

1 This manuscript is a copy of a peer-reviewed article published in *The Seismic Record*

2 <https://doi.org/10.1785/0320250024>

3 **Title:** Curved fault slip captured by CCTV video during the 2025 Mw 7.7
4 Myanmar earthquake.

5 **Authors:** Jesse Kearse¹ and Yoshihiro Kaneko¹

6 ¹Graduate School of Science, Kyoto University, Japan.

7 July 19, 2025

8 **Corresponding author:** Jesse Kearse

9 **Email:** jesse@kearse.co.nz

10 Department of Geophysics

11 Graduate School of Science, Kyoto University

12 Postal Code: 606-8502

13 Kitashirakawa, Oiwake-cho, Sakyo-ku, Kyoto, Japan

14 **Abstract**

15 On-fault geological observations from surface breaking earthquakes typically contain curved
16 slickenlines, suggesting fault slip is curved. However, slickenlines commonly record only a
17 fraction of coseismic slip, making it difficult to reconstruct the full slip trajectory. Near-fault
18 seismic records, though capable of capturing ground motions associated with rupture, are
19 limited in their ability to constrain on-fault slip direction as they record motion on only one
20 side of the fault. Here, we overcome these challenges by directly observing fault slip using
21 video footage of the 2025 Mw 7.7 Mandalay (Myanmar) strike-slip earthquake. We use pixel
22 cross correlation to track features in successive frames of the video, revealing a pulse of fault
23 slip with a magnitude of 2.5 ± 0.5 m, duration of 1.3 ± 0.2 s, and peak velocity of 3.2 ± 1.0
24 m/s. The observed trajectory is notably curved, and includes a transient (0.3 m) dip slip
25 component on a steeply dipping strike-slip fault. These observations are consistent with
26 geological records of curved slickenlines supporting mechanical models that link rupture
27 propagation direction to near-surface slip curvature. Our results provide the first direct
28 visual evidence of curved coseismic fault slip, bridging a critical gap among seismological
29 observations, geological data, and theoretical models.

30 Introduction

31 Resolving the dynamics of fault slip during large earthquake ruptures is a major challenge
32 in earthquake science. On-fault geological data represent a valuable archive of slip in surface
33 breaking earthquakes, recorded as slickenlines embedded into the fault plane itself (Spu-
34 dich et al., 1998; Kearse et al., 2019; Barth et al., 2024). Slickenlines are typically curved
35 (Kearse and Kaneko, 2020), suggesting fault motions evolve dynamically during seismic slip.
36 However, inferring the full coseismic slip trajectory from slickenlines is challenging, as they
37 typically record only a fraction of slip, or may form a complex network of overlapping stria-
38 tions (Kearse and Kaneko, 2020; Little et al., 2025). Because these observations are typically
39 made days after the event, there is inherent uncertainty about the influence of non-seismic
40 sources of slickenline formation, such as postseismic slip, or gravity-driven movement within
41 the unstable ground surface rupture zone, limiting their potential to capture the dynamics
42 of seismic slip.

43 Another approach to resolving the rate and direction of slip during earthquake rupture
44 involves using near-field instrumental records—such as strong-motion seismometers or high-
45 rate GNSS—since ground motions within a few kilometers of the fault are dominated by the
46 direct effects of fault slip (the so-called near-field terms) (Bouchon et al., 2000; Kearse et al.,
47 2024). However, due to their off-fault location, it is unclear to what extent these records are
48 contaminated by free surface effects, and whether they are able to resolve the cohesive zone
49 of the propagating rupture (Cruz-Atienza et al., 2009). Furthermore, because instruments
50 are typically located on only one side of the fault, reconstructing the relative motion between
51 both sides is not straightforward.

52 In this paper, we overcome these challenges using CCTV video footage of ground surface
53 rupture during the 2025 moment magnitude (M_w) 7.7 Mandalay earthquake (Myanmar),
54 which provides the first direct observation of surface fault slip in real time. We track objects

55 by pixel cross correlation in successive frames of the video to measure the rate and direction
56 of fault motion during coseismic slip. Our observations show that slip near the ground
57 surface is distinctly curved. We demonstrate that these new observations are consistent with
58 previous reports of curved slickenlines and recent models of dynamic rupture propagation,
59 and discuss how these data provide an important link between physics-based earthquake
60 simulations, on-fault geological data, and near-fault observations of strong ground motion.

61 **Video analysis of the Mandalay earthquake**

62 The Mw 7.7 2025 Mandalay earthquake occurred on March 28, with a hypocenter 20 km west
63 of Mandalay city, Myanmar at a depth 10 km (USGS, 2025). The hypocenter location and
64 right-lateral strike-slip mechanism are consistent with rupture on the Sagaing Fault, a major
65 north-striking structure accommodating right-lateral shear between the Burma Plate to the
66 west and Sundaland to the east (Vigny et al., 2003). The earthquake lasted approximately 90
67 seconds (Inoue et al., 2025), and propagated both north and south with total rupture length
68 exceeding 400 km and surface strike slip exceeding 6 m (Fig. 1). Due to the exceptionally
69 long rupture, strong ground shaking of Modified Mercalli Intensity (MMI) X extended over a
70 broad area causing widespread damage to homes, sites of historical and cultural significance,
71 and to key infrastructure in Myanmar, resulting in 3600 confirmed fatalities (Witze, 2025).

72 At the time of the earthquake, a CCTV security camera was recording video at the trace
73 of the Sagaing Fault, 120 km south of earthquake hypocenter (Fig. 1). The camera was
74 positioned approximately 20 m to the east of the Sagaing Fault, and was facing southwest
75 across the Fault (Figs. 1b and 1c). The remarkable footage clearly shows relative northward
76 translation of the western side of the fault during coseismic slip on the Sagaing Fault, which
77 lasted approximately 2 seconds, and was accompanied by the simultaneous formation of a
78 1-2 meter wide moletrack along the surface rupture trace.

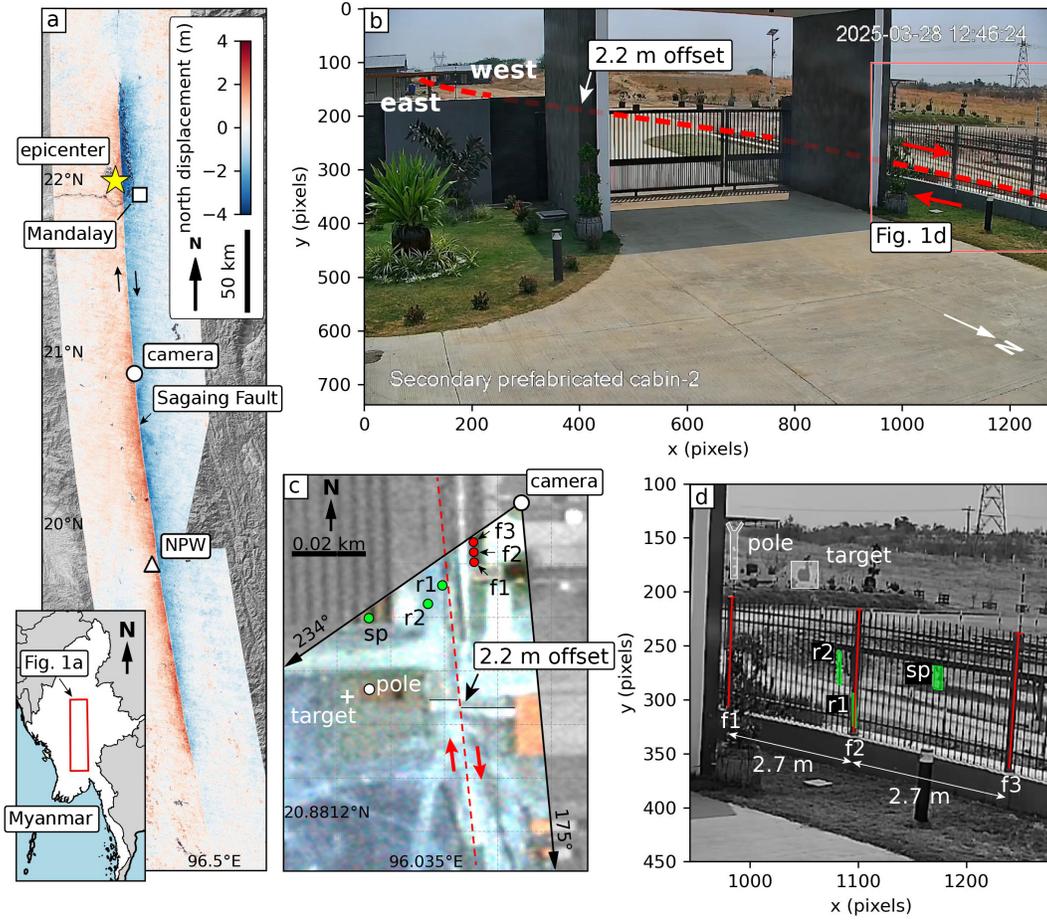


Figure 1: (a) Map of Myanmar (inset) and the Mandalay earthquake. Red and blue colors show the coseismic surface displacement field derived from sentinel-2 images taken before and after the earthquake from Van Wyk De Vries (2025). Location of CCTV camera and strong motion station NPW are shown. (b) Frame 1 of video (before rupture arrives) showing the field of view captured by the CCTV camera. Dashed red line shows the location of the Sagaing Fault rupture. Offset path is obscured behind the gate structure in the foreground. (c) Planet labs satellite image with a 0.5 m resolution taken after the earthquake (2025-04-05). Features observable in (d) are labeled. Colorized area corresponds to the field of view of the video frames in (b). f1-f3 denote fence posts located on the east side of the fault and used to calibrate coseismic displacements. r1, r2, sp, and pole, are objects that are displaced by fault motion. White cross labeled "target" shows the location of features tracked using image cross correlation. (d) Enlarged subset of the video frame showing the locations of the objects in pixel coordinates.

79 We use a windowed pixel cross correlation approach to measure the accrual of slip across
80 the Sagaing Fault from the first frame of the video (Fig. 2a) to the last frame (Fig. 2b).
81 To track displacements on the west side of the fault, we define 25 overlapping 26x26-pixel
82 subsets of the image each containing objects located 70 – 80 m from the camera. Our
83 analysis is based primarily on the subset that produced the sharpest cross correlation results
84 ("target", Fig. 2a), however, our results are consistent across all subsets analyzed. We also
85 track features on the eastern side of the fault, the same side as the camera (e.g., "noise",
86 Fig. 2a).

87 Figure 2c shows the displacement timeseries of tracked features relative to the image frame
88 over the duration of the video. Ground shaking commences at 9.5 ± 0.1 s characterized by
89 coherent motion of both features (target and noise), and is followed by stronger shaking at
90 12 ± 0.1 s. The displacement timeseries of the target begins to diverge from the noise at
91 14.1 ± 0.1 s approximately 5 s after the first arrivals. Later at 15.4 ± 0.1 s both features resume
92 their coherent, time-synchronized displacements, which continues until the last frame of the
93 record. During this 1.3-second interval, the largest pixel displacements are observed for the
94 target: +33 pixels in the positive x-direction and -13 pixels in the negative y-direction. In
95 contrast, the feature on the near side of the fault shows relatively minor displacements: -1
96 pixel in x and -7 pixels in y.

97 To estimate the timeseries of slip across the Sagaing Fault, we follow a workflow to convert
98 from pixel displacement to meters on the Sagaing Fault plane (Fig. S1, available in the
99 electronic supplement to this article). First, we subtract the displacement timeseries of the
100 noise from the target (Fig. 2c). This removes noise introduced by wobbling and tilting of the
101 camera during ground shaking. Next, we use fence posts of known spacing and orientation
102 (while accounting for lens distortion and parallax) to estimate displacements in units of
103 meters at the target location (Figs. S3 and S4). By projecting the displacements along the
104 fault parallel direction estimated from post-earthquake satellite imagery, we obtain the strike-

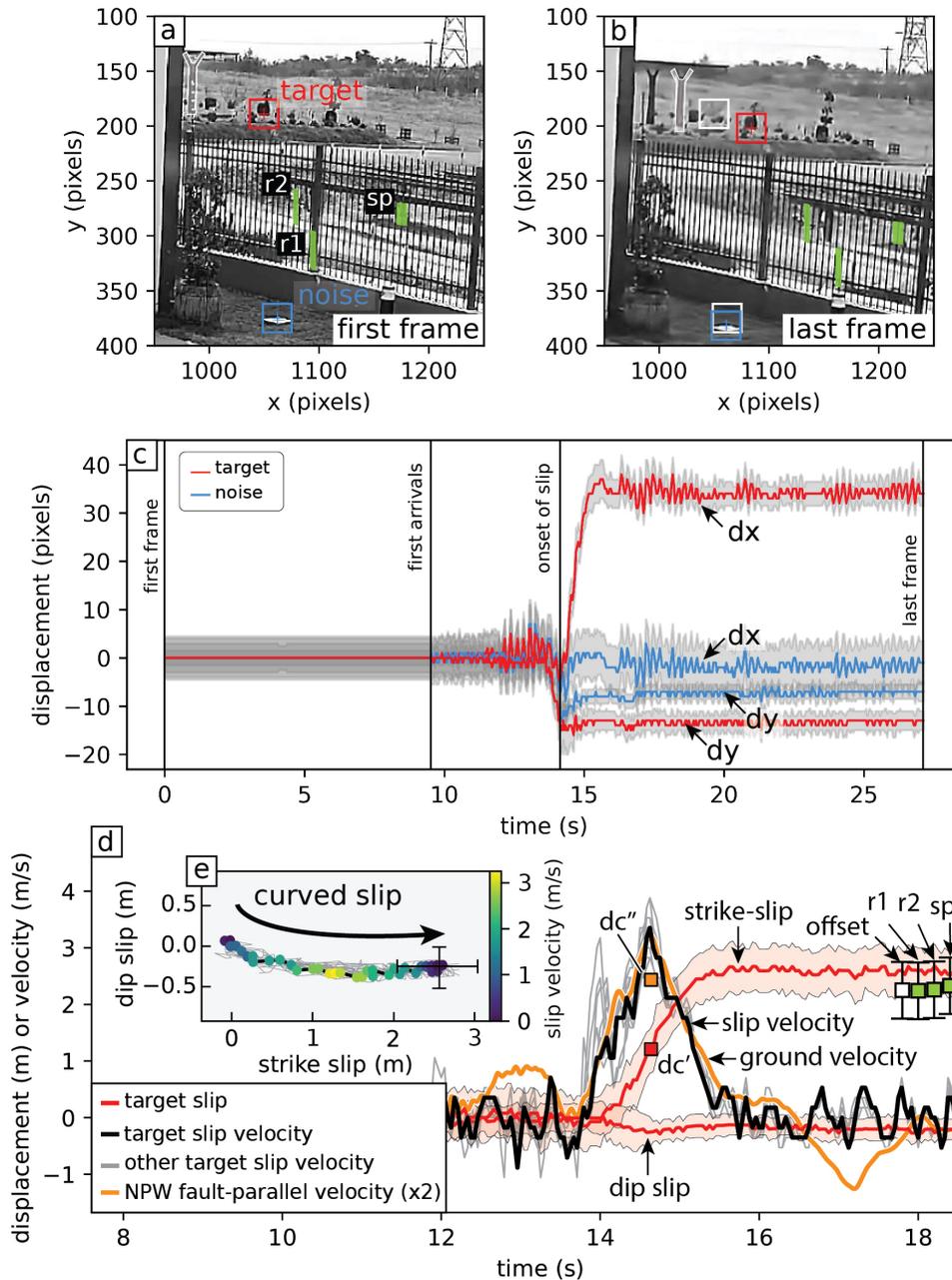


Figure 2: First frame (a) and last frame (b) of the CCTV video. Red box labeled "target" shows the 26-pixel window used to track displacements on the west (far) side of the Sagaing Fault, and on the east (near) side of the fault to correct for camera motion (blue box labeled "noise"). White boxes show the original pixel location of the target and noise in the first frame of the CCTV video. Location of roadside posts (r1, r2) and solar panel (sp) are shown. (c) Timeseries of pixel displacements as measured by pixel cross correlation of target (red) and noise (blue), y displacements are inverted such that positive y displacement represents positive vertical movement within the image. (d) Timeseries of fault slip (red) and horizontal slip velocity (black). Dip slip assumes that the Sagaing Fault is vertical. Grey velocity curves show the results of additional targets for comparison. Fault parallel offset of the footpath is shown for comparison, as well as total slip measured for r1, r2, and sp (green squares). Amplitude of fault-parallel ground velocity at NPW (orange) is doubled to compare with slip velocity. Slip weakening distance derived from on-fault slip velocity (dc') and off-fault ground velocity (dc''). (e) Curved fault slip trajectory colored by slip velocity. Curvature occurs at the beginning of slip before slip reaches maximum velocity and slip $< dc'$. Dip slip assumes that the Sagaing Fault is vertical.

105 slip and dip-slip components of relative fault motion (Fig. S6). To obtain the slip velocity
106 function, we differentiate the displacement timeseries and apply a 0.2 s moving average to
107 suppress artifacts introduced by the discrete digital sampling (24 fps). Uncertainties in the
108 measured pixel displacements are calculated at each frame from the sharpness of the 2D
109 cross correlation function (Fig. S2, available in the electronic supplement to this article) and
110 are carried forward into uncertainties in fault slip using the same workflow.

111 Coseismic slip of the Sagaing Fault

112 Our analysis reveals coseismic slip across the Sagaing Fault as a smooth ramp-like slip
113 function with an amplitude of 2.5 ± 0.5 m and duration of 1.3 ± 0.2 s (Fig. 2d). Down-to-
114 the-west dip-slip displacement reaches a maximum of 0.3 ± 0.25 m only 0.5 s after the onset
115 of slip, and subsequently reducing to 0.2 ± 0.25 m. The magnitude of net slip agrees well with
116 the post-earthquake satellite observation of a discrete footpath offset of 2.2 ± 0.5 m (e.g.,
117 Fig. 1c). We calculated additional displacements of 2.2 ± 0.5 m, 2.2 ± 0.5 m, 2.3 ± 0.5 m for
118 three objects located on the western side of the Sagaing Fault at distances of 5, 10, and 35
119 m from the fault trace, respectively (r1, r2, sp, Fig. 2d). The slight increase in fault-parallel
120 displacement amplitude (from 2.2 to 2.5 m) with distance from the fault (0 - 35 m) aligns
121 with previous field observations of on- and off-fault coseismic strain associated with other
122 large strike-slip ruptures (Rockwell et al., 2002; Kearse et al., 2018).

123 Slip on Sagaing Fault reaches a peak rate of 3.2 ± 1 m/s at 14.6 ± 0.1 s, exhibiting a
124 slightly asymmetric slip velocity envelope characterized by a longer deceleration tail (0.8
125 s) relative to the initial acceleration phase (0.5 s). For comparison, slip velocities derived
126 from tracking additional targets are also shown (gray velocity curves, Fig. 2d), and exhibit
127 similarly shaped velocity envelopes. The coseismic slip trajectory of the Sagaing Fault is
128 dominated by right-lateral strike slip, and contains a non-zero time-dependent component
129 of vertical slip resulting in slip curvature (Fig. 2e). The first meter of slip accumulation is

130 oblique (maximum rake of 35°), containing a component of down-to-the-west motion across
131 the fault. This corresponds to the initial 0.5 s of the rupture as slip velocity is increasing.
132 The subsequent 1.5 m of slip is characterized by nearly pure strike-slip, corresponding to the
133 final 0.8 s of rupture as slip velocity decreases and fault slip is arrested.

134 Our analysis demonstrates that the net slip direction is approximately horizontal, consis-
135 tent with strike-slip motion. However, due to the inherent non-uniqueness in transforming
136 pixel displacements into real-world coordinates, the exact orientation of the net slip vec-
137 tor cannot be precisely resolved. Despite this limitation, the consistent curvature observed
138 across multiple slip trajectories suggests that this feature is robust and independent of the
139 precise slip direction.

140 Discussion and Conclusions

141 This video record provides the first direct observations of seismic fault slip in a natural
142 earthquake. The observed slip duration (rise time of 1.3 s) and high slip velocity (>3 m/s)
143 offer clear evidence of pulse-like rupture propagation at the site. While pulse-like rupture
144 is commonly observed in large earthquakes (e.g., Melgar and Hayes, 2017), the mechanisms
145 responsible for slip arrest remain debated. Proposed explanations include self-healing of slip
146 governed by velocity-dependent friction (Heaton, 1990), or stopping phases generated either
147 at fault strength barriers (Beroza and Mikumo, 1996), fault edges (Day, 1982), or within the
148 fault damage zone (Huang and Ampuero, 2011). Stopping phases originating from the base
149 of the fault are anticipated for elongated strike-slip ruptures that saturate the seismogenic
150 width—conditions that are clearly met by the 2025 rupture of the Sagaing Fault. Modeling
151 of rupture dynamics may provide some insight on this, but is beyond the scope of this paper.

152 Previously, on-fault evidence for time-varying slip direction has come primarily from
153 curved slickenlines observed on exhumed fault planes. While suggestive of dynamic processes,

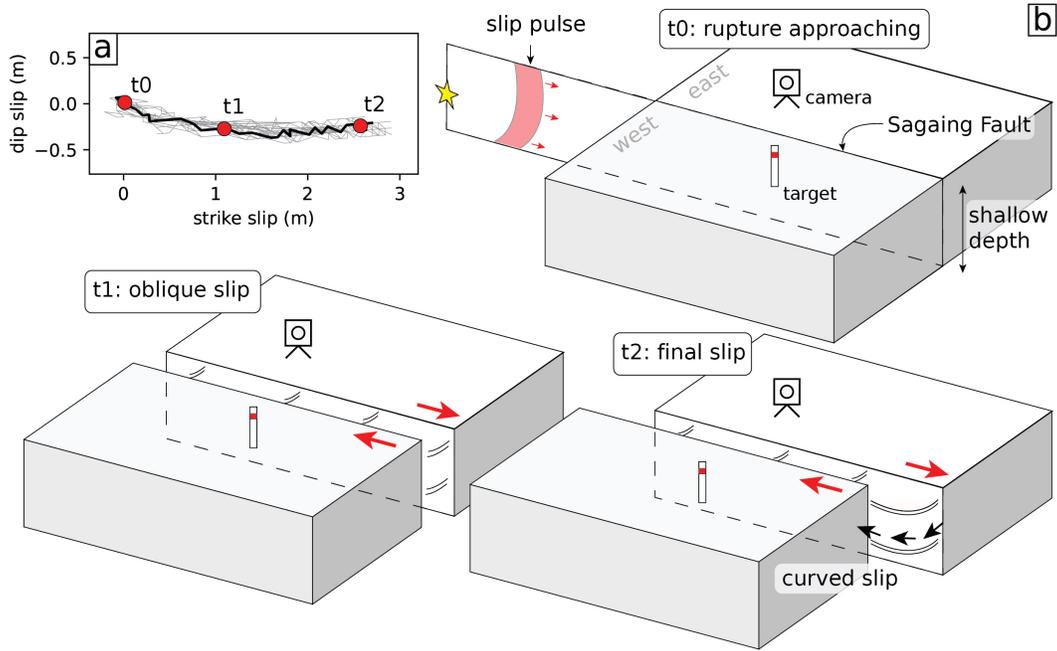


Figure 3: Cartoon illustrating coseismic slip evolution on the Sagaing Fault during the 2025 Mandalay earthquake. (a) Slip path of the Sagaing Fault during the earthquake showing three key time intervals corresponding to snapshots shown in (b). (b) Schematic snapshots of slip evolution as the rupture front approaches the CCTV observation site from the north: at initial seismic wave arrival (t_0), during early slip acceleration with an oblique trajectory including a down-to-the-west component (t_1), and after slip arrest (t_2). Black curves on the fault plane depict the slip path that would be recorded by slickenlines.

154 such geological observations lack a direct temporal context, limiting their ability to resolve
155 rupture dynamics. This study presents the first direct observation of curved fault slip,
156 providing real-time validation that curved slickenlines can form during seismic rupture (Fig.
157 3). The geometry of the curved slip trajectory on the Sagaing Fault is consistent with curved
158 slickenlines observed in other large strike-slip ruptures, such as the 2016 Mw 7.8 Kaikoura
159 earthquake, New Zealand (Kearse et al., 2019). During rupture of the Kekerengu Fault in
160 2016, slip was initially oblique and subsequently curved to become dominantly strike-slip,
161 forming a curved slip trajectory that closely resembles that of the Sagaing Fault in 2025.

162 A key result of our analysis is the observation that slip on the Sagaing Fault curves rapidly
163 during the acceleration phase, but remains linear as slip decelerates (Fig. 2e), a relationship
164 that was not resolvable using geological data alone. This type of dynamic behavior during
165 slip onset is a feature observed across a suite of dynamic rupture simulations (Kaneko et al.,
166 2008; Kearse and Kaneko, 2020). These models suggest a mechanism for slip curvature
167 that is controlled by the dynamic stresses within the cohesive zone of the rupture, which is
168 dependent on the direction of rupture propagation. The curvature of slip on the Sagaing Fault
169 as the 2025 Mandalay earthquake rupture propagated southward past the CCTV camera is
170 consistent with these models, which predict transient uplift of the side of the fault moving
171 in the direction of rupture propagation (east side of the Sagaing Fault moves south and up),
172 relative to the other side of the fault.

173 Fault-parallel velocity pulses in near-fault strong-motion records have been used to esti-
174 mate the slip-weakening distance (d_c) on the nearby fault plane during rupture (Fukuyama
175 and Mikumo, 2007; Kaneko et al., 2017; Kearse et al., 2024). However, this approach lacks
176 direct on-fault observations of slip velocity, which are needed to validate the methods, and
177 to quantify the influence of off-fault free surface effects. This study provides the first op-
178 portunity to compare on-fault slip velocity and off-fault ground velocity at a strong-motion
179 station during the same earthquake rupture, and to compare estimates of slip-weakening

180 distances between the two. The strong motion station NPW (Lai et al., 2025) is located 2.7
181 km from the Sagaing Fault and 130 km further south along strike from the location of this
182 study (i.e. the rupture first arrived at the CCTV camera, and later at NPW). Figure 2d
183 displays the un-filtered fault-parallel component of ground velocity at NPW, but with its
184 amplitude doubled to allow a more direct comparison with the on-fault slip velocity function.
185 Both records show remarkable agreement, with similar amplitude, duration, and shape of
186 the velocity function. This suggests that ground motions recorded at NPW likely reflect the
187 off-fault signature of a pulse of slip on the nearby Sagaing Fault during the 2025 Mandalay
188 earthquake. This comparison supports the use of near-fault ground velocity records to con-
189 strain key rupture parameters—such as local rise time and peak slip velocity—to first order.
190 These quantities are often difficult to uniquely resolve with conventional kinematic inversion
191 techniques (Gutteri and Spudich, 2000; Konca Ozgun et al., 2013). Slip-weakening distance
192 estimated using the method of Fukuyama and Mikumo (2007) with the strong-motion data
193 ($dc'' = 2.4$ m) is notably larger than that inferred from on-fault observations ($dc' = 1.2$
194 m) (Fig. S7). This discrepancy likely reflects the added complexity in the ground velocity
195 time series at NPW, including challenges in isolating direct fault-slip phases from secondary
196 free-surface effects (e.g., Yao and Yang, 2025).

197 Overall, these observations establish a new benchmark for understanding dynamic rup-
198 ture processes. They offer real-time confirmation that curved slickenlines can form during
199 seismic slip, reinforce model-based interpretations of slip curvature governed by rupture dy-
200 namics, and validate near-fault ground motion records as reliable proxies for on-fault slip
201 behavior. Together, these findings impose critical observational constraints on future rup-
202 ture simulations and deepen our understanding of the physical mechanisms that control rapid
203 fault slip during large earthquakes.

204 Data and Resources

205 Video used in this study is available at <https://www.youtube.com/watch?v=77ubC4bcgRM>
206 (last accessed on June 10, 2025). Normalized cross-correlation was performed using MAT-
207 LAB’s built-in `normxcorr2` function (R2024a, The MathWorks, Inc.). Coseismic displace-
208 ments derived from Sentinel-2 images and presented in Figure 1a are available at doi:
209 10.5281/zenodo.15123647. Supplemental Material for this article includes detailed descrip-
210 tions of the video analysis and slip velocity data obtained from this study.

211 Acknowledgments

212 We thank Editor Keith Koper, Associate Editor Ruth Harris, Chelsea Scott, and anonymous
213 reviewer for their comments which improved this manuscript. The authors thank Great
214 Success Energy Co. Ltd for making the CCTV footage available, and Nic Barth for insightful
215 discussion and assistance with preliminary analysis. This work was supported by JSPS
216 KAKENHI (21H05206, 23K03547) and Marsden Fund, Royal Society Te Apārangi (project
217 id: GNS2002).

218 References

- 219 Barth, N. C., J. R. Kearse, T. A. Little, and R. J. Van Dissen, 2024: Rupture direction of
220 paleoearthquakes on the Alpine Fault, New Zealand, as recorded by curved slickenlines.
221 *Geology*, **52** (12), 917–921.
- 222 Beroza, G. C., and T. Mikumo, 1996: Short slip duration in dynamic rupture in the pres-
223 ence of heterogeneous fault properties. *Journal of Geophysical Research: Solid Earth*,
224 **101** (B10), 22 449–22 460.

- 225 Bouchon, M., N. Toksöz, H. Karabulut, M.-P. Bouin, M. Dietrich, M. Aktar, and M. Edie,
226 2000: Seismic imaging of the 1999 Izmit (Turkey) rupture inferred from the near-fault
227 recordings. *Geophysical Research Letters*, **27 (18)**, 3013–3016.
- 228 Cruz-Atienza, V. M., K. B. Olsen, and L. A. Dalguer, 2009: Estimation of the breakdown
229 slip from strong-motion seismograms: Insights from numerical experiments. *Bulletin of*
230 *the Seismological Society of America*, **99 (6)**, 3454–3469.
- 231 Day, S. M., 1982: Three-dimensional finite difference simulation of fault dynamics: rectan-
232 gular faults with fixed rupture velocity. *Bulletin of the Seismological Society of America*,
233 **72 (3)**, 705–727.
- 234 Fukuyama, E., and T. Mikumo, 2007: Slip-weakening distance estimated at near-fault sta-
235 tions. *Geophysical Research Letters*, **34 (9)**.
- 236 Guatteri, M., and P. Spudich, 2000: What can strong-motion data tell us about slip-
237 weakening fault-friction laws? *Bulletin of the Seismological Society of America*, **90 (1)**,
238 98–116.
- 239 Heaton, T. H., 1990: Evidence for and implications of self-healing pulses of slip in earthquake
240 rupture. *Physics of the Earth and Planetary Interiors*, **64 (1)**, 1–20.
- 241 Huang, Y., and J.-P. Ampuero, 2011: Pulse-like ruptures induced by low-velocity fault zones.
242 *Journal of Geophysical Research: Solid Earth*, **116 (B12)**.
- 243 Inoue, N., R. Yamaguchi, Y. Yagi, R. Okuwaki, B. Enescu, and T. Tadapansawut, 2025: A
244 multiple asymmetric bilateral rupture sequence derived from the peculiar tele-seismic P-
245 waves of the 2025 Mandalay, Myanmar earthquake. *Seismica*, **4 (1)**, doi:10.26443/seismica.
246 v4i1.1691, URL <https://seismica.library.mcgill.ca/article/view/1691>.

247 Kaneko, Y., E. Fukuyama, and I. J. Hamling, 2017: Slip-weakening distance and energy
248 budget inferred from near-fault ground deformation during the 2016 Mw7. 8 Kaikōura
249 earthquake. *Geophysical Research Letters*, **44** (10), 4765–4773.

250 Kaneko, Y., N. Lapusta, and J.-P. Ampuero, 2008: Spectral element modeling of spontaneous
251 earthquake rupture on rate and state faults: Effect of velocity-strengthening friction at
252 shallow depths. *Journal of Geophysical Research: Solid Earth*, **113** (B9).

253 Kearse, J., and Y. Kaneko, 2020: On-fault geological fingerprint of earthquake rupture
254 direction. *Journal of Geophysical Research: Solid Earth*, **125** (9), e2020JB019 863.

255 Kearse, J., Y. Kaneko, T. Little, and R. Van Dissen, 2019: Curved slickenlines preserve
256 direction of rupture propagation. *Geology*, **47** (9), 838–842.

257 Kearse, J., Y. Kaneko, Y. Nozuka, C. Milliner, Y. J. Hsu, and J.-P. Avouac, 2024: Strong
258 asymmetry in near-fault ground velocity during an oblique strike-slip earthquake revealed
259 by waveform particle motions and dynamic rupture simulations. *Seismica*, **3** (2), 1–12.

260 Kearse, J., and Coauthors, 2018: Onshore to offshore ground-surface and seabed rupture
261 of the Jordan–Kekerengu–Needles fault network during the 2016 Mw 7.8 Kaikōura earth-
262 quake, New Zealand. *Bulletin of the Seismological Society of America*, **108** (3B), 1573–
263 1595.

264 Konca Ozgun, A., Y. Kaneko, N. Lapusta, and J.-P. Avouac, 2013: Kinematic inversion of
265 physically plausible earthquake source models obtained from dynamic rupture simulations.
266 *Bulletin of the Seismological Society of America*, **103** (5), 2621–2644.

267 Lai, S.-T., and Coauthors, 2025: Capacity Building Enables Unique Near-Fault Observa-
268 tions of the destructive 2025 M w 7.7 Myanmar Earthquake. *Earth System Science Data*
269 *Discussions*, **2025**, 1–23.

270 Little, T. A., J. Kearse, Y. Kaneko, and R. Van Dissen, 2025: Geometry of curved slickenlines
271 as a function of rupture direction, asperity durability and coseismic roughening of fault
272 surfaces. *Journal of Structural Geology*, **190**, 105–291.

273 Melgar, D., and G. P. Hayes, 2017: Systematic observations of the slip pulse properties of
274 large earthquake ruptures. *Geophysical Research Letters*, **44** (19), 9691–9698.

275 Rockwell, T. K., S. Lindvall, T. Dawson, R. Langridge, W. Lettis, and Y. Klinger, 2002:
276 Lateral offsets on surveyed cultural features resulting from the 1999 Izmit and Duzce
277 earthquakes, Turkey. *Bulletin of the Seismological Society of America*, **92** (1), 79–94.

278 Spudich, P., M. Guatteri, K. Otsuki, and J. Minagawa, 1998: Use of fault striations and
279 dislocation models to infer tectonic shear stress during the 1995 Hyogo-ken Nanbu (Kobe)
280 earthquake. *Bulletin of the Seismological Society of America*, **88** (2), 413–427.

281 USGS, 2025: M 7.7 - 2025 Mandalay, Burma (Myanmar) Earthquake. [https://earthquake.
282 usgs.gov/earthquakes/eventpage/us7000pn9s/executive](https://earthquake.usgs.gov/earthquakes/eventpage/us7000pn9s/executive).

283 Van Wyk De Vries, M., 2025: 2025 Myanmar earthquake displacement maps. Zenodo, doi:
284 10.5281/zenodo.15123647.

285 Vigny, C., A. Socquet, C. Rangin, N. Chamot-Rooke, M. Pubellier, M.-N. Bouin,
286 G. Bertrand, and M. Becker, 2003: Present-day crustal deformation around Sagaing fault,
287 Myanmar. *Journal of Geophysical Research: Solid Earth*, **108** (B11).

288 Witze, A., 2025: Deadly Myanmar earthquake was probably a rare rupture, scientists say.
289 *Nature*, **640** (8058), 296–297.

290 Yao, S., and H. Yang, 2025: Rupture phases reveal geometry-related rupture propagation in
291 a natural earthquake. *Science Advances*, **11** (4), eadq0154.