenhoft *et al.*, 2022) (see Fig. 2a). If observations
159 are available, they frequently suffer from inconsistencies due to differences in data collection between
160 administrative boundaries (Fig. 2b), which are challenging to eradicate and can significantly impact
161 model results. In addition, observations are often available in places where anthropogenic influences
162 are considerable but unquantified (often because the data is not publicly available; Fig. 2c). For
163 example, while global datasets on reservoirs and dams are available (Mulligan *et al.*, 2020), their
164 operation schemes are largely unknown (Hanasaki *et al.*, 2006).

165
166 Furthermore, it is difficult to tailor GWMs to reflect diverse regional hydrological systems (Fig. 2d)
167 because that regional process knowledge is either not (easily) available or biased (i.e., our perceptual
168 understanding is limited) (Stein *et al.*, 2024) or because we lack the flexibility to implement that
169 knowledge in the current generation of models. In addition, observations rarely represent the scale of
170 model units (Weber *et al.*, 2023). In-situ observations of individual variables (e.g., soil moisture) are
171 often only representative of areas much smaller than the scale of the modeling unit (e.g., a raster cell;
172 this is also true for regional models, but the scale difference is likely more severe for GWMs). In
173 contrast, observations measured at larger spatial scales (i.e., satellite measurements) often integrate over
174 multiple state variables and/or larger areas than the modeling unit. Streamflow observations are a special
175 case as they integrate various processes inside a catchment. However, (especially) for large catchments,
176 the influence of diverse spatially distributed and heterogeneous runoff generation processes cannot be
177 identified easily (if at all) from the signal that arrives at the catchment outlet (van Werkhoven *et al.*,
178 2008).

Sources of uncertainty



180
 181 **Figure 2:** Sources of uncertainty for global water models. Uncertainties mainly originate from three
 182 sources: **a**, imbalances in data availability, exemplified by showing the number of available data
 183 points in a global dataset of groundwater recharge (Moeck *et al.*, 2020), and **b**, consistency across
 184 geographical regions illustrated by a zoom-in showing that hydraulic conductivity in a widely used
 185 global dataset (Gleeson *et al.*, 2014) changes abruptly at the border between Canada and the USA, **c**,
 186 poorly quantified human influence on the water cycle demonstrated with available data on
 187 groundwater withdrawal on a country level in the AQUASTAT and IGRAC database, and **d**,
 188 difficulties in tailoring process representations to regionally diverse hydrologic systems.

189

190 Building global water models

191 Any process-based water model, independent of its application scale, is generally built through a
 192 modeling process that establishes a perceptual (or conceptual) model of the system under study and
 193 ends with a computational model that can be executed (Beven, 2018). For regional models, much
 194 discussion has been placed on how these stages are implemented (Beven, 2012). Current GWMs are
 195 generally built along the following steps: (1) Given the size of the domain, one or very few
 196 representative perceptual models are used (e.g., separating landscapes into mountains and sedimentary
 197 basins (Hartmann *et al.*, 2017)). (2) The perceptual model(s) are then translated into model structures
 198 applied at the modeling unit (typically a raster cell or a catchment), and routing functions are added to
 199 connect the individual modeling units. (3) Each model unit is then tailored to regional conditions (e.g.,
 200 hydro-climatic) via the model parameters, mostly through a priori estimates directly derived from
 201 globally available soil, geology, vegetation, and other datasets. (4) Models may consider different
 202 aspects of human interventions, such as water abstractions or reservoirs. (5) The model is then driven
 203 by forcing inputs such as precipitation, temperature, and radiation, either using observational records,

204 reanalysis products, or projections from Global Climate Models (GCMs). Sometimes, GWMs are
205 directly coupled to a GCM together with other additional physical, chemical, and biological processes,
206 then referred to as an Earth System Model (ESM) (Clark & Fan *et al.*, 2015). (6) GWMs can be
207 evaluated based on their main outputs, such as streamflow, soil moisture, or evapotranspiration, though
208 whether and how this is done might vary by model and study focus. Calibration of global models to
209 streamflow or other observations is not standard yet (Kupzig *et al.*, 2023) but can be achieved in
210 principle (Döll *et al.*, 2003; Arheimer *et al.*, 2020). While all these modeling steps offer options and
211 choices that introduce uncertainty, they also result in diverse models. However, the current model
212 diversity does not reflect the diversity of hydrologic processes found across the global land surface. It
213 is rather a consequence of different modelling groups selecting a specific underlying model structure to
214 build their GWM with. This diversity can be captured by model ensembles, which offer more robust
215 predictions and help reveal knowledge gaps regarding the appropriate representation of the terrestrial
216 water cycle (e.g., Reinecke *et al.* (2021), Gnann *et al.* (2023)). Even though the ensemble is an
217 ensemble of opportunity and does not necessarily reflect model structural uncertainty in a coherent
218 manner.

219

220 Data availability is a key problem for all steps of the model-building process for GWMs. It starts during
221 perceptual model development, where the availability of data limits how detailed our system perception
222 can be. Given that modelers are also limited in their knowledge of global hydrologic diversity, this
223 limitation influences what structural representations we might even consider. While local experts may
224 have a thorough understanding of a certain hydrologic system, collecting and combining that local
225 knowledge into a coherent global database has not yet been achieved. Even though the first steps have
226 been made (McMillan *et al.*, 2023), the transferability of system understanding, especially across scales,
227 remains difficult (Wagener *et al.*, 2010). Ultimately, the lack of trustworthy (not uncertainty-free)
228 perceptual models limits our capability of tailoring global models to the diversity of hydrologic systems
229 that we find on Earth.

230

231 A chosen perceptual model is then translated into a model structure and tailored to different hydrologic
232 systems, mainly through global datasets (Table S2). The datasets are used to estimate a priori model
233 parameters, and in many cases, these data may have already influenced the equations that were used to
234 build the model structure in the first place. For example, the Harmonized World Soil Database (HWSD)
235 (Nachtergaele *et al.*, 2010) is utilized as a soil map in eight GWMs in the global water sector of the
236 Inter-Sectoral Impact Model Intercomparison Project (ISIMIP) (Frieler *et al.*, 2017), and is playing a
237 crucial role in estimating soil-related parameters. Without alternative datasets, quantifying the
238 uncertainty that this choice introduces remains a challenge. Some processes, such as groundwater
239 recharge, for which there is a lack of direct measurements of the relevant system properties are
240 parameterized by combining geology, soil, topography, and permafrost datasets, as well as expert
241 knowledge (Döll & Fiedler, 2008). However, such a complex combination of different sources of
242 information may lead to the inability to explain model differences (Reinecke *et al.*, 2021).

243 Our ability to represent the processes we assume to be present is related to finding an adequate model
244 structure, especially for scales far finer than the spatial or temporal resolution of GWMs. Adequate here
245 means that the model can be used for its intended purpose (see also Fig. 1). The representation of sub-
246 grid scale processes and their variability is a challenge to GWMs, with long-lasting debates around the
247 issues of model and parameter adequacy as well as data limitation and uncertainty (Beven & Cloke,
248 2012; Clark *et al.*, 2017). Reasons for this ongoing dispute are questions regarding the validity of
249 theories when applied beyond their scale of derivation, the representation of interactions and feedback
250 among processes, strategies to describe the effects of sub-grid scale heterogeneity, and the availability

251 of data to parameterize and test model formulations. A prominent and illustrative example is the
252 structural representation of the land surface, particularly the representation of soil processes (Fatichi *et*
253 *al.*, 2020; Or, 2020; Weber *et al.*, 2023), whose description is generally rooted in theories and limited
254 observations (Vereecken *et al.*, 2016). As mentioned, most models use maps of soil types (e.g., HWSD
255 (Nachtergaele *et al.*, 2010) or SoilGrids (Poggio *et al.*, 2021)) and correlate them with the model
256 parameters of interest via pedotransfer functions (PTFs). However, current parameterizations of soil
257 hydraulic properties based on PTFs rely on geographically limited data, generally derived from small
258 samples taken from agricultural fields, thus not accounting for soil structure effects and spatial
259 heterogeneities (Or, 2020; Gleeson *et al.*, 2021). Such effects may significantly alter infiltration-runoff
260 and other exchange processes at larger scales (Fatichi *et al.*, 2020; Bonetti *et al.*, 2021). Recent research
261 showed that it is possible to incorporate soil structure corrections into pedotransfer functions based on
262 remotely-sensed vegetation metrics and local soil texture (Bonetti *et al.*, 2021). The uncertainties in soil
263 process representation influence multiple other processes within GWMs. Besides infiltration and runoff,
264 different soil and land use representations can also influence model translation from radiation forcing
265 into evapotranspiration, thus significantly altering the water balance representation of the model (Gnann
266 *et al.*, 2023).

267 Another critical aspect of process representation and parameter estimation are anthropogenic alterations
268 of the terrestrial water cycle through land and water management. Humans have profoundly impacted
269 freshwater systems by changing land use patterns, expanding irrigation, building dams, transporting
270 water across catchment boundaries, and pumping groundwater (Abbott *et al.*, 2019). It is challenging
271 to represent these human water cycle alterations in GWMs, making it very difficult to distinguish natural
272 and anthropogenic components in hydrological signals as a consequence (Salwey *et al.*, 2023). Many
273 GWMs now represent water management processes (e.g., irrigation, reservoir operation, and
274 groundwater pumping), but with great difficulty, especially when trying to capture complex human
275 decision-making processes and field-scale management practices (McDermid *et al.*, 2023). The
276 representation of water management is often challenging because of data paucity, especially at the
277 global scale (e.g., water used for irrigation, source of water withdrawal, reservoir operation rules
278 (Pokhrel *et al.*, 2016; Wada *et al.*, 2017)). Future projections considering human activities are even
279 more problematic because scenarios of future water use and management practices are almost
280 nonexistent due to limited data of the past and lack of approaches to model the future. On the positive
281 side, there is a growing body of literature on attributing observed changes to natural versus human
282 drivers (Felfelani *et al.*, 2017), even though a comprehensive quantification is often challenging. For
283 example, the desiccation of the Aral Sea is likely primarily caused by anthropogenic disturbances, but
284 a reliable quantification is lacking (Pokhrel *et al.*, 2017).

285
286 Increasing awareness of the problem of model structural uncertainty has led to a range of modular
287 modeling frameworks that maximize flexibility to allow users, in principle, to tailor models to the
288 specific perceptual model of a particular system (Clark *et al.*, 2008; Fencia *et al.*, 2011; McMillan *et*
289 *al.*, 2011; Dembélé *et al.*, 2020). It has also led to increasing efforts to highlight and demonstrate the
290 need to explicitly formulate perceptual models to distinguish uncertainty in system perception from
291 uncertainty in model implementation (Wagener *et al.*, 2021; McMillan *et al.*, 2023). GWMs have not
292 yet fully explored the possibility of modularity. This is due to the high diversity of the subsystems (Fig.
293 2d) and missing approaches to disaggregate them sensibly and efficiently on the global scale (models
294 already separate between, e.g., humid and arid (Müller Schmied *et al.*, 2021), or mountains and plains
295 (Hoch *et al.*, 2023), but that does not account for the full hydrologic diversity). Also, current GWM
296 software architectures are rarely flexible enough to allow for flexible parameterization of different
297 subsystems with diverse process equations. Second, we lack strategies and initiatives to collect, verify,
298 organize, store, and share the vast knowledge of diverse hydrologic systems in a structured way that

299 allows a robust, transparent, and computationally efficient integration in GWMs. Finally, the diversity
300 of global hydrologic systems also underlines the need for methods to analyze and evaluate the diverse
301 outputs of GWMs. Likely, the lack of structural tailoring and, thus, limited flexibility of current global
302 models entails significant structural uncertainty. Some studies suggested that calibration should also
303 consider the hydrologic diversity and would benefit from tailoring the model structure to different
304 regions (Beck & van Dijk *et al.*, 2017; Santos *et al.*, 2022; Kupzig *et al.*, 2023).

305

306 Despite all these challenges, there are multiple possibilities for improving GWM building. Regional
307 information can be collected through community data portals (Crochemore *et al.*, 2020; Zipper *et al.*,
308 2023), increasingly high-resolution satellite products are available, and some studies have shown that
309 structural improvements can be derived from more informed and diverse perceptual models, e.g., the
310 inclusion of preferential recharge in karst regions, an important yet often omitted process (Hartmann *et*
311 *al.*, 2017).

312

313 **Forcing global models**

314 Once a model is established and a priori parameter values have been defined based on available data,
315 GWMs are driven by time-varying inputs of meteorological variables such as precipitation, temperature,
316 and radiation. These inputs may be based on historical observations, most likely reanalysis products
317 that combine observations with simulations (Beck & Vergopolan *et al.*, 2017), or climate projections of
318 future conditions, possibly with additional downscaling and bias correction steps (Maraun *et al.*, 2017)
319 (see also section 3). A less common forcing for GWMs (so far) are reconstructions of the deeper past
320 with paleo-hydro-climatic conditions (Gladstone *et al.*, 2007) to understand how the hydrologic cycle
321 has evolved over long time scales.

322 Reanalysis products depend strongly on existing observations, which means that any uncertainties (due
323 to uncertainties in the measurements themselves and in interpolation and modeling techniques to derive
324 spatial data fields, e.g., for precipitation (Viviroli *et al.*, 2011)) will propagate into the final forcing
325 product. For example, precipitation stations cover only a small area of the world (likely less than 1% of
326 the Earth's surface is represented (Kidd *et al.*, 2017)) and generally, fewer (and poorer) observations
327 are available in mountainous or economically poorer regions, leading to unbalanced datasets (Viviroli
328 *et al.*, 2011). This availability issue also affects simulations of the future, e.g., for climate impact studies,
329 because uncertainty in historical observations still matters as we require them as reference data (Tarek
330 *et al.*, 2021).

331 Uncertainty in GWMs forcing for projections of future climates is caused by three primary factors:
332 GCM/ESM or structural uncertainty (e.g., different models giving different outcomes for the same data
333 or initializations), scenario-related uncertainty (e.g., differences in outcomes due to varying
334 scenarios/input specified, e.g., atmospheric composition), and uncertainty caused by internal variability
335 (i.e., arising from natural processes such as multi-decadal oscillations) (Deser *et al.*, 2020; Lehner *et*
336 *al.*, 2020). The specific contribution of these three components to the total uncertainty generally depends
337 on the time horizon considered (the more distant the time window is from the present states, the higher
338 the uncertainty), the variable of interest (e.g., uncertainty in precipitation is generally higher than for
339 temperature), the GCM/ESM used, and the geographic region (Schwarzwald & Lenssen, 2022). While
340 structural and scenario uncertainties are important, uncertainties from internal variability can account
341 for over 50% of the total uncertainty in climate projections (Xie *et al.*, 2015; Kumar & Ganguly, 2018;
342 Deser *et al.*, 2020; Schwarzwald & Lenssen, 2022). This implies that the uncertainty in climate forcing
343 should be a key consideration in future projections by GWMs, for example, by utilizing model
344 ensembles. Among different climate forcing variables, precipitation is a key field, distant projection of

345 which can be highly uncertain and can directly influence streamflow and other outcomes in hydrological
346 models (Deser *et al.*, 2020). The uncertainty from GCM/ESM structure and scenarios is usually
347 considered in hydrologic studies by using projections from multiple GCMs/ESMs and radiative forcing
348 scenarios, respectively (Bartosova *et al.*, 2021).

349 **Evaluation of global models**

350 Evaluation is a key step to assess a model's ability to perform a specific task, or to adjust its parameters
351 as part of an iterative calibration process (sometimes referred to as tuning). Ideally, model evaluation
352 should be diagnostic (Gupta *et al.*, 2008) and help to identify model deficiencies in, e.g., capturing water
353 fluxes and storage dynamics. Evaluating process realism is an important step towards enhancing the
354 credibility of GWMs' multiple uses (Fig. 1), for example, for climate change impact assessments
355 (Krysanova *et al.*, 2020). GWMs are mostly evaluated by comparing simulated and observed
356 streamflow time series (Arheimer *et al.*, 2020), given that streamflow is relatively widely available and
357 provides information for model performance across a larger region - the upstream catchment. Other
358 fluxes and states such as evapotranspiration, snow, terrestrial water storage and soil moisture are less
359 commonly used (Pimentel & Arheimer *et al.*, 2023), but are gaining more traction with new evaluation
360 protocols (Collier *et al.*, 2018). Globally, datasets of streamflow are biased towards large rivers
361 (Downing, 2012) with extensive anthropogenic influences (Wagener & Montanari, 2011; Krabbenhoft
362 *et al.*, 2022), while other variables like groundwater recharge are often only available as long term
363 averages and certain climatic regions (dry regions) (Moeck *et al.*, 2020). Some variables are not
364 measured at all (e.g., lateral groundwater fluxes, macropore flow) and others are measured at scales
365 which are very different from the current model scales (e.g., evapotranspiration (Wartenburger *et al.*,
366 2018), soil moisture (Crow *et al.*, 2012), or groundwater table depth (Reinecke *et al.*, 2020) and
367 groundwater recharge (Moeck *et al.*, 2020)). Due to insufficient length and homogeneity of
368 observational records, long-term variations and trends in components of the water cycle can only be
369 quantified with large uncertainty (Dorigo *et al.*, 2021).

370
371 The uncertainties of observation data themselves is rarely accounted for (even if they can be substantial
372 (Westerberg & McMillan, 2015)) during GWM evaluation (or calibration) (Moges *et al.*, 2021), and
373 little is known about how this in turn affects the predictive uncertainty of GWMs. Direct comparisons
374 with observations are difficult in data-sparse regions, in regions with substantial anthropogenic impacts
375 (Döll *et al.*, 2014), and generally not possible for the future. Thus, alternative evaluation strategies have
376 been proposed. To provide information for evaluation also in regions without measurements, we may
377 use regionalized streamflow characteristics (Troy *et al.*, 2008) or functional relationships that capture
378 the co-variability of forcing and response variables in space (e.g., Koster and P. Mahanama (2012),
379 Gnann *et al.* (2023)). As a complimentary method to point-by-point comparisons with historical data,
380 evaluation focusing on input-output relationships can help to reveal additional insights into model
381 functioning (e.g., Luo *et al.* (2012), Gnann *et al.* (2023)). This is particularly relevant for climate
382 change impact studies, where response-based analysis methods can provide insight into whether a
383 model is fit for purpose, for instance, by showing whether a model's sensitivity to changing forcing is
384 as expected (Wagener *et al.*, 2022).

385
386 If the evaluation shows discrepancies between observations and model results calibration is a potential
387 strategy to reduce them. Few global models so far have been calibrated against observed variables to
388 improve a priori parameter estimates (Kupzig *et al.*, 2023). In light of the equifinality of parameter sets
389 and the risk that the model is adjusted only for the variable that is used for calibration, but not for other
390 flux or state variables, multi-criterial calibration of GWMs with different observables and signatures
391 has been recommended (Döll *et al.*, 2016; Pimentel & Crochemore *et al.*, 2023). Model calibration

392 beyond streamflow with multiple remote-sensing-based observations such as evapotranspiration, snow
393 cover, snow water equivalent, soil moisture, water level, surface temperature, among others, has been
394 realized for several river basin studies (Meyer Oliveira *et al.*, 2021). However, neither single- nor multi-
395 objective calibration has become general practice for GWMs (Telteu *et al.*, 2021). Apart from a lack of
396 observational data for many regions, the observations themselves may carry large uncertainties
397 (Pimentel & Crochemore *et al.*, 2023) and calibration procedures can be computationally expensive.
398 With km-scale models and nested catchments, calibration can be very time and resource consuming.
399 Ultimately calibration on historical observations does not ensure that GWMs are also providing robust
400 projections of future changes (Wagener *et al.*, 2022), e.g., a particular parameter might not be adequate
401 to represent streamflow processes if conditions have changed substantially due to climate and land use
402 change (Milly *et al.*, 2008).

403

404 Evaluating or calibrating GWMs requires observations of (at least some) simulated variables. Given
405 that in-situ observations do not seamlessly cover all land areas, there is prospect of using satellite-based
406 products with global coverage. Terrestrial water storage (TWS) is a variable estimated using satellite
407 gravimetry (GRACE, GRACE-FollowOn) (Landerer *et al.*, 2020; Rodell & Reager, 2023) and has
408 become an important observation for assessing GWM performance as TWS is an integrative
409 hydrological state variable (Lee *et al.*, 2023). First efforts have been made to assimilate GRACE data
410 in GWMs (Tian *et al.*, 2019). However, TWS products for model evaluation also hold substantial
411 uncertainties due to the coarse spatial and temporal resolution (Scanlon *et al.*, 2018; Rodell & Reager,
412 2023) and complex attribution to specific water storage components (Döll *et al.*, 2014). Other satellite
413 missions like Landsat (e.g., extents of surface water bodies, surface temperature, land use change),
414 altimetry missions for water level of inland water bodies and SMAP (Soil Moisture Active Passive)
415 have also proven to be essential sources to evaluate and build GWMs (McCabe *et al.*, 2017), although
416 they may also include considerable uncertainties (Pimentel & Crochemore *et al.*, 2023). Among recent
417 satellite missions, the Surface Water and Ocean Topography (SWOT) mission is expected to be an
418 important step for assessing surface water dynamics and storage variations of inland water bodies
419 (instead of water level only) with unprecedented spatial resolutions and global coverage, providing
420 insights into small and otherwise ungauged water bodies at scales of about 100 meters (Papa & Frappart,
421 2021).

422

423 To facilitate a more structured comparison between models, model intercomparison projects have
424 gained importance by providing modeling protocols that define standardized forcing data, scenarios,
425 and other modeling choices. These have been carried out very successfully in the climate community
426 with the Climate Model Intercomparison Project (CMIP) (Eyring *et al.*, 2019). The Earth System
427 Modeling community has implemented the ILAMB (International Land Model Benchmarking)
428 benchmark, which offers a structured comparison of models to observations in a standardized software
429 package (Collier *et al.*, 2018). The ISIMIP project, specifically the global water sector (Frieler *et al.*,
430 2017), has also developed standardized protocols for joint simulations to evaluate models, which have
431 already yielded multiple insights on model deficiencies and uncertainties (e.g., Zaherpour *et al.* (2018),
432 Reinecke *et al.* (2021)). Model intercomparison projects offer a powerful framework to diagnose
433 differences between GWMs and their potential reasons, as well as GWM uncertainties.

434

435 To summarize, building GWMs remains challenging regarding the identification of an adequate model
436 structure, building complex simulations software, estimating parameters, simulating human activity,
437 driving models with uncertain inputs, and evaluating them with limited observations. All these issues
438 require further study to understand and quantify existing uncertainties and their origins, and to
439 understand their implication for GWM applications. On the positive side, new and growing datasets,

440 alternative methods for model evaluation, and increasing computational resources have the potential to
441 push forward the development of GWMs.

442 **3 Uncertainties in simulating the past, future, and near future water cycle**

443 In this section, we discuss how GWM uncertainties influence simulations of past, future, and near-
444 future water cycles. We focus on six essential hydrological variables: streamflow, evapotranspiration,
445 groundwater recharge, soil moisture, terrestrial water storage, and anthropogenic water use (Table S3).

446

447 **Simulating the (recent) past**

448 Reconstructions of the terrestrial water cycle over the last 100 years include different sources of
449 uncertainty, such as model conceptualization and parameterization, meteorological forcing, and
450 anthropogenic influences that will impact simulated hydrological variables (see Section 2). This period
451 largely covers our observational records (and thus enables the use of reanalysis products) and includes
452 the main upswing of global economic growth after the Second World War. Multiple model comparison
453 studies and global water balance studies that include GWM outputs reveal substantial uncertainties,
454 even for global average fluxes.

455

456 For streamflow, studies estimate ranges from less than 40,000 km³/y to over 60,000 km³/y globally [
457 300 mm/y to > 450 mm/y] (Haddeland *et al.*, 2011; Schellekens *et al.*, 2017; Abbott *et al.*, 2019;
458 Rockström *et al.*, 2023) (see Fig. 3a for differences in a GWM ensemble). Correspondingly, estimates
459 of evapotranspiration range from approximately 60,000 to over 80,000 km³/y [450 to 600 mm/y]
460 (Haddeland *et al.*, 2011; Schellekens *et al.*, 2017; Abbott *et al.*, 2019) (see also Fig. 3b and 5d). The
461 (relative) disagreement is similarly large for fluxes such as groundwater recharge, ranging from
462 approximately 12,000 to 25,000 km³/y [90 to 190 mm/y] (Abbott *et al.*, 2019; Rockström *et al.*, 2023)
463 (see also Fig. 3c), with a recent data-based study suggesting that models generally underestimate diffuse
464 groundwater recharge (water that percolates down to groundwater rather evenly across the landscape,
465 in contrast to focused recharge that enters groundwater at certain “focused” points, such as rivers and
466 lakes) compared to observations [observation-based estimate: 218 mm/y] (Berghuijs *et al.*, 2022).

467

468 For terrestrial water storage, we can only assess relative differences between models and observations,
469 often done by examining anomalies and trends. For example, Scanlon *et al.* (2018) noted substantial
470 uncertainties among different models, reporting that terrestrial water storage anomaly trends (summed
471 over all investigated basins) are "positive for GRACE (~71–82 km³/y) but negative for models (–450
472 to –12 km³/y)". Storages, such as groundwater, accumulate errors (in contrast to fluxes) and may exhibit
473 long-term memory. This is often not captured by the current generation of models that usually contain
474 very simplified representations of groundwater systems, for example, bucket models that may not be
475 able to represent long-term storage depletion (Fowler *et al.*, 2020).

476

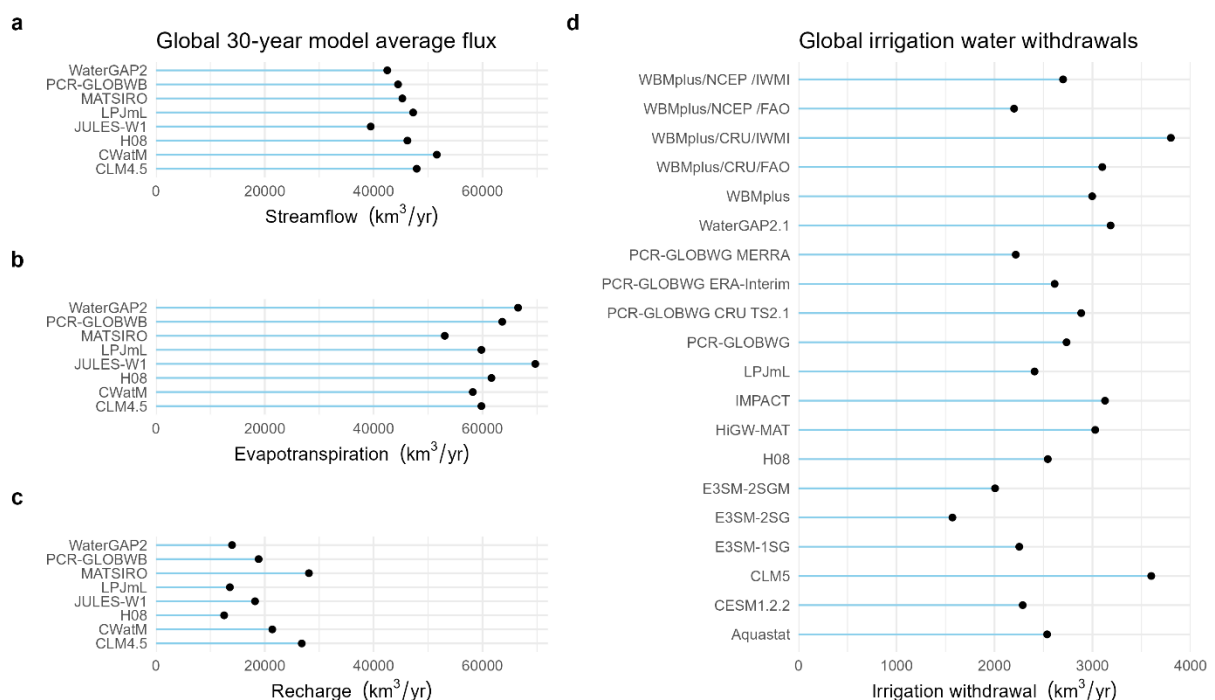
477 Anthropogenic water use is particularly uncertain, especially for irrigation, which accounts for ~70%
478 of global water withdrawals, with estimates collated by a recent study ranging from 1571 to 3,800 km³/y
479 (McDermid *et al.*, 2023) (i.e., differences by a factor of 2; Fig. 3d). Uncertainties of water use are,
480 however, not necessarily a direct consequence of GWM uncertainty but a reporting issue since minor
481 changes to definitions can change reporting of water consumption of, for example the US energy
482 system, substantially (Grubert *et al.*, 2020). Another example is the area equipped for irrigation data,
483 which is used in multiple global water models and datasets (Siebert *et al.*, 2015). If a municipality or
484 private entity reports an area as being equipped with irrigation equipment, it includes planned-but-not-
485 implemented, and existing-but-not-used equipment as well. While challenges especially remain in

486 correctly allocating withdrawals to their sources (e.g., surface water or groundwater), determining the
 487 withdrawals in the first place is highly uncertain as, for example, uncertain information on where
 488 irrigation equipment exists is fed into an uncertain irrigation model to determine irrigation estimates
 489 (McDermid *et al.*, 2023).

490

491 While global long-term averages already reveal large differences, these uncertainties are even larger in
 492 specific regions and during specific time periods. Streamflow is typically more uncertain, in relative
 493 terms, in dry regions (Zaherpour *et al.*, 2018; Heinicke *et al.*, 2024), and in lake-rich and snowy places
 494 (Giuntoli *et al.*, 2015; Beck & van Dijk *et al.*, 2017; Gädeke *et al.*, 2020). Possible reasons are that in
 495 these regions, precipitation is a weaker or less direct control on streamflow, because other processes
 496 (e.g., related to filling and spilling the storage) and their representation in GWMs are more important.
 497 For example, seasonal dynamics are often poorly captured and timing bias of the annual flow maximum
 498 is regularly more than one month, in part because of poor representation of snow, lake dynamics, and
 499 other storage processes (Gudmundsson & Wagener *et al.*, 2012; Zaherpour *et al.*, 2018). Also, studies
 500 tend to find larger uncertainties for extremes such as high and low flows (Gudmundsson & Tallaksen
 501 *et al.*, 2012; Schewe *et al.*, 2019), which are particularly important for flood and drought impact
 502 analyses. For instance, assessing modeled streamflow during the European heatwave in 2003, Schewe
 503 *et al.* (2019) found that many models underestimate low flows compared to observations, likely because
 504 these models poorly represent groundwater flow to streams that become particularly important during
 505 dry conditions. Devitt *et al.* (2021) tested four global models regarding their ability to simulate
 506 historical floods in the USA and found that two models underestimated floods by more than 25% in
 507 roughly two-thirds of all catchments, while the other two overestimated flows by the same amount in a
 508 similar fraction of catchments.

509



510

511 **Figure 3:** Disagreements between key variables of global water models. **a-c**, Differences between
 512 multiple global water models for streamflow, evapotranspiration, and groundwater recharge (replotted
 513 from Table S5 in Gnann *et al.* (2023) with a factor of 132 for conversion to km³, which is an estimate
 514 of average model cell size). **d**, Irrigation: Estimated global irrigation water withdrawals show large
 515 disagreement between models, with global water models tending to show larger values than reported

516 by the United Nations Food and Agriculture Organization in Aquastat (replotted from McDermid *et al.*
517 (2023)).

518

519

520 **Simulating the near future – seasonal forecasts**

521 Generation of near-future (seasonal to sub-seasonal) climate and hydrological forecasts is crucial for
522 integrated water resources management as well as for generating early warnings for hazards, such as
523 floods and droughts, which can have long transition periods. While seasonal climate predictions (see
524 Fig.S2 for mapping meteorological to hydrological forecasts based on timescales) are common practice,
525 their utilization for global hydrological forecasts remains uncertain and is largely under development
526 and not yet operational, except for flood forecasting (<https://www.globalfloods.eu>). The
527 quality/accuracy of global seasonal hydrological forecasts is driven by three major factors: (a) initial
528 hydrological conditions, which consider various observed variables (both hydrological and
529 meteorological), (b) GWM uncertainties (WMO, 2023), and (c) seasonal climate forecasts accuracy,
530 which depends on historical climate data and climate forecasts (temperature and precipitation being of
531 utmost significance to hydrological models; Fig.S3). However, contribution of a) - c) to the uncertainty
532 of the seasonal hydrological forecast vary with hydro-climatic zones (Shukla *et al.*, 2013), size of the
533 catchment (Paiva *et al.*, 2012), chosen reference year(s) (Shukla *et al.*, 2013; Sinha &
534 Sankarasubramanian, 2013), and prediction method (Wood *et al.*, 2016). An important component to
535 counteract these uncertainties is data assimilation (see also 4.1.) which is pivotal for state updates when
536 simulating the near future (Zhang *et al.*, 2021).

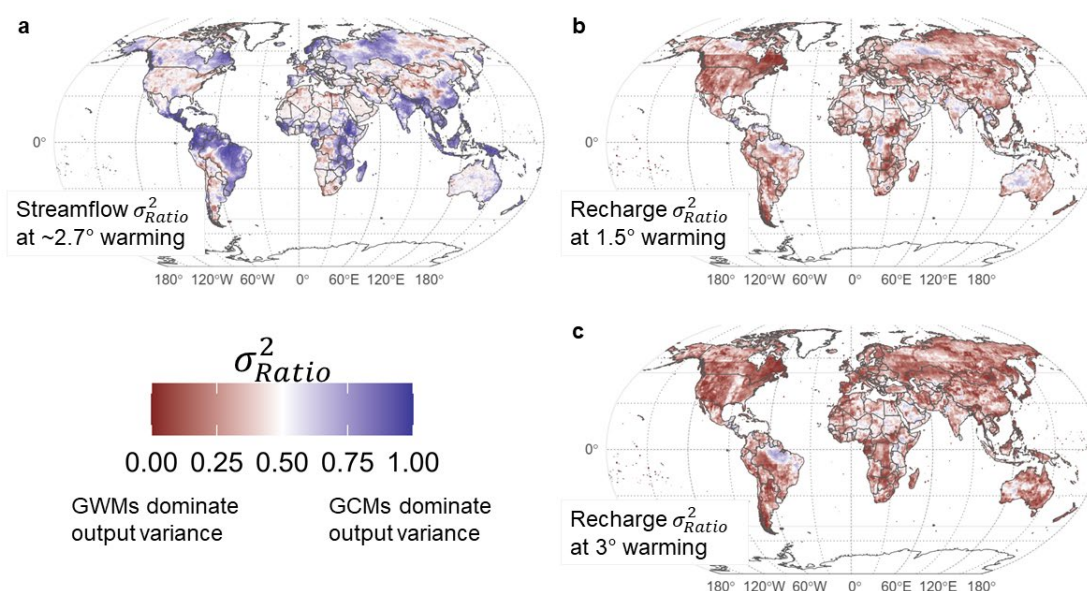
537 **Simulating the far future - climate change and water use projections**

538 The further we move away from the instrumental record of observations, into the past or future, the
539 more we expect uncertainties to grow due to the influence of scenarios and other choices (e.g.,
540 quantification of human influences, land-cover changes) (Collins *et al.*, 2012). Uncertainties related to
541 the reconstruction of the recent (50-100 years) water cycle by GWMs are thus naturally smaller than
542 the uncertainties related to future projections. This is because meteorological forcings are constrained
543 by data assimilation (reanalysis data instead of climate model projections), actual land use data are
544 obtained from remote sensing (at least in recent decades), and socio-economic forcings (GDP,
545 population, water demand) are constrained by regular country reporting. In addition, GWMs may
546 become more uncertain in future regimes for which they were not developed or calibrated, for example,
547 because of changes in biophysical processes related to CO₂ fertilization.

548

549 A question often posed is if input uncertainty or model structure uncertainty dominates the uncertainty
550 in the model output. Is the uncertainty in climate forcing originating from GCMs or are the differences
551 related to the GWMs? While this has been evaluated in multiple studies (Prudhomme *et al.*, 2014;
552 Schewe *et al.*, 2014; Giuntoli *et al.*, 2015; Wartenburger *et al.*, 2018; Reinecke *et al.*, 2021), the answer
553 depends on which models, variables, time periods, and geographic regions are included in the analysis.
554 Wartenburger *et al.* (2018) showed that evapotranspiration differences between different model choices
555 largely explain overall variability but that the spatio-temporal differences can mainly be explained by
556 forcing uncertainty. Schewe *et al.* (2014) (depicted in Fig. 4) compared sources of uncertainty for
557 streamflow and found high spatial variability in what sources dominated. In some warm arid regions,
558 GWMs dominate uncertainty more than GCMs while at least in some humid and in some cold regions
559 forcing is the major contributor to output uncertainty. This is comparable to results by Giuntoli *et al.*
560 (2015), who evaluated sources of uncertainty separately for low and high streamflow. In their analysis,
561 GCMs generally dominate uncertainty for both flow regimes with exceptions in snow dominated and
562 arid regions. They conclude that GWMs dominate uncertainty where flow processes are more relevant

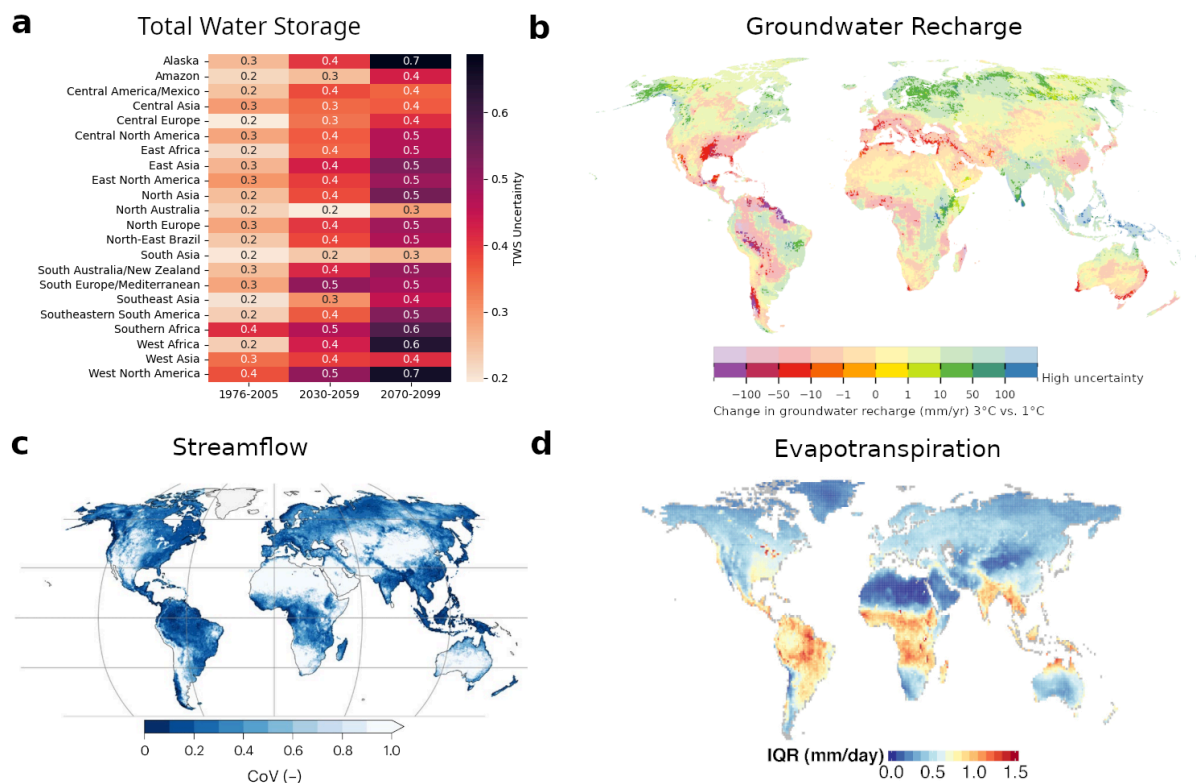
563 than precipitation input. Somewhat similarly, if we investigate subsurface water fluxes like groundwater
 564 recharge, GWM uncertainty becomes more important because these hydrological processes are less
 565 directly controlled by climatic input. For instance, Reinecke *et al.* (2021) (depicted in Fig. 4) found
 566 that in most regions the variability in process representation for groundwater recharge modeling has a
 567 larger impact on output differences than GCMs. While these studies suggest that the ratio of GWM to
 568 GCM uncertainty depends on climate characteristics and hydrological processes, a comprehensive
 569 review of sources of uncertainty across different variables is currently lacking. It would be worthwhile
 570 studying systematically for which variables, which time periods, and which regions each of these
 571 uncertainties dominate globally to show where future model improvement would have the most
 572 leverage.



573
 574 **Figure 4:** Do Global Water Models or their forcing (Global Climate Models) dominate output
 575 uncertainty? Figures a-c show maps of GWM output variance of different GCM forcing divided by total
 576 output variance for different variables and warming scenarios (in comparison to pre-industrial
 577 temperatures). **a**, Variance ratio for streamflow replotted from Schewe *et al.* (2014)(Schewe *et al.*,
 578 2014). **b-c**, Variance ratio for groundwater recharge replotted from Reinecke *et al.* (2021).

579 Uncertainty originating from the GWMs in the context of climate projections is at least partially related
 580 to the representations of various biophysical processes, such as those related to vegetation and soils
 581 (Wartenburger *et al.*, 2018), which influence how future atmospheric moisture and energy translate into
 582 hydrologic impacts variables (Samaniego *et al.*, 2017). How, for example, the function of the
 583 vegetation-soil sub-system will evolve under different climate change trajectories is uncertain, thus
 584 adding uncertainty to estimates of evapotranspiration or percolation. One would expect that the overall
 585 uncertainty increases with longer projection horizons, yet current literature is inconclusive whether
 586 GCMs or GWMs dominate projection uncertainty. For example, Pokhrel *et al.* (2021) found that for
 587 terrestrial water storage, GCM uncertainty is significantly larger than GWM uncertainty for any given
 588 Representative Concentration Pathway (RCP) scenario, with variations between regions (e.g., Fig. 5a).
 589 However, GWM uncertainty increases with time within a scenario, potentially surpassing GCM
 590 uncertainty for the distant future (e.g., a century into the future) (Pokhrel *et al.*, 2021). While one might
 591 expect GCM uncertainty to become increasingly dominant in the future, this does not always seem to

592 be the case. One reason might be that variables like TWS accumulate errors from different
 593 compartments, which is linked to a not fully closed water balance, and thus become increasingly
 594 uncertain. Another reason might be that some water models reach thresholds at which certain processes
 595 or their numerical representations change unpredictably. Some models, for example, may encode a
 596 specific fixed process behavior or factor for dryer and wetter regions, respectively; e.g., Müller Schmied
 597 *et al.* (2021). If a region shifts from wet to dry in the future, this may lead to inconsistent model
 598 behaviors, thus amplifying GWM uncertainty. The uncertainty arising from socio-economic and water
 599 use scenarios is challenging to quantify owing to the lack of data and thus limited model accuracy (see
 600 also section 2). The limited number of studies that have quantified this uncertainty indicate that future
 601 projections of water availability and use, especially for irrigation, are greatly influenced by the scenarios
 602 considered (Wada *et al.*, 2013; Rosenzweig *et al.*, 2014).



603
 604 **Figure 5:** Uncertainty in projected total water storage (a) and groundwater recharge (b), replotted from
 605 Pokhrel *et al.* (2021) and Reinecke *et al.* (2021) respectively. Uncertainty in streamflow (c) and
 606 uncertainty in evapotranspiration (d) reproduced from Gnann *et al.* (2023) and Wartenburger *et al.*
 607 (2018) respectively. In (b) only regions where model agreement is significantly large are plotted in solid
 608 colors, all other regions are shown in an opaque color. In (c) the coefficient of variation (CoV) is
 609 calculated for an ensemble of eight GWMs over a 30-year period. In (d) the interquartile range (IQR)
 610 is shown for an ensemble of 11 GWMs. The ensembles of all four studies may not use the same models.

611 One aspect of projection uncertainty is that different processes may be active or in-active; or play a
 612 dominant or minor role during changing conditions. For example, CO₂ levels can increase leaf-level
 613 water use efficiency of plants, potentially offsetting reductions in water availability due to higher
 614 temperatures through reduced evapotranspiration (Rosenzweig *et al.*, 2014; Berg *et al.*, 2016;
 615 Lemordant *et al.*, 2018; Hatfield & Dold, 2019). However, recent work also suggests that the change
 616 in water use efficiency is already exhausted due to an increased vapor pressure deficit (Li *et al.*, 2023).
 617 Water use efficiency has been suggested to strongly influence total terrestrial runoff and
 618 evapotranspiration (Gedney *et al.*, 2006; Piao *et al.*, 2007), and is not represented in some GWMs

619 despite predictions of CO₂ fertilization effects being credited as a source of uncertainties. This can lead
620 to contradicting findings regarding the extent to which a climate induced decline in water availability
621 and improved plant water use efficiency counterbalance each other (Mankin *et al.*, 2019; Adams *et al.*,
622 2020; Singh *et al.*, 2020). Uncertainty from CO₂ fertilization effects have also been linked to the
623 uncertainty in future projections of crop productivity, irrigation water use, and groundwater recharge
624 (Fig. 5b) (Elliott *et al.*, 2014; Rosenzweig *et al.*, 2014; Reinecke *et al.*, 2021). A second example are
625 cold regions, many of which will experience considerable change as rising temperatures will affect
626 frozen water storage in snow, glaciers, and permafrost. Given that some models are already associated
627 with considerable uncertainty in cold and lake-rich places (Giuntoli *et al.*, 2015; Beck & van Dijk *et*
628 *al.*, 2017; Gädeke *et al.*, 2020), it is unclear how robust future projections are and what role threshold
629 behavior will play. For example, reduction in snow cover and/or greening due to vegetation growth can
630 lead to albedo feedback, reducing streamflow due to increased net radiation (Milly & Dunne, 2020).
631 Better representation of glaciers increasing runoff in glacierized basins is already included in some
632 models (Cáceres *et al.*, 2020; Wiersma *et al.*, 2022). Other aspects related to human decisions, such as
633 land use change (Sterling *et al.*, 2013) and water regulation (Arheimer *et al.*, 2017), may even mask
634 climatic change but are difficult to investigate due to a lack of historical data as discussed earlier.

635 **4 Uncertainties as a guide for the advancement of global water models**

636 The use of global water models is unavoidably associated with uncertainties that arise during model-
637 building and execution. These uncertainties influence simulations of past, near-future, and future water
638 cycles. Key sources of uncertainties in GWMs are deficits and imbalances in data quality and
639 availability across geographical regions and between hydrologic variables, poorly quantified human
640 influences on the water cycle, and difficulties in tailoring process representations to regionally diverse
641 hydrologic systems. Due to these GWM uncertainties, we have a limited understanding of when and
642 where our models provide reliable and consistent results. Specifically, it is unclear to what extent the
643 models realistically reflect regional hydrological behavior, and a distinction between natural variability
644 and human impacts remains challenging. The scientific community can use uncertainties to guide future
645 GWM development by gathering new, more accurate, and larger datasets, improving process
646 knowledge, and ultimately building more reliable and consistent models.

647 **4.1 Towards more consistent and reliable information**

649 We have discussed in depth that limited information is a core issue causing GWM uncertainty. So where
650 is new information likely to come from? Upcoming satellite missions will provide information on
651 variations in inland water bodies at unprecedented spatial resolutions, providing new insights into the
652 hydrology of ungauged regions (Papa & Frappart, 2021). Some initiatives, like ESA-CCI
653 (<https://climate.esa.int>), offer possibilities for better parameterization of, for example, land cover, which
654 would lead to a better representation of surface heterogeneity, and many other essential climate
655 variables to be used for model forcing, parameterization, calibration, or evaluation (even if they may
656 also carry substantial uncertainties (Pimentel & Crochemore *et al.*, 2023)). Recent efforts have also
657 shown that remote sensing data can be used to monitor human alterations of the water cycle such as
658 dam construction (Zhang & Gu, 2023) and can be used to extend in-situ observations of streamflow
659 (Elmi *et al.*, 2024).

660
661 Beyond satellites, there are ongoing efforts to collect high-resolution data such as HydroBASINS
662 (Lehner & Grill, 2013), which are not yet fully utilized. For example, increasing spatial resolution of
663 digital elevation data offers new possibilities for high-resolution river routing (Yamazaki *et al.*, 2019).
664 However, to profit from such advancements requires new methods to utilize this high-resolution data

665 in the current comparably coarse-scale models. Advances in data availability also require advancements
666 in how we merge data and models. Data assimilation methods established in other communities can be
667 utilized to adjust GWMs and have already been adopted (Gerdener *et al.*, 2023). Importantly, satellites,
668 and in fact any observations, carry uncertainty that should be propagated through GWM estimates.
669 While propagating this uncertainty into model results is computationally expensive, the main problem
670 again is that information about uncertainty is rarely available for existing datasets.

671

672 The spatial resolution of GWMs is increasing, with the hope of improving model accuracies because
673 parameter heterogeneities and spatial variability can be better resolved (Wood *et al.*, 2011; Beven &
674 Cloke, 2012; Bierkens, 2015). However, existing problems in process representation and data
675 availability will not be eliminated through increased resolutions (Beven & Cloke, 2012). Hoch *et al.*
676 (2023) showed that improvements may be found for streamflow but not necessarily for other
677 hydrological variables, owing to a lack of accurate high-resolution forcing data, inaccurate scale
678 transitions of model parameters, and challenges in realistically representing scale-dependent processes
679 (Beven & Cloke, 2012). However, increasing resolutions might enable more regional information to be
680 used in GWMs, for example, by assimilating regional system conceptualizations.

681

682 Data is used in all stages of the model-building and execution process. Hence, new and improved data
683 will be critical for advancing GWMs, including data on local/regional hydrologic knowledge, newly
684 measured or collated datasets, and more information on data uncertainties. The scientific community
685 started investing resources in collecting local knowledge to improve model structures and tailor them
686 to specific regions. For example, community portals (Crochemore *et al.*, 2020; 2023) allow uploading
687 existing local models (including data, code, and documentation) or perceptual models (McMillan *et al.*,
688 2023) that encode the hydrological knowledge and human influences of particular regions. We can
689 extract and synthesize information from such databases to tailor global models to specific areas.

690

691 New research may also extract knowledge from the enormous number of existing publications, which
692 could be automatically built into new global datasets of regional knowledge (Stein *et al.*, 2022). Existing
693 data may also be found in non-scientific resources and can be combined into valuable products of human
694 influences on the water cycle, e.g., freshwater demand for energy production (Gerbens-Leenes *et al.*,
695 2024). Existing data can be combined into joint datasets such as the Global Gravity-based Groundwater
696 Product (G3P) (Güntner *et al.*, 2023), which combines different observational products into one global
697 product of groundwater storage variations (other examples of combined datasets exists such as (Moeck
698 *et al.*, 2020)). Further, datasets often lack uncertainty quantification, which would be valuable to
699 rigorously test how uncertainties affect GWM output uncertainties (when used to force or calibrate
700 models) and allow for a more improved model evaluation (Kiang *et al.*, 2018; Beven *et al.*, 2020;
701 Pimentel & Crochemore *et al.*, 2023). Model evaluation should also include not just streamflow but
702 other components of the water cycle as well, such as evaporation (Pimentel & Arheimer *et al.*, 2023),
703 groundwater recharge (Wan *et al.*, 2024), soil moisture (Crow *et al.*, 2012), and snow (Arheimer *et al.*,
704 2017). However, this again requires datasets that are less biased towards specific regions, quantified
705 uncertainties of the measurements themselves, and methods to compare point measurements to coarse-
706 scale models estimates.

707

708 **4.2 Toward more consistent and reliable models**

709 Collecting existing regional knowledge provides the opportunity to tailor GWMs to particular regions.
710 However, current modeling frameworks (Clark *et al.*, 2008; McMillan *et al.*, 2011; Clark & Nijssen *et al.*,
711 2015) that allow for a more modular approach to hydrologic modeling require information about
712 the model structure that best fits particular hydrologic settings, something we rarely have. Modular

713 catchment-scale modeling mainly works through model structure comparison using performance
714 metrics, which does not allow for upscaling to largely ungauged global settings and suffers from model
715 structure equifinality (Knoben *et al.*, 2020). New approaches that express global hydrologic diversity
716 in a model without the computational and diagnostic drawbacks of existing frameworks (i.e., sampling
717 a multitude of model structures) are necessary. One path might be better utilization of perceptual models
718 to guide a priori model component selection based on our hydrologic understanding (Kiraz *et al.*, 2023).
719 During the model-building process, different assumptions may lead to different models. Making the
720 perceptual (or conceptual) model explicit (e.g., through a graphical representation) can help to
721 understand assumptions about the underlying system and resulting uncertainties (Wagener *et al.*, 2021).
722 Making the computer code of these models openly available is equally important as it enables the
723 community to work towards open science goals and make internal assumptions such as hard-coded
724 empirical factors (Hutton *et al.*, 2016) more transparent.

725
726 Another pathway to GWM improvement lies in evaluation strategies that use the global process
727 variability represented already in these models as an advantage. Compared to single catchment models,
728 GWMs simulate a large diversity of regions simultaneously. This enables us to search for similar
729 patterns of hydrologic behavior, for instance, functional relationships between forcing and response
730 variables, which can be used for model diagnosis and improvement (Gnann *et al.*, 2023). Also, the wider
731 application of diagnostic signatures (Gnann *et al.*, 2021; McMillan, 2021) provides a pathway to
732 improve GWM evaluation. Methods for uncertainty attribution can guide the necessary reduction in
733 data and model uncertainty (by focusing on main sources of uncertainty) and help evaluate the models'
734 sensitivity to future changes (Wagener *et al.*, 2022). Connected to those ideas is the development of
735 calibration in general and new calibration schemes adapted for GWMs as mentioned in Section 2.
736 Currently, most of the existing methods have been developed in a catchment or regional modeling
737 context and lack the flexibility to account for the hydrologic diversity of GWMs (Kupzig *et al.*, 2023).
738

739 The GWM community increasingly couples their models with those developed by other communities
740 (climate models, flood models, crop models, water quality models, groundwater models, socio-
741 economic models, and many more) to obtain a more integrated Earth system view. The hope is that
742 these models will be able to represent feedback loops that could otherwise not be simulated, such as
743 land-atmosphere feedback (Koster *et al.*, 2004; Zipper *et al.*, 2019) or groundwater-surface water
744 interactions and the supply of groundwater to the atmosphere through capillary rise (Reinecke *et al.*,
745 2019). These coupled systems can then be used to, for example, investigate the nitrogen cycle (Vilmin
746 *et al.*, 2020), the carbon cycle (Zhang *et al.*, 2020) or in the future possibly to better represent human
747 interaction, e.g., by coupling socio-economic models with GWMs.

748
749 However, it is still unclear how model coupling affects model uncertainty. Coupling requires additional
750 assumptions and thus likely increases uncertainty, yet examples of coupling land surface processes with
751 atmospheric processes have shown that coupling might help to constrain model dynamics and possibly
752 reduce uncertainty (Lewis & Dadson, 2021). While some efforts already achieved online coupling
753 (allowing feedbacks to flow into both model domains (Furusho-Percot *et al.*, 2019)), others are limited
754 by the computational burden of one model or the resulting coupling feedbacks (e.g., flood modeling
755 (Hoch & Trigg, 2019)). In addition, the challenge of multi-parameter calibration (e.g., for energy and
756 water fluxes) escalates for these coupled systems (Sellar *et al.*, 2019).

757
758 Finally, an aspect which is often overlooked is the modeling software itself. Several GWMs have been
759 developed for almost 30 years (e.g., WaterGAP since 1996 and VIC since 1994 (Liang *et al.*, 1994)) by
760 many students and researchers with diverse programming experience (Reinecke *et al.*, 2022). While

761 some have been published as open-source, most models remain closed-source projects primarily used
762 by one research group (Melsen, 2022). Openly available models rarely contain comprehensible
763 documentation of the code itself, i.e., internal documentation, and of how to use and modify it, i.e.,
764 external documentation, and require experts to be executed. The unavailability and complexity of the
765 models and their code mean that they usually do not comply with FAIR principles (Findability,
766 Accessibility, Interoperability, Reusability) (Barker *et al.*, 2022; Nyenah *et al.*, 2024), affecting the
767 reproducibility of research relying on GWMs. It is currently unclear to what extent the code complexity
768 and lack of application of established software engineering best practices affect model uncertainty
769 (Nyenah *et al.*, 2024). Poorly documented code may lead to unintentional wrong use, missing rigorous
770 automated tests may lead to mistakes, and hidden physical constants and assumptions contribute to
771 uncertainty (Mendoza *et al.*, 2015; Cuntz *et al.*, 2016; Hutton *et al.*, 2016). Still, efforts have been made
772 to make underlying assumptions and equations more transparent (Telteu *et al.*, 2021). A likely source
773 for this missing compliance with FAIR principle is that current funding and hiring practices undervalue
774 model development efforts (Reinecke *et al.*, 2022; Nyenah *et al.*, 2024). GWMs should strive to make
775 their code openly available, including comprehensive internal and external documentation. Open code
776 will lead to fewer hidden and implicit assumptions, reducing model uncertainty and will lead to faster
777 progress. Modular software, for example, offers the possibility to transfer implementations (e.g., human
778 water use, routing) between models. In addition, a more flexible code would allow for a more flexible
779 implementation of different model structures, which in turn would be an essential step towards
780 achieving regional tailoring. Reproducible experiments will provide a pathway to more in-depth
781 knowledge of model differences, and more modular and modern software code will lead to experiments
782 that can pinpoint uncertainties in process understanding more accurately.

783

784 **4.3 Machine learning as a complementary modeling approach**

785 Machine learning (ML) methods are rapidly entering global hydrology and will likely help gather better
786 information, fill knowledge gaps regarding hydrologic processes, human dynamics, etc., and build
787 better models (Tsai *et al.*, 2021). Purely data-driven ML has already demonstrated high performance in
788 predicting hydrologic variables across the water cycle (Shen *et al.*, 2021), including streamflow (Feng
789 *et al.*, 2020), soil moisture (Fang *et al.*, 2017; O & Orth, 2021), snow water equivalent (Meyal *et al.*,
790 2020), and groundwater levels (Wunsch *et al.*, 2022). One benefit of ML is that it absorbs information
791 directly from data. This produces models that are inherently consistent with data, but which also inherit
792 the imbalances and uncertainties of these data. In addition, purely data-driven models may be hard to
793 interpret or helpful in making a specific scientific inquiry as they do not directly encode physical
794 concepts. As an important mission of GWMs is to create long-term projections under future climate, it
795 remains unclear (and difficult to evaluate) if pure ML models are suitable for such long-term tasks. At
796 the same time, ML models have already shown to provide more accurate real-time flood forecasts than
797 state-of-the-art global modeling systems, indicating their potential (Nearing *et al.*, 2024).

798

799 Other approaches have shown the capability of ML approaches to emulate complex physical models,
800 which could foster future uncertainty quantification in continental to global scales water models
801 (Bennett *et al.*, 2024). ML models can also be used to estimate human water uses and thus reduce
802 uncertainty in GWMs (Shrestha *et al.*, 2024). Hybrid models of classical GWMs and ML (Kraft *et al.*,
803 2022; Slater *et al.*, 2023), such as differentiable models (Shen *et al.*, 2023), are developed to reap the
804 benefits of both worlds while circumventing their respective limitations. Differentiable models mix
805 process-based equations with neural networks and offer the ability to learn unknown physical
806 relationships. By finding new relationships that govern large scale processes of the water cycle they
807 could help to reduce GWM uncertainty. While ML models potentially carry less of the uncertainty as
808 they can skip steps in the classical modeling chain (Nearing *et al.*, 2021), they will ultimately also suffer

809 from limited global hydrological information and thus will equally benefit from new, more accurate,
810 and larger datasets (Beven, 2020; Nearing *et al.*, 2024). In the future, machine learning and process-
811 based models are likely to be particularly powerful when used as complementary approaches that can
812 both efficiently learn from data and be enriched with hydrological and other process knowledge
813 (Reichstein *et al.*, 2019).

814

815 **5 The future of global water models**

816 The water cycle is a central element in the Earth system, transporting and storing water and energy,
817 nutrients, sediments, and pollutants. Thus, the water cycle influences our climate, societal development,
818 and the evolution of ecosystems. Global water models have evolved into widely used tools that help us
819 understand and predict the terrestrial water cycle under past, current, and potential future conditions.
820 Key water fluxes such as streamflow, evapotranspiration, groundwater recharge, and water storage in
821 its various forms can now be simulated consistently across the whole global land surface. Outputs of
822 these models support critical global discussions and scientific analyses around the central resource of
823 all life on Earth and are a dominant source of disaster risk assessments for society.

824

825 However, considerable uncertainties remain despite significant advances in GWMs in recent years.
826 Reasons for these uncertainties are that data quality and availability are hugely imbalanced worldwide,
827 imprints of human alterations on the water cycle are poorly quantified, and the diversity of hydrologic
828 systems makes it challenging to represent process diversity adequately. Yet, these uncertainties are
829 mostly epistemic in nature and can be reduced if knowledge gaps are closed. We think that reducing
830 these gaps will happen through new observations, the synthesis of existing regional hydrologic
831 knowledge, diagnostic model evaluation strategies tailored to the specific characteristics of GWMs, and
832 through improved and new modeling approaches, including machine learning and hybrid strategies.

833

834 In the future, new data sources, including those from new satellites and new and open collections of
835 existing observations, will provide considerably more information that can be assimilated into GWMs
836 to improve model structures, parameters, and, ultimately, predictions. How quickly this might happen
837 will depend on how new approaches, including those from Machine Learning, enable us to interrogate
838 large and diverse datasets to estimate model parameters and structures (with more or less stringent
839 physical constraints). Increasing the space-time resolution of existing models further means that model
840 parameters and state variables become closer in scale to the variables we can observe. Whether this will
841 lead to improved model performances, as seen in meteorology (Bauer *et al.*, 2015), is questionable
842 (Beven & Cloke, 2012) and examples show that increasing hydrologic model resolution does not
843 necessarily lead to better results (Hoch *et al.*, 2023). Also, blind spots in our observations of properties
844 and dynamics of hydrologic systems remain despite advancements in observations. Lastly, significant
845 opportunities for advancement remain in the context of GWM evaluation. Few strategies have so far
846 been developed that benefit from the nature of GWMs, e.g., by looking across large gradients in the
847 model domain or by establishing contrasting expectations of model form (structure and parameters) and
848 behavior.

849

850 Keeping track of and utilizing advancements in machine learning, observational capabilities, computer
851 science, and other relevant fields will be increasingly difficult for individuals and groups. Integrating
852 diverse knowledge and skill sets will be critical to developing and maintaining a highly dynamic
853 research field. In addition, various other fields also attempt to establish global modeling capabilities
854 across the Earth sciences, e.g., vegetation modeling, to understand carbon fluxes. Cross-communication
855 and exchange will likely be highly beneficial for all areas where similar problems of building, testing,

856 and utilizing global models exist. Therefore, the reasoning put forward in this review goes beyond the
857 topic of GWMs but provides a wider blueprint for how understanding epistemic uncertainties can be a
858 light to guide knowledge discovery and accumulation for global model improvement.

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870

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