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	<p>Our results emphasize the ice-dynamical relevance of needing to better constrain the strength of fabric processes. This calls for more widespread fabric and temperature measurements from the field, since measurements are currently too sparse for model validation.</p>

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Rheological control of crystal fabrics on Antarctic ice shelves

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ABSTRACT. Ice crystal fabrics can exert significant rheological control on ice sheets and ice shelves, potentially softening or hardening anisotropic ice by several orders of magnitude compared to isotropic ice. We introduce an anisotropic extension of the Shallow Shelf Approximation (SSA), allowing for fabric-induced viscous anisotropy to affect the flow of ice shelves in coupled, transient simulations. We show that the viscous anisotropy of synthetic ice shelves can be parameterized using an isotropic flow enhancement factor, suggesting that existing SSA flow models could, with little effort, approximate the effect of fabric on flow. Next, we propose a new way to directly solve for SSA fabric fields using satellite-derived velocities, assuming velocities are approximately steady and that fabric evolution is dominated by lattice rotation with or without discontinuous dynamic recrystallization. We apply our method to the Ross and Pine Island ice shelves, Antarctica, suggesting that these regions might experience significant fabric-induced hardening and softening depending on the relative strength of lattice rotation and recrystallization. Our results emphasize the ice-dynamical relevance of needing to better constrain the strength of fabric processes.

26 **This calls for more widespread fabric and temperature measurements from the field, since**
27 **measurements are currently too sparse for model validation.**

28 INTRODUCTION

29 Nearly three-quarters of Antarctica's coastline is surrounded by floating ice shelves that affect the stability and
30 mass balance of the Antarctic ice sheet. The buttressing provided by these ice shelves can influence the mass
31 flux of marine-terminating glaciers across their grounding lines, but estimating the effect requires an accurate
32 representation of ice shelves in large-scale flow models (Otosaka and others, 2023; Sun and Gudmundsson, 2023;
33 Joughin and others, 2021; Rignot and others, 2004; Reese and others, 2018; Rathmann and others, 2017) with
34 some caveats (Hulbe and Fahnestock, 2004; Hill and others, 2021). Unlike modeling the flow of grounded ice
35 which depends on information about ice geometry, boundary conditions, thermal state, and material (rheological)
36 properties, floating ice shelves represent a somewhat simpler problem: their boundary conditions are better known
37 (no drag on the bottom ocean boundary), they deform by plug flow (negligible vertical shear), and their geometry
38 can be approximated from surface elevation measurements if assumed to fulfill the flotation criterion.

39 Despite their simpler setting, many factors complicate the modeling of ice shelves, such as (hydro)fracturing
40 causing locally softer ice (Borstad and others, 2017; Sun and others, 2017), heterogeneous sub-shelf melting
41 (Adusumilli and others, 2018), and the accretion of marine ice with different thermal and rheological properties
42 (Craw and others, 2023; Treverrow and others, 2010). Another rheological phenomenon that is often neglected (or
43 at least not explicitly modeled) is the heterogeneous viscous anisotropy caused by an evolving crystal-orientation
44 fabric (henceforth *fabric*) (Lutz and others, 2020; Diez and others, 2016; LeDoux and others, 2017), with potential
45 analogies to continental ice streams insofar as they are facilitated by negligible basal drag due to subglacial melting
46 (Gerber and others, 2023; Ma and others, 2010).

47 Of the rheological properties that evolve spatiotemporally (Figure 1), ice temperature exerts in general the most
48 important control. For the range of temperatures observed in ice sheets, -55°C to 0°C , ice fluidity (ease of
49 deformation) can vary by up to a factor of 1000 (Cuffey and Paterson, 2010). If deformation is dominated by
50 dislocation creep (typical for ice colder than -10°C , but depends on stress magnitude, too), the crystal fabric is
51 arguably the second most important rheological property (Fan and Prior, 2023; Duval and others, 1983; Castelnu
52 and others, 1998), unless the ice mass is very fractured. Strongly developed anisotropic ice can be up to 10 times
53 easier to shear and 100 times harder to compress compared to isotropic ice, depending on how favorable grain

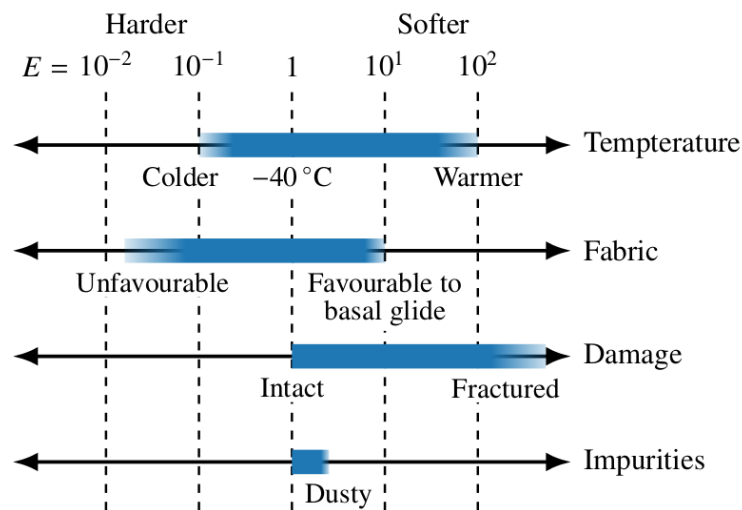


Fig. 1. Overview of strain-rate enhancing mechanisms in ice.

54 orientations are to basal glide (Pimienta and others, 1987; Shoji and Langway, 1985; Jacka and Budd, 1989; Jacka
55 and Jun, 2000) (Figure 1).

56 Modeling the coupled evolution between fabric and flow has received a lot of attention in the literature, although
57 limited to flow-line models primarily due to computational expense (Lilien and others, 2023, 2021; Rathmann and
58 Lilien, 2021; Martín and others, 2009; Martín and Gudmundsson, 2012; Ma and others, 2010; Durand and others,
59 2007; Pettit and others, 2007; Castelnau and others, 1998; Gillet-Chaulet and others, 2006; Mangeney and others,
60 1996). The full-Stokes problem (unapproximated momentum balance) for isotropic ice is likewise computationally
61 expensive, making it unfeasible for transient simulations over long time scales. Vertically integrated momentum
62 balance approximations are therefore frequently used (Seroussi and others, 2023), relying on scaling arguments and
63 the shallow aspect ratio of polar ice masses.

64 The Shallow Shelf Approximation (SSA), loosely referred to as *plug flow*, was originally proposed to model
65 the flow of ice shelves, assuming negligible vertical shear and basal drag (Morland, 1987; MacAyeal, 1989). But
66 ice shelves are predominantly in a state of longitudinal extension, which can lead to the development of girdle
67 fabrics (Treverrow and others, 2010) that harden the ice for further along-flow extension compared to isotropic ice
68 (Castelnau and others, 1996; Pimienta and others, 1987). Moreover, horizontal single-maximum fabrics can develop
69 in ice-shelf shear margins similar to ice streams (Monz and others, 2021; Thomas and others, 2021; Gerber and
70 others, 2023) that are softer for shear than isotropic ice (Echelmeyer and others, 1994; Jackson and Kamb, 1997;
71 Pimienta and others, 1987), potentially leading to faster interior (trunk) flow than predicted by isotropic ice flow
72 models.

73 In this paper, we introduce an anisotropic version of the SSA equations and explore the extent to which viscous
 74 anisotropy of ice shelves can be parameterized by an equivalent scalar flow enhancement factor, thus making it easier
 75 to account for the effect of crystal fabrics in existing state-of-art *isotropic* ice flow models. This paper therefore
 76 shares the goals of, and builds on, previous work by Placidi and others (2010), Ma and others (2010), Treverrow and
 77 others (2015), and Graham and others (2018).

78 In the following, we first introduce the methodological background, which includes the anisotropic SSA problem,
 79 how the two-way coupling with fabric evolution is solved, and how the equivalent enhancement factor has previously
 80 been defined, including a new definition that we find useful. The methodology builds on recent developments of
 81 ours (Richards and others, 2021; Rathmann and Lilien, 2021; Lilien and others, 2023), and the reader less interested
 82 in technical details may choose to focus on the section “Equivalent isotropic enhancement” where the equivalent
 83 enhancement is introduced and subsequently section “Application to Antarctic ice shelves” where it is applied to the
 84 Ross and Pine Island Glacier (PIG) ice shelves, Antarctica, suggesting that significant fabric-induced hardening and
 85 softening may be present in Antarctic ice shelves.

86 ANISOTROPIC SSA

87 Momentum balance

88 The SSA momentum balance is (Morland, 1987; MacAyeal, 1989)

$$\nabla \cdot (H\mathbf{R}) = \rho g H \nabla S, \quad (1)$$

89 where S is the surface height, H is the ice thickness, $\rho = 917 \text{ kg m}^{-3}$ is the density of ice, $g = 9.8 \text{ m s}^{-2}$ is the
 90 gravitational acceleration, and the resistive viscous stress tensor is defined as

$$\mathbf{R} = \begin{bmatrix} 2\tau_{xx} + \tau_{yy} & \tau_{xy} \\ \tau_{xy} & \tau_{xx} + 2\tau_{yy} \end{bmatrix}. \quad (2)$$

91 The deviatoric stress components τ_{xx} , τ_{yy} and τ_{xy} follow from the power-law rheology of ice assuming dislocation
 92 creep is the dominant deformation mechanism,

$$\boldsymbol{\tau} = A^{-1/n} \dot{\boldsymbol{\epsilon}}^{(1-n)/n} \mathbf{C}, \quad (3)$$

$$\dot{\boldsymbol{\epsilon}} = \sqrt{\frac{\mathbf{C} : \dot{\boldsymbol{\epsilon}}}{2}}, \quad (4)$$

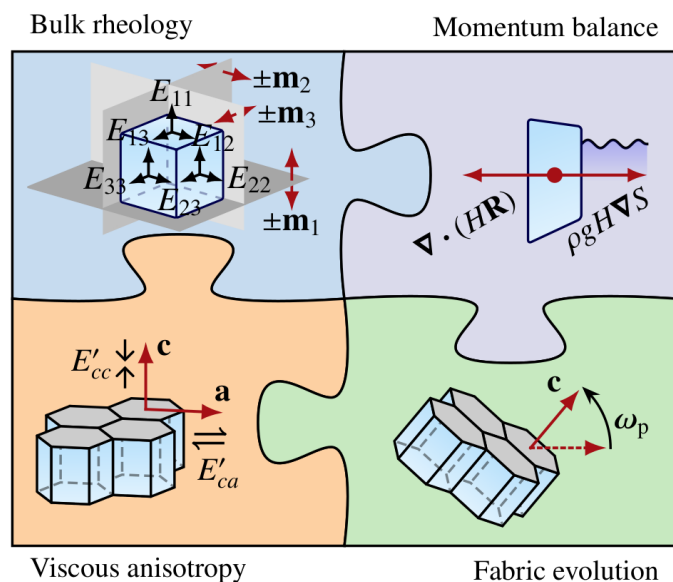


Fig. 2. Schematic of the two-way coupled problem between flow and fabric evolution.

93 where A is the depth-averaged flow rate factor, $\dot{\epsilon}$ is the strain rate tensor, $\dot{\epsilon}$ is the effective strain rate, n is the flow
 94 exponent, and \mathbf{C} is the tensorial part of the rheology. Assuming incompressibility, the strain-rate tensor is

$$\dot{\epsilon} = \begin{bmatrix} \dot{\epsilon}_{xx} & \dot{\epsilon}_{xy} & 0 \\ \dot{\epsilon}_{xy} & \dot{\epsilon}_{yy} & 0 \\ 0 & 0 & -\dot{\epsilon}_{xx} - \dot{\epsilon}_{yy} \end{bmatrix}, \quad (5)$$

95 following usual scaling arguments for ice masses with a small aspect ratio, allowing vertical shear to be neglected
 96 (MacAyeal, 1989).

97 The difference between the isotropic and anisotropic SSA equations is presented in Supplementary A. In effect,
 98 vertical velocity gradients vanish only to first order in the ice-mass aspect ratio, whereas for isotropic ice they also
 99 vanish to second order. Therefore, care should be taken when applying the anisotropic SSA to ice masses with aspect
 100 ratios less than ~ 100 .

101 Bulk rheology

102 In the case of Glen's isotropic rheology, the tensorial part is $\mathbf{C} = \dot{\epsilon}$. For anisotropic rheologies, however, the strain-
 103 rate components should be scaled according to the local fabric-induced viscous anisotropy.

104 The orthotropic rheology (Gillet-Chaulet and others, 2005) has three mutually perpendicular planes of reflection
 105 symmetry with normals \mathbf{m}_1 , \mathbf{m}_2 , and \mathbf{m}_3 , allowing each strain-rate component to be uniquely scaled by viscous

106 anisotropy (Figure 2). In the notation of Lilien and others (2023), the tensorial part of the orthotropic rheology is

$$\mathbf{C} = \sum_{i=1}^3 \left(\eta_i (\mathbf{P}_i : \dot{\boldsymbol{\epsilon}}) \mathbf{P}_i + \eta_{i+3} (\mathbf{P}_{i+3} : \dot{\boldsymbol{\epsilon}}) \mathbf{P}_{i+3} \right), \quad (6)$$

107 where

$$\mathbf{P}_i = \frac{\mathbf{I}}{3} - \mathbf{m}_i \mathbf{m}_i, \quad \mathbf{P}_{i+3} = \frac{\mathbf{m}_{j_i} \mathbf{m}_{k_i} + \mathbf{m}_{k_i} \mathbf{m}_{j_i}}{2}, \quad (7)$$

108 are projectors such that $\mathbf{P}_i : \dot{\boldsymbol{\epsilon}}$ and $\mathbf{P}_{i+3} : \dot{\boldsymbol{\epsilon}}$ give the longitudinal and shear strain-rate components in the \mathbf{m}_i frame,
109 respectively, $\mathbf{m}_i \mathbf{m}_i$ and $\mathbf{m}_{j_i} \mathbf{m}_{k_i}$ denote outer products, and the index tuples are defined as $(j_1, j_2, j_3) = (2, 3, 1)$ and
110 $(k_1, k_2, k_3) = (3, 1, 2)$.

111 The coefficients η_i and η_{i+3} are dimensionless directional viscosities that scale the strain rate components in the
112 \mathbf{m}_i frame. These can conveniently be written in terms of the fabric-induced directional enhancement factors E_{ij}
113 (Rathmann and Lilien, 2022)

$$\eta_i = 3 \frac{E_{j_i j_i}^{2/(n+1)} + E_{k_i k_i}^{2/(n+1)} - E_{ii}^{2/(n+1)}}{\sum_{i=1}^3 \left(2E_{j_i j_i}^{2/(n+1)} E_{k_i k_i}^{2/(n+1)} - E_{ii}^{4/(n+1)} \right)}, \quad \eta_{i+3} = 2E_{j_i k_i}^{-2/(n+1)}. \quad (8)$$

114 Here, E_{ij} are to be understood as the size of the strain-rate components in the \mathbf{m}_i frame relative to that if the fabric
115 was isotropic (Glen's rheology)

$$E_{ij} = \frac{\mathbf{m}_i \cdot \dot{\boldsymbol{\epsilon}}(\hat{\boldsymbol{\tau}}) \cdot \mathbf{m}_j}{\mathbf{m}_i \cdot \dot{\boldsymbol{\epsilon}}_{\text{iso}}(\hat{\boldsymbol{\tau}}) \cdot \mathbf{m}_j}, \quad (9)$$

116 for a longitudinal ($i = j$) or shear ($i \neq j$) stress state aligned with the \mathbf{m}_i frame

$$\hat{\boldsymbol{\tau}} = \tau_0 \begin{cases} \mathbf{I}/3 - \mathbf{m}_i \mathbf{m}_i & \text{if } i = j \\ (\mathbf{m}_i \mathbf{m}_j + \mathbf{m}_j \mathbf{m}_i)/2 & \text{if } i \neq j \end{cases}. \quad (10)$$

117 In this way, E_{11} is the longitudinal strain-rate enhancement along \mathbf{m}_1 when subject to compression/tension along
118 \mathbf{m}_1 , E_{12} is the \mathbf{m}_1 – \mathbf{m}_2 shear strain-rate enhancement when subject to shear in the \mathbf{m}_1 – \mathbf{m}_2 plane, etc. To be clear:
119 $E_{ij} > 1$ implies a softened material response due to fabric anisotropy compared to isotropic ice, whereas $E_{ij} < 1$
120 implies hardening. Notice that (6)–(8) reduces to Glen's isotropic rheology for $E_{ij} \rightarrow 1$.

121 We mention in passing that modeling ice flow using an orthotropic rheology is not new (Staroszczyk and
122 Gagliardini, 1999; Gillet-Chaulet and others, 2006; Ma and others, 2010; Lilien and others, 2021, 2023) and is
123 capable of (i) reproducing the viscous anisotropy of Dye 3 ice core samples (Rathmann and Lilien (2022); revisited
124 in Supplementary B), (ii) modeling the fabric profile of the EPICA Dome C ice core (Durand and others, 2007), and
125 (iii) explaining the formation of Raymond bumps with double peaks (Martín and others, 2009).

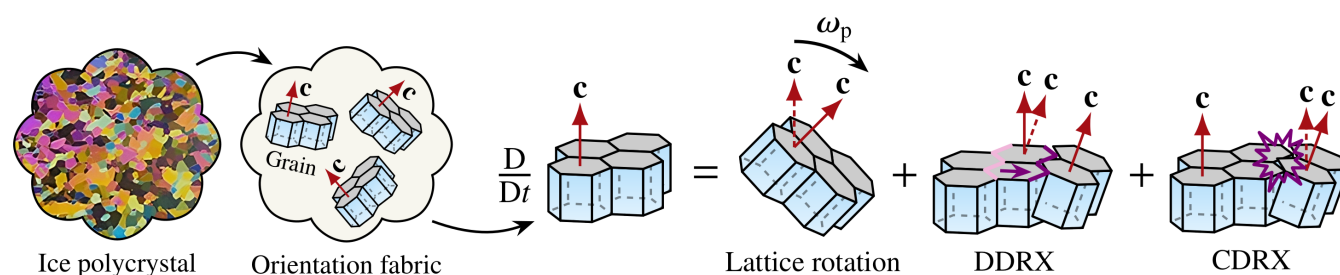


Fig. 3. Ice crystal processes affecting orientation fabric development: strain-induced rotation of crystal lattices (lattice rotation) and mass transfer between grains with different orientations (recrystallization; DDRX and CDRX).

126 Fabric evolution

127 The orientation fabric of ice evolves as a function of several crystallographic processes, such as lattice
 128 rotation, continuous dynamic recrystallization (CDRX; or rotation recrystallization), and discontinuous dynamic
 129 recrystallization (DDRX), depending on the thermomechanical setting (Figure 3). For brevity, we focus on
 130 introducing the models of crystal processes used here, referring the reader to e.g. Montagnat and others (2014)
 131 or Faria and others (2014a,b) for an introduction to the physics and observations of crystal processes.

132 In our vertically integrated orthotropic rheology, the fabric field is to be understood as the depth-averaged fabric
 133 field (elaborated on below). We therefore argue that it is sufficient to model the dominant crystallographic process
 134 in a depth-averaged sense, which is approximately lattice rotation for cold ice but must include DDRX if warmer
 135 than $\sim -15^\circ\text{C}$ (De La Chapelle and others, 1998; Samyn and others, 2008; Qi and others, 2019).

136 CDRX accounts for the subdivision of grains along subgrain boundaries resulting from local strain
 137 incompatibilities and is generally understood to not change grain orientations much (subdominant to lattice rotation),
 138 although it may impact the reduction of stored strain energy (Montagnat and Duval, 2000). For this reason, and
 139 because some work (Lilien and others, 2023; Richards and others, 2023) suggests little or no need to include this
 140 process when trying to reproduce ice core fabrics, we neglect CDRX for simplification.

141 Lattice rotation

142 Following a popular approach first proposed by Castelnau and others (1996) and Svendsen and Hutter (1996), lattice
 143 rotation is modeled as an advection process on the surface unit sphere (S^2), which is supposed to capture the strain-
 144 induced rotation of crystal lattices (c axes). In this case the c -axis velocity field $\dot{\mathbf{c}}$, responsible for advection on S^2 ,
 145 depends on the bulk stretching $\dot{\boldsymbol{\epsilon}}$ and spin $\boldsymbol{\omega}$ tensors,

$$\dot{\mathbf{c}} = (\boldsymbol{\omega} + \boldsymbol{\omega}_p) \cdot \mathbf{c}, \quad (11)$$

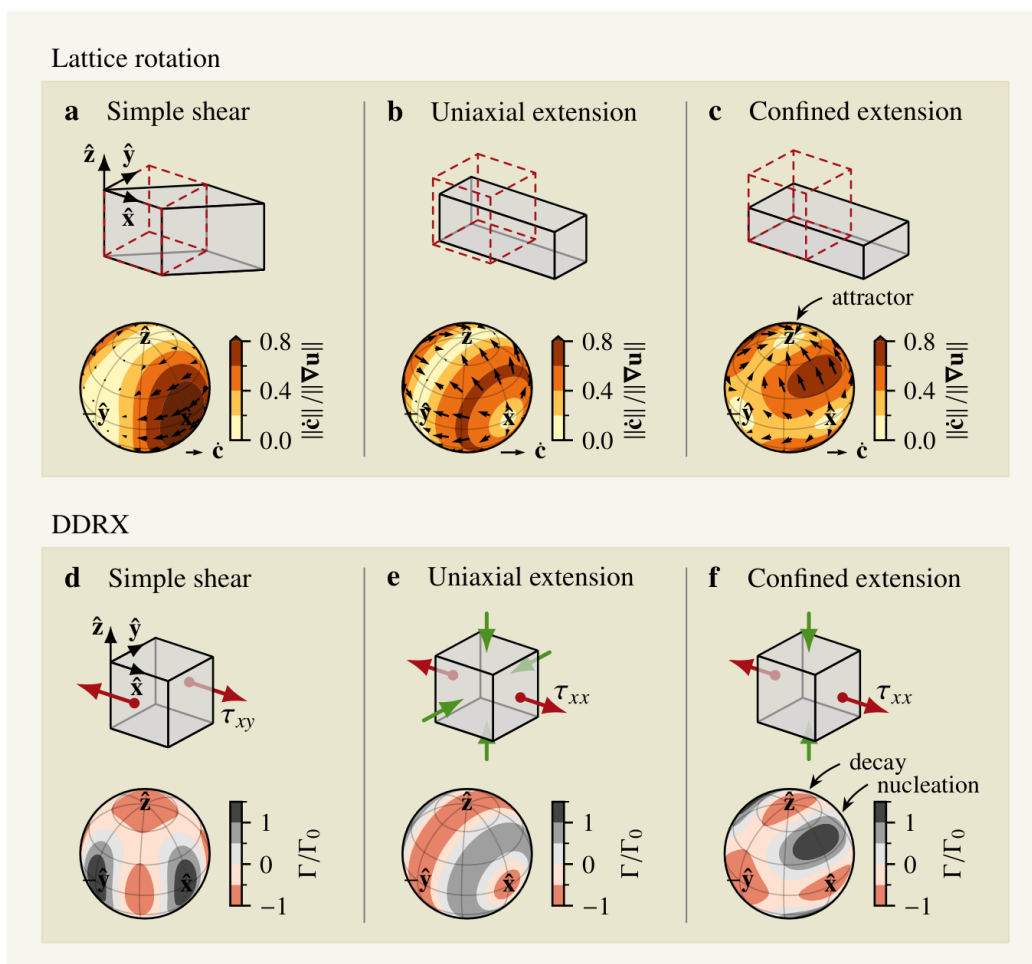


Fig. 4. Fabric dynamics for different deformation kinematics and stress states relevant to SSA flows: c -axis velocity field for lattice rotation (a – c), and DDRX decay–production rate for an initially-isotropic fabric (d – f).

146 where \mathbf{c} is an arbitrary c -axis, $\omega_p = \iota(\mathbf{c}^2 \cdot \dot{\epsilon} - \dot{\epsilon} \cdot \mathbf{c}^2)$ is the plastic spin, and \mathbf{c}^k is the k th repeated outer product of
 147 \mathbf{c} with itself. We take $\iota = 1$ to ensure that basal slip systems behave like a deck of cards—that is, slip planes tend
 148 towards aligning with the bulk shear plane—although ι could take another value to mimic non-basal slip systems
 149 activity (Richards and others, 2021; Gillet-Chaulet and others, 2006).

150 Figure 4a–c shows the predicted c -axis velocity field (arrows) and speed (colored contours) for ice subject to three
 151 different deformation kinematics (strain geometries) relevant in SSA flows.

152 *DDRX*

153 Following Placidi and others (2010), DDRX is modeled as a spontaneous mass decay–production process in
 154 orientation space, intended to represent the combined effect of nucleation and grain boundary migration. That is,
 155 mass is spontaneously exchanged between grains with different orientations depending on the local stress state,

156 strain rate, and temperature, in a statistical sense. The decay–production rate is defined as

$$\Gamma = \Gamma_0(D - \langle D \rangle), \quad (12)$$

157 where the prefactor Γ_0 accounts for the preferential (Arrhenius) activation at warm temperatures and the effect of
158 strain-rate magnitude, defined as (Richards and others, 2021; Lilien and others, 2023)

$$\Gamma_0 = \sqrt{\frac{\dot{\epsilon} : \dot{\epsilon}}{2}} A_\Gamma \exp\left(\frac{-Q_\Gamma}{RT}\right). \quad (13)$$

159 Here, R is the gas constant, T is the temperature, and $A_\Gamma = 1.91 \times 10^7$ and $Q_\Gamma = 3.36 \times 10^4 \text{ J mol}^{-1}$ according to
160 a recent calibration by Lilien and others (2023). The deformability D is the normalized square of the basal-plane
161 resolved shear stress

$$D = 5 \frac{(\boldsymbol{\tau} \cdot \boldsymbol{\tau}) : \langle \mathbf{c}^2 \rangle - \boldsymbol{\tau} : \langle \mathbf{c}^4 \rangle : \boldsymbol{\tau}}{\boldsymbol{\tau} : \boldsymbol{\tau}}, \quad (14)$$

162 where \mathbf{c} is an arbitrary c -axis and the factor of 5 is conventional to include. Because D is largest for grains with an
163 orientation favorable to basal glide, mass is spontaneously created/added to grains with such preferred orientations
164 (in a statistical sense). Conversely, mass spontaneously decays if $D < \langle D \rangle$, corresponding to grains with an
165 unfavorable orientation being consumed by grains with a more favorable orientation to basal glide. Here, $\langle D \rangle$ is
166 the grain-average deformability of the polycrystal, where the averaging operation $\langle \cdot \rangle$ is defined below.

167 Figure 4d–f shows the normalized decay–production rate Γ/Γ_0 of an initially-isotropic fabric when subject to
168 three different stress states relevant to SSA flows, i.e. mass is transferred from grains with orientations in red-shaded
169 regions to gray-shaded regions.

170 Representation

171 The crystal orientation fabric is represented by the grain mass-density distribution function in orientation space, ψ ,
172 following the theory of mixtures of continuous diversity (Faria, 2001) (also referred to as ρ^* in the literature, but
173 here $*$ is reserved for complex conjugation). We expand ψ in terms of a spherical harmonic series following recent
174 work (Richards and others, 2021; Rathmann and others, 2021)

$$\psi(\mathbf{x}, t, \theta, \phi) = \sum_{l=0}^L \sum_{m=-l}^l \psi_l^m(\mathbf{x}, t) Y_l^m(\theta, \phi), \quad (15)$$

175 where ψ_l^m are complex-valued expansion coefficients, Y_l^m are harmonic basis functions, and L is the wave mode
176 truncation above which finer-scale structure in ψ is unresolved. Since ψ is the distribution of mass density in
177 orientation space, integrating over orientation space gives the usual mass density of glacier ice $\rho = \int_{S^2} \psi \, d\Omega$, where

178 $d\Omega = \sin(\theta) d\theta d\phi$ is the infinitesimal solid angle. Note that $\psi_l^{-m} = (-1)^m (\psi_l^m)^*$ by identity since ψ is real, and that
 179 the mass orientation distribution function (MODF) is defined as the normalized distribution function ψ/ρ .

180 The combined effect of advection, lattice rotation, and DDRX on ψ is (see e.g. Svendsen and Hutter, 1996;
 181 Richards and others, 2021)

$$\frac{D\psi}{Dt} = -\nabla_{S^2} \cdot (\psi \dot{\mathbf{c}}) + \Gamma\psi, \quad (16)$$

182 where ∇_{S^2} is the gradient on S^2 and D/Dt is the material derivative. The harmonic expansion of ψ transforms
 183 the fabric model (16) into a high-dimensional matrix problem (Rathmann and others, 2021; Rathmann and Lilien,
 184 2021),

$$\frac{D\mathbf{s}}{Dt} = (\mathbf{M}_{\text{LROT}} + \mathbf{M}_{\text{DDR}}) \cdot \mathbf{s}, \quad (17)$$

185 where \mathbf{M}_{LROT} and \mathbf{M}_{DDR} are matrices of harmonic interaction coefficients, and

$$\mathbf{s} = [\psi_0^0, \psi_2^0, \psi_2^1, \psi_2^2, \psi_4^0, \dots, \psi_4^4, \dots, \psi_L^0, \dots, \psi_L^L] \in \mathbb{C}^{(L+2)^2/4} \quad (18)$$

186 is the unknown *fabric state vector field* to be solved for. That is, the harmonic expansion transforms the problem of
 187 fabric evolution in $\mathbb{R}^3 \times S^2$ to a high-dimensional advection–reaction vector field problem in $\mathbb{R}^3 \times \mathbb{C}^{(L+2)^2/4}$.

188 *Truncation error*

189 The spectral formulation suffers from a closure problem in the sense that to represent fabric anisotropy of increasing
 190 strength (increasing alignment of grains), harmonic modes of increasing degree l must be included. For practical
 191 reasons, the expansion series is truncated at degree $L = 10$ so that the finer-scale structure is ignored. To avoid
 192 backscatter effects in spectral space at $l = L$ (causing quasi periodic noise to dominate ψ), a spectrally-sharpened
 193 Laplacian term in orientation space is applied that disproportionately causes high wave-number modes to decay (for
 194 details see Rathmann and Lilien, 2021).

195 *SSA fabric evolution*

196 The vertically-averaged model of fabric evolution, consistent with the SSA approximation, is derived in
 197 Supplementary C. Denoting the depth average of $\mathbf{s}(x, y, z, t)$ by $\bar{\mathbf{s}}(x, y, t)$, and implicitly assuming that the velocity
 198 field and all gradients refer to their horizontal x – y parts, $\bar{\mathbf{s}}$ is governed by (Figure 5)

$$\frac{D\bar{\mathbf{s}}}{Dt} = (\mathbf{M}_{\text{LROT}} + \mathbf{M}_{\text{DDR}}) \cdot \bar{\mathbf{s}} + \frac{a_{\text{sfc}}}{H} (\mathbf{s}_{\text{sfc}} - \bar{\mathbf{s}}) + \frac{a_{\text{sub}}}{H} (\mathbf{s}_{\text{sub}} - \bar{\mathbf{s}}) \quad (19)$$

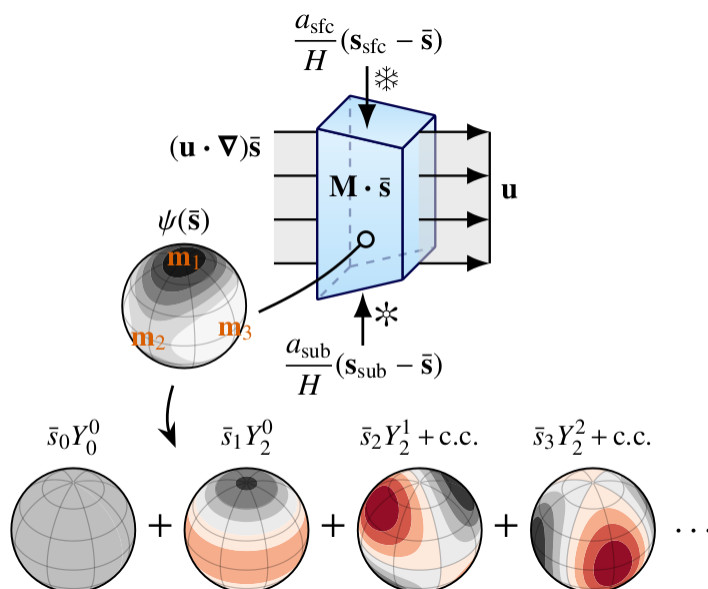


Fig. 5. Fabric harmonic expansion series and contributions to SSA fabric evolution from advection, englacial crystal processes, and surface/subglacial accumulation of ice.

199 where S is the surface height, B is the bottom of the ice mass, and $H = S - B$ is the ice thickness. Compared to the
 200 above three-dimensional problem, the vertically averaged problem (19) contains additional terms on the right-hand
 201 side. The first term is simply the depth-averaged effect of englacial crystal processes such as lattice rotation and
 202 DDRX. The second and third terms are state-space attractors, causing $\bar{\mathbf{s}}$ to tend towards the characteristic fabric
 203 states of ice that accumulates on the surface \mathbf{s}_{sfc} or subglacially \mathbf{s}_{sub} (likely isotropic), depending on the positively-
 204 defined accumulation rates a_{sfc} and a_{sub} .

205 Viscous anisotropy

206 Given the fabric state \mathbf{s} or its depth average $\bar{\mathbf{s}}$, we are left to provide the local rheological symmetry axes \mathbf{m}_i and
 207 associated enhancement factors E_{ij} , required by the bulk orthotropic rheology.

208 We follow Rathmann and Lilien (2021) and Lilien and others (2023) who calculated E_{ij} by substituting $\dot{\boldsymbol{\epsilon}}$ in (9)
 209 for the grain-averaged strain-rate tensor, subject to a linear combination of stress (Sachs) and strain-rate (Taylor)
 210 homogenization assumptions over the polycrystal scale:

$$E_{ij} = (1 - \alpha) \frac{\mathbf{m}_i \cdot \dot{\boldsymbol{\epsilon}}^{\text{Sachs}}(\hat{\boldsymbol{\tau}}) \cdot \mathbf{m}_j}{\mathbf{m}_i \cdot \dot{\boldsymbol{\epsilon}}_{\text{iso}}^{\text{Sachs}}(\hat{\boldsymbol{\tau}}) \cdot \mathbf{m}_j} + \alpha \frac{\mathbf{m}_i \cdot \dot{\boldsymbol{\epsilon}}^{\text{Taylor}}(\hat{\boldsymbol{\tau}}) \cdot \mathbf{m}_j}{\mathbf{m}_i \cdot \dot{\boldsymbol{\epsilon}}_{\text{iso}}^{\text{Taylor}}(\hat{\boldsymbol{\tau}}) \cdot \mathbf{m}_j}, \quad (20)$$

211 for $\alpha \in [0; 1]$. The Sachs and Taylor contributions are

$$\dot{\epsilon}^{\text{Sachs}} = \langle \dot{\epsilon}'(\boldsymbol{\tau}') \rangle, \quad (21)$$

$$\dot{\epsilon}^{\text{Taylor}} = \langle \boldsymbol{\tau}'(\dot{\epsilon}')^{-1} \rangle, \quad (22)$$

212 where $\boldsymbol{\tau}'$ and $\dot{\epsilon}'$ are the microscopic (grain scale) stress and strain-rate tensors, and $\langle \cdot \rangle^{-1}$ inverts the tensorial
213 relationship. The fabric averaging operator is defined as

$$\langle \cdot \rangle = \frac{1}{\rho} \int_{S^2} (\cdot) \psi \, d\Omega. \quad (23)$$

214 In effect, grains are modeled as interactionless, which reduces the homogenizations (21)–(22) to that of calculating
215 the ensemble-averaged monocrystal rheology (Figure 2).

216 Here, monocrystals are approximated as linear-viscous transversely isotropic following Rathmann and Lilien
217 (2021):

$$\dot{\epsilon}'(\boldsymbol{\tau}') = A' \left(\boldsymbol{\tau}' - \frac{E'_{cc} - 1}{2} (\boldsymbol{\tau}' : \mathbf{c}^2) \mathbf{I} + \frac{3(E'_{cc} - 1) - 4(E'_{ca} - 1)}{2} \boldsymbol{\tau}' : \langle \mathbf{c}^4 \rangle + (E'_{ca} - 1) (\boldsymbol{\tau}' \cdot \mathbf{c}^2 + \mathbf{c}^2 \cdot \boldsymbol{\tau}') \right), \quad (24)$$

218 where A' is the isotropic part of the fluidity, $E'_{ca}A$ is the fluidity specific for basal plane shear, and $E'_{cc}A$ is the fluidity
219 specific for compression/tension along \mathbf{c} (Figure 2). The inverse $\boldsymbol{\tau}'(\dot{\epsilon}')$ is simply (24) where $\dot{\epsilon}' \leftrightarrow \boldsymbol{\tau}'$ are swapped,
220 $E'_{ij} \rightarrow 1/E'_{ij}$, and $A' \rightarrow 1/A'$.

221 From (24) it is clear that $\dot{\epsilon}^{\text{Sachs}}$ and $\dot{\epsilon}^{\text{Taylor}}$ end up depending on the second- and fourth-order structure tensors,
222 $\langle \mathbf{c}^2 \rangle$ and $\langle \mathbf{c}^4 \rangle$. These depend, in turn, exclusively on the low-order harmonics ψ_2^m and ψ_4^m , respectively, implying that
223 choosing a small truncation L is sufficient as long as regularization does not affect harmonics of degree $l \leq 4$ too
224 much. This is the primary motivation for considering a linear viscous monocrystal rheology in spite of observations
225 that indicate nonlinear viscous behavior (Duval and others, 1983). In the nonlinear-viscous case, the Sachs and
226 Taylor averages depend on higher-order structure tensors (i.e. $l > 4$ harmonics) which is not computationally
227 feasible in our coupled flow–fabric simulations when also needing to dedicate spectral width for regularization,
228 in effect requiring $L \geq 10$ and therefore $\dim(\mathbf{s}) \geq 36$ (Rathmann and others, 2021).

229 *Eigenenhancements*

230 The rheological symmetry axes \mathbf{m}_i are taken to align with the fabric principal directions, defined as the eigenvectors
231 of $\langle \mathbf{c}^2 \rangle$ (Gillet-Chaulet and others, 2005). In the following, we therefore refer to the bulk enhancement factors in the
232 frame \mathbf{m}_i as *eigenenhancements*, denoted by subscripts $i, j = 1, 2, 3$, e.g. E_{11} , E_{22} , E_{12} , and so on. These are to be

233 distinguished from the *Cartesian enhancements* where \mathbf{m}_i are replaced by the Cartesian basis vectors in (9), denoted
 234 by subscripts $i, j = x, y, z$, e.g. E_{xx}, E_{yy}, E_{xy} , and so on, primarily useful for diagnostic purposes.

235 *Micromechanical model parameters*

236 The free parameters of our micromechanical model (monocrystal parameters A', E'_{cc}, E'_{ca} , and homogenization
 237 weight α) should be chosen such that modeled E_{ij} reproduce bulk deformation tests; they are not the values
 238 derived from deformation tests on single crystals. Put differently, grain interactions are not accounted for in our
 239 micromechanical model but can, to some extent, be corrected for by appropriately choosing "effective" monocrystal
 240 and homogenization parameters, different from those derived from deformation tests on single crystals.

241 Since A' cancels by virtue of the division in (9), only E'_{cc}, E'_{ca} , and α need to be specified. We set for simplicity
 242 $E'_{cc} = 1$ (rendering the compressional fluidity of monocrystals isotropic) and promote the preferential activation of
 243 basal glide by making that system comparatively soft: $E'_{ca} \gg 1$. Note that grains are not assumed to be undeformable
 244 when subject to compression along the c - or a -axes, nor is nonbasal plane shear prohibited. If that were the case
 245 (i.e. setting $E'_{cc} = 0$), modeled bulk ice would become undeformable for certain arrangements of stress and fabric,
 246 whereas in reality other strain accommodation mechanisms than dislocation creep would become relevant, such as
 247 dynamic recrystallization processes or grain boundary sliding.

248 Rathmann and Lilien (2021) found that previously reported shear and compressional enhancements of ice with
 249 strong single-maximum fabrics (Shoji and Langway, 1985; Pimienta and others, 1987) could be reproduced by
 250 setting $(E'_{ca}, \alpha) = (1000, 0.0125)$. That result depended, however, on approximating the experimental fabrics as
 251 unidirectional. In Supplementary B, we revisit this calibration, arguing that $(E'_{ca}, \alpha) = (1000, 0.455)$ might be a
 252 better practical choice (calibration used henceforth), since it permits significant enhancements to develop in both
 253 shear and compression for fabrics of intermediate strength, relevant for the large-scale problems considered here.

254 **EQUIVALENT ISOTROPIC ENHANCEMENT**

255 Following previous work (e.g. Placidi and others, 2010; Ma and others, 2010; Treverrow and others, 2015; Graham
 256 and others, 2018), we posit that the effect of fabric on ice viscosity can be approximated by an equivalent isotropic
 257 enhancement factor, understood in the usual sense as a scalar prefactor E to the flow rate factor A in Glen's rheology
 258 (3). If additional softening/hardening effects are present, the combined effect is given by the product of the respective
 259 enhancement factors. For example, damaged (fractured) ice is softer than undamaged, and dusty ice from glacial
 260 periods is typically two times softer than interglacial ice (Dahl-Jensen and Gundestrup, 1987) (although this effect

261 is to some extent indirectly caused by the dust impeding DDRX; Durand and others (2007)), implying

$$E = E_{\text{fabric}} E_{\text{damage}} E_{\text{dust}} \dots \quad (25)$$

262 In this work, the effect of fabric is considered in isolation, so $E = E_{\text{fabric}}$ is henceforth assumed implicit.

263 The hypothesis that viscous anisotropy can be represented by (reduced to) a scalar enhancement E implies that
 264 some tensorial viscosity components matter more than others. This is not unreasonable: if ice is (say) subject to
 265 x - y shear stress, setting $E = E_{xy}$ will probably give the most accurate strain-rate prediction, whereas the remaining
 266 directional enhancements matter less insofar as the fabric is favorably aligned to the shear stress, $\mathbf{m}_1, \mathbf{m}_2, \mathbf{m}_3 = \hat{\mathbf{x}}, \hat{\mathbf{y}}, \hat{\mathbf{z}}$
 267 (or some permutation thereof). Figure 6a makes this point more clear by showing $\dot{\epsilon}_{xy}$ and $\dot{\epsilon}_{xx}$ (black lines) of the
 268 orthotropic rheology (using the above homogenization scheme and $n = 3$), normalized by the effective isotropic
 269 strain rate

$$\dot{\epsilon}_{\text{iso}} = \sqrt{\frac{\dot{\epsilon} : \dot{\epsilon}}{2}}, \quad (26)$$

270 for a strong horizontal single-maximum fabric that is increasingly unfavorably aligned to (rotated away from) a fixed
 271 x - y shear stress. Note that both the stress magnitude and the rate factor A cancel out in the division. As anticipated,
 272 the orthotropic x - y strain rate (solid black line) is found to decrease from E_{12} when favorably aligned at $\vartheta = 0^\circ$
 273 (softer than predicted by Glen's law; solid gray line) to $\sim E_{11}$ when unfavorably aligned at $\vartheta = 45^\circ$ (harder than
 274 predicted by Glen's law). However, using a scalar enhancement E to account for fabric-induced softening/hardening
 275 is complicated by the fact that noncoaxial behavior is permitted by the orthotropic rheology, unlike Glen's isotropic
 276 rheology where $\boldsymbol{\tau}$ and $\dot{\boldsymbol{\epsilon}}$ are coaxial. In the present example of simple shear, coaxiality is fulfilled only when the fabric
 277 and stress states are favorably aligned ($\vartheta = 0^\circ$), in which case setting $E = E_{12}$ allows Glen's law to reproduce the
 278 orthotropic rheology and thus give the sought strain-rate tensor. But as the misalignment increases, other strain-rate
 279 components may become nonzero (e.g. ϵ_{yy} ; dashed black line) which a scalar enhancement of Glen's law cannot
 280 capture (dashed grey line). The degree to which a scalar enhancement E can accurately represent fabric-induced
 281 softening/hardening depends, therefore, partly on the alignment between the local fabric and the stress (or strain
 282 rate) geometry, henceforth referred to as *fabric compatibility*.

283 In addition to fabric compatibility, another bias may occur whenever $\boldsymbol{\tau}$ is a superposition of two or more stress
 284 states. Consider a horizontal single-maximum fabric, perfectly aligned with the x -axis. Such an ice fabric is soft
 285 for x - y shear but hard for compression/tension along x and y . Hence, it is not clear which enhancement-factor
 286 component E_{ij} to apply if shear and compression/tension stresses are superimposed. Figure 6b makes this point
 287 clear by showing $\dot{\epsilon}_{xy}$ and $\dot{\epsilon}_{xx}$ (black lines) of the orthotropic rheology, normalized by $\dot{\epsilon}_{\text{iso}}$, for a stress state that

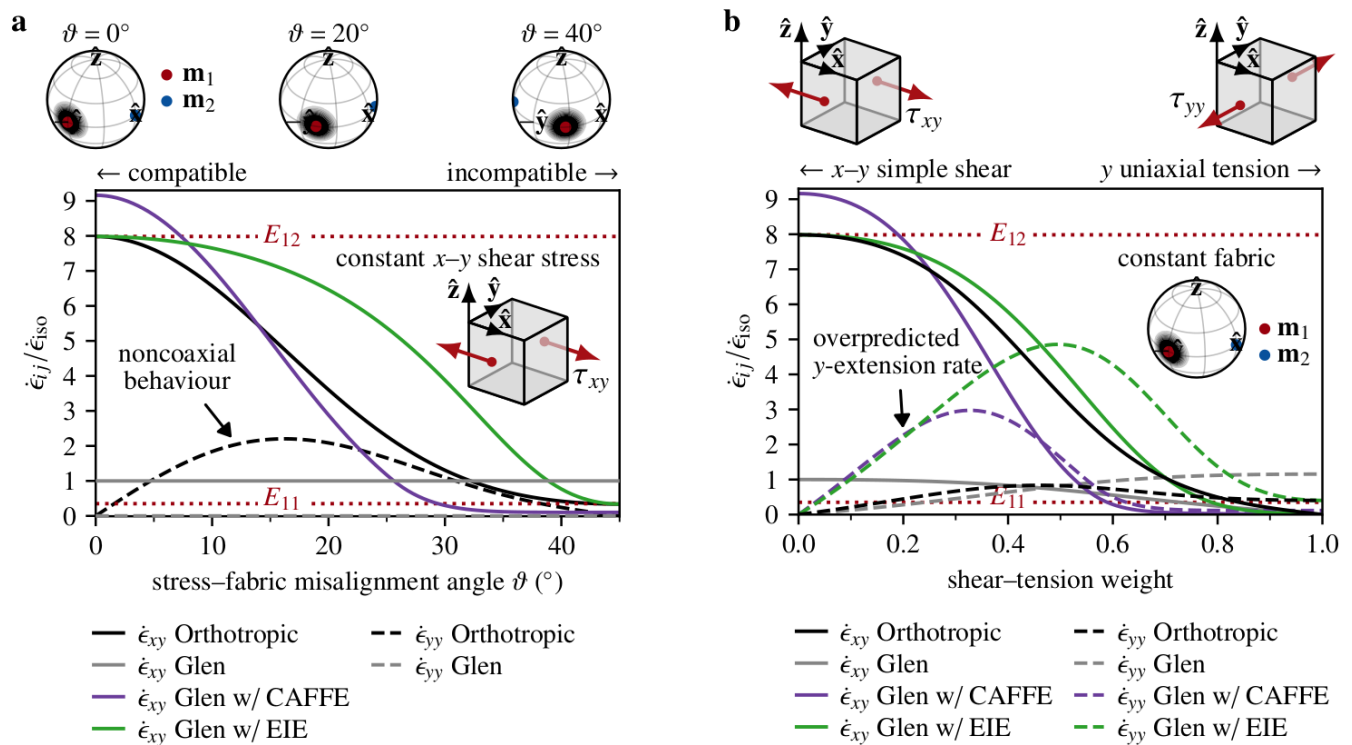


Fig. 6. Biases resulting from approximating the viscous anisotropy of ice using a scalar enhancement factor model. (a): Normalized strain-rate components of the orthotropic (black lines) and isotropic (grey and colored lines) rheologies when subject to a fixed x - y shear stress that is increasingly unfavorably aligned with a horizontal single-maximum fabric (decreasing compatibility). (b): Same as (a) but for a fixed horizontal single-maximum fabric aligned with the x axis, subject to a stress state that varies linearly between x - y shear and uniaxial tension along y (varying stress superposition). Colored lines show predictions for Glen's rheology when using either CAFFE (purple) or EIE (green) to calculate E .

288 varies linearly between x - y shear and uniaxial tension along y . Scaling all components of the strain rate in
 289 Glen's rheology (gray lines) by the same factor, E , to match the orthotropic rheology is not possible when both
 290 shear and tension stresses are simultaneously important. The degree to which E can accurately represent fabric-
 291 induced softening/hardening depends, therefore, also on the number and strength of stress (or strain rate) modes that
 292 contribute to τ (or $\dot{\epsilon}$), henceforth referred to as *stress* (or *strain-rate*) *superposition*.

293 CAFFE

294 Placidi and others (2010) proposed parameterizing an equivalent isotropic enhancement in terms of the average
 295 grain deformability $\langle D \rangle$. Isotropic fabrics are then characterized by $\langle D \rangle = 1$, while fabrics that are minimally and
 296 maximally favorable to basal glide are characterized by $\langle D \rangle = 0$ and $\langle D \rangle = 5/2$, respectively. CAFFE assigns
 297 the bulk enhancements E_c and E_s to these minimally and maximally favorable states, respectively, whereas for

298 intermediate states an empirically-tuned scaling is proposed:

$$E = \begin{cases} (1 - E_c) \langle D \rangle^{8/21(E_s-1)/(1-E_c)} & \text{for } 0 \leq \langle D \rangle \leq 1, \\ \frac{4 \langle D \rangle^2 (E_s - 1) + 25 - 4E_s}{21} & \text{for } 1 < \langle D \rangle \leq 5/2. \end{cases} \quad (27)$$

299 Here, we follow Placidi and others (2010) by setting $E_c = 0.1$ and $E_s = 10$, in agreement with bulk deformation tests
300 made on strong single-maximum fabrics subject to compression or shear that is aligned with the preferred c -axis
301 direction, respectively. Because CAFFE assumes that Glen's isotropic rheology is a suitable large-scale rheology, τ
302 can be exchanged for $\dot{\epsilon}$ in the deformability D .

303 **ESTAR**

304 ESTAR (Graham and others, 2018; McCormack and others, 2022) builds on deformation experiments made by
305 Budd and others (2013) showing that ice deformed in confined compression results in different tertiary creep rates
306 compared to simple shear, even though the corresponding stress invariants are equal. Focusing on this steady-state
307 regime where the only form of fabric anisotropy of concern is that which develops in conjunction with the tertiary
308 deformation (termed compatible anisotropy), Graham and others (2018) proposed parameterizing E as a function of
309 the shear fraction $\gamma = \dot{\epsilon}_s / \dot{\epsilon}_{iso}$ so that

$$E = E_c + (E_s - E_c)\gamma^2, \quad (28)$$

310 where $\dot{\epsilon}_s$ is the magnitude of the simple shear strain rate on the locally non-rotating shear plane (see Graham
311 and others (2018) for details). In this way, $\gamma = 1$ for simple shear and $\gamma = 0$ for uniaxial or confined
312 compression/extension, yielding $E = E_s$ and $E = E_c$, respectively. So far, there is no fixed set of recommended
313 values for E_c and E_s in ESTAR. Although there is experimental evidence for $E_c/E_s = 3/8$, the value of E_s can range
314 from ~ 3 to 12 depending on the application (Budd and others, 2013; Treverrow and others, 2012).

315 Since the tertiary creep experiments were made for warm ice at -2°C , this method is validated only for DDRX-
316 dominated fabrics. In effect, ESTAR assumes warm ice where recrystallization is instantaneous, generating fabrics
317 in perfect agreement with (compatible with) the local stress/strain-rate state so that advective effects are negligible,
318 which has the advantage of decoupling E from the need to track fabric evolution. Here, however, we wish to
319 allow for advection to also affect fabric evolution so that non-compatible fabrics may develop. Combined with the
320 uncertainty in which E_s to apply, we therefore do not include ESTAR in what follows, but mention it nonetheless
321 for completeness.

322 **Our definition (EIE)**

323 Formally, E is the strain rate response of a parcel of anisotropic ice, divided by that of isotropic ice, for a given stress
 324 state. This ratio is only meaningful for scalar quantities, so we conjecture that the effective strain rate $\dot{\epsilon}$ in (4) is a
 325 useful quantity to consider, which fulfills the effective Norton–Bailey creep law for both isotropic and orthotropic
 326 rheologies:

$$\dot{\epsilon} = A\tau^n, \quad (29)$$

327 where τ is the effective deviatoric stress. The motivation for considering $\dot{\epsilon}$ is straight forward: it is a natural
 328 measure (contraction) of the strain-rate tensor that weighs each component according to E_{ij} . Further, $\dot{\epsilon}$ satisfies the
 329 requirement that if deformation is (say) simple shear aligned with \mathbf{m}_2 and \mathbf{m}_3 so that $\dot{\epsilon} \propto \mathbf{P}_4$, then $\dot{\epsilon}$ is dominated by
 330 the term involving the corresponding shear enhancement E_{23} since $\mathbf{P}_4 : \dot{\epsilon}$ is the only nonzero strain-rate projection
 331 in (6).

332 The problem is, however, not as easy as defining $E = \dot{\epsilon}/\dot{\epsilon}_{\text{iso}}$, where $\dot{\epsilon}$ and $\dot{\epsilon}_{\text{iso}}$ are given by the contraction (4) with
 333 \mathbf{C} replaced by (6) and $\dot{\epsilon}$, respectively. In the aforementioned case of simple shear, it follows that

$$\frac{\dot{\epsilon}}{\dot{\epsilon}_{\text{iso}}} = \sqrt{\frac{\eta_4(\mathbf{P}_4 : \dot{\epsilon})^2}{\dot{\epsilon} : \dot{\epsilon}}} = E_{23}^{-1/(n+1)}. \quad (30)$$

334 Hence $\dot{\epsilon}/\dot{\epsilon}_{\text{iso}}$ should be raised to the power of $-n-1$ to give the desired result $E = E_{23}$. We therefore propose defining
 335 E according to the scaling relation (henceforth Equivalent Isotropic Enhancement, or *EIE*)

$$E = \left(\frac{\dot{\epsilon}}{\dot{\epsilon}_{\text{iso}}} \right)^q, \quad (31)$$

336 where $q = -n - 1$. The fact that q is negative can also be understood intuitively: if an observed flow field is (say)
 337 soft for shear due to fabric, the stress required to facilitate that deformation is less than that required for isotropic
 338 ice and therefore $\tau < \tau_{\text{iso}} \Rightarrow \dot{\epsilon} < \dot{\epsilon}_{\text{iso}}$ by virtue of (29).

339 In the general case where deformation is a superposition of different kinematic modes, or if fabric compatibility
 340 is poor, $\dot{\epsilon}$ will consist of multiple contributions and the appropriate exponent q might differ from $-n - 1$. However,
 341 in the following comparison between CAFFE and EIE, we find that $q = -n - 1$ is a good approximation for several
 342 deformation kinematics and is therefore taken to suffice.

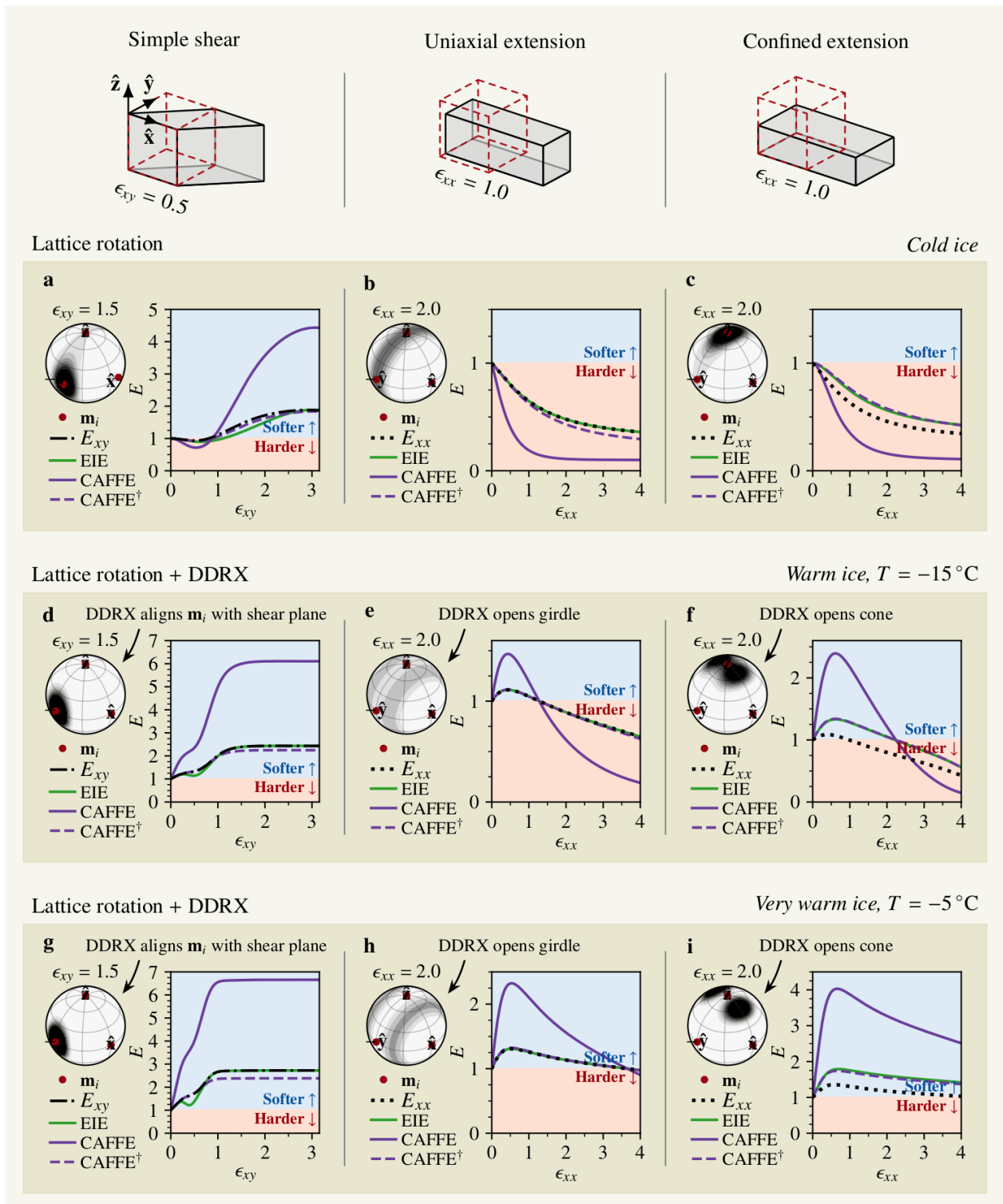


Fig. 7. Fabric-induced enhancement factors for different deformation kinematics relevant to SSA flows, depending on whether DDRX is negligible (cold ice limit; panels *a–c*), strong (warm ice limit; panels *d–f*) or very strong (very warm ice limit; panels *g–i*). In each panel, the equivalent enhancement E is shown for each method (colored lines) compared to the most relevant component of E_{ij} (black line). MODF insets show the modeled fabrics at selected strains for reference.

343 **Method comparison**

344 Figure 7 shows E predicted by CAFFE and EIE (colored lines) for a parcel of initially-isotropic ice subject to
 345 different deformation kinematics relevant to SSA flows, assuming that DDRX is either negligible (cold ice limit;
 346 Figure 7a–c), strong (warm ice limit; Figure 7d–f), or very strong (very warm ice limit; Figure 7g–i), imposed by
 347 setting $\Gamma_0 = 0$, $\Gamma_0 = \Gamma_0(-15^\circ\text{C})$, and $\Gamma_0 = \Gamma_0(-5^\circ\text{C})$, respectively. In general, EIE is found to approximately recover
 348 the most important component of E_{ij} (black line). CAFFE predicts similar behavior, but with more significant
 349 magnitudes. However, setting $E_c = 0.2$ and $E_s = 3.2$ enables CAFFE to approximately reproduce the behavior of
 350 EIE, henceforth referred to as CAFFE[†] (dashed purple line). Note that modeled rates of DDRX depend exponentially
 351 on temperature, so steady-state fabrics are quickly reached for very warm ice (fulfilling the compatibility assumption
 352 of ESTAR).

353 The discrepancy between EIE and CAFFE is partly due to spectral resolution (increasing the truncation L permits
 354 larger E for fabrics of intermediate strength; not shown) and partly due to using a linear grain rheology rather than
 355 nonlinear (Rathmann and others, 2021). Insofar as CAFFE is able to correctly estimate the hardening/softening
 356 behavior for a given fabric and stress/strain-rate state, adopting CAFFE over EIE or ESTAR is probably to be
 357 preferred since it allows for *both* an evolving fabric and is able to predict strong enhancements not limited by
 358 grain-rheological assumptions.

359 Regarding the biases mentioned above, caused by fabric incompatibility and strain-rate superposition, none of
 360 these are relevant in Figure 7 except in the case of simple shear where the fabric and strain-rate principal frames are
 361 slightly misaligned (Figure 7a). To quantify how these biases affect CAFFE and EIE, Figures 6a,b therefore also
 362 show the strain rate components predicted by Glen's law using either method (purple and green lines, respectively).
 363 Overall, both CAFFE and EIE demonstrate a reasonable ability to capture the shear enhancement (solid lines
 364 approximately agree in Figure 6), but significantly overestimate longitudinal strain rates when the stress state is
 365 a superposition of shear and tension (dashed purple and green lines disagree with the dashed black line in Figure
 366 6b).

367 **Accuracy of isotropic viscosity**

368 Although the simple comparison above provides some confidence in the ability of CAFFE and EIE to parameterize
 369 the most important component of viscous anisotropy as a scalar enhancement E , the error made by neglecting
 370 the tensorial viscosity structure in more realistic flow problems remains to be understood. Before proceeding to
 371 calculate E over Antarctic ice shelves, we therefore estimate the velocity error resulting from replacing E_{ij} with E
 372 in a simple ice shelf model, thus aiming to quantify (albeit not comprehensively) potential flow biases introduced

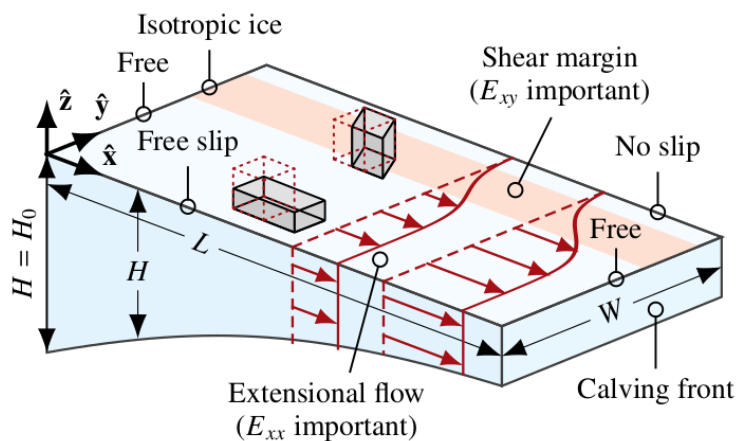


Fig. 8. Schematic of half-width ice shelf model.

373 by neglecting the tensorial viscosity structure. More precisely, we tested the ability of the isotropic SSA rheology,
 374 given an equivalent enhancement E calculated using CAFFE and EIE, to reproduce the steady-state velocities of an
 375 idealized ice-shelf model that builds on the orthotropic SSA rheology (full fabric–flow coupling).

376 The orthotropic model considers the transient evolution of a laterally-confined shelf of half width $W = 15$ km,
 377 length $L = 100$ km, and uniform initial thickness $H_0 = 500$ m, subject to no-slip conditions at its lateral boundaries
 378 (Figure 8). The ice thickness H is allowed to evolve according to the local mass divergence plus a Laplacian term
 379 for regularization but neglects accumulation and subshelf melting,

$$\frac{\partial H}{\partial t} = -\nabla \cdot (H\mathbf{u}) + \beta_H \nabla^2 H, \quad (32)$$

380 where \mathbf{u} is the velocity field. The thickness is taken to be constant on the inflow boundary, equal to the initial
 381 thickness H_0 . On the outflow boundary, calving is assumed instantaneous so that the shelf length is preserved, and
 382 is subject to the usual stress boundary condition according to the seawater pressure gradient (Huth and others, 2021)
 383 where the freeboard height is determined from the floatation criterion.

384 The crystal fabric is assumed to be isotropic at the inflow boundary but unconstrained elsewhere. The ice mass
 385 is taken to be isothermal with a temperature of -15 °C to make the effect of fabric on modeled viscosity fields
 386 unambiguous. Fabric evolution is assumed to be dominated by the depth-averaged effect of crystal processes; that is,
 387 dominated by the englacial fabric evolution owing to lattice rotation and DDRX. We therefore neglect contributions
 388 from surface and subglacial accumulation that add new ice with a different fabric signature, reducing the transient
 389 problem to

$$\frac{\partial \bar{\mathbf{s}}}{\partial t} + (\mathbf{u} \cdot \nabla) \bar{\mathbf{s}} = (\mathbf{M}_{\text{LROT}} + \mathbf{M}_{\text{DDR}}) \cdot \bar{\mathbf{s}} + \beta_s \nabla^2 \bar{\mathbf{s}}. \quad (33)$$

390 The additional real-space Laplacian term in (33) is included to provide numerical stability following Rathmann and
 391 Lilien (2021) and Lilien and others (2023) at the expense of slightly limiting how large spatial fabric gradients are
 392 permitted (more sophisticated upwinding techniques were not attempted). Here, a spectral resolution of $L = 10$ was
 393 chosen to be consistent with the above Lagrangian parcel modeling.

394 The problem was solved by using FEniCS (Logg and others, 2012), relying on Newton's method to solve the
 395 nonlinear momentum balance. The Jacobian of the residual form (required for Newton iterations) was calculated
 396 using the unified form language (UFL) (Alnæs and others, 2014), which is used by FEniCS to specify weak forms
 397 and supports automatic symbolic differentiation. For brevity, the reader is referred to Rathmann and Lilien (2021)
 398 for details on the weak form of the equations solved.

399 *Results*

400 The steady state of the orthotropic model is shown in Figures 9a–d and 10a–d for DDRX being negligible ($\Gamma_0 = 0$)
 401 or strong ($\Gamma_0 = \Gamma_0(-15^\circ\text{C})$), respectively, assuming a bulk flow exponent of $n = 3$ and using the micromechanical
 402 model introduced above. As expected, the shelf is found to thin and accelerate towards the calving front in both
 403 cases (panel a).

404 When DDRX is negligible (Figure 9), significant anisotropy develops in the shear margins (horizontal single-
 405 maximum fabrics) as measured by the pole figure index $J = \int_{S^2} |\psi|^2 d\Omega$ (Ismail and Mainprice, 1998) (Figure
 406 9b; a value of 1 represents isotropic ice, larger values represent increasing grain alignment), while girdle fabrics
 407 develop in the trunk that become particularly strong near the calving front. Modeled MODFs are shown as insets
 408 for selected locations, denoted by markers 1–6. When DDRX is strong (Figure 10), the horizontal anisotropy and
 409 induced softening that develops in the shear margins is more pronounced than if DDRX is negligible. In the trunk
 410 where flow is primarily extensional, a double maximum structure is found, making along-flow extension softer than
 411 if DDRX is negligible.

412 In both orthotropic models, simulated MODFs match the patterns anticipated from the idealized deformation
 413 experiments shown in Figure 7.

414 Figures 9c–d and 10c–d show the horizontal components of E_{ij} expected to be most important for the simulated
 415 flows (Figure 8). In the lattice rotation model without DDRX, both EIE and CAFFE[†] are found to approximately
 416 reproduce E_{xy} in the shear margin but E_{xx} in the trunk (Figure 9e,g), resulting in velocity errors that are generally
 417 below 10 % (Figure 9f,h; see Supplementary E for actual velocity maps). In the model with strong DDRX the same
 418 applies, except in the trunk where fabric-induced hardening is somewhat underestimated, and that CAFFE[†] predicts
 419 slightly too small E in the shear margin (compared to EIE) that explains why upstream flow speeds are too slow by

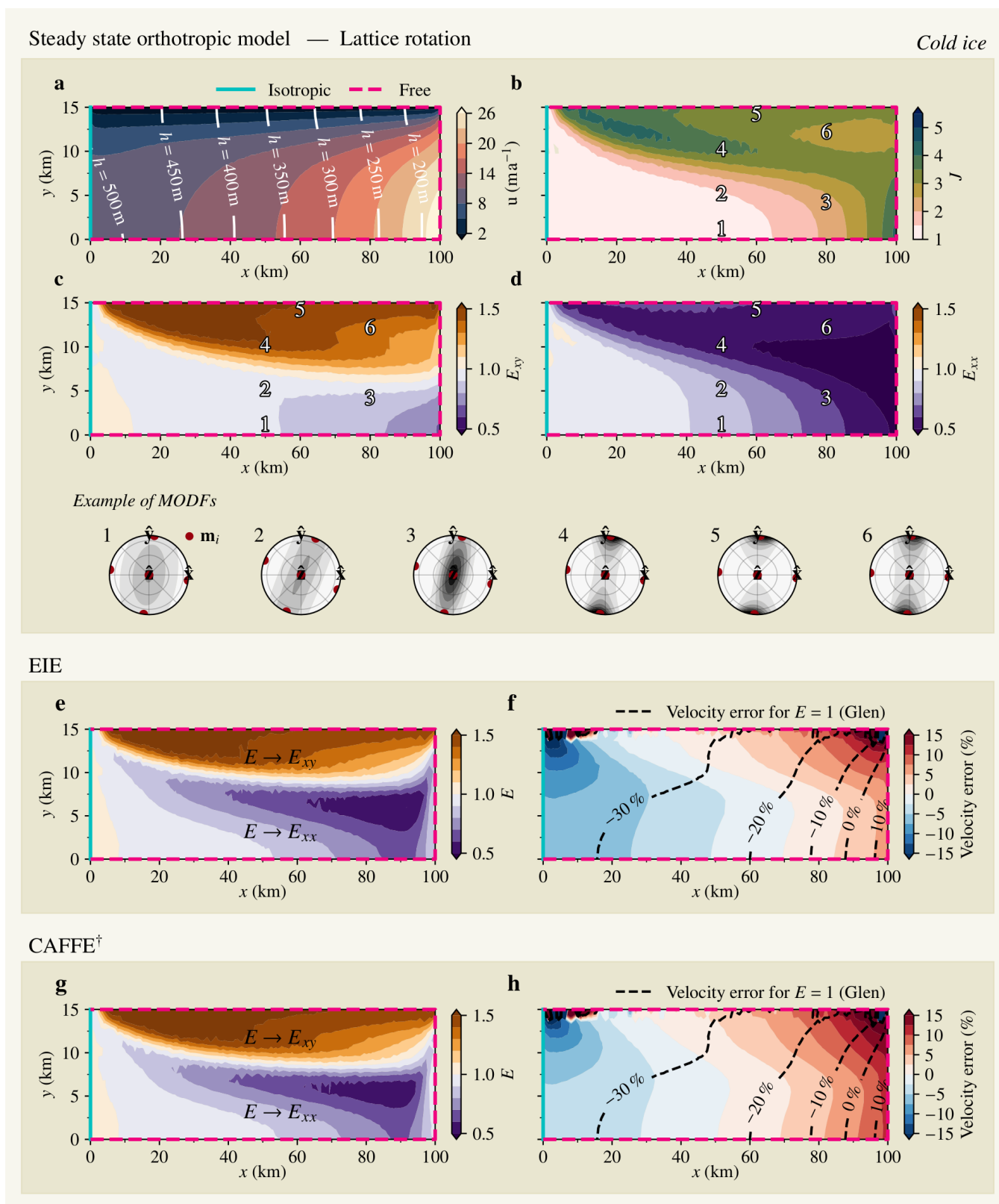


Fig. 9. Orthotropic model results in steady state when lattice rotation is the dominant crystal process. (a): Ice speed (colored contours) and thickness (white contours). (b): Strength of fabric anisotropy as measured by the pole figure J index. (c) and (d): Fabric-induced shear and longitudinal enhancement factors. (e) and (f): E predicted by EIE and corresponding velocity misfit, respectively. (g) and (h): Same as EIE panels but for the CAFFE[†] method. Isotropic and free fabric boundaries are shown as cyan and magenta lines, respectively. Examples of MODFs are shown at selected locations denoted by markers 1–6. Dashed contours in panel (f) and (h) show the velocity misfits resulting from entirely disregarding fabric-induced enhancements (naively applying Glen's law, $E = 1$, for the steady-state ice geometry).

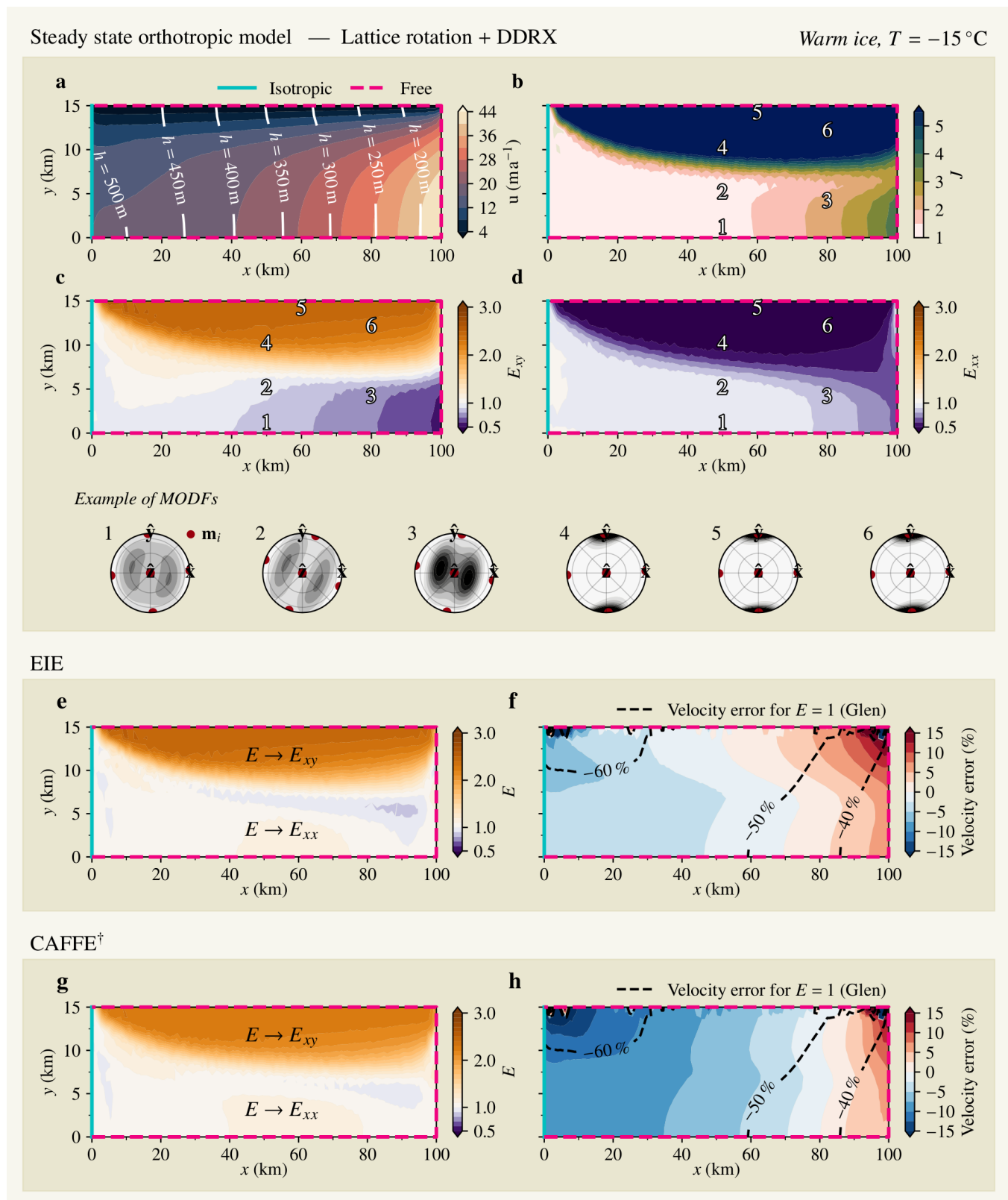


Fig. 10. Orthotropic model results in steady state when DDRX is the dominant crystal process. Caption same as in Figure 9.

420 more than 15 % (Figure 10f versus 10h). This bias is likely caused by CAFFE[†] underestimating E for DDRX fabrics

421 in simple shear (Figure 7d,g). Whether more optimal values of E_c and E_s exist, improving the CAFFE[†] misfit for
 422 DDRX fabrics, was not explored.

423 Note that we considered CAFFE[†], rather than CAFFE (no dagger), for these experiments, since the misfit analysis
 424 is meaningful only if E_c and E_s are chosen such that the enhancement magnitudes of the orthotropic SSA rheology
 425 are approximately reproduced (and hence overall flow speed). When applied to real ice shelves, the original CAFFE
 426 parameters are, however, most appropriate to use since they allow for the full range of observed fabric hardening
 427 and softening to be realized. Note also that if fabric-induced enhancements are not accounted for (i.e. setting $E = 1$),
 428 velocity errors as large as 30 % to 60 % are found (dashed contours in Figure 9f,h and 10f,h).

429 In conclusion, using Glen's isotropic rheology with either CAFFE or EIE is able to reproduce the behavior of the
 430 orthotropic rheology with acceptable velocity errors (at least in our idealized model), suggesting that either model
 431 of E is useful for understanding the potential effect of fabric anisotropy on real ice shelves. Although E is found to
 432 map to the components of E_{ij} largely following intuition built from the above Lagrangian parcel experiments, we
 433 warn that such intuition *might* fail if advection is important so that fabric incompatibility is significant or if recent
 434 ice-dynamical changes cause significant stress superposition (cf. the above discussion).

435 APPLICATION TO ANTARCTIC ICE SHELVES

436 We investigate the importance of accounting for fabric-induced viscous heterogeneities over ice shelves by using
 437 CAFFE to calculate the equivalent scalar enhancement E over the Ross and Pine Island Glacier (PIG) ice shelves,
 438 Antarctica. Both ice shelves and their upstream glaciers are assumed to exhibit plug flow such that the local strain-
 439 rate tensor can be determined from satellite-derived surface velocities (MEaSURES; Rignot and others (2017)). To
 440 close the SSA fabric problem (33), we further assume that all flows are in approximately steady state and therefore
 441 fabric too, $\partial \bar{s} / \partial t = 0$. Since it is unclear where DDRX is important (observations of fabric and temperature are few
 442 and sparse), we calculate the steady-state fabric field assuming that DDRX is either negligible or strong to explore
 443 the range of possible predictions for E , which are supposed to represent the limits of cold and warm ice, respectively.
 444 Uncertainties and caveats introduced by the above assumptions are addressed in the discussion.

445 If lattice rotation is the dominant crystal process (no DDRX), fabric evolution (33) reduces to a boundary value
 446 problem w.r.t. \bar{s} that can be solved given surface velocities alone (i.e. no velocity field modeling is required)

$$(\mathbf{u} \cdot \nabla) \bar{s} = \mathbf{M}_{\text{LROT}} \cdot \bar{s} + \beta_s \nabla^2 \bar{s}. \quad (34)$$

447 Disregarding regularization, the fabric field \bar{s} that solves (34) is nothing but a balance between advective effects and
 448 lattice rotation. If velocity gradients are small, then fabric is advected along flow lines (long memory timescale),

449 whereas if velocity gradients are large, then upstream fabrics matter less compared to the local strain-induced
450 rotation of c -axes (short memory timescale).

451 If DDRX is non-negligible, then $\mathbf{M}_{\text{LROT}} \rightarrow \mathbf{M}_{\text{LROT}} + \mathbf{M}_{\text{DDRX}}$ in (34) and fabric evolution depends on τ and
452 T in addition to $\dot{\epsilon}$. To close the DDRX problem, we approximate τ as coaxial to $\dot{\epsilon}$ and assume isothermal ice
453 at $T = -15^\circ\text{C}$ over both Ross and PIG. Coaxiality is not guaranteed unless fabric is favorably aligned with the
454 local strain rate geometry (i.e., advective effects are small and no recent ice-dynamical changes have occurred; cf.
455 above discussion). Temperatures as high as -15°C are probably unlikely over most parts of the Ross and PIG,
456 especially in upstream regions where the ice is not in contact with the warm ocean. But we are primarily interested
457 in the *potential* effect of DDRX, which at -15°C is strong enough that developed fabrics can differ substantially
458 from those generated by lattice rotation alone (Figure 7). If temperatures were better known over Ross or PIG, the
459 importance of DDRX in controlling fabric fields (and thus E) could be determined more precisely. Without this
460 information, the best we can do is to provide end-member solutions where the ice is assumed to be very cold or very
461 warm so that DDRX is negligible or strong, respectively.

462 The steady-state Ross and PIG fabric problems were solved numerically using FEniCS, and the method was
463 validated by reproducing the steady-state fabrics of the idealized shelf model above (see Supplementary D). For
464 both Ross and PIG, we considered a rectangular bounding model geometry and assumed isotropic ice on upstream
465 inflow boundaries but unconstrained on outflow boundaries. Because lattice rotation and DDRX are modeled to be
466 more important than advection over grounded ice, assuming isotropic ice on inflow boundaries affects the solution
467 only in the neighborhood near the inflow boundaries. That is, our method and results are robust against uncertainties
468 in fabric boundary conditions if the model boundaries are set to be sufficiently far from the region of interest (see
469 Supplementary F).

470 Results

471 Figures 11 and 12 show our model results for Ross and PIG, respectively, including surface speeds in panel *a* and
472 the corresponding strain rate magnitude $\dot{\epsilon}_{\text{iso}}$ in panel *b*.

473 The strength of fabric horizontal anisotropy is shown in panels *d* and *f* for the model with and without
474 DDRX, respectively, defined as the horizontal eigenvalue difference $\Delta\lambda$ of $\langle \mathbf{c}^2 \rangle$, a measure frequently reported
475 in radioglaciological field studies (e.g. Gerber and others, 2023; Zeising and others, 2023). In the model of Ross and
476 PIG that neglects DDRX (lattice rotation only), horizontal anisotropy is found to be well developed throughout, and
477 horizontal single-maximum fabrics that are (sub)perpendicular to the shear plane are prevalent in shear zones. In
478 contrast, girdle-like fabrics are modeled in regions of longitudinal or trunk flow (see MODF insets). In the DDRX-

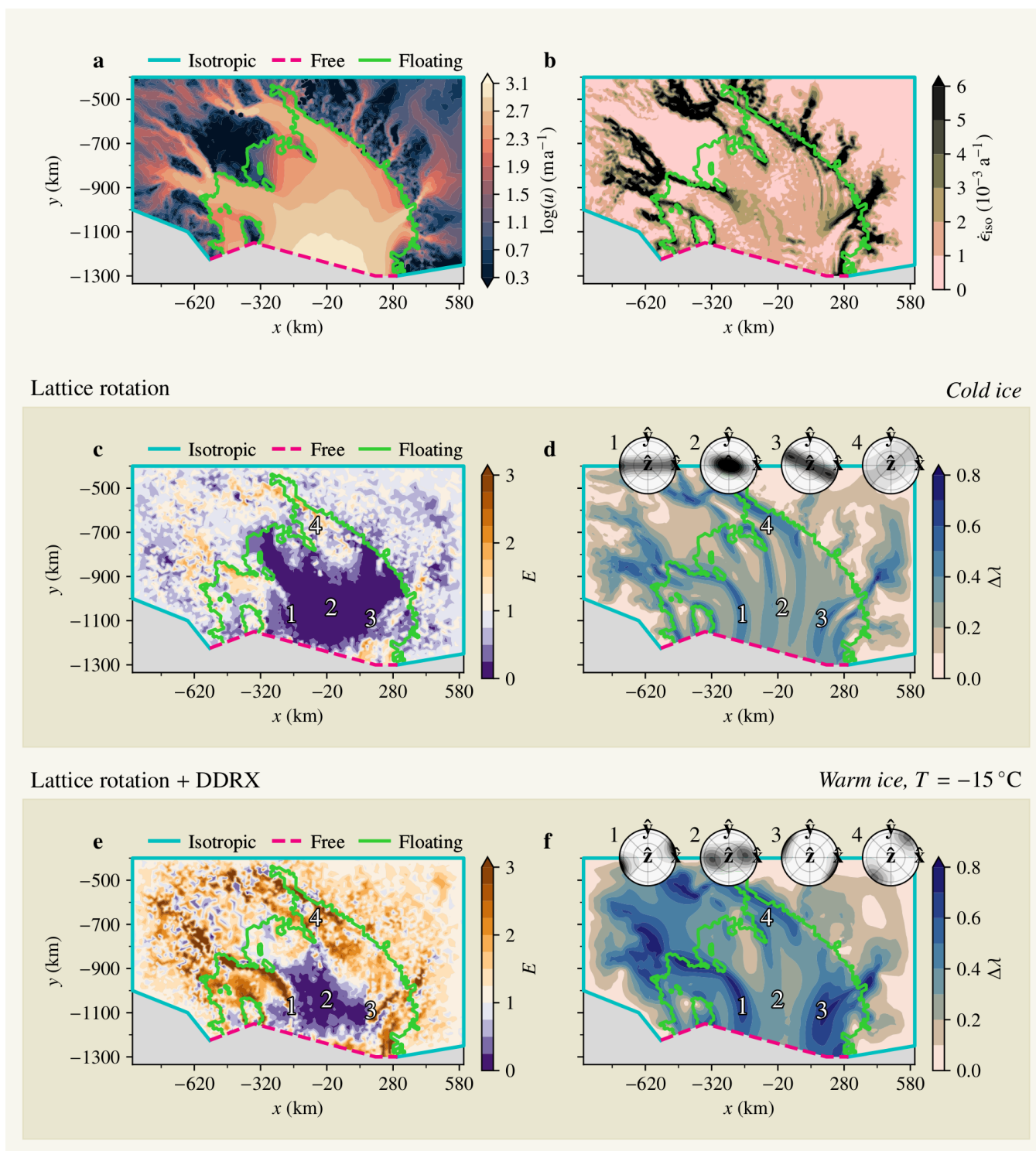


Fig. 11. SSA fabric model results for the Ross ice shelf. (a): Satellite-derived surface velocities. (b): Effective strain rate. (c): E estimated using CAFFE assuming lattice rotation is the dominant crystal process (cold ice limit). (d): Fabric horizontal eigenvalue difference. (e–f): Same as (c–d) but assuming DDRX is strong (warm ice limit). Isotropic and free model boundaries are shown as cyan and magenta lines, respectively, and floating ice is delineated by green contours. Modeled MODFs are shown at selected locations, denoted by markers 1–4.

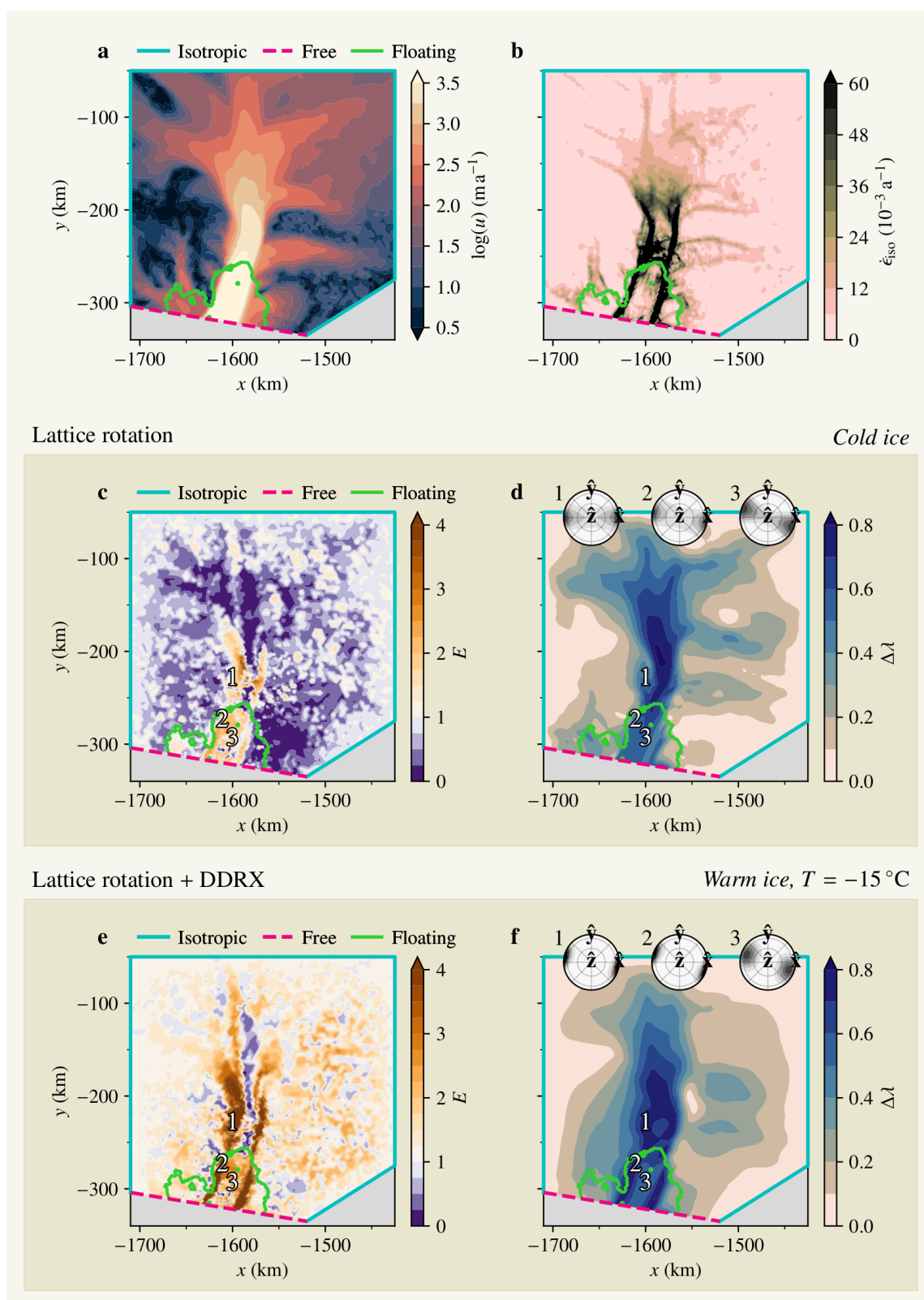


Fig. 12. PIG model results. Caption same as in Figure 11.

479 activated model of Ross and PIG, horizontal anisotropy is also well developed, especially in shear margins where
 480 $\Delta\lambda$ is much larger compared to the model that neglects DDRX.

481 The equivalent enhancement E using CAFFE is shown in panels c and e . In the case of the Ross ice shelf, we find
482 that lattice rotation alone can give rise to widespread fabric-hardening of the shelf ($E < 1$), but if DDRX is strong
483 then zones of softening are also present ($E > 1$), especially near the grounding line and in shear margins. For PIG,
484 both models with and without DDRX suggest that the shelf and its near-upstream region are softened due to fabric,
485 particularly the shear margins, while hardening is prevalent over some grounded parts of PIG if DDRX is negligible.

486 DISCUSSION

487 Ross and PIG results

488 The fact that fabric development results in hard ice over most of Ross when lattice rotation is dominant, but that
489 significant softening can occur when DDRX is strong, leaves us with little ability to conclude how fabric might affect
490 the shelf viscosity without knowing more about the relative importance of the two processes. In contrast, fabric
491 development over PIG seems to generally soften the shelf and upstream shear margins regardless of the strength of
492 DDRX. PIG is a dynamically active part of West Antarctica, which has contributed ~ 1.5 mm to global sea level
493 between 1995 and 2017 (Shepherd and others, 2019) and may undergo irreversible retreat should its grounding line
494 continue to migrate further backward (Favier and others, 2014). Accounting for the effect of fabric development over
495 PIG in large-scale flow models (particularly the effect of shear-margin weakening) might therefore be important for
496 accurately predicting the near-term mass loss from Antarctica, as well as other key outlet systems in Antarctica and
497 Greenland.

498 To make further progress on understanding the effect of crystal fabrics on the viscosity structure of ice shelves,
499 we emphasize the need for more field observations of fabric and temperature to help inform and validate fabric
500 modeling. Useful locations would include transects on ice shelves where fabric gradients are expected to be large,
501 such as across shear margins, along flow lines with extensional flow, and near pinning points. Only with widespread
502 ice temperature measurements (allowing for the rate of DDRX to be accurately modeled) and widespread fabric
503 measurements (allowing modeled fabric fields to be validated) do we have confidence in relaxing the "cold" and
504 "warm" ice bounds considered here. Ultimately, this is needed for large-scale ice flow models to accurately account
505 for fabric-induced viscosity contrasts in prognostic simulations of future ice mass loss.

506 *Steady state assumption*

507 The Ross and PIG ice shelves have experienced large area changes of -1.3% and -16.6% , respectively, between
508 2009 and 2019 (Andreasen and others, 2023), casting doubt on whether crystal fabrics can indeed be predicted
509 assuming steady flow as is done here (assuming area changes are not caused by melting alone). Moreover, in the

510 grounded parts of the Western Ross, there is evidence of deceleration on Ice Stream B (Joughin and others, 2002),
 511 that Ice Stream C might have shut down ~ 150 to 170 years ago (Retzlaff and Bentley, 1993; Catania and others,
 512 2006), and that Ice Stream D shut down ~ 450 years ago despite flowing rapidly today (Conway and others, 2002).
 513 Determining how these dynamical changes affect modeled fabric fields, compared to our steady-state results, is a
 514 major challenge that only forward ice flow modeling can answer (outside the scope of our work). We emphasize,
 515 however, that our aim is *not* to provide accurate present-day maps of E over Ross and PIG, directly useful for
 516 large-scale ice flow modeling. Rather, we wish to highlight and quantify the potential effect that developed fabrics
 517 can have on controlling ice viscosity in regions of floating ice, which may constitute a large rheological uncertainty
 518 when attempting to estimate future ice-mass loss.

519 *Fabric compatibility and strain rate superposition*

520 We gauge the extent to which fabric incompatibility and strain-rate superposition could make our estimates of E less
 521 applicable to the Ross and PIG systems by calculating the shear fraction γ and a new measure of fabric compatibility.

522 The shear fraction quantifies how much simple shear deformation contributes to $\dot{\epsilon}$, where $\gamma = 0$ and $\gamma = 1$ imply
 523 no or an exclusively simple shear contribution, respectively. Hence for intermediate values, $\dot{\epsilon}$ is a superposition of
 524 different deformation kinematics (simple and pure shear), and less confidence may be placed in the ability of a scalar
 525 enhancement factor to capture the full effect of fabric on viscosity.

526 For fabric compatibility, we construct a normalized measure χ , defined so that $\chi = 1$ represents a maximally
 527 compatible fabric (favorably aligned with the strain-rate geometry) and $\chi = 0$ represents a minimally compatible
 528 fabric:

$$\chi = \sqrt{(1 - \gamma)G_p^2 + \gamma G_s^2}, \quad (35)$$

529 where

$$G_p = 1 - \frac{2}{\|\dot{\epsilon}\| \|\langle \mathbf{c}^2 \rangle\|} \|\dot{\epsilon} \cdot \langle \mathbf{c}^2 \rangle - \langle \mathbf{c}^2 \rangle \cdot \dot{\epsilon}\|, \quad (36)$$

$$G_s = 1 - \frac{1}{\sin(45^\circ) \|\mathbf{t}^2\| \|\langle \mathbf{c}^2 \rangle\|} \|\mathbf{t}^2 \cdot \langle \mathbf{c}^2 \rangle - \langle \mathbf{c}^2 \rangle \cdot \mathbf{t}^2\|. \quad (37)$$

530 Since the commutator $\mathbf{A} \cdot \mathbf{B} - \mathbf{B} \cdot \mathbf{A}$ vanishes for coaxial matrices \mathbf{A} and \mathbf{B} (shared eigenvectors), it is useful to
 531 assess how well the fabric, represented by $\langle \mathbf{c}^2 \rangle$, is aligned with deformation. In the case of longitudinal straining
 532 (pure shear), G_p measures the corresponding degree of fabric compatibility. The normalizing denominators in (36),
 533 including the offset and prefactor of 2, are chosen such that $G_p^2 = 1$ when comparability is maximal for a single-
 534 maximum fabric, whereas $G_p^2 = 0$ when minimal (single-maximum misaligned at 45°). For simple shear, the same

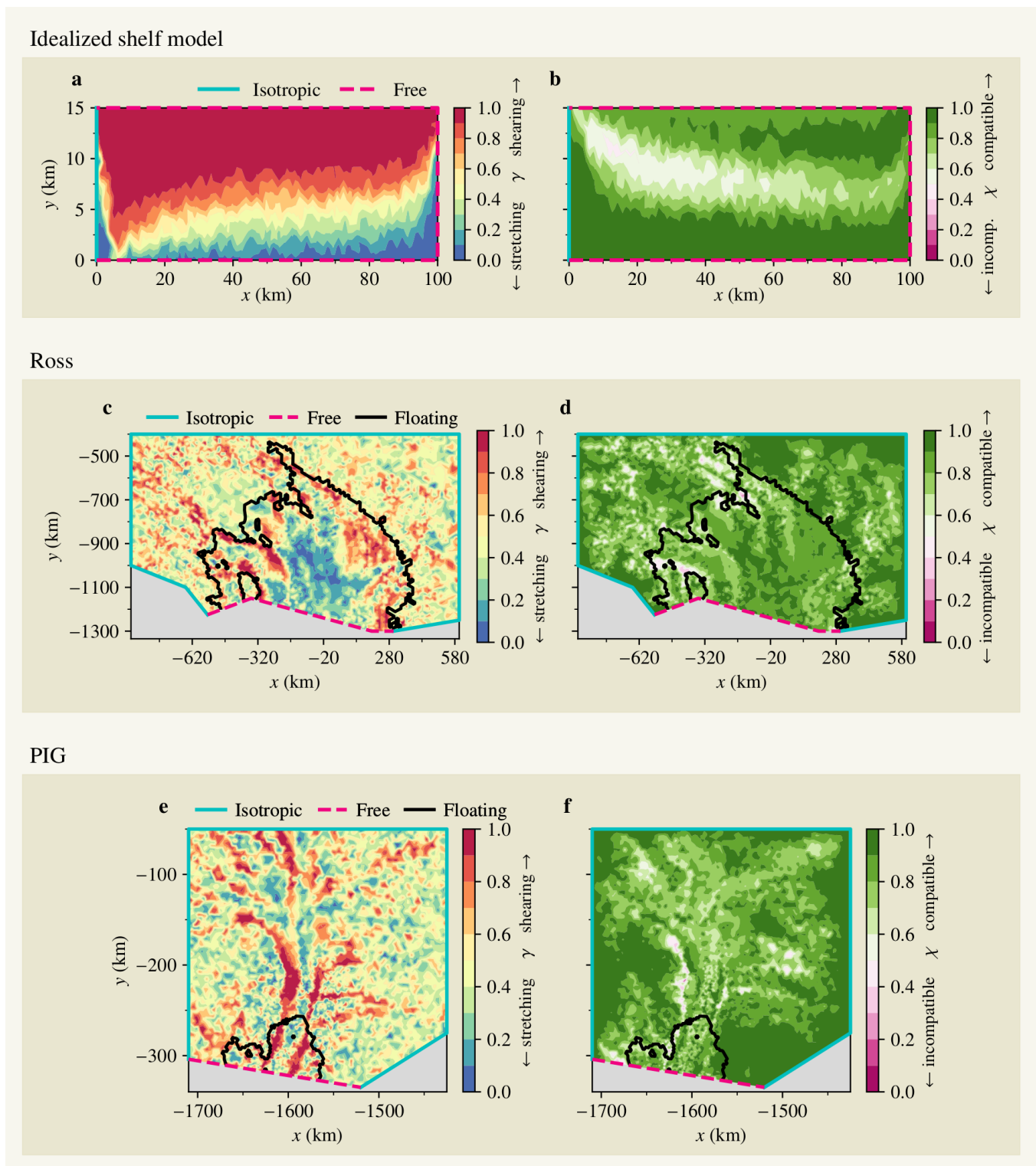


Fig. 13. Shear fraction (left-hand panels) and fabric compatibility (right-hand panels) for the idealized ice shelf model (a–b) and Antarctic ice shelves Ross (c–d) and PIG (e–f). Fabric compatibility is calculated assuming DDRX is negligible (results are similar for strong DDRX but not shown).

535 commutator is not useful. Instead, we replace $\dot{\epsilon}$ with the outer product of the velocity normal, \mathbf{t}^2 . In this case,
536 the offset and prefactor $1/\sin(45^\circ)$ are chosen such that $G_s^2 = 1$ when a single-maximum fabric is most favorably
537 aligned with the bulk shear-plane normal \mathbf{t} , whereas $G_s^2 = 0$ when shear is misaligned at 45° (least favorable). The
538 shear fraction γ in (35) weighs how much the two measures of compatibility are relevant, depending on the relative
539 contribution of simple versus pure shear to $\dot{\epsilon}$.

540 Although the end-member values $\gamma = 0, 1$ and $\chi = 0, 1$ have a clear meaning, it is not obvious what the
541 intermediate threshold values are that, once crossed, indicate that CAFFE or EIE provide a poor approximation
542 and should not be used. We therefore determine how applicable our calculated maps of E are to the Ross and PIG
543 systems by comparing γ and χ to the values calculated for the idealized shelf model (Figure 13a,b) where fabric
544 compatibility and strain rate superposition cause relatively small velocity errors when using CAFFE (Figures 9 and
545 10). For both Ross (Figure 13c,d) and PIG (Figure 13e,f), ice shelf flow is generally simple shear or longitudinal
546 ($\gamma \sim 1, 0$, respectively) like in the idealized shelf model, and fabric compatibility is no worse than in the idealized
547 model. We therefore argue that our maps of E over Ross and PIG are sufficiently unaffected by fabric incompatibility
548 and strain rate superposition to be useful for understanding the potential effect of fabric on ice viscosity.

549 *Ice damage*

550 As indicated in Figure 1, strongly damaged (fractured) ice is much softer than undamaged. In regions where
551 damage is prevalent, the main rheological uncertainty is possibly the ability to model ice damage and its effect
552 on ice viscosity. Between 2017 to 2020, three large calving events took place at PIG, and the resulting velocity
553 speedup (Joughin and others, 2021) has been suggested to be partly facilitated by the damage that evolved in the
554 ice-shelf shear margins (Sun and Gudmundsson, 2023). On the other hand, more recent work (Gerli and others,
555 2024) finds that remotely sensed damage maps over the PIG and Filchner–Ronne shelves are only modestly related
556 to patterns in the inferred flow rate factor A , suggesting that remotely detected damage fields are not of direct
557 relevance to present-day ice shelf flow. Either way, if the effect of fabric on ice viscosity is multiplicative as
558 assumed here (25), any damaged-induced softening should be further modified (multiplied) by the effect of fabric;
559 that is, the fact that ice is damaged does not cause fabric effects to become irrelevant. Indeed, recent modeling
560 has suggested that recrystallization (causing larger grain sizes in addition to developing the orientation fabric) can
561 increase the vulnerability to fracture of ice shelves by decreasing the tensile strength of shear margins by up to
562 $\sim 75\%$ (Ranganathan and others, 2021).

563 **Implications for large-scale modeling**

564 The agreement between velocities modeled using the orthotropic, EIE, and CAFFE[†] rheologies suggests that a
565 scalar, isotropic enhancement can sufficiently approximate the full orthotropic rheology *if the fabric field is known*.
566 Typical ice flow models, including those that solve vertically-integrated stress balance problems like the SSA,
567 already permit spatially varying fields of A , so incorporating the EIE or CAFFE methods into large-scale models is
568 trivial if the fabric is known. However, the sparsity of fabric measurements limits the use of fabric as a constraint
569 on ice flow models and validation of fabric development models that could be used as a stopgap. For example, some
570 models that rely on laboratory-calibrated rates of DDRX struggle to reproduce the fabric development observed in
571 ice cores (Lilien and others, 2023; Richards and others, 2023), suggesting care must be taken to ensure the rate of
572 DDRX is accurately modeled. Considering the variation in enhancement that can result from DDRX being weak or
573 strong (Figure 11), this uncertainty in fabric directly impacts the putative effect on ice flow. In certain situations, the
574 flow enhancement appears independent of the process dominating fabric development (Figure 12), implying that, in
575 isolated areas, there may be sufficient confidence in the effect of fabric on flow to include it in large-scale models.

576 Our results show that with better validation of fabric models, or better spatial constraints on fabric, the effect
577 of fabric could be included in existing large-scale, transient models of ice shelf flow without much effort or
578 computational expense. In practice, ice flow models that rely on initialization-by-inversion may already implicitly
579 incorporate some effect of fabric by inverting for E (or equivalently, A) using remote sensing data (e.g. MacAyeal,
580 1993; Ranganathan and others, 2020). However, inferring E this way combines multiple rheological effects into a
581 single factor in the sense that $E = E_{\text{fabric}} E_{\text{damage}} E_{\text{dust}} \dots$, making it difficult to separate individual contributions
582 (see also Minchew and others, 2018). This work suggests new ways in which individual contributions might be
583 disentangled. For example, estimates of E , inferred from inversions using an ice flow model, could be divided by
584 E_{fabric} (as calculated above for Ross and PIG), allowing one to isolate how other mechanisms than fabric cause
585 spatial variations in viscosity. Alternatively, E_{fabric} might be used as a prior to inform Bayesian inversions of E .

586 **Relevance for ice streams**

587 This initial application of our anisotropic SSA model focuses on ice shelves due to their simplified stress state
588 and boundary conditions, but SSA models are commonly applied to ice streams as well. Applying our method to
589 grounded ice requires more caution than for ice shelves. Asserting a depth-constant fabric is problematic near ice-
590 stream sticky spots or topographical bumps where fabrics can develop that facilitate flows in potential in violation of
591 the SSA assumptions (Zhang and others, 2024; Rathmann and Lilien, 2021). For example, if the fabric develops in a
592 way that is favorable for vertical shear, the assumption of plug flow may be less valid, similar to the effect of localized

593 shear heating above topographical bumps (Liu and others, 2024). On the other hand, the undisturbed internal-layer
594 structure of the North-East Greenland ice stream (NEGIS) (Jansen and others, 2024), together with surface velocity
595 observations, indicates that the ice stream deforms by plug flow (Gerber and others, 2023). Although NEGIS is
596 unique in being relatively flat-bedded (at least upstream), this suggests that anisotropic SSA modeling might be
597 relevant in some parts of some ice streams. On that note, the near-bed fabrics of NEGIS (Stoll and others, 2024)
598 are affected by DDRX which would support faster vertical shearing compared to shallower fabrics if vertical shear
599 stresses are important, similar to the above-mentioned situation over bed bumps or sticky spots. But the fabric-
600 induced softness for vertical shear is irrelevant if the stress regime is predominantly longitudinal (assuming fabric
601 compatibility is good), which the observed plug flow would seem to indicate.

602 Because it is difficult to judge where applications of our method to ice streams will fail without comparing to a
603 higher-order or full-Stokes model, it may be prudent simply to use a more complex flow model for grounded ice.
604 That is not to say our results are irrelevant for such regions; considerable computational expense could be avoided
605 by calculating E using EIE or CAFFE, rather than adopting an anisotropic rheology, regardless of stress balance
606 approximation.

607 **Marine ice accretion**

608 The idealized ice shelf model considered here relies on the assumption of a bulk rheology relevant to meteoric ice.
609 In real ice shelves, there are places where this assumption is less valid, such as when significant marine ice layers
610 are present. Marine ice forms because of the accretion of platelet crystals on the ice shelf base. The microstructural,
611 chemical, and thermal characteristics of marine ice differ significantly from meteoric ice. In particular, it is
612 rheologically weaker than standard ice when in the tertiary creep phase (Craw, 2023), which may be related to
613 the presence of liquid on the grain boundaries of marine ice crystals and hence grain boundary sliding processes
614 (Barnes and others, 1971; Dash and others, 2006), that could facilitate lower viscosity and lead to faster ice flow
615 compared to meteoric ice.

616 Marine ice is unlikely to be widespread in Antarctica, but has been inferred—either directly from borehole
617 measurements or indirectly from satellite observations or ocean modeling—on the Amery Ice Shelf (Craven and
618 others, 2005; Fricker and others, 2001; Galton-Fenzi and others, 2012; Treverrow and others, 2010), the Filchner-
619 Ronne Ice Shelf (Moore and others, 1994), and the Nansen Ice Shelf (Dierckx and others, 2014; Dierckx and Tison,
620 2013; Khazendar and Jenkins, 2003). On these ice shelves, a bulk rheology that matches that of meteoric ice may
621 not suffice, and changes in the distribution of marine ice over time may also impact the relevance of the steady-state
622 fabric assumption. It is also worth noting that modeling of an idealized ice shelf using ESTAR (Craw and others,

623 2023) indicates that while fabric differences between marine and meteoric may be significant, variations in the
624 vertical temperature distribution through an ice shelf had an order of magnitude greater impact on flow dynamics.

625 **Fabric model shortcomings**

626 Simulating ice fabric evolution, whether in laboratory conditions or in glaciers and ice sheets, requires accounting
627 for both lattice rotation due to dislocation glide (intracrystalline slip) and accommodation processes such as dynamic
628 recrystallization (DRX). Both processes are related to the strong viscoplastic anisotropy of ice. First, because
629 the predominance of dislocation glide in the basal plane results in strongly anisotropic fabrics. Second, because
630 DRX mechanisms are driven by the stored strain energy, which is related to deformation incompatibilities between
631 polycrystal grains. Any modeling approach that does not provide an accurate representation of these processes will
632 result in biased predictions of fabric evolution that somehow need to be compensated for.

633 Castelnau and others (1996) demonstrated this in detail, showing that the Sachs (homogeneous stress) and
634 Taylor (homogeneous strain) approximations are bound estimates, unable to sufficiently simulate the mechanical
635 response of ice polycrystals and hence fabric evolution. By neglecting grain interactions, the two bounds lead
636 to an over- and underestimation of the mechanical anisotropy, respectively, and therefore also of lattice rotation
637 due to intracrystalline slip. In the coupled model approach presented here, fabric evolution relies on the Taylor
638 approximation, but this is (to some extent) compensated for by the α parameter, which controls how much the Sachs
639 approximation contributes to the fabric-induced mechanical anisotropy (and hence large-scale flow, which drives
640 fabric evolution).

641 The formulation of Placidi and others (2010) used here relates the occurrence of DRX to the deformability of
642 an individual grain, defined as the square of the basal-plane resolved shear stress that depends on the basal Schmid
643 factor. This approach implicitly assumes that each grain is subjected to the same macro (bulk) stress, regardless of the
644 stress redistribution resulting from intergranular interactions. The impact of these interactions on the redistribution
645 of stress and strain has been investigated experimentally and using full-field modeling (Grennerat and others, 2012;
646 Piazzolo and others, 2015). Results suggest that there is no correlation between the Schmid factor (as used here)
647 and the amount of strain experienced by a grain, but also that local stresses can significantly deviate from the
648 applied (bulk) stress. This stress heterogeneity probably explains why DDRX fabrics observed in the laboratory
649 (e.g. Bouchez and Duval, 1982; Jacka, 1984; Montagnat and others, 2015; Journaux and others, 2019; Qi and others,
650 2019) are close to, but not exactly, the most favorable fabric for an applied stress. To some extent, this effect can
651 be viewed as a dispersion of grain orientations that could be taken into account by including CDRX as a diffusive
652 process in orientation space (Richards and others, 2021).

653 Most of the simulated fabrics presented here are in good agreement with recent full-field finite-element model
654 predictions made by Chauve and others (2024), where the local (finite element scale) resolved shear stress is used
655 to calculate an attractor toward which c -axis rotate due to DDRX. Using this approach, fabrics observed under
656 various laboratory conditions can be reproduced by appropriately adjusting one single DDRX kinetic parameter.
657 In particular, the double-maximum transitory fabrics that develop under simple shear (Hudleston, 1977; Bouchez
658 and Duval, 1982) are well reproduced. Despite the increased physical realism of such full-field models compared to
659 our fabric model that treats grains as interactionless and assumes crude stress/strain homogenizations, our approach
660 has also been shown to be able to reproduce complicated transitory fabrics (Richards and others, 2021). But how
661 exactly the rate of DDRX is to be parameterized as a function of temperature and stress/strain-rate magnitude is not
662 settled; recent work suggests that lab-calibrated rate functions are not necessarily applicable to large-scale ice flow
663 modeling in East Antarctica (Lilien and others, 2023).

664 CONCLUSIONS

665 We investigated the rheological control (ease of deformation) exerted by well-developed crystal orientation fabrics
666 on the flow of the Ross and Pine Island Glacier (PIG) ice shelves, Antarctica, by calculating maps of fabric-induced
667 flow enhancement factors using the CAFFE model (Placidi and others, 2010). To do so, we estimated steady-state
668 fabric fields over Ross and PIG by solving a high-dimensional boundary value problem, assuming depth-independent
669 horizontal velocities (plug flow) and that the ice accumulation rate is small compared to the local ice thickness. In
670 effect, the problem is closed by prescribing satellite-derived surface velocities and ice temperatures. Since the latter
671 is not known in sufficient spatial detail, we considered the two end-member cases in which the Ross and PIG
672 regions are either very cold or warm, so that dynamic recrystallization is either negligible or strong, respectively.
673 The two solutions show that significant ice shelf hardening or softening can occur depending on whether dynamic
674 recrystallization is important or not. This emphasizes the ice-dynamical relevance of needing to better constrain the
675 strength of fabric processes, which in turn calls on widespread fabric and temperature measurements from the field
676 that are currently missing or too sparsely available for model validation.

677 To increase our confidence in the relevance of the calculated enhancement factor maps, we tested how well
678 CAFFE, when combined with Glen's isotropic flow law, can reproduce the velocity field of an idealized ice-shelf
679 box model that has a two-way coupling between fabric and flow (anisotropic plug flow rheology). We find that
680 replacing the tensorial viscosity structure by a scalar flow enhancement factor leads to velocity errors on the order
681 of ten percent, but if DDRX is strong, the error might be a bit larger. Given that neglecting the effect of ice fabric
682 altogether leads to modeled velocity errors between thirty to sixty percent, this is much of an improvement. We

683 therefore argue that in some instances it might be reasonable to simply use CAFFE in large-scale flow models to
684 account for the rheological control exerted by evolving ice-crystal fabrics, which can easily be implemented when
685 combined with the spectral fabric model presented here.

686 OPEN RESEARCH

687 The FEniCS model code and scripts for generating all plots are available at [https://github.com/nicholasmr/
688 specfab](https://github.com/nicholasmr/specfab)

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