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# Unraveling the effect of convergence obliquity on overriding-plate deformation and strain partitioning in subduction zones

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1	Unraveling the effect of convergence obliquity on overriding-plate deformation and
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11	Abstract
12	The subduction of an oceanic plate causes deformation of the overriding plate, from the
13	forearc to the back-arc regions. Over years, to address the physical controls on such a
14	deformation, various compilations on active deformation have been made, mixing various
15	types of datasets including fault-slip rates, focal mechanisms and geodetic motions. The
16	growing amount of available data now allows for the construction of consistent
17	compilations in terms of data types. Here, we present a database for the kinematics of
18	subduction zones which includes that of the overriding-plate deformation, consistently
19	based on geodetic data. The database describes the 2-d (trench-normal and trench-
20	parallel) motions of arc blocks for ~90% of active subduction zones, through the magnitude
21	$(v_d)$ and the deformation-obliquity angle $(O_{vd})$ between the blocks and the upper plate

- 22 (undeformed interior of the overriding plate). We classify subduction zones into 4 dominant

strain classes (compressional, strike-slip, extensional, and neutral), and into up to 8 classes 23 including intermediate regimes. Focusing on the strike-slip strain class, we show that a non-24 negligeable trench-parallel motion is a widespread feature of active subduction zones. The 25 26 convergence obliquity exerts, however, a contrasting effect on  $O_{vd}$ , thereby suggesting a 27 limited effect on strain partitioning at oblique subduction zones. On another hand,  $O_{vd}$ shows a positive correlation with slab dip, where low and high values are associated with 28 compression and extensional classes, respectively. Finally, we provide revised estimations 29 of subduction rates, allowing for instance refined estimations of the thermal parameter, 30 which will permit future comparative investigations on subduction dynamics and tectonics. 31 32

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#### 34 I. Introduction

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Subduction dynamics leads to the deformation of the overriding plate which 36 encompasses all tectonic regimes from back-arc spreading to mountain building (Uyeda 37 and Kanamori, 1979). Using geological and geophysical global datasets, various statistical 38 39 studies have characterized the deformation of the overriding plate for present-day subduction zones, focusing on characterization of one-dimensionnal trench-perpendicular 40 41 deformation regimes (Doglioni et al., 2007; Heuret & Lallemand, 2005; Jarrard, 1986; Lallemand et al., 2005; Petricca & Carminati, 2016; Schellart, 2008b, 2008a). For instance, 42 43 arc-to-back arc one-dimensional deformation rates were inferred from geodetic velocities and geological deformation rates by Heuret and Lallemand (2005) and Schellart et al. 44

(2008b). In addition, focal mechanisms were used to define semi-quantitative overridingplate strain classes (Jarrard, 1986; Lallemand et al., 2005). These studies showed some
correlations of the trench-normal overriding plate deformation to overriding plate motion
(Heuret & Lallemand, 2005; Jarrard, 1986), to the slab dip (Lallemand et al., 2005), and to
the combination of overriding plate motion and distance to a slab edge (Schellart, 2008a,
2024).

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While the global statistical studies listed above focused on deciphering the controls 52 on one-dimensional trench-normal deformation of the overriding plate, in nature, 53 however, deformation is, at least, a two-dimensional process, and the direction of 54 maximum deformation most often deviates from the normal to the trench. This can 55 produce, in extensive settings, for instance, a misorientation between the direction of back-56 arc spreading and the trench normal. This is the case in the southern Marianas, in the North 57 and South Sandwich back-arc, and most notably in the Andaman Sea. But the most striking 58 59 observation on the two-dimensionality of overriding-plates deformation is strain partitioning at oblique subduction zones. Oblique subduction zones are those where the 60 convergence vector between the subducting and the overriding plates deviates from the 61 62 direction of the normal to the trench, and appear as the rule rather than the exception in present-day subduction zones (Jarrard, 1986; Philippon & Corti, 2016). In a pioneering work, 63 Fitch et al. (1972), suggested that oblique convergence was mostly consumed along strike-64 65 slip faults quasi-parallel to the trench while the remaining was taken up on thrust 66 structures. Jarrard et al. (1986) later demonstrate that the strike-slip or transcurrent

motions tend to increase with the obliquity angle (see also McCaffrey, 1992; Yu et al., 1993), 67 and that they are more frequent at oceanic-continent subduction zones. In many cases, the 68 strike-slip fault (system) that accommodates strain partition, occurs in the vicinity of the arc 69 70 and defines a "forearc sliver" that tends to move independently of the interior of the 71 overriding plate. Among the most notable examples of strike-slip faults accommodating partition are the Great Sumatran Fault (Bellier & Sébrier, 1995), the Philippine Fault (Barrier 72 et al., 1991), the Southern Kuril strike-slip system (DeMets, 1992; Kimura, 1986), the 73 Chingual-Cosanga-Pallatanga-Puña Fault in the Northern Andes (Alvarado et al., 2016; Baize 74 75 et al., 2020) or the Yaeyama Fault in the Southern Ryukyus (Lallemand et al., 1999). It is also 76 worth noting that even though strain partitioning originally referred to partition of slip on 77 two localized faults, the term has also been more generally used for any type of deformation partition, whether localized or diffuse, including some component parallel to 78 the subduction trench such as the set of conjugate and transcurrent strike-slip faults in SW 79 Japan (Gutscher & Lallemand, 1999) or the Sorong Fault system in New Guinea (Patria et 80 81 al., 2021).

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Despite a long list of physical studies that investigated the conditions which may or may not allow for strain partitioning, no consensus has yet emerged (Byrne et al., 1985; Chemenda et al., 2000; Cooke et al., 2020; Dominguez et al., 1998; Haq & Davis, 2010; Jarrard, 1986; Liu et al., 1995; Martinez et al., 2002; McCaffrey, 1992; McClay et al., 2004; Suárez et al., 2022). One of the potential limitations to address strain partitioning, and more generally, to address the amount of overriding plate deformation in space and its relation

89 to other subduction processes, has been the lack of a complete global database for 90 present-day subduction zones. This is precisely the purpose of the present study where we 91 have built a database of the direction and intensity of the main sites of overriding plate 92 deformation.

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94 We present a comprehensive update on the kinematics component of the Submap database (Heuret, 2005; Lallemand & Heuret, 2017). The latter database consists in the 95 sampling of all present-day subduction zones approximately every 200 km, amounting to 96 a total of 260 subduction transects, for which a wide range of parameters have been 97 constrained from the compilation of a wide range of published studies. The parameters 98 99 include data on kinematics (Cerpa et al., 2022b; Heuret & Lallemand, 2005), on the subducting slab geometry (Lallemand et al., 2005), on the structural parameters (Heuret et 100 101 al., 2012; Lallemand et al., 2024), and on the characteristics of the seismogenic zone (Heuret et al., 2011). In particular, the kinematics in the Submap database compiles information on 102 103 the absolute and relative plate motions, the subduction rate, and the deformation rate of 104 the overriding plate. This compilation has been widely applied in studies of diverse topics, 105 from subduction dynamics (Faccenna et al., 2007; Funiciello et al., 2008; Lallemand et al., 106 2008; Nakao et al., 2022) to the seismogenic behavior of the plate interface (Brizzi et al., 2018; Marzocchi et al., 2016; Wirth et al., 2022; Zelst et al., 2025). 107

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109 Our update concerns the relative and absolute plate motions at subduction 110 trenches, accounting for estimations of the overriding plate deformation rate, following

111 preliminary work in Cerpa et al., (2022b). Importantly, in the previous version of the Submap kinematic database, Heuret and Lallemand (2005) determined only the trench-112 normal overriding-plate deformation velocity  $v_{d_n}$ , providing non-null values of  $v_{d_n}$  for 113 114 about half of the Submap transects. In the current update, based on the most recent literature, we are able to reach a spatial description (full vector  $v_d$ ) for 78% of the transects. 115 It is also worth noting that information on the overriding-plate deformation rates allows 116 for a more precise estimate of subduction rates at present-day than what would be 117 118 constrained solely based on the far-field subducting plate and overriding plate velocities 119 obtained from global plate kinematic models (i.e., by the estimation of the convergence 120 rate).

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Below, we describe how we built the kinematic database. Then, we assess global characteristics of overriding-plate deformation, before assessing its relationship to other subduction parameters. Finally, we discuss some implications of revised values of the rates of subducting-plate consumption at trench, i. e. the subduction velocities.

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### 128 **II. Building the kinematic database**

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### II.1.General definitions

For describing the kinematics at each subduction transect of the Submap database,we associate each transect to a subducting plate (SP) and to an undeformed area of the

overriding plate, which we refer to as the upper plate (UP) (Figure 1). The SP and the UP move at absolute velocities of  $V_{sub}$  and  $V_{up}$ , respectively. Here, by "absolute velocities" we mean velocities that describe the motion of the plates relative to a deep, stable, reference frame, often taken to be the Earth lower mantle. The sum of these two velocities gives the convergence velocity  $v_c = V_{sub} + V_{up}$ , that is the rate at which the assumed undeformable interiors of the two plates move relative to each other.

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141 In nature, however, the overriding plate generally undergoes deformation in the forearc, in the arc and/or in the back-arc regions. The deformation may either localize on 142 one or more faults, or being diffuse across part or all of the forearc-to-back-arc regions, 143 sometimes leading to the formation of a sliver which moves semi-independently of the UP. 144 145 Thus, to account for the overriding-plate deformation, we define a deformation velocity  $v_d$ 146 which aims to integrate any deformation occurring from the forearc to the back-arc, 147 whether it is distributed or localized at single faults. In doing so, we define a real or an idealized pseudo-kinematic block, that we refer to as the "arc" block (AB). The velocity of 148 the AB relative to the UP is given by  $v_d$ . Knowing the latter, we can assess an absolute trench 149 velocity  $V_{trench}$  which differs from  $V_{up}$  if  $v_d \neq 0$ . Finally, we can define the subduction 150 151 velocity  $v_s = V_{sub} + V_{trench}$  which best represents the rate of SP consumption at trench. It is supposed to represent the slip velocity on the subduction interface estimated by geodesy, 152 153 and which can be compared to the seismic slip velocity inferred from the seismic moment 154 of the earthquakes on the subduction interface (Brune, 1968).

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We define the SP and UP for each subduction transect from the major plates of the plate set model MORVEL56 (Argus et al., 2011), which also gives us the convergence velocities between those plates. As described in details below, we assess the deformation velocities in the present-day subduction zones, which also permit us to provide an estimation of the subduction velocity. Moreover, although the present study focuses on relative velocities ( $v_c$ ,  $v_s$  and  $v_d$ ), we have calculated absolute velocities ( $V_{sub}$ ,  $V_{up}$ , and  $V_t$ ) for each transect in four selected absolute references frames: MORVEL56-NNR model (Argus

et al., 2011), the spreading-alignment model (Becker et al., 2015), the T25m model (Wang
et al., 2018), and the GMHRF-1Ma model (Doubrovine et al., 2012). Although not exhaustive,
such a selection covers part of the variety of absolute plate kinematic models, e.g., in terms
of the data used to establish them (see Cerpa et al., 2022b).

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For all type of velocities, we calculate their obliquity *O* relative the normal to the trench. We can then calculate the trench-normal and trench-orthogonal component of all velocities, which are denoted with the subscripts *n* and *t*, respectively.

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## II.2.Arc blocks and estimation of deformation velocities

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We seek to characterize the deformation of overriding plates in relatively close distances to the subduction trenches, by estimating  $v_d$  for as many subduction transects as possible. This relies on the definition of an AB for several subduction segments, inferred exclusively from GPS data.

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To illustrate how we integrated the deformation of the overriding plate predicted by GPS studies into  $v_d$ , we take the example of the South-East Asia region (see Figure 2) which illustrates the several possible definitions of an AB:

An AB is defined as one of the plates in the MORVEL56 plates set (dark blue patches
 in Figure 2a and in Table 1), if the latter plate occupies a region which is small relative
 to the size of the large plates taken to be the upper plates (Eurasia plate, Sunda plate,
 Philippine Sea plate, etc.). This is, for instance, the case for the Andaman subduction
 transects for which we take the Sunda plate from MORVEL56 as the UP, and the

- 187 Burma plate from MORVEL56 as the AB. This is also the case for the Mariana 188 transects where both the UP and the AB are from the MORVEL56 plates set.
- An AB is taken from a GPS-derived rigid block defined in published studies, with
   available Euler pole and rotation rate (light blue patches in Figure 2ab and Table 1).
   Two sub-cases exist here:
- 1) The AB motion was neglected in the MORVEL56 plate set model. This is, for
   instance, the case for the Sumatra transects for which the Sunda Plate from
   MORVEL56 is the UP, and for which we take into account the Sumatra forearc
   sliver block described by Bradley et al. (2017).
- 2) An update of the AB motion post-MORVEL56 is available and we thus modify
   part of a block of the MORVEL56 model. This is the case for the case for the
   Yonaguni block at the southwestern end of the Ryukyus transects (Chen et al.,
   2022), which substitutes the southernmost solution given by the Okinawa
   block of MORVEL56

• In some other cases (Taiwan, Luzon, Visayas and East-Philippines), the UP deformation appears distributed. GPS velocities have been published for specific stations (Hsu et al., in press; e.g. Rangin et al., 1999; Simons et al., 2007; Socquet et al., 2006) but no rigid blocks have been identified in past studies. In such cases, we extract, from published studies, the motion of the station closest to the trench as a proxy of AB motion. We then post-calculate the deformation rate  $v_d$  between the forearc and the UP by difference between both GPS velocities, thereby neglecting

- the interseismic loading, if any. We refer to these regions as to deformed areas (red
  patches in Figure 2ac and Table 1).
- In regions such as the Southernmost Marianas or the Northernmost Philippines, we did not find any published geodetic-velocity solution for the overriding plate deformation despite geological evidences of recent deformation (Hsu et al., in press; Ribeiro et al., 2013). For those cases, we set  $v_d$  as undefined (rather than 0). However, we make use of the a MORVEL-56 derived solution for  $v_c$  and assume that  $v_s = v_c$  (blue stripes in Figure2a and Table 2).
- Finally, in Halmahera, Sangihe, South Philippines or Sulu, the use of M56 plate kinematics provides unreasonable values of  $v_c$  because UP or SP are difficult to constrain. Despite the scarcity of GPS data in those regions, we utilized the published motions of a few stations on both sides of the trench to provide first-order estimates of  $v_s$ , but not to retrieve  $v_d$ . We define these cases as the deformed areas (red stripes in Figure2a and Table 2).
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Exceptionally, and for reasons of consistency, we have assigned a  $v_s$  extrapolated from adjacent transects on one of our transects across the Manila Trough because at this latitude only the Philippine Sea plate (UP) motion relative to the Sunda plate is known through the GPS stations installed on the Batan islets despite the fact that the forearc deforms (Martinez et al., 2002).

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In addition to the above exposed cases, there are further specificities which are not
encountered in the Southeast-Asia region but which are to be noted for a few transects in
other regions:

For NE Japan subduction transects (Figure 3), the Okhotsk plate from MORVEL56 is
 taken to be the AB while the Amur Plate is taken to be the UP. Further north, for the
 northern Kurils and for the Kamchatka transects, the Okhotsk plate is rather defined
 as the UP. Only for the South-Kuril transects, we are able to provide a solution for
 the motion of a pseudo-rigid AB. For the other transects in this area we have not
 defined an AB (though the UP may be experiencing active deformation, see below).

- For the northernmost Andean transects, the AB motion was taken from (Jarrin et al.,
   2023) in place of the entire north Andean block of MORVEL56.
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Overall, this inventory leads to the use of 11 ABs from the M56 plates set, 35 additional rigid ABs and 14 additional pseudo-ABs or deformed areas for which  $v_d$  are indirectly constrained by single GPS stations (Table 1). Furthermore, we also have identified 13 regions where  $v_d$  is not constrained (Table 2), but 4 of them for which  $v_s$  can be derived from GPS and 9 for which we assume  $v_s = v_c$ . The 73 areas are displayed in Figure 3. The names of the blocks together with the references from which they were taken, are listed in Table 1 and 2.

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249 *II.3.Potential limitations of our approach*250
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Our estimation of the deformation vector  $v_d$  is exclusively based on geodetic data 251 252 and most often derived from rigid blocks. While in most cases the use of these blocks 253 improves the estimation of relative subduction velocities, the rigid solution near 254 extremities of the slivers may be poorly resolved in some cases. We thus preferred to 255 ignore, for instance, the AB corresponding to the western termination of the Scotia plate at 256 the southernmost tip of Patagonia, as the Eulerian solution of its motion relative to the 257 South America plate did not match the deformation observed in the field (Perucca et al., 258 2016). Furthermore, the deformation of the submerged forearc or backarc may be 259 underestimated because of the lack of ocean bottom geodetic stations.

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261 In a few regions (blue stripes in Figure3), geodetic deformation velocities are 262 unavailable while geological evidence of active deformation exist. These regions include 263 the Kamchatka region which has undergone Quaternary extension at a geological rate of 17 +/- 3 mm/yr (Kozhurin et al., 2006; Kozhurin & Zelenin, 2017), the Central Chile with 264 evidences of Plio-Quaternary compression through tectonic inversion of former 265 extensional faults (Becerra et al., 2013), the Southernmost Patagonia where the forearc 266 267 consists of the western end of the Scotia plate sliding along the Magallanes-Fagnano leftlateral fault system at a rate of 8.1 +/- 1.5 mm/yr (Perucca et al., 2016), some poorly 268 constrained subduction zones of Southeast Asia including the Banda Sea (Aru, Seram), the 269 270 Molucca Sea (Halmahera, Sangihe, S- and N-Philippines), and the Celebes Sea (Cotobato, 271 Sulu), the Southermost Mariana arc and forearc undergoing trench-parallel extension 272 (Ribeiro et al., 2013), the Solomon arc which is shortened by subduction-collision of the 273 Ontong-Java plateau (Mann & Taira, 2004), the Southermost New-Hebrides where the arc 274 rotates clockwise as a result of its indentation by the Loyalty Arc (Patriat et al., 2015), as 275 well as the Puysegur Ridge hosting the right-lateral transcurrent Puysegur Fault (Collot et 276 al., 1995). We acknowledge the limitation of the available data for constraining geodetic 277 deformation by marking those regions as undefined rather than marking them as neutral. 278 Moreover, in some cases, we find that it is not even possible to characterize  $v_c$  because the 279 complexity of region, including high UP or SP deformation such as that in the Molucca Sea

area (Rangin et al., (1999), red stripes in Figure 3). All the above regions where  $v_d$  is unconstrained are listed in Table 2. We further split those regions depending on whether  $v_s$  is constrained but  $v_c$  is not (red stripes in Table 2) or whether we have approximated  $v_s$ as  $v_c = v_s$  (blue stripes in Table 2).

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# 286 III. Upper-plate deformation: general characteristics and comparison to 287 geological constraints

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# III.1. Defining strain classes from the obliquity of the deformation velocity

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292 To analyze globally the kinematics of overriding-plates deformation in the arc to back-arc regions, we seek to define strain classes (e.g., Lallemand et al., 2005). We conduct 293 the classification using the value of the obliquity  $O_{v_d}$  of the overriding plate deformation 294 295 velocity, that is the misorientation of  $v_d$  relative to the trench-normal which takes values between 0 and 180° (see Figure 1), or equivalently, on the basis of the directed obliquity 296  $\bar{O}_{v_d}$  which takes values between -180° and 180° (positive for right-lateral and negative for 297 left-lateral components of sliver motions). The reasoning behind our choice, is based on 298 the fact that, within our framework, the ideal cases of pure overriding plate compression, 299 extension and ideal strike-slip, would correspond to values of  $O_{\nu_d}$  equal to 0°, 180°, and 90°, 300 respectively (see Figure 1). 301

However, the direction of overriding plate deformation generally deviates from these three
ideal cases and thus we can expand the definition to define three dominant-strain classes
as (see Figure 4a):

307• overriding plates undergoing dominant extension are defined when  $135^{\circ} \le O_{v_d} \le$ 308 $180^{\circ}$  (or  $135 \le \overline{O}_{v_d} \le 180^{\circ} \& -180 \le \overline{O}_{v_d} \le -135^{\circ}$ )

<sup>305•</sup> overriding plates undergoing dominant compression are defined when  $O_{v_d} < 45^\circ$  (or306 $-45^\circ < \bar{O}_{v_d} < 45^\circ$ )

• overriding plates undergoing dominant strike-slip are defined when  $45^{\circ} \le O_{v_d} < 310$  $135^{\circ}$  (or  $45 \le \overline{O}_{v_d} < 135^{\circ} \& -135 < \overline{O}_{v_d} \le -45^{\circ}$ 

These three dominant classes can be further declined into seven strain (sub)classes composed of three pure-strain classes (C, E, SS) and four other combinations of these endmembers (C-SS, SS-C, E-SS, and SS-E), as illustrated on Figure 4a. We emphasize that, below, we will use the term "dominant compression" to describe collectively the subclasses C and C-SS, "dominant strike-slip" for SS-C, SS, and SS-E, and "dominant extension" for E and E-SS.

317 It is worth noting that some necessary simplifications underlie our approach to derive strain (sub)classes based on the value of  $O_{v_d}$ . In particular, our dominant 318 319 compressive and extensive regimes are good descriptors of (quasi-)trench normal 320 compression and extension. Quasi-trench parallel compression or extension, would 321 instead fall into our SS classes. Likewise, our strike-slip class is well suited to characterize 322 quasi-trench parallel strike-slip deformation, while oblique to trench-normal strike-slip systems would lie in our C or E classes. However, we argue that these concern only a few 323 324 cases and that the advantage of our classification is that it permits to carry a consistent 325 global analysis.

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327 With the above caveats in mind, Figures 4b-f provide a global view of the overridingplate deformation calculated for most of the transects of our database, as well as their 328 associated strain classes. A more synthetic and schematic global overview is provided in 329 330 Figure 5 along with a piechart of their relative and absolute distribution. In the database, 331 among the 213 transects with constrained non-zeros values of  $v_d$  (82% of all transects), we count 40 (19% of all transects), 39 (18% of all transects), and 134 (60% of all transects) 332 333 transects belonging to the three classes: dominant compression (C, C-SS), dominant 334 extension (E, E-SS) and dominant strike-slip (SS, SS-C, SS-E), respectively. We note that our 335 database describes the deformation of the overriding plates within a mean distance of 336 ~340 km, with a minimum of ~100 km (in eastern Philippines) and up to a maximum of 900 km (in the Altiplano region). 337

339 Transects in the pure compression (C,  $|\bar{O}_{v_d}| < 10^\circ$ ) or pure extension (E,  $|\bar{O}_{v_d}| \ge 170^\circ$ ) 340 regimes are relatively rare (each representing only 3% of all of our transects). The few 341 transects having a pure C regime are in E-Makran (Reilinger et al., 2006), E-Alaska (Elliott & 342 Freymueller, 2020) and C-Andes (Altiplano, Argus et al., (2011)). The transects under pure E regime are found in C-Ryukyus (Argus et al., 2011), the C-Sandwich (Argus et al., 2011), in 343 344 W-Mexico (Andreani et al., 2008; Selvans et al., 2011) and in N-Marianas (Argus et al., 2011). Compression associated with strike-slip (C-SS,  $10^{\circ} \le |O v_d| < 45^{\circ}$ ) as well as extension 345 346 associated with strike-slip (E-SS, 135°≤ $|Ov_d|$ <170°) represent 13 and 12% of the transects, 347 respectively. C-SS regime is observed along the Andes in Ecuador (Jarrin et al., 2023) and in 348 C-Chile (Brooks et al., 2003), in Timor and Flores (Koulali et al., 2016), in W-Makran (Reilinger et al., 2006), or in C-New Hebrides due to the subduction of the D'Entrecastaux Ridge 349 350 (Bergeot et al., 2009). E-SS regime is observed in Calabrian (Serpelloni et al., 2007) and the 351 Hellenic area (Vernant et al., 2014), in the Tonga-Kermadec (Argus et al., 2011) and in some 352 portions of the Izu-Bonin-Mariana (Argus et al., 2011; Nishimura, 2011), in C-Aleutians 353 (Elliott & Freymueller, 2020) and in New Britain (Argus et al., 2011).

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355 A pure strike-slip regime (SS,  $|Ov_d| = 90 \pm 10^\circ$ ) is observed in 14% of the subduction 356 zone transects including in the Sumatra (Bradley et al., 2017), the S-Kurils (DeMets, 1992) 357 trenches, in Cascadia (Mazzotti et al., 2002, 2003), in Smost-Chile (Wang et al., 2007), and 358 along some transects of the W- and the E-Aleutians trenches (Cross & Freymueller, 2008; Elliott & Freymueller, 2020). In a higher number of cases though, the lateral component of 359 360 the deformation is combined with either compression (23% of transects, SS-C,  $10^{\circ} \leq |Ov_d| <$ 361 45°) or extension (15% of transects, SS-E, 100°  $\leq |Ov_d| < 135^\circ$ ). Typical cases of the SS-C 362 regime are in the Andes (Brooks et al., 2003; Jarrin et al., 2023; Villegas-Lanza et al., 2016), in the W-Aleutians and in W-Alaska (Cross & Freymueller, 2008; Elliott & Freymueller, 2020), 363 364 in Japan (Argus et al., 2011; Nishimura et al., 2018), in C-Philippines (Rangin et al., 1999), in 365 W-Java (Koulali et al., 2017), and on the Muertos Trough (Calais et al., 2022). Examples of 366 SS-E strain regime are observed in C-America (Andreani et al., 2008; Carvajal-Soto et al.,

2020), in Andaman (Argus et al., 2011), in the Aleutians (Cross & Freymueller, 2008; Elliott
& Freymueller, 2020), and in the Izu-Bonin-Mariana (Argus et al., 2011; Nishimura, 2011)
and of Hikurangi (Argus et al., 2011).

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We have further classified 6% of our transects as neutral ( $v_d$ =0). Typically, the Lesser Antilles falls into this category as it does not how significant upper plate deformation (Symithe et al., 2015).

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Finally, we have 30 transects (12% of the total) which we classify as "undefined" since geological observations suggest active tectonics but no geodetic-based quantification of it has been proposed (see Section II.3).

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In what follows, although we classified our transects into 8 subclasses of strain regimes
(and one "undefined" subclass) we will carry our analysis describing them only in terms of
the three classes of dominant regime (cf. Figure 4a).

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### III.2. Global trends of UP-deformation velocities

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385 The mean of all magnitudes of  $v_d$  is ~23 mm/yr but the distribution of the 386 magnitudes shows important differences depending on the dominant strain class (Figure 6a). The mean  $v_d$  for both the regimes of dominant compression and strike-slip regimes 387 388 are around 20 mm/yr, while dominant-extensive settings rise a mean  $v_d$  of about 40 389 mm/yr. As expected, the highest magnitudes (> 80 mm/yr) of overriding-plate deformation 390 rates are found exclusively for regimes of dominant extension. These highest  $v_d$  are 391 predicted for fast-spreading centers at the back-arc of Tonga and New Britain subduction 392 zones. More moderate extensive deformation rates (40-80 mm/yr) are observed for the 393 Kermadec, the Ryukyus and the Marianas back-arcs. On the contrary, overriding plates 394 under dominant compression experience mostly deformation rates of less than 50 mm/yr, 395 with 75% of compressive transects deforming at less than approximately 30 mm/yr. Some

anomalous high deformation rates are found for the South-Philippines transects, reflecting 396 397 both strike-slip at the Philippine fault and the presence of retro-subduction zones 398 (Cotobato, Sulu/Negros SZs), and at the site of the collision between the D'Entrecasteaux 399 Ridge and the New Hebrides subduction trench. The transects with overriding plate under 400 dominant strike-slip regime, also show mostly deformation rates of less than ~50 mm/yr. 401 The highest value (81 mm/yr) is predicted for one C-Philippine transects for the reason 402 explained above. Other moderately high values of deformation in strike-slip systems (50-403 60 mm/yr) come from oblique-spreading settings (Andaman, S-Sandwich, S-Marianas).

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405 To further analyze the deformation rates, we can decompose the rate  $v_d$  into a trench-normal component  $v_{d_n}$  and a trench-parallel/tangential component  $v_{d_t}$  (Figure 1). 406 Our definition of the trench-normal component  $v_{d_n}$  is such that overriding plates under 407 dominant compression yield positive values of  $v_{d_n}$ , while those under dominant extension 408 409 rise negative values. The transects with overriding plates under dominant strike-slip motion can be associated with either positive or negative values of  $v_{d_n}$ , depicting either overall 410 411 transpressional or transtentional regimes, respectively. In addition, the trench-parallel 412 component  $v_{d_t}$  is also signed with positive values indicating right-lateral strike slip, and 413 negative values left-lateral strike slip (Figure6c).

414

415 Figure 6b shows that the absolute values of trench-normal components  $|v_{d_n}|$  are less 416 than 60 mm/yr (mean of 17 mm/yr) with a very few transects under dominant extension experiencing higher rates of extension. The values of  $|v_{d_n}|$  are generally higher for 417 418 extensive regions than those of the compressive regions, as noted for the magnitude of 419 the deformation vector. The transects falling under our dominant strike-slip class display 420 values of  $|v_{d_n}|$  with a relatively low mean of ~6 mm/yr. Transtention and transpression are 421 almost equally represented by all subduction transects. Figure 6c shows that the absolute 422 value of trench-parallel component  $|v_{d_t}|$  for systems under dominant strike-slip can be as 423 high as 60 mm/yr, with a mean value of ~20 mm/yr. Within our classification framework 424 there are more right-lateral strike slip systems (~2/3) than left-lateral (~1/3).

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- III.3.1. Degree of strain partitioning

111.3.

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432 The trench-parallel component of deformation in subduction zones is thought to be 433 promoted by the obliquity of the convergence between SP and UP (e.g. Jarrard et al., 1986; 434 McCaffrey et al., 1992). Before re-assessing this relationship based on our estimations of 435 deformation in overriding plates, we first provide an overview on how the convergence and 436 the deformation velocities compare in terms of their normal and tangential components, by calculating the ratios  $\frac{|v_{d_n}|}{|v_{c_n}|}$  and  $\frac{|v_{d_t}|}{|v_{c_t}|}$ , respectively. Note that the latter has been often 437 referred to as the partition coefficient, and has served to evaluate the efficiency of strain 438 partitioning at oblique subduction zones in which the strike-slip motion was 439 440 accommodated along a single transform fault (e.g. Chemenda et al., 2000). Hereafter, we refer the ratios  $p_n = \frac{|v_{d_n}|}{|v_{c_n}|}$  and  $p_t = \frac{|v_{d_t}|}{|v_{c_t}|}$ , to as the normal and the lateral partition 441 442 coefficients, respectively.

the convergence velocity  $v_c$ 

Relationship between the deformation velocity  $v_d$  and

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444 The first striking observation for the normal partition coefficient (Figure 7a) is that only extensive deformation velocities can exceed the trench-normal component of 445 convergence. This is most notably the case for the Sandwich ( $p_n \approx 7 - 8$ ), the New Britain 446  $(p_n \approx 8 - 13)$  and the W-Aegean  $(p_n \text{ up to } 10)$  transects, where the trench-normal 447 448 convergence component mostly remains under 10 mm/yr while the trench-normal component of extension rate is higher than 30 mm/yr, reaching 110 mm/yr in the New 449 450 Britain. The normal partition coefficient  $p_n$  for compressive transects mostly display values of less than 0.6 (75 % of transect). The highest values (0.6 to 1) of  $p_n$  in compressive settings 451 correspond to regions where a retro-subduction zone develops (Panama, Tanimbar, Timor, 452

453 Flores, Philippines) or where subduction of a prominent buoyant feature tends to create a

454 collisional context (Alaska, New Hebrides).

455

456 Figure 7b shows the lateral partition coefficient for transects falling within our dominant 457 strike-slip class. More than 75% of those transects have lateral partition coefficient  $p_t$  of 458 less than 0.9. Those which have a trench-parallel overriding plate deformation velocity 459 largely exceeding the trench-parallel convergence velocity ( $p_t \gtrsim 5$ ) include those portions 460 of subduction zones experiencing spreading in a direction that depart from the normal to 461 the trench due to trench curvature. The latter cases include the Smost -Marianas ( $p_t \approx 8$ ), 462 the Sandwich ( $p_t \approx 7 - 8$ ), the C-New Hebrides ( $p_t \approx 8$ ) and Wmost-Aegean ( $p_t \approx 5$ ). Those large values of  $p_t$  are also found in regions with oblique retro-arc subduction zones such 463 464 as Manila ( $p_t \approx 9$ ) and Emost Java ( $p_t \approx 6$ ). Other transects having a high lateral partition coefficient ( $p_t \approx 1-5$ ) include the Nmost Tonga ( $p_t \approx 4$ ), C-Java and W-Java ( $p_t \approx 1-1.5$ ), N-465 Sumatra and Andaman ( $p_t \approx 1.5 - 2$ ), as well as the Mexican subduction trench ( $p_t \approx 1 - 5$ ). 466

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## III.3.2. Relationship between the directed $O_{vc}$ and $O_{vd}$

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470 Figure 8 shows that 84% of the transects undergoing overriding-plate deformation 471 display deformation obliquities O<sub>vd</sub> that are compatible with the obliquity of the 472 convergence O<sub>vc</sub>, regardless of the tectonic regime. Seven transects under the strike-slip dominant regime exhibit values  $[O_{vc}] > 90^{\circ}$  which, in the absence of deformation within 473 474 the arc block, would represent eduction rather than subduction. These 7 transects are all 475 located in five regions (Venezuela, N-Andaman, W-Aegean, E-Tanimbar, Panama) and 476 correspond to subduction zone terminations where the trench azimuth becomes 477 subparallel to  $v_c$  and where lateral displacement of AB re-establishes convergence 478 between AB and SP. There are 16% of the transects which fall into the upper-left or lower-479 right shaded quadrants, where the obliquities have opposite signs. They generally 480 correspond to collisional areas (Wetar, Timor, New-Hebrides, Makran, Solomons, Alaska) 481 or regions characterized by active back-arc extension (Calabria, Aegean, N-Tonga, S- 482 Sandwich, Ryukyus, Mariana). Extrusion processes and backarc rifting caused by buoyant
483 features indentation can provide an explanation for these "outliers" (Wallace et al., 2005,
484 2009).

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#### III.3.3. Focus on the strike-slip dominant-strain regime

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Next, we focus on the transects which fall in our dominant strike-slip regime ( $45^{\circ} < |O_{v_d}| < 135^{\circ}$ , cf. Figure 4a) to specifically assess the potential relationship between the kinematics of overriding plate deformation and that of the convergence, as proposed by numerous previous studies (e.g., Jarrard, 1986; McCaffrey 1992). These theoretical and modeling works suggested that the obliquity of convergence should transmit a shear force on the plate interface with some lateral component, potentially resulting on lateral 494 deformation in the overriding plate.

495

496 As noted above, the transects under dominant strike-slip regime on Figure 8 show 497 that the majority of transects have deformation obliquities that are higher than the convergence obliquity which is consistent with the fact that in most cases the subduction 498 499 obliguity is lower than that of the convergence. We note, however, a few exceptions for transects in which the convergence is almost tangential to the trench in the presence of a 500 501 very curved trench such as in the Wmost-Aleutians and Emost-Venezuela. Overall, there is 502 no clear relationship between the obliquity of deformation and that of the convergence. In particular, relatively low convergence obliquities (<30°) are associated with a variety of 503 504 deformation obliguities within the range 45-135°.

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Figure 9 displays the tangential deformation velocity against the tangential convergence velocity. We first note that a few regions (less than 10%) display values of  $v_{d_t}$ and  $v_{c_t}$  with opposite sign. These cases correspond to trench edges with sharp azimuthal trend changes, often associated with backarc spreading. We then perform an extraction of the transects where deformation is most likely strain partitioning, that is a conversion of

511 part of the convergence velocity into a deformation velocity. In our interpretation, this is 512 given by values of  $p_t$  equal or less than 1 (non-transparent green dots). Through the 513 extraction, it clearly appears that  $|v_{d_t}|$  increases with  $|v_{c_t}|$ , which we think is a piece of 514 evidence of a relationship between the convergence and deformation.

515

516 Next, following the proposal by earlier studies, we tested the relationship between 517 convergence obliquity  $0v_c$  and the degree of lateral partitioning on the overriding plate  $p_t$ , for transects under dominant strike-slip and with  $p_t \leq 1$  and  $v_d \geq 1$  mm/yr (Figure 10). 518 519 Again, the criterion  $p_t \leq 1$  is, in our interpretation, aims to select the areas where 520 convergence-related strain partitioning may be at play. The criterion  $v_d \ge 1$  mm/yr is meant 521 to avoid selection bias of very small deformation-rates which may not be due to 522 convergence. The first-order observation on Figure 10 is that the degree of lateral 523 partitioning is highly variable and that there is no obvious trend appearing between  $p_t$  and  $Ov_c$ , even when excluding the few cases of high  $p_t$  for very low  $Ov_c$  or very low  $p_t$  for high 524  $Ov_c$ . More in-depth analysis of Figure 10 shows that most of the regions displaying 525 convergence obliquities  $0v_c > 25^{\circ}$  (S-Kurils, N-Hikurangi, W-Aleutians, Luzon, Sumatra, 526 527 Nankai, Philippines, Muertos-Hispaniola, Venezuela, N-Colombia, Andaman) are 528 characterized by a forearc sliver migrating laterally along a transcurrent fault. Such a transcurrent faulting occurs even at small values of  $0v_{c_1}$  such as in the southern Chile just 529 530 north of the triple junction along the Liquine-Ofqui Fault Zone. On the other hand, a 531 number of overriding plates do not localize the lateral component of the deformation onto strike-slip faults, even with high convergence obliquities like Panama, Cascades or Central 532 533 Aleutians.

534

535 Interestingly, analog sandbox models demonstrated that oblique subducting ridges 536 or seamounts favored strain partitioning at the rear of accretionary wedges (Dominguez et 537 al., 1998; Lewis et al., 2004; Martinez et al., 2002). We have thus checked whether the 538 transects displayed on Figure 10 are associated with the subduction of buoyant features. 539 We found that about two third of the displayed transects are indeed associated with

prominent buoyant features including the Carnegie Ridge, Cocos Ridge, Hikurangi Plateau, 540 541 Palawan Ridge, Benham Plateau, Bahamas bank, Caribbean Plateau, Taiwan Coastal Range, 542 Gagua Ridge, Izu-Bonin Arc, Palau-Kyushu Ridge, Obruchev Rise, and Papuan Peninsula. 543 Our exercice allows us to confirm that most of the transects which exhibit a high degree of 544 partitioning are on or close to a prominent subducting high. 545 546 547 IV. Implications of our new kinematic database 548 549 IV.1. Comparison to previous studies Based on previous compilations of overriding plate deformation at present-day subduction 550 551 zones, several correlations have been highlighted. Here, we re-assess and discuss some of those correlations based on our determination of the sub-actual deformation of upper 552 553 plates. 554 555 Overriding plate strain and slab dip IV.1.1. 556 Lallemand et al., (2005) classified 159 subduction transects within three discrete-strain 557 classes (neutral, compressive, extensive) based on a qualitative assessment of focal 558 559 mechanisms in the back-arc of the overriding plate. Moreover, based on Wadati-Benioff 560 zones, they defined a shallow slab dip  $\alpha_s$  representative of a mean subduction angle 561 between the surface and a 125-km depth, and a deep slab dip  $\alpha_d$  more representative of 562 the subduction angle beyond a 125-km depth. The authors suggested a direct relationship 563 between the slab dip and the overriding plate strain. Compressive transects were found 564 for deep slab dip lower than 30° while extensive transects were mostly observed for deep-565 slab dip values higher than 50°.

566

To revise the correlations, we have re-computed the shallow and the deep slab dips, usingthe Slab2.0 model (Hayes et al., 2018), when available. To keep consistency with past works,

569 we have adopted similar definitions. For each subduction transect, the shallow slab dip  $\alpha_s$ 570 is computed by averaging the estimated dip between 10 and 125-km depths. The deep slab 571 dip  $\alpha_d$  is the average dip between 125 and 400-km depth.

572

573 We assume that our quantification of the obliquity of the deformation velocity provides a 574 continuous description of the overriding-plate strain (see section III.1) and allows for the 575 application of a linear regression analysis with slab dip. Taking all of our 213 subduction 576 transects with a defined value of  $v_d$ , we find weak correlations between the obliquity of 577 deformation and both the shallow (Figure 11a) and the deep (Figure 11b) slab dip. However, 578 excluding complex areas such as the Southeast Asia (Taiwan, Philippines, Banda Sea region, 579 Molucca Sea region, etc), the Mediterranean and the Melanesia, we find a good correlation 580 (linear correlation coefficient r = 0.58, Figure 11c) between the shallow slab dip and the 581 obliquity of deformation for the 160 transects. A few large subduction trenches, such as the Alaska-Aleutians from east to west, the Andaman-Sumatra-Java from south to north, 582 583 and Izu-Bonin-Marianas, illustrate the tendency of deformation obliquity to increase with 584 the shallow slab dip. On one hand, the transects of subduction zones that fall in the compressive class (Andean, Alaska) generally exhibit values of  $\alpha_s$  between 10° and 20°. A 585 586 few outliers in Central America (Costa Rica) and Southern Japan (Kyushu) are compressive 587 but display higher values of shallow slap dip. Those outliers may be explained by the 588 subduction of shallow bathymetric features: the Cocos ridge and the Kyushu-Palau ridge as well as the Amami-Daito-Oki-Daito massif, respectively, which may enforce compression 589 590 locally but do not lead to significant flattening of the subducting plate (Gardner et al., 2013; 591 Lallemand, 2016). On the other hand, the transects of subduction zones that fall in the 592 extensive class most often exhibit values of  $\alpha_s$  higher than 25°. Note that a few transects 593 belonging to the Nmost and Smost-Sandwich subduction trench lie in our strike-slip class 594 but this is biased by the orientation of the subduction transects relative to the direction of 595 back-arc spreading.

596 Contrary to the findings of Lallemand et al., 2005, our database suggests only a weak 597 correlation between the deep slab dip and the deformation obliquity, regardless of the

598 exclusion of complex areas (see Figure 11d). Although some tendency to increase  $Ov_d$  with 599  $\alpha_d$  is perceivable, the spread is much larger than with  $\alpha_s$ .

The relationship between the shallow slab dip and the deformation obliquity, and thus the strain regime, can be interpreted as the expression of the geometrical effect of subduction interface contact on the transmission of forces to the overriding plate and thus on its deformation. A wider plate-to-plate contact, induced by a relatively low value of  $\alpha_s$ , promotes compression while the opposite promotes extension. The mean friction coefficient along the subduction interface may modulate this geometrical effect.

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## *IV.1.2.* Overriding-plate strain and distance to the slab edge

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609 Schellart (2008a) and Schellart (2024) inferred a direct relationship between the 610 overriding plate deformation rate and the distance to the proximal subducting plate edge 611 from a compilation of geodetic and geologic 1-d (i.e. trench normal) deformation rates at 612 present-day subduction zones. Extension rates were found to be higher close to a slab edge and decrease away from the edge, while compression rates were found to follow the 613 opposite trend. Such observations were explained by analog and numerical models 614 615 showing that a mantle toroidal flow around slab edges can facilitate the slab rollback near 616 the edges while preventing rollback far from the edges, especially in wide subduction zones 617 (Schellart & Moresi, 2013; Stegman et al., 2006; Sternai et al., 2014).

618

Taking our 213 subduction transects with a defined non-zero value of  $v_d$ , we observe that the highest deformation rates (> 50 mm/yr) generally lie within the first two thousands of kms from a slab edge, regardless of the strain class (Figure 12 a,b). This observation appears to apply to all tectonic regimes, although we note slightly less scatter at low distance for dominant extensive regimes.

624

625 Restraining the analysis to major subduction zones, the general trend still holds 626 when taking the transects as a whole (Figure 12 c). However, a more detailed analysis of

the trench-normal deformation velocity  $(v_{d_n})$  region per region, gives different insights 627 628 (Figure 12d). We observe that the decrease in trench-normal extension with increasing 629 distance to the slab edge is clearly observable for the Tonga-Kermadec subduction zone, where the highest extension rates are found in the Lau Basin and decrease southward 630 631 towards the Havre Trough. This is also the case for the Ryukyus where the spreading rates decrease from west to east. On the contrary, in the Marianas-Izu-Bonin system the trench-632 633 normal extension is the highest in Central Marianas and decrease both north- and south-634 wards. For the Andaman and the Sandwich trenches, there is no obvious trend. Among the 635 settings of dominant compression, the Andes show an increase in trench-normal 636 compression rate with increasing distance to the slab edge, with the highest values 637 observed in the C-Andes (Altiplano region). Likewise trench-normal compression rates are 638 higher in C-Japan and decrease towards the Kurils. On the contrary, high compression rates 639 are observed in Alaska, close to the slab edge, and decrease west-wards towards W- and 640 C-Aleutians, where the regimes switch to dominant strike-slip. Overall, as also discussed by previous studies, our estimation of overriding-plate deformation in systems under 641 642 dominant compression and extension suggest that the model in which mantle toroidal flow 643 exerts a prime effect on surface deformation may be invoked for only certain subduction zones (Tonga-Kermadec, Ryukyus, the C-Andes), but appear inefficient for explaining the 644 645 observations in others (e.g. Marianas, Alaska-Aleutians).

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647 One of the novelties of our work is that our kinematic database permits to classify subduction zones under a dominant strike-slip regime, which differs from those in the 648 649 neutral regime. For the transects under the strike-slip class, only those which correspond 650 to regions of oceanic spreading in directions diverting from the trench normal, exhibit high 651 values of deformation within the first thousands of kms of the slab edge (e.g. Nmost-Tonga, 652 New Hebrides, Smost-Marianas, the Nmost and Smost-Sandwich). Other region in the 653 strike-slip regime, such as Andaman-Sumatra-Java, Central America, or Southern Chile, do 654 not show any trend with the distance to the slab edge. These observations suggest that

655 mantle flow (alone) is difficult to invoke to explain the lateral deformation in subduction 656 zones experiencing strike-slip dominant regime.

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# 658

## IV.1.3. Previous studies on strain partitioning

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Early studies suggest that strain partitioning at oblique subduction zones, involving the 660 661 motion of a forearc sliver, were mainly controlled by the convergence obliquity (e.g. Fitch 662 1972) and propose the existence of a threshold convergence angle above which such 663 partitioning could occur (Jarrard, 1986; McCaffrey 1992). Following later studies (Turner et 664 al., 2007; Hoffmann-Rothe, et al., 2006; Cooke et al., 2020; Morell et al., 2025), we show that 665 the idea of an obliquity threshold is questionable and that trench-parallel overriding-plate 666 deformation can occur at any value of convergence obliquity (Figure 8). We, however, 667 highlight that there is a certain tendency to increase trench-parallel deformation rate with the increase of the trench-parallel convergence velocity (Figure 9) for areas under dominant 668 669 strike-slip regime. We also show that the degree of lateral partitioning  $p_t$  shows little sensitivity to the convergence obliquity (Figure 10). It is also worth noting that, in contrast 670 671 to what was suggested by Jarrard (1986), we do not detect any specificity of intra-oceanic 672 versus sub-continental subductions in terms of degree of partitioning of deformation, which might suggest that the rheological profile of the overriding plate is not a critical 673 674 factor. Finally, as noted above, some geographical coincidence exists (2/3 of the cases) between the region undergoing a strong lateral partitioning of deformation and the 675 676 subduction of prominent bathymetric features. Overall, our statistical analysis may depict 677 a conceptual model where it is rather the "friction" along the plate interface which plays a 678 key role in defining partitioning, as previously proposed (e.g. Chemenda et al. 2000). In such 679 a conceptual model, the subduction of bathymetric features could enhance the effective 680 long-term "friction" at the interplate contact. It is however beyond the scope of the paper 681 to further assess this hypothesis and will be the focus of later works.

682

Recently, Morell et al. (2025) have specifically analyzed the arc and forearc active 683 684 deformation through computation of the vorticity of GNSS velocities, for major subduction 685 zones amounting to a total length of 24 000 km of present-day subduction zones (about 686 half of the total). A main result of their work is that a low to moderate obliquity can lead to 687 strain partitioning (see above). Furthermore, their sampled subduction zones show that the vorticity tends to increase with convergence obliquity. Our sampling of ~45 000 km of 688 689 subduction zones for which we have a constrained value of overriding-plate deformation, 690 shows a weak relationship between the convergence and the deformation obliquities, and 691 confirms that low obliquities can lead to a wide range of deformation obliquity. In addition, 692 the finding on the relationship between GNSS vorticity and convergence obliquity by Morell 693 et al., (2025) may be compared to our observation that the trench-parallel component of 694 deformation velocity tends to increase with that of the convergence velocity for our 90 695 transects under a dominant strike-slip regime with values of lateral partition coefficient below of equal to 1 (~19000 km in terms of length, non-transparent dots on Figure 9). 696 Overall, our study confirms the main conclusions of Morell et al. (2025), showing that they 697 698 also apply to other subduction zones not considered in their study.

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## *IV.2. Consequences for the revised subduction velocities*

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702 Accounting for an overriding plate deformation velocity  $v_d$ , we are able to correct 703 the convergence velocities  $v_c$  inferred from global plate models, and to assess a better 704 estimate of the rate of SP consumption at trench, that is the subduction velocity  $v_s = v_c + v_c$ 705  $v_d$ . The values of  $v_s$  impact the estimates of mass transfers in present-day subduction 706 zones, including that of volatiles (von Huene & Scholl, 1991; Lallemand et al., 2024), of the 707 thermal structure of the subducting plate via the thermal parameter (Kirby et al., 1996), 708 and of the seismic potential of the subduction megathrust (Scholz & Campos, 1995; Wirth 709 et al., 2022). Moreover, thermo-mechanical models of subduction zones often use the 710 estimations subduction velocities as input parameters, with consequence on the 711 estimations of the thermal structure of present-day subduction zones (e.g. Syracuse et al., 712 2010), that of the release-depth of volatiles (Cerpa et al., 2022a; Van Keken et al., 2011), or 713 that of the interface strength (Fraters et al., 2025). Other indirect impacts through 714 numerical modeling, would be the assessment of the dynamics of plate-mantle coupling 715 (Arcay, 2012; Turino & Holt, 2024), of the deformation of the overriding plate (Cerpa et al., 716 2018), and of the slab-dynamics in the mantle transition zone (Cerpa et al., 2022b). For obvious reasons, it is beyond the scope of this contribution, to re-assess or discuss all of 717 718 these estimates. Here, we thus made the choice to illustrate the changes induced by the 719 account of the overriding plate deformation on the thermal parameter and on the slip 720 length.

- 721
- 722 IV.2.1. Thermal parameter
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724 The thermal parameter  $\varphi$  is generally used as a first-order estimation of the slab-725 thermal structure. It has been shown to correlate with the seismogenic potential within the slab especially of intermediate-depth earthquakes (Kirby et al., 1996; Stein & Stein, 1996; 726 727 Wiens & Gilbert, 1996). Its value, expressed in km, is the product of the slab's rate of 728 descent,  $v.\sin\alpha$  in km/m.y.,  $\alpha$  being the slab's dip, and its age in millions of years. We thus 729 calculate the thermal parameter for transects that have a defined convergence/subduction 730 kinematics, slab age and slab dip (Figures 13a,b). Note that for the slab dip, we use the average of  $\alpha_s$  and  $\alpha_d$ , and we take the trench-normal components of velocities. We also 731 compute the difference between the thermal parameter calculated using  $v_{c_n}$  and that using 732  $v_{s_{m}}$  (Figures 13c). Different values of the thermal parameters are reached for 155 of our 733 734 transects (where  $v_{d_n} \neq 0$ ).

735

The most striking differences between the calculations of the thermal parameter are for the transects undergoing moderate to fast back-arc spreading, such as in Tonga, the Marianas and the Aegean where the thermal parameter increase by a factor of two to three if we use  $v_{s_n}$  instead of  $v_{c_n}$ . For the Sandwich transects, the difference is up to an order of magnitude. In addition, transects that undergo an important compression deformation

rate, such as those in N-New-Hebrides or those where the overriding plate deformation 741 742 represents a retro-subduction zone (Timor, Philippines), also lead to important 743 deformation rates and thus relatively important decrease in the estimations of the thermal 744 parameter if one uses  $v_{s_n}$ . Overall, comparing the two possibilities for estimating the 745 thermal parameter, we find that approximately in 70% of the cases the change in thermal parameter are of absolute values of 10<sup>3</sup> km or less. In 10% of cases the absolute difference 746 is between  $10^3$  and  $2 \times 10^3$  km, , among which ~70% and ~35% are under dominant 747 extension and strike-slip, respectively. In 10% of cases between 2×10<sup>3</sup> and 3×10<sup>3</sup>, among 748 749 which ~70% and ~20% are under dominant extension and strike-slip, respectively. In the 750 remaining 10% of cases the absolute difference is between  $3 \times 10^3$  km and up to  $9 \times 10^3$  km, 751 with 80% and 20% of transects being under dominant extension and strike-slip, 752 respectively. The latter cases are mostly transects undergoing fast back-arc spreading.

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- 754 IV.2.2. Slip length
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For a given seismogenic zone width, the slip length on the megathrust is ideally determined by the angle at which the subducting plate actually enters the trench, that is  $O_{vs}$ . When  $O_{vc} \simeq O_{vs}$  estimating the slip length using global plate circuit models is a reasonable approach. However, in the case of important strain-partitioning and, for instance, activation of slip on a strike-slip fault, a reduction in the slip length on the seismogenic interface is expected.

Using our up-to-date kinematic database, we can compare the estimations of slip length using the convergence  $L_{vc}$  and that using the subduction velocity  $L_{vs}$ . Figure 14 shows areas where the reduction in slip length due to arc blocks deformation exceeds 10%, and reaches in extreme cases (New Britain, Andaman) as much as 80-90%. These sectors represent 16.5% of subduction zone transects, two-third of which were not covered by MORVEL56 (underlined transects in Figure 14). As an example, the Smost section of the Ryukyu subduction zone deforms in a way that the slip length across the seismogenic zone is 769 decreased by more than 60%. This reduction reaches 20% in the Nankai trough, 35% in W770 Aleutians, 10 to 30% in Central-Aleutians or 10 to 15% in Sumatra.

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## 773 V. Conclusion and perspective

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775 We have built a new database of overriding-plate deformation in present-day subduction zones, consistently based on geodetic data. Our kinematic description of overriding-plate 776 777 deformation, through the motion of an "arc block" relative to an undeformed upper plate, 778 permits to characterize both the trench-normal and the trench-parallel components of 779 deformation. Our analysis confirms that the obliquity of convergence generally leads to a lateral (quasi-trench parallel) deformation in the overriding plate, which we interpret as the 780 781 evidence of a lateral shear component on the subduction interface. However, we 782 demonstrate that there is not a straightforward relationship between the convergence 783 obliquity and the degree of (lateral) strain partitioning. Other subduction characteristics, 784 such as the subduction of large oceanic reliefs may largely contribute to shear on the 785 interface and thus trigger lateral deformation in the overriding plate. Furthermore, 786 although there are a few counter-examples, we also confirm the trend that the dip of a 787 slab, especially for depths lesser than 125 km, correlates with the deformation regime of 788 the overriding plate (low values of slab dip leading to compression, high values to 789 extension, and intermediate to strike-slip).

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Finally, our estimations of overriding plate deformation permit an enhancement of the estimation of subducting-plate consumption rates at the trenches, relative to studies using instead estimations based on far-field (convergence) relative velocities. This has implications for the predictions of mass transfers from the surface to the mantle, the thermal structure of the slab, the shear on the subduction interface, or seismic coupling, insofar as the slip along the subduction interface predicted by kinematics is compared withseismic slip.

799

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805

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- 813 Visualization N. Cerpa, S. Lallemand
- 814

## 815 Data availability

- 816 Our database will be made available through our webtool submap (www.submap.fr).
- 817

## 818 Conflict interests

819 The authors declare no competing interests.31



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**Figure 1**: Conventions used in the geometrical and kinematical description of the subduction transects in the Submap database. UP = upper plate, AB = arc block, SP = subducting plate,  $v_c$ : convergence velocity,  $v_s$ : subduction velocity,  $v_d$ : deformation velocity. The indices n and t denote the normal and tangential components, respectively, of the vectors.  $O_{vx}$  stands for the obliquity and  $A_z v_x$  for azimuth of the velocities.



831 Figure 2: Major plates and arc blocks in the Southeast-Asia region (a) and schematic 832 illustration of two ways of assessing the AB motion (b,c). Thick blue lines represent the 833 contours of the major plates from MORVEL56 which are used to define our SP and UP. 834 Dark-blue filled regions represent the AB from MORVEL56. Light-blue filled regions 835 represent the AB that we introduce from published studies. Red-patches represent the regions where we found single GPS velocities (no-block motion defined) and which we have 836 837 used to either estimate  $v_d$  (pseudo-rigid blocks). In few cases,  $v_c$  is undefined but  $v_s$  can be estimated from GPS stations (red stripes). The abbreviations of plates and block names are 838 listed in Table 1. Blue-stripe areas indicate regions where geological-evidence of 839 deformation exists but where we have not found geodetic data to characterize the 840 841 deformation. We thus assume  $v_s = v_c$ . The gray straight lines represent the subduction transects used in our study (i.e. the submap transects). Black dashed lines are the 842 843 subduction trenches

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Figure 3 Maps with all AB and deformed regions accounted for in our kinematic database
(a- Mediterranean and Makran, b- Southeast Asia, c- Southwest Pacific, d- North Pacific, eCentral & South America, Caribbeans & South-Sandwich.). See Figure 2 for legend details.



**Figure 4**. Maps of the deformation velocity vector  $v_d$  represented at the intersection between the subducction transects and the inner boundaries of the arc blocks, and colored by the magnitude and the associated strain regime. The top-left diagram illustrates the classes of strain (dominant) regimes defined as a function of the directed obliquity  $\bar{o}_{v_d}$ between the trench-normal and  $v_d$ .





**Figure 5**. Schematic global view of the strain classes determined in our study with their distribution (piechart). The symbolic representation of overriding-plate deformation is positioned at the boundary between AB and UP. Note that our representation is intentionally schematic and is not intended to always represent actual geological structures. The azimuth of some faults may therefore not correspond to that obserserved on the field.



**Figure 6**. Distribution of overriding plate deformation rates determined for all transect of the Submap database. a) magnitude of deformation velocity  $v_d$ , b) normal component  $v_{d_n}$  of deformation velocity, tangential component  $v_{d_t}$  of the deformation velocity





**Figure 7**. Ratios of the components of overriding plate deformation velocities to the components of the convergence velocities. Other legend details are as in Figure 6.



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**Figure 8**. Obliquity of the convergence between major subducting (SP) and upper (UP) plates against the obliquity of deformation for 213 transects with non-null vd. The transects are colored following their Ovd-based tectonic regimes (blue for extension, green for strikeslip and red for compression). The shaded quadrants highlight cases of opposite signs of obliquities, i.e., the transects for which the convergence obliquity fails to explain the deformation obliquity. The regions for which  $|Ov_c| > 90^\circ$  (dotted black line) are also shaded.



Figure 9. Tangential component of the deformation velocity as a function of the tangential component of the convergence velocity for all transects in the dominant strike-slip regime. The non-transparent green dots are those for which the magnitude of deformation velocity is higher than 1 mm/yr, which have a lateral partition coefficient equal or less than 1, and which have consistent directions of the tangential components of both velocities. Semi-transparent green dots denote all the remaining transects under the dominant strike-slip strain regime.



**Figure 10**. Lateral partition coefficient  $p_t$  as a function of convergence obliquity  $Ov_c$  for subduction transects under a dominant strike-slip strain class.



**Figure 11**. Obliquity of the deformation velocity with shallow (0 to 125 km depth ; left) and deep (125 to 400 km ; right) slap dip for all (top) and selected major (bottom) subduction zones. Sam:South America, CAm:Central America, Anti:Lesser Antilles, Sandw:Sandiwch, Casc: Cascadia, Ala-Aleut:Alaska-Aleutians, Kam-Kur-Jap:Kamchatcka-Kurils-Japan, Ryu-Nan:Ryukyus-Nankai, IBM:Izu-Bonin-Marianas, Ton-Ker:Tonga-Kermadec, And-Sum-Jav:Andaman-Sumatra-Java.



**Figure 12**. Overriding-plate deformation velocity with distance to the edge of the trench. Left column (a,c) is for total velocity and right column (b,d) for only the trench-normal component. Top rows (a,b) display the values for all 213 subduction transects with definite non-zero values of  $v_d$  and the bottom row (c,d) that of 141 transects corresponding to selected subduction zones.



- 912 (b), as well as their difference (c).



**Figure 14**. Slip length reduction expected along the subduction (seismogenic) interface using our estimated values of  $v_s$ . Transect-names in bold correspond to the transects for which we have added constraints on overriding-plate deformation beyond the MORVEL56 model.

AB types	Short names			Number of		
(constrained vd)	incl. aggregates	AB names	Sources	ABs		
	(+)	0//1070/	A			
	ок	PANAMA	Argus et al. (2011) Argus et al. (2011)			
	ap	ALTIPLANO	Argus et al. (2011)			
	SW	SANDWICH	Argus et al. (2011)			
	bu	BURMA	Argus et al. (2011)			
M56 blocks	on	OKINAWA	Argus et al. (2011)	11		
	ma	MARIANA SOUTH RISMARCK	Argus et al. (2011)			
	nb	NORTH BISMARCK	Argus et al. (2011)			
	to	TONGA	Argus et al. (2011)			
	ke	KERMADEC	Argus et al. (2011)			
		WESTERN PELOPONNESE	Vemant et al. (2014)			
		AEGEAN SEA	Vemant et al. (2014)			
	aeg+	RHODES	Vemant et al. (2014)			
		ISPARTA	Vemant et al. (2014)			
	lut	шт	Reilinger et al. (2006)			
		PENINSULA	Elliot and Freymueller (2020)			
	alat	KODIAK	Elliot and Freymueller (2020)			
	0107	PRINCE WILLIAM SOUND	Elliot and Freymueller (2020)			
		ICY BAY	Elliot and Freymueller (2020)			
	sme	SOUTHERN MEXICO	Andreani et al., (2008)			
	caf	CENTRAL AMERICAN FOREARC	Carvajal-Soto et al., (2020)			
		BONAIRE	Jarrin et al. (2023)			
		SAN JACINTO	Jarrin et al. (2023)			
	nan+	ROMERAL	Jarrin et al. (2023)			
		NORTH ANDEAN WEST	Jarrin et al. (2023)			
additional rigid		PERUVIAN FOREARC WEST	Jarrin et al. (2023)			
blocks (our	hict	HISPANIOLA	Calais et al. (2023)			
compilation)	11134		Calais et al. (2023)			
compliation	per	PERU	Villenas-Lanza et al. (2016)	35		
	can	CENTRAL ANDES	Brooks et al. (2003)			
	suf	SUMATRA FOREARC	Bradlev et al. (2017)			
		WEST JAVA	Koulali et al. (2017)			
	jav+	EAST JAVA	Koulali et al. (2016)			
	smb	SUMBA	Koulali et al. (2016)			
	tim	TIMOR	Koulali et al. (2016)			
	yon	YONAGUN	Chen et al. (2022)			
	chi±	SHIKOKU	Nishimura et al. (2018)			
	51117	CHUBU	Nishimura et al. (2018)			
	kan+	IZU	Nishimura (2011)			
		KANTO	Nishimura (2011)			
	izu	IZU BONIN ARC	Nishimura (2011)			
		NORTH NEW-HEBRIDES	Bergeot et al. (2009)			
	nne+	CENTRAL NEW-HEBRIDES	Bergeot et al. (2009)			
	esh	DEE CALAPPIAN APC	Sergeot et al. (2009)			
	dku	DEF_KURIL FORFARC	Demets (1992)			
	dko	DEF_KOMANDORSKY FOREARC	Cross and Freymueller (2008)			
		DEF_VANCOUVER ISLAND	Mazzotti et al. (2003)			
	dor+	DEF_OREGON	Mazzotti et al. (2002)			
additional deformed	dja	DEF_JALISCO	Selvans et al. (2010)			
areas (vd based on	dsa	DEF_SOUTH ANDES	Wang et al., (2007)	14		
GPS stations, our	des	DEF_SERAM	Rangin et al. (1999)			
compilation)	dns+	DEF_MANADO	Socquet et al. (2006)			
	UIDT	DEF_NORTH SULA	Socquet et al. (2006)			
	dep	DEF_EAST PHILIPPINES	Rangin et al. (1999)			
	dlu	DEF_LUZON	Hsu YJ (pers. comm. 2023)			
	dvi	DEF_VISAYAS	Simons et al. (2007)			
	dta	DEF_TAIWAN	Hsu YJ (pers. comm. 2023)			
Total 60						

921 **Table 1**: List of "arc blocks", including the short names as they appear in Figures 2 and 3.

922 The symbol "+" stands for cases where we have merged together several blocks into a single 923 one on the figures.

AB types (unconstrained vd)	Short names incl. aggregates (+)	AB names	Sources	number of ABs
deformed areas with GPS- derived vs and undefined vc (our compilation)	udha udsa udsp udsu	Undef_Halmahera Arc Undef_Sangihe Arc Undef_South Philippines Undef_Sulu Arc	Rangin et al. (1999) Rangin et al. (1999) Rangin et al. (1999) Simons et al. (2007)	//,4′///
deformed areas with M56- derived vc and used as a proxy for vs, assuming vd to be small (our compilation)	udka udcc udpa udsm udnp udso+ udso+ udso	UNDEF_KAMCHATKA UNDEF_CENTRAL CHILE UNDEF_SOUTH PATAGONIA UNDEF_SOUTH MARIANA UNDEF_NORTH PHILIPPINES UNDEF_SOLOMONS UNDEF_SOLOMONS UNDEF_SANTA-CRUZ UNDEF_MATTHEW ISLAND UNDEF_PUYSEGUR		'//, 9 <i>'///</i>
Total	·			13

**Table 2**: List of complementary areas where we have derived subduction velocities without anyconstraints on the deformation velocity.

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